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# A LORENTZIAN SURFACE IN A FOUR-DIMENSIONAL MANIFOLD OF NEUTRAL SIGNATURE AND ITS REFLECTOR LIFT

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**Abstract.** A Lorentzian surface in a four-dimensional manifold of neutral signature is called super-extremal if its reflector lift is horizontal. We give an elementary proof of a rigidity theorem for super-extremal surfaces in the space of constant curvature and neutral signature. As corollary, a characterization of the immersion of the Veronese type is given.

## 1. Introduction

The twistor lifts play an important role for oriented surfaces in oriented fourdimensional Riemannian manifolds and have been studied by many researchers (see [1, 3–5, 7–10] for example). In geometry of pseudo-Riemannian manifold of neutral signature, the reflector bundle is the corresponding object to the twistor space. For Lorentzian surfaces in four-dimensional manifolds of neutral signature, the reflector lifts are defined in [12], which are corresponding to the twistor lifts in Riemannian case. In this paper, we study Lorentzian surfaces in four-dimensional manifolds of neutral signature with horizontal reflector lifts, which are corresponding to superminimal surfaces in Riemannian geometry. In pseudo-Riemannian geometry, because of the failure of definiteness for metrics, different situations often occur from Riemannian cases. For example, in Riemannian case, a connected minimal surface of constant Gaussian curvature in the Euclidean space must be flat and an open part of a two-plane (see [2]). But one can find many non-totally geodesic extremal flat surfaces in the pseudo-Euclidean space of neutral signature (see Section 4), where extremal means vanishing of the mean curvature vector field. We say that a Lorentzian surface is super-extremal if its reflector lift is horizontal.

Note that the notions of the reflector lift and super-extremal surface can be defined for higher even-dimentional cases. In [11], a rigidity theorem for super-extremal surfaces is obtained.

The purpose of this paper is to give several examples of surfaces such that their reflector lifts are horizontal or para-holomorphic and an elementary proof of a rigidity theorem in a low dimensional case, that is, in the case of super-extremal surfaces in the four-dimensional space forms  $Q_2^4(c)$  of constant curvature c and neutral signature.

#### 2. Preliminaries

Throughout this paper, all manifolds and maps are assumed to be smooth. Let E be a vector bundle over a manifold M and  $E_x$  the fiber of E over  $x \in M$ . We write TP for the tangent bundle of a manifold P. For vector bundles E, E' over M, we denote the homomorphism bundle whose fiber is the space of linear mappings  $E_x$  to  $E'_x$  by  $\operatorname{Hom}(E,E')$ , and set  $\operatorname{End}(E) := \operatorname{Hom}(E,E)$ . The space of all sections of a vector bundle E is denoted by  $\Gamma(E)$ . Let  $\varphi \colon N \to M$  be a smooth map and E a vector bundle over E. The pull back bundle of E by E is denoted by E is denoted by E.

In this section, we recall some definitions and equations for pseudo-Riemannian manifolds and submanifolds. Let  $\tilde{M}$  be a pseudo-Riemannian manifold with a fixed pseudo-Riemannian metric  $\tilde{g}$ . A tangent vector X of  $\tilde{M}$  is called **spacelike** if  $\tilde{g}(X,X)>0$  or X=0, **null** if  $\tilde{g}(X,X)=0$  and  $X\neq 0$ , and **timelike** if  $\tilde{g}(X,X)<0$ . The set of all null vectors at  $x\in \tilde{M}$  is called the nullcone at  $x\in \tilde{M}$ , which is denoted by  $\Lambda_{\tilde{g}}(x)$ . If  $\dim \tilde{M}-\nu=\nu$ , then we say that  $\tilde{M}$  is of **neutral signature**, where  $\nu$  is the index of  $\tilde{g}$ . We call a psudo-Riemannian manifold  $\tilde{M}$  Lorentzian if  $\nu=1$ .

Let (M,g) be a pseudo-Riemannian submanifold in  $(\tilde{M},\tilde{g})$ . We denote the Levi-Civita connection of  $\tilde{g}$  (respectively g) by  $\tilde{\nabla}$  (respectively  $\nabla$ ). Let  $\nabla^{\perp}$  be the normal connection of the normal bundle  $T^{\perp}M$ . Let  $\alpha$  and A be the second fundamental form and the shape operator of M. The mean curvature vector field of M is denoted by H. We define  $\nabla'\alpha$  by the equality

$$(\nabla_X'\alpha)(Y,Z) = \nabla_X^{\perp}\alpha(Y,Z) - \alpha(\nabla_X Y,Z) - \alpha(Y,\nabla_X Z)$$

for all  $X,Y,Z\in\Gamma(TM)$ . Let  $\tilde{R},R$  and  $R^{\perp}$  be the curvatures forms of  $\tilde{\nabla},\nabla$  and  $\nabla^{\perp}$ , respectively. Then the following equations hold

$$\tilde{g}(\tilde{R}(X,Y)Z,W) = g(R(X,Y)Z,W) + g^{\perp}(\alpha(X,Z),\alpha(Y,W)) -g^{\perp}(\alpha(X,W),\alpha(Y,Z))$$
(1)

$$\tilde{g}(\tilde{R}(X,Y)Z,\xi) = g^{\perp}((\nabla'_X\alpha)(Y,Z),\xi) - g^{\perp}((\nabla'_Y\alpha)(X,Z),\xi)$$
 (2)

$$\tilde{g}(\tilde{R}(X,Y)\xi,\zeta) = g^{\perp}(R^{\perp}(X,Y)\xi,\zeta) + g(A_{\xi}X,A_{\zeta}Y) - g(A_{\xi}Y,A_{\zeta}X)$$
(3)

for all  $X,Y\!\in\!TM$  and  $\xi,\zeta\in T^\perp M$ , where  $g^\perp$  is the metric of the normal bundle  $T^\perp M$ . We say that M is totally geodesic (respectively totally umbilic) if  $\alpha=0$  (respectively  $\alpha(X,Y)=g(X,Y)H$  for all  $X,Y\in TM$ ). If H=0, then M is called an extremal submanifold ([17]). Note that, in [12], a submanifold with H=0 is called string. Let  $\mathbb{R}^n_\nu$  be the pseudo-Euclidean space of the dimension n and the index  $\nu$  with the flat standard metric. Let  $(x^1,\ldots,x^{n+1})$  be the standard coordinate on  $\mathbb{R}^{n+1}$ . The pseudosphere  $S^n_\nu(r)$  of the index  $\nu$  and the radius r>0 is defined by

$$S_{\nu}^{n}(r) = \{ p \in \mathbb{R}_{\nu}^{n+1}; -\sum_{i=1}^{\nu} (x^{i}(p))^{2} + \sum_{j=\nu+1}^{n+1} (x^{j}(p))^{2} = r^{2} \}.$$

Similarly, the pseudohyperbolic space  $H^n_{\nu}(r)$  of the index  $\nu$  and the radius r>0 is defined by

$$H_{\nu}^{n}(r) = \{ p \in \mathbb{R}_{\nu+1}^{n+1}; -\sum_{i=1}^{\nu+1} (x^{i}(p))^{2} + \sum_{j=\nu+2}^{n+1} (x^{j}(p))^{2} = -r^{2} \}.$$

The all spaces  $\mathbb{R}^n_{\nu}$ ,  $\mathrm{S}^n_{\nu}(r)$  and  $H^n_{\nu}(r)$  are of constant curvature  $0, 1/r^2, -1/r^2$ . We denote the space form by  $Q^n_{\nu}(c)$  which is one of  $\mathbb{R}^n_{\nu}$ ,  $\mathrm{S}^n_{\nu}(r)$  or  $H^n_{\nu}(r)$ , where n is the dimension,  $\nu$  is the index and c is constant curvature of  $Q^n_{\nu}(c)$ .

## 3. Reflector Bundles and Reflector Lifts

Let  $(\tilde{M}, \tilde{g})$  be an oriented four-dimensional manifold of neutral signature. The Hodge star operator is denoted by \*. Since  $*^2 = \mathrm{id}$  on the space of two-forms  $\Lambda^2(\tilde{M})$ , we have

$$\Lambda^2(\tilde{M}) = \Lambda^2_+(\tilde{M}) \oplus \Lambda^2_-(\tilde{M})$$

where  $\Lambda^2_{\pm}(\tilde{M})=\{\omega\in\Lambda^2(\tilde{M});\ *\omega=\pm\omega\}$ . Let  $(e_1,\ldots,e_4)$  of  $\tilde{M}$  be an orthonormal frame which is compatible with the orientation and  $\tilde{g}(e_i,e_i)=\varepsilon_i,$   $\varepsilon_1=\varepsilon_2=-1,\ \varepsilon_3=\varepsilon_4=1$ . We denote its dual frame by  $(\omega^1,\ldots,\omega^4)$ . Set  $s_1\!:=\omega^1\wedge\omega^2-\omega^3\wedge\omega^4, s_2\!:=\omega^1\wedge\omega^3-\omega^2\wedge\omega^4, s_3\!:=\omega^1\wedge\omega^4+\omega^2\wedge\omega^3.$  Then  $s_1,s_2,s_3$  is an orthonormal frame of  $\Lambda^2_-(\tilde{M})$ . Let  $J_i\in\Gamma(\mathrm{End}(T\tilde{M}))$  be the endomorphism corresponding to  $s_i\ (i=1,2,3)$ . Then we have  $J_1(e_1)=-e_2,\ J_1(e_3)=-e_4$  and so on. It is easy to see that  $(J_1)^2=-I,\ (J_2)^2=I,\ (J_3)^2=I$  and  $J_3=J_2J_1=-J_1J_2.$  Let Q be the vector subbundle of  $\mathrm{End}(T\tilde{M})$  which is locally spanned by  $J_1,J_2,J_3.$  We have  $\tilde{g}(J_1,J_1)=1,\ \tilde{g}(J_2,J_2)=-1,\ \tilde{g}(J_3,J_3)=-1,$  that is, the fiber metric of Q has the index two. It it easy to see

that Q is a parallel subbundle in  $\operatorname{End}(T\tilde{M})$  with respect to the connection which is induced by the Levi-Civita connection  $\tilde{\nabla}$  of  $\tilde{M}$ . We use the same letter  $\tilde{\nabla}$  for the connection of  $\operatorname{End}(T\tilde{M})$  induced by  $\tilde{\nabla}$ .

**Lemma 1.** Set  $J = aJ_1(x) + bJ_2(x) + cJ_3(x)$  at each  $x \in \tilde{M}$  (a, b,  $c \in \mathbb{R}$ ). The following statements are mutually equivalent: 1)  $J^2 = I$ , 2)  $-a^2 + b^2 + c^2 = 1$ , 3)  $\tilde{g}_x(J,J) = -1$ .

We define the reflector bundle Z by

$$Z = \bigcup_{x \in M} \{ J \in Q_x; \, \tilde{g}_x(J, J) = -1 \}.$$

The bundle projection  $p\colon Z\to \tilde M$  and the Levi-Civita connection  $\tilde \nabla$  on  $\tilde M$  induce the decomposition  $TZ=T^hZ\oplus T^vZ$  into the horizontal subbundle  $T^hZ$  and the vertical subbundle  $T^vZ$ . On the reflector bundle Z, the almost para-complex (or bilagrangian) structure  $J^Z$  is defined by  $J^Z(X)=(J(p_*(X)))^h_J$  for all horizontal vector X at  $J\in Z$  and  $J^Z(V)=J^v(V)$  for all vertical vector V, where  $Y^h$  is the horizontal lift of  $Y\in TM$  and  $J^v$  is the canonical para-complex structure on each fiber  $\simeq H^1_1(1)$ .

Let  $f\colon (M,g)\to (\tilde M,\tilde g)$  be an isometric immersion from an oriented two dimensional Lorentzian manifold (M,g) into an oriented four-dimensional manifold  $(\tilde M,\tilde g)$  of neutral signature. Using an orthonormal frame  $e_1,e_2,e_3,e_4$  adapted to the orientation of  $\tilde M$  such that  $e_1,e_3$  defines the orientation of M and  $e_2,e_4$  are normal to M, we define  $J\colon TM\to TM$  by  $J(e_1)=-e_3$  and  $J(e_3)=-e_1$ , and  $J^\perp\colon T^\perp M\to T^\perp M$  by  $J^\perp(e_2)=e_4$  and  $J^\perp(e_4)=e_2$ . Such frame  $e_1,e_2,e_3,e_4$  is said to be **adapted**. We define  $\tilde J\in \Gamma(f^\# Q)$  by

$$\tilde{J}(X){:=}\;J(X)\;\;\mathrm{and}\;\;\tilde{J}(\zeta){:=}\;J^\perp(\zeta)$$

for  $X \in TM$  and  $\zeta \in T^{\perp}M$ . Then  $\tilde{J} \in \Gamma(f^{\#}Q)$  is called the **reflector lift** of M (see [12]). Hereafter, we often omit the symbol "f" for the induced objects of the immersion f if there is no confusion for the simplicity. For reflector bundles and reflector lift, see [12].

**Lemma 2.** The para-complex structures J and  $J^{\perp}$  are parallel with respect to  $\nabla$  and  $\nabla^{\perp}$  respectively.

Here we define surfaces corresponding to superminimal and twistor holomorphic surfaces in Riemannian geometry. A surface M in  $\tilde{M}$  is called **super-extremal** if its reflector lift is horizontal, that is,  $\tilde{\nabla}\tilde{J}=0$ , where  $\tilde{\nabla}$  is the induced connection on  $f^\#Q$  from the Levi-Civita connection of  $\tilde{M}$ . By the similar way to the Riemannian case and using Lemma 2, we have

**Lemma 3.** A surface M is super-extremal if and only if the second fundamental form  $\alpha$  satisfies  $\alpha(X, JY) - J^{\perp}\alpha(X, Y) = 0$  for all  $X, Y \in TM$ .

A surface M in  $\tilde{M}$  is called *isotropic with negative spin* if its reflector lift is paraholomorphic (or bilagrangian), that is,  $\tilde{J}_* \circ J = J^Z \circ \tilde{J}_*$  (precisely,  $(f_\# \circ \tilde{J})_* \circ J = J^Z \circ (f_\# \circ \tilde{J})_*$ ), see [12]. A surface is called isotropic with positive spin if the reflector lift is para-holomorphic with respect to the opposite orientation. We also obtain

**Lemma 4.** A surface M is isotropic with negative spin if and only if the second fundamental form  $\alpha$  satisfies

$$J^{\perp}\alpha(JX,JY) - \alpha(JX,Y) - \alpha(X,JY) + J^{\perp}\alpha(X,Y) = 0, \qquad X,Y \in TM.$$

After proving fundamental lemmas for super-extremal and isotropic surfaces with negative spin, we give examples of such surfaces in the next section. We define  $\beta$  and  $\gamma$  by

$$\beta(X,Y) = \alpha(X,JY) - J^{\perp}\alpha(X,Y)$$

and

$$\gamma(X,Y) = J^{\perp}\alpha(JX,JY) - \alpha(JX,Y) - \alpha(X,JY) + J^{\perp}\alpha(X,Y)$$

for  $X,Y\in TM$ . Let K be the Gaussian curvature of M. We define the normal curvature function  $K^{\perp}$  by  $K^{\perp}=g^{\perp}(R^{\perp}(e_1,e_3)e_4,e_2)$  and a function  $\rho$  by

$$\rho = g^{\perp}(\alpha(e_1, e_3) + J^{\perp}\alpha(e_1, e_1), \alpha(e_1, e_3) + J^{\perp}\alpha(e_3, e_3))$$

where  $(e_1,\ldots,e_4)$  is an adapted frame. Note that  $\rho=0$  if M is super-extremal. We summarize the fundamental formulae which we use in this paper. These are obtained by the straightforward calculations. By the definition of  $\rho$  and (3), we have

$$\rho = -\det A_{e_2} + \det A_{e_4} + K^{\perp} - \tilde{g}(\tilde{R}(e_1, e_3)e_4, e_2).$$

By (1), it is easy to see

$$K = -\det A_{e_2} + \det A_{e_4} - \tilde{g}(\tilde{R}(e_1, e_3)e_3, e_1).$$

Combined with these equations, we have

$$\rho - K = K^{\perp} - \tilde{g}(\tilde{R}(e_1, e_3)e_4, e_2) + \tilde{g}(\tilde{R}(e_1, e_3)e_3, e_1). \tag{4}$$

# 4. Examples and a Rigidity Theorem for Super-Extremal Surfaces

Let (M, q) be an oriented Lorentzian surface in an oriented four-dimensional pseudo-Riemannian manifold  $(\tilde{M}, \tilde{q})$  of neutral signature, which is isometrically immersed by f. Let  $J \in \Gamma(\operatorname{End}(TM))$  (respectively  $J^{\perp} \in \Gamma(\operatorname{End}(T^{\perp}M))$ ) be the para-complex structure on M (respectively  $T^{\perp}M$ ). We set  $T_{\varepsilon}^{\top} := \operatorname{Ker}(J - \varepsilon I)$  and  $T_{\varepsilon}^{\perp} := \operatorname{Ker}(J^{\perp} - \varepsilon I)$  ( $\varepsilon = \pm 1$ ). Let  $p_{\varepsilon}^{\top}$  (respectively  $p_{\varepsilon}^{\perp}$ ) be the projection from TM (respectively  $T^{\perp}M$ ) onto  $T_{\varepsilon}^{\top}$  (respectively  $T_{\varepsilon}^{\perp}$ ) ( $\varepsilon = \pm 1$ ). The projections  $p_{\varepsilon}^{\top}$  (respectively  $p_{\varepsilon}^{\perp}$ ) are given by  $p_{\varepsilon}^{\top} = (1/2)(I + \varepsilon J)$  (respectively  $p_{\varepsilon}^{\perp} = (1/2)(I + \varepsilon J^{\perp})$  ( $\varepsilon = \pm 1$ ). It is easy to prove the following lemma.

## Lemma 5. We have

- 1)  $T_{\varepsilon}^{\top}$  and  $T_{\varepsilon}^{\perp}$  are the parallel subbundles of TM and  $T^{\perp}M$  respectively
- 2)  $TM = T_1^{\top} \oplus T_{-1}^{\top} \text{ and } T^{\perp}M = T_1^{\perp} \oplus T_{-1}^{\perp}$

3) 
$$\Lambda_q \cup \{0\} = T_1^\top \cup T_{-1}^\top$$
 and  $\Lambda_{q^{\perp}} \cup \{0\} = T_1^{\perp} \cup T_{-1}^{\perp}$ .

By Lemma 5, we obtain

**Lemma 6.** For  $X \in T_1^{\top}$  and  $Y \in T_{-1}^{\top}$ , we have

$$\alpha(X,Y) = g(X,Y)H. \tag{1}$$

By the straightforward calculations, we have the following lemmas.

**Lemma 7.** If  $X \in T_1^{\top}$  and  $Y \in T_{-1}^{\top}$ , then we have

$$\beta(X,X) = \alpha(X,X) - J^{\perp}\alpha(X,X) \tag{2}$$

$$\beta(Y,Y) = -\alpha(Y,Y) - J^{\perp}\alpha(Y,Y) \tag{3}$$

$$\beta(X,Y) = -g(X,Y)(H+J^{\perp}H) \tag{4}$$

$$\beta(Y,X) = g(X,Y)(H - J^{\perp}H). \tag{5}$$

**Lemma 8.** If  $X \in T_1^{\top}$  and  $Y \in T_{-1}^{\top}$ , then we have

$$\gamma(X,X) = 2(J^{\perp}\alpha(X,X) - \alpha(X,X))$$
  

$$\gamma(Y,Y) = 2(J^{\perp}\alpha(Y,Y) + \alpha(Y,Y))$$
  

$$\gamma(X,Y) = 0.$$

The following fact is proved in [12] using a local frame.

**Lemma 9.** A surface M is super-extremal if and only if M is extremal and isotropic with negative spin.

**Proof:** Assume that M is super-extremal. Then we have  $\alpha(X,X) \in T_1^{\perp}$  for all  $X \in T_1^{\top}$  and  $\alpha(Y,Y) \in T_{-1}^{\perp}$  for all  $Y \in T_{-1}^{\top}$  by Lemma 3, (2) and (3). Then M is isotropic with negative spin. Moreover, it follows that  $H \in T_1^{\perp} \cap T_{-1}^{\perp}$  from (4) and (5). Hence, by Lemma 5, we have H = 0. Next, we assume that M is extremal and isotropic with negative spin. By Lemmas 7 and 8, we see  $\beta = 0$ , that is, M is super-extremal.

By Lemma 8, we have

**Proposition 1.** A surface M is isotropic with negative spin if and only if it holds that  $\alpha(X,X) \in T_1^{\perp}$  for all  $X \in T_1^{\perp}$  and  $\alpha(Y,Y) \in T_{-1}^{\perp}$  for all  $Y \in T_{-1}^{\perp}$ .

Hence, to check if the surface is isotropic with a negative spin, it is sufficient to consider the second fundamental form with respect to null directions. Using Proposition 1, we see that the following immersions is isotropic with negative spin.

**Example 1.** Let U be an open set of  $\mathbb{R}^2$ . We consider the immersion  $f: U \to \mathbb{R}^4$  by

$$f(x,y) = (a(x) + c(y)b(x), b(x) - c(y)a(x), a(x) - c(y)b(x), b(x) + c(y)a(x))$$

where a, b, c are functions defined on open intervals with  $c'(a'b - ab') \neq 0$ . Since

$$f_*(\partial_x) = (a' + cb', b' - ca', a' - cb', b' + ca')$$
  
$$f_*(\partial_y) = (c'b, -c'a, -c'b, c'a)$$

and we have also  $\tilde{g}(f_*(\partial_x), f_*(\partial_x)) = 0$ ,  $\tilde{g}(f_*(\partial_y), f_*(\partial_y)) = 0$ ,  $\tilde{g}(f_*(\partial_x), f_*(\partial_y)) = -2c'(a'b - ab')$ . Moreover, we obtain

$$\tilde{\nabla}_{\partial_x}\partial_x = (a'', b'', a'', b'') + c(b'', -a'', -b'', a'') 
\tilde{\nabla}_{\partial_x}\partial_y = c'(b', -a', -b', a') 
\tilde{\nabla}_{\partial_y}\partial_u = c''(b, -a, -b, a).$$

Besides, it holds that

$$\tilde{g}(\alpha(\partial_x, \partial_x)\alpha(\partial_x, \partial_x)) = 0, \quad \alpha(\partial_x, \partial_y) = c'(b', -a', -b', a'), \quad \alpha(\partial_y, \partial_y) = 0.$$

Therefore, by Proposition 1, we see that f is an isotropic immersion with negative spin. By Lemma 6, we have

$$H = -\frac{1}{2(a'b - ab')}(b', -a', -b', a').$$

Hence the mean curvature vector field is null.

We see that f is totally umbilic if and only if, for any null geodesic c on M, the curve  $f \circ c$  is geodesic. In fact, if  $\alpha(X,X) = 0$  for all  $X \in T_1^\top$  and  $\alpha(Y,Y) = 0$ 

for all  $Y \in T_{-1}^{\top}$ , then it holds that  $\alpha(Z, W) = g(Z, W)H$  for all  $Z, W \in TM$  by Lemma 6. Consider

$$U_2^4(x_0) := \{ x \in \mathbb{R}_2^4; \ \tilde{g}(x, x) = 0, \ \ \tilde{g}(x, x_0) = -1 \}$$

for a null vector  $x_0 \in \mathbb{R}^4_2$ . Then  $U_2^4(x_0)$  is a flat totally umbilic surface in  $\mathbb{R}^4_2$  with parallel null mean curvature vector field (see [13]). In Example 1, when a(x)= 1, b(x) = x, c(y) = y, the immersion is totally umbilic. In fact, this immersion is locally congruent to  $U_2^4(x_0)$ . In terms of null geodesics on M, we have the following corollary.

**Corollary 1.** Let M be an oriented Lorentzian surface in an oriented four-dimensional pseudo-Riemannian manifold M of neutral signature. Then the following statements are mutually equivalent:

- 1) *M* is isotropic with negative spin.
- 2) For any  $\varepsilon$  and any null geodesic c on M with  $c' \in T_{\varepsilon}^{\top}$ , the curve  $f \circ c$  satisfies  $(f \circ c)''(t) \in (T_{\varepsilon}^{\perp})_{c(t)}$  for all  $t \in \text{Dom}(c)$ .

Next we give examples of super-extremal surfaces.

**Example 2.** If  $(M, \tilde{g})$  is a four-dimensional para-Kähler manifold with the parallel para-complex structure  $J' \in \Gamma(Q)$ . If  $f_* \circ J = J' \circ f_*$ , then M is a super-extremal surface. For example,  $f: U \to \mathbb{R}^4$  defined by

$$f(x,y) = (a(x) + c(y), b(x) + d(y), a(x) - c(y), b(x) - d(y))$$

is super-extremal, where U is an open set in  $\mathbb{R}^2_1$  and a, b, c, d are functions defined on open intervals such that  $a'c' + b'd' \neq 0$ .

**Example 3.** We define an extremal immersion  $f: S_1^2(1) \to S_2^4(1/\sqrt{3})$  by

$$f(x, y, z) = (xy, zx, yz, \frac{\sqrt{3}}{6}(2x^2 + y^2 + z^2), \frac{1}{2}(y^2 - z^2))$$

which is corresponding to the Veronese immerison in Riemannian geometry (see [14]) where more general situations are considered. See also [15]. Note that the Veronese immerison in Riemannian geometry is a typical example of superminimal immersions. Next using Corollary 1, we show that f is isotropic with negative spin. It is sufficient to consider null geodesics passing through one point p = (0, 1, 0). Null geodesics passing through p can be written by  $\gamma_{\pm}(t) = (t, 1, \pm t)$  for  $t \in \mathbb{R}$ . Then we have

$$(f \circ \gamma_{\pm})(t) = (t, \pm t^2, \pm t, \frac{\sqrt{3}}{6}(3t^2 + 1), \frac{1}{2}(1 - t^2))$$

for  $t \in \mathbb{R}$ . Therefore we have  $(f \circ \gamma_{\pm})''(t) = (0, \pm 2, 0, \sqrt{3}, -1)$ , and hence,  $(f \circ \gamma_{\pm})''(t)$  are null vector and  $\tilde{g}((f \circ \gamma_{-})''(0), (f \circ \gamma_{+})''(0)) \neq 0$ . Then f is isotropic with negative spin and extremal, that is, f is super-extremal by Lemma 9.

Composing homotheties and anti-isometries of  $S_1^2(1)$  and  $S_2^4(1/\sqrt{3})$ , we can obtain super-extremal immersions of the Veronese type from  $Q_1^4(c)$  to  $Q_2^4(3c)$  ( $c \neq 0$ ).

The notions of the reflector lift and super-extremal surface can be defined for higher even-dimentional cases. In [11], a rigidity theorem for super-extremal surfaces is obtained in such cases. For the low dimensional case, we give more elementary proof of the rigidity theorem. To do this, we prepare a lemma for connections of a pseudo-Riemannian vector bundle. Let E be a pseudo-Riemannian vector bundle with fiber metric  $g^E$  over a pseudo-Riemannian manifold with the Levi-Civita connection  $\nabla$ , and  $\nabla'$  metric connections of E. Let  $\alpha$  be an E-valued symmetric tensor and its covariant derivative  $\nabla'\alpha$  induced by  $\nabla'$  and  $\nabla$ . We define  $d^{\nabla'}\alpha$  by

$$(d^{\nabla'}\alpha)(X,Y,Z) := (\nabla'_X\alpha)(Y,Z) - (\nabla'_Y\alpha)(X,Z)$$

for  $X,Y,Z\in\Gamma(TM)$ . We note that  $\alpha$  is  $d^{\nabla'}$ -closed, that is,  $d^{\nabla'}\alpha=0$  if and only if the connection satisfies the equation of the Codazzi type. The following lemma can be proved in a similar way as Theorem 1 in [16].

**Lemma 10.** Let E be a pseudo-Riemannian vector bundle with fiber metric  $g^E$  over a pseudo-Riemannian manifold with the Levi-Civita connection  $\nabla$ , and  $\nabla^1$ ,  $\nabla^2$  metric connections of E. Let  $\alpha$  be an E-valued symmetric tensor which satisfies  $d^{\nabla^1}\alpha = 0$  and  $d^{\nabla^2}\alpha = 0$ . If  $E_x = \operatorname{Span}\{\alpha(X,Y); X,Y \in T_xM\}$  for all  $x \in M$ , then  $\nabla^1 = \nabla^2$ .

Here we can prove the following theorem.

**Theorem 2.** Let f,  $\bar{f}$ :  $M \to Q_2^4(c)$  be super-extremal immersions from a Lorentzian surface M such that both normal curvatures do not vanish at any point of M. Then there exist an isometry  $\Phi$  of  $Q_2^4(c)$  such that  $\bar{f} = \Phi \circ f$ .

**Proof:** The corresponding objects associated with  $\bar{f}$  are denoted by the symbol with "-", for example,  $\overline{T^{\perp}M}$  is the normal bundle of  $\bar{f}$ . By (4), we have  $K+K^{\perp}=c$ , so  $c\neq K$ . On the other hand, for nonzero vectors  $X\in T_1^{\top}$  and  $Y\in T_1^{\top}$ , we see that  $g^{\perp}(\alpha(X,X),\alpha(Y,Y))\neq 0$ . The first normal spaces coincide with the normal spaces, that is,  $T^{\perp}M=\mathrm{Span}\{\alpha(X,X),\alpha(Y,Y)\}$  and  $\overline{T^{\perp}M}=\mathrm{Span}\{\bar{\alpha}(X,X),\bar{\alpha}(Y,Y)\}$ . We define an isomorphism  $\varphi\colon T^{\perp}M\to \overline{T^{\perp}M}$  by  $\varphi(\alpha(X,X))=\bar{\alpha}(X,X)$  and  $\varphi(\alpha(Y,Y))=\bar{\alpha}(Y,Y)$ . Then we have

$$g^{\perp}(\alpha(X,X),\alpha(X,X)) = \bar{g}^{\perp}(\bar{\alpha}(X,X),\bar{\alpha}(X,X))$$

and

$$g^{\perp}(\alpha(Y,Y),\alpha(Y,Y)) = \bar{g}^{\perp}(\bar{\alpha}(Y,Y),\bar{\alpha}(Y,Y)).$$

We see that  $\varphi$  preserves the metrics of normal bundles. In fact, using by the Gauss equation (1), we have

$$cg(X,Y)^2 = Kg(X,Y)^2 + g^{\perp}(\alpha(X,X),\alpha(Y,Y))$$

and hence, we have  $g^{\perp}(\alpha(X,X),\alpha(Y,Y))=\bar{g}^{\perp}(\bar{\alpha}(X,X),\bar{\alpha}(Y,Y))(\neq 0)$ . Therefore we see that  $\varphi$  is isometry. Since both f and  $\bar{f}$  are extremal, we have

$$\varphi(\alpha(X,Y)) = \varphi(g(X,Y)H) = 0 = \bar{\alpha}(X,Y)$$

for all  $X \in T_1^{\top}$  and  $Y \in T_{-1}^{\top}$ . Therefore  $\varphi$  preserves the second fundamental forms. Consider a connection  $\bar{\nabla}^{\perp\prime}$  on the normal bundle  $\overline{T^{\perp}M}$  defined by  $\bar{\nabla}_X^{\perp\prime}\xi$ :=  $\varphi(\nabla_X^{\perp}\varphi^{-1}\xi)$  for  $X\in\Gamma(TM)$  and  $\xi\in\Gamma(\overline{T^{\perp}M})$ . By the Codazzi equation (2) for f, we see that the connection  $\bar{\nabla}^{\perp\prime}$  satisfies  $d^{\bar{\nabla}^{\perp\prime}}\alpha=0$ . From Lemma 10, it follows that  $\bar{\nabla}^{\perp} = \bar{\nabla}^{\perp \prime}$ . Therefore  $\varphi$  also preserves the normal connections. By the congruence theorem for pseudo-Riemannian submanifolds in the space forms (see [6], for example), we see that there exists an isometry  $\Phi$  of  $Q_2^4(c)$  such that  $\bar{f} = \Phi \circ f$ .

By Theorem 2, we have

**Corollary 2.** Let  $f, \bar{f}: M \to Q_2^4(c)$  be super-extremal immersions from a Lorentzian surface M of constant Gaussian curvature c'. If  $c \neq c'$ , then there exist an isometry  $\Phi$  of  $Q_2^4(c)$  such that  $\bar{f} = \Phi \circ f$ .

An isometric immersion  $f: (M, g) \to (M, \tilde{g})$  is called *locally homogeneous* if for all point x and y of M, there exists a neighborhood U of x and an isometry  $\Phi \colon \widetilde{M} \to \widetilde{M}$  such that  $\Phi(f(x)) = f(y)$  and  $\Phi(f(U)) \subset f(M)$ . In particular, when U = M, f is said to be homogenous. By Corollary 2, we have

**Corollary 3.** Let  $f: M \to Q_2^4(c)$  be a super-extremal immersion from a Lorentzian surface M of constant Gaussian curvature c'. If  $c \neq c'$ , f is locally homogeneous. In particular, if  $M = Q_1^2(c')$  and  $c \neq c'$ , then f is homogeneous.

For locally homogeneous super-extremal surfaces, a quantization phenomenon of the Gaussian curvature of M holds.

**Lemma 11.** Let  $f: M \to Q_2^4(c)$  be a locally homogeneous super-extremal immersion from a Lorentzian surface M. We have K = c or K = c/3.

**Proof:** Take vectors  $X \in T_1^\top$ ,  $Y \in T_{-1}^\top$ ,  $\xi \in T_1^\bot$  and  $\eta \in T_{-1}^\bot$  such that g(X,Y) = 1 and  $g^\bot(\xi,\eta) = 1$  at each point of M. We define

$$s := g^{\perp}(\alpha(X, X), \eta)g^{\perp}(\alpha(Y, Y), \xi).$$

Note that the function s is independent of the choice of such frames. Since f is locally homogeneous, s is constant. If s=0, then we see that  $\alpha(X,X)=0$  or  $\alpha(Y,Y)=0$ . From the Gauss equation (1), we have K=c. If  $s\neq 0$ , then we have  $0=\triangle\log|s|=(2K-K^\perp)$  by Proposition 3.4.1 in [12] (we use the opposite sign convention to the definition of the normal curvature of [12]). By (4), we have c=3K.

By Corollary 3 and Lemma 11, we characterize the immersion of the Veronese type as follows.

**Corollary 4.** Let  $f: M \to Q_2^4(c)$  be a super-extremal immersion from a Lorentzian surface M of constant Gaussian curvature c'. If  $c' \neq c$ , then  $c = 3c' \neq 0$  and f is congruent to a restriction to an open set of the immersion of the Veronese type given in Example 3.

**Remark 1.** From Corollary 4, there are no super-extremal immersions of the Lorentzian surfaces of constant Gaussian curvature c' into  $Q_2^4(c)$  if cc' < 0.

**Remark 2.** In Riemannian case, superminimal surfaces in the spaces of constant curvature with flat normal connection are totally geodesic (see Lemma 4.5 in [7], for example). But the corresponding fact does not hold in general. In fact, there exists a non-totally geodesic super-extremal surface in  $\mathbb{R}^4_2$  with flat normal connection. For example, consider the case of d=0 in Example 2. By the straightforward calculation, we have

$$f_*(\partial_x) = (a', b', a', b'), \qquad f_*(\partial_y) = (c', 0, -c', 0)$$

and the induced metric satisfies

$$g(\partial_x, \partial_x) = 0,$$
  $g(\partial_y, \partial_y) = 0,$   $g(\partial_x, \partial_y) = -2a'c'.$ 

Then the Gaussian curvature of the induced metric is flat, and hence  $K^{\perp}=0$ . Moreover it holds that

$$\alpha(\partial_x, \partial_x) = (0, b'' - \frac{a''}{a'}b', 0, b'' - \frac{a''}{a'}b'), \qquad \alpha(\partial_x, \partial_y) = 0 \ \alpha(\partial_y, \partial_y) = 0$$

and hence we can find many functions a, b, c such that M is not totally geodesic, for example,

$$a(x) = x,$$
  $b(x) = \sin x,$   $c(y) = -e^{y}.$  (6)

In Riemannian case, a connected minimal surface of constant Gaussian curvature in  $\mathbb{R}^n (\cong \mathbb{R}^n_0)$  must be flat and an open part of a two-plane on  $\mathbb{R}^n$  (see [2]). The example as above implies that the corresponding fact does not hold in general. In fact, by Corollary 4, we can see that super-extremal Lorentzian surfaces of constant Gaussian curvature in  $\mathbb{R}^4_2$  must be flat but there are many non-totally geodesic super-extremal flat surfaces. Moreover the immersion given by (6) shows that there exists a non-homogeneous super-extremal flat surface in  $\mathbb{R}^4_2$ . So the condition  $c \neq c'$  in Corollary 3 is needed in general.

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