

# On some relations between the harmonic measure and the Lévy measure for a certain class of Markov processes

By

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**1. Introduction.** Consider a Markov process  $x(t)$  on a locally compact separable metric space  $S$  with right continuous path functions and, given an open set  $D$ , let  $\tau_D$  be the first passage time for the complement of  $D$ . The main purpose of this paper is to establish the following relation

$$E_x(e^{-\lambda\tau_D}; x(\tau_D) \in E) = \int_D \bar{g}_\lambda^D(x, dy)n(y, E)^{1)},$$

under some appropriate conditions where  $\bar{g}_\lambda^D(x, \cdot)$  is the *Green measure* of the subprocess on  $D$ :

$$\bar{g}_\lambda^D(x, \cdot) = E_x \left( \int_0^{\tau_D} e^{-\lambda t} \chi_\cdot(x_t) dt \right)^{2)}$$

and  $n(y, E)$  is *Lévy measure* of this process:

$$n(y, E)\Delta t \sim P_y(x(\Delta t) \in E) \quad (t \downarrow 0).$$

This relation was first introduced by J. Elliott and W. Feller [4] for the Cauchy process on the line  $(-\infty, \infty)$  and was used for the investigation of the symmetric stable processes [3], [8].

It is natural to conjecture that

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1) The suffix  $x$  of  $E_x$ ,  $P_x$ , etc. refers to the starting point,  
2)  $\chi_E(x)$  is the characteristic function of set  $E$ .

$$\begin{aligned} E_x(e^{-\lambda\tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E) \\ = \int_F \bar{g}_\lambda^D(x, dy)n(y, E) \end{aligned}$$

for  $F \subset D$  and  $\rho(E, D) > 0^3$ , and this formula will be proved under certain assumptions. We shall apply this formula to the one-sided stable process  $x(t)$  to compute the joint distribution of  $x(\tau_D-)$  and  $x(\tau_D)$  for  $D = [0, b)$  which was obtained by E. B. Dynkin [1] by a different method.

**2. Assumptions.** Let  $M = (S, P_x, x \in S)$  be a Markov process on a locally compact, separable, metric space  $S$  which satisfies the following two assumptions.

(A.1) *Its semi-group*

$$T_t f(x) = \int_S f(y)P(t, x, dy)$$

maps  $C(\bar{S})$  into  $C(\bar{S})^4$  and is strongly continuous in  $t \geq 0$ .

(A.2) *There exists a positive kernel<sup>5)</sup>  $n(x, E)$ ,  $x \in S$ ,  $E \in \mathbf{B}(S)^6$  such that*

$$(i) \quad n(x, E) < +\infty \quad \text{if } \rho(x, E) > 0,$$

and

$$(ii) \quad \text{for } f \in C(\bar{S}) \quad \text{and a bounded open set } D$$

with  $\rho(D, S(f)) > 0^7$ ,

$$T_t f(x)/t \text{ is uniformly bounded in } x \in D, t > 0$$

and

$$\lim_{t \downarrow 0} T_t f(x)/t = \lim_{t \downarrow 0} \int_S f(y)P(t, x, dy)/t = \int_S f(y)n(x, dy)$$

for every  $x \in D$ .

We shall call  $n(x, E)$  the *Lévy measure* of the process  $M$ .

3)  $\rho$  is the metric of the state space  $S$ .

4)  $\bar{S} = S$  if  $S$  is compact and  $\bar{S} = S \cup \{\infty\}$  is the one-point compactification of  $S$  if  $S$  is not compact.  $C(\bar{S})$  is the Banach space of all continuous functions on  $\bar{S}$  which vanish at  $\infty$ .

5) Hunt's terminology, cf. [5].

6)  $\mathbf{B}(S)$  is the topological Borel field of  $S$ .

7)  $S(f)$  is the support of  $f$ .

**Remark.** We assume as we may by virtue of (A.1) that the path functions are right continuous and have left limits and that, if  $\{\sigma_n\}$  is an increasing sequence of Markov times, then

$$\lim_{n \uparrow +\infty} x(\sigma_n(w), w) = x(\lim_{n \uparrow +\infty} \sigma_n(w), w)$$

for almost all  $w$  for which  $\sigma_n(w)$  is bounded.

**Example 1.** Let  $x(t, w)$  be a temporally homogeneous Lévy process on  $R^n$  given by

$$E(\exp i(\xi, x_t)) = \exp \{t\psi(\xi)\},$$

where

$$\psi(\xi) = i(m, \xi) - (v\xi, \xi)/2 + \int_{R^n} \left( e^{i(\xi, u)} - 1 - \frac{i(\xi, u)}{1 + |u|^2} \right) \sigma(du).$$

This process induces a Markov process if we define the probability law governing the paths starting at  $x \in R^n$  by

$$P_x(B) = P(x + x(\cdot, w) \in B),$$

where  $B$  is a Borel subset of the space of path functions<sup>8)</sup>. The process thus obtained satisfies (A.1) and (A.2) and in this case

$$n(x, E) = \sigma(E - x);$$

in fact, putting  $\pi_t(E) = P(x(t, w) \in E)$ , we have

$$T_t f(x) = \int_{R^n} f(x+y) \pi_t(dy)$$

from which (A.1) follows at once, and using the known fact

$$\pi_t(E)/t \rightarrow \sigma(E) \quad (t \downarrow 0) \quad \text{for any continuity set } E$$

for the measure  $\sigma$  such that  $\rho(E, 0) > 0$ , we have (A.2).

**Example 2.** Let  $x(t, w)$  be a Markov process on  $S$  which satisfies the condition (A.1) and (A.2). We shall denote its transition probability and Lévy measure by  $P^1(t, x, E)$  and  $n^1(x, E)$  respectively<sup>9)</sup>.

8) Cf. [6].

9) If  $P^1(t, x, E) = o(t)$ , uniformly in  $x \in D$ ,  $\rho(E, D) > 0$ , (A.2) is trivially satisfied and  $n^1(x, E) \equiv 0$ .

Let  $\theta(t, w)$  be a one-dimensional Lévy process with increasing paths given by

$$E\{\exp[-\gamma\theta(t)]\} = \exp\{-t\psi(\gamma)\}, \quad \gamma \geq 0, \quad \theta(0) = 0,$$

where

$$\begin{aligned} \psi(\gamma) &= c\gamma + \int_0^\infty (1 - e^{-\gamma u})n(du), \\ c &\geq 0, \quad \int_0^\infty \frac{u}{1+u}n(du) < +\infty. \end{aligned}$$

Further we assume that these two processes  $x(t, w)$  and  $\theta(t, w)$  are independent. Then the process  $y(t, w)$  defined by

$$y(t, w) = x(\theta(t, w), w)$$

is a Markov process on  $S$  which satisfies (A.1) and (A.2) and the Lévy measure  $n(x, E)$  is given by

$$n(x, E) = cn^1(x, E) + \int_0^\infty P^1(\tau, x, E)n(d\tau).$$

For the proof, putting  $F_t(d\tau) = P(\theta(t) \in d\tau)$  and  $T_t^1 f(x) = E_x\{f(x(t))\} = \int_S f(y)P^1(t, x, dy)$ , we define  $P(t, x, E)$   $T_t f(x)$  by

$$\begin{aligned} P(t, x, E) &= \int_0^\infty P^1(\tau, x, E)F_t(d\tau) \\ T_t f(x) &= \int_S f(y)P(t, x, dy) = \int_0^\infty T_\tau^1 f(x)F_t(d\tau). \end{aligned}$$

Then it is easy to show that

$$\begin{aligned} \|T_t f\| &\leq \|f\|,^{10)} \\ T_{t+s} &= T_t T_s, \\ \|T_t f - f\| &\rightarrow 0, \quad t \downarrow 0, \end{aligned}$$

and

$$\begin{aligned} &P_x(y(t_1) \in E_1, \dots, y(t_n) \in E_n) \\ &= \int_{E_1} \dots \int_{E_n} P(t_1, x, dx_1)P(t_2 - t_1, x_1, dx_2) \dots P(t_n - t_{n-1}, x_{n-1}, dx_n). \end{aligned}$$

Hence  $y(t, w)$  is a Markov process on  $S$  which satisfies (A.1), (cf. [6]).

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10)  $\| \cdot \|$  is the norm of  $C(\bar{S})$ :  $\|f\| = \max_{x \in \bar{S}} |f(x)|$ .

Now (A.2) can be proved by using the method given by K. Ito [7]. Since it was published in Japanese only, we shall reproduce here some of his arguments. We have

$$\begin{aligned} \int_0^\infty (1-e^{-\lambda\tau}) \frac{F_t(d\tau)}{t} &= (1-E(e^{-\lambda\theta_t}))/t = \{1-e^{-t\psi(\lambda)}\}/t \\ &\rightarrow \psi(\lambda) = c\lambda + \int_0^\infty (1-e^{-\lambda\tau})n(d\tau), \quad (t \downarrow 0). \end{aligned}$$

Put

$$G_t(d\tau) = (1-e^{-\tau})F_t(d\tau)/t, \quad t > 0,$$

and

$$G(d\tau) = (1-e^{-\tau})n(d\tau) + c\delta_0(d\tau).$$

We shall prove that for any bounded and continuous function  $\varphi(\tau)$ ,  $0 \leq \tau < +\infty$ ,

$$\int_0^\infty \varphi(\tau)G_t(d\tau) \rightarrow \int_0^\infty \varphi(\tau)G(d\tau), \quad t \downarrow 0.$$

For this it is sufficient to show that considering  $G_t(d\tau)$  and  $G(d\tau)$  as measures on  $[0, +\infty]$   $G_t(d\tau)$  converges weakly to  $G(d\tau)$ , since  $G(\{+\infty\})=0$ . Take any sequence  $\{t_n\}$  tending to zero. Since the total measure of  $G_{t_n}$  is bounded in  $n$ , there exists some subsequence  $\{s_n\}$  of  $\{t_n\}$  such that

$$G_{s_n} \rightarrow G^* \text{ weakly for some measure } G^* \text{ on } [0, +\infty].$$

Define  $h_\lambda(\tau)$  by

$$\begin{aligned} h_\lambda(\tau) &= \lambda, & \tau &= 0, \\ &= (1-e^{-\lambda\tau})/(1-e^{-\tau}), & 0 < \tau < \infty, \\ &= 1, & \tau &= \infty, \end{aligned}$$

then  $h_\lambda(\tau) \in C[0, +\infty]$  and hence

$$\int_0^\infty h_\lambda(\tau)G_{s_n}(d\tau) \rightarrow \int_{[0, +\infty]} h_\lambda(\tau)G^*(d\tau).$$

On the otherhand

$$\begin{aligned} \int_0^\infty h_\lambda(\tau)G_{s_n}(d\tau) &= \int_0^\infty (1-e^{-\lambda\tau})F_{s_n}(d\tau)/s_n \\ &\rightarrow c\lambda + \int_0^\infty (1-e^{-\lambda\tau})n(d\tau) = \int_0^\infty h_\lambda(\tau)G(d\tau) \end{aligned}$$

and hence we have

$$\int_{[0, +\infty[} h_\lambda(\tau) G^*(d\tau) = \int_0^\infty h_\lambda(\tau) G(d\tau).$$

Letting  $\lambda \downarrow 0$  we have, since  $h_\lambda(\tau) \rightarrow 0$  ( $\tau \neq +\infty$ ) and  $h_\lambda(+\infty) \equiv 1$ ,

$$G^*(\{+\infty\}) = G(\{+\infty\}) = 0.$$

$$\begin{aligned} \text{Now } \int_{[0, \infty)} h_\lambda(\tau) G^*(d\tau) &= \lambda G^*(\{0\}) + \int_{(0, \infty)} (1 - e^{-\lambda\tau}) G^*(d\tau) / (1 - e^{-\tau}) \\ &= c\lambda + \int_{(0, \infty)} (1 - e^{-\lambda\tau}) G(d\tau) / (1 - e^{-\tau}) \\ &= \int_{[0, \infty)} h_\lambda(\tau) G(d\tau) \end{aligned}$$

and putting  $H^*(\sigma) = \int_\sigma^\infty G^*(d\tau) / (1 - e^{-\tau})$  and  $H(\sigma) = \int_\sigma^\infty G(d\tau) / (1 - e^{-\tau})$ , we have from this

$$G^*(\{0\}) + \int_0^\infty H^*(\tau) e^{-\lambda\tau} d\tau = c + \int_0^\infty H(\tau) e^{-\lambda\tau} d\tau.$$

Letting  $\lambda \uparrow +\infty$  we have

$$\begin{aligned} G^*(\{0\}) &= c = G(\{0\}) \\ \int_0^\infty H^*(\tau) e^{-\lambda\tau} d\tau &= \int_0^\infty H(\tau) e^{-\lambda\tau} d\tau. \end{aligned}$$

This proves  $H^*(\tau) = H(\tau)$  and hence

$$G^* = G,$$

that is

$$G_{S_n} \rightarrow G \text{ weakly on } [0, +\infty[.$$

Now returning to (A.2), take  $f \in C(\bar{S})$  with  $(S(f), D) > 0$ , then

$$\begin{aligned} T_t f(x) / t &= \int_0^\infty T_\tau^1 f(x) F_t(d\tau) / t \\ &= \int_0^\infty \frac{T_\tau^1(x)}{1 - e^{-\tau}} G_t(d\tau). \end{aligned}$$

Since  $x_t$ -process satisfies (A.2),  $T_\tau^1 f(x) / \tau$  is uniformly bounded in  $x \in D$ ,  $\tau > 0$  and  $\lim_{\tau \downarrow 0} T_\tau^1 f(x) / \tau = \int f(y) n^1(x, dy)$ , where  $n^1(x, dy)$  is the Lévy measure of  $x_t$ -process.

Defining  $\varphi(\tau)$  as

$$\begin{aligned} \varphi(\tau) &= T_\tau^1 f(x)/(1-e^{-\tau}), \quad 0 < \tau < +\infty, \\ &= \int f(y)n^1(x, dy), \quad \tau = 0, \end{aligned}$$

$\varphi(\tau)$  is a bounded and continuous function on  $[0, +\infty)$  and hence

$$\int_0^\infty \varphi(\tau)G_t(d\tau) \rightarrow \int_0^\infty \varphi(\tau)G(d\tau),$$

this means

$$\begin{aligned} T_t f(x)/t &\rightarrow c \int f(y)n^1(x, dy) + \int_0^\infty T_\tau^1 f(x)n(d\tau) \\ &= \int f(y) \left\{ cn^1(x, dy) + \int_0^\infty P^1(\tau, x, dy)n(d\tau) \right\}. \end{aligned}$$

This proves that  $y_t$ -process satisfies (A.2) and the Lévy measure is given by

$$n(x, E) = cn^1(x, E) + \int_0^\infty P^1(\tau, x, E)n(d\tau).$$

**3. The joint distribution of  $\tau_D$  and  $x(\tau_D)$ .** Let  $M=(S, P_x, W)$  be a Markov process on  $S$  which satisfies (A.1) and (A.2) and let  $D$  be an open set in  $S$  such that  $\bar{D}$  is compact. Define  $\tau_D(w)$  for any path function  $x(t, w)$  by

$$\begin{aligned} \tau_D(w) &= \inf \{t; t \geq 0, x(t, w) \notin D\}, \\ &= +\infty \quad \text{if there is no such } t. \end{aligned}$$

The subprocess  $M^D = (D, \bar{P}_x^D, x \in D)$  of  $M$  on  $D$  is a Markov process on  $D$  obtained from  $M$  by killing the paths of  $M$  at time  $\tau_D$ <sup>11)</sup>.

Its transition probability  $\bar{P}^D(t, x, E)$  is given by

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11) The precise definition is as follows: we take as the probability space  $W$  of  $M$  the set of all functions  $w; [0, +\infty) \rightarrow S \cup \{\omega\}$  which are right continuous and have left limits and further if  $w(t)=\omega$  then for any  $s \geq t, w(s)=\omega$ , where  $\omega$  is an extra point (killing point) which we add to  $S$  as an isolated one. Define a mapping  $w \rightarrow w_{\tau_D}$  from  $W$  into itself by

$$\begin{aligned} w_{\tau_D}(t) &= w(t), \quad t < \tau_D(w), \\ &= \omega, \quad t \geq \tau_D(w). \end{aligned}$$

Then  $M^D=(D, \bar{P}_x^D, x \in D)$  is defined from the process  $M$  by  $\bar{P}_x^D(B)=P_x(w; w_{\tau_D} \in B), x \in D$ .

$$\bar{P}^D(t, x, E) = P_x(x(t, w) \in E, \tau_D(w) > t), \quad x \in D, \quad E \in \mathbf{B}(S).$$

Also we put

$$\bar{g}_\lambda^D(x, E) = \int_0^\infty e^{-\lambda t} \bar{P}^D(t, x, E) dt = E_x \left\{ \int_0^{\tau_D} e^{-\lambda t} \chi_E(x(t, w)) dt \right\}, \quad \lambda > 0. \quad ^{12)}$$

**Theorem 1.** *If  $\rho(D, E) > 0$ , we have for every  $x \in D$  and  $\lambda > 0$ ,*

$$(1) \quad E_x \{ e^{-\lambda \tau_D}; x(\tau_D) \in E \} = \int_D \bar{g}_\lambda^D(x, dy) n(y, E),$$

and this formula holds also for  $\lambda = 0$  if

$$(A.3) \quad E_x(\tau_D) < +\infty.$$

Proof. Take any  $f \in C(\bar{S})$  such that it has the compact support and  $f \equiv 0$  on some neighborhood of  $\bar{D}$ .

Put

$$nG_n f(x) = u_n(x).$$

Then it follows immediately from the assumption (A.1) that  $u_n(x)$  converges to  $f(x)$  uniformly in  $x \in S$ . In particular,

$$\lim_{n \rightarrow \infty} u_n(x) = 0, \quad \text{uniformly on } D.$$

Now

$$\begin{aligned} nu_n(x) &= n^2 \int_0^\infty e^{-nt} T_t f(x) dt \\ &= \int_0^\infty e^{-t} T_{t/n} f(x) / t / n dt. \end{aligned}$$

By the assumption (A.2), we have that

$$T_{t/n} f(x) / t / n \text{ is uniformly bounded in } x \in D, \quad t > 0, \quad n = 1, 2, \dots$$

and for fixed  $t$

$$\lim_{n \rightarrow \infty} T_{t/n} f(x) / t / n = \int f(y) n(x, dy), \quad x \in D.$$

Hence by Lebesgue convergence theorem

$$\begin{aligned} \lim_{n \rightarrow \infty} nu_n(x) &= \int_0^\infty e^{-t} dt \int f(y) n(x, dy) \\ &= \int f(y) n(x, dy), \quad x \in D, \end{aligned}$$

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12) If  $E_x(\tau_D) < +\infty$ ,  $x \in D$ , then  $\bar{g}_\lambda^D(x, E)$  can be defined including  $\lambda = 0$ .

and the above convergence is bounded on  $D$ .

Let  $\mathfrak{G}$  be the generator of  $M$ , then if  $x \in D$ ,

$$\begin{aligned} \mathfrak{G}u_n(x) &= nu_n(x) - nf(x) \\ &= nu_n(x). \end{aligned}$$

Hence

$$\lim_{n \uparrow \infty} \mathfrak{G}u_n(x) = \int f(y)n(x, dy), \quad x \in D,$$

and  $\mathfrak{G}u_n(x)$  is bound on  $D$  uniformly in  $n$ . Hence it follows from the Dynkin formula (cf. [6]).

$$\begin{aligned} &E_x(e^{-\lambda\tau_D}u_n(x(\tau_D))) - u_n(x) \\ &= -E_x \left\{ \int_0^{\tau_D} e^{-\lambda t} (\lambda - \mathfrak{G})u_n(x(t)) dt \right\} \\ &= - \int_D \bar{g}_\lambda^D(x, dy) (\lambda - \mathfrak{G})u_n(y), \quad x \in D, \quad \lambda > 0. \end{aligned}$$

Letting  $n \uparrow +\infty$ , we have

$$\begin{aligned} E_x \{ e^{-\lambda\tau_D} f(x(\tau_D)) \} &= \int_D \bar{g}_\lambda^D(x, dy) \int f(z)n(y, dz) \\ &= \int f(z) \left( \int_D \bar{g}_\lambda^D(x, dy) n(y, dz) \right), \end{aligned}$$

since  $u_n(x)$  converges uniformly to  $f(x)$  and  $f(x) \equiv 0$  on  $D$ . This proves the theorem.

We introduce the following assumption (A.4).

(A.4) For every point  $x_0 \in S$ , if  $f \in C(S)$  vanishes on some neighborhood of  $x_0$  then

$$\int f(y)n(x, dy)$$

is continuous at  $x = x_0$ .

**Remark.** Every process of Example 1 satisfies this assumption.

**Corollary 1.** If the process  $M$  satisfies (A.4) and every point is no trap, then putting  $\pi^{U_n}(x, dy) = P_x(x(\tau_{U_n}) \in dy)$  for a neighborhood  $U_n$  of  $x$ , we have

$$\frac{\pi^{U_n}(x, dy)}{E_x(\tau_{U_n})} \rightarrow n(x, dy), \quad \text{when } U_n \downarrow x,$$

in the sense that for any function  $f \in C(S)$  which vanishes on some neighborhood of  $x$ , we have

$$\lim_{U_n \downarrow x} \frac{\int \pi^{U_n}(x, dy) f(y)}{E_x(\tau_{U_n})} = \int n(x, dy) f(y).$$

Proof. We remark first that by Lemma 4 of Dynkin [2] there exists a neighborhood  $U$  of  $x$  such that  $E_y(\tau_U) < +\infty$ ,  $y \in U$ . Then from (1) we have for every  $U' \subset U$  and  $x' \in U'$

$$P_{x'}(x(\tau_{U'}) \in E) = \int \bar{g}_0^{U'}(x', dy) n(y, E).$$

Hence

$$\begin{aligned} \frac{\int_{U_n} \pi^{U_n}(x, dy) f(y)}{E_x(\tau_{U_n})} &= \frac{\int_{U_n} \bar{g}_0^{U_n}(x, dz) \int n(z, dy) f(y)}{\int_{U_n} \bar{g}_0^{U_n}(x, dz)} \\ &= \frac{E_x\left(\int_0^{\tau_{U_n}} \left\{ \int n(x_t, dy) f(y) \right\} dt\right)}{E_x\left(\int_0^{\tau_{U_n}} dt\right)} \\ &\rightarrow \int n(x, dy) f(y), \quad U_n \downarrow x, \end{aligned}$$

from the continuity of  $\int n(z, dy) f(y)$  at  $z=x$  and the right-continuity of the path functions.

**4. The joint distribution of  $\tau_D$ ,  $x(\tau_D^-)$ , and  $x(\tau_D)$ .** Define  $x(\tau_D(w)^-, w) \equiv x(\tau_D^-)$  by

$$x(\tau_D(w)^-, w) = \lim_{n \rightarrow \infty} x\left(\tau_D(w) - \frac{1}{n}, w\right).$$

We want to obtain the joint distribution of  $\tau_D$ ,  $x(\tau_D^-)$  and  $x(\tau_D)$ . For this purpose we introduce the following assumption (A.5).

Put  $D_n = \left\{ x; \rho(x, D^c) > \frac{1}{n} \right\}$ , then

$$D_1 \subset D_2 \subset \dots, \quad \bar{D}_n \subset D_{n+1} \quad \text{and} \quad \lim D_n = D.$$

(A.5). *There exists a finite Borel measure  $m$  on  $D$  such that the Green measure  $\bar{g}_\lambda^D(x, \cdot)$  is absolutely continuous with respect to  $m$ :*

$$\bar{g}_\lambda^D(x, E) = \int_E \bar{g}_\lambda^D(x, y)m(dy).$$

Further the operator

$$G_\lambda^* : C(D) \ni f(x) \rightarrow u(x) = \int \bar{g}_\lambda^D(y, x)f(y)m(dy)$$

maps  $C(D)^{13)}$  into  $C(D)$  and the range  $G_\lambda^*(C(D))$  is dense in each  $C(\bar{D}_n)$ ,  $n=1, 2, \dots$ .

**Theorem 2.** *If the process  $M$  satisfies (A.5), then we have,  $\lambda > 0$ ,  $x \in D$ ,*

$$\begin{aligned} (2) \quad E_x \{e^{-\lambda\tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E\} \\ &= \int_F \bar{g}_\lambda^D(x, dy)n(y, E) \\ &= \int_F \bar{g}_\lambda^D(x, y)n(y, E)m(dy), \end{aligned}$$

for  $E, F \in \mathbf{B}(S)$  such that  $\rho(E, D) > 0$  and  $F \subset D$ , and the formula holds also for  $\lambda=0$  if (A.3) is satisfied.

*Proof.* It is enough to prove (2) for a closed set  $F \subset D$  such that  $m(\partial F)=0$ , since both sides are Borel measures with respect to the set  $F \subset D$ .

Now take such  $F$  and  $\lambda > 0$ . Put for  $x \in D$

$$\begin{aligned} u(x) &= E_x(e^{-\lambda\tau_D}; x(\tau_D) \in E, x(\tau_D-) \in F) \\ v_n(x) &= E_x(e^{-\lambda\tau_D}; x(\tau_D) \in E, x(\tau_D-) \in D_n - F) \\ v(x) &= E_x(e^{-\lambda\tau_D}; x(\tau_D) \in E, x(\tau_D-) \in D - F), \end{aligned}$$

and

$$w(x) = E_x(e^{-\lambda\tau_D}; x(\tau_D) \in E).$$

Then it is obvious that  $v_1 \leq v_2 \leq \dots$  and  $\lim_{n \uparrow +\infty} v_n = v$  on  $D$ . We have also

$$w(x) = u(x) + v(x) \text{ on } D.$$

For this it is sufficient to show that

$$P_x(x(\tau_D-) \in \partial D, x(\tau_D) \in E) = 0.$$

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13)  $C(D) = \{f; f \text{ is bounded and continuous on } D\}$ .

Put  $E_n = D - D_n$ ,

$$\begin{aligned}\sigma_{E_n}(w) &= \inf \{t \geq 0, x_t \in E_n\} \\ &= +\infty, \text{ if there is no such } t,\end{aligned}$$

and

$$\sigma_n(w) = \min(\tau_D(w), \sigma_{E_n}(w)).$$

Then  $\sigma_n(w)$  is an increasing sequence of Markov times and it is easy to see that if  $x(\tau_D(w)-, w) \in \partial D$ , then

$$\sigma_n(w) = \sigma_{E_n}(w) < \tau_D(w)$$

for large  $n$  and  $x(\lim_{n \rightarrow +\infty} \sigma_n(w), w) = \lim_{n \rightarrow +\infty} x(\sigma_n(w), w) \in \partial D$ . This implies that  $\lim_{n \rightarrow \infty} \sigma_n(w) = \tau_D(w)$  and  $x(\tau_D(w), w) \notin E$ . Hence

$$P_x(x(\tau_D-) \in \partial D, x(\tau_D) \in E) = 0.$$

We shall now prove that  $u(x)$  is  $\lambda$ -excessive with respect to  $M^D$ -process, that is<sup>14)</sup>

$$e^{-\lambda t} \bar{E}_x^D(u(x(t))) \leq u(x)$$

and

$$e^{-\lambda t} \bar{E}_x^D(u(x(t))) \uparrow u(x), \quad t \downarrow 0,$$

at every point  $x \in D$ <sup>15)</sup>. For, using Markov property,

$$\begin{aligned}u(x) - e^{-\lambda t} \bar{E}_x^D(u(x(t))) &= u(x) - e^{-\lambda t} E_x(u(x(t)); t < \tau_D) \\ &= E_x(e^{-\lambda \tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E) \\ &\quad - e^{-\lambda t} E_x(E_{x(t)}(e^{-\lambda \tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E), t < \tau_D) \\ &= E_x(e^{-\lambda \tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E) \\ &\quad - E_x(e^{-\lambda t + \tau_D(w_t^+)}; x((t + \tau_D(w_t^+)) -) \in F, x(t + \tau_D(w_t^+)) \in E,^{16)} t < \tau_D) \\ &= E_x(e^{-\lambda \tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E) \\ &\quad - E_x(e^{-\lambda \tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E, t < \tau_D) \\ &= E_x(e^{-\lambda \tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E, t \geq \tau_D),\end{aligned}$$

and this decreases to zero with  $t \downarrow 0$  by the right continuity of path functions.

14)  $\bar{E}_x^D(\cdot)$  is the expectation with respect to  $M^D$ -process, thus  $\bar{E}_x^D(u(x(t))) = E_x(u(x(t)); t < \tau_D)$ , cf. foot note 11).

15) Cf. [5].

16)  $w_t^+$  is defined by  $w_t^+(s) = w(t+s)$ , cf. [6].

Let  $G$  ( $\bar{G} \subset D$ ) be an open neighborhood of  $F$  and  $\sigma_G$  be the first passage time for  $G$ :

$$\begin{aligned}\sigma_G(w) &= \inf \{t \geq 0; x(t, w) \in G\}, \\ &= +\infty, \text{ if there is not such } t.\end{aligned}$$

Then

$$\begin{aligned}u(x) &= E_x(e^{-\lambda\tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E) \\ &= E_x(e^{-\lambda\tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E, \tau_D > \sigma_G) \\ &\quad + E(e^{-\lambda\tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E, \tau_D < \sigma_G),\end{aligned}$$

and the second term is zero since if  $\sigma_G > \tau_D$   $x(\tau_D-) \notin F$ .

$$\begin{aligned}u(x) &= E_x(e^{-\lambda\tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E, \sigma_G < \tau_D) \\ &= E_x(e^{-\lambda(\sigma_G + \tau_D(w_{\sigma_G}^+))}; x((\sigma_G + \tau_D(w_{\sigma_G}^+)) -) \in F, \\ &\quad x(\sigma_G + \tau_D(w_{\sigma_G}^+)) \in E, \sigma_G < \tau_D) \\ &= E_x(e^{-\lambda\sigma_G} E_{x(\sigma_G)}(e^{-\lambda\tau_D}; x(\tau_D-) \in F, x(\tau_D) \in E); \sigma_G < \tau_D) \\ &= \bar{E}_x^D(e^{-\lambda\sigma_G} u(x_{\sigma_G})),\end{aligned}$$

by strong Markov property and hence from a theorem of Hunt [5, Th 6.6.] there exists a sequence of functions  $\{f_n\}$  ( $f_n \geq 0$ ) each vanishing outside  $G$  such that  $\int_G \bar{g}_\lambda^D(x, y) f_n(y) m(dy)$  increase to  $u(x)$  everywhere on  $D$  as  $n \uparrow +\infty$ . Take  $\varphi_0 \in C(D)$  such that

$$\psi(x) = G_\lambda^* \varphi_0(x) \geq 1, \quad x \in G,$$

(such a function exists by virtue of (A.5)). Then

$$\int_G f_n(y) m(dy) \leq \int_G \psi(y) f_n(y) m(dy) \leq \int_D u(x) \varphi_0(x) m(dx) < +\infty,$$

and hence there exists a bounded measure  $\mu$  on  $\bar{G}$  such that some subsequence of  $\{f_n(y) m(dy)\}$  converges to  $\mu$ . Then for  $\varphi \in C(D)$  we have

$$\begin{aligned}&\int_D u(x) \varphi(x) m(dx) \\ &= \lim_{n \uparrow +\infty} \int_D \left\{ \int_G \bar{g}_\lambda^D(x, y) f_n(y) m(dy) \right\} \varphi(x) m(dx) \\ &= \lim_{n \uparrow +\infty} \int_{\bar{G}} \left\{ \int_D \bar{g}_\lambda^D(x, y) \varphi(x) m(dx) \right\} f_n(y) m(dy)\end{aligned}$$

$$\begin{aligned}
 &= \int_{\bar{G}} \left\{ \int_D \bar{g}_\lambda^D(x, y) \varphi(x) m(dx) \right\} \mu(dy) \\
 &= \int_D \varphi(x) \left\{ \int_{\bar{G}} \bar{g}_\lambda^D(x, y) \mu(dy) \right\} m(dx).
 \end{aligned}$$

Hence

$$u(x) = \int_{\bar{G}} \bar{g}_\lambda^D(x, y) \mu(dy), \quad \text{a.a. } x \quad (m(dx)),$$

and since each function of both sides is  $\lambda$ -excessive with respect to  $M^D$ -process the above equality holds for every  $x \in D$ . From the assumption (A.5) we can easily see that the measure  $\mu$  is uniquely determined by  $u(x)$  and since  $G$  is an arbitrary neighborhood of  $F$ , it follows that the support of  $\mu$  is contained in  $F$ :

$$u(x) = \int_F \bar{g}_\lambda^D(x, y) \mu(dy).$$

Now a similar argument applies to  $v_n(y)$  and we can prove that for each  $n$  there exists a measure  $\nu_n$  such that

$$v_n(x) = \int_{D_n - F} \bar{g}_\lambda^D(x, y) \nu_n(dy).$$

It is easy to see that

$$\nu_1 \leq \nu_2 \leq \dots \dots \dots$$

and hence

$$v(x) = \lim_{n \uparrow +\infty} v_n(x) = \int_{D - \overset{\circ}{F}} \bar{g}_\lambda^D(x, y) \nu(dy)^{17)},$$

where

$$\nu = \lim_{n \uparrow +\infty} \nu_n.$$

Now using (1) we have

$$\begin{aligned}
 w(x) = u(x) + v(x) &= \int_D \bar{g}_\lambda^D(x, y) n(y, E) m(dy) \\
 &= \int_F \bar{g}_\lambda^D(x, y) \mu(dy) + \int_{D - \overset{\circ}{F}} \bar{g}_\lambda^D(x, y) \nu(dy).
 \end{aligned}$$

Noting the assumption  $m(\partial F) = 0$ , we have

17)  $\overset{\circ}{F}$  is the interior of  $F$ .

$$u(x) = \int_F \bar{g}_\lambda^D(x, y) n(y, E) m(dy)$$

$$v(x) = \int_{D-F} \bar{g}_\lambda^D(x, y) n(y, E) m(dy),$$

since the measure of a potential is uniquely determined by virtue of the assumption (A. 5).

This proves our theorem.

**Corollary 2.** *If the process  $\mathbf{M}$  satisfies besides (A. 3), (A. 5) the following condition (A. 6)<sup>18)</sup>,*

$$(A. 6) \quad P_x(x(\tau_D) \in \partial D) = 0,$$

then we have for  $E \in \mathbf{B}(S)$ ,  $\rho(E, D) > 0$ ,

$$(3) \quad P_x(x(\tau_D) \in E / x(\tau_D -) = y) = \frac{n(y, E)}{n(y, S - \bar{D})}, \quad y \in D.$$

Proof. Put  $U_n = \left\{ x; \rho(x, D) > \frac{1}{n} \right\}$ , then  $U_n \uparrow S - \bar{D}$  and

$$P_x(x(\tau_D -) \in F, x(\tau_D) \in U_n) = \int_F \bar{g}_0^D(x, dy) n(y, U_n).$$

Letting  $n \uparrow +\infty$ , we have, noting (A. 6)

$$P_x(x(\tau_D -) \in F) = \int_F \bar{g}_0^D(x, dy) n(y, S - \bar{D})$$

and

$$\int_F \frac{n(y, E)}{n(y, S - \bar{D})} n(y, S - \bar{D}) \bar{g}_0^D(x, dy)$$

$$= \int_F n(y, E) \bar{g}_0^D(x, dy)$$

$$= P_x(x(\tau_D -) \in F, x(\tau_D) \in E).$$

**Corollary 3.** *Under the same assumptions as in Cor. 2,  $\tau_D$  and  $x(\tau_D)$  are independent under the condition that  $x(\tau_D -)$  be given.*

Proof. By (3)

$$P_x(x(\tau_D) \in E / x(\tau_D -) = y) = \frac{n(y, E)}{n(y, S - \bar{D})}, \quad y \in D.$$

---

18) This condition is satisfied, e.g. in the case that  $\mathbf{M}$  is the symmetric stable process on  $R^n$  with exponent  $0 < \alpha < 2$  and  $D$  is a sphere in  $R^n$ .

Similarly, we can prove

$$E_x(e^{-\lambda\tau_D}/x(\tau_D-) = y) = \frac{\bar{g}_\lambda^D(x, y)}{\bar{g}_0^D(x, y)}, \quad y \in D,$$

and also

$$\begin{aligned} E_x(e^{-\lambda\tau_D}; x(\tau_D) \in E/x(\tau_D-) = y) \\ = \frac{n(y, E)}{n(y, S-\bar{D})} \frac{\bar{g}_\lambda^D(x, y)}{\bar{g}_0^D(x, y)}, \quad y \in D. \end{aligned}$$

Hence

$$\begin{aligned} E_x(e^{-\lambda\tau_D}; x(\tau_D) \in E/x(\tau_D-) = y) \\ = E_x(e^{-\lambda\tau_D}/x(\tau_D-) = y) P_x(x(\tau_D) \in E/x(\tau_D-) = y) \quad y \in D. \end{aligned}$$

**Remark.** Cor. 3 may be considered as the continuous analogue of the well known fact for the Markov process with discrete states and right continuous paths that  $\tau_a$  and  $x(\tau_a)$  are independent where  $\tau_a$  is the holding time at a state  $a$ .

**5. Application.** Here we shall give an application of Theorem 2.

**Example 3.** Consider a *one-sided stable process* given by

$$E(e^{-\gamma x(t)}) = \exp\{-t\gamma^\alpha\}, \quad 0 < \alpha < 1, \quad x(0) = 0.$$

This process is a special case of Example 1 and a Markov process on  $(-\infty, \infty)$  is induced from it. Its transition probability  $P(t, x, d\xi)$  is  $p(t, \xi - x)d\xi$ , where

$$\int_0^\infty e^{-\gamma\xi} p(t, \xi)d\xi = \exp\{-t\gamma^\alpha\},$$

and

$$p(t, \xi) = 0, \quad \text{if } \xi < 0.$$

Now

$$g_0(\xi) = \int_0^\infty p(t, \xi)dt = [\Gamma(\alpha)\xi^{1-\alpha}]^{-1}, \quad \xi > 0.$$

Since

$$\gamma^\alpha = \int_0^\infty (1 - e^{-\gamma u}) \frac{\alpha}{\Gamma(1-\alpha)} \frac{du}{u^{1+\alpha}},$$

the Lévy measure is given by

$$\begin{aligned} n(x, dy) &= [\alpha/\Gamma(1-\alpha)](y-x)^{-(\alpha+1)}dy, & y > x, \\ &= 0, & y \leq x. \end{aligned}$$

Let  $D=(-1, b)$ ,  $b > 0$ , then

$$\begin{aligned} \bar{g}_0^D(x, dy) &= (\Gamma(\alpha))^{-1}(y-x)^{\alpha-1}dy, & -1 < x < y < b \\ &= 0, & \text{otherwise} \end{aligned}$$

In this case, taking  $m(dy)=dy$ , (A. 3), (A. 5) and (A. 6) are satisfied and so we have for  $0 < \xi < b < \eta$ ,

$$\begin{aligned} P_0(x(\tau_D-) \in d\xi, x(\tau_D) \in d\eta) \\ &= \bar{g}_0^D(0, d\xi)n(\eta-\xi)d\eta, \\ &= (\alpha \sin \pi\alpha/\pi)\xi^{\alpha-1}(\eta-\xi)^{-(1+\alpha)}d\xi d\eta. \end{aligned}$$

Now put

$$\begin{aligned} y_1(w) &= b - x(\tau_D(w)-, w), \\ y_2(w) &= x(\tau_D(w), w) - b, \end{aligned}$$

then the joint distribution of  $y_1, y_2$  is given by

$$\begin{aligned} P(y_1 \in du, y_2 \in dv) &= p_b(u, v)dudv \\ &0 < u < b, v > 0, \end{aligned}$$

where

$$p_b(u, v) = (\alpha \sin \pi\alpha/\pi)(b-u)^{\alpha-1}(u+v)^{-(1+\alpha)}.$$

This formula was obtained by E. B. Dynkin [1].

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