# STABILITY OF HYPERSURFACES WITH CONSTANT $(r+1)$-TH ANISOTROPIC MEAN CURVATURE 

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#### Abstract

Given a positive function $F$ on $S^{n}$ which satisfies a convexity condition, we define the $r$-th anisotropic mean curvature function $H_{r}^{F}$ for hypersurfaces in $\mathbb{R}^{n+1}$ which is a generalization of the usual $r$-th mean curvature function. Let $X: M \rightarrow$ $\mathbb{R}^{n+1}$ be an $n$-dimensional closed hypersurface with $H_{r+1}^{F}=$ constant, for some $r$ with $0 \leq r \leq n-1$, which is a critical point for a variational problem. We show that $X(M)$ is stable if and only if $X(M)$ is the Wulff shape.


## 1. Introduction

Let $F: S^{n} \rightarrow \mathbb{R}^{+}$be a smooth function which satisfies the following convexity condition:

$$
\begin{equation*}
\left(D^{2} F+F 1\right)_{x}>0 \quad \forall x \in S^{n} \tag{1.1}
\end{equation*}
$$

where $S^{n}$ denotes the standard unit sphere in $\mathbb{R}^{n+1}, D^{2} F$ denotes the intrinsic Hessian of $F$ on $S^{n}$ and 1 denotes the identity on $T_{x} S^{n},>0$ means that the matrix is positive definite. We consider the map

$$
\begin{gather*}
\phi: S^{n} \rightarrow \mathbb{R}^{n+1}  \tag{1.2}\\
x \mapsto F(x) x+\left(\operatorname{grad}_{S^{n}} F\right)_{x},
\end{gather*}
$$

its image $W_{F}=\phi\left(S^{n}\right)$ is a smooth, convex hypersurface in $\mathbb{R}^{n+1}$ called the Wulff shape of $F$ (see [4], [7]-[9], [11], [14], [18], [19]). We note when $F \equiv 1$, $W_{F}$ is just the sphere $S^{n}$.

[^0]Now let $X: M \rightarrow \mathbb{R}^{n+1}$ be a smooth immersion of a closed, orientable hypersurface. Let $\nu: M \rightarrow S^{n}$ denotes its Gauss map, that is $\nu$ is the unit inner normal vector of $M$.

Let $A_{F}=D^{2} F+F 1, S_{F}=-\mathrm{d}(\phi \circ \nu)=-A_{F} \circ \mathrm{~d} \nu . \quad S_{F}$ is called the $F-$ Weingarten operator, and the eigenvalues of $S_{F}$ are called anisotropic principal curvatures. Let $\sigma_{r}$ be the elementary symmetric functions of the anisotropic principal curvatures $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{n}$ :

$$
\begin{equation*}
\sigma_{r}=\sum_{i_{1}<\cdots<i_{r}} \lambda_{i_{1}} \cdots \lambda_{i_{r}} \quad(1 \leq r \leq n) \tag{1.3}
\end{equation*}
$$

We set $\sigma_{0}=1$. The $r$-th anisotropic mean curvature $H_{r}^{F}$ is defined by $H_{r}^{F}=$ $\sigma_{r} / C_{n}^{r}$, also see Reilly [16].

For each $r, 0 \leq r \leq n-1$, we set

$$
\begin{equation*}
\mathscr{A}_{r, F}=\int_{M} F(\nu) \sigma_{r} \mathrm{~d} A_{X} \tag{1.4}
\end{equation*}
$$

The algebraic $(n+1)$-volume enclosed by $M$ is given by

$$
\begin{equation*}
V=\frac{1}{n+1} \int_{M}\langle X, \nu\rangle \mathrm{d} A_{X} \tag{1.5}
\end{equation*}
$$

We consider those hypersurfaces which are critical points of $\mathscr{A}_{r, F}$ restricted to those hypersurfaces enclosing a fixed volume $V$. By a standard argument involving Lagrange multipliers, this means we are considering critical points of the functional

$$
\begin{equation*}
\mathscr{F}_{r, F ; \Lambda}=\mathscr{A}_{r, F}+\Lambda V(X), \tag{1.6}
\end{equation*}
$$

where $\Lambda$ is a constant. We will show the Euler-Lagrange equation of $\mathscr{F}_{r, F ; \Lambda}$ is:

$$
\begin{equation*}
(r+1) \sigma_{r+1}-\Lambda=0 \tag{1.7}
\end{equation*}
$$

So the critical points are just hypersurfaces with $H_{r+1}^{F}=$ constant.
If $F \equiv 1$, then the function $\mathscr{A}_{r, F}$ is just the functional $\mathscr{A}_{r}=\int_{M} S_{r} \mathrm{~d} A_{X}$ which was studied by Alencar, do Carmo, and Rosenberg in [1], where $H_{r}=$ $S_{r} / C_{n}^{r}$ is the usual $r$-th mean curvature. For such a variational problem, they call a critical immersion $X$ of the functional $\mathscr{A}_{r}$ (that is, a hypersurface with $H_{r+1}=$ constant) stable if and only if the second variation of $\mathscr{A}_{r}$ is nonnegative for all variations of $X$ preserving the enclosed $(n+1)$-volume $V$. They proved the following theorem.

Theorem 1.1 ([1]). Suppose $0 \leq r \leq n-1$. Let $X: M \rightarrow \mathbb{R}^{n+1}$ be a closed hypersurface with $H_{r+1}=$ constant. Then $X$ is stable if and only if $X(M)$ is a round sphere.

Analogously, we call a critical immersion $X$ of the functional $\mathscr{A}_{r, F}$ stable if and only if the second variation of $\mathscr{A}_{r, F}$ (or equivalently of $\mathscr{F}_{r, F ; \Lambda}$ ) is nonnegative for all variations of $X$ preserving the enclosed $(n+1)$-volume $V$.

In [14], Palmer proved the following theorem (also see Winklmann [19]).
Theorem 1.2 ([14]). Let $X: M \rightarrow \mathbb{R}^{n+1}$ be a closed hypersurface with $H_{1}^{F}=$ constant. Then $X$ is stable if and only if, up to translations and homotheties, $X(M)$ is the Wulff shape.

In this paper, we prove the following theorem.
Theorem 1.3. Suppose $0 \leq r \leq n-1$. Let $X: M \rightarrow \mathbb{R}^{n+1}$ be a closed hypersurface with $H_{r+1}^{F}=$ constant. Then $X$ is stable if and only if, up to translations and homotheties, $X(M)$ is the Wulff shape.

Remark 1.4. In the case $F \equiv 1$, Theorem 1.3 becomes Theorem 1.1. Theorem 1.3 gives an affirmative answer to the problem proposed in [8]. We also note that in the case $F \equiv 1$, our result here gives a new and geometric proof of Theorem 1.1, which is different from [1].

## 2. Preliminaries

Let $X: M \rightarrow R^{n+1}$ be a smooth closed, oriented hypersurface with Gauss $\operatorname{map} \nu: M \rightarrow S^{n}$, that is, $\nu$ is the unit inner normal vector field. Let $X_{t}$ be a variation of $X$, and $\nu_{t}: M \rightarrow S^{n}$ be the Gauss map of $X_{t}$. We define

$$
\begin{equation*}
\psi=\left\langle\frac{\mathrm{d} X_{t}}{\mathrm{~d} t}, \nu_{t}\right\rangle, \quad \xi=\left(\frac{\mathrm{d} X_{t}}{\mathrm{~d} t}\right)^{\top} \tag{2.1}
\end{equation*}
$$

where $\top$ represents the tangent component and $\psi, \xi$ are dependent of $t$. The corresponding first variation of the unit normal vector is given by (see [8], [11], [14], [19])

$$
\begin{equation*}
\nu_{t}^{\prime}=-\operatorname{grad} \psi+\mathrm{d} \nu_{t}(\xi) \tag{2.2}
\end{equation*}
$$

the first variation of the volume element is (see [2], [3], or [10])

$$
\begin{equation*}
\partial_{t} \mathrm{~d} A_{X_{t}}=(\operatorname{div} \xi-n H \psi) \mathrm{d} A_{X_{t}} \tag{2.3}
\end{equation*}
$$

and the first variation of the volume $V$ is

$$
\begin{equation*}
V^{\prime}(t)=\int_{M} \psi \mathrm{~d} A_{X_{t}} \tag{2.4}
\end{equation*}
$$

where grad, div, $H$ represents the gradients, the divergence, the mean curvature with respect to $X_{t}$, respectively.

Let $\left\{E_{1}, \ldots, E_{n}\right\}$ be a local orthogonal frame on $S^{n}$, let $e_{i}=e_{i}(t)=E_{i} \circ \nu_{t}$, where $i=1, \ldots, n$ and $\nu_{t}$ is the Gauss map of $X_{t}$, then $\left\{e_{1}, \ldots, e_{n}\right\}$ is a local orthogonal frame of $X_{t}: M \rightarrow \mathbb{R}^{n+1}$.

The structure equations of $x: S^{n} \rightarrow \mathbb{R}^{n+1}$ are:

$$
\left\{\begin{array}{l}
\mathrm{d} x=\sum_{i} \theta_{i} E_{i},  \tag{2.5}\\
\mathrm{~d} E_{i}=\sum_{j} \theta_{i j} E_{j}-\theta_{i} x, \\
\mathrm{~d} \theta_{i}=\sum_{j} \theta_{i j} \wedge \theta_{j} \\
\mathrm{~d} \theta_{i j}-\sum_{k} \theta_{i k} \wedge \theta_{k j}=\frac{1}{2} \sum_{k, l} \tilde{R}_{i j k l} \theta_{k} \wedge \theta_{l}=-\theta_{i} \wedge \theta_{j}
\end{array}\right.
$$

where $\theta_{i j}+\theta_{j i}=0$ and $\tilde{R}_{i j k l}=\delta_{i l} \delta_{j k}-\delta_{i k} \delta_{j l}$.
The structure equations of $X_{t}$ are (see [12], [13]):

$$
\left\{\begin{array}{l}
\mathrm{d} X_{t}=\sum_{i} \omega_{i} e_{i}  \tag{2.6}\\
\mathrm{~d} \nu_{t}=-\sum_{i, j} h_{i j} \omega_{j} e_{i} \\
\mathrm{~d} e_{i}=\sum_{j} \omega_{i j} e_{j}+\sum_{j} h_{i j} \omega_{j} \nu_{t} \\
\mathrm{~d} \omega_{i}=\sum_{j} \omega_{i j} \wedge \omega_{j} \\
\mathrm{~d} \omega_{i j}-\sum_{k} \omega_{i k} \wedge \omega_{k j}=\frac{1}{2} \sum_{k, l} R_{i j k l} \theta_{k} \wedge \theta_{l}
\end{array}\right.
$$

where $\omega_{i j}+\omega_{j i}=0, R_{i j k l}+R_{i j l k}=0$, and $R_{i j k l}$ are the components of the Riemannian curvature tensor of $X_{t}(M)$ with respect to the induced metric $\mathrm{d} X_{t} \cdot \mathrm{~d} X_{t}$. Here, we have omitted the variable $t$ for some geometric quantities.

From de $e_{i}=\mathrm{d}\left(E_{i} \circ \nu_{t}\right)=\nu_{t}^{*} \mathrm{~d} E_{i}=\sum_{j} \nu_{t}^{*} \theta_{i j} e_{j}-\nu_{t}^{*} \theta_{i} \nu_{t}$, we get

$$
\left\{\begin{array}{l}
\omega_{i j}=\nu_{t}^{*} \theta_{i j},  \tag{2.7}\\
\nu_{t}^{*} \theta_{i}=-\sum_{j} h_{i j} \omega_{j}
\end{array}\right.
$$

where $\omega_{i j}+\omega_{j i}=0, h_{i j}=h_{j i}$.
Let $F: S^{n} \rightarrow \mathbb{R}^{+}$be a smooth function, we denote the coefficients of covariant differential of $F, \operatorname{grad}_{S^{n}} F$ with respect to $\left\{E_{i}\right\}_{i=1, \ldots, n}$ by $F_{i}, F_{i j}$ respectively.

From (2.7), $\mathrm{d}\left(F\left(\nu_{t}\right)\right)=\nu_{t}^{*} \mathrm{~d} F=\nu_{t}^{*}\left(\sum_{i} F_{i} \theta_{i}\right)=-\sum_{i, j}\left(F_{i} \circ \nu_{t}\right) h_{i j} \omega_{j}$, thus,

$$
\begin{equation*}
\operatorname{grad}\left(F\left(\nu_{t}\right)\right)=-\sum_{i, j}\left(F_{i} \circ \nu_{t}\right) h_{i j} e_{j}=\mathrm{d} \nu_{t}\left(\operatorname{grad}_{S^{n}} F\right) \tag{2.8}
\end{equation*}
$$

Through a direct calculation, we easily get

$$
\begin{equation*}
\mathrm{d} \phi=\left(D^{2} F+F 1\right) \circ \mathrm{d} x=\sum_{i, j} A_{i j} \theta_{i} E_{j} \tag{2.9}
\end{equation*}
$$

where $A_{i j}$ is the coefficient of $A_{F}$, that is, $A_{i j}=F_{i j}+F \delta_{i j}$.
Taking exterior differential of (2.9) and using (2.5), we get

$$
\begin{equation*}
A_{i j k}=A_{j i k}=A_{i k j} \tag{2.10}
\end{equation*}
$$

where $A_{i j k}$ denotes coefficient of the covariant differential of $A_{F}$ on $S^{n}$.
We define $\left(A_{i j} \circ \nu_{t}\right)_{k}$ by

$$
\begin{equation*}
\mathrm{d}\left(A_{i j} \circ \nu_{t}\right)+\sum\left(A_{k j} \circ \nu_{t}\right) \omega_{k i}+\sum_{k}\left(A_{i k} \circ \nu_{t}\right) \omega_{k j}=\sum_{k}\left(A_{i j} \circ \nu_{t}\right)_{k} \omega_{k} \tag{2.11}
\end{equation*}
$$

By a direct calculation by using (2.7) and (2.11), we have

$$
\begin{equation*}
\left(A_{i j} \circ \nu_{t}\right)_{k}=-\sum_{l} h_{k l} A_{i j l} \circ \nu_{t} . \tag{2.12}
\end{equation*}
$$

We define $L_{i j}$ by

$$
\begin{equation*}
\left(\frac{\mathrm{d} e_{i}}{\mathrm{~d} t}\right)^{\top}=-\sum_{j} L_{i j} e_{j} \tag{2.13}
\end{equation*}
$$

where $\top$ denote the tangent component, then $L_{i j}=-L_{j i}$ and we have (see [2], [3], or [10])

$$
\begin{equation*}
h_{i j}^{\prime}=\psi_{i j}+\sum_{k}\left\{h_{i j k} \xi_{k}+\psi h_{i k} h_{j k}+h_{i k} L_{k j}+h_{j k} L_{k i}\right\} \tag{2.14}
\end{equation*}
$$

Let $s_{i j}=\sum_{k}\left(A_{i k} \circ \nu\right) h_{k j}$, then from (2.7) and (2.9), we have

$$
\begin{equation*}
\mathrm{d}\left(\phi \circ \nu_{t}\right)=\nu_{t}^{*} \mathrm{~d} \phi=-\sum_{i, j} s_{i j} \omega_{j} e_{i} . \tag{2.15}
\end{equation*}
$$

We define $S_{F}$ by $S_{F}=-\mathrm{d}(\phi \circ \nu)=-A_{F} \circ \mathrm{~d} \nu$, then we have $S_{F}\left(e_{j}\right)=\sum_{i} s_{i j} e_{i}$. We call $S_{F}$ the $F$-Weingarten operator. From the positive definiteness of $\left(A_{i j}\right)$ and the symmetry of $\left(h_{i j}\right)$, we know the eigenvalues of $\left(s_{i j}\right)$ are all real. We call them anisotropic principal curvatures, and denote them by $\lambda_{1}, \ldots, \lambda_{n}$.

Taking exterior differential of (2.15) and using (2.6), we get

$$
\begin{equation*}
s_{i j k}=s_{i k j} \tag{2.16}
\end{equation*}
$$

where $s_{i j k}$ denotes coefficient of the covariant differential of $S_{F}$.
We have $n$ invariants, the elementary symmetric function $\sigma_{r}$ of the anisotropic principal curvatures:

$$
\begin{equation*}
\sigma_{r}=\sum_{i_{1}<\cdots<i_{r}} \lambda_{i_{1}} \cdots \lambda_{i_{n}} \quad(1 \leq r \leq n) . \tag{2.17}
\end{equation*}
$$

For convenience, we set $\sigma_{0}=1$ and $\sigma_{n+1}=0$. The $r$-th anisotropic mean curvature $H_{r}^{F}$ is defined by

$$
\begin{equation*}
H_{r}^{F}=\sigma_{r} / C_{n}^{r}, \quad C_{n}^{r}=\frac{n!}{r!(n-r)!} \tag{2.18}
\end{equation*}
$$

We have, by use of (2.2) and (2.6),

$$
\begin{align*}
\sum_{i, j} \frac{\mathrm{~d}\left(\left(A_{i j} E_{i} \otimes E_{j}\right) \circ \nu_{t}\right)}{\mathrm{d} t} & =\sum_{i, j}\left\langle\left(D\left(A_{i j} E_{i} \otimes E_{j}\right)\right)_{\nu_{t}}, \nu_{t}^{\prime}\right\rangle  \tag{2.19}\\
& =-\sum_{i, j, k} A_{i j k}\left(\psi_{k}+\sum_{l} h_{k l} \xi_{l}\right) e_{i} \otimes e_{j}
\end{align*}
$$

where $D$ is the Levi-Civita connection on $S^{n}$.

On the other hand, we have

$$
\begin{align*}
& \sum_{i, j} \frac{\mathrm{~d}\left(\left(A_{i j} E_{i} \otimes E_{j}\right) \circ \nu_{t}\right)}{\mathrm{d} t}  \tag{2.20}\\
& \quad=\sum_{i, j}\left\{A_{i j}^{\prime} e_{i} \otimes e_{j}+A_{i j}\left(\frac{\mathrm{~d} e_{i}}{\mathrm{~d} t}\right)^{\top} \otimes e_{j}+A_{i j} e_{i} \otimes\left(\frac{\mathrm{~d} e_{j}}{\mathrm{~d} t}\right)^{\top}\right\}
\end{align*}
$$

By use of (2.13), we get from (2.19) and (2.20)

$$
\begin{align*}
\frac{\mathrm{d}\left(A_{i j} \circ \nu_{t}\right)}{\mathrm{d} t} & =A_{i j}^{\prime}(t)  \tag{2.21}\\
& =\sum_{k}\left\{-A_{i j k} \psi_{k}-\sum_{l} A_{i j k} h_{k l} \xi_{l}+A_{i k} L_{k j}+A_{j k} L_{k i}\right\}
\end{align*}
$$

By (2.12), (2.14), (2.21) and the fact $L_{i j}=-L_{j i}$, through a direct calculation, we get the following lemma.

Lemma 2.1.

$$
\frac{\mathrm{d} s_{i j}}{\mathrm{~d} t}=s_{i j}^{\prime}(t)=\sum_{k}\left\{\left(A_{i k} \psi_{k}\right)_{j}+s_{i j k} \xi_{k}+\psi s_{i k} h_{k j}+s_{k j} L_{k i}+s_{i k} L_{k j}\right\}
$$

As $M$ is a closed oriented hypersurface, one can find a point where all the principal curvatures with respect to $\nu$ are positive. By the positiveness of $A_{F}$, all the anisotropic principal curvatures are positive at this point. Using the results of Gårding [5], we have the following lemma.

Lemma 2.2. Let $X: M \rightarrow \mathbb{R}^{n+1}$ be a closed, oriented hypersurface. Assume $H_{r+1}^{F}>0$ holds at every point of $M$, then $H_{k}^{F}>0$ holds on every point of $M$ for every $k=1, \ldots, r$.

Using the characteristic polynomial of $S_{F}, \sigma_{r}$ is defined by

$$
\begin{equation*}
\operatorname{det}\left(t I-S_{F}\right)=\sum_{r=0}^{n}(-1)^{r} \sigma_{r} t^{n-r} \tag{2.22}
\end{equation*}
$$

So, we have

$$
\begin{equation*}
\sigma_{r}=\frac{1}{r!} \sum_{i_{1}, \ldots, i_{r} ; j_{1}, \ldots, j_{r}} \delta_{i_{1} \cdots i_{r}}^{j_{1} \cdots j_{r}} s_{i_{1} j_{1}} \cdots s_{i_{r} j_{r}} \tag{2.23}
\end{equation*}
$$

where $\delta_{i_{1} \cdots i_{r}}^{j_{1} \cdots j_{r}}$ is the usual generalized Kronecker symbol, i.e., $\delta_{i_{1} \cdots i_{r}}^{j_{1} \cdots j_{r}}$ equals +1 (resp. -1 ) if $i_{1} \cdots i_{r}$ are distinct and $\left(j_{1} \cdots j_{r}\right)$ is an even (resp. odd) permutation of $\left(i_{1} \cdots i_{r}\right)$ and in other cases it equals zero.

We introduce two important operators $P_{r}$ and $T_{r}$ by

$$
\begin{align*}
& P_{r}=\sigma_{r} I-\sigma_{r-1} S_{F}+\cdots+(-1)^{r} S_{F}^{r}, \quad r=0,1, \ldots, n  \tag{2.24}\\
& T_{r}=P_{r} A_{F}, \quad r=0,1, \ldots, n-1 \tag{2.25}
\end{align*}
$$

Obviously, $P_{n}=0$ and we have

$$
\begin{equation*}
P_{r}=\sigma_{r} I-P_{r-1} S_{F}=\sigma_{r} I+T_{r-1} \mathrm{~d} \nu, \quad r=1, \ldots, n \tag{2.26}
\end{equation*}
$$

From the symmetry of $A_{F}$ and $\mathrm{d} \nu, S_{F} A_{F}$ and $\mathrm{d} \nu \circ S_{F}$ are symmetric, so $T_{r}=P_{r} A_{F}$ and $\mathrm{d} \nu \circ P_{r}$ are also symmetric for each $r$.

Lemma 2.3. The matrix of $P_{r}$ is given by:

$$
\begin{equation*}
\left(P_{r}\right)_{i j}=\frac{1}{r!} \sum_{i_{1}, \ldots, i_{r} ; j_{1}, \ldots, j_{r}} \delta_{i_{1} \cdots i_{r} j}^{j_{1} \cdots j_{r} i} s_{i_{1} j_{1}} \cdots s_{i_{r} j_{r}} . \tag{2.27}
\end{equation*}
$$

Proof. We prove Lemma 2.3 inductively. For $r=0$, it is easy to check that (2.27) is true.

Assume (2.27) is true for $r=k$, then from (2.26),

$$
\begin{aligned}
\left(P_{k+1}\right)_{i j}= & \sigma_{k+1} \delta_{j}^{i}-\sum_{l}\left(P_{k}\right)_{i l} s_{l j} \\
= & \frac{1}{(k+1)!} \sum\left(\delta_{i_{1} \cdots i_{k+1}}^{j_{1} \cdots j_{k+1}} \delta_{j}^{i}-\sum_{l} \delta_{i_{1} \cdots i_{l-1} i_{l} i_{l+1} \cdots i_{k+1}}^{j_{1} \cdots j_{l-1} i j_{l+1} \cdots j_{k+1}} \delta_{j}^{j_{l}}\right) \\
& \times s_{i_{1} j_{1} \cdots} \cdots s_{i_{k+1} j_{k+1}} \\
= & \frac{1}{(k+1)!} \sum \delta_{i_{1} \cdots i_{k+1} j}^{j_{1} \cdots j_{k+1} i} s_{i_{1} j_{1}} \cdots s_{i_{k+1} j_{k+1}} .
\end{aligned}
$$

Lemma 2.4. For each $r$, we have
(i) $\sum_{j}\left(P_{r}\right)_{j i j}=0$,
(ii) $\operatorname{tr}\left(P_{r} S_{F}\right)=(r+1) \sigma_{r+1}$,
(iii) $\operatorname{tr}\left(P_{r}\right)=(n-r) \sigma_{r}$,
(iv) $\operatorname{tr}\left(P_{r} S_{F}^{2}\right)=\sigma_{1} \sigma_{r+1}-(r+2) \sigma_{r+2}$.

Proof. We only prove (i), the others are easily obtained from (2.23), (2.26), and (2.27).

Noting $s_{i_{1} j_{1}} \cdots s_{i_{r} j_{r} j}=s_{i_{1} j_{1}} \cdots s_{i_{r} j j_{r}}$ by (2.16) and $\delta_{i_{1} \cdots i_{r} i}^{j_{1} \cdots j_{r} j}=-\delta_{i_{1} \cdots i_{r} i}^{j_{1} \cdots j j_{r}}$, we have

$$
\sum_{j}\left(P_{r}\right)_{j i j}=\frac{1}{(r-1)!} \sum_{i_{1}, \ldots, i_{r} ; j_{1}, \ldots, j_{r} ; j} \delta_{i_{1} \cdots i_{r} i}^{j_{1} \cdots j_{r} j} s_{i_{1} j_{1}} \cdots s_{i_{r} j_{r} j}=0
$$

Remark 2.5. When $F=1$, Lemma 2.4 was a well-known result (for example, see Barbosa-Colares [2], Reilly [15], or Rosenberg [17]).

Since $P_{r-1} S_{F}$ is symmetric and $L_{i j}$ is anti-symmetric, we have

$$
\begin{equation*}
\sum_{i, j, k}\left(P_{r-1}\right)_{j i}\left(s_{k j} L_{k i}+s_{i k} L_{k j}\right)=0 . \tag{2.28}
\end{equation*}
$$

From (2.16), (2.26), and (i) of Lemma 2.4, we get

$$
\begin{align*}
\left(\sigma_{r}\right)_{k} & =\sum_{j}\left(\sigma_{r} \delta_{j k}\right)_{j}=\sum_{j}\left(P_{r}\right)_{j k j}+\sum_{j, l}\left[\left(P_{r-1}\right)_{j l} s_{l k}\right]_{j}  \tag{2.29}\\
& =\sum_{i, j}\left(P_{r-1}\right)_{j i} s_{i j k} .
\end{align*}
$$

## 3. First and second variation formulas of $\mathscr{F}_{r, F ; \Lambda}$

Define the operator $L_{r}: C^{\infty}(M) \rightarrow C^{\infty}(M)$ as follows:

$$
\begin{equation*}
L_{r} f=\sum_{i, j}\left[\left(T_{r}\right)_{i j} f_{j}\right]_{i} \tag{3.1}
\end{equation*}
$$

Lemma 3.1.

$$
\frac{\mathrm{d} \sigma_{r}}{\mathrm{~d} t}=\sigma_{r}^{\prime}(t)=L_{r-1} \psi+\psi\left\langle T_{r-1} \circ \mathrm{~d} \nu_{t}, \mathrm{~d} \nu_{t}\right\rangle+\left\langle\operatorname{grad} \sigma_{r}, \xi\right\rangle
$$

Proof. Using (2.23), (2.28), (2.29), Lemma 2.1, Lemma 2.3, and (i) of Lemma 2.4, we have

$$
\begin{aligned}
\sigma_{r}^{\prime} & =\frac{1}{(r-1)!} \sum_{i_{1}, \ldots, i_{r} ; j_{1}, \ldots, j_{r}} \delta_{i_{1} \cdots i_{r}}^{j_{1} \cdots j_{r}} s_{i_{1} j_{1}} \cdots s_{i_{r-1} j_{r-1}} s_{i_{r} j_{r}}^{\prime} \\
& =\sum_{i, j}\left(P_{r-1}\right)_{j i} s_{i j}^{\prime} \\
& =\sum_{i, j, k}\left(P_{r-1}\right)_{j i}\left[\left(A_{i k} \psi_{k}\right)_{j}+\psi s_{i k} h_{k j}+s_{i j k} \xi_{k}+s_{k j} L_{k i}+s_{i k} L_{k j}\right] \\
& =\sum_{i, j, k}\left[\left(P_{r-1}\right)_{j i} A_{i k} \psi_{k}\right]_{j}+\psi \sum_{i, j, k, l}\left(P_{r-1}\right)_{j i} A_{i l} h_{l k} h_{k j}+\sum_{k}\left(\sigma_{r}\right)_{k} \xi_{k} \\
& =\sum_{j, k}\left[\left(T_{r-1}\right)_{j k} \psi_{k}\right]_{j}+\psi \sum_{i, j, k}\left(T_{r-1}\right)_{j i} h_{i k} h_{k j}+\sum_{k}\left(\sigma_{r}\right)_{k} \xi_{k} \\
& =L_{r-1} \psi+\psi\left\langle T_{r-1} \circ \mathrm{~d} \nu_{t}, \mathrm{~d} \nu_{t}\right\rangle+\left\langle\operatorname{grad} \sigma_{r}, \xi\right\rangle .
\end{aligned}
$$

Lemma 3.2. For each $0 \leq r \leq n$, we have

$$
\begin{equation*}
\operatorname{div}\left(P_{r}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu_{t}\right)+F\left(\nu_{t}\right) \operatorname{tr}\left(P_{r} \circ \mathrm{~d} \nu_{t}\right)=-(r+1) \sigma_{r+1} \tag{3.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{div}\left(P_{r} X^{\top}\right)+\left\langle X, \nu_{t}\right\rangle \operatorname{tr}\left(P_{r} \circ \mathrm{~d} \nu_{t}\right)=(n-r) \sigma_{r} . \tag{3.3}
\end{equation*}
$$

Proof. From (2.6), (2.15), and Lemma 2.4,

$$
\begin{aligned}
\operatorname{div}\left(P_{r}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu_{t}\right) & =\operatorname{div}\left(P_{r}\left(\phi \circ \nu_{t}\right)^{\top}\right) \\
& =\sum_{i, j}\left(\left(P_{r}\right)_{j i}\left\langle\phi \circ \nu_{t}, e_{i}\right\rangle\right)_{j}
\end{aligned}
$$

$$
\begin{aligned}
& =-\sum_{i, j}\left(P_{r}\right)_{j i} s_{i j}+F\left(\nu_{t}\right) \sum_{i, j}\left(P_{r}\right)_{j i} h_{i j} \\
& =-\operatorname{tr}\left(P_{r} S_{F}\right)-F\left(\nu_{t}\right) \operatorname{tr}\left(P_{r} \circ \mathrm{~d} \nu_{t}\right) \\
& =-(r+1) \sigma_{r+1}-F\left(\nu_{t}\right) \operatorname{tr}\left(P_{r} \circ \mathrm{~d} \nu_{t}\right), \\
\operatorname{div}\left(P_{r} X^{\top}\right) & =\sum_{i, j}\left(\left(P_{r}\right)_{j i}\left\langle X, e_{i}\right\rangle\right)_{j} \\
& =\sum_{i, j}\left(P_{r}\right)_{j i} \delta_{i j}+\sum_{i, j}\left(P_{r}\right)_{j i} h_{i j}\left\langle X, \nu_{t}\right\rangle \\
& =\operatorname{tr}\left(P_{r}\right)-\operatorname{tr}\left(P_{r} \circ \mathrm{~d} \nu_{t}\right)\left\langle X, \nu_{t}\right\rangle \\
& =(n-r) \sigma_{r}-\operatorname{tr}\left(P_{r} \circ \mathrm{~d} \nu_{t}\right)\left\langle X, \nu_{t}\right\rangle .
\end{aligned}
$$

Thus, the conclusion follows.
TheOrem 3.3 (First variational formula of $\mathscr{A}_{r, F}$ ).

$$
\begin{equation*}
\mathscr{A}_{r, F}^{\prime}(t)=-(r+1) \int_{M} \psi \sigma_{r+1} \mathrm{~d} A_{X_{t}} \tag{3.4}
\end{equation*}
$$

Proof. We have $\left(F\left(\nu_{t}\right)\right)^{\prime}=\left\langle\operatorname{grad}_{S^{n}} F, \nu_{t}^{\prime}\right\rangle$, so by use of Lemma 3.1, Lemma 3.2, (2.2), (2.3), (2.8), (2.26), and Stokes formula, we have

$$
\begin{aligned}
\mathscr{A}_{r, F}^{\prime}(t)= & \int_{M}\left(F\left(\nu_{t}\right) \sigma_{r}^{\prime}+\left(F\left(\nu_{t}\right)\right)^{\prime} \sigma_{r}\right) \mathrm{d} A_{X_{t}}+F\left(\nu_{t}\right) \sigma_{r} \partial_{t} \mathrm{~d} A_{X_{t}} \\
= & \int_{M}\left\{F\left(\nu_{t}\right) \operatorname{div}\left(T_{r-1} \operatorname{grad} \psi\right)+F\left(\nu_{t}\right) \psi\left\langle T_{r-1} \circ \mathrm{~d} \nu_{t}, \mathrm{~d} \nu_{t}\right\rangle\right. \\
& +F\left(\nu_{t}\right)\left\langle\operatorname{grad} \sigma_{r}, \xi\right\rangle+\left\langle\sigma_{r}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu_{t},-\operatorname{grad} \psi+\mathrm{d} \nu_{t}(\xi)\right\rangle \\
& \left.+F\left(\nu_{t}\right) \sigma_{r}(-n H \psi+\operatorname{div} \xi)\right\} \mathrm{d} A_{X_{t}} \\
= & \int_{M}\left\{-\left\langle\operatorname{grad}\left(F\left(\nu_{t}\right)\right), T_{r-1} \operatorname{grad} \psi\right\rangle+F\left(\nu_{t}\right) \psi\left\langle T_{r-1} \circ \mathrm{~d} \nu_{t}, \mathrm{~d} \nu_{t}\right\rangle\right. \\
& +\left\langle F\left(\nu_{t}\right) \operatorname{grad} \sigma_{r}, \xi\right\rangle+\psi \operatorname{div}\left(\sigma_{r}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu_{t}\right) \\
& \left.+\left\langle\sigma_{r} \operatorname{grad}\left(F\left(\nu_{t}\right)\right), \xi\right\rangle-n H \psi F\left(\nu_{t}\right) \sigma_{r}+F\left(\nu_{t}\right) \sigma_{r} \operatorname{div} \xi\right\} \mathrm{d} A_{X_{t}} \\
= & \int_{M}\left\{-\left\langle T_{r-1} \operatorname{grad}\left(F\left(\nu_{t}\right)\right), \operatorname{grad} \psi\right\rangle+F\left(\nu_{t}\right) \psi\left\langle T_{r-1} \circ \mathrm{~d} \nu_{t}, \mathrm{~d} \nu_{t}\right\rangle\right. \\
& \left.+\psi \operatorname{div}\left(\sigma_{r}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu_{t}\right)-n H \psi F\left(\nu_{t}\right) \sigma_{r}\right\} \mathrm{d} A_{X_{t}} \\
= & \int_{M} \psi\left\{\operatorname{div}\left(\sigma_{r}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu_{t}\right)+\operatorname{div}\left(T_{r-1} \operatorname{grad}\left(F\left(\nu_{t}\right)\right)\right)\right. \\
& \left.+F\left(\nu_{t}\right)\left\langle T_{r-1} \circ \mathrm{~d} \nu_{t}, \mathrm{~d} \nu_{t}\right\rangle-n H F\left(\nu_{t}\right) \sigma_{r}\right\} \mathrm{d} A_{X_{t}} \\
= & \int_{M} \psi\left\{\operatorname{div}\left[\left(\sigma_{r}+T_{r-1} \circ \mathrm{~d} \nu_{t}\right)\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu_{t}\right]\right. \\
& \left.+F\left(\nu_{t}\right) \operatorname{tr}\left[\left(T_{r-1} \circ \mathrm{~d} \nu_{t}+\sigma_{r} I\right) \circ \mathrm{d} \nu_{t}\right]\right\} \mathrm{d} A_{X_{t}}
\end{aligned}
$$

$$
\begin{aligned}
& =\int_{M} \psi\left\{\operatorname{div}\left(P_{r}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu_{t}\right)+F\left(\nu_{t}\right) \operatorname{tr}\left(P_{r} \circ \mathrm{~d} \nu_{t}\right)\right\} \mathrm{d} A_{X_{t}} \\
& =-(r+1) \int_{M} \psi \sigma_{r+1} \mathrm{~d} A_{X_{t}} .
\end{aligned}
$$

Remark 3.4. When $F=1$, Lemma 4.1 and Theorem 3.3 were proved by R. Reilly [15] (also see [2], [3]).

From (1.6), (2.4), and (3.4), we get
Proposition 3.5 (The first variational formula). For all variations of $X$, we have

$$
\begin{equation*}
\mathscr{F}_{r, F ; \Lambda}^{\prime}(t)=-\int_{M} \psi\left\{(r+1) \sigma_{r+1}-\Lambda\right\} \mathrm{d} A_{X_{t}} \tag{3.5}
\end{equation*}
$$

Hence, we obtain the Euler-Lagrange equation of $\mathscr{F}_{r, F ; \Lambda}$ :

$$
\begin{equation*}
(r+1) \sigma_{r+1}-\Lambda=0 \tag{3.6}
\end{equation*}
$$

THEOREM 3.6 (The second variational formula). Let $X: M \rightarrow R^{n+1}$ be an $n$-dimensional closed hypersurface, which satisfies (3.6), then for all variations of $X$ preserving $V$, the second variational formula of $\mathscr{A}_{r, F}$ at $t=0$ is given by

$$
\begin{equation*}
\mathscr{A}_{r}^{\prime \prime}(0)=\mathscr{F}_{r, F ; \Lambda}^{\prime \prime}(0)=-(r+1) \int_{M} \psi\left\{L_{r} \psi+\psi\left\langle T_{r} \circ \mathrm{~d} \nu, \mathrm{~d} \nu\right\rangle\right\} \mathrm{d} A_{X} \tag{3.7}
\end{equation*}
$$

where $\psi$ satisfies

$$
\begin{equation*}
\int_{M} \psi \mathrm{~d} A_{X}=0 \tag{3.8}
\end{equation*}
$$

Proof. Differentiating (3.5), we get (3.7) by use of (3.6) and Lemma 3.1.
We call $X: M \rightarrow R^{n+1}$ to be a stable critical point of $\mathscr{A}_{r, F}$ for all variations of $X$ preserving $V$, if it satisfies (3.6) and $\mathscr{A}_{r}^{\prime \prime}(0) \geq 0$ for all $\psi$ with condition (3.8).

## 4. Proof of Theorem 1.3

Firstly, we prove that if $X(M)$ is, up to translations and homotheties, the Wulff shape, then $X$ is stable.

From $\mathrm{d} \phi=\left(D^{2} F+F 1\right) \circ \mathrm{d} x, \mathrm{~d} \phi$ is perpendicular to $x$. So $\nu=-x$ is the unit inner normal vector. We have

$$
\begin{equation*}
\mathrm{d} \phi=-A_{F} \circ \mathrm{~d} \nu=\sum_{i j k} A_{j k} h_{k i} \omega_{i} e_{j} . \tag{4.1}
\end{equation*}
$$

On the other hand,

$$
\begin{equation*}
\mathrm{d} \phi=\sum_{i} \omega_{i} e_{i} \tag{4.2}
\end{equation*}
$$

so we have

$$
\begin{equation*}
s_{i j}=\sum_{k} A_{i k} h_{k j}=\delta_{i j} \tag{4.3}
\end{equation*}
$$

From this, we easily get $\sigma_{r}=C_{n}^{r}$ and $\sigma_{r+1}=C_{n}^{r+1}$, thus, the Wulff shape satisfies (3.6) with $\Lambda=(r+1) C_{n}^{r+1}$. Through a direct calculation, we easily know for Wulff shape,

$$
\begin{equation*}
\mathscr{A}_{r}^{\prime \prime}(0)=-(r+1) C_{n-1}^{r} \int_{M}\left[\operatorname{div}\left(A_{F} \operatorname{grad} \psi\right)+\psi\left\langle A_{F} \circ \mathrm{~d} \nu, \mathrm{~d} \nu\right\rangle\right] \mathrm{d} A_{X} \tag{4.4}
\end{equation*}
$$

and $\psi$ satisfies

$$
\begin{equation*}
\int_{M} \psi \mathrm{~d} A_{X}=0 \tag{4.5}
\end{equation*}
$$

From Palmer [14] (also see Winklmann [19]), we know $\mathscr{A}_{r}^{\prime \prime}(0) \geq 0$, that is the Wulff shape is stable.

Next, we prove that if $X$ is stable, then up to translations and homotheties, $X(M)$ is the Wulff shape. We recall the following lemmas.

Lemma 4.1 ([7], [8]). For each $r=0,1, \ldots, n-1$, the following integral formulas of Minkowski type hold:

$$
\begin{equation*}
\int_{M}\left(H_{r}^{F} F(\nu)+H_{r+1}^{F}\langle X, \nu\rangle\right) \mathrm{d} A_{X}=0, \quad r=0,1, \ldots, n-1 \tag{4.6}
\end{equation*}
$$

Lemma 4.2 ([7], [8], [14]). If $\lambda_{1}=\lambda_{2}=\cdots=\lambda_{n}=$ const $\neq 0$, then up to translations and homotheties, $X(M)$ is the Wulff shape.

From Lemmas 4.1 and (3.8), we can choose $\psi=\alpha F(\nu)+H_{r+1}^{F}\langle X, \nu\rangle$ as the test function, where $\alpha=\int_{M} F(\nu) H_{r}^{F} \mathrm{~d} A_{X} / \int_{M} F(\nu) \mathrm{d} A_{X}$. For every smooth function $f: M \rightarrow \mathbb{R}$, and each $r$, we define:

$$
\begin{equation*}
I_{r}[f]=L_{r} f+f\left\langle T_{r} \circ \mathrm{~d} \nu, \mathrm{~d} \nu\right\rangle \tag{4.7}
\end{equation*}
$$

Then we have from (3.7)

$$
\begin{equation*}
\mathscr{A}_{r}^{\prime \prime}(0)=-(r+1) \int_{M} \psi I_{r}[\psi] \mathrm{d} A_{X} . \tag{4.8}
\end{equation*}
$$

Lemma 4.3. For each $0 \leq r \leq n-1$, we have

$$
\begin{equation*}
I_{r}[F \circ \nu]=-\left\langle\operatorname{grad} \sigma_{r+1},\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu\right\rangle+\sigma_{1} \sigma_{r+1}-(r+2) \sigma_{r+2} \tag{4.9}
\end{equation*}
$$

and

$$
\begin{equation*}
I_{r}[\langle X, \nu\rangle]=-\left\langle\operatorname{grad} \sigma_{r+1}, X^{\top}\right\rangle-(r+1) \sigma_{r+1} \tag{4.10}
\end{equation*}
$$

Proof. From (2.8) and (2.26),

$$
\begin{aligned}
I_{r}[F \circ \nu] & =\operatorname{div}\left\{T_{r} \operatorname{grad}(F(\nu))\right\}+F(\nu)\left\langle T_{r} \circ \mathrm{~d} \nu, \mathrm{~d} \nu\right\rangle \\
& =\operatorname{div}\left(T_{r} \circ \mathrm{~d} \nu\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu\right)+F(\nu)\left\langle T_{r} \circ \mathrm{~d} \nu, \mathrm{~d} \nu\right\rangle \\
& =\operatorname{div}\left(P_{r+1}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu\right)+F(\nu) \operatorname{tr}\left(P_{r+1} \mathrm{~d} \nu\right)
\end{aligned}
$$

$$
\begin{aligned}
& -\left\langle\operatorname{grad} \sigma_{r+1},\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu\right\rangle \\
& -\sigma_{r+1}\left\{\operatorname{div}\left(P_{0}\left(\operatorname{grad}_{S^{n}} F\right) \circ \nu\right)+F(\nu) \operatorname{tr}\left(P_{0} \mathrm{~d} \nu\right)\right\}, \\
I_{r}[\langle X, \nu\rangle]= & \operatorname{div}\left(T_{r} \operatorname{grad}\langle X, \nu\rangle\right)+\langle X, \nu\rangle\left\langle T_{r} \circ \mathrm{~d} \nu, \mathrm{~d} \nu\right\rangle \\
= & \operatorname{div}\left(T_{r} \circ \mathrm{~d} \nu X^{\top}\right)+\langle X, \nu\rangle\left\langle T_{r} \circ \mathrm{~d} \nu, \mathrm{~d} \nu\right\rangle \\
= & \operatorname{div}\left(P_{r+1} X^{\top}\right)+\langle X, \nu\rangle \operatorname{tr}\left(P_{r+1} \mathrm{~d} \nu\right)-\left\langle\operatorname{grad} \sigma_{r+1}, X^{\top}\right\rangle \\
& -\sigma_{r+1}\left\{\operatorname{div}\left(P_{0} X^{\top}\right)+\langle X, \nu\rangle \operatorname{tr}\left(P_{0} \mathrm{~d} \nu\right)\right\} .
\end{aligned}
$$

So the conclusions follow from Lemma 3.2.
As $H_{r+1}^{F}$ is a constant, from (4.9) and (4.10), we have

$$
\begin{align*}
I_{r}[\psi] & =\alpha I_{r}[F \circ \nu]+H_{r+1}^{F} I_{r}[\langle X, \nu\rangle]  \tag{4.11}\\
& =\alpha\left(\sigma_{1} \sigma_{r+1}-(r+2) \sigma_{r+2}\right)-(r+1) H_{r+1}^{F} \sigma_{r+1} \\
& =C_{n}^{r+1}\left\{\alpha\left[n H_{1}^{F} H_{r+1}^{F}-(n-r-1) H_{r+2}^{F}\right]-(r+1)\left(H_{r+1}^{F}\right)^{2}\right\}
\end{align*}
$$

Therefore, we obtain from Lemma 4.1 (recall $H_{r+1}^{F}$ is constant and $\int_{M} \psi \mathrm{~d} A_{X}=$ $0)$

$$
\begin{aligned}
\frac{1}{r+1} & \mathscr{A}_{r}^{\prime \prime}(0) \\
= & -\int_{M} \psi I_{r}[\psi] \mathrm{d} A_{X} \\
= & -\int_{M} \psi C_{n}^{r+1}\left\{\alpha\left[n H_{1}^{F} H_{r+1}^{F}-(n-r-1) H_{r+2}^{F}\right]-(r+1)\left(H_{r+1}^{F}\right)^{2}\right\} \mathrm{d} A_{X} \\
= & -\alpha C_{n}^{r+1} \int_{M}\left[\alpha F(\nu)+H_{r+1}^{F}\langle X, \nu\rangle\right]\left[n H_{1}^{F} H_{r+1}^{F}-(n-r-1) H_{r+2}^{F}\right] \mathrm{d} A_{X} \\
= & -\alpha^{2} C_{n}^{r+1} \int_{M} F(\nu)\left[n H_{1}^{F} H_{r+1}^{F}-(n-r-1) H_{r+2}^{F}\right] \mathrm{d} A_{X} \\
& -\alpha C_{n}^{r+1} H_{r+1}^{F} \int_{M}\langle X, \nu\rangle\left[n H_{1}^{F} H_{r+1}^{F}-(n-r-1) H_{r+2}^{F}\right] \mathrm{d} A_{X} \\
= & -\alpha^{2} C_{n}^{r+1} \int_{M} F(\nu)\left[n H_{1}^{F} H_{r+1}^{F}-(n-r-1) H_{r+2}^{F}\right] \mathrm{d} A_{X} \\
& +\alpha C_{n}^{r+1} H_{r+1}^{F} \int_{M} F(\nu)\left[n H_{r+1}^{F}-(n-r-1) H_{r+1}^{F}\right] \mathrm{d} A_{X} \\
= & -\alpha^{2}(n-r-1) C_{n}^{r+1} \int_{M} F(\nu)\left(H_{1}^{F} H_{r+1}^{F}-H_{r+2}^{F}\right) \mathrm{d} A_{X} \\
& -\frac{\alpha(r+1) C_{n}^{r+1}\left(H_{r+1}^{F}\right)^{2}}{\int_{M} F(\nu) \mathrm{d} A_{X}} \\
& \times\left\{\int_{M} F(\nu) H_{1}^{F} \mathrm{~d} A_{X} \int_{M} F(\nu) \frac{H_{r}^{F}}{H_{r+1}^{F}} \mathrm{~d} A_{X}-\left(\int_{M} F(\nu) \mathrm{d} A_{X}\right)^{2}\right\}
\end{aligned}
$$

where we used $\alpha=\int_{M} F(\nu) H_{r}^{F} \mathrm{~d} A_{X} / \int_{M} F(\nu) \mathrm{d} A_{X}$ in the last equality of the above formula.

As $H_{r+1}^{F}$ is a constant, it must be positive by the compactness of $M$. Thus, by Lemma 2.2, $H_{1}^{F}, \ldots, H_{r}^{F}$ are all positive. So, from [6] or [20], we have:
(i) for each $0 \leq r<n-1$,

$$
\begin{equation*}
H_{1}^{F} H_{r+1}^{F}-H_{r+2}^{F} \geq 0 \tag{4.12}
\end{equation*}
$$

with the equality holds if and only if $\lambda_{1}=\cdots=\lambda_{n}$, and
(ii) for each $1 \leq r \leq n-1$,

$$
\begin{align*}
& \int_{M} F(\nu) H_{1}^{F} \mathrm{~d} A_{X} \int_{M} F(\nu) \frac{H_{r}^{F}}{H_{r+1}^{F}} \mathrm{~d} A_{X}-\left(\int_{M} F(\nu) \mathrm{d} A_{X}\right)^{2}  \tag{4.13}\\
& \quad \geq \int_{M} F(\nu) H_{1}^{F} \mathrm{~d} A_{X} \int_{M} F(\nu) / H_{1}^{F} \mathrm{~d} A_{X}-\left(\int_{M} F(\nu) \mathrm{d} A_{X}\right)^{2} \\
& \quad \geq 0
\end{align*}
$$

with the equality holds if and only if $\lambda_{1}=\cdots=\lambda_{n}$.
From (4.12) and (4.13), we easily obtain that, for each $0 \leq r \leq n-1$,

$$
\mathscr{A}_{r}^{\prime \prime}(0) \leq 0
$$

with the equality holds if and only if $\lambda_{1}=\cdots=\lambda_{n}$. Thus, from Lemma 4.2, up to translations and homotheties, $X(M)$ is the Wulff shape. We complete the proof of Theorem 1.3.

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