# ACTIONS OF FINITE GROUPS ON KNOT COMPLEMENTS 

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#### Abstract

We examine the symmetry of the complement of a non-trivial knot $K$ in $S^{3}$ and obtain a classification of the actions of finite groups on the complement of a non-trivial knot in the case where the actions extend to non-fixed point free actions on the three sphere. We prove the result by showing first an extension theorem which says that any action of finite group on a non-trivial knot complement extends to an action on the three sphere and then by applying the solution of the Smith conjecture.


Let $N(K)$ be a regular neighborhood of $K ; m, l$ be a meridian and a preferred longitude of $K$ in $\partial N(K)$ respectively; [ $m$ ], [l] be the homology classes in $H_{1}(\partial N(K), Z)$ represented by $m, l$ respectively. A knot is called a hyperbolic knot if $S^{3}-K$ has a hyperbolic structure. See $[R]$, or $[B, Z]$ for the standard terminology that we use. The main results of this note are the following. Theorem 1 also follows from the recent result of Gordon and Luecke [G, L]. Since the proof is simple, it is included here for completeness.

Theorem 1. If $K$ is a hyperbolic knot, then any self-diffeomorphism of the knot complement $S^{3}-\operatorname{int}(N(K))$ extends to a self-diffeomorphism of $S^{3}$.

Satellite knots have property P by Gabai's work, and torus knots are also known to have property P. One obtains the following theorem.

Corollary 1. Any self-diffeomorphism of a non-trivial knot complement $S^{3}-N(K)$ extends to a self-diffeomorphism of $S^{3}$.

Theorem 2. If $G$ is a finite group acting smoothly on the complement $S^{3}-\operatorname{int}(N(K))$ of a non-trivial knot $K$, then the group $G$ is a cyclic or a dihedral group, and the $G$-action extends to a $G$-action on $S^{3}$. In particular, if $K$ is a hyperbolic knot, then $\operatorname{Out}\left(\pi_{1}\left(S^{3}-K\right)\right.$ ) (or what is the same $\operatorname{Isom}\left(S^{3}-K\right)$ ) is a cyclic or a dihedral group.

With the help of a computer, Riley [Ri] has calculated the
$\operatorname{Out}\left(\pi_{1}\left(S^{3}-K\right)\right)$ for the following hyperbolic knots, $5_{2}, 6_{3}, 7_{7}, 8_{21}$, $9_{35}, 9_{43}$, and $9_{48}$, the corresponding groups are: $D_{2}, D_{4}, D_{4}, D_{2}$, $D_{6}, Z_{2}$, and $D_{6}$. The theorem explains the general fact behind Riley's work. Combining with the work of Culler, Gordon, Luecke, Shalen (see [CGLS]), Bleiler and Scharlemann [B, S] on the property P of non-trivial knots invariant under non-trivial periodic automorphisms of $S^{3}$, we have the following.

Corollary 2. If there exists a finite group acting smoothly nontrivially on a knot complement in $S^{3}$, then the knot has property P. In particular, if $K$ is a hyperbolic knot with non-trivial $\operatorname{Out}\left(\pi_{1}\left(S^{3}-K\right)\right)$, then $K$ has property P .

If the group $G$ in Theorem 2 is cyclic, the $G$-action on the knot complement can be described more explicitly. Before stating the corollary, let us make the following conventions. A $2 \pi / n$-rotation of $S^{3}$ is a $Z_{n}$-action which is conjugate to the orientation preserving $Z_{n}$ action generated by $A$ where $A$ sends a point $(x, z)$ in $S^{3}=R^{1} \times$ $C \cup\{$ infinity $\}$ to $\left(x, e^{2 \pi i / n} z\right)$ and infinity to infinity. The circle $\{(x, z) \mid z=0\} \cup\{$ infinity $\}$ is called the axis of the rotation. A twisted $2 \pi / n$-rotation of $S^{3}$ is an action conjugate to the non-orientation preserving $Z_{n}$-action generated by $\alpha$, where $\alpha$ is described as follows. Represent $S^{3}$ as $\left(R^{1} \times C\right) \cup\{$ infinity $\}, \alpha$ is the automorphism sending $(x, z)$ to $\left(-x,-e^{2 \pi i / n} z\right)$, and infinity to infinity. The circle $\{(x, z) \mid z=0\} \cup\{$ infinity $\}$ is called the axis of the twisted rotation. A reflection of $S^{3}$ through two points is an action conjugate to the orientation reversing involution of $S^{3}$ generated by $\beta$, where $\beta$ is the automorphism of $S^{3}$ considered as $R^{3} \cup\{$ infinity $\}$ sending $x$ to $-x$, for $x$ in $R^{3}$, and infinity to infinity.

Corollary 3. The smooth action of a cyclic group $Z_{n}$ on a nontrivial knot complement $S^{3}-\operatorname{int}(N(K))$ are classified as follows.
(I) The action preserves the orientation. There are two cases.
(a) The action on $S^{3}-\operatorname{int}(N(K))$ is free. Then the action is induced by a fixed point free $Z_{n}$-action on $S^{3} . K$ is invariant under the action.
(b) The action is not free. Then the $Z_{n}$-action is induced by a $2 \pi / n$ rotation of $S^{3}$ about a trivial knot $L . K$ is invariant under the rotation. $K$ is disjoint from $L$, or $K$ intersects $L$ transversely in two points. If the latter happens, $n=2$.
(II) The $Z_{n}$-action on $S^{3}-\operatorname{int}(N(K))$ does not preserve the orientation. Then the $Z_{n}$-action has fixed points in $S^{3}$, and is of even order.

There are four kinds:
(c) $n=2$. Then the action is induced by a reflection $R$ of $S^{3}$ through two points, or is induced by a reflection $R^{\prime}$ of $S^{3}$ with respect to a two-sphere, which is the same as a twisted $\pi$-rotation of $S^{3}$.K is invariant under the involution. There are three types of $Z_{2}$-actions on $S^{3}-\operatorname{int}(N(K))$.
$(\mathrm{c})_{1} K$ is disjoint from the two fixed points of the reflection $R$. In this case the $Z_{2}$-action on $S^{3}-\operatorname{int}(N(K))$ has two fixed points.
$(\mathrm{c})_{2} K$ contains the two fixed points of $R$. In this case, the $Z_{2^{-}}$ action is a free action on $S^{3}-\operatorname{int}(N(K))$.
(c) $)_{3} K$ intersects the 2-sphere fixed points of $R^{\prime}$ transversely in two points. In this case, $K$ is of the form $K=L \#(-L)$ for some knot $L$.
(d) $n \geq 4$. Then the action is induced by a twisted $2 \pi / n$-rotation of $S^{3}$ about an axis $L . K$ is invariant, and is disjoint from $L$.

We state the following as a corollary for convenience.
Corollary 4. If a cyclic group $Z_{n}$ generated by $g$ acts smoothly on a non-trivial knot complement $S^{3}-\operatorname{int}(N(K))$ such that $g_{*}([l])=-[l]$ in $H_{1}(\partial N(K), Z)$, then $g$ is an involution.

Combining Corollaries 3 and 4, smooth action of dihedral groups on a knot complement can also be classified. We omit it here.

Recall that a knot $K$ is invertible if $K$ is oriented equivalent to $-K$, the inverted knot of $K ; K$ is amphicheiral if $K$ is equivalent to its mirror-image $K^{*}$.

COROLLARY 5. If $K$ is a hyperbolic knot in $S^{3}$, then the following holds.
(a) $K$ is invertible if and only if $K$ is invariant under a $\pi$-rotation in $S^{3}$ about an axis $L$ such that $L$ intersects $K$ transversely in two points.
(b) $K$ is amphicheiral if and only if $K$ is invariant under a twisted $2 \pi / n$-rotation of $S^{3}$ about an axis missing $K$, for $n \geq 4$, or $K$ is invariant under a reflection of $S^{3}$ through two points missing $K$.
(c) If $K$ is both invertible and amphicheiral, then $K$ is invariant under a reflection of $S^{3}$ through two points contained in $K$.

In $\S 1$, we prove Theorem 1. In $\S 2$, we prove Theorem 2, and its corollaries. In the appendix, we prove the following proposition concerning smooth non-orientation preserving cyclic group actions on $S^{3}$.

Proposition. Any smooth non-orientation preserving cyclic group action on the 3 -sphere is conjugate to a twisted rotation or a reflection of the sphere through two points.

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1. Proof of Theorem 1. Let $K$ be a hyperbolic knot in $S^{3}$ with $S^{3}-K$ having a hyperbolic metric; $N(K)$ be a regular neighborhood of $K$ such that $\partial N(K)$ is a flat torus in $S^{3}-K$ with respect to the hyperbolic metric; $m, l$ be a meridian and a preferred longitude of $K$ respectively, $m, l$ lie in $\partial N(K)$ and be realized as geodesics. $m, l$ will also be used to denote the elements in $\pi_{1}\left(S^{3}-\operatorname{int}(N(K))\right)$ represented by them. Let [ $m$ ], [ $l$ ] be the homology classes in $H_{1}(\partial N(K), Z)$ represented by $m, l$ respectively. Let $h$ be a self-diffeomorphism of $S^{3}-\operatorname{int}(N(K))$. Our goal is to prove that $h^{*}([m])$ is $\pm[m]$ in $H_{1}(\partial N(K), Z)$. Since if this condition is satisfied,

$$
\left.h\right|_{\partial N(K)}: \partial N(K) \rightarrow \partial N(K)
$$

extends to be a self-diffeomorphism of $N(K)$ which in turn gives an extension of $h$ to $S^{3}$ by gluing. By Mostow Rigidity, one can assume that $h$ is a hyperbolic isometry. $h_{*}([l])=\varepsilon_{1}[l]$ with $\varepsilon_{1}$ being $\pm 1$ in $H_{1}(\partial N(K), Z)$, because $\pm[l]$ are the only primitive homology classes in $H_{1}(\partial N(K), Z)$ which vanish in $H_{1}\left(S^{3}-\operatorname{int}(N(K)), Z\right)$ under the inclusion homomorphism. $h_{*}$ is an automorphism of $H_{1}(\partial N(K), Z)$; hence $h_{*}[m]=\varepsilon[m]+a[l]$, where $\varepsilon_{2}= \pm 1$, and $a$ is in $Z$. Our goal is to show $a=0$. If $\varepsilon_{1}=\varepsilon_{2}$, i.e., $h$ is orientation preserving, the result is trivial because on one hand $h$, being an isometry of a hyperbolic manifold of finite volume, is of finite order (i.e., composition of $h$ finite times is the identity map; see [ $\mathbf{M}, \mathbf{B}]$, or $[\mathbf{T h}]$ ), on the other hand the matrix $\left[\begin{array}{cc}\varepsilon_{1} & a \\ 0 & \varepsilon_{2}\end{array}\right]$ has infinite order if $a$ is non-zero. Therefore, we need only to consider the case where $\varepsilon_{1}=-\varepsilon_{2}$. Suppose conversely $a \neq 0$. Then by Culler, Gordon, Luecke, Shalen [CGLS], one has that $a= \pm 1$, and that $K$ does not have property P. Since the matrix $\left[\begin{array}{cc}\varepsilon_{1} & a \\ 0 & \varepsilon_{2}\end{array}\right]$ is of order two, $h_{*} h_{*}=$ id in $H_{1}(\partial N(K), Z)$. Consider the orientation preserving isometry $g=h \circ h . g$ is of finite order; hence it generates a finite cyclic group $G$ acting isometrically on the flat torus $\partial N(K)$. Because $g_{*}([m])=[m]$ and $g_{*}[l]=[l]$ in $H_{1}(\partial N(K), Z), G$ preserves the foliations $\partial N(K)$ by geodesic
meridians and by geodesic longitudes. The following lemma shows that the $G$-action on $\partial N(K)$ can be extended to a $G$-action on $N(K)$.

Lemma 1. If $G$ acts isometrically on a flat boundary $\partial N$ of a solid torus $N$ and $g_{*}[m]= \pm[m], g_{*}[l]= \pm[l]$ in $H_{1}(\partial N, Z)$ where $g$ is a generator of $G, m, l$ are a meridian and a longitude of $\partial N$ respectively, then the G-action can be extended to an action on $N$. Moreover the extended $G$-action on the core of $N$ preserves a flat Riemannian metric on it.

Proof. Parametrize $\partial N$ by $(u, v)$, where $u, v$ are the unit complex numbers such that $S^{1} \times\{v\}$ and $\{u\} \times S^{1}$ correspond to the geodesic meridian $m$ and the geodesic longitude $l$ in $\partial N$. Since the action on the homology group $H_{1}(\partial N, Z)$ satisfies the conditions above, the $G$-action on $\partial N$ corresponds now to a $G$-action on $S^{1} \times S^{1}$ preserving the standard product metric and the product structure. Extending the $G$-action on $\partial N$ to $N$ is the same as extending the $G$-action on $S^{1} \times S^{1}$ to $D^{2} \times S^{1}$. The extension of the latter is trivial. To see this, for $g \in G$, we have,

$$
g(u, v)=(\phi(u, g), \psi(v, g))
$$

where $u, v \in S^{1}, \phi(u, g)=\alpha u$, or $\alpha \bar{u}$, and $\psi(v, g)=\beta v$ or $\beta \bar{v}$, for some roots of unity $\alpha$ and $\beta$. The extension of the $G$-action to $D^{2} \times S^{1}$ is given by the same formula with $u$ in $D^{2}=\{z \in C| | z \mid \leq 1\}$. The extended $G$-action still preserves the product metric and acts on the core $\{0\} \times S^{1}$ isometrically with respect to the flat metric induced from $D^{2} \times S^{1}$.

We have now a cyclic group $G$ which acts on $S^{3}$ preserving $K$. If $G$ is non-trivial, then $K$ has property P by Corollary 7 of Culler, Gordon, Luecke, Shalen [CGLS] which contradicts $a \neq 0$. Therefore $h \circ h=\mathrm{id}$ in $S^{3}-\operatorname{int}(N(K))$. It is easy to check, using $a= \pm 1$, $h_{*}([m])=-\varepsilon_{1}[m]+a[l]$ and $h_{*}([l])=\varepsilon_{1}[l]$, that

$$
h_{*}\left(-2 \varepsilon_{1} a[m]+[l]\right)=-\varepsilon_{1}\left(-2 \varepsilon_{1} a[m]+[l]\right)
$$

Note that $[l]$, and $-2 \varepsilon_{1} a[m]+[l]$ are primitive elements, and are the ( $\pm 1$ )-eigenvectors of $h_{*}$ in $H_{1}(\partial N(K), Z)$. The algebraic intersection number of $[l]$ and $-2 \varepsilon_{1} a[m]+[l]$ is $\pm 2$. The following lemma shows that $h$ has fixed points in $\partial N(K)$.

Lemma 2. Suppose $h$ is an orientation reversing fixed point free involution of a torus $T^{2}$, then the ( $\pm 1$ )-eigenspaces of $h_{*}$ are generated by two primitive classes with $\pm 1$ as their algebraic intersection number.

Proof. Since any orientation reversing fixed point free involution of $T^{2}$ has the quotient space homeomorphic to the Klein bottle, and since the Klein bottle has only one orientable two-fold cover up to covering equivalence, any two orientation reversing fixed point free involutions on $T^{2}$ are conjugate. Because the hypothesis and the conclusion of the lemma are invariant under conjugation, the lemma follows by checking a concrete example. Take $T^{2}$ to be $S^{1} \times S^{1}$ parametrized by $(u, v)$, where $u, v \in S^{1}$, the unit circle in the complex plane. Let $h: T^{2} \rightarrow T^{2}$ be the automorphism sending $(u, v)$ to $(\bar{u},-v)$. $h$ generates a fixed point free orientation reversing involution of $T^{2}$. The 1 -eigenspace of $h_{*}$ is generated by the homology class of the curve $\{1\} \times S^{1}$, and the $(-1)$-eigenspace of $h_{*}$ is generated by the homology class of the curve $S^{1} \times\{1\}$. Hence the algebraic intersection number of the primitive generators of ( $\pm 1$ )-eigenspaces is $\pm 1$.

By the lemma, $h$ has fixed points in $\partial N(K)$. However, $h$ is an orientation reversing involution, $\operatorname{Fix}\left(\left.h\right|_{\partial N(K)}\right)$ is a 1 -dimensional submanifold. This implies that Fix $(h)$ contains a 2-manifold, say $F$. We claim that this is impossible. By Smith theory (see [B], Theorem 5.1), for the $Z_{2}$-action generated by $h$ on the 1 -dimensional $Z_{2}$-homology sphere $S^{3}-\operatorname{int}(N(K))$, the fixed point set $\operatorname{Fix}(h)$ is a $Z_{2}$-homology sphere of dimension at most one. Hence $\operatorname{Fix}(h)(=F)$ is an annulus or a Möbius band.

Case 1. $F$ is an annulus. Since $S^{3}-K$ has a hyperbolic structure, $S^{3}=\operatorname{int}(N(K))$ is annulus free. Hence $F$ is parallel to an annulus in $\partial N(K)$. In particular, $F$ is separating. The two components of the complement of $F$ in $S^{3}-\operatorname{int}(N(K))$ are interchanged by $h$ and hence are homeomorphic. Therefore both of them are solid tori. This implies that $S^{3}-\operatorname{int}(N(K))$ is the union of two solid tori along an annulus in their boundaries which contradicts the existence of the hyperbolic structure of finite volume in $S^{3}-K$.

Case 2. $F$ is a Möbius band. $\partial F$ is now a simple closed curve in $\partial N(K)$ fixed by $h$, and hence [ $\partial F]$ is in the 1 -eigenspace of $h_{*}$ which is generated by $[l]$, or by $2 a[m]+[l]$ according to $\varepsilon_{1}=1$, or -1 . Thus $\partial F$ and $K$ bound an annulus $A$ in $N(K)$. The Möbius band $F \cup_{\partial} A$ in $S^{3}$ has $K$ as its boundary. Let $L$ be the core of
the Möbius band. If $L$ is non-trivial, $K$ is the cable knot of $L$. This contradicts that $K$ is a hyperbolic knot. If $L$ is the trivial knot, then $K$ is the $(2, n)$-torus which is again absurd.

This completes the proof of Theorem 1.

Since any non-trivial knot with property $P$ has the property that any self-diffeomorphism of the knot complement preserves the meridian, and since the only non-trivial knots which are not known to have property P are some hyperbolic knots by the work of Gabai and others, Corollary 2 follows from Theorem 1.
2. Proof of Theorem 2. We shall still use the same notations introduced in $\S 1$. Hence $K$ is a non-trivial knot in $S^{3} ; N(K)$ is a regular neighborhood of $K ; m, l$ are a meridian and a preferred longitude of $K$ respectively. $m, l$ lie in $\partial N(K)$. Our first observation is that there exists a flat metric on $\partial N(K)$ such that $G$ acts on $\partial N(K)$ isometrically. This follows from the Geometrization Theorem that any action of a finite group $G$ on a 2 -manifold is equivalent to a geometric group action (see [E]). Fix the metric on $\partial N(K)$, and realize $m, l$ by geodesics in $\partial N(K)$. Theorem 1 shows that the $G$-action on $\partial N(K)$ preserves the geodesic meridians and geodesic longitudes in $\partial N(K)$. By Lemma 1 , the $G$-action on $\partial N(K)$ extends to a $G$-action on $N(K)$ such that the extended $G$-action preserves a flat metric on $K$. Hence the $G$-action on $S^{3}-\operatorname{int}(N(K))$ extends to a $G$-action on $S^{3}$ which preserves $K$ and acts on $K$ preserving a flat metric $d$. The restriction of the $G$-action to $K$ gives a representation:

$$
\sigma: G \rightarrow \operatorname{Isom}(K, d)
$$

The solution of the Smith Conjecture shows that $\sigma$ is a monomorphism. To see this, let $h \in \operatorname{ker}(\sigma)$, and $H$ be the cyclic group by $h$. Then $H$ acts on $S^{3}$ with fixed point set containing $K$, and $H$ preserves each geodesic meridian in $\partial N(K)$. Moreover, $h_{*}([l])=[l]$ in $H_{1}(\partial N(K), Z)$. There are now two cases that might happen.

Case 1. $h_{*}([m])=[m] . h$ is now an orientation preserving homeomorphism because $h_{*}([l])=[l]$ and $h_{*}([m])=[m]$ imply that $h$ is an orientation preserving homeomorphism in $H_{1}(\partial N(K), Z)$. Therefore the $H$-action on a geodesic meridian $m$ is a rotation. Suppose $h \neq \mathrm{id}$; then $H$ acts non-trivially on $m$. Therefore $K$ is the only fixed point set of $h$ in $N(K)$. By Smith theory, $\operatorname{Fix}(h)=K$, which then contradicts the solution of the Smith Conjecture.

Case 2. $h_{*}([m])=-[m] . h$ is now an orientation reversing homeomorphism. Since $h \circ h \in \operatorname{ker}(\sigma)$, and $h_{*} h_{*}([m])=[m]$, one has $h \circ h=\mathrm{id}$ by the solution of Case 1. Hence $h$ is an orientation reversing involution of $S^{3}$ with fixed point set containing $K$. Because the $\operatorname{Fix}(h)$ is a submanifold of odd codimension and contains $K$, Fix $(h)$ contains a 2-manifold. By Smith Theory, the Fix $(h)$ is a $Z_{2}-$ homology sphere. Hence $\operatorname{Fix}(h)$ is a 2 -sphere and contains $K$. This implies that $K$ is a trivial knot which is absurd.

Therefore $G$ is a subgroup of $\operatorname{Isom}(K, d)$. It is well known that a finite subgroup of $\operatorname{Isom}(K, d)$ is a cyclic or a dihedral group. In case $K$ is a hyperbolic $\operatorname{knot}, \operatorname{Out}\left(\pi_{1}\left(S^{3}-K\right)\right)$ acts isometrically on $S^{3}-\operatorname{int}(N(K))$ where $\partial N(K)$ is a flat torus in $S^{3}=K$ (see [M, B], or [Th]). Hence $\operatorname{Out}\left(\pi_{1}\left(S^{3}-K\right)\right.$ ) (or the same $\operatorname{Isom}\left(S^{3}-K\right)$ ) is a cyclic or a dihedral group.

Proof of Corollary 3. By Theorem 2 and its proof, the $Z_{n}$-action extends to a $Z_{n}$-action on $S^{3}$ such that $K$ is invariant and $K$ intersects the fixed point set of a nontrivial element $f$ in $Z_{n}$ if and only if $\operatorname{Fix}(\sigma(f)) \cap K \neq \varnothing$. But $\operatorname{Fix}(\sigma(f)) \cap K \neq \varnothing$ if and only if $\sigma(f)$ is a reflection on $K$ which in turn is the same as $f_{*}([l])=-[l]$ in $H_{1}(\partial N(K), Z)$. Moreover, in this case, $K$ intersects Fix $(f)$ transversely in two points. The classification is now reduced to the classification of smooth cyclic group actions on $S^{3}$.
(I) The $Z_{n}$-action preserves the orientation.

If the $Z_{n}$-action on $S^{3}$ is fixed point free, we have (a). Otherwise, by Smith theory, the fixed point set is a knot, say $L$. The solution of the Smith Conjecture shows that $L$ is a trivial knot, and the $Z_{n}$-action is a $2 \pi / n$-rotation about $L$. Let $g$ be a generator of the $Z_{n}$-action. If $L$ intersects $K$, then by the remark above, we have $g_{*}([l])=[l]$, and $\sigma(g)$ is a reflection in $K$. Hence Fix $(g \circ g)$ contains $K$. However $g g$ is orientation preserving. Therefore the solution of the Smith Conjecture implies that $g \circ g$ is the identity, i.e., $n=2$. This proves (b).
(II) The $Z_{n}$-action does not preserve the orientation.

Let $g$ still be the generator of the $Z_{n}$-action on $S^{3}$. Since $g$ reverses the orientation, $g$ has fixed points in $S^{3}, n$ is even, and Fix $(g)$ is a submanifold of odd codimension in $S^{3}$.
(c) $n=2$.

By Smith theory, $\operatorname{Fix}(g)$ is a $Z_{2}$-homology sphere. Hence $\operatorname{Fix}(g)$ is the two points set or the 2 -sphere. If $\operatorname{Fix}(g)$ is the two points set,
by Livesay's theorem [L], the $Z_{2}$-action is a reflection of $S^{3}$ through two points; if $\operatorname{Fix}(g)$ is a 2-sphere, then the action is a reflection of $S^{3}$ with respect to a 2 -sphere by Schonflies theorem. Now the $Z_{2}$-action is classified as follows. If $g_{*}([l])=[l]$, then $\operatorname{Fix}(g) \cap K=\varnothing$. In this case $\operatorname{Fix}(G)$ cannot be a 2 -sphere. To see this, $\operatorname{Fix}(g) \cap K=\varnothing$. In this case $\operatorname{Fix}(G)$ cannot be a 2 -sphere. To see this, $\operatorname{Fix}(g) \cap K=\varnothing$ implies the fixed point set of $g$ in $S^{3}$ is actually in $S^{3}-\operatorname{int}(N(K))$. By Smith theory, for the $g$ involution on the one-dimensional homology sphere $S^{3}-\operatorname{int}(N(K)), \operatorname{Fix}\left(\left.g\right|_{S^{3}-\operatorname{int}(N(K))}\right)$ is a $Z_{2}$-homology sphere of dimension at most one. Hence Fix $(g)$ are two points. This gives $(c)_{1}$. If $g_{*}([l])=-[l]$, then $\sigma(g)$ is a reflection in $K$, and $K$ intersects $\operatorname{Fix}(g)$ transversely in two points. (c) $)_{2},(\mathrm{c})_{3}$ follow from the above mentioned classification of the orientation reversing involutions of $S^{3}$.
(d) $n \geq 4$.

The result is a consequence of the following proposition which will be proven in the appendix.

Proposition. Any smooth cyclic group action on $S^{3}$ which does not preserve the orientation is conjugate to a twisted rotation of $S^{3}$, or to a reflection of $S^{3}$ through two points.

Applying the proposition, we need only to check that $K$ is disjoint from the axis of the twisted rotation $g$. However the axis of $g$ is $\operatorname{Fix}(g \circ g)$. $\operatorname{Fix}(g \circ g)$ does not intersect $K$ follows now from $g_{*} g_{*}([l])=[l]$, and $g \circ g \neq \mathrm{id}$. This completes the proof of $(\mathrm{d})$.

Corollary 4 is actually proven in the proof of Corollary 3.
Proof of Corollary 5. (a) By Proposition 3.19 of [B, Z], $K$ is invertible if and only if there is an automorphism

$$
\phi: \pi_{1}\left(S^{3}-\operatorname{int}(N(K))\right) \rightarrow \pi_{1}\left(S^{3}-\operatorname{int}(N(K))\right)
$$

such that $\phi(m)=m^{-1}$ and $\phi(l)=l^{-1}$. Since $K$ is a hyperbolic knot, Mostow Rigidity Theorem shows that $\phi$ can be realized by a hyperbolic isometry $h: S^{3}-\operatorname{int}(N(K)) \rightarrow S^{3}-\operatorname{int}(N(K))$ such that $h_{*}([m])=-[m]$, and $h_{*}([l])=-[l]$ in $H_{1}(\partial N(K), Z)$. Here we have assumed that $\partial N(K)$ is a flat torus in $S^{3}-K$. The condition $h_{*}([l])=-[l]$ implies that $h$ is an involution by Corollary 4. Because $h_{*}([m])=-[m], h$ is orientation preserving. Hence by Corollary 3, the $Z_{2}$-action generated by the extension of $h$ on $S^{3}$ is induced by a $\pi$-rotation of $S^{3}$ about an axis $L . \quad H_{*}([l])=-[l]$ implies that
$L$ intersects $K$ transversely in two points. Therefore $K$ is invariant under a $\pi$-rotation about an axis intersecting $K$ at two points. The inverse implication is trivial.
(b) By Proposition 3.19 of [ $\mathbf{B}, \mathbf{Z}], K$ is amphicheiral if and only if there is an automorphism

$$
\phi: \pi_{1}\left(S^{3}-\operatorname{int}(N(K))\right) \rightarrow \pi_{1}\left(S^{3}-\operatorname{int}(N(K))\right)
$$

such that $\phi(m)=m^{-1}$ and $\phi(l)=l$. Realize $\phi$ by an isometry $h: S^{3}-\operatorname{int}(N(K)) \rightarrow S^{3}-\operatorname{int}(N(K)) . h$ is orientation reversing since $h_{*}([m])=-[m]$, and $h_{*}([l])=[l]$ in $H_{1}(\partial N(K), Z) . h$ generates a smooth cyclic group action on $S^{3}-\operatorname{int}(N(K))$ which does not preserve the orientation. Hence by Corollary $3, h$ is induced by a twisted rotation of $S^{3}$ about an axis $L$ missing $K$ if the order of $h$ is at least four. If the order of $h$ is two, the $h$ involution is the case (c) $)_{1}$ in Corollary 3 because $h_{*}([l])=[l]$. Therefore, in this case $K$ is invariant under a reflection of $S^{3}$ through two points missing $K$. Then the condition is clearly sufficient.
(c) If the knot is both invertible and amphicheiral, then there exists an automorphism

$$
\phi: \pi_{1}\left(S^{3}-\operatorname{int}(N(K))\right) \rightarrow \pi_{1}\left(S^{3}-\operatorname{int}(N(K))\right)
$$

such that $\phi(m)=m$, and $\phi(l)=l^{-1} . \phi$ is the composition of the two automorphisms coming from (a) and (b). Realize $\phi$ by an orientation reversing hyperbolic isometry $h$ such that $h_{*}([m])=[m]$, and $h_{*}([l])=-[l]$ in $H_{1}(\partial N(K), Z)$. By Corollary $4, h_{*}([l])=-[l]$ and $h_{*}([m])=[m]$ imply $h$ is an orientation reversing involution of $S^{3}-\operatorname{int}(N(K)) \rightarrow S^{3}-N(K)$. By Corollary 3, $h$ is the case (c) ${ }_{2}$ or the case (c) $)_{3}$. Case (c) $)_{3}$ cannot happen since $K$ is a prime knot. Hence $K$ is invariant under the reflection of $S^{3}$ through two points contained in $K$.

Appendix. We prove the following proposition concerning smooth cyclic group action on the 3 -sphere which does not preserve the orientation.

Proposition. Any smooth non-orientation preserving cyclic group action on $S^{3}$ is conjugate to a twisted rotation of $S^{3}$, or to a reflection of $S^{3}$ through two points.

Proof. Let $g$ be a generator of the $Z_{n}$-action. $n$ has to be even. $g$ is orientation reversing, and hence has fixed points in $S^{3}$. If $n=2$,
we have shown in the proof of Corollary 3 (c) that the result holds. Assume $n \geq 4$ from now on. Let $h=g \circ g . \quad h$ is an orientation preserving automorphism of order $m$, and has fixed points. The solution of the Smith Conjecture shows that the $\operatorname{Fix}(h)$ is a trivial knot, say $L$. Now $L$ is invariant under $g . g$ acts on $L$ with fixed point and is of order two in $L$. Hence the action of $g$ on $L$ is a reflection by the classification of $Z_{2}$-action on the circle. Take a $Z_{n}$ equivariant regular neighborhood $N(L)$ of $L$ in $S^{3}$ (see [B]). By the choice of the regular neighborhood, one knows that the action of $Z_{n}$ on $N(L)$ is standard. Therefore by choosing the generator $g$ of the $Z_{n}$-action appropriately, we can assume that the restriction of $g$ on $N(L)=D^{2} \times S^{1}$ is conjugate to $\alpha$, where

$$
\alpha: D^{2} \times S^{1} \rightarrow D^{2} \times S^{1}
$$

sends $(z, w)$ to $\left(e^{2 \pi i / n} z, \bar{w}\right)$, with $z$ in $D^{2}=\{z \in C| | z \mid \leq 1\}$ and $w$ in $S^{1}=\{z \in C| | z \mid=1\}$. Note that $\alpha$ generates an orientation reversing $Z_{n}$-action on $D^{2} \times S^{1}$ with two fixed points in $\{0\} \times S^{1}$. Since $L$ is the trivial knot, $S^{3}-\operatorname{int}(N(L))$ is a solid torus. Let $\phi: S^{3}=\left(S^{3}-\operatorname{int}(N(L))\right) \cup N(L) \rightarrow \bar{S}^{3}=\left(S^{1} \times D^{2}\right) \cup_{\text {id }}\left(D^{2} \times S^{1}\right)$ be a diffeomorphism taking $N(L)$ to $D^{2} \times S^{1}$ such that $\left.\phi g\right|_{N(L)} \phi^{-1}=$ $\alpha$. Now extend $\alpha$ to be a self-diffeomorphism $\bar{\alpha}$ of $\bar{S}^{3}$ by sending $(z, w) S^{1} \times D^{2}$ to $\left(e^{2 \pi i / n} z, \bar{w}\right)$ with $z \in S^{1}$ and $w \in D^{2}$. Then $\bar{\alpha}$ generates a twisted $2 \pi / n$-rotation of $\bar{S}^{3}$. Our goal is to show that $\phi g \phi^{-1}$ is conjugate to $\bar{\alpha}$ in $\bar{S}^{3}$. This is consequence of the following claim.

Claim. $g^{\prime}=\left.\phi g \phi^{-1}\right|_{S^{1} \times D^{2}}$ is conjugate to $\beta=\left.\bar{\alpha}\right|_{S^{1} \times D^{2}}$ by a piecewise smooth diffeomorphism $\psi$ such that $\psi$ is the identity map on $\partial\left(S^{1} \times D^{2}\right)$.

Let us assume the claim and finish the proof. By gluing $\psi$ with Id $\left.\right|_{D^{2} \times S^{1}}$ along the boundaries, we obtain a piecewise smooth selfdiffeomorphism of $\bar{S}^{3}$ which conjugates $\phi g \phi^{-1}$ to $\bar{\alpha}$. Therefore $\phi g \phi^{-1}$ is smoothly conjugate to $\bar{\alpha}$ by the work of Moise.

Proof of the Claim. By the choice of $\phi, g^{\prime}$ is the same as $\beta$ on $\partial\left(S^{1} \times D^{2}\right)$. Using the equivariant Dehn's lemma, we can find $n$ copies of disjoint properly embedded disks $D_{1}, D_{2}, \ldots, D_{n}$ with $\partial D_{j}$ $=e^{e \pi j i / n} \times \partial D^{2}$ in $S^{1} \times D^{2}$, such that $g^{\prime}\left(D_{j}\right)=D_{j+1}$ for $j=$
$1,2, \ldots, n$, where $D_{1}=D_{n+1} . g^{\prime}: D_{j} \rightarrow D_{j+1}$ is a diffeomorphism for each $j$. These disks cut $S^{1} \times D^{2}$ into $n$ components, say $B_{1}, B_{2}, \ldots, B_{n}$ with $D_{j} \cup D_{j+1} \subset \partial B_{j}$, and each of $B_{j}$ is a 3-ball by Schonflies' theorem. Let $D_{j}^{\prime}=e^{2 \pi i j / n} \times D^{2}$ (where $D_{n+1}^{\prime}=D_{1}^{\prime}$ ); $B_{j}^{\prime}=\left\{e^{2 \pi i t / n} \mid j \leq t \leq j+1\right\} \times D^{2}$; and $E_{j}=\partial B_{j}^{\prime}-\left(D_{j} \cup D_{j+1}\right)$, the annulus, for each $i=1,2, \ldots, n$. The construction of $\psi$ is now as follows. Let $A_{1}: D_{1} \rightarrow D_{1}^{\prime}$ be a diffeomorphism which is the identity on $\partial D_{1}$. Define $A_{2}: D_{2} \rightarrow D_{2}^{\prime}$ to be $\left.\left.\beta\right|_{D_{1}^{\prime}} A_{1} g^{\prime-1}\right|_{D_{2}}$. It is still a diffeomorphism which fixes $\partial D_{2}$ pointwise. Since $\partial B_{1}=D_{1} \cup E_{1} \cup D_{2}$ and $\partial B_{1}^{\prime}=D_{1}^{\prime} \cup E_{1} \cup D_{2}^{\prime}$, glue $A_{1}, A_{2}$ and id $\left.\right|_{E_{1}}$ along the boundaries, one obtains a piecewise smooth diffeomorphism from $\partial B_{1} \rightarrow \partial B_{1}^{\prime}$ which is the identity on $E_{1}$. Extend it to be a piecewise smooth diffeomorphism from $B_{1}$ to $B_{1}^{\prime}$ by Alexander's lemma, and call it $\psi_{1}$. Now $\psi_{j}: B_{j} \rightarrow B_{j}^{\prime}$ is defined to be

$$
\left.\left.\beta_{j}\right|_{B_{1}^{\prime}} \psi_{1} g^{\prime-j}\right|_{B_{j}}
$$

for $j=2,3, \ldots, n$. All these piecewise smooth diffeomorphisms match on the $D_{j}$ 's. Gluing them together along the $D_{j}$ 's, we obtain a piecewise diffeomorphism $\psi: S^{1} \times D^{2} \rightarrow S^{1} \times D^{2}$. Then $\left.\psi\right|_{\partial\left(S^{1} \times D^{2}\right)}=$ id and $\beta=\psi^{-1} \beta \psi$.

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