

## $L_{p,q}$ -ESTIMATES FOR CERTAIN SEMI-LINEAR PARABOLIC EQUATIONS

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**1. Introduction and results.** In this paper we study the  $L_{p,q}$ -estimates for the solution of the equations

$$(1.1) \quad \begin{cases} u_t + Au = F_1(u, \partial u) + F_2(u), & t > 0, \\ u(0) = a, \\ u = (u^1, \dots, u^N) \quad (N \in \mathbb{N}) \end{cases}$$

in the  $(L_p(\Omega))^N$ -space. Here  $\Omega$  is a bounded domain in  $\mathbb{R}^n$  with smooth boundary, or  $\mathbb{R}^n$  itself ( $n \geq 2$ ). We assume that  $A$  is of the form

$$(1.2) \quad A = -PL,$$

where  $L$  is the realization in  $(L_p(\Omega))^N$  of an elliptic operator of the second order (with certain boundary condition if  $\partial\Omega \neq \emptyset$ ) and  $P$  is a bounded operator from  $(L_p(\Omega))^N$  into the closed subspace  $(PL_p(\Omega))^N$ . The non-linear terms  $F_1$  and  $F_2$  of the types

$$(1.3) \quad \begin{cases} F_1(u, \partial u) = PN_1(u, \partial u), \\ N_1(u, \partial u) = \sum_{i,j,k} a_{ijk} u^i \partial_j u^k, \\ (\partial u = (\partial_j u^k), j = 1, \dots, n; k = 1, \dots, N), \\ F_2(u) = PN_2(u), \\ N_2(u) = \sum_{i,j,k} b_{ijk} u^i u^j u^k, \end{cases}$$

where  $a_{ijk}$  and  $b_{ijk}$  are bounded functions, and  $\partial_j = \partial/\partial x_j$  ( $j = 1, 2, \dots, n$ ).

Our main purpose is to establish the  $L_{p,q}$ -estimates for solutions to this system. We know some examples of such a system in mathematical physics and differential geometry (see Section 2). For the Navier-Stokes system, which is one of the typical examples, the  $L_{p,q}$ -estimates play an important role in showing the regularity of weak solutions [2], [3]. Kato [4] and Giga [3] obtained such estimates for the system using certain special feature of non-linear terms. We shall show similar results using only the non-linearity (1.3). We shall also study an application of our results to the system of

semi-linear heat equations having the non-linearity (1.3), because the gradient flow of the Yang-Mills functional is described by such a system.

Before stating our results, we describe our assumption more precisely. We denote  $(L_p(\Omega))^N$  simply by  $L_p(\Omega)$ , and utilize other notation basically found in [7]. We assume that the restriction of  $P$  to  $C_0(\Omega)$  is independent of  $p$ ,  $1 < p < \infty$ , and that the space  $C_0(\Omega) \cap PL_p(\Omega)$  is dense in  $PL_p(\Omega)$ .

$A$  defined by (1.2) is assumed to have the following property:  $-A$  is an infinitesimal generator of a strongly continuous semigroup  $\{e^{-tA}\}$  simultaneously on  $PL_p(\Omega)$  for all  $p \in (1, \infty)$  satisfying

$$(1.4) \quad \|e^{-tA}u\|_{p,\Omega} \leq C(p, q, n, \Omega)t^{-(n/q-n/p)/2} \|u\|_{q,\Omega},$$

$$(1.5) \quad \|\partial e^{-tA}u\|_{p,\Omega} \leq C(p, q, n, \Omega)t^{-(1+n/q-n/p)/2} \|u\|_{q,\Omega},$$

( $1 < q \leq p < \infty$ ,  $0 < t < T$ ,  $T \in (0, \infty]$ ) for  $u \in PL_q(\Omega)$ . Since our system is parabolic type, the equation (1.1) can be converted into

$$(1.6) \quad \begin{cases} u(t) = e^{-tA}a + S_1(u) + S_2(u), \\ S_1(u) = \int_0^t e^{-(t-\tau)A} F_1(u(\tau), \partial u(\tau)) d\tau, \\ S_2(u) = \int_0^t e^{-(t-\tau)A} F_2(u(\tau)) d\tau. \end{cases}$$

Our examples in §2 below satisfy the above assumptions for  $T = \infty$ .

We first establish the existence theorem.

**THEOREM 1.1.** *Let  $a$  be in  $PL_n(\Omega)$ . Then there exists a positive constant  $\lambda$  such that if  $\|a\|_{n,\Omega} < \lambda$  then there exists a unique solution to (1.1) satisfying*

$$t^{(1-n/p)/2}u \in BC([0, T]; PL_p(\Omega)) \quad \text{for } n \leq p < \infty,$$

$$t^{(1-n/(2q))}\partial u \in BC([0, T]; PL_q(\Omega)) \quad \text{for } n \leq q < \infty$$

with values zero at  $t=0$  except  $u(0)=a$  in the case  $p=n$ .

**PROOF.** The solution is constructed by means of a standard successive approximation

$$(1.7) \quad \begin{cases} u_0 = e^{-tA}a, \\ u_{m+1} = u_0 + S_1(u_m) + S_2(u_m) \quad (m=0, 1, 2, \dots). \end{cases}$$

Our result then follows from an argument analogous to that in [6, Theorem 2 (i)]. ■

Let  $Q_T := \Omega \times (0, T)$ . We would like to establish the  $L_{p,q}$ -estimates for  $u$  and its derivatives  $\partial u$ . To begin with, we have the following:

**PROPOSITION 1.1.** *Assume that  $a \in PL_n(\Omega)$  and that its norm is sufficiently small.*

Let  $p_1, p_2, q_1$  and  $q_2$  be positive numbers satisfying the relations

$$\frac{1}{q_1} = \left( \frac{1}{n} - \frac{1}{p_1} \right) \frac{n}{2}, \quad \frac{1}{q_2} = \left( \frac{2}{n} - \frac{1}{p_2} \right) \frac{n}{2},$$

with

$$\begin{aligned} \max\{3, n\} < p_1 \leq 3p_2, & \quad \frac{n}{2} < p_2, \\ \max\{3, n\} < q_1, \quad n < q_2, & \quad \frac{3}{p_1} - \frac{1}{p_2} < \frac{1}{n}, \end{aligned}$$

and

$$\frac{1}{p_1} + \frac{1}{p_2} < 1.$$

Then the solution  $u$  to (1.1) which is constructed in Theorem 1.1 satisfies

$$\begin{aligned} u &\in L_{q_1}(0, T; PL_{p_1}(\Omega)) \subset L_{p_1, q_1}(Q_T), \\ \partial u &\in L_{q_2}(0, T; PL_{p_2}(\Omega)) \subset L_{p_2, q_2}(Q_T), \end{aligned}$$

and  $\|u\|_{p_1, q_1, Q_T} + \|\partial u\|_{p_2, q_2, Q_T} \rightarrow 0$  as  $\|a\|_{n, \Omega} \rightarrow 0$ .

To show this proposition we need the following lemma:

LEMMA 1.1. Let  $p_1, p_2, q, r$  and  $s$  satisfy

$$\frac{1}{q} = \left( \frac{1}{s} - \frac{1}{p_1} \right) \frac{n}{2}, \quad \frac{1}{r} = \left( \frac{1}{n} + \frac{1}{s} - \frac{1}{p_2} \right) \frac{n}{2}$$

and

$$p_1, q, r > s > 1, \quad p_2 > \left( \frac{1}{n} + \frac{1}{s} \right)^{-1}.$$

Then we have

$$(1.8) \quad \|e^{-tA}u\|_{p_1, q, Q_T} \leq C(p_1, q, s, n, \Omega) \|u\|_{s, \Omega},$$

$$(1.9) \quad \|\partial e^{-tA}u\|_{p_2, r, Q_T} \leq C(p_2, r, s, n, \Omega) \|u\|_{s, \Omega}$$

for  $u \in PL_s(\Omega)$ .

PROOF. We find in [3] the proof of (1.8) by means of the Marcinkiewicz interpolation theorem and (1.4). (1.9) is proved in a similar manner. ■

PROOF OF PROPOSITION 1.1. We prove that  $\{u_m\}$  defined by (1.7) satisfies

$$\|u_m\|_{p_1, q_1, Q_T} + \|\partial u_m\|_{p_2, q_2, Q_T} \leq K,$$

where  $K$  is a positive constant independent of  $m$ . Since  $u_m$  converges to  $u$ , we get the first part of our assertions from this estimate.

First we have the estimate

$$\|u_0\|_{p_1, q_1, Q_T} + \|\partial u_0\|_{p_2, q_2, Q_T} \leq C \|a\|_{n, \Omega}$$

by Lemma 1.1 with  $s = n$ .

By (1.4) with  $p = p_1$ ,  $q = r$ , where  $1/r = 1/p_1 + 1/p_2$ , we have

$$\|S_1(u_m)\|_{p_1, \Omega} \leq C \int_0^t (t-\tau)^{-n/(2p_2)} \|u_m(\tau)\|_{p_1, \Omega} \|\partial u_m(\tau)\|_{p_2, \Omega} d\tau.$$

An application of the Hardy-Littlewood-Sobolev inequality [8, Corollary 1 of Lemma 7.1] gives us

$$\|S_1(u_m)\|_{p_1, q_1, Q_T} \leq C \|u_m\|_{p_1, q_1, Q_T} \|\partial u_m\|_{p_2, q_2, Q_T}.$$

Similarly we obtain

$$\|S_2(u_m)\|_{p_1, \Omega} \leq C \int_0^t (t-\tau)^{-n/p_1} \|u_m(\tau)\|_{p_1, \Omega}^3 d\tau$$

and

$$\|S_2(u_m)\|_{p_1, q_1, Q_T} \leq C \|u_m\|_{p_1, p_1, Q_T}^3.$$

By suitable use of (1.5), we can get similar estimates for  $\partial S_i$ 's, i.e.,

$$\|\partial S_1(u_m)\|_{p_2, \Omega} \leq C \int_0^t (t-\tau)^{-(1+n/p_1)/2} \|u_m(\tau)\|_{p_1, \Omega} \|\partial u_m(\tau)\|_{p_2, \Omega} d\tau,$$

$$\|\partial S_2(u_m)\|_{p_2, \Omega} \leq C \int_0^t (t-\tau)^{-(1+(3n)/p_1 - n/p_2)/2} \|u_m(\tau)\|_{p_1, \Omega}^3 d\tau.$$

These yield

$$\|\partial S_1(u_m)\|_{p_2, q_2, Q_T} \leq C \|u_m\|_{p_1, q_1, Q_T} \|\partial u_m\|_{p_2, q_2, Q_T},$$

$$\|\partial S_2(u_m)\|_{p_2, q_2, Q_T} \leq C \|u_m\|_{p_1, q_1, Q_T}^3.$$

Summing up these estimates, we get

$$\begin{aligned} & \|u_{m+1}\|_{p_1, q_1, Q_T} + \|\partial u_{m+1}\|_{p_2, q_2, Q_T} \\ & \leq C_1 \|a\|_{n, \Omega} + C_2 (\|u_m\|_{p_1, q_1, Q_T} \|\partial u_m\|_{p_2, q_2, Q_T} + \|u_m\|_{p_1, q_1, Q_T}^3). \end{aligned}$$

In the same manner as in [6, Lemma 3.3], we get the desired estimate if  $\|a\|_{n, \Omega}$  is sufficiently small. It is easy to see  $\|u\|_{p_1, q_1, Q_T} + \|\partial u\|_{p_2, q_2, Q_T} \rightarrow 0$  as  $\|a\|_{n, \Omega} \rightarrow 0$  from the above argument. ■

$$p_1 = q_1 = n + 2, \quad p_2 = \frac{n+1}{2}, \quad q_2 = n + 1$$

satisfy the conditions in Proposition 1.1, in view of our basic assumption  $n \geq 2$ . Therefore we have:

**COROLLARY 1.1.** *The solution  $u$  to (1.1) has properties*

$$\begin{aligned} u &\in L^{n+2}(Q_T), \quad \partial u \in L_{n+1}(0, T; PL_{(n+1)/2}(\Omega)), \\ \|u\|_{n+2, Q_T} + \|\partial u\|_{(n+1)/2, n+1, Q_T} &\rightarrow 0 \quad \text{as } \|a\|_{n, \Omega} \rightarrow 0. \end{aligned}$$

We are in a position to state one of our results.

**THEOREM 1.2.** *Assume that  $a \in PL_n(\Omega) \cap PL_s(\Omega)$  ( $s > 1$ ) and that  $\|a\|_{n, \Omega}$  is sufficiently small. Suppose  $p$  and  $q$  satisfy the relations*

$$\frac{1}{q} = \left( \frac{1}{s} - \frac{1}{p} \right) \frac{n}{2}, \quad p > \max \left\{ \frac{n+1}{n-1}, s \right\},$$

and

$$q > \max \left\{ \frac{n+1}{n}, s \right\}.$$

Then the solution  $u$  to (1.1) which is constructed in Theorem 1.1 satisfies

$$u \in L_q(0, T; PL_p(\Omega)) \subset L_{p,q}(Q_T).$$

**PROOF.** By Lemma 1.1, we get

$$\|u_0\|_{p,q, Q_T} \leq C \|a\|_{s, \Omega}.$$

Making use of (1.4), we obtain

$$\|S_1(u)\|_{p, \Omega} \leq C \int_0^t (t-\tau)^{-n/(n+1)} \|u(\tau)\|_{p, \Omega} \|\partial u(\tau)\|_{(n+1)/2, \Omega} d\tau$$

and

$$\|S_1(u)\|_{p,q, Q_T} \leq C \|u\|_{p,q, Q_T} \|\partial u\|_{(n+1)/2, n+1, Q_T}.$$

Similarly we get

$$\|S_2(u)\|_{p, \Omega} \leq C \int_0^t (t-\tau)^{-n/(n+2)} \|u(\tau)\|_{p, \Omega} \|u(\tau)\|_{n+2, \Omega}^2 d\tau$$

and

$$\|S_2(u)\|_{p,q, Q_T} \leq C \|u\|_{p,q, Q_T} \|u\|_{n+2, n+2, Q_T}^2.$$

If  $\|a\|_{n,\Omega}$  is sufficiently small, we then obtain the boundedness of the  $L_{p,q}$ -norm for  $u$  by virtue of Corollary 1.1. ■

For  $s > (n^2 + n)/(n^2 + n - 2)$ ,

$$p = q = \frac{s(n+2)}{2}$$

fulfill the conditions in Theorem 1.2. Thus we have:

**COROLLARY 1.2.** *If the hypotheses of Theorem 1.2 for  $s > (n^2 + n)/(n^2 + n - 2)$  are satisfied, then*

$$u \in L_{(s(n+2))/n}(0, T; PL_{(s(n+2))/n}(\Omega)) \subset L_{(s(n+2))/n}(Q_T),$$

$$\|u\|_{(s(n+2))/n, Q_T} \rightarrow 0 \quad \text{as} \quad \|a\|_{n,\Omega} + \|a\|_{s,\Omega} \rightarrow 0$$

hold for the solution  $u$  to (1.1).

Making use of Corollaries 1.1 and 1.2, we get an estimate for  $\partial u$ .

**THEOREM 1.3.** *Assume that  $a \in PL_n(\Omega) \cap PL_s(\Omega)$  ( $s > (n^2 + n)/(n^2 + n - 2)$ ) and that  $\|a\|_{n,\Omega}$  is sufficiently small. Let  $p$  and  $r$  be positive numbers satisfying*

$$\frac{1}{r} = \left( \frac{1}{n} + \frac{1}{s} - \frac{1}{p} \right) \frac{n}{2}, \quad p > \max \left\{ \frac{n+2}{n}, \left( \frac{1}{n} + \frac{1}{s} \right)^{-1} \right\}, \quad r > \max \left\{ \frac{n+2}{n+1}, s \right\},$$

and

$$\frac{1}{p} - \frac{1}{n} < \frac{1}{n+2} \left( 2 + \frac{n}{s} \right) < \frac{1}{p} + \frac{1}{n}.$$

Then the solution  $u$  to (1.1) which is constructed in Theorem 1.1 satisfies

$$\partial u \in L_r(0, T; PL_p(\Omega)) \subset L_{p,r}(Q_T).$$

**PROOF.** By (1.5), we have

$$\|\partial u_0\|_{p,r, Q_T} \leq C \|a\|_{s,\Omega},$$

and

$$\|\partial S_1(u)\|_{p,\Omega} \leq C \int_0^t (t-\tau)^{-(n+1)/(n+2)} \|u(\tau)\|_{n+2,\Omega} \|\partial u(\tau)\|_{p,\Omega} d\tau.$$

By virtue of Corollary 1.1,

$$\|\partial S_1(u)\|_{p,r, Q_T} \leq C \|u\|_{n+2, Q_T} \|\partial u\|_{p,r, Q_T}$$

holds.

Let  $s'$  be a positive number satisfying

$$\frac{3}{s'} = \frac{2}{n} + \frac{1}{s}.$$

Since  $s'$  is between  $n$  and  $s$ ,  $a \in PL_{s'}(\Omega)$  and  $s' \geq \min\{n, s\} > (n^2 + n)/(n^2 + n - 2)$ . It follows from Corollary 1.2 that  $u \in L_{(s'(n+2))/n}(0, T; PL_{(s'(n+2))/n}(\Omega))$ . By (1.5), we have

$$\|\partial S_2(u)\|_{p,\Omega} \leq C \int_0^t (t-\tau)^{-(1+(3n^2)/(s'(n+2))-n/p)/2} \|u(\tau)\|_{(s'(n+2))/n,\Omega}^3 d\tau.$$

In view of our assumption

$$0 < \frac{1}{2} \left( 1 + \frac{3n^2}{s'(n+2)} - \frac{n}{p} \right) < 1,$$

we get

$$\|\partial S_2(u)\|_{p,r,Q_T} \leq C \|u\|_{(s'(n+2))/n,Q_T}^3$$

by [8, Corollary 1 to Lemma 7.1]. Hence our assertion follows if  $\|a\|_{n,\Omega}$  is sufficiently small. ■

**2. Applications.** In this section we study some applications of our theorems.

2.1 The Navier-Stokes system. The motion of incompressible viscous fluid in  $\Omega$  (with fixed boundary condition) is described by the following system of equations, called the Navier-Stokes system:

$$(2.1.1) \quad \begin{cases} u_t = \Delta u - (u \cdot \text{grad})u - \text{grad } p, \\ \text{div } u = 0, \\ u(0) = a, \\ u|_{\partial\Omega} = 0 \text{ if } \partial\Omega \neq \emptyset. \end{cases}$$

Here,  $u = (u^1, \dots, u^n)$  and  $p$  represent the velocity and the pressure of the fluid, respectively. Let  $X_p$  be the closure in  $L_p(\Omega)$  of all  $C^\infty$ -solenoidal functions with compact support in  $\Omega$ . We define  $G_p$  by

$$G_p = \{f = \text{grad } \phi \mid \phi \in W_p^1(\Omega)\}.$$

It is well-known that the Helmholtz decomposition

$$L_p(\Omega) = X_p \oplus G_p$$

holds and that the projection  $P$  from  $L_p(\Omega)$  to  $X_p$  is a bounded operator (cf. e.g., [1]).

Applying  $P$  to both sides of the first equation of (2.1.1), we have

$$(2.1.2) \quad u_t + Au = -P(u \cdot \text{grad})u,$$

where  $A = -P\Delta$  is the Stokes operator with domain

$$\mathcal{D}(A) = PL_p(\Omega) \cap \{u \in W_p^2(\Omega) \mid u|_{\partial\Omega} = 0 \text{ if } \partial\Omega \neq \emptyset\}.$$

We can check our assumptions with  $T = \infty$  on  $A$  and on the non-linear terms described in the previous section (see [4], [3]). Therefore we get the existence of a unique solution  $u$  to (2.1.2) with initial value  $a$  by Theorem 1.1 and the  $L_{p,q}$ -estimates for  $u$  and  $\partial u$  by Theorems 1.2 and 1.3. Looking at the proof of Theorem 1.3 more carefully, we find that the assumptions in the theorem

$$s > \frac{n^2 + n}{n^2 + n - 2}, \quad \frac{1}{p} - \frac{1}{n} < \frac{1}{n+2} \left(2 + \frac{n}{s}\right) < \frac{1}{p} + \frac{1}{n}$$

are needed only for the estimate for  $\|\partial S_2(u)\|_{p,r,Q_T}$ . Since the term  $F_2(u)$  does not appear in the Navier-Stokes system, we can replace the above conditions by  $s > 1$ . Thus we have:

**THEOREM 2.1.** (i) *Assume that  $a$  is in  $PL_n(\Omega)$  and that its norm is sufficiently small. Then there exists a unique solution  $u$  to (2.1.2) with initial value  $a$  satisfying*

$$\begin{aligned} t^{(1-n/p)/2} u &\in BC([0, \infty); PL_p(\Omega)) \quad \text{for } n \leq p < \infty, \\ t^{(1-n/(2q))} \partial u &\in BC([0, \infty); PL_q(\Omega)) \quad \text{for } n \leq q < \infty \end{aligned}$$

with values zero at  $t = 0$  except  $u(0) = a$  in the case  $p = n$ .

(ii) *Assume that  $a \in PL_n(\Omega) \cap PL_s(\Omega)$  ( $s > 1$ ) and that  $\|a\|_{n,\Omega}$  is sufficiently small. Let  $p_1, p_2, q$  and  $r$  be positive numbers satisfying*

$$\begin{aligned} \frac{1}{q} &= \left(\frac{1}{s} - \frac{1}{p_1}\right) \frac{n}{2}, \quad \frac{1}{r} = \left(\frac{1}{n} + \frac{1}{s} - \frac{1}{p_2}\right) \frac{n}{2}, \\ p_1 &> \max\left\{\frac{n+1}{n-1}, s\right\}, \quad q > \max\left\{\frac{n+1}{n}, s\right\}, \quad p_2 > \max\left\{\frac{n+2}{n}, \left(\frac{1}{n} + \frac{1}{s}\right)^{-1}\right\}, \end{aligned}$$

and

$$r > \max\left\{\frac{n+2}{n+1}, s\right\}.$$

Then the solution  $u$  constructed in (i) has the properties

$$\begin{aligned} u &\in L_q(0, \infty; PL_{p_1}(\Omega)) \subset L_{p_1,q}(Q_\infty), \\ \partial u &\in L_r(0, \infty; PL_{p_2}(\Omega)) \subset L_{p_2,r}(Q_\infty). \end{aligned}$$

Kato [4] and Giga [3] already obtained similar results, using the special feature of the non-linear term

$$(u \cdot \text{grad})u^i = \text{div}(u^i u),$$

whereas we do not need such a feature.

The  $L_{p,q}$ -estimates for the Navier-Stokes system give the criteria for the regularity of weak solutions. For various regularity theorems on this system, the reader is referred to [2], [3] and references cited therein.

2.2 Semi-linear heat equations. The second example is the simplest case  $A = -\Delta$  ( $P$ =identity,  $\Delta$ =Laplacian (with the Dirichlet condition if  $\partial\Omega \neq \emptyset$ )), i.e.,

$$(2.2.1) \quad \begin{cases} u_t = \Delta u + N_1(u, \partial u) + N_2(u), \\ u(0) = a, \\ u|_{\partial\Omega} = 0 \text{ if } \partial\Omega \neq \emptyset. \end{cases}$$

As is shown in [6], our assumptions on  $A$  are fulfilled for  $T = \infty$ . Theorems 1.2 and 1.3 yield the regularity of the solutions which are constructed in Theorem 1.1. For simplicity, we assume  $a \in \bigcap_{s \geq n} L_s(\Omega)$ . For  $\varepsilon \in (0, 1)$ ,  $k, l \in (0, 2)$ , set

$$\begin{aligned} p_1 &= \frac{n^2}{(1-\varepsilon)(n-k)}, & q_1 &= \frac{2n}{k(1-\varepsilon)}, \\ p_2 &= \frac{n^2}{(2-\varepsilon)n-l(1-\varepsilon)}, & q_2 &= \frac{2n}{l(1-\varepsilon)}, \\ s_1 = s_2 &= \frac{n}{1-\varepsilon}. \end{aligned}$$

If  $1-\varepsilon$  is sufficiently small, the conditions in Theorem 1.2 hold for  $(p, q, s) = (p_1, q_1, s_1)$  and those in Theorem 1.3 do for  $(p, r, s) = (p_1, q_2, s_2)$ . Hence we have  $N_1(u, \partial u) \in L_{p,q}(Q_\infty)$ , where  $1/p = 1/p_1 + 1/p_2$ ,  $1/q = 1/q_1 + 1/q_2$ . If  $k+l$  is sufficiently small, then  $p < q$  holds. Therefore  $N_1(u, \partial u) \in L_p(Q_T)$  is valid for any  $T \in (0, \infty)$ . For any  $\delta > 0$ , we take  $1-\varepsilon$  and  $k+l$  so small that  $p \geq (n+2)/(2+\delta)$  holds. We choose  $\delta$  sufficiently small.

On the other hand, Corollary 1.2 gives us  $N_2(u) \in \bigcap_{r \geq (n+2)/3} L_r(Q_\infty)$ . Therefore the nonlinear terms belong to  $L_p(Q_T)$ . A priori estimate of  $W_p^{2,1}(Q_T)$ -type [7, IV, Theorem 9.1 or VII, Theorem 10.4] gives  $u \in W_p^{2,1}(Q_T)$  provided  $a \in W_p^{2-2/p}(\Omega)$ . Using [7, II, Lemma 3.3], we have  $N_1(u, \partial u) + N_2(u) \in L_{p'}(Q_T)$  for some  $p' > (n+2)/2$ , and therefore  $u \in W_{p'}^{2,1}(Q_T)$  provided  $a \in W_{p'}^{2-2/p'}(\Omega)$ . By the same procedure we obtain  $u \in W_r^{2,1}(Q_T)$  provided  $a \in W_r^{2-2/r}(\Omega)$  for some  $r > n+2$ . By virtue of [7, II, Lemma 3.3] again, the Hölder continuity of non-linear terms follows from the Hölder continuity of the coefficients  $a_{ijk}, b_{ijk}$ . Finally the Schauder estimate [7, IV, Theorems 5.1/5.2 or VII, Theorems 10.1/10.2] gives the fact  $u \in H^{\alpha+2, \alpha/2+1}(\overline{Q_T})$  for some  $\alpha \in (0, 1)$  provided that  $a$  is Hölder continuous up to its second order derivatives. Hence we have:

**THEOREM 2.2.** *We assume that  $a_{ijk}$  and  $b_{ijk}$  are Hölder continuous in  $\overline{Q_\infty}$ . If  $a$  belongs to  $\bigcap_{s \geq n} W_s^{2-2/s}(\Omega)$ , if  $\|a\|_{n,\Omega}$  is small, and if it is Hölder continuous up to its second order derivatives, then there exists a unique global classical solution to (2.2.1).*

REMARK. Looking at the above argument more carefully, we find that we can weaken the assumption on  $a$ .

Using a standard bootstrap argument, we get:

THEOREM 2.3. *Suppose that the hypotheses of Theorem 2.2 are satisfied and that  $a_{ijk}, b_{ijk}, a$  and  $\partial\Omega$  (if it exists) are  $C^\infty$ -smooth. Moreover when  $\partial\Omega \neq \emptyset$ , we assume that the compatibility conditions of any order hold between the initial and boundary data. Then the solution is also  $C^\infty$ .*

2.3 The equations of Yang-Mills' gradient flow. Let  $(\Omega, dx^2)$  be a smooth ( $= C^\infty$ )  $n$ -dimensional Riemannian manifold.  $E = (\Omega \times \mathbf{R}^m, \langle, \rangle)$  is a Riemannian vector bundle over  $\Omega$  of rank  $m$ .  $\mathcal{C}_E$  is the space consisting of all smooth metric connections on  $E$ . For  $\nabla \in \mathcal{C}_E$ , we define the  $\text{Hom}(E, E)$ -valued 2-form  $R^\nabla$ , called the curvature, by

$$R_{V,W}^\nabla = \nabla_V \nabla_W - \nabla_W \nabla_V - \nabla_{[V,W]}$$

for any smooth vector fields  $V, W$  on  $\Omega$ . The Yang-Mills functional  $\mathcal{YM} : \mathcal{C}_E \rightarrow [0, \infty]$  is defined by the square integral of  $R^\nabla$ :

$$\mathcal{YM}(\nabla) = \frac{1}{2} \int_{\Omega} \langle R^\nabla, R^\nabla \rangle_x.$$

We call  $\nabla$  the Yang-Mills connection, if it is a critical point of the functional. To find such a connection and to study its stability, we consider the flow

$$(2.3.1) \quad \frac{d\nabla(t)}{dt} = -\text{grad } \mathcal{YM}(\nabla(t)).$$

In [6], we studied the asymptotical stability of the flat connection  $\nabla_0$  by reducing (2.3.1) to certain system of heat equations. Taking the gauge invariance of the functional into consideration, we put

$$\nabla(t) = g(t)(\nabla_0 + A(t))g^{-1}(t),$$

where  $A(t) \in \Omega_0^1(\mathfrak{g}_E)$ ,  $g(t) \in \mathcal{G}$  (see [6, §1] for the definition of  $\Omega_0^1(\mathfrak{g}_E)$  and  $\mathcal{G}$ ). Then the principal part of the right-hand side of (2.3.1) is

$$-\delta^{\nabla_0} d^{\nabla_0} A(t) + [\nabla_0 + A(t), Y(t)],$$

where  $Y(t) = g^{-1}(t)dg(t)/dt$ , and  $\delta^{\nabla_0}$  is a formal adjoint operator of the covariant derivative  $d^{\nabla_0}$ . This does not satisfy our assumption because of the lack of ellipticity. We impose Yokotani's idea [9] on  $g(t)$ , i.e., it satisfies

$$(2.3.2) \quad \frac{dg(t)}{dt} = -g(t)\delta^{\nabla_0} A(t), \quad g(0) = \text{identity}.$$

This condition makes  $-\delta^{\nabla_0} d^{\nabla_0} A(t)$  of the term  $[\nabla_0, Y(t)]$ . Since  $-(\delta^{\nabla_0} d^{\nabla_0} + d^{\nabla_0} \delta^{\nabla_0}) = \Delta$ ,

the principal part recovers the ellipticity, and (2.3.1) is reduced to the following system of heat equations:

$$(2.3.3) \quad \begin{cases} \frac{dA(t)}{dt} = \Delta A(t) + [A(t), -\delta^{\nabla_0} A(t)] - \delta^{\nabla_0} [A(t), A(t)] \\ \quad + \sum_{\alpha=1}^n [A_{e_\alpha}(t), d^{\nabla_0} A_{e_\alpha}(t)] + \sum_{\alpha=1}^n [A_{e_\alpha}(t), [A_{e_\alpha}(t), A(t)]], \\ A|_{\partial\Omega} = 0 \quad \text{if } \partial\Omega \neq \emptyset, \end{cases}$$

where  $\{e_\alpha\}_{\alpha=1, \dots, n}$  is an orthonormal basis on  $T_x\Omega$ . For the detailed derivation of above system, the reader is referred to [9] and [5].

Our results are applicable to the equations (2.3.3). The global solvability and the stability of (2.3.2) and (2.3.3) with the given initial data  $A(0)$  are established in [6, Theorem 1], provided that the components of  $A(0)$  belong to  $\dot{W}_n^1(\Omega)$  and  $\|A(0)\|_{n,\Omega}$  is sufficiently small. (It is enough to assume  $A(0) \in L_n(\Omega)$  to solve (2.3.3), but it is not sufficient to solve (2.3.2)).

The Sobolev imbedding theorem gives the fact  $\dot{W}_n^1(\Omega) \subset \bigcap_{s \geq n} L_s(\Omega)$ . Therefore we can apply the argument of the previous subsection.

**THEOREM 2.4.** *If  $A(0)$  belongs to  $\dot{W}_n^1(\Omega) \cap \bigcap_{s \geq n} W_s^{2-2/s}(\Omega)$ , if  $\|A(0)\|_{n,\Omega}$  is small and if it is Hölder continuous up to its second order derivatives, then there exists a unique global classical solution to (2.3.2)–(2.3.3). Moreover if  $A(0)$  is  $C^\infty$  and the compatibility conditions of any order hold between the initial and boundary data in the case  $\partial\Omega \neq \emptyset$ , then the solution is also  $C^\infty$ .*

**PROOF.** It is enough to see the regularity of  $g(t)$ . This follows from the theorems of regularity and continuous dependence on parameters of ordinary differential equations. ■

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