

8 Some Applications of the Enneper-Weierstrass Representation

Given a minimal surface $X : M \hookrightarrow \mathbf{R}^3$ and its Enneper-Weierstrass representation, fix a simply connected open set $U \subset M$. Fixing $p_0 \in U$ we can define a family of isometric minimal surfaces associated to $X_\theta : U \rightarrow \mathbf{R}^3$, $0 \leq \theta < 2\pi$, by

$$X_\theta(p) = \Re e^{i\theta} \int_{p_0}^p (\omega_1, \omega_2, \omega_3) + C, \quad p \in U, \quad (8.35)$$

where the ω_i 's are the 1-forms in the Enneper-Weierstrass representation of X and C is a constant vector. The Enneper-Weierstrass data for X_θ are $g_\theta = g$ and $\eta_\theta = e^{i\theta}\eta$. When $\theta = \pi/2$, $X_{\pi/2}$ is called the *conjugate surface* of X .

Let $I \subset \mathbf{R}$ be an interval and $r : I \rightarrow U$ be a geodesic such that $X \circ r$ is a plane curve. Then we know that r must be a curvature line, thus by our criterion in the previous section,

$$d(g \circ r)\eta \circ r \in \mathbf{R}.$$

Since X and $X_{\pi/2}$ are isometric, r is also a geodesic of $X_{\pi/2}$. Moreover,

$$d(g_{\pi/2} \circ r)\eta_{\pi/2} \circ r = id(g \circ r)\eta \circ r \in i\mathbf{R},$$

and hence r is an asymptotic line of $X_{\pi/2}$. Since the space curve $X_{\pi/2} \circ r$ is both a geodesic and an asymptotic line of $X_{\pi/2}$, it must be a straight line segment on $X_{\pi/2}$ (in fact, the normal and geodesic curvatures of $X_{\pi/2} \circ r$ are both zero, and so its curvature is zero everywhere). Since X and $X_{\pi/2}$ are conjugate to each other (up to sign), we have

Proposition 8.1 *$X \circ r$ is a plane geodesic (straight line segment) if and only if $X_{\pi/2} \circ r$ is a straight line segment (a plane geodesic).*

In fact, we have more information whenever we have a plane geodesic or a straight line segment on X . Namely, the surface X must have some symmetry.

Theorem 8.2 (Reflection and Rotation Theorems) *If a plane geodesic which is not a straight line segment lies on a minimal surface, then reflection in the plane of the geodesic is a congruence of the minimal surface.*

If a straight line segment lies on a minimal surface, then 180°-rotation around the straight line is a congruence of the minimal surface.

Proof. Let $X \circ r$ be a plane geodesic but not a straight line segment on X . By a rotation in \mathbf{R}^3 we can assume that $X \circ r$ is in the xz -plane. Since $X \circ r$ is a geodesic and is not a straight line segment, the Gauss map N of X along r must be in the xz -plane. Thus $g = \tau \circ N$ is real along r . Select a point $r(t_0)$ such that $g'(r(t_0)) \neq 0$; then in a

simply connected neighbourhood U of $r(t_0)$, $w = g(z)$ is a well defined coordinate of M . We can use the representation (6.27) and consider the holomorphic mapping on U ,

$$(G^1, G^2, G^3) = G := \int_{p_0}^p (\omega_1, \omega_2, \omega_3) + C,$$

where $p_0 = r(t_0)$ and $C \in \mathbf{C}^3$ is a constant complex vector. Remember that our surface $X = \Re G$ and $X_{\pi/2} = -\Im G$. By Proposition 8.1, $X_{\pi/2} \circ r$ is a straight line segment. Since the Gauss map of $X_{\pi/2}$ is the same as that of X , the Gauss map of $X_{\pi/2}$ is in the xz -plane along r , so the straight line segment $X_{\pi/2} \circ r$ is parallel to the y -axis. Thus $\Im G^1 \circ r$ and $\Im G^3 \circ r$ are constants. By adjusting C we may assume that the constants are zeros. Remember that along r , $w \in \mathbf{R}$. Now let $U_+ := \{w \in U \mid \Re w \geq 0\}$ and $U_- := \{w \in U \mid \Re w \leq 0\}$. We can extend $G^1|_{U_+}$ and $G^3|_{U_+}$ to U by $\tilde{G}^i(w) = \overline{G^i(\bar{w})}$, for $i = 1, 3$, $w \in U_-$ and $\bar{w} \in U_+$. Since $\Re G^2 \circ r = 0$, we can extend $G^2|_{U_+}$ to U_- by $\tilde{G}^2(w) = -\overline{G^2(\bar{w})}$, for $w \in U_-$ and $\bar{w} \in U_+$. Since G is holomorphic, we know that \tilde{G} is holomorphic and $\tilde{G} = G$ on U . Choose a small disk $D \subset U_- \cup U_+$ such that $\bar{D} = D$, then $Y = \Re \tilde{G}$ is a minimal surface on D . Since $X = Y$ on $D \cap U_-$, by the Extension Theorem (Theorem 4.2), $X = Y$ on D . Looking at the real part, we have for any $w \in D$,

$$(X^1(w), X^2(w), X^3(w)) = \Re G(w) = \Re \tilde{G}(w) = (X^1(\bar{w}), -X^2(\bar{w}), X^3(\bar{w})) = X(\bar{w}),$$

which is a reflection in the xz -plane. By the Extension Theorem (Theorem 4.2) again, this reflection is a congruence of X .

Similarly we can prove that if $X \circ r$ is a straight line segment, then the rotation by 180° around $X \circ r$ is a congruence of X . \square

Exercise : Prove that if $X \circ r$ is a straight line segment, then rotation by 180° around $X \circ r$ is a congruence of X .

Finally, we show that each component of the Gauss map N is an eigenvector of the Laplace operator Δ_X . First remember that for a conformal representation of a minimal surface, $\Delta_X = \Lambda^{-2} \Delta$.

Proposition 8.3 *The Gauss map N satisfies*

$$\Delta_X N = 2KN, \tag{8.36}$$

where K is the Gauss curvature.

Proof. Let g and η be the Enneper-Weierstrass data for X . On an isothermal neighbourhood (U, z) we have

$$\begin{aligned} \Delta N &= 4 \frac{\partial^2}{\partial z \partial \bar{z}} N = 4 \frac{\partial^2}{\partial z \partial \bar{z}} \left[\frac{1}{1 + |g|^2} (2\Re g, 2\Im g, |g|^2 - 1) \right] \\ &= \left[4 \frac{\partial^2}{\partial z \partial \bar{z}} (1 + |g|^2)^{-1} \right] (2\Re g, 2\Im g, |g|^2 - 1) + 4(1 + |g|^2)^{-1} \frac{\partial^2}{\partial z \partial \bar{z}} (2\Re g, 2\Im g, |g|^2 - 1) \\ &\quad + 8\Re \left\{ \left[\frac{\partial}{\partial z} (1 + |g|^2)^{-1} \right] \frac{\partial}{\partial \bar{z}} (2\Re g, 2\Im g, |g|^2 - 1) \right\}. \end{aligned}$$

Since g is holomorphic,

$$\begin{aligned}\frac{\partial}{\partial z}(1 + |g|^2)^{-1} &= \frac{-g'\bar{g}}{(1 + |g|^2)^2}, \\ 4\frac{\partial^2}{\partial z\partial\bar{z}}(1 + |g|^2)^{-1} &= \frac{4|g'|^2(|g|^2 - 1)}{(|g|^2 + 1)^3}.\end{aligned}$$

Using the Cauchy-Riemann equations we have

$$\frac{\partial}{\partial\bar{z}}(2\Re g, 2\Im g, |g|^2 - 1) = (\bar{g}', i\bar{g}', g\bar{g}').$$

Since $\Re g$ and $\Im g$ are harmonic,

$$\frac{\partial^2}{\partial z\partial\bar{z}}(2\Re g, 2\Im g, |g|^2 - 1) = (0, 0, |g'|^2).$$

Hence

$$\begin{aligned}\Delta N &= \frac{4|g'|^2(|g|^2 - 1)}{(1 + |g|^2)^3}(2\Re g, 2\Im g, |g|^2 - 1) + 4(1 + |g|^2)^{-1}(0, 0, |g'|^2) \\ &\quad + 8\Re\left[\frac{-g'\bar{g}}{(1 + |g|^2)^2}\bar{g}'(1, i, g)\right] \\ &= \frac{4|g'|^2(|g|^2 - 1)}{(1 + |g|^2)^3}(2\Re g, 2\Im g, |g|^2 - 1) + 4(1 + |g|^2)^{-1}(0, 0, |g'|^2) \\ &\quad + 8\left[\frac{-|g'|^2\bar{g}}{(1 + |g|^2)^2}(\Re g, \Im g, |g|^2)\right] \\ &= \frac{4|g'|^2}{(|g|^2 + 1)^2}\frac{|g|^2}{1 + |g|^2}(2\Re g, 2\Im g, |g|^2 - 1) + \frac{4|g'|^2}{(1 + |g|^2)^2}\frac{1}{1 + |g|^2}(0, 0, (1 + |g|^2)^2) \\ &\quad - \frac{4|g'|^2}{(1 + |g|^2)^2}\frac{1 + |g|^2}{1 + |g|^2}(2\Re g, 2\Im g, 2|g|^2) \\ &= \frac{-8|g'|^2}{(1 + |g|^2)^2}\left[\frac{1}{1 + |g|^2}(2\Re g, 2\Im g, |g|^2 - 1)\right] = \frac{-8|g'|^2}{(1 + |g|^2)^2}N.\end{aligned}$$

Now by (7.28) and (7.30),

$$K\Lambda^2 = \frac{-4|g'|^2}{(1 + |g|^2)^2},$$

and thus

$$\Delta N = 2K\Lambda^2 N.$$

□