

48. On the Resolution of Two-dimensional Singularities

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§ 1. Introduction. Let $f(z_1, \dots, z_n)$ be a germ of an analytic function at the origin such that $f(0)=0$ and f has an isolated critical point at the origin. We assume that f has a non-degenerate Newton boundary. Let V be a germ of hypersurface $f^{-1}(0)$. Let $\Gamma^*(f)$ be the dual Newton diagram and let Σ^* be a simplicial subdivision of $\Gamma^*(f)$. It is known that there is a canonical resolution $\pi: \tilde{V} \rightarrow V$ which is associated with Σ^* . ([1]). However the process to get Σ^* from $\Gamma^*(f)$ is not unique and a "bad" Σ^* gives unnecessary exceptional divisors. The purpose of this paper is to show that in the case $n=3$, there is a canonical subdivision Σ^* of $\Gamma^*(f)$ so that the resolution graph is obtained by a canonical surgery from $S_2\Gamma^*(f)$ (= two-skeleton of $\Gamma^*(f)$). See Theorem (5.1).

§ 2. Newton boundary and the dual Newton diagram. Let $f(z_1, \dots, z_n) = \sum_{\nu} a_{\nu} z^{\nu}$ be the Taylor expansion of f where $z^{\nu} = z_1^{\nu_1} \cdots z_n^{\nu_n}$. Recall that the Newton boundary $\Gamma(f)$ is the union of the compact faces of $\Gamma_+(f)$ where $\Gamma_+(f)$ is the convex hull of the union of the subsets $\{\nu + (\mathbf{R}^+)^n\}$ for ν such that $a_{\nu} \neq 0$. For any closed face Δ of $\Gamma(f)$, we associate the polynomial $f_{\Delta}(z) = \sum_{\nu \in \Delta} a_{\nu} z^{\nu}$. We say that f is *non-degenerate* if f_{Δ} has no critical point in $(\mathbf{C}^*)^n$ for any $\Delta \in \Gamma(f)$. ([2]).

Let N^+ be the space of positive vectors in the dual space of \mathbf{R}^n . For any vector $P = {}^t(p_1, \dots, p_n)$ of N^+ , we associate the linear function $P(x) = \sum_i p_i x_i$ on $\Gamma_+(f)$ and let $d(P)$ be the minimal value of $P(x)$ on $\Gamma_+(f)$ and let $\Delta(P) = \{x \in \Gamma_+(f); P(x) = d(P)\}$. We introduce an equivalence relation \sim on N^+ by $P \sim Q$ if and only if $\Delta(P) = \Delta(Q)$. For any face Δ of $\Gamma_+(f)$, let $\Delta^* = \{P \in N^+; \Delta(P) = \Delta\}$. The collection of Δ^* gives a polyhedral decomposition of N^+ which we call *the dual Newton diagram of f* and we denote it by $\Gamma^*(f)$. $\Delta(P)$ is a compact face of $\Gamma(f)$ if and only if P is strictly positive. We say that a subdivision Σ^* of $\Gamma^*(f)$ is a *simplicial subdivision* if the following conditions are satisfied ([1]).

(i) Σ^* is a subdivision by the cones over a simplicial polyhedron whose simplexes are spanned by primitive integral vectors with determinant ± 1 in the sense of § 3.

(ii) Let $\sigma = (P_1, \dots, P_n)$ be an $(n-1)$ -simplex. Then there exists

a permutation τ of $\{1, \dots, n\}$ such that

$$(2.1) \quad \Delta(P_{\tau(1)}) \supset \Delta(P_{\tau(2)}) \supset \dots \supset \Delta(P_{\tau(n)}).$$

§3. Canonical simplicial subdivision. Let $P_i = {}^t(p_{1,i}, \dots, p_{n,i})$ ($i=1, \dots, k$) be given primitive integral vectors of N^+ . We define a non-negative integer $\det(P_1, \dots, P_k)$ by the greatest common divisor of all $k \times k$ minors of the matrix $(p_{j,i})$ and we call $\det(p_1, \dots, p_k)$ the determinant of P_1, \dots, P_k .

Lemma (3.1). Let P and Q be given primitive integral vectors in N^+ . Let $c = \det(P, Q)$ and assume that $c > 1$. There exists a unique integer c_1 such that $0 < c_1 < c$ and $P_1 = (Q + c_1 P)/c$ is an integral vector on \overline{PQ} . We have $\det(P, P_1) = 1$ and $\det(P_1, Q) = c_1$.

Remark. By the abuse of language, we say that P_1 is on \overline{PQ} if the normalized vector $P'_1 = P_1/a$ is on \overline{PQ} where $a = (1 + c_1)/c$.

Definition. Let \overline{PQ} be a line segment of $S_2\Gamma^*(f)$. We say that primitive vectors $\{P_1, \dots, P_k\}$ is the canonical primitive sequence on \overline{PQ} if the followings are satisfied.

(i) Let $c = \det(P, Q)$ and assume that $c > 1$. There exists positive integers $c = c_0 > c_1 > \dots > c_k = 1$ such that $P_{i+1} = (Q + c_{i+1} P_i)/c_i$ for each i . ($P_0 = P$.)

(ii) If $c = 1, k = 1$ and $P_1 = P + Q$.

Lemma (3.2). Assume that $c = \det(P, Q) > 1$. Let P_1, \dots, P_k be the canonical primitive sequence on \overline{PQ} and let c_i ($i=1, \dots, k$) be as above. Let $m_i = (c_{i-1} + c_{i+1})/c_i$. ($c_{k+1} = 0$.) Then m_i ($i=1, \dots, k$) are integers and $m_i \geq 2$ and the continuous fraction

$$m_1 - \frac{1}{m_2 - \dots - \frac{1}{m_k}}$$

is equal to c/c_1 . Let $P_i = {}^t(p_{1,i}, \dots, p_{n,i})$. Then $m_i = (p_{j,i-1} + p_{j,i+1})/p_{j,i}$ for each j .

We say that a simplicial subdivision Σ^* is canonical if it gives the canonical primitive sequence on each line segment \overline{PQ} of $S_2\Gamma^*(f)$. The existence is derived from the following lemma ($n=3$).

Lemma (3.3). Let Δ be a triangle with primitive vectors P, Q and R as vertices. Let $c = \det(P, Q, R)$. We assume that $\det(p, Q) = \det(P, R) = 1$ and $c > 1$. Then there exist unique c_1 and d_1 such that $0 < c_1 < c, 0 \leq d_1 < c$ and $T_1 = (R + c_1 Q + d_1 P)/c$ is an integral vector. T_1 divides Δ into three triangles with $\det(P, Q, T_1) = 1, \det(P, T_1, R) = c_1, \det(Q, T_1, R) = d_1$.

§4. Resolution of V . Let Σ^* be a simplicial subdivision of $\Gamma^*(f)$. For each $(n-1)$ -simplex $\sigma = (P_1, \dots, P_n)$, we associate an n -dimensional Euclidean space C^n with coordinates $(y_{\sigma,1}, \dots, y_{\sigma,n})$ and a

birational mapping $\pi_\sigma : C_\sigma^n \rightarrow C_\sigma^n$ which is defined by $z_i = y_{\sigma,1}^{p_{i,1}} \cdots y_{\sigma,n}^{p_{i,n}}$. Let X be the union of C_σ^n which are glued along the images of π_σ . Let π be the projection and let \tilde{V} be the closure of $\pi^{-1}(V \cap (C^*)^n)$. It is known that $\pi : \tilde{V} \rightarrow V$ is a resolution of V ([1]). Let $d_i = d(P_i)$ and $\Delta_i = \Delta(P_i)$. We assume that $\Delta_1 \supset \Delta_2 \supset \cdots \supset \Delta_n$. We define $f_\sigma(\mathbf{y}_\sigma)$ and $g_{\Delta_i}(\mathbf{y}_\sigma)$ by $f(\pi_\sigma(\mathbf{y}_\sigma)) = f_\sigma(\mathbf{y}_\sigma) \prod_i y_{\sigma,i}^{d_i}$ and $f_{\Delta_i}(\pi_\sigma(\mathbf{y}_\sigma)) = g_{\Delta_i}(\mathbf{y}_\sigma) \prod_i y_{\sigma,i}^{d_i}$. By the definition, \tilde{V} is defined by $f_\sigma(\mathbf{y}_\sigma) = 0$ and $\tilde{V} \cap \{y_{\sigma,i} = 0\}$ is $\{\mathbf{y}_\sigma ; y_{\sigma,i} = 0 \text{ and } g_{\Delta_i}(\mathbf{y}_\sigma) = 0\}$. Note that $g_{\Delta_i}(\mathbf{y}_\sigma)$ is a function of $y_{\sigma,i+1}, \dots, y_{\sigma,n}$. Thus $\tilde{V} \cap \{y_{\sigma,i} = 0\}$ is non-empty if and only if $\dim \Delta_i > 0$. Let $E(P_i; \sigma) = \{\mathbf{y}_\sigma \in \tilde{V} ; y_{\sigma,i} = 0\}$. $\pi(E(P_i; \sigma)) = \{0\}$ if and only if P_i is strictly positive. The union of $E(P_i; \sigma)$ for simplexes σ which contain P_i is a divisor of V and we denote it by $E(P_i)$. We say that vertices P_1, \dots, P_k in Σ^* are adjacent if there is an $(n-1)$ -simplex σ of Σ^* which contains P_1, \dots, P_k .

Lemma (4.1). *Let P_1, \dots, P_k be vertices of Σ^* with $\dim \Delta(P_i) \geq 1$. $\bigcap_i E(P_i)$ is non-empty if and only if P_1, \dots, P_k are adjacent.*

Lemma (4.2). *Assume that P is a strictly positive vertex of Σ^* such that $\dim \Delta(P) = 1$. Then $E(P)$ has $r(P) + 1$ connected components. If $n = 3$, they are rational curves. Here $r(P)$ is the number of the integral points in $\Delta(P) - \partial \Delta(P)$.*

Let $g(u_1, \dots, u_k)$ be a polynomial with support $S(g)$. We say that g is globally non-degenerate (=0-non-degenerate in [7]) if $g_\Delta(u)$ has no critical point in $(C^*)^k \cap g_\Delta^{-1}(0)$ for each Δ .

The exceptional divisor $E(P)$ has a canonical stratification in which each stratum is described by $g^{-1}(0)$ for some globally non-degenerate polynomial g .

Lemma (4.3) ([2], [5], [7]). *Let $g(u_1, \dots, u_k)$ be a globally non-degenerate polynomial and let $V^* = g^{-1}(0) \cap (C^*)^k$. Then the Euler characteristic of V^* is $(-1)^{k+1} k! k\text{-dim. volume } S(g)$.*

§ 5. Main result. We assume that $n = 3$ and let $\pi : \tilde{V} \rightarrow V$ be the good resolution associated with Σ^* . Let Δ be a two dimensional face of $\Gamma(f)$. We define $g(\Delta)$ by the number of the integral points in $\Delta - \partial \Delta$. Our main result is

Theorem (5.1). *Let $\pi : \tilde{V} \rightarrow V$ be as above. Then for a strictly positive vertex of Σ^* , we have*

- (i) *If $\dim \Delta(P) = 2$, $E(P)$ has genus $g(\Delta(P))$.*
- (ii) *If $\dim \Delta(P) = 1$, $E(P)$ is a disjoint union of $r(P) + 1$ rational curves.*

(iii) *Assume that Σ^* is canonical. Then the resolution graph is obtained by a canonical surgery of $\Gamma^*(f)$ as follows: Let \overline{PQ} be a line segment of $\Gamma^*(f)$ and assume that P is strictly positive. Let $c = \det(P, Q)$ and assume that $c > 1$. Let c_1 be as Lemma (3.1). Let*

$$m_1 = \cfrac{1}{m_2 - \cfrac{1}{\dots - \cfrac{1}{m_k}}}$$

be the continuous fraction of c/c_1 . We insert $r(P, Q)+1$ copies of chains of rational curves $\overset{-m_1}{\text{---}} \cdot \overset{-m_2}{\text{---}} \dots \overset{-m_k}{\text{---}}$ between P and Q . Here $r(P, Q)=r(P+Q)$. In the case of $c=1$, the chain is $\overset{-1}{\text{---}} \cdot \text{---}$ by definition. If neither P nor Q is strictly positive, we do nothing. Those vertices which are not strictly positive are omitted from the resolution diagram after the surgery. Assume that $\dim \Delta(P)=2$. Let Q_1, \dots, Q_s be the vertices of Σ^* which are adjacent to P . Let $P = {}^t(p_1, p_2, p_3)$ and $Q_i = {}^t(q_{1,i}, q_{2,i}, q_{3,i})$ ($i=1, \dots, s$). (s is the number of one-dimensional boundaries of $\Delta(P)$.) Then the self-intersection number of $E(P)$ is $-\sum_i^s (r(P, Q_i)+1)q_{1,i}/p_1$.

The proof is done by considering the divisor of the holomorphic function π^*z_1 on \tilde{V} and by the property $(\pi^*z_1) \cdot E(P)=0$. Lemmas (3.2) and (4.3) and the following lemma play the key role in the proof.

Lemma (5.1). *Let Δ be a compact polyhedron in \mathbb{R}^2 with integral points as vertices. Let $\Delta_1, \dots, \Delta_s$ be one dimensional faces of Δ . Then we have $2 \text{ volume } \Delta = 2g(\Delta) + \sum_i^s (r(\Delta_i)+1) - 2$.*

Further details will be treated in [6].

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