

On the structure of infinitesimal automorphisms of linear Poisson manifolds II

Dedicated to Professor Masahisa Adachi on his sixtieth birthday

By

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Introduction

Let $\{x, y, z\}$ be a basis of $\mathfrak{g} = \mathfrak{so}(3, R)$ which satisfies the relations:

$$(0.1) \quad [x, y] = z, [z, x] = y, [y, z] = x.$$

We regard x, y and z as coordinate functions on \mathfrak{g}^* and we may identify \mathfrak{g}^* with R^3 . A linear Poisson structure on \mathfrak{g}^* is defined by the following antisymmetric contravariant tensor P of order 2:

$$(0.2) \quad P = z\partial_x \wedge \partial_y + y\partial_z \wedge \partial_x + x\partial_y \wedge \partial_z.$$

Using the tensor P , we can define a bracket operation $\{\cdot, \cdot\}$ on $C^\infty(\mathfrak{g}^*)$:

$$(0.3) \quad \{f, g\} = \langle df \wedge dg | P \rangle, \quad \text{for all } f, g \in C^\infty(\mathfrak{g}^*).$$

Then $C^\infty(\mathfrak{g}^*)$ becomes a Lie algebra and \mathfrak{g}^* has a structure of a linear Poisson manifold. An infinitesimal automorphism of a linear Poisson manifold $\mathfrak{so}(3, R)^*$ is a smooth vector field X on $\mathfrak{so}(3, R)^*$ which satisfies $\mathcal{L}(X)P = 0$, where $\mathcal{L}(X)$ denotes the Lie derivative along X . In the present paper, we shall discuss infinitesimal automorphisms defined on a linear Poisson manifold $\mathfrak{g}^* = \mathfrak{so}(3, R)^*$. This is a sequel of the author's papers [2] and [3].

A Lie group $SO(3, R)$ acts on $\mathfrak{so}(3, R)^*$ through the coadjoint action. All coadjoint orbits except for the origin are compact, which are diffeomorphic to S^2 . Contrary to the case of $\mathfrak{sl}(2, R)^*$, infinitesimal automorphisms of $\mathfrak{so}(3, R)^*$ have some restrictions. This depends on the fact that each orbit is compact in the case of $\mathfrak{so}(3, R)^*$.

In §1, we shall prove that every infinitesimal automorphism is tangent to orbits at each point. In §2, we consider the formal version of smooth infinitesimal automorphisms and calculate derivation algebras of the space of polynomial functions, which we call the polynomial Poisson algebra.

§1. The Schouten bracket and infinitesimal automorphisms

First recall the definition of the Schouten bracket (Lichnerowicz [1]). We call i -tensor an antisymmetric covariant tensor of order i . For an i -tensor A and a j -tensor B , we shall define the Schouten bracket $[A, B]$ which is an $(i + j - 1)$ -tensor as follows: for every closed $(i + j - 1)$ -form β , we have

$$(1.1) \quad i([A, B])\beta = (-1)^{ij+j}i(A)di(B)\beta + (-1)^i i(B)di(A)\beta,$$

where $i(\cdot)$ is the interior product. Then the Schouten bracket satisfies

$$(1.2) \quad [A, B] = (-1)^{ij}[B, A].$$

Moreover if C is a k -tensor, we have the generalized Jacobi identity

$$(1.3) \quad (-1)^{ij}[[B, C], A] + (-1)^{jk}[[C, A], B] + (-1)^{ki}[[A, B], C] = 0.$$

A function $f \in C^\infty(\mathfrak{g}^*)$ is called a Casimir function if it satisfies $\{f, g\} = 0$ for all $g \in C^\infty(\mathfrak{g}^*)$. We denote by \mathcal{C} a space of Casimir functions. Using the Schouten bracket, we can give another definition of Casimir functions and infinitesimal automorphisms. A function f is a Casimir function if $[P, f] = 0$, and a vector field X is an infinitesimal automorphism if $[P, X] = 0$. In the case of $\mathfrak{so}(3, R)^*$, by an easy consideration, we know that the space \mathcal{C} is consisting of functions $\phi(x^2 + y^2 + z^2)$.

We denote by \mathcal{L} the Lie algebra of infinitesimal automorphisms of $\mathfrak{so}(3, R)^*$. Let \mathcal{I} be an ideal of \mathcal{L} whose elements are tangent to coadjoint orbits. We shall prove $\mathcal{L} = \mathcal{I}$ in the following.

Lemma 1.1. *Let $X = f\partial_x + g\partial_y + h\partial_z$ be an element of \mathcal{L} . Then there exists $\phi \in \mathcal{C}$ such that $xf + yg + zh = \phi(x^2 + y^2 + z^2)$.*

Proof. By the generalized Jacobi identity, we have

$$(1.4) \quad [[X, P], \psi] + [[P, \psi], X] + [[\psi, X], P] = 0, \quad \text{for all } \psi \in \mathcal{C}.$$

Since $[X, P] = 0$ and $[P, \psi] = 0$, we get $X(\psi) \in \mathcal{C}$. Hence there exists $\tilde{\psi} \in \mathcal{C}$ such that $2\psi'(x^2 + y^2 + z^2)(xf + yg + zh) = \tilde{\psi}(x^2 + y^2 + z^2)$. Put $\phi = \tilde{\psi}/2\psi'$. Then ϕ is the desired Casimir function. q.e.d.

Theorem 1.2. *In the case of $\mathfrak{g}^* = \mathfrak{so}(3, R)^*$, it holds $\mathcal{L} = \mathcal{I}$.*

Proof. Let $X = f\partial_x + g\partial_y + h\partial_z$ be an element of \mathcal{L} . Then f, g and h satisfy the relations:

$$(1.5) \quad \begin{cases} f = xg_y - yg_x + xh_z - zh_x, \\ g = yf_x - xf_y + yh_z - zh_y, \\ h = zf_x - xf_z + zg_y - yg_z. \end{cases}$$

Put $\text{div}(X) = f_x + g_y + h_z$. Combining Lemma 1.1 with (1.5), we have

$$(1.6) \quad \begin{cases} x \operatorname{div}(X) = (xf + yg + zh)_x = 2x \phi'(x^2 + y^2 + z^2), \\ y \operatorname{div}(X) = (xf + yg + zh)_y = 2y \phi'(x^2 + y^2 + z^2), \\ z \operatorname{div}(X) = (xf + yg + zh)_z = 2z \phi'(x^2 + y^2 + z^2). \end{cases}$$

Hence $\operatorname{div}(X) = f_x + g_y + h_z = 2\phi'(x^2 + y^2 + z^2)$ on $R^3 - \{0\}$. The continuity of $\operatorname{div}(X)$ and ϕ implies $\operatorname{div}(X) = 2\phi'(x^2 + y^2 + z^2)$ on R^3 .

Let V be an open ball of a radius r centered at the origin. Let $\iota: \partial V \rightarrow V$ be the inclusion mapping. By the Stokes formula, we have

$$(1.7) \quad \int_V \operatorname{div}(X) dV = \int_{\partial V} \iota^*(i(X)dV).$$

First compute the left hand side of (1.7). We use the polar coordinates of R^3 .

$$(1.8) \quad \begin{aligned} \int_V \operatorname{div}(X) dV &= \int_V (f_x + g_y + h_z) dV = 2 \int_V \phi'(r^2) r^2 \sin \theta \, dr d\theta d\phi \\ &= 8\pi \int_0^r \phi'(r^2) r^2 \, dr. \end{aligned}$$

On the other hand, we have

$$(1.9) \quad \int_{\partial V} \iota^*(i(X)dV) = \int_{\partial V} \phi(r^2) r \sin \theta \, d\theta d\phi = 4\pi \phi(r^2) r.$$

Thus we get

$$(1.10) \quad 2 \int_0^r \phi'(r^2) r^2 \, dr = \phi(r^2) r.$$

Differentiating both sides of (1.10), we have $\phi(r^2) = 0$ for any $r > 0$. The continuity of ϕ implies $\phi(0) = 0$. Thus $\phi \equiv 0$ on R^3 and hence $xf + yg + zh = 0$. This means that a vector field X is tangent to each coadjoint orbit. (Note that $X = 0$ at the origin by (1.5.) q.e.d.

§2. Derivations of the polynomial Poisson algebra

Let $\{x, y, z\}$ be basis of $\mathfrak{so}(3, R)$ which satisfies (0.1). Let F_p be a space of homogeneous polynomials $f(x, y, z)$ with $\deg(f) = p + 1$, and put $F = \sum F_p$. Using the linear Poisson tensor P of (0.2), a Poisson bracket $\{\cdot, \cdot\}$ on F is defined. Since it holds $\{F_p, F_q\} \subset F_{p+q}$ ($p, q \geq 0$), F becomes a graded Lie algebra. We call F the polynomial Poisson algebra.

The following proposition can be proved by the same method as the case of $\mathfrak{sl}(2, R)$. So we omit the proof. (For the proof, see [3].)

Proposition 2.1. *Each space F_p ($p \geq 2$) is generated by F_1 . Namely it holds $F_p = \{F_1, F_{p-1}\}$.*

Let \mathfrak{g}^c be the complexification of $\mathfrak{g} = \mathfrak{so}(3, R)$. A subspace $\mathfrak{g}_0 = \{x\}$ is a Cartan subalgebra of \mathfrak{g}^c and a root decomposition of \mathfrak{g}^c with respect to \mathfrak{g}_0 is given by

$$(2.1) \quad \mathfrak{g}^c = \mathfrak{g}_{-i} + \mathfrak{g}_0 + \mathfrak{g}_i = \{y + iz\} + \{x\} + \{y - iz\}.$$

Let F_p^C be the complexification of F_p . A linear mapping $\text{ad}(x): F_p \rightarrow F_p$ is naturally extended to $\text{ad}(x): F_p^C \rightarrow F_p^C$. Then by direct calculations, we have

Proposition 2.2. *All eigen values of a linear mapping $\text{ad}(x): F_p^C \rightarrow F_p^C$ are $0, \pm i, \pm 2i, \dots, \pm(p+1)i$. Let $F_p(ki)$ be an eigen space corresponding to an eigen value ki . Then we obtain $F_p^C = \sum_{k=-(p+1)}^{p+1} F_p(ki)$, where each $F_p(ki)$ is given by:*

(i) *If p is even, say $p = 2m$,*

$$\left\{ \begin{array}{l} F_p(0) = \langle x^{2m+1}, x^{2m-1}(y^2 + z^2), \dots, x(y^2 + z^2)^m \rangle, \\ F_p(i) = \langle x^{2m}(y - iz), x^{2m-2}(y - iz)(y^2 + z^2), \dots, (y - iz)(y^2 + z^2)^m \rangle, \\ F_p(-i) = \langle x^{2m}(y + iz), x^{2m-2}(y + iz)(y^2 + z^2), \dots, (y + iz)(y^2 + z^2)^m \rangle, \\ F_p(2i) = \langle x^{2m-1}(y - iz)^2, x^{2m-3}(y - iz)^2(y^2 + z^2), \dots, x(y - iz)^2(y^2 + z^2)^{m-1} \rangle \\ F_p(-2i) = \langle x^{2m-1}(y + iz)^2, x^{2m-3}(y + iz)^2(y^2 + z^2), \dots, x(y + iz)^2(y^2 + z^2)^{m-1} \rangle, \\ \vdots \\ F_p((2m+1)i) = \langle (y - iz)^{2m+1} \rangle, \\ F_p(-(2m+1)i) = \langle (y + iz)^{2m+1} \rangle. \end{array} \right.$$

(ii) *If p is odd, say $p = 2m - 1$,*

$$\left\{ \begin{array}{l} F_p(0) = \langle x^{2m}, x^{2m-2}(y^2 + z^2), \dots, (y^2 + z^2)^m \rangle, \\ F_p(i) = \langle x^{2m-1}(y - iz), x^{2m-3}(y - iz)(y^2 + z^2), \dots, x(y - iz)(y^2 + z^2)^{m-1} \rangle, \\ F_p(-i) = \langle x^{2m-1}(y + iz), x^{2m-3}(y + iz)(y^2 + z^2), \dots, x(y + iz)(y^2 + z^2)^{m-1} \rangle, \\ F_p(2i) = \langle x^{2m-2}(y - iz)^2, x^{2m-4}(y - iz)^2(y^2 + z^2), \dots, (y - iz)^2(y^2 + z^2)^{m-1} \rangle, \\ F_p(-2i) = \langle x^{2m-2}(y + iz)^2, x^{2m-4}(y + iz)^2(y^2 + z^2), \dots, (y + iz)^2(y^2 + z^2)^{m-1} \rangle, \\ \vdots \\ F_p(2mi) = \langle (y - iz)^{2m} \rangle, \\ F_p(-2mi) = \langle (y + iz)^{2m} \rangle. \end{array} \right.$$

A linear mapping $c: F \rightarrow F$ is called a derivation if it satisfies

$$(2.2) \quad c\{f, g\} = \{c(f), g\} + \{f, c(g)\} \quad \text{for all } f, g \in F.$$

In the rest of this section, we shall calculate all derivations of F . First define the degree of c . If a derivation c satisfies $c(F_p) \subset F_{p+r}$ for all p , we say that the degree of c is r , and write as $\text{deg } c = r$. For any derivation c , we denote by $c_p^{(k)}$ the

$$\left\{ \begin{aligned} r_{-2i} &= d_1 x^{2m-1}(y+iz)^2 + d_2 x^{2m-3}(y+iz)^2(y^2+z^2) + \dots \\ &\qquad \qquad \qquad \times d_m x(y+iz)^2(y^2+z^2)^{m-1}. \end{aligned} \right.$$

Substituting (2.3) into $\{y, c(y^2)\} = c\{y, y^2\} = 0$, and equating coefficients of z^k ($k = 0, 1, 2, \dots, 2m + 1$) to zero, we have $a_i = c_k = d_k = 0$ ($1 \leq j \leq m + 1, 1 \leq k \leq m$). Thus $c(x^2) = c(y^2) = c(z^2) = 0$. Since $c(F_0) = 0$, we also have $c(xy) = c(xz) = c(yz) = 0$. Hence $c(F_1) = 0$. By Proposition 2.1, $c(F_p) = 0$ ($p \geq 1$), and hence $c = 0$ on F .

(ii) Since $c(F_1) \subset F_{2m+1}$, we can write down a_0, r_{2i} and r_{-2i} according to the direct sum decomposition of F_{2m+1}^C as follows:

$$(2.4) \quad \left\{ \begin{aligned} a_0 &= a_1 x^{2m+2} + a_2 x^{2m}(y^2+z^2) + \dots + a_{m+2}(y^2+z^2)^{m+1}, \\ r_{2i} &= c_1 x^{2m}(y-iz)^2 + c_2 x^{2m-2}(y-iz)^2(y^2+z^2) + \dots \\ &\qquad \qquad \qquad + c_{m+1}(y-iz)^2(y^2+z^2)^m, \\ r_{-2i} &= d_1 x^{2m}(y+iz)^2 + d_2 x^{2m-2}(y+iz)^2(y^2+z^2) + \dots \\ &\qquad \qquad \qquad + d_{m+1}(y+iz)^2(y^2+z^2)^m. \end{aligned} \right.$$

In F_{2m+1} , there is one dimensional subspace of Casimir functions whose basis is $(x^2 + y^2 + z^2)^{m+1}$. Hence we need put $b_0 = (K(x^2 + y^2 + z^2)^{m+1} - a_0)/2$. Substituting (2.4) into $\{y, c(y^2)\} = 0$, and equating coefficients of z^k ($k = 1, 2, \dots, 2m + 2$) to zero, we have

$$(2.5) \quad \left\{ \begin{aligned} c(x^2) &= 4d_1 i x^2(x^2 + y^2 + z^2)^m + a_{m+2}(x^2 + y^2 + z^2)^{m+1}, \\ c(y^2) &= 4d_1 i y^2(x^2 + y^2 + z^2)^m - (1/2)(a_{m+2} - K + 4d_1 i)(x^2 + y^2 + z^2)^{m+1}, \\ c(z^2) &= 4d_1 i z^2(x^2 + y^2 + z^2)^m - (1/2)(a_{m+2} - K + 4d_1 i)(x^2 + y^2 + z^2)^{m+1}. \end{aligned} \right.$$

Using (2.5), we also have

$$(2.6) \quad \left\{ \begin{aligned} c(xy) &= c\{y^2, z\}/2 = \{c(y^2), z\}/2 = 4d_1 i xy(x^2 + y^2 + z^2)^m, \\ c(xz) &= c\{x^2, y\}/2 = \{c(x^2), y\}/2 = 4d_1 i xz(x^2 + y^2 + z^2)^m, \\ c(yz) &= c\{x, y^2\}/2 = \{x, c(y^2)\}/2 = 4d_1 i yz(x^2 + y^2 + z^2)^m. \end{aligned} \right.$$

By equations (2.5) and (2.6), we know that a derivation c can be essentially written as $c(u_1) = u_1(x^2 + y^2 + z^2)^m$ for all $u_1 \in F_1$. (Recall that c is a “real” derivation.) Since F_1 generates F_p ($p \geq 2$), we also obtain that $c(u_p) = pu_p(x^2 + y^2 + z^2)^m$ for all $u_p \in F_p$. Finally we see that a derivation c is outer. In fact, if c is inner, there exists a function $f \in F_{2m}$ such that $c = \text{ad}(f)$. Then $0 = c(x) = \{f, x\}$. Thus we have $c(x^2) = \{f, x^2\} = 2x\{f, x\} = 0$. On the other hand, $c(x^2) = x^2(x^2 + y^2 + z^2) \neq 0$. This is a contradiction. q.e.d.

We have thus determined the derivation algebra of F . We shall resume all results in

Theorem 2.6. *Let $c : F \rightarrow F$ be a derivation. Then $c \equiv \sum_{m \geq 0} \alpha_m c^{(2m)} \pmod{\dots}$*

$\text{ad}(F)$), where $c^{(2m)}$ is derivation defined by

$$(2.7) \quad c^{(2m)}(u_p) = pu_p(x^2 + y^2 + z^2)^m \quad \text{for all } u_p \in F_p,$$

and α_m is some constant depending on c . In particular, all $c^{(2m)}$ are outer derivations, hence $H^1(F, F)$ is infinite dimensional.

Let L be the formal Lie algebra of \mathcal{L} at the origin. (For the precise definition of the formal Lie algebras, see [4].) Then the derivation c obtained in Theorem 2.6 induces a derivation \bar{c} of L . The form of \bar{c} is explicitly given by $\bar{c} = \text{ad}((x^2 + y^2 + z^2)^m(x\partial_x + y\partial_y + z\partial_z))$.

We shall consider here C^∞ -versions of the results obtained in the above theorem. For all non-negative integers m , let $X = (x^2 + y^2 + z^2)^m(x\partial_x + y\partial_y + z\partial_z)$ be a smooth vector field on $\mathfrak{so}(3, R)^* = R^3$. Then for all $Y = f\partial_x + g\partial_y + h\partial_z \in \mathcal{L}$, we have

$$\begin{aligned} \mathcal{L}([X, Y])P &= -\mathcal{L}(Y)L(X)P = \mathcal{L}(Y)\{(x^2 + y^2 + z^2)^m P\} \\ &= Y\{(x^2 + y^2 + z^2)^m\}P \\ &= 2m(x^2 + y^2 + z^2)^{m-1}(xf + yg + zh)P = 0. \end{aligned}$$

(Recall that $\mathcal{L} = \mathcal{F}$ by Theorem 1.2, hence $xf + yg + zh = 0$.) This implies $[X, Y] \in \mathcal{L}$ and thus $\text{ad}(X)$ is a derivation of \mathcal{L} for all $m \geq 0$. This fact is quite different from the case of $\mathfrak{sl}(2, R)$. (See Proposition 3.1 in [3].)

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