

## On ideal boundaries of some Coxeter groups

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### Abstract.

If a group acts geometrically (i.e., properly discontinuously, co-compactly and isometrically) on two geodesic spaces  $X$  and  $X'$ , then an automorphism of the group induces a quasi-isometry  $X \rightarrow X'$ . We find a geometric action of a Coxeter group  $W$  on a CAT(0) space  $X$  and an automorphism  $\phi$  of  $W$  such that the quasi-isometry  $X \rightarrow X$  arising from  $\phi$  can not induce a homeomorphism on the boundary of  $X$  as in the case of Gromov-hyperbolic spaces.

### §1. Introduction

In the study of Gromov-hyperbolic spaces, it is well-known that for two proper Gromov-hyperbolic geodesic spaces  $X, X'$ , if there exists a quasi-isometry  $F : X \rightarrow X'$ , then it induces a homeomorphism between their ideal boundaries ([BH, III.H.3.9]). We explain the homeomorphism between their ideal boundaries. For a geodesic ray  $\gamma$  in  $X$  there always exists a geodesic ray  $\gamma'$  such that the Hausdorff distance between  $F(\gamma)$  and  $\gamma'$  is finite, therefore we define a map  $\bar{F} : \partial X \ni \gamma(\infty) \mapsto \gamma'(\infty) \in \partial X'$ . Here, we denote by  $\gamma(\infty)$  the equivalence class of a geodesic ray  $\gamma$ . Then the map  $\bar{F}$  is a homeomorphism between the ideal boundaries.

In the case of CAT(0) spaces, Croke–Kleiner [CK] proved that there exists a group acting geometrically on two CAT(0) spaces whose ideal boundaries are not homeomorphic to each other. Bowers–Ruane [BR] found two distinct geometric actions of  $F_2 \times \mathbb{Z}$  on a CAT(0) space  $X$  and a quasi-isometry  $F : X \rightarrow X$  (which is equivariant under the two actions) such that there exists a geodesic ray  $\gamma$  in  $X$  whose image  $F(\gamma)$  does not have finite Hausdorff distance from any geodesic ray in  $X$ . Therefore,  $F$  can not induce a homeomorphism on  $\partial X$  in the same way as in the case of Gromov-hyperbolic spaces.

On the other hand, it is known that Coxeter groups act geometrically on some CAT(0) spaces ([M]). Let  $W$  be a Coxeter group having a

presentation

$$W = \langle t_1, \dots, t_5 \mid t_i^2 = e \ (i = 1, \dots, 5), t_j t_k = t_k t_j \ (j = 1, 2, 3, k = 4, 5) \rangle,$$

and let  $(X, d)$  be the CAT(0) space defined in [M] on which  $W$  acts geometrically. Let  $\phi$  be an automorphism on  $W$  defined by

$$t_i \mapsto t_i \ (i \neq 3), \quad t_3 \mapsto t_1 t_3 t_1.$$

We give  $W$  a word metric  $d_S$  associated to the generating set  $S = \{t_1, t_2, \dots, t_5\}$ . Then for any choice of a basepoint  $x_0 \in X$ , there exists a quasi-isometry  $f : (W, d_S) \ni w \mapsto w \cdot x_0 \in (X, d)$  ([BH, I.8.19]), and the automorphism  $\phi : W \rightarrow W$  is in fact a quasi-isometry  $(W, d_S) \rightarrow (W, d_S)$ . Therefore,  $F = f \circ \phi \circ f^{-1} : (X, d) \rightarrow (X, d)$  is also a quasi-isometry. In this paper, we will prove the following theorem.

**Theorem 1.1.** *We have a geodesic ray  $\gamma$  in  $X$  such that there exist no geodesic rays in  $X$  whose Hausdorff distance from  $F(\gamma)$  is finite.*

By Theorem 1.1 we know that the quasi-isometry  $F : X \rightarrow X$  can not induce a homeomorphism  $\partial X \rightarrow \partial X$  in the same way as in the case of Gromov-hyperbolic spaces.

## §2. CAT(0) spaces and Coxeter groups

We shall recall terminologies about CAT(0) spaces and Coxeter groups. We refer to [BH] about CAT(0) spaces.

**Definition 2.1.** For a metric space  $(X, d)$ , a *geodesic* from  $x \in X$  to  $y \in X$  is a map  $\gamma : [0, l] \rightarrow X$  such that

$$l = d(x, y), \quad \gamma(0) = x, \quad \gamma(l) = y,$$

$$d(\gamma(t), \gamma(t')) = |t - t'| \quad (\forall t, t' \in [0, l]).$$

We denote the image in  $X$  of a geodesic from  $x$  to  $y$  by  $[x, y]$  if we do not specify a choice of such geodesics joining  $x$  and  $y$ , and call it a *geodesic segment*. We call  $(X, d)$  a *geodesic space* if every two points in  $X$  can be joined by a (not necessarily unique) geodesic.

**Definition 2.2.** Given a geodesic space  $(X, d)$  and  $a, b, c \in X$ , we denote by  $\Delta(a, b, c)$  a geodesic triangle whose vertexes are  $a, b, c$ , and sides are geodesic segments  $[a, b], [b, c], [c, a]$ .

For any geodesic triangle  $\Delta(a, b, c)$  in  $X$ , we can construct a geodesic triangle  $\bar{\Delta}(\bar{a}, \bar{b}, \bar{c})$  in the 2-dimensional Euclidean space  $\mathbb{E}^2$  such that  $d_{\mathbb{E}^2}(\bar{a}, \bar{b}) = d(a, b)$ ,  $d_{\mathbb{E}^2}(\bar{b}, \bar{c}) = d(b, c)$  and  $d_{\mathbb{E}^2}(\bar{c}, \bar{a}) = d(c, a)$ . Here,  $d_{\mathbb{E}^2}$

is a standard metric on  $\mathbb{E}^2$ . We call  $\overline{\Delta}(\overline{a}, \overline{b}, \overline{c})$  a *comparison triangle* of  $\Delta(a, b, c)$ .

Let  $x$  be a point in  $[a, b]$ . A point  $\overline{x}$  in  $[\overline{a}, \overline{b}]$  is called a *comparison point* of  $x$  if  $d_{\mathbb{E}^2}(\overline{a}, \overline{x}) = d(a, x)$ . In the case of  $x \in [b, c]$  or  $x \in [c, a]$ , we define a comparison point of  $x$  in the same way.

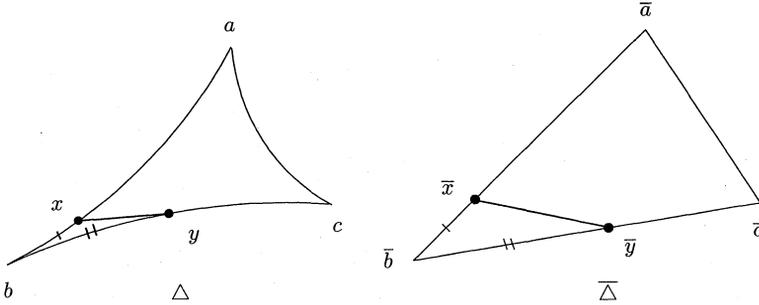


Fig. 1. A geodesic triangle and its comparison triangle

**Definition 2.3.** Let  $\Delta$  be a geodesic triangle in a geodesic space  $(X, d)$ , and  $\overline{\Delta}$  a comparison triangle of  $\Delta$ . If for any  $x, y \in \Delta$  and their comparison points  $\overline{x}, \overline{y} \in \overline{\Delta}$ , the inequality

$$d(x, y) \leq d_{\mathbb{E}^2}(\overline{x}, \overline{y})$$

holds, then we call  $(X, d)$  a *CAT(0) space*.

It is easy to see that for any points  $x, y$  in a CAT(0) space, there exists a unique geodesic joining  $x$  and  $y$ .

**Definition 2.4.** For a metric space  $(X, d)$ , we call  $(X, d)$  a *proper* metric space if for every  $x \in X$  and every  $r > 0$ , the closed ball  $\overline{B}(x, r)$  is compact.

Let  $(X, d)$  be a proper CAT(0) space. If a map  $\gamma : [0, \infty) \rightarrow X$  satisfies

$$d(\gamma(t), \gamma(t')) = |t - t'| \quad (\forall t, t' \in [0, \infty)), \quad \gamma(0) = x_0,$$

then  $\gamma$  is called a *geodesic ray* from  $x_0$ .

Two geodesic rays  $\gamma, \gamma' : [0, \infty) \rightarrow X$  are said to be *asymptotic* if there exists a constant  $K$  such that  $d(\gamma(t), \gamma'(t)) \leq K$  for all  $t \geq 0$ . We give an equivalence relation on the set of geodesic rays in  $X$  such that

two geodesic rays are equivalent if and only if they are asymptotic. We denote by  $\partial X$  the set of equivalence classes of geodesic rays in  $X$ , and give the cone topology on  $\partial X$  (see [BH, II.8.6] for the definition of the topology).

**Definition 2.5.** Let  $(X_1, d_1)$  and  $(X_2, d_2)$  be complete CAT(0) spaces,  $X$  the product  $X_1 \times X_2$ , and define a metric  $d$  on  $X$  by  $d = \sqrt{d_1^2 + d_2^2}$ . Let  $\gamma_1(\infty)$  (resp.  $\gamma_2(\infty)$ ) be the equivalence class of a geodesic ray  $\gamma_1$  in  $X_1$  (resp.  $\gamma_2$  in  $X_2$ ).

If  $\theta \in [0, \pi/2]$ , we denote by  $(\cos \theta)\gamma_1(\infty) + (\sin \theta)\gamma_2(\infty)$  the point of  $\partial X$  represented by the geodesic ray  $\gamma(t) = (\gamma_1(t \cos \theta), \gamma_2(t \sin \theta))$  in  $X$ . The *spherical join*  $\partial X_1 * \partial X_2$  is the quotient of the product  $\partial X_1 \times [0, \pi/2] \times \partial X_2$  by the equivalence relation identifying  $(\gamma_1(\infty), \theta, \gamma_2(\infty))$  with  $(\gamma'_1(\infty), \theta', \gamma'_2(\infty))$  if and only if either of the following conditions are satisfied:

- (1)  $\gamma_1(\infty) = \gamma'_1(\infty), \theta = \theta'$  and  $\gamma_2(\infty) = \gamma'_2(\infty)$ ;
- (2)  $\theta = \theta' = 0$  and  $\gamma_1(\infty) = \gamma'_1(\infty)$ ;
- (3)  $\theta = \theta' = \pi/2$  and  $\gamma_2(\infty) = \gamma'_2(\infty)$ .

It is easy to see that the boundary  $\partial X$  is homeomorphic to the spherical join  $\partial X_1 * \partial X_2$ .

**Definition 2.6.** Let  $(X, d)$  be a metric space. For a subset  $A \subset X$  and a positive number  $k$ , we denote the  $k$ -neighbourhood of  $A$  by

$$\mathcal{N}_k(A) = \{x \in X \mid \exists a \in A \text{ s.t. } d(x, a) \leq k\}.$$

For subsets  $A, B \subset X$ , the *Hausdorff distance* between  $A$  and  $B$  is defined by

$$d_H(A, B) = \inf\{k \mid A \subseteq \mathcal{N}_k(B), B \subseteq \mathcal{N}_k(A)\}.$$

**Definition 2.7.** Let  $(X, d)$  and  $(X', d')$  be metric spaces. If a map  $f : X \rightarrow X'$  satisfies that there exist  $\varepsilon, k \geq 0, \lambda \geq 1$  such that

$$\frac{1}{\lambda}d(x, y) - \varepsilon \leq d'(f(x), f(y)) \leq \lambda d(x, y) + \varepsilon \quad (\forall x, y \in X),$$

$$\mathcal{N}_k(\text{Im} f) = X',$$

then  $f$  is called a  $(\lambda, \varepsilon)$ -*quasi-isometry*. If we do not specify the values  $\lambda, \varepsilon$ , then we call  $f$  a *quasi-isometry* simply.

We note that if there exists a  $(\lambda, \varepsilon)$ -quasi-isometry  $f : X \rightarrow X'$ , then there exists a  $(\lambda', \varepsilon')$ -quasi-isometry  $f^{-1} : X' \rightarrow X$  (for some  $\lambda', \varepsilon'$ ) and a constant  $k' \geq 0$  such that  $d(f \circ f^{-1}(x'), x') \leq k'$  and  $d(f^{-1} \circ f(x), x) \leq k'$  for all  $x' \in X'$  and all  $x \in X$ . We call  $f^{-1}$  a *quasi-inverse* for  $f$ .

Finally, we recall the definition of Coxeter groups.

**Definition 2.8.** A Coxeter group  $W$  is a finitely presented group having the following presentation:

$$W = \langle S \mid (ss')^{m(s,s')} = e \text{ for } \forall s, s' \in S \rangle,$$

where  $S$  is a non-empty finite set and  $m : S \times S \rightarrow \mathbb{N} \cup \{\infty\}$  is a function satisfying the following conditions:

- (1)  $m(s, s) = 1$  for  $\forall s \in S$ ;
- (2)  $m(s, s') = m(s', s)$  for  $\forall s, s' \in S$ ;
- (3)  $m(s, s') \geq 2$  for  $\forall s \neq s' \in S$ .

Here, for  $s, s' \in S$ ,  $m(s, s') = \infty$  means that there exists no relation between  $s$  and  $s'$ .

**§3. Proof of the main theorem**

In the following context, let  $W$  be the Coxeter group whose presentation is given by

$$W = \langle t_1, \dots, t_5 \mid t_i^2 = e \ (i = 1, \dots, 5), t_j t_k = t_k t_j \ (j = 1, 2, 3, k = 4, 5) \rangle.$$

Let  $H$  be the subgroup of  $W$  generated by  $t_1, t_2$  and  $t_3$ , and let  $H'$  be the subgroup of  $W$  generated by  $t_4, t_5$ .

By the presentation of  $W$ , we know that

$$\begin{aligned} W &= H \times H' \\ &\cong (\mathbb{Z}_2 * \mathbb{Z}_2 * \mathbb{Z}_2) \times (\mathbb{Z}_2 * \mathbb{Z}_2). \end{aligned}$$

Define an automorphism  $\phi$  of  $W$  by

$$t_i \mapsto t_i \ (i \neq 3), \quad t_3 \mapsto t_1 t_3 t_1.$$

(Especially,  $\phi$  is an isomorphism of the Coxeter system.)

Let  $T$  be the Cayley graph of the group  $H$  with respect to the generating set  $\{t_1, t_2, t_3\}$ , which is a regular tree of valence 3. The Cayley graph of the group  $H'$  with respect to a generating set  $\{t_4, t_5\}$  is isometric to  $\mathbb{R}$  where the vertex set of this graph corresponds to  $\mathbb{Z}$ . Therefore, we call this graph  $\mathbb{R}$ .

Let  $X$  be the product  $T \times \mathbb{R}$ . Let  $d_T$  (resp.  $d_{\mathbb{R}}$ ) be a metric on the Cayley graph  $T$  (resp.  $\mathbb{R}$ ). A metric  $d$  on  $X$  is defined by

$$d((t, r), (t', r')) = \sqrt{d_T(t, t')^2 + d_{\mathbb{R}}(r, r')^2} \quad (\forall t, t' \in T, \forall r, r' \in \mathbb{R}).$$

Then  $X$  is a proper CAT(0) space and is called the Davis–Vinberg complex of  $W$ . The Coxeter group  $W$  acts geometrically (i.e., properly discontinuously, cocompactly and isometrically) on  $X$  ([M]).

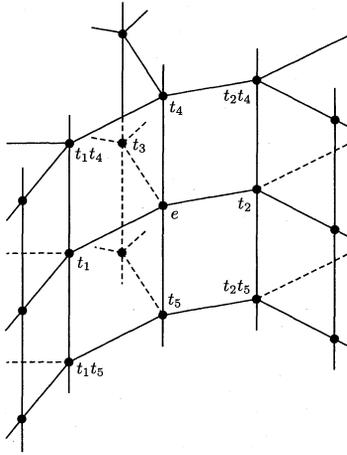


Fig. 2.  $T \times \mathbb{R}$

We give  $W$  a word metric  $d_S$  with respect to the generating set  $S = \{t_1, t_2, \dots, t_5\}$ . Let  $e \in X$  be the vertex corresponding to the unit element. Then there exists a quasi-isometry  $f : (W, d_S) \ni w \mapsto w \cdot e \in X$  ([BH, I.8.19]). We can take a quasi-inverse  $f^{-1} : X \rightarrow W$  satisfying that for any  $w \in W$ ,  $f^{-1}(w \cdot e) = w$ .

The ideal boundary of  $T$  is a Cantor set and the ideal boundary of  $\mathbb{R}$  consists of two points. Therefore, the ideal boundary of  $X$  is the spherical join of the Cantor set and the set of two points. Since the automorphism  $\phi$  on  $W$  is in fact a quasi-isometry  $(W, d_S) \rightarrow (W, d_S)$ , and  $f : (W, d_S) \rightarrow (X, d)$  is also a quasi-isometry, so is  $F = f \circ \phi \circ f^{-1} : X \rightarrow X$ .

**Theorem 3.1.** *We have a geodesic ray  $\gamma$  in  $X$  such that there exist no geodesic rays in  $X$  whose Hausdorff distance from  $F(\gamma)$  is finite.*

*Proof.* Put  $a = t_1t_2$ ,  $b = t_3t_2$ ,  $c = t_4t_5$  and  $b' = t_1t_3t_1t_2$ . We note that  $c$  commutes with  $a$ ,  $b$  and  $b'$ . Then

$$F(a) = f \circ \phi \circ f^{-1}(a \cdot e) = f \circ \phi(a) = f(a) = a \cdot e = a,$$

$$F(b) = f \circ \phi \circ f^{-1}(b \cdot e) = f \circ \phi(b) = f(b') = b' \cdot e = b',$$

$$F(c) = f \circ \phi \circ f^{-1}(c \cdot e) = f \circ \phi(c) = f(c) = c \cdot e = c.$$

Let  $\gamma$  be a piecewise geodesic path in  $X$  such that

$$[e, ac] \cup [ac, abc^2] \cup [abc^2, abac^3] \cup [abac^3, ababc^4] \cup [ababc^4, abab^2c^5] \cup \dots$$

$$\cup [abab^2 \dots ab^{n-1} c^{\frac{n(n+3)}{2}-1}, abab^2 \dots ab^n c^{\frac{n(n+3)}{2}}] \cup \dots$$

The piecewise geodesic path  $\gamma$  is in fact a geodesic ray in  $X$  because the projection of  $\gamma$  onto  $T$  is a geodesic ray passing through  $e, a, ab, aba, abab, abab^2, \dots, abab^2 ab^3 \dots ab^n, \dots$ , where the distance between successive two points is equal to 2, and the projection of  $\gamma$  onto  $\mathbb{R}$  is also geodesic ray passing through  $e, c, c^2, \dots, c^n, \dots$ , where the distance between successive two points is equal to 2.

Put  $A_n = ab'ab'^2 ab'^3 \dots ab'^n c^{\frac{n(n+3)}{2}}$ . Then  $F(\gamma)$  passes through each  $A_n$  ( $n \in \mathbb{N}$ ). We will deduce a contradiction under the assumption that there exists a geodesic ray  $\gamma'$  such that the Hausdorff distance between  $\gamma'$  and  $F(\gamma)$  is finite.

For each  $n \in \mathbb{N}$ , the Hausdorff distance between  $\gamma'$  and a geodesic segment  $[e, A_n]$  would be uniformly finite because  $F(\gamma)$  passes through  $e$  and  $A_n$ .

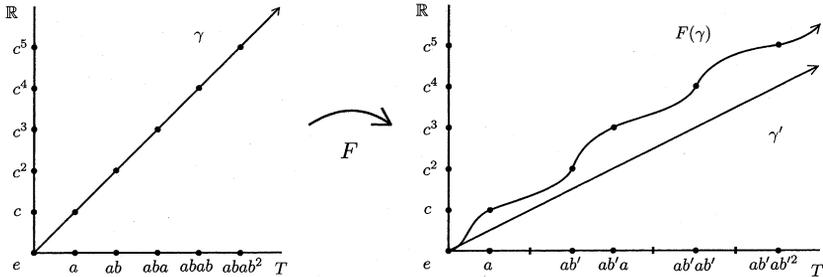


Fig. 3.  $\gamma$  and  $F(\gamma)$

Next, we consider the slope of the geodesic segment  $[e, A_n]$ . Note that the projections of  $A_n$  onto  $T$  and  $\mathbb{R}$  are equal to  $ab'ab'^2 ab'^3 \dots ab'^n$  and  $c^{\frac{n(n+3)}{2}}$ , respectively. It is easy to see that

$$d_T(e, ab'ab'^2 ab'^3 \dots ab'^n) = 2n(n + 2),$$

$$d_{\mathbb{R}}(e, c^{\frac{n(n+3)}{2}}) = n(n + 3).$$

Hence the slope of the geodesic segment  $[e, A_n]$  is  $n(n + 3)/2n(n + 2)$ . Then

$$\frac{n(n + 3)}{2n(n + 2)} \rightarrow \frac{1}{2} \quad (n \rightarrow \infty).$$

Therefore, the slope of  $\gamma'$  should be  $1/2$ .

Finally, we calculate the distance between  $A_n \in F(\gamma)$  and  $\gamma'$ . We take a geodesic  $\xi_n$  which passes through  $A_n$  and is orthogonal to  $\gamma'$ . The slope of  $\xi_n$  must be equal to  $-2$ . Let  $B_n$  be the intersection point of  $\xi_n$  and  $\gamma'$ , which is the closest point on  $\gamma'$  to  $A_n$ . The distance between  $e$  and the projection of  $B_n$  onto  $T$  is equal to  $2n(5n+11)/5$  and the distance between  $e$  and the projection of  $B_n$  onto  $\mathbb{R}$  is equal to  $n(5n+11)/5$ . Therefore, the distance between  $A_n$  and  $B_n$  is equal to  $2\sqrt{5}n/5$ . Then

$$\frac{2\sqrt{5}}{5}n \rightarrow \infty \quad (n \rightarrow \infty),$$

and therefore, the Hausdorff distance between  $\gamma'$  and  $F(\gamma)$  must be infinite, which is a contradiction.

Consequently, we can not obtain a geodesic ray whose Hausdorff distance from  $F(\gamma)$  is finite. Q.E.D.

### References

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