

A remark on ellipticity of general systems of partial differential operators with constant coefficients

By

Shigetake MATSUURA

(Received, June 15, 1961)

1. In the previous paper [4], we treated systems of partial differential operators of the form

$$P\left(\frac{1}{i} \frac{\partial}{\partial x}\right) = \begin{pmatrix} P_{11}\left(\frac{1}{i} \frac{\partial}{\partial x}\right) \cdots P_{1n}\left(\frac{1}{i} \frac{\partial}{\partial x}\right) \\ \cdots \\ P_{m1}\left(\frac{1}{i} \frac{\partial}{\partial x}\right) \cdots P_{mn}\left(\frac{1}{i} \frac{\partial}{\partial x}\right) \end{pmatrix},$$

where $P_{jk}(X)$ is a polynomial of l variables $X=(X_1, \dots, X_l)$ with complex coefficients¹⁾. Replacing X by $\frac{1}{i} \frac{\partial}{\partial x} = \left(\frac{1}{i} \frac{\partial}{\partial x_1}, \dots, \frac{1}{i} \frac{\partial}{\partial x_l}\right)$, we get the differential operator $P_{jk}\left(\frac{1}{i} \frac{\partial}{\partial x}\right)$. We can suppose here, without loss of generality, $m \geq n$ (see [4] §2.).

In the polynomial ring $\mathcal{C}[X_1, \dots, X_l]$, denote by α the ideal generated by all the (n, n) -minors of the matrix $P(X) = (P_{jk}(X))$. And denote by V the affine variety defined by α . Let us recall some concepts defined in [4].

Definition 1. A differential operator $P\left(\frac{1}{i} \frac{\partial}{\partial x}\right)$ is called *elliptic* if the corresponding variety V has no real point at infinity.

Definition 2. A differential operator $P\left(\frac{1}{i} \frac{\partial}{\partial x}\right)$ is called *analytic-hypoelliptic* if every solution U of the equation

1) For notations, see [4].

$$P\left(\frac{1}{i} \frac{\partial}{\partial x}\right)U = F$$

is (real) analytic in the open set of R^l where the right hand side F is analytic. Here F is a known and U is an unknown column vector function²⁾ with n and m components respectively.

One of the results obtained in [4] is the following

THEOREM. *For the operator $P\left(\frac{1}{i} \frac{\partial}{\partial x}\right)$, ellipticity is a necessary and sufficient condition for analytic-hypoellipticity³⁾.*

To prove the sufficiency in the above theorem, the ellipticity of the differential operator corresponding to Lech's polynomial $L(X) \in \mathfrak{a}$ was used in [4] (see Corollary to Theorem 2 and the proof of Theorem 4 in [4]). For the proof of the previous theorem, however, only the existence of a polynomial $\in \mathfrak{a}$ corresponding to an elliptic differential operator is needed. And the use of Lech's theorem (see [3]) seems too heavy for the purpose. Therefore, in the following, we give a proof of its existence without using Lech's theorem. (We use only *Hilbert's basis theorem* instead.)

2. To this end, it is sufficient to prove the following

PROPOSITION. *For any given ideal \mathfrak{a} in $\mathbf{C}[X_1, \dots, X_l]$, there exists a polynomial f in \mathfrak{a} such that any real point at infinity of the hypersurface H defined by f is also a real point at infinity of the variety V defined by \mathfrak{a} .*

And replace Lech's polynomial L in the proof of Theorem 4 in [4] by the above polynomial f .

Proof of Proposition. Let $P_l(\mathbf{C})$ be the complex projective space of l dimensions with a fixed homogeneous coordinates system which contains canonically the real projective space $P_l(\mathbf{R})$ and the complex affine space \mathbf{C}^l .

2) Strictly speaking, each component of these vectors is a distribution of L. Schwartz [5].

3) See Theorem 4 in [4], where F is supposed to be 0 for simplicity but the proof doesn't require any change for general F .

Let $\varphi: \mathcal{C}[X_0, X_1, \dots, X_l] \rightarrow \mathcal{C}[X_1, \dots, X_l]$ be the homomorphism sending each polynomial $h(X_0, X_1, \dots, X_l)$ into $h(1, X_1, \dots, X_l)$, and consider the ideal α^* in $\mathcal{C}[X_0, X_1, \dots, X_l]$ generated by the homogeneous elements in $\varphi^{-1}(\alpha)$. Take a system of generators h_1, \dots, h_N of α^* . Since α^* is a homogeneous ideal (see [2, pp. 30-31]), we can suppose that h_1, \dots, h_N are homogenous polynomials. Let d_s be the degree of h_s and put $g_s = h_s^{\frac{d}{d_s}}$ with d the least common multiple of d_1, \dots, d_N . And consider the following homogeneous polynomial in α^*

$$g = \sum_{s=1}^N g_s \bar{g}_s,$$

where \bar{g}_s is the polynomial whose coefficients are complex conjugates of those of g_s .

In $P_l(\mathcal{C})$, let V^* be the variety defined by α^* , H^* be the hypersurface defined by g . H^* is well-defined since g is homogeneous. Then, by the construction above, it is evident that

$$P_l(\mathbf{R}) \cap V^* = P_l(\mathbf{R}) \cap H^*.$$

And it is clear that the polynomial $f=f(X_1, \dots, X_l)=g(1, X_1, \dots, X_l)$ satisfies the requirements of the proposition.

3. We notice here that the original basis of α , i.e. the set of the (n, n) -minors of $P(X)$ cannot always play the role played by the basis of the homogeneous ideal α^* . For instance, consider the following system of differential equations in two independent variables $x=(x_1, x_2)$ and in one unknown function $u=u(x_1, x_2)$.

$$\begin{cases} P_1\left(\frac{1}{i} \frac{\partial}{\partial x}\right)u = \frac{1}{i} \frac{\partial}{\partial x_1}u + u = 0, \\ P_2\left(\frac{1}{i} \frac{\partial}{\partial x}\right)u = \frac{1}{i} \frac{\partial}{\partial x_1}u = 0. \end{cases}$$

Subtracting the second from the first, we see that this system has no solution other than the trivial one $u=0$. Therefore, accord-

ing to the theorem in the first section, this system is elliptic⁴⁾. But the operator

$$\begin{aligned} P_1\left(\frac{1}{i}\frac{\partial}{\partial x}\right)\bar{P}_1\left(\frac{1}{i}\frac{\partial}{\partial x}\right) + P_2\left(\frac{1}{i}\frac{\partial}{\partial x}\right)\bar{P}_2\left(\frac{1}{i}\frac{\partial}{\partial x}\right) \\ = -2\frac{\partial^2}{\partial x_1^2} + \frac{2}{i}\frac{\partial}{\partial x_1} + 1 \end{aligned}$$

is clearly not an elliptic operator in two variables (x_1, x_2) .

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4) For the analytic-hypoellipticity, it is sufficient that every solution of the equation with the right hand side 0 is analytic (see [4] § 6. Definition 4, ii) and Theorem 4).