## MINIMAL SURFACES WITH FREE BOUNDARIES

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We will in this lecture give a survey of some recent results for minimal surfaces with free boundaries. To this end, we consider boundary configurations  $\langle r, S \rangle$  in  $\mathbb{R}^3$  consisting of a fixed part rand a free part S. The fixed part r is the union of Jordan arcs  $r_1, \ldots, r_m$ , and the free part consists of surfaces  $S_1, \ldots, S_n$  in  $\mathbb{R}^3$ with or without boundary. Each of the curves  $r_j$  is either a closed curve, or else an arc with end points on S. In the following, the fixed part r may be void, whereas the free part S is always assumed to be non-empty.

A mapping  $X : \overline{\Omega} \to \mathbb{R}^3$  of some Riemann surface  $\Omega$  with boundary  $\partial \Omega$  into  $\mathbb{R}^3$  is called a solution of the free boundary problem for the configuration  $\langle r, S \rangle$  if the following properties are satisfied:

- (i)  $X \in C^{0}(\overline{\Omega}, \mathbb{R}^{3}) \cap C^{2}(\Omega, \mathbb{R}^{3})$ ;
- (ii) X is a harmonic mapping ;
- (iii) X maps  $\Omega$  conformally onto X( $\Omega$ ), except for isolated branch points in  $\Omega$ ;
- (iv)  $X(\partial \Omega) \subset \Gamma \cup S$ ;
- (v) the surface  $M = X(\overline{\Omega})$  intersects S at  $\Sigma \cap$  int S perpendicularly. Here  $\Sigma$  denotes the *free trace*  $X(\partial\Omega)$  of the minimal surface M on the free boundary S.

Obviously, property (v) does not make sense since we assumed X to be only continuous at the boundary  $\partial \Omega$ . Therefore, (v) has to be understood in a weak sense. However, it follows from well known