

Remarks on Boolean functions.¹⁾

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1. Introduction. Let B be a Boolean algebra with partial ordering, meet, join, complement, and symmetric difference denoted by $a \leq b$, $a \wedge b$, $a \vee b$, a' , and $a \oplus b$, respectively. When employing the ring notation (11), in B we write merely ab for $a \wedge b$.

Numerous authors have considered Boolean functions [1, 6, 7, 8, 9, 10] of one or more variables. In this note we restrict attention for the most part to Boolean functions of one variable. As is well known [1, 6], every such function allows representation in its disjunctive normal form

$$(\nabla) \quad f(x) = (a \wedge x) \vee (b \wedge x'),$$

or, in ring notation, $f(x) = (a \oplus b)x \oplus b$.

It is clear that (∇) is a motion of B as an autometrized Boolean algebra [2, 3] if and only if $a = b'$. We shall need the following two lemmas.

LEMMA 1. (*Solution Criterion* [1]). *The equation $ax = b$ has solutions in B if and only if $ab = b$ in which case the general solution is $x = b \oplus t$; $t \leq 1 \oplus a$.*

LEMMA 2. (*Müller's Theorem* [9, 10]). *The function (∇) maps B onto $[a \wedge b, a \vee b]$.*

COROLLARY. *The function (∇) takes on minimum and maximum values $a \wedge b$ and $a \vee b$, respectively.*

From Lemma 2 one may observe with Schmidt [10] that $a = b'$ is necessary in order that (∇) map B onto itself.

Combining this last remark with the remark preceding Lemma 1, we have

LEMMA 3. *The Boolean functions which map B onto itself are the autometrized motions of B and, hence, are necessarily biuniform.*

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Since the class of Boolean functions in B is precisely the class of linear functions in ring notation, and since a transformation product of linear functions (possibly constant) is a linear function in a ring, the class of Boolean functions in B is closed under transformation product.

2. The operator structure of the class of Boolean functions. From Lemma 3 and the remark following it in Section 1, we may conclude

THEOREM 1. *The class of Boolean functions on B forms a transformation semigroup on B in which the group of units is precisely the group of motions of B in its autometrization, or, equivalently, the regular representation of the additive group of B under $(+)$ (see [2, 3, 5]).*

THEOREM 2. *The class R of Boolean functions on B forms an operator ring on B . The constant functions form an ideal J_c in R and R/J_c is a Boolean ring with identity isomorphic to B .*

PROOF. One easily verifies the distributive laws for transformation product over symmetric difference. This proves the first statement. That J_c is an ideal is also easily verified, and the required isomorphism is $a \mapsto \{ax\}$, where $\{ax\}$ is the congruence class of the function mod J_c .

3. Müller's Theorem.

THEOREM 3. *The minimum arguments for which (∇) takes on its minimum and maximum values, respectively, are $a' \wedge b$ and $a \wedge b'$. The maximum arguments for which (∇) takes on its minimum and maximum values, respectively, are $a' \vee b$ and $a \vee b'$.*

PROOF. Suppose $(a \wedge x) \vee (b \wedge x') = a \wedge b$. Then $a' \wedge b \wedge x' = 0$ so that $a' \wedge b \leq x$. Also,

$$(a \wedge (a' \wedge b)) \vee (b \wedge (a' \wedge b)') = a \wedge b. \text{ Similarly,}$$

$$(a \wedge (a \wedge b')) \vee (b \wedge (a \wedge b')') = a \vee b \text{ and}$$

$$(a \wedge x) \vee (b \wedge x') = a \wedge b \text{ implies } a \wedge b' \wedge x = a \wedge b'$$

so that $a \wedge b' \leq x$. The second part of Theorem 3 follows dually.

We may generalize Müller's theorem to Boolean functions of several variables by induction. Let $f(x_1, x_2, \dots, x_{n-1}, x_n)$ be a Boolean function of n variables. We may write it in the disjunctive normal form as

$$(\nabla \nabla) f(x_1, \dots, x_n) = \bigvee_{P_i} \left\{ a_i \wedge \left[\bigwedge_{j=1}^n x_j^{i_j} \right] \right\},$$

where $x_j^{i_j}$ is either x_j or x'_j and P_i ranges over the various combinations of these choices.

THEOREM 4. *The function $(\nabla \nabla)$ maps B^n onto $\left[\bigwedge_{P_i} a_i, \bigvee_{P_i} a_i \right]$.*

PROOF. The proposition is valid for $n=1$, by Müller's theorem. Suppose it is valid for all $k < n$. Write $(\nabla \nabla)$ as $f(x_1, \dots, x_{n-1}, x_n) = \bigvee_{P_i} \left\{ \left[(a_i \wedge x_n) \vee (b_i \wedge x'_n) \right] \wedge \left[\bigwedge_{j=1}^{n-1} x_j^{i_j} \right] \right\}$. Where the b_i are the a_i corresponding to values of P_i for which $x_n^{i_n}$ is x'_n .

For each value of x_n , $(\nabla \nabla)$ maps B^{n-1} onto

$$\left[\bigwedge_{P_i} \left\{ (a_i \wedge x_n) \vee (b_i \wedge x'_n) \right\}, \bigwedge_{P_i} \left\{ (a_i \wedge x_n) \vee (b_i \wedge x'_n) \right\} \right]$$

by the inductive hypothesis. We may rewrite this interval as $[(a \wedge x_n) \vee (b \wedge x'_n), (c \wedge x_n) \vee (d \wedge x'_n)]$, where $a = \bigwedge_{P_i} a_i$, $b = \bigwedge_{P_i} b_i$, $c = \bigvee_{P_i} a_i$, $d = \bigvee_{P_i} b_i$. By Müller's theorem, however, a suitable choice of x_n will

lower the left endpoint of the interval to $a \wedge b$ and another choice will raise the right endpoint to $c \vee d$.

We now observe an interesting application of Müller's theorem. It is well-known [1] that in a normed lattice, the triangle function $\delta(x) = \delta(a, x) + \delta(b, x) + \delta(c, x)$ takes on a minimum at $x = (a, b, c)$, the "median" of the triangle [1]. Our application is to obtain the corresponding fact for the triangle function $d(x) = d(a, x) \vee d(b, x) \vee d(c, x)$ in the autometrization of B .

THEOREM 5. *$d(x)$ takes its minimum value at $x = (a, b, c)$.*

PROOF. Since $d(x) = [(a' \vee b' \vee c') \wedge x] \vee [(a \vee b \vee c) \wedge x']$, the minimum values is, by the Corollary to Müller's theorem, $(a' \vee b' \vee c') \wedge (a \vee b \vee c)$. But one verifies by direct computation that this is $d((a, b, c))$. One might also observe that this value is the "perimeter" of the triangle, $d(a, b) \vee d(b, c) \vee d(a, c)$.

4. Curve fitting. In a 1936 paper [8] J.C.C. McKinsey discusses the fitting of graphs of Boolean function of n variables to sets of points in B^{n+1} . His results are, however, qualitative. In this section we

determine the exact families of Boolean function of a single variable whose graphs pass through one or a pair of preassigned points in B^2 .

In addition to the case of exact fit, we also discuss the curve of best fit to a set of points in B^2 in the following sense: If $(x_i, y_i); i=1, 2, \dots, n$ is a finite set of points in B^2 , and if $f(x)=y$ is a Boolean function in B , then by the total deviation of the function from the set we shall mean $\bigvee_{i=1}^n (y_i \oplus f(x_i))$; that is, the join of the autometrized distances between actual ordinates and computed ordinates. The curve (or, more precisely, a curve) of best fit will be one whose total deviation from the set is minimal. Obviously, a curve will be an exact fit if and only if the total deviation is 0.

THEOREM 6. *If (x_1, y_1) is any point in B^2 , there is a two-parameter family (possibly degenerate) of Boolean functions whose graphs pass through (x_1, y_1) , namely,*

$$f_{s,t}(x) = (y_1(1 \oplus x_1) \oplus s \oplus t)x \oplus y_1 \oplus s; \text{ where } s \leq x_1 \text{ and } t \leq 1 \oplus x_1.$$

PROOF. The statement is verified by direct computation.

THEOREM 7. *Let (x_1, y_1) and (x_2, y_2) be any pair of points in B^2 . There is a Boolean function whose graph passes through the pair if and only if $y_1 \oplus y_2 \leq x_1 \oplus x_2$ in which case there is a one-parameter (possibly degenerate) family of such functions, namely,*

$$f_t(x) = ((y_1 \oplus y_2) \oplus t)x \oplus (y_1 \oplus x_1(y_1 \oplus y_2) \oplus x_1 t); \text{ where } t \leq 1 \oplus x_1 \oplus x_2.$$

PROOF. $f_t(x)$ as given goes through (x_1, y_1) by Theorem 6. By Lemma 1, one finds that $f_t(x_2)$ is y_2 if and only if the conditions given in Theorem 7 are valid.

THEOREM 8. *A Boolean curve of best fit, $f(x) = (a \oplus b)x \oplus b$, with respect to the set $(x_i, y_i); i=1, \dots, n$, is obtained by taking*

$$a = \left[\left(\bigwedge_{i=1}^n y_i \right) \wedge \left(\bigvee_{i=1}^n (x_i \oplus y_i)' \right) \wedge \left(\bigvee_{i=1}^n (x_i \oplus y_i) \right) \right] \vee \left[\left(\bigvee_{i=1}^n y_i' \right) \wedge \left(\bigwedge_{i=1}^n (x_i \oplus y_i)' \right) \right. \\ \left. \wedge \left(\bigvee_{i=1}^n y_i \right) \right] \text{ and } b = \left[\left(\bigwedge_{i=1}^n y_i \right) \wedge \left(\bigvee_{i=1}^n (x_i \oplus y_i) \right) \right] \vee \left[\left(\bigwedge_{i=1}^n (x_i \oplus y_i) \right) \wedge \left(\bigvee_{i=1}^n y_i \right) \right].$$

In this case, the total deviation will be

$$\left(\bigvee_{i=1}^n y_i' \right) \wedge \left(\bigvee_{i=1}^n (x_i \oplus y_i)' \right) \wedge \left(\bigvee_{i=1}^n (x_i \oplus y_i) \right) \wedge \left(\bigvee_{i=1}^n y_i \right).$$

PROOF. To verify Theorem 8, one merely regards the total deviation of an arbitrary curve with respect to the given set of points as a Boolean function of the coefficients and applies Theorem 4.

5. The special case. Homomorphism and orbital topologies. In this section, we restrict attention to those functions (∇) for which $b \leq a$. By Lemma 2, such a function maps B onto $[b, a]$. This case we call the special case. For the notions involved in the discussion of orbital topologies, see [4]. We denote by B_f the space of B under the orbital topology induced by $f(x)$.

THEOREM 9. *For the special case, $f(f(x))=f(x)$; for all x . Also, $f(x)=f(y)$ if and only if $x=y \pmod{J_f}$, where J_f is the principal ideal of $1 \oplus a \oplus b$.*

PROOF. The first assertion follows by direct computation. Suppose $x \oplus y \leq 1 \oplus a \oplus b$. Then $f(x) \oplus f(y) = (a \oplus b)(x \oplus y) \oplus b \oplus b = 0$. Conversely, if $f(x) \oplus f(y) = 0$, then $(a \oplus b)(x \oplus y) = 0$ and $x \oplus y \leq 1 \oplus a \oplus b$.

THEOREM 10. *For the special case, $f(x)$ is a lattice homomorphism of B onto $[b, a]$ and, in B_f , x is an accumulation point of a set E if and only if x is in $[b, a]$ and E contains infinitely many points of the congruence class of $x \pmod{J_f}$.*

PROOF. In the special case, $(a \oplus b)b = 0$. Thus, $f(u \vee v) = (a \oplus b)(u \oplus v \oplus uv) \oplus b$ and $f(u) \vee f(v) = (a \oplus b)(u \oplus v \oplus uv) \oplus b \oplus (a \oplus b)b(u \oplus v) \oplus 0$. Similarly, $f(u \wedge v) = f(u) \wedge f(v)$. This proves the first assertion. If $f(y) = x$, then $(a \oplus b)y = x \oplus b$, $(a \oplus b \oplus 1)y = (x \oplus y) \oplus b$, $x \oplus y = (a \oplus b \oplus 1)y \oplus b$. But, $(a \oplus b \oplus 1)y$ is in J_f and, in the special case, $b = b(a \oplus b \oplus 1)$ is in J_f so that $x = y \pmod{J_f}$.

THEOREM 11. *In the special case, I , the principal ideal of $a \oplus b$, is a group of homeomorphisms of B_f onto itself.*

PROOF. Take c in I and consider T_c , the \oplus translation by c . $f(x \oplus c) = (a \oplus b)(x \oplus c) \oplus b = (a \oplus b)x \oplus b \oplus c$, since c is in I . Hence, $f(xT_c) = (f(x))T_c$ and T_c commutes with f . Also, T_c is biuniform and is its own inverse so that T_c is a homeomorphism of B_f onto itself by Theorem 5 of [4].

THEOREM 12. *In the lattice of all topologies on B , the join of the orbital topologies induced by functions in the special case is the strongest T_1 topology on B (see [12] for terminology).*

PROOF. Taking $a=b$ in $f(x)$ we find $J_f=B$. By Theorem 10, then, only finite sets are closed in the join of these topologies.

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