

SOME CONTENT MAXIMIZING PROPERTIES OF THE REGULAR SIMPLEX

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In this paper it is shown that the regular simplex maximizes the sum of the squared contents of all i -dimensional faces, for all $i = 2, \dots, n$, when the sum of the one-dimensional squared contents is fixed. An immediate corollary is that the regular simplex has the largest total length of all joining lines, total area of all triangles, total volume of all tetrahedra, and so forth, for a fixed sum of squared line lengths. Some related unsolved conjectures are presented.

If a set of $n + 1$ points in n -dimensional Euclidean space do not lie in an $(n - 1)$ -dimensional hyperplane, their convex hull is a simplex, the simplest of all n -dimensional polytopes. Any two points in the set determine a one-dimensional edge, or line, any three points determine a two-dimensional face, or triangle, and so forth. If all one-dimensional edges have the same length, the simplex is called regular. If for no other reason than pure symmetry, the regular simplex should seem to be the extremum in any number of constrained maximization problems involving simplices. In this paper we consider a class of problems for which it is indeed maximal.

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1. **A symmetrization.** Let S be the simplex in E^n with vertices A_1, \dots, A_{n+1} and let $V(i, j) = a_{ij} = |A_i - A_j|$ be a typical one-dimensional edge length. More generally, let $V(i_1, \dots, i_s)$ be the content of the subsimplex formed by A_{i_1}, \dots, A_{i_s} .

THEOREM. *For $\sum a_{ij}^2 > 0$ fixed, the content power sum*

$$\sum V^\lambda(i_1, \dots, i_s) \quad 0 < \lambda \leq 2,$$

taken over all s -tuples $i_1 < \dots < i_s$, is maximal if and only if S is a regular simplex.

The proof is based on a symmetrization which can be applied to any nonregular simplex to increase each of the sums while maintaining the constraint. We will give two equivalent constructions for the symmetrization: The first gives insight into its general nature, whereas the second is more immediately useful to the proof.

Given A_1, \dots, A_{n+1} , let J be the matrix whose (i, j) th component is $A_i \cdot A_j$, a vector inner product. If the simplex is not regular, we

can assume without loss of generality that $a_{ik} \neq a_{jk}$ for some k . Let $J_{i,j}$ be the matrix formed from J by replacing every (i, k) th component and (k, i) th component by the (j, k) th component and every (j, k) th and (k, j) th component by the (i, k) th. In effect, this corresponds to an interchanging of the labels on A_i and A_j . Then let $J' = 1/2(J + J_{i,j})$. As the average of two nonnegative definite matrices, J' is itself nonnegative definite, so $J' = PAP^T$, where $A = (\lambda_{ij})$ is a diagonal matrix with nonnegative entries. Thus $J' = QQ^T$ where $Q = PA^{1/2}$. The column vectors of Q can be taken for A'_1, \dots, A'_{n+1} , the vertices of a new simplex for which $a'_{ik} = a'_{jk}$ for all k .

In physical terms, this construction is equivalent to rotating the $A_i - A_j$ edge into E^{n+1} , holding its midpoint fixed, until the edge is normal to the original E^n . The sum $\sum a_{ij}^2$ will not be affected, but the content power sum for $\lambda = 2$ will become strictly larger unless the simplex is already regular. The reader might try this for $n = 2$ to get the idea. To handle the general case, we always represent E^n as the hyperplane $x_{n+1} = 0$ in $E^{n+1} = \{(x_1, \dots, x_n, x_{n+1})\}$. Choose the origin at $1/2(A_i + A_j)$ and the x_i axis so that $A_i = (1, 0, \dots, 0)$, and $A_j = (-1, 0, \dots, 0)$. Define $S' = S(i, j; x)$ to be the simplex formed from S by replacing A_i and A_j with $A_i(x) = (x, 0, \dots, 0, \sqrt{1-x^2})$ and $A_j(x) = (-x, 0, \dots, 0, \sqrt{1-x^2})$. Note that $A_i(1) = A_i$, $A_i(-1) = A_j$, and similarly for A_j .

LEMMA 1. *If A is any point in E^n then*

$$|A_i(x) - A|^2 = \left(\frac{1+x}{2}\right) |A_i - A|^2 + \left(\frac{1-x}{2}\right) |A_j - A|^2$$

and this remains true if i and j are interchanged; hence

$$|A_i(x) - A|^2 + |A_j(x) - A|^2 = \{|A_i - A|^2 + |A_j - A|^2\}.$$

Proof. Simply write $A = (x_1, \dots, x_n, 0)$ and calculate directly.

In what follows we call the translate of a subspace a flat, and write $d(K, p)$ for the distance from the set K to the point p .

LEMMA 2. *Let F be any flat of E^n . Then*

$$g(x) = d^2(F, A_i(x))$$

is concave in x .

Proof. By the Pythagorean theorem,

$$d^2(F, A_i(x)) = 1 - x^2 + d^2(F, p)$$

where $p = (x, 0, \dots, 0) \in E^n$. Clearly $d(F, p) = |(x - x_0) \sin \theta_0|$ for some real numbers x_0 and θ_0 , unless the x_1 axis is parallel to F , in which case it is constant. In either case $g(x) = ax^2 + bx + c$ with $a \leq 0$.

Note. The above remains true if i is replaced by j . The function $g(x)$ is strictly concave unless the x_1 -axis is normal to F .

LEMMA 3. *The distance from $(x, 0, \dots, 0) \in E^{n+1}$ to a subspace of E^n is at most the distance from $(0, \dots, 0, 1) \in E^{n+1}$ to that subspace for any $-1 \leq x \leq 1$.*

Proof. The point $0 \in E^{n+1}$ belongs to the subspace.

Let $V(i, j, k_1, \dots, k_s; x)$ be the content of the subsimplex formed by $A_i(x), A_j(x), A_{k_1}, \dots, A_{k_s}$.

LEMMA 4. *We have $V(i, j, k_1, \dots, k_s) \leq V(i, j, k_1, \dots, k_s; 0)$. Equality holds if and only if the line segment joining A_i and the A_j is normal to the flat F determined by all the A_{k_m} and the point $A_0 = 1/2(A_i + A_j)$.*

Proof. The flat F cuts the subsimplex into two (measure disjoint) simplices, each of which can be considered as having for its base the convex hull of A_0 and the A_{k_m} . The heights of these simplices are $d(F, A_i)$ and $d(F, A_j)$ respectively. By choosing coordinates as before we have $A_0 = 0$ and it follows from Lemma 3 with $x = 1$ and $x = -1$ that $d(F, A_i(0)) \geq d(F, A_i)$ and $d(F, A_j(0)) \geq d(F, A_j)$. The case of equality is obvious.

LEMMA 5. *If A_1, \dots, A_k are the vertices of a simplex and if the flat formed by any $k - 2$ of them and the midpoint of the remaining two is normal to the line segment formed by the remaining two, then the simplex is regular.*

Proof. Consider A_i, A_j , and A_k where i, j and k are distinct. Since the flat determined by all vertices except A_j and A_k is equidistant from these two points, $d(A_i, A_j) = d(A_i, A_k)$. Since this is also true with i and j interchanged, every triangle is equilateral and the result follows.

We now prove the theorem. Consider the sum

$$\sum (T) = \sum V^2(i_1, \dots, i_s)$$

both for $T = S$ and $T = S(i, j; x) = S'$. There are 3 types of terms: (i) those which involve neither i nor j , (ii) those which involve exactly one of i and j , and (iii) those which involve both i and j . Terms

of type (i) are the same for S and S' . By Lemma 4 terms of type (iii) for S are at most as large as the corresponding terms for S' . We now group the terms of type (ii) in pairs so that the subscripts of two paired terms are the same except that one has an i where the other has a j . Consider a typical pair. Let B_1, \dots, B_r be the vertices corresponding to their common subscripts, H their convex hull, $V(H)$ its content, and F the flat they determine. Then each pair is proportional to

$$V^2(H) \cdot (d_i^2(x) + d_j^2(x))$$

where $d_k(x) = d(F, A_k(x))$. Note that $d_i(1) = d_j(-1)$ and $d_i(-1) = d_j(1)$. By Lemma 2,

$$\begin{aligned} d_i^2(0) + d_j^2(0) &\geq \frac{1}{2}(d_i^2(1) + d_i^2(-1)) + \frac{1}{2}(d_j^2(1) + d_j^2(-1)) \\ &= d_i^2(1) + d_j^2(1). \end{aligned}$$

Thus $\sum(S) \leq \sum(S(i, j; 0))$. By Lemma 1, when S is replaced by $S(i, j; 0)$ the quantity $\sum a_{ij}^2$ is not changed, and both distances $|A_k - A_i|$ and $|A_k - A_j|$, for any k , are replaced by their root mean square. Thus, by applying an infinite sequence of operations $S \rightarrow S(i, j; 0)$ where every pair (i, j) occurs infinitely often, one obtains a sequence of simplices $S = S_1, S_2, \dots$ which converges to a regular simplex, and moreover $\sum(S_1) \leq \sum(S_2) \leq \dots$. By Lemma 5, one of these inequalities must be strict unless S is regular.

Now for $0 < \lambda \leq 2$ the function $f(x) = x^{\lambda/2}$ is concave, so if N is the number of $V(i_1, \dots, i_s)$ then

$$\frac{1}{N} \sum f(V^2(i_1, \dots, i_s)) \leq f\left(\frac{1}{N} \sum V^2(i_1, \dots, i_s)\right),$$

i.e.

$$\sum V^\lambda(i_1, \dots, i_s) \leq N^{1-\lambda/2} (\sum V^2(i_1, \dots, i_s))^{\lambda/2}.$$

The right side is maximal if and only if S is regular. However, if S is regular then all terms in both sums are equal and we have equality. This completes the proof of the theorem.

COROLLARY. *Of all simplices whose vertices lie on a unit hypersphere U , the regular simplex uniquely maximizes the sum*

$$\sum V^\lambda(i_1, \dots, i_s) \quad 0 < \lambda \leq 2$$

taken over all s -tuples $i_1 < \dots < i_s$.

Proof. It is well known (see, e.g., [1]) that if A_1, \dots, A_{n+1} lie on U , then $\sum a_{ij}^2 = (n+1)^2(1-d^2)$ where d is the distance from the

centroid of the vertices of the simplex to the center of the sphere. Since $d = 0$ for the regular simplex, the result follows from the previous theorem.

2. Conjectures. The following conjectures concern the relationship between a hypersphere and a simplex. The interest in these particular questions comes from Information Theory: Proof of either would be sufficient to resolve the long-standing simplex code conjecture [2].

Let S be an arbitrary simplex and \hat{S} a regular simplex of n -dimensions centered on the origin. Define the function

$$s(r) = \mu_{n-1}\{X \in S: |X| = r\}$$

where μ_{n-1} is $(n - 1)$ -dimensional measure. The function thus represents the amount of a shell of radius r contained within the simplex. S . Let $\hat{s}(r)$ be the corresponding function for the regular simplex. The first conjecture is that for a given intersection volume the regular simplex minimizes the shell, or surface, content.

Conjecture 1.

$$\text{If } \int_0^{r_0} \hat{s}(r) dr = \int_0^{r_0} s(r) dr \text{ then } \hat{s}(r_0) \leq s(r_0) .$$

The second conjecture is weaker than the first, being implied by the first. Now S and \hat{S} are restricted to being formed by hyperplanes which are all at some constant distance d from the origin. Under the restriction, the conjecture is that \hat{S} minimizes the content in the following strict sense.

Conjecture 2.

$$\hat{s}(r) \leq s(r) \text{ for all } r .$$

Both conjectures seem intuitively correct, but the constraints are of a much greater complexity than those in the previous theorems.

3. Conclusions. The regular simplex is the obvious candidate for achieving the extremum of a number of functions defined on simplices under constraints. Intuitively its maximal symmetry must give it special properties. We have here explicitly shown for a set of problems a method for generating the symmetries in the course of the optimization; in addition we make some conjectures on other extremal properties. The symmetrization technique developed in this pursuit, which was originally motivated by a problem in communi-

cation theory, appears to have potential in other areas related to group representation theory. Here we started with a matrix of vertex inner products and forced it, by a convexity operation, to be invariant under all permutations of row and column indices in the symmetric group of degree n , S_n . By restricting the group to be proper subgroup of S_n , a lower degree of symmetry would be imposed. This may then give a solution to extremal problems involving more complex polytopes.

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