

DECOMPOSITION THEOREMS FOR 3-CONVEX SUBSETS OF THE PLANE

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Let S be a 3-convex subset of the plane. If $(\text{cl } S \sim S) \subseteq \text{int } (\text{cl } S)$ or if $(\text{cl } S \sim S) \subseteq \text{bdry } (\text{cl } S)$, then S is expressible as a union of four or fewer convex sets. Otherwise, S is a union of six or fewer convex sets. In each case, the bound is best possible.

1. **Introduction.** Let S be a subset of R^d . Then S is said to be 3-convex iff for every three distinct points in S , at least one of the segments determined by these points lies in S . Valentine [2] has proved that for S a closed, 3-convex subset of the plane, S is expressible as a union of three or fewer closed convex sets. We are interested in obtaining a similar decomposition without requiring the set S to be closed. The following definitions and results obtained by Valentine will be useful.

For $S \subseteq R^d$, a point x in S is a *point of local convexity* of S iff there is some neighborhood U of x such that, if $y, z \in S \cap U$, then $[y, z] \subseteq S$. If S fails to be locally convex at some point q in S , then q is called a *point of local nonconvexity* (lnc point) of S .

Let S be a closed, connected, 3-convex subset of the plane, and let Q denote the closure of the set of isolated lnc points of S . Valentine has proved that for S not convex, then $\text{card } Q \geq 1$, Q lies in the convex kernel of S , and $Q \subseteq \text{bdry } (\text{conv } Q)$. An *edge* of $\text{bdry } (\text{conv } Q)$ is a closed segment (or ray) in $\text{bdry } (\text{conv } Q)$ whose endpoints are in Q . We define a *leaf* of S in the following manner: In case $\text{card } Q \geq 3$, let L be the line determined by an edge of $\text{bdry } (\text{conv } Q)$, L_1, L_2 the corresponding open halfspaces. Then L supports $\text{conv } Q$, and we may assume $\text{conv } Q \subseteq \text{cl } (L_1)$. We define $W = \text{cl } (L_2 \cap S)$ to be a *leaf* of S . For $2 \geq \text{card } Q \geq 1$, constructions used by Valentine may be employed to decompose S into two closed convex sets, and we define each of these convex sets to be a *leaf* of S .

By Valentine's results, every point of S is either in $\text{conv } Q$ or in some leaf W of S (or both), and every leaf W is convex. Moreover, Valentine obtains his decomposition of S by showing that for any collection $\{s_i\}$ of disjoint edges of $\text{bdry } (\text{conv } Q)$, with $\{W_i\}$ the corresponding collection of leaves, $\text{conv } Q \cup (\bigcup W_i)$ is closed and convex.

Finally, we will use the following familiar definitions: For x, y in S , we say x *see* y *via* S iff the corresponding segment $[x, y]$ lies in S . A subset T of S is *visually independent via* S iff for every

x, y in T , x does not see y via S .

Throughout the paper, S will denote a 3-convex subset of the plane, Q the closure of the set of isolated lnc points of $\text{cl } S$.

2. Preliminary lemmas. The following sequence of lemmas will be useful in obtaining the desired representation theorems. We begin with an easy result.

LEMMA 1. $\text{Cl } S$ is 3-convex.

Proof. Let x, y, z be distinct points in $\text{cl } S$ and select disjoint sequences $(x_i), (y_i), (z_i)$ in S converging to x, y, z respectively. For each i , one of the corresponding segments is in S , and for one pair, say x and y , infinitely many of the segments $[x_i, y_i]$ lie in S . Since these segments converge to $[x, y]$, $[x, y]$ lies in $\text{cl } S$.

The remaining lemmas are technical in nature. Lemmas 2, 3, and 4 reveal various pleasant features of $\text{int}(\text{cl } S) \sim S$, while 5 and 6 are concerned with lnc points of $\text{cl } S$.

LEMMA 2. If $p \in \text{int}(\text{cl } S) \sim \ker(\text{cl } S) \neq \emptyset$, then $p \in S$.

Proof. Since $p \notin \ker(\text{cl } S)$, there is some point x in $\text{cl } S$ for which $[x, p] \not\subseteq \text{cl } S$. Moreover, x may be chosen in S (for if p saw every member of S via $\text{cl } S$, then p would see every member of $\text{cl } S$ via $\text{cl } S$ and p would lie in $\ker(\text{cl } S)$).

There is a convex neighborhood N of p , no point of which sees x via $\text{cl } S$, with $N \subseteq \text{int}(\text{cl } S)$. For any s, t distinct points in $N \cap S$, necessarily $[s, t] \subseteq S$ by the 3-convexity of S , so $N \cap S$ is convex. Since $N \subseteq \text{int}(\text{cl } S)$, p is interior to some triangle $\text{conv}\{w, y, z\}$ with vertices belonging to $N \cap S$. Then since $N \cap S$ is convex, $\text{conv}\{w, y, z\} \subseteq S$, and $p \in S$. In fact, $p \in \text{int } S$.

COROLLARY. If $p \in \text{cl } S \sim S$, then either $p \in \text{bdry}(\text{cl } S)$ or $p \in \ker(\text{cl } S)$ (or both).

LEMMA 3. Let $T \neq \emptyset$ be the set of points p of $\text{cl } S \sim S$ for which $p \in \text{bdry}(\text{cl } S)$. Then every connected component of T is either an isolated point of $\text{cl } S \sim S$ or an interval. Moreover, there can be at most one isolated point, and all components of T lie on a common line.

Proof. If T is a singleton point, the result is immediate, so assume that T contains at least two distinct points x, y . Let $L(x, y)$ denote

the line determined by these points. It is clear that not both x and y can be isolated in $\text{cl } S \sim S$, for otherwise, since $x, y \in \text{int}(\text{cl } S)$, it would be easy to select three points of S on $L(x, y)$ visually independent via S .

Again using the 3-convexity of S , $L(x, y) \cap S$ has at most two components, and $L(x, y) \cap T \subseteq \ker(\text{cl } S)$ has at most three components. By an earlier argument, at most one component of $L(x, y) \cap T$ is an isolated point, and clearly each component is either an isolated point or an interval.

To complete the proof, it suffices to show that $T \subseteq L(x, y)$. Let $t \in \text{int}(\text{cl } S) \sim L(x, y)$ to show $t \notin T$. Since $L(x, y) \cap T$ contains at most one isolated point, $L(x, y) \cap T$ contains at least one interval $(r, s) \subseteq \text{int}(\text{cl } S)$, and we may choose some point u in S for which (u, t) cuts (r, s) . Then select a convex neighborhood N of t , $N \subseteq \text{int}(\text{cl } S)$, so that for every q in N , (u, q) cuts (r, s) . By techniques similar to those used in the proof of Lemma 2, $N \cap S$ is convex and $t \in S$. Hence $t \notin T$ and $T \subseteq L(x, y)$.

LEMMA 4. *If $\text{cl } S \sim S$ contains an interval (r, s) disjoint from $\text{bdry}(\text{cl } S)$, then every lnc point of $\text{cl } S$ lies on $L(r, s)$.*

Proof. Assume that for some lnc point t of $\text{cl } S$, $t \notin L(r, s)$. As in the proof of Lemma 3, choose a point u and a neighborhood N of t so that u sees no point of $N \cap S$ via S . Since t is an lnc point of $\text{cl } S$, N contains points v, w in S which are visually independent via S . Hence u, v, w are visually independent via S , a contradiction, and t must lie on $L(r, s)$.

LEMMA 5. *If p is in $\ker(\text{cl } S)$ and q, r are in Q , then $q \notin (p, r)$ (where p, q, r are distinct points).*

Proof. Assume, on the contrary, that the points are collinear, with $p < q < r$. Let L denote the line containing p, q, r , L_1, L_2 the corresponding open halfspaces. Since $p \in \ker(\text{cl } S)$ and $\text{cl } S$ is not convex, there must be some point x of $\text{cl } S$ not on L , say in L_1 . Our hypothesis implies that $\text{cl } S$ is connected, so by [2], Corollary 1, $r \in \ker(\text{cl } S)$, and the triangle $\text{conv}\{p, x, r\}$ has its boundary in $\text{cl } S$. It is easy to see that the closed, 3-convex set $\text{cl } S$ is simply connected, so $\text{conv}\{p, x, r\} \subseteq \text{cl } S$. Thus since q is an lnc point for $\text{cl } S$, there must be some point y of $\text{cl } S$ in L_2 , $\text{conv}\{p, y, r\} \subseteq \text{cl } S$, and q cannot be an lnc point for $\text{cl } S$, clearly impossible. Our assumption is false, and $q \notin (p, r)$.

COROLLARY. *No three members of Q are collinear.*

LEMMA 6. *If $p \in \text{conv } Q$, $q \in Q$, $q \neq p$, and W_1, W_2 are leaves of $\text{cl } S$ containing q , then W_1, W_2 are in opposite closed halfspaces determined by $L(p, q)$.*

Proof. Clearly the hypothesis implies that $\text{cl } S$ is connected and that $\text{card } Q \geq 2$. If $\text{card } Q = 2$, the result is an immediate consequence of an argument used by Valentine (Case 2, Theorem 3 of [2]), so we may assume that $\text{card } Q \geq 3$. Let r lie on the edge of $\text{bdry}(\text{conv } Q)$ which defines W_1 , $r \neq q$. If $r \in L(p, q) \equiv L$, then by the definition of W_1 , it is obvious that W_1 is in one of the closed halfspaces determined by L , say $\text{cl } L_1$. Otherwise, without loss of generality, assume that r is in the open halfspace L_1 . Clearly p and W_1 are separated by $L(r, q)$. Now if any point x of W_1 lay in L_2 , then q would lie interior to the triangle $\text{conv } \{p, x, r\} \subseteq \text{cl } S$, and q could not be an lnc point for $\text{cl } S$, a contradiction. Hence W_1 lies in $\text{cl } L_1$ in either case.

Since $W_1 \cup \text{conv } Q$ is convex (by Valentine's results) and q is an lnc point for $\text{cl } S$, W_2 necessarily contains points in L_2 , and $W_2 \subseteq \text{cl } L_2$, finishing the proof.

3. **Decomposition theorems.** With the preliminary lemmas behind us, we begin to investigate conditions under which S may be represented as a union of four or fewer convex sets, dealing primarily with the case for $(\text{cl } S \sim S) \subseteq \text{int}(\text{cl } S)$.

The first theorem, allowing us to restrict attention to the case for $\text{cl } S = \text{cl}(\text{int } S)$, will be helpful later.

THEOREM 1. *If $\text{cl } S \neq \text{cl}(\text{int } S)$, then S is a union of two or fewer convex sets.*

Proof. Without loss of generality, assume S is connected, for otherwise the result is trivial. Let $x \in S \sim \text{cl}(\text{int } S) \neq \emptyset$, and let N be a convex neighborhood of x disjoint from $\text{int } S$. Since S is connected, x is not an isolated point of S , and it is clear that $N \cap S$ contains at least one segment.

We examine the maximal segments of $N \cap S$ (i.e., the segments which are not proper subsets of segments in $N \cap S$). It is easy to show that $N \cap S$ has at most two maximal segments, for otherwise, the 3-convexity of S together with the simple connectedness of $\text{cl } S$ would yield an open region in $\text{cl } S \cap N$. Since by Lemma 3 the points of $\text{int}(\text{cl } S) \sim S$ are collinear, this would imply that $N \cap S$ has interior points, clearly impossible by our choice of N .

In case $N \cap S$ has exactly two maximal segments, an argument similar to the one above may be used to show that any point of S

lies on one of the corresponding lines, and S is a union of two segments (possibly infinite). If $N \cap S$ has just one segment, let K_1 denote a maximal convex subset of S containing it, and let $K_2 \equiv \text{conv}(S \sim K_1)$. Again using the facts that N contains no interior points of $\text{cl } S$ and $\text{cl } S$ is simply connected, it is not hard to show that $K_2 \subseteq S$, and $S = K_1 \cup K_2$, completing the proof.

Theorems 2 and 3 show that a decomposition is possible when $(\text{cl } S \sim S) \subseteq \text{int}(\text{cl } S)$. There are two cases to consider, depending on the cardinality of Q .

THEOREM 2. *If $(\text{cl } S \sim S) \cap \text{bdry}(\text{cl } S) = \emptyset$, and $\text{card } Q = n$ for n an odd integer, $n > 1$, then S is expressible as a union of four or fewer convex sets.*

Proof. Clearly the hypothesis implies that $\text{cl } S = \text{cl}(\text{int } S)$. By the Corollary to Lemma 2, $\text{cl } S \sim S \subseteq \text{ker}(\text{cl } S)$, and by Lemma 3, every component of $\text{cl } S \sim S$ is either an isolated point or an interval. Since $\text{card } Q \geq 3$ and (by the corollary to Lemma 5) no three members of Q can be collinear, Lemma 4 implies that $\text{cl } S \sim S$ cannot contain an interval. Hence $\text{cl } S \sim S$ consists of exactly one isolated point p in $\text{ker}(\text{cl } S)$.

Select $q \in Q$ in the following manner: If $p \in \text{conv } Q$, choose $q \in Q$ so that the line $L(p, q)$ contains no other member of Q . (Clearly this is possible since $\text{card } Q$ is odd and no three members of Q are collinear.) If $p \notin \text{conv } Q$, let $\{e_i: 1 \leq i \leq n\}$ denote the edges of $\text{conv } Q$, $\{E_i: 1 \leq i \leq n\}$ the corresponding lines, with $\text{conv } Q$ in the closed halfspace $\text{cl}(E_{i1})$ for each i . Then $p \in E_{i2}$ for exactly one i , for otherwise, if $p \in E_{i2} \cap E_{j2}$, then $\text{int} \text{conv}(\{p\} \cup e_1 \cup e_2)$ would contain an lnc point of $\text{cl } S$, clearly impossible since $\{p\} \cup e_1 \cup e_2 \subseteq \text{ker}(\text{cl } S)$ and $\text{conv}(\{p\} \cup e_1 \cup e_2) \subseteq \text{cl } S$. Thus we may choose some $q \in Q$ so that $p \in \text{cl } E_{i1}$ for each edge e_i containing q . Then (p, q) contains points of $\text{conv } Q$. Since all points of $L(p, q) \cap \text{conv } Q$ are on the open ray at p emanating through q , Lemma 5 implies that $L(p, q)$ contains no other members of Q (and in fact p cannot lie on any line E_i).

To review, in either case we have chosen q in Q so that $L(p, q)$ contains no other member of Q and (p, q) contains points of $\text{conv } Q$. Letting L_1, L_2 denote distinct open halfspaces determined by $L = L(p, q)$, define $A \equiv \text{cl}(S \cap L_1)$, $B \equiv \text{cl}(S \cap L_2)$. If W_1, W_2 are leaves of $\text{cl } S$ containing q , then by Lemma 6, W_1 and W_2 are in opposite closed halfspaces determined by L , say $W_1 \subseteq \text{cl } L_1$, $W_2 \subseteq \text{cl } L_2$.

Let R_1, R_2 denote opposite closed rays at p , $R_1 \cup R_2 = L$, labeled so that $q \in R_2$. Each of $R_1 \cap S$, $R_2 \cap S$ is an interval by the 3-convexity of S . Points of $R_1 \cap S$ necessarily lie in $A \cap B$, for otherwise

R_1 would contain an lnc point of $\text{cl } S$, clearly impossible. If there are any points of $R_2 \cap S$ not in $A \cap B$, without loss of generality we may assume such points lie in W_1 and hence in $A \sim B$. Then $R_2 \cap S \subseteq A$.

By Case 4 in Theorems 2 and 3 of [2], $\text{cl}(S \sim W_2)$ is a union of two closed convex sets C_1, C_2 , selected as in Valentine's proof. Since $A = \text{cl}[\text{cl}(S \sim W_2) \cap L_1]$, A is the union of the two closed convex sets A_1, A_2 , where $A_i = \text{cl}(C_i \cap L_1)$, $i = 1, 2$. Moreover, $(R_1 \cap S) \cup (p, q]$ lies in one of these sets, say A_1 , and $R_2 \sim (p, q]$ is either in A_1 or in A_2 .

Using an identical argument for B and $\text{cl}(S \sim W_1)$, we may write B as a union of two closed convex sets B_1, B_2 with $(R_1 \cap S) \cup (p, q]$ in B_1 , and $R_2 \sim (p, q]$ disjoint from B .

At last, define sets A'_1, A'_2, B'_1, B'_2 in the following manner: If $(R_2 \cap S) \sim (p, q] \subseteq A_2$, let

$$\begin{aligned} A'_1 &\equiv A_1 \sim R_2, & A'_2 &\equiv A_2 \sim R_1, \\ B'_1 &\equiv B_1 \sim R_1, & B'_2 &\equiv B_2 \sim R_2. \end{aligned}$$

And if $(R_2 \cap S) \sim (p, q] \subseteq A_1$, let

$$\begin{aligned} A'_1 &\equiv A_1 \sim R_1, & A'_2 &\equiv A_2 \sim R_2, \\ B'_1 &\equiv B_1 \sim R_2, & B'_2 &\equiv B_2 \sim R_1. \end{aligned}$$

We assert that these are convex subsets of S whose union is S : Clearly each is a convex subset of S , and $S \sim L$ is contained in their union. For $(R_2 \cap S) \sim (p, q] \subseteq A_2$, $R_2 \cap S \subseteq A'_2 \cup B'_1$, $R_1 \cap S \subseteq A'_1$. For $(R_2 \cap S) \sim (p, q] \subseteq A_1$, $R_2 \cap S \subseteq A'_1$, $R_1 \cap S \subseteq B'_1$. Hence in either case $S \cap L$ is contained in the union of these sets, and $S = A'_1 \cup A'_2 \cup B'_1 \cup B'_2$, completing the proof of the theorem.

THEOREM 3. *If $(\text{cl } S \sim S) \cap \text{bdry}(\text{cl } S) = \emptyset$ and $\text{card } Q = n \geq 0$, where n (possibly infinite) is not an odd integer greater than one, then S is expressible as a union of four or fewer convex sets.*

Proof. If S is not connected, the result is trivial. Otherwise, by Theorem 3 of Valentine [2], $\text{cl } S$ may be expressed as a union of two or fewer closed convex sets A, B . Using Lemma 3, let L be a line containing $\text{cl } S \sim S$, L_1, L_2 the corresponding open halfspaces. Since S is 3-convex and A is convex, $S \cap A$ is 3-convex, and hence $(S \cap A) \cap L$ has at most two components, say C_1, C_2 . Let R_1, R_2 denote opposite rays on L with $C_1 \subseteq R_1, C_2 \subseteq R_2$.

Define

$$\begin{aligned} A_1 &\equiv (A \cap S \cap \text{cl } L_1) \sim R_1, \\ A_2 &\equiv (A \cap S \cap \text{cl } L_2) \sim R_2. \end{aligned}$$

Then A_1, A_2 are convex subsets of S whose union is $A \cap S$.

Similarly define convex sets B_1, B_2 whose union is $B \cap S$. Clearly $S = A_1 \cup A_2 \cup B_1 \cup B_2$, the desired result.

COROLLARY. *If $(\text{cl } S \sim S) \cap \text{bdry}(\text{cl } S) = \emptyset$, then S is expressible as a union of four or fewer convex sets. The number four is best possible.*

That the number four in the corollary is best possible is evident from Example 1.

EXAMPLE 1. Let S be the set in Figure 1, with $p \in S$. Then S is not expressible as a union of fewer than four convex sets.

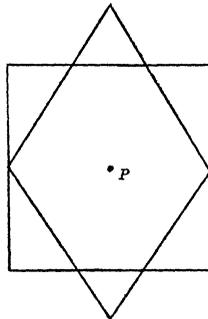


FIGURE 1

The preceding theorems allow us to obtain the following decomposition for open sets.

THEOREM 4. *If S is open, then S is expressible as a union of four or fewer convex sets. The result is best possible.*

Proof. Let $T \equiv S \cup \text{bdry}(\text{cl } S)$. Applying arguments identical to those used in the proofs of Theorems 2 and 3, T is expressible as a union of four or fewer convex sets $A_i, 1 \leq i \leq 4$. Define $B_i \equiv A_i \cap S, 1 \leq i \leq 4$. We assert that each B_i is convex. The proof follows:

By Valentine's results, $\text{cl } S$ is expressible as a union of three or fewer closed convex sets $C_j, 1 \leq j \leq 3$, each consisting of an appropriate selection of leaves of $\text{cl } S$, together with $\text{conv } Q$. Examining the proofs of Theorems 2 and 3, it is clear that each A_i may be considered as a subset of some C_j set. Thus we may assume $B_1 \subseteq C_1, A_1 \subseteq C_1$ for an appropriate C_1 .

Let $x, y \in B_1$, and let $p \in (x, y)$ to show $p \in B_1$. If x (or y) is interior to some leaf W , then $W \subseteq C_1, y$ sees a neighborhood of x via

C_i , and p is interior to $\text{cl } S$. Since $p \in A_1$ and $p \notin \text{bdry}(\text{cl } S)$, p is in $A_1 \cap S = B_1$. A similar argument holds if x (or y) is interior to $\text{conv } Q$. Since neither x nor y is in $\text{bdry}(\text{cl } S)$, the only other possibility to consider is the case in which $x, y \in \text{bdry}(\text{conv } Q) \sim Q \subseteq \ker(\text{cl } S)$. Then $x \in \text{int}(\text{cl } S)$, $y \in \ker(\text{cl } S)$, y sees some neighborhood of x via $\text{cl } S$, and $p \in \text{int}(\text{cl } S)$. Again $p \in A_1 \cap S = B_1$ and B_1 is indeed convex. Thus S is the union of the convex sets B_i , $1 \leq i \leq 4$, and the theorem is proved.

To see that the number four is best possible, let S denote the set in Example 1 with its boundary deleted. Then S is an open 3-convex set not expressible as a union of fewer than four convex sets.

4. The general case. It remains to investigate the case for S an arbitrary 3-convex subset of the plane. A decomposition of S into six convex sets may be obtained from our previous results, together with Theorems 5 and 6, which deal with the case for $(\text{cl } S \sim S) \subseteq \text{bdry}(\text{cl } S)$.

The following result by Lawrence, Hare, and Kenelly [1, Theorem 2] will be useful:

Lawrence, Hare, Kenelly Theorem. Let T be a subset of a linear space such that each finite subset $F \subseteq T$ has a k -partition, $\{F_1, \dots, F_k\}$, where $\text{conv } F_i \subseteq T$, $1 \leq i \leq k$. Then T is a union of k convex sets.

THEOREM 5. *If $\text{cl } S$ is convex and $(\text{cl } S \sim S) \subseteq \text{bdry}(\text{cl } S)$, then S is a union of three or fewer convex sets. The bound of three is best possible.*

Proof. Consider the collection of all intervals in $\text{bdry}(\text{cl } S)$ having endpoints in S and some relatively interior point not in S . Each interval determines a line L , and by the 3-convexity of S , $L \cap S$ has exactly two components. Let \mathcal{L} denote the collection of all such lines. By the Lawrence, Hare, Kenelly Theorem, without loss of generality we may assume that \mathcal{L} is finite. Hence the set $\bigcup \{L \cap S : L \text{ in } \mathcal{L}\}$ has finitely many components, and we may order these components in a clockwise direction along $\text{bdry}(\text{cl } S)$. If c_i denotes the i th component in our ordering, let

$$\begin{aligned} A' &\equiv \{c_i : i \text{ odd}, i < n\}, \\ B' &\equiv \{c_i : i \text{ even}, i < n\}, \\ C' &\equiv \{c_n\}. \end{aligned}$$

Define

$$\begin{aligned} A &\equiv S \sim (B' \cup C'), \\ B &\equiv S \sim (A' \cup C'), \\ C &\equiv S \sim (A' \cup B'). \end{aligned}$$

We assert that A, B, C are convex sets whose union is S . The proof follows:

For x, y in A , if $[x, y]$ contains any point of $\text{int}(\text{cl } S)$, then $(x, y) \subseteq \text{int}(\text{cl } S) \subseteq A$, and $[x, y] \subseteq A$. Otherwise, $[x, y]$ lies in the boundary of the convex set $\text{cl } S$. If the corresponding line $L(x, y)$ is not in \mathcal{L} , the result is clear, so suppose $L(x, y) \in \mathcal{L}$. Then x, y must lie in the same c_i set for some i odd, $i < n$, again giving the desired result. Hence A is convex. Similarly, B, C are convex. It is easy to see that $A \cup B \cup C = S$ and the proof is complete.

The surprising fact that three is best possible is illustrated by Example 2.

EXAMPLE 2. Let S denote the set in Figure 2, where dotted lines represent segments not in S . Then S is not expressible as a union of fewer than three convex sets.

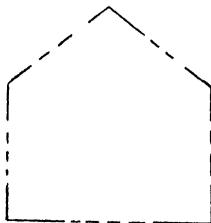


FIGURE 2

THEOREM 6. *If $(\text{cl } S \sim S) \subseteq \text{bdry}(\text{cl } S)$, then S is a union of four or fewer convex sets. The number four is best possible.*

Proof. We assume that S is connected and $\text{cl } S = \text{cl}(\text{int } S)$, for otherwise S is a union of two convex sets. Furthermore, by the Lawrence, Hare, Kenelly Theorem, we may assume that $\text{cl } S$ has finitely many leaves, and hence $\text{card } Q = n$ is finite. Notice also that since $\text{cl } S$ is simply connected and $(\text{cl } S \sim S) \subseteq \text{bdry}(\text{cl } S)$, S is simply connected.

For the moment, suppose $3 \leq n$. Order the points of Q in a clockwise direction along $\text{bdry}(\text{conv } Q)$, letting W_i denote the leaf of $\text{cl } S$ determined by line points q_i, q_{i+1} (where $n + 1 \equiv 1$). By Valentine's results in [2], for any pair of disjoint leaves W_i, W_j of $\text{cl } S$, the set $R \equiv \text{conv } Q \cup W_i \cup W_j$ is a closed convex set. (In case there are no disjoint leaves, $n = 3, W_j = \emptyset$, and $R \equiv \text{conv } Q \cup W_i$ is closed and convex.) Consider the collection of intervals in $\text{bdry } R$ having end-

points x, y in S and some relatively interior point p not in S . Either such an interval is contained in one leaf, or $x \in W_i \cup \text{conv } Q$, $y \in W_j \cup \text{conv } Q$. We examine the latter case. It is clear that for an appropriate labeling, $j = i + 2$, so to simplify notation, say $i = 1$, $j = 3$, and $L(x, y)$ supports W_2 . Clearly not both x, y can lie in $\text{conv } Q$, for then $p \in \text{int } S \subseteq S$. However, we assert that either x or y must lie in $\text{conv } Q$ and that $W_2 \cap S$ is convex. The proof follows:

Assume that x is not an lnc point and that $x < p \leq q_2 < q_3$, where q_2, q_3 are the lnc points in $W_1 \cap W_2, W_2 \cap W_3$ respectively. Then $q_2 \leq y$. For w in $W_2 \cap S$, w cannot see x via S , so necessarily w sees y via S , by the 3-convexity of S . This implies that $y \leq q_3$ (for otherwise q_3 could not be an lnc point for $\text{cl } S$). Moreover, since no two points of $W_2 \cap S$ see x via S , the 3-convexity of S together with the convexity of W_2 imply that $W_2 \cap S$ is convex.

Here we digress briefly for future reference. The set $L(x, y) \cap S$ has two components, and by the above argument, one must lie in the interval $[q_2, q_3]$, the other in $W_1 \sim Q$ (by our labeling). For general W_{i-1}, W_{i+1} (disjoint if and only if $n > 3$), we let T_i denote the connected set of all the somewhat troublesome points y in $[q_i, q_{i+1}] \cap S$ having the above property. That is, there exist points x in exactly one of $(W_{i-1} \cap S) \sim Q, (W_{i+1} \cap S) \sim Q$ for which $[x, y] \not\subseteq S$ ($n + 1 \equiv 1$).

Continuing the argument, delete W_2 and consider the 3-convex set $(S \sim W_2) \cup (S \cap L(x, y))$. Renumber the lnc points and leaves for this set so that the old W_1 and W_3 are contained in the new leaf U_1 . Since we are assuming $\text{card } Q$ is finite, repeating the procedure finitely many times yields a 3-convex set S_0 having the following property: For V_i, V_j disjoint leaves of $\text{cl } S_0$, x in $V_i \cap S_0$, y in $V_j \cap S_0$, then $[x, y] \subseteq S_0$. In addition, without loss of generality we may assume that for each leaf V_i of $\text{cl } S_0$, $V_i \cap S_0$ is not convex, for otherwise, V_i may be deleted by the above procedure.

To avoid confusion, let Q_0 denote the set of lnc points of $\text{cl } S_0$, $Q_0 \subseteq Q$, $\text{card } Q_0 = m \leq n$. For $3 \leq m$, let V_i denote the leaf determined by lnc points p_i, p_{i+1} in Q_0 (where $p_{m+1} = p_1$). For $m = 2$, let V_1, V_2 denote the leaves of $\text{cl } S_0$ as defined in the introduction to this paper. If $0 \leq m \leq 1$, let $V_1 = V_2 = \text{cl } S_0$.

For each i , consider the collection of intervals in $\text{bdry } V_i$ having endpoints in $V_i \cap S_0$ and some relatively interior point not in S_0 . Each interval determines a line L , and for $m \neq 1$, $L \cap V_i \cap S_0$ has exactly two components, each in $\text{bdry } V_i$. In case $m = 1$, an obvious adjustment may be made (by deleting any ray of L which contains interior points of $\text{cl } S_0$) to yield the same result. For each i , let \mathcal{L}_i denote the collection of all such lines. Again using the Lawrence, Hare, Kenelly Theorem, we may assume that each \mathcal{L}_i is finite. The set $\bigcup \{L \cap V_i \cap S_0: L \text{ in } \mathcal{L}_i\}$ has finitely many components, and we

may order them in a clockwise direction along bdry V_i . Let c_{ij} denote the j th such component for V_i , and let \mathcal{C}_i denote the collection of all the c_{ij} sets corresponding to V_i . Clearly each c_{ij} is either a point, an interval, or the union of two noncollinear intervals. Moreover, for $m \geq 2$, no components for V_i, V_{i+1} may have common points. (Such a point would necessarily be p_{i+1} , and if $s_i \in V_i \cap S_0, s_{i+1} \in V_{i+1} \cap S_0$ with some interior point of each of $[s_i, p_{i+1}], [p_{i+1}, s_{i+1}]$ not in S_0 , then s_i, p_{i+1}, s_{i+1} would be visually independent via S_0 , clearly impossible.)

For each V_i , select every c_{i2j} . That is, select the members of \mathcal{C}_i having second subscript even. No two components selected correspond to the same line, and for $m \neq 0$, we have chosen one component corresponding to each line in \mathcal{L} . If $m = 0$, without loss of generality we may assume \mathcal{C}_1 is ordered in a clockwise direction from some point in $Q \cap \text{cl } S_0 \neq \emptyset$. In case no component has been chosen for some line L in \mathcal{L}_1 , then L must contain points of both the first and last members of \mathcal{C}_1 , and by a previous argument, one of these components must lie in $\text{conv } Q$.

For $m \neq 1$, since V_i is convex, it is easy to show that $\text{conv } \{c_{i2j} : 1 \leq j\}$ is a subset of S_0 (and this is certainly true even if $\text{cl } S_0$ is convex). We will prove that $B_0 \equiv \text{conv } \{c_{i2j} : 1 \leq i \leq m, 1 \leq j\}$ is in S_0 and hence in S . If $\text{cl } S_0$ is convex (or empty) the result is immediate, so assume $\text{cl } S_0$ has at least one lnc point. For convenience, in case $\text{cl } S_0$ has only one lnc point, call it p_2 , and let $V_1 = V_2$ follow p_2 in our clockwise ordering.

Recall that $V_i \cap S_0$ is not convex for any i , so no \mathcal{C}_i is empty. Let c_0 denote the last member of \mathcal{C}_1 selected, x the last point of $\text{cl } c_0$ (relative to our ordering). If $x \neq p_2$, let $L = L(x, p_2)$. Otherwise, by the 3-convexity of S_0 , $c_0 = \{p_2\}$, and in this case let L denote the corresponding member of \mathcal{L}_1 . Let L_1, L_2 be the open halfspaces determined by L , with $Q_0 \subseteq \text{cl } L_1$. Since p_2 is an lnc point of S_0 and S_0 is 3-convex, it is clear that at most one member of \mathcal{C}_2 , namely c_{21} , may contain points in L_2 . We assert that c_0 sees c_{22} via S_0 . The proof follows:

In case $L \in \mathcal{L}_1, L \cap V_1 \cap S_0$ has two components, each in bdry V_1 , and one of these must be $\{p_2\}$. Then by the 3-convexity of $S_0, c_{22} \subseteq L_1$ and c_0 sees c_{22} via S_0 . Otherwise, $c_0 \sim \{x\} \subseteq L_1$. If $x \notin S_0$, then since $c_{22} \subseteq \text{cl } L_1$, it is clear that c_0 sees c_{22} via S_0 . If $x \in S_0$ and $p_2 \in S_0$, then again the result is clear. If $x \in S_0$ and $p_2 \notin S_0$, then $c_{22} \subseteq L_1$ and c_0 sees c_{22} via S_0 , finishing the argument.

In case V_1, V_2 are the only leaves for $\text{cl } S_0, V_1 \neq V_2$, then repeating the argument for the last member of \mathcal{C}_2 and c_{12} and using the fact that S_0 is simply connected, we have $B_0 \subseteq S_0 \subseteq S$. (If $V_1 = V_2$, the result is immediate.) Otherwise, $3 \leq m$ and an inductive argument may be used to show that B_0 is in S .

Using Valentine's results, write $\text{cl } S$ as a union of three or fewer convex sets A_j , $j = 1, 2, 3$, where for n odd

$$\begin{aligned} A_1 &\equiv \bigcup \{W_i: i \text{ odd}, i < n\} \cup \text{conv } Q, \\ A_2 &\equiv \bigcup \{W_i: i \text{ even}, i < n\} \cup \text{conv } Q, \\ A_3 &\equiv W_n \cup \text{conv } Q, \end{aligned}$$

and for n even

$$\begin{aligned} A_1 &\equiv \bigcup \{W_i: i \text{ odd}, i \leq n\} \cup \text{conv } Q, \\ A_2 &\equiv \bigcup \{W_i: i \text{ even}, i \leq n\} \cup \text{conv } Q, \\ A_3 &= \emptyset. \end{aligned}$$

Define $B_j \equiv S \cap [A_j \sim ((\text{bdry } S) \cap B_0)]$, $j = 1, 2, 3$.

Recall the T_i sets defined previously, $T_i \subseteq [q_i, q_{i+1}] \subseteq W_i$, $1 \leq i \leq n$. To simplify notation, let $L_i = L(q_i, q_{i+1})$, and define sets F_i, G_i in the following manner: For i even, let $F_i = T_i$ if points from both components of $L_i \cap S$ are in B_1 , $F_i = \emptyset$ otherwise. Similarly for i odd, let $F_i = T_i$ if points from both components of $L_i \cap S$ are in B_2 , $F_i = \emptyset$ otherwise. For $i = 1, i = n - 1$, let $G_i = T_i$ if points from both components of $L_i \cap S$ are in B_3 , $G_i = \emptyset$ otherwise. By previous remarks, at least one of G_1, F_1 is empty, and at least one of G_{n-1}, F_{n-1} is empty.

Define

$$\begin{aligned} D_1 &\equiv B_1 \sim \bigcup \{F_i: i \text{ even}\}, \\ D_2 &\equiv B_2 \sim \bigcup \{F_i: i \text{ odd}\}, \\ D_3 &\equiv B_3 \sim \bigcup \{G_i, G_{n-1}\}. \end{aligned}$$

Finally, letting $P = \{F_i \cap F_j: 1 \leq i < j \leq n\} \cup \{G_i \cap F_j: i = 1, n - 1, 1 \leq j \leq n\}$, define $D_0 \equiv \text{conv}(B_0 \cup P)$. We assert that the sets D_j , $0 \leq j \leq 3$, are convex sets whose union is S . The proof follows:

Suppose that one of the sets D_1, D_2, D_3 , say D_1 , is not convex to obtain a contradiction. Choose x, y in D_1 for which $[x, y] \not\subseteq D_1$. It is clear that $[x, y] \subseteq \text{bdry}(\text{cl } D_1) = \text{bdry } A_1$. Furthermore, x, y cannot both belong to $W \sim Q$ for any leaf W of $\text{cl } S$, for otherwise they would belong to the same leaf of $\text{cl } S_0$, and one of x, y would lie in $(\text{bdry } S) \cap B_0$ and hence not in D_1 , a contradiction. Employing a previous argument, the set $L(x, y) \cap S$ has two components, each having points in B_1 , and one of these components is the set $[q_i, q_{i+1}] \cap S = T_i$ for some i even ($n + 1 \equiv 1$). Let R_i denote the other component of $L(x, y) \cap S$. If $R_i \cap B_0 \neq \emptyset$, then R_i, T_i would lie on the boundary of a leaf of $\text{cl } S_0$, $R_i \subseteq B_0$, $T_i \subseteq B_1$, and $[x, y] \subseteq T_i \subseteq D_1$, a contradiction. Thus $R_i \cap B_0 = \emptyset$ and $R_i \subseteq D_1$. However, this implies that one of x, y must lie in F_i and not in D_1 , again a contradiction. Our assumption is false and D_1 is convex. Similarly D_2, D_3 are convex,

and clearly each is a subset of S .

It remains to show that the convex set D_0 lies in S . Examining the set P , if $F_i \cap F_j \neq \emptyset$ for some $i \neq j$ (or if $G_i \cap F_j \neq \emptyset$), then $F_i = T_i, F_j = T_j$, for an appropriate labeling $j = i+1$, and $F_i \cap F_{i+1} = \{q_{i+1}\} \subseteq S$. We will show that for each z in $B_0, [q_{i+1}, z] \subseteq S$. The proof follows:

We have seen that $W_i \cap S, W_{i+1} \cap S$ are both convex, so for every z in one of these sets, $[q_{i+1}, z] \subseteq S$. Moreover, we assert that the components of $L(q_i, q_{i+1}) \cap S, L(q_{i+1}, q_{i+2}) \cap S$ not in $\text{conv } Q$, call them R_i, R_{i+1} , are disjoint from B_0 : If $R_i \cap B_0 \neq \emptyset$, then by an earlier argument, $R_i \subseteq B_0, T_i \cap B_0 = \emptyset, T_i \subseteq D_1 \cap D_2 \cap D_3$, and $F_i = \emptyset$, a contradiction. Hence for z in $B_0 \sim (W_i \cup W_{i+1}), (q_{i+1}, z) \subseteq \text{int } S$, and $[q_{i+1}, z] \subseteq S$ whenever $z \in B_0$, the desired result.

Certainly for q_i, q_j, q_k in $P \subseteq S, \text{conv } \{q_i, q_j, q_k\} \subseteq S$.

By Carathéodory's theorem in the plane, to prove that $D_0 \equiv \text{conv}(B_0 \cup P)$ is in S , it is sufficient to show that the convex hull of any three points of $B_0 \cup P$ is in S , and from the remarks above, clearly we need only show $\text{conv } \{q_i, q_j, z\} \subseteq S$ for q_i, q_j in P, z in B_0 . However, since S is simply connected and $\text{bdry}(\text{conv } \{q_i, q_j, z\}) \subseteq S, \text{conv } \{q_i, q_j, z\} \subseteq S$ and $D_0 \subseteq S$, the desired result.

Finally, by inspection, each $F_i \neq \emptyset$ fails to belong to at most one of the sets D_1, D_2, D_3 . Points in intersecting F_i sets are in D_0 , so $\bigcup \{D_j: 0 \leq j \leq 3\} = S$ and the argument for $3 \leq \text{card } Q$ is complete.

To finish the proof, we must examine the cases for $0 \leq \text{card } Q \leq 2$. If $\text{card } Q = 2$ or if $\text{card } Q = 1$ and $S \sim Q$ is connected, then let W_1, W_2 denote the corresponding leaves of $\text{cl } S$, and use a simplified version of the previous proof to define B_0, B_1, B_2 . If one of B_1, B_2 , say B_1 , is not convex, then letting $T = W_1 \cap W_2 \cap S, W_2 \cap S = B_2$ is convex, $T \subseteq B_2$, and $B_0, B_1 \sim T, B_2$ are the desired convex sets.

In case $\text{card } Q = 1$ and $S \sim Q$ is not connected, then for W_1, W_2 the corresponding leaves of $\text{cl } S$, each of $W_1 \cap S, W_2 \cap S$ is convex. For $\text{card } Q = 0$, the result follows from Theorem 5, and the proof of Theorem 6 is complete.

The number four in Theorem 6 is best possible, as the following example illustrates.

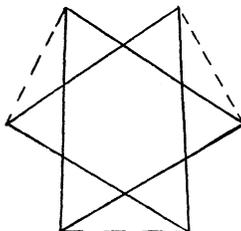


FIGURE 3

EXAMPLE 3. Let S denote the set in Figure 3, where dotted segments are in $\text{bdry}(\text{cl } S) \sim S$. Then S is a union of no fewer than four convex sets.

At last, using Theorem 6, we have a decomposition theorem for S an arbitrary 3-convex subset of the plane.

THEOREM 7. *The set S is a union of six or fewer convex sets. The result is best possible.*

Proof. By earlier comments, we may assume that S is connected, $\text{cl } S = \text{cl}(\text{int } S)$, and Q is finite. Furthermore, we assume $\text{int}(\text{cl } S) \sim S \neq \emptyset$, for otherwise the result is an immediate consequence of Theorem 6. Let $T \equiv S \cup \text{bdry}(\text{cl } S)$, and let L be the line containing $\text{cl } T \sim T$ described in Theorem 2 or Theorem 3 (whichever is appropriate). Clearly L may be chosen to contain an lnc point q of $\text{cl } S$. If L_1, L_2 are the corresponding open halfspaces, then each of $T_1 \equiv \text{cl}(T \cap L_1) = \text{cl}(S \cap L_1)$, $T_2 \equiv \text{cl}(T \cap L_2) = \text{cl}(S \cap L_2)$ is 3-convex.

Define $S_i \equiv T_i \cap S$, $i = 1, 2, \dots$. We assert that each S_i is 3-convex: For x, y, z in $S_1 = T_1 \cap S$, assume $[x, y]$ lies in the 3-convex set S to show $[x, y] \subseteq S_1$. If x or y is in L_1 , then certainly $(x, y) \subseteq L_1 \cap S \subseteq T_1$, and $[x, y] \subseteq S_1$. If x, y are on L , then since no lnc points of the closed set T_1 are on L , x, y lie in the same leaf of T_1 , and $[x, y] \subseteq T_1 \cap S = S_1$. Thus S_1 is 3-convex. Similarly S_2 is 3-convex. Moreover, $(\text{cl } S_i \sim S_i) \subseteq \text{bdry}(\text{cl } S_i)$, $i = 1, 2$.

Using Theorem 6, we will show that each S_i is a union of three convex sets: By the proofs of Theorems 2 and 3, $\text{cl } S_i = T_i$ is a union of two convex sets A_1, A_2 , and each A_i may be considered a subset of an appropriate C_j set, $1 \leq j \leq 3$, where the C_j sets are those described in Valentine's paper with $\text{cl } S = C_1 \cup C_2 \cup C_3$. In case T_1 has one leaf or an even number of leaves, then clearly the proof of Theorem 6 may be used to write S_1 as a union of three convex sets. If T_1 has n leaves for n odd, $n > 1$, let V be the leaf of T_1 bounded by L , $q \in Q \cap L \subseteq A_1 \cap A_2$. Order the lnc points of T_1 in a clockwise direction so that V is determined by q_n, q_1 , and let U_n, U_{n+1} denote the closed subsets of V bounded by $L(q_n, q)$, $L(q, q_1)$ respectively. Treating U_1, \dots, U_n, U_{n+1} as leaves of T_1 , U_i determined by lnc points q_i, q_{i+1} , $1 \leq i < n$, the proof of Theorem 6 may be applied to write S_1 as a union of three convex sets. (Of course, in defining B_0 , points of V in S_0 belong to the same leaf of S_0 .)

By a parallel argument S_2 is a union of three convex sets, and $S = S_1 \cup S_2$ is a union of six or fewer convex sets, finishing the proof of the theorem.

Our final example shows that the bound of six in Theorem 7 is

best possible.

EXAMPLE 4. Let S be the set in Figure 4, with dotted segments in $\text{bdry}(\text{cl } S) \sim S$ and $p \in \text{int}(\text{cl } S) \sim S$. Then S cannot be expressed as a union of fewer than six convex sets.

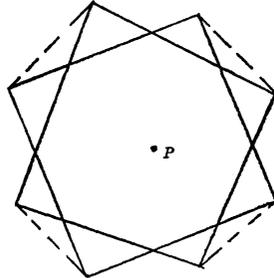


FIGURE 4

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