THE INTRINSIC FLAT DISTANCE BETWEEN RIEMANNIAN MANIFOLDS AND OTHER INTEGRAL CURRENT SPACES

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Abstract

Inspired by the Gromov-Hausdorff distance, we define a new notion called the intrinsic flat distance between oriented m dimensional Riemannian manifolds with boundary by isometrically embedding the manifolds into a common metric space, measuring the flat distance between them and taking an infimum over all isometric embeddings and all common metric spaces. This is made rigorous by applying Ambrosio-Kirchheim's extension of Federer-Fleming's notion of integral currents to arbitrary metric spaces.

We prove the intrinsic flat distance between two compact oriented Riemannian manifolds is zero iff they have an orientation preserving isometry between them. Using the theory of Ambrosio-Kirchheim, we study converging sequences of manifolds and their limits, which are in a class of metric spaces that we call integral current spaces. We describe the properties of such spaces including the fact that they are countably \mathcal{H}^m rectifiable spaces and present numerous examples.

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1. Introduction

1.1. A brief history. In 1981, Gromov introduced the Gromov-Hausdorff distance between Riemannian manifolds as an intrinsic version of the Hausdorff distance. Recall that the Hausdorff distance measures distances between subsets in a common metric space [Gro07]. To measure the distance between Riemannian manifolds, Gromov isometrically embeds the pair of manifolds into a common metric space, Z, then measures the Hausdorff distance between them in Z, and then takes the infimum over all isometric embeddings into all common metric spaces, Z. Two compact Riemannian manifolds have $d_{GH}(M_1, M_2) = 0$ if and only if they are isometric. This notion of distance enables Riemannian

geometers to study sequences of Riemannian manifolds which are not diffeomorphic to their limits and have no uniform lower bounds on their injectivity radii. The limits of converging sequences of compact Riemannian manifolds with a uniform upper bound on diameter need not be Riemannian manifolds at all. However, they are compact geodesic metric spaces.

Gromov's compactness theorem states that a sequence of compact metric spaces, X_i , has a Gromov-Hausdorff converging subsequence to a compact metric space, X, if and only if there is a uniform upper bound on diameter and a uniform upper bound on the function, N(r), equal to the number of disjoint balls of radius r contained in the metric space. He observes that manifolds with nonnegative Ricci curvature, for example, have a uniform upper bound on N(r) and thus have converging subsequences [Gro07]. Such sequences need not have uniform lower bounds on their injectivity radii (cf. [Per97]) and their limit spaces can have locally infinite topological type [Men00]. Nevertheless, Cheeger-Colding proved these limit spaces have many intriguing properties which has led to a wealth of further research. One particularly relevant result states that when the sequence also has a uniform lower bound on volume, then the limit spaces are countably \mathcal{H}^m rectifiable of the same dimension as the sequence [CC00]. However, Gromov-Hausdorff convergence does not apply well to sequences with positive scalar curvature.

In 2004, Ilmanen described the following example of a sequence of three dimensional spheres with positive scalar curvature which has no Gromov-Hausdorff converging subsequence. He felt the sequence should converge in some weak sense to a standard sphere [Figure 1].

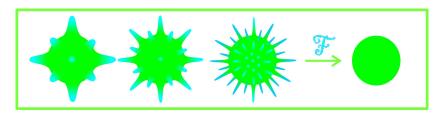


Figure 1. Ilmanen's sequence of increasingly hairy spheres.

Viewing the Riemannian manifolds in Figure 1 as submanifolds of Euclidean space, they are seen to converge in Federer-Fleming's flat sense as integral currents to the standard sphere. One of the beautiful properties of limits under Federer-Fleming's flat convergence is that they are countably \mathcal{H}^m rectifiable with the same dimension as the sequence. In light of Cheeger-Colding's work, it seems natural, therefore, to look for an intrinsic flat convergence whose limit spaces would be countably \mathcal{H}^m rectifiable metric spaces. The intrinsic flat distance introduced in this paper leads to exactly this kind of convergence. The sequence of 3

dimensional manifolds depicted in Figure 1 does in fact converge to the sphere in this intrinsic flat sense [Example A.7].

Ambrosio-Kirchheim's 2000 paper [AK00] developing the theory of currents on arbitrary metric spaces is an essential ingredient for this paper. Without it we could not define the intrinsic flat distance, we could not define an integral current space and we could not explore the properties of converging sequences. Other important background to this paper is prior work of the second author, particularly [Wen07], and a coauthored piece [SW10]. Riemannian geometers may not have read these papers (which are aimed at geometric measure theorists), so we review key results as they are needed within.

1.2. An overview. In this paper, we view a compact oriented Riemannian manifold with boundary, M^m , as a metric space, (X,d), with an integral current, $T \in \mathbf{I}_m(M)$, defined by integration over $M \colon T(\omega) := \int_M \omega$. We write M = (X, d, T) and refer to T as the integral current structure. Using this structure, we can define an intrinsic flat distance between such manifolds and study the intrinsic flat limits of sequences of such spaces. As an immediate consequence of the theory of Ambrosio-Kirchheim, the limits of converging sequences of such spaces are countably \mathcal{H}^m rectifiable metric spaces, (X,d), endowed with a current structure, $T \in \mathbf{I}_m(Z)$, which represents an orientation and a multiplicity on X.

In Section 2 we describe these spaces in more detail, referring to them as m dimensional integral current spaces [Defn 2.35] [Defn 2.46]. The class of such spaces is denoted \mathcal{M}^m and includes the zero current space, denoted $\mathbf{0} = (\mathbf{0}, \mathbf{0}, \mathbf{0})$. Given an integral current space (X, d, T), we define its boundary using the boundary, ∂T , of the integral current structure [Defn 2.46]. We also define the mass of the space using the mass, $\mathbf{M}(T)$, of the current structure [Defn 2.41]. When (X, d, T) is an oriented Riemannian manifold, the boundary is just the usual boundary and the mass is just the volume.

Recall that the flat distance between m dimensional integral currents $S, T \in \mathbf{I}_m(Z)$ is given by

(1)
$$d_F^Z(S,T) := \inf\{\mathbf{M}(U) + \mathbf{M}(V) : S - T = U + \partial V\}$$

where $U \in \mathbf{I}_m(Z)$ and $V \in \mathbf{I}_{m+1}(Z)$. This notion of a flat distance was first introduced by Whitney in [Whi57] and later adapted to rectifiable currents by Federer-Fleming [FF60]. The flat distance between integral currents on an arbitrary metric space was introduced by the second author in [Wen07].

Our definition of the intrinsic flat distance between elements of \mathcal{M}^m is modeled after Gromov's intrinsic Hausdorff distance [Gro07]:

Definition 1.1. For $M_1 = (X_1, d_1, T_1)$ and $M_2 = (X_2, d_2, T_2) \in \mathcal{M}^m$, let the intrinsic flat distance be defined:

(2)
$$d_{\mathcal{F}}(M_1, M_2) := \inf d_F^Z(\varphi_{1\#} T_1, \varphi_{2\#} T_2),$$

where the infimum is taken over all complete metric spaces (Z,d) and isometric embeddings $\varphi_1: (\bar{X}_1,d_1) \to (Z,d)$ and $\varphi_2: (\bar{X}_2,d_2) \to (Z,d)$ and the flat norm d_F^Z is taken in Z. Here \bar{X}_i denotes the metric completion of X_i and d_i is the extension of d_i on \bar{X}_i , while $\phi_\# T$ denotes the push forward of T.

All notions from Ambrosio-Kirchheim's work needed to understand this definition are reviewed in detail in Section 2. As in Gromov, an isometric embedding is a map $\phi: A \to B$ which preserves distances, not just the Riemannian metric tensors:

(3)
$$d_B(\phi(x),\phi(y)) = d_A(x,y) \qquad \forall x,y \in A.$$

For example, a map $f:S^1\to D^2$ mapping the circle to the boundary of a flat disk is not an isometric embedding while the map $\varphi:S^1\to S^2$ mapping the circle to a great circle in the sphere is an isometric embedding. If the infimum in (2) were taken over maps preserving the Riemannian metric tensors rather than isometric embeddings in the sense of Gromov, then the value would not be positive.

It is fairly easy to estimate the intrinsic flat distances between compact oriented Riemannian manifolds using standard methods from Riemannian geometry. If M_1^m and M_2^m are m dimensional Riemannian manifolds which isometrically embed into an m+1 dimensional Riemannian manifold, V, such that the boundary, $\partial V = \varphi(M_1) \sqcup \varphi(M_2) \sqcup U$, then by (1) we have

$$d_{\mathcal{F}}(M_1, M_2) \le \operatorname{Vol}_m(U) + \operatorname{Vol}_{m+1}(V).$$

This technique and others are applied in the Appendix to explicitly compute the intrinsic flat limits of converging sequences of manifolds depicted here.

It should be noted that $d_{\mathcal{F}}(M, \mathbf{0})$ is related to Gromov's filling volume of a manifold [**Gro83**] via [**Wen07**] and [**SW10**]. DePauw and Hardt have recently defined a flat norm a la Gromov for chains in a metric space. When the chain is an isometrically embedded Riemannian manifold, M, then their "flat norm" of M seems to take on the same value as $d_{\mathcal{F}}(M, \mathbf{0})$ [**DPH**].

In Section 3 we explore the properties of our intrinsic flat distance, $d_{\mathcal{F}}$. It is always finite and, in particular, satisfies $d_{\mathcal{F}}(M_1, M_2) \leq \operatorname{Vol}(M_1) + \operatorname{Vol}(M_2)$ when M_i are compact oriented Riemannian manifolds [Remark 3.3]. We prove $d_{\mathcal{F}}$ is a distance on \mathcal{M}_0^m , the space of precompact integral current spaces [Theorem 3.2 and Theorem 3.27]. In particular, for compact oriented Riemannian manifolds, M and N, $d_{\mathcal{F}}(M, N) = 0$ iff there is an orientation preserving isometry from M to N.

Applying the Compactness Theorem of Ambrosio-Kirchheim, we see that when a sequence of Riemannian manifolds, M_j , has volume uniformly bounded above and converges in the Gromov-Hausdorff sense to a compact metric space, Y, then a subsequence of the M_j converges to an integral current space, X, where $X \subset Y$ [Theorem 3.20]. Example A.4, depicted in Figure 2, demonstrates that the intrinsic flat and Gromov-Hausdorff limits need not always agree: the Gromov-Hausdorff limit is a sphere with an interval attached while the intrinsic flat limit is just the sphere.

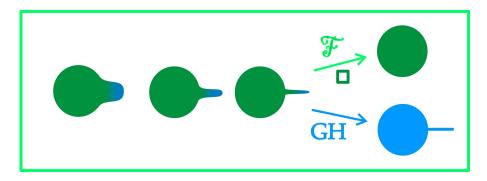


Figure 2. A sphere with a disappearing hair [Ex A.4].

Gromov-Hausdorff limits of Riemannian manifolds are geodesic spaces. Recall that a geodesic space is a metric space such that

(4)
$$d(x,y) = \inf\{L(c) : c \text{ is a curve s.t. } c(0) = x, c(1) = y\}$$

and the infimum is attained by a curve called a geodesic segment. In Example A.12, depicted in Figure 3, we show that the intrinsic flat limit of Riemannian manifolds need not be a geodesic space. In fact, the intrinsic flat limit is not even path connected.

While the limit spaces are not geodesic spaces, they are countably \mathcal{H}^m rectifiable metric spaces of the same dimension. These spaces, introduced and studied by Kirchheim in [**Kir94**], are covered almost everywhere by the bi-Lipschitz charts of Borel sets in \mathbb{R}^m . Gromov-Hausdorff limits do not in general have rectifiability properties.

An interesting example of such a space is depicted in Figure 4 [Example A.14]. The intrinsic flat limit depicted here is the disjoint collection of spheres while the Gromov-Hausdorff limit has line segments between them.

If a sequence of Riemannian manifolds, M_j^m , has volume converging to 0 or has a Gromov-Hausdorff limit whose dimension is less than m, then the intrinsic flat limit is the zero space [Corollary 3.21 and Remark 3.22]. See Figure 5 [Example A.16]. Such sequences are referred to as collapsing sequences.

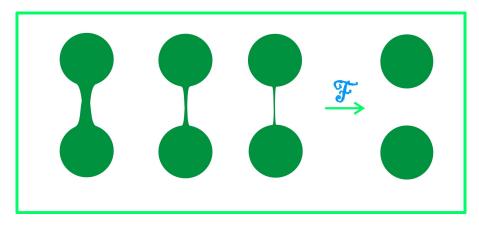


Figure 3. The intrinsic flat limit is a disjoint pair of spheres [Ex A.12].

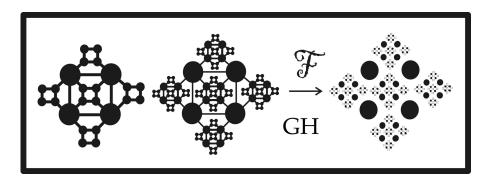


Figure 4. The limit is a countably \mathcal{H}^m rectifiable space [Ex A.14].

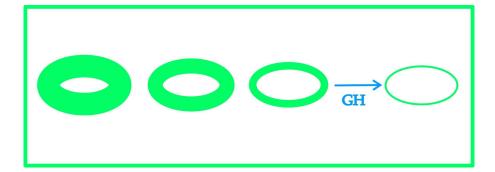


Figure 5. The Gromov-Hausdorff limit is lower dimensional and the intrinsic flat limit is the zero space [Example A.16].

Sequences may also converge to the zero integral current space due to an effect called cancellation. With significantly growing local topology,

a sequence of M_j^m which Gromov-Hausdorff converges to a Riemannian manifold, X, of the same dimension might cancel with itself so that Y=0. In [SW10], the authors gave an example of two standard three dimensional spheres joined together by increasingly dense tunnels, providing a sequence of compact manifolds of positive scalar curvature which converges in the Gromov-Hausdorff sense to a standard sphere. However, the sequence could be isometrically embedded into a common space $\varphi_j: M_j \to Z$ such that $\varphi_{j\#}M_j$ converges in the flat sense to 0 due to cancellation. Thus $M_j \xrightarrow{\mathcal{F}} \mathbf{0}$. In Figure 6 we depict a two dimensional example. Here two sheets are joined together by many tunnels so that they isometrically embed into the boundary of a Riemannian manifold of arbitrarily small volume.

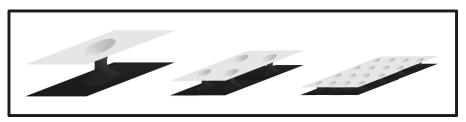


Figure 6. A sequence converging in the intrinsic flat sense to the zero space due to cancellation [Example A.19].

It is also possible for a sequence of Riemannian manifolds with increasing local topology to overlap with itself so that the limit Y = 2X [Example A.20]. If one provides a twist in the middle of each tunnel in Figure 6 so as to flip the orientation of one of the two sheets, then the sequence of manifolds doesn't cancel in the limit but instead doubles. We say the limit space has weight or multiplicity 2. In general, intrinsic flat limit spaces have a weight function, which is an integer valued Borel measurable function, just like integral currents [Defn 2.9].

In Section 4 we examine the properties of intrinsic flat convergence. We first have a section proving that converging and Cauchy sequences embed into a common metric space. This allows us to then immediately extend properties of weakly converging sequences of integral currents to integral current spaces. In particular, the mass is lower semicontinuous as in Ambrosio-Kirchheim [AK00] and the filling volume is continuous as in [Wen07].

When M_j^m have nonnegative Ricci curvature, the intrinsic flat limits and Gromov-Hausdorff limits agree [SW10]. In this sense one may think of intrinsic flat convergence as a means of extending to a larger class of manifolds the rectifiability properties already proven by Cheeger-Colding to hold on Gromov-Hausdorff limits of noncollapsing sequences of such manifolds [CC97].

When M_j^m have a common lower bound on injectivity radius or a uniform linear local contractibility radius, then work of Croke applying Berger's volume estimates and work of Greene-Petersen applying Gromov's filling volume inequality imply that a subsequence of the M_j^m converge in the Gromov-Hausdorff sense [Cro84][GPV92]. In [SW10], the authors proved cancellation does not occur in that setting either, so that the Gromov-Hausdorff limit X agrees with the flat limit Y and is countable \mathcal{H}^m rectifiable.

The second author has proven a compactness theorem: Any sequence of oriented Riemannian manifolds with boundary, M_j^m , with a uniform upper bound on diam $\left(M_j^m\right)$, $\operatorname{Vol}_m\left(M_j^m\right)$, and $\operatorname{Vol}_{m-1}\left(\partial M_j^m\right)$ always has a subsequence which converges in the intrinsic flat sense to an integral current space [Wen11]. In fact, Wenger's compactness theorem holds for integral current spaces. We do not apply this theorem in this paper except for a few immediate corollaries given in Subsection 4.5 and occasional footnotes.

Unlike the limits in Gromov's compactness theorem, the sequences in Wenger's compactness theorem need not converge to a compact limit space. In Figure 7 we see that the limit space need not be precompact even when the sequence of manifolds has a uniform upper bound on volume and diameter.

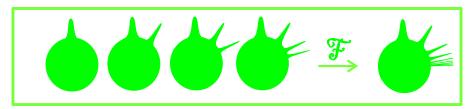


Figure 7. Spheres with increasingly thin extra bumps converging to a bounded noncompact limit [Ex A.11].

In Section 5, we describe the relationship between the intrinsic flat convergence of Riemannian manifolds and other forms of convergence including C^{∞} convergence, $C^{k,\alpha}$ convergence, and Gromov's Lipschitz convergence.

In the Appendix by the first author, we include many examples of sequences explicitly proving they converge to their limits. Although the examples are referred to throughout the textbook, they are deferred to the final section so that proofs of convergence may apply any or all lemmas proven in the paper.

While we do not have room in this introduction to refer to all the results presented here, we refer the reader to the beginning of each section with a more detailed description of what is contained within it. Some sections mention explicit open problems and conjectures.

1.3. Recommended reading. For Riemannian geometry, recommended background is a standard one semester graduate course. For metric geometry background, the beginning of Burago-Burago-Ivanov [BBI01] is recommended or Gromov's classic [Gro07]. For geometric measure theory, a basic guide to Federer is provided in Morgan's textbook [Mor09]. One may also consult Lin-Yang [LY02]. We try to cover what is needed from Ambrosio-Kirchheim's seminal paper [AK00], but we recommend that paper as well.

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2. Defining current spaces

In this section we introduce current spaces (X, d, T). Everything in this section is a reformulation of Ambrosio-Kirchheim's theory of currents on metric spaces, so that we may clearly define the new notions of an integer rectifiable current space [Defn 2.35] and an integral current space [Defn 2.46]. Experts in the theory of Ambrosio-Kirchheim may wish to skip to these definitions. In Section 3 we will discuss the intrinsic flat distance between such spaces. This section is aimed at Riemannian geometers who have not yet read Ambrosio-Kirchheim's work [AK00].

In Subsection 2.1, we provide a description of these spaces as weighted oriented countably \mathcal{H}^m rectifiable metric spaces. Our spaces need not be complete but must be "completely settled" as defined in Definition 2.11. In Subsections 2.2 and 2.3, we review Ambrosio-Kirchheim's integer rectifiable currents on complete metric spaces, emphasizing a parametric

¹Marcus Khuri, Michael Munn, Ovidiu Munteanu, Natasa Sesum, Mu-Tao Wang, William Wylie

perspective and proving a couple lemmas regarding this parametrization. In Subsection 2.3, we introduce the notion of an integer rectifiable current structure on a metric space [Definition 2.35] and prove in Proposition 2.40 that metric spaces with such current structures are exactly the completely settled weighted oriented rectifiable metric spaces defined in the first subsection. In Subsection 2.4, we introduce the notion of the boundary of a current space and define integral current spaces [Definition 2.46].

2.1. Weighted oriented countably \mathcal{H}^m rectifiable metric spaces. We begin with the following standard definition ([Fed69] cf. [AK00]):

Definition 2.1. A metric space X is called countably \mathcal{H}^m rectifiable iff there exist countably many Lipschitz maps φ_i from Borel measurable subsets $A_i \subset \mathbb{R}^m$ to X such that the Hausdorff measure

(5)
$$\mathcal{H}^{m}\left(X\setminus\bigcup_{i=1}^{\infty}\varphi_{i}\left(A_{i}\right)\right)=0.$$

Remark 2.2. Note that Kirchheim [Kir94] defined a metric differential for Lipschitz maps $\varphi: A \subset \mathbb{R}^k \to Z$ where Z is a metric space. When A is open,

(6)
$$md\varphi_{y}\left(v\right) := \lim_{r \to 0^{+}} \frac{d\left(\varphi\left(y + rv\right), \varphi\left(y\right)\right)}{r},$$

if the limit exists. In fact, Kirchheim has proven that for almost every $y \in A$, $md\varphi_y(v)$ is defined for all $v \in \mathbb{R}^m$ and $md\varphi_y$ is a seminorm. On a Riemannian manifold Z with a smooth map f, $mdf_y(v) = |df_y(v)|$. See also Korevaar-Schoen [**KS93**].

In [**Kir94**], Kirchheim proved this collection of charts can be chosen so that the maps φ_i are bi-Lipschitz. So we may extend the Riemannian notion of an atlas to this setting:

Definition 2.3. A bi-Lipschitz collection of charts, $\{\varphi_i\}$, is called an atlas of X.

Remark 2.4. Note that when $\varphi: A \subset \mathbb{R}^m \to X$ is bi-Lipschitz, then $md\varphi_y$ is a norm on \mathbb{R}^m . In fact there is a notion of an approximate tangent space at almost every $y \in X$ which is a normed space of dimension m whose norm is defined by the metric differential of a well chosen bi-Lipschitz chart (cf. [Kir94]).

Recall that by Rademacher's Theorem we know that given a Lipschitz function $f: \mathbb{R}^m \to \mathbb{R}^m$, ∇f is defined \mathcal{H}^m almost everywhere. In particular, given two bi-Lipschitz charts, φ_i, φ_j , $\det[\nabla \left(\varphi_i^{-1} \circ \varphi_j\right)]$ is defined almost everywhere. So we can extend the Riemannian definitions of an atlas and an oriented atlas to countably \mathcal{H}^m rectifiable spaces:

Definition 2.5. An atlas on a countably \mathcal{H}^m rectifiable space X is called an **oriented atlas** if the orientations agree on all overlapping charts:

(7)
$$\det \left[\nabla \left(\varphi_i^{-1} \circ \varphi_j\right)\right] > 0$$
 almost everywhere on $A_j \cap \varphi_j^{-1} \left(\varphi_i\left(A_i\right)\right)$.

Definition 2.6. An **orientation** on a countably \mathcal{H}^m rectifiable space X is an equivalence class of atlases where two atlases, $\{\varphi_i\}, \{\bar{\varphi}_j\}$, are considered to be equivalent if their union is an oriented atlas.

Remark 2.7. Given an orientation $[\{\varphi_i\}]$, we can choose a representative atlas such that the charts are pairwise disjoint, $\varphi_i(A_i) \cap \varphi_j(A_j) = \emptyset$, and the domains A_i are precompact. We call such an oriented atlas a preferred oriented atlas.

Remark 2.8. Orientable Riemannian manifolds and, more generally, connected orientable Lipschitz manifolds have only two standard orientations because they are connected metric spaces and their charts overlap. Countably \mathcal{H}^m rectifiable spaces may have uncountably many orientations as each disjoint chart may be flipped on its own. Recall that a Lipschitz manifold is a metric space, X, such that for all $x \in X$ there is an open set U about x with a bi-Lipschitz homeomorphism to the open unit ball in Euclidean space. A Lipschitz manifold is said to be orientable when the bi-Lipschitz maps can be chosen so that (7) holds for all pairs of charts.

When we say "oriented," we will mean that the orientation has been provided, and we will always orient Riemannian manifolds and Lipschitz manifolds according to one of their two standard orientations, and we will always assign them an atlas restricted from the standard charts used to define them as manifolds.

Definition 2.9. A multiplicity function (or weight) on a countably \mathcal{H}^m rectifiable space X with $\mathcal{H}^m(X) < \infty$ is a Borel measurable function $\theta: X \to \mathbb{N}$ whose weighted volume,

(8)
$$\operatorname{Vol}(X,\theta) := \int_X \theta d\mathcal{H}^m,$$

is finite.

Note that on a Riemannian manifold, with multiplicity $\theta = 1$, the weighted volume is the volume. Later we will define the mass of these spaces which will agree with the weighted volume on Riemannian manifolds with arbitrary multiplicity functions but will not be equal to the weighted volume for more general spaces.

Remark 2.10. Given a multiplicity function and an atlas, one may refine the atlas so that the multiplicity function is constant on the image of each chart.

Recall the notion of the lower m dimensional density, $\theta_{*m}(\mu, p)$, of a Borel measure μ at $p \in X$ is defined by

(9)
$$\Theta_{*m}(\mu, p) := \liminf_{r \to 0^+} \frac{\mu(B_p(r))}{\omega_m r^m}.$$

We introduce the following new concept:

Definition 2.11. A weighted oriented countably \mathcal{H}^m rectifiable metric space, $(X, d, [\{\phi_i\}], \theta)$, is called **completely settled** iff

(10)
$$X = \{ p \in \bar{X} : \Theta_{*m} (\theta \mathcal{H}^m, p) > 0 \}.$$

Example 2.12. An oriented Riemannian manifold with a conical singular point and constant multiplicity $\theta = 1$, which includes the singular point, is a completely settled space. An oriented Riemannian manifold with a cusped singular point and constant multiplicity $\theta = 1$, which does not include the singular point, is a completely settled space. In particular, a completely settled space need not be complete.

An oriented Riemannian manifold with a cusped singular point p and a multiplicity function θ , approaching infinity at p such that

(11)
$$\lim_{r \to 0^+} \frac{1}{r^m} \int_{B_n(r)} \theta \, d\mathcal{H}^m > 0,$$

is completely settled only if it includes p.

In Subsection 2.3 we will define our current spaces as metric spaces with current structures. We will prove in Proposition 2.40 that a metric space is a nonzero integer rectifiable current space iff it is a completely settled weighted oriented countably \mathcal{H}^m rectifiable metric space. Note that the notion of a completely settled space does not appear in Ambrosio-Kirchheim's work and is introduced here to allow us to understand current spaces in an intrinsic way. Integral current spaces will have an added condition that their boundaries are integer rectifiable metric spaces as well.

2.2. Reviewing Ambrosio-Kirchheim's currents on metric

spaces. In this subsection we review all definitions and theorems of Ambrosio-Kirchheim and Federer-Fleming necessary to define current structures on metric spaces [AK00][FF60].

For readers familiar with the Federer-Fleming theory of currents, one may recall that an m dimensional current, T, acts on smooth m forms (e.g. $\omega = f d\pi_1 \wedge \cdots \wedge d\pi_m$). An integer rectifiable current is defined by integration over a rectifiable set in a precise way with integer weight and the notion of the boundary of T is defined as in Stokes' theorem: $\partial T(\omega) = T(d\omega)$. This approach extends naturally to smooth manifolds but not to metric spaces which do not have differential forms.

In the place of differential forms, Ambrosio-Kirchheim use m+1 tuples, $\omega \in \mathcal{D}^m(Z)$,

(12)
$$\omega = f\pi = (f, \pi_1, \dots, \pi_m) \in \mathcal{D}^m(Z)$$

where $f: Z \to \mathbb{R}$ is a bounded Lipschitz function and $\pi_i: Z \to \mathbb{R}$ are Lipschitz. They credit this approach to DeGiorgi [**DeG95**].

In [**AK00**] Definitions 2.1, 2.2, 2.6, and 3.1, an m dimensional current $T \in \mathbf{M}_m(Z)$ is defined as a multilinear functional on $\mathcal{D}^m(Z)$ such that $T(f, \pi_1, \ldots, \pi_m)$ satisfies a variety of functional properties similar to $T(\omega)$ where $\omega = f d\pi_1 \wedge \cdots \wedge d\pi_m$ in the smooth setting as follows:

Definition 2.13 (Ambrosio-Kirchheim). An m dimensional current, T, on a complete metric space, Z, is a real valued multilinear functional on $\mathcal{D}^m(Z)$, with the following required properties:

i) Locality:

(13)
$$T(f, \pi_1, \dots, \pi_m) = 0 \text{ if } \exists i \in \{1, \dots m\} \text{ s.t. } \pi_i$$
 is constant on a nbd of $\{f \neq 0\}.$

ii) Continuity:

T is continuous with respect to the pointwise convergence of the π_i such that $\text{Lip}(\pi_i) \leq 1$.

iii) Finite mass: There exists a finite Borel measure μ on Z such that

(14)

$$|T(f, \pi_1, \dots, \pi_m)| \le \prod_{i=1}^m \operatorname{Lip}(\pi_i) \int_Z |f| d\mu \qquad \forall (f, \pi_1, \dots, \pi_m) \in \mathcal{D}^m(Z).$$

The space of m dimensional currents on Z is denoted $\mathbf{M}_m(Z)$.

Example 2.14. Given an L^1 function $h:A\subset\mathbb{R}^m\to\mathbb{Z}$, one can define an m dimensional current $\llbracket h\rrbracket$ as follows:

(15)
$$\llbracket h \rrbracket (f, \pi) := \int_{A \subset \mathbb{R}^m} hf \det (\nabla \pi) \ d\mathcal{L}^m = \int_{A \subset \mathbb{R}^m} hf \ d\pi_1 \wedge \dots \wedge d\pi_m.$$

Given a Borel measurable set, $A \subset \mathbb{R}^m$, the current $[1_A]$ is defined by the indicator function $1_A : \mathbb{R}^m \to \mathbb{R}$. Ambrosio-Kirchheim prove $[\![h]\!] \in \mathbf{M}_m(Z)$ [AK00].

Remark 2.15. Stronger versions of locality and continuity, as well as product and chain rules, are proven in [AK00, Theorem 3.5]. In particular, they prove

(16)
$$T(f, \pi_{\sigma(1)}, \dots, \pi_{\sigma(m)}) = \operatorname{sgn}(\sigma) T(f, \pi_1, \dots, \pi_m)$$

for any permutation, σ , of $\{1, 2, \ldots, m\}$.

The following definition will allow us to define the most important currents explicitly: **Definition 2.16** (Ambrosio-Kirchheim). Given a Lipschitz map $\varphi : Z \to Z'$, the *push forward* of a current $T \in \mathbf{M}_m(Z)$ to a current $\varphi_\# T \in \mathbf{M}_m(Z')$ is given in [**AK00**, Defn 2.4] by

(17)
$$\varphi_{\#}T(f,\pi_1,\ldots,\pi_m) := T(f \circ \varphi,\pi_1 \circ \varphi,\ldots,\pi_m \circ \varphi)$$

exactly as in Federer-Fleming when everything is smooth.

Example 2.17. If one has a bi-Lipschitz map, $\varphi : \mathbb{R}^m \to Z$, and a Lebesgue function $h \in L^1(A, \mathbb{Z})$ where $A \subset \mathbb{R}^m$, then $\varphi_{\#}[\![h]\!] \in \mathbf{M}_m(Z)$ is an example of an m dimensional current in Z. Note that

(18)
$$\varphi_{\#}[h](f, \pi_1, \dots, \pi_m) = \int_{A \subset \mathbb{R}^m} (h \circ \varphi)(f \circ \varphi) d(\pi_1 \circ \varphi) \wedge \dots \wedge d(\pi_m \circ \varphi)$$

where $d(\pi_i \circ \varphi)$ is well defined almost everywhere by Rademacher's Theorem. All currents of importance in this paper are built from currents of this form.

The following are Definition 2.3 and Definition 2.5 in [AK00]:

Definition 2.18 (Ambrosio-Kirchheim). The **boundary** of $T \in \mathbf{M}_{m+1}(Z)$ is defined

(19)
$$\partial T(f, \pi_1, \dots, \pi_m) := T(1, f, \pi_1, \dots, \pi_m)$$

since in the smooth setting

(20)
$$\partial T(f d\pi_1 \wedge \cdots \wedge d\pi_m) = T(1 df \wedge d\pi_1 \wedge \cdots \wedge d\pi_m).$$

Note that $\varphi_{\#}(\partial T) = \partial(\varphi_{\#}T)$ and $\partial \partial T = 0$.

Definition 2.19 (Ambrosio-Kirchheim). The **restriction** $T \, \boldsymbol{\sqcup} \, \omega \in \mathbf{M}_m(Z)$ of a current $T \in M_{m+k}(Z)$ by a k+1 tuple $\omega = (g, \tau_1, \dots, \tau_k) \in \mathcal{D}^k(Z)$:

$$(21) (T \sqcup \omega)(f, \pi_1, \dots, \pi_m) := T(f \cdot g, \tau_1, \dots, \tau_k, \pi_1, \dots, \pi_m).$$

The following definition of the mass of a current is technical [**AK00**, Defn 2.6]. A simpler formula for mass will be given in Lemma 2.34 when we restrict ourselves to integer rectifiable currents.

Definition 2.20 (Ambrosio-Kirchheim). The mass measure ||T|| of a current $T \in \mathbf{M}_m(Z)$ is the smallest Borel measure μ such that (14) holds for all m+1 tuples, (f,π) . The mass of T is defined

(22)
$$M(T) = ||T||(Z) = \int_{Z} d||T||.$$

In particular

(23)
$$|T(f, \pi_1, \dots, \pi_m)| \leq \mathbf{M}(T)|f|_{\infty} \operatorname{Lip}(\pi_1) \cdots \operatorname{Lip}(\pi_m).$$

Note that the currents in $\mathbf{M}_m(Z)$ defined by Ambrosio-Kirchheim have finite mass by definition. Urs Lang develops a variant of Ambrosio-Kirchheim theory that does not rely on the finite mass condition in [Lanar].

Note the integral current, $\llbracket h \rrbracket \in \mathbf{M}_m(\mathbb{R}^m)$, in Example 2.14 has mass measure

$$(24) ||\llbracket h \rrbracket|| = |h| d\mathcal{L}^m$$

and mass

(25)
$$\mathbf{M}(\llbracket h \rrbracket) = \int_{A} |h| d\mathcal{L}^{m}.$$

Remark 2.21. In (2.4) [AK00], Ambrosio-Kirchheim show that

$$(26) ||\varphi_{\#}T|| \le [\operatorname{Lip}(\varphi)]^m \varphi_{\#}||T||,$$

so that when φ is an isometry $||\varphi_{\#}T|| = \varphi_{\#}||T||$ and $\mathbf{M}(T) = \mathbf{M}(\varphi_{\#}T)$.

Computing the mass of the push forward current in Example 2.17 is a little more complicated and will be done in the next section.

2.3. Parametrized integer rectifiable currents. Ambrosio and Kirchheim define integer rectifiable currents, $\mathcal{I}_m(Z)$, on an arbitrary complete metric space Z [**AK00**, Defn 4.2]. Rather than giving their definition, we will use their characterization of integer rectifiable currents given in [**AK00**, Thm 4.5]: A current $T \in \mathbf{M}_m(Z)$ is an integer rectifiable current iff it has a parametrization of the following form:

Definition 2.22 (Ambrosio-Kirchheim). A parametrization ($\{\varphi_i\}$, $\{\theta_i\}$) of an integer rectifiable current $T \in \mathcal{I}_m(Z)$ with $m \geq 1$ is a countable collection of bi-Lipschitz maps $\varphi_i : A_i \to Z$ with $A_i \subset \mathbb{R}^m$ precompact Borel measurable and with pairwise disjoint images and weight functions $\theta_i \in L^1(A_i, \mathbb{N})$ such that

(27)
$$T = \sum_{i=1}^{\infty} \varphi_{i\#} \llbracket \theta_i \rrbracket \quad \text{and} \quad \mathbf{M} (T) = \sum_{i=1}^{\infty} \mathbf{M} (\varphi_{i\#} \llbracket \theta_i \rrbracket).$$

The mass measure is

(28)
$$||T|| = \sum_{i=1}^{\infty} ||\varphi_{i\#}[\theta_i]||.$$

Note that the current in Example 2.17 is an integer rectifiable current.

Example 2.23. If one has an oriented Riemannian manifold, M^m , of finite volume and a bi-Lipschitz map $\varphi: M^m \to Z$, then $T = \varphi_{\#} \llbracket 1_M \rrbracket$ is an integer rectifiable current of dimension m in Z. If φ is an isometry, and Z = M, then $\mathbf{M}(T) = \operatorname{Vol}(M^m)$. Note further that ||T|| is concentrated on $\varphi(M)$ which is a set of Hausdorff dimension m.

In [AK00, Theorem 4.6] Ambrosio-Kirchheim define a canonical set associated with any integer rectifiable current:

Definition 2.24 (Ambrosio-Kirchheim). The **canonical set** of a current, T, is the collection of points in Z with positive lower density:

(29)
$$set (T) = \{ p \in Z : \Theta_{*m} (||T||, p) > 0 \},$$

where the definition of lower density is given in (9).

Remark 2.25. In [AK00, Thm 4.6], Ambrosio-Kirchheim prove that given a current $T \in \mathcal{I}_m(Z)$ on a complete metric space Z with a parametrization $(\{\varphi_i\}, \theta_i)$ of T, we have

$$\mathcal{H}^{m}\left(\operatorname{set}\left(T\right) \Lambda \bigcup_{i=1}^{\infty}\varphi_{i}\left(A_{i}\right) \right) =0,$$

where Λ is the symmetric difference,

(31)
$$A\Lambda B = (A \setminus B) \cup (B \setminus A).$$

In particular, the canonical set, set (T), endowed with the restricted metric, d_Z , is a countably \mathcal{H}^m rectifiable metric space, (set (T), d_Z).

Example 2.26. Note that the current in Example 2.23 has

(32)
$$\operatorname{set}(\varphi_{\#}[1_{\mathbf{M}}]) = \varphi(\mathbf{M}),$$

when M is a smooth oriented Riemannian manifold. If M has a conical singularity, then (33) holds as well. However, if M has a cusp singularity at a point p then

(33)
$$\operatorname{set}(\varphi_{\#}[1_{\mathbf{M}}]) = \varphi(\mathbf{M} \setminus \{p\}).$$

Recall that the support of a current (cf. [AK00] Definition 2.8) is

(34)
$$\operatorname{spt}(T) := \operatorname{spt} ||T|| = \{ p \in Z : ||T|| (B_p(r)) > 0 \ \forall r > 0 \}.$$

Ambrosio-Kirchheim show the closure of set(T) is spt(T).

Remark 2.27. Note that there are integer rectifiable currents T^m on \mathbb{R}^n such that the support is all of \mathbb{R}^n . For example, take a countable dense collection of points $p_j \in \mathbb{R}^3$; then $X = \bigcup_{j \in \mathbb{N}} \partial B_{p_j} (1/2^j)$ is the set of the current $T \in \mathbf{I}_m(\mathbb{R}^3)$ defined by integration over X and yet the support is \mathbb{R}^3 .

Remark 2.28. Given a parametrization of an integer rectifiable current T, one may refine this parametrization by choosing Borel measurable subsets A'_i of the A_i such that $\varphi_i: A'_i \to set(T)$. The new collection of maps $\{\varphi_i: A'_i \to Z\}$ is also a parametrization of T and we will call it a settled parametrization. Unless stated otherwise, all our parametrizations will be settled. We may also choose precompact $A'_i \subset A_i$ such that $\varphi_i(A'_i) \cap \varphi_j(A'_j) = \emptyset$. We will call such a parametrization a preferred settled parametrization.

Recall the definition of orientation in Definition 2.6 and the definition of multiplicity in Definition 2.9. The next lemma allows one to define the orientation and multiplicity of an integer rectifiable current [Definition 2.30].

Lemma 2.29. Given two currents $T, T' \in \mathcal{I}_m(Z)$ on a complete metric space Z and respective parametrizations $(\{\varphi_i\}, \theta_i), (\{\varphi_i'\}, \theta_i')$ we have T = T' iff the following hold:

i) The symmetric difference satisfies

(35)
$$\mathcal{H}^{m}\left(\bigcup_{i=1}^{\infty}\varphi_{i}\left(A_{i}\right)\Lambda\bigcup_{i=1}^{\infty}\varphi_{i}'\left(A_{i}'\right)\right)=0.$$

ii) The union of the atlases $\{\varphi_i\}$ and $\{\varphi_i'\}$ is an oriented atlas of

(36)
$$X = \bigcup_{i=1}^{\infty} \varphi_i(A_i) \cup \bigcup_{i=1}^{\infty} \varphi'_i(A'_i).$$

iii) The sums:

(37)
$$\sum_{i=1}^{\infty} \theta_i \circ \varphi_i^{-1} 1_{\varphi_i(A_i)} = \sum_{i=1}^{\infty} \theta_i' \circ {\varphi_i'}^{-1} 1_{\varphi_i'(A_i')} \qquad \mathcal{H}^m a.e. \ on \ Z.$$

Definition 2.30. Given T, the sum in (37) will be called the **multiplicity** function, θ_T . This function is an \mathcal{H}^m measurable function from Z to $\mathbb{N} \cup \{0\}$. The uniquely defined equivalence class of oriented atlases of set (T) will be called the orientation of T.

A similar result is in [AK00, Thm 9.1] with a less Riemannian approach to the notion of orientation. The θ in their theorem is our θ_T .

Proof. We begin by relating some equations and then prove the theorem.

Note that by restricting to $A_{i,j} := \varphi_i(A_i) \cap \varphi'_j(A'_j)$, we can focus on one term in the parametrization at a time:

(38)
$$T \sqcup A_{i,j} = \sum_{k=1}^{\infty} \varphi_{k\#} \llbracket \theta_k \rrbracket \sqcup A_{i,j} = \varphi_{i\#} \llbracket \theta_i \rrbracket \sqcup A_{i,j} = \varphi_{i\#} \llbracket \theta_i 1_{\varphi_i^{-1}(A_{i,j})} \rrbracket.$$

Thus $T \, {\mathrel{\sqsubseteq}} \, A_{i,j} = T' \, {\mathrel{\sqsubseteq}} \, A'_{i,j}$ iff

(39)
$$\varphi_{i\#}[\![\theta_{i}1_{\varphi_{i}^{-1}(A_{i,j})}]\!] = \varphi'_{j\#}[\![\theta'_{j}1_{\varphi'_{j}^{-1}(A_{i,j})}]\!] \quad \text{iff}$$
$$[\![\theta'_{j}1_{\varphi'_{i}^{-1}(A_{i,j})}]\!] = \varphi'_{j\#}^{-1}\varphi_{i\#}[\![\theta_{i}1_{\varphi_{i}^{-1}(A_{i,j})}]\!].$$

This is true iff for any Lipschitz function f defined on A'_{i} we have

(40)
$$\int_{\varphi_{j}^{'-1}(A_{i,j})} \theta_{j}' \cdot f \, d\mathcal{L}^{m} = \int_{\varphi_{i}^{-1}(A_{i,j})} \theta_{i} \cdot (f \circ {\varphi_{j}'}^{-1} \circ \varphi_{i}) \, \det \left(\nabla \left({\varphi_{j}'}^{-1} \circ \varphi_{i} \right) \right) d\mathcal{L}^{m}.$$

By the change of variables formula, this is true iff

(41)
$$\int_{\varphi_{j}^{'-1}(A_{i,j})} \theta_{j}^{\prime} \cdot f \, d\mathcal{L}^{m} = \int_{\varphi_{j}^{'-1}(A_{i,j})} (\theta_{i} \circ \varphi_{i}^{-1} \circ \varphi_{j}^{\prime}) \cdot f \operatorname{sgn} \det \left(\nabla (\varphi_{i}^{-1} \circ \varphi_{j}^{\prime}) \right) d\mathcal{L}^{m}$$

because the change of variables formula involves the absolute value of the determinant. This is true iff the following two equations hold:

(42)
$$\theta'_{j} = \theta_{i} \circ \varphi_{i}^{-1} \circ \varphi'_{j} \qquad \mathcal{L}^{m} \text{ a.e. on } {\varphi'_{j}}^{-1} (A_{i,j})$$

and

(43)
$$\operatorname{sgn} \det(\nabla(\varphi_i^{-1} \circ \varphi_j')) = 1$$
 \mathcal{L}^m a.e. on $\varphi_j'^{-1}(A_{i,j})$. Setting

(44)
$$Y := \bigcup_{i=1}^{\infty} \varphi_i(A_i) \text{ and } Y' := \bigcup_{j=1}^{\infty} \varphi'_j(A'_j),$$

we have $X = Y \cup Y'$ and $\bigcup_{i,j=1}^{\infty} A_{i,j} = Y \cap Y'$. Furthermore, by Remark 2.25, we have

(45) (i) iff
$$\mathcal{H}^m(Y\Lambda Y')$$
 iff $\mathcal{H}^m(set(T)\Lambda set(T')) = 0$.

We may now prove the theorem. If T = T', then set (T) = set (T') and we have (i). Furthermore, $T \sqcup A_{i,j} = T' \sqcup A_{i,j}$ for all i, j which implies (43), which implies (ii). We also have (42), which implies

(46)
$$\sum_{i=1}^{\infty} \theta_i \circ \varphi_i^{-1} 1_{\varphi_i(A_i)} = \sum_{i=1}^{\infty} \theta_i' \circ \varphi_i^{-1} 1_{\varphi_i'(A_i')}$$

holds \mathcal{H}^m almost everywhere on $\bigcup_{i,j=1}^{\infty} A_{i,j} = Y \cap Y'$. Since we already have (i), then (45) implies (46) holds \mathcal{H}^m almost everywhere on $Y \cup Y' = X$ and we get (iii).

Conversely, if (i), (ii), (iii) hold for a pair of parametrizations, then (ii) implies (43) and (iii) implies (42). Thus, by (39) we have $T \, \square \, A_{i,j} = T' \, \square \, A_{i,j}$ for all i,j. Summing over i and j, we have $T \, \square \, X = T' \, \square \, X$. By (i) and (45), we have

(47)
$$T = T \bigsqcup_{i=1}^{\infty} \varphi_i(A_i) = T \bigsqcup Y = T' \bigsqcup Y' = T' \bigsqcup_{j=1}^{\infty} \varphi_j(A'_j) = T'.$$
 q.e.d.

In Proposition 2.40 we will prove that if $T \in \mathcal{I}_m(Z)$ is an integer rectifiable current, then $(\operatorname{set}(T), \operatorname{d}_Z, [\{\varphi_i\}], \theta_T)$ as defined in Definition 2.30 is a completely settled weighted oriented countably \mathcal{H}^m rectifiable metric space as in Definitions 2.9 and 2.11. To prove this we must show $\operatorname{set}(T)$ is completely settled. Thus we must better understand the relationship between the mass measure of T, ||T||, which is used to define the canonical set, and the weight $\theta_T \mathcal{H}^m$, which is used to defined settled. Both measures must have positive density at the same locations.

Remark 2.31. In the proof of [AK00, Theorem 4.6], Ambrosio-Kirchheim note that

(48)
$$||T|| = \Theta_{*m}(||T||, \cdot)\mathcal{H}^m \sqcup \operatorname{set}(T).$$

Example 2.32. Suppose $T \in \mathbf{I}_m(M^m)$ in a smooth oriented Riemannian manifold of finite volume is defined $T = \llbracket 1_M \rrbracket$. Then $\theta_T = 1$ while ||T|| is the Lebesgue measure on M. Since the Hausdorff and Lebesgue measures agree on a smooth Riemannian manifold, we have $\Theta_{*m}(||T||,p)=1$ as well. The Hausdorff and Lebesgue measures also agree on manifolds that have point singularities as in Example 2.26, so that set(T) is completely settled with respect to $\theta_T d\mathcal{H}^m$ in both cases given in that example as well. In that case we again have $\theta_T = 1$ everywhere, but $\Theta_{*m}(||T||,p) = \Theta_{*m}(\theta_T \mathcal{H}^m,p) < 1$ at conical singularities and 0 at cusp points.

In general, however, the lower density of T need not agree with the weight, θ_T . To find a formula relating the multiplicity θ_T to the lower density of ||T|| we need a notion called the area factor of a normed space V (cf. [AK00](9.11)):

(49)
$$\lambda_V := \frac{2^m}{\omega_m} \sup \left\{ \frac{\mathcal{H}^m(B_0(1))}{\mathcal{H}^m(R)} \right\},\,$$

where the supremum is taken over all parallelepipeds $R \subset V$ which contain the unit ball $B_0(1)$.

Remark 2.33. In $[\mathbf{AK00}, \text{Lemma 9.2}]$, Ambrosio-Kirchheim prove that

$$\lambda_V \in [m^{-m/2}, 2^m/\omega_m]$$

and observe that $\lambda_V = 1$ whenever $B_0(1)$ is a solid ellipsoid. This will occur when V is the tangent space on a Riemannian manifold because the norm is an inner product. It is also possible that $\lambda_V = 1$ when V does not have an inner product norm (cf. [AK00] Remark 9.3).

The following lemma consolidates a few results in [AK00] and [Kir94]:

Lemma 2.34. Given an integer rectifiable current $T \in \mathcal{I}_m(Z)$, in a complete metric space Z there is a function

(51)
$$\lambda : set(T) \to [m^{-m/2}, 2^m/\omega_m]$$

satisfying

(52)
$$\Theta_{*m}(||T||, x) = \theta_T(x)\lambda(x),$$

for \mathcal{H}^m almost every $x \in \operatorname{set}(T)$ such that

(53)
$$||T|| = \theta_T \lambda \mathcal{H}^m \sqcup \operatorname{set}(T).$$

In particular, set(T) with the restricted metric from Z is a completely settled weighted oriented countably \mathcal{H}^m rectifiable metric space with respect to the weight function θ_T defined in Definition 2.30.

When $T = \varphi_{\#}[\![1_A]\!]$, with a bi-Lipschitz function, φ , then for $x \in \varphi(A)$ we have $\lambda(x) = \lambda_{V_x}$ where V_x is \mathbb{R}^m with the norm defined by the metric differential $md\varphi_{\varphi^{-1}(x)}$.

Proof. On the top of page 58 in [**AK00**], Ambrosio-Kirchheim observe that for \mathcal{H}^m almost every $x \in S = \text{set}(T)$, one can define an approximate tangent space $\text{Tan}^m(S,x)$ which is \mathbb{R}^m with a norm. Taking $\lambda(x) = \lambda_{\text{Tan}^m(S,x)}$ and applying [**AK00**](9.10), one sees they have proven (53). We then deduce (52) using the fact that $\Theta_{*m}(\mathcal{H}^m \sqcup \text{set}(T), x) = 1$ almost everywhere [**Kir94**, Theorem 9].

The bounds on λ in (51) come from (50) and they allow us to conclude that the lower density of $\theta_T \mathcal{H}^m$ and the lower density of ||T|| are positive at the same collection of points.

Examining the proof of [**AK00**], Theorem 9.1, one sees that $V_x = \operatorname{Tan}^m(S, x)$ in this setting.

In this section we introduce the notion of an integer rectifiable current structure on a metric space and define integer rectifiable current spaces. We then prove Proposition 2.40 that integer rectifiable current spaces are completely settled weighted oriented \mathcal{H}^m rectifiable metric spaces using the lemmas from Subsection 2.2.

Definition 2.35. An m dimensional **integer rectifiable current structure** on a metric space (X, d) is an integer rectifiable current $T \in \mathcal{I}_m(\bar{X})$ on the completion, \bar{X} , of X such that set (T) = X. We call such a space an **integer rectifiable current space** and denote it (X, d, T).

Given an integer rectifiable current space M=(X,d,T), we let set (M) and X_M denote X, $d_M=d$, and $[\![M]\!]=T$.

Remark 2.36. By [AK00] Defn 4.2, any metric space with an m dimensional current structure must be countably \mathcal{H}^m rectifiable because the set of an m dimensional integer rectifiable current is countably \mathcal{H}^m rectifiable. By [AK00] Thm 4.5, there is a countable collection of bi-Lipschitz charts with compact domains which map onto a dense subset of the metric space (because we only include points of positive density). In particular, the space is separable.

Remark 2.37. We do not use the support, spt(T), in this definition as it is not necessarily countably \mathcal{H}^m rectifiable and may have a higher dimension as described in Remark 2.27. See Example A.22.

Remark 2.38. Recall that in Remark 2.8 we said that any m dimensional oriented connected Lipschitz or Riemannian manifold, M, is endowed with a standard atlas of charts with a fixed orientation. We will also view these spaces as having multiplicity or weight 1. If M has finite volume and we've chosen an orientation, then we can define an integer rectifiable current structure, $T = \llbracket M \rrbracket \in \mathcal{I}_m(M)$, parametrized by a finite disjoint selection of charts with weight 1. It is easy to verify that set (T) = M.

Lemma 2.39. Suppose (X,d,T) is an integer rectifiable current space and Z is a complete metric space. If $\phi: X \to Z$ is an isometric embedding then the induced map on the completion, $\bar{\phi}: \bar{X} \to Z$, is also an isometric embedding. Furthermore, the pushforward $\bar{\phi}_{\#}T$ is an integer rectifiable current on Z and

(54)
$$\phi: X \to \operatorname{set}\left(\bar{\phi}_{\#} \mathrm{T}\right)$$

is an isometry.

Proof. Follows from the fact that set $(\bar{\phi}_{\#}T) = \bar{\phi}(\text{set}(T))$ [AK00]. q.e.d.

Conversely, if T is an integer rectifiable current in Z, then (set (T), d_Z, T) is an m dimensional integer rectifiable current space.

Proposition 2.40. There is a one-to-one correspondence between completely settled weighted oriented countably \mathcal{H}^m rectifiable metric spaces, $(X, d, [\{\phi\}], \theta)$, and integer rectifiable current spaces (X, d, T) as follows:

Given (X, d, T), we define a weight $\theta = \theta_T$ and orientation $[\{\varphi_i\}]$ as in Definition 2.30, so that

(55)
$$\theta := \theta_T = \sum_{i=1}^{\infty} \theta_i \circ \varphi_i^{-1} 1_{\varphi_i(A_i)},$$

and the corresponding space is $(X, d, [\{\varphi_i\}], \theta)$.

Given $(X, d, [\{\varphi\}], \theta)$, we define a unique induced current structure $T \in \mathcal{I}_m(\bar{X})$ given by (56)

$$T\left(f,\pi\right) = \sum \varphi_{i\#} \llbracket \theta \circ \varphi_{i} \rrbracket \left(f,\pi\right) = \sum \int_{A_{i}} \theta \circ \varphi_{i} f \circ \varphi_{i} \det\left(\nabla \left(\pi \circ \varphi_{i}\right)\right) d\mathcal{L}^{m},$$

and the corresponding space is then (X, d, T) because set(T) = X.

Proof. Given $(X, d, [\{\varphi_i\}], \theta)$, we first define a current on the completion \bar{X} using a preferred oriented atlas as in (56). This is well defined because

(57)
$$\sum_{i=1}^{\infty} M\left(\varphi_{i\#}\llbracket\theta\circ\varphi_{i}\rrbracket\right) \leq C_{m} \sum_{i=1}^{\infty} \int_{\varphi_{i}(A_{i})} \theta \, d\mathcal{H}^{m} < \infty$$

where C_m is a constant that may be computed using Lemma 2.34. The sum is then finite by Definition 2.9.

So we have a current with a parametrization $(\{\varphi_i\}, \{\theta_i\})$ where $\theta_i := \theta \circ \varphi_i$. The weight function θ_T of the current T defined below Lemma 2.29 agrees with the weight function θ on X because for almost every $x \in X$ there is a chart such that $x \in \varphi_i(A_i)$, and

(58)
$$\theta_T(x) = \theta_i \circ \varphi_i^{-1}(x) = \theta(x).$$

Furthermore, set (T) = {p $\in \bar{X} : \Theta_{*m}(||T||, p) > 0$ }, so by Lemma 2.34 we have

$$(59) \qquad \operatorname{set}\left(T\right) = \left\{p \in \bar{X}: \Theta_{*m}\left(\theta \, d\mathcal{H}^{m} \, \bigsqcup_{i=1}^{\infty} \varphi_{i}\left(A_{i}\right), p\right) > 0\right\}$$

which is X because X is completely settled. Since X is a countably \mathcal{H}^m rectifiable space, we know $T \in \mathcal{I}_m(\bar{X})$. Thus we have an integer rectifiable current space (X, d, T).

Conversely, we start with (X, d, T). Applying Lemma 2.29, we have a unique well defined orientation and weight function θ_T . Thus (set (T), d, $[\{\varphi_i\}], \theta_T$) is an oriented weighted countably \mathcal{H}^m rectifiable metric space. Since set (T) = X in the definition of a current space, we have shown $(X, d, [\{\varphi_i\}], \theta_T)$ is an oriented weighted countably \mathcal{H}^m rectifiable metric space. As in the above paragraph, we see that set (T) is a completely settled subset of \bar{X} . So X is completely settled.

Note that since the $\{\varphi_i\}$ from the preferred atlas are the $\{\varphi_i\}$ of the parametrization and the weights agree in (58), this pair of maps is a correspondence.

We may now define the mass and relate it to the weighted volume:

Definition 2.41. The **mass** of an integer rectifiable current space (X, d, T) is defined to be the mass, $\mathbf{M}(T)$, of the current structure, T.

Note that the mass is always finite by (iii) in the definition of a current.

Lemma 2.42. If $\varphi: X \to Y$ is a 1-Lipschitz map, then $\mathbf{M}(\varphi_{\#}(T)) \leq \mathbf{M}(T)$. Thus if $\varphi: X \to Y$ is an isometric embedding, then $\mathbf{M}(T) = \mathbf{M}(\varphi_{\#}(T))$.

Recall Definition 2.9 of the weighted volume, $Vol(X, \theta)$. We have the following corollary of Lemma 2.34 and Proposition 2.40:

Lemma 2.43. The mass of an integer rectifiable current space (X, d, T) with multiplicity or weight, θ_T , satisfies

(60)
$$\mathbf{M}(T) = \int_{X} \theta_{T}(x)\lambda(x)d\mathcal{H}^{m}(x).$$

In particular,

(61)
$$M(T) \in \left[m^{-m/2} \operatorname{Vol}(X, \theta), \frac{2^m}{\omega_m} \operatorname{Vol}(X, \theta) \right],$$

where $Vol(X, \theta)$ is the weighted volume defined in Definition 2.9.

Note that on a Riemannian manifold with multiplicity one, the mass and the weighted volume agree and are both equal to the volume of the manifold. On reversible Finsler spaces, $\lambda(x)$ depends on the norm of the tangent space at x.

2.4. Integral current spaces. In this subsection, we define the boundaries of integer rectifiable current spaces and the notion of an integral current space. We begin with Ambrosio-Kirchheim's extension of Federer-Fleming's notion of an integral current [**AK00**, Defn 3.4 and 4.2]:

Definition 2.44 (Ambrosio-Kirchheim). An **integral current** is an integer rectifiable current, $T \in \mathcal{I}_m(Z)$, such that ∂T defined as

(62)
$$\partial T(f, \pi_1, \dots, \pi_{m-1}) := T(1, f, \pi_1, \dots, \pi_{m-1})$$

satisfies the requirements to be a current. One need only verify that ∂T has finite mass as the other conditions always hold. We use the standard notation, $\mathbf{I}_m(Z)$, to denote the space of m dimensional integral currents on Z.

Remark 2.45. By the boundary rectifiability theorem of Ambrosio-Kirchheim [AK00, Theorem 8.6], ∂T is then an integer rectifiable current itself. And in fact it is an integral current whose boundary is 0.

Thus we can make the following new definition:

Definition 2.46. An m dimensional **integral current space** is an integer rectifiable current space, (X, d, T), whose current structure, T, is an integral current (that is, ∂T is an integer rectifiable current in \bar{X}). The boundary of (X, d, T) is then the integral current space:

(63)
$$\partial (X, d_X, T) := (\operatorname{set}(\partial T), d_{\bar{X}}, \partial T).$$

If $\partial T = 0$ then we say (X, d, T) is an integral current without boundary or with zero boundary.

Note that set (∂T) is not necessarily a subset of set (T) = X but it is always a subset of \bar{X} . As in Definition 2.35, given an integer rectifiable current space M = (X, d, T) we will use set (M) or X_M to denote X, $d_M = d$, and [M] = T.

Remark 2.47. On an oriented Riemannian manifold with boundary M, the boundary ∂M defined as a current space agrees with the definition of ∂M in Riemannian geometry. In that setting an atlas of M can be restricted to provide an atlas for ∂M . It is not always possible to do this on integer rectifiable current spaces. In fact, the boundaries of charts need not even have finite mass for an individual chart. If a chart $\varphi: K \subset \mathbb{R}^m \to Z$ with K compact, then $\partial \varphi_{\#} \llbracket 1_K \rrbracket$ is an integral current iff K has finite perimeter.

Remark 2.48. Suppose M and N are connected m dimensional oriented Lipschitz manifolds with the standard current structures $[\![M]\!]$ and $[\![N]\!]$ as in Remark 2.8 and $\psi:M\to N$ a bi-Lipschitz homeomorphism. Then one can do a computation, mapping charts on M to charts on N and applying Lemma 2.29, to see that

(64)
$$\psi_{\#} \llbracket M \rrbracket = \pm \llbracket N \rrbracket.$$

That is, the bi-Lipschitz homeomorphism is either a current preserving or a current reversing map. When M and N are isometric, then the isometry is also current preserving or current reversing.

When M and N are integral current spaces, they may have multiplicity, so that a bi-Lipschitz homeomorphism or isometry from set (M) to set (N) does not in general push $[\![M]\!]$ to $[\![N]\!]$. Even with multiplicity 1, the fact that orientations are defined using disjoint charts can lead to different signs on different charts so that (64) fails.

As in Federer, Ambrosio-Kirchheim define the total mass and we do as well:

Definition 2.49. The **total mass** of an integral current with boundary, T, is

(65)
$$\mathbf{N}(T) = \mathbf{M}(T) + \mathbf{M}(\partial T).$$

Naturally, we can extend this concept to current spaces: $\mathbf{N}(X, d, T) = \mathbf{N}(T)$.

Recall that by Remark 2.36, an integral current space is separable and has a collection of disjoint bi-Lipschitz charts whose image is dense and the boundary of the integral current space has the same property. An integral current space need not be precompact or bounded. An integral current space is not necessarily a geodesic space.

3. The intrinsic flat distance between current spaces

Let \mathcal{M}^m be the space of m dimensional integral current spaces as defined in Definition 2.46. Recall they have the form $M = (X_M, d_M, T_M)$ where $T_M \in \mathbf{I}_m(\bar{X}_M)$ and $\operatorname{set}(T_M) = X_M$. Note \mathcal{M}^m also includes the zero current denoted $\mathbf{0}$.

Definition 1.1 in the introduction naturally applies to any $M, N \in \mathcal{M}^m$ so that

(66)
$$d_{\mathcal{F}}(M, N) := \inf\{\mathbf{M}(U) + \mathbf{M}(V)\}\$$

where the infimum is taken over all complete metric spaces, (Z, d), and all integral currents, $U \in \mathbf{I}_m(Z)$, $V \in \mathbf{I}_{m+1}(Z)$, such that there exist isometric embeddings

(67)
$$\varphi: (\bar{X}_M, d_{\bar{X}_M}) \to (Z, d) \text{ and } \psi: (\bar{X}_N, d_{\bar{X}_N}) \to (Z, d)$$

with

(68)
$$\varphi_{\#}T_M - \psi_{\#}T_N = U + \partial V.$$

Here we consider the **0** space to isometrically embed into any Z with $\varphi_{\#}0 = 0 \in \mathbf{I}_m(Z)$.

Note that, by the definition, $d_{\mathcal{F}}$ is clearly symmetric. In Subsection 3.1 we prove that $d_{\mathcal{F}}$ satisfies the triangle inequality on \mathcal{M}^m [Theorem 3.2]. As a consequence, the distance between integral current spaces is always finite and is easy to estimate [Remark 3.3].

In Subsection 3.2, we review the compactness theorems of Gromov and of Ambrosio-Kirchheim, and present a compactness theorem for intrinsic flat convergence [Theorem 3.20], which follows immediately from theirs.

In Subsection 3.3, we prove Theorem 3.23 that the infimum in the definition of the intrinsic flat distance is attained between precompact integral current spaces. That is, there exist a common metric space, Z, and integral currents, $U \in \mathbf{I}_m(Z)$ and $V \in \mathbf{I}_{m+1}(Z)$, achieving the infimum in (66).

In Subsection 3.4 we prove that $d_{\mathcal{F}}$ is a distance on \mathcal{M}_0^m . That is, we prove that when two precompact integral current spaces are a distance zero apart, there is a current preserving isometry between them [Theorem 3.27]. Thus $d_{\mathcal{F}}$ is a distance on \mathcal{M}_0^m where

(69)
$$\mathcal{M}_0^m = \{ M \in \mathcal{M}^m : X_M \text{ is precompact} \}.$$

Remark 3.1. Note that the flat distance d_F^Z given above Definition 1.1 has an infimum that is taken over all $U \in \mathbf{I}_m(Z)$, $V \in \mathbf{I}_{m+1}(Z)$ where the supports of U and V may be noncompact or even unbounded as long as they have finite mass. Thus we can have unbounded limits [Example A.10] and bounded noncompact limits [Example A.11].

3.1. The triangle inequality. In this section we prove the triangle inequality for the intrinsic flat distance between integral current spaces:

Theorem 3.2. For all $M_1, M_2, N \in \mathcal{M}^m$, we have

(70)
$$d_{\mathcal{F}}(M_1, M_2) \leq d_{\mathcal{F}}(M_1, N) + d_{\mathcal{F}}(N, M_2).$$

In the proof of this theorem, we do not assume the infimum in (66) is finite. Naturally, the theorem is immediately true if the right hand side of (70) is infinite. It is a consequence of the theorem that when the right hand side is finite, the left hand side is finite as well. Applying the theorem with $N_1 = \mathbf{0}$, we may then conclude the distance is finite and estimate it using the masses of M_1 and M_2 :

Remark 3.3. Taking U = M and V = 0 in (66), we see that $d_{\mathcal{F}}(M,0) \leq \mathbf{M}(M)$, so the intrinsic flat distance between any pair of integral current spaces of finite mass is finite

(71)
$$d_{\mathcal{F}}(M_1, M_2) \leq d_{\mathcal{F}}(M_1, 0) + d_{\mathcal{F}}(0, M_2) \leq \mathbf{M}(M_1) + \mathbf{M}(M_2).$$

In particular, when M_i are Riemannian manifolds, then $\mathbf{M}(M_i) = \operatorname{Vol}(M_i)$ and we have

(72)
$$d_{\mathcal{F}}(M_1, M_2) \leq \operatorname{Vol}(M_1) + \operatorname{Vol}(M_2).$$

To prove Theorem 3.2 we apply the following well-known gluing lemma (cf. [BBI01]):

Lemma 3.4. Given three metric spaces (Z_1, d_1) , (Z_2, d_2) , and (X, d_X) and two isometric embeddings $\varphi_i : X \to Z_i$, we can glue Z_1 to Z_2 along the isometric images of X to create a space $Z = Z_1 \sqcup_X Z_2$ where $d_Z(x, x') = d_i(x, x')$ when $x, x' \in Z_i$ and

(73)
$$d_{Z}\left(z,z'\right) = \inf_{x \in X} \left(d_{1}\left(z,\varphi_{1}\left(x\right)\right) + d_{2}\left(\varphi_{2}\left(x\right),z'\right)\right)$$

whenever $z \in Z_1, z' \in Z_2$. There exist natural isometric embeddings $f_i: Z_i \to Z$ such that $f_1 \circ \varphi_1 = f_2 \circ \varphi_2$ is an isometric embedding of X into Z.

We now prove Theorem 3.2:

Proof. Let $M_i = (X_i, d_i, T_i)$ and N = (X, d, T), and let Z_1, Z_2 be metric spaces and let $\psi_i : \bar{X}_i \to Z_i$ and $\varphi_i : \bar{X} \to Z_i$ be isometric embeddings. Let $U_i \in \mathbf{I}_m(Z_i)$ and $V_i \in \mathbf{I}_{m+1}(Z_i)$ such that

(74)
$$\varphi_{i\#}T - \psi_{i\#}T_i = U_i + \partial V_i.$$

Applying Lemma 3.4, we create a metric space Z with isometric embeddings $f_i: Z_i \to Z$ such that $f_1 \circ \varphi_1 = f_2 \circ \varphi_2$ is an isometric embedding of X into Z. Pushing forward the current structures to Z, we have $f_{1\#}\varphi_{1\#}T = f_{2\#}\varphi_{2\#}T$, so

$$f_{1\#}\psi_{1\#}T_1 - f_{2\#}\psi_{2\#}T_2$$

$$(75) = f_{1\#}\psi_{1\#}T_1 - f_{1\#}\varphi_{1\#}T + f_{2\#}\varphi_{2\#}T - f_{2\#}\psi_{2\#}T_2$$

(76)
$$= f_{1\#}(\psi_{1\#}T_1 - \varphi_{1\#}T) + f_{2\#}(\varphi_{2\#}T - \psi_{2\#}T_2)$$

$$(77) = f_{1\#}(-U_1 - \partial V_1) + f_{2\#}(U_2 + \partial V_2)$$

$$(78) \qquad = -f_{1\#}U_1 - \partial f_{1\#}V_1 + f_{2\#}U_2 + \partial f_{2\#}V_2$$

(79)
$$= f_{2\#}U_2 - f_{1\#}U_1 + \partial(f_{2\#}V_2 - f_{1\#}V_1).$$

So by (66) applied to the isometric embeddings $f_i \circ \psi_i : \bar{X}_i \to Z$, we have

(80)
$$d_{\mathcal{F}}(M_1, M_2) \leq \mathbf{M}(f_{2\#}U_2 - f_{1\#}U_1) + \mathbf{M}(f_{2\#}V_2 - f_{1\#}V_1).$$

Applying the fact that mass is a norm and Lemma 2.42, we have

(81)

$$d_{\mathcal{F}}(M_1, M_2) \leq \mathbf{M}(f_{2\#}U_2) + \mathbf{M}(f_{1\#}U_1) + \mathbf{M}(f_{2\#}V_2) + \mathbf{M}(f_{1\#}V_1)$$

$$= \mathbf{M}(U_2) + \mathbf{M}(U_1) + \mathbf{M}(V_2) + \mathbf{M}(V_1).$$
(82)

Taking an infimum over all U_i and V_i satisfying (74), we see that

(83)
$$d_{\mathcal{F}}(M_1, M_2) \le d_F^{Z_1}(\varphi_{1\#}T, \psi_{1\#}T_1) + d_F^{Z_2}(\varphi_{2\#}T, \psi_{2\#}T_2).$$

Taking an infimum over all metric spaces Z_1, Z_2 and all isometric embeddings $\psi_i : \bar{X}_i \to Z_i$ and $\varphi_i : \bar{X} \to Z_i$, we obtain the triangle inequality. q.e.d.

3.2. A brief review of existing compactness theorems. Gromov defined the following distance between metric spaces in [Gro07]:

Definition 3.5 (Gromov). Recall that the Gromov-Hausdorff distance between two metric spaces (X, d_X) and (Y, d_Y) is defined as

(84)
$$d_{GH}(X,Y) := \inf d_H^Z(\varphi(X), \psi(Y))$$

where Z is a complete metric space, and $\varphi: X \to Z$ and $\psi: Y \to Z$ are isometric embeddings, and where the Hausdorff distance in Z is defined as

(85)
$$d_H^Z(A, B) = \inf\{\epsilon > 0 : A \subset T_{\epsilon}(B) \text{ and } B \subset T_{\epsilon}(A)\}.$$

Gromov proved that this is indeed a distance on compact metric spaces: $d_{GH}(X,Y) = 0$ iff there is an isometry between X and Y. There are many equivalent definitions of this distance; we choose to state this version because it inspired our definition of the intrinsic flat distance. Gromov also introduced the following notions:

Definition 3.6 (Gromov). A collection of metric spaces is said to be equibounded or uniformly bounded if there is a uniform upper bound on the diameter of the spaces.

Remark 3.7. We will write N(X,r) to denote the maximal number of disjoint balls of radius r in a space X. Note that X can always be covered by N(X,r) balls of radius 2r.

Definition 3.8 (Gromov). A collection of spaces is said to be equicompact or uniformly compact if they have a common upper bound N(r) such that $N(X,r) \leq N(r)$ for all spaces X in the collection.

Note that Ilmanen's Example depicted in Figure 1 is not equicompact, as the number of balls centered on the tips approaches infinity [Example A.7].

Gromov's Compactness Theorem states that sequences of equibounded and equicompact metric spaces have a Gromov-Hausdorff converging subsequence [Gro81]. In fact, Gromov proves a stronger version of this statement in a subsequent work, [Gro82, p. 65], which we state here so that we may apply it:

Theorem 3.9 (Gromov's Compactness Theorem). If a sequence of compact metric spaces, X_j , is equibounded and equicompact, then there is a pair of compact metric spaces $Y \subset Z$, and a subsequence X_{j_i} which isometrically embed into $Z: \varphi_{j_i}: X_{j_i} \to Z$ such that

(86)
$$\lim_{i \to \infty} d_H^Z \left(\varphi_{j_i} \left(X_{j_i} \right), Y \right) = 0.$$

So (Y, d_Z) is the Gromov-Hausdorff limit of the X_{i_1} .

Gromov's proof of the stronger statement involves a construction of a metric on the disjoint union of the sequence of spaces. This method of proving the Gromov compactness theorem relies on the fact that infimum in (3.5) can be estimated arbitrarily well by taking Z to be a disjoint union of the spaces and choosing a clever metric on Z.

The reason we have stated this stronger version of Gromov's Compactness Theorem is because it can be applied in combination with Ambrosio-Kirchheim's compactness theorem to prove our first compactness theorem for integral current spaces [Theorem 3.20].

Recall the notion of total mass [Definition 2.49]. Ambrosio-Kirchheim's Compactness Theorem, which extends Federer-Fleming's Flat Norm Compactness Theorem, is stated in terms of weak convergence of currents. See Definition 3.6 in [AK00] which extends Federer-Fleming's notion of weak convergence:

Definition 3.10 (Weak Convergence). A sequence of integral currents $T_j \in \mathbf{I}_m(Z)$ is said to converge weakly to a current T iff the pointwise limits satisfy

(87)
$$\lim_{j \to \infty} T_j(f, \pi_1, \dots, \pi_m) = T(f, \pi_1, \dots, \pi_m)$$

for all bounded Lipschitz f and Lipschitz π_i .

Remark 3.11. If we suppose one has a sequence of isometric embeddings, $\varphi_i: X \to Z$, which converge uniformly to $\varphi: X \to Z$, and $T \in \mathbf{I}_m(X)$, then $\varphi_{i\#}T$ converges to $\varphi_{\#}T$. This can be seen by applying properties (ii) and (iii) in the definition of a current as follows:

$$\lim_{i \to \infty} \varphi_{i\#} T(f, \pi_1, \dots, \pi_m) = \lim_{i \to \infty} T(f \circ \varphi_i, \pi_1 \circ \varphi_i, \dots, \pi_m \circ \varphi_i)$$

$$= T(f \circ \varphi, \pi_1 \circ \varphi, \dots, \pi_m \circ \varphi)$$

$$= \varphi_\# T(f, \pi_1, \dots, \pi_m).$$

Remark 3.12. If $T_j \in \mathbf{I}_m(Z)$ has $\mathbf{M}(T_j) \to 0$, then by (23),

(88)
$$\left|T_j(f, \pi_1, \dots, \pi_m)\right| \leq \mathbf{M}(T_j)|f|_{\infty} \operatorname{Lip}(\pi_1) \cdots \operatorname{Lip}(\pi_m) \to 0,$$
 so T_j converges weakly to 0.

Remark 3.13. Note that flat convergence implies weak convergence because $T_j \stackrel{\mathcal{F}}{\longrightarrow} T$ implies there exists U_j, V_j with $\mathbf{M}(U_j) + \mathbf{M}(V_j) \to 0$ such that $T_j - T = U_j + \partial V_j$. This implies that U_j and V_j must converge weakly to 0 and ∂V_j must as well. So $T_j - T \rightharpoonup 0$ and $T_j \rightharpoonup T$.

Remark 3.14. Immediately below the definition of weak convergence [**AK00**] Defn 3.6, Ambrosio-Kirchheim prove the lower semicontinuity of mass. In particular, if T_j converges weakly to T, then $\lim\inf_{j\to\infty}\mathbf{M}(T_j)\geq\mathbf{M}(T)$.

Remark 3.15. It should be noted here that weak convergence as defined in Federer [Fed69] is tested only with differential forms of compact support while weak convergence in Ambrosio-Kirchheim does not require the test tuples to have compact support. Sequences of unit spheres in Euclidean space whose centers diverge to infinity converge weakly to 0 in the sense of Federer but not in the sense of Ambrosio-Kirchheim.

Theorem 3.16 (Ambrosio-Kirchheim Compactness). Given any complete metric space Z, a compact set $K \subset Z$, and any sequence of integral currents $T_j \in \mathbf{I}_m(Z)$ with a uniform upper bound on their total mass $\mathbf{N}(T_j) = \mathbf{M}(T_j) + \mathbf{M}(\partial T_j) \leq M_0$, such that set $(T_j) \subset K$, there exist a subsequence, T_{j_i} , and a limit current $T \in \mathbf{I}_m(Z)$ such that T_{j_i} converges weakly to T.

The key point of this theorem is that the limit current is an integral current and has a rectifiable set with finite mass and rectifiable boundary with bounded mass.

In order to apply Ambrosio-Kirchheim's result, we need a result of the second author from [Wen07, Theorem 1.4] which generalizes a theorem of Federer-Fleming relating the weak and flat norms. As in Federer-Fleming, one needs a uniform bound on total mass to have the relationship. To simplify the statement of [Wen07, Theorem 1.4], we restrict the setting to Banach spaces although his result is far more general:

Theorem 3.17 (Wenger Flat=Weak Convergence). Let E be a Banach space and $m \geq 1$. If we assume a sequence of integral currents, $T_j \in \mathbf{I}_m(E)$, has a uniform upper bound on total mass $\mathbf{M}(T_j) + \mathbf{M}(\partial T_j)$, then T_j converges weakly to $T \in \mathbf{I}_m(E)$ iff T_j converges to T in the flat sense.

For our purposes, it suffices to have a Banach space, because we may apply Kuratowski's embedding theorem to embed any complete metric space into a Banach space:

Theorem 3.18 (Kuratowski Embedding Theorem). Let Z be a complete metric space, and $\ell^{\infty}(Z)$ be the space of bounded real valued functions on Z endowed with the sup norm. Then the map $\iota: Z \to \ell^{\infty}(Z)$ defined by fixing a basepoint $z_0 \in Z$ and letting $\iota(z) = d_Z(z_0, \cdot) - d_Z(z, \cdot)$ is an isometric embedding.

Remark 3.19. By the Kuratowski embedding theorem, the infimum in (66) can be taken over Banach spaces, Z.

Combining Kuratowski's Embedding Theorem with Gromov and Ambrosio-Kirchheim's Compactness Theorems, we immediately obtain:

Theorem 3.20. Given a sequence of m dimensional integral current spaces $M_j = (X_j, d_j, T_j)$ such that X_j are equibounded and equicompact and such that $\mathbf{N}(T_j)$ is uniformly bounded above, then a subsequence converges in the Gromov-Hausdorff sense $(X_{j_i}, d_{j_i}) \to (Y, d_Y)$ and in the intrinsic flat sense $(X_{j_i}, d_{j_i}, T_{j_i}) \to (X, d, T)$ where either (X, d, T) is an m dimensional integral current space with $X \subset Y$ or it is the $\mathbf{0}$ current space.

Note that X might be a strict subset of Y as seen in Example A.12, depicted in Figure 3.

Proof. By Gromov's Compactness Theorem, there exist a compact space Z and isometric embeddings $\varphi_j: X_j \to Z$ such that a subsequence of the $\varphi_j(X_j)$, still denoted $\varphi_j(X_j)$, converges in the Hausdorff sense to a closed subset, $Y' \subset Z$. We then apply Kuratowski's Theorem to define isometric embeddings $\varphi'_j = \iota \circ \varphi_j: X_j \to \ell^{\infty}(Z)$. Note that $K = \iota(Z) \subset \ell^{\infty}(Z)$ is compact and

(89)
$$\operatorname{spt} \varphi'_{j\#}(T_j) \subset Cl\left(\varphi'_j(X_j)\right) \subset \iota(Z) = K.$$

Let $Y = \iota(Y')$ with the restricted metric.

We now apply the Ambrosio-Kirchheim Compactness Theorem to see that there exists a further subsequence $\varphi'_{j_i\#}T_{j_i}$ converging weakly to an integral current $S\in \mathbf{I}_m$ ($\ell^\infty(Z)$). We claim spt $S\subset Y$. If not, then there exists $x\in\operatorname{spt} S\setminus Y$, and there exists r>0 such that $B(x,r)\cap Y=0$. By definition of support, ||S||(B(x,r/2))>0. By weak convergence, there is an i sufficiently large that $||S_{j_i}||(B(x,r))>0$. In particular, $x\in T_{r/2}(\operatorname{spt} S_{j_i})$. Taking $i\to\infty$, we see that $x\in T_r(Y)$ because Y is the Hausdorff limit of the spt S_{j_i} .

Since $E = \ell^{\infty}(Z)$ is a Banach space and there is a uniform upper bound on the total mass, we apply Wenger's Flat=Weak Convergence Theorem to see that

(90)
$$d_F^E\left(\varphi_{j_i\#}'T_{j_i},S\right)\to 0.$$

We now define our limit current space (X, d, T) by taking X = set(S), $d = d_E$, and T = S. The identity map isometrically embeds X into E and takes T to S. Since $\text{set}(S) \subset \text{spt}(S) \subset Y$, we are done. q.e.d.

We have the following immediate corollary of Theorem 3.20:

Corollary 3.21. Given a sequence of precompact m dimensional integral current spaces, $M_j = (X_j, d_j, T_j)$, with a uniform upper bound on their total mass such that X_j converge in the Gromov-Hausdorff sense to a compact limit space, Y, of lower Hausdorff dimension, $\dim_{\mathcal{H}}(Y) < m$, then M_j converges in the intrinsic flat sense to the $\mathbf{0}$ current space because the zero current is the only m dimensional integral current whose canonical set has Hausdorff dimension less than m.

Remark 3.22. Note that by Remark 3.3 any collapsing sequence of Riemannian manifolds, M_j^m such that $\operatorname{Vol}(M_j) \to 0$, converges in the intrinsic flat sense to the $\mathbf{0}$ integral current space. Thus even when the Gromov-Hausdorff limit is higher dimensional as in Example A.17 the intrinsic flat limit may collapse to the $\mathbf{0}$ current space.

3.3. The infimum is achieved. In this subsection we prove the infimum in the definition of the intrinsic flat distance (66) is achieved for precompact integral current spaces.

Theorem 3.23. Given a pair of precompact integral current spaces, M = (X, d, T) and M' = (X', d', T'), there exist a compact metric space, Z, integral currents $U \in \mathbf{I}_m(Z)$ and $V \in \mathbf{I}_{m+1}(Z)$, and isometric embeddings $\varphi : \bar{X} \to Z$ and $\varphi' : \bar{X}' \to Z$ with

(91)
$$\varphi_{\#}T - \varphi'_{\#}T' = U + \partial V$$

such that

(92)
$$d_{\mathcal{F}}(M, M') = \mathbf{M}(U) + \mathbf{M}(V).$$

In fact, we can take $Z = \operatorname{spt}(U) \cup \operatorname{spt}(V)$.

This theorem also holds for $M' = \mathbf{0}$, where we just take T' = 0 and do not concern ourselves with embedding X' into Z.

In our proof of this theorem, we use the notion of an injective metric space and Isbell's theorem regarding the existence of an injective envelope of a metric space [Isb64]:

Definition 3.24. A metric space W is said to be injective iff it has the following property: given any pair of metric spaces, $Y \subset Z$, and any 1-Lipschitz function, $f: Y \subset Z \to W$, we can extend f to a 1-Lipschitz function $\bar{f}: Z \to W$.

Theorem 3.25 (Isbell). Given any metric space X, there is a smallest injective space, which contains X, called the injective envelope. Furthermore, when X is compact, its injective envelope is compact as well.

We now prove Theorem 3.23.

Proof. Let Z_n and $U_n \in \mathbf{I}_m(Z_n)$ and $V_n \in \mathbf{I}_{m+1}(Z_n)$ approach the infimum in the definition of the flat distance between current spaces (66). That is, there exist isometric embeddings $\varphi_n : \bar{X} \to Z_n$ and $\varphi'_n : \bar{X}' \to Z_n$ such that

(93)
$$\varphi_{n\#}T - \varphi'_{n\#}T' = U_n + \partial V_n$$

where

(94)
$$\mathbf{M}(U_n) + \mathbf{M}(V_n) \le d_{\mathcal{F}}(M, M') + \frac{1}{n}.$$

We would like to apply Ambrosio-Kirchheim's Compactness Theorem, so we need to find a common compact metric space, Z, and push U_n and V_n into this common space and then take their limits to find U and V. We will build Z in a few stages using Gromov's Compactness Theorem and Isbell's Theorem. The Z_n we have right now need not be equicompact or equibounded.

We first claim that φ_n, φ'_n and Z_n may be chosen so that (95)

$$\operatorname{diam}(Z_n) \leq 3 \operatorname{diam}(\varphi_n(\bar{X})) + 3 \operatorname{diam}(\varphi'_n(\bar{X}')) = 3 \operatorname{diam}(X) + 3 \operatorname{diam}(X').$$

If not, then there exist $p_n \in \varphi_n(\bar{X})$ and $p'_n \in \varphi'_n(\bar{X}')$ such that the closed balls

(96)
$$\bar{B}(p_n, 2\operatorname{diam}(X)) \cap \bar{B}(p'_n, 2\operatorname{diam}(X')) = \emptyset.$$

Taking $A_n = Z_n \setminus (\bar{B}(p_n, 2\operatorname{diam}(X)) \cup \bar{B}(p'_n, 2\operatorname{diam}(X')))$, we would then define $Z'_n := Z_n/A_n$ with the quotient metric (97)

$$d_{Z'_n}([z_1],[z_2]) := \inf \{ d_{Z_n}(x_1,a_1) + d_{Z_n}(a_2,x_2) : x_i \in [z_i], a_i \in A_n \}.$$

Then Z'_n has the required bound on diameter and we need only construct the embeddings.

Let $p: Z_n \to Z_n/A$ be the projection. Then p is an isometric embedding when restricted to $\varphi_n(X) \subset \bar{B}(p_n, \operatorname{diam}(X))$ or to $\varphi_n(X') \subset \bar{B}(p'_n, \operatorname{diam}(X'))$. Thus $p \circ \varphi_n : \bar{X} \to Z_n/A$ and $p \circ \varphi'_n : \bar{X}' \to Z_n/A$ are isometric embeddings. Furthermore, p is 1-Lipschitz on Z_n , so

(98)
$$p_{\#}\varphi_{n\#}T - p_{\#}\varphi'_{n\#}T' = p_{\#}U_n + \partial p_{\#}V_n$$

and, by Lemma 2.42.

(99)
$$\mathbf{M}\left(p_{\#}U_{n}\right) + \mathbf{M}\left(p_{\#}V_{n}\right) \leq \mathbf{M}\left(U_{n}\right) + \mathbf{M}\left(V_{n}\right).$$

So our first claim is proven.

Now let $Y_n := \varphi_n(\bar{X}) \cup \varphi'_n(\bar{X}') \subset Z_n$ with the restricted metric from Z_n . By our first claim, the diameters of the Y_n are uniformly bounded. In fact, the Y_n are equicompact because the number of disjoint balls of radius r may easily be estimated:

(100)
$$N(Y_n, r) \le N(\varphi_n(X), r) + N(\varphi'_n(X'), r) = N(X, r) + N(X', r).$$

Thus, by Gromov's Compactness Theorem, there exist a compact metric space, Z', and isometric embeddings $\psi_n: Y_n \to Z'$.

Recall that $U_n \in \mathbf{I}_m(Z_n)$ and $V_n \in \mathbf{I}_{m+1}(Z_n)$, so we need to extend ψ_n to Z_n in order to push forward these currents into the common compact metric space, Z, and take their limits.

By Isbell's Theorem, we may take Z to be the injective envelope of Z'. Since Z is injective, we can extend the 1-Lipschitz maps, ψ_n , to 1-Lipschitz maps, $\bar{\psi}_n:Z_n\to Z$. So now we have a common compact metric space, Z, and isometric embeddings $\bar{\psi}_n\circ\varphi_n:\bar{X}\to Z$ and $\bar{\psi}_n\circ\varphi_n':\bar{X}'\to Z$, such that

(101)
$$\bar{\psi}_{n\#}\varphi_{n\#}T - \bar{\psi}_{n\#}\varphi'_{n\#}T' = \bar{\psi}_{n\#}U_n + \partial\bar{\psi}_{n\#}V_n$$

where

(102)
$$\mathbf{M}\left(\bar{\psi}_{n\#}U_{n}\right) + \mathbf{M}\left(\bar{\psi}_{n\#}V_{n}\right) \leq d_{\mathcal{F}}\left(M, M'\right) + \frac{1}{n}.$$

By Arzela-Ascoli's Theorem, after taking a subsequence, the isometric embeddings $\bar{\psi} \circ \varphi_n : X \to Z$ and $\bar{\psi} \circ \varphi_n' : X' \to Z$ converge uniformly to isometric embeddings $\varphi : X \to Z$ and $\varphi' : X' \to Z$. As in Remark 3.11, we then have weak convergence:

(103)
$$\bar{\psi}_{n\#}\varphi_{n\#}T \rightharpoonup \varphi_{\#}T \text{ and } \bar{\psi}_{n\#}\varphi'_{n\#}T' \rightharpoonup \varphi'_{\#}T'.$$

By Ambrosio-Kirchheim's Compactness Theorem, after possibly taking a further subsequence, there exist $U \in \mathbf{I}_m(Z)$, $V \in \mathbf{I}_{m+1}(Z)$ such that

(104)
$$\bar{\psi}_{\#}U_n \rightharpoonup U \text{ and } \bar{\psi}_{\#}V_n \rightharpoonup V.$$

In particular, $\varphi_{\#}T - \varphi'_{\#}T' = U - \partial V$.

By the lower semicontinuity of mass (cf. Remark 3.14),

(105)
$$\mathbf{M}(U) + \mathbf{M}(V) \le d_{\mathcal{F}}(M, M') + \frac{1}{n} \quad \forall n \in \mathbb{N}$$

and we are done. q.e.d.

3.4. Current preserving isometries. We can now prove that the intrinsic flat distance is a distance on the space of precompact oriented Riemannian manifolds with boundary and, more generally, on precompact integral current spaces in \mathcal{M}_0^m .

Definition 3.26. Given $M, N \in \mathcal{M}^m$, an isometry $f: X_M \to X_N$ is called a current preserving isometry between M and N, if its extension $\bar{f}: \bar{X}_M \to \bar{X}_N$ pushes forward the current structure on M to the current structure on N: $\bar{f}_\# T_M = T_N$.

When M and N are oriented Riemannian manifolds or other Lipschitz manifolds with the standard current structures as described in Remark 2.8, then orientation preserving isometries are exactly current preserving isometries. See Remark 2.48.

Theorem 3.27. If M, N are precompact integral current spaces such that $d_{\mathcal{F}}(M, N) = 0$ then there is a current preserving isometry from M to N. Thus $d_{\mathcal{F}}$ is a distance on \mathcal{M}_0^m .

It should be noted that a pair of precompact metric spaces, X, Y such that $d_{GH}(X,Y) = 0$ need not be isometric (e.g. the Gromov-Hausdorff distance between a Riemannian manifold, and the same manifold with one point removed, is 0). However, if X and Y are compact, then Gromov proved $d_{GH}(X,Y) = 0$ implies they are isometric [**Gro07**].

While we do not require that our spaces be complete, the definition of an integral current space requires that the spaces be completely settled [Defn 2.11] so that X = set(T) [Defn 2.46]. This is as essential to the proof of Theorem 3.27 as the compactness is essential in Gromov's theorem. Precompactness, on the other hand, is not a necessary condition. Theorem 3.27 can be extended to noncompact integral current spaces applying Theorem 6.1 in the second author's compactness paper [Wen11].

Proof. By Theorem 3.23 and the fact that an integral current has zero mass iff it is 0, we know there exist a compact space Z and isometric embeddings, $\varphi: (\bar{X}_M, d_{\bar{X}}) \to (Z, d)$ and $\psi: (\bar{X}_N, d_{\bar{X}_N}) \to (Z, d)$, with

(106)
$$\varphi_{\#}T_{M} - \psi_{\#}T_{N} = 0 \in \mathbf{I}_{m}\left(Z\right).$$

Thus

(107)
$$\operatorname{set}(\varphi_{\#}T_{M}) = \operatorname{set}(\psi_{\#}T_{N}).$$

By Lemma 2.39, we know $\varphi: X_M \to \text{set}(\varphi_\# T_M)$ and $\psi: X_N \to \text{set}(\psi_\# T_N)$ are isometries.

We define our isometry $f: X_M \to X_N$ to be $f = \psi^{-1} \circ \varphi$. Then $\bar{f}: \bar{X}_M \to \bar{X}_N$ pushes $T_M \in \mathbf{I}_m(\bar{X}_M)$ to $\bar{f}_\# T_M \in \mathbf{I}_m(\bar{X}_N)$, so that with (106) we have

(108)
$$\psi_{\#}\bar{f}_{\#}T_{M} = \varphi_{\#}T_{M} = \psi_{\#}T_{N}.$$

Since $\psi_{\#}(f_{\#}T_M - T_N) = 0 \in \mathbf{I}_m(Z)$ and ψ is an isometry, we have $f_{\#}T_M - T_N = 0 \in \mathbf{I}_m(\bar{X}_N)$.

The following is an immediate consequence of Theorem 3.27:

Corollary 3.28. If M^m and N^m are precompact oriented Riemannian manifolds with finite volume, then $d_{\mathcal{F}}(M^m, N^m) = 0$ iff there is an orientation preserving isometry, $\psi: M^m \to N^m$. Thus $d_{\mathcal{F}}$ is a distance on the space of precompact oriented Riemannian manifolds with finite volume.

Remark 3.29. Initially we were hoping to prove that if the intrinsic flat distance between two Riemannian manifolds is zero then the manifolds are isometric. This is false unless the manifold has an orientation reversing isometry as we prove in Theorem 3.27. We thought we might

use a \mathbb{Z}_2 notion of integral currents to avoid the issue of orientation. However, at the time there was no such theory, so we settled on this version of the theorem with this notion of intrinsic flat distance. Very recently, Ambrosio-Katz [**AK10**] and Ambrosio-Wenger [**AW**] completed work covering this theory, and one expects this will lead to interesting new ideas. Alternatively, one could try to use the even more recent theory of DePauw-Hardt [**DPH**].

4. Sequences of integral current spaces

In this section we describe the properties of sequences of integral current spaces which converge in the intrinsic flat sense.

In Subsection 4.1 we take a Cauchy or converging sequence of precompact integral current spaces and construct a common metric space, Z, into which the entire sequence embeds [Theorem 4.1 and Theorem 4.2]. Note that Z need not be compact even when the spaces are. Relevant examples are given and an open question appears in Remark 4.5.

In Subsection 4.2 we remark on the properties of converging sequences of integral current spaces. We prove the lower semicontinuity of mass [Theorem 4.6] which is a direct consequence of Ambrosio-Kirchheim [AK00]. We remark on the continuity of filling volume which follows from work of the second author [Wen07].

In Subsection 4.3 we state consequences of the authors' first paper [SW10] concerning limits of sequences of Riemannian manifolds with contractibility conditions as in work of Greene-Petersen [GPV92]. We discuss how to avoid the kind of cancellation in Example A.19, depicted in Figure 6, using Gromov's filling volume [Gro83].

In Subsection 4.4 we discuss noncollapsing sequences of manifolds with nonnegative Ricci or positive scalar curvature, particularly in Theorem 4.16 and Conjecture 4.18, which appear in our first paper [SW10].

In Subsection 4.5 we state the second author's compactness theorem [Theorem 4.19] which is proven in [Wen11]. We then prove Theorem 4.20 which provides a common metric space Z for a Cauchy sequence bounded as in the compactness theorem. In particular, any Cauchy sequence of integral current spaces with a uniform upper bound on diameter and total mass converges to an integral current space.

4.1. Embeddings into a common metric space. In this subsection we prove Theorems 4.1, 4.2, and 4.3 which describe how Cauchy and converging sequences of integral current spaces, M_i , can be isometrically embedded into a common separable complete metric space Z as a flat Cauchy or converging sequence. These theorems are essential to understanding sequences of manifolds which do not have Gromov-Hausdorff limits. We will also apply them to prove Theorem 4.20.

Theorem 4.1. Given an intrinsic flat Cauchy sequence of integral current spaces, $M_j = (X_j, d_j, T_j) \in \mathcal{M}^m$, there exist a separable complete metric space Z, and a sequence of isometric embeddings $\varphi_j : X_j \to Z$ such that $\varphi_{j\#}T_j$ is a flat Cauchy sequence of integral currents in Z.

The classic example of a Cauchy sequence of integral currents converging to Gabriel's Horn shows that a uniform upper bound on mass is required to have a limit space which is an integral current space [Example A.23]. So the Cauchy sequence in this theorem need not converge without an additional assumption on total mass. In Example A.10 we see that even with the uniform bound on total mass, the sequence may have a limit which is unbounded. In Example A.11, depicted in Figure 7, we see that even with a uniform bound on total mass and diameter, the limit space need not be precompact. See also Remark 4.5 and Theorem 4.20.

If we assume that the Cauchy sequence of integral current spaces converges to a given integral current space, then we can embed the entire sequence including the limit into a common metric space Z:

Theorem 4.2. If a sequence of integral current spaces, $M_j = (X_j, d_j, T_j)$, converges to an integral current space, $M_0 = (X_0, d_0, T_0)$, in the intrinsic flat sense, then there is a separable complete metric space, Z, and isometric embeddings $\varphi_j : X_j \to Z$ such that $\varphi_{j\#}T_j$ flat converges to $\varphi_{0\#}T_0$ in Z and thus converges weakly as well.

Note that one cannot construct a compact Z as Gromov did in $[\mathbf{Gro82}]$, even when one knows the sequence converges in the intrinsic flat sense to a compact limit space and that the sequence has a uniform bound on total mass. The sequence of hairy spheres in Example A.7 converges to a sphere in the flat norm but cannot be isometrically embedded into a common compact space because the sequence is not equicompact.

The special case of Theorem 4.2 where M_j converges to the **0** space can have prescribed pointed isometries:

Theorem 4.3. If a sequence of integral current spaces $M_j = (X_j, d_j, T_j)$ converges in the intrinsic flat sense to the zero integral current space, $\mathbf{0}$, then we may choose points $p_j \in X_j$ and a separable complete metric space, Z, and isometric embeddings $\varphi_j : \bar{X}_j \to Z$ such that $\varphi_j(p_j) = z_0 \in Z$ and $\varphi_{j\#}T_j$ flat converges to 0 in Z and thus converges weakly as well.

We prove this theorem first since it is the simplest.

Proof. By the definition of the flat distance, we know there exists a complete metric space Z_j and $U_j \in \mathbf{I}_m(Z_j)$ and $V_j \in \mathbf{I}_{m+1}(Z_j)$ and an isometry $\varphi_j: X_j \to Z_j$ such that $\varphi_{j\#}T_j = U_j + \partial V_j$ and

(109)
$$d_{\mathcal{F}}(M_i, \mathbf{0}) \le \mathbf{M}(U_i) + \mathbf{M}(V_i) \to 0.$$

We may choose $Z_j = \operatorname{spt} U_j \cup \operatorname{spt} V_j$, so it is separable.

We then create a common complete separable metric space Z by gluing all the Z_j together at the common point $\varphi_j(p_j)$:

$$(110) Z = Z_1 \sqcup Z_2 \sqcup \cdots$$

where $d_Z(z_1, z_2) = d_{Z_i}(z_1, z_2)$ when there exists an i with $z_1, z_2 \in Z_i$ and

(111)
$$d_Z(z_i, z_j) = d_{Z_i}(z_i, \varphi_i(p_i)) + d_{Z_i}(z_j, \varphi_i(p_j)).$$

We then identify all the $\varphi_i(p_i) = \varphi_j(p_j) \in Z$ so that this is a metric. Since mass is preserved under isometric embeddings, we have $d_F^Z(\varphi_{j\#}T_j,0) \leq \mathbf{M}(U_j) + \mathbf{M}(V_j) \to 0$. q.e.d.

To prove Theorems 4.1 and 4.2, we need to glue together our spaces Z in a much more complicated way. So we first prove the following two lemmas and then prove the theorems. We close the section with Remark 4.5 which discusses a related open problem.

Recall the well known gluing lemma [Lemma 3.4] that we applied to prove the triangle inequality in Subsection 3.1. One may apply this gluing of metric spaces countably many times, to glue together countably many distinct metric spaces:

Lemma 4.4. We are given a connected tree with countable vertices $\{V_i : i \in A \subset \mathbb{N}\}$ and edges $\{E_{i,j} : (i,j) \in B\}$ where $B \subset \{(i,j) : i < j, i, j \in A\}$, and a corresponding countable collection of metric spaces $\{X_i : i \in A\}$ and $\{Z_{i,j} : (i,j) \in B\}$ and isometric embeddings

(112)
$$\varphi_{i,(i,j)}: X_i \to Z_{i,j} \text{ and } \varphi_{j,(i,j)}: X_j \to Z_{i,j} \quad \forall (i,j) \in B.$$

Then there is a unique metric space Z defined by gluing the $Z_{i,j}$ along the isometric images of the X_i . In particular, there exist isometric embeddings $f_{i,j}: Z_{i,j} \to Z$ for all $(i,j) \in B$ such that for all $(i,j), (j,k) \in B$ we have isometric embeddings

(113)
$$f_{i,j} \circ \varphi_{j,(i,j)} = f_{j,k} \circ \varphi_{j,(j,k)} : X_j \to Z.$$

If $Z_{i,j}$ are separable, then so is Z.

Proof. Let Z be the disjoint union of the $Z_{i,j}$. We define a quasimetric on Z and then identify the images of the X_i so that the quasimetric becomes a metric. Let $z, z' \in Z$, so each lies in one of the $Z_{i,j}$ and thus has a corresponding edge $E(z), E(z') \in \{E_{i,j} : (i,j) \in B\}$.

If E(z) = E(z'), then they lie in the same $Z_{i,j}$ and we let $d_Z(z,z') := d_{Z_{i,j}}(z,z')$ which we denote as $d_{i,j}$ to avoid excessive subscripts below.

If $E(z) \neq E(z')$, then because the graph is a connected tree there is a unique sequence of distinct edges $\{E_{i_0,i_1}, E_{i_1,i_2}, \dots, E_{i_n,i_{n+1}}\}$ where

$$E(z) = E_{i_0,i_1}$$
 and $E(z') = E_{i_n,i_{n+1}}$. We define

$$d_{Z}(z,z') = \inf \left\{ d_{i_{0},i_{1}}(z,\varphi_{i_{1},(i_{0},i_{1})}(y_{1})) + \sum_{j=1}^{n-1} d_{i_{j},i_{j+1}}(\varphi_{i_{j},(i_{j},i_{j+1})}(y_{j}),\varphi_{i_{j+1},(i_{j},i_{j+1})}(y_{j+1})) + d_{i_{n},i_{n+1}}(\varphi_{i_{n},(i_{n},i_{n+1})}(y_{n}),z') : (y_{1},\ldots,y_{n}) \in X_{i_{1}} \times \cdots \times X_{i_{n}} \right\}.$$

One may then easily verify the triangle inequality $d_Z(a,b) + d_Z(b,c) \ge d_Z(a,c)$ by breaking into cases regarding the location of E(b) relative to E(a) and E(c). Finally we identify points z and z' such that $d_Z(z,z') = 0$.

We can now prove Theorem 4.1:

Proof. Recall that we have a Cauchy sequence of current spaces, so for all $\epsilon > 0$, there exists $N_{\epsilon} \in \mathbb{N}$ such that

(114)
$$r_{i,j} = d_{\mathcal{F}}(M_i, M_j) < \epsilon \qquad \forall i, j \ge N_{\epsilon}.$$

By the definition of the intrinsic flat distance between M_i and M_j in (66), there exist metric spaces $Z_{i,j}$ and isometric embeddings $\varphi_{i,(i,j)}$: $\bar{X}_i \to Z_{i,j}$ and $\varphi_{j,(i,j)}: \bar{X}_j \to Z_{i,j}$ and integral currents $U_{i,j} \in \mathbf{I}_m(Z_{i,j})$ and $V_{i,j} \in \mathbf{I}_{m+1}(Z_{i,j})$ with

(115)
$$\varphi_{i,(i,j)\#}T_{i} - \varphi_{j,(i,j)\#}T_{j} = U_{i,j} + \partial V_{i,j} \in \mathbf{I}_{m}(Z_{i,j})$$

such that

(116)
$$r_{i,j} := d_{\mathcal{F}}(M_i, M_j) = d_F^{Z_{i,j}} \left(\varphi_{i,(i,j)\#} T_i, \varphi_{j,(i,j)\#} T_j \right) \\ \leq \mathbf{M} \left(U_{i,j} \right) + \mathbf{M} \left(V_{i,j} \right) \leq 3r_{i,j} / 2.$$

We choose $Z_{i,j} = \operatorname{spt} U_j \cup \operatorname{spt} V_j$ and so it is separable.

Since the sequence is Cauchy, we know there exists a subsequence $j_k \in \mathbb{N}$ such that $j_1 = 1$, and when $k \geq 2$ we have $r_{j_k,i} \leq 1/2^k \ \forall i \geq j_k$. In particular, $r_{j_k,j_{k+1}} \leq 1/2^k$ when $k \geq 2$. We call this special subsequence a geometric subsequence.

We now apply Lemma 4.4 to the graph whose vertices are $\{V_i : i \in A = \mathbb{N}\}$ and edges $\{E_{i,j} : (i,j) \in B \subset \mathbb{N} \times \mathbb{N}\}$ where

(117)
$$B = \{(j_k, j_{k+1}) : k \in \mathbb{N}\} \cup \{(j_k, i) : i = j_k, \dots, j_{k+1} - 1\}.$$

Intuitively, this is a tree whose trunk is the geometric subsequence and whose branches consist of single edges attached to the nearest vertex on the trunk.

As a result, we have a complete metric space Z and isometric embeddings $f_{i,j}: Z_{i,j} \to Z$ such that

$$(118) f_{i,j} \circ \varphi_{i,(i,j)} = f_{i,i'} \circ \varphi_{i,(i,i')} : X_i \to Z$$

are isometric embeddings for all $(i, j), (j, i') \in B$. In particular, each current space M_j has been mapped to a unique current in Z:

(119)
$$T'_{i} := f_{i,j\#} \varphi_{i,(i,j)\#} T_{j} = f_{j,i'\#} \varphi_{j,(j,i')\#} T_{j} \in \mathbf{I}_{m}(Z).$$

So $f_{i,j} \circ \varphi_{j,(i,j)}$ is a current preserving isometry from $M_j = (X_j, d_j, T_j)$ to $(\text{set}(T'_j), d_Z, T'_j)$.

Applying (115), we have for any $(i, j) \in B$:

$$\dot{T}'_{i} - \dot{T}'_{j} = f_{i,j\#} \varphi_{i,(i,j)\#} T_{i} - f_{i,j\#} \varphi_{j,(i,j)\#} T_{j} = f_{i,j\#} U_{i,j} + \partial f_{i,j\#} V_{i,j} \in \mathbf{I}_{m} (Z) .$$

Since mass is conserved under isometries (cf. Lemma 2.42), we have (121)

$$d_F^Z(T_i', T_j') \le \mathbf{M}(f_{i,j\#}U_{i,j}) + \mathbf{M}(f_{i,j\#}V_{i,j}) = \mathbf{M}(U_{i,j}) + \mathbf{M}(V_{i,j}) = 3r_{i,j}/2.$$

In particular, by our choice of B in (118), we have for the geometric subsequence:

(122)
$$d_F^Z\left(T'_{j_k}, T'_{j_{k+1}}\right) \le 3/2^k \ \forall k \ge 2.$$

For $i, i' \geq j_2$ we have $k, k' \geq 2$ respectively such that $(i, j_k), (i', j_{k'}) \in B$ and

(123)
$$d_F^Z(T'_{j_k}, T'_i) \le 3/2^k \text{ and } d_F^Z(T'_{j_{k'}}, T'_{i'}) \le 3/2^{k'}.$$

So we have

(124)

$$d_F^Z\left(T_i', T_{i'}'\right) \le d_F^Z\left(T_{j_k}', T_i'\right) + \sum_{h=k}^{k'-1} d_F^Z\left(T_{j_h}', T_{j_{h+1}}'\right) + d_F^Z\left(T_{j_{k'}}', T_{i'}'\right)$$

$$(125) \qquad \le 3/2^k + \left(3/2^k + 3/2^{k+1} + \dots + 3/2^{k'}\right) < 9/2^k$$

and thus our sequence of integral current spaces has been mapped into a Cauchy sequence of integral currents. q.e.d.

We now prove Theorem 4.2. Since we have already proven Theorem 4.3, we will assume we have a nonzero limit in this proof:

Proof. As in the proof of Theorem 4.1, we take a geometrically converging subsequence of the converging sequence of current spaces. This time we apply Lemma 4.4 to the tree whose vertices are $\{V_i : i \in A = 0 \cup \mathbb{N}\}$ and edges $\{E_{i,j} : (i,j) \in B \subset \mathbb{N} \times \mathbb{N}\}$ where

(126)
$$B = \{(j_k, 0) : k \in \mathbb{N}\} \cup \{(j_k, i) : i = j_k, \dots, j_{k+1} - 1\}$$

so that all the terms in the geometric subsequence will be directly attached to the limit, and everything else will be attached to the subsequence as before. As in (119) we obtain unique currents $T'_j \in \mathbf{I}_m(Z)$ such that $\left(\operatorname{set}(\mathbf{T}'_j), \mathbf{d}_{\mathbf{Z}}, \mathbf{T}'_j \right)$ has a current preserving isometry with (X_j, d_j, T_j) . This time our currents flat converge, because for any $i \in [j_k, j_{k+1} - 1]$ we have

$$(127) d_F^Z\left(T_i', T_0'\right) \le d_F^Z\left(T_{i_k}', T_0'\right) + d_F^Z\left(T_i', T_{i_k}'\right) \le 3/2^k + 3/2^k.$$

Weak convergence then follows by Remark 3.13.

q.e.d.

Remark 4.5. We do not know if the sequence $\varphi_{j\#}T_j$ in Theorem 4.1 when given a uniform bound on total mass converges in the flat sense to an integral current in Z. Without a uniform bound on total mass it is possible there is no limit integral current space [Example A.23].

It is an open question whether flat Cauchy sequences with uniform upper bounds on total mass have flat converging subsequences which converge to an integral current in the sense of Ambrosio-Kirchheim. In Federer-Fleming, one needs to add a diameter bound because integral currents in Federer-Fleming have compact support. In Ambrosio-Kirchheim compactness is never assumed, so an unbounded limit like the one in Example A.10 is not a counter example here.

In Theorem 4.20 we prove that by adding a uniform bound on diameter as well as the bound on total mass, we can find a common metric space Z where $\varphi_{j\#}T_j$ do converge. The metric space Z in that theorem may not be the metric space constructed in Theorem 4.1. To prove that theorem, we need Theorem 4.2 as well as the second author's compactness theorem, Theorem 4.19. It would be of interest to eliminate the bound on diameter or find a counter example.

4.2. Properties of intrinsic flat convergence. As a consequence of Theorems 4.2 and 4.3 and Kuratowski's Embedding Theorem, we may now observe that sequences of integral current spaces that converge in the intrinsic flat sense have all the same properties Ambrosio-Kirchheim have proven for sequences of integral currents that converge weakly in a Banach space. Most importantly, one has the lower semicontinuity of mass. Applying work of the second author in [Wen07] [Theorem 1.4], one also observes that one has continuity of the filling volume. Here we only give the details on lower semicontinuity of mass and leave it to the reader to extend the ideas to other properties of integral currents.

Theorem 4.6. If a sequence of integral current spaces $M_j = (X_j, d_j, T_j)$ converges in the intrinsic flat sense to $M_0 = (X_0, d_0, T_0)$ then ∂M_j converges to ∂M_0 in the intrinsic flat sense

(128)
$$\liminf_{j\to\infty} \mathbf{M}(M_j) \ge \mathbf{M}(M_0)$$
 and $\liminf_{j\to\infty} \mathbf{M}(\partial M_j) \ge \mathbf{M}(\partial M_0)$.

In Example A.19, depicted in Figure 6, we see that the mass of the limit space may be 0 despite a uniform lower bound on the mass of the sequence.

Proof. First we isometrically embed the converging sequence into a common metric space, Z, applying Theorem 4.2 and Theorem 4.3: φ_j : $\bar{X}_j \to Z$ such that $\varphi_{j\#}T_j$ converges in the flat sense in Z to $\varphi_{0\#}T_0$. Note that

$$d_F^Z(\partial \varphi_{i\#}T_i, \partial \varphi_{0\#}T_0) \le d_F^Z(\varphi_{i\#}T_i, \varphi_{0\#}T_0) \to 0.$$

By the definition of $\partial M=(\operatorname{set}(\partial T),\operatorname{d},\partial T)$ and the fact that $\partial \varphi_{j\#}T=\varphi_{j\#}\partial T$, we have

(129)
$$d_{\mathcal{F}}(\partial M_j, \partial M_0) \le d_F^Z(\varphi_{j\#} \partial T_j, \varphi_{0\#} T_0) \to 0.$$

Immediately below the definition of weak convergence of currents in a metric space Z in [AK00, Defn 3.6], Ambrosio-Kirchheim remark that the mapping $T \mapsto ||T||(A)$ is lower semicontinuous with respect to weak convergence for any open set $A \subset Z$. Since $\varphi_{j\#}T_j$ converge weakly to $\varphi_{0\#}T_0$, we may take A = Z and apply Lemma 2.42, to see that

(130)
$$\liminf_{j \to \infty} \mathbf{M}(M_j) = \liminf_{j \to \infty} \mathbf{M}(\varphi_{j\#}T_j) \ge \mathbf{M}(\varphi_{0\#}T_0) = \mathbf{M}(M_0).$$

The same may be done to the boundaries to conclude that

$$\liminf_{j\to\infty} \mathbf{M}\left(\partial M_j\right) \ge \mathbf{M}\left(\partial M_0\right).$$
 q.e.d.

Remark 4.7. Note that there are also local versions of the lower semicontinuity of mass which can be seen by taking A in the proof above to be a ball $B_{\varphi_0(x_0)}(r)$. These local versions require an application of Ambrosio-Kirchheim's Slicing Theorem [AK00] [Thm 5.6], which implies that $\varphi_{j\#}T_j \sqcup B_{\varphi_0(x_0)}(r)$ is an integral current for almost all values of r. The reader is referred to [SW10] where local versions of lower semicontinuity of mass and continuity of filling volume are applied.

4.3. Cancellation and intrinsic flat convergence. When a sequence of integral currents converges to the 0 current due to the effect of two sheets of opposing orientation coming together, this is referred to as cancellation. In Example A.19, depicted in Figure 6, we see that the same effect can occur causing a sequence of Riemannian manifolds to converge in the intrinsic flat sense to the **0** current space. Naturally, it is of great importance to avoid this situation.

In [SW10], the authors proved a few theorems providing conditions that prevent cancellation of certain weakly converging sequences of integral currents. These theorems immediately apply to prevent the cancellation of certain sequences of Riemannian manifolds, although they do not extend to arbitrary integral current spaces. The reader is referred to [SW10] for the most general statements of these results.

In this section we give some of the intuition that led to these results, then review Greene-Petersen's compactness theorem, and finally review a result of [SW10], Theorem 4.14, which states that under the conditions of Greene-Petersen's theorem, there is no cancellation and, in fact, the intrinsic flat and Gromov-Hausdorff limits agree.

Remark 4.8. The initial observation that led to the results in [SW10] was that the sequence in Example A.19, depicted in Figure 6, has increasing topological type. The only way to bring two sheets together with an intrinsic distance on a smooth Riemannian manifold was to create many small tubes between the two sheets, and all these tubes led to increasing local topology.

Remark 4.9. The second observation was that, in order to avoid cancellation, one needed to locally bound the filling volume of spheres away from 0. More precisely, the filling volumes of distance spheres of radius r had to be bounded below by Cr^m , so that the filling volumes in the limit would have the same bound. Since the volume of a ball is larger than the filling volume of the sphere, we could then prove the limit points had positive density.

Note that if a sequence of Riemannian manifolds converges to a Riemannian manifold with a cusp singularity as in Example A.9 (depicted in Figure 8), the cusp point disappears in the limit because it does not have positive density [Example 2.12, Example 2.26]. To avoid cancellation, we need to prevent points from disappearing.

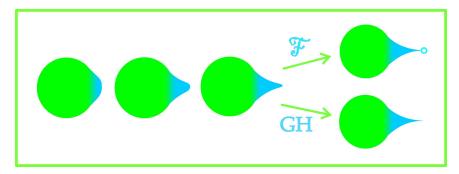


Figure 8. The intrinsic flat limit does not include the tip of the cusp.

In Gromov's initial paper defining filling volume, he proved the filling volume could be bounded from below by the filling radius and the filling radius could be bounded from below by applying contractibility estimates [Gro83]. Greene-Petersen applied Gromov's technique to estimate the filling volumes of balls and consequently prove the following compactness theorem [GPV92]. They needed a uniform estimate on contractibility to prove their theorem:

Definition 4.10. On a Riemannian manifold, M^m , a geometric contractibility function, $\rho:(0,r_0]\to(0,\infty)$, is a function such that $\lim_{r\to 0}\rho(r)=0$ and such that any ball $B_p(r)\subset M^m$ is contractible in $B_p(\rho(r))\subset M^m$.

Theorem 4.11 (Greene-Petersen). If a sequence of Riemannian manifolds M_j^m without boundary have a uniform geometric contractibility function, $\rho: (0, r_0] \to (0, \infty)$ then one can construct uniform lower bound $\nu_{\rho,m}: (0,D] \to (0,\infty)$ such that

(131)
$$\operatorname{Vol}(B_{p}(r)) \geq \operatorname{Fillvol}(\partial B_{p}(r)) \geq \nu_{\rho,m}(r)$$

for all balls $B_p(r)$ in all the manifolds. If, in addition, there is a uniform upper bound on volume $\operatorname{Vol}(M_j^m) \leq V$, then a subsequence $M_j^m \stackrel{GH}{\longrightarrow} Y$.

Immediately below the statement of this theorem, Greene-Petersen mention that if ρ is linear, $\rho(r) = \lambda r$, then there exists a constant $C_m > 0$ such that $\nu_{\rho,m}(r) \geq C_m r^m$. This is exactly the bound needed to avoid cancellation.

If the geometric contractibility function ρ is not linear then one can have a sequence of Riemannian manifolds which converge to a Riemannian manifold with a cusp singularity as in Example A.9 depicted, in Figure 8. The lack of a uniform linear geometric contractibility function for that sequence is depicted in Figure 9.

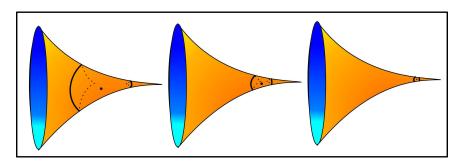


Figure 9. The first ball contracts in a ball of twice its radius, the second in a ball of 3 times its radius, the next in a ball of five times its radius...

Cones have linear geometric contractibility functions (as seen in Figure 10). Riemannian manifolds with conical singularities viewed as integral current spaces include their conical singularities [Example 2.12, Example 2.26].

In [SW10], we dealt with a far more general class of integral current spaces than Riemannian manifolds. We began by applying Gromov's compactness theorem to isometrically embed the sequence into a common metric space where we used a notion of integral filling volume (cf.

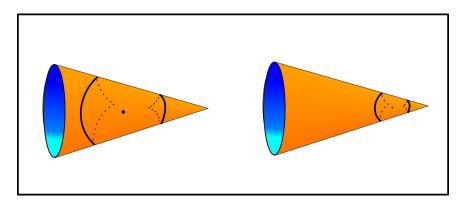


Figure 10. The contractibility function is $\rho(r) = 2r$ here.

[Wen05]), which is well defined for integral currents without boundary. We did not use Greene-Petersen's smoothing arguments, applying Ambrosio-Kirchheim's Slicing Theorem instead. We needed to adapt everything to integral filling volumes, so we applied a new Lipschitz extension theorem akin to that of Lang-Schlichenmaier [LS05]. This led to the following local theorem we could apply to avoid cancellation. The following is a simplified restatement of [SW10] Theorem 4.1:

Theorem 4.12. [SW10] If M^m is an oriented Lipschitz manifold of finite volume with integral current structure, T, and if there is a ball, $B_x(r) \subset M^m$, that has $\partial T \sqcup B_x(r) = 0$, and if $B_x(r)$ has a uniform linear geometric contractibility function, $\rho : [0, 2r] \to [0, \infty)$, with $\rho(r) = \lambda r$, then (132)

$$||T||(B_x(s)) \ge Fillvol_{\infty}(\partial (T \sqcup \bar{B}_x(r)) \ge C_{\lambda} s^m \ a.e. \ s \in [0, r/(2^{m+6} \lambda^{m+1})].$$

Example 4.13. Note that the condition here that $\partial T \perp B_x(r) = 0$ is necessary. If M^m were a thin flat strip $[0,1] \times [0,\epsilon]$, all balls in M^m would have $\rho(r) = r$, but the volumes of the balls would be less than $2r\epsilon$.

This theorem combined with the ideas described in Remark 4.9 leads to the following theorem demonstrating that the limits occurring in Greene-Petersen's compactness theorem have no cancellation:

Theorem 4.14. [SW10] If a sequence of connected oriented Lipschitz manifolds without boundary, $M_j^m = (X_j, d_j, T_j)$, has a uniform linear geometric contractibility function, $\rho : [0, r_0] \to [0, \infty)$, with $\rho(r) = \lambda r$, and a uniform upper bound on volume, then a subsequence converges in both the intrinsic flat sense and the Gromov-Hausdorff sense to the same space $M^m = (X, d, T)$. In particular, M^m is a countably \mathcal{H}^m rectifiable metric space.

A more general version of Theorem 4.14, which allows for boundaries, is stated as Corollary 1.6 in our paper [SW10].

Remark 4.15. If the contractibility function is not linear, Schul-Wenger have shown the limit space need not be countably \mathcal{H}^m rectifiable [SW10, Appendix]. Note that Ferry-Okun have shown that without a uniform upper bound on volume, these sequences can converge to an infinite dimensional space [FO95].

4.4. Ricci and Scalar curvature. Gromov proved that a sequence of manifolds, M_j^m , with nonnegative Ricci curvature and a uniform upper bound on diameter, have a subsequence which converges in the Gromov-Hausdorff sense to a compact geodesic space, Y [Gro07]. Cheeger-Colding proved that in the noncollapsed setting, where the volumes are uniformly bounded below, the manifolds converge in the metric measure sense to Y with the Hausdorff measure, \mathcal{H}^m . In particular, if $p_j \in M_j$ converge to $y \in Y$ then $\operatorname{Vol}(B_{p_j}(r))$ converges to $\mathcal{H}^m(B_y(r))$. Furthermore, Y is countably \mathcal{H}^m rectifiable with Euclidean tangent cones almost everywhere. Points with Euclidean tangent cones are called regular points and, at such points, the density of the Hausdorff measure is 1. In fact, $\lim_{r\to 0} \mathcal{H}^m(B_y(r))/r^m = \omega_m$. [CC97].

Such sequences do not have uniform geometric contractibility functions as seen by Perelman's example in [Per97]. In fact Menguy proved the limit space could have infinite topological type [Men00]. Nevertheless, in [SW10], the authors proved that the Gromov-Hausdorff and intrinsic flat distances agree in this setting:

Theorem 4.16. [SW10] If a noncollapsing sequence of oriented Riemannian manifolds without boundary, $M_j^m = (X_j, d_j, T_j)$, has nonnegative Ricci curvature and a uniform upper bound on diameter, then a subsequence converges in both the intrinsic flat sense and the Gromov-Hausdorff sense to the same space $M^m = (X, d, T)$.

This theorem can be viewed as an example of a noncancellation theorem. The proof is based on Theorem 4.12 and the fact that Perelman proved that balls of large volume in a manifold with nonnegative Ricci curvature are contractible [**Per94**]. We also applied the work of Cheeger-Colding [**CC97**], which states that in this setting the volumes of balls converge and that almost every point in the Gromov-Hausdorff limit is a regular point. Regular points have Euclidean tangent cones and $\lim_{r\to 0} \mathcal{H}^m(B_y(r))/r^m = \omega_m$.

Remark 4.17. It would be interesting if one could prove this theorem directly without resorting to the powerful theory of Cheeger-Colding. That would give new insight, perhaps allowing one to extend this result to situations with weaker conditions on the curvature.

In [SW10] we presented an example of a sequence of three dimensional Riemannian manifolds with positive scalar curvature that converge in the intrinsic flat sense to the 0 integral current space. Example A.19, depicted in Figure 6, is a two dimensional version of this example. The example with positive scalar curvature is constructed by connecting a pair of standard three dimensional spheres by an increasingly dense collection of tunnels. Each tunnel is constructed using Schoen-Yau or Gromov-Lawson's method [SY79] [GL80]. This sequence has increasingly negative Ricci and sectional curvatures within the tunnels, but the scalar curvature remains positive. Note that each tunnel has a minimal two sphere inside. It is natural, in the study of general relativity, to require that a manifold have positive scalar curvature and no interior minimal surfaces. The boundary is allowed to consist of minimal surfaces.

The following conjecture is based upon discussions with Ilmanen:

Conjecture 4.18. A converging sequence of three dimensional Riemannian manifolds with positive scalar curvature, a uniform lower bound on volume, and no interior minimal surfaces converges without cancellation to a nonzero integral current space.

A solution to this conjecture would have applications in general relativity and is essential to solving Ilmanen's 2004 proposal that a new weak form of convergence needs to be developed to better understand manifolds with positive scalar curvature.

4.5. Wenger's compactness theorem. In [Wen11], the second author has proven the key compactness theorem for the intrinsic flat distance:

Theorem 4.19. [Wen11] [Theorem 1.2] Let m, C, D > 0 and let \bar{X}_j be a sequence of complete metric spaces. Given $T_j \in \mathbf{I}_m(\bar{X}_j)$ with uniform bounds on total mass and diameter

(133)
$$\mathbf{M}(T_i) + \mathbf{M}(\partial T_i) < C$$

and

(134)
$$\operatorname{diam}(\operatorname{spt}(T_i)) \le D,$$

then there exist a subsequence T_{j_i} , a complete metric space Z, an integral current $T \in \mathbf{I}_m(Z)$, and isometric embeddings $\varphi_{j_i} : \bar{X}_{j_i} \to Z$ such that

(135)
$$d_F^Z(\varphi_{j_i\#}T_{j_i},T) \to 0.$$

In particular, if $M_n = (X_n, d_n, T_n)$ is a sequence of integral current spaces satisfying (133) and (134), then a subsequence converges in the intrinsic flat sense to an integral current space of the same dimension. The limit space is in fact $M = (\text{set}(T), d_Z, T)$.

In particular, sequences of oriented Riemannian manifolds with boundary with a uniform upper bound on volume, on the volume of the boundary, and on diameter have a subsequence which converges in the intrinsic flat sense to an integral current space. Note that even when the sequence of manifolds is compact, the limit space need not be precompact, as seen in Example A.11, depicted in Figure 7.

We now apply this compactness theorem combined with techniques from the proof of Theorem 4.2 to prove Theorem 4.20. We do not apply this compactness theorem anywhere else in this paper.

Contrast this with Theorem 4.1 and see Remark 4.5.

Theorem 4.20. Given an intrinsic flat Cauchy sequence of integral current spaces, $M_j^m = (X_j, d_j, T_j)$, with a uniform bound on total mass, $\mathbf{N}(M_j) \leq V_0$, and a uniform bound on diameter, $\operatorname{diam}(M_j) \leq D$, there exist a complete metric space Z and a sequence of isometric embeddings $\varphi_j : X_j \to Z$ such that $\varphi_{j\#}T_j$ is a flat Cauchy sequence of integer rectifiable currents in Z which converges in the flat sense to an integral current $T \in \mathbf{I}_m(Z)$.

Thus M_j^m converges in the intrinsic flat sense to an integral current space (set(T), d_Z, T).

Proof. First there is a subsequence $(X_{j_i}, d_{j_i}, T_{j_i})$ which converges in the intrinsic flat sense to an integral current space (X, d, T), by Wenger's compactness theorem. Since (X_j, d_j, T_j) is Cauchy, it also converges to (X, d, T). Theorem 4.2 then yields the claim.

5. Lipschitz maps and convergence

We review Lipschitz convergence and prove that when sequences of manifolds converge in the Lipschitz sense, then they converge in the intrinsic flat sense. As a consequence, sequences of manifolds which converge in the $C^{k,\alpha}$ sense or the C^{∞} sense also converge in the intrinsic flat sense. Lemmas in this section will also be useful when proving the examples in the final section of the paper.

5.1. Lipschitz maps. The purpose of this subsection is to list some basic properties of the intrinsic flat norm of an integral current space. Some of the lemmas will be used later on for the construction of examples in Appendix A. Others will be used to relate the Lipschitz convergence to intrinsic flat convergence [Theorem 5.6].

Recall that a metric space X is called injective if for every metric space Y, every subset $A \subset Y$, and every Lipschitz map $\varphi : A \to X$, there exists a Lipschitz extension $\bar{\varphi} : Y \to X$ of φ with the same Lipschitz constant. It is not difficult to check that given a set Z, the Banach space $l^{\infty}(Z)$ of bounded functions, endowed with the supremum norm, is injective (cf. [**BL00**] p 12–13).

Given a complete metric space X and $T \in \mathbf{I}_m(X)$, we define (136)

$$\mathcal{F}_X(T) :=$$

$$\inf \left\{ \mathbf{M}\left(U\right) + \mathbf{M}\left(V\right) : U \in \mathbf{I}_{m}\left(X\right), V \in \mathbf{I}_{m+1}\left(X\right), T = U + \partial V \right\}$$

whereas

(137)

$$\mathcal{F}(T) :=$$

 $\inf \{ \mathcal{F}_Z (\varphi_\# T) : Z \text{ metric space, } \varphi : X \hookrightarrow Z \text{ isometric embedding} \}.$

Lemma 5.1. Given an injective metric space X and $T \in \mathbf{I}_m(X)$, we have $\mathcal{F}(T) = \mathcal{F}_X(T)$.

Proof. Let Z be a metric space and $\varphi: X \hookrightarrow Z$ an isometric embedding. Since X is injective, there exists a 1-Lipschitz extension $\psi: Z \to X$ of $\varphi^{-1}: \varphi(X) \to X$. Let $U \in \mathbf{I}_m(Z)$ and $V \in \mathbf{I}_{m+1}(Z)$ with $\varphi_\# T = U + \partial V$ and observe that $U' := \psi_\# U$ and $V' := \psi_\# V$ satisfy T = U' + V' and

(138)
$$\mathbf{M}(U') + \mathbf{M}(V') \leq \mathbf{M}(U) + \mathbf{M}(V).$$

Since U and V were arbitrary, it follows that $\mathcal{F}_X(T) \leq \mathcal{F}(T)$. q.e.d.

Lemma 5.2. Let X and Y be complete metric spaces and let φ : $X \to Y$ be a λ -bi-Lipschitz map. Then for each $T \in \mathbf{I}_m(X)$ we have

$$\mathcal{F}(T) \leq \lambda^{m+1} \mathcal{F}_Y(\varphi_\# T)$$
.

Proof. Let $\iota: X \to l^{\infty}(X)$ be the Kuratowski embedding and let $\bar{\varphi}: Y \to l^{\infty}(X)$ be a λ -Lipschitz extension of $\iota \circ \varphi^{-1}$. Given $U \in \mathbf{I}_m(Y)$ and $V \in \mathbf{I}_{m+1}(Y)$ with $\varphi_{\#}T = U + \partial V$ then $\iota_{\#}T = \bar{\varphi}_{\#}U + \partial (\bar{\varphi}_{\#}V)$ and thus (139)

$$\mathcal{F}\left(T\right) = \mathcal{F}_{l^{\infty}(X)}\left(\iota_{\#}T\right) \leq \mathbf{M}\left(\bar{\varphi}_{\#}U\right) + \mathbf{M}\left(\bar{\varphi}_{\#}V\right) \leq \lambda^{m}\mathbf{M}\left(U\right) + \lambda^{m+1}\mathbf{M}\left(V\right).$$

Minimizing over all U and V selected as above completes the proof. q.e.d.

Lemma 5.3. Let X be a complete metric space and $\varphi: X \to \mathbb{R}^N$ a λ -Lipschitz map where $\lambda \geq 1$. For $T \in \mathbf{I}_m(X)$ we have

(140)
$$\mathcal{F}(T) \ge \left(\sqrt{N}\lambda\right)^{-(m+1)} \mathcal{F}_{\mathbb{R}^N}\left(\varphi_{\#}T\right).$$

We illustrate the use of the lemma by a simple example: Let M be an m dimensional oriented submanifold of \mathbb{R}^N of finite volume and finite boundary volume. Endow M with the length metric and call the so-defined metric space X. Clearly, the inclusion $\varphi: X \to \mathbb{R}^N$ is 1-Lipschitz. Let T be the integral current in X induced by integration over M. The above lemma thus implies

(141)
$$\mathcal{F}(T) \ge N^{-\frac{m+1}{2}} \mathcal{F}_{\mathbb{R}^N} \left(\llbracket M \rrbracket \right)$$

where $[\![M]\!]$ is the current in \mathbb{R}^N induced by integration over M.

Proof. Let $A = \iota(X) \subset l^{\infty}(X)$ where $\iota: X \to l^{\infty}(X)$ denotes the Kuratowski embedding. Then $\varphi \circ \iota^{-1}: A \to \mathbb{R}^N$ is a λ -Lipschitz map. By McShane's extension theorem there exists a $\sqrt{N}\lambda$ -Lipschitz extension $\psi: l^{\infty}(X) \to \mathbb{R}^N$ of $\varphi \circ \iota^{-1}: A \to \mathbb{R}^N$ [McS34].

Thus, if $U \in \mathbf{I}_m(l^{\infty}(X))$ and $V \in \mathbf{I}_{m+1}(l^{\infty}(X))$ are such that $\iota_{\#}T = U + \partial V$, then

(142)
$$\varphi_{\#}T = \psi_{\#}\iota_{\#}T = \psi_{\#}U + \psi_{\#}(\partial V) = \psi_{\#}U + \partial(\psi_{\#}V)$$

and

(143)

$$\mathcal{F}_{\mathbb{R}^{N}}\left(\varphi_{\#}T\right) \leq \mathbf{M}\left(\psi_{\#}U\right) + \mathbf{M}\left(\psi_{\#}V\right) \leq \left(\sqrt{N}\lambda\right)^{m+1} \left[\mathbf{M}\left(U\right) + \mathbf{M}\left(V\right)\right].$$

We now obtain the claim by minimizing over all U and V and using Lemma 5.1.

In the following lemma we bound the intrinsic flat distance between an integral current space and its image under a bi-Lipschitz map. Recall the total mass $\mathbf{N}(T) = \mathbf{M}(T) + \mathbf{M}(\partial T)$ [Definition 2.49].

Lemma 5.4. Let X and Y be complete metric spaces and let $\varphi: X \to Y$ be a λ -bi-Lipschitz map for some $\lambda > 1$. Then for $T \in \mathbf{I}_m(X)$ viewed as an integral current space $T = (\text{set}(T), d_X, T)$ and $\varphi_\# T = (\text{set}(\varphi_\# T), d_Y, \varphi_\# T)$, we have

(144)
$$d_{\mathcal{F}}(T, \varphi_{\#}T) \leq k_{\lambda,m} \max\{\operatorname{diam}(\operatorname{spt} T), \operatorname{diam}(\varphi(\operatorname{spt} T))\} \mathbf{N}(T)$$

where $k_{\lambda,m} := \frac{1}{2}(m+1)\lambda^{m-1}(\lambda-1)$.

Proof. Let $C_0 := \operatorname{spt} T$, $C_1 := \varphi(C_0)$, and denote by d_0 and d_1 the metric on C_0 and C_1 , respectively. Let $D := \max\{\operatorname{diam} C_0, \operatorname{diam} C_1\}$. Let d_Z be the metric on $Z := C_0 \sqcup C_1$ which extends d_0 on C_0 and d_1 on C_1 and which satisfies

(145)
$$d_{Z}(x, x') = \inf\{d_{0}(x, \bar{x}) + d_{1}(\varphi(\bar{x}), x') : \bar{x} \in C_{0}\} + \lambda' D,$$

whenever $x \in C_0$ and $x' \in C_1$ and where $\lambda' := \frac{1}{2}\lambda^{-1}(\lambda - 1)$. It is not difficult to verify that d_Z is in fact a metric.

Let $\varphi_i: C_i \to l^{\infty}(Z)$ be the composition of the inclusion map with the Kuratowski embedding. Note that these are isometric embeddings. Define a map $\psi: [0,1] \times C_0 \to l^{\infty}(Z)$ using linear interpolation:

(146)
$$\psi(t,x) := (1-t)\varphi_0(x) + t\varphi_1(\varphi(x)).$$

It is then clear that

$$\operatorname{Lip}(\psi(\cdot, x)) = \lambda' D \quad \forall x \in C_0 \quad \text{and} \quad \operatorname{Lip}(\psi(t, \cdot)) \leq \lambda \quad \forall t \in [0, 1].$$

We now apply the linear interpolation to define two currents,

(148)
$$U := \psi_{\#} ([0,1] \times \partial T) \in \mathbf{I}_{m} (l^{\infty}(Z)) \text{ and } V := \psi_{\#} ([0,1] \times T) \in \mathbf{I}_{m+1} (l^{\infty}(Z)),$$

where the product of currents is defined as in [Wen05] Defn 2.8. By Theorem 2.9 in [Wen05],

(149)
$$\partial ([0,1] \times T) = [1] \times T - [0] \times T - [0,1] \times \partial T.$$

So if we push forward by ψ applying (146), we get

$$\begin{array}{lll} \partial V & = & \psi_{\#}\left([1] \times T\right) - \psi_{\#}\left([0] \times T\right) - \psi_{\#}\left([0,1] \times \partial T\right) \\ & = & \varphi_{1\#}\varphi_{0\#}T - \varphi_{0\#}T - U. \end{array}$$

Since φ_0 is an isometric embedding, we have

(150)
$$d_{\mathcal{F}}\left(\varphi_{\#}T,T\right) \leq d_{F}^{Z}\left(\varphi_{0\#}\varphi_{\#}T,\varphi_{0\#}T\right) \leq \mathbf{M}\left(U\right) + \mathbf{M}\left(V\right).$$

By Proposition 2.10 in [Wen05], we have

(151)
$$\mathbf{M}(U) + \mathbf{M}(V) \leq m\lambda^{m-1}\lambda' D \mathbf{M}(\partial T) + (m+1)\lambda^m\lambda' D \mathbf{M}(T)$$
.

Thus we obtain the lemma.

q.e.d.

5.2. Lipschitz and smooth convergence. Over the years, various notions of smooth convergence and compactness theorems have been proven. We recommend Petersen's textbook [Pet06] for a survey of these various notions of convergence, progressing from $C^{1,\alpha}$ to C^{∞} convergence. All these notions involve maps $f_j: M_j \to M_{\infty}$ and the push forward of the metric tensors g_j from M_j to positive definite tensors $f_{j*}g_j$ on M and then studying the appropriate convergence of these tensors to g.

A weaker notion than these notions is Gromov's Lipschitz convergence introduced in 1979 which does not require one to examine the metric tensors but rather just the distances on the spaces [Gro07, Defn 1.1 and Defn 1.3]. In this section we will briefly review Lipschitz convergence and prove that whenever a sequence of manifolds converges in the Lipschitz sense, then it converges in the intrinsic flat sense [Theorem 5.6]. As a consequence, $C^{1,\alpha}$ convergence and all other smooth forms of convergence are stronger than intrinsic flat convergence as well. That is, any sequence of manifolds converging in the smooth sense to a manifold, converges in the intrinsic flat sense as well.

Definition 5.5 (Gromov). The Lipschitz distance between two metric spaces X, Y, is defined as (152)

$$d_L(X,Y) = \inf\{ |\log \operatorname{dil}(f)| + |\log \operatorname{dil}(f^{-1})| : \text{ bi-Lipschitz } f: X \to Y \}$$

where

(153)
$$\operatorname{dil}(f) = \sup \left\{ \frac{d(f(x), f(y))}{d(x, y)} : x, y \in X \text{ s.t. } x \neq y \right\}.$$

When there is no bi-Lipschitz map from X to Y, one says $d_L(X, Y) = \infty$.

Note that if a sequence of orientable Riemannian manifolds M_j converges in the Lipschitz sense to a metric space M, then M is bi-Lipschitz to an orientable Riemannian manifold. In particular, M is an orientable Lipschitz manifold and by Remarks 2.48 and 2.38, it has a natural structure as an integral current space determined completely by choosing an orientation on the space.

Theorem 5.6. If M_j are orientable Lipschitz manifolds converging in the Lipschitz sense to an oriented Lipschitz manifold M, then after matching orientations of the M_j to the limit manifold, M, the oriented Lipschitz manifolds $[\![M_j]\!]$ converge in the intrinsic flat sense to $[\![M]\!]$.

In fact, whenever M and N are Lipschitz manifolds with matching orientations,

$$d_{\mathcal{F}}(M,N) < k_{\lambda,m} \max\{\operatorname{diam}(M), \operatorname{diam}(N)\} (\operatorname{Vol}(M) + \operatorname{Vol}(\partial M))$$

where $k_{\lambda,m} := \frac{1}{2} (m+1) \lambda^{m-1} (\lambda - 1)$ and where $\lambda = e^{d_L(M,N)}$.

Gromov has proved that Lipschitz convergence implies Gromov-Hausdorff convergence [**Gro07**, Prop 3.7], so that in this setting the Gromov-Hausdorff limits and intrinsic flat limits agree. Gromov's proof applies to any sequence of metric spaces. We cannot extend our theorem to arbitrary integral current spaces because, in general, one cannot

just reverse orientations to match the orientations between a pair of bi-Lipschitz homeomorphic integral current spaces.

Proof. Recall Remarks 2.48 and 2.38, that when $\psi: M^m \to N^m$ is a bi-Lipschitz homeomorphism between connected oriented Lipschitz manifolds, then $\psi_{\#}\llbracket M \rrbracket = \pm \llbracket N \rrbracket$. Once the orientations have been fixed to match, the sign becomes positive.

Lemma 5.4 implies that

(155)
$$d_{\mathcal{F}}(M,N) \leq \frac{1}{2} (m+1) \lambda^{m-1} (\lambda - 1) \max \{ \operatorname{diam}(M), \operatorname{diam}(N) \} (\operatorname{Vol}(M) + \operatorname{Vol}(\partial M))$$

where $\lambda > 1$ is the bi-Lipschitz constant for ψ . Note further that

(156)
$$\log \lambda \le |\log \operatorname{dil}(\psi)| + |\log \operatorname{dil}(\psi^{-1})| \le 2\log \lambda.$$

Taking the infimum of this sum over all ψ and applying (155), we see that

$$d_{\mathcal{F}}(M, N) \leq k_{\lambda,m} \max\{\operatorname{diam}(M), \operatorname{diam}(N)\} (\operatorname{Vol}(M) + \operatorname{Vol}(\partial M))$$

where $\lambda = e^{d_L(M,N)}$.

Now whenever a sequence of Lipschitz manifolds, M_j , converges in the Lipschitz sense to a Lipschitz manifold, M, then

(158)
$$\lambda_j = e^{d_L(M_j, M)} \to 1 \text{ and } \operatorname{diam}(M_j) \to \operatorname{diam}(M).$$

Thus $d_{\mathcal{F}}(M_i, M)$ is less than or equal to

(159)
$$k_{\lambda_j,m} \max \{ \operatorname{diam}(M_j), \operatorname{diam}(M) \} (\operatorname{Vol}(M) + \operatorname{Vol}(\partial M))$$
 which converges to 0 as $j \to \infty$.

Appendix A. Examples by C. Sormani

In this section we present proofs of all the examples referred to throughout the paper. In order to prove our examples converge in the intrinsic flat sense, we need convenient ways to isometrically embed our Riemannian manifolds into a common metric space, Z. In most examples we explicitly construct Z. Two major techniques we develop are the *bridge construction* [Lemma A.2 and Proposition A.3] and the *pipe filling construction* [Remark A.13]. In all examples in this section, the common metric space Z is an integral current space whose tangent spaces are Euclidean almost everywhere so that the weighted volume and mass agree [Lemma 2.34 and Remark 2.33]. We also have multiplicity one (so that the volume and mass agree), enabling us to use volumes to estimate the intrinsic flat distance.

A.1. Isometric embeddings. Recall that a metric space is a geodesic or length space if the metric is determined by taking an infimum over the lengths of all rectifiable curves. In Riemannian manifolds, the lengths of curves are defined by integrating the curve using the metric tensor. Given a connected subset, X, of a metric space, Z, one has the restricted metric, d_Z , on X as well as an induced length metric on X, d_X , which is found by taking the infimum of all lengths of rectifiable curves lying within X where the lengths of the curves are computed locally using d_Z :

(160)
$$L(C) = \sup_{0=t_0 < t_1 < \dots t_k = 1} \sum_{i=1}^k d_Z(c(t_i), c(t_{i-1})).$$

When one uses this induced length metric on X, then X may no longer isometrically embed into Z.

In our first lemma, we describe a process of attaching one geodesic metric space, Y, to another metric space, Z, along a closed subset, $X \subset Z$, to form a metric space, Z', into which Z isometrically embeds. This lemma is one sided, as Y need not isometrically embed into Z' [see Figure 11].

Lemma A.1. Let (Z, d_Z) and (Y, d_Y) be geodesic metric spaces and let $X \subset Z$ be a closed subset. Suppose $\psi : (X, d_X) \to (Y, d_Y)$ is an isometric embedding.

Then we can create a metric space $Z' = Z \sqcup Y/ \sim$ where $z \sim y$ iff $z \in X \subset Z$ and $y = \psi(z)$. We endow Z' with the induced length metric where lengths of curves are measured by d_Z between points in Z and by d_Y between points in Y. The natural map $\varphi_Z : Z \to Z'$ is an isometric embedding.

If we assume further that $Y \setminus \psi(X)$ is locally convex then the natural map $f: Y \to Z'$ is a bijection onto its image which is a local isometry on $Y \setminus \psi(X)$.

We will say that Z' is created by attaching Y to Z along X. Note that $f: Y \to Z'$ need not be an isometry. This can be seen, for example, when Z is the flat Euclidean plane, X is the unit circle in Z, and Y is a hemisphere. See Figure 11.

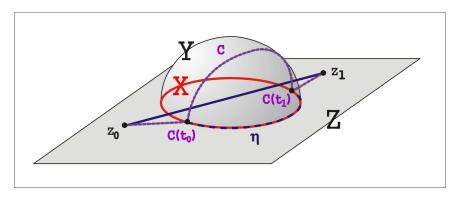


Figure 11. Lemma A.1.

Proof. First we show φ_Z is an isometry. Let $z_0, z_1 \in Z$, so $d_Z(z_0, z_1) = L_Y(\gamma)$ where $\gamma : [0,1] \to Z$, $\gamma(0) = z_0$ and $\gamma(1) = z_1$. Since $\varphi_Z \circ \gamma$ runs from $\varphi_Z(z_0)$ to $\varphi_Z(z_1)$ and has the same length, we know $d_{Z'}(\varphi_Z(z_0), \varphi_Z(z_1)) \leq d_Z(z_0, z_1)$. Now suppose there is a shorter curve $C : [0,1] \to Z'$ running from $\varphi_Z(z_0)$ to $\varphi_Z(z_1)$. If C were the image of a curve in Z under φ_Z , then C would not be shorter than γ , so C passes through $\varphi_Z(X)$ into $f(Y) \subset Z'$.

We claim there is a curve $C':[0,1] \to \varphi_Z(Z)$ running from C(0) to C(1) with $L(C') \le L(C)$, contradicting the fact that γ is the shortest such curve.

Since $Z \setminus X$ is open, $U = Z' \setminus \varphi_Z(Z)$ is open, and $C^{-1}(U)$ is a collection of open intervals in [0,1]. Let t_0,t_1 be any endpoints of a pair of such intervals so that $C:[t_0,t_1]\to f(Y)\subset Z'$ and $C(t_0),C(t_1)\in \varphi_Z(X)\subset Z$. Since X isometrically embeds into Y, the shortest curve η from $C(t_0)$ to $C(t_1)$ lies in $\varphi(X)$. Thus we can replace this segment of C with η without increasing the length. We do this for all segments passing into f(Y) and we have created C', proving our claim. Thus φ_Z is an isometric embedding.

Assuming now that $Y \setminus \psi(X)$ is locally convex, we know that $\forall p \in Y \setminus \psi(X)$ there exists a convex ball $B_p(r_p)$. We claim f is an isometry on $B_p(r_p/2)$. If $y_1, y_2 \in B_p(r_p/2)$, then the shortest curve between them, γ , has $L(\gamma) < r_p$ and lies in $B_p(r_p)$. If there were a shorter curve, C, between $f(y_1)$ and $f(y_2)$ in Z, then it could not be restricted to f(Y), and in particular it would have to be long enough to reach $\partial B_p(r_p)$ and would thus have length $L(C) \geq 2(r_p/2)$, which is a contradiction.

When we wish to isometrically embed two spaces with isometric subdomains into a common space Z', we may attach them using an isometric product as a bridge between them. Recall that the isometric product $Z \times [a, b]$ of a geodesic space, Z, has a metric defined by

(161)
$$d((z_1, s_1), (z_2, s_2)) := \sqrt{(d_Z(z_1, z_2))^2 + (s_1 - s_2)^2},$$

and it is a geodesic metric space with this metric, and a geodesic, γ , projects to a geodesic, $\pi \circ \gamma$, in Z.

Lemma A.2. Suppose there exists an isometry, $\psi: U_1 \subset M_1 \to U_2 \subset M_2$, between smooth connected open domains, U_i , in a pair of geodesic spaces, M_i , each endowed with their own induced length metrics, d_{U_i} . Let

(162)
$$h_{i} = \sqrt{\operatorname{diam}_{U_{i}}(\partial U_{i})\left(2\operatorname{diam}_{U_{i}}(U_{i}) + \operatorname{diam}_{U_{i}}(\partial U_{i})\right)}.$$

Then there exist isometric embeddings φ_i from each M_i into a common complete geodesic metric space,

(163)
$$Z = M_1 \sqcup (U_1 \times [-h_1, h_2]) \sqcup M_2 / \sim,$$

where $z_1 \sim z_2$ if and only if one of the following holds:

(164)
$$z_1 \in U_1 \text{ and } z_2 = (z_1, -h_1) \in U_1 \times [-h_1, h_2]$$

or visa versa or

(165)
$$z_1 \in U_2 \text{ and } z_2 = (\psi(z_1), h_2) \in U_1 \times [-h_1, h_2]$$

or visa versa. The length metric on Z is computed by taking the lengths of segments from each region using d_{M_i} and the product metric on $U_1 \times [-h_1, h_2]$. The isometries φ_i are mapped bijectively onto the copies of M_i lying in Z.

We will say that we have joined M_1 and M_2 with the bridge $U_1 \times [-h_1, h_2]$ and refer to the h_i as the heights of the bridge. See Figure 12.

Proof. Suppose $x, y \in M_1$; then there exists a geodesic γ running from x to y achieving the length between them, and clearly $\varphi_1 \circ \gamma$ has the same length, so $d_{M_1}(x,y) \geq d_Z(\varphi_1(x), \varphi_1(y))$. Suppose on the contrary that φ_1 is not an isometric embedding. So there is a curve

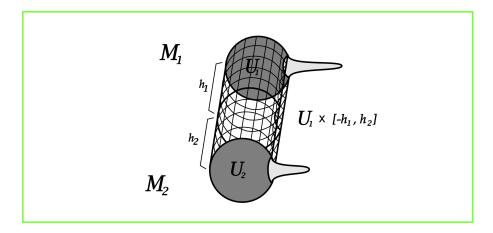


Figure 12. The Bridge Construction [Lemma A.2].

 $c:[0,1]\to Z$ running from $c(0)=\varphi_1(x)$ to $c(1)=\varphi_1(y)$ which is shorter than any curve running from x to y in M_1 .

If the image of c lies in $M_1 \sqcup (U_1 \times [-h_1, h_2]) \subset Z$, then the projection of c to M_1 , $\pi \circ c$ would be shorter than c and lie in M_1 and we would have a contradiction. Thus c must pass into $M_2 \setminus U_2 \subset Z$.

We divide c into parts: c_1 runs from $\varphi_1(x)$ to $x' \in \partial(M_2 \setminus U_2)$, c_3 runs from a point $y' \in \partial(M_2 \setminus U_2)$ to $\varphi(y)$, and c_2 lies between these. Note that the projections $\pi(x') = \varphi_1(x'')$ and $\pi(y') = \varphi_2(y'')$ where $x'', y'' \subset \partial U_1$. Then

(166)

$$L(c) = L(c_1) + L(c_2) + L(c_3)$$

$$(167)$$

$$= \sqrt{L(\pi \circ c_1)^2 + (h_1 + h_2)^2} + L(c_2) + \sqrt{L(\pi \circ c_2)^2 + (h_1 + h_2)^2}$$

$$(168)$$

$$\geq \sqrt{L(\gamma_1)^2 + (h_1)^2} + \sqrt{L(\gamma_2)^2 + (h_1)^2}$$

where γ_1 is the shortest curve from x to x'' and γ_2 is the shortest curve from y to y'' in $U_1 \subset M_1$.

By the definition of h_i we know

$$L(\gamma_i)^2 + h_i^2 = L(\gamma_i)^2 + \operatorname{diam}(\partial U_i) (2 \operatorname{diam}(U_i) + \operatorname{diam}(\partial U_i))$$

$$\geq L(\gamma_i)^2 + \operatorname{diam}(\partial U_i) (2L(\gamma_i) + \operatorname{diam}(\partial U_i))$$

$$= (L(\gamma_i) + \operatorname{diam}(\partial U_i))^2.$$

Thus

(169)
$$L(c) \geq L(\gamma_1) + \operatorname{diam}(\partial U_1) + L(\gamma_2) + \operatorname{diam}(\partial U_1) \\ > L(\gamma_1) + L(\gamma_2) + \operatorname{diam}(\partial(U_i)).$$

Thus c is longer than a curve lying in M_1 which runs from x to y via $x'', y'' \in \partial U_1$. This is a contradiction. We can similarly prove φ_2 is an isometric embedding.

The difficulty with applying Lemma A.2 is that often M_1 and M_2 do not end up close together in the flat norm on Z'. This can occur when $M_i \setminus U_i$ have large volume. In the next proposition we combine this lemma with the prior lemma to create a better Z'.

Proposition A.3. Suppose two oriented Riemannian manifolds with boundary, $M_i^m = (M_i, d_i, T_i)$, have connected open subregions, $U_i \subset M_i$, such that $T_i \sqcup U_i \in \mathbf{I}_m(M_i)$, and there exists an orientation preserving isometry, $\psi: U_1 \to U_2$. Taking $V_i = M_i \setminus U_i$, and geodesic metric spaces X_i such that

$$(170) \psi_i: (V_i, d_{V_i}) \to (X_i, d_{X_i})$$

are isometric embeddings and $X_i \setminus \psi_i(V_i)$ are locally convex, and $B_i \in \mathbf{I}_{m+1}(X_i)$ and $A_i \in \mathbf{I}_m(X_i)$ with set (B_i) , set $(A_i) \subset X_i \setminus \psi_i(V_i)$ satisfying

(171)
$$\psi_{i\#} (T_i \sqcup V_i) = A_i + \partial B_i,$$

then we have

(172)

 $d_{\mathcal{F}}(M_1, M_2) \le \text{Vol}(U_1)(h_1 + h_2) + \mathbf{M}(B_1) + \mathbf{M}(B_2) + \mathbf{M}(A_1) + \mathbf{M}(A_2)$ where h_i is as in (162) and

(173)
$$d_{GH}(M_1, M_2) \le (h_1 + h_2) + \operatorname{diam}(M_1 \setminus U_1) + \operatorname{diam}(M_2 \setminus U_2)$$
.

Note that when $X_i = V_i$, taking $B_i = 0$ and $A_i = T \sqcup V_i$, we have

(174)
$$d_{\mathcal{F}}(M_1, M_2) \leq \text{Vol}(U_1)(h_1 + h_2) + \text{Vol}(V_1) + \text{Vol}(V_2).$$

See Figure 13.

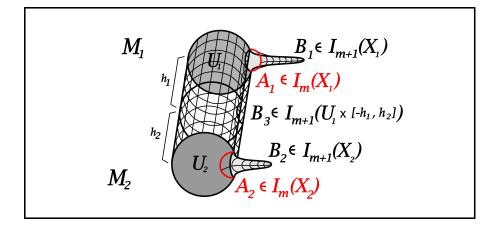


Figure 13. Proposition A.3

Proof. First we construct Z exactly as in Lemma A.2. We obtain the estimate on the Gromov-Hausdorff distance by observing that (175)

$$d_H^Z(\varphi_1(M_1), \varphi_2(M_2)) \le (b_1 + b_2) + \operatorname{diam}(M_1 \setminus U_1) + \operatorname{diam}(M_2 \setminus U_2).$$

To estimate the flat distance, we construct Z' by applying Lemma A.1 to attach both X_i to Z. Note that $f_{i\#}B_i \in \mathbf{I}_{m+1}(Z)$ and $f_{i\#}A_i \in \mathbf{I}_m(Z)$ have the same mass as B_i and A_i respectively because $f_i: X_i - \psi_i(V_i)$ are locally isometries on set (B_i) and set (A_i) . Since Z isometrically embeds in Z', the manifolds M_i are isometrically embedded and we will call the embeddings φ'_i . Furthermore,

$$\varphi'_{1\#}T_{1} - \varphi'_{2\#}T_{2} = \varphi'_{i\#}(T_{1} \sqcup V_{1}) - \varphi'_{2\#}(T_{2} \sqcup V_{2})$$

$$+ \varphi'_{i\#}(T_{1} \sqcup U_{1}) - \varphi'_{2\#}(T_{2} \sqcup U_{2})$$

$$= f_{1\#}A_{1} - f_{2\#}A_{2} + f_{1\#}\partial B_{1} - f_{2\#}\partial B_{2} + \partial B_{3}$$

where $B_3 \in \mathbf{I}_{m+1}(Z)$ is defined as integration over $U_1 \times [-h_1, h_2]$ with the correct orientation. Thus (176)

$$d_F^Z(\varphi_{1\#}T_1, \varphi_{2\#}(T_2)) \leq \mathbf{M}(B_3) + \mathbf{M}(B_1) + \mathbf{M}(B_2) + \mathbf{M}(A_1) + \mathbf{M}(A_2)$$
and we obtain the required estimate.
q.e.d.

A.2. Disappearing tips and Ilmanen's example. In this subsection we apply the bridge and filling techniques from the last subsection to prove a few key examples. We remark upon Gromov's square convergence [Figure 14, Remark A.5]. We close with a proof that Ilmanen's Example, depicted in Figure 1, does in fact converge in the intrinsic flat sense [Example A.7]. Each example is written as a statement followed by a proof.

Example A.4. Let M_j^m be spheres which have one increasingly thin tip as in Figure 2. In each M_j there is a subdomain, U_j , which is isometric to $U'_j = M_0 \setminus B_p(r_j)$ where M_0 is the round sphere. We further assume that $V_j = M_j \setminus U_j$ have $\operatorname{Vol}(V_j) \to 0$. We claim M_j converges to M_0 in the intrinsic flat sense.

We prove this example converges with an explicit construction:

Proof. Since there is an isometry $\psi: U_j \to U'_j$ we join M_j to the sphere M_0 with a bridge $U_j \times [-h_j, h'_j]$, creating a metric space Z as in Lemma A.2, where $h_j, h'_j \to 0$ as $j \to \infty$. Furthermore, the isometric embeddings $\varphi_j: M_j \to Z$ and $\varphi'_j: M_0 \to Z$ push forward the current structures T_j on M_j and T_0 on M_0 so that

(177)
$$\varphi_{j\#}T_{j} - \varphi_{j}'T_{0} = \varphi_{j\#} \left(T_{j} \sqcup U_{j}\right) - \varphi_{j}' \left(T_{0} \sqcup U_{j}'\right) + \varphi_{j\#} \left(T_{j} \sqcup V_{j}\right) - \varphi_{j}' \left(T_{0} \sqcup V_{j}'\right)$$

where $V_j = M_j \setminus U_j$ and $V'_j = M_0 \setminus U'_j$. We define $B_j \in \mathbf{I}_3(Z)$ by integration over the bridge $U_j \times [-h_j, h'_j]$ so that we have

$$(178) \varphi_{j\#}T_j - \varphi_j'T_0 = \varphi_{j\#}\left(T_j \sqcup U_j\right) - \varphi_j'\left(T_0 \sqcup U_j'\right) + \partial B_j.$$

Note that $\mathbf{M}(T_j \sqcup V_j) = \operatorname{Vol}(V_j) \leq 2/j^2$ and $\mathbf{M}(T_0 \sqcup V_j')$ both converge to 0 as $j \to \infty$, and $\mathbf{M}(B_j) \leq \operatorname{Vol}(U_j)(h_j + h_j')$ does as well, because diam $(\partial U_j) \to 0$ while diam $(M_j) \leq 4\pi$. Thus M_j converge to the sphere M_0 in the intrinsic flat sense. q.e.d.

Remark A.5. The above example is similar to Gromov's Example on page 118 in [Gro07]. The \square_{λ} limit agrees with the flat limit for $\lambda > 0$. The Gromov-Hausdorff limit of this sequence is the sphere with a unit length segment attached. Gromov points out that if $M_j \xrightarrow{\text{GH}} M_{\infty}$ and $p_j \in M_j \to p_{\infty} \in M_{\infty}$ have a uniform positive lower bound on the measure of B_{p_j} (1), the \square_1 limit of the M_j which is a subset of M_{∞} includes p_{∞} . This is not true for the intrinsic flat limit, as can be seen in the following example.

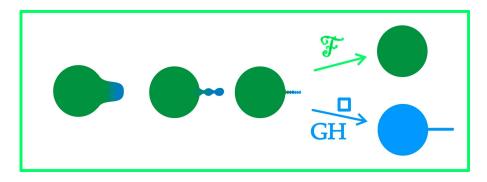


Figure 14. Contrasting with Gromov's square limit.

Example A.6. Let M_j^m be spheres which have one increasingly thin tip with uniformly bounded volume as in Figure 14. In each M_j there is a subdomain U_j which is isometric to $U'_j = M_0 \setminus B_p(r_j)$ where M_0 is the round sphere. We further assume that $V_j = M_j \setminus U_j$ have $\operatorname{Vol}(V_j)$ decreasing but $\geq V_0 > 0$ while V_j converge in the Gromov-Hausdorff sense to a line segment. Then M_j converges to M_0 in the intrinsic flat sense.

Proof. Since there is an isometry ψ from U_j to U'_j , we join M_j to the sphere M_0 with a bridge $U_j \times [-h_j, h'_j]$, creating a metric space Z as in Lemma A.2 where $h_j, h'_j \to 0$ as $j \to \infty$. Furthermore, the isometric embeddings $\varphi_j : M_j \to Z$ and $\varphi'_j : M_0 \to Z$ push forward the current structures T_j on M_j and T_0 on M_0 .

By Corollary 3.21 and $V_j \xrightarrow{\text{GH}} [0,1]$, we know $(V_j, d_j, T_j \, \sqcup \, V_j)$ converges to 0 as an integral current space. By Theorem 3.23, there is a metric space X_j with an isometry $\phi_j : V_j \to X_j$ and integral currents A_j, B_j such that $\phi_{j\#}(T \, \sqcup \, V_j) = A_j + \partial B_j$ with $\mathbf{M}(A_j) + \mathbf{M}(B_j) \to 0$. We now apply Proposition A.3, attaching X_j to Z to create Z', and we have

(179)

$$d_{\mathcal{F}}\left(M_{j}, M_{0}\right) \leq \operatorname{Vol}\left(U_{j}\right)\left(h_{j} + h_{j}'\right) + \mathbf{M}\left(B_{j}\right) + \mathbf{M}\left(A_{j}\right) + \operatorname{Vol}\left(M_{0} \setminus U_{j}'\right) \to 0.$$

Note that here we did not bother with two fillings as in the proposition.
q.e.d.

We now prove Ilmanen's Example in Figure 1 converges to a standard sphere in the intrinsic flat sense. Although Ilmanen's sequence of examples have positive scalar curvature and are three dimensional, here we show convergence in any dimension including two.

Example A.7. We assume M_j are diffeomorphic to spheres with a uniform upper bound on volume and that each M_j contains a connected open domain U_j which is isometric to a domain $U'_j = M_0 \setminus \bigcup_{i=1}^{N_j} B_{p_{j,i}}(R_j)$ where M_0 is the round sphere and $B_{p_{j,i}}(R_j)$ are pairwise disjoint. We assume that each connected component $U_{j,i}$ of $V_j = M_j \setminus U_j$ and each ball $B_{p_{j,i}}(R_j)$ has volume $\leq v_j/N_j$ where $v_j \to 0$. Then M_j converges to a round sphere in the intrinsic flat sense as long as $N_j \sqrt{R_j} \to 0$.

Proof. We cannot directly apply Proposition A.3 in this setting because diam (∂U_j) are not converging to 0. So instead of building a bridge Z directly from M_j to M_0 , we build bridges from $M_0 = M_{j,0}$ to $M_{j,1}$ to $M_{j,2}$ and up to $M_{j,N_j} = M_j$ by adding one bump at a time. Each pair has only one new bump and so we can show

(180)
$$d_{\mathcal{F}}(M_{j,i}, M_{j,i+1}) \le \operatorname{Vol}(U_{j,i}) \left(h_{j,i} + h'_{j,i} \right) + 2v_j / N_j$$

where

$$h_{i,j}, h'_{i,j} \le \sqrt{\operatorname{diam}(\partial U_{j,i+1})(\operatorname{diam}(M_{j,i}) + \operatorname{diam}(\partial U_{j,I+1}))}$$

 $\le \sqrt{\pi R_j(\operatorname{diam}(M_j) + \pi R_j)}.$

Summing from i = 1 to N_j we see that

(181)
$$d_{\mathcal{F}}(M_0, M_j) \leq \text{Vol}(U_j) 2\sqrt{\pi R_j (\text{diam}(M_j) + \pi R_j)} + 2v_j \to 0.$$

q.e.d.

A.3. Limits with point singularities. Recall that when defining an integral current space, (X, d, T), we required that set(T) = X so that all points in the space have positive density [Defn 2.24, Defn 2.35]. In this subsection, we present two related examples.

Example A.8. In Figure 15 we have a sequence of Riemannian surfaces, M_j , diffeomorphic to the sphere converging in the intrinsic flat sense to a Lipschitz manifold, M_0 , with a conical singularity. Since this sequence clearly converges in the Lipschitz sense to M_0 , this is proven by applying Theorem 5.6.

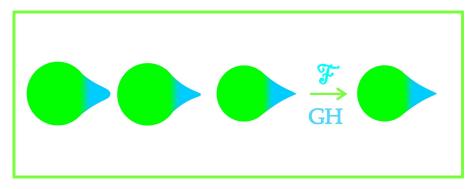


Figure 15. The intrinsic flat limit does include the tip of the cone.

Example A.9. In Figure 8 we see a sequence of Riemannian surfaces, M_j , diffeomorphic to the sphere converging in the intrinsic flat sense to a Riemannian manifold, M_{∞} , with a cusp singularity. The cusp singularity is not included in the limit current space because we only include points of positive lower density.

There is no Lipschitz convergence here even if we were to include the cusp point, so we prove this example:

Proof. Note that M_{∞} is a geodesic space because no minimizing curves pass over a cusp point. So we apply Lemma A.2 to build a bridge Z between M_j and M_{∞} , removing small balls V_j near their tips so that $U_j = M_j \setminus V_j$ are locally isometric. Now we apply Proposition A.3 with $X_i = V_i$, which works even though M_{∞} has a point singularity because $\mathbf{M}(V_{\infty}) = \mathrm{Vol}(V_{\infty})$. So we have:

(182)
$$d_{\mathcal{F}}(M_j, M_{\infty}) \leq \operatorname{Vol}(U_j) h_j + \operatorname{Vol}(V_j) + \operatorname{Vol}(V_{\infty})$$
where $h_j = \sqrt{\operatorname{diam}(\partial U_j) (\operatorname{diam}(M_j) + \operatorname{diam}(\partial U_j))}$. q.e.d.

A.4. Limits need not be precompact. In this subsection, we present a pair of integral current spaces which are not precompact and yet are the limits of a sequence of Riemannian surfaces diffeomorphic to the sphere with a uniform upper bound on volume. Example A.10 is not bounded and is a classic surface of revolution of finite area. Example A.11, depicted in Figure 7, is the limit of a sequence with a uniform upper bound on diameter and is bounded but has infinitely many tips.

Example A.10. Let M_0 be the surface of revolution in Euclidean space defined by

(183)
$$M_0 = \{(x, y, z) : x^2 + y^2 = 1/(1-z)^4, z \ge 0\} \subset E^3$$

with the outward orientation and the induced Riemannian length metric. Since M_0 has finite area and its boundary has finite length, it is an integral current space.

Let

(184)
$$M_j = \{(x, y, z) : x^2 + y^2 = f_j(z)/(1-z)^4, z \ge 0\} \subset E^3$$

where $f_j(z) = 1$ for $z \leq j$ and such that $f_j(z) = 0$ for $z \geq j + 1/j$ and smoothly decreasing between these values so that M_j is smooth at z = j + 1/j. We also orient M_j outward and give it the induced Riemannian length metric. Note that $\operatorname{diam}(M_j) \to \infty$ so M_j is not Cauchy in the Gromov-Hausdorff sense. However, M_j converges to M_0 in the intrinsic flat sense.

Proof. Note that $U_j \in M_j$ defined as $M_j \cap \{z \in [0, j]\}$ is locally isometric to $U'_j \in M_0$ defined by $M_0 \cap \{z \in [0, j]\}$. We join M_j to the sphere M_0 with a bridge $U_j \times [-h_j, h'_j]$, creating a metric space Z where h_j, h'_j are bounded by

(185)
$$\sqrt{\frac{\pi}{(1-j)^4} \left(2(2j) + \frac{\pi}{(1-j)^4} \right)} \to 0 \text{ as } j \to \infty.$$

From here onward we may apply Proposition A.3 using the fact that $V_j = M_j \setminus U_j$ and $V'_i = M_0 \setminus U'_i$ both have area converging to 0. q.e.d.

Example A.11. The sequence of Riemannian manifolds M_j in Figure 7 is defined by taking a sequence of p_j lying on a geodesic in the sphere M_0 converging to a point p_{∞} and choosing balls $B_{p_j}(r_j)$ that are disjoint. The tips are Riemannian manifolds N_j , with boundary such that ∂N_j is isometric to $\partial B_{p_j}(r_j)$ and N_j can be glued smoothly to $M_0 \setminus B_{p_j}(r_j)$. We further require that diam $(N_j) \leq 2$ and $\operatorname{Vol}(N_j) \leq (1/2)^j$. Then M_j is formed by removing the first j balls from M_0 and

gluing in the first j tips, N_1, N_2, \ldots, N_j , with the usual induced Riemannian length metric:

$$(186) M_j := \left(M_0 \setminus \bigcup_{i=1}^j B_{p_i}(r_i) \right) \sqcup N_1 \sqcup N_2 \sqcup \cdots \sqcup N_j.$$

So the diameter and volume of M_i are uniformly bounded above.

The intrinsic flat limit M_{∞} is defined by removing all the balls and gluing in all the tips:

(187)
$$M_{\infty} := \left(M_0 \setminus \bigcup_{i=1}^{j} B_{p_i}(r_i) \right) \sqcup N_1 \sqcup N_2 \sqcup \cdots$$

so that M_{∞} is not smooth at p_{∞} but it is a countably \mathcal{H}^m rectifiable space. There are natural current structures T_j and T_{∞} on these spaces with weight 1 and orientation defined by the orientation on M_0 . Note that M_{∞} has finite volume and diameter but is not precompact because it contains infinitely many disjoint balls of radius 1.

Proof. Let $\epsilon_j = d_{M_0} \, (p_j, p_\infty)$. Then there is an isometry $\psi : U_j \to U_j'$ where $U_j = M_j \setminus B_{p_\infty} \, (\epsilon_j - r_j)$ and $U_j' \subset M_\infty$. So we join M_j to M_∞ with a bridge $U_j \times [-h_j, h_j']$ creating a metric space Z as in Lemma A.2 where $h_j, h_j' \to 0$ as $j \to \infty$. Furthermore, the isometric embeddings $\varphi_j : M_j \to Z$ and $\varphi_j' : M_\infty \to Z$ push forward the current structures T_j on M_j and T_∞ on M_∞ so that

(188)
$$\varphi_{j\#}T_{j} - \varphi'_{j}T_{\infty} = \varphi_{j\#}\left(T_{j} \sqcup U_{j}\right) - \varphi'_{j}\left(T_{\infty} \sqcup U'_{j}\right) + \varphi_{j\#}\left(T_{j} \sqcup V_{j}\right) - \varphi'_{j}\left(T_{\infty} \sqcup V'_{j}\right)$$

where $V_j = M_j \setminus U_j$ and $V'_j = M_\infty \setminus U'_j$. Letting $B \in \mathbf{I}_{m+1}(Z)$ be defined by integration over the bridge $U_j \times [-h_j, h'_j]$, we have

(189)
$$\varphi_{j\#}T_j - \varphi_j'T_0 = \partial B_j + \varphi_{j\#} \left(T_j \sqcup V_j \right) - \varphi_j' \left(T_\infty \sqcup V_j' \right).$$

However,

$$\mathbf{M}(T_j \mathbf{L} V_j) = \text{Vol}(V_j) \le \omega_m (\epsilon_j - r_j)^m \to 0 \text{ and }$$

(190)
$$\mathbf{M}\left(T_{\infty} \, \sqcup V_j'\right) \leq \sum_{i=j+1}^{\infty} \frac{1}{2^j} \to 0 \text{ and}$$

$$\mathbf{M}\left(B_{j}\right) \leq \operatorname{Vol}\left(U_{j}\right)\left(h_{j}+h_{j}'\right) \to 0$$

because diam $(\partial U_j) \to 0$ while diam $(M_j) \le \pi + 2$. Thus M_j converge to the sphere M_{∞} in the intrinsic flat sense. q.e.d.

A.5. Pipe filling and disconnected limits. In this subsection we study sequences of Riemannian manifolds which converge to spaces which are not geodesic spaces. Our examples consist of spheres joined by cylinders where the cylinders disappear in the intrinsic flat limit. For these examples we cannot just apply Lemma A.2 because we do not have connected isometric domains.

We develop a new concept called "pipe filling" [see Remark A.13]. Note that a cylinder, $S^{m-1} \times [0,1]$, does not isometrically embed into a solid Euclidean cylinder, $D^m \times [0,1]$, but that it does isometrically embed into a cylinder of higher dimension $S^m \times [0,1]$. We prove Example A.12, depicted in Figure 3, and Example A.14, depicted in Figure A.14.

Example A.12. The sequence of manifolds in Figure 3 are smooth manifolds, M'_i , which are bi-Lipschitz close to Lipschitz manifolds,

(191)
$$M_j = \{(x, y, z) : x^2 + z^2 = f_j^2(y), y \in [-3, 3]\},\$$

where $f_{i}\left(y\right)$ is a smooth function such that

(192)
$$f_j(y) := \sqrt{1 - (y+2)^2} \text{ for } y \in [-3, -2 + \sqrt{1 - (1/j)^2}],$$

(193)
$$f_j(y) := \sqrt{1 - (y - 2)^2} \text{ for } y \in [2 - \sqrt{1 - (1/j)^2}, 3]$$

and $f_j(y) = 1/j$ between these two intervals. For $j = \infty$ we let $f_{\infty}(y)$ satisfy (192) and (193) and $f_{\infty}(y) := 0$ between the two intervals so that M_{∞} is two spheres joined by a line segment.

All M_j for $j=1,2,3\ldots$ are endowed with geodesic metrics and outward orientations. Then M_j Gromov-Hausdorff converges to the connected geodesic space M_∞ but converges in the intrinsic flat sense to two disjoint spheres, $N_\infty = (\operatorname{set}(T_\infty), \operatorname{d}_{M_\infty}, T_\infty)$ where $T_\infty \in \mathbf{I}_2(M_\infty)$ is integration over the spheres. Since $d_{lip}\left(M_j, M_j'\right) \to 0$ we also have a sequence of Riemannian manifolds converging to this disconnected limit space.

Proof. We construct a common metric space Z_j as in Figure 16. More precisely,

(194)

$$Z_{j} = \{(x, y, z, w): x^{2} + z^{2} = \overline{f}_{j}^{2}(y, w), y \in [-3, 3], w \in [0, 1/j]\}$$

where

(195)
$$\bar{f}_{j}\left(y,w\right) = \max\left\{f_{j}\left(y\right)\sqrt{1 - j^{2}w^{2}}, f_{\infty}\left(y\right)\right\}$$

with the induced length metric from four dimensional Euclidean space. Z_j is roughly two spheres of radius 1 crossed with intervals, $S^2 \times [0, 1/j]$, with a thin half cylinder, $S^2_{+,1/j} \times [-1,1]$, between them. This half

cylinder is filling in the thin cylinder in M_j and is the key step in the pipe filling construction.

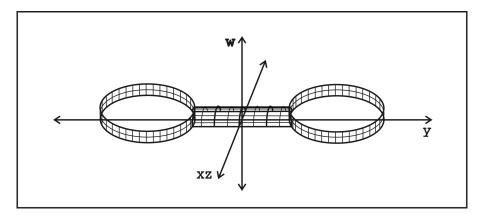


Figure 16. Here the cylinder in the xzy plane is filled in by a half cylinder.

It is easy to see that $\varphi_{\infty}: M_{\infty} \to Z_j$ such that $\varphi_{\infty}(p) = (p, 1/j)$ is an isometric embedding because there is a distance nonincreasing retraction from Z_j to the level set w = 1/j. It is also an isometric embedding when restricted to N_{∞} .

Regrettably, $\varphi_j: M_j \to Z_j$ with $\varphi_j(p) = (p,0)$ is not isometric embedding. It preserves distances between points which both lie in one of the balls or which both lie in the thin cylinder, but not necessarily between points in different regions. Let

(196)
$$h_j = \sqrt{\pi/j + (\pi/(2j))^2}$$

and glue $M_j \times [-h_j, 0]$ to Z_j to create Z_j' which can be viewed as a metric space lying in four dimensional Euclidean space with the induced intrinsic length metric. Then $\varphi_j': M_j \to Z_j'$ where $\varphi_j'(p) = (p, -h_j)$ is an isometry. Any minimizing curve in Z_j' between points $(p, -h_j)$ and $(q, -h_j)$ can either be retracted down to the $w = -h_j$ level, or it must travel up at least to the w = 0 level. So the curve has length $\sqrt{l_1^2 + h_j^2}$ before reaching w = 0 and then travels some distance, l_2 , within the half thin cylinder and then comes back down with length $\sqrt{l_3^2 + h_j^2}$. However, a curve lying in the $w = -h_j$ level set would travel only l_1 then l_2 in the thin cylinder, then πr around the thin cylinder, and then l_3 to its endpoint. However,

(197)
$$\sqrt{l_1^2 + h_j^2} + l_2 + \sqrt{l_3^2 + h_j^2} \ge l_1 + l_2 + l_3 + \pi r$$

by our choice of h_j . Thus φ'_j is an isometric embedding.

Now Z'_j has a naturally defined current structure B_j such that $\mathbf{M}(B_j) = \operatorname{Vol}(Z'_j)$ and such that $\partial B_j = \varphi_{j\#}T_j - \varphi_{\infty\#}T_{\infty}$. So we have $M(B_j)$ equal to

(198)

$$2 \text{ Vol } (S^2 \times [-h_j, 1/j]) + \frac{1}{2} \text{ Vol } ([-1, 1] \times S^2_{1/j}) + \text{Vol } ([-1, 1] \times S^1_{1/j}) h_j$$
 and thus

(199)
$$d_F^{Z_j}\left(\varphi_{j\#}T_j, \varphi_{\infty\#}T_{\infty}\right) \le \mathbf{M}\left(B_j\right) = \operatorname{Vol}\left(Z_j\right) \to 0.$$

Furthermore, it is easy to see that

$$(200) d_{GH}\left(M_{j}, M_{\infty}\right) \leq d_{H}^{Z_{j}}\left(\varphi_{j}\left(M_{j}\right), \varphi_{0}\left(M_{\infty}\right)\right) \leq \frac{\pi}{2j}. + h_{j} \to 0.$$

So M_j converge in the intrinsic flat sense to N_{∞} but in the Gromov-Hausdorff sense to M_{∞} . q.e.d.

Remark A.13. The process used in Example A.12 can be used more generally to show that an integral current space M which is a collection of k disjoint spheres, $S_{R_j}^m$, of radius $R_j \leq R$ for $j = 1 \dots k$ connected by n cylinders $S_{r_i}^{m-1} \times [0, L_i]$ of length $L_i \leq L$ and radius r for $i = 1 \dots n$ between them is close to an integral current space N which is defined by integration over the same collection of spheres with the metric restricted from the metric space X, which is the same collection of spheres joined by line segments of length L_i rather than cylinders.

More precisely, one can construct a Z by gluing together the collection of $S_{R_j}^m \times [0, \pi r/2]$ together with thin half cylinders of radius r and length L_i , and then take $h = \sqrt{\pi r R + (\pi r/2)^2}$, and define Z' by attaching $M \times [-h, 0]$ to Z. Thus the Gromov-Hausdorff distance

$$(201) d_{GH}(M,X) \le \pi r + h$$

and the intrinsic flat distance can be estimated using the volume of Z'. In particular,

(202)
$$d_{\mathcal{F}}(M, N) \leq V(r+h) + \operatorname{Vol}_{m-1}(S_r^m) L/2 + \operatorname{Vol}_m(S_r^{m-1}) Lh,$$

where $L = \sum_{i=1}^{k} L_i$ and $V = \sum_{j=1}^{n} \operatorname{Vol}_m(S_R^m)$. Note that if one has $r \to 0$, the product $r^{m-1/2}L \to 0$ and R and V are uniformly bounded above, then the right hand side of (202) goes to 0. We will call this *pipe filling*.

Example A.14. In Figure 4 we have an example of a sequence of Riemannian manifolds, M'_j , which are collections of spheres of various sizes joined by cylinders, which converge in the intrinsic flat sense to a compact integral current space N_{∞} consisting of countably many spheres oriented outward whose metric is restricted from the Gromov Hausdorff limit, X_{∞} , formed by joining the spheres in N_{∞} with line segments. The explicit inductive construction is given in the proof.

Proof. We begin the inductive construction of the collection of spheres N_j used to build the Riemannian manifolds, M'_j . Let N_0 be four disjoint spheres of radius R_0 lying in Euclidean space whose centers form a square of side length $L_0 + 2R_0$.

To build N_j , we first rescale N_{j-1} by a factor of 3 and make 5 copies, then place them symmetrically around N_0 , thus creating N_j where $R_j = R_0/3^j$ is the radius of the smallest sphere and (203)

$$Vol(N_j) = \frac{5}{3^2} Vol(N_{j-1}) + Vol(N_0) = \sum_{i=0}^{j} \left(\frac{5}{9}\right)^j Vol(N_0) \le \frac{9}{4} Vol(N_0).$$

Now M_j is built by joining the spheres in N_j with cylinders of radius $\epsilon_j << R_j$ chosen so that the total length L_j of all the cylinders satisfies $\epsilon_j L_j < 1/j$ and $\lim_{j\to\infty} \operatorname{Vol}(M_j) = 9\operatorname{Vol}(N_0)/4$. We give M_j the outward orientation and note that there are Riemannian manifolds M'_j arbitrarily close to M_j in the Lipschitz sense which will have the same intrinsic flat and Gromov-Hausdorff limits as M_j by Theorem 5.6.

Let X_j be created by joining the N_j with line segments and give X_j the induced length metric so that it is a geodesic metric space. Let X_{∞} be the union of all these metric spaces, which is also a compact geodesic metric space with the induced length metric. The integral current space N_{∞} is defined as the union of all the N_j with the metric d_{∞} restricted from the length metric on X_{∞} .

Note that for any $\varepsilon > 0$, we can find j sufficiently large that $d_{GH}(M_j, X_j) < \epsilon$ and $d_{\mathcal{F}}(M_j, N_j) < \epsilon$. This can be seen by creating a pipe filling from M_j to X_j as in Remark A.13 with $r = \epsilon_j L = L_j$, R = 1 and $V = \frac{9}{4} \operatorname{Vol}(N_0)$.

Next we observe that the maps $\psi_j: X_j \to X_\infty$ are isometric embeddings because paths between points in $\psi_j(X_j)$ are shorter if they stay in $\psi_j(X_j)$. Thus

$$d_{\mathcal{F}}(N_{j}, N_{\infty}) \leq d_{F}^{X_{\infty}}(\psi_{j\#}[N_{j}], N_{\infty})$$

$$\leq \mathbf{M}(\psi_{j\#}[N_{j}] - N_{\infty})$$

$$\leq \sum_{i=j+1}^{\infty} \left(\frac{5}{9}\right)^{j} \operatorname{Vol}(N_{0}) \rightarrow 0.$$

Since $X_{\infty} \subset T_{R_j}(\psi_j(X_j))$ where $R_j \to 0$ we see that $d_H(\psi_j(X_j), X_{\infty}) \to 0$. Combining this with our pipe filling estimates above, we see that the integral current spaces M_j converge to N_{∞} in the intrinsic flat sense and to X_{∞} in the Gromov-Hausdorff sense. q.e.d.

Remark A.15. Note that in the pipe filling construction described in Remark A.13, one might have a single sphere with many thin cylinders looping around and back to it. One does not need to view the space as a subset of Euclidean space.

One can apply the pipe filling approach to any collection of Riemannian manifolds joined by collections of thin cylinders. A very small sphere in a Riemannian manifold is arbitrarily close to a small Euclidean sphere. As long as the cylinders are standard isometric products of spheres with line segments, this technique works. The metric space Z can be created with thin half cylinders between products of the manifolds with small intervals, and Z' can be built using the diameter of the manifolds in the place of πR when defining h.

A.6. Collapse in the limit. A sequence of Riemannian manifolds, M_j , is said to collapse if $Vol(M_j) \to 0$. Such sequences do not converge in the Lipschitz or smooth sense because the limit spaces have the same dimension and volume converges in that setting. They have been studied using Gromov-Hausdorff and metric measure convergence. As mentioned in Remark 3.22, collapsing sequences of Riemannian manifolds converge in the intrinsic flat sense to the **0** current space. In fact, if M_j converges in the Gromov-Hausdorff sense to a lower dimensional limit space, then they converge in the intrinsic flat sense to **0** as well [Corollary 3.21].

Example A.16. The sequence of tori, $M_j = S_{\pi/j}^1 \times S_{\pi}^1$, depicted in Figure 5 has volume $\operatorname{Vol}(M_j) = \pi/j \to 0$, so M_j converges in the intrinsic flat sense to **0**. Note that M_j converges in the Gromov-Hausdorff sense to S^1 because

(204)
$$d_{GH}(S^1, M_j) \le d_H(\{p\} \times S_{\pi}^1, S_{\pi/j}^1 \times S_1^1) = \pi/(2j) \to 0.$$

In the next example is the well known "jungle-gym" example where the Gromov-Hausdorff limit is higher dimensional than the sequence. Here we see that the intrinsic flat limit is **0**:

Example A.17. The Riemannian surface, M_j , is defined as a submanifold of Euclidean space by attaching adjacent disjoint spheres of radius R_j centered on lattice points of the form $(\frac{n_1}{2^j}, \frac{n_2}{2^j}, \frac{n_3}{2^j})$ where $n_i \in \mathbb{N}$ with cylinders of radius $r_j << R_j$ with

(205)
$$\sum_{i=1}^{2^{3j}} \frac{4}{3} \pi R_j^2 \le A_0,$$

and total area of the cylinders approaches 0.

As $j \to \infty$ this sequence converges to the cube $[0,1]^3$ with the taxical norm:

(206)
$$d_{taxi}((x_1, x_2, x_3), (y_1, y_2, y_3)) = \sum_{i=1}^{3} |x_i - y_i|$$

and in the intrinsic flat sense to 0.

We skip the proof of the Gromov-Hausdorff convergence since this is best done using Gromov's ϵ nets [Gro07].

Proof. By Theorem 3.20, a subsequence of M_j converges in the intrinsic flat sense to some integral current space $M_0 \subset [0,1]^3$ since $\operatorname{area}(M_j)$ is uniformly bounded by (205) and the diminishing areas of the cylinders. By the pipe filling technique [Remark A.13], we know the collections of spheres, N_j , converge in the intrinsic flat sense to M_0 as well. However, each sphere isometrically embeds into a hemisphere of higher dimension, so we can embed N_j into a collection of hemispheres and see that

(207)
$$d_{\mathcal{F}}(M_j, \mathbf{0}) \leq \sum_{j=1}^{2^{3j}} \frac{5}{8} \pi R_j^3 \leq A_0 R_j \to 0,$$

so M_0 is the zero space.

q.e.d.

A.7. Cancellation in the limit. Sometimes sequences of integral current spaces converge to the 0 current space even when their total mass is uniformly bounded below. We begin with a classical example of integral currents in Euclidean space and then give a sequence of Riemannian manifolds which cancel in the limit [Example A.19].

Example A.18. Let $T_j \in \mathbf{I}_2(\mathbb{R}^3)$ be defined as integration over $\{(x,y,1/j): x^2 + y^2 \leq 1\}$ oriented upward plus integration over $\{(x,y,-1/j): x^2 + y^2 \leq 1\}$ oriented downward. As $j \to \infty$, T_j converges in the flat sense to the $\mathbf{0}$ current. Thus the integral current spaces, $(\operatorname{set}(T_j), d_{\mathbb{R}^3}, T_j)$, converge to the 0 current space.

Proof. This example is easily proven taking B_j equal to integration over the solid cylinder between the disks in T_j , and A_j equal to integration over the cylinder. q.e.d.

To create a sequence of Riemannian manifolds which cancel in the limit like this is more tricky. If one tries to fold a surface onto itself so that it is close enough to cancel, it is not isometrically embedded into the space. To create an isometric embedding in a folded position we need to provide shortcuts between the two sheets. See Figure 6.

Example A.19. Given any compact oriented Riemannian manifold, M_0^m , one can find a sequence of oriented Riemannian manifolds, M_j^m , which converge in the Gromov-Hausdorff sense to M_0^m and yet in the intrinsic flat sense to $\mathbf{0}$. The sequence, M_j^m , have volumes converging to twice the volume of M_0^m .

This example is also described in [SW10] but the proof there is not constructive.

Proof. First, let M_0 be an arbitrary closed oriented Riemannian manifold and fix $j \in \mathbb{N}$ before defining M_j . Choose a collection of points

$$(208) \{p_1, p_2, \dots p_{N_j}\} \subset M_0$$

such that $d(p_i, p_k) > 3/j$ and $M_0 \subset \bigcup_i B(p_i, 10/j)$. We choose any r_n such that $r_n \leq \min\{1/j, \operatorname{injrad}(M_0)/2\}$, where $\operatorname{injrad}(M_0)$ denotes the injectivity radius of M_0 .

Define an integral current space W_j as a Riemannian manifold with corners via the isometric product

(209)
$$W_j = (M_0 \setminus U_j) \times [0, \delta_j]$$

where

(210)
$$U_j = \bigcup_{i=1}^{N_n} B(p_i, r_n)$$
 and $\delta_j < \min \{ (\operatorname{Vol}_{m-1}(\partial U_j))^{-1}, 1/j \}$.

Let $M_j = \partial W_j$ so that M_j is two copies of $M_0 \setminus U_j$ with opposite orientations glued together by cylinders of the form $\partial B(p_i, r_n) \times [0, \delta_j]$ as in Figure 6. There are smooth Riemannian manifolds arbitrarily close to the M_j in the Lipschitz sense.

Note that $d_W((x, \delta_j), (x, 0)) = \delta_j$ while $d_{M_j}((x, \delta_j), (x, 0))$ is achieved by a curve traveling to a cylinder, then a distance δ_j and back again, so M_j does not isometrically embed into W_j . One might try constructing a bridge Z_j from M_j to W_j using Lemma A.2 but since diam (∂M_j) does not converge to 0, we cannot apply this lemma directly. Instead, we will use a similar technique, taking advantage of the increasing density of ∂M_j .

First we set $\bar{\epsilon}_i = 10/j + \delta_i + 10/j$; then, by the density of the balls,

(211)
$$d_{M_j}\left(\left(x,0\right),\left(x,s\right)\right) \leq \bar{\epsilon}_j,$$

for all choices of $(x, s) \in M_j = \partial W_j$.

We now construct another Lipschitz manifold Z_j into which M_j does isometrically embed and such that $M_j = \partial Z_j$ where $\mathbf{M}(Z_j) = \operatorname{Vol}(Z_j) \to 0$, proving that M_j flat converges to 0. Taking

(212)
$$\epsilon_j := 2\sqrt{\bar{\epsilon}_j^2 + \bar{\epsilon}_j \operatorname{diam}(M_j)},$$

we define our metric space:

(213)
$$Z_{i} = \partial W_{i} \times [0, \epsilon_{i}] \cup W_{i} \times \{\epsilon_{i}\} \subset W_{i} \times [0, \epsilon_{i}],$$

where the product is an isometric product and Z_j is endowed with the induced length metric. Clearly M, ∂W_j , and ∂Z_j are all isometric and

$$Vol(Z_{j}) = Vol_{m}(M_{j}) \epsilon_{j} + Vol_{m+1}(W_{j})$$

$$= (2 Vol_{m}(M_{0} \setminus U_{j}) + Vol_{m-1}(\partial U_{j}) 2\delta_{j}) \epsilon_{j} + Vol_{m}(M_{0} \setminus U_{j}) \delta_{j}$$

$$\leq (2 Vol_{m}(M_{0}) + 2) \epsilon_{j} + Vol_{m}(M_{0}) \delta_{j},$$

q.e.d.

by the choice of δ_j . Thus to prove $d_{\mathcal{F}}(M_j,0) \to 0$, we need only show that the map $\phi_j: M_j = \partial W_j \to M_j \times \{0\} \subset Z_j$ is an isometric embedding.

Recall that all points in M_j may be denoted (x,s) where $x \in M_0 \setminus U_j$, $s \in [0, \delta_j]$. Note that when $s \in (0, \delta_j)$, then we are on a tube and $x \in \partial U_j$. Thus all points in Z_j may be denoted (x, s, r) where $x \in M_0 \setminus U_j$, $s \in [0, \delta_j]$ and $r \in [0, \epsilon_j]$. Note that when $s \in (0, \delta_j)$ then either we are in a tube, in which case $x \in \partial U_j$, or we are in the interior of W, in which case $r = \epsilon_j$. Then $\phi_j(x, s) := (x, s, 0)$.

Let $\gamma(t) = (x(t), s(t), r(t))$ run minimally in Z_j from $\phi_j(x_0, s_0)$ to $\phi_j(x_1, s_1)$. So r(0) = r(1) = 0. If $r(t) < \epsilon_j$ for all t, then γ may be deformed, decreasing its length to

(214)
$$\eta(t) = (x(t), s(t)) \subset \phi_i(M_i),$$

where η runs minimally between the endpoints, in which case the length is $L(\gamma) = d_{M_i}((x_1, s_1), (x_2, s_2))$.

So we may assume there exists t where $r(t) = \epsilon_j$. Let t_0, t_1 be the first and last times where $r(t) = \epsilon_j$, respectively. For $t < t_0$ and $t > t_1$ we can again use the fact that $\eta(t) = (x(t), s(t))$ lies in M_j , but this time we make a more careful estimate on the length. Since γ runs minimally from $\gamma(0) = (x(0), s(0), 0)$ to $\gamma(t_0) = (x(t_0), s(t_0), \epsilon_j)$ and our space has an isometric product metric $M_j \times [0, \epsilon_j]$,

(215)
$$L\left(\gamma\left([0,t_{0}]\right)\right) = \sqrt{L\left(\eta\left([0,t_{0}]\right)\right)^{2} + \epsilon_{j}^{2}} = \sqrt{d_{0}^{2} + \epsilon_{j}^{2}}$$

where $d_0 = d_{M_j}\left(\left(x_0, s_0\right), \left(x(t_0), s(t_0)\right)\right)$. Similarly,

(216)
$$L(\gamma([t_1, 1])) = \sqrt{L(\eta([t_1, 1]))^2 + \epsilon_j^2} = \sqrt{d_1^2 + \epsilon_j^2}$$

where $d_1 = d_{M_j}((x(t_1), s(t_1)), (x_1, s_1))$. We can project the middle segment to $M_0 \setminus U_j$ to see that

(217)
$$L(\gamma([t_0, t_1])) \ge L(x([t_0, t_1])) = d_{M_j}((x(t_0), 0), (x(t_1), 0)).$$

By (211) we can estimate the distance in M_j from $(x(t_i), 0)$ to $(x(t_i), s(t_i))$ and apply the triangle inequality to see that

$$(218) \ L\left(\gamma\left([t_{0},t_{1}]\right)\right) \ \geq \ d_{M_{j}}\left(\left(x\left(t_{0}\right),s\left(t_{0}\right)\right),\left(x\left(t_{1}\right),s\left(t_{1}\right)\right)\right) - 4\bar{\epsilon}_{j}$$

$$(219) = d_{M_j}((x_0, s_0), (x_1, s_1)) - d_0 - d_1 - 4\bar{\epsilon}_j.$$

Combining (215), (216), and (218), and applying the definition of ϵ_j in (212) using the fact that $d_j \leq \text{diam}(M_j)$, we have: (220)

$$L\left(\gamma\right) - d_{M_{j}}\left(\left(x_{0}, s_{0}\right), \left(x_{1}, s_{1}\right)\right) \geq \sqrt{d_{0}^{2} + \epsilon_{j}^{2}} + \sqrt{d_{1}^{2} + \epsilon_{j}^{2}} - d_{0} - d_{1} - 4\bar{\epsilon}_{j} \geq 0.$$

Thus we have an isometric embedding.

A.8. Doubling in the limit. In this subsection we provide an example of a sequence of Riemannian manifolds which converge to an integral current space whose integral current structure is twice the standard structure and whose mass is twice its volume. The construction is the same as the one in the last subsection of a canceling sequence except that all tubes are now twisted so that the orientations line up instead of canceling with each other.

Example A.20. Given any compact oriented Riemannian manifold $M_0^m = (M_0, d_0, T_0)$ we can find a sequence of a sequence of oriented Riemannian manifolds N_j^m which converge in the Gromov-Hausdorff sense to M_0^m and yet in the intrinsic flat sense to M_0^m with weight 2: $(M_0, d_0, 2T_0)$. The sequence N_j^m have volumes converging to twice the volume of M_0^m and large regions converging smoothly to M_0^m .

Proof. We begin the construction exactly as in the beginning of the construction of Example A.19, creating a sequence of $M_j = \partial W_j$ which flat converge to 0. We cut M_j along the level $s = \delta_j/2$ which is a disjoint union of spheres. These spheres may be made isometric to a standard sphere of appropriate radius with a bi-Lipschitz map whose constant is very close to 1. These spheres are glued back together with the reverse orientation to create an oriented Riemannian manifold N_j . Note that there are two copies of $M_0 \setminus U_j$ in N_j , both with the same orientation defined by T_0 , and that there is an orientation preserving isometry between these two copies.

Let (X_j, d_j) be the metric space formed by taking two copies of M_0 with line segments of length δ_j joining the corresponding points $p_{j,1}, \ldots, p_{j,N_j}$ endowed with the length metric. Applying an adaption of the pipe filling technique [Remark A.15] to N_j and M_j respectively, we see that both are Gromov Hausdorff close to X_j . Furthermore,

(221)
$$\lim_{j \to \infty} d_{\mathcal{F}}(N_j, (X_j, d_j, T_j)) \to 0 \text{ and}$$

(222)
$$\lim_{j \to \infty} d_{\mathcal{F}}(M_j, (X_j, d_j, S_j)) \to 0,$$

where the distinction is that T_j has the same orientation on both copies of M_0 in X_j while S_j has opposite orientations on each slice.

Thus the canonical set, set $(T_j + S_j)$, is a copy of M_0 lying in X_j , and there is a current preserving isometry

(223)
$$\varphi: (M_0, d_0, 2T_0) \to (\text{set}(T_j + S_j), d_j, T_j + S_j).$$

By Example A.19, we know that $d_{\mathcal{F}}(M_j,0) \to 0$. Combining this fact with (222), we see that $d_{\mathcal{F}}((X_j,d_j,S_j),0) \to 0$ as well. So there exists a metric space Z_j and an isometric embedding $\psi: X_j \to Z_j$ such that

(224)
$$d_F^{Z_j}(\psi_\# S_j, 0) \to 0.$$

By (223), we see that $\psi \circ \varphi$ isometrically embeds M_0 in Z_j as well. Thus,

$$d_{\mathcal{F}}((X_{j}, d_{j}, T_{j}), (M_{0}, d_{0}, 2T_{0})) \leq d_{F}^{Z_{j}}(\psi_{\#}T_{j}, \psi \circ \varphi_{\#}2T_{0})$$

$$= d_{F}^{Z_{j}}(\psi_{\#}T_{j}, \psi_{\#}(T_{j} + S_{j}))$$

$$= d_{F}^{Z_{j}}(0, \psi_{\#}(S_{j})) \to 0.$$

By (221), we then have M_j converging to $(M_0, d_0, 2T_0)$. q.e.d.

A.9. Taxi cab limit space. In this subsection we give an example of a sequence of Riemannian manifolds which converge in both the Gromov-Hausdorff and intrinsic flat sense to the square torus with the taxicab metric, $M_{taxi} = (T^2, d_{taxi})$, where

(225)
$$d((x_1, x_2), (y_1, y_2)) = |x_1 - y_1| + |x_2 - y_2|.$$

Although the sequence converges without cancellation, the mass does not converge.

This sequence was described to the first coauthor by Dimitri Burago as a sequence which converges in the Gromov-Hausdorff sense. Here we describe Burago's proof and then prove that the flat and Gromov-Hausdorff limits agree in this setting. We show an integral current structure exists on the taxicab torus but we do not explicitly construct this structure. It would be of interest to investigate this in more detail.

Example A.21. There exists a sequence of Riemannian manifolds M_j^2 which converge in the intrinsic flat and Gromov-Hausdorff sense to the flat 1×1 torus with the taxi metric $M_{taxi} = (T^2, d_{taxi})$. In this example the mass drops in the limit.

Proof. The manifolds can be described as submanifolds of $T^2 \times R$ with the standard flat metric by the following graph:

(226)
$$M_{n,j}^2 = \{(x, y, f_{n,j}(x, y)) : f_{n,j}(x, y) = (1 - \sin^n(2^j \pi t)) / 2^j \}.$$

The metric on $M_{n,j}^2$ is defined as the length metric induced by the metric tensor defined by this embedding (which is not an isometric embedding).

Let G_j be the grid of $1/2^j$ squares defined by

(227)
$$G_j = M_{n,j}^2 \cap T^2 \times \{0\}.$$

As $n \to \infty$ for fixed j, $f_{n,j}$ converge pointwise to $h_j: T^2 \to R$ where $h_j(x,y) = 0$ for $(x,y) \in G_j$ and is 1 elsewhere.

Note also that $M_{n,j}^2$ converges in the Gromov-Hausdorff and Lipschitz sense as $n \to \infty$ to a metric space X_j defined by attaching disjoint five-sided $1/2^j$ cubes to each square in the $1/2^j$ grid, G_j , so that G_j with the induced length metric isometrically embeds into X_j with its natural length metric. We see it is an isometric embedding because a minimizing

geodesic between points in the grid would never be shorter going over the top of a cube rather than going around the base square.

This space X_j converges in the Gromov-Hausdorff sense to T_{taxi}^2 . This can be seen because grid G_j isometrically embeds into both spaces so

$$d_{GH}(X_{j}, T_{taxi}^{2}) \leq d_{GH}(X_{j}, G_{j}) + d_{GH}(G_{j}, T_{taxi}^{2})$$

$$\leq d_{H}^{X_{j}}(X_{j}, G_{j}) + d_{H}^{T_{taxi}^{2}}(G_{j}, T_{taxi}^{2})$$

$$\leq 2/2^{j} + 1/2^{j} \to 0.$$

Here we will see that the flat limit is also the torus with the taxicab metric.

By the Lipschitz convergence we have a natural current structure T_j on X_j and we can choose n_j large enough that $d_{\mathcal{F}}\left(\left(X_j,d_j,T_j\right),M_{n_j,j}\right)<1/j$ and $d_{GH}\left(X_j,M_{n_j,j}\right)<1/j$. So if we set $M_j=M_{n_j,j}$ and prove M_j converges in the intrinsic flat sense to T_{taxi}^2 , we are done.

By Theorem 3.20, we know a subsequence $(X_{j_i}, d_{j_i}, T_{j_i})$ converges to an integral current space $(X, d_{taxi}, T_{\infty})$ where $X \subset T_{taxi}^2$. Since X_{j_i} are locally contractible, we may apply Theorem 1.3 from [SW10], to see that $X = T_{taxi}^2$ (cf. Theorem 4.12). It is not immediately clear what the limit current structure on T_{taxi}^2 looks like, so we just call it T_{∞} .

We can also explicitly check that (X_j, d_j, T_j) is a Cauchy sequence with respect to the intrinsic flat distance. This can be seen because G_j isometrically embeds into G_{j+1} and so we may glue X_j to X_{j+1} along this embedding to create a geodesic metric space W_j . The metric space W_j consists of $(2^j)^2$ copies of a $(1/2^j) \times (1/2^j)$ five-sided cube attached to four $(1/2^{j+1}) \times (1/2^{j+1})$ five-sided cubes. The restriction of $T_j - T_{j+1}$ to this collection of five cubes has no boundary (as can be seen because the collection of five cubes is bi-Lipschitz to a sphere). By isometrically embedding W_j into a Banach space, we may apply the second author's filling theorem [Wen07] to fill in each collection of five cubes with a three dimensional integral current of mass $M_0 (1/2^j)^3$. Thus (228)

$$d_{\mathcal{F}}((X_j, d_j, T_j), (X_{j+1}, d_{j+1}, T_{j+1})) \le (2^j)^2 M_0 (1/2^j)^3 = M_0/2^j,$$

and our sequence is Cauchy.

Thus (X_j, d_j, T_j) converges to the limit of the subsequence $(T_{taxi}^2, d_{taxi}, T_{\infty})$.

Note $\mathbf{M}(T_j) \to 5$ due to the five faces on each cube. Thus $\mathbf{M}(T_\infty) \le 5$ by the lower semicontinuity of mass.

Now we slightly alter the top face of each cube to have a central peak, creating a new sequence of manifolds which also converge to the taxicab space in both the Gromov-Hausdorff and intrinsic flat sense with the exact same arguments as above. These new manifolds have mass

converging to a limit strictly greater than 5. Thus we have found a sequence of integral current spaces whose Gromov-Hausdorff and intrinsic flat limits agree but whose masses do not converge.

q.e.d.

A.10. Limit whose completion has higher dimension. There were many reasons that we defined integral current spaces using the set of positive lower density of the current rather than the support [Definition 2.35]. The key reason is that the set of a current has the correct dimension so that our integral current spaces are always countable H^k rectifiable of the correct dimension even though they need not be compact or complete. If one takes the completion on an integral current space, it may have higher dimension as we see here:

Example A.22. There is a sequence of Riemannian surfaces M'_j that converge to a nonzero 2 dimensional integral current space N_{∞} such that the closure of N^3 is the solid 3 dimensional cube with the standard Euclidean metric.

Proof. As in Example A.14, our sequence of M'_j will be constructed using spheres joined by cylinders. In that example, we never used anything special about the arrangement of the spheres used to define M_j except that the total volumes of the spheres were uniformly bounded and the radii ϵ_j of the connecting cylinders were chosen small enough that the total length of the cylinders L_j satisfied $L_j \epsilon_j \to 0$. Note that it was not necessary that the spheres and cylinders isometrically embed into Euclidean space as this embedding was only used to describe the locations of the spheres. Here we will again start with a sequence of inductively defined spheres embedded into Euclidean 3 space, but we will connect them with abstract cylinders so that we need not concern ourselves with intersections.

We begin by constructing a sequence of outward oriented spheres which are disjoint and dense in the solid unit cube, $[0,1]^3$. The first $n_1=8$ spheres are centered on points of the form (n/4,m/4) where $(n,m) \in \{1,2,3\} \times \{1,2,3\}$ and have radius $r_1>0$ and sufficiently small that they are disjoint, they have total area $n_1 4\pi r_1^2 < 1$, and the total of their diameters is $n_1\pi r_1 < 1/2$. The next collection of n_2 spheres are centered on points of the form (n/8,m/8) where $(n,m) \in \{1,2,3\ldots 7\} \times \{1,2,3\ldots 7\}$ but excluding any such points which already lie on the first n_1 spheres. Then the radius r_2 of these n_2 spheres is chosen small enough that all the n_1+n_2 spheres are disjoint, the total area of the spheres, $n_1 4\pi r_1^2 + n_2 4\pi r_2^2 < 1$, and the total of the diameters, $n_2\pi r_2 < 1/4$. We continue in this matter, creating a dense collection of disjoint spheres lying in $[0,1]^3$ whose closure is $[0,1]^3$ and whose total area is ≤ 1 and total of the last n_j spheres' diameters is $< 1/2^j$. We will let V_j denote the first $n_1 + \cdots + n_j$ disjoint spheres.

We next create geodesic metric spaces X_j by connecting the spheres in V_j with line segments, and prove X_j converges in the Gromov-Hausdorff sense to $[0,1]^3$ with the standard Euclidean metric. The X_j will have induced length metrics and will not isometrically embed into $[0,1]^3$. The line segments connecting the spheres may appear to intersect in $[0,1]^3$ but, by definition, do not intersect. More precisely, we will say we have connected a sphere, S_1 , to a sphere, S_2 , if we find points $x_1 \in S_1$ and $x_2 \in S_2$ such that $d_{[0,1]^3}(x_1, x_2)$ achieves the distance, d, between S_1 and S_2 as measured in $[0,1]^3$, and then we attach an abstract line segment of length d between these two points.

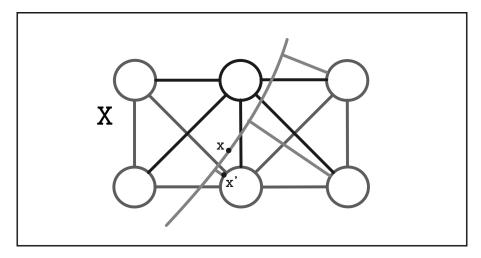


Figure 17. Here the spheres are drawn as circles.

Each space X_j is a connected collection of the first $n_1 + \cdots + n_j$ spheres. Not all spheres will be connected to each other. See Figure 17 for a view of a tiny region in the cube where the spheres are depicted as circles and the endpoints of segments connecting spheres are solid points. To build X_j we take each sphere ∂B_1 of radius r_j and connect it to any other neighboring sphere ∂B_2 of radius $r \leq r_j$ (whose line segment is of length at most 1/j) and such that $B_1 \cap B_2 = \emptyset$. This second condition will help with orientation later. Note that none of the larger spheres are connected directly to each other, only via connections among the smaller spheres. This X_j is a connected geodesic metric space and let L_j be the total lengths of all segments in X_j . We can create an integral current space $N_j = (\text{set}(T_j), d_{X_j}, T_j)$ where T_j is integration over the spheres in X_j with outward orientation.

We define Lipschitz Riemannian manifolds, $M_j = \partial T_{\epsilon_j}(X_j)$, as the boundary of an abstract tubular neighborhood around X_j , where ϵ_j is taken so small that any pair of spheres in X_j is still disjoint when the radii are ϵ_j larger and such that $\epsilon_j L_j < 1/j$, and such that the area

of M_j is less than 1 + 1/j. This abstractly defined space does not lie in $[0,1]^3$ but each geodesic segment has been replaced by a cylinder of the appropriate width so that M_j immerses into X_j with a local isometry. Note that by our careful connection of the spheres in the previous paragraph, M_j is orientable and we orient it so that all the spheres are outward oriented. See Figure 18.

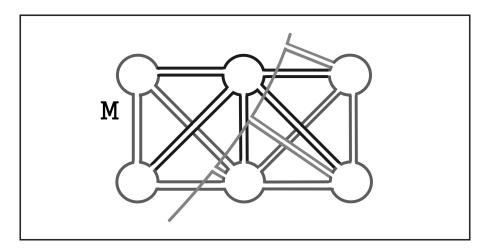


Figure 18. Note the outward orientation.

By the pipe filling technique [Remark A.13] and the bounds on ϵ_j , L_j , and the total area, $d_{\mathcal{F}}(M_j,N_j)\to 0$ and $d_{GH}(M_j,X_j)\to 0$. To complete our example we need only prove that X_j converges in the Gromov-Hausdorff sense to $[0,1]^3$ and N_j converges in the intrinsic flat sense to N_{∞} , where $N_{\infty}=\left(\operatorname{set}(T_{\infty}),\operatorname{d}_{[0,1]^3},T_{\infty}\right)$ and T_{∞} is defined by integration over all the spheres in our collection with outward orientation. Note that by the density of the spheres in $[0,1]^3$ the completion of N_{∞} is $[0,1]^3$.

Notice that $d_{GH}(N_j, X_j) \leq d_H^{X_j}(N_j, X_j) \leq 1/j$ by the shortness of the joining line segments in the creation of X_j . So we need only prove N_j converges in the Gromov-Hausdorff sense to $[0,1]^3$ and in the flat sense to N_{∞} .

There is a natural map $f_j: N_j \to [0,1]^3$ which is not an isometry. However, we claim there is a uniform distortion, D_j , such that if $x, y \in N_j$, then

(229)
$$d_{[0,1]^3}(f_j(x), f_j(y)) - d_{X_j}(x, y) | \leq D_j \to 0$$

as $j \to \infty$. After proving this claim we will use it to prove our convergence claims.

Given $x \in N_j$, there exists x' in a sphere of radius r_j in N_j outside the sphere containing x such that $d_{[0,1]^3}(x',x) < 6/2^j$ by the density of

the smallest spheres in $[0,1]^3$. See Figure 17 again. By the connecting of the spheres by line segments, we know $d_{X_j}(x',x) \leq \pi 6/2^j + 1/j$ since an arclength can always be bounded by π times a secant length and we need travel down at most one line segment to reach the smaller sphere. Similarly for $y \in N_j$, there exists y' with $d_{X_j}(y',y) \leq 26/2^j + 1/j$. So we need only prove (229) for x', y' lying in smallest spheres in X_j .

Between x' and y', one can draw a straight line segment in $[0,1]^3$ and then select the smallest spheres in X_j with radius r_j which are closest to this line segment. By the density of the smallest spheres we know there are many spheres very close to this segment, but we need to avoid zigzagging between them. We apply the fact that the connecting segments in X_j get as long as 1/j while the density of the spheres is $1/2^j$, so that we may actually select smallest spheres between x' and y' which are joined by segments whose total length approximates $d_{[0,1]^3}(x',y')$. Between the segments a path between x' and y' lying in X_j must go around the small spheres; however, their total diameter has been bounded above by $1/2^j$, so this does not add to the error significantly and we have (229).

We now create spaces $Z_j = X_j \times [0, h_j] \sqcup [0, 1]^3$ where

(230)
$$h_j = \sqrt{(D_j/2)(2\operatorname{diam}(N_j) + D_j/2)}$$

so that (x, h_j) is identified with $f_j(x)$ with the induced length metric. Note that there is a distance nonincreasing retraction to $[0, 1]^3$, so there is an isometry $\varphi: [0, 1]^3 \to Z_j$. We claim there is also an isometric embedding $\psi: N_j \to N_j \times \{0\} \subset Z_j$ since a shortest curve between points in $N_j \times \{0\}$ either stays in the $X_j \times \{0\}$ level or enters the $[0, 1]^3$ region where we can apply (229) to control the short cut in that region. To enter the $[0, 1]^3$ region, it first travels a distance $\sqrt{L_1^2 + h_j^2}$ to the region, then a distance greater than $L_2 - D_j$ in the region, and then a distance $\sqrt{L_3^2 + h_j^2}$ back from the region where $L_1 + L_2 + L_3$ equals the distance in N_j between the endpoints of the curve. However, by the choice of h_j this causes a contradiction.

Thus $d_G H\left(N_j, [0,1]^3\right) \leq d_H^{Z_j}\left(\psi\left(N_j\right), \varphi\left([0,1]^3\right)\right) \to 0$. Furthermore,

(231)
$$d_{\mathcal{F}}\left(N_{j}, N_{\infty}\right) \leq d_{F}^{Z_{j}}\left(\psi_{\#}N_{j}, \varphi_{\#}N_{\infty}\right) \leq \mathbf{M}\left(A_{j}\right) + \mathbf{M}\left(B_{j}\right)$$

where $A_j \in \mathbf{I}_2(Z_j)$ is integration over the spheres of radius r_j in $[0,1]^3$ and $B_j \in \mathbf{I}_3(Z_j)$ is integration over the collection of cylinders $N_j \times [0, h_j]$. By our bound on the total area of the spheres, $\mathbf{M}A_j \to 0$ and $\mathbf{M}(B_j) \leq h_j \to 0$. So we are done.

A.11. Gabriel's horn and the Cauchy sequence with no limit. In this section we present an example of a sequence of compact Riemannian manifolds which are Cauchy with respect to the intrinsic flat

distance but have no limit. This example demonstrates the necessity of the uniform bound on volume in Theorem 4.20. See also Remark 4.5. It is based on the classical example of Gabriel's Horn:

(232)
$$M_0 = \{(x, y, z) : x^2 + y^2 = 1/(1-z)^2, z > 0\} \subset E^3$$

which is a rotationally symmetric surface of infinite area enclosing a finite volume. Note that M_0 is not an integral current space because it has infinite mass. The fact that it is unbounded is not a problem as seen in Example A.10.

Example A.23. Define the sequence of Riemannian manifolds diffeomorphic to the sphere

(233)
$$M_i = \{(x, y, z) : x^2 + y^2 = f_i(z)/(1-z)^2, \} \subset E^3$$

such that $f_j(z)$ is sin(z) for $z \in [0,1]$, is 1 for $z \in [1,j]$, and then decreases to 0 at z = j + 1/j so that each M_j is smooth. This is a sequence of integral current spaces without a uniform upper bound on their total mass that is Cauchy with respect to the intrinsic flat distance but has no limit in the intrinsic flat sense.

Proof. First we prove that M_j is a Cauchy sequence by explicitly building a metric space Z between an arbitrary pair M_i and M_j with fixed $i \geq j$. Let T_1 be the current structure on M_j and T_2 the current structure on M_i . Let $U_1 = M_j \cap \{z \in [0,j]\}$ and $U_2 = M_i \cap \{z \in [0,j]\}$ so U_1 and U_2 with the induced length metrics are isometric. We now apply Proposition A.3 to estimate the flat distance between them. In applying this proposition we take $X_1 = V_1 = M_j \setminus U_1$ and $B_1 = 0$ and A_1 to be integration over X_1 . Then one can find a constant C_1 not depending on i or j such that

(234)
$$\mathbf{M}(A_1) \le \frac{C_1}{j^2}$$
 and $\mathbf{M}(B_1) = 0$.

Unlike V_1 , V_2 may be very long and have large area. So let (235)

$$X_2 = \{(x, y, z, w) : x^2 + y^2 + w^2 = f_i(z)/(1-z)^2, z \ge j w \ge 0\} \subset E^3$$

so that V_2 isometrically embeds into X_2 and let B_2 be integration over X_2 and A_2 be integration over the disk, $X_2 \cap \{z = j\}$, with the appropriate orientation. Then there exist constants C_2, C_3 such that

(236)
$$\mathbf{M}(A_2) \le C_2/j^2$$
 and $\mathbf{M}(B_2) = \text{Vol}(V_2) \le C_3/j$.

So by Proposition A.3, we have (237)

$$d_{\mathcal{F}}(M_i, M_j) \le \text{Vol}(U_1)(h_1 + h_2) + \mathbf{M}(B_1) + \mathbf{M}(B_2) + \mathbf{M}(A_1) + \mathbf{M}(A_2)$$

where

$$h_i \leq \operatorname{diam}(\partial U_i) \left(2 \operatorname{diam}(U_i) + \operatorname{diam}(\partial U_i) \right)$$

(238)
$$\leq \pi/(1-j)^2 \left(2(2j) + \pi/(1-j)^2\right) \leq \frac{C_4}{j}.$$

By integrating, one sees that $Vol(U_1) \leq C_5 Ln(j)$. Substituting this into (237), we see that the sequence is Cauchy.

To prove there is no limit for this sequence, we assume on the contrary that M_j converge in the intrinsic flat sense to an integral current space M_{∞} . We will prove that there are large balls in M_{∞} isometric to large balls in

(239)
$$N_{\infty} = \{(x, y, z) : x^2 + y^2 = f_{\infty}(z)/(1-z)^2, \} \subset E^3$$

where $f_{\infty}(z)$ is sin(z) for $z \in [0,1]$, and is 1 for $z \in [1,\infty)$. Then apply this to force $\mathbf{M}(M_{\infty}) = \infty$, which is a contradiction.

Suppose M_{∞} is not the **0** integral current space. Then there exists $x \in M_{\infty}$ and there exists $y_j \in M_j$ converging to x, and for almost every R > 0, there exists R_j increasing to R, such that

(240)
$$\liminf_{j \to \infty} \operatorname{Vol}(B(y_j, R_j)) \ge \mathbf{M}(B(x, R)) > 0.$$

However, we need a lower bound $\mathbf{M}(B(x,R))$.

By our particular choice of M_j , there thus exists D > 0 such that $y_j \subset M_j \cap \{z \in [0, D]\}$, otherwise the volumes would go to zero. For j sufficiently large, there also exist isometries

(241)
$$\varphi_j: M_j \cap \{z \in [0, D]\} \to N_\infty \cap \{z \in [0, D]\}.$$

Since $N_{\infty} \cap \{z \in [0,D]\}$ is compact, a subsequence of the $\varphi_j(y_j)$ converges to some $y_{\infty} \in N_{\infty}$. By the fact that R_j increases to R, $B(\varphi_j(y_j), R_j)$ converges in the Lipschitz sense to the open ball $B(y,R) \subset M_{\infty}$. Thus by Theorem 5.6, $S(y_j,R_j) = T_j \sqcup B(y_j,R_j)$ converge in the intrinsic flat sense to the integral current space T_R defined by integration over B(y,R) in N_{∞} . Note that $\mathbf{M}(T_R) \to \infty$.

The Lipschitz convergence also implies that the total masses of $S(y_j, R_j)$ are uniformly bounded above. We see that $S(y_j, R_j)$ converge in the intrinsic flat sense to $S(x, R) = T_\infty \, \sqcup \, B(y, R) \in \mathbf{I}_2(M_\infty)$. Thus there is a current preserving isometry from $B(x, R) \subset M_\infty$ to $B(y, R) \subset N_\infty$ for almost every R > 0. In particular, we see that

(242)
$$\mathbf{M}(M_{\infty}) \ge \lim_{R \to \infty} \mathbf{M}(B(x,R)) = \lim_{R \to \infty} (T_R) = \infty,$$

which contradicts the fact that M_{∞} is an integral current space.

The only other possibility is that the M_j converge to the **0** current space. Then by Theorem 4.3, we can choose points $p_j \in M_j$ and find isometric embeddings $\varphi_j : M_j \to Z$ such that $\varphi_j(p_j) = z \in Z$ and $\varphi_{j\#}(T_j) \xrightarrow{\mathcal{F}} 0$ in Z.

We can choose the $p_j = (0,0,0) \in M_j$ so that all the $B(p_j,R)$ are isometric for j sufficiently large. Note that φ_j maps $B(p_j,R)$ isometrically onto $B(z,R) \cap \varphi_j(M_j)$. So for almost every R > 0 fixed, we have $\varphi_{j\#}S(p_j,R) = \varphi_{j\#}T_j \, \sqcup \, B(z,R) \xrightarrow{\mathcal{F}} 0$. However, this is a constant sequence of nonzero integral current spaces, so we have a contradiction. q.e.d.

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