# SUBMANIFOLDS OF CODIMENSION 2 IN AN EVEN-DIMENSIONAL EUCLIDEAN SPACE 

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## § 0. Introduction.

A structure induced on a submanifold of codimension 2 of an almost Hermitian manifold or on a hypersurface of an almost contact metric manifold, called an ( $f, g, u, v, \lambda$ )-structure, has been studied in [1, 5, 6,7]. Okumura and one of the present authors [7] proved

Theorem 0.1. Let a complete differentiable submanifold $M$ of codimension 2 of an even-dimensional Euclidean space $E$ be such that the connection induced in the normal bundle of $M$ is trivial. If the ( $f, g, u, v, \lambda$ )-structure induced on $M$ is normal, then $M$ is a sphere, a plane or a product of a sphere and a plane, provided that $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero in $M$.

For an orientable hypersurface $M$ of an odd-dimensional sphere $S^{2 n+1}$, we can choose the first unit normal $C$ in the direction opposite to that of the radius vector of $S^{2 n+1}$ and hence the second unit normal $D$ is automatically fixed. We denote by $H$ the second fundamental tensor with respect to $C$ and by $K$ that with respect to $D$. Then $H$ is the identity and the connection induced in the normal bundle of $M$ is trivial. Moreover, the normality of the ( $f, g, u, v, \lambda$ )-structure induced on $M$ naturally is equivalent to the condition $K f-f K=0$. Thus we can deduce, from Theorem 0.1, the following

Theorem 0.2. If $M$ is a complete orientable hypersurface of $S^{2 n+1}$ satisfying $f K-K f=0$ and $\lambda \neq$ constant, then $M$ is "a sphere of radius $1 / \sqrt{1+\alpha^{2}}$, where $\alpha$ is some constant determined by the embedding, provided that $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero in $M$.

In [2], Blair, Ludden and one of the present authors proved:
Theorem 0.3. If $M$ is a complete orientable hypersurface of $S^{2 n+1}$ of constant scalar curvature satisfying $K f+f K=0$ and $\lambda \neq$ constant, then $M$ is a natural sphere $S^{2 n}$ or $S^{n} \times S^{n}$, provided that $n>2$ and $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero in $M$ (See also [3]).

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The main purpose of the present paper is to study complete orientable submanifolds $M$ of codimension 2 in an even-dimensional Euclidean space $F$ which satisfies the conditions $H f-f H=0$ and $K f+f K=0$, the normal bundle of $M$ being locally trivial. Our main result will be stated in Theorem 3.1.

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## § 1. Submanifolds of codimension 2 of an even-dimensional Euclidean space.

Let $E$ be a ( $2 n+2$ )-dimensional Euclidean space and $X$ the position vector starting from the origin of $E$ and ending at a point P of $E$. The $E$ being evendimensional, it can be regarded as a flat Kählerian manifold with the numerical structure tensor $F: F^{2}=-I$, where $I$ denotes the unit tensor and $F Y \cdot F Z=Y \cdot Z$ for arbitrary vector fields $Y$ and $Z$, where the dot denotes the inner product of vectors of $E$.

Let $M$ be a $2 n$-dimensional orientable manifold covered by a system of coordinate neighborhoods $\left\{U ; x^{h}\right\}$, where here and in the sequel the indices $h, i, j, \cdots$ run over the range $\{1,2, \cdots, 2 n\}$ and the summation convention will be used with respect to these indices.

We assume that $M$ is immersed in $E$ by $X: M \rightarrow E$ and put $X_{\imath}=\partial_{i} X, \partial_{i}=\partial / \partial x^{2}$. Then $X_{\nu}$ are $2 n$ linearly independent local vector fields tangent to $X(M)$ and $g_{j i}=X_{j} \cdot X_{i}$ are local components of the tensor representing the Riemannian metric induced on $M$ from that of $E$.

We assume that we can take two globally defined mutually orthogonal unit normals $C$ and $D$ to $X(M)$ in such a way that $X_{1}, X_{2}, \cdots, X_{2 n}, C, D$ give the positive orientation of $E$. In the sequel we identify $X(M)$ with $M$ itself.

The transforms $F X_{\imath}$ of $X_{\imath}$ by $F$ can be expressed as linear combinations of $X_{h}, C$ and $D$, that is, we have equations of the form

$$
\begin{equation*}
F X_{\imath}=f_{\imath}^{h} X_{h}+u_{i} C+v_{i} D, \tag{1.1}
\end{equation*}
$$

where $f_{2}{ }^{h}$ are components of a tensor field of type $(1,1)$ and $u_{i}, v_{i}$ are those of 1 -forms of $M$, all globally defined on $M$. The transforms $F C$ and $F D$ of $C$ and $D$ by $F$ can be expressed as

$$
\begin{align*}
& F C=-u^{h} X_{h}+\lambda D,  \tag{1.2}\\
& F D=-v^{h} X_{h}-\lambda C \tag{1.3}
\end{align*}
$$

respectively, where $u^{h}=u_{i} g^{i h}, v^{h}=v_{i} g^{i h}$ and $\lambda$ is a function on $M$, because

$$
\begin{aligned}
& X_{i} \cdot F C=F X_{i} \cdot F^{2} C=-F X_{i} \cdot C=-u_{2}, \\
& X_{i} \cdot F D=F X_{i} \cdot F^{2} D=-F X_{i} \cdot D=-v_{i}, \\
& F C \cdot D=F^{2} C \cdot F D=-C \cdot F D .
\end{aligned}
$$

Applying $F$ to (1.1), (1.2) and (1.3) and using $F^{2}=-I,(1.1),(1.2)$ and (1.3), we find

$$
\begin{align*}
& f_{\imath}^{t} f_{t}^{h}=-\partial_{i}^{h}+u_{i} u^{h}+v_{i} v^{h}, \\
& u_{t} f_{\imath}^{t}=+\lambda v_{i}, \quad f_{\imath}^{h} u^{\imath}=-\lambda v^{h}, \\
& v_{t} f_{\imath}^{t}=-\lambda u_{i}, \quad f_{\imath}^{h} v^{2}=+\lambda u^{h},  \tag{1.4}\\
& u_{i} u^{2}=v_{i} v^{i}=1-\lambda^{2}, \quad u_{i} v^{2}=0
\end{align*}
$$

(cf. [7]). We also have, from (1.1),

$$
\begin{equation*}
g_{t s} f_{j}^{t} f_{i}^{s}=g_{j i}-u_{j} u_{i}-v_{j} v_{i} \tag{1.5}
\end{equation*}
$$

by virtue of $F X_{j} \cdot F X_{\imath}=X_{j} \cdot X_{\imath}=g_{j i}$. We can easily see that $f_{j i}=f_{j}{ }^{t} g_{t i}$ is skewsymmetric in lower indices $j$ and $i$.

The structure defined on $M$ by such a set of a tensor field $f$ of type (1, 1), a Riemannian metric $g$, two 1 -forms $u$ and $v$ and a function $\lambda$ satisfying (1.4) and (1.5) is called an ( $f, g, u, v, \lambda$ )-structure (cf. [6]).

We denote by $\left\{j^{{ }^{h}}{ }_{i}\right\}$ the Christoffel symbols formed with $g_{j i}$ and by $\nabla_{\imath}$ the operator of covariant differentiation with respect to $\left\{{ }_{3}{ }_{i}{ }_{i}\right\}$. Then equations of Gauss are

$$
\nabla_{\jmath} X_{\imath}=\partial_{j} X_{i}-\left\{\begin{array}{c}
h  \tag{1.6}\\
j
\end{array}\right\} X_{h}=h_{j i} C+k_{j i} D
$$

where $h_{j i}$ and $k_{j i}$ are components of the second fundamental tensors with respect to $C$ and $D$ respectively, and equations of Weingarten are

$$
\nabla_{j} C=\partial_{j} C=-h_{j}{ }^{h} X_{h}+l_{j} D,
$$

$$
\begin{equation*}
\nabla_{j} D=\partial_{j} D=-k_{j}{ }^{h} X_{h}-l_{j} C, \tag{1.7}
\end{equation*}
$$

where $h_{J}{ }^{h}$ and $k_{J}{ }^{h}$ are given respectively by $h_{J}{ }^{h}=h_{j i} g^{i h}$ and $k_{J}{ }^{h}=k_{j i} g^{i h}$, and $l_{J}$ are components of the third fundamental tensor, i.e., components of the connection induced on the normal bundle.

Now, differentiating (1.1) covariantly and taking account of $\nabla_{j} F=0$ and of equations of Gauss and Weingarten, we obtain

$$
\begin{equation*}
\nabla_{j} f_{2}{ }^{h}=-h_{j i} u^{h}+h_{\jmath}{ }^{h} u_{i}-k_{j i} v^{h}+k_{\jmath}{ }^{h} v_{i} \tag{1.8}
\end{equation*}
$$

$$
\begin{align*}
& \nabla_{j} u_{i}=-h_{j l} f_{\imath}^{t}-\lambda k_{j i}+l_{j} v_{i},  \tag{1.9}\\
& \nabla_{j} v_{i}=-k_{j t} f_{i}^{t}+\lambda h_{j i}-l_{j} u_{i} . \tag{1.10}
\end{align*}
$$

Similarly we have, from (1.2),
(1.11)

$$
\nabla_{j} \lambda=-h_{j i} v^{2}+k_{j i} u^{2} .
$$

Now we put

$$
\begin{equation*}
S_{j i}{ }^{h}=N_{j i}{ }^{h}+\left(\nabla_{j} u_{i}-\nabla_{i} u_{j}\right) u^{h}+\left(\nabla_{j} v_{i}-\nabla_{i} v_{j}\right) v^{h}, \tag{1.12}
\end{equation*}
$$

where $N_{j i}{ }^{h}$ is the Nijenhuis tensor formed with $f_{2}{ }^{h}$, i.e.,

$$
N_{j i}{ }^{h}=f_{j}^{t} \nabla_{t} f_{2}^{h}-f_{\imath} \nabla_{t} \nabla_{j}^{h}-\left(\nabla_{J} f_{\imath}^{t}-\nabla_{\imath} f_{j}^{t}\right) f_{t}^{h} .
$$

If the tensor $S_{j i}{ }^{h}$ vanishes, the ( $f, g, u, v, \lambda$ )-structure is said to be normal. Substituting (1.8), (1.9) and (1.10) into (1.12), we find

$$
\begin{align*}
S_{j i}{ }^{h}= & \left(f_{j}{ }^{t} h_{t}{ }^{h}-h_{j}{ }^{t} f_{l}{ }^{h}\right) u_{i}-\left(f_{i}{ }^{t} h_{t}{ }^{h}-h_{i}{ }^{t} f_{t}{ }^{h}\right) u_{j} \\
& +\left(f_{j}{ }^{t} k_{t}{ }^{h}-k_{j}{ }^{t} f_{t}{ }^{h}\right) v_{i}-\left(f_{i}{ }^{t} k_{t}{ }^{h}-k_{i}{ }^{t} f_{t}^{h}\right) v_{j}  \tag{1.13}\\
& +\left(l_{j} v_{i}-l_{i} v_{j}\right) u^{h}-\left(l_{j} u_{i}-l_{i} u_{j}\right) v^{h} .
\end{align*}
$$

In the sequel, we need the structure equations of the submanifold $M$, that is, the following equations of Gauss

$$
\begin{equation*}
K_{k j i \hbar}=h_{k h} h_{j i}-h_{j h} h_{k i}+k_{k h} k_{j i}-k_{j h} k_{k i}, \tag{1.14}
\end{equation*}
$$

where $K_{k j i l}$ are covariant components of the curvature tensor of $M$, and equations of Codazzi and Ricci

$$
\begin{equation*}
\nabla_{k} h_{j i}-\nabla_{j} h_{k i}-l_{k} k_{j i}+l_{j} k_{k i}=0, \tag{1.15}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{k} k_{j i}-\nabla_{j} k_{k i}+l_{k} h_{j i}-l_{j} h_{k i}=0, \tag{1.16}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{j} l_{i}-\nabla_{i} l_{j}+h_{j l} k_{i}{ }^{t}-h_{i t} k_{j}{ }^{t}=0 \tag{1.17}
\end{equation*}
$$

## $\S 2$. The case in which $\boldsymbol{f}$ and $\boldsymbol{H}$ commute and $\boldsymbol{f}$ and $\boldsymbol{K}$ anticommute.

We suppose that $f$ and $H$ commute, i.e.,

$$
\begin{equation*}
f_{J}{ }^{t} h_{t}{ }^{h}-h_{J}{ }^{t} f_{t}^{h}=0, \tag{2.1}
\end{equation*}
$$

which is equivalent to

$$
\begin{equation*}
h_{j t} f_{\imath}^{t}+h_{i t} f_{j}^{t}=0 \tag{2.2}
\end{equation*}
$$

that is, $h_{j t} f_{l}$ is skew-symmetric. We suppose also that $f$ and $K$ anticommute, i.e.,

$$
\begin{equation*}
f_{J}{ }^{t} k_{t}{ }^{h}+k_{J}{ }^{t} f_{t}^{h}=0, \tag{2.3}
\end{equation*}
$$

which is equivalent to

$$
\begin{equation*}
k_{j t} f_{\imath}^{t}-k_{i t} f_{J}^{t}=0 \tag{2.4}
\end{equation*}
$$

that is, $k_{j t} f_{2}$ is symmetric. We first prove
Proposition 2.1. Let $X(M)$ be a submanifold of codimension 2 of $E$ such that (2.3) is satisfied and the function $\lambda$ is almost everywhere non-zero in $M$. Then

$$
\begin{equation*}
k_{t}^{t}=0 \tag{2.5}
\end{equation*}
$$

that is, the mean curvature vector is in the direction of $C$ if it does not vanish.
Proof. Transvecting (2.4) with $u^{j} v^{2}$, we find $\lambda\left(k_{j t} u^{j} u^{t}+k_{i v} v^{i} v^{t}\right)=0$, from which

$$
\begin{equation*}
k_{j i} w^{j} u^{2}+k_{j i} v^{j} v^{i}=0 . \tag{2.6}
\end{equation*}
$$

Transvecting next (2.4) with $f^{j i}$, we find $2 k_{j t}\left(-g^{t j}+u^{t} u^{j}+v^{t} v^{j}\right)=0$, which implies $k_{t}{ }^{t}=0$ by virtue of (2.6). But the mean curvature vector of $X(M)$ is given by

$$
\begin{equation*}
\frac{1}{2 n} g^{j i} \nabla_{\jmath} X_{\imath}=\frac{1}{2 n}\left(h_{t}{ }^{t} C+k_{t}{ }^{t} D\right)=\frac{1}{2 n} h_{t}{ }^{t} C \tag{2.7}
\end{equation*}
$$

and consequently, we see that the mean curvature vector is in the direction of $C$ if it does not vanish.

We next prove
Proposition 2.2. Let $X(M)$ be a submanifold of codimension 2 of $E$ such that (2.1) is satisfied and the function $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero in $M$. Then we have

$$
\left(1-\lambda^{2}\right) h_{j i} u^{2}=\left(h_{t s} u^{t} u^{s}\right) u_{j}
$$

$$
\begin{equation*}
\left(1-\lambda^{2}\right) h_{j i} v^{i}=\left(h_{t s} v^{t} v^{s}\right) v_{j} \tag{2.8}
\end{equation*}
$$

where $h_{t s} u^{t} u^{s}=h_{t s} v^{t} v^{s}$ and consequently, at every point at which $1-\lambda^{2} \neq 0$,

$$
\begin{equation*}
h_{j i} u^{2}=p u_{j}, \quad h_{j i} v^{i}=p v_{j}, \tag{2.9}
\end{equation*}
$$

p being given by

$$
p=\frac{h_{t s} u^{t} u^{s}}{1-\lambda^{2}}=\frac{h_{t s} v^{t} v^{s}}{1-\lambda^{2}}
$$

Proof. Transvecting (2.2) with $u^{j} u^{2}$, we find $\lambda\left(-h_{j t} u^{j} v^{t}-h_{i t} u^{i} v^{t}\right)=0$, from which

$$
\begin{equation*}
h_{j i} u^{j} v^{i}=0 . \tag{2.10}
\end{equation*}
$$

Transvecting (2.2) with $u^{j} v^{i}$, we obtain $\lambda\left(h_{j t} u^{j} u^{t}-h_{j i} v^{j} v^{t}\right)=0$, from which

$$
\begin{equation*}
h_{j i} u^{j} u^{i}=h_{j i} v^{j} v^{2} . \tag{2.11}
\end{equation*}
$$

Transvecting (2.2) with $f_{h}{ }^{j}$, we find

$$
h_{t s} f_{\imath}^{t} f_{h}^{s}+h_{i t}\left(-\delta_{h}^{t}+u_{h} u^{t}+v_{h} v^{t}\right)=0
$$

or equivalently

$$
\begin{equation*}
h_{t s} f_{\imath}^{t} f_{h}^{s}-h_{i h}+\left(h_{i t} u^{t}\right) u_{h}+\left(h_{i t} v^{t}\right) v_{h}=0, \tag{2.12}
\end{equation*}
$$

from which, taking the skew-symmetric part,

$$
\left(h_{i t} u^{t}\right) u_{h}-\left(h_{h t} u^{t}\right) u_{i}+\left(h_{i t} v^{t}\right) v_{h}-\left(h_{h t} v^{t}\right) v_{i}=0 .
$$

Transvecting this with $u^{h}$, we find

$$
\left(1-\lambda^{2}\right) h_{i t} u^{t}=\left(h_{t s} u^{t} u^{s}\right) u_{i}+\left(h_{t s} u^{t} v^{s}\right) v_{i},
$$

from which, using (2.10),

$$
\left(1-\lambda^{2}\right) h_{i t} u^{t}=\left(h_{t s} u^{t} u^{s}\right) u_{i} .
$$

Similarly, we can get

$$
\left(1-\lambda^{2}\right) h_{i t} v^{t}=\left(h_{t s} v^{t} v^{s}\right) v_{i}
$$

Thus we have (2.9). Consequently, Proposition 2.2 is proved.
From (2. 9), (2.11) and (2.12), we have

$$
\begin{equation*}
h_{i h}=h_{t s} f_{l}^{t} f_{h}^{s}+p\left(u_{i} u_{h}+v_{i} v_{h}\right) . \tag{2.13}
\end{equation*}
$$

We also have
Proposition 2.3. Let $X(M)$ be a submanifold of codimension 2 of $E$ such that (2.3) is satisfied and the function $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero in $M$. Then

$$
\begin{equation*}
\left(1-\lambda^{2}\right) k_{j i} u^{i}=\left(k_{t s} u^{t} u^{s}\right) u_{j}+\left(k_{t s} u^{t} v^{s}\right) v_{j}, \tag{2.14}
\end{equation*}
$$

$$
\left(1-\lambda^{2}\right) k_{j i} v^{i}=\left(k_{t s} u^{t} v^{s}\right) u_{j}+\left(k_{t s} v^{t} v^{s}\right) v_{j}
$$

where $k_{t s} u^{t} u^{s}+k_{t s} v^{t} v^{s}=0$, and consequently, at every point at which $1-\lambda^{2} \neq 0$, we have

$$
\begin{equation*}
k_{j i} u^{i}=\alpha u_{j}+\beta v_{j}, \quad k_{j i} v^{i}=\beta u_{j}-\alpha v_{j}, \tag{2.15}
\end{equation*}
$$

$\alpha$ and $\beta$ being given respectively by

$$
\alpha=\frac{k_{t s s} u^{t} u^{s}}{1-\lambda^{2}}=-\frac{k_{t s} v^{t} v^{s}}{1-\lambda^{2}}, \quad \beta=\frac{k_{t s} u^{t} v^{s}}{1-\lambda^{2}} .
$$

Proof. Transvecting (2.4) with $u^{j} v^{i}$, we find $\lambda\left(k_{j t} u^{j} u^{t}+k_{i t} v^{i} v^{t}\right)=0$, from which $k_{j i} u^{j} u^{i}+k_{j i} v^{\nu} v^{2}=0$. Transvecting (2.4) with $f_{h}^{j}$, we find

$$
k_{t s} f_{\imath}^{t} f_{h}^{s}-k_{i l}\left(-\delta_{h}^{t}+u_{h} u^{t}+v_{h} v^{t}\right)=0
$$

or equivalently

$$
\begin{equation*}
k_{t s} f_{\imath}^{t} f_{h}^{s}+k_{i h}-\left(k_{i t} u^{t}\right) u_{h}-\left(k_{i t} v^{t}\right) v_{h}=0, \tag{2.16}
\end{equation*}
$$

from which, taking the skew-symmetric part,

$$
\left(k_{i t} u u^{t}\right) u_{h}-\left(k_{h t} u^{t}\right) u_{i}+\left(k_{i t} v^{t}\right) v_{h}-\left(k_{h t} v^{t}\right) v_{i}=0 .
$$

Transvecting this with $u^{h}$, we find

$$
\left(1-\lambda^{2}\right) k_{i t} u^{t}=\left(k_{t s} u^{t} u^{s}\right) u_{i}+\left(k_{t s} u^{t} v^{s}\right) v_{i}
$$

Similarly we can get

$$
\left(1-\lambda^{2}\right) k_{i t} v^{t}=\left(k_{t s} u^{t} v^{s}\right) u_{i}+\left(k_{t s} v^{t} v^{s}\right) v_{i} .
$$

Thus, taking account of $k_{j i} u^{j} u^{2}+k_{j i} v^{v} v^{2}=0$, we get (2.15). Consequently, Proposition 2.3 is proved.

From (2.14) and (2.16), we have

$$
\begin{equation*}
k_{i h}=-k_{t s} f_{i}{ }^{t} f_{h}^{s}+\alpha\left(u_{i} u_{h}-v_{i} v_{h}\right)+\beta\left(u_{i} v_{h}+u_{h} v_{i}\right) . \tag{2.17}
\end{equation*}
$$

We next prove
Proposition 2.4. Let $X(M)$ be a submanifold of codimension 2 of $E$ such that the global unit normals $C$ and $D$ are parallel in the normal bundle. Assume that (2.1) and (2.3) are satisfied and the function $\lambda\left(1-\lambda^{2}\right)$ is almost everywhere non-zero in $M$. Then

$$
\begin{equation*}
h_{t}{ }^{t}=\text { constant }, \tag{2.18}
\end{equation*}
$$

that is, the mean curvature of $X(M)$ is constant.
Proof. Since $C$ and $D$ are parallel in the normal bundle, the third fundamental tensor $l_{3}$ vanishes identically. Then, differentiating the first equation of (2.9) covariantly, we find, by using (1.9) with $l_{j}=0$,

$$
\begin{equation*}
\left(\nabla_{j} h_{i}{ }^{t}\right) u_{t}+h_{i}{ }^{t}\left(-h_{j s} f_{i}^{s}-\lambda k_{j t}\right)=\left(\nabla_{j} p\right) u_{i}+p\left(-h_{j t} f_{i}^{t}-\lambda k_{j i}\right), \tag{2.19}
\end{equation*}
$$

from which, using equation (1.15) of Codazzi with $l_{\jmath}=0$, we have

$$
\begin{equation*}
2 h_{j}^{t} h_{i}^{s} f_{t s}=\left(\nabla_{j} p\right) u_{i}-\left(\nabla_{\imath} p\right) u_{j}-2 p h_{j t} f_{\imath}^{t} . \tag{2.20}
\end{equation*}
$$

Transvecting this with $u^{i}$, we find $\left(1-\lambda^{2}\right) \nabla_{j} p=\left(u^{i} \nabla_{\imath} p\right) u_{j}$. In the same way, we can prove, from the second equation of (2.9), $\left(1-\lambda^{2}\right) \nabla_{j} p=\left(v^{i} \nabla_{2} p\right) v_{j}$. The last two equations imply that $\nabla_{3} p=0$, from which we have

$$
\begin{equation*}
p=\text { const. } \tag{2.21}
\end{equation*}
$$

Thus (2.20) becomes $h_{\jmath}{ }^{t} h_{i}{ }^{s} f_{s t}=p h_{j t} f_{\imath}^{t}$, or $h_{\jmath}{ }^{t} h_{t}{ }^{s} f_{l s}=p h_{j t} f_{\imath}^{t}$, from which, transvecting
with $f_{h}{ }^{i}$, we find

$$
h_{j} h_{t} h^{s}\left(-g_{s h}+u_{s} u_{h}+v_{s} v_{h}\right)=p h_{j t}\left(-\delta_{h}^{t}+u_{h} u^{t}+v_{h} v^{t}\right) .
$$

Therefore, using (2.9), we have

$$
\begin{equation*}
h_{j t} h_{h}{ }^{t}=p h_{j h}, \quad \text { or } \quad h_{t}{ }^{h} h_{i}^{t}=p h_{i}^{h} . \tag{2.22}
\end{equation*}
$$

Denote by $\rho$ an eigenvalue of $h_{i}{ }^{h}$ and by $w^{h}$ the corresponding eigenvector. Then we have $h_{i}{ }^{t} w^{2}=\rho w^{t}$, from which, applying $h_{t}{ }^{h}$ and using (2.22), $p h_{i}{ }^{h} w^{2}=\rho h_{t}{ }^{h} w^{t}$, $p \rho=\rho^{2}$, that is,

$$
\begin{equation*}
\rho=0 \quad \text { or } \quad \rho=p . \tag{2.23}
\end{equation*}
$$

Thus the second fundamental tensor $h_{i}{ }^{h}$ has only two constant eigenvalues. Let $m$ be the multiplicity of the eigenvalue $p, p$ being assumed to be non-zero, then $m$ is constant, and we have

$$
\begin{equation*}
h_{t}{ }^{t}=m p, \tag{2.24}
\end{equation*}
$$

which is a constant. But the mean curvature is given by

$$
\frac{1}{2 n} h_{t}^{t}=\frac{1}{2 n} m p
$$

and consequently is a constant too. Therefore Proposition 2.4 is proved.
We can prove
Proposition 2.5. Under the same assumptions as stated in Proposition 2.4, we have

$$
\begin{equation*}
\nabla_{k} h_{j i}=0 . \tag{2.25}
\end{equation*}
$$

Proof. Differentiating (2.22) covariantly, we find

$$
\begin{equation*}
\left(\nabla_{k} h_{j t}\right) h_{h}{ }^{t}+\left(\nabla_{k} h_{h}{ }^{t}\right) h_{j t}=p \nabla_{k} h_{j h} . \tag{2.26}
\end{equation*}
$$

Thus, using $\nabla_{k} h_{j h}=\nabla_{j} h_{k h}$, which is a direct consequence of (1.15) with $l_{J}=0$, we have from (2.26)

$$
\left(\nabla_{k} h_{h}{ }^{t}\right) h_{j t}-\left(\nabla_{j} h_{h}{ }^{t}\right) h_{k t}=0,
$$

and, interchanging the indices $h$ and $k$,

$$
\begin{equation*}
\left(\nabla_{h} h_{k}{ }^{t}\right) h_{j t}-\left(\nabla_{j} h_{k}{ }^{t}\right) h_{h t}=0 . \tag{2.27}
\end{equation*}
$$

Adding (2.26) and (2.27), we find

$$
\begin{equation*}
2\left(\nabla_{k} h_{h}{ }^{t}\right) h_{j t}=p \nabla_{k} h_{j h} . \tag{2.28}
\end{equation*}
$$

Transvecting (2.28) with $h_{l}{ }^{3}$ and using (2.22), we have

$$
h_{l}^{t}\left(\nabla_{k} h_{n t}\right)=0 .
$$

Thus, (2.28) implies that

$$
\begin{equation*}
p \nabla_{k} h_{j h}=0 . \tag{2.29}
\end{equation*}
$$

Since $p$ is constant, (2.29) implies that $\nabla_{k} h_{j i}=0$, if $p \neq 0$. On the other hand, from (2.22), we have $h_{j i} h^{j i}=p h_{t}{ }^{t}$. Thus, if $p=0$, we have $h_{j i}=0$ and hence $\nabla_{k} h_{j i}=0$. Therefore, in any case, we have $\nabla_{k} h_{j i}=0$. This completes the proof of the proposition.

We are now going to prove formulas (2.39) and (2.40) which will be useful in the sequel. Substituting (2.9) and (2.15) into (1.11), we have

$$
\begin{equation*}
\nabla_{i} \lambda=\alpha u_{i}+(\beta-p) v_{i} . \tag{2.30}
\end{equation*}
$$

Differentiating (2.30) covariantly, we find

$$
\nabla_{j} \nabla_{i} \lambda=\left(\nabla_{j} \alpha\right) u_{i}+\alpha \nabla_{j} u_{i}+\left(\nabla_{j} \beta\right) v_{i}+(\beta-p) \nabla_{j} v_{i},
$$

and, hence, using (1.9) and (1.10),

$$
\begin{equation*}
\nabla_{j} \nabla_{i} \lambda=\left(\nabla_{j} \alpha\right) u_{i}+\alpha\left(-h_{j t} f_{\imath}^{t}-\lambda k_{j i}\right)+\left(\nabla_{j} \beta\right) v_{i}+(\beta-p)\left(-k_{j t} f_{\imath}^{t}+\lambda h_{j i}\right), \tag{2.31}
\end{equation*}
$$

from which, taking the skew-symmetric part,

$$
\begin{equation*}
0=\left(\nabla_{j} \alpha\right) u_{i}-\left(\nabla_{i} \alpha\right) u_{j}-2 \alpha h_{j t} f_{i}^{t}+\left(\nabla_{j} \beta\right) v_{i}-\left(\nabla_{i} \beta\right) v_{j} . \tag{2.32}
\end{equation*}
$$

Transvecting (2.32) with $u^{2}$, we find

$$
\begin{equation*}
\left(1-\lambda^{2}\right)\left(\nabla_{j} \alpha\right)=\left(u^{t} \nabla_{t} \alpha\right) u_{j}+\left(u^{t} \nabla_{t} \beta-2 \alpha \lambda p\right) v_{j} . \tag{2.33}
\end{equation*}
$$

Transvecting (2.32) with $v^{2}$, we find

$$
\begin{equation*}
\left(1-\lambda^{2}\right)\left(\nabla_{j} \beta\right)=\left(v^{t} \nabla_{t} \alpha+2 \alpha \lambda p\right) u_{j}+\left(v^{t} \nabla_{t} \beta\right) v_{j} . \tag{2.34}
\end{equation*}
$$

Multiplying (2.32) by $1-\lambda^{2}$ and subsituting (2.33) and (2.34) in the equation obtained, we find

$$
\begin{equation*}
2 \alpha\left(1-\lambda^{2}\right) h_{j t} f_{\imath}^{t}=-\left(u^{t} \nabla_{t} \beta-v^{t} \nabla_{t} \alpha-4 \alpha \lambda p\right)\left(u_{j} v_{i}-u_{i} v_{j}\right) \tag{2.35}
\end{equation*}
$$

from which, transvecting with $u^{2},-2 \alpha \lambda p=u^{t} \nabla_{t} \beta-v^{t} \nabla_{t} \alpha-4 \alpha \lambda p$, or equivalently

$$
\begin{equation*}
u^{t} \nabla_{t} \beta-v^{t} \nabla_{t} \alpha=2 \alpha \lambda p \tag{2.36}
\end{equation*}
$$

Thus (2.35) becomes

$$
\begin{equation*}
\alpha\left(1-\lambda^{2}\right) h_{j l} f_{i}^{t}=\alpha \lambda p\left(u_{j} v_{i}-u_{i} v_{j}\right), \tag{2.37}
\end{equation*}
$$

from which, transvecting with $f_{h}{ }^{2}, \alpha\left(1-\lambda^{2}\right) h_{j t}\left(-\delta_{h}^{t}+u_{h} u^{t}+v_{h} v^{t}\right)=-\alpha \lambda^{2} p\left(u_{j} u_{h}+v_{j} v_{h}\right)$,
or equivalently

$$
\begin{equation*}
\alpha\left(1-\lambda^{2}\right) h_{j h}=\alpha p\left(u_{j} u_{h}+v_{j} v_{h}\right) \tag{2.38}
\end{equation*}
$$

Transvecting (2.38) with $g^{\jmath^{h}}$, we find $\alpha\left(1-\lambda^{2}\right) h_{t}{ }^{t}=2 \alpha p\left(1-\lambda^{2}\right)$, from which, using (2. 24),

$$
\begin{equation*}
\alpha(m-2) p=0 . \tag{2.39}
\end{equation*}
$$

Thus, since $m$ and $p$ are constant, we have

$$
\begin{equation*}
(m-2) p=0 \quad \text { or } \quad \alpha=0 . \tag{2.40}
\end{equation*}
$$

We shall consider three cases, that is, Case I where $m \neq 2, p \neq 0$, Case II where $m=2$ and Case III where $p=0$. These cases with some additional assumptions will be discussed in $\S 3$.

In the next step, we prove
Proposition 2.6. Under the same assumptions as stated in Proposition 2.4, we have

$$
\begin{equation*}
\left(1-\lambda^{2}\right)\left(k_{j}{ }^{t} k_{t i}+\beta h_{j i}\right)=\left[\alpha^{2}+\beta(\beta+p)\right]\left(u_{j} u_{i}+v_{j} v_{i}\right) . \tag{2.41}
\end{equation*}
$$

Proof. Differentiating the second equation of (2.15) covariantly, we find

$$
\begin{aligned}
& \left(\nabla_{j} k_{i}^{t}\right) v_{t}+k_{i}^{t}\left(-k_{j s} f_{t}^{s}+\lambda h_{j t}\right) \\
= & \left(\nabla_{j} \beta\right) u_{i}+\beta\left(-h_{j t} f_{i}^{t}-\lambda k_{j i}\right)-\left(\nabla_{j} \alpha\right) v_{i}-\alpha\left(-k_{j t} f_{v}^{t}+\lambda h_{j i}\right) .
\end{aligned}
$$

Taking the skew-symmetric part and using $\nabla_{k} k_{j i}=\nabla_{j} k_{k i}$, which is a direct consequence of (1.16) with $l_{J}=0$, we find

$$
2 k_{j}^{t} k_{i}{ }^{s} f_{t s}=\left(\nabla_{j} \beta\right) u_{i}-\left(\nabla_{i} \beta\right) u_{j}-\left(\nabla_{j} \alpha\right) v_{i}+\left(\nabla_{i} \alpha\right) v_{j}-2 \beta h_{j t} f_{i}^{t} .
$$

Multiplying this equation by $1-\lambda^{2}$ and substituting (2.33) and (2.34) into the equation obtained, we find

$$
2\left(1-\lambda^{2}\right) k_{j}{ }^{t} k_{i}{ }^{s} f_{t s}=-\left(u^{t} V_{t} \alpha+v^{t} V_{t} \beta\right)\left(u_{j} v_{i}-u_{i} v_{j}\right)-2\left(1-\lambda^{2}\right) \beta h_{j t} f_{i}^{t},
$$

or equivalently

$$
\begin{equation*}
2\left(1-\lambda^{2}\right) k_{j}^{t} k_{t}^{s} f_{i s}=-\left(u^{t} \nabla_{t} \alpha+v^{t} \nabla_{t} \beta\right)\left(u_{j} v_{i}-u_{i} v_{j}\right)-2\left(1-\lambda^{2}\right) \beta h_{j t} f_{2}^{t} \tag{2.42}
\end{equation*}
$$

from which, transvecting with $u^{j} v^{i}$ and using (2.9) and (2.15),

$$
\begin{equation*}
u^{t} \nabla_{t} \alpha+v^{t} \nabla_{t} \beta=-2 \lambda\left[\alpha^{2}+\beta(\beta+p)\right] . \tag{2.43}
\end{equation*}
$$

Thus (2.42) becomes

$$
\left(1-\lambda^{2}\right) k_{J}{ }^{t} k_{t}{ }^{s} f_{i s}=\lambda\left[\alpha^{2}+\beta(\beta+p)\right]\left(u_{j} v_{i}-u_{i} v_{j}\right)-\left(1-\lambda^{2}\right) \beta h_{j t} f_{i}^{t} .
$$

Transvecting this with $f_{n}{ }^{2}$, we find
$\left(1-\lambda^{2}\right) k_{j}{ }^{t} k_{t}{ }^{s}\left(-g_{s h}+u_{s} u_{h}+v_{s} v_{h}\right)=-\lambda^{2}\left[\alpha^{2}+\beta(\beta+p)\right]\left(u_{j} u_{h}+v_{j} v_{h}\right)-\left(1-\lambda^{2}\right) \beta h_{j t}\left(-\partial_{h}^{t}+u_{h} u^{t}+v_{h} v^{t}\right)$,
from which, using (2.9) and (2.15),

$$
\left(1-\lambda^{2}\right)\left(k_{j}{ }^{t} k_{t h}+\beta h_{j n}\right)=-\left[\alpha^{2}+\beta(\beta+p)\right]\left(u_{j} u_{h}+v_{j} v_{h}\right),
$$

which proves proposition 2.6.
We have, from equation (1.14) of Gauss,

$$
\begin{equation*}
K_{j i}=h_{t}{ }^{t} h_{j i}-h_{j t} h_{i}{ }^{t}-k_{j t} k_{i}{ }^{t}, \tag{2.44}
\end{equation*}
$$

from which, using (2.22),

$$
\begin{equation*}
K_{j i}=\left(h_{t}{ }^{t}-p\right) h_{j i}-k_{j t} k_{i}{ }^{t} . \tag{2.45}
\end{equation*}
$$

From (2.41) and (2.45), we find

$$
\begin{equation*}
\left(1-\lambda^{2}\right) K_{j i}=\left(1-\lambda^{2}\right)\left(h_{t} t-p+\beta\right) h_{j i}-\left[\alpha^{2}+\beta(\beta+p)\right]\left(u_{j} u_{i}+v_{j} v_{i}\right), \tag{2.46}
\end{equation*}
$$

from which, transvecting with $g^{j i}$,

$$
\begin{equation*}
g^{j i} K_{j i}=\left(h_{t}{ }^{t}-p+\beta\right) h_{s}^{s}-2\left[\alpha^{2}+\beta(\beta+p)\right], \tag{2.47}
\end{equation*}
$$

which gives the scalar curvature of $M$.

## § 3. Complete submanifolds with constant scalar curvature.

We assume, here and in the sequel, that the submanifold $M$ is complete and the scalar curvature $g^{j i} K_{j i}$ of $M$ is constant. We have mentioned in $\S 2$ three Cases I, II and III. First we consider Case I where $m \neq 2$ and $p \neq 0$. We find $\alpha=0$ from (2.39) with ( $m-2$ ) $p \neq 0$. The scalar curvature $g^{j i} K_{j i}$ being constant, we see from (2.47) that $\beta$ is constant. Thus (2.43) implies $\lambda \beta(\beta+p)=0$, that is,

$$
\begin{equation*}
\beta=0 \quad \text { or } \quad \beta=-p . \tag{3.1}
\end{equation*}
$$

Then (2.41) becomes

$$
\begin{equation*}
k_{j t} k_{i}^{t}=-\beta h_{j i}, \tag{3.2}
\end{equation*}
$$

because $\alpha=0$ and $\beta(\beta+p)=0$. Differentiating (3.2) covariantly and taking account of (2.25), we find

$$
\begin{equation*}
\left(\nabla_{k} k_{j t}\right) k_{i}^{t}+k_{j t}\left(\nabla_{k} k_{i}{ }^{t}\right)=0, \tag{3.3}
\end{equation*}
$$

from which, using equation (1.16) of Codazzi with $l_{j}=0 . k_{j t}\left(\nabla_{k} k_{i}{ }^{t}\right)-k_{k t}\left(\nabla_{j} k_{i}{ }^{t}\right)=0$, or equivalently

$$
\begin{equation*}
k_{j t}\left(\nabla_{i} k_{k}{ }^{t}\right)-k_{i t}\left(\nabla_{j} k_{k}{ }^{t}\right)=0 . \tag{3.4}
\end{equation*}
$$

Adding (3.3) and (3.4), we have $k_{j t}\left(\nabla_{k} k_{i}{ }^{t}\right)=0$. Transvecting this with $k_{h}{ }^{j}$ and
using (3.2), we obtain

$$
\begin{equation*}
\beta h_{h}{ }^{t}\left(\nabla_{k} k_{i t}\right)=0 . \tag{3.5}
\end{equation*}
$$

Since $\beta$ is constant, (3.5) implies $h_{h}{ }^{t}\left(\nabla_{k} k_{i t}\right)=0$ if $\beta \neq 0$. On the other hand, taking account of (3.2), we have trivially $h_{h}{ }^{t}\left(\nabla_{k} k_{i t}\right)=0$ if $\beta=0$. Therefore, in any case, we have

$$
\begin{equation*}
h_{h}{ }^{t}\left(\nabla_{k} k_{i t}\right)=0 . \tag{3.6}
\end{equation*}
$$

We see, from (1.17) with $l_{j}=0$, that $h_{i}{ }^{h}$ and $k_{i}{ }^{h}$ are commutative, that is, $h_{t}{ }^{i} k_{J}{ }^{t}-k_{t}{ }^{i} h_{\jmath}{ }^{t}=0$. Thus, using (2.5), (2.22) and (3.2), we see that the second fundamental tensors $h_{i}{ }^{h}$ and $k_{i}{ }^{h}$ have at each point of $M$ respectively the forms

$$
\left(h_{3}{ }^{h}\right)=\left(\begin{array}{cccc}
p & & \vdots &  \tag{3.7}\\
& p & & \vdots \\
& \ddots & \vdots \\
& & p & \vdots \\
\ldots \ldots \ldots \ldots \ldots \ldots \ldots \\
& 0 & & \vdots \\
& & & 0
\end{array}\right),
$$

with respect to a suitable orthonormal frame, because of (3.1), where $q=p$ if $\beta=-p$ and $q=0$ if $\beta=0$. Thus, we can choose in any coordinate neighborhood of $M$, since $\operatorname{dim} M=2 n$, a field of frames $\left\{e_{(1)}, e_{(2)}, \cdots, e_{(2 n)}\right\}$ such that

$$
\begin{array}{ll}
{h_{i}{ }^{h} e^{2}{ }_{(r)}=p e^{h}{ }_{(r)},}(\gamma=1,2, \cdots, m), \\
{k_{i}{ }^{h} e^{2}{ }_{(\mu)}=q e^{h}{ }_{(\mu)},} \quad(\mu=1,2, \cdots, m / 2),  \tag{3.8}\\
{k_{i}{ }^{h} e^{2}{ }_{(\nu)}=-q e^{h}{ }_{(\nu)},}^{(\nu=m / 2+1, \cdots, m) .}
\end{array}
$$

If we denote by $\mathscr{D}$ the distribution spanned by $e_{(1)}, e_{(2)}, \cdots$, and $e_{(m)}$, then $\mathscr{D}$ is a global dirtribution because $p \neq 0$. We denote by $\overline{\mathcal{D}}$ the orthogonal complement of $\mathscr{D}$. The distribution $\overline{\operatorname{D}}$ is locally spanned by $e_{(m+1)}, \cdots, e_{(2 n)}$. Since $\nabla_{k} h_{j}{ }^{h}=0$ and $p \neq 0$, the distribution $\mathscr{D}$ is integrable and the integral manifolds of $\mathscr{D}$ are totally geodesic in $M$. Thus $\overline{\mathscr{D}}$ is also integrable and the integral manifolds of $\overline{\mathscr{D}}$ are totally geodesic in $M$.

If we denote by $\bar{V}$ an arbitrary maximal integral submanifold of $\overline{\mathscr{D}}$, then we see, taking account of (3.7), that $\bar{V}$ is totally geodesic in $E^{2 n+2}$. On the other hand, $\bar{V}$ is complete because $\bar{V}$ is totally geodesic in $M$ which is complete. Thus, $\bar{V}$ is a plane $E^{2 n-m}$ in $E^{2 n+2}$.

Let $V$ be the maximal integral submanifold of $\mathscr{D}$ passing through a point P of $M$. Then we see that $V$ is complete and lies on an ( $m+2$ )-dimensional plane $E^{m+2}$ which is orthogonal to $\bar{V}$ passing through P , where $\bar{V}$ is a ( $2 n-m$ )-dimen-
sional plane $E^{2 n-m}$. Hence, taking account of (3.7), we see that the submanifold $V$, which is immersed in $E^{m+2}$, has the second fundamental tensors $\bar{h}_{b}{ }^{a}$ and $\bar{k}_{b}{ }^{a}$ of the forms
with respect to the local frame $\left\{e_{(1)}, e_{(2)}, \cdots, e_{(m)}\right\}$ and the unit normals $C$ and $D$, where $C$ and $D$ are contained in $E^{m+2}$ along $V$, the indices $a, b, c, \cdots$ running over the range $\{1,2, \cdots, m\}$.

According to (3.1), we first consider the case where $\beta=-p$, which implies $q=p$. If we take account of (3.6), we see that the distributions $\Delta^{+}$spanned by $\left\{e_{(1)}, e_{(2)}, \cdots, e_{(m / 2)}\right\}$ and $\Delta^{-}$spanned by $\left\{e_{(m / 2+1)}, \cdots, e_{(m)}\right\}$ are both parallel along $V$. Consequently, since $V$ is complete, we can easily verify the following fact: the submanifold $V$ is congruent in $E^{m+2}$ to the submanifold $S^{m / 2}(1 / \sqrt{2 \mid} p \mid) \times S^{m / 2}(1 / \sqrt{2}|p|)$, which is natually imbedded in $E^{m+2}$ (cf. Yano and Ishihara [4]). Next, we consider the case where $\beta=0$, which implies $q=0$, then we see, using (3.9) with $q=0$, that $V$ is totally umbilical in $E^{m+2}$ and complete. Thus, in this case, $V$ is congruent to $S^{m}(1 /|p|)$ in $E^{m+2}$, which is natually imbedded in $E^{m+2}$.

Summing up the arguments developed above, we can conclude that in Case I, the submanifold $M$ is congruent in $E^{2 n+2}$ to $S^{m}(r) \times E^{2 n-m}$ or $S^{m / 2}(r) \times S^{m / 2}(r) \times E^{2 n-m}$, $r$ being a positive number, which is natually imbedded in $E^{2 n+2}$, where $S^{k}(r)$ denotes a $k$-dimensional sphere of radius $r$.

In the next step, we consider Case II where $m=2$. In this case we see that $p \neq 0$. From (2.24), we find that

$$
\begin{equation*}
h_{t}^{t}=2 p \tag{3.10}
\end{equation*}
$$

which implies that

$$
\begin{equation*}
\left(1-\lambda^{2}\right) h_{j i}=p\left(u_{j} u_{i}+v_{j} v_{i}\right), \tag{3.11}
\end{equation*}
$$

by virtue of (2.9). Taking account of (3.10), we have, from (2.46),

$$
\begin{equation*}
g^{j i} K_{j i}=2\left(p^{2}-\alpha^{2}-\beta^{2}\right) . \tag{3.12}
\end{equation*}
$$

Substituting (3.11) into (2.41) and using $p \neq 0$, we find

$$
\begin{equation*}
k_{J}^{t} k_{t i}=\frac{1}{p}\left(\alpha^{2}+\beta^{2}\right) h_{j i} \tag{3.13}
\end{equation*}
$$

In Case I, we found that (3.2) with $\beta=$ const. implies (3.6). The scalar curvature $g^{j i} K_{j i}$ being constant, we see from (3.12) that $\alpha^{2}+\beta^{2}$ is constant. Thus, in
the same way as developed in Case I, we can prove that (3.13) implies $h_{h}{ }^{t}\left(\nabla_{k} k_{i t}\right)=0$.
Since $h_{i}{ }^{h}$ and $k_{i}{ }^{h}$ are commutative, using (2.5), (2.22) and (3.13), we see that the second fundamental tensors $h_{i}{ }^{h}$ and $k_{i}{ }^{h}$ have at each point of $M$ the form

with respect to a suitable orthonormal frame, where $q=\sqrt{\alpha^{2}+\beta^{2}}$ is constant. Thus we can choose in any coordinate neighborhood of $M$, where $\operatorname{dim} M=2 n$, a field of frames $\left\{e_{(1)}, e_{(2)}, \cdots, e_{(2 n)}\right\}$ such that

$$
\begin{array}{ll}
h_{i}{ }^{h} e_{(1)}=p e_{(1)}^{h}, & h_{i}{ }^{h} e_{(2)}^{2}=p e_{(2)}^{h}, \\
k_{i}{ }^{h} e^{2}{ }_{(1)}=q e^{h}{ }_{(1)}, & k_{i}{ }^{h} e_{(2)}^{2}=-q e_{(2)}^{h} . \tag{3.15}
\end{array}
$$

As in Case I, by using $h_{h}{ }^{t}\left(\nabla_{k} k_{i t}\right)=0$, (3.13), (3.14) and (3.15), we can prove that, when $q=0$, the submanifold $M$ is congruent in $E^{2 n+2}$ to $S^{2}(1 /|p|) \times E^{2 n-2}$, and when $q \neq 0$, to $S^{1}(1 / \sqrt{2} q) \times S^{1}(1 / \sqrt{2} q) \times E^{2 n-2}$. Therefore, we can conclude that in Case II, the submanifold $M$ is congruent to $S^{2}(r) \times E^{2 n-2}$ or $S^{1}(r) \times S^{1}(r) \times E^{2 n-2}, r$ being a positive number, which is naturally imbedded in $E^{2 n+2}$.

Finally, we consider Case III where $p=0$. In this case (2.22) implies $h_{j i}=0$. Thus, the submanifold $M$ lies on hypersurface $E^{2 n+1}$ of $E^{2 n+2}$. Taking account of $h_{j i}=0$ and $l_{j}=0$, we can write (2.41) and (2.46) as

$$
\begin{gather*}
\left(1-\lambda^{2}\right) k_{j}{ }^{t} k_{t i}=\left(\alpha^{2}+\beta^{2}\right)\left(u_{j} u_{i}+v_{j} v_{i}\right),  \tag{3.16}\\
g^{j i} K_{j i}=-2\left(\alpha^{2}+\beta^{2}\right), \tag{3.17}
\end{gather*}
$$

respectively, where $\alpha^{2}+\beta^{2}$ is constant because of $g^{j i} K_{j i}=$ const. The tensor $k_{i}{ }^{h}$ is the second fundamental tensor of $M$ immersed in the hypersurface $E^{2 n+1}$ with respect to the normal $D$. We now suppose that $\alpha^{2}+\beta^{2} \neq 0$ and restrict ourselves to the open set $M_{0}(\subset M)$ where $1-\lambda^{2} \neq 0$. Then, taking account of (2.5) and (3.16), we see that $k_{i}{ }^{h}$ has at each point of $M_{0}$ the form

$$
\left(k_{i}{ }^{h}\right)=\left(\begin{array}{cc:c}
q & 0 & \vdots  \tag{3.18}\\
0 & -q & 0 \\
\ldots \ldots \ldots \ldots \ldots \ldots \ldots . & \ldots \ldots \ldots \\
0 & & 0
\end{array}\right), \quad q=\sqrt{\alpha^{2}+\beta^{2}}
$$

with respect to a suitable orthonormal frame. Therefore we can choose in any
coordinate neighborhood of $M_{0}$ a field of frames $\left\{e_{(1)}, e_{(2)}, \cdots, e_{(2 n)}\right\}$, with respect to which (3.8) holds, where $e_{(1)}$ and $e_{(2)}$ are linear combinations of $u^{h}$ and $v^{h}$. On the other hand, we can easily see, by using (1.9) and (1.10) with $h_{j i}=0$ and $l_{J}=0$, that the distribution spanned in $M_{0}$ by $u^{h}$ and $v^{h}$ is integrable and totally geodesic in $M_{0}$. Thus, the distribution spanned in $M_{0}$ by $e_{(1)}$ and $e_{(2)}$ is also integrable and its integral manifolds are totally geodesic in $M_{0}$. Therefore, according to the same arguments developed in discussing the Cases I and II, we can conclude the fact: In Case III, the open submanifold $M_{0}$ is locally isometric to $S^{1}(r) \times S^{1}(r) \times E^{2 n-2}$, which is locally flat. Thus the scalar curvature $g^{j i} K_{j i}$ of $M$ vanishes identically in $M_{0}$ and hence in $M$ because of the continuity of $g^{j i} K_{j i}$. Since $g^{j i} K_{j i}=0$ in $M$, (3.17) implies $\alpha^{2}+\beta^{2}=0$, which contradicts the assumption that $\alpha^{2}+\beta^{2} \neq 0$. Consequently, we see that $\alpha^{2}+\beta^{2}=0$ in Case III. Therefore we find, from (3.16), that $k_{j i}=0$ holds identically in $M$. Thus, $M$ is totally geodesic in the hyperplane $E^{2 n+1}$ and consequently is congruent to a plane $E^{2 n}\left(\subset E^{2 n+1} \subset E^{2 n+2}\right)$.

Summing up the conclusions obtained in Cases I, II and III, we have
Theorem 3.1. Let $M$ be a complete submanifold of codimension 2 in an evendimensional Euclidean space $E^{2 n+2}$ such that the scalar curvature of $M$ is constant and there are global unit normals $C$ and $D$ to $M$ which are parallel in the normal bundle. If $f H=H f$ and $f K=-K f$ hold, where $H$ and $K$ are the second fundamental tensors of $M$ respectively with respect to $C$ and $D, f$ being the tensor field of type $(1,1)$ appearing in the induced structure $(f, g, u, v, \lambda)$ of $M$, then $M$ is in $E^{2 n+2}$, provided that $\lambda\left(1-\lambda^{2}\right)$ is non-zero almost everywhere in $M$, congruent to one of the following submanifolds:

$$
\begin{array}{ll}
E^{2 n}, S^{2 n}(r), S^{n}(r) \times S^{n}(r), S^{l}(r) \times E^{2 n-l} & (l=1,2, \cdots, 2 n-1), \\
S^{k}(r) \times S^{k}(r) \times E^{2 n-2 k} & (k=1,2, \cdots, n-1),
\end{array}
$$

where $S^{k}(r)$ denotes a $k$-dimensional sphere of radius $r(>0)$ imbedded natrually in $E^{2 n+2}$.

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