# 81. On the Rate of Convergence of the Difference Finite Element Approximation for Parabolic Equations 

By Takashi Suzuki<br>Department of Mathematics, Faculty of Science, University of Tokyo<br>(Communicated by Kôsaku Yosida, M. J. A., Dec. 12, 1978)

1. Introduction. Our purpose is to make some error analysis on the difference finite element approximation for the parabolic equation.

Let $\Omega$ be a bounded domain in $R^{2}$ whose boundary $\partial \Omega$ is smooth, and let $-\mathcal{A}$ be a uniformly elliptic differential operator of second order with smooth coefficients:

$$
\begin{equation*}
-\mathcal{A}=\sum_{i, j=1}^{2} \frac{\partial}{\partial x_{i}} a_{i j}(t, x) \frac{\partial}{\partial x_{j}}+\sum_{j=1}^{2} b_{j}(t, x) \frac{\partial}{\partial x_{j}}+c(t, x) . \tag{1.1}
\end{equation*}
$$

We consider the following parabolic equation

$$
\begin{equation*}
\frac{\partial u}{\partial t}+\mathcal{A} u=0 \quad(0<t \leqslant T, x \in \Omega) \tag{1.2}
\end{equation*}
$$

with the boundary condition

$$
\begin{equation*}
u=0 \quad(0<t \leqslant T, x \in \partial \Omega) \tag{1.3}
\end{equation*}
$$

and with an initial condition

$$
\begin{equation*}
\left.u\right|_{t=0}=\varphi(x) \quad(x \in \Omega) . \tag{1.4}
\end{equation*}
$$

Assuming $\varphi \in X=L^{2}(\Omega)$, we can reduce the equation (1.2) with (1.3) and (1.4) to the following evolution equation

$$
\begin{equation*}
\frac{d u}{d t}+A(t) u=0 \quad(0<t \leqslant T) \tag{1.5}
\end{equation*}
$$

with

$$
\begin{equation*}
u(0)=\varphi . \tag{1.6}
\end{equation*}
$$

in $X$. Here the operator $A(t)$ is the $m$-sectorial operator associated with the following sesqui-linear form $a_{t}\left(\right.$, ) on $V \times V$, where $V=H_{0}^{1}(\Omega)$ :

$$
\begin{align*}
a_{t}(u, v)= & \sum_{i, j=1}^{2} \int_{\Omega} a_{i j}(t, x) \frac{\partial}{\partial x_{j}} u \cdot \frac{\bar{\partial}}{\partial x_{i}} v d x-\sum_{j=1}^{2} \int_{\Omega} b_{j}(t, x) \frac{\partial}{\partial x_{j}} u \cdot \bar{v} d x  \tag{1.7}\\
& -\int_{\Omega} c(t, x) u \cdot \bar{v} d x
\end{align*} \quad(u, v \in V) .
$$

In order to discretize the equation (1.5) with (1.6), we introduce an approximate space $V_{h}$ for each $h>0$ by triangulating $\Omega$ regularly with the size parameter $h$ and adopting piecewise linear trial functions in the usual manner. As for precise definition of $V_{h}$, particularly in the case of curved boundaries, see Zlámal [7]. Here we note only that $V_{h}$ satisfies the following three conditions:
i) $\quad V_{h}$ is of finite dimensional.
ii) $V_{h} \subset V$.
iii) The estimate

$$
\inf _{x \in V_{h}}\|\chi-v\|_{1} \leqslant C h\|v\|_{2} \quad\left(v \in H^{2}(\Omega) \cap V\right)
$$

holds true.
Here and hereafter the symbol $C$ stands for a generic positive constant. Firstly we consider the equation

$$
\begin{equation*}
\frac{d u_{h}}{d t}+A_{h}(t) u_{h}=0 \quad(0<t \leqslant T) \tag{1.8}
\end{equation*}
$$

with

$$
\begin{equation*}
u_{h}(0)=P_{h} \varphi \tag{1.9}
\end{equation*}
$$

in $V_{h}$, as a semi-discretization of the equation (1.5) with (1.6). Here the operator $A_{h}(t): V_{h} \rightarrow V_{h}$ is the $m$-sectorial operator associated with $\left.a_{t}\right|_{V_{h} \times V_{h}}$ through the identity :
(1.10) $\quad a_{t}(u, v)=\left(A_{h}(t) u, v\right) \quad\left(u, v \in V_{h}\right)$,
where (, ) is the $L^{2}$-inner product. $P_{h}$ is the orthogonal projection in $X$.

Furthermore we discretize the time variable as well as the space variables. We consider the equation
(1.11) $\quad u_{h}^{\tau}(t+\tau)-u_{h}^{\tau}(t)+\tau A_{h}(t+\tau) u_{h}^{\tau}(t+\tau)=0 \quad(t=n \tau, n=0,1,2, \cdots)$ with
(1.12)

$$
u_{h}^{\tau}(0)=P_{h} \varphi
$$

for a small positive parameter $\tau$. The solution $u_{h}^{\tau}=u_{h}^{\tau}(t)$ of the equation (1.11) with (1.12) is called the backward difference finite element approximation of the solution $u=u(t)$ of the equation (1.5) with (1.6).

We want to estimate the error $u_{n}^{\tau}(t)-u(t)$ in $L^{2}$-norm. To this end we estimate $\left\|u_{n}^{\tau}(t)-u_{h}(t)\right\|_{0}$ and $\left\|u_{n}(t)-u(t)\right\|_{0}$, while the estimate

$$
\begin{equation*}
\left\|u_{h}(t)-u(t)\right\|_{0} \leqslant C h^{2} / t\|\varphi\|_{0} \quad(0<t \leqslant T) \tag{1.13}
\end{equation*}
$$

is already known. See, Fujita-Suzuki [2] and Suzuki [5], [6]. See also Fujita-Mizutani [1] and Helfrich [3], for more restricted results.

In this paper, the estimate
(1.14) $\quad\left\|u_{h}^{\tau}(t)-u_{h}(t)\right\|_{0} \leqslant C_{r}(\tau / t)^{1-r}\|\varphi\|_{0} \quad(t=n \tau)(0<\gamma \leqslant 1)$
is derived with a constant $C_{r}>0$ depending on $\gamma$, which gives our final estimate
(1.15) $\left\|u_{h}^{\tau}(t)-u(t)\right\|_{0} \leqslant C_{r}\left(h^{2} / t+(\tau / t)^{1-r}\right)\|\varphi\|_{0} \quad(t=n \tau)(0<r \leqslant 1)$.
2. Theorems on generation and approximation of evolution operators. The following theorem is due to Kato-Tanabe [4].

Theorem 1. Suppose that the operator $A(t)(0 \leqslant t \leqslant T)$ in $X, a$ Banach space, satisfies the following four conditions.
(A0) $A(t)$ is a densely defined closed linear operator on $X$ whose resolvent set $\rho(A(t))$ contains the set $G$ :

$$
G=\left\{\lambda \in C ;|\arg \lambda| \geqslant \theta_{1}\right\} \cup\{0\} \quad\left(0<\theta_{1}<\pi / 2\right),
$$

with the inequality

$$
\begin{equation*}
\left\|(\lambda-A(t))^{-1}\right\| \leqslant M /(|\lambda|+1) \quad(\lambda \in G, t \in[0, T]) \tag{2.1}
\end{equation*}
$$

(A1) $A(t)^{-1}$ is continuously differentiable in $t$ with respect to the operator norm in $X$.
(A2) The inequality

$$
\begin{equation*}
\left\|\frac{d}{d t} A(t)^{-1}-\frac{d}{d s} A(s)^{-1}\right\| \leqslant K|t-s|^{\alpha} \quad(t, s \in[0, T]) \tag{2.2}
\end{equation*}
$$

holds with $K>0$ and $\alpha$ in $0<\alpha \leqslant 1$.
(A3) The inequality

$$
\begin{equation*}
\left\|\frac{\partial}{\partial t}(\lambda-A(t))^{-1}\right\| \leqslant N /|\lambda|^{\rho} \quad(\lambda \in G, t \in[0, T]) \tag{2.3}
\end{equation*}
$$

holds with $N>0$ and $\rho$ in $0<\rho \leqslant 1$.
Then $A(t)$ generates a family of evolution operators : $X \rightarrow X$ of $C^{1}$ class which is denoted by $\{U(t, s)\}$.

We can make use of Theorem 1 not only to construct $u_{h}(t)$, the solution of (1.8) and (1.9), but also to derive the estimate for $u_{h}(t)$ uniform in $h$. That is, we have the following

Theorem 2. Let $X, V$ be a couple of Hilbert spaces with continuous inclusion $V \hookrightarrow X$ and $\left\{V_{h}\right\}$ be a family of finite dimensional spaces contained in $V$. And let $a_{t}():, V \times V \rightarrow C$ be a given sesquilinear form satisfying the following inequalities with constants $C>0$ and $\delta>0$ :

$$
\begin{array}{cc}
\left|a_{t}(u, v)\right| \leqslant C\|u\|_{V} \cdot\|v\|_{V} & (u, v \in V)  \tag{2.4}\\
\operatorname{Re} a_{t}(u, u) \geqslant \delta\|u\|_{V}^{2} & (u \in V)
\end{array}
$$

Suppose that another sesqui-linear form $\dot{a}_{t}():, V \times V \rightarrow C$ exists and satisfies the following inequalities:

$$
\begin{equation*}
\left|\dot{a}_{t}(u, v)\right| \leqslant C\|u\|_{V} \cdot\|v\|_{V} \quad(u, v \in V) \tag{2.6}
\end{equation*}
$$

$$
\begin{equation*}
\left|\dot{a}_{t}(u, v)-\dot{a}_{s}(u, v)\right| \leqslant C|t-s|\|u\|_{V} \cdot\|v\|_{V} \quad(u, v \in V) \tag{2.7}
\end{equation*}
$$

and the following equality :

$$
\begin{equation*}
\lim _{t \rightarrow s} \sup _{\substack{u, v v v \\\|u\| v, u v \| v \leq 1}}\left|\frac{a_{t}(u, v)-a_{s}(u, v)}{t-s}-\dot{a}_{s}(u, v)\right|=0 . \tag{2.8}
\end{equation*}
$$

Then the $m$-sectorial operator $A_{h}(t): V_{h} \rightarrow V_{h}$ associated with the sesqui-linear form $\left.a_{t}\right|_{V_{h} \times V_{h}}$ satisfies the conditions (A0)-(A3) with $\alpha=\rho$ $=1$. Furthermore, the constants $\theta_{1}, M, K$ and $N$ in these conditions depend only on the constants $C$ and $\delta$ in (2.4)-(2.7).

By virtue of Theorems 1 and 2, we obtain

$$
\begin{equation*}
u_{h}(t)=U_{h}(t, 0) P_{h} \varphi, \tag{2.9}
\end{equation*}
$$

where $\left\{U_{h}(t, s)\right\}$ is the family of evolution operators generated by $A_{h}(t)$. Indeed we can construct the form $\dot{\alpha}_{t}($, ) satisfying the relations (2.6)(2.8) by differentiating $a_{i j}, b_{j}$ and $c$ in $t$ in the right hand side of (1.7).

On the other hand, we see
(2.10) $\quad u_{h}^{\tau}(n \tau)=\left(1+\tau A_{h}(n \tau)\right)^{-1}\left(1+\tau A_{h}((n-1) \tau)^{-1} \cdots\left(1+\tau A_{h}(\tau)\right)^{-1} P_{h} \varphi\right.$.

With the aid of Theorem 2, following Theorem 3 yields our main results, (1.14) and (1.15), when applied for $A=A_{h}$ and $U=U_{h}$.

Theorem 3. Under the conditions (A0)-(A3) with $\alpha=\rho=1$, the estimate
(2.11) $\left\|U(n \tau, 0)-(1+\tau A(n \tau))^{-1}(1+\tau A((n-1) \tau))^{-1} \cdots(1+\tau A(\tau))^{-1}\right\|$ $\leqslant C_{r} 1 / n^{r}$
holds for each $\gamma$ in $0 \leqslant \gamma<1$. Here the constant $C_{\gamma}$ depends only on the constants $\theta_{1}, M, K$ and $N$ in (A0), (A2) and (A3), on $T$ and on the parameter $\gamma$.

In below we give an outline of the proof of Theorem 3. We omit here the proof of Theorem 2 which may not be so trivial but is rather straight-forward.
3. Outline of the proof of Theorem 3. Put

$$
\begin{equation*}
u(t)=U(t, 0) \varphi \tag{3.1}
\end{equation*}
$$

(3.2) $u^{\tau}(t)=(1+\tau A(n \tau))^{-1}(1+\tau A((n-1) \tau))^{-1} \cdots(1+\tau A(\tau))^{-1} \varphi \quad(t=n \tau)$ and

$$
\begin{equation*}
e^{\tau}(t)=u^{\tau}(t)-u(t) \quad(t=n \tau) . \tag{3.3}
\end{equation*}
$$

We can derive the following equality (3.4) whose proof is omitted :

$$
\begin{align*}
e^{\tau}\left(t_{n}\right)=-\sum_{k=1}^{n} \int_{t_{k-1}}^{t_{k}}\left(1+\tau A\left(t_{n}\right)\right)^{-1}(1 & \left.+\tau A\left(t_{n-1}\right)\right)^{-1} \cdots\left(1+\tau A\left(t_{k}\right)\right)^{-1}  \tag{3.4}\\
\times & {\left[A\left(t_{k}\right) U\left(t_{k}, 0\right)-A(r) U(r, 0)\right] \varphi d r }
\end{align*}
$$

where $t_{k}=k \tau$. We now examine the operator

$$
A\left(t_{k}\right) U\left(t_{k}, 0\right)-A(r) U(r, 0)
$$

and the operator

$$
\left(1+\tau A\left(t_{n}\right)\right)^{-1}\left(1+\tau A\left(t_{n-1}\right)\right)^{-1} \cdots\left(1+\tau A\left(t_{k}\right)\right)^{-1} .
$$

For these operators we claim following Propositions 1 and 2, respectively.

Propositon 1. Under the conditions (A0)-(A3) in Theorem 1, we have

$$
\begin{align*}
& A(t+\Delta t) U(t+\Delta t, s)-A(t) U(t, s)  \tag{3.5}\\
& =\frac{1}{2 \pi \sqrt{-1}} \int_{\Gamma} \lambda e^{-(t-s) \lambda}\left[(\lambda-A(t+\Delta t))^{-1}-(\lambda-A(t))^{-1}\right] d \lambda \\
& \quad+A(t+\Delta t)\left[e^{-(t+\Delta t-s) A(t+\Delta t)}-e^{-(t-s) A(t+\Delta t)}\right]+\tilde{V}(t, s ; \Delta t) \\
& \quad(T \geqslant t+\Delta t>t>s \geqslant 0)
\end{align*}
$$

with
(3.6) $\|\tilde{V}(t, s ; \Delta t)\| \leqslant C_{\gamma} \Delta t^{r}\left\{(t-s)^{\rho-r-1}+(t-s)^{\alpha-r-1}\right\} \quad(0<\gamma<\alpha, \rho)$
for each $\gamma$. Here $\Gamma$ is the positively oriented boundary, running from $+\infty e^{\sqrt{-1} \theta_{1}}$ to $+\infty e^{-\sqrt{-1} \theta_{1}}$ of the sector $\Sigma$ :

$$
\Sigma=\left\{\lambda \in C ;|\arg \lambda| \leqslant \theta_{1}\right\} .
$$

The constant $C_{\gamma}$ in (3.6) depends only on the constants $\theta_{1}, M, K, \alpha, N, \rho, T$ and $\gamma$.

Proposition 2. Under the conditions (A0)-(A3) in Theorem 1
with $\rho=1$, we have the estimate

$$
\begin{align*}
& \left\|\left(1+\tau A\left(t_{n}\right)\right)^{-1}\left(1+\tau A\left(t_{n-1}\right)\right)^{-1} \cdots\left(1+\tau A\left(t_{k+1}\right)\right)^{-1} A\left(t_{k+1}\right)^{1-\beta}\right\|  \tag{3.7}\\
& \quad \leqslant C_{\beta} \tau^{\beta-1}(n-k)^{\beta-1}
\end{align*}
$$

for each $\beta$ in $0<\beta \leqslant 1$. The constant $C_{\beta}$ depends only on $\theta_{1}, M, K, \alpha, N, T$ and $\beta$.

To prove Proposition 1, we just need a refined version of the method by Kato-Tanabe [4] for the construction of evolution operators $U(t, s)$. Proposition 2 can be proved by adopting Levy-Tanabe's method. Namely, in dealing with our discrete case, we imitate the method by Kato-Tanabe [4] which was originally employed in order to prove the inequality
(3.8)

$$
\|A(t) U(t, s)\| \leqslant C(t-s)^{-1}
$$

Now, putting

$$
\begin{equation*}
e^{\tau}(t)=E^{\tau}(t) \varphi, \tag{3.9}
\end{equation*}
$$

we have

$$
\begin{equation*}
-\boldsymbol{E}^{\tau}\left(t_{n}\right)=\sum_{k=1}^{n} \boldsymbol{F}_{1}(k)+\sum_{k=1}^{n} \boldsymbol{F}_{2}(k)+\sum_{k=1}^{n} \boldsymbol{F}_{3}(k) \tag{3.10}
\end{equation*}
$$

with

$$
\begin{align*}
& F_{1}(k)=\int_{t_{k-1}}^{t_{k}} d r\left(1+\tau A\left(t_{n}\right)\right)^{-1} \cdots\left(1+\tau A\left(t_{k}\right)\right)^{-1}  \tag{3.11}\\
& \quad \times \frac{1}{2 \pi \sqrt{-1}} \int_{\Gamma} \lambda e^{-r \lambda}\left[\left(\lambda-A\left(t_{k}\right)\right)^{-1}-(\lambda-A(r))^{-1}\right] d \lambda \\
& F_{2}(k)=\int_{t_{k-1}}^{t_{k}} d r\left(1+\tau A\left(t_{n}\right)\right)^{-1} \cdots\left(1+\tau A\left(t_{k}\right)\right)^{-1} A\left(t_{k}\right)^{1-\beta}  \tag{3.12}\\
& \quad \times A\left(t_{k}\right)^{\beta}\left[e^{-t_{k} A\left(t_{k}\right)}-e^{-r A\left(t_{k}\right)}\right]
\end{align*}
$$

and
(3.13) $\quad F_{3}(k)=\int_{t_{k-1}}^{t_{k}} d r\left(1+\tau A\left(t_{n}\right)\right)^{-1} \cdots\left(1+\tau A\left(t_{k}\right)\right)^{-1} \tilde{V}\left(r, 0 ; t_{k}-r\right)$,
because of (3.4) and (3.5).
$F_{3}(k)$ is estimated as follows by Proposition 1:
(3.14)

$$
\left\|F_{3}(k)\right\| \leqslant C_{r} \tau k^{-r}
$$

which yields

$$
\begin{equation*}
\sum_{k=1}^{n}\left\|\boldsymbol{F}_{3}(k)\right\| \leqslant C_{r} n^{-r} . \tag{3.15}
\end{equation*}
$$

We can estimate $F_{2}(k)$ as

$$
\begin{equation*}
\left\|F_{2}(k)\right\| \leqslant C_{\beta, r}(n+1-k)^{\beta-1} k^{-\beta-r} \tag{3.16}
\end{equation*}
$$

by taking the parameter $\beta>0$ in Proposition 2 so small that $\beta+\gamma<1$ for the given $\gamma$. Hence we have

$$
\begin{equation*}
\sum_{k=1}^{n}\left\|\boldsymbol{F}_{2}(k)\right\| \leqslant C_{r} n^{-r} \tag{3.17}
\end{equation*}
$$

$F_{1}(k)$ is estimated as follows if $k \geqslant 2$ :

$$
\begin{equation*}
\left\|F_{1}(k)\right\| \leqslant C \int_{t_{k-1}}^{t_{k}} r^{-1}\left(t_{k}-1\right) d r \leqslant C \tau k^{-1} \tag{3.18}
\end{equation*}
$$

We can derive also (3.18) for $k=1$ by a standard technique of tele-
scoping. Hence we end up with

$$
\begin{equation*}
\sum_{k=1}^{n}\left\|F_{1}(k)\right\| \leqslant C_{r} n^{-r} \tag{3.19}
\end{equation*}
$$

Proofs of Propositions 1 and 2 will be given in a forthcoming paper along with detailed proofs and generalization of Theorems 2 and 3 which can cover also the case of the Neumann boundary condition.

A note added. Recently the author succeeded in proving the inequality (1.14) for $\gamma=0$, which generalizes a result of Fujita-Mizutani [1] in the case of $t$-independence of $a_{t}($,$) . The proof is based on a$ refined study of fractional powers of operators and evolution operators. Details will be given in the paper mentioned above.

## References

[1] Fujita, H., and A. Mizutani: On the finite element method for parabolic equations. I. Approximation of holomorphic semi-groups. J. Math. Soc. Japan, 28, 749-771 (1976).
[2] Fujita, H., and T. Suzuki: On the finite element approximation for evolution equations of parabolic type. Proc. 3rd IRIA Inter. Symp. Com. Sci. Eng. Versailles, December, pp. 5-9 (1977).
[ 3 ] Helfrich, H. P.: Lokale Konvergenz des Galerkinverfahrens bei Gleichungen vom parabolic Typ in Helberträumen. Thesis (1975).
[4] Kato, T., and H. Tanabe: On the abstract evolution equation. Osaka Math. J., 14, 107-133 (1962).
[5] Suzuki, T.: An abstract study of Galerkin's method for the evolution equation $u_{t}+A(t) u=0$ of parabolic type with the Neumann boundary condition. J. Fac. Sci. Univ. Tokyo, 25, 25-46 (1978).
[6] --: On the optimal rate of convergence of Galerkin finite element approximation for parabolic equations with Neumann boundary conditions (to appear).
[7] Zlámal, M.: Curved elements in the finite element method. I. SIAM J. Num. Anal., 10, 229-240 (1973).

