# THE PROJECTIVE TRANSFORMATION ON A SPACE WITH PARALLEL RICCI TENSOR 

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## Introduction.

Recently we have proved [2] that a complete connected Riemannian space $M, 2<\operatorname{dim} M$, with parallel Ricci tensor does not admit a non-isometric conformal transformation, unless $M$ is isometric either to the Euclidean space or to the sphere. An analogous fact is true for a projective transformation, as the following main theorem of this paper shows.

Theorem 1. Let $g$ and $\hat{g}$ be two complete Riemannian metrics on a connected manifold $M$ with dimension $>1$ whose Ricci tensors $R$ and $R^{\prime}$ are parallel. If $g$ and $\hat{g}$ are projectively related, then 1) Levi-Civita connections of $g$ and $\hat{g}$ coincide, or 2) $g$ and $\hat{g}$ are of positive constant curvature.

On the other hand Tanaka [5] studied projective transformations of affine connections. To describe his theorem we explain some terminologies. Two affine connections without torsion $L$ and $\hat{L}$ (on the same manifold) are said projectively relaled when there exists a 1-form $\phi$ satisfying

$$
\begin{equation*}
\hat{L}_{j j_{k}}^{i}=L_{j_{k}}^{i}+\delta_{j}^{i} \phi_{k}+\delta_{k}^{i} \phi_{j}, \tag{0.1}
\end{equation*}
$$

where $\delta$ is Kronecker's delta. $\phi$ is then called the associated form. Two Riemannian metrics on the same manifold are said projectively related when their Levi-Civita connections are projectively related. $B$ denoting the Ricci tensor of $L$, the symmetrized Ricci tensor $R$ shall have the components $R_{\imath \jmath}=\left(B_{i j}+B_{j i}\right) / 2$. Now Tanaka's theorem states:

Theorem T. Let $L$ and $\hat{L}$ be two complete and torsion-free affine connections (on a connected manifold $M$ with $\operatorname{dim} M>1$ ) whose Ricci tensors are parallel. Assume that they are projectively related.

1) If the symmetrized Ricci tensors $R$ and $\hat{R}$ are both positive semidefinite, then, for any point $x$ in $M$ any vector $X$ at $x, R_{\imath j}(x) X^{i}=0$ is equivalent to $\hat{R}_{i j}^{\prime}(x) X^{i}=0$ and implies $\phi_{i}(x) X^{i}=0, \phi$ being the associated form
2) In the other case, $L$ and $\hat{L}$ coincide.

By Theorem T we have only to prove Theorem 1 in the two cases I) and II); I) $R$ and $\hat{R}$ are non-zero, degenerate and positive semi-definite, II) $R$ and $\hat{R}$
are positive definite. But we shall give a complete proof.
From Theorem 1 follows easily Theorem 2 which is not covered by Theorem T.

Theorem 2. Under the hypothesis of Theorem $T$, if $R$ and $\hat{R}$ are positive definite then 1) $L$ and $\hat{L}$ coincide, or 2) $L$ and $\hat{L}$ are the Levi-Civita connections of Riemannian metrics of positive constant curvature.

To close Introduction we must pay attention to Tashiro's results [6]: if one of two complete Riemannian metrics which are projectively related is (locally) reducible then their Levi-Civita connections coincide. Ishihara, Sumitomo and Yano-Nagano obtained some results concerning projective transformations, which are covered by the above theorems.

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## 1. Construction of $\boldsymbol{M}^{\prime}$.

Let $M$ be an $n$-dimensional differentiable (i.e. $C^{\infty}$-differentiable) manifold, $1<n$, and $E$ the one-dimensional Euclidean space. We consider the direct product $M \times E$ of these differentiable manifolds, which will be denoted by $M^{\prime} . M^{\prime}$ is covered by the coordinate systems $\left(x^{0}, x^{i}\right)$ which are pairs of a fixed cartesian coordinate ( $x^{0}$ ) on $E$ and arbitrary coordinate systems ( $x^{i}$ ) on $M$. Given an affine connection $L$ on $M$ without torsion, we define two affine connection $L^{\prime \prime}$ and $L^{\prime}$ on $M^{\prime}$ in terms of these coordinates by

$$
\begin{gather*}
L^{\prime \prime \lambda}=0 \text { if } \lambda \mu \nu=0, \quad \text { and }=L_{\mu \nu}^{\lambda} \text { if } \lambda \mu \nu \neq 0,  \tag{1.1}\\
L_{\mu \nu}^{\prime \lambda}=L^{\prime \prime \prime}{ }_{\mu \nu}^{\lambda}+\delta_{\mu}^{\lambda} \delta_{\nu}^{0}+\delta_{\nu}^{\lambda} \delta_{\mu}-g^{\prime \prime}{ }_{\mu \nu} w^{\lambda}, \tag{1.2}
\end{gather*}
$$

where $w$ is the vector field on $M^{\prime}$ with the components $w^{2}=\delta_{0}^{2}$, and $g^{\prime \prime}$ is the tensor field defined at $x^{\prime} \in M^{\prime}$ by

$$
\begin{equation*}
g^{\prime \prime}{ }_{\mu \nu} X^{\mu} X^{\nu}=\left(X^{0}\right)^{2}+X^{i} X^{j} R_{\imath \jmath} /(n-1) \tag{1.3}
\end{equation*}
$$

for any vector $X$ at $x^{\prime}, R$ being the symmetrized Ricci tensor of $L$. We have here adopted the conventions: Greek indices run over $0,1, \cdots, n$ and Latin ones run over $1, \cdots, n$. The affine connection $L^{\prime}$ will be called the Thomas connection of $L$ or of a Riemannian metric $g$ when $L$ is the Levi-Civita connection of $g$ [7].
(1.4) Any geodesic (=path) of the Thomas connection is mapped to that of $L$ by the natural projection of $M^{\prime}$ onto $M$.

Proposition 1. Let $L$ and $\hat{L}$ be affine connections without torsion on a differentiable manifold. Assume that the Ricci tensors of $L$ and $\hat{L}$ are symmetric and that $M$ is simply connected. If these affine connections are projectively related, then there exists a transformation $\alpha$ of $M^{\prime}$ (i.e. a dif-
feomorphism of $M^{\prime}$ onto itself) which transforms the Thomas connection $L^{\prime}$ of $L$ to that of $\hat{L}$. (See [8]:)

Proof. The associated one-form $\phi$ is exact; i.e. there exists a function $\rho$ on $M$ with $d \rho=\phi$, because the Ricci tensors are symmetric and $M$ is simply connected (see [4] for example). Now $\alpha$ is defined by $\alpha\left(x^{0}, x^{i}\right)=\left(x^{0}+\rho, x^{i}\right)$, and satisfies the required condition as is easily seen.

Remark. When $\hat{L}$ and $L$ are Levi-Civita connections, simple-connectedness of $M$ is a redundant condition, as we have $\phi=d[\log (\hat{G} / G)] / 2(n+1)$ where $G$ and $\hat{G}$ are the determinants of the metric tensors.
(1.5) If $R$ is parallel with respect to $L$ then the tensor field $\exp \left(2 x^{0}\right) \cdot g^{\prime \prime}$ is parallel with respect to the Thomas connection $L^{\prime}$, as is seen by means of some straightforward calculation.

## 2. Tanaka's method.

Based on Tanaka's idea [5], but using no projective connection, we shall prove his Theorem T under some restrictions:
(2.1) Let $L$ and $\hat{L}$ be complete affine connections on a manifold $M$ such that the Ricci tensors are symmetric and parallel. Assume that these connections are projectively related. 1) In case both of the Ricci tensors are positive semi-definite, we have $R_{\imath \jmath} X^{j}=0$ if and only if $\hat{R}_{\imath \jmath} X^{\jmath}=0$ for any vector $X$, and this implies $\phi_{i} X^{i}=0, \phi$ being the associated form. 2) Otherwise we have $L=\hat{L}$.

Proof. We can suppose that $M$ is simply connected. For the moment we consider $L$ only and put $\hat{L}$ aside. Given a geodesic $\gamma^{\prime}$ of $L^{\prime}$ on $M^{\prime}$ with an affine parameter $t$, the equation of $\gamma^{\prime}$ is written as

$$
\begin{equation*}
D D x^{2}+L_{\mu \nu}^{\prime 2} D x^{\mu} D x^{\nu}=0, \quad D \text { denoting } d / d t \tag{2.2}
\end{equation*}
$$

Let $f$ be the function $\exp \left(2 x^{0}\right)$ on $\gamma^{\prime}$. By (1.5) we get the first integral of (2.2).

$$
\begin{equation*}
f \cdot g^{\prime \prime}{ }_{\mu \nu} D x^{\mu} D x^{\nu}=a \quad(a=\text { const. }) \tag{2.3}
\end{equation*}
$$

Solving (2.2) for $\lambda=0$, we obtain

$$
\begin{equation*}
f=a t^{2}+2 b t+c \quad(b, c=\text { const. }) \tag{2.4}
\end{equation*}
$$

and

$$
\begin{equation*}
b / c=X^{0} \tag{2.5}
\end{equation*}
$$

where $X^{0}$ is the first component of the initial tangent vector $X^{\prime}=D x(0)$. We note that $c$ is strictly positive.

Let $s$ denote an affine parameter of the image geodesic $\pi \gamma^{\prime}$ (see (1.4)) of
$r^{\prime}$. $s$ is a function of $t$. Then $f D s$ is a non-zero constant $k: f D s=k$. Since $L$ is complete, the range of $s$ is $(-\infty, \infty)$. By Cauchy's theorem applied to the differential equation $f D s=k$, we infer that the domain of $t$ is the interval containing 0 given by $0<f$. Owing to (2.3), (2.4) and (2.5) this implies

$$
0<g^{\prime \prime}{ }_{\mu \nu}(x) X^{\mu} X^{\nu}+2 X^{0} t+1, \quad x=\gamma^{\prime}(0) .
$$

In other words, given a direction $X^{\prime}$ at $x^{\prime} \in M^{\prime}$, the geodesic $\gamma^{\prime}$ with an initial vector $Y^{\prime}$ in that direction $X^{\prime}$ is defined exactly for the interval $0 \leqq u<1$ of the affine parameter $u$, provided that $Y^{\prime}$ satisfies

$$
\begin{align*}
0 & =g^{\prime \prime}{ }_{\mu \nu}(x) Y^{\mu} Y^{\nu}+2 Y^{0}+1  \tag{2.6}\\
& =\left(Y^{0}+1\right)^{2}+Y^{i} Y^{j} R_{\imath j}(x) /(n-1) .
\end{align*}
$$

$\gamma^{\prime}$ is defined for $0 \leqq u<\infty$ if no vector $Y^{\prime}$ in that direction satisfies (2.6).
Given an affine connection $L$ mentioned in (2.1), we assign to each point $x^{\prime} \in M^{\prime}$ a quadric $Q\left(x^{\prime}\right)$ on the tangent space at $x^{\prime}$ defined by (2.6). To $\hat{L}$ in (2.1) corresponds $\hat{Q}\left(x^{\prime}\right)$ in the same way. By Proposition 1 these two figures must coincide, or precisely $\delta \alpha Q\left(x^{\prime}\right)=\hat{Q}\left(\alpha\left(x^{\prime}\right)\right.$ ), where $\delta \alpha$ is the differential of $\alpha$. Since $\delta \alpha\left(Y^{\prime}\right)$ has the components ( $Y^{0}+Y^{a} \nabla_{\alpha} \rho, Y^{i}$ ), this gives that (2.6) implies

$$
\begin{equation*}
\left(Y^{0}+Y^{a} \nabla_{a} \rho+1\right)^{2}+Y^{i} Y^{j} \hat{R}_{\imath \jmath} /(n-1)=0 \tag{2.7}
\end{equation*}
$$

Now assume that some vector $Y=\left(Y^{i}\right)$ at a point $x \in M$ satisfies

$$
\begin{equation*}
R_{\imath \jmath} Y^{i} Y^{j}<0 . \tag{2.8}
\end{equation*}
$$

Then there exists a number $Y^{0} \neq-1$ such that the vector $Y^{\prime}=\left(Y^{0}, Y^{i}\right)$ at any point $x^{\prime} \in \pi^{-1}(x) \subset M^{\prime}$ satisfies (2.6). We have (2.7). Since the vector $Y^{\prime \prime}=\left(Y^{0},-Y^{i}\right)$ satisfies (2.6) too, it follows

$$
\left(Y^{0}+1\right) Y^{a} \nabla_{\alpha} \rho=0, \text { and so } Y^{a} \nabla_{\alpha} \rho=0 .
$$

The last equation is satisfied by every vector $Z$ sufficiently near to $Y$; $Z^{a} \nabla_{\alpha} \rho=0$. This shows $\phi=d \rho=0$ at $x$. Since $R$ is parallel, at any point in $M$ there exists a vector $Y$ satisfying (2.8) under the above assumption and we have $\phi=0$ on $M$. The second half 2) of (2.1) is thus proved.

Next we assume that a vector $Y$ satisfies

$$
R_{\imath \jmath} Y^{i} Y^{j}=0
$$

Then, putting $Y^{0}=-1$, the vector $Y^{\prime}=\left(Y^{0}, Y^{i}\right)$ tangent to $M^{\prime}$ satisfies (2.6), and (2.7) reads

$$
\begin{equation*}
\left(Y^{a} \nabla_{a} \rho\right)+Y^{i} Y^{j} R_{i j} /(n-1)=0 \tag{2.9}
\end{equation*}
$$

It follows

$$
\begin{equation*}
Y^{a} V_{a} \rho=0, \tag{2.10}
\end{equation*}
$$

because otherwise we should have $Y^{i} Y^{j} \hat{R}_{\imath \jmath}<0$ and so by the above arguments $Y^{a} V_{\alpha} \rho=0$. (2.9) and (2.10) give $Y^{i} Y^{j} \hat{R}_{\iota \jmath}=0$. When $R$ is symmetric and
positive semi-definite, $R_{\imath \jmath} Y^{i} Y^{j}=0$ is equivalent to $R_{\iota j} Y^{\jmath}=0$. Thus the first half 1) of (2.1) is also proved.

## 3. The positive definite case.

This section is devoted to the proof of Theorem 2 in the introduction. The hypothesis of Theorem 2 and the notations in Section 1 will be preserved.

Let $f$ be the function $\exp \left(2 x^{0}\right)$ on $M^{\prime}$. Then $g^{\prime}=f g^{\prime \prime}$ (see (1.3)) and $\hat{g}^{\prime}=f \hat{g}^{\prime \prime}$ define Riemannian metrics on $M^{\prime}$ whose Levi-Civita connections are $L^{\prime}$ and $\hat{L}^{\prime}$ respectively by (1.5).

Proposition 2. Under the above hypothesis, $M^{\prime}$ with $g^{\prime}$ is either irreducible or locally flat. In the latter case L is a Levi-Civita connection of positive constant curvature.

Proof. Assume that $M^{\prime}$ with $g^{\prime}$ is reducible; i.e. the homogeneous holonomy group $H^{\prime}$ of $g^{\prime}$ is reducible. Then there exists a parallel tensor field $P$ of type (1.1) on $M^{\prime}$ such that, for each point $x^{\prime}$ in $M^{\prime}, P\left(x^{\prime}\right)$ is an orthogonal projection of the tangent space at $x^{\prime}$ onto a non-trivial subspace invariant under $H$. We identify $P$ with the distribution assigning this subspace to $x^{\prime}$. Let $Q$ denote $I-P$; i.e. $Q_{\mu}^{\lambda}=\delta_{\mu}^{\lambda}-P_{\mu}^{\lambda}$. Proposition 2 will be proved after several lemmas.
(3.1) Given any real number $c$ the subset $\left\{x^{\prime} \in M^{\prime} ; 0 \leqq x^{0}\right\}$ of $M^{\prime}$ is complete with respect to the metric on $M^{\prime}$ defined from $g^{\prime}$.
(3.2) The vector field $w$ defined in Section 1 is concurrent: $\nabla_{\mu}^{\prime} w^{2}=\delta_{\mu}^{\lambda} . \quad P w$ is concurrent on any integral manifold of $P$, where $P w$ is the vector field with $(P w)^{\lambda}=P_{\alpha}^{\lambda} w^{\alpha}$.

$$
\begin{equation*}
\nabla^{\prime}(Q w)=Q . \tag{3.3}
\end{equation*}
$$

(3.4) The length of $Q w$ is constant on a connected integral manifold of $P$.

In fact from (3.3) follows

$$
P_{\nu}^{\alpha} \nabla_{\alpha}^{\prime}\left((Q w)_{\beta}(Q w)^{\beta}\right)=2 P_{\nu}^{\alpha}(Q w)_{\beta} Q_{\alpha}^{\beta}=0 .
$$

(3.5) The union $U$ of integral manifolds of $P$ to which $w$ is tangent at each point is nowhere dense.

Proof. Let $V$ be an open subset contained in $U$. We have $Q w=0$ on $V$, whence $\nabla^{\prime}(Q w)=0$, contrarily to (3.3). Thus $V$ is vacuous.
(3.6) A connected integral manifold $N$ of $P$ is locally flat, if $w$ is not tangent to $N$ (at a point).

Proof. Then $w$ is not tangent to $N$ at any point by (3.4). It suffices to verify (3.6) in case $N$ is a maximal connected integral manifold. Let $z$ be an arbitrary point of $N$. Assume that $P w=0$ at $z$. By (3.2) the curvature
tensor $S$ of $N$ is invariant by $P w ; \mathcal{L}_{P w} S=0, \mathcal{L}$ denoting the Lie derivative [9]. By (2.2) and the equality $P w(z)=0$, we find that $S(z)=0$. Next suppose that $P w \neq 0$ at $z$. Consider the trajectory $\gamma$ of $P w$ issuing from $z$ in such a direction that the length $\lambda$ of $P w$ is a decreasing function of the arc length $s$ of $r$. By (3.2), $2 \lambda+s$ is constant on $Y$. By (3.4) and the assumption of (3.6) the length $\|w\|$ of $w$ is bounded below on $\gamma$. This shows that the first coordinate $x^{0}=\log \|w\|$ is bounded below. From (3.1) it follows that $s$ can attain the value $s_{0}$ such that $2 \lambda+s_{0}=0$; i.e. there exists a point $y$ on $r$ at which $P w=0$. We have $S(y)=0$ as shown before. On the other hand $\|S\| \lambda^{2}$ is constant on $r$ [10] where

$$
\|S\|^{2}=S_{\alpha \beta \gamma \delta} S^{\alpha \beta \gamma \delta}
$$

Therefore $S$ must vanish on $\gamma$. In particular we have $S(z)=0$, and (3.6) is proved.

By (3.5) and (3.6) any integral manifold of $P$ is locally flat. The analogue holds good for $Q$ too. Thus $M^{\prime}$ is locally flat, and the first half of Proposition 2 is established. Since the symmetrized Ricci tensor $R$ of an affine connection $L$ without torsion is parallel and positive definite, $L$ is the Levi-Civita connection of the Riemannian metric $R$, and $R$ coincides with the Ricci tensor of $L$. In particular $M$ with the metric tensor $R$ is an Einstein space. If $M^{\prime}$ with $g^{\prime}=f g^{\prime \prime}$ is locally flat, then $g^{\prime \prime}$ is locally conformally flat. Since $M^{\prime}$ with $g^{\prime \prime}$ is the Riemann product of the Euclidean space $E$ and the Einstein space $M$ with $R$, it follows that $M$ with $R$ is locally conformally flat. Thus $M$ with $R$ is a space of constant curvature. This completes the proof of Proposition 2.

Proof of Theorem 2. By Proposition 1, $M^{\prime}$ with $g^{\prime \prime}$ is irreducible if and only if $M^{\prime}$ with $\hat{g}^{\prime \prime}$ is irreducible. Then $\alpha$ is a homothetic transformation ([1], [3]). Owing to the definition (1.3) of $g^{\prime \prime}$ and $\hat{g}^{\prime \prime} \alpha$ is then an isometry. Hence $R$ coincides with $\hat{R}$. Hence the Levi-Civita connection $L$ of the metric tensor $R$ coincides with $\hat{L}$. If $M^{\prime}$ is reducible, Theorem 2 follows from Proposition 2 immediately.

## 4. The non-definite case.

Eventually we have to survey the case that the Ricci tensors of $g$ and $\hat{g}$ are positive semi-definite but not definite in order to complete the proof of Theorem 1. In this case applies Tanaka's theorem mentioned in the introduction, since both $g$ and $\hat{g}$ are then reducible. We shall however give an independent proof. $M$ can be assumed to be simply connected. $M$ with $g$ (or $\hat{g}$ ) is then a Riemann product of a space $N$ with the vanishing Ricci tensor and a space $S$ (or $\hat{S}$ ) with the parallel positive definite Ricci tensor. $N$ is common to $g$ and $\hat{g}$ because of 1) in Theorem T. Let $D$ be the distribution on $M$ which is parallel with respect to $g$ and whose maximal connected integral submanifolds are isometric to $S$. The distribution $\hat{D}$ is defined ana-
logously from $\hat{g}$.
If $D$ coincides with $\hat{D}$, then the associated form $\phi$ vanishes on $M$, as follows immediately from (0.1). In this case Theorem 1 is thus proved.

Now assume $D \neq \hat{D}$. Then there exists a point $x$ in $M$ such that the maximal connected integral submanifold $S(x)$ of $D$ which contains $x$ is different from $\hat{S}(x)$. For the sake of brevity we write $S$ for $S(x), \hat{S}$ for $\hat{S}(x)$ and $N$ for the (totally geodesic) submanifold containing $x$ isometric to $N$ whose tangent space at $x$ is orthocomplement of that of $S$ at $x$ with respect to $g$.

Let $\mu$ be the orthogonal projection of $M$ with $g$ onto $S$, and $\nu$ that of $M$ with $g$ onto $N . \hat{\mu}$ and $\hat{\nu}$ are analogously defined from $\hat{g} ; \hat{\nu}(M)=\nu(M)=N$.
$S$ with $g$ and $\hat{S}$ with $\hat{g}$ are isometric to the sphere. Hence $S$ with $\hat{g}$ and $\hat{S}$ with $g$ are projectively flat and so spaces of constant curvature. Being compact and simply connected, they are isometric to the sphere. Restricted to $\hat{S}$ with $\hat{g}, \mu$ is a mapping onto $S$ and sends any geodesic to a geodesic with the affine parameters preserved. Restricted to some neighborhood $U$ of $x$ in $\hat{S}$ with $g, \mu$ is a diffeomorphism and so an affine transformation. Since $U$ with $g$ is irreducible, it is a homothetic transformation. It follows that $\mu$, restricted to $\hat{S}$ with $g$, is a homothetic transformation onto $S$; in particular it is a diffeomorphism of $\hat{S}$ onto $S$. Therefore $\nu$, restricted to $\grave{S}$ with $g$, is a homothetic taansformation of $\hat{S}$ onto $\nu(\hat{S}) \subset N$.

Consider the submanifolds $B$ and $\hat{B}$ of $M$ such that $B=\{p \in M ; \nu(p)$ $\in \nu(\hat{S}), \mu(p) \in S\}$ and $\hat{B}=\{p \in M ; \hat{\nu}(p) \in \nu(\hat{S})$ and $\hat{\mu}(p) \in \hat{S}\} . \quad B$ with $g$ and $\hat{B}$ with $\hat{g}$ are both isometric to the Riemannian product $S \times S$. Let $\lambda$ be the map of $\hat{B}$ into $B$ defined by the conditions: $\hat{\nu}=\nu \lambda$ and $\mu \hat{\mu}=\mu \lambda$ on $\hat{B}$. Then $\lambda$ is a projectiue transformation of $\hat{B}$ with $\hat{g}$ onto $B$ with $g$. By theorem 2, $\lambda$ is an affine transformation. Restricted to $\hat{S}, \lambda$ coincides with $\mu$. Hence $g$ and $\hat{g}$ on $\hat{S}$ has the same Levi-Civita connection. By (0.1) and 2) in Theorem T we conclude that $\phi$ vanishes on $\hat{S}$ and so on $M$.

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