## 4. INCREASING EVENTS.

This chapter contains the well known FKG inequality and a formula of Russo's for the derivative of $P_{p}\{E\}$ with respect to $p$ for an increasing event $E$. No periodicity assumptions are necessary in this chapter, so that we shall take as our probability space the triple $\left(\Omega_{l}, \mathbb{B}_{l}, P_{l}\right)$ as defined in Sect. 3.1. $E_{l}$ will denote expectation with respect to $P_{V}$.
Def. 1 A $\mathbb{R}_{\imath}$-measurable function $f: \Omega_{\imath} \rightarrow \mathbb{R}$ is called increasing (decreasing) if it is ${ }^{1 \text { ) }}$ increasing (decreasing) in each $\omega(v), V \in l$. An event $E \in \mathfrak{b}_{\checkmark} \quad$ is called increasing (decreasing) if its indicator function is increasing (decreasing).

## Examples

(i) $\{\# \mathrm{~W}(\mathrm{v})\}$ is an increasing function, since making more sites occupied can only increase $W(v)$.

$$
\begin{equation*}
E_{1}=\{\# W(v)=\infty\} \quad \text { for fixed } v \text { is an increasing } \tag{ii}
\end{equation*}
$$

event; if $E_{1}$ occurs in the configuration $\omega^{\prime}$, and every site which is occupied in $\quad \omega^{\prime}$ is also occupied in $\quad \omega^{\prime \prime}$ - and possibly more sites are occupied in $\omega^{\prime \prime}$ - then $E_{1}$ also occurs in confiquration $\omega^{\prime \prime}$.
(iii) $\quad E_{2}=\left\{\exists\right.$ an occupied path on $\mathscr{G}$ from $v_{1}$ to $\left.v_{2}\right\}$ for fixed vertices $v_{1}$ and $v_{2}$ is increasing for the same reasons as $E_{1}$ in ex. (ii).
(iv) The most important example of an increasing event for our purposes is the existence of an occupied crosscut of a certain Jordan domain in $\mathbb{R}^{2}$. More precisely we shall be interested in pair of
 $m_{p l}$ will be the planar modifications of $\mathscr{G}_{6}, \mathscr{y}^{*}$ and $\pi_{6}$ respectively (see Sect. 2.2 and 2.3) . Let $J$ be a Jordan curve on $m_{p \ell}$

[^0]consisting of four closed areas $B_{1}, A_{1}, B_{2}$ and $C$ with disjoint interiors. Then
\[

$$
\begin{aligned}
& E_{3}:=\left\{\exists \text { occupied path } r \text { on } \mathscr{C}_{p \ell}\right. \text { with initial (final) } \\
& \text { point on } B_{1}\left(B_{2}\right) \text { and such that } r \text { minus its endpoints } \\
&\text { is contained in int }(J)\} .
\end{aligned}
$$
\]

is an increasing event. For further details see Ex. (iii) in the next section.

Before treating the principal results of this chapter we prove a simple lemma, stating that the expectation of an increasing function goes up when the probability that a site is occupied goes up. Inequality (4.2) gives an upper bound for this effect, though. The lemma will be useful later.

Lemma 4.1. If $f: \Omega_{v} \rightarrow[0, \infty)$ is an increasing non-negative function and

$$
P_{v}=\prod_{v \varepsilon v} \mu_{v} \quad, P_{i}^{\prime}=\prod_{v \varepsilon v} \quad \mu_{v}^{\prime}
$$

are two product measure on $\quad \Omega_{v} \quad$ which satisfy

$$
\mu_{v}^{\prime}\{\omega(v)=1\} \geq \mu_{v}\{\omega(v)=1\}, v \varepsilon u,
$$

then (with $E_{l}\left(E_{l}^{\prime}\right)$ denoting expectation with respect to $P_{l}\left(P_{l}^{\prime}\right)$ )

$$
\begin{equation*}
E_{l}^{\prime} f \geq E_{l} f . \tag{4.1}
\end{equation*}
$$

If $f \geq 0$ depends only on the $\omega(v)$ for $v$ in a subset $w$ of $v \quad$ with cardinality $m=\# \psi$, then.

$$
\begin{equation*}
E_{l}^{\prime} f \leq\left(\max _{\left.v \varepsilon u^{\prime} \frac{\mu_{v}^{\prime}\{\omega(v)=1\}}{\mu_{v}\{\omega(v)=1\}}\right)^{m} \quad E_{v} \quad f .} .\right. \tag{4.2}
\end{equation*}
$$

For a decreasing non-negative function $f$ the inequality in (4.1) is reversed, while (4.2) is to be replaced by

$$
E_{v} f \leq\left(\max _{v \in w} \frac{\mu_{v}\{\omega(v)=-1\}}{\mu_{v}^{\prime}\{\omega(v)=-1\}}\right)^{m} E_{v}^{\prime} \quad f
$$

Proof: The lemma is proved by "coupling". We construct a measure
$P$ on $\left(\Omega_{v} \times \Omega_{v}, \mathbb{B}_{v} \times \mathbb{Q}_{v}\right)$ such that its marginal distribution on the first (second) factor is $P_{l}\left(P_{l}^{\prime}\right)$ and with the following properties:
(4.3) $\quad P$ is a product measure $\prod_{V \in \downarrow}$,
where $v_{v}$ is a measure on $\{-1,1\} \times\{-1,1\}$. Thus if we write a generic point of $\Omega_{\imath} \times \Omega_{\imath}$ as $\left\{\left(\omega(v), \omega^{\prime}\left(v_{\prime}^{\prime}\right): v \varepsilon \downarrow\right\}\right.$, then the random variables $\left(\omega(v), \omega^{\prime}(v)\right), v \varepsilon l$, are indeperdent under $P$. Moreover we will have

$$
\begin{array}{l|l}
P\{\omega(v)=1 & \left.\omega^{\prime}(v)=1\right\}=\frac{\mu\{\omega(v)=1\}}{\mu^{\prime}\{\omega(v)=1\}} \tag{4.4}
\end{array}
$$

and

$$
\begin{equation*}
P\left\{\left(\omega, \prime^{\prime}\right) \varepsilon \Omega_{v} \times \Omega_{v}: \omega(v) \leq \omega^{\prime}(v) \text { for all } v\right\}=1 . \tag{4.5}
\end{equation*}
$$

To corstruct such a product measure we merely have to choose the $\nu_{v}$ suitably. Ne take

$$
\begin{aligned}
& \nu_{v}\left\{\omega(v)=-1, \quad \omega^{\prime}(v)=-1\right\}=\mu_{v}^{\prime}\{\omega(v)=-1\}, \\
& \nu_{v}\left\{\omega(v)=-1, \omega^{\prime}(v)=1\right\}=\mu_{v}^{\prime}\{\omega(v)=1\}-\mu_{v}\{\omega(v)=1\}, \\
& \nu_{v}\left\{\omega(v)=1, \quad \omega^{\prime}(v)=-1\right\}=0, \\
& \nu_{v}\left\{\omega(v)=1, \quad \omega^{\prime}(v)=1\right\}=\mu\{\omega(v)=1\} .
\end{aligned}
$$

(4.4) and (4.5) obviously hold for these $\nu_{v}$, and one easily checks that $P$ has the prescribed marginal distributions. Now, for any increasing $f \geq 0$, by (4.5)

$$
\begin{aligned}
E_{l}^{\prime} f & =\int_{\Omega_{l}} f\left(\omega^{\prime}\right) d P_{l}^{\prime}\left(\omega^{\prime}\right)=\int_{l} \times \Omega_{l} f\left(\omega^{\prime}\right) d P\left(\omega, \omega^{\prime}\right) \\
& \geq \Omega_{l} \int_{\times \Omega_{l}} f(\omega) d P\left(\omega=\omega^{\prime}\right)=E_{l} f .
\end{aligned}
$$

This proves (4.1).
To prove (4.2) note that (4.4) implies

$$
\begin{aligned}
& P\left\{\omega(v) \geq \omega^{\prime}(v) \text { for all } v \varepsilon \| \omega^{\prime}\right\} \\
& =\prod_{v \in \omega} P\left\{\omega(v)=1 \mid \omega^{\prime}(v)=1\right\} \geq\left(\min _{v \in \omega} \frac{\mu\{\omega(v)=1\}}{\mu^{\prime}\{\omega(v)=1\}}\right)^{m} . \\
& \omega^{\prime}(v)=1
\end{aligned}
$$

For an increasing $f \geq 0$ which depends only on the occupancies in us we now have

$$
\begin{aligned}
& E_{\imath} f=\Omega_{\imath} \int_{x} \Omega_{\imath} f(\omega) d P\left(\omega, \omega^{\prime}\right) \\
& \geq \Omega_{\imath} \int_{\times} f\left(\Omega_{\imath}\right) d P\left(\omega, \omega^{\prime}\right) \\
& \omega(v) \geq \omega^{\prime}(v) \text { on } u \\
&=\int_{\Omega} f\left(\omega^{\prime}\right) P\left\{\omega(v) \geq \omega^{\prime}(v) \text { for all } v \in \omega \mid \omega^{\prime}\right) d P\left(\omega^{\prime}\right) \\
& \geq\left(\min _{v \varepsilon \omega_{0}} \frac{\mu\{\omega(v)=1\}}{\mu^{\prime}\{\omega(v)=1\}}\right)^{m} \quad E_{l}^{\prime} f .
\end{aligned}
$$

This is equivalent to (4.2). We leave it to the reader to derive the analogues of (4.1) and (4.2) for decreasing $f$, by interchanging the roles of $E_{V}$ and $E_{V}^{\prime}$.
4.1. The FKG inequality.

We only discuss the very special case of the FKG inequality which we need in these notes. This special case already appeared in Harris (1960). For more general versions the reader can consult the original article of Fortuin, Kasteleyn and Ginibre (1971) or the recent article by Batty and Bollman (1980) and its references.

Proposition 4.1. If $f$ and $g$ are two bounded functions on $\Omega_{l}$ which depend on finitely many coordinates of $\omega$ only and which are both increasing or both decreasing functions, then

$$
\begin{equation*}
E_{V}\{f(\omega) g(\omega)\} \geq E_{V}\{f(\omega)\} E_{V}\{g(\omega)\} \text {. } \tag{4.6}
\end{equation*}
$$

In particular, if $E$ and $F$ are two increasing events, or two decreasing events, which depend on finitely many coordinates of
$\omega$ only, then

$$
\begin{equation*}
P_{\imath}\{E \cap F\} \geq P_{\imath}\{E\} \cdot P_{\ell}\{F\} \text {. } \tag{4.7}
\end{equation*}
$$

Proof: For (4.6) it suffices to take $f$ and $g$ increasing. The decreasing case follows by applying (4.6) to $-f$ and $-g$. Order the elements of $l$ in some arbitrary way as $v_{1}, v_{2}, \ldots$, and write $\omega_{i}$ for $\omega\left(v_{i}\right)$. Without loss of generality assume that $f(\omega)$ and $g(\omega)$ depend on $\omega_{1}, \ldots, \omega_{n}$ only. If $n=1$, then (4.6) follows from the fact that for each $\omega_{1}, \omega_{1}^{\prime}$,

$$
\left\{f\left(\omega_{1}\right)-f\left(\omega_{p}^{\prime}\right)\right\}\left\{g\left(\omega_{1}\right)-g\left(\omega_{1}^{\prime}\right)\right\} \geq 0
$$

(check the cases $\omega_{1} \geq \omega_{1}^{\prime}$ and $\omega_{1} \leq \omega_{1}^{\prime}$ ). Thus

$$
\begin{aligned}
0 & \leq \iint\left\{f\left(\omega_{1}\right)-f\left(\omega_{1}^{\prime}\right)\right\}\left\{g\left(\omega_{1}\right)-g\left(\omega_{j}^{\prime}\right)\right\} P_{L}(d \omega) P_{G}\left(d \omega^{\prime}\right) \\
& =2 E_{\succeq}\{f g\}-2 E_{\imath}\{f\} E_{V}\{g\} .
\end{aligned}
$$

The general case of (4.6) follows by induction on $n$ since

$$
\begin{aligned}
& E_{l}\{f g\}=E_{l}\left\{E_{l}\left\{f g \mid \omega_{2}, \ldots,{ }_{n}\right\}\right\}, \\
& \geq E_{l}\left\{E_{l}\left\{f \mid \omega_{2}, \ldots, \omega_{n}\right\} E_{l}\left\{g \mid \omega_{2}, \ldots, \omega_{n}\right\}\right\}
\end{aligned}
$$

(since for fixed $\omega_{2}, \ldots, \omega_{n}, f(\omega)$ and $g(\omega)$ are increasing functions of $\omega_{1}$ only)

$$
\geq E_{l}\left\{E_{l}\left\{f \mid \omega_{2}, \ldots, \omega_{n}\right\}\right\} E_{l}\left\{E_{l}\left\{g \mid \omega_{2}, \ldots, \omega_{n}\right\}\right\}
$$

(since $E_{l}\left\{f \mid \omega_{2}, \ldots, \omega_{n}\right\}$ is an increasing function of $\omega_{2}, \ldots, \omega_{n}$ and similarly for $g$, plus the induction hypotheses) $=E_{l}\{f\} E_{\imath}\{g\}$.

This proves (4.6) and (4.7) is the special case with $f=I_{E}, g=I_{F} \cdot \square$

## Application.

For a simple application of the FKG inequality let $\mathrm{v}_{1}, \mathrm{v}_{2}$ be two vertices of a connected graph $\mathcal{C}_{\mathcal{G}}$. Then if there is an occupied path from $v_{1}$ to $v_{2}$ the occupied clusters of $v_{1}$ and $v_{2}$ are identical. Therefore, by (4.7) and Ex. 4(i) and 4(iii).

$$
\begin{align*}
& \qquad P_{v}\left\{\# W\left(v_{1}\right) \geq n\right\} \geq P_{v}\left\{\exists \text { occupied path from } v_{1} \text { to } v_{2}\right.  \tag{4.8}\\
& \text { and } \left.\# W\left(v_{2}\right) \geq n\right\} \geq P_{l}\left\{\exists \text { occupied path from } v_{1} \text { to } v_{2}\right\} \\
& P_{\imath}\left\{\# W\left(v_{2}\right) \geq n\right\} .
\end{align*}
$$

If $\mathcal{G}$ is connected and $P_{V}\{v$ is occupied $\}>0$ for all $v$, then also

$$
P_{\imath}\left\{\exists \text { occupied path from } v_{1} \text { to } v_{2}\right\}>0 .
$$

Therefore

$$
\begin{aligned}
& \theta\left(v_{2}\right)>0 \text { implies } \theta\left(v_{1}\right)>0 \text { and } \\
& E\left\{\# W\left(v_{2}\right)\right\}=\infty \text { implies } E\left\{\# W\left(v_{1}\right)\right\}=\infty
\end{aligned}
$$

This justifies our statement in Sect. 3.4, that $P_{H}$ and $P_{T}$ are independent of the choice of $v$.
4.2. Pivotal sites and Russo's formula.

Def. 2. Let $E \varepsilon \mathbb{a}_{l}$ be an event and $\omega \in \Omega_{l} \quad$ an occupancy configuration. A site $v \varepsilon l$ is called pivotal for ( $E, \omega$ ) (or for E for short) iff

$$
I_{E}(\omega) \neq I_{E}\left(T_{v} \omega\right)
$$

where $T_{v} \omega \in \Omega \quad$ is determined by

$$
T_{v} \omega(w)=\left\{\begin{align*}
w(w) & \text { for } w \in v \text { but } w \neq v  \tag{4.9}\\
-w(v) & \text { for } w=v .
\end{align*}\right.
$$

In other words, $v$ is pivotal, if changing the occupancy of $v$ only changes the occupancy configuration from one where $E$ occurs to one where $E$ does not occur, or vice versa.

## Examples.

(i) Let $E_{1}$ be as in Ex. 4(ii) and take

$$
F_{1}=\{\omega: \# W(w, \omega)=\infty \quad \text { for some neighbor } w \text { of } v\}
$$

Then $v$ is pivotal for $\left(E_{1}, \omega\right)$ iff $\omega \varepsilon F_{1}$. Indeed for $\omega \varepsilon F_{1}, E_{1}$ occurs af $v$ itself is occupied (recall that $W(v)=\emptyset$ if $v$ is vacant), and hence $I_{E_{1}}(\omega)$ will change with $\omega(v)$ for $\omega \in F_{1}$. On the other hand, if $\omega \notin F_{1}$, then $\# W(v, \omega)<\infty$, no matter what $\omega(v)$ is.
(ii) Let $E_{2}$ be as in Ex. 4(iii) and take

$$
\begin{aligned}
F_{2}= & E_{2} \cap\left\{\omega: \text { all occupied paths from } v_{1}\right. \text { to } \\
& \left.v_{2} \text { contain the vertex } v\right\} .
\end{aligned}
$$

Then

$$
\mathrm{I}_{\mathrm{E}_{2}}(\omega)=1 \text { and } \omega(v)=1 \text { for } \omega \in \mathrm{F}_{2}
$$

But in $T_{v^{\omega}}{ }^{\omega}, v$ is vacant and there are no longer any occupied paths from $v_{1}$ to $v_{2}$, since on $F_{2}$ all these paths had to go through $v$, and $v$ has now been made vacant. Thus $v$ is pivotal for $\left(E_{2}, \omega\right)$ whenever $\omega \in \quad F_{2}$.
(iii) This example plays a fundamental role in the later development. Let $\left(y, y^{*}\right)$ be a periodic matching pair of graphs in $\mathbb{R}^{2}$, based on $\left(\pi_{l}, \vec{F}\right)$ and let $\mathcal{C}_{p \ell}, \mathcal{C}_{\dot{f} \ell}^{*}$ and $m_{p l}$ be the planar modifications defined in Sect. 2.3. This time we take $u=$ vertex set of $G_{p \ell}$ and define $\Omega_{u}, \mathbb{B}_{\imath}$ accordingly. We are interested in the existence of "occupied crosscuts of Jordan domains". More precisely, let $J$ be a Jordan curve on $m_{p l}$, consisting of four closed arcs, $B_{1}, A, B_{2}$ and $C$, with disjoint interiors and occuring in this order as $J$ is traversed in one direction. $\bar{J}=\operatorname{int}(J) \cup J$. We consider paths $r=\left(v_{0}, e_{1}, \ldots, e_{v}, v_{v}\right)$ on $G_{\text {El }}$ which satisfy

$$
\begin{equation*}
\left(e_{1} \backslash\left\{v_{0}\right\}, v_{1}, e_{2}, \ldots, e_{v-1}, v_{v-1}, e_{v} \backslash\left\{v_{v}\right\}\right) \subset \operatorname{int}(u), \tag{4.10}
\end{equation*}
$$

and

$$
\begin{equation*}
v_{0} \varepsilon B_{1}, v_{v} \varepsilon B_{2} . \tag{4.11}
\end{equation*}
$$

(4.10) and (4.11) are just the conditions (2.23) - (2.25) in the present setup, since an edge of $\mathscr{C}_{\mathrm{p} \ell} \subset M_{\mathrm{pl}} \quad$ can intersect
the curve $J$ on $m_{p l}$ in a vertex of $m_{p l}$ only, by virtue of the planarity of $m_{p l}$. We call any path $r$ on $\mathcal{G}_{p l}$ which satisfies (4.10) and (4.11) a crosscut of int(J) . We can now define $J^{-}(r)$ and $J^{+}(r)$ as in Def. 2.11 and order $r_{1}$ and $r_{2}$ as in Def. 2.12, whenever $r, r_{1}, r_{2}$ satisfy (4.10) and (4.11). We take
$E_{3}=\{\omega: \exists$ at least one occupied crosscut of $\operatorname{int}(J)\}$, and we want to find the pivotal sites for $\left(E_{3}, \omega\right)$ when $\omega \in E_{3}$. By Prop. 2.3, if $E_{3}$ occurs, then there exists a unique lowest crosscut of $\operatorname{int}(J)$ on $G_{p l}$, which we denote by $R(\omega)$. Now let $\omega \in E_{3}$, so $R(\omega)$ exists and $v$ a vertex which is not on $R$. Then changing the occupancy of $v$ leaves the crosscut $R$ intact and such a site $v$ is therefore not pivotal for $\left(E_{3}, \omega\right)$. Next consider a $v$ on $R \cap \operatorname{int}(J)$ which has a $\frac{\text { vacant connection to }{ }_{\star} \dot{C}_{\star}^{*}}{*}$ By this we mean that there exists a path $s^{\star}=\left(v_{0}^{*}, e_{1}^{*}, \ldots, e_{\rho}^{*}, v_{\rho}^{*}\right)$ on $\mathcal{C}_{p l}^{*}$ satisfying the following conditions (4.13) - (4.16):

$$
\begin{equation*}
\text { there exists an edge e of } m_{p l} \text { between } v \text { and } v_{0} \tag{4.13}
\end{equation*}
$$ such that $\mathrm{e} \subset \mathrm{J}^{+}(\mathrm{R})$ (in particular $v M_{p l} v_{0}$ ),

$$
\begin{equation*}
v_{\rho}^{\star} \varepsilon \text { C } \tag{4.14}
\end{equation*}
$$

$$
\begin{equation*}
\left(v_{0}^{*}, e_{1}^{*}, \ldots, v_{\rho-i}^{*}, e_{\rho}^{*} \backslash\left\{v_{\rho}^{*}\right\}\right) \subset J^{+}(R) \tag{4.15}
\end{equation*}
$$

all vertices of $s^{*}$ are vacant.
We allow here the possibility $\rho=0$ in which case $s^{*}$ reduces to the single vertex $v_{0}^{*}=v_{\rho}^{*}$, and we make the convention that (4.15) is automatically fulfilled in this case. We claim that any $v \in R \cap \operatorname{int}(J)$ with such a vacant connection to $\stackrel{\circ}{C}$ is pivotal for $\left(E_{3}, \omega\right)$ whenever $\omega \in E_{3}$. To prove this claim note that $v$ is on $R(\omega)$, hence is occupied in $\omega$, and therefore vacant in $T_{v} \omega$. If there would exist an occupied crosscut $r$ of $\operatorname{int}(J)$ in $T_{v}{ }^{\omega}$, then $r$ could not contain $v$, which is vacant in $T_{v}{ }^{\omega}$. Thus $r$ would also be occupied in $\omega$ and by Prop. 2.3 (see (2.27)) we would have

$$
\begin{equation*}
r \varepsilon \bar{J}^{+}(R) . \tag{4.17}
\end{equation*}
$$

Now, if $R=\left(v_{0}, e_{1}, \ldots, e_{v}, v_{v}\right)$, then the boundary of $J^{+}(R)$ consists of $R$, the segment of $B_{2}$ from $v_{v}$ to the intersection of $B_{2}$
with $C$ (call this segment $B_{2}^{+}$), $C$, and the segment of $B_{1}$ from the intersection of $B_{1}$ with $C$ to $v_{0}\left(c a l l\right.$ this segment $\left.B_{1}^{+}\right)$; see Fig. 4.1. This boundary is, in fact, a Jordan curve.


Figure 4.1
Since $r$ would begin on $B_{1}$ and end on $B_{2}$ and satisfy (4.17) it would in fact connect a point on $\mathrm{B}_{1}^{+}$with a point on $\mathrm{B}_{2_{*}^{+}}$inside $\bar{J}^{+}(R)$. Next consider, the path $\tilde{s}:=\left(v, e, v_{0}^{*}, e_{1}^{*}, \ldots, e_{\nu}^{*}, v_{v}^{*}\right)$, where $e$ is as in (4.13). From the requirements ${ }^{\circ} \subset J^{+}(R),(4.14)$ and (4.15) it follows that $\tilde{s}$ is a crosscut of $J^{+}(R)$. Moreover, its endpoints $-v$ on $R \cap \operatorname{int}(J)$ and $v_{\rho}^{*}$ on $\AA_{C}^{\circ}$ - separate the endpoints of $r$ on $B_{1}^{+}$and $B_{2}^{+}$. Thus $r$ would have to intersect $\tilde{s}$. This, however, is impossible. Indeed, the paths $r$ and $\tilde{s}$ on $m_{p \ell}$ would have to intersect in a vertex of $m_{p \ell}$ (recall that $m_{l e}$ is planar) which would have to be occupied - being a vertex of $r_{*}$ - as well as vacant - being also a vertex on $\tilde{s}$. (Note that the $v_{i}^{*}$ are vacant in $\omega$, hence in $T_{v} \omega$, and $v$ became vacant in $T_{v} \omega$ ). Thus no occupied crosscut $r$ of $\operatorname{int}(J)$ can exist in $T_{v} \omega$, ie., $T_{v} \omega \notin E_{3}$, which proves our claim.

We remark (without proof) that a certain converse of the above holds. Assume that $A \cap B_{i}$ as well as $C \cap B_{i}$ is a vertex of $m_{p l}, i=1,2$. Then under the convention (2.15), (2.16) the only pivotal sites on $R \cap \operatorname{int}(J)$ for ( $E_{3}, \omega$ ) are vertices which have a vacant connection to $C$. (We call $s^{*}$ a vacant connection to $C$ if (4.13) (4.15) and (4.16) hold but (4.14) is replaced by $v_{\rho}^{*} \varepsilon C$ ). This can be derived from a variant of Prop. 2.2. We shall, however, not need this fact.
Proposition 4.2 (Russo's formula) Let $E \in \mathcal{B}_{\checkmark}$ be an increasing event and $P_{i}$ as in (3.3), (3.4) with $\mathcal{E}$ replaced by $u$.

Then
(4.18) $\quad \frac{\partial}{\partial p(v)} P_{G}\{E\}=P_{G}\{v$ is pivotal for $(E, w)\}$.

Let $p^{\prime}$ and $p^{\prime \prime}$ be any two functions from $v$ into $[0,1]$ and set

$$
\begin{align*}
\mu_{v t}\{\omega(v) & =1\}=1-\mu_{v t}\{\omega(v)=-1\}  \tag{4.19}\\
& =(1-t) p^{\prime}(v)+t p^{\prime \prime}(v), v \varepsilon u, 0 \leq t \leq 1,
\end{align*}
$$

$$
\begin{equation*}
P_{v_{t}}=\prod_{v \varepsilon v} \mu_{v t} \tag{4.20}
\end{equation*}
$$

If

$$
\begin{equation*}
p^{\prime}(v) \leq p^{\prime \prime}(v) \text { for all } v \varepsilon u \text {, } \tag{4.21}
\end{equation*}
$$

and $E$ is an increasing event which depends on the occupancy of finitely many vertices only, then for any subset $w$ of $v$, then

$$
\begin{align*}
& \frac{d}{d t} P_{v t}\{E\}  \tag{4.22}\\
= & \sum_{v i}\left\{p^{\prime \prime}(v)-p^{\prime}(v)\right\} P_{\imath t}\{v \text { is pivotal for } E\} \\
\geq & \inf _{v \varepsilon w}\left\{p^{\prime \prime}(v)-p^{\prime}(v)\right\} E_{v t}\{\# \text { of pivotal sites for } \\
& E \text { in } w\} .
\end{align*}
$$

(Of course $E_{l_{t}}$ denotes expectation with respect to $\quad P_{\text {lt }}$ )
Proof: (Russo (1981)). To prove (4.18) write

$$
\begin{align*}
P_{l}\{E\} & =E_{l}\left\{I_{E}\right\}=p(v) E_{l}\left\{I_{E} \mid v \text { is occupied }\right\}  \tag{4.23}\\
& +(1-p(v)) E_{V}\left\{I_{E} \mid v \text { is vacant }\right\} .
\end{align*}
$$

Since $\omega(v)$ is independent of all other sites, the conditional expectations in the right hand side of (4.23) are integrals with respect to $\prod_{w \neq v} \mu_{w}$ and are independent of $p(v)$. Therefore

$$
\begin{align*}
\frac{\partial}{\partial p(v)} P_{l}\{E\} & =E_{l}\left\{I_{E} \mid v \text { is occupied }\right\}  \tag{4.24}\\
& -E_{l}\left\{I_{E} \mid v \text { is vacant }\right\}
\end{align*}
$$

Next set

$$
J=J(\omega)=J(\omega ; E, v)= \begin{cases}1 & \text { if } v \text { is pivotal for }(E, \omega) \\ 0 & \text { if } v \text { is not pivotal for }(E, \omega)\end{cases}
$$

Then, from (4.24)
(4.25) $\frac{\partial}{\partial p(v)} P_{l}\{E\}=E_{l}\left\{I_{E} J \mid v\right.$ is occupied $\}$

$$
\begin{aligned}
& +E_{q}\left\{I_{E}(1-J) \mid v \text { is occupied }\right\}-E_{q}\left\{I_{E} J \mid v \text { is vacant }\right\} \\
& -E_{q}\left\{I_{E}(1-J) \mid v \text { is vacant }\right\} .
\end{aligned}
$$

Now the function $I_{E}(\omega)(1-J(\omega))$ can take only the values 0 and 1 : $I_{E}(\omega)(1-J(\omega))=1$ only if $E$ occurs and $v$ is not pivotal for ( $\mathrm{E}, \omega$ ), i.e., E occurs in $\omega$, and also if $\omega(v)$ is changed to $-\omega(v)$. Clearly $I_{E}(\omega)(1-J(\omega))=1$ is a condition on $\omega(w), w \neq v$, only, so that $I_{E}(\omega)(1-J(\omega))$ is independent of $\omega(v)$. Therefore the second and fourth term in the right hand side of (4.25) cancel. Also, if $v$ is pivotal for $(E, \omega)$ and $E$ is increasing, then $E$ must occur if $\omega(v)=1$ and cannot occur if $\omega(v)=-1$. Therefore the third term in the right hand side of (4.25) vanishes. This leaves us with

$$
\begin{equation*}
\frac{\partial}{\partial p(v)} P_{v}\{E\}=\frac{E_{v}\left\{I_{E}(\omega) J^{\prime}(\omega) I[\omega(v)=+1]\right\}}{P_{v}\{\omega(v)=1\}} \tag{4.26}
\end{equation*}
$$

But, by the argument just given, $E$ must occur if $J(\omega) I[\omega(v)=1]=1$, so that we can drop the factor $I_{E}$ in the numerator on the right of (4.26). Finally $J(\omega)$ is again independent of $\omega(v)$, since $J(\omega)=1$ means $\omega(w), w \neq v$, is such that $E$ occurs when $\omega(v)=1$ and does not occur when $\omega(v)=-1$. Thus, the right hand side of (4.26) equals

$$
E_{V}\{J(\omega)\}=P_{V}\{v \text { is pivotal for } E\} .
$$

This proves (4.18). (4.22) follows now from the chain rule and
(4.21). (Note that $v$ can be pivotal for $E$ only if $I_{E}$ depends on $\omega(v)$; hence the sum in the middle of (4.22) has only finitely many non-zero terms).


[^0]:    1) We use "increasing" and "strictly increasing" instead of "nondecreasing" and "increasing".
