# On $h$-isotropic and $\boldsymbol{C}^{\boldsymbol{h}}$-recurrent <br> Finsler spaces 

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(Received May 13, 1970)

The purpose of the present paper is to consider a Finsler space, characterized simply by the equations

$$
R_{h}{ }^{i}{ }_{j k}=R\left(g_{h j} \delta_{k}^{i}-g_{h k} \delta_{j}^{i}\right), \quad C_{h j \mid k}^{i}=C_{h j}^{i} K_{k},
$$

where the euclidean connection of E. Cartan [4] is treated. The first equation means that the Finsler space $F^{n}$ is $h$-isotropic [1, p. 43-49], [6], [7, §39], and Akbar-Zadeh proves that the scalar $R$ is constant. On the other hand, the second equation means that the torsion tensor $C$ of $F^{n}$ is recurrent with respect to the covariant differentiation due to E. Cartan. A generalization of the concept of recurrence was first introduced by A. Moór [9], who treated the recurrence of $R_{h}{ }^{i}{ }_{j k}$ and gave some interesting results.

An interesting example of a Finsler space which is characterized by some simple conditions imposed upon the curvature and torsion has been given by Gy. Soós [11]. His conditions are expressed by

$$
C_{i} R_{0 j k}^{i}=0, \quad C_{h j \mid k}^{i}=0, \quad\left(C_{i}=C_{i j}^{j}\right) .
$$

Similar to the Finsler space due to Gy. Soós, the Finsler space under consideration in the present paper is a simple generalization of Riemannian or Minkowskian spaces, because the former is characterized by $C_{h i}^{i}=0$, and the latter is done by $R=0$ and $K_{k}=0[4$, p. 39], [10,
p. 136], [5], [8].

## § 1. Fundamental tensors and important formulas

Let us consider an $n$-dimensional Finsler space $F^{n}$, equipped with the euclidean connection of E. Cartan [4]. If we denote by $g_{i j}(x, y)$ the components of the metric tensor derived from the Finsler fundamental function $L(x, y)$, and if we put

$$
\begin{aligned}
& \gamma_{j k}^{i}=\frac{1}{2} g^{i n}\left(\frac{\partial g_{j h}}{\partial x^{k}}+\frac{\partial g_{k h}}{\partial x^{j}}-\frac{\partial g_{j_{k}}}{\partial x^{h}}\right), \\
& N_{j}^{i}=\frac{\partial}{\partial y^{j}}\left(\frac{1}{2} \gamma_{k l}^{i} y^{k} y^{l}\right), \\
& \frac{\delta}{\delta x^{i}}=\frac{\partial}{\partial x^{i}}-N_{i}^{j} \frac{\partial}{\partial y^{j}},
\end{aligned}
$$

then the parameters ( $F_{j k}^{i}, C_{j k}^{i}$ ) of the euclidean connection are given by

$$
\begin{aligned}
& F_{j k}^{i}=\frac{1}{2} g^{i n}\left(\frac{\delta g_{j_{h}}}{\delta x^{k}}+\frac{\delta g_{k h}}{\delta x^{j}}-\frac{\delta g_{j_{k}}}{\delta x^{h}}\right) \\
& C_{j k}^{i}=\frac{1}{2} g^{i h}\left(\frac{\partial g_{j_{h}}}{\partial y^{k}}+\frac{\partial g_{k h}}{\partial y^{j}}-\frac{\partial g_{j_{k}}}{\partial y^{h}}\right)=\frac{1}{2} g^{i h} \frac{\partial g_{j_{h}}}{\partial y^{k}} .
\end{aligned}
$$

According to our theory of Finsler spaces based on connections in fibre bundles [7], we shall use the following terminologies and notations throughout the paper. First of all, let $T_{j}^{i}$ be components of a (1, 1). tensor field, and we have three kinds of covariant derivatives of $T_{j}^{i}$ as follows.

$$
\begin{aligned}
& T_{j \mid k}^{j}=\frac{\delta T_{j}^{i}}{\delta x^{k}}+T_{j}^{h} F_{h k}^{i}-T_{h}^{i} F_{j k}^{h} \cdots \cdots h \text {-cov. derivative }, \\
& \left.T_{j}^{i}\right|_{k}=\frac{\partial T_{j}^{i}}{\partial y^{k}}+T_{j}^{h} C_{h k}^{i}-T_{h}^{i} C_{j k}^{h} \cdots \cdots v \text {-cov. derivative } \\
& T_{j \| k}^{j}=\frac{\partial T_{j}^{i}}{\partial y^{k}} \quad
\end{aligned}
$$

Now, there are three kinds of curvature tensors:
$R_{j k l}^{i} \ldots \ldots h$-curvature tensor,
$P_{j k l}^{i} \ldots \ldots h v$-curvature tensor, $S_{j k l}^{i} \ldots \cdots v$-curvature tensor,
and five torsion tensors in general. In the case of the euclidean connection of Cartan, two of them vanish and

$$
\begin{aligned}
& R_{j k}^{i}=y^{h} R_{h j k}^{i} \cdots \cdots(v) h \text {-torsion tensor, } \\
& P_{j k}^{i}=y^{h} P_{h j k}^{i} \cdots \cdots(v) h v \text {-torsion tensor, } \\
& C_{j k}^{i} \quad \cdots \cdots(h) h v \text {-torsion tensor. }
\end{aligned}
$$

The following expressions are well-known.

$$
\begin{gather*}
P_{i j k l}\left(=g_{j h} P_{i k l}^{h}\right)=S_{i j}\left\{C_{j k l \mid i}+C_{i k h} C_{j l \mid 0}^{h}\right\},  \tag{1.1}\\
P_{i j k}\left(=g_{i h} P_{j k}^{h}\right)=C_{i j k \mid 0},  \tag{1.2}\\
S_{j k l}^{i}=  \tag{1.3}\\
S_{k l}\left\{C_{j l}^{h} C_{h k}^{i}\right\}=S_{k l}\left\{\frac{1}{2} C_{j k \| l}^{i}\right\},
\end{gather*}
$$

where the index 0 means contraction by $y^{i}$, and $S_{i j}\{\ldots\}$ does interchange of indices $i, j$ and subtraction.

Next, the Ricci identities for a tensor $T_{j}^{i}$ will show the role of curvatures and torsions as follows.

$$
\begin{gather*}
T_{j|k| l}^{i}-T_{j|l| k}^{i}=T_{j}^{h} R_{h k l}^{i}-T_{h}^{i} R_{j k l}^{h}-\left.T_{j}^{i}\right|_{h} R_{k l}^{h},  \tag{1.4}\\
\left.T_{j \mid k}^{i}\right|_{l}-\left.T_{j}^{i}\right|_{l \mid k}=T_{j}^{h} P_{h k l}^{i}-T_{h}^{i} P_{j k l}^{h}-T_{j \mid h}^{i} C_{k l}^{h}-\left.T_{j}^{i}\right|_{h} P_{k l}^{h},  \tag{1.5}\\
\left.\left.T_{j}^{i}\right|_{k}\right|_{l}-\left.\left.T_{j}^{i}\right|_{l}\right|_{k}=T_{j}^{h} S_{h k l}^{i}-T_{h}^{i} S_{j k l}^{h} . \tag{1.6}
\end{gather*}
$$

Finally, the Bianchi identities of curvature tensors are expressed by

$$
\begin{gather*}
S_{j k l}\left\{R_{i j k l l}^{h}+P_{i j m}^{h} R_{k l}^{m}\right\}=0,  \tag{1.7}\\
S_{k l}\left\{P_{i k j \mid l}^{h}+R_{i l m}^{h} C_{k j}^{m}+P_{i l m}^{h} P_{k j}^{m}\right\}+\left.R_{i l k}^{h}\right|_{j}+S_{i j m}^{h} R_{l k}^{m}=0, \\
S_{k l}\left\{\left.P_{i j k}^{h}\right|_{l}-P_{i m l}^{h} C_{j k}^{m}-S_{i m l}^{h} P_{j k}^{m}\right\}+S_{i k l \mid j}^{h}=0,
\end{gather*}
$$

$$
\begin{equation*}
S_{j k l}\left\{\left.S_{i j k}^{h}\right|_{l}\right\}=0, \tag{1.10}
\end{equation*}
$$

where $S_{j k l}\{\ldots\}$ means cyclic permutation of indices $j, k, l$ and summation. The identity (1.1) is thought of as a Bianchi identity of the $(h) h v$-torsion tensor $C_{j k}^{i}$. The other Bianchi identities will be obtained from (1.7), (1.8), (1.9) by contracting by $y^{i}$. For the later use, we shall here write one of them, derived from (1.8):

$$
\begin{equation*}
S_{k l}\left\{P_{h k j l}+R_{h l m} C_{k j}^{m}+P_{h l m} P_{k j}^{m}\right\}+\left.R_{h l k}\right|_{j}-R_{j h l k}=0 \tag{1.11}
\end{equation*}
$$

## §2. C-recurrent Finsler spaces

Definition. A Finsler space $F^{n}$ will be called $C^{h}$ - or $C^{v}$ - or $C^{0}$. recurrent, if the ( $h$ ) $h v$-torsion tensor $C_{j k}^{i}$ satisfies the equation

$$
\Delta_{l} C_{j k}^{i}=C_{j k}^{i} K_{l},
$$

where we denote by $\Delta_{l}$ the $h$ - or $v$ - or 0 -covariant differentiation respectively, and $K_{l}=K_{l}(x, y)$ is a covariant vector field.

In this section, we shall be concerned with $v$ - and 0 -recurrences only. From the following proposition, we are not interested in these concepts.

Proposition 1. If a Finsler space $F^{n}$ is $C^{v}$ - or $C^{0}$-recurrent, then $F^{n}$ is essentially Riemannian.

Proof. If $F^{n}$ is $C^{v}$-recurrent, then

$$
\begin{equation*}
\left.C_{j k}^{i}\right|_{l}=C_{j k}^{i} K_{l}, \tag{2.1}
\end{equation*}
$$

and hence the identity $\left.C_{j k}^{i}\right|_{l}=\left.C_{j}^{i}\right|_{k}$ gives immediately

$$
C_{j k}^{i} K_{l}=C_{j l}^{i} K_{k}
$$

By contracting these two equations by $y^{l}$, we obtain $-C_{j k}^{i}=C_{j k}^{i} K_{0}$ and $C_{j k}^{i} K_{0}=0$, which imply $C_{j k}^{i}=0$.

Next, if $F^{n}$ is $C^{0}$-recurrent, then

$$
\begin{equation*}
C_{j k \| l}^{i}=C_{j k}^{i} K_{l} \tag{2.2}
\end{equation*}
$$

and hence (1.3) leads us to

$$
S_{j k l}^{i}=\frac{1}{2}\left(C_{j k}^{i} K_{l}-C_{j l}^{i} K_{k}\right) .
$$

Similar to the above case, contractions of these equations by $y^{l}$ give us $C_{j k}^{i}=0$ easily.

## §3. $\quad C^{\boldsymbol{h}}$-recurrent Finsler spaces

The remainder of the present paper will be devoted to studying $C^{h}$-recurrent Finsler spaces. First of all, we shall give two notes. The first is that any essentially Riemannian $F^{n}$ is $C^{h}$-recurrent, because of $C_{j k}^{i}=0$. The second is that any 2 -dimensional $F^{2}$ is also $C^{h}$-recurrent, because $C_{i j k}$ is then written in the form $C_{i j k}=C h_{i} h_{j} h_{k}$, where $h_{i}$ is orthogonal to $y^{i}$ and $h$-covariant constant [2], [10, p. 253].

Now, assume that $F^{n}$ is $C^{h}$-recurrent:

$$
\begin{equation*}
C_{h i j \mid k}=C_{h i j} K_{k} . \tag{3.1}
\end{equation*}
$$

Then, the expressions (1.1), (1.2) and (1.3) lead us to

$$
\begin{gather*}
P_{i j k l}=K_{i} C_{j k l}-K_{j} C_{i k l}-K_{0} S_{i j k l},  \tag{3.2}\\
P_{i j k}=K_{0} C_{i j k} \tag{3.3}
\end{gather*}
$$

Differentiating (3.3) $h$-covariantly, we obtain

$$
\begin{equation*}
P_{i j k \mid l}=C_{i j k}\left(K_{0 \mid l}+K_{0} K_{l}\right), \tag{3.4}
\end{equation*}
$$

from which we conclude as follows.

Proposition 2. Assume that $F^{n}$ is $C^{h}$-recurrent. Then, the $v$ curvature $S_{\text {hijk }}$ is also recurrent with respect to the $h$-covariant differentiation, that is,

$$
S_{h i j k \mid l}=2 K_{l} S_{h i j k .}
$$

If $K_{0}=0$, then the hv-curvature $P_{i j k l}$ is expressed

$$
P_{i j k l}=K_{i} C_{j k l}-K_{j} C_{i k l},
$$

and the (v)hv-torsion $P_{i j k}$ vanishes. If $K_{0} \neq 0$, then the (v)hv-torsion $P_{i j k}$ is recurrent, that is,

$$
P_{i j k \mid l}=P_{i j k}\left(K_{l}+\frac{K_{0 \mid l}}{K_{0}}\right) .
$$

Next, it follows from (3.1) and the Ricci identity (1.4) that

$$
\begin{equation*}
C_{h i j} K_{k l}=-C_{m i j} R_{h k l}^{m}-C_{h m j} R_{i k l}^{m}-C_{n i m} R_{j k l}^{m}-\left.C_{h i j}\right|_{m} R_{k l}^{m}, \tag{3.5}
\end{equation*}
$$

where $K_{k l}=K_{k \mid l}-K_{l \mid k}$. In order to treat (3.5) in detail, we shall assume that $F_{n}$ is $h$-isotropic [1], [6], which is characterized by

$$
R_{h i j k}=R\left(g_{h j} g_{i k}-g_{h k} g_{i j}\right),
$$

where $R$ is a scalar. Akbar-Zadeh proves that $R$ is constant, provided that $n \geqq 3$. It is remarked that the concept of $h$-isotropy does not coincide with that of constant curvature due to L. Berwald [3].

For the $h$-isotropic $F^{n}$, the equation (3.5) is simply expressed as

$$
\begin{equation*}
C_{h i j} K_{k l}=R S_{h i j}\left\{C_{k h i} g_{j l}-C_{l h i} g_{j k}\right\}+R S_{k l}\left\{\left.C_{h i j}\right|_{k} y_{l}\right\} . \tag{3.5'}
\end{equation*}
$$

Then, contraction of (3.5') by $y^{l}$ gives us

$$
\begin{equation*}
\left.R L^{2} C_{h i j}\right|_{k}=C_{h i j} K_{k 0}-R\left(C_{k i j} y_{h}+C_{k j h} y_{i}+C_{k h i} y_{j}+C_{h i j} y_{k}\right), \tag{3.6}
\end{equation*}
$$

where $L$ is the Finsler fundamental function, namely, $L^{2}=g_{i j} y^{i} y^{j}$. Substituting (3.6) into (3.5'), we obtain

$$
\begin{equation*}
C_{h i j}\left(L^{2} K_{k l}-K_{k 0} y_{l}+K_{l 0} y_{k}\right)=R S_{h i j}\left\{C_{k h i} b_{j l}-C_{l h i} b_{j k}\right\}, \tag{3.7}
\end{equation*}
$$

where $b_{j k}=L^{2} g_{j k}-y_{i} y_{k}$. If we contract (3.7) by $g^{h i}$ and then by $C^{j}=g^{i k} C_{i k}^{j}$, we obtain

$$
\begin{gather*}
C_{j}\left(L^{2} K_{k l}-K_{k 0} y_{l}+K_{l 0} y_{k}\right)=R\left(C_{k} b_{j l}-C_{l} b_{j k}\right),  \tag{3.8}\\
C_{j} C^{j}\left(L^{2} K_{k l}-K_{k 0} y_{l}+K_{l 0} y_{k}\right)=0 . \tag{3.9}
\end{gather*}
$$

If $C_{j} C^{j}=0$, that is, $C_{j}=0$, then Deicke's theorem shows that $F^{n}$ is essentially Riemannian. Therefore, assume that $F^{n}$ is not so, and (3.8), (3.9) lead us to

$$
\begin{gather*}
R\left(C_{k} b_{j l}-C_{l} b_{j k}\right)=0, \\
L^{2} K_{k l}-K_{k 0} y_{l}+K_{l 0} y_{k}=0 .
\end{gather*}
$$

It will be seen from (3.8') that, if $F^{n}$ is essentially Finsler and $R \neq 0$, then there exists such a scalar $\alpha$ that $b_{i j}=\alpha C_{i} C_{j}$, which implies $n=2$. If $F^{n}$ is essentially Finsler and $R=0$, then it is observed from (3.5') that $K_{k l}=0$, and (3.9') is reduced to the trivial equation.

Summarizing the above, we have

Proposition 3. All of $h$-isotropic and $C^{h}$-recurrent Finsler spaces are divided into one of the following three classes.
(1) Riemannian space of constant curvature,
(2) essentially Finsler space of 2-dimensions,
(3) essentially Finsler space of dimension $n \geqq 3$ with vanishing scalar curvature $R$, and $K_{i \mid j}=K_{j \mid i}$.

In the remainder of the paper, we shall treat only the interesting case (3). In this case, $R_{i j k l}=0$ and hence $R_{i j k}=0$. Therefore, (1.11) is reduced to

$$
S_{k l}\left\{P_{h k j l l}+P_{h l m} P_{k j}^{m}\right\}=0,
$$

which is, in virtue of (3.3), (3.4), (1.3), rewritten in the form

$$
K_{0}^{2} S_{h j k l}=S_{k l}\left\{\left(K_{0 \mid k}+K_{0} K_{k}\right) C_{h j l}\right\} .
$$

$S_{h j k l}$ are skew-symmetric with respect to indices $h, j$, while the righthand side of the above equation are symmetric with respect the same indices, and hence we obtain

$$
\begin{equation*}
K_{0}^{2} S_{h j k l}=0, \tag{3.10}
\end{equation*}
$$

$$
\begin{equation*}
S_{k l}\left\{\left(K_{0 \mid k}+K_{0} K_{k}\right) C_{h j l}\right\}=0 . \tag{3.11}
\end{equation*}
$$

It follows from (3.10) and (3.2) that $P_{i j k l}=K_{i} C_{j k l}-K_{j} C_{i k l}$. On the other hand, if $K_{0} \neq 0$, then $S_{h j k l}=0$ from (3.10). Next, it is seen from (3.11) that, if $\beta_{k}=K_{0 \mid k}+K_{0} K_{k} \neq 0$, then there exists a scalar $C$ that $C_{i j k}=C \beta_{i} \beta_{j} \beta_{k}$.

Summarizing all the above results, we conclude

Theorem. Let $F^{n}$ be an essentially Finsler space of dimension $n \geqq 3$. If $F^{n}$ is h-isotropic and $C^{h}$-recurrent (3.1), then

$$
K_{i \mid j}=K_{j \mid i},
$$

$h$-curvature $R_{i j k l}=0, \quad(v) h$-torsion $R_{i j k}=0$,
$h v$-curvature $P_{i j k l}=K_{i} C_{j k l}-K_{j} C_{i k l}$,
(v)hv-torsion $P_{i j k}=K_{0} C_{i j k}$.

Moreover, if $K_{0} \neq 0$, then
$v$-curvature $S_{i j k l}=0$,
(h)hv-torsion $C_{i j k}=C \beta_{i} \beta_{j} \beta_{k}, \beta_{i}=K_{0 \mid i}+K_{0} K_{i}$.

From the expression of $P_{i j k l}$ given in Theorem, $K_{i}$ will be easily eliminated and we obtain

$$
\begin{equation*}
S_{h i j}\left\{P_{h m r s} P_{i j k l}+P_{h m k l} P_{i j r s}\right\}=0 . \tag{3.12}
\end{equation*}
$$

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