

On an Application of Zagier's Method in the Theory of Selberg's Trace Formula

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Introduction

Let H be the complex upper half plane, and put $G = PSL(2, \mathbf{R})$, $\Gamma = PSL(2, \mathbf{Z})$. Then, the well-known Selberg trace formula holds for the Hilbert space $L^2(\Gamma \backslash H)$. Let furthermore $\omega: z \rightarrow -\bar{z}$ be the reflection with respect to the imaginary axis, and let $\tilde{G} = \langle G, \omega \rangle$ be the group generated by G and ω . Then, the triple $(\tilde{G}, H, 1)$ turns out to be a weakly symmetric Riemannian space in the notation of Selberg (§1). Therefore, it is possible to investigate the trace formula for the Hilbert space $L^2(\tilde{\Gamma} \backslash H)$ with $\tilde{\Gamma} = \langle \Gamma, \omega \rangle$.

The space $L^2(\Gamma \backslash H)$ has the direct sum decomposition $L^2(\Gamma \backslash H) = V_e \oplus V_o$, where V_e and V_o are defined by $V_e = \{f \in L^2(\Gamma \backslash H) | f(\omega z) = f(z)\}$, $V_o = \{f \in L^2(\Gamma \backslash H) | f(\omega z) = -f(z)\}$ respectively, in accordance with the operation of ω . Since it is clear that $V_e = L^2(\tilde{\Gamma} \backslash H)$, the trace formulas for $L^2(\tilde{\Gamma} \backslash H)$ and for V_e are the same.

In fact, Venkov [8: Chap. 6] presented trace formulas for V_e and V_o in more general cases where the discontinuous group has an ω -invariant fundamental domain.

On the other hand, Zagier [10] gave a new method to derive the trace formulas in the case of $\Gamma = PSL(2, \mathbf{Z})$, considering an integral of the form

$$I(s) = \int_{\Gamma \backslash H} K_0(z, z) E(z, s) dz \quad (\S 2).$$

In the present paper, we shall prove the trace formula for V_e , i.e., for $L^2(\tilde{\Gamma} \backslash H)$ by means of Zagier's method in the case of $\Gamma = PSL(2, \mathbf{Z})$ (§3 and Theorem 2), and add an explicit form of the trace formula for V_o as a direct consequence of the trace formulas for $L^2(\Gamma \backslash H)$ and V_e (Theorem 3).

§ 1. Weakly symmetric Riemannian space

Let S be a Riemannian manifold with a positive definite metric $ds^2 = \sum g_{ij} dx^i dx^j$. The mapping of S onto itself is called an isometry if it holds

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