

## The Length Function of Geodesic Parallel Circles

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*Dedicated to Professor T. Otsuki on his 75th birthday*

### §0. Introduction

The isoperimetric inequalities for a simply closed curve  $C$  on a Riemannian plane  $\Pi$  (i.e., a complete Riemannian manifold homeomorphic to  $\mathbf{R}^2$ ) was first investigated by Fiala in [1] and later by Hartman in [2]. These inequalities were generalized by the first named author in [3], [4] for a simply closed curve on a finitely connected complete open surface and by both authors in [5] for a simply closed curve on an infinitely connected complete open surface. Here a noncompact complete and open Riemannian 2-manifold  $M$  is called *finitely connected* if it is homeomorphic to a compact 2-manifold without boundary from which finitely many points are removed, and otherwise  $M$  is called *infinitely connected*. Fiala and Hartman investigated certain properties of geodesic parallel circles  $S(t) := \{x \in \Pi ; d(x, C) = t\}$ ,  $t \geq 0$  around  $C$  of a Riemannian plane  $\Pi$  in order to prove the isoperimetric inequalities, where  $d$  denotes the Riemannian distance function. Fiala proved in [1] that if a Riemannian plane  $\Pi$  and a simple closed curve  $C$  on  $\Pi$  are *analytic*, then  $S(t)$  is a finite union of piecewise smooth simple closed curves except for  $t$  in a discrete subset of  $[0, \infty)$  and its length  $L(t)$  is *continuous* on  $[0, \infty)$ . If  $\Pi$  and  $C$  are *not analytic but smooth*, then  $L(t)$  is *not always continuous* as pointed out by Hartman in [2]. What is worse is that  $S(t)$  does not always admit its length. Under the assumption of low differentiability of  $\Pi$  and  $C$ , Hartman proved that  $S(t)$  is a finite union of piecewise smooth simple closed curves except for  $t$  in a closed subset of Lebesgue measure zero in  $[0, \infty)$ . This result was recently extended by the authors [5] to an arbitrary given simply closed curve  $C$  in an arbitrary given complete, connected, oriented and noncompact Riemannian 2-manifold  $M$ .

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The normal exponential map along  $C$  induces a local chart and a function  $L(t)$  for all  $t \geq 0$  is well defined with the aid of this local chart. As mentioned above,  $L(t)$  for all  $t \geq 0$  defines the length of  $S(t)$  whenever  $S(t)$  is a finite union of piecewise smooth simple closed curves. However we do not know the geometric meaning of  $L(t)$  for the other  $t$ -values. Hartman introduced a certain monotone function  $J: [0, \infty) \rightarrow \mathbf{R}$  by using this local chart and proved in Theorem 6.2 ; [2] that the following function

$$(*) \quad H(t) := J(t) + L(t)$$

is absolutely continuous on every compact interval of  $[0, \infty)$ .

The purpose of the present article is to extend the absolute continuity of  $H$  as defined in  $(*)$  for an arbitrary given simple closed curve  $C$  in an arbitrary given connected, complete, noncompact and oriented Riemannian 2-manifold  $M$ . The cut locus and focal locus to  $C$  are essential in our discussion. In §1 we introduce the notations concerning with the cut points and focal points to  $C$  as used in [2],[5]. Under our situation  $M \setminus C$  has at most two components. The type of cut locus and focal locus changes as the number of components of  $M \setminus C$ . In §2 we deal with the simpler case where  $M \setminus C$  has two components and prove the absolute continuity of  $(*)$  in this case (see Theorem 2.2). We also need to modify the definition of  $J(t)$  in the case where  $M \setminus C$  is connected. In §3 we prove the absolute continuity of  $(*)$  in the case where  $M \setminus C$  is connected (see Theorem 3.2).

## §1. Preliminaries

From now on let  $M$  be a connected, oriented, complete and noncompact Riemannian 2-manifold and  $C$  a smooth simply closed curve on  $M$ . Since our discussion proceeds in the same manner as developed by Hartman, we shall employ the same terminologies as used in [2],[5]. Let  $L_0$  be the length of  $C$ . A point on  $C$  is expressed as  $z_0(s)$  with respect to the arclength parameter  $s \in [0, L_0]$ .  $z_0(s)$  and other functions of  $s$  will be considered periodic of period of  $L_0$  for convenience. Let  $g$  be the Riemannian metric on  $M$  and  $N$  a unit normal field along  $C$  with  $N_0 = N_{L_0}$ . A map  $z: \mathbf{R} \times [0, L_0] \rightarrow M$  is defined by

$$z(t, s) := \exp_{z_0(s)} tN_s$$

where  $\exp_p$  is the exponential map of  $M$  at  $p$ . If  $|t|$  is sufficiently small, then  $z$  gives a coordinate system  $(t, s)$  and  $g \left( \frac{\partial z}{\partial t}, \frac{\partial z}{\partial t} \right) = 1$  holds around

$C$  and  $g\left(\frac{\partial z}{\partial t}, \frac{\partial z}{\partial s}\right) = 0$  follows from Gauss Lemma. For every  $s \in [0, L_0]$  let  $\gamma_s: R \rightarrow M$  be a geodesic with  $\gamma_s(t) = z(t, s)$  and  $e_s(t)$  a unit parallel vector field along  $\gamma_s$  with  $e_s(0) = \frac{\partial z}{\partial s}(0, s)$ . For each  $s$  let  $Y_s(t)$  denote the Jacobi field along  $\gamma_s$  with  $Y_s(0) = e_s(0)$ ,  $g(Y_s(t), \gamma'_s(t)) = 0$ . By setting  $f(t, s) = g(Y_s(t), e_s(t))$ , we have  $f(0, s) = 1$ ,  $f_t(0, s) = \kappa(s)$  and  $g\left(\frac{\partial z}{\partial s}, \frac{\partial z}{\partial s}\right) = f^2(t, s)$ , where  $\kappa(s)$  is the geodesic curvature of  $C$  at  $z_0(s)$  and  $f_t = \frac{\partial f}{\partial t}$ . Since  $Y_s$  is a Jacobi field we have  $f_{tt}(t, s) + G(z(t, s))f(t, s) = 0$ , where  $f_{tt} = \frac{\partial^2 f}{\partial t^2}$ .

Let  $P(s)$  (respectively  $N(s)$ ) denote the least positive (respectively the largest negative)  $t$  with  $f(s, t) = 0$ , or  $P(s) = +\infty$  (respectively  $N(s) = -\infty$ ) if there is no such zero. If  $P(s_0) < +\infty$  (respectively  $N(s_0) > -\infty$ ), then  $P$  (respectively  $N$ ) is smooth around  $s_0$  and  $z(P(s_0), s_0)$ , (respectively  $z(N(s_0), s_0)$ ) is called the first positive (respectively negative) focal point to  $C$  along  $\gamma_{s_0}$ .

A unit speed geodesic  $\sigma: [0, \ell] \rightarrow M$  is called a  $C$ -segment iff  $\sigma(0) \in C$  and  $d(\sigma(t), C) = t$  holds for all  $t \in [0, \ell]$ . Every  $C$ -segment is a subarc of some  $\gamma_s$ . Let  $\rho(s) := \sup\{t > 0; d(\gamma_s(t), C) = t\}$  and  $\nu(s) := \inf\{t < 0; d(\gamma_s(t), C) = -t\}$ .  $\rho(s)$  (respectively  $\nu(s)$ ) is the cut point distance to  $C$  along  $\gamma_s|_{[0, \infty)}$  (respectively  $\gamma_s|_{(-\infty, 0]}$ ).  $z(\rho(s), s)$  is called a cut point to  $C$  along  $\gamma_s$  and  $\gamma_s|_{[0, \rho(s)]}$  is a maximal  $C$ -segment contained in  $\gamma_s|_{[0, \infty)}$ . A cut point is a first focal point of a  $C$ -segment or the intersection of at least two distinct  $C$ -segments.

A cut point at  $C$  is called *normal* if it is the endpoint of exactly two distinct  $C$ -segments and is not a first focal point along either of them. A cut point to  $C$  which is not normal is called *anormal*. An anormal cut point  $z(\rho(s), s)$  (or  $z(\nu(s), s)$ ) is called *totally nondegenerate* iff  $z(\rho(s), s)$  (or  $z(\nu(s), s)$ ) is not a first focal point to  $C$  along any  $C$ -segment ending at  $z(\rho(s), s)$  (or  $z(\nu(s), s)$ ). An anormal cut point is called *degenerate* iff it is not totally nondegenerate. A number  $t > 0$  is called *anormal* iff there exists a value  $s \in \rho^{-1}(t)$  (or  $s \in \nu^{-1}(-t)$ ) such that  $z(t, s)$  (or  $z(-t, s)$ ) is anormal. If  $t > 0$  is not anormal, then  $t$  is called *normal*. Also  $t > 0$  is called *exceptional* iff it is either anormal or normal but there exists an  $s$  such that  $\rho(s) = t$  (or  $\nu(s) = -t$ ) and  $\rho' = 0$  (or  $\nu' = 0$ ) at  $s$ . A positive number  $t$  is by definition *non-exceptional* iff it is not exceptional.

§2. The case where  $C$  bounds a domain

Throughout this section let  $M \setminus C$  have two components and  $M_1$  the component containing  $\{z(\rho(s), s) ; \rho(s) < \infty\}$ . Note that the sets  $\{z(\rho(s), s) ; \rho(s) < \infty\}$  and  $\{z(\nu(s), s) ; \nu(s) > -\infty\}$  have no common point. We only restrict to consider  $M_1$ , since the same discussion holds for  $M \setminus M_1$ .

We begin with the discussion of degenerate cut points that was not discussed in [2]. It seems to the authors that the lack of degenerate cut points in [2] would cause unclearness in the proof of Theorem 6.2 in [2]. The following Lemma 2.1 is useful to prove our results.

**Lemma 2.1.** *The set  $F = \{s \in [0, L_0] ; \rho(s) < P(s), \text{ but } z(\rho(s), s) \in M_1 \text{ is a degenerate cut point along some } C\text{-segment}\}$  is of Lebesgue measure zero.*

*Proof.* It suffices for the proof to show that for any  $s \in F$  there exists a positive  $\delta$  such that  $F \cap (s - \delta, s + \delta)$  is of Lebesgue measure zero. Let  $s_0 \in F$  and set  $p = z(\rho(s_0), s_0)$ . Choose a small positive  $\epsilon$  such that  $B_\epsilon$  is an open normal convex  $\epsilon$ -ball around  $p$ . For each  $s \in [0, L_0]$  with  $z(\rho(s), s) = p$  let  $s'$  denote the common point of  $\partial B_\epsilon$  and  $\gamma_s([0, \rho(s_0)])$ . The circle  $\partial B_\epsilon$  is naturally oriented. Define the oriented open subarc from  $s'_1$  to  $s'_2$  of  $\partial B_\epsilon$  by  $(s'_1, s'_2)$ . For each  $s \in [0, L_0] \setminus \{s_0\}$  with  $z(\rho(s), s) = p$  let  $D(s'_0, s')$  (respectively  $D(s', s'_0)$ ) be the disk domain bounded by three arcs  $\gamma_{s_0}|[\rho(s_0) - \epsilon, \rho(s_0)]$ ,  $\gamma_s|[\rho(s_0) - \epsilon, \rho(s_0)]$  and  $(s'_0, s')$  (respectively  $D(s', s'_0)$ ). Since  $\rho(s_0) < P(s_0)$ , there exist  $s_+, s_- \in [0, L_0]$  such that  $z(\rho(s_+), s_+) = z(\rho(s_-), s_-) = p$  and such that  $D_+ := D(s'_0, s'_+)$  and  $D_- := D(s'_-, s'_0)$  are disjoint and they do not contain any  $C$ -segment passing through  $p$ . Let  $(\pi, NC, M)$  be the normal bundle over  $C$  with projection  $\pi$ , total space  $NC$  and base space  $M$ . Since  $p$  is not a focal point to  $C$  along  $\gamma_{s_0}$ , there exist a neighborhood  $V$  of  $\rho(s_0) \cdot \dot{\gamma}_{s_0}(0)$  in  $NC$  and a neighborhood  $U$  of  $p$  in  $M$  such that the restriction  $\exp_V$  of the normal exponential map to  $V$  is a diffeomorphism of  $V$  onto  $U$ . Since  $p$  is a degenerate cut point, there is a  $C$ -segment ending at  $p$  along which  $p$  is the first focal point to  $C$ . Suppose  $P(s_+) = \rho(s_+)$ . Choose a positive number  $\epsilon_1$  such that  $U$  contains  $z(\rho(s), s)$  and  $z(P(s), s)$  for all  $s \in [s_+ - \epsilon_1, s_+ + \epsilon_1]$ . From construction of  $D_+$  we can choose a positive number  $\delta_1 < \epsilon_1$  such that if  $z(\rho(s_1), s_1) = z(\rho(s), s)$  for  $s_1 \in [0, L_0]$ ,  $s \in (s_0, s_0 + \delta_1)$ , then  $s = s_1$  or  $s_1 \in (s_+ - \epsilon_1, s_+)$ . Let  $v : (s_+ - \epsilon_1, s_+) \rightarrow (s_1, s_0 + \delta_1)$  be defined as

$$v(s) := z_0^{-1} \circ \pi \circ (\exp_V^{-1})(z(\rho(s), s))$$

If  $s \in (s_+ - \epsilon, s_+)$  satisfies  $P'(s) = 0$  and  $P(s) = \rho(s)$ , then  $v'(s) = 0$ ,

and hence  $s$  is a critical point of  $v$ . Let  $K \subset (s_+ - \epsilon_1, s_+)$  be the set of all critical points of  $v$ . If  $s \in (s_0, s_0 + \delta_1)$  is an element of  $F$ , then there exists an  $s_1 \in [0, L_0]$  such that  $z(\rho(s), s) = z(\rho(s_1), s_1)$ ,  $P(s_1) = \rho(s_1)$ . It follows from the choice of  $\delta_1$  and Proposition 2.1 in [5] that  $P'(s_1) = 0$  and  $s_1 \in (s_+ - \epsilon_1, s_+)$ . Therefore we find an  $s_1 \in K$  such that  $z(\rho(s), s) = z(\rho(s_1), s_1) = z(P(s_1), s_1)$ . This fact means that  $(s_0, s_0 + \delta_1) \cap F$  is contained entirely in  $v(K)$ . The Sard Theorem implies that  $v(K)$  is of Lebesgue measure zero. If  $\rho(s_+) < P(s_+)$ , then there exists a positive number  $\delta$  such that  $(s_0, s_0 + \delta) \cap F = \emptyset$ . Summing up these discussion we observe that there exists a positive number  $\delta_1$  such that  $(s_0, s_0 + \delta_1) \cap F$  is of measure zero.

An analogous discussion applies to  $D_-$  to prove that  $(s_0 - \delta'_1, s_0) \cap F$  is of measure zero for some positive number  $\delta'_1$ . This completes the proof of Lemma 2.1.

Let  $D := \{(t, s) ; 0 \leq t < \rho(s), 0 \leq s \leq L_0\}$  and  $\chi(t, s)$  the characteristic function of  $D$  such that  $\chi(s, t) = 1$  or  $0$  according as  $(t, s) \in D$  or not. For any  $t \geq 0$  set

$$L(t) := \int_0^{L_0} \chi(t, s) f(t, s) ds$$

This  $L(t)$  is the length of  $S(t) = \{x \in M_1 | d(x, C) = t\}$  if  $t$  is a non-exceptional value. We define for  $t \geq 0$  the set  $Q(t)$  as follows.

$$Q(t) := \{s \in \rho^{-1}(t) ; z(s, t) \text{ is normal and } \rho'(s) = 0\}.$$

$Q(t)$  has the property that elements in it are pairwise disjoint, and hence it is of Lebesgue measure zero except for an at most countable set of  $[0, \infty)$ . We define for  $t \geq 0$  the function

$$J(t) := \sum_{0 \leq u \leq t} \int_{Q(u)} f(u, s) ds.$$

Note that  $L$  and also  $J$  is discontinuous at  $t = t_0$  iff the Lebesgue measure of  $Q(t_0)$  is positive.

In order to prove Theorem 2.2 we shall need some basic tools from measure theory which is referred to [6]. Let  $h$  be a continuous function of bounded variation defined on a closed interval  $[a, b]$ . Then the function  $h$  defines a *Lebesgue-Stieltjes measure*  $\Lambda_h$  such that  $\Lambda_h((x, y])$  for each subinterval  $(x, y]$  of  $[a, b]$  equals the total variation of  $h$  on  $[x, y]$ . It is known that any Borel set  $B$  in  $[a, b]$  is  $\Lambda_h$ -measurable. For each Lebesgue measurable set  $S \subset \mathbf{R}$ ,  $|S|$  denotes its Lebesgue measure.

**Theorem 2.2.** *The function  $H(t) = L(t) + J(t)$  is absolutely continuous on any compact subinterval of  $[0, \infty)$ .*

*Proof.* Let  $[a, b]$  be a compact subinterval of  $[0, \infty)$ . In order to prove the theorem we shall show that for any positive  $\epsilon$  there exists a positive  $\eta = \eta(\epsilon, a, b)$  such that if  $\delta_1, \delta_2, \dots, \delta_k$  are non-overlapping subintervals of  $[a, b]$ , then

$$(2.1) \quad \sum_{i=1}^k |\delta_i H| < (L_0 + 2)\epsilon \text{ whenever } \sum_{i=1}^k |\delta_i| < \eta$$

where  $\delta_i H = H(\tau) - H(\sigma)$ ,  $|\delta_i| = \tau - \sigma$  if  $\delta_i = (\sigma, \tau]$ . Let  $\epsilon > 0$  be fixed. It follows from Proposition 3.1 in [5] that the set  $T_b := \{s \in [0, L_0] ; \rho(s) \leq b, z(\rho(s), s) \text{ is a totally nondegenerate anormal point}\}$  is finite. Let  $c = c(b)$  be a constant satisfying

$$|f(t, s)| \leq c, |f_t(t, s)| \leq c, (t, s) \in [0, b] \times [0, L_0]$$

By Lemma 2.1 the set  $F^\epsilon$  defined by

$$F^\epsilon = \{s \in [0, L_0] ; \rho(s) \leq b, s \in F, f(\rho(s), s) \geq \epsilon/2\}$$

is compact and of Lebesgue measure zero. Here there exists a set  $V^\epsilon$  with  $|V^\epsilon| < \epsilon/c$  consisting of a finite number of open subintervals of  $[0, L_0]$  such that  $V^\epsilon \supset T_b \cap F^\epsilon$ . Let  $Q^\epsilon$  be the set

$$Q^\epsilon := \{s \in [0, L_0] ; \rho(s) \leq b, f(\rho(s), s) \leq \epsilon/2\}.$$

Since  $Q^\epsilon$  is compact,  $Q^\epsilon$  can be covered by a set  $S^\epsilon$  consisting of a finite number of open subintervals of  $[0, L_0]$  on which  $f(\rho(s), s) < 3\epsilon/4$ . Then the set  $R^\epsilon = [0, L_0] - (S^\epsilon \cup V^\epsilon)$  consists of a finite number of closed subintervals  $I_1, \dots, I_p$  of  $[0, L_0]$ . It follows from construction of  $R^\epsilon$  and from Proposition 2.2 in [5] that  $\rho$  is smooth at each point  $s \in R^\epsilon$  if  $\rho(s) \leq b$ . Hence the function  $\rho_b := \text{Max}\{\rho, b\}$  is Lipschitz continuous on each closed intervals  $I_j, j = 1, \dots, p$ . In particular the restriction  $\rho_j$  of  $\rho_b$  to  $I_j$  is of bounded variation. If  $\Lambda_j$  denotes the Lebesgue-Stieltjes measure defined by  $\rho_j$ , then we observe from Corollary 3.1 in [2] that

$$(2.2) \quad \sum_{j=1}^k \Lambda_j(\rho_j^{-1}(\delta_i)) = \int_\sigma^\tau n(r) dr$$

where  $n(r)$  is the Lebesgue summable function defined by the number of the elements of the set  $\{s \in R^\epsilon ; \rho(s) = r\}$ . Let  $O(i)$  be an open set

containing  $R(i) = \cup_{\sigma < t \leq \tau} Q(t)$  such that  $|O(i) - R(i)| < |\delta_i|$ . Setting  $S(i) = \rho^{-1}(\delta_i)$ , we define

$$\begin{aligned} S_1 &= (S(i) - R(i)) \cap O(i) \\ S_2 &= (S(i) - R(i)) \cap [\{s ; f(\rho(s), s) < \epsilon\} \cup V^\epsilon] \\ S_3 &= (S(i) - R(i)) - (S_1 \cup S_2). \end{aligned}$$

Making use of the inequality (6.20) in [2], we obtain

$$\begin{aligned} (2.3) \quad |\delta_i H| &\leq \sum_{j=1}^3 \int_{S_j} f(\rho(s), s) ds + 2cL_0|\delta_i| \\ &\leq c|\delta_i| + \epsilon|S(i)| + c|V^\epsilon \cap S(i)| + c|S_3| + 2cL_0|\delta_i| \end{aligned}$$

Since  $S_3 \subset R^\epsilon$  and  $S_3 \cap O(i) = \emptyset$ ,  $\rho$  is smooth at each point of  $S_3$  and  $|\rho'| \geq c_1$  on  $S_3$  holds for some positive constant  $c_1 = c_1(\epsilon, a, b)$ . From the property of the Lebesgue-Stieltjes measure  $\Lambda_j$  we obtain

$$\sum_{j=1}^p \Lambda_j(I_j \cap S_3) \geq c_1 \sum_{j=1}^p |I_j \cap S_3| = c_1 |R^\epsilon \cap S_3| = c_1 |S_3|.$$

From (2.2) and the above inequality, we get

$$(2.4) \quad |S_3| \leq c_1^{-1} \sum_{j=1}^p \Lambda_j(I_j \cap S_3) \leq c_1^{-1} \sum_{j=1}^p \Lambda_j(I_j \cap \rho^{-1}(\delta_i)) = c_1^{-1} \int_\sigma^\tau n(r) dr.$$

From inequalities (2.3) and (2.4) we have

$$(2.5) \quad \sum_{i=1}^k |\delta_i H| \leq c(1 + 2L_0) \sum_{i=1}^k |\delta_i| + (L_0 + 1)\epsilon + cc_1^{-1} \sum_{i=1}^k \int_{\delta_i} n(r) dr.$$

The inequality (2.5) implies that we can find a positive  $\eta = \eta(\epsilon, a, b)$  satisfying (2.1). Note that the function  $n(r)$  is Lebesgue summable.

### §3. The case where $C$ bounds no domain

We deal with the case where a closed curve  $C$  does not bound any domain of  $M$ . Our situation means that there exists a cut point  $p \in M$

to  $C$  such that  $p = z(\rho(s_1), s_1) = z(\nu(s_2), s_2)$  for some  $s_1, s_2 \in [0, L_0]$ . Three types of cut points to  $C$  appear. A cut point  $p$  to  $C$  is by definition of  $\rho$ -type (respectively  $\nu$ -type) iff all  $C$ -segments ending at  $p$  are tangent to  $N$  (respectively to  $-N$ ) at their starting points. A cut point  $p$  to  $C$  is of *mixed type* iff  $p = z(\rho(s_1), s_1) = z(\nu(s_2), s_2)$  for some  $s_1, s_2 \in [0, L_0]$ . For a mixed type cut point to  $C$  the normality, anormality, degeneracy and all other properties are well defined by the same manner as before. These properties are defined for  $t$ -value where  $S(t)$  contains a mixed type cut point having the corresponding properties. Let  $F_+$ ,  $F_-$  be the sets

$$F_+ := \{s \in [0, L_0] ; \rho(s) < P(s), \\ \text{but } z(\rho(s), s) \text{ is a degenerate cut point}\}$$

$$F_- := \{s \in [0, L_0] ; \nu(s) > Q(s), \\ \text{but } z(\nu(s), s) \text{ is a degenerate cut point}\}.$$

Since the proof of Lemma 2.1 is done by a local discussion in a small convex ball around a cut point, we obtain the following lemma by a similar discussion.

**Lemma 3.1.** *The set  $F := F_+ \cup F_-$  is of Lebesgue measure zero.*

Let  $D_+ := \{(t, s) ; 0 \leq t < \rho(s), s \in [0, L_0]\}$  and  $D_- := \{(t, s) ; \nu(s) < t \leq 0, s \in [0, L_0]\}$ . We then define two functions  $L_+$  and  $L_-$  on  $[0, \infty)$  by

$$L_+(t) := \int_0^{L_0} \chi_+(t, s) f(t, s) ds \\ L_-(t) := \int_0^{L_0} \chi_-(t, s) f(-t, s) ds$$

where  $\chi_+(t, s)$  and  $\chi_-(t, s)$  are the characteristic functions of  $D_+$  and  $D_-$  respectively. If  $t > 0$  is non-exceptional, then the function

$$L(t) := L_+(t) + L_-(t)$$

is nothing but the length of  $S(t) = \{x \in M ; d(x, C) = t\}$ .

Note that if  $t_0 > 0$  is a normal exceptional value, then  $S(t_0)$  consists of a set of piecewise smooth curves. However the length of  $S(t_0)$  is not necessarily equal to  $L(t_0)$  but equal to

$$L(t_0) + \frac{1}{2} \left\{ \int_{Q_+(t_0)} f(t_0, s) ds + \int_{Q_-(t_0)} f(-t_0, s) ds \right\}.$$

Here we set

$$Q_+(t) := \{s \in \rho^{-1}(t) ; z(t, s) \text{ is normal and } \rho'(s) = 0\},$$

$$Q_-(t) := \{s \in \nu^{-1}(-t) ; z(-t, s) \text{ is normal and } \nu'(s) = 0\}.$$

In order to define  $J(t)$  in this case we need to set

$$J_+(t) := \sum_{0 \leq u \leq t} \int_{Q_+(t)} f(u, s) ds,$$

$$J_-(t) := \sum_{0 \leq u \leq t} \int_{Q_-(t)} f(-u, s) ds.$$

We then define  $J(t)$  as follows.

$$J(t) := J_+(t) + J_-(t).$$

By a similar discussion as in the proof of Theorem 2.2 we obtain the following

**Theorem 3.2.** *The function  $H(t) = L(t) + J(t)$  is absolutely continuous on any compact subinterval of  $[0, \infty)$ .*

## References

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