

APPENDIX A
A GENERAL REGULARITY THEOREM

We here prove a useful general regularity theorem, which is essentially an abstraction of the "dimension reducing" argument of Federer [FH2]. There are a number of important applications of this general theorem in the text.

Let $P \geq n \geq 2$ and let F be a collection of functions $\phi = (\phi^1, \dots, \phi^Q) : \mathbb{R}^P \rightarrow \mathbb{R}^Q$ ($Q=1$ is an important case) such that each ϕ^j is locally H^n -integrable on \mathbb{R}^P . For $\phi \in F$, $y \in \mathbb{R}^P$ and $\lambda > 0$ we let $\phi_{y,\lambda}$ be defined by

$$\phi_{y,\lambda}(x) = \phi(y + \lambda x), \quad x \in \mathbb{R}^P.$$

Also, for $\phi \in F$ and a given sequence $\{\phi_k\} \subset F$ we write $\phi_k \rightarrow \phi$ if $\int \phi_k f \, dH^n \rightarrow \int \phi f \, dH^n$ (in \mathbb{R}^Q) for each given $f \in C_c^0(\mathbb{R}^P)$.

We subsequently make the following 3 special assumptions concerning F :

A.1 (Closure under appropriate scaling and translation): If $|y| \leq 1 - \lambda$, $0 < \lambda < 1$, and if $\phi \in F$, then $\phi_{y,\lambda} \in F$.

A.2 (Existence of homogeneous degree zero "tangent functions"): If $|y| < 1$, if $\{\lambda_k\} \downarrow 0$ and if $\phi \in F$, then there is a subsequence $\{\lambda_{k_i}\}$ and $\psi \in F$ such that $\phi_{y,\lambda_{k_i}} \rightarrow \psi$ and $\psi_{0,\lambda} = \psi$ for each $\lambda > 0$.

A.3 ("Singular set" hypotheses): We assume there is a map

$$\text{sing} : F \rightarrow \mathcal{C} \quad (= \text{set of closed subsets of } \mathbb{R}^P)$$

such that

(1) $\text{sing } \phi = \emptyset$ if $\phi \in F$ is a constant multiple of the characteristic function of an n -dimensional subspace of \mathbb{R}^P ,

(2) if $|y| \leq 1-\lambda$, $0 < \lambda < 1$, then $\text{sing } \phi_{y,\lambda} = \lambda^{-1}(\text{sing } \phi - y)$,

(3) if $\phi, \phi_k \in F$ with $\phi_k \rightarrow \phi$, then for each $\varepsilon > 0$ there is a $k(\varepsilon)$ such that

$$B_1(0) \cap \text{sing } \phi_k \subset \{x \in \mathbb{R}^P : \text{dist}(\text{sing } \phi, x) < \varepsilon\} \quad \forall k \geq k(\varepsilon).$$

We can now state the main result of this section:

A.4 THEOREM *Subject to the notation and assumptions A.1, A.2, A.3 above, we have*

$$(*) \quad \dim B_1(0) \cap \text{sing } \phi \leq n-1 \quad \forall \phi \in F.$$

(Here "dim" is Hausdorff dimension, so that (*) means $H^{n-1+\alpha}(\text{sing } \phi) = 0$ $\forall \alpha > 0$.)

In fact either $\text{sing } \phi \cap B_1(0) = \emptyset$ for every $\phi \in F$ or else there is an integer $d \in [0, n-1]$ such that

$$\dim \text{sing } \phi \cap B_1(0) \leq d \quad \forall \phi \in F$$

and such that there is some $\psi \in F$ and a d -dimensional subspace $L \subset \mathbb{R}^P$ with

$$(**) \quad \psi_{y,\lambda} = \psi \quad \forall y \in L, \lambda > 0$$

and

$$\text{sing } \psi = L.$$

If $d = 0$ then $\text{sing } \phi \cap B_\rho(0)$ is finite for each $\phi \in F$ and each $\rho < 1$.

A.5 REMARK One readily checks that if L is an n -dimensional subspace of \mathbb{R}^P and $\psi \in F$ satisfies (**), then ψ is exactly a constant multiple of the characteristic function of L (hence $\text{sing } \psi = \emptyset$ by A.3(1)); otherwise we would have $P > n$ and $\psi \equiv \text{const.} \neq 0$ on some $(n+1)$ -dimensional half-space,

thus contradicting the fact that ψ is locally H^n -integrable on \mathbb{R}^P .

Proof of A.4 Assume $\text{sing } \phi \cap B_1(0) \neq \emptyset$ for some $\phi \in F$, and let $d = \sup\{\dim L : L \text{ is a } d\text{-dimensional subspace of } \mathbb{R}^P \text{ and there is } \phi \in F \text{ with } \text{sing } \phi \neq \emptyset \text{ and } \phi_{y,\lambda} = \phi \ \forall y \in L, \lambda > 0\}$. Then by Remark A.5 we have $d \leq n-1$.

For a given $\phi \in F$ and $y \in B_1(0)$ we let $T(\phi, y)$ be the set of $\psi \in F$ with $\psi_{0,\lambda} = \psi \ \forall \lambda > 0$ and with $\lim \phi_{y,\lambda_k} = \psi$ for some sequence $\lambda_k \downarrow 0$. ($T(\phi, y) \neq \emptyset$ by assumption A.2).

Let $\ell \geq 0$ and let

$$(1) \quad F^\ell = \{\phi \in F : H^\ell(\text{sing } \phi \cap B_1(0)) > 0\}.$$

Our first task is to prove the implication

$$(2) \quad \phi \in F^\ell \Rightarrow \exists \psi \in T(\phi, x) \cap F^\ell$$

for H^ℓ -a.e. $x \in \text{sing } \phi \cap B_1(0)$.

To see this, let H_δ^ℓ be the "size δ approximation" of H^ℓ as described in §2 and recall that $H_\delta^\ell(A) > 0 \Leftrightarrow H_\infty^\ell(A) > 0$, so that $F^\ell = \{\phi \in F : H_\infty^\ell(\text{sing } \phi \cap B_1(0)) > 0\}$. Also note that (by 3.6(2)), for any bounded subset A of \mathbb{R}^P ,

$$(3) \quad H_\infty^\ell(A) > 0 \Rightarrow \Theta^{*n}(H_\infty^\ell \llcorner A, x) > 0 \text{ for } H^\ell\text{-a.e. } x \in A.$$

Thus we see that if $\phi \in F^\ell$ then for H^ℓ -a.e. $x \in \text{sing } \phi \cap B_1(0)$ we have $\Theta^{*\ell}(H_\infty^\ell \llcorner \text{sing } \phi, x) > 0$. For such x we thus have a sequence $\lambda_k \downarrow 0$ such that

$$(4) \quad \lim_{k \rightarrow \infty} \frac{H_{\infty}^{\ell}(\text{sing} \phi \cap B_{\lambda_k}(x))}{\lambda_k^{\ell}} > 0,$$

and by assumption A.2 there is a subsequence $\{\lambda_k\}$ such that $\phi_{x, \lambda_k} \rightarrow \psi \in T(\phi, x)$. If now $H_{\infty}^{\ell}(\text{sing} \psi) = 0$, then for any $\varepsilon > 0$ we could find open balls $\{B_{\rho_j}(x_j)\}$ such that

$$(5) \quad \text{sing} \psi \subset \bigcup_j B_{\rho_j}(x_j)$$

and

$$(6) \quad \sum_j \omega_{\ell} \rho_j^{\ell} < \varepsilon$$

(by definition of H_{∞}^{ℓ}). Now (5) in particular implies that

$K \equiv \overline{B_1(0)} \sim \bigcup_j B_{\rho_j}(x_j)$ is a compact set with positive distance from $\text{sing} \psi$.

Hence by assumption A.3(3) we have

$$(7) \quad \text{sing} \phi_{x, \lambda_k} \cap B_1(0) \subset \bigcup_j B_{\rho_j}(x_j)$$

for all sufficiently large k , and hence by (6)

$$H_{\infty}^{\ell}(\text{sing} \phi_{x, \lambda_k} \cap B_1(0)) < \varepsilon, \quad k \geq k(\varepsilon).$$

Thus since $\lambda_k^{-1}(\text{sing} \phi - x) = \text{sing} \phi_{x, \lambda_k}$ (by A.3(2)) we have

$$\lambda_k^{-\ell} H_{\infty}^{\ell}(\text{sing} \phi \cap B_{\lambda_k}(x)) < \varepsilon$$

for all sufficiently large k , thus a contradiction for

$$\varepsilon < \lim_{k \rightarrow \infty} \lambda_k^{-\ell} H_{\infty}^{\ell}(\text{sing} \phi \cap B_{\lambda_k}(x)). \quad (\text{Such } \varepsilon \text{ can be chosen by (4).)}$$

We have therefore established the general implication (2). From now on take $\ell > d-1$ so that $F^\ell \neq \emptyset$ (which is automatic for $\ell \leq d$ by definition of d). By (2) there is $\phi \in F^\ell$ with $\phi_{0,\lambda} = \phi \quad \forall \lambda > 0$. Suppose also that there is a k -dimensional subspace ($k \geq 0$) S of \mathbb{R}^P such that $\phi_{y,\lambda} = \phi \quad \forall y \in S, \lambda > 0$. (Notice of course this is no additional restriction for ϕ in case $k=0$.) Now if $k \geq d+1$ then, by definition of d , we can assert $\text{sing } \phi = \emptyset$, thus contradicting the fact that $\phi \in F^\ell$. Therefore $0 \leq k \leq d$, and if $k \leq d-1$ ($< \ell$), then $H^\ell(S) = 0$ and in particular

$$(8) \quad \exists x \in B_1(0) \cap \text{sing } \phi \sim S.$$

But by A.2 we can choose $\psi \in T(\phi, x)$. Since $\psi = \lim \phi_{x,\lambda_j}$ for some sequence $\lambda_j \downarrow 0$, we evidently have (since $\phi_{y+x,\lambda} = \phi_{x,\lambda} \quad \forall y \in S, \lambda > 0$)

$$(9) \quad \psi_{y,1} = \lim \phi_{y+x,\lambda_j} = \lim \phi_{x,\lambda_j} = \psi \quad \forall y \in S$$

and

$$(10) \quad \psi_{\beta x,1} = \lim \phi_{x+\lambda_j \beta x,\lambda_j} = \psi \quad \forall \beta \in \mathbb{R}.$$

(All limits in the weak sense described at the beginning of the section.)

Thus $\psi_{z,\lambda} = \psi$ for each $\lambda > 0$ and each z in the $(k+1)$ -dimensional subspace T of \mathbb{R}^P spanned by S and x . $\text{Sing } \psi \neq \emptyset$ (by A.3(3)), hence by induction on k we can take $k = d-1$; i.e. $\dim T = d$, and hence $\text{sing } \psi \supset T$ by A.3(2). On the other hand if $\exists \tilde{x} \in \text{sing } \psi \sim T$ then we can repeat the above argument (beginning at (8)) with T in place of S and ψ in place of ϕ . This would then give a $(d+1)$ -dimensional subspace \tilde{T} and a $\tilde{\psi} \in F$ with $\text{sing } \tilde{\psi} \supset \tilde{T}$, thus contradicting the definition of d . Therefore $\text{sing } \phi = T$. Furthermore if $\ell > d$ then the above induction works up to $k = d$ and again therefore we would have a contradiction. Thus $\dim(B_1(0) \cap \text{sing } \phi) \leq d \quad \forall \phi \in F$.

Finally to prove the last claim of the theorem, we suppose that $d=0$.

Then we have already established that

$$(11) \quad H^\alpha(\text{sing } \phi \cap B_1(0)) = 0 \quad \forall \alpha > 0, \phi \in F.$$

If $\text{sing } \phi \cap B_\rho(0)$ is not finite, then we select $x \in \overline{B_\rho(0)}$ such that

$x = \lim x_k$ for some sequence $x_k \in \text{sing } \phi \cap B_1(0) \sim \{x\}$. Then letting

$\lambda_k = 2|x_k - x|$ we see from A.3(2) that there is a subsequence $\{\lambda_{k_i}\}$ with

$\phi_{x, \lambda_{k_i}} \rightarrow \psi \in T(\phi, x)$ and $(x_{k_i}, -x) / |x_{k_i} - x| \rightarrow \xi \in \partial B_1(0)$. Now by A.3(2), (3)

we know that $\{\xi/2\} \cap \{0\} \subset \text{sing } \psi$ and, since $\psi_{0, \lambda} = \psi$, this (together with

A.3(2)) gives $L_\xi \subset \text{sing } \psi$ where L_ξ is the ray determined by 0 and ξ .

Then $H^1(\text{sing } \psi \cap B_1(0)) > 0$, thus contradicting (11), because $\psi \in F$.

APPENDIX B

NON-EXISTENCE OF STABLE MINIMAL CONES, $2 \leq n \leq 6$.

Here we describe J. Simons [SJ] result on non-existence of n -dimensional stable minimal cones (previously established in case $n=2,3$ by Fleming [F] and Almgren [A4] respectively). The proof here follows essentially Schoen-Simon-Yau [SSY], and is slightly cleaner than the original proof in [SJ].

Suppose to begin that $C \in \mathcal{D}_n(\mathbb{R}^{n+1})$ is a cone ($\eta_{0,\lambda\#}C=C$) and C is integer multiplicity with $\partial C = 0$. If $\text{sing } C \subset \{0\}$ and if C is minimizing in \mathbb{R}^{n+1} then, writing $M = \text{spt } C \sim \{0\}$ and taking M_t as in §9, we have $\left. \frac{d}{dt} H^n(M_t) \right|_{t=0} = 0$ and $\left. \frac{d^2}{dt^2} H^n(M_t) \right|_{t=0} \geq 0$. (This is clear because in fact $H^n(M_t)$ takes its minimum value at $t=0$, by virtue of our assumption that C is minimizing.) Notice that M is orientable, with orientation induced from C , and hence in particular we can deduce from 9.8 that

$$\text{B.1} \quad \int_M (|\nabla^M \zeta|^2 - \zeta^2 |A|^2) dH^n \geq 0$$

for any $\zeta \in C_c^1(M)$ (notice $0 \notin M$, so such ζ vanish in a neighbourhood of 0). Here A is the second fundamental form of M and $|A|$ is its length, as described in §7 and in 9.8.

The main result we need is given in the following theorem.

B.2 THEOREM *Suppose $2 \leq n \leq 6$ and M is an n -dimensional cone embedded in \mathbb{R}^{n+1} with zero mean curvature (see §7) and with $\bar{M} \sim M = \{0\}$, and suppose that M is stable in the sense that B.1 holds. Then \bar{M} is a hyperplane.*

(As explained above, the hypotheses are in particular satisfied if

$M = \text{spt } C \sim \{0\}$, with $C \in \mathcal{D}_n(\mathbb{R}^{n+1})$ a minimizing cone with $\partial C = 0$ and $\text{sing } C \subset \{0\}$.)

B.3 REMARK Theorem B.2 is false for $n=7$; J. Simons [SJ] was the first to point out that the cone $M = \{(x^1, \dots, x^8) \in \mathbb{R}^8 : \sum_{i=1}^4 (x^i)^2 = \sum_{i=5}^8 (x^i)^2\}$ is a stable minimal cone. (Notice that M is the cone over the compact manifold $(\frac{1}{\sqrt{2}} S^3) \times (\frac{1}{\sqrt{2}} S^3) \subset S^7 \subset \mathbb{R}^8$.) The fact that the mean curvature of M is zero is checked by direct computation. The fact that M is actually *stable* is checked as follows. First, by direct computation one checks that the second fundamental form A of M satisfies $|A|^2 = 6/|x|^2$.

On the other hand for a stationary hypersurface $M \subset \mathbb{R}^{n+1}$ the first variation formula 9.3 says $\int \operatorname{div}_M X dH^n = 0$ if $\operatorname{spt}|X|$ is a compact subset of M . Taking $X_x = (\zeta^2/r^2)x$, $\zeta \in C_c^\infty(M)$, $r = |x|$, and computing as in §17, we get

$$(n-2) \int_M (\zeta^2/r^2) dH^n = -2 \int_M \zeta r^{-2} x \cdot \nabla^M \zeta dH^n.$$

Using the Schwartz inequality on the right we get

$$\frac{(n-2)^2}{4} \int_M (\zeta^2/r^2) dH^n \leq \int_M |\nabla^M \zeta|^2 dH^n.$$

Thus we have stability for M (in the sense of B.1) whenever A satisfies $|x|^2 |A|^2 \leq (n-2)^2/4$.

For the example above we have $n=7$ and $|x|^2 |A|^2 = 6$, so that this inequality is satisfied, and the cone over $S^3 \times S^3$ is stable as claimed. (Similarly the cone over $S^q \times S^q$ is stable for $q \geq 3$; i.e. when the dimension of the cone is ≥ 7 .)

Before giving the proof of B.2 we need to derive the identity of J. Simons for the Laplacian of the length of the second fundamental form of a hypersurface (Lemma B.8 below).

The simple derivation here assumes the reader's familiarity with basic Riemannian geometry. (A completely elementary derivation, assuming no such background, is described in [G].)

For the moment let M be an arbitrary hypersurface in \mathbb{R}^{n+1} (M not necessarily a cone, and not necessarily having zero mean curvature).

Let τ_1, \dots, τ_n be a locally defined family of smooth vector fields which, together with the unit normal ν of M , define an orthonormal basis for \mathbb{R}^{n+1} at all points in some region of M .

The second fundamental form of M relative to the unit normal ν is the tensor $A = h_{ij} \tau_i \otimes \tau_j$, where $h_{ij} = \langle D_{\tau_j} \nu, \tau_i \rangle$. (Cf. §7.) Recall that we have

$$\text{B.4} \quad h_{ij} = h_{ji},$$

and, since the Riemann tensor of \mathbb{R}^{n+1} is zero, we have the *Codazzi equations*

$$\text{B.5} \quad h_{ij,k} = h_{ik,j}, \quad i, j, k \in \{1, \dots, n\}.$$

Here $h_{ij,k}$ denotes the covariant derivative of A with respect to τ_k ; that is, $h_{ij,k}$ are such that $\nabla_{\tau_k} A = h_{ij,k} \tau_i \otimes \tau_j$.

We also have the *Gauss curvature equations*

$$\text{B.6} \quad R_{ijkl} = h_{il} h_{jk} - h_{ik} h_{jl},$$

where $R = R_{ijkl} \tau_i \otimes \tau_j \otimes \tau_k \otimes \tau_l$ is the Riemann curvature tensor of M , and where we use the sign convention such that R_{ijji} ($i \neq j$) are sectional curvatures of M ($= +1$ if $M = S^n$).

From the properties of R (in fact essentially by definition of R) we also have, for any 2-tensor $a_{ij} \tau_i \otimes \tau_j$,

$$a_{ij,kl} = a_{ij,lk} + a_{im}^R m_{jlk} + a_{mj}^R m_{ilk}$$

(where $a_{ij,kl}$ means $a_{ij,k,l}$ - i.e. the covariant derivative with respect to τ_l of the tensor $a_{ij,k} \tau_i \otimes \tau_j \otimes \tau_k$). In particular

$$\begin{aligned} \text{B.7} \quad h_{ij,kl} &= h_{ij,lk} + h_{im}^R m_{jlk} + h_{mj}^R m_{ilk} \\ &= h_{ij,lk} + h_{im} [h_{ml} h_{jk} - h_{mk} h_{jl}] - h_{mj} [h_{il} h_{mk} - h_{ik} h_{ml}] \end{aligned}$$

by B.6.

B.8 LEMMA *In the notation above*

$$\Delta_M (\frac{1}{2} |A|^2) = \sum_{i,j,k} h_{ij,k}^2 - |A|^4 + h_{ij} H_{,ij} + H h_{mi} h_{mj} h_{ij},$$

where $H = h_{kk} = \text{trace } A$.

Proof We first compute $h_{ij,kk}$:

$$\begin{aligned} h_{ij,kk} &= h_{ik,jk} \quad (\text{by B.5}) \\ &= h_{ki,jk} \quad (\text{by B.4}) \\ &= h_{ki,kj} + h_{km} [h_{mj} h_{ik} - h_{mk} h_{ij}] \\ &\quad - h_{mi} [h_{kj} h_{mk} - h_{kk} h_{mj}] \quad (\text{by B.7}) \\ &= h_{ki,kj} - \left(\sum_{m,k} h_{mk}^2 \right) h_{ij} + h_{kk} h_{mi} h_{mj} \\ &= h_{kk,ij} - \left(\sum_{m,k} h_{mk}^2 \right) h_{ij} + h_{kk} h_{mi} h_{mj} \quad (\text{by B.5}) \end{aligned}$$

Now multiplying by h_{ij} we then get (since $h_{ij} h_{ij,kk} = \frac{1}{2} \left(\sum_{i,j} h_{ij}^2 \right)_{,kk} - \sum_{i,j,k} h_{ij,k}^2$)

$$\frac{1}{2} \left(\sum_{i,j} h_{ij}^2 \right)_{,kk} = \sum_{i,j,k} h_{ij,k}^2 - \left(\sum_{i,j} h_{ij}^2 \right)^2 + h_{ij,H,ij} + Hh_{mi}h_{mj}h_{ij},$$

which is the required identity.

We now want to examine carefully the term $\sum_{i,j,k} h_{ij,k}^2$ appearing in the identity of B.8 in case M is a cone with vertex at 0 (i.e. $\eta_{0,\lambda}^{M=M} \forall \lambda > 0$). In particular we want to compare $\sum_{i,j,k} h_{ij,k}^2$ with $|\nabla^M |A||^2$ in this case. Since $|\nabla^M |A||^2 = \sum_{k=1}^n |A|^{-2} (h_{ij} h_{ij,k})^2$, we look at the difference

$$(*) \quad D \equiv \sum_{i,j,k} h_{ij,k}^2 - \sum_{k=1}^n |A|^{-2} (h_{ij} h_{ij,k})^2.$$

B.9 LEMMA *If M is a cone (not necessarily minimal) the quantity D defined in (*) satisfies*

$$D(x) \geq 2|x|^{-2}|A(x)|^2, \quad x \in M.$$

Proof Let $x \in M$ and select the frame τ_1, \dots, τ_n so that τ_n is radial ($x/|x|$) along the ray ℓ_x through x , and so that (as vectors in \mathbb{R}^{n+1}) τ_1, \dots, τ_n are constant along ℓ_x . Then

$$(1) \quad h_{nj} = h_{jn} = 0 \quad \text{along } \ell_x, \quad j=1, \dots, n,$$

and (since $h_{ij}(\lambda x) = \lambda^{-1} h_{ij}(x)$, $\lambda > 0$)

$$(2) \quad h_{ij,n} = -r^{-1} h_{ij} \quad \text{along } \ell_x.$$

Rearranging the expression for D , we have

$$D = \frac{1}{2} \sum_{k=1}^n \sum_{i,j,r,s=1}^n |A|^{-2} (h_{rs} h_{ij,k} - h_{ij} h_{rs,k})^2,$$

as one easily checks by expanding the square on the right. Now since

$$\sum_{i,j,r,s=1}^n (\quad)^2 \geq 4 \sum_{\substack{i,j,r=1 \\ s=n}}^{n-1} (\quad)^2 ,$$

we thus have

$$D \geq 2|A|^{-2} \sum_{k=1}^n \sum_{i,j,r=1}^{n-1} (h_{ij} h_{rn,k})^2 .$$

By the Codazzi equations B.5 and (2) this gives

$$\begin{aligned} D &\geq 2r^{-2}|A|^{-2} \sum_{k=1}^n \sum_{i,j,r=1}^{n-1} h_{ij}^2 h_{rk}^2 \\ &= 2r^{-2}|A|^{-2}|A|^4 \quad (\text{by (1)}) \\ &= 2r^{-2}|A|^2 , \end{aligned}$$

as required.

Proof of B.2 Notice that so far we have not used the minimality of M (i.e. we have not used $H(=h_{kk}) = 0$). We now do set $H=0$ in the above computations, thus giving (by B.8, B.9)

$$(1) \quad \Delta_M(\frac{1}{2}|A|^2) + |A|^4 \geq 2r^{-2}|A|^2 + |\nabla|A||^2$$

for the minimal cone M . (Notice that $|A|$ is Lipschitz, and hence $|\nabla|A||$ makes sense \mathcal{H}^n - a.e. in M .)

Our aim now is to use (1) in combination with the stability inequality B.1 to get a contradiction in case $2 \leq n \leq 6$.

Specifically, replace ζ by $\zeta|A|$ in B.1. This gives

$$\begin{aligned} (2) \quad \int_M \zeta^2 |A|^4 &\leq \int_M |\nabla(\zeta|A|)|^2 \\ &= \int_M (|\nabla\zeta|^2 |A|^2 + \zeta^2 |\nabla|A||^2) \\ &\quad + 2 \int_M \zeta |A| \nabla\zeta \cdot \nabla|A| . \end{aligned}$$

Now

$$\begin{aligned}
 2 \int_M \zeta |A| |\nabla \zeta \cdot \nabla A| &= 2 \int_M \zeta \nabla \zeta \cdot \nabla (\frac{1}{2} |A|^2) \\
 &= \int_M (\nabla \zeta^2) \cdot \nabla (\frac{1}{2} |A|^2) \\
 &= - \int_M \zeta^2 \Delta_M (\frac{1}{2} |A|^2) \\
 &\leq \int_M (|A|^4 \zeta^2 - 2r^{-2} \zeta^2 |A|^2 + \zeta^2 |\nabla |A||^2) \quad \text{by (1) ,}
 \end{aligned}$$

and hence (2) gives

$$(3) \quad 2 \int_M r^{-2} \zeta^2 |A|^2 \leq \int_M |A|^2 |\nabla \zeta|^2 \quad \forall \zeta \in C_c^1(M) .$$

Now we claim that (3) is valid even if ζ does not have compact support on M , provided that ζ is locally Lipschitz and

$$(4) \quad \int_M r^{-2} \zeta^2 |A|^2 < \infty .$$

(This is proved by applying (3) with $\zeta \gamma_\varepsilon$ in place of ζ , where γ_ε is such that $\gamma_\varepsilon(x) \equiv 1$ for $|x| \in (\varepsilon, \varepsilon^{-1})$, $|\nabla \gamma_\varepsilon(x)| \leq 3/|x|$ for all x , $\gamma_\varepsilon(x) = 0$ for $|x| < \varepsilon/2$ or $|x| > 2\varepsilon^{-1}$, and $0 \leq \gamma_\varepsilon \leq 1$ everywhere, then letting $\varepsilon \downarrow 0$ and using (4).)

Since M is a cone we can write

$$(5) \quad \int_M \phi(x) dH^n(x) = \int_0^\infty r^{n-1} \int_\Sigma \phi(r\omega) dH^{n-1}(\omega) dr$$

for any non-negative continuous ϕ on M , where $\Sigma = M \cap S^n$ is a compact $(n-1)$ -dimensional submanifold. Since $|A(x)|^2 = r^{-2} |A(x/|x|)|^2$, we can now use (5) to check that $\zeta = r^{1+\varepsilon} r_1^{1-n/2-2\varepsilon}$, $r_1 = \max\{1, r\}$, is a valid choice to ensure (4), hence we may use this choice in (3). This is easily seen to give

$$\begin{aligned}
 (6) \quad 2 \int_M r^{2\varepsilon} r_1^{2-n-4\varepsilon} |A|^2 &\leq ((n/2)-2+\varepsilon)^2 \int_{M \cap \{r>1\}} |A|^2 r^{2-n-2\varepsilon} \\
 &\quad + (1+\varepsilon)^2 \int_{M \cap \{r<1\}} |A|^2 r^{2\varepsilon} \\
 &< \infty .
 \end{aligned}$$

For $2 \leq n \leq 6$ we can choose ε such that $((n/2)-2+\varepsilon)^2 < 2$ and $(1+\varepsilon)^2 < 2$, hence (6) gives $|A|^2 \equiv 0$ on M as required.