3. FINITE DIMENSIONALITY

In any numerical approximation process, we deal solely with finite dimensional subspaces and with operators whose ranges are finite dimensional. In this section we study such subspaces and operators.

We start with a result concerning the closedness of the sum of two closed subspaces of a complex Banach space X . In general, such a sum need not be a closed subspace, as can be seen by considering X = ℓ^2 , F₁ = the closed linear span of $\{e_{2n}: n=1,2,\ldots\}$, i.e., $\left\{\sum_{n=1}^{\infty} a_n e_{2n}: a_n \in \mathbb{C} \right., \left.\sum_{n=1}^{\infty} |a_n|^2 < \infty\right\} \text{ and } F_2 = \text{the closed linear span of } \left\{e_{2n}+\frac{1}{n}e_{2n+1}: n=1,2,\ldots\right\}, \text{ i.e., } \left\{\sum_{n=1}^{\infty} b_n(e_{2n}+\frac{1}{n}e_{2n+1}): b_n \in \mathbb{C} \right., \\ \left.\sum_{n=1}^{\infty} |b_n|^2 < \infty\right\}. \text{ Then } \sum_{n=1}^{j} \frac{e_{2n+1}}{n} \text{ belongs to } F_1 + F_2 \text{ for each } j=1,2,\ldots, \text{ but } \sum_{n=1}^{\infty} \frac{e_{2n+1}}{n} \text{ does not. However, if one of the summands is finite dimensional, we have the following result.}$

PROPOSITION 3.1 Let Y be a finite dimensional subspace and Z be a closed subspace of X . Then Y + Z = $\{y + z : y \in Y, z \in Z\}$ is a closed subspace of X . In particular, Y itself is closed in X .

Proof Assume first that Y is one dimensional, say Y = span $\{y_1\}$. If $y_1 \in Z$, then Y + Z = Z, which is given to be closed. If $y_1 \notin Z$, let

$$d = dist(y_1, Z) > 0$$
.

Consider a sequence $(\alpha_n y_1 + z_n)$ in Y + Z , which converges to x in X . Now, for every $z \in Z$, we have

$$|\alpha_n| d \le ||\alpha_n y_1 + z|| .$$

This is obvious if $\alpha_n=0$, and if $\alpha_n\neq 0$, then $-z/\alpha_n$ is in Z so that $d\leq \|y_1-(-z/\alpha_n)\|$. Since $(\alpha_ny_1+z_n)$ is a Cauchy sequence, it follows from (3.1) that (α_n) is also Cauchy. Let $\alpha_n\to\alpha\in\mathbb{C}$. Then $z_n\to x-\alpha y_1$ which belongs to Z , since Z is closed. Thus,

$$x = \alpha y_1 + (x - \alpha y_1) \in Y + Z ,$$

showing that Y + Z is closed.

If Y is of dimension $m<\infty$, and $\{y_1,\ldots,y_m\}$ is a basis for Y, then a repeated application of the above result to Z, $\mathrm{span}\{y_1,Z\},\ldots,\mathrm{span}\{y_1,\ldots,y_{m-1},Z\} \text{ shows that } Y+Z \text{ is closed}.$

In particular, if we take $Z = \{0\}$, then we see that Y + Z = Y is closed. //

We are now in a position to prove a result regarding the complementation of finite dimensional subspaces, which was promised in the last section.

THEOREM 3.2 Let Y be an m dimensional subspace of X , and let x_1, \ldots, x_m form an ordered basis for Y .

Then there exist x_1^*, \dots, x_m^* in X^* such that

(3.2)
$$\langle \mathbf{x}_{\mathbf{j}}^*, \mathbf{x}_{\mathbf{i}} \rangle = \delta_{\mathbf{i}, \mathbf{j}}, \ \mathbf{i}, \mathbf{j} = 1, \dots, \mathbf{m} .$$

The map

(3.3)
$$Px = \sum_{j=1}^{m} \langle x, x_{j}^{*} \rangle x_{j}, \quad x \in X,$$

is a projection on Y along Z $\equiv \bigcap_{j=1}^m Z(\mathbf{x}_j^\divideontimes)$, so that X = Y \oplus Z . Also,

(3.4)
$$P^*x^* = \sum_{j=1}^{m} \langle x^*, x_j \rangle x_j^*, \quad x^* \in X^*.$$

If $X = Y \oplus \widetilde{Z}$, then there exist unique $\widetilde{x}_1^*, \ldots, \widetilde{x}_m^* \in \widetilde{Z}^\perp$ which satisfy $\langle \widetilde{x}_j^*, x_i \rangle = \delta_{i,j}, i,j = 1,\ldots,m$. They form the <u>ordered basis of</u> \widetilde{Z}^\perp which is adjoint to the given ordered basis x_1,\ldots,x_m of Y.

Proof Let $Y_j = \operatorname{span}\{x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_m\}$ for $j = 1, \dots, m$. Then by Proposition 3.1, Y_j is a closed subspace of X and $x_j \notin Y_j$. By Corollary 1.2, there is $x_j^* \in X^*$ such that $x_j^* \in Y_j^{\perp}$ and $\langle x_j^*, x_j \rangle = 1$ for each $j = 1, \dots, m$. These x_1^*, \dots, x_m^* satisfy (3.2).

The map P given by (3.3) is clearly linear and continuous; it is a projection since $Px_j = x_j$ for j = 1, ..., m by (3.2), so that

$$\mathbf{P}^2\mathbf{x} = \sum_{j=1}^m \langle \mathbf{x}, \mathbf{x}_j^{\bigstar} \rangle \mathbf{P} \mathbf{x}_j = \sum_{j=1}^m \langle \mathbf{x}, \mathbf{x}_j^{\bigstar} \rangle \mathbf{x}_j = \mathbf{P} \mathbf{x} \ .$$

Also, $R(P) = \text{span}\{x_1, \dots, x_m\} = Y$, and since x_1, \dots, x_m are linearly independent, we have $Z(P) = \bigcap_{i=1}^m Z(x_j^*)$.

Next, for $x \in X$ and all $x \in X$, we have

$$\langle P^*x^*, x \rangle = \langle x^*, Px \rangle$$

$$= \langle x^*, \sum_{j=1}^m \langle x, x_j^* \rangle x_j \rangle$$

$$= \sum_{j=1}^m \langle x_j^*, x \rangle \langle x^*, x_j \rangle$$

$$= \langle \sum_{j=1}^m \langle x^*, x_j \rangle x_j^*, x \rangle.$$

Hence we obtain (3.4).

Now, let $X=Y\oplus\widetilde{Z}$ and let \widetilde{P} be the projection on Y along \widetilde{Z} . Let $\widetilde{x}_j^*=\widetilde{P}^*x_j^*$ for $j=1,\ldots,m$. Then for $i,j=1,\ldots,m$,

$$\begin{split} &\langle \mathbf{x_i}, \mathbf{x_j^*} \rangle = \langle \widetilde{\mathbf{P}} \mathbf{x_i}, \mathbf{x_j^*} \rangle = \langle \mathbf{x_i}, \mathbf{x_j^*} \rangle = \delta_{\mathbf{i,j}}, \\ &\langle \mathbf{y}, \mathbf{x_j^*} \rangle = \langle \widetilde{\mathbf{P}} \mathbf{y}, \mathbf{x_j^*} \rangle = 0 \quad \text{for all} \quad \mathbf{y} \in \mathbf{Z}(\widetilde{\mathbf{P}}) = \widetilde{\mathbf{Z}} \end{split}.$$

Thus, $\widetilde{x}_1^*,\ldots,\widetilde{x}_m^*$ form a linearly independent set in \widetilde{Z}^{\perp} . Since \widetilde{Z}^{\perp} is isomorphic to Y^* (Proposition 2.2), it has the same dimension as Y, viz., m. This shows that $\widetilde{x}_1^*,\ldots,\widetilde{x}_m^*$ form a basis of \widetilde{Z}^{\perp} .

It follows from (3.3) and (3.4) that

(3.5)
$$\|P\| = \|P^*\| \le \sum_{j=1}^{m} \|x_j^*\| \|x_j\| .$$

If m = 1, then we have

$$\|Px\| = |\langle x, x_1^{\varkappa} \rangle| \ \|x_1\| \quad , \quad x \in X \ ,$$

so that

$$\|P\| = \sup\{\|Px\| : x \in X, \|x\| \le 1\}$$

$$= \|x_1^*\| \|x\|.$$

If m > 1, then strict inequality can hold in (3.5). This will be clear from the examples we shall soon give.

Remark 3.3 Here is a result which is 'dual' to the first part of Theorem 3.2: Let $\{x_1^{*},\ldots,x_m^{*}\}$ be a linearly independent subset of X^{*} . Then there exist x_1,\ldots,x_m in X such that

$$\langle \mathbf{x}_{\mathbf{j}}^*, \mathbf{x}_{\mathbf{i}} \rangle = \delta_{\mathbf{i}, \mathbf{j}}$$
, $\mathbf{i}, \mathbf{j} = 1, \dots, m$.

This is an immediate consequence of the following: If y^* , y_1^* ,..., y_n^* are in X^* and $Z(y^*) \supset \bigcap_{j=1}^n Z(y_j^*)$, then $y^* \in \operatorname{span}\{y_1^*,\ldots,y_n^*\}$. In fact, consider the conjugate linear function $F:X \to \mathbb{C}^n$ given by

$$\mathrm{Fx} = \left[\langle y_1^{\varkappa}, \mathbf{x} \rangle, \dots, \langle y_n^{\varkappa}, \mathbf{x} \rangle \right]^{\mathsf{t}} \ , \quad \mathbf{x} \in \mathbb{X} \ .$$

If $\operatorname{Fx} = \operatorname{Fx}$, then $\langle y^*, x \rangle = \langle y^*, \widetilde{x} \rangle$. Hence we see that there is a linear map $A: \mathbb{C}^n \to \mathbb{C}$ such that $y^* = \operatorname{AF}$. Let $\alpha_1, \ldots, \alpha_n \in \mathbb{C}$ be such that for all $c(1), \ldots, c(n)$ in \mathbb{C} ,

$$A[c(1),...,c(n)]^{t} = \alpha_{1}c(1) + ... + \alpha_{n}c(n)$$
.

Then for every $x \in X$,

$$\langle y^*, x \rangle = A(Fx)$$

$$= \alpha_1 \langle y_1^*, x \rangle + \dots + \alpha_n \langle y_n^*, x \rangle$$

$$= \langle \sum_{i=1}^n \alpha_i y_i^*, x \rangle.$$

Thus,
$$y^* = \sum_{i=1}^n \alpha_i y_i^* \in \text{span}\{y_1^*, \dots, y_n^*\}$$
.

Remark 3.4 Let x_1, \dots, x_m be in X and x_1^*, \dots, x_m^* be in X^* such that the matrix

$$A = [a_{i,j}]$$
, $a_{i,j} = \langle x_i, x_j^* \rangle$, $i,j = 1, \dots, m$,

is invertible. Let its inverse be given by $B=\left[b_{i\,,\,j}\right]$. Then $\{x_1^{},\ldots,x_m^{}\}$ is a linearly independent set in X and

(3.6)
$$y_{j}^{*} = \sum_{k=1}^{m} \bar{b}_{k,j} x_{k}^{*}, \quad j = 1, ..., m$$

satisfies

$$\langle x_i, y_j^* \rangle = \delta_{i,j}$$
, $i, j = 1, ..., m$.

This can be seen as follows. Let $\alpha_1 x_1 + \ldots + \alpha_m x_m = 0$ for some $\alpha_i \in \mathbb{C}$, $i=1,\ldots,m$. Then

$$\sum_{i=1}^{m} \alpha_{i} \langle x_{i}, x_{j}^{*} \rangle = 0 , \quad j = 1, \dots, m .$$

Since the matrix A is invertible, the above system has a unique solution, namely $\alpha_1=\ldots=\alpha_m=0$. Thus, $\{x_1,\ldots,x_m\}$ is linearly independent in X . Again, since AB is the identity matrix, we see that

$$\sum_{k=1}^{m} a_{i,k} b_{k,j} = \delta_{i,j}.$$

But for i, j = 1, ..., m,

$$\sum_{k=1}^{m} a_{i,k} b_{k,j} = \sum_{k=1}^{m} \langle x_{i}, x_{k}^{*} \rangle b_{k,j} = \langle x_{i}, \sum_{k=1}^{m} \overline{b}_{k,j} x_{k}^{*} \rangle.$$

Hence the result. Also, it can be similarly seen that the set $\{x_1^{\bigstar},\dots,x_m^{\bigstar}\} \ \text{is linearly independent in } X^{\bigstar} \ , \ \text{and since } A^HB^H \ \text{is the identity matrix, it follows that}$

(3.7)
$$y_{j} = \sum_{k=1}^{m} b_{j,k} x_{k}$$
satisfies $\langle y_{j}, x_{i}^{*} \rangle = \delta_{i,j}$, $i, j = 1, ..., m$.

Examples of projections on finite dimensional subspaces

(i) Let X be an n-dimensional space and Y be the m-dimensional subspace with an ordered basis x_1,\ldots,x_m . Extend this basis to a basis of X by adding the elements x_{m+1},\ldots,x_n to it. Let $Z=\text{span}\{x_{m+1},\ldots,x_n\}\text{ . Then the projection P on Y along Z is represented by the matrix}$

$$\mathbf{m} \left\{ \begin{bmatrix} 1 & & 0 & \vdots & & \\ & \ddots & & & 0 & \\ 0 & & 1 & \vdots & & \\ & & & & 0 & \\ & & & & & 0 & \\ \end{bmatrix} \right.$$

with respect to the ordered basis x_1,\dots,x_n . If $x_j^*\in X^*$ with $\langle x_j^*,x_i\rangle=\delta_{i,j}$, $i,j=1,\dots,m$, then P^* is also represented by the same matrix with respect to the ordered basis x_1^*,\dots,x_n^* .

(ii) Let X be a Hilbert space and Y a subspace with an ordered basis x_1, \dots, x_m . Then $X = Y \oplus Y^{\perp}$, and it follows from Theorem 3.2 that there exist y_1, \dots, y_m in $(Y^{\perp})^{\perp} = Y$ such that

$$\langle y_j, x_i \rangle = \delta_{i,j}$$
, $i, j = 1, ..., m$.

It is clear that y_1,\dots,y_m are linearly independent and hence form a basis of Y . The sets x_1,\dots,x_m and y_1,\dots,y_m are said to form a biorthogonal family in Y . Given x_1,\dots,x_m , the y_j 's can be found as follows. Since $y_i \in Y$, we have

$$y_j = \alpha_{1,j} x_1 + \dots + \alpha_{m,j} x_m, \quad \alpha_{1,j}, \dots, \alpha_{m,j} \quad \text{in } \mathbb{C}.$$

Hence for i = 1, ..., m,

$$\delta_{i,j} = \langle y_j, x_i \rangle = \sum_{k=1}^{m} \alpha_{k,j} \langle x_k, x_i \rangle$$
.

Thus, $\alpha_{1,j},\ldots,\alpha_{m,j}$ can be obtained as the unique solution of the above system of m equations in m unknowns.

Note that the set $\{x_1,\ldots,x_m\}$ is orthonormal iff $y_j=x_j$ for $j=1,\ldots,m$. Often it is convenient to have an orthonormal basis $\{u_1,\ldots,u_m\}$ of Y such that $\mathrm{span}\{u_1,\ldots,u_k\}=\mathrm{span}\{x_1,\ldots,x_k\}$ for each $k=1,\ldots,m$. Such a set can be obtained by the famous Gram-Schmidt orthonormalization process ([L], 22.3).

Note that the projection P on Y along Y^{\perp} is given by

$$Px = \sum_{j=1}^{m} \langle x, y_j \rangle x_j, \quad x \in X.$$

Since P is an orthogonal projection and P \neq 0 , we see by Proposition 2.3 that P* = P and ||P|| = 1 . Since

$$1 = |\langle x_{j}, y_{j} \rangle| \le ||x_{j}|| ||y_{j}||,$$

we see that the upper bound for $\|P\|$ given in (3.5) , namely $\sum_{j=1}^m \|x_j\| \|y_j\| \ , \ \ \text{is very rough when} \ \ \text{m} \ \ \text{is large}.$

As a concrete case, consider $X=L^2([0,1])$ and $x_j(t)=t^j$, $0 \le t \le 1$, for $j=0,\ldots,m-1$. Then $Y=\mathrm{span}\{x_0,\ldots,x_{m-1}\}$ is the space of all polynomials of degree $\le m-1$. To find $y_j \in Y$ with $\langle y_j,x_i \rangle = \delta_{i,j}$, we consider

$$y_{j}(t) = \alpha_{0,j} + \alpha_{1,j}t + ... + \alpha_{m-1,j}t^{m-1}, 0 \le t \le 1.$$

Since

$$\langle x_k, x_i \rangle = \int_0^1 t^{k+i} dt = \frac{1}{k+i+1}$$
,

we see that $[\alpha_{i,j}]$ is the inverse of the m × n <u>Hilbert matrix</u> $\left[\frac{1}{i+j+1}\right]$, $i,j=0,\ldots,m-1$. This matrix is, however, known to be numerically intractable. It is, therefore, advisable to orthonormalize the set $\{x_0,\ldots,x_{m-1}\}$ to obtain the Legendre polynomials and work with them.

(iii) Let X = C([a,b]) with the supremum norm. Consider a partition

$$a = t_0 \le t_1 \le \ldots \le t_m \le t_{m+1} = b$$

of [a,b] . The points t_1,\ldots,t_m will be called the nodes. Let

$$Y = \{x \in X : x \text{ is linear on } [t_{i-1}, t_i], i = 1, ..., m + 1,$$

$$x(a) = x(t_1) \text{ and } x(t_m) = x(b)\}.$$

Every element x of Y is piecewise linear; the linearity of x can break down only at the nodes t_1, \dots, t_m . Let $e_i \in Y$ be such that

$$e_{i}(t_{j}) = \delta_{i,j}$$
, $i, j = 1,...,m$.

The functions e_1, \ldots, e_m form a basis of Y; their graphs are shown in Figure 3.1.

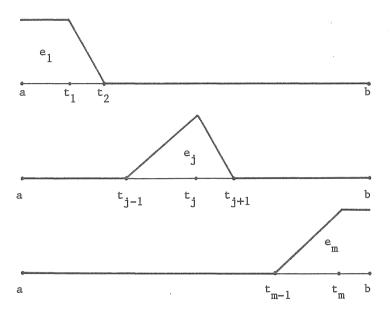


Figure 3.1

We give explicit formulae for these <u>piecewise linear hat functions</u> for later computational use:

$$\mathbf{e}_{1}(t) = \begin{cases} 1 & \text{if } \mathbf{a} \leq \mathbf{t} \leq \mathbf{t}_{1} \\ (\mathbf{t}_{2}^{-t})/(\mathbf{t}_{2}^{-t}_{1}) & \text{if } \mathbf{t}_{1} \leq \mathbf{t} \leq \mathbf{t}_{2} \\ 0 & \text{if } \mathbf{t}_{2} \leq \mathbf{t} \leq \mathbf{b} \end{cases}$$

$$\mathbf{e}_{m}(\mathbf{t}) = \begin{cases} 0 , & \text{if } \mathbf{a} \leq \mathbf{t} < \mathbf{t}_{m-1} \\ (\mathbf{t}_{m-1} - \mathbf{t}) / (\mathbf{t}_{m-1} - \mathbf{t}_{m}) , & \text{if } \mathbf{t}_{m-1} \leq \mathbf{t} < \mathbf{t}_{m} , \\ 1 , & \text{if } \mathbf{t}_{m} \leq \mathbf{t} \leq \mathbf{b} \end{cases}$$

and for j = 2, ..., m-1,

$$\mathbf{e_{j}(t)} = \begin{cases} 0 & , & \text{if} & \text{a} \leq t < t_{j-1} \\ (t_{j-1} - t)/(t_{j-1} - t_{j}) & , & \text{if} & t_{j-1} \leq t < t_{j} \\ (t_{j+1} - t)/(t_{j+1} - t_{j}) & , & \text{if} & t_{j} \leq t < t_{j+1} \\ 0 & , & \text{if} & t_{j+1} \leq t \leq b \end{cases}.$$

It can be easily checked that for $j=1,\ldots,m$, $e_j(t)\geq 0$ for all $t\in [a,b]$, e_j vanishes outside $[t_{j-1},t_{j+1}]$, at any fixed $t\in [a,b]$ at most two of the functions e_1,\ldots,e_m are nonzero, and for all t,

$$e_1(t) + ... + e_m(t) = 1$$
.

Because of such very nice properties, these so-called hat functions e_1, \ldots, e_m prove to be very useful in numerical calculations.

For
$$j$$
 = 1,...,m , define $e_j^{\varkappa} \in X^{\varkappa}$ by

$$e_j^*(x) = x(t_j), x \in X.$$

Then $\langle e_j^*, e_i \rangle = \delta_{i,j}$. Consider for $x \in X$,

$$Px = \sum_{j=1}^{m} x(t_j)e_j.$$

Then P is a projection on Y along

$$Z = \{x \in X : x(t_j) = 0 \text{ for each } j = 1,...,m\}$$
.

Note that for $t \in [a,b]$,

$$\begin{split} |\operatorname{Px}(\mathsf{t})| & \leq \sum_{\mathsf{j}=1}^{\mathsf{m}} |\mathsf{x}(\mathsf{t}_{\mathsf{j}})| || \mathsf{e}_{\mathsf{j}}(\mathsf{t})| \\ & \leq ||\mathsf{x}||_{\infty} \sum_{\mathsf{j}=1}^{\mathsf{m}} \mathsf{e}_{\mathsf{j}}(\mathsf{t}) = ||\mathsf{x}||_{\infty} . \end{split}$$

Hence $\|P\| = 1$. Also, it is easy to see that $\|e_j\| = \|e_j^*\| = 1$ for j = 1, ..., m. Again, we see that the bound for $\|P\|$ given in (3.5) need not be sharp.

Finite rank operators

We now consider operators whose ranges are finite dimensional. An operator $T \in BL(X)$ is said to be <u>of finite rank</u> if the dimension of its range R(T) is finite; this dimension is called the <u>rank</u> of the operator.

Let T be of finite rank. Consider a subspace Y of X containing R(T), and let x_1,\ldots,x_m be an ordered basis of Y. By Theorem 3.2, find $x_j^* \in X^*$, $j=1,\ldots,m$ such that $\langle x_j^*,x_i\rangle = \delta_{i,j}$. For $x\in X$, we have

$$\mathsf{Tx} = \alpha_1 \mathsf{x}_1 + \ldots + \alpha_m \mathsf{x}_m , \quad \alpha_j \in \mathbb{C} .$$

By applying x_i^* on both sides, we see

(3.8)
$$\operatorname{Tx} = \sum_{j=1}^{m} \langle \operatorname{Tx}, \mathbf{x}_{j}^{*} \rangle \mathbf{x}_{j} = \sum_{j=1}^{m} \langle \mathbf{x}, \mathbf{T}^{*} \mathbf{x}_{j}^{*} \rangle \mathbf{x}_{j}.$$

Now, T maps Y into Y and $x_j^*|_Y$, $j=1,\ldots,m$ form the ordered basis of Y^* which is adjoint to the ordered basis x_1,\ldots,x_m of Y. Hence T_Y is represented by the matrix $(t_{i,j})$ with respect to the basis x_1,\ldots,x_m , where $t_{i,j}=\langle Tx_j,x_i^*\rangle$, $i,j=1,\ldots,m$. The operator $(T_Y)^*:Y^*\to Y^*$ is then represented by the matrix $[\overline{t}_{j,i}]$ with respect to the basis $x_1^*|_Y,\ldots,x_m^*|_Y$. See Example (i) at the end of Section 1.

The sum of the diagonal entries $\langle Tx_j, x_j^* \rangle$, j = 1, ..., m of the above matrix $(t_{i,j})$ is called the <u>trace of the finite rank</u> operator T:

(3.9)
$$\operatorname{tr}(T) = \sum_{j=1}^{m} \langle Tx_{j}, x_{j}^{*} \rangle.$$

We now show that the trace of T does not depend on the choice of the finite dimensional subspace Y which contains R(T), or the ordered basis x_1, \ldots, x_m of Y, or its adjoint basis x_1^*, \ldots, x_m^* .

PROPOSITION 3.6 Let Y_0 be a finite dimensional subspace of X containing R(T), y_1,\ldots,y_n an ordered basis of Y_0 , and y_1^*,\ldots,y_n^* an adjoint basis. Then

$$tr(T) = \sum_{j=1}^{n} \langle Ty_{j}, y_{j}^{*} \rangle .$$

Proof We can assume without loss of generality that Y_0 contains Y. For, otherwise we can consider the subspace Y_1 spanned by Y and Y_0 and argue in a similar manner twice.

Now, if necessary, extend the linearly independent set $\{x_1,\dots,x_m\}$ in Y to an ordered basis x_1,\dots,x_n of Y_0 in such a way that for $i=m+1,\dots,n$, we have $\langle x_j^{*},x_i\rangle=0$, $j=1,\dots,m$. For $j=m+1,\dots,n$, find $x_j^{*}\in X^{*}$ such that

$$\langle x_j^*, x_i \rangle = \delta_{i,j}$$
, $i = 1,...,n$.

For $m+1 \le j \le n$, we have $Tx_j \in Y$ so that

$$\operatorname{Tx}_{\mathbf{j}} = \alpha_{1} \mathbf{x}_{1} + \ldots + \alpha_{m} \mathbf{x}_{m} \; , \quad \alpha_{\mathbf{j}} \in \mathbb{C} \; .$$

Hence for j = m + 1, ..., n we have

$$\langle \text{Tx}_{j}, \mathbf{x}_{j}^{*} \rangle = \sum_{i=1}^{m} \alpha_{i} \langle \mathbf{x}_{i}, \mathbf{x}_{j}^{*} \rangle = 0$$
.

Thus,

(3.10)
$$\sum_{j=1}^{n} \langle Tx_j, x_j^* \rangle = \sum_{j=1}^{m} \langle Tx_j, x_j^* \rangle = tr(T) .$$

Since $\{x_1, \dots, x_n\}$ is a basis of Y_0 , we have

$$y_i = \sum_{k=1}^{n} \alpha_{k,i} x_k$$
, $\alpha_{k,i} \in \mathbb{C}$, $i = 1,...,n$.

Similarly, since $\{x_k^*|_{Y_0}: k=1,\ldots,n\}$ is a basis of Y_0^* , we have

$$\mathbf{y_i^{*}}\big|_{Y_{0}} = \sum_{k=1}^{n} \beta_{k,i} \mathbf{x_k^{*}}\big|_{Y_{0}} \;, \quad \boldsymbol{\beta_{k,i}} \in \mathbb{C} \;, \; i = 1, \dots, n \;.$$

Now,

$$\begin{split} \boldsymbol{\delta}_{\mathbf{i},\mathbf{j}} &= \langle \mathbf{y}_{\mathbf{j}}^{\mathbf{x}}, \mathbf{y}_{\mathbf{i}} \rangle = \sum_{k=1}^{n} \beta_{k,\mathbf{j}} \langle \mathbf{x}_{k}^{\mathbf{x}}, \sum_{p=1}^{n} \alpha_{p,\mathbf{i}} \mathbf{x}_{p} \rangle \\ &= \sum_{k=1}^{n} \beta_{k,\mathbf{j}} \bar{\alpha}_{k,\mathbf{i}}, \quad \mathbf{i}, \mathbf{j} = 1, \dots, n \end{split}.$$

If $A=[\alpha_{i,j}]$ and $B=[\beta_{i,j}]$, then we see that $A^HB=I$. Hence the matrix A is nonsingular and $A^{-1}=B^H$, so that $AB^H=I$, i.e.,

$$\sum_{i=1}^{n} \alpha_{k,i} \overline{\beta}_{j,i} = \delta_{k,j} , \quad k,j = 1,...,n .$$

Hence

$$\begin{split} & \sum_{\mathbf{i}=1}^{n} \ \langle \mathsf{Ty}_{\mathbf{i}}, \mathsf{y}_{\mathbf{i}}^{\bigstar} \rangle \ = \ \sum_{\mathbf{i}=1}^{n} \ \sum_{\mathbf{k}=1}^{n} \ \alpha_{\mathbf{k}, \mathbf{i}} \langle \mathsf{Tx}_{\mathbf{k}}, \ \sum_{\mathbf{j}=1}^{n} \ \beta_{\mathbf{j}, \mathbf{i}} \mathsf{x}_{\mathbf{j}}^{\bigstar} \rangle \\ & = \ \sum_{\mathbf{k}=1}^{n} \ \sum_{\mathbf{j}=1}^{n} \ \langle \mathsf{Tx}_{\mathbf{k}}, \mathsf{x}_{\mathbf{j}}^{\bigstar} \rangle \ \sum_{\mathbf{i}=1}^{n} \ \alpha_{\mathbf{k}, \mathbf{i}} \ \overline{\beta}_{\mathbf{j}, \mathbf{i}} \\ & = \ \sum_{\mathbf{k}=1}^{n} \ \langle \mathsf{Tx}_{\mathbf{k}}, \mathsf{x}_{\mathbf{k}}^{\bigstar} \rangle \ . \end{split}$$

Now (3.10) shows that
$$\sum_{i=1}^{n} \langle Ty_i, y_i^* \rangle = tr(T)$$
.

Let us now consider the adjoint of a finite rank operator.

THEOREM 3.7 If T is of rank $m < \infty$, then so is T^* . In fact, if

 $\begin{array}{lll} x_1,\dots,x_m & \text{is an ordered basis of} & R(T) & \text{and} & x_j^* \in X^* & \text{with} \\ \langle x_j^*,x_i^* \rangle = \delta_{i,j}^{} & , & \text{then} & T^*x_1^*,\dots,T^*x_m^* & \text{form a basis of} & \mathbb{W} = R(T^*)^* & , & \text{and} \\ (T^*)_{\mathbb{W}} : \mathbb{W} \to \mathbb{W} & \text{is represented by the matrix} & \begin{bmatrix} \bar{t}_{j,i} \end{bmatrix} & \text{with respect to} \\ \text{this basis, where} & t_{i,j}^{} = \langle Tx_j^*,x_i^* \rangle & . & \text{For} & x^* \in X^* & , & \text{we have} \\ (3.11) & T^*x^* = \sum_{i=1}^m \langle x^*,x_j\rangle T^*x_j^* & . & \end{array}$

Moreover, we have

$$(3.12) R(T^*) = Z(T)^{\perp}.$$

Proof For $x \in X$ and $x \in X$, we have

$$\langle T^*x^*, x \rangle = \langle x^*, Tx \rangle = \langle x^*, \sum_{j=1}^m \langle x, T^*x_j^* \rangle x_j \rangle$$

$$= \sum_{j=1}^m \langle T^*x_j^*, x \rangle \langle x^*, x_j \rangle$$

$$= \langle \sum_{j=1}^m \langle x^*, x_j \rangle T^*x_j^*, x \rangle.$$

Hence (3.11) follows. This shows that

$$\boldsymbol{W} = \boldsymbol{R}(\boldsymbol{T}^{\boldsymbol{\times}}) = \operatorname{span}\{\boldsymbol{T}^{\boldsymbol{\times}}\boldsymbol{x}_{1}^{\boldsymbol{\times}}, \dots, \boldsymbol{T}^{\boldsymbol{\times}}\boldsymbol{x}_{m}^{\boldsymbol{\times}}\} \ .$$

Since $x_j \in R(T)$, let $x_j = Tu_j$, $u_j \in X$ for j = 1, ..., m. Then

(3.13)
$$\langle T^* x_j^*, u_i \rangle = \langle x_j^*, Tu_i \rangle = \langle x_j^*, x_i \rangle = \delta_{i,j}.$$

Hence $T^*x_1^*, \dots, T^*x_m^*$ are linearly independent as well. Thus, T^* has rank m . Let

$$T^*(T^*x_i^*) = s_{1,i}T^*x_1^* + \dots + s_{m,i}T^*x_m^*, s_{i,i} \in \mathbb{C}$$

Then (3.13) shows that

$$\begin{split} \mathbf{s}_{\mathbf{i},\mathbf{j}} &= \langle \mathbf{T}^{\mathbf{*}}(\mathbf{T}^{\mathbf{*}}\mathbf{x}_{\mathbf{j}}^{\mathbf{*}}), \mathbf{u}_{\mathbf{i}} \rangle = \langle \mathbf{T}^{\mathbf{*}}\mathbf{x}_{\mathbf{j}}^{\mathbf{*}}, \mathbf{T}\mathbf{u}_{\mathbf{i}} \rangle \\ &= \langle \mathbf{T}^{\mathbf{*}}\mathbf{x}_{\mathbf{i}}^{\mathbf{*}}, \mathbf{x}_{\mathbf{i}} \rangle = \langle \mathbf{x}_{\mathbf{i}}^{\mathbf{*}}, \mathbf{T}\mathbf{x}_{\mathbf{i}} \rangle \end{split}$$

Hence $T^*|_{\mathbb{W}}$ is represented by the matrix $(\bar{t}_{j,i})$, where $t_{i,j} = \langle Tx_j, x_i^* \rangle$.

Finally, it is easy to see that $R(T^*)$ is contained in $Z(T)^{\perp}$. On the other hand, let $y^* \in Z(T)^{\perp}$. Since for $x \in X$, we have $Tx = \sum_{j=1}^m \langle Tx, x_j^* \rangle x_j \text{ and } x_j = Tu_j \text{, we see that}$

$$x - \sum_{j=1}^{m} \langle Tx, x_j^* \rangle u_j \in Z(T)$$
.

Hence

$$\langle \mathbf{y}^{*}, \mathbf{x} \rangle = \langle \mathbf{y}^{*}, \quad \sum_{j=1}^{m} \langle T\mathbf{x}, \mathbf{x}_{j}^{*} \rangle \mathbf{u}_{j} \rangle$$

$$= \langle \sum_{j=1}^{m} \langle \mathbf{y}^{*}, \mathbf{u}_{j} \rangle T^{*} \mathbf{x}_{j}^{*}, \quad \mathbf{x} \rangle .$$

This shows that $y^* = \sum_{j=1}^{m} \langle y^*, u_j \rangle T^* x_j^* \in R(T^*)$, and proves (3.12). //

Before we conclude this longish section, we give a characterization of bounded operators of finite rank.

PROPOSITION 3.8 $T \in BL(X)$ is of finite rank if and only if T is compact and R(T) is closed in X.

Proof Let T be a bounded operator of finite rank. If (x_n) is a bounded sequence in X, then (Tx_n) is also a bounded sequence in R(T), which is finite dimensional. Hence by the Heine-Borel theorem, (Tx_n) has a convergent subsequence. This shows that T is compact. Also, being finite dimensional, R(T) is closed in X by Proposition 3.1.

Conversely, let T be compact and R(T) be closed in X . Then $T:X\to R(T) \mbox{ is a continuous map from the Banach space }X \mbox{ onto the}$

Banach space R(T). By the open mapping theorem ([L], 11.1), there is $\delta>0$ such that $y\in R(T)$ and $\|y\|\leq \delta$ imply y=Tx for some $x\in X$ with $\|x\|<1$, i.e.,

$$\{y \in R(T) : ||y|| \le \delta\} \subset \{Tx : ||x|| \le 1\}$$
,

Since T is compact, the closure of the set $\{Tx: \|x\| \le 1\}$ is compact. This shows that the closed ball of radius δ in R(T) is compact. Hence R(T) is finite dimensional ([L], 6.9).

COROLLARY 3.9 Let $P \in BL(X)$ be a projection. Then P is of finite rank if and only if P is compact.

Proof Since R(P) = Z(I-P) is closed, the result is immediate from Proposition 3.8.

Problems

- 3.1 If Y is an m dimensional subspace of X , then there is a basis $\{y_1,\ldots,y_m\}$ of Y such that $\|y_j\|=1$ and $\mathrm{dist}(y_j,\mathrm{span}\{y_1,\ldots,y_{j-1}\})=1$. Can we have, in fact, $\mathrm{dist}(y_j,\mathrm{span}\{y_1,\ldots,y_{j-1},y_{j+1},\ldots,y_m\})=1$?
- 3.2 Let $X = Y \oplus Z$, and let x_1, \dots, x_m (resp., x_1^*, \dots, x_m^*) form an ordered basis of Y (resp., Z^{\perp}) such that $\langle x_1, x_j^* \rangle = \delta_{i,j}$. Then $\|x_j^*\| = 1/\mathrm{dist}(x_j, x_j) ,$

where $X_j = Y_j \oplus Z$, with $Y_j = span\{x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_m\}$.

3.3 Let t_1,\ldots,t_m be the nodes in [a,b] for the piecewise linear hat functions e_1,\ldots,e_m . Let $\widetilde{X}=\text{NBV}([a,b])$, and for $\widetilde{x}\in\widetilde{X}$

$$Q\widetilde{x} = \sum_{j=1}^{m} \left[\int_{a}^{b} e_{j}(t) d\widetilde{x}(t) \right] f_{j}$$
,

where f_j is the characteristic function of the set $[t_j,b]$, $j=1,\ldots,m$. (In case $t_1=a$, we take $f_1(a)=0$.) Then Q is the projection on $\operatorname{span}\{f_1,\ldots,f_m\}$ along $\{\widetilde{x}\in\widetilde{X}:\int_a^b e_j(t)d\widetilde{x}(t)=0$, $j=1,\ldots,m\}$ and has norm 1. It can be identified with the adjoint of the projection P of Example (iii).

3.4 $T \in BL(X)$ is of finite rank if and only if there exist x_1, \dots, x_n in X and x_1^*, \dots, x_n^* in X^* such that

$$Tx = \sum_{j=1}^{n} \langle x, x_{j}^{*} \rangle x_{j}, \quad x \in X,$$

and in that case,

$$T^*x^* = \sum_{j=1}^n \langle x^*, x_j \rangle x_j^*, x^* \in X^*.$$

One may assume without loss of generality that the sets $\{x_1,\ldots,x_n\}$ and $\{x_1^*,\ldots,x_n^*\}$ are linearly independent.

3.5 If $T \in BL(X)$ is of finite rank and $A \in BL(X)$, then TA and AT are of finite rank, and tr(TA) = tr(AT).