81. On the Rate of Convergence of the Difference Finite Element Approximation for Parabolic Equations

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1. Introduction. Our purpose is to make some error analysis on the difference finite element approximation for the parabolic equation.

Let Ω be a bounded domain in \mathbb{R}^2 whose boundary $\partial\Omega$ is smooth, and let $-\mathcal{A}$ be a uniformly elliptic differential operator of second order with smooth coefficients:

(1.1)
$$-\mathcal{A} = \sum_{i,j=1}^{2} \frac{\partial}{\partial x_{i}} a_{ij}(t,x) \frac{\partial}{\partial x_{j}} + \sum_{j=1}^{2} b_{j}(t,x) \frac{\partial}{\partial x_{j}} + c(t,x).$$

We consider the following parabolic equation

(1.2)
$$\frac{\partial u}{\partial t} + \mathcal{A}u = 0 \qquad (0 < t \leq T, \ x \in \Omega)$$

with the boundary condition

 $(1.3) u=0 (0 \le t \le T, x \in \partial \Omega)$

and with an initial condition

(1.4)
$$u|_{t=0} = \varphi(x) \qquad (x \in \Omega).$$

Assuming $\varphi \in X = L^2(\Omega)$, we can reduce the equation (1.2) with (1.3) and (1.4) to the following evolution equation

(1.5)
$$\frac{du}{dt} + A(t)u = 0 \qquad (0 < t \leq T)$$

with

$$(1.6) u(0) = \varphi$$

in X. Here the operator A(t) is the *m*-sectorial operator associated with the following sesqui-linear form $a_t(,)$ on $V \times V$, where $V = H_0^1(\Omega)$:

(1.7)
$$a_{t}(u,v) = \sum_{i,j=1}^{2} \int_{a} a_{ij}(t,x) \frac{\partial}{\partial x_{j}} u \cdot \overline{\frac{\partial}{\partial x_{i}}} v dx - \sum_{j=1}^{2} \int_{a} b_{j}(t,x) \frac{\partial}{\partial x_{j}} u \cdot \overline{v} dx - \int_{a} c(t,x) u \cdot \overline{v} dx \qquad (u,v \in V).$$

In order to discretize the equation (1.5) with (1.6), we introduce an approximate space V_h for each h>0 by triangulating Ω regularly with the size parameter h and adopting piecewise linear trial functions in the usual manner. As for precise definition of V_h , particularly in the case of curved boundaries, see Zlámal [7]. Here we note only that V_h satisfies the following three conditions: No. 10]

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- i) V_h is of finite dimensional.
- ii) $V_h \subset V$.
- iii) The estimate

$$\inf_{\chi \in V_h} \|\chi - v\|_1 \leq Ch \|v\|_2 \qquad (v \in H^2(\Omega) \cap V)$$

holds true.

Here and hereafter the symbol C stands for a generic positive constant. Firstly we consider the equation

(1.8)
$$\frac{du_h}{dt} + A_h(t)u_h = 0 \qquad (0 \le t \le T)$$

with

$$(1.9) u_h(0) = P_h \varphi$$

in V_h , as a semi-discretization of the equation (1.5) with (1.6). Here the operator $A_h(t): V_h \rightarrow V_h$ is the *m*-sectorial operator associated with $a_t|_{V_h \times V_h}$ through the identity:

(1.10) $a_t(u, v) = (A_h(t)u, v) \quad (u, v \in V_h),$

where (,) is the L^2 -inner product. P_n is the orthogonal projection in X.

Furthermore we discretize the time variable as well as the space variables. We consider the equation

(1.11) $u_h^{t}(t+\tau) - u_h^{t}(t) + \tau A_h(t+\tau)u_h^{t}(t+\tau) = 0$ $(t=n\tau, n=0, 1, 2, \cdots)$ with

 $(1.12) u_h^t(0) = P_h \varphi$

for a small positive parameter τ . The solution $u_h^{\tau} = u_h^{\tau}(t)$ of the equation (1.11) with (1.12) is called the backward difference finite element approximation of the solution u = u(t) of the equation (1.5) with (1.6).

We want to estimate the error $u_h^{\mathsf{r}}(t) - u(t)$ in L^2 -norm. To this end we estimate $||u_h^{\mathsf{r}}(t) - u_h(t)||_0$ and $||u_h(t) - u(t)||_0$, while the estimate (1.13) $||u_h(t) - u(t)||_0 \leq Ch^2/t ||\varphi||_0$ ($0 \leq t \leq T$)

is already known. See, Fujita-Suzuki [2] and Suzuki [5], [6]. See also Fujita-Mizutani [1] and Helfrich [3], for more restricted results. In this paper, the estimate

(1.14) $\|u_{\hbar}^{\tau}(t)-u_{\hbar}(t)\|_{0} \leq C_{r}(\tau/t)^{1-r} \|\varphi\|_{0}$ $(t=n\tau) \ (0 < \gamma \leq 1)$ is derived with a constant $C_{r} > 0$ depending on γ , which gives our final estimate

(1.15) $\|u_h^{\tau}(t) - u(t)\|_0 \leq C_r(h^2/t + (\tau/t)^{1-\gamma}) \|\varphi\|_0$ $(t = n\tau) \ (0 < \gamma \leq 1).$

2. Theorems on generation and approximation of evolution operators. The following theorem is due to Kato-Tanabe [4].

Theorem 1. Suppose that the operator A(t) $(0 \le t \le T)$ in X, a Banach space, satisfies the following four conditions.

(A0) A(t) is a densely defined closed linear operator on X whose resolvent set $\rho(A(t))$ contains the set G:

 $G = \{\lambda \in \mathbf{C}; |\arg \lambda| \ge \theta_1\} \cup \{0\} \qquad (0 < \theta_1 < \pi/2),$

with the inequality

(2.1) $\|(\lambda - A(t))^{-1}\| \leq M/(|\lambda| + 1)$ $(\lambda \in G, t \in [0, T]).$

(A1) $A(t)^{-1}$ is continuously differentiable in t with respect to the operator norm in X.

(A2) The inequality

(2.2)
$$\left\|\frac{d}{dt}A(t)^{-1}-\frac{d}{ds}A(s)^{-1}\right\| \leq K |t-s|^{\alpha}$$
 $(t,s \in [0,T])$

holds with K>0 and α in $0 \le \alpha \le 1$.

(A3) The inequality

(2.3)
$$\left\|\frac{\partial}{\partial t}(\lambda - A(t))^{-1}\right\| \leq N/|\lambda|^{\rho} \qquad (\lambda \in G, \ t \in [0, T])$$

holds with N>0 and ρ in $0 < \rho \leq 1$.

Then A(t) generates a family of evolution operators: $X \rightarrow X$ of C^1 class which is denoted by $\{U(t, s)\}$.

We can make use of Theorem 1 not only to construct $u_h(t)$, the solution of (1.8) and (1.9), but also to derive the estimate for $u_h(t)$ uniform in h. That is, we have the following

Theorem 2. Let X, V be a couple of Hilbert spaces with continuous inclusion $V \longrightarrow X$ and $\{V_h\}$ be a family of finite dimensional spaces contained in V. And let $a_t(,): V \times V \rightarrow C$ be a given sesquilinear form satisfying the following inequalities with constants C>0and $\delta>0$:

(2.4) $|a_t(u, v)| \leq C ||u||_V \cdot ||v||_V \quad (u, v \in V)$

(2.5) $\operatorname{Re} a_t(u, u) \geq \delta \|u\|_V^2 \qquad (u \in V).$

Suppose that another sesqui-linear form $\dot{a}_i(,): V \times V \rightarrow C$ exists and satisfies the following inequalities:

(2.8)
$$\lim_{t \to s} \sup_{\substack{u, v \in V \\ \|\|u\|_{Y}, \|v\|\|v \leq 1}} \left| \frac{a_t(u, v) - a_s(u, v)}{t - s} - \dot{a}_s(u, v) \right| = 0.$$

Then the m-sectorial operator $A_h(t): V_h \to V_h$ associated with the sesqui-linear form $a_t|_{V_h \times V_h}$ satisfies the conditions (A0)–(A3) with $\alpha = \rho$ =1. Furthermore, the constants θ_1 , M, K and N in these conditions depend only on the constants C and δ in (2.4)–(2.7).

By virtue of Theorems 1 and 2, we obtain

 $(2.9) u_h(t) = U_h(t, 0)P_h\varphi,$

where $\{U_n(t,s)\}$ is the family of evolution operators generated by $A_n(t)$. Indeed we can construct the form $\dot{a}_t(,)$ satisfying the relations (2.6)–(2.8) by differentiating a_{ij}, b_j and c in t in the right hand side of (1.7).

On the other hand, we see

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 $(2.10) \quad u_h^{\tau}(n\tau) = (1 + \tau A_h(n\tau))^{-1} (1 + \tau A_h((n-1)\tau)^{-1} \cdots (1 + \tau A_h(\tau))^{-1} P_h \varphi.$

With the aid of Theorem 2, following Theorem 3 yields our main results, (1.14) and (1.15), when applied for $A = A_h$ and $U = U_h$.

Theorem 3. Under the conditions (A0)-(A3) with $\alpha = \rho = 1$, the estimate

(2.11)
$$||U(n\tau, 0) - (1 + \tau A(n\tau))^{-1} (1 + \tau A((n-1)\tau))^{-1} \cdots (1 + \tau A(\tau))^{-1}|| \leq C, 1/n^{\tau}$$

holds for each γ in $0 \leq \gamma \leq 1$. Here the constant C_{γ} depends only on the constants θ_1, M, K and N in (A0), (A2) and (A3), on T and on the parameter γ .

In below we give an outline of the proof of Theorem 3. We omit here the proof of Theorem 2 which may not be so trivial but is rather straight-forward.

3. Outline of the proof of Theorem 3. Put

$$(3.1) u(t) = U(t, 0)\varphi$$

(3.2) $u^{\tau}(t) = (1 + \tau A(n\tau))^{-1} (1 + \tau A((n-1)\tau))^{-1} \cdots (1 + \tau A(\tau))^{-1} \varphi$ $(t = n\tau)$ and

(3.3) $e^{\tau}(t) = u^{\tau}(t) - u(t)$ $(t = n\tau).$

We can derive the following equality (3.4) whose proof is omitted:

(3.4)
$$e^{\tau}(t_n) = -\sum_{k=1}^n \int_{t_{k-1}}^{t_k} (1 + \tau A(t_n))^{-1} (1 + \tau A(t_{n-1}))^{-1} \cdots (1 + \tau A(t_k))^{-1} \times [A(t_k)U(t_k, 0) - A(r)U(r, 0)]\varphi dr,$$

where $t_k = k\tau$. We now examine the operator $A(t_k)U(t_k, 0) - A(r)U(r, 0)$

and the operator

 $(1+\tau A(t_n))^{-1}(1+\tau A(t_{n-1}))^{-1}\cdots(1+\tau A(t_k))^{-1}.$

For these operators we claim following Propositions 1 and 2, respectively.

Propositon 1. Under the conditions (A0)-(A3) in Theorem 1, we have

(3.5)
$$A(t+\Delta t)U(t+\Delta t,s) - A(t)U(t,s) = \frac{1}{2\pi\sqrt{-1}} \int_{\Gamma} \lambda e^{-(t-s)\lambda} [(\lambda - A(t+\Delta t))^{-1} - (\lambda - A(t))^{-1}] d\lambda + A(t+\Delta t) [e^{-(t+\Delta t-s)A(t+\Delta t)} - e^{-(t-s)A(t+\Delta t)}] + \tilde{V}(t,s;\Delta t)$$

$$(T \ge t + \Delta t \ge t \ge s \ge 0)$$

with

(3.6) $\|\tilde{V}(t,s;\Delta t)\| \leq C_{\gamma} \Delta t^{\gamma} \{(t-s)^{\rho-\gamma-1} + (t-s)^{\alpha-\gamma-1}\}$ $(0 < \gamma < \alpha, \rho)$ for each γ . Here Γ is the positively oriented boundary, running from $+ \infty e^{\sqrt{-1}\theta_1}$ to $+ \infty e^{-\sqrt{-1}\theta_1}$ of the sector Σ :

$$\Sigma = \{ \lambda \in oldsymbol{C} extbf{;} | rg \lambda | \leqslant heta_1 \}.$$

The constant C_{γ} in (3.6) depends only on the constants θ_1 , M, K, α , N, ρ , T and γ .

Proposition 2. Under the conditions (A0)-(A3) in Theorem 1

with $\rho = 1$, we have the estimate

(3.7)
$$\| \overline{(1 + \tau A(t_n))^{-1} (1 + \tau A(t_{n-1}))^{-1} \cdots (1 + \tau A(t_{k+1}))^{-1} A(t_{k+1})^{1-\beta}} \| \\ \leq C_{\theta} \tau^{\beta-1} (n-k)^{\beta-1}$$

for each β in $0 < \beta \leq 1$. The constant C_{β} depends only on θ_1 , M, K, α , N, T and β .

To prove Proposition 1, we just need a refined version of the method by Kato-Tanabe [4] for the construction of evolution operators U(t, s). Proposition 2 can be proved by adopting Levy-Tanabe's method. Namely, in dealing with our discrete case, we imitate the method by Kato-Tanabe [4] which was originally employed in order to prove the inequality

(3.8)
$$||A(t)U(t,s)|| \leq C(t-s)^{-1}.$$

Now, putting
(3.9) $e^{\tau}(t) = E^{\tau}(t)\varphi,$
we have
(3.10) $-E^{\tau}(t_n) = \sum_{k=1}^n F_1(k) + \sum_{k=1}^n F_2(k) + \sum_{k=1}^n F_3(k)$
with
(3.11) $F_1(k) = \int_{t_{k-1}}^{t_k} dr(1+\tau A(t_n))^{-1} \cdots (1+\tau A(t_k))^{-1} \\ \times \frac{1}{2\pi\sqrt{-1}} \int_{\Gamma} \lambda e^{-r^2} [(\lambda - A(t_k))^{-1} - (\lambda - A(r))^{-1}] d\lambda$
(3.12) $F_2(k) = \int_{t_{k-1}}^{t_k} dr(1+\tau A(t_n))^{-1} \cdots (1+\tau A(t_k))^{-1} A(t_k)^{1-\beta}$

$$\times A(t_k)^{\beta}[e^{-t_kA(t_k)}-e^{-rA(t_k)}]$$

and

(3.13) $F_{3}(k) = \int_{t_{k-1}}^{t_{k}} dr (1 + \tau A(t_{n}))^{-1} \cdots (1 + \tau A(t_{k}))^{-1} \tilde{V}(r, 0; t_{k} - r),$ because of (3.4) and (3.5).

 $F_3(k)$ is estimated as follows by Proposition 1: (3.14) $\|F_3(k)\| \leqslant C_r \tau k^{-r}$, which yields

(3.15)
$$\sum_{k=1}^{n} \|F_{3}(k)\| \leqslant C_{r} n^{-r}.$$

We can estimate $F_2(k)$ as

(3.16) $||F_2(k)|| \leq C_{\beta,\gamma}(n+1-k)^{\beta-1}k^{-\beta-\gamma}$

by taking the parameter $\beta > 0$ in Proposition 2 so small that $\beta + \gamma < 1$ for the given γ . Hence we have

(3.17)
$$\sum_{k=1}^{n} \|F_2(k)\| \leqslant C_r n^{-r}.$$

 $F_1(k)$ is estimated as follows if $k \ge 2$:

(3.18)
$$||F_1(k)|| \leq C \int_{t_{k-1}}^{t_k} r^{-1}(t_k-1) dr \leq C \tau k^{-1}.$$

We can derive also (3.18) for k=1 by a standard technique of tele-

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scoping. Hence we end up with

(3.19) $\sum_{k=1}^{n} \|F_{1}(k)\| \leqslant C_{r} n^{-r}.$

Proofs of Propositions 1 and 2 will be given in a forthcoming paper along with detailed proofs and generalization of Theorems 2 and 3 which can cover also the case of the Neumann boundary condition.

A note added. Recently the author succeeded in proving the inequality (1.14) for $\gamma = 0$, which generalizes a result of Fujita-Mizutani [1] in the case of *t*-independence of $a_t(,)$. The proof is based on a refined study of fractional powers of operators and evolution operators. Details will be given in the paper mentioned above.

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