## 10 Complete Minimal Surfaces, Osserman's Theorem

Let  $X: M \hookrightarrow \mathbb{R}^3$  be a surface,  $\Lambda^2 = |X_1|^2 = |X_2|^2$ , and  $\gamma: I \to M$  be a differentiable curve. The arc length of  $\gamma$  is  $\Gamma := \int_I |(X \circ r)'(t)| dt$ . A divergent path on M is a piecewise differentiable curve  $\gamma: [0, \infty) \to M$  such that for every compact set  $V \subset M$  there is a T > 0 such that  $\gamma(t) \notin V$  for every t > T. If  $\gamma$  is piecewise differentiable, we define its arc length as

 $\Gamma := \int_0^\infty |(X \circ r)'(t)| \, dt = \int_0^\infty \Lambda(\gamma(t)) |r'(t)| \, dt.$ 

Note that  $\Gamma$  could be  $\infty$ .

**Definition 10.1** We say that X is *complete* if for any divergent curve  $\gamma$ ,  $\Gamma = \infty$ .

**Remark 10.2** The use of a divergent curve instead of boundary to describe completeness is because that if  $M = \mathbf{D}^*$ ,  $\{0\}$  is not a boundary point of M, but is the limit point of a divergent curve.

Note that in case that (M, g) is a non-compact Riemannian manifold and  $\partial M = \emptyset$ , according to the Hopf-Reno theorem, this definition of completeness is equivalent to each of the following:

- 1. Any geodesic  $\gamma: I \subset \mathbf{R} \hookrightarrow M$  can be extended to a geodesic  $\gamma: \mathbf{R} \hookrightarrow M$ ,
- 2. (M, d) is a complete metric space, where d is the induced distance from the Riemannian metric g (roughly speaking, d(p,q) = the arc length of the shortest geodesic segment connecting p and q),
- 3. in (M, d), any bounded closed set is compact.

In general, there are many examples of closed minimal submanifolds  $M \hookrightarrow (N,g)$  where (N,g) is a Riemannian manifold. For example,  $S^2 \subset S^3$  is minimal. But we have seen that there are no closed minimal surfaces in  $\mathbb{R}^3$ . Hence in some sense a complete minimal surface without boundary is the closest analogue to a "closed minimal surface in  $\mathbb{R}^3$ ".

**Definition 10.3** Let  $X: M \hookrightarrow \mathbf{R}^3$  be a complete minimal surface. Remember that the Gauss curvature K is a non-positive function on M, hence the integral of K has a meaning. We define

$$K(M) := \int_{M} K dA \tag{10.39}$$

to be the total Gauss curvature of M.

Let  $X: M \hookrightarrow \mathbb{R}^3$  be a surface and K be the Gauss curvature. Let  $K^- = \max\{-K,0\}$ ,  $K^+ = \max\{K,0\}$ , then  $K = K^+ - K^-$ ,  $|K| = K^+ + K^-$ . We first prove a theorem of A. Huber, the proof shown here belongs to B. White [82].

**Theorem 10.4 (Huber [35])** Let  $X: M \hookrightarrow \mathbb{R}^3$  be a non-compact, complete surface. If  $\int_M |K^-| dA < \infty$ , then  $\int_M |K^+| dA < \infty$ , and M is homeomorphic to  $\overline{M} - \{p_1, \dots, p_k\}$ , where  $\overline{M}$  is a compact 2-manifold.

**Proof.** Fix  $x_0 \in M$ , and let

$$\Omega_r = \Omega(r) = \{ x \in M \mid d(x, x_0) < r \},\$$

where d(x, y) is the geodesic distance from x to y. P. Hartman [23] has shown that  $\partial \Omega_r$  is, for almost all r, a piecewise smooth, embedded closed curve. Let  $\theta_i$ ,  $i = 1, \dots, n$  be the exterior angles of  $\partial \Omega_r$ . By Gauss-Bonnet theorem,

$$\int_{\partial\Omega_r} \kappa_g \, ds + \sum_i \theta_i = 2\pi \chi(r) - \int_{\Omega_r} K \, dA$$
$$= 2\pi (2 - 2h(r) - c(r)) - \int_{\Omega_r} K \, dA, \tag{10.40}$$

where  $\chi(r)$ , h(r), and c(r) are the Euler characteristic, number of handles, and the number of boundary components, respectively, of  $\Omega_r$ .

Let L(r) denote the length of  $\partial\Omega_r$ . P. Hartman [23] has proved that L(r) is absolutely continuous. As proved in [83],

$$L'(r) = 2\pi(2 - 2h(r) - c(r)) - \int_{\Omega_r} K \, dA + \sum_{\theta_i < 0} (2\tan(\theta_i/2) - \theta_i),$$

when  $-\pi/2 < \theta_i < 0, 2 \tan(\theta_i/2) - \theta_i < 0$ , so

$$L'(r) \le 2\pi(2 - 2h(r) - c(r)) - \int_{\Omega_n} K \, dA.$$

Since M is complete and noncompact, L(r) > 0 for all r > 0; so

$$0 \leq \limsup L'(r) \\ \leq 2\pi (2 - 2 \liminf h(r) - \liminf c(r)) - \int_{M} |K^{+}| dA + \int_{M} |K^{-}| dA. \quad (10.41)$$

Thus the negative quantities on the right-hand side are all finite. Since h(r) is a non-decreasing, integer valued function of r,

$$h(r) = \text{some constant } h \text{ for } r > R.$$

Also, c(r) is integer valued, so we can find a sequence  $r_i \to \infty$  with

$$c(r_i) = c = \liminf c(r) < \infty.$$

Let  $A_i$  be the union of  $\Omega_{r_i}$  with those connected components of  $M - \Omega_{r_i}$  which happen to be compact. (There may not be any, in which case  $A_i = \Omega_{r_i}$ .) Let  $h(A_i)$  and  $c(A_i)$ denote the number of handles and boundary components, respectively, of  $A_i$ . Then

$$h = h(\Omega_{r_i}) \le h(A_i) \le h(\Omega_{r_{i+1}}) = h$$

provided j is large enough that  $A_i \subset \Omega_{r_{i+j}}$ : so

$$h(A_i) \equiv h \tag{10.42}$$

and clearly  $c(A_i) \leq c(\Omega_{r_i})$ . By passing to a subsequence we may assume

$$c(A_i) \equiv c' \ (\le c). \tag{10.43}$$

By (10.42) and (10.43), the  $A_i$  are homeomorphic, with  $A_{i+1}$  obtained from  $A_i$  by attaching annuli. The result follows immediately.

Since for minimal surfaces  $K \leq 0$  on M, we know that a complete minimal surface of finite total curvature has finite topology. We are interested in the conformal structure of M. Now since M has finite topology,  $M = S_k - (\{p_1, \dots, p_n\} \cup \bigcup_{i=1}^l U_i)$  as a Riemann surface, where  $U_i \subset S_k$  is conformally a closed disk. Furthermore, there are disjoint conformal open disks  $D_i \subset S_k$ ,  $i = 1, \dots, n + l$ , such that  $p_i \in D_i$ ,  $i = 1, \dots, n$ , and  $U_i \subset D_{i+n}$ ,  $i = 1, \dots, l$ , and the boundaries  $\partial D_i$  are mutually disjoint analytic Jordan curves. See, for example, [1], I 44D and II 3B. Hence each  $\overline{D}_{i+n} - U_i$  is conformally a doubly connected plane domain, which must be conformally equivalent to some

$$\tilde{A}_R := \{ z \in \mathbb{C} \mid 1/R \le |z| < R \}$$

with  $1 < R < \infty$ .

Let  $\phi: \overline{D}_{i+n} - U_i \to \widetilde{A}_R$  be a conformal diffeomorphism. Since X is complete with finite total curvature,  $X \circ \phi^{-1}$  is a complete minimal annulus with finite total curvature, where completeness of  $X \circ \phi^{-1}$  means for any curve  $\gamma: I \to A_R$  diverging to |z| = R, the arc length  $\Gamma$  of  $\gamma$  is infinity. We will prove that such a complete minimal annulus does not exist and hence  $M = S_k - \{p_1, \dots, p_n\}$ .

Actually, we will prove  $M = S_k - \{p_1, \dots, p_n\}$  by showing that for any  $\tilde{A}_R$  there is no complete Riemannian metric which is conformal to the Euclidean metric and has non-positive Gauss curvature and finite total curvature. If there were a closed disk  $U_i$  removed from  $S_k$ , the induced metric on some  $\tilde{A}_R$  by  $X \circ \phi^{-1}$  would be a complete Riemannian metric which is conformal to the Euclidean metric and has non-positive Gauss curvature and finite total curvature. Thus we know that it must be the case that  $M = S_k - \{p_1, \dots, p_n\}$ .

By the way, since there do exist complete minimal annuli  $Y: D^* \hookrightarrow \mathbb{R}^3$ , we see that  $D^*$  is not conformally equivalent of any  $A_R$  or  $\tilde{A}_R$  as mentioned in the last section.

First we give an easy lemma which uses the special structure of  $\tilde{A}_R$ . The proof is left as an exercise.

**Lemma 10.5** If  $g_{ij} = \lambda^2 \delta_{ij}$  is a complete Riemannian metric on  $\tilde{A}_R$ , then  $\tilde{g}_{ij}(z) := \lambda^2(z)\lambda(1/z)\delta_{ij}$  is a complete Riemannian metric on  $\hat{A}_R := \{1/R < |z| < R\}$ .

Next we prove that if  $\lambda = e^h$  and h is harmonic, then  $\lambda^2 \delta_{ij}$  on  $\tilde{A}_R$  cannot be complete.

**Proposition 10.6** Suppose  $D \subset \mathbf{C}$  and  $g_{ij} = e^{2h} \delta_{ij}$  is a complete Riemannian metric on D. If  $\triangle h = 0$ , then conformally D is either  $\mathbf{C} - \{0\}$  or  $\mathbf{C}$ .

**Proof.** Consider the conformal universal covering  $\pi: \tilde{D} \subset \mathbf{C} \to D$ . Since  $\pi$  is holomorphic,  $\tilde{h}(z) = h(\pi(z))$  is harmonic. Furthermore,  $\tilde{g}_{ij} = e^{2\tilde{h}}\delta_{ij}$  is a complete Riemannian metric on  $\tilde{D}$ . Since  $\tilde{D}$  is simply connected, there is a harmonic function  $\tilde{k}$  conjugate to  $\tilde{h}$ . Define a holomorphic function  $w: \tilde{D} \to \mathbf{C}$  by

$$w(z) = \int_0^z e^{\tilde{h}(\zeta) + i\tilde{k}(\zeta)} d\zeta.$$

Since  $\tilde{D}$  is simply connected, w is well defined.

First we claim that w sends a geodesic into a straight line. In fact, the induced metric by w from the Euclidean metric on  $\mathbf{C}$  is  $|w'|^2 \delta_{ij} = e^{2\tilde{h}} \delta_{ij} = \tilde{g}_{ij}$ . Hence the metric  $\tilde{g}$  is the first fundamental form of the surface  $w: \tilde{D} \to \mathbf{C} \subset \mathbf{R}^3$  and  $w: (\tilde{D}, \tilde{g}) \to (\mathbf{C}, \bullet)$  is an isometry. Let  $\gamma$  be a geodesic on  $\tilde{D}$ , then  $w \circ \gamma$  is a plane geodesic of  $w(\tilde{D}) \subset \mathbf{C}$ , and thus  $w \circ \gamma$  must be a straight line segment in  $\mathbf{C}$ .

Next we prove that w is one to one and onto. Let  $\gamma:[0,\infty)\hookrightarrow \tilde{D}$  be a geodesic ray of unit speed on  $\tilde{D}$ . Then  $(w\circ\gamma)'(t)=w'(\gamma(t))\,\gamma'(t)=\rho(t)e^{i\theta(t)}\neq 0$ , since w' and  $\gamma'$  are both non-zero. Since  $\gamma$  is unit speed,  $1=|\gamma'(t))|_{\tilde{g}}=|(w\circ\gamma)'(t)|=\rho(t)$ . Since  $w\circ\gamma$  is a straight line segment,  $\theta(t)$  must be a constant, say  $\theta_0$ . Thus we can write

$$w(\gamma(t)) = w(\gamma(0)) + te^{i\theta_0}.$$

This proves that w sends any geodesic ray one to one and onto a ray in  $\mathbb{C}$ .

Now by completeness,  $\tilde{D}$  is the union of all geodesic rays starting from 0. Since w is locally a conformal diffeomorphism, different geodesic rays starting from 0 are mapped by w one to one and onto different rays starting from  $w(\gamma(0)) \in \mathbb{C}$ , thus w must be one to one and onto  $\mathbb{C}$ .

Now  $w: \tilde{D} \to \mathbf{C}$  is a conformal diffeomorphism, so  $\tilde{D} = \mathbf{C}$ . Since the conformal universal covering of D is  $\mathbf{C}$ , conformally D must be either  $\mathbf{C}$  or  $\mathbf{C} - \{0\}$ .

Now we have to use the facts that  $X: M \hookrightarrow \mathbb{R}^3$  has finite total curvature and  $\tilde{A}_R$  is hyperbolic in order to construct a complete metric  $e^{2h}\delta_{ij}$  on  $A_R$  such that h is harmonic.

**Proposition 10.7** Let  $D \subset \mathbf{C}$  be a hyperbolic domain and  $g_{ij} = \lambda^2 \delta_{ij}$  a Riemannian metric on D, such that  $\triangle \log \lambda \ge 0$  and

$$\int_{D} \triangle \log \lambda \, dx \, dy < \infty. \tag{10.44}$$

Then there is a harmonic function h such that  $\log \lambda \leq h$ .

**Proof.** Since D is a hyperbolic domain, there is a Green's function  $G(\zeta, z)$  on D for any  $\zeta \in D$  which is positive except at  $\zeta$  and such that  $G(\zeta, z) + \log |z - \zeta|$  is a harmonic function on D. Since  $\Delta \log \lambda \in L^1(D)$ ,

$$u(\zeta) := \frac{1}{2\pi} \int_D G(\zeta, z) \triangle \log \lambda \, dx \, dy$$

solves the Poisson equation  $\Delta u = -\Delta \log \lambda$ . Note that  $u \geq 0$ ,  $h = u + \log \lambda \geq \log \lambda$  is the desired harmonic function.

Now by Lemma 10.5 the induced metric by  $X \circ \phi^{-1}$  on  $\tilde{A}_R$  is  $\Lambda^2 g_{ij}$ . Then the Gauss curvature is

 $K = -\frac{\triangle \log \Lambda}{\Lambda^2}.$ 

Since  $K \leq 0$ , we know that  $\Delta \log \Lambda \geq 0$  is non-negative. Moreover, since

$$K(\tilde{A}_R) = \int_{\tilde{A}_R} K dA = -\int_{\tilde{A}_R} \frac{\Delta \log \Lambda}{\Lambda^2} \Lambda^2 dx dy = -\int_{\tilde{A}_R} \Delta \log \Lambda dx dy,$$

condition (10.44) is equivalent to  $X \circ \phi^{-1}$  having finite total curvature. So we have a harmonic function  $h \ge \log \Lambda$ . Thus

$$\log \Lambda(z) + \log \Lambda(1/z) \le H(z) := h(z) + h(1/z).$$

Obviously  $e^{2H}\delta_{ij}$  is a complete Riemannian metric on  $\hat{A}_R$ . Since H(z) = h(z) + h(1/z) is harmonic, by Proposition 10.6 we have  $R = \infty$ , a contradiction. This contradiction proves the first part of the following theorem due to Osserman:

**Theorem 10.8 (Osserman, [66])** Let M be a Riemann surface without boundary and  $X: M \hookrightarrow \mathbf{R}^3$  a complete minimal surface such that the total curvature K(M) is finite. Then

- 1. There exists a closed Riemann surface  $S_k$  and a finite number of points  $p_1, \ldots, p_r$  on  $S_k$  such that M is conformally  $S_k \{p_1, \ldots, p_r\}$ ;
- 2. The Gauss map  $g: M \to \Sigma$  can be extended to  $S_k$  such that the extension  $\tilde{g}: S_k \to \Sigma$  is a holomorphic function. Moreover,

$$K(M) = -4\pi \deg g. \tag{10.45}$$

Recall that if  $g: S_k \to \mathbb{C}$  is a meromorphic function, where  $S_k$  is a closed Riemann surface, then there is a positive integer n such that for all but finitely many  $p \in \mathbb{C}$ ,  $g^{-1}(p) \subset S_k$  consists of n points. We say that g has degree n, and denote this by  $\deg g = n$ .

**Proof.** Since we have proved the first part, we only need prove the second part. Recall that

$$K = -\frac{16|g'|^2}{|f|^2(1+|g|^2)^4}$$
 and  $\Lambda^2 = \frac{1}{4}|f|^2(1+|g|^2)^2$ .

Recall that  $\tau^{-1}: \mathbb{C} \to S^2$  is a complex chart of  $S^2$ . In this chart the volume form of  $S^2$  is

$$dS(w) = \frac{4}{(1+|w|^2)^2} du \wedge dv$$

where  $w = u + iv \in \mathbb{C}$ . Obviously

$$\int_{S^2} dS = \int_{\mathbf{C}} dS(w) = 4\pi.$$

Let U be a coordinate neighbourhood in M on which g has no pole. Since g is holomorphic,  $|g'|^2 = \det Dg$ , where we interpret g as  $g: U \to \mathbb{R}^2$ . The induced metric by  $g: U \to (\mathbb{C}, dS)$  has the volume form

$$g^*(dS) = \frac{4 \det Dg}{(1 + |g|^2)^2} dx \, dy.$$

Since  $g^*(dS)$  is well defined on  $M - g^{-1}(\infty)$  (in fact on M), by

$$\int_{U} K dA = \int_{U} K \Lambda^{2} dx \wedge dy = -\int_{U} \frac{4|g'|^{2}}{(1+|g|^{2})^{2}} dx \wedge dy$$
$$= -\int_{U} \frac{4 \det Dg}{(1+|g|^{2})^{2}} dx \wedge dy = -\int_{U} g^{*}(dS)$$

we have

$$\int_{M} K dA = -\int_{M} g^{*}(dS).$$

Thus by the area formula we finally get

$$\int_{M} g^{*}(dS) = \int_{\mathbf{C}} \sharp \{g^{-1}(w)\} dS(w) = 4\pi \deg g,$$

where  $\sharp\{g^{-1}(w)\}$  is the number of points in  $g^{-1}(w)$ . Since g is meromorphic, for almost every  $w \in \mathbb{C}$ ,  $\sharp\{g^{-1}(w)\} = \deg g$ . The proof is complete.

**Corollary 10.9** If  $X: M \hookrightarrow \mathbf{R}^3$  is a non-planar complete minimal surface of finite total curvature, then the Gauss map  $g: M \to \mathbf{C}$  can miss at most a finite number of points of  $\mathbf{C}$ .

**Proof.** Since g can be extended to a closed Riemann surface  $S_k$  and g is not a constant, (otherwise X will be contained in a plane) we know that  $g(S_k) = \mathbb{C} \cup \{\infty\}$ . Now  $M = S_k - \{p_1, \dots, p_r\}$ , so  $\mathbb{C} - g(M)$  has at most a finite number of points.  $\square$ 

**Corollary 10.10 (Bernstein's Theorem)** Let  $u : \mathbf{R}^2 \to \mathbf{R}$  be a solution to the minimal surface equation. Then u is an affine function, i.e., u(x,y) = ax + by + c where a, b, and c are constants.

**Proof.** If u is not affine, then the graph of u is a non-planar complete minimal surface S of conformal type  $\mathbf{C} = S^2 - \{(0,0,1)\}$ . In fact, the special isothermal coordinate in Section 5,  $(\xi,\eta): \mathbf{R}^2 \to \mathbf{R}^2$ , is one to one and onto  $\mathbf{R}^2$ . If S has infinite total curvature, then the Gauss map g of S has an essential singularity at  $\infty$ , and hence g misses at most one point in  $\mathbf{C}$ . If S has finite total curvature and is non-planar, then Corollary 10.9 tells us that g misses at most a finite number of points of  $\mathbf{C}$ . But since S is a graph,

 $N = \frac{1}{(1 + u_x^2 + u_y^2)^{1/2}} \left( -u_x, -u_y, 1 \right)$ 

misses the lower hemisphere of  $S^2$ . This contradiction shows that S must be planar and forces  $g \equiv \text{constant}$ , and hence  $u_x$  and  $u_y$  must be constant and u must be affine.  $\square$