

**THE IDENTITY MAP AS A HARMONIC MAP OF A
 $(4r+3)$ -SPHERE WITH DEFORMED METRICS**

Dedicated to Professor Yoji Hatakeyama on his sixtieth birthday

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§ 1. Introduction.

It is known that the identity map Id_M of a compact Riemannian manifold (M, g) is a harmonic map. (M, g) is said to be unstable, if the Jacobi operator J defined by the second variation of the energy functional at Id_M has negative eigenvalues. The standard m -dimensional sphere (S^m, g_0) of constant curvature 1 is unstable for $m \geq 3$. More generally, unstable, simply connected compact (irreducible) symmetric spaces were determined (Smith [5], Nagano [3], Ohnita [4], Urakawa [11]).

In [9] the author studied instability of spheres $(S^m, g(t))$ with $m=2n+1$, as a class of homogeneous Riemannian manifolds which are not symmetric nor Einstein (cf. also Urakawa [12]), and gave the expression of some eigenvector of the Jacobi operator corresponding to a negative eigenvalue. The Riemannian metrics $g(t)$ considered in [9] or [12] is related to the Hopf fibration $(S^{2n+1}, g_0) \rightarrow (CP^n, h_0)$, where (CP^n, h_0) denotes the complex projective space with the Fubini-Study metric of constant holomorphic sectional curvature 4.

As the next step, we study the Riemannian metrics related to the Hopf fibration $(S^{4r+3}, g_0) \rightarrow (QP^r, h_0)$, where QP^r denotes the quaternion projective space. (S^{4r+3}, g_0) admits a Sasakian 3-structure $\{\eta_{(1)}, \eta_{(2)}, \eta_{(3)}\}$. The dual vector fields $\{\xi_{(1)}, \xi_{(2)}, \xi_{(3)}\}$ define the 3-dimensional distribution on S^{4r+3} whose integral submanifolds are fibers of the Hopf fibration. We define a 1-parameter family of Riemannian metrics $g(t)$ on S^{4r+3} by

$$(1.1) \quad g(t) = t^{-1}g_0 + t^{-1}(t^{m/3} - 1) \sum_{\alpha} \eta_{(\alpha)} \otimes \eta_{(\alpha)},$$

where $m=4r+3$, and $0 < t < \infty$ (cf. Tanno [7]). The volume form for $g(t)$ is unchanged for all t . The purpose of this paper is to show the following:

- THEOREM.** (i) For $m=4r+3=7, 11$, the sphere $(S^{4r+3}, g(t))$ is unstable.
 (ii) For $m=4r+3 \geq 15$, and for $t \in (0, t_0(m))$ or $t \in (t_1(m), \infty)$, the sphere $(S^{4r+3}, g(t))$ is unstable, where $t_0(m)$ and $t_1(m)$ are given in § 4.
 (iii) For each eigenfunction f corresponding to the (non-zero) first eigenvalue $\lambda_1=4r+3$ of the Laplacian acting on functions on (S^{4r+3}, g_0) ,

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$$(1.2) \quad f\xi_{(1)} + t^{m/3}k(t)\nabla\xi_{\text{grad}f}\xi_{(1)} + (1-t^{m/3}k(t))((\xi_{(3)}f)\xi_{(2)} - (\xi_{(2)}f)\xi_{(3)})$$

is an eigenvector corresponding to the negative eigenvalue $\mu(t)$ of the Jacobi operator $J_{(t)}$. $k(t)$ and $\mu(t)$ are given in §4. The multiplicity of $\mu(t)$ is $m+1$ for almost all t in $(0, t_0(m))$ or $(t_1(m), \infty)$.

It is an open problem if the positivity of $\mu(t)$ (for $t_0(m) < t < t_1(m)$) is related to some geometric property, and if $(S^{4r+3}, g(t))$ is stable for $t_0(m) < t < t_1(m)$.

§2. Preliminaries.

Let (S^{4r+3}, g_0) be the unit sphere in the $4(r+1)$ -dimensional Euclidean space $E^{4(r+1)}$, where $E^{4(r+1)}$ is considered as a product space $Q \times \dots \times Q$ of $r+1$ copies of the space Q of quaternions with the canonical metric. Let $\{x^\sigma, y^\sigma, z^\sigma, w^\sigma; \sigma=1, \dots, r+1\}$ be the natural coordinate system of $E^{4(r+1)}$. Let $\{I, J, K\}$ be the quaternion structure of $E^{4(r+1)}$. If one considers a point $x=(x^\sigma, y^\sigma, z^\sigma, w^\sigma)$ of S^{4r+3} as a unit vector in $E^{4(r+1)}$ and

$$\begin{aligned} Ix &= (y^\sigma, -x^\sigma, w^\sigma, -z^\sigma), \\ Jx &= (z^\sigma, -w^\sigma, -x^\sigma, y^\sigma), \\ Kx &= (w^\sigma, z^\sigma, -y^\sigma, -x^\sigma), \end{aligned}$$

as tangent vectors at x to S^{4r+3} , we get a field of orthonormal vectors $\{\xi_{(1)}, \xi_{(2)}, \xi_{(3)}\}$ on S^{4r+3} . Each $\xi_{(\alpha)}$ is a Killing vector field on (S^{4r+3}, g_0) , and we have the following:

$$(2.1) \quad [\xi_{(1)}, \xi_{(2)}] = 2\xi_{(3)}, \quad [\xi_{(2)}, \xi_{(3)}] = 2\xi_{(1)}, \quad [\xi_{(3)}, \xi_{(1)}] = 2\xi_{(2)}.$$

The 3-dimensional distribution defined by $\{\xi_{(1)}, \xi_{(2)}, \xi_{(3)}\}$ on S^{4r+3} is integrable and each integral submanifold is isometric to a unit 3-sphere in E^4 . This gives the Hopf fibration $S^{4r+3} \rightarrow QP^r$. Now let $\{\eta_{(1)}, \eta_{(2)}, \eta_{(3)}\}$ be the dual of $\{\xi_{(1)}, \xi_{(2)}, \xi_{(3)}\}$ with respect to g_0 . Then each $\eta_{(\alpha)}$ defines a contact structure on S^{4r+3} , and $\{\eta_{(\alpha)}, g_0\}$ is a Sasakian structure. Furthermore, $\{\eta_{(1)}, \eta_{(2)}, \eta_{(3)}; g_0\}$ is called the canonical Sasakian 3-structure of (S^{4r+3}, g_0) . For each α ($\alpha=1, 2, 3$), we define a $(1, 1)$ -tensor field $\phi_{(\alpha)}$ by

$$(2.2) \quad \phi_{(\alpha)} = -\nabla\xi_{(\alpha)}.$$

$\phi_{(1)}, \phi_{(2)}$, and $\phi_{(3)}$ are canonically related to I, J , and K .

We have the following relations:

$$(2.3) \quad \phi_{(\alpha)}\xi_{(\alpha)} = 0, \quad \eta_{(\alpha)}\phi_{(\alpha)} = 0,$$

$$(2.4) \quad \phi_{(\alpha)}^2 X = -X + \eta_{(\alpha)}(X)\xi_{(\alpha)},$$

$$(2.5) \quad g_0(X, Y) = g_0(\phi_{(\alpha)}X, \phi_{(\alpha)}Y) + \eta_{(\alpha)}(X)\eta_{(\alpha)}(Y),$$

$$(2.6) \quad \nabla_{\xi_{(\alpha)}} \xi_{(\alpha)} = \nabla_{\xi_{(\alpha)}} \eta_{(\alpha)} = 0, \quad L_{\xi_{(\alpha)}} \phi_{(\alpha)} = L_{\xi_{(\alpha)}} \eta_{(\alpha)} = 0,$$

$$(2.7) \quad (\nabla_X \phi_{(\alpha)})(Y) = g_0(X, Y) \xi_{(\alpha)} - \eta_{(\alpha)}(Y)X,$$

$$(2.8) \quad \phi_{(\alpha)} \xi_{(\beta)} = -\phi_{(\beta)} \xi_{(\alpha)} = \xi_{(\gamma)}, \quad [\alpha, \beta, \gamma: \text{cyclic}]$$

$$(2.9) \quad \phi_{(\alpha)} \phi_{(\beta)} - \xi_{(\alpha)} \eta_{(\beta)} = -\phi_{(\beta)} \phi_{(\alpha)} + \xi_{(\beta)} \eta_{(\alpha)} = \phi_{(\gamma)}, \quad [\alpha, \beta, \gamma: \text{cyclic}]$$

where X, Y denote tangent vectors or vector fields, and $[\alpha, \beta, \gamma: \text{cyclic}]$ means that $\{\alpha, \beta, \gamma\}$ in (2.8) and (2.9) is a cyclic permutation of $(1, 2, 3)$. This convention is used also in the following. Also, we have the following:

$$(2.10) \quad \eta_{(\alpha)} \phi_{(\beta)} = -\eta_{(\beta)} \phi_{(\alpha)} = \eta_{(\gamma)}, \quad [\alpha, \beta, \gamma: \text{cyclic}]$$

$$(2.11) \quad \nabla_{\xi_{(\alpha)}} \eta_{(\beta)} = -\nabla_{\xi_{(\beta)}} \eta_{(\alpha)} = \eta_{(\gamma)},$$

$$\nabla_{\xi_{(\alpha)}} \xi_{(\beta)} = -\nabla_{\xi_{(\beta)}} \xi_{(\alpha)} = \xi_{(\gamma)}, \quad [\alpha, \beta, \gamma: \text{cyclic}]$$

$$(2.12) \quad L_{\xi_{(\alpha)}} \phi_{(\beta)} = -L_{\xi_{(\beta)}} \phi_{(\alpha)} = 2\phi_{(\gamma)},$$

$$L_{\xi_{(\alpha)}} \eta_{(\beta)} = -L_{\xi_{(\beta)}} \eta_{(\alpha)} = 2\eta_{(\gamma)}, \quad [\alpha, \beta, \gamma: \text{cyclic}]$$

where L_X denotes the Lie derivation by X . Next, we define an operator L by

$$L = \sum_{\alpha} L_{\xi_{(\alpha)}} L_{\xi_{(\alpha)}}.$$

The restriction of L (for functions) to each integral submanifold (which is isometric to the 3-sphere) is identical with the usual Laplacian Δ acting on functions on (S^3, g_0) . Thus, we have the following (cf. Tanno [7]):

PROPOSITION 2.1. *For a non-negative integer k , the eigenspace V_k corresponding to the k -th eigenvalue of the Laplacian Δ acting on functions on (S^{4r+3}, g_0) has the orthogonal decomposition;*

$$V_k = W_{k, k} + W_{k, k-2} + \cdots + W_{k, k-2[k/2]}$$

such that $f \in W_{k, \theta}$ satisfies

$$Lf = \theta(\theta+2)f.$$

§ 3. Riemannian metrics $g(t)$.

We define $\{g(t); 0 < t < \infty\}$ such that $g(1) = g_0$ on S^{4r+3} by

$$(3.1) \quad g(t) = t^{-1}g_0 + t^{-1}(t^{m/3} - 1) \sum_{\alpha} \eta_{(\alpha)} \otimes \eta_{(\alpha)}.$$

For simplicity we denote $g(t)$ by \tilde{g} , and g_0 by g in the following calculation. So, in the local coordinate expression we have

$$(3.1) \quad \tilde{g}_{jk} = t^{-1}g_{jk} + t^{-1}(t^{m/3} - 1) \sum_{\alpha} \eta_{(\alpha)j} \eta_{(\alpha)k},$$

$$(3.2) \quad \tilde{g}^{ij} = t g^{ij} - t(1-t^{-m/3}) \sum_{\alpha} \xi_{(\alpha)}^i \xi_{(\alpha)}^j.$$

LEMMA 3.1. *The difference W_{jk}^i of the Christoffel symbols $\tilde{\Gamma}_{jk}^i$ and Γ_{jk}^i with respect to $g(t)$ and g_0 is given by*

$$(3.3) \quad W_{jk}^i = -(t^{m/3} - 1) \sum_{\alpha} (\phi_{(\alpha)j}^i \eta_{(\alpha)k} + \phi_{(\alpha)k}^i \eta_{(\alpha)j}).$$

Proof. By a classical formula we have

$$\begin{aligned} W_{jk}^i &= \tilde{\Gamma}_{jk}^i - \Gamma_{jk}^i \\ &= (1/2) \tilde{g}^{ir} (\nabla_j \tilde{g}_{rk} + \nabla_k \tilde{g}_{rj} - \nabla_r \tilde{g}_{jk}). \end{aligned}$$

Substituting (3.1) and (3.2) into the above, and using (2.2), etc., we have (3.3).

LEMMA 3.2. *The Riemannian curvature tensor $\hat{R} = R_{(t)}$ of $\tilde{g} = g(t)$ is given by*

$$(3.4) \quad \begin{aligned} \hat{R}_{jkl}^i &= R_{jkl}^i + (1-t^{m/3}) \sum_{\alpha} \{2\phi_{(\alpha)j}^i \phi_{(\alpha)kl} - \phi_{(\alpha)l}^i \phi_{(\alpha)jk} + \phi_{(\alpha)k}^i \phi_{(\alpha)jl} \\ &\quad + \xi_{(\alpha)}^i (g_{jk} \eta_{(\alpha)l} - g_{jl} \eta_{(\alpha)k}) - 2\eta_{(\alpha)j} (\delta_k^i \eta_{(\alpha)l} - \delta_l^i \eta_{(\alpha)k})\} \\ &\quad + (1-t^{m/3})^2 \sum_{\alpha} \eta_{(\alpha)j} (\delta_k^i \eta_{(\alpha)l} - \delta_l^i \eta_{(\alpha)k}) \\ &\quad + (1-t^{m/3})^2 \sum_{[cyclic]} \{2\phi_{(\alpha)j}^i (\eta_{(\beta)k} \eta_{(\gamma)l} - \eta_{(\gamma)k} \eta_{(\beta)l}) \\ &\quad + \phi_{(\alpha)l}^i (\eta_{(\beta)k} \eta_{(\gamma)j} - \eta_{(\gamma)k} \eta_{(\beta)j}) - \phi_{(\alpha)k}^i (\eta_{(\beta)l} \eta_{(\gamma)j} - \eta_{(\gamma)l} \eta_{(\beta)j}) \\ &\quad + 2(\xi_{(\alpha)}^i \eta_{(\beta)j} - \xi_{(\beta)}^i \eta_{(\alpha)j}) (\eta_{(\alpha)k} \eta_{(\beta)l} - \eta_{(\beta)k} \eta_{(\alpha)l})\}. \end{aligned}$$

Proof. We calculate the following:

$$\hat{R}_{jkl}^i = R_{jkl}^i + \nabla_k W_{lj}^i - \nabla_l W_{kj}^i + W_{lj}^i W_{ks}^s - W_{kj}^i W_{ls}^s.$$

By (2.2), (2.7), etc., and (3.3) we have

$$\begin{aligned} \nabla_k W_{lj}^i - \nabla_l W_{kj}^i &= (1-t^{m/3}) \sum_{\alpha} \{2\phi_{(\alpha)j}^i \phi_{(\alpha)kl} - \phi_{(\alpha)l}^i \phi_{(\alpha)jk} + \phi_{(\alpha)k}^i \phi_{(\alpha)jl} \\ &\quad + \xi_{(\alpha)}^i (g_{jk} \eta_{(\alpha)l} - g_{jl} \eta_{(\alpha)k}) - 2\eta_{(\alpha)j} (\delta_k^i \eta_{(\alpha)l} - \delta_l^i \eta_{(\alpha)k})\}. \end{aligned}$$

As for $W_{lj}^i W_{ks}^s$, we calculate it directly as

$$W_{lj}^i W_{ks}^s = (1-t^{m/3})^2 \{ \sum_{\alpha} (\phi_{(\alpha)l}^i \eta_{(\alpha)j} + \phi_{(\alpha)j}^i \eta_{(\alpha)l}) \} \sum_{\beta} (\phi_{(\beta)k}^s \eta_{(\beta)s} + \phi_{(\beta)s}^s \eta_{(\beta)k}).$$

Summing up the results, proof is completed.

LEMMA 3.3. *The Ricci curvature tensor (\hat{R}_{jl}) and the scalar curvature $\hat{S} = S_{(t)}$ of $(S^{4r+3}, g(t))$ are given by*

$$(3.5) \quad \begin{aligned} \hat{R}_{jl} &= R_{jl} + 6(1-t^{m/3}) g_{jl} \\ &\quad + (1-t^{m/3}) [-2m + (m-3)(1-t^{m/3})] \sum_{\alpha} \eta_{(\alpha)j} \eta_{(\alpha)l}, \end{aligned}$$

$$(3.6) \quad \tilde{S} = tS - 3t(1-t^{-m/3})[2+(m-3)t^{m/3}].$$

The Ricci operator $\tilde{Q} = Q_{(t)}$ is given by

$$(3.7) \quad \hat{R}_i^h = t[m-1+6(1-t^{m/3})]\delta_i^h - t(1-t^{-m/3})[2-(m+3)t^{m/3}]\sum_{\alpha} \xi_{(\alpha)}^h \eta_{(\alpha)_i}.$$

Proof. By contraction \tilde{R}_{jil}^i we have \tilde{R}_{jl} . \tilde{S} is given by $\tilde{g}^{jl}\tilde{R}_{jl}$. And, $\hat{R}_i^h = \tilde{g}^{hj}\hat{R}_{ji}$.

LEMMA 3.4. Each $\xi_{(\alpha)}$ is a Killing vector field with respect to $g(t)$.

Proof. It suffices to show that $\xi_{(1)}$ is a Killing vector field with respect to $g(t)$. $L_{\xi_{(1)}}g = L_{\xi_{(1)}}\eta_{(1)} = 0$ is trivial. By (2.12) we have

$$\begin{aligned} L_{\xi_{(1)}}(\eta_{(2)} \otimes \eta_{(2)}) &= 2(\eta_{(3)} \otimes \eta_{(2)} + \eta_{(2)} \otimes \eta_{(3)}), \\ L_{\xi_{(1)}}(\eta_{(3)} \otimes \eta_{(3)}) &= -2(\eta_{(2)} \otimes \eta_{(3)} + \eta_{(3)} \otimes \eta_{(2)}). \end{aligned}$$

Since $g(t)$ is given by (3.1), proof is completed.

We define two operators Φ and Ψ acting on 1-forms by the following :

$$\begin{aligned} \Phi(w) &= \sum_{\alpha} \phi_{(\alpha)}^{rs} \nabla_r w_s \cdot \eta_{(\alpha)}, \\ \Psi(w) &= \sum_{(\alpha, \beta, \gamma)} \text{sgn} \begin{pmatrix} 1 & 2 & 3 \\ \alpha & \beta & \gamma \end{pmatrix} (\nabla_{\xi_{(\alpha)}} w)(\xi_{(\beta)}) \eta_{(\gamma)}, \end{aligned}$$

where $\text{sgn}(\dots)$ denotes the signature of permutation.

PROPOSITION 3.5. The Laplacian $\tilde{\Delta} = \Delta_{(t)}$ for functions and 1-forms are given by

$$(3.8) \quad \Delta_{(t)}f = t\Delta f - t(1-t^{-m/3})Lf,$$

$$(3.9) \quad \begin{aligned} \Delta_{(t)}w &= t\Delta w - t(1-t^{-m/3})Lw + 2t(1-t^{m/3})\Phi(w) \\ &\quad + 2t(1-t^{-m/3})(1-t^{m/3})\Psi(w). \end{aligned}$$

Proof. (3.8) was proved in [7]. To show (3.9), we calculate the following :

$$\begin{aligned} \tilde{\Delta}w_i &= \tilde{g}^{rs} \tilde{\nabla}_r \tilde{\nabla}_s w_i - \tilde{R}_i^s w_s \\ &= \tilde{g}^{rs} \tilde{\nabla}_r (\nabla_s w_i - W_{si}^h w_h) - \tilde{R}_i^s w_s \\ &= \tilde{g}^{rs} (\nabla_r \nabla_s w_i - \nabla_r W_{si}^h w_h - W_{si}^h \nabla_r w_h - W_{rs}^q \nabla_q w_i \\ &\quad + W_{rs}^q W_{qi}^h w_h - W_{ri}^q \nabla_s w_q + W_{ri}^q W_{sq}^h w_h) - \tilde{R}_i^s w_s. \end{aligned}$$

First we check the following relation for each α ;

$$(3.10) \quad L_{\xi(\alpha)} L_{\xi(\alpha)} w = \nabla_{\xi(\alpha)} \nabla_{\xi(\alpha)} w - 2\nabla_{\xi(\alpha)} w \cdot \phi_{(\alpha)} - w + w(\xi(\alpha))\eta_{(\alpha)}.$$

Then we have

$$\begin{aligned} \tilde{g}^{rs} \nabla_r \nabla_s w_i &= t \nabla_r \nabla^r w_i - t(1-t^{-m/3}) \{3w_i + (Lw)_i \\ &\quad + \sum_{\alpha} (2\nabla_{\xi(\alpha)} w_h \cdot \phi_{(\alpha)_i}^h - w(\xi(\alpha))\eta_{(\alpha)_i})\}, \\ \tilde{g}^{rs} \nabla_r W_{s_i}^h w_h &= t(1-t^{-m/3}) \{-3w_i + m \sum_{\alpha} w(\xi(\alpha))\eta_{(\alpha)_i}\}, \\ \tilde{g}^{rs} W_{s_i}^h \nabla_r w_h &= t(1-t^{-m/3}) \{\sum_{\alpha} \nabla_{\xi(\alpha)} w_h \cdot \phi_{(\alpha)_i}^h - (\Phi(w))_i\} \\ &\quad - t(1-t^{-m/3})(1-t^{-m/3}) \{\sum_{\alpha} \nabla_{\xi(\alpha)} w_h \cdot \phi_{(\alpha)_i}^h + (\Psi(w))_i\}, \\ \tilde{g}^{rs} W_{rs}^q \nabla_q w_i &= \tilde{g}^{rs} W_{rs}^q W_{q_i}^h w_h = 0, \\ \tilde{g}^{rs} W_{rs}^q W_{q_i}^h w_h &= -3t(1-t^{-m/3})^2 t^{-m/3} (w_i - \sum_{\alpha} w(\xi(\alpha))\eta_{(\alpha)_i}). \end{aligned}$$

Summing up the above and using (3.7), we obtain (3.9).

LEMMA 3.6. For each α , $\eta_{(\alpha)}$ is an eigenform of $\Delta_{(\iota)}$;

$$(3.11) \quad \Delta_{(\iota)} \eta_{(\alpha)} = -2t[(m-1)t^{m/3} - 2(1-t^{-m/3})(1+t^{m/3})] \eta_{(\alpha)}.$$

Proof. It is known that $\Delta \eta_{(\alpha)} = -2(m-1)\eta_{(\alpha)}$ holds. Furthermore we have

$$\begin{aligned} L \eta_{(\alpha)} &= -8\eta_{(\alpha)}, \\ \Phi(\eta_{(\alpha)}) &= (m-1)\eta_{(\alpha)}, \\ \Psi(\eta_{(\alpha)}) &= -2\eta_{(\alpha)}. \end{aligned}$$

By (3.9) we obtain (3.11).

Remark. If one wants to obtain geometric expressions of eigen 1-forms of the Laplacian $\Delta_{(\iota)}$ of $(S^{4r+3}, g(t))$, then the decomposition of V_k given by Proposition 2.1 and the expression (3.9) of $\Delta_{(\iota)}$ are helpful (cf. Tanno [8]).

§ 4. The Jacobi operator $J_{(\iota)}$.

The Jacobi operator $J_{(\iota)}$ acting on 1-forms on $(S^{4r+3}, g(t))$ is given by

$$(4.1) \quad J_{(\iota)} = -\Delta_{(\iota)} - 2Q_{(\iota)}$$

and the local coordinate expression is $(J_{(\iota)} w)_i = -(\Delta_{(\iota)} w)_i - 2\hat{R}_i^h w_h$ (cf. Smith [5]). The Jacobi operator $J_{(\iota)}$ for vector fields is understood by the natural correspondence between the space of 1-forms and the space of vector fields. In the following we use $J_{(\iota)}$ for 1-forms.

Putting $P(w) = \sum_{\alpha} w(\xi(\alpha))\eta_{(\alpha)}$, we have

$$(4.2) \quad \begin{aligned} J_{(\iota)}w &= -t\Delta w + t(1-t^{-m/3})Lw - 2t(1-t^{m/3})\Phi(w) \\ &\quad - 2t(1-t^{-m/3})(1-t^{m/3})\Psi(w) - 2t[m-1+6(1-t^{m/3})]w \\ &\quad + 2t(1-t^{-m/3})[2-(m+3)t^{m/3}]P(w). \end{aligned}$$

PROPOSITION 4.1. *For each α , we have $J_{(\iota)}\eta_{(\alpha)}=0$.*

Proof. This follows from the fact that $\xi_{(\alpha)}$ is a Killing vector field and Killing vector fields belong to the null eigenspace of $J_{(\iota)}$. Also, the direct calculation using (3.7) and (3.11) is easy. q. e. d.

Let V_1 be the eigenspace corresponding to the first eigenvalue $\lambda_1=4r+3$ of the Laplacian acting on functions on $(S^{4r+3}, g(t))$, and let $f \in V_1$. Then f satisfies $\nabla_j \nabla_i f = -f g_{ij}$. Therefore, we have

$$(4.3) \quad \xi_{(\alpha)}\xi_{(\alpha)}f = -f,$$

$$(4.4) \quad \xi_{(\alpha)}\xi_{(\beta)}f = \xi_{(\gamma)}f.$$

LEMMA 4.2. *Let $f \in V_1$. Then we have the following:*

- (1-i) $\Delta(f\eta_{(1)}) = -(3m-2)f\eta_{(1)} + 2df \cdot \phi_{(1)},$
- (1-ii) $L(f\eta_{(1)}) = -11f\eta_{(1)} + 4((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (1-iii) $\Phi(f\eta_{(1)}) = (m-1)f\eta_{(1)} - ((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (1-iv) $\Psi(f\eta_{(1)}) = -2f\eta_{(1)} + ((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (2-i) $\Delta(df \cdot \phi_{(1)}) = 2(m-1)f\eta_{(1)} - (m+2)df \cdot \phi_{(1)},$
- (2-ii) $L(df \cdot \phi_{(1)}) = 8f\eta_{(1)} - 3df \cdot \phi_{(1)} - 4((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (2-iii) $\Phi(df \cdot \phi_{(1)}) = -(m-1)f\eta_{(1)} + ((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (2-iv) $\Psi(df \cdot \phi_{(1)}) = 2f\eta_{(1)} - ((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (3-i) $\Delta((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}) = 4f\eta_{(1)} + 4df \cdot \phi_{(1)} - 3m((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (3-ii) $L((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}) = 8f\eta_{(1)} - 7((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (3-iii) $\Phi((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}) = -2f\eta_{(1)} + (m-2)((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}),$
- (3-iv) $\Psi((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}) = 2f\eta_{(1)} - ((\xi_{(3)}f)\eta_{(2)} - (\xi_{(2)}f)\eta_{(3)}).$

Proof. Verification is done by a direct calculation using (2.2)~(2.12).

LEMMA 4.3. *With respect to the projection P , we have*

$$P(df \cdot \phi_{(1)}) = (\xi_{(3)} f) \eta_{(2)} - (\xi_{(2)} f) \eta_{(3)},$$

$$P(f \eta_{(1)}) = f \eta_{(1)} \text{ and } P((\xi_{(3)} f) \eta_{(2)} - (\xi_{(2)} f) \eta_{(3)}) = (\xi_{(3)} f) \eta_{(2)} - (\xi_{(2)} f) \eta_{(3)}.$$

Proof. The first identity is verified by (2.8).

PROPOSITION 4.4. For $f \in V_1$, $w_{[f, t]}$ is an eigenform of $J_{(t)}$ corresponding to $\mu(t)$ for each t ($0 < t < \infty$), where $w_{[f, t]}$ is defined by

$$(4.5) \quad w_{[f, t]} = f \eta_{(1)} + k(t) df \cdot \phi_{(1)} + (1 - k(t)) ((\xi_{(3)} f) \eta_{(2)} - (\xi_{(2)} f) \eta_{(3)}),$$

$$(4.6) \quad k(t) = [2(m-3)t^{m/3}]^{-1} \{m+2-2t^{-m/3}-6t^{m/3} \\ + [(m+2-2t^{-m/3}-6t^{m/3})^2 + 12(m-3)t^{m/3}]^{1/2}\},$$

and $\mu(t)$ is given by

$$(4.7) \quad \mu(t) = t[-5 + t^{-m/3} + 6t^{m/3}] \\ - t[(m+2-2t^{-m/3}-6t^{m/3})^2 + 12(m-3)t^{m/3}]^{1/2}.$$

For $m=4r+3=7, 11$, $\mu(t)$ is negative for all t ($0 < t < \infty$). For $m \geq 15$, $\mu(t)$ is negative, if $0 < t < t_0(m)$ or $t_1(m) < t$, where

$$(4.8) \quad 3(t_0(m))^{-m/3} = 2m-1 + [(m-2)(m-14)]^{1/2},$$

$$(4.9) \quad 3(t_1(m))^{-m/3} = 2m-1 - [(m-2)(m-14)]^{1/2}.$$

Proof. We define $w_{[f, t]}$ by (4.5) with undetermined $k(t)$. By (4.2), Lemma 4.2 and Lemma 4.3, we have

$$J_{(t)} w_{[f, t]} = t \{m-3-t^{-m/3}-2(m-3)t^{m/3}k(t)\} f \eta_{(1)} \\ + t \{-6-(m+7-3t^{-m/3}-12t^{m/3})k(t)\} df \cdot \phi_{(1)} \\ + t \{m+3-t^{-m/3} \\ + (m+7-2(m+3)t^{m/3}-3t^{-m/3})k(t)\} ((\xi_{(3)} f) \eta_{(2)} - (\xi_{(2)} f) \eta_{(3)}).$$

Therefore, $J_{(t)} w_{[f, t]} = \mu(t) w_{[f, t]}$ holds, if $k(t)$ is a solution of

$$(m-3)t^{m/3}k(t)^2 - (m+2-2t^{-m/3}-6t^{m/3})k(t) - 3 = 0,$$

and $\mu(t)$ is given by

$$\mu(t) = t[m-3-t^{-m/3}-2(m-3)t^{m/3}k(t)].$$

Because we are interested in the case where $\mu(t)$ is negative, we choose $k(t)$ as the positive solution of the above equation. So, $k(t)$ is given by (4.6), and consequently, $\mu(t)$ is equal to (4.7). t satisfies $\mu(t)=0$, if and only if

$$3t^{-2m/3} - 2(2m-1)t^{-m/3} + m^2 + 4m - 9 = 0.$$

Therefore, two solutions $t_0(m)$ and $t_1(m)$ of the above equation are given by (4.8) and (4.9).

Remark. The values $t_0(m)$ and $t_1(m)$ for $m=15, 19$ are given by

$$\begin{aligned} t_0(15) &= 0.6205 \dots, & t_1(15) &= 0.6523 \dots, \\ t_0(19) &= 0.6493 \dots, & t_1(19) &= 0.7036 \dots. \end{aligned}$$

PROPOSITION 4.5. *Let $\Omega_{(t)}$ denote the eigenspace of $J_{(t)}$ corresponding to $\mu(t)$, and let $\Omega'_{(t)} = \{w_{[f, t]}; f \in V_1\}$. Then $\Omega_{(t)} = \Omega'_{(t)}$ and $\dim \Omega_{(t)} = m+1$ hold except for at most countably many values of t in $(0, \infty)$.*

Proof. Let $\{f_1, f_2, \dots, f_{m+1}\}$ be a basis of V_1 and define $w_{[f, t]}$ by (4.5) with $f = f_\rho$. For each t , the set

$$\{w_{[f_\rho, t]}; \rho = 1, 2, \dots, m+1\}$$

is linearly independent. In fact, it suffices to see that the set $\{w_{[f_\rho, t]}(\eta_{(1)})\} = \{f_\rho\}$ is linearly independent. So, we have $\dim \Omega'_{(t)} = m+1$. For all t , $\Omega_{(t)} \supset \Omega'_{(t)}$ is trivial. At $t=1$, we see that $\dim \Omega_{(1)} = m+1 = \dim \Omega'_{(1)}$. Next, if t is near 1, then $\Omega_{(t)} = \Omega'_{(t)}$, and $\dim \Omega_{(t)} = m+1$. Since $J_{(t)}$ depends on t analytically, the case $\dim \Omega_{(t)} > m+1$ happens only for at most countably many values of t .

PROPOSITION 4.6. *For each α , $L_{\xi_{(\alpha)}}$ defines an isomorphism of $\Omega'_{(t)}$.*

Proof. Since $\xi_{(\alpha)}$ is a Killing vector field with respect to $g(t)$, two operators $L_{\xi_{(\alpha)}}$ and $J_{(t)}$ are commutative. Thus, $L_{\xi_{(\alpha)}}$ preserves $\Omega_{(t)}$. Since $\Omega_{(t)} = \Omega'_{(t)}$ except for at most countably many values of t , $L_{\xi_{(\alpha)}}$ preserves $\Omega'_{(t)}$.

Remark. The expression (4.5) of $w_{[f, t]}$ is based on $\xi_{(1)}$ and $\phi_{(1)}$. Contrary to this, we define $w'_{[f, t]}$ and $w''_{[f, t]}$ by

$$(4.10) \quad w'_{[f, t]} = f \eta_{(2)} + k(t) df \cdot \phi_{(2)} + (1-k(t))((\xi_{(1)} f) \eta_{(3)} - (\xi_{(3)} f) \eta_{(1)}),$$

$$(4.11) \quad w''_{[f, t]} = f \eta_{(3)} + k(t) df \cdot \phi_{(3)} + (1-k(t))((\xi_{(2)} f) \eta_{(1)} - (\xi_{(1)} f) \eta_{(2)}).$$

Then we have the following relations:

$$\begin{aligned} L_{\xi_{(1)}} w_{[f, t]} &= w_{[\xi_{(1)} f, t]}, \\ L_{\xi_{(2)}} w_{[f, t]} &= w_{[\xi_{(2)} f, t]} - 2w''_{[f, t]}, \\ L_{\xi_{(3)}} w_{[f, t]} &= w_{[\xi_{(3)} f, t]} + 2w'_{[f, t]}. \end{aligned}$$

Since $L_{\xi_{(\alpha)}} w_{[f, t]}$ and $w_{[\xi_{(\alpha)} f, t]}$ belong to $\Omega'_{(t)}$, we see that $w'_{[f, t]}$ and $w''_{[f, t]}$ belong to $\Omega'_{(t)}$. This means that the expression (4.5) based on $\xi_{(1)}$ and $\phi_{(1)}$ is

enough for our purpose.

Remark. Let X be a unit tangent vector at a point x of $(S^{4r+3}, g(t))$ satisfying $\eta_{(t)}(X)=0$ for $\alpha=1, 2, 3$, then the sectional curvature $K_{(t)}(X, \phi_{(t)}X)$ is given by

$$K_{(t)}(X, \phi_{(t)}X)=t(4-3t^{m/3}).$$

So, it takes a negative value for $4 < 3t^{m/3}$.

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