

## Ends of metric measure spaces with nonnegative Ricci curvature

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### Abstract.

We prove that metric measure spaces with nonnegative Ricci curvature have at most two ends.

### §1. Introduction

We show a result of our previous paper [19], which states that measured length spaces with nonnegative Ricci curvature have at most two ends.

Lott–Villani [10], [11], [18] and Sturm [15], [16] introduced the concept of lower Ricci curvature bounds for measured length spaces. We use the definition in [18]: the weak curvature-dimension  $CD(K, N)$  condition ( $K \in \mathbb{R}, N \in [1, \infty]$ ). Ohta [12] and Sturm [16] also gave a definition of lower Ricci curvature bounds: the measure contraction property  $MCP(K, N)$  ( $K \in \mathbb{R}, N \in [1, \infty)$ ).

The parameters  $K$  and  $N$  play roles of lower Ricci curvature bound and dimension respectively. In fact, given a complete Riemannian manifold  $(M, g)$  with Riemannian distance  $d_g$  and measure  $\nu_g$ , the measured length space  $(M, d_g, \nu_g)$  satisfies the weak  $CD(K, N)$  condition if and only if  $\text{Ric}_M \geq K$  and  $\dim(M) \leq N$ . The property  $MCP(K, \dim(M))$  implies  $\text{Ric}_M \geq K$ ; however,  $MCP(K, N)$  does not imply  $\text{Ric}_M \geq K$  for  $N > \dim(M)$ .

If a measured length space  $X$  satisfies the weak  $CD(K, N)$  condition and if all geodesics in  $X$  do not branch, then  $X$  satisfies  $MCP(K, N)$ ; see [16]. Both the weak  $CD(K, N)$  condition and  $MCP(K, N)$  are preserved under measured Gromov–Hausdorff limits.

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This paper is concerned with the case that  $K = 0$  and  $N < \infty$  (i.e. the weak  $\text{CD}(0, N)$  condition or  $\text{MCP}(0, N)$ ). Our main theorem is as follows:

**Theorem 1.1.** *Let  $(X, d)$  be a complete, locally compact, separable length space equipped with a nonnegative Radon measure  $\nu$ . Given  $N \in [1, \infty)$ , we assume one of the following (i) and (ii):*

- (i) *The measured length space  $(X, d, \nu)$  satisfies the weak  $\text{CD}(0, N)$  condition.*
- (ii) *The measured length space  $(X, d, \nu)$  satisfies  $\text{MCP}(0, N)$ .*

*Then  $X$  has at most two ends.*

In the case of Riemannian manifolds with nonnegative Ricci curvature, the Cheeger–Gromoll splitting theorem [5] implies Theorem 1.1. The splitting theorem states that if a complete Riemannian manifold  $M$  of nonnegative Ricci curvature contains a straight line, then  $M$  is isometric to the product  $\mathbb{R} \times N$  for some Riemannian manifold  $N$ . Cheeger and Colding [2] extended this to the Gromov–Hausdorff limits of a sequence of Riemannian manifolds  $M_i$  with  $\text{Ric}_{M_i} \geq -\delta_i$ , where  $\delta_i \rightarrow 0$ . Unfortunately, the splitting theorem does not hold under the assumption of Theorem 1.1. In fact, any finite-dimensional, say  $n$ -dimensional, normed linear space with Lebesgue measure satisfies the weak  $\text{CD}(0, n)$  condition and  $\text{MCP}(0, n)$  [18]. Theorem 1.1 is proved without the splitting theorem.

For many recent results on this area, see [8], [9], [13], and [14].

This paper is organized as follows: In Section 2, we recall basic definitions: length spaces, the (pointed, measured) Gromov–Hausdorff convergence and the Wasserstein distance. In Section 3, we give the definition of the weak  $\text{CD}(0, N)$  condition and then summarize some basic properties. We prove Theorem 1.1 in Section 4.

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## §2. Preliminaries

**Length spaces.** Let  $(X, d)$  be a metric space. Given  $x \in X$  and  $r > 0$ , we denote by  $B_r(x)$  and  $\bar{B}_r(x)$  the open and closed ball of radius  $r$  and centered at  $x$ , respectively. The sphere of radius  $r$  and centered at  $x$  is denoted by  $S_r(x)$ .

A path  $\gamma : [0, l] \rightarrow X$  is called a *geodesic* if it is locally minimizing and has a constant speed. We say that  $(X, d)$  is a *length space* if  $d(x, y) =$

$\inf_\gamma \text{Length}(\gamma)$  for all  $x, y \in X$ , where the infimum is taken over all paths joining  $x$  and  $y$ . If  $X$  is a complete, locally compact length space, then all two points in  $X$  are joined by a minimal geodesic.

**Gromov–Hausdorff convergence.** Let  $(X, d_X), (Y, d_Y)$  be metric spaces. We say that, for  $\epsilon > 0$ , a map  $\varphi : X \rightarrow Y$  is an  $\epsilon$ -approximation if

- (i)  $|d_X(x, y) - d_Y(\varphi(x), \varphi(y))| < \epsilon$  holds for all  $x, y \in X$ , and
- (ii) the  $\epsilon$ -neighborhood of  $\varphi(X)$  coincides with  $Y$ .

Let  $(X_i, x_i)$  for  $i = 1, 2, \dots$  and  $(X, x)$  be pointed metric spaces. We say that  $\{(X_i, x_i)\}$  *pointed Gromov–Hausdorff converges to*  $(X, x)$  if for each  $R > 0$  there exist  $R_i \searrow R$ ,  $\epsilon_i \searrow 0$ , and  $\epsilon_i$ -approximations  $\varphi_i : B_{R_i}(x_i) \rightarrow B_R(x)$  with  $\varphi_i(x_i) = x$ . The Gromov–Hausdorff limits of a sequence of length spaces are also length spaces. See [1] and [7] for further information.

**Measured Gromov–Hausdorff convergence.** A *metric measure space* is a triple  $(X, d, \nu)$  where  $(X, d)$  is a metric space and  $\nu$  is a nonnegative Radon measure on  $X$ . Let  $(X_i, x_i, \nu_i)$  for  $i = 1, 2, \dots$  and  $(X, x, \nu)$  be pointed metric measure spaces. We say that  $\{(X_i, x_i, \nu_i)\}$  *pointed measured Gromov–Hausdorff converges to*  $(X, x, \nu)$  if there exist  $\epsilon_i \searrow 0$ ,  $R_i \rightarrow \infty$ , and Borel measurable  $\epsilon_i$ -approximations  $\varphi_i : B_{R_i}(x_i) \rightarrow B_{R_i}(x)$  such that the sequence of push-forward measures  $\{(\varphi_i)_* \nu_i\}$  converges vaguely to  $\nu$ , that is,  $\lim_{i \rightarrow \infty} \int_{X_i} f \circ \varphi_i d\nu_i = \int_X f d\nu$  holds for all continuous functions  $f : X \rightarrow \mathbb{R}$  with compact support. We refer to [6] for details.

**Wasserstein distance.** Let  $(X, d, x)$  be a complete, locally compact, separable, pointed length space. We denote by  $P(X)$  the set of Borel probability measures on  $X$ . Let  $P_2(X)$  be the set of Borel probability measures on  $X$  with finite second moment:

$$P_2(X) = \left\{ \mu \in P(X) \mid \int_X d(x, y)^2 d\mu(y) < \infty \right\},$$

which is independent of the choice of  $x$ . Given  $\mu_0, \mu_1 \in P_2(X)$ , a probability measure  $\pi \in P(X \times X)$  is called a *transference plan* between  $\mu_0$  and  $\mu_1$  if  $\pi(A \times X) = \mu_0(A)$  and  $\pi(X \times A) = \mu_1(A)$  hold for all measurable sets  $A \subset X$ . For example, the product measure  $\mu_0 \times \mu_1$  is a transference plan between  $\mu_0$  and  $\mu_1$ . We define the *Wasserstein*

distance  $W_2$  of order 2 between  $\mu_0$  and  $\mu_1$  by

$$W_2(\mu_0, \mu_1)^2 = \inf_{\pi} \left\{ \int_{X \times X} d(x_0, x_1)^2 d\pi(x_0, x_1) \right\},$$

where the infimum (in fact, minimum) is taken over all transference plans  $\pi$  between  $\mu_0$  and  $\mu_1$ . Then  $W_2$  defines a metric on  $P_2(X)$ ; moreover,  $(P_2(X), W_2)$  is a complete, separable length space. We refer to the book [17] of Villani for details.

### §3. Weak curvature-dimension condition

In this section we first define a suitable set of “entropy” functions in order to give the definition of the weak  $CD(0, N)$  condition. We then give some basic properties of measured length spaces with the weak  $CD(0, N)$  condition.

Results in this section come from [10], [11], [15], [16], or [18].

Let  $(X, d)$  be a complete, locally compact, separable length space equipped with a nonnegative Radon measure  $\nu$ .

#### 3.1. Definition of the weak $CD(0, N)$ condition

Let  $U : [0, \infty) \rightarrow \mathbb{R}$  be a continuous, convex function with  $U(0) = 0$ . Given a compactly supported Borel measure  $\mu$  on  $X$ , the *relative entropy function*  $U_\nu$  is defined by

$$U_\nu(\mu) = \int_X U(\rho(x)) d\nu(x) + U'(\infty)\mu_s(X),$$

where  $\mu = \rho\nu + \mu_s$  is the Lebesgue decomposition of  $\mu$  with respect to  $\nu$ , and  $U'(\infty) := \lim_{r \rightarrow \infty} (U(r)/r) \in \mathbb{R} \cup \{\infty\}$ . For  $N \in [1, \infty)$ , we define the *displacement convexity class  $\mathcal{DC}_N$  of order  $N$*  by

$$\mathcal{DC}_N = \{U : [0, \infty) \rightarrow \mathbb{R} \mid U \text{ is a continuous, convex function with } U(0) = 0 \text{ such that } (0, \infty) \ni \lambda \mapsto \lambda^N U(\lambda^{-N}) \text{ is convex}\}.$$

If  $N' \geq N$ , then  $\mathcal{DC}_{N'} \subset \mathcal{DC}_N$ . Put

$$U_N(r) = \begin{cases} Nr(1 - r^{-1/N}) & \text{if } 1 < N < \infty, \\ r & \text{if } N = 1. \end{cases}$$

Then  $U_N \in \mathcal{DC}_N$ .

**Definition 3.1.** Let  $N \in [1, \infty)$ . We say that  $(X, d, \nu)$  satisfies the weak  $CD(0, N)$  condition if for any compactly supported probability measures  $\mu_0$  and  $\mu_1$  with  $\text{supp}(\mu_0), \text{supp}(\mu_1) \subset \text{supp}(\nu)$  there exists a geodesic  $\{\mu_t\}_{t \in [0,1]}$  in  $(P_2(X), W_2)$  from  $\mu_0$  to  $\mu_1$  such that

$$U_\nu(\mu_t) \leq (1 - t)U_\nu(\mu_0) + tU_\nu(\mu_1)$$

holds for all  $U \in \mathcal{DC}_N$  and all  $t \in [0, 1]$ .

If  $(X, d, \nu)$  satisfies the weak  $CD(0, N)$  condition for some  $N \in [1, \infty)$ , then it satisfies the weak  $CD(0, N')$  condition for  $N' \geq N$ .

**3.2. Basic properties**

A subset  $A$  in  $X$  is said to be *totally convex* if for any two points  $x, y \in A$ , all minimal geodesics between  $x$  and  $y$  are contained in  $A$ .

**Proposition 3.2.** Assume that  $(X, d, \nu)$  satisfies the weak  $CD(0, N)$  condition for some  $N \in [1, \infty)$ .

- (1) Let  $A$  be a totally convex, closed subset of  $X$ . Then  $(A, d, \nu|_A)$  also satisfies the weak  $CD(0, N)$  condition.
- (2) Given  $\epsilon, \delta > 0$ , the measured length space  $(X, \epsilon d, \delta \nu)$  also satisfies the weak  $CD(0, N)$  condition.
- (3) The measure  $\nu$  either is a delta function or is non-atomic.

For a point  $x \in X$ , a subset  $A \subset X$ , and  $t \in [0, 1]$ , we put

$$[x, A]_t = \{\gamma(t) \mid \gamma : [0, 1] \rightarrow X \text{ is a minimal geodesic} \\ \text{with } \gamma(0) = x \text{ and } \gamma(1) \in A\}$$

(that is,  $[x, A]_t$  is the set of all  $t$ -barycenters of  $x$  and each point in  $A$ ). The proof of Theorem 30.11 in [18] (Theorem 5.31 in [10]) gives a directionally restricted version of the Bishop–Gromov inequality:

**Proposition 3.3.** Assume that  $(X, d, \nu)$  satisfies the weak  $CD(0, N)$  condition for some  $N \in [1, \infty)$ . Then for any  $x \in \text{supp}(\nu)$  and any Borel set  $A \subset X$ ,

$$(3.1) \quad t^N \nu(A) \leq \nu([x, A]_t)$$

holds for all  $t \in [0, 1]$ .

**Theorem 3.4.** Let  $\{(X_i, x_i, \nu_i)\}_{i=1}^\infty$  be a sequence of pointed measured length spaces satisfying the weak  $CD(0, N)$  condition for some  $N \in [1, \infty)$  with  $\text{supp}(\nu_i) = X_i$  and  $\nu_i(B_1(x_i)) = 1$ .

Then there exists a subsequence  $\{j\} \subset \{i\}$  such that  $\{(X_j, x_j, \nu_j)\}$  pointed measured Gromov–Hausdorff converges to some pointed measured length space  $(X_\infty, x_\infty, \nu_\infty)$ . Moreover, the limit space  $(X_\infty, \nu_\infty)$  satisfies the weak  $CD(0, N)$  condition.

**Remark 3.5** (On the measure contraction property). Given  $N \in [1, \infty)$ , Proposition 3.2, Proposition 3.3, and Theorem 3.4 hold for measured length spaces with MCP(0,  $N$ ). See [12] and [16, Section 5] for details.

#### §4. Proof of Theorem 1.1

We start with the definition of ends. Let  $X$  be a complete length space. A path  $\gamma : [0, \infty) \rightarrow X$  is a *ray* if each finite geodesic segment is minimal. Let  $\gamma_1, \gamma_2 : [0, \infty) \rightarrow X$  be rays from the base point  $x$ . Two rays  $\gamma_1$  and  $\gamma_2$  are said to be *cofinal* if  $\gamma_1(t)$  and  $\gamma_2(t)$  lie in the same connected component of  $X \setminus B_r(x)$  for all  $t, r > 0$  with  $t \geq r$ . An equivalence class of cofinal rays is called an *end* of  $X$ .

**Example 4.1.** Let  $\|\cdot\|$  be any norm on  $\mathbb{R}^n$ . Consider the set  $A := \mathbb{R} \times [0, 1]^{n-1}$ , which is totally convex in  $(\mathbb{R}^n, \|\cdot\|)$ . The length space  $(A, \|\cdot\|)$  has two ends. Since  $(\mathbb{R}^n, \|\cdot\|, \mathcal{L}^n)$  satisfies the weak CD(0,  $n$ ) condition and MCP(0,  $n$ ) as mentioned in the introduction, it follows from Proposition 3.2(1) that the measured length space  $(A, \|\cdot\|, \mathcal{L}^n|_A)$  also satisfies the properties.

To prove Theorem 1.1, we first study the local structure of measured length spaces with the weak CD(0,  $N$ ) condition or with MCP(0,  $N$ ).

**Definition 4.2** ([7, 3.32]). We say that a point  $x \in X$  is a *local cut point* if  $V \setminus \{x\}$  is disconnected for some connected neighborhood  $V$  of  $x$ . The *degree* of  $x$ , denoted by  $\deg(x)$ , is defined as the supremum of the number of connected components of  $V \setminus \{x\}$  for all connected neighborhoods  $V$  of  $x$ .

If  $x$  is a local cut point, then  $V \setminus \{x\}$  is disconnected for *every* sufficiently small neighborhood  $V$  of  $x$ . We have  $\deg(x) \geq 2$  for each local cut point  $x$ . The end points in a graph (one-dimensional space) are *not* local cut points.

An interior point in a graph is not always a local cut point; consider the length space  $\{(x, 0) \mid 0 \leq x \leq 1\} \cup \{(0, y) \mid 0 \leq y \leq 1\} \cup (\bigcup_{i=0}^{\infty} \{(x, -x + 2^{-i}) \mid 0 \leq x \leq 2^{-i}\}) \subset \mathbb{R}^2$ . The origin is *not* a local cut point.

On the basis of an idea in the proof of Theorem 5.1 in [4], we have

**Lemma 4.3.** *Let  $(X, d)$  be a complete, locally compact, separable length space equipped with a nonnegative Radon measure  $\nu$ . Given  $N \in [1, \infty)$ , we assume one of the following (i) and (ii):*

- (i) The measured length space  $(X, d, \nu)$  satisfies the weak  $\text{CD}(0, N)$  condition.  
(ii) The measured length space  $(X, d, \nu)$  satisfies  $\text{MCP}(0, N)$ .

If there exists a local cut point  $x \in X$ , then  $\deg(x) = 2$ .

*Proof.* Assume the condition (i). The proof is by contradiction: suppose that  $\deg(x) \geq 3$ . We may assume that  $\text{supp}(\nu) = X$ ; see [18, Theorem 30.2]. For a sufficiently small  $r > 0$ , we can take three connected components  $O_1, O_2, O_3$  of  $\overline{B}_r(x) \setminus \{x\}$  such that  $O_i \cap S_r(x)$  is nonempty for all  $i = 1, 2, 3$ . Fix  $0 < l \leq r/2$ . For each  $i = 1, 2, 3$ , we choose a point  $x_i \in O_i$  with  $d(x, x_i) = l$ . See Figure 1.

We put  $A = B_\epsilon(x) \cap O_1$  for  $0 < \epsilon < l$ . Then every minimal geodesic between any point in  $A$  and  $x_i$  for  $i = 2, 3$  passes through the local cut point  $x$ .

We now use Proposition 3.3, the Bishop–Gromov inequality (3.1), for  $x_i$  ( $i = 2, 3$ ),  $A$ , and  $t = l/(l + \epsilon)$ :

$$(4.1) \quad \left(\frac{l}{l + \epsilon}\right)^N \nu(A) \leq \nu([x_i, A]_{l/(l+\epsilon)}).$$

Put  $A_i = [x_i, A]_{l/(l+\epsilon)}$  for  $i = 2, 3$  and  $A' = B_\epsilon(x) \cap (O_2 \cup O_3)$ . We remark that  $A_2, A_3 \subset A'$  and  $A_2 \cap A_3 = \emptyset$ ; hence,  $\nu(A_2) + \nu(A_3) \leq \nu(A')$ . From (4.1) for  $i = 2, 3$ , we have

$$(4.2) \quad 2\left(\frac{l}{l + \epsilon}\right)^N \leq \frac{\nu(A_2) + \nu(A_3)}{\nu(A)} \leq \frac{\nu(A')}{\nu(A)}.$$

Next, we use the inequality (3.1) for  $x_1, A'$ , and  $t = l/(l + \epsilon)$ :

$$(4.3) \quad \left(\frac{l}{l + \epsilon}\right)^N \nu(A') \leq \nu([x_1, A']_{l/(l+\epsilon)}).$$

Since  $[x_1, A']_{l/(l+\epsilon)} \subset A$ , it follows from (4.2) and (4.3) that

$$2\left(\frac{l}{l + \epsilon}\right)^N \leq \left(\frac{l + \epsilon}{l}\right)^N.$$

Taking  $\epsilon \rightarrow 0$ , we get a contradiction.

The proof in the case (ii) is the same as above.

Q.E.D.

**Remark 4.4.** The assumption  $K = 0$  is not essential in Lemma 4.3: given  $K \in \mathbb{R}$  and  $N < \infty$ , Lemma 4.3 (that is,  $\deg(x) = 2$ ) holds for measured length spaces with the weak  $\text{CD}(K, N)$  condition or with  $\text{MCP}(K, N)$ ; see [19].

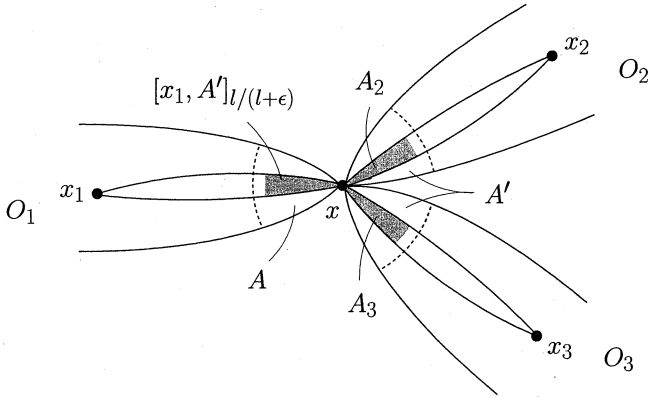


Fig. 1. Proof of Lemma 4.3

*Proof of Theorem 1.1.* Assume the condition (i). The proof is by contradiction: suppose that  $X$  has at least three ends. We assume that  $\text{supp}(\nu) = X$  as in Lemma 4.3. Given any sequence  $\epsilon_i \rightarrow 0$  and any point  $x \in X$ , we put  $(X_i, d_i, x_i) = (X, \epsilon_i d, x)$ . Let  $\nu_i$  be the push-forward of the measure  $\nu(B_{1/\epsilon_i}(x))^{-1}\nu$  by the identity map from  $X$  to  $X_i$ . It follows from Proposition 3.2(2) that the measured length space  $(X_i, d_i, \nu_i)$  satisfies the weak  $\text{CD}(0, N)$  condition. From Theorem 3.4 (or [3, Chapter 1]), there exists a subsequence  $\{j\} \subset \{i\}$  such that  $\{(X_j, d_j, x_j, \nu_j)\}$  pointed measured Gromov–Hausdorff converges to some pointed measured length space  $(X_\infty, d_\infty, x_\infty, \nu_\infty)$ ; then,  $(X_\infty, d_\infty, \nu_\infty)$  also satisfies the weak  $\text{CD}(0, N)$  condition. Since  $X$  has at least three ends, the point  $x_\infty$  is a local cut point. Then  $\text{deg}(x_\infty)$  is equal to the number of ends of  $X$ . This contradicts Lemma 4.3.

The proof in the case (ii) is the same as above.

Q.E.D.

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