A NOTE ON TURING MACHINE REGULARITY AND PRIMITIVE RECURSION

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1 Introduction The purpose of this paper is to present an explicit Turing machine $\mathbf Z$ which computes any function which is defined by means of primitive recursion from two given computable functions. The formulation of $\mathbf Z$ uses results of Davis [1] and Mal'cev [3], with the added feature that $\mathbf Z$ yields outputs in a standard form, such outputs usable as inputs in subsequent Turing machines which can be activated after $\mathbf Z$ has completed its computation. Such machines as $\mathbf Z$ are defined as n-regular, for a positive integer n. The course of a computation in $\mathbf Z$ follows along lines suggested by Davis [2], for a similar computation using abstract programs instead of Turing machines.

2 Preliminary concepts We will assume a general familiarity with [1], explicitly defining only those concepts which are absolutely necessary for the continuity of this discussion. A Turing machine is any non-empty and finite set of quadruples, any one of which assumes the form (i) $q_i S_i S_k q_l$, or (ii) $q_i S_j R q_l$, or (iii) $q_i S_j L q_l$, where i, j, k, l are positive integers. The symbols q_i , q_l are elements of a finite set Q, called the *internal states* of the machine; the symbols S_i , S_k are elements of the set $A = \{1, B\}$ disjoint from Q and called the alphabet of the machine; the symbols L and R are distinct symbols not in $Q \cup A$. It is understood that no two distinct quadruples of a given Turing machine begin with the same first two symbols. The usual meanings are attached to the quadruples: (i) is the instruction which, when the state of the machine is q_i and the symbol S_i is being scanned, erases S_i and prints S_k in its place, the machine then moving to state q_l ; (ii) instructs the machine to move one square to the right and change to state q_l when the machine is in state q_i and scans a square with S_i printed there; (iii) is the instruction similar to (ii), except the machine moves one square to the left.

^{1.} Using the terminology of [1], this paper will deal only with *simple* Turing machines, but these results can easily be generalized to the case of relative computability.

Let **T** be a fixed Turing machine. Then $\theta(\mathbf{T})$ will denote the largest subscript of an internal state symbol appearing in T. Furthermore, for any natural number m, $T^{(m)}$ will denote the Turing machine obtained from T by adding m to the value of each subscript of an internal state symbol of T. By an instantaneous description of T we mean any finite string of symbols from $Q \cup A$ containing exactly one element of Q, and where this element of Q is not permitted to be the rightmost member of the string. In any instantaneous description α , we regard the symbol appearing immediately to the right of the internal state symbol q_i of α as the symbol being scanned by T when T is in state q_i . If α , β are instantaneous descriptions of T, we write $\alpha \to \beta(T)$ (or simply $\alpha \to \beta$ when T is understood) to signify that β is the result of an application to α of a single quadruple of **T**. If, for a given instantaneous description β of T, there is no instantaneous description γ of **T** such that $\beta \to \gamma(\mathbf{T})$, we say that β is final with respect to **T**. Any finite sequence $\alpha_1, \ldots, \alpha_n$ of instantaneous descriptions of **T** such that $\alpha_i \rightarrow$ $\alpha_{i+1}(T)$ for $1 \le i \le n$, and such that α_n is final with respect to T, is called a computation in **T** with resultant (or output) α_n . We denote this by $Res_{\mathbf{T}}(\alpha_1) = \alpha_n.$

The set of natural numbers will be denoted by N, and N^n will denote the set of all n-tuples of elements of N. If x>0, we define 1^x (respectively B^x) to be string of length x of the symbol 1 (respectively B) of A. We also define 1^0 and B^0 to be the empty string. If $n \in N$, we define \overline{n} to be 1^{n+1} , and if $\langle a_1, \ldots, a_n \rangle \in N^n$, we define $\overline{\langle a_1, \ldots, a_n \rangle}$ to be the string $1^{a_1+1}B1^{a_2+1}B\ldots B1^{a_n+1}$. We will consider instantaneous descriptions of \mathbb{T} of the form $q_1\langle a_1, \ldots, a_n \rangle$ as usable inputs of \mathbb{T} . For any instantaneous description α of \mathbb{T} , we define $[\alpha]$ to be the number of occurrences of the symbol 1 in α .

If n is a fixed positive integer, then T is called n-regular if (1) there is a positive integer p such that

$$\operatorname{Res}_{\mathbf{T}}(q_1\overline{\langle a_1,\ldots,a_n\rangle}) = q_{\theta(\mathbf{T})}\overline{\langle b_1,\ldots,b_p\rangle}$$

whenever $\operatorname{Res}_{\mathbf{T}}(q_1(a_1,\ldots,a_n))$ is defined, and if (2) T has no quadruple beginning with $q_{\theta(\mathbf{T})}$.

A function F whose domain is a subset of N^n and having values in N is called partially computable if there is some Turing machine T such that for any $\langle a_1, \ldots, a_n \rangle$ in the domain of F, it is the case that

$$F(a_1, \ldots, a_n) = [\operatorname{Res}_{\mathbf{T}}(q_1\langle a_1, \ldots, a_n\rangle)].$$

Thus, for an input of the form $\alpha = q_1 \overline{\langle a_1, \ldots, a_n \rangle}$, T will yield an output for just those n-tuples $\langle a_1, \ldots, a_n \rangle$ which happen to be members of the domain of F; otherwise, T will hot yield an output for the input α . Furthermore, F is called a total function if its domain is all of N^n , and is called computable if it is partially computable and is total. If F is (partially) computable via the Turing machine T, then we say that T (partially) computes F.

3 Main result We prove the following

Theorem Let n be a positive integer. If f is a total function of n+1

variables, and is defined by primitive recursion in terms of the computable functions g, h, of n and n+2 variables, respectively, i.e., if for any $\langle x_1, \ldots, x_n \rangle \in N^n$ and $t \in N$,

$$f(x_1, \ldots, x_n, 0) = g(x_1, \ldots, x_n),$$

$$f(x_1, \ldots, x_n, t+1) = h(x_1, \ldots, x_n, t, f(x_1, \ldots, x_n, t)),$$

then there is an (n + 1)-regular Turing machine **Z** which computes f. More precisely, for any $\langle x_1, \ldots, x_n, y \rangle \in \mathbb{N}^{n+1}$.

$$\operatorname{Res}_{\mathbf{Z}}(q_1\langle x_1, \ldots, x_n, y \rangle) = q_{\theta(\mathbf{Z})} f^{(x_1, \ldots, x_n, y)}$$

Proof: Suppose **G** is a Turing machine which computes g, and **H** is a Turing machine which computes h. By results of [1], we may assume that **G** is n-regular, and that **H** is (n+2)-regular. Indeed, using results of [1], there then exists an (n+1)-regular Turing machine \mathbf{V}_1 such that, for any $\langle x_1, \ldots, x_n, y \rangle \in N^{n+1}$,

$$\operatorname{Res}_{\mathbf{V}_{1}}(q_{1}\langle x_{1}, \ldots, x_{n}, y \rangle) = q_{p}\langle g(x_{1}, \ldots, x_{n}), y, x_{1}, \ldots, x_{n}\rangle$$
$$= q_{p}\langle f(x_{1}, \ldots, x_{n}, 0), y, x_{1}, \ldots, x_{n}\rangle.$$

where $p = \theta(V_1)$. Similarly, using the fact that H is (n + 2)-regular, there is an (n + 2)-regular Turing machine \overline{H} such that, for all t, y, x_1 , ..., $x_n \in N$,

$$\operatorname{Res}_{\bar{\mathbf{H}}}(q_1(f(x_1, \ldots, x_n, t), y, x_1, \ldots, x_n)) = q_{\theta(\bar{\mathbf{H}})}(h(x_1, \ldots, x_n, t, f(x_1, \ldots, x_n, t)), y, x_1, \ldots, x_n) = q_{\theta(\bar{\mathbf{H}})}(f(x_1, \ldots, x_n, t + 1), y, x_1, \ldots, x_n).$$

In addition, there is a Turing machine $\overline{\overline{H}}$ such that, for every $t, y, x_1, \ldots, x_n \in N$,

Res
$$\bar{\mathbf{H}}(1B^2q_1\overline{\langle f(x_1,\ldots,x_n,t),y,x_1,\ldots,x_n\rangle})$$

= $1B^2q_0(\bar{\mathbf{H}})\overline{\langle f(x_1,\ldots,x_n,t+1),y,x_1,\ldots,x_n\rangle}.$

In particular, \overline{H} may be regarded as the Turing machine which first moves left to erase the leftmost 1 of the input $1B^2q_1\overline{\langle f(x_1,\ldots,x_n,t), y, x_1,\ldots,x_n\rangle}$, then moves right until a 1 is found. $\overline{\overline{H}}$ then performs the identical computation which \overline{H} performs on $q_1\overline{\langle f(x_1,\ldots,x_n,t), y, x_1,\ldots,x_n\rangle}$. After this last computation has been completed, $\overline{\overline{H}}$ then moves left to reprint a 1 three squares to the left of the leftmost 1 of the resultant β of the \overline{H} -computation. Finally, $\overline{\overline{H}}$ moves right until it scans the leftmost 1 of β .

Now set $k = \theta(\overrightarrow{\mathbf{H}}^{(u+3)})$, where u = p + 10 + 2n, and let **W** be the following set of quadruples:

$$\begin{array}{lll} q_{p} & q_{p+\theta} 1 \mathbb{E} q_{p+1} & q_{p+\theta} 1 \mathbb{E} q_{p+1} \\ q_{p} \mathbb{E} \mathbb{E} q_{p+1} & q_{p+1} \mathbb{E} \mathbb{E} q_{p+\theta} \\ q_{p+1} \mathbb{E} \mathbb{E} q_{p+1} & q_{p+7+2i} \mathbb{E} \mathbb{E} q_{p+7+2(i+1)} \\ q_{p+1} 1 \mathbb{E} q_{p+2} & q_{p+7+2(i+1)} 1 \mathbb{E} q_{p+7+2(i+1)+1} \\ q_{p+2} \mathbb{E} \mathbb{E} q_{p+3} & q_{p+7+2(i+1)+1} \mathbb{E} \mathbb{E} q_{p+7+2(i+1)} \\ q_{p+3} 1 \mathbb{E} q_{p+4} & q_{p+8} \mathbb{E} \mathbb{E} q_{p+1} \\ q_{p+4} \mathbb{E} \mathbb{E} q_{p+5} & q_{p+1} \mathbb{E} \mathbb{E} q_{p+2} \end{array} \right)$$

$$\begin{array}{lll} q_{p+5} 1 R \, q_{p+5} & q_{u+2} B 1 q_{u+3} \\ q_{p+5} B R \, q_{p+6} & q_{u+3} 1 L \, q_{u+3} \\ q_{p+6} 1 B q_{p+7} & q_{u+3} B R \, q_{u+4} \\ q_{p+7} B R \, q_{p+8} & q_{u-1} B B q_{k+1} \\ q_{p+8} B R \, q_{p+9} & \end{array}$$

Let E be the following set of quadruples:

| $q_{k+1}BLq_{k+1}$ | $q_{k+4}B$ R q_{k+7} |
|-------------------------|------------------------|
| q_{k+1} 1 L q_{k+2} | $q_{k+5}B$ R q_{k+5} |
| q_{k+2} 1L q_{k+2} | q_{k+5} 1L q_{k+6} |
| $q_{k+2}B$ L q_{k+3} | $q_{k+6}B1q_{k+7}$ |
| $q_{k+3}B$ L q_{k+4} | $q_{k+7}B$ R q_{k+7} |
| $q_{k+4} 1 B q_{k+5}$ | $q_{k+7}11q_{k+8}$. |

Finally, let $\mathbf{Z}=\mathbf{V}_1\cup\overline{\mathbf{H}}^{(u+3)}\cup\mathbf{W}\cup\mathbf{E}\cup\{q_k11q_p\}$. We claim that \mathbf{Z} is a Turing machine which computes f. Note first that $\theta(\mathbf{Z})=k+8$, and that there is no quadruple of \mathbf{Z} beginning with $\theta(\mathbf{Z})$. Hence the second property of (n+1)-regularity is satisfied by \mathbf{Z} . The first property of (n+1)-regularity will be verified if we can show that for any $\langle x_1,\ldots,x_ny\rangle\in N^{n+1}$,

$$\operatorname{Res}_{\mathbf{Z}}(q_1\langle x_1, \ldots, x_n, y \rangle) = q_{\theta(\mathbf{Z})} \overline{f(x_1, \ldots, x_n, y)}.$$

This will be done by tracing a computation in **Z** beginning with an input of the form $q_1\langle x_1, \ldots, x_n, y \rangle$. First of all,

$$q_1\langle x_1,\ldots,x_n,y\rangle \to \ldots \to q_p\langle f(x_1,\ldots,x_n,0),y,x_1,\ldots,x_n\rangle$$
(using V_1).

(i) Suppose that y = 0. Then

$$q_p \langle f(x_1, \ldots, x_n, 0), 0, x_1, \ldots, x_n \rangle \to \ldots$$

 $\to 1B^2 1^{f(x_1, \ldots, x_n, 0)} B^3 B^{x_1+1} B \ldots B^{x_n+1} q_{k+1} B = \alpha_1$, (using **W**).

Applying E to α_1 , either of two possibilities exist as the resultant of a computation in E beginning with α_1 ; namely,

$$\operatorname{Res}_{\mathbf{E}}(\alpha_{1}) = \begin{cases} B^{2}q_{k+8}f(x_{1}, \ldots, x_{n}, 0)B^{3}B^{x_{1}+1}B \ldots BB^{x_{n}+1}B, & \text{in case} \\ f(x_{1}, \ldots, x_{n}) > 0, \\ B^{3}q_{k+8}f(x_{1}, \ldots, x_{n}, 0)B^{5}B^{x_{1}+1}B \ldots BB^{x_{n}+1}B, & \text{if} \\ f(x_{1}, \ldots, x_{n}) = 0. \end{cases}$$

Each of these resultants is final with respect to **Z**. Hence, if we disregard initial and terminal blocks of 1's, we get

$$\operatorname{Res}_{\mathbf{Z}}(q_1\overline{\langle x_1,\ldots,x_n,0\rangle})=q_{\theta(\mathbf{Z})}\overline{f(x_1,\ldots,x_n,0)},$$

which is the desired result when y = 0. Note that, in this case, the machine $\overline{\overline{H}}^{(u+3)}$ was never activated. Indeed, $\overline{\overline{H}}^{(u+3)}$ would not be activated unless the function h were used in evaluating f, which is not the case if y = 0.

(ii) Now suppose y > 0. Then, after V_1 has completed its computation,

$$\begin{array}{l} q_{p}\overline{\langle f(x_{1},\ldots,x_{n},0),\,y,\,x_{1},\ldots,x_{n}\rangle} \to \ldots \\ \to 1B^{2}q_{u+4}\overline{\langle f(x_{1},\ldots,x_{n},0),\,y-1,\,x_{1},\ldots,x_{n}\rangle} \; (\text{using } \mathbf{W}), \\ \to \ldots \to 1B^{2}q_{k}\overline{\langle f(x_{1},\ldots,x_{n},1),\,y-1,\,x_{1},\ldots,x_{n}\rangle} \; (\text{using } \overline{\mathbf{H}}^{(u+3)}), \\ \to \ldots \to 1B^{2}q_{p}\overline{\langle f(x_{1},\ldots,x_{n},1),\,y-1,\,x_{1},\ldots,x_{n}\rangle} \; (\text{using } q_{k}11q_{p}), \\ \to \ldots \to 1B^{2}1^{f(x_{1},\ldots,x_{n},y)}B^{3}B^{x_{1}+1}B \ldots BB^{x_{n}+1}q_{k+1}B, \\ \text{iterating the sequence, } \mathbf{W}, \, \overline{\mathbf{H}}^{(u+3)},\,q_{k}11q_{p},\,\text{until } y=0. \end{array}$$

Let $\overline{\beta} = 1B^2 1^{f(x_1, \dots, x_n, y)} B^3 B^{x_1 + 1} B \dots B B^{x_n + 1} q_{k+1} B$. Then, using the quadruple $q_{k+1} B L q_{k+1}$ as many times as is applicable, we get either

$$\overline{\beta} \rightarrow q_{k+1} 1 B^5 B^{x_1+1} B \dots B B^{x_n+1} B = \beta_1,$$

if
$$f(x_1, ..., x_n, y) = 0$$
, or

$$\overline{\beta} \to 1B^2 1^{f(x_1, \dots, x_n, y)-1} q_{k+1} 1B^3 B^{x_1+1} B \dots BB^{x_n+1} B = \beta_2,$$

if $f(x_1, ..., x_n, y) > 0$.

- (a) Suppose $f(x_1, \ldots, x_n, y) = 0$; then, using the remaining quadruples of E, $\beta_1 \to \ldots \to B^3 q_{k+8} 1 B^5 B^{x_1+1} B \ldots B B^{x_n+1} B$ $= B^3 q_{k+8} f(x_1, \ldots, x_n, y) B^5 B^{x_1+1} B \ldots B B^{x_n+1} B$.
- (b) Suppose $f(x_1, \ldots, x_n, y) > 0$; then, using the remaining quadruples of E, $\beta_2 \to \ldots \to B^2 q_{k+8} \overline{f(x_1, \ldots, x_n, y)} B^3 B^{x_1+1} B \ldots B B^{x_n+1} B$.

The resultants obtained in (a) and (b) above are each final with respect to Z. Thus, omitting initial and terminal block's of B's, we get

Res_{**Z**}
$$(q_1 \langle x_1, \ldots, x_n, y \rangle) = q_{\theta(\mathbf{Z})} \overline{f(x_1, \ldots, x_n, y)}$$

whenever y > 0.

This completes the proof of (ii), and thus the proof of the Theorem is complete.

4 Additional notes In case y>0, the machine **Z** decreases the value of y by 1 whenever **W** is activated. The quadruple $q_k 11q_p$ acts as a recycling instruction, demanding a repetition of the sequence **W**, $\overline{\mathbf{H}}^{(u+3)}$ as many times as is necessary to obtain y=0. When y=0, the machine **E** acts as an exiting mechanism, yielding an output in the standard form $q_{\theta(\mathbf{Z})} \overline{f(x_1, \ldots, x_n, y)}$.

The leftmost 1 in the instantaneous descriptions α_1 , β_1 , β_2 plays the role of a marker", in the sense that it prevents an infinite leftward movement of **Z** via the quadruple $q_{k+1}B \sqcup q_{k+1}$, in case y > 0 and $f(x_1, \ldots, x_n, y) = 0$. This 1 is then erased by **E** as part of its computation.

Finally, if **Z** is augmented by the single quadruple $q_{k+\theta}1Bq_{k+\theta}$, then the resulting machine **Z'** has the property of (n+1)-regularity, and, in addition

$$[\operatorname{Res}_{\mathbf{Z}}, (q_1 \overline{\langle x_1, \ldots, x_n, y \rangle})] = f(x_1, \ldots, x_n, y),$$

for every $\langle x_1, \ldots, x_n, y \rangle \in N^{n+1}$.

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