

## CHAPTER 3. THE LIKELIHOOD PRINCIPLE AND GENERALIZATIONS

### 3.1 INTRODUCTION

The LP deals with situations in which  $X$  has a density  $f_{\theta}(x)$  (with respect to some measure  $\nu$ ) for all  $\theta \in \Theta$ . Of crucial importance is the *likelihood function for  $\theta$  given  $x$* , given by

$$(3.1.1) \quad \ell_x(\theta) = f_{\theta}(x),$$

i.e., the density evaluated at the observed value  $X = x$  and considered as a function of  $\theta$ . Often we will call  $\ell_x(\theta)$  the *likelihood function for  $\theta$*  or simply the *likelihood function*. The LP, which follows, is stated in a form suitable for easy initial understanding; certain implicit qualifications are discussed at the end of the section.

*THE LIKELIHOOD PRINCIPLE.* All the information about  $\theta$  obtainable from an experiment is contained in the likelihood function for  $\theta$  given  $x$ . Two likelihood functions for  $\theta$  (from the same or different experiments) contain the same information about  $\theta$  if they are proportional to one another.

It has been known since Fisher (1925, 1934) that the "random" likelihood function  $\ell_x(\theta)$  is a minimal sufficient statistic for  $\theta$ , and hence contains all information about  $\theta$  from a classical viewpoint. The LP goes considerably farther, however, maintaining that only  $\ell_x(\theta)$  for the actual observation  $X = x$  is relevant.