

# ELLIPTIC SYSTEMS

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## 1 Introduction

Elliptic equations model the behaviour of *scalar* quantities  $u$ , such as temperature or gravitational potential, which are in an equilibrium situation subject to certain imposed boundary conditions. In his first four lectures, John Urbas discussed *linear*<sup>1</sup> elliptic equations. In his lectures on the minimal surface equation, Graham Williams discussed the minimal surface equation, a *quasi-linear*<sup>2</sup> elliptic equation in divergence form. Neil Trudinger and Tim Cranny will discuss *fully nonlinear*<sup>3</sup> elliptic equations.

Elliptic systems model *vector-valued* quantities in an equilibrium situation subject to certain imposed boundary conditions. Examples are a vector-field describing the molecular orientation of a liquid crystal, and the displacement of an elastic body under an external force.

Solutions of elliptic *equations* are typically as smooth as the data allows (e.g. are  $C^\infty$  if the given data is  $C^\infty$ ). Solutions of elliptic *systems* typically have singularities.

We use as reference [G] the book *Multiple Integrals in the Calculus of Variations* by M. Giaquinta.

## 2 A Model, Harmonic Map, Problem

Suppose  $\Omega \subset \mathbb{R}^n$  is an elastic membrane, “stretched” via the function  $w$  over a part of the  $n$ -dimensional sphere  $S^n \subset \mathbb{R}^{n+1}$ , where  $w$  is specified on the boundary  $\partial\Omega$ . As a simple approximation to the physical situation, we can regard  $w$  as a minimiser of the *Dirichlet energy*

$$\frac{1}{2} \int_{\Omega} |Dw|^2, \quad (1)$$

amongst all maps  $w: \Omega \rightarrow \mathbb{R}^{n+1}$  such that

$$|w| = 1, \quad w|_{\partial\Omega} \text{ specified.}$$

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<sup>1</sup>The unknown function  $u$  and its first and second derivatives occur linearly. The *coefficients* of  $u$  and its derivatives may be nonlinear, but usually smooth, functions of the domain variables  $x_1, \dots, x_n$ .

<sup>2</sup>Linear in the second derivatives of  $u$ , but not necessarily linear in  $u$  or its first derivatives.

<sup>3</sup>Not even linear in the second derivatives of  $u$ .

<sup>4</sup>Where  $|Dw|^2 = \sum_{i,\alpha} |D_i w^\alpha|^2$ . The  $\frac{1}{2}$  is merely a convenient normalisation constant.