

Research Article

Existence of Solutions of $\alpha \in (2, 3]$ Order Fractional Three-Point Boundary Value Problems with Integral Conditions

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Existence and uniqueness of solutions for $\alpha \in (2, 3]$ order fractional differential equations with three-point fractional boundary and integral conditions involving the nonlinearity depending on the fractional derivatives of the unknown function are discussed. The results are obtained by using fixed point theorems. Two examples are given to illustrate the results.

1. Introduction

Recently, the theory on existence and uniqueness of solutions of linear and nonlinear fractional differential equations has attracted the attention of many authors; see, for example, [1–19] and references therein. Many of the physical systems can better be described by integral boundary conditions. Integral boundary conditions are encountered in various applications such as population dynamics, blood flow models, chemical engineering, and cellular systems. Moreover, boundary value problems with integral boundary conditions constitute a very interesting and important class of problems. They include two-point, three-point, multipoint, and nonlocal boundary value problems as special cases. The existing literature mainly deals with first order and second order boundary value problems and there are a few papers on third order problems.

El-Shahed [14] studied existence and nonexistence of positive solution of nonlinear fractional two-point boundary value problem:

$$\begin{aligned} \mathfrak{D}_{0+}^{\alpha} u(t) + \lambda a(t) f(u(t)) &= 0, \quad 0 < t < 1; \quad 2 < \alpha < 3, \\ u(0) = u'(0) = u'(1) &= 0, \end{aligned} \quad (1)$$

where $\mathfrak{D}_{0+}^{\alpha}$ denotes the Caputo derivative of fractional order α , λ is a positive parameter, and $a : (0, 1) \rightarrow [0, \infty)$ is continuous function.

In [8], Ahmad and Ntouyas studied a boundary value problem of nonlinear fractional differential equations of

order $\alpha \in (2, 3]$ with antiperiodic type integral boundary conditions:

$$\begin{aligned} \mathfrak{D}_{0+}^{\alpha} u(t) &= f(t, u(t)); \quad 0 < t < T; \quad 2 < \alpha \leq 3, \\ u^{(j)}(0) - \lambda_j u^{(j)}(T) &= \mu_j \int_0^T g_j(s, u(s)) ds, \quad j = 0, 1, 2, \end{aligned} \quad (2)$$

where $\mathfrak{D}_{0+}^{\alpha}$ denotes the Caputo derivative of fractional order α , $u^{(j)}$ denotes j th derivative of u , $f, g_0, g_1, g_2 : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ are given continuous functions, and $\lambda_j, \mu_j \in \mathbb{R}$ ($\lambda_j \neq 1$). The same problem for fractional differential inclusions is considered in [9].

Ahmad and Nieto [7] studied existence and uniqueness results for the following general three-point fractional boundary value problem involving a nonlinear fractional differential equation of order $\alpha \in (m-1, m]$:

$$\begin{aligned} \mathfrak{D}_{0+}^{\alpha} u(t) &= f(t, u(t)); \quad 0 < t < T, \quad m \geq 2, \\ u(0) = u'(0) = \dots = u^{(m-2)}(0) &= 0, \quad u(1) = \lambda u(\eta). \end{aligned} \quad (3)$$

However, very little work has been done on the case when the nonlinearity f depends on the fractional derivative of the unknown function. Su and Zhang [17] and Rehman et al. [16] studied the existence and uniqueness of solutions for following nonlinear two-point and three-point fractional

boundary value problem when the nonlinearity f depends on the fractional derivative of the unknown function.

In this paper, we investigate the existence (and uniqueness) of solution for nonlinear fractional differential equations of order $\alpha \in (2, 3]$ when the nonlinearity f depends on the fractional derivatives of the unknown function

$$\mathfrak{D}_{0^+}^\alpha u(t) = f(t, u(t), \mathfrak{D}_{0^+}^{\beta_1} u(t), \mathfrak{D}_{0^+}^{\beta_2} u(t)); \tag{4}$$

$$0 \leq t \leq T; \quad 2 < \alpha \leq 3$$

with the three-point and integral boundary conditions

$$a_0 u(0) + b_0 u(T) = \lambda_0 \int_0^T g_0(s, u(s)) ds,$$

$$a_1 \mathfrak{D}_{0^+}^{\beta_1} u(\eta) + b_1 \mathfrak{D}_{0^+}^{\beta_1} u(T) = \lambda_1 \int_0^T g_1(s, u(s)) ds,$$

$$0 < \beta_1 \leq 1, \quad 0 < \eta < T, \tag{5}$$

$$a_2 \mathfrak{D}_{0^+}^{\beta_2} u(\eta) + b_2 \mathfrak{D}_{0^+}^{\beta_2} u(T) = \lambda_2 \int_0^T g_2(s, u(s)) ds,$$

$$1 < \beta_2 \leq 2,$$

where $\mathfrak{D}_{0^+}^\alpha$ denotes the Caputo fractional derivative of order α , f, g_i are continuous functions, and $a_i, b_i, \lambda_i \in \mathbb{R}$, for $i = 0, 1, 2$.

2. Preliminaries

Let us recall some basic definitions [20–22].

Definition 1. The Riemann Liouville fractional integral of order α for continuous function $f : [0, \infty) \rightarrow \mathbb{R}$ is defined as

$$I_{0^+}^\alpha f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s) ds, \quad \alpha > 0, \tag{6}$$

provided the integral exists.

Definition 2. For $(n-1)$ -times absolutely continuous function $f : [0, \infty) \rightarrow \mathbb{R}$, the Caputo derivative fractional order α is defined as

$$\mathfrak{D}_{0^+}^\alpha f(t) = \frac{1}{\Gamma(n-\alpha)} \int_0^t (t-s)^{n-\alpha-1} f^{(n)}(s) ds;$$

$$n-1 < \alpha < n, \quad n = [\alpha] + 1, \tag{7}$$

where $[\alpha]$ denotes the integral part of the real number α .

Lemma 3. Let $\alpha > 0$. Then, the differential equation $\mathfrak{D}_{0^+}^\alpha f(t) = 0$ has solutions

$$f(t) = k_0 + k_1 t + k_2 t^2 + \dots + k_{n-1} t^{n-1}, \tag{8}$$

$$I_{0^+}^\alpha \mathfrak{D}_{0^+}^\alpha f(t) = f(t) + k_0 + k_1 t + k_2 t^2 + \dots + k_{n-1} t^{n-1},$$

where $k_i \in \mathbb{R}$ and $i = 1, 2, 3, \dots, n-1, n = [\alpha] + 1$.

Caputo fractional derivative of order $n-1 < \alpha < n$ for t^γ is given as

$$\mathfrak{D}_{0^+}^\alpha t^\gamma = \begin{cases} \frac{\Gamma(\gamma+1)}{\Gamma(\gamma-\alpha+1)} t^{\gamma-\alpha}, & \gamma \in \mathbb{N}, \gamma \geq n \text{ or } \gamma \notin \mathbb{N}, \gamma > n-1 \\ 0, & \gamma \in \{0, 1, \dots, n-1\}. \end{cases} \tag{9}$$

Assume that $\beta_0 = 0$ and

$$a_0 + b_0 \neq 0, \quad a_1 \eta^{1-\beta_1} + b_1 T^{1-\beta_1} \neq 0,$$

$$a_i \eta^{2-\beta_i} + b_i T^{2-\beta_i} \neq 0. \tag{10}$$

For convenience, we set

$$\mu^{\beta_1} := \frac{\Gamma(3-\beta_1)}{2(a_1 \eta^{2-\beta_1} + b_1 T^{2-\beta_1})},$$

$$\mu^{\beta_2} := \frac{\Gamma(3-\beta_2)}{2(a_2 \eta^{2-\beta_2} + b_2 T^{2-\beta_2})},$$

$$\nu^{\beta_1} := \frac{\Gamma(2-\beta_1)}{a_1 \eta^{1-\beta_1} + b_1 T^{1-\beta_1}},$$

$$\omega_0 := -\frac{1}{a_0 + b_0},$$

$$\omega_1(t) := \nu^{\beta_1} \left(\frac{b_0}{a_0 + b_0} T - t \right),$$

$$\omega_2(t) := \frac{b_0 T^2}{a_0 + b_0} \mu^{\beta_2} - \frac{b_0 T}{a_0 + b_0} \nu^{\beta_1} \frac{\mu^{\beta_2}}{\mu^{\beta_1}} + \nu^{\beta_1} \frac{\mu^{\beta_2}}{\mu^{\beta_1}} t - \mu^{\beta_2} t^2. \tag{11}$$

Lemma 4. For any $f, g_0, g_1, g_2 \in C([0, T]; \mathbb{R})$, the unique solution of the fractional boundary value problem

$$\mathfrak{D}_{0^+}^\alpha u(t) = f(t); \quad 0 \leq t \leq T, \quad 2 < \alpha \leq 3, \tag{12}$$

$$a_0 u(0) + b_0 u(T) = \lambda_0 \int_0^T g_0(s) ds,$$

$$a_1 \mathfrak{D}_{0^+}^{\beta_1} u(\eta) + b_1 \mathfrak{D}_{0^+}^{\beta_1} u(T) = \lambda_1 \int_0^T g_1(s) ds,$$

$$0 < \eta < T, \quad 0 < \beta_1 \leq 1,$$

$$a_2 \mathfrak{D}_{0^+}^{\beta_2} u(\eta) + b_2 \mathfrak{D}_{0^+}^{\beta_2} u(T) = \lambda_2 \int_0^T g_2(s) ds, \quad 1 < \beta_2 \leq 2, \tag{13}$$

is given by

$$\begin{aligned}
 u(t) &= \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} f(s) ds \\
 &+ \sum_{i=0}^2 \omega_i(t) b_i \int_0^T \frac{(T-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} f(s) ds \\
 &+ \sum_{i=1}^2 \omega_i(t) a_i \int_0^\eta \frac{(\eta-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} f(s) ds \\
 &- \sum_{i=0}^2 \omega_i(t) \lambda_i \int_0^T g_i(s) ds.
 \end{aligned} \tag{14}$$

Proof. By Lemma 3, for $2 < \alpha \leq 3$, the general solution of the equation $\mathfrak{D}_{0^+}^\alpha u(t) = f(t)$ can be written as

$$u(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s) ds - k_0 - k_1 t - k_2 t^2, \tag{15}$$

where $k_0, k_1, k_2 \in \mathbb{R}$ are arbitrary constants. Moreover, by the formula (9), β_1 and β_2 order derivatives are as follows:

$$\begin{aligned}
 \mathfrak{D}_{0^+}^{\beta_1} u(t) &= I^{\alpha-\beta_1} f(t) - k_1 \frac{t^{1-\beta_1}}{\Gamma(2-\beta_1)} - 2k_2 \frac{t^{2-\beta_1}}{\Gamma(3-\beta_1)}, \\
 \mathfrak{D}_{0^+}^{\beta_2} u(t) &= I^{\alpha-\beta_2} f(t) - 2k_2 \frac{t^{2-\beta_2}}{\Gamma(3-\beta_2)}.
 \end{aligned} \tag{16}$$

Using boundary conditions (13), we get the following algebraic system of equations, for k_0, k_1, k_2 ,

$$\begin{aligned}
 &-(a_0 + b_0)k_0 - b_0 T k_1 - b_0 T^2 k_2 \\
 &= \lambda_0 \int_0^T g_0(s) ds - b_0 I_{0^+}^\alpha f(T), \\
 &-\frac{a_1 \eta^{1-\beta_1} + b_1 T^{1-\beta_1}}{\Gamma(2-\beta_1)} k_1 - 2 \frac{a_1 \eta^{2-\beta_1} + b_1 T^{2-\beta_1}}{\Gamma(3-\beta_1)} k_2 \\
 &= \lambda_1 \int_0^T g_1(s) ds - a_1 I_{0^+}^{\alpha-\beta_1} f(\eta) - b_1 I_{0^+}^{\alpha-\beta_1} f(T), \\
 &-2 \frac{a_2 \eta^{2-\beta_2} + b_2 T^{2-\beta_2}}{\Gamma(3-\beta_2)} k_2 \\
 &= \lambda_2 \int_0^T g_2(s) ds - a_2 I_{0^+}^{\alpha-\beta_2} f(\eta) - b_2 I_{0^+}^{\alpha-\beta_2} f(T).
 \end{aligned} \tag{17}$$

Solving the above system of equations for k_0, k_1, k_2 , we get the following:

$$\begin{aligned}
 k_2 &= b_2 \mu^{\beta_2} I_{0^+}^{\alpha-\beta_2} f(T) + a_2 \mu^{\beta_2} I_{0^+}^{\alpha-\beta_2} f(\eta) - \lambda_2 \mu^{\beta_2} \int_0^T g_2(s) ds, \\
 k_1 &= b_1 \nu^{\beta_1} I_{0^+}^{\alpha-\beta_1} f(T) + a_1 \nu^{\beta_1} I_{0^+}^{\alpha-\beta_1} f(\eta) - \lambda_1 \nu^{\beta_1} \int_0^T g_1(s) ds \\
 &- b_2 \nu^{\beta_1} \frac{\mu^{\beta_2}}{\mu^{\beta_1}} I_{0^+}^{\alpha-\beta_2} f(T) - a_2 \nu^{\beta_1} \frac{\mu^{\beta_2}}{\mu^{\beta_1}} I_{0^+}^{\alpha-\beta_2} f(\eta) \\
 &+ \lambda_2 \nu^{\beta_1} \frac{\mu^{\beta_2}}{\mu^{\beta_1}} \int_0^T g_2(s) ds, \\
 k_0 &= \frac{b_0}{a_0 + b_0} I_{0^+}^\alpha f(T) - \frac{\lambda_0}{a_0 + b_0} \int_0^T g_0(s) ds \\
 &- \frac{b_0 b_1 \nu^{\beta_1} T}{a_0 + b_0} I_{0^+}^{\alpha-\beta_1} f(T) - \frac{b_0 a_1 \nu^{\beta_1} T}{a_0 + b_0} I_{0^+}^{\alpha-\beta_1} f(\eta) \\
 &+ \frac{b_0 \lambda_1 \nu^{\beta_1} T}{a_0 + b_0} \int_0^T g_1(s) ds + \frac{b_0 b_2 \nu^{\beta_1} T}{a_0 + b_0} \frac{\mu^{\beta_2}}{\mu^{\beta_1}} I_{0^+}^{\alpha-\beta_2} f(T) \\
 &+ \frac{b_0 a_2 \nu^{\beta_1} T}{a_0 + b_0} \frac{\mu^{\beta_2}}{\mu^{\beta_1}} I_{0^+}^{\alpha-\beta_2} f(\eta) - \frac{b_0 \lambda_2 \nu^{\beta_1} T}{a_0 + b_0} \frac{\mu^{\beta_2}}{\mu^{\beta_1}} \int_0^T g_2(s) ds \\
 &- \frac{b_0 b_2 \mu^{\beta_2} T^2}{a_0 + b_0} I_{0^+}^{\alpha-\beta_2} f(T) - \frac{b_0 a_2 \mu^{\beta_2} T^2}{a_0 + b_0} I_{0^+}^{\alpha-\beta_2} f(\eta) \\
 &+ \frac{b_0 \lambda_2 \mu^{\beta_2} T^2}{a_0 + b_0} \int_0^T g_2(s) ds.
 \end{aligned} \tag{18}$$

Inserting k_0, k_1, k_2 into (15), we get the desired representation for the solution of (12)-(13). \square

Remark 5. The Green function of the BVP (4)-(5) is defined by

$$G(t; s) = \begin{cases} \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} + G_0(t; s), & 0 \leq s \leq t \leq T, \\ G_0(t; s), & 0 \leq t \leq s \leq T, \end{cases} \tag{19}$$

where

$$\begin{aligned}
 G_0(t; s) &= \sum_{i=0}^2 \omega_i(t) b_i \frac{(T-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} \\
 &+ \sum_{i=1}^2 \omega_i(t) a_i \frac{(\eta-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} \chi_{(0,\eta)}(s), \\
 \chi_{(a,b)}(s) &:= \begin{cases} 1, & s \in (a, b), \\ 0, & s \notin (a, b). \end{cases}
 \end{aligned} \tag{20}$$

Remark 6. For $\alpha = 3$, $\beta_1 = 1$, $\beta_2 = 2$, and $\eta = 0$, the BVP (4)-(5) can be written as follows:

$$\begin{aligned} u'''(t) &= f(t, u(t), u'(t), u''(t)), \quad 0 \leq t \leq T, \\ a_0 u(0) + b_0 u(T) &= \lambda_0 \int_0^T g_0(s, u(s)) ds, \\ a_1 u'(0) + b_1 u'(T) &= \lambda_1 \int_0^T g_1(s, u(s)) ds, \\ a_2 u''(0) + b_2 u''(T) &= \lambda_2 \int_0^T g_2(s, u(s)) ds. \end{aligned} \tag{21}$$

In this case, the Green function can be written as follows:

$$G(t; s) = \begin{cases} \frac{(t-s)^2}{\Gamma(\alpha)} + G_0(t; s), & 0 \leq s \leq t \leq T, \\ G_0(t; s), & 0 \leq t \leq s \leq T, \end{cases} \tag{22}$$

where

$$\begin{aligned} G_0(t; s) &= \frac{b_0}{a_0 + b_0} \frac{(T-s)^2}{\Gamma(\alpha)} + \left(-\frac{b_0}{a_0 + b_0} \frac{b_1}{a_1 + b_1} T + \frac{b_1}{a_1 + b_1} t \right) \\ &\quad \times \frac{T-s}{\Gamma(\alpha-1)} \\ &\quad + \left(\frac{b_0}{a_0 + b_0} \frac{b_1}{a_1 + b_1} \frac{b_2}{a_2 + b_2} T \right. \\ &\quad \left. - \frac{b_0}{a_0 + b_0} \frac{b_2}{2(a_2 + b_2)} T^2 - \frac{2b_1}{a_1 + b_1} \frac{b_2}{2(a_2 + b_2)} t \right. \\ &\quad \left. + \frac{b_2}{2(a_2 + b_2)} t^2 \right) \frac{1}{\Gamma(\alpha-2)}. \end{aligned} \tag{23}$$

Moreover, the case

$$\begin{aligned} a_0 &= 1, & b_0 &= 0, & a_1 &= 0, \\ b_1 &= 1, & a_2 &= 1, & b_2 &= 0 \end{aligned} \tag{24}$$

is investigated in [10]. In this case,

$$G(t; s) = \begin{cases} \frac{(t-s)^2}{\Gamma(\alpha)} + \frac{t(T-s)}{\Gamma(\alpha-1)}, & 0 \leq s \leq t \leq T, \\ \frac{t(T-s)}{\Gamma(\alpha-1)}, & 0 \leq t \leq s \leq T. \end{cases} \tag{25}$$

3. Existence and Uniqueness Results

In this section we state and prove an existence and uniqueness result for the fractional BVP (4)-(5) by using the Banach fixed-point theorem. We study our problem in the space

$$\begin{aligned} C_\beta([0, T]; \mathbb{R}) \\ := \{v \in C([0, T]; \mathbb{R}) : \mathfrak{D}_{0^+}^{\beta_1} v, \mathfrak{D}_{0^+}^{\beta_2} v \in C([0, T]; \mathbb{R})\} \end{aligned} \tag{26}$$

equipped with the norm

$$\|v\|_\beta := \|v\|_C + \|\mathfrak{D}_{0^+}^{\beta_1} v\|_C + \|\mathfrak{D}_{0^+}^{\beta_2} v\|_C, \tag{27}$$

where $\|\cdot\|_C$ is the sup norm in $C([0, T]; \mathbb{R})$.

The following notations, formulae, and estimations will be used throughout the paper:

$$\begin{aligned} \mathfrak{D}_{0^+}^{\beta_1} \omega_1(t) &= -\frac{\nu^{\beta_1} t^{1-\beta_1}}{\Gamma(2-\beta_1)}, \\ \mathfrak{D}_{0^+}^{\beta_2} \omega_1(t) &= 0, \\ \mathfrak{D}_{0^+}^{\beta_1} \omega_2(t) &= \frac{\nu^{\beta_1} \mu^{\beta_2} t^{1-\beta_1}}{\mu^{\beta_1} \Gamma(2-\beta_1)} - 2 \frac{\mu^{\beta_2} t^{2-\beta_1}}{\Gamma(3-\beta_1)}, \\ \mathfrak{D}_{0^+}^{\beta_2} \omega_2(t) &= -2 \frac{\mu^{\beta_2} t^{2-\beta_2}}{\Gamma(3-\beta_2)}, \\ |\omega_0| &= \frac{1}{|a_0 + b_0|} =: \rho_0, \\ |\omega_1(t)| &\leq |\nu^{\beta_1}| (|\omega_0| |b_0| + 1) T =: \rho_1, \\ |\omega_2(t)| &\leq \frac{|b_0| |\mu^{\beta_2}|}{|a_0 + b_0|} T^2 + \frac{|b_0| |\nu^{\beta_1}| |\mu^{\beta_2}|}{|a_0 + b_0| |\mu^{\beta_1}|} T \\ &\quad + \frac{|\nu^{\beta_1}| |\mu^{\beta_2}|}{|\mu^{\beta_1}|} T + |\mu^{\beta_2}| T^2 =: \rho_2, \end{aligned}$$

$$\tilde{\rho}_0 = 0,$$

$$|\mathfrak{D}_{0^+}^{\beta_1} \omega_1(t)| \leq \frac{|\nu^{\beta_1}| T^{1-\beta_1}}{\Gamma(2-\beta_1)} =: \tilde{\rho}_1,$$

$$|\mathfrak{D}_{0^+}^{\beta_1} \omega_2(t)| \leq \frac{|\mu^{\beta_2}| |\nu^{\beta_1}| T^{1-\beta_1}}{|\mu^{\beta_1}| \Gamma(2-\beta_1)} + 2 \frac{|\mu^{\beta_2}| T^{2-\beta_1}}{\Gamma(3-\beta_1)} =: \tilde{\rho}_2,$$

$$\hat{\rho}_0 = \hat{\rho}_1 = 0,$$

$$|\mathfrak{D}_{0^+}^{\beta_2} \omega_2(t)| \leq 2 \frac{|\mu^{\beta_2}| T^{2-\beta_2}}{\Gamma(3-\beta_2)} =: \hat{\rho}_2,$$

$$\begin{aligned} \Delta_0 &:= \frac{T^{\alpha-\tau}}{\Gamma(\alpha)} \left(\frac{1-\tau}{\alpha-\tau} \right)^{1-\tau} \\ &\quad + \sum_{i=0}^2 \rho_i \left(|b_i| \frac{T^{\alpha-\beta_i-\tau}}{\Gamma(\alpha-\beta_i)} + |a_i| \frac{\eta^{\alpha-\beta_i-\tau}}{\Gamma(\alpha-\beta_i)} \right) \\ &\quad \times \left(\frac{1-\tau}{\alpha-\beta_i-\tau} \right)^{1-\tau}, \end{aligned}$$

$$\begin{aligned} \Delta_1 &:= \frac{T^{\alpha-\beta_1-\tau}}{\Gamma(\alpha-\beta_1)} \left(\frac{1-\tau}{\alpha-\beta_1-\tau} \right)^{1-\tau} \|l_f\|_{1/\tau} \\ &\quad + \sum_{i=1}^2 \tilde{\rho}_i \|l_f\|_{1/\tau} \left(|b_i| \frac{T^{\alpha-\beta_i-\tau}}{\Gamma(\alpha-\beta_i)} + |a_i| \frac{\eta^{\alpha-\beta_i-\tau}}{\Gamma(\alpha-\beta_i)} \right) \\ &\quad \times \left(\frac{1-\tau}{\alpha-\beta_i-\tau} \right)^{1-\tau}, \\ \Delta_2 &:= \frac{T^{\alpha-\beta_2-\tau}}{\Gamma(\alpha-\beta_2)} \left(\frac{1-\tau}{\alpha-\beta_2-\tau} \right)^{1-\tau} \|l_f\|_{1/\tau} \\ &\quad + \hat{\rho}_2 \|l_f\|_{1/\tau} \left(|b_2| \frac{T^{\alpha-\beta_2-\tau}}{\Gamma(\alpha-\beta_2)} + |a_2| \frac{\eta^{\alpha-\beta_2-\tau}}{\Gamma(\alpha-\beta_2)} \right) \\ &\quad \times \left(\frac{1-\tau}{\alpha-\beta_2-\tau} \right)^{1-\tau}. \end{aligned} \tag{28}$$

Theorem 7. Assume the following.

(H₁) The function $f : [0, T] \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is jointly continuous.

(H₂) There exists a function $l_f \in L^{1/\tau}([0, T]; \mathbb{R}^+)$ with $\tau \in (0, \min(1, \alpha - \beta_2))$ such that

$$\begin{aligned} &|f(t, u_1, u_2, u_3) - f(t, v_1, v_2, v_3)| \\ &\leq l_f(t) (|u_1 - v_1| + |u_2 - v_2| + |u_3 - v_3|), \end{aligned} \tag{29}$$

for each $(t, u_1, u_2, u_3), (t, v_1, v_2, v_3) \in [0, T] \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}$.

(H₃) The function $g_i : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is jointly continuous and there exists $l_{g_i} \in L^1([0, T], \mathbb{R}^+)$ such that

$$|g_i(t, u) - g_i(t, v)| \leq l_{g_i}(t) |u - v|, \quad i = 0, 1, 2 \tag{30}$$

for each $(t, u), (t, v) \in [0, T] \times \mathbb{R}$.

If

$$\begin{aligned} &(\Delta_0 + \Delta_1 + \Delta_2) \|l_f\|_{1/\tau} + \sum_{i=0}^2 \rho_i |\lambda_i| \|l_{g_i}\|_1 \\ &\quad + \sum_{i=1}^2 \tilde{\rho}_i |\lambda_i| \|l_{g_i}\|_1 + \hat{\rho}_2 |\lambda_2| \|l_{g_2}\|_1 < 1, \end{aligned} \tag{31}$$

then the problem (4)-(5) has a unique solution on $[0, T]$.

Proof. In order to transform the BVP (4)-(5) into a fixed point problem, we consider the operator $\mathfrak{F} : C_\beta([0, T]; \mathbb{R}) \rightarrow C_\beta([0, T]; \mathbb{R})$ which is defined by

$$\begin{aligned} &(\mathfrak{F}u)(t) \\ &= \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\ &\quad + \sum_{i=0}^2 \omega_i(t) b_i \\ &\quad \times \int_0^T \frac{(T-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\ &\quad + \sum_{i=1}^2 \omega_i(t) a_i \\ &\quad \times \int_0^\eta \frac{(\eta-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\ &\quad - \sum_{i=0}^2 \omega_i(t) \lambda_i \int_0^T g_i(s, u(s)) ds \end{aligned} \tag{32}$$

and take its β_1 th and β_2 th fractional derivative to get

$$\begin{aligned} &\mathfrak{D}_{0^+}^{\beta_1} (\mathfrak{F}u)(t) \\ &= \int_0^t \frac{(t-s)^{\alpha-\beta_1-1}}{\Gamma(\alpha-\beta_1)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\ &\quad + \sum_{i=1}^2 \mathfrak{D}_{0^+}^{\beta_1} \omega_i(t) b_i \\ &\quad \times \int_0^T \frac{(T-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\ &\quad + \sum_{i=1}^2 \mathfrak{D}_{0^+}^{\beta_1} \omega_i(t) a_i \\ &\quad \times \int_0^\eta \frac{(\eta-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\ &\quad - \sum_{i=0}^2 \mathfrak{D}_{0^+}^{\beta_1} \omega_i(t) \lambda_i \int_0^T g_i(s, u(s)) ds, \end{aligned}$$

$$\begin{aligned}
& \mathfrak{D}_{0^+}^{\beta_2} (\mathfrak{F}u) (t) \\
&= \int_0^t \frac{(t-s)^{\alpha-\beta_2-1}}{\Gamma(\alpha-\beta_2)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\
&+ \mathfrak{D}_{0^+}^{\beta_2} \omega_2(t) b_2 \\
&\times \int_0^T \frac{(T-s)^{\alpha-\beta_2-1}}{\Gamma(\alpha-\beta_2)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\
&+ \mathfrak{D}_{0^+}^{\beta_2} \omega_2(t) a_2 \\
&\times \int_0^\eta \frac{(\eta-s)^{\alpha-\beta_2-1}}{\Gamma(\alpha-\beta_2)} f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) ds \\
&- \mathfrak{D}_{0^+}^{\beta_2} \omega_2(t) \lambda_2 \int_0^T g_2(s, u(s)) ds.
\end{aligned} \tag{33}$$

Clearly, due to $f, g_0, g_1,$ and g_2 being jointly continuous, the expressions (32)-(33) are well defined. It is obvious that the fixed point of the operator \mathfrak{F} is a solution of the problem (4)-(5). To show existence and uniqueness of the solution (12)-(13), we use the Banach fixed point theorem. To this end, we show that \mathfrak{F} is contraction:

$$\begin{aligned}
& |(\mathfrak{F}u)(t) - (\mathfrak{F}v)(t)| \\
&\leq \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} \\
&\quad \times \left| f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) \right. \\
&\quad \left. - f(s, v(s), \mathfrak{D}_{0^+}^{\beta_1} v(s), \mathfrak{D}_{0^+}^{\beta_2} v(s)) \right| ds \\
&+ \sum_{i=0}^2 |\omega_i(t)| |b_i| \int_0^T \frac{(T-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} \\
&\quad \times \left| f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) \right. \\
&\quad \left. - f(s, v(s), \mathfrak{D}_{0^+}^{\beta_1} v(s), \mathfrak{D}_{0^+}^{\beta_2} v(s)) \right| ds \\
&+ \sum_{i=1}^2 |\omega_i(t)| |a_i| \int_0^\eta \frac{(\eta-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} \\
&\quad \times \left| f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) \right. \\
&\quad \left. - f(s, v(s), \mathfrak{D}_{0^+}^{\beta_1} v(s), \mathfrak{D}_{0^+}^{\beta_2} v(s)) \right| ds \\
&+ \sum_{i=0}^2 |\omega_i(t)| |\lambda_i| \int_0^T |g_i(s, u(s)) - g_i(s, v(s))| ds
\end{aligned}$$

$$\begin{aligned}
&\leq \|l_f\|_{1/\tau} \frac{T^{\alpha-\tau}}{\Gamma(\alpha)} \left(\frac{1-\tau}{\alpha-\tau} \right)^{1-\tau} \|u-v\|_\beta \\
&+ \left(\|l_f\|_{1/\tau} \sum_{i=0}^2 \rho_i \left(|b_i| \frac{T^{\alpha-\beta_i-\tau}}{\Gamma(\alpha-\beta_i)} + |a_i| \frac{\eta^{\alpha-\beta_i-\tau}}{\Gamma(\alpha-\beta_i)} \right) \right. \\
&\quad \times \left(\frac{1-\tau}{\alpha-\beta_i-\tau} \right)^{1-\tau} + \sum_{i=0}^2 \rho_i |\lambda_i| \|l_{g_i}\|_1 \left. \right) \|u-v\|_\beta \\
&= \left(\Delta_0 \|l_f\|_{1/\tau} + \sum_{i=0}^2 \rho_i |\lambda_i| \|l_{g_i}\|_1 \right) \|u-v\|_\beta.
\end{aligned} \tag{34}$$

On the other hand,

$$\begin{aligned}
& \left| \mathfrak{D}_{0^+}^{\beta_1} (\mathfrak{F}u)(t) - \mathfrak{D}_{0^+}^{\beta_1} (\mathfrak{F}v)(t) \right| \\
&\leq \int_0^t \frac{(t-s)^{\alpha-\beta_1-1}}{\Gamma(\alpha-\beta_1)} \\
&\quad \times \left| f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) \right. \\
&\quad \left. - f(s, v(s), \mathfrak{D}_{0^+}^{\beta_1} v(s), \mathfrak{D}_{0^+}^{\beta_2} v(s)) \right| ds \\
&+ \sum_{i=1}^2 \left| \mathfrak{D}_{0^+}^{\beta_1} \omega_i(t) \right| |b_i| \\
&\quad \times \int_0^T \frac{(T-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} \left| f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) \right. \\
&\quad \left. - f(s, v(s), \mathfrak{D}_{0^+}^{\beta_1} v(s), \mathfrak{D}_{0^+}^{\beta_2} v(s)) \right| ds \\
&+ \sum_{i=1}^2 \left| \mathfrak{D}_{0^+}^{\beta_1} \omega_i(t) \right| |a_i| \\
&\quad \times \int_0^\eta \frac{(\eta-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} \left| f(s, u(s), \mathfrak{D}_{0^+}^{\beta_1} u(s), \mathfrak{D}_{0^+}^{\beta_2} u(s)) \right. \\
&\quad \left. - f(s, v(s), \mathfrak{D}_{0^+}^{\beta_1} v(s), \mathfrak{D}_{0^+}^{\beta_2} v(s)) \right| ds \\
&+ \sum_{i=1}^2 \left| \mathfrak{D}_{0^+}^{\beta_1} \omega_i(t) \right| |\lambda_i| \int_0^T |g_i(s, u(s)) - g_i(s, v(s))| ds \\
&\leq \frac{T^{\alpha-\beta_1-\tau}}{\Gamma(\alpha-\beta_1)} \left(\frac{1-\tau}{\alpha-\beta_1-\tau} \right)^{1-\tau} \|l_f\|_{1/\tau} \|u-v\|_\beta \\
&+ \sum_{i=1}^2 \tilde{\rho}_i \left[\|l_f\|_{1/\tau} \left(|b_i| \frac{T^{\alpha-\beta_i-\tau}}{\Gamma(\alpha-\beta_i)} + |a_i| \frac{\eta^{\alpha-\beta_i-\tau}}{\Gamma(\alpha-\beta_i)} \right) \right. \\
&\quad \times \left(\frac{1-\tau}{\alpha-\beta_i-\tau} \right)^{1-\tau} + |\lambda_i| \|l_{g_i}\|_1 \left. \right] \|u-v\|_\beta \\
&= \left(\Delta_1 \|l_f\|_{1/\tau} + \sum_{i=1}^2 \tilde{\rho}_i |\lambda_i| \|l_{g_i}\|_1 \right) \|u-v\|_\beta.
\end{aligned} \tag{35}$$

Similarly,

$$\begin{aligned}
 & \left| \mathfrak{D}_{0+}^{\beta_2} (\mathfrak{F}u)(t) - \mathfrak{D}_{0+}^{\beta_2} (\mathfrak{F}v)(t) \right| \\
 & \leq \int_0^t \frac{(t-s)^{\alpha-\beta_2-1}}{\Gamma(\alpha-\beta_2)} \\
 & \quad \times \left| f(s, u(s), \mathfrak{D}_{0+}^{\beta_1} u(s), \mathfrak{D}_{0+}^{\beta_2} u(s)) \right. \\
 & \quad \left. - f(s, v(s), \mathfrak{D}_{0+}^{\beta_1} v(s), \mathfrak{D}_{0+}^{\beta_2} v(s)) \right| ds \\
 & + \left| \mathfrak{D}_{0+}^{\beta_2} \omega_2(t) \right| |b_2| \\
 & \times \int_0^T \frac{(T-s)^{\alpha-\beta_2-1}}{\Gamma(\alpha-\beta_2)} \\
 & \quad \times \left| f(s, u(s), \mathfrak{D}_{0+}^{\beta_1} u(s), \mathfrak{D}_{0+}^{\beta_2} u(s)) \right. \\
 & \quad \left. - f(s, v(s), \mathfrak{D}_{0+}^{\beta_1} v(s), \mathfrak{D}_{0+}^{\beta_2} v(s)) \right| ds \\
 & + \left| \mathfrak{D}_{0+}^{\beta_2} \omega_2(t) \right| |a_2| \\
 & \times \int_0^\eta \frac{(\eta-s)^{\alpha-\beta_2-1}}{\Gamma(\alpha-\beta_2)} \\
 & \quad \times \left| f(s, u(s), \mathfrak{D}_{0+}^{\beta_1} u(s), \mathfrak{D}_{0+}^{\beta_2} u(s)) \right. \\
 & \quad \left. - f(s, v(s), \mathfrak{D}_{0+}^{\beta_1} v(s), \mathfrak{D}_{0+}^{\beta_2} v(s)) \right| ds \\
 & + \left| \mathfrak{D}_{0+}^{\beta_2} \omega_2(t) \right| |\lambda_2| \\
 & \times \int_0^T |g_2(s, u(s)) - g_2(s, v(s))| ds \\
 & \leq \frac{T^{\alpha-\beta_2-\tau}}{\Gamma(\alpha-\beta_2)} \left(\frac{1-\tau}{\alpha-\beta_2-\tau} \right)^{1-\tau} \|l_f\|_{1/\tau} \|u-v\|_\beta \\
 & + \left(\widehat{\rho}_2 \left(|b_2| \frac{T^{\alpha-\beta_2-\tau}}{\Gamma(\alpha-\beta_2)} + |a_2| \frac{\eta^{\alpha-\beta_2-\tau}}{\Gamma(\alpha-\beta_2)} \right) \right. \\
 & \quad \times \left. \left(\frac{1-\tau}{\alpha-\beta_2-\tau} \right)^{1-\tau} \|l_f\|_{1/\tau} + \widehat{\rho}_2 |\lambda_2| \|l_{g_2}\|_1 \right) \\
 & \times \|u-v\|_\beta \\
 & = \left(\Delta_2 \|l_f\|_{1/\tau} + \widehat{\rho}_2 |\lambda_2| \|l_{g_2}\|_1 \right) \|u-v\|_\beta.
 \end{aligned} \tag{36}$$

Here, in estimations (34)–(36), we used the Hölder inequality:

$$\begin{aligned}
 & \int_0^t l_f(s) (t-s)^{\alpha-m-1} ds \\
 & \leq \left(\int_0^t (l_f(s))^{1/\tau} ds \right)^\tau \left(\int_0^t ((t-s)^{\alpha-m-1})^{1/(1-\tau)} ds \right)^{1-\tau}
 \end{aligned}$$

$$= \|l_f\|_{L^{1/\tau}} \left(\frac{1-\tau}{\alpha-m-\tau} \right)^{1-\tau} t^{\alpha-m-\tau}, \quad \text{if } 0 < \tau < \min(1, \alpha-m). \tag{37}$$

From (34)–(36), it follows that

$$\begin{aligned}
 & \|(\mathfrak{F}u) - (\mathfrak{F}v)\|_\beta \\
 & \leq \left[(\Delta_0 + \Delta_1 + \Delta_2) \|l_f\|_{1/\tau} + \sum_{i=0}^2 \rho_i |\lambda_i| \|l_{g_i}\|_1 \right. \\
 & \quad \left. + \sum_{i=1}^2 \widehat{\rho}_i |\lambda_i| \|l_{g_i}\|_1 + \widehat{\rho}_2 |\lambda_2| \|l_{g_2}\|_1 \right] \|u-v\|_\beta.
 \end{aligned} \tag{38}$$

Consequently, by (31), \mathfrak{F} is a contraction mapping. As a consequence of the Banach fixed point theorem, we deduce that \mathfrak{F} has a fixed point which is a solution of the problem (4)–(5). \square

Remark 8. In the assumptions (H_2) , if l_f is a positive constant, then the condition (31) can be replaced by

$$\begin{aligned}
 & \frac{l_f T^\alpha}{\Gamma(\alpha+1)} \\
 & + l_f \sum_{i=0}^2 \rho_i \left(|b_i| \frac{T^{\alpha-\beta_i}}{\Gamma(\alpha-\beta_i+1)} + |a_i| \frac{\eta^{\alpha-\beta_i}}{\Gamma(\alpha-\beta_i+1)} \right) \\
 & + \frac{l_f T^{\alpha-\beta_1}}{\Gamma(\alpha-\beta_1+1)} \\
 & + l_f \sum_{i=1}^2 \widehat{\rho}_i \left(|b_i| \frac{T^{\alpha-\beta_i}}{\Gamma(\alpha-\beta_i+1)} + |a_i| \frac{\eta^{\alpha-\beta_i}}{\Gamma(\alpha-\beta_i+1)} \right) \\
 & + \frac{l_f T^{\alpha-\beta_2}}{\Gamma(\alpha-\beta_2+1)} \\
 & + l_f \widehat{\rho}_2 \left(|b_2| \frac{T^{\alpha-\beta_2}}{\Gamma(\alpha-\beta_2+1)} + |a_2| \frac{\eta^{\alpha-\beta_2}}{\Gamma(\alpha-\beta_2+1)} \right) \\
 & + \sum_{i=0}^2 \rho_i |\lambda_i| \|l_{g_i}\|_1 + \sum_{i=1}^2 \widehat{\rho}_i |\lambda_i| \|l_{g_i}\|_1 \\
 & + \widehat{\rho}_2 |\lambda_2| \|l_{g_2}\|_1 < 1.
 \end{aligned} \tag{39}$$

4. Existence Results

To prove the existence of solutions for BVP (4)–(5), we recall the following known nonlinear alternative.

Theorem 9 (nonlinear alternative). *Let X be a Banach space; let B be a closed, convex subset of X ; let W be an open subset of B and $0 \in W$. Suppose that $F : \overline{W} \rightarrow B$ is a continuous and compact map. Then, either (a) F has a fixed point in \overline{W} or (b) there exist an $x \in \partial W$ (the boundary of W) and $\lambda \in (0, 1)$ with $x = \lambda F(x)$.*

Theorem 10. Assume that

(H₄) functions $f : [0, T] \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$, $g_i : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ ($i = 0, 1, 2$) are jointly continuous;

(H₅) there exist nondecreasing functions $\varphi : [0, \infty) \rightarrow [0, \infty)$, $\psi_i : [0, \infty) \rightarrow [0, \infty)$ and functions $l_f \in L^{1/\tau}([0, T], \mathbb{R}^+)$, $l_{g_i} \in L^1([0, T], \mathbb{R}^+)$ with $\tau \in (0, \min(1, \alpha - \beta_2))$ such that

$$|f(t, u, v, w)| \leq l_f(t) \varphi(|u| + |v| + |w|),$$

$$|g_i(t, u)| \leq l_{g_i}(t) \psi_i(|u|), \tag{40}$$

$i = 0, 1, 2$, for all $t \in [0, T]$ and $u, v, w \in \mathbb{R}$;

(H₆) there exists a constant $K > 0$ such that

$$K \left(\varphi(K) \|l_f\|_{1/\tau} (\Delta_0 + \Delta_1 + \Delta_2) + \sum_{i=0}^2 (\rho_i + \tilde{\rho}_i + \hat{\rho}_i) |\lambda_i| \psi_i(K) \|l_{g_i}\|_1 \right)^{-1} > 1. \tag{41}$$

Then the problem (4)-(5) has at least one solution on $[0, T]$.

Proof. Let $B_r := \{u \in C_\beta([0, T]; \mathbb{R}) : \|u\|_\beta \leq r\}$.

Step 1. We show that the operator $\mathfrak{F} : C_\beta([0, T]; \mathbb{R}) \rightarrow C_\beta([0, T]; \mathbb{R})$ defined by (32) maps B_r into bounded set.

For each $u \in B_r$, we have

$$|(\mathfrak{F}u)(t)| \leq \frac{\varphi(r)}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} |l_f(s)| ds + \varphi(r) \sum_{i=0}^2 \rho_i |b_i| \frac{1}{\Gamma(\alpha - \beta_i)} \int_0^T (T-s)^{\alpha-\beta_i-1} |l_f(s)| ds + \varphi(r) \sum_{i=1}^2 \rho_i |a_i| \frac{1}{\Gamma(\alpha - \beta_i)} \int_0^\eta (\eta-s)^{\alpha-\beta_i-1} |l_f(s)| ds + \sum_{i=0}^2 \rho_i |\lambda_i| \psi_i(r) \int_0^T |l_{g_i}(s)| ds. \tag{42}$$

By the Hölder inequality, we have

$$|(\mathfrak{F}u)(t)| \leq \varphi(r) \|l_f\|_{1/\tau} \left(\frac{T^{\alpha-\tau}}{\Gamma(\alpha)} \left(\frac{1-\tau}{\alpha-\tau} \right)^{1-\tau} + \sum_{i=0}^2 \rho_i |b_i| \frac{T^{\alpha-\beta_i-\tau}}{\Gamma(\alpha - \beta_i)} \left(\frac{1-\tau}{\alpha - \beta_i - \tau} \right)^{1-\tau} + \sum_{i=1}^2 \rho_i |a_i| \frac{\eta^{\alpha-\beta_i-\tau}}{\Gamma(\alpha - \beta_i)} \left(\frac{1-\tau}{\alpha - \beta_i - \tau} \right)^{1-\tau} \right) + \sum_{i=0}^2 \rho_i |\lambda_i| \psi_i(r) \|l_{g_i}\|_1 = \varphi(r) \|l_f\|_{1/\tau} \Delta_0 + \sum_{i=0}^2 \rho_i |\lambda_i| \psi_i(r) \|l_{g_i}\|_1. \tag{43}$$

In a similar manner,

$$|\mathfrak{D}_{0+}^{\beta_1}(\mathfrak{F}u)(t)| \leq \varphi(r) \|l_f\|_{1/\tau} \left(\frac{T^{\alpha-\beta_1-\tau}}{\Gamma(\alpha - \beta_1)} \left(\frac{1-\tau}{\alpha - \beta_1 - \tau} \right)^{1-\tau} + \sum_{i=1}^2 \tilde{\rho}_i |b_i| \frac{T^{\alpha-\beta_i-\tau}}{\Gamma(\alpha - \beta_i)} \left(\frac{1-\tau}{\alpha - \beta_i - \tau} \right)^{1-\tau} + \sum_{i=1}^2 \tilde{\rho}_i |a_i| \frac{\eta^{\alpha-\beta_i-\tau}}{\Gamma(\alpha - \beta_i)} \left(\frac{1-\tau}{\alpha - \beta_i - \tau} \right)^{1-\tau} \right) + \sum_{i=1}^2 \tilde{\rho}_i |\lambda_i| \psi_i(r) \|l_{g_i}\|_1 = \varphi(r) \|l_f\|_{1/\tau} \Delta_1 + \sum_{i=1}^2 \tilde{\rho}_i |\lambda_i| \psi_i(r) \|l_{g_i}\|_1, |\mathfrak{D}_{0+}^{\beta_2}(\mathfrak{F}u)(t)| \leq \varphi(r) \|l_f\|_{1/\tau} \left(\frac{T^{\alpha-\beta_2-\tau}}{\Gamma(\alpha - \beta_2)} \left(\frac{1-\tau}{\alpha - \beta_2 - \tau} \right)^{1-\tau} + \hat{\rho}_2 \frac{T^{\alpha-\beta_2-\tau} |b_2|}{\Gamma(\alpha - \beta_2)} \left(\frac{1-\tau}{\alpha - \beta_2 - \tau} \right)^{1-\tau} + \hat{\rho}_2 \frac{\eta^{\alpha-\beta_2-\tau} |b_2|}{\Gamma(\alpha - \beta_2)} \left(\frac{1-\tau}{\alpha - \beta_2 - \tau} \right)^{1-\tau} \right) + \hat{\rho}_2 |\lambda_2| \psi_2(r) \|l_{g_2}\|_1 = \varphi(r) \|l_f\|_{1/\tau} \Delta_2 + \hat{\rho}_2 |\lambda_2| \psi_2(r) \|l_{g_2}\|_1. \tag{44}$$

Thus,

$$\begin{aligned} \|(\mathfrak{F}u)\|_\beta &\leq \varphi(r) \|l_f\|_{1/\tau} (\Delta_0 + \Delta_1 + \Delta_2) \\ &\quad + \sum_{i=0}^2 (\rho_i + \tilde{\rho}_i + \hat{\rho}_i) |\lambda_i| \psi_i(r) \|l_{g_i}\|_1. \end{aligned} \tag{45}$$

Step 2. The families $\{\mathfrak{F}u : u \in B_r\}$, $\{\mathfrak{D}_{0+}^{\beta_1}(\mathfrak{F}u) : u \in B_r\}$, and $\{\mathfrak{D}_{0+}^{\beta_2}(\mathfrak{F}u) : u \in B_r\}$ are equicontinuous.

Because of the continuity of $\omega_i(t)$ and assumption (H₅) we have

$$\begin{aligned} &|(\mathfrak{F}u)(t_2) - (\mathfrak{F}u)(t_1)| \\ &\leq \frac{1}{\Gamma(\alpha)} \varphi(r) \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} l_f(s) ds \\ &\quad + \frac{1}{\Gamma(\alpha)} \varphi(r) \int_0^{t_1} ((t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1}) l_f(s) ds \\ &\quad + \varphi(r) \sum_{i=0}^2 |\omega_i(t_2) - \omega_i(t_1)| |b_i| \\ &\quad \times \int_0^T \frac{(T-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} l_f(s) ds \\ &\quad + \varphi(r) \sum_{i=1}^2 |\omega_i(t_2) - \omega_i(t_1)| |a_i| \\ &\quad \times \int_0^\eta \frac{(\eta-s)^{\alpha-\beta_i-1}}{\Gamma(\alpha-\beta_i)} l_f(s) ds \\ &\quad + \sum_{i=0}^2 |\omega_i(t_2) - \omega_i(t_1)| |\lambda_i| \psi_i(r) \|l_{g_i}\|_1 \longrightarrow 0 \\ &\hspace{15em} \text{as } t_2 \longrightarrow t_1. \end{aligned} \tag{46}$$

Therefore, $\{\mathfrak{F}u : u \in B_r\}$ is equicontinuous. Similarly, we may prove that $\{\mathfrak{D}_{0+}^{\beta_1}(\mathfrak{F}u) : u \in B_r\}$ and $\{\mathfrak{D}_{0+}^{\beta_2}(\mathfrak{F}u) : u \in B_r\}$ are equicontinuous.

Hence, by the Arzela-Ascoli theorem, the sets $\{\mathfrak{F}u : u \in B_r\}$, $\{\mathfrak{D}_{0+}^{\beta_1}(\mathfrak{F}u) : u \in B_r\}$, and $\{\mathfrak{D}_{0+}^{\beta_2}(\mathfrak{F}u) : u \in B_r\}$ are relatively compact in $C([0, T]; \mathbb{R})$. Therefore, $\mathfrak{F}(B_r)$ is a relatively compact subset of $C_\beta([0, T]; \mathbb{R})$. Consequently, the operator \mathfrak{F} is compact.

Step 3. \mathfrak{F} has a fixed point in $W = \{u \in C_\beta([0, T]; \mathbb{R}) : \|u\|_\beta < K\}$.

We let $u = \lambda(\mathfrak{F}u)$ for $0 < \lambda < 1$. Then, for each $t \in [0, T]$,

$$\begin{aligned} \|u\|_\beta &= \|\lambda(\mathfrak{F}u)\|_\beta \leq \varphi(\|u\|_\beta) \|l_f\|_{1/\tau} (\Delta_0 + \Delta_1 + \Delta_2) \\ &\quad + \sum_{i=0}^2 (\rho_i + \tilde{\rho}_i + \hat{\rho}_i) |\lambda_i| \psi_i(\|u\|_\beta) \|l_{g_i}\|_1. \end{aligned} \tag{47}$$

In other words,

$$\begin{aligned} \|u\|_\beta &\left(\varphi(\|u\|_\beta) \|l_f\|_{1/\tau} (\Delta_0 + \Delta_1 + \Delta_2) \right. \\ &\quad \left. + \sum_{i=0}^2 (\rho_i + \tilde{\rho}_i + \hat{\rho}_i) |\lambda_i| \psi_i(\|u\|_\beta) \|l_{g_i}\|_1 \right)^{-1} \leq 1. \end{aligned} \tag{48}$$

According to the assumption (H₆), we know that there exists $K > 0$ such that $K > \|u\|_\beta$ and

$$\begin{aligned} &K \left(\varphi(K) \|l_f\|_{1/\tau} (\Delta_0 + \Delta_1 + \Delta_2) \right. \\ &\quad \left. + \sum_{i=0}^2 (\rho_i + \tilde{\rho}_i + \hat{\rho}_i) |\lambda_i| \psi_i(K) \|l_{g_i}\|_1 \right)^{-1} > 1. \end{aligned} \tag{49}$$

In other words, for all $u \in \partial W$, we have $u \neq \lambda(\mathfrak{F}u)$. Since the operator $\mathfrak{F} : \overline{W} \rightarrow C_\beta([0, T]; \mathbb{R})$ is continuous and compact, from Theorem 9(a), we can deduce that \mathfrak{F} has a fixed point in \overline{W} . \square

Remark 11. Notice that analogues of Theorems 7 and 10 for the case $f(t, u, v, w) = f(t, u)$ were considered in [9]. Thus, our results are a generalization of [9] in the special case when (fractional) differential inclusion is replaced by (fractional) differential equation.

Remark 12. Since the number $(\alpha - \beta_2 - 1)$ can be negative, the function $(T - s)^{\alpha-\beta_2-1} \notin L^\infty([0, T], \mathbb{R})$. That is why in Theorems 7 and 10 it is assumed that $l_f \in L^{1/\tau}$, $\tau \in (0, \min(1, \alpha - \beta_2))$.

5. Examples

Example 1. Consider the following boundary value problem of fractional differential equation:

$$\begin{aligned} &\mathfrak{D}_{0+}^{5/2} u(t) \\ &= \frac{1}{11} \left(\frac{|u(t)|}{1 + |u(t)|} + \frac{|\mathfrak{D}_{0+}^{1/2} u(t)|}{1 + |\mathfrak{D}_{0+}^{1/2} u(t)|} + \tan^{-1}(\mathfrak{D}_{0+}^{3/2} u(t)) \right) \\ &\hspace{15em} 0 \leq t \leq 1, \end{aligned}$$

$$u(0) + u(1) = \int_0^1 \frac{u(s)}{(1+s)^2} ds,$$

$$\mathfrak{D}_{0+}^{1/2} u\left(\frac{1}{10}\right) + \mathfrak{D}_{0+}^{1/2} u(1) = \frac{1}{2} \int_0^1 \left(\frac{e^s u(s)}{1 + 2e^s} + \frac{1}{2} \right) ds,$$

$$\mathfrak{D}_{0+}^{3/2} u\left(\frac{1}{10}\right) + \mathfrak{D}_{0+}^{3/2} u(1) = \frac{1}{3} \int_0^1 \left(\frac{u(s)}{1 + e^s} + \frac{3}{4} \right) ds. \tag{50}$$

Here,

$$\begin{aligned}
 \alpha &= \frac{5}{2}, & \beta_1 &= \frac{1}{2}, & \beta_2 &= \frac{3}{2}, \\
 T = 1, & \quad \tau = \frac{1}{10}, & a_0 = b_0 = a_1 = b_1 = a_2 = b_2 &= 1, \\
 \eta &= \frac{1}{10}, & \lambda_0 &= 1, & \lambda_1 &= \frac{1}{2}, \\
 \lambda_2 &= \frac{1}{3}, & l_{g_0} = l_{g_1} = l_{g_2} &= 1, \\
 f(t, u, v, w) &:= \frac{1}{11} \left(\frac{u}{1+u} + \frac{v}{1+v} + \tan^{-1}(w) \right), \\
 l_f(t) &= \frac{1}{11}, \\
 g_0(t, u) &:= \frac{u}{(1+t)^2}, & g_1(t, u) &:= \frac{e^t u}{1+2e^t} + \frac{1}{2}, \\
 g_2(t, u) &:= \frac{u}{1+e^t} + \frac{3}{4}.
 \end{aligned} \tag{51}$$

Since $1.77 < \Gamma(1/2) < 1.78$, $0.88 < \Gamma(3/2) < 0.89$, $1.32 < \Gamma(5/2) < 1.33$, and $3.32 < \Gamma(7/2) < 3.33$, with simple calculations, we show that

$$\begin{aligned}
 \Delta_0 &= 2.34, & \Delta_1 &= 0.19, & \Delta_2 &= 0.15, \\
 \rho_0 &= 0.5, & \rho_1 &= 1.01, & \rho_2 &= 1.2, \\
 \tilde{\rho}_0 &= 0, & \tilde{\rho}_1 &= 0.76, & \tilde{\rho}_2 &= 0.9, \\
 \hat{\rho}_0 &= \hat{\rho}_1 = 0, & \hat{\rho}_2 &= 0.51.
 \end{aligned} \tag{52}$$

Furthermore,

$$\begin{aligned}
 (\Delta_0 + \Delta_1 + \Delta_2) \|l_f\|_{1/\tau} + \sum_{i=0}^2 \rho_i |\lambda_i| \|l_{g_i}\|_1 \\
 + \sum_{i=1}^2 \tilde{\rho}_i |\lambda_i| \|l_{g_i}\|_1 + \hat{\rho}_2 |\lambda_2| \|l_{g_2}\|_1 < 2.7 \frac{1}{11} + 0.75 < 1.
 \end{aligned} \tag{53}$$

Thus, all the assumptions of Theorem 7 are satisfied. Hence, the problem (50) has a unique solution on $[0, 1]$.

Example 2. Consider the following boundary value problem of fractional differential equation:

$$\begin{aligned}
 \mathfrak{D}_{0^+}^{5/2} u(t) &= \frac{|u(t)|^3}{9(|u(t)|^3 + 3)} + \frac{|\sin \mathfrak{D}_{0^+}^{1/2} u(t)|}{9(|\sin \mathfrak{D}_{0^+}^{1/2} u(t)| + 1)} + \frac{1}{12}, \\
 & \quad t \in [0, 1], \\
 u(0) + u(1) &= \int_0^1 \frac{u(s)}{3(1+s)^2} ds, \\
 \mathfrak{D}_{0^+}^{1/2} u\left(\frac{1}{10}\right) + \mathfrak{D}_{0^+}^{1/2} u(1) &= \frac{1}{2} \int_0^1 \frac{e^s u(s)}{3(1+e^s)^2} ds, \\
 \mathfrak{D}_{0^+}^{3/2} u\left(\frac{1}{10}\right) + \mathfrak{D}_{0^+}^{3/2} u(1) &= \frac{1}{3} \int_0^1 \frac{u(s)}{3(1+e^s)^2} ds,
 \end{aligned} \tag{54}$$

where f is given by

$$f(t, u, v, w) = \frac{|u|^3}{10(|u|^3 + 3)} + \frac{|\sin v|}{9(|\sin v| + 1)} + \frac{1}{12}. \tag{55}$$

We have

$$|f(t, u, v, w)| \leq \frac{|u|^3}{9(|u|^3 + 3)} + \frac{|\sin v|}{9(|\sin v| + 1)} + \frac{1}{12} \leq \frac{11}{36},$$

$u, v, w \in \mathbb{R}.$ (56)

Thus,

$$|f(t, u, v, w)| \leq \frac{11}{36} = l_f(t) \varphi(|u| + |v| + |w|),$$

(57)

with $l_f(t) = \frac{1}{3}, \quad \varphi(t) = \frac{11}{12}.$

Moreover,

$$\begin{aligned}
 \alpha &= \frac{5}{2}, & \beta_1 &= \frac{1}{2}, & \beta_2 &= \frac{3}{2}, \\
 T = 1, & \quad \tau = \frac{1}{10}, & a_0 = b_0 = a_1 = b_1 = a_2 = b_2 &= 1, \\
 \eta &= \frac{1}{10}, & \lambda_0 &= 1, & \lambda_1 &= \frac{1}{2},
 \end{aligned}$$

$$\begin{aligned}
 \lambda_2 &= \frac{1}{3}, & l_{g_0} &= l_{g_1} = l_{g_2} = \frac{1}{3}, \\
 \Delta_0 &= 2.34, & \Delta_1 &= 0.19, & \Delta_2 &= 0.15, \\
 \rho_0 &= 0.5, & \rho_1 &= 1.01, & \rho_2 &= 1.2, \\
 \tilde{\rho}_0 &= 0, & \tilde{\rho}_1 &= 0.76, & \tilde{\rho}_2 &= 0.9, \\
 \hat{\rho}_0 &= \hat{\rho}_1 = 0, & \hat{\rho}_2 &= 0.51, \\
 g_0(t, u) &:= \frac{u}{3(1+t)^2}, \\
 g_1(t, u) &:= \frac{e^t u}{3(1+e^t)^2}, \\
 g_2(t, u) &:= \frac{u}{3(1+e^t)^2}, \\
 \psi_i(u) &= u, \quad i = 0, 1, 2.
 \end{aligned}
 \tag{58}$$

From the condition

$$\begin{aligned}
 &K \left(\varphi(K) \|l_f\|_{1/\tau} (\Delta_0 + \Delta_1 + \Delta_2) \right. \\
 &\left. + \sum_{i=0}^2 (\rho_i + \tilde{\rho}_i + \hat{\rho}_i) |\lambda_i| \psi_i(K) \|l_{g_i}\|_1 \right)^{-1} > 1,
 \end{aligned}
 \tag{59}$$

we find that

$$K > 9.8. \tag{60}$$

Thus, all the conditions of Theorem 10 are satisfied. So, there exists at least one solution of problem (54) on $[0, 1]$.

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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