

## 95. Uniqueness of the $\omega$ -limit Point of Solutions of a Semilinear Heat Equation on the Circle

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§ 1. **Introduction.** In this paper we discuss the asymptotic behavior of a semilinear heat equation on the circle. Namely we shall show that the  $\omega$ -limit set of any solution contains at most one element. This implies that any bounded global solution converges to an equilibrium solution as  $t \rightarrow \infty$ .

To be more precise, consider the initial value problem

$$(1.1) \quad \begin{cases} u_t = u_{xx} + f(u), & x \in \mathbf{R}, t > 0, \\ u(x, 0) = u_0(x), & x \in \mathbf{R}, \\ u_0(x+1) = u_0(x), & x \in \mathbf{R}, \end{cases}$$

where  $f$  is a  $C^1$ -function on  $\mathbf{R}$  and  $u_0$  is a continuous function of period 1. It is well known that (1.1) has a unique classical solution  $u(x, t)$  such that  $u(\cdot, t) \in L^\infty(\mathbf{R})$  for every  $t \in [0, s(u))$ , where  $[0, s(u))$  denotes the maximal interval of existence for the solution  $u$ . Also one can easily show that  $u(x+1, t) = u(x, t)$  for  $x \in \mathbf{R}, t > 0$ . Therefore (1.1) can be regarded as an equation on a circle.

For a solution  $u$  of (1.1), its  $\omega$ -limit set is defined by

$$(1.2) \quad \omega(u) = \bigcap_{0 < t < s(u)} \text{closure} \{u(\cdot, \tau) : \tau > t\},$$

where the "closure" is with respect to the topology of  $C^2(\mathbf{R})$ .

A standard *a priori* estimate and dynamical systems argument show that  $\omega(u) \neq \emptyset$  if and only if  $s(u) = \infty$  and there exists a sequence  $t_n \rightarrow \infty$  such that  $u(\cdot, t_n)$  remains bounded as  $n \rightarrow \infty$ , in which case  $\omega(u)$  is a connected locally compact subset of  $C^2(\mathbf{R})$ . Using the Lyapunov functional, one can show that each  $\phi \in \omega(u)$  is an equilibrium of (1.1), that is,  $\phi$  satisfies

$$(1.3) \quad \begin{cases} \phi'' + f(\phi) = 0, & x \in \mathbf{R}, \\ \phi(x+1) = \phi(x), & x \in \mathbf{R}. \end{cases}$$

For the details, see, for instance, [1] and [4].

For each  $\lambda \in \mathbf{R}$ , we let  $\phi(x; \lambda)$  be the solution of the following initial value problem for ordinary differential equation:

$$(1.4) \quad \begin{cases} \phi'' + f(\phi) = 0, & x \in \mathbf{R}, \\ \phi(0; \lambda) = \lambda, \\ \phi'(0; \lambda) = 0, \end{cases}$$

where ' stands for  $d/dx$ . Define

$$A(f) = \{\lambda \in \mathbf{R} : \phi(x; \lambda) \text{ is nonconstant and 1-periodic in } x\}.$$

Our main result is the following:

**Theorem.** *If  $A(f)$  contains no interior point, then  $\omega(u)$  contains at*

most one element.

A direct consequence is

**Corollary.** *If  $\Lambda(f)$  contains no interior point and  $u$  is a solution of (1.1), then either  $\lim_{t \rightarrow s(u)} \|u(\cdot, t)\|_{L^\infty(\mathbf{R})} = \infty$ , or there exists a solution  $\phi(x)$  of (1.3) such that  $\lim_{t \rightarrow \infty} u(\cdot, t) = \phi$  in  $C^2(\mathbf{R})$ , with  $s(u) = \infty$ .*

In his pioneering work [3], Matano obtained an analogous (and stronger) result in the case of initial-boundary value problems on a compact interval. His approach is based on the investigation of the behavior of  $u$  at the boundary of the interval via the maximum principle. The main difficulty in our case is that a circle has no boundary, so that his argument does not directly apply. This difficulty is overcome by comparing  $u$  with its reflection (Lemma 1 in § 2).

**§ 2. Proof of Theorem.** The following lemma is essential :

**Lemma 1.** *If  $\phi \in \omega(u)$  and  $\phi'(a) > 0$  (resp.  $< 0$ ) at some  $a \in \mathbf{R}$ , then there exists  $T > 0$  such that  $u_x(a, t) \geq 0$  (resp.  $\leq 0$ ) for any  $t \geq T$ .*

*Proof.* Let

$$\begin{aligned} \xi(x) &= \phi(x) - \phi(2a - x), \\ v(x, t) &= u(x, t) - u(2a - x, t). \end{aligned}$$

By (1.1) and (1.3), we obtain

$$(2.1) \quad \begin{cases} \xi'' + b(x)\xi = 0, & x \in \mathbf{R}, \\ \xi(a) = \xi(a+1) = 0, \\ \xi'(a) = 2\phi'(a) > 0, \end{cases}$$

$$(2.2) \quad \begin{cases} v_t = v_{xx} + b(x, t)v, & x \in \mathbf{R}, t > 0, \\ v(a, t) = v(a+1, t) = 0, & t \geq 0, \\ v_x(a, t) = 2u_x(a, t), & t > 0, \end{cases}$$

where  $b(x)$  and  $b(x, t)$  are continuous functions. We remark that  $\xi \in \omega(v)$ , where  $\omega(v)$  is defined in the same manner as in (1.2). Combining (2.1) and (2.2), and following the argument found in [3], one can prove Lemma 1. We omit the details.

Using Lemma 1, one can easily prove the following :

**Lemma 2.** *Let  $\phi, \psi \in \omega(u)$  be both nonconstant and let  $a \in \mathbf{R}$ . Then  $\phi'(a) > 0$  (resp.  $< 0, = 0$ ) implies  $\psi'(a) > 0$  (resp.  $< 0, = 0$ ).*

*Proof of Theorem.* We consider only the case where  $\omega(u)$  contains a nonconstant function, say  $\psi$ , since otherwise the proof is much easier by the connectedness of  $\omega(u)$  and the maximum principle. By making a translation in  $x$ -axis if necessary, we may assume without loss of generality that  $\psi'(0) = 0$ . Let

$$I(u) = \{\lambda \in \mathbf{R} : \phi(\cdot; \lambda) \in \omega(u)\}.$$

Then, by Lemma 2,  $\omega(u) = \{\phi(\cdot; \lambda) : \lambda \in I(u)\}$ . As  $\omega(u)$  is connected and closed,  $I(u)$  is a closed interval containing  $\psi(0)$ . Since  $\Lambda(f)$  contains no interior point and  $\phi(\cdot; \lambda)$  are nonconstant for  $\lambda \in \mathbf{R}$  sufficiently near  $\psi(0)$ , it follows that  $\omega(u)$  has only one element. This proves the theorem.

**Remark.** Our assumption on  $\Lambda(f)$  in Theorem is very technical and it does not cover the linear case, say  $f(u) = 4\pi^2 k^2 u$ , with  $k$  a nonzero integer,

although in this case the uniqueness of the  $\omega$ -limit point is obvious. But we note that it covers a wide class of nonlinear equations including the case where  $f(u) = A|u|^p u$  ( $A > 0, p > 0$ ) and the case where  $f(u) = (A - B|u|^p)u$  ( $A > 0, B > 0, p > 0$ ).

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