# Existence results for degenerate quasilinear elliptic equations in weighted Sobolev spaces 

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#### Abstract

In this paper we are interested in the existence of solutions for Dirichlet problem associated to the degenerate quasilinear elliptic equations $$
-\operatorname{div}[v(x) \mathcal{A}(x, u, \nabla u)]+\omega(x) \mathcal{A}_{0}(x, u(x))=f_{0}-\sum_{j=1}^{n} D_{j} f_{j}, \text { on } \Omega
$$


in the setting of the weighted Sobolev spaces $\mathrm{W}_{0}^{1, p}(\Omega, \omega, v)$.

## 1 Introduction

In this paper we prove the existence of (weak) solutions in the weighted Sobolev spaces $W_{0}^{1, p}(\Omega, \omega, v)$ (see Definition 2.3) for the Dirichlet problem

$$
\text { (P) }\left\{\begin{array}{l}
L u(x)=f_{0}(x)-\sum_{j=1}^{n} D_{j} f_{j}(x), \text { on } \Omega \\
u(x)=0, \text { on } \partial \Omega
\end{array}\right.
$$

where $L$ is the partial differential operator

$$
\begin{equation*}
L u(x)=-\sum_{j=1}^{n} D_{j}\left[v(x) \mathcal{A}_{j}(x, u(x), \nabla u(x))\right]+\omega(x) \mathcal{A}_{0}(x, u(x)) \tag{1.1}
\end{equation*}
$$

[^0]where $D_{j}=\partial / \partial x_{j}, \Omega$ is a bounded open set in $\mathbb{R}^{n}, \omega$ and $v$ are weight functions (i.e., locally integrable non-negative functions on $\mathbb{R}^{n}$ ), and the functions $\mathcal{A}_{j}: \Omega \times \mathbb{R} \times \mathbb{R}^{n} \rightarrow \mathbb{R}(j=1, \ldots, n)$ (with $\mathcal{A}(x, \eta, \xi)=\left(\mathcal{A}_{1}(x, \eta, \xi), \ldots, \mathcal{A}_{n}(x, \eta, \xi)\right)$ ) and $\mathcal{A}_{0}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ satisfy the following conditions:
(H1) $x \mapsto \mathcal{A}_{j}(x, \eta, \xi)$ is measurable in $\Omega$ for all $(\eta, \xi) \in \mathbb{R} \times \mathbb{R}^{n}(j=1,2 \ldots, n)$ $(\eta, \xi) \mapsto \mathcal{A}_{j}(x, \eta, \xi)$ is continuous in $\mathbb{R} \times \mathbb{R}^{n}$ for almost all $x \in \Omega$, and
$x \mapsto \mathcal{A}_{0}(x, \eta)$ is measurable in $\Omega$ for all $\eta \in \mathbb{R}$
$\eta \mapsto \mathcal{A}_{0}(x, \eta)$ is continuous in $\mathbb{R}$ for almost all $x \in \Omega$.
(H2) There are $\lambda>0$ and functions $h_{0}, h_{1}, h_{2}, \tilde{h}_{1}$ and $\tilde{h}_{2}$, with $h_{0} \in L^{p^{\prime}}(\Omega, v)$, $h_{2} \in L^{1}(\Omega, v), h_{1} v / \omega \in L^{p^{\prime}}(\Omega, \omega), \tilde{h}_{1} \in L^{p^{\prime}}(\Omega, \omega)$ and $\tilde{h}_{2} \in L^{1}(\Omega, \omega)$ such that
$$
\mathcal{A}(x, \eta, \xi) \cdot \xi \geq \lambda|\xi|^{p}-h_{0}(x)|\xi|-h_{1}(x)|\eta|-h_{2}(x)
$$
(where $\mathcal{A}(x, \eta, \xi) \cdot \xi$ denotes the usual inner product in $\mathbb{R}^{n}$ ) and
$$
\mathcal{A}_{0}(x, \eta) \eta \geq \lambda|\eta|^{p}-\tilde{h}_{1}(x)|\eta|-\tilde{h}_{2}(x)
$$
with $1<p<\infty$, and we denote by $p^{\prime}$ the real number such that $1 / p+1 / p^{\prime}=1$ (that is , $p^{\prime}$ is the conjugate exponent to $p$ ).
(H3) There are positive functions $K_{1}, K_{2}, h_{3}, h_{4}, \tilde{h}_{3}$ and $\tilde{h}_{4}$, with $h_{3}, \tilde{h}_{3}, h_{4}$ and $\tilde{h}_{4} \in L^{\infty}(\Omega), K_{1} \in L^{p^{\prime}}(\Omega, v)$ and $K_{2} \in L^{p^{\prime}}(\Omega, \omega)$ such that
\[

$$
\begin{aligned}
& |\mathcal{A}(x, \eta, \xi)| \leq K_{1}(x)+h_{3}(x)|\eta|^{\theta(p-1)}+h_{4}(x)|\xi|^{p-1}, \\
& \left|\mathcal{A}_{0}(x, \eta)\right| \leq K_{2}(x)+\tilde{h}_{3}(x)|\eta|^{p-1},
\end{aligned}
$$
\]

where $\theta$ as in Theorem 2.6.
(H4) For $(\eta, \xi),\left(\eta^{\prime}, \xi^{\prime}\right) \in \mathbb{R} \times \mathbb{R}^{n}$ and $x \in \Omega$, the function

$$
t \mapsto v(x) \mathcal{A}\left(x, \eta^{\prime}+t \eta, \xi^{\prime}+t \xi\right) \cdot \xi+\omega(x) \mathcal{A}_{0}\left(x, \eta^{\prime}+t \eta\right) \eta
$$

is monotone increasing as a function of $t \in[0,1]$.
Remark 1.1 Note that the condition (H4) holds if

$$
\left[\mathcal{A}(x, \eta, \xi)-\mathcal{A}\left(x, \eta^{\prime}, \xi^{\prime}\right)\right] \cdot\left(\xi-\xi^{\prime}\right) \geq 0 \text { and }\left(\mathcal{A}_{0}(x, \eta)-\mathcal{A}_{0}\left(x, \eta^{\prime}\right)\right)\left(\eta-\eta^{\prime}\right) \geq 0
$$

whenever $\xi, \xi^{\prime} \in \mathbb{R}^{n}, \xi \neq \xi^{\prime}, \eta, \eta^{\prime} \in \mathbb{R}, \eta \neq \eta^{\prime}$ (see Proposition 25.6 in [17]).
By a weight, we shall mean a locally integrable function $v$ on $\mathbb{R}^{n}$ such that $v(x)>0$ for a.e. $x \in \mathbb{R}^{n}$. Every weight $v$ gives rise to a measure on the measurable subsets on $\mathbb{R}^{n}$ through integration. This measure will also be denoted by $v$. Thus, $v(E)=\int_{E} v(x) d x$ for measurable sets $E \subset \mathbb{R}^{n}$.

In general, the Sobolev spaces $\mathrm{W}^{k, p}(\Omega)$ without weights occur as spaces of solutions for elliptic and parabolic partial differential equations. For degenerate partial differential equations, i.e., equations with various types of singularities in
the coefficients, it is natural to look for solutions in weighted Sobolev spaces (see [5], [6],[7] and [10]).

A class of weights, which is particularly well understood, is the class of $A_{p^{-}}$ weights (or Muckenhoupt class) that was introduced by B. Muckenhoupt (see [13]). These classes have found many useful applications in harmonic analysis (see [14]). Another reason for studying $A_{p}$-weights is the fact that powers of distance to submanifolds of $\mathbb{R}^{n}$ often belong to $A_{p}$ (see [11]). There are, in fact, many interesting examples of weights (see [10] for $p$-admissible weights).

Equations like (1.1) have been studied by many authors in the non-degenerate case (i.e. with $\omega(x)=v(x) \equiv 1$ ) (see e.g. [4] and the references therein).

The degenerate case with different conditions have been studied by many authors. In [2] Drábek, Kufner and Mustonen proved that under certain condition the Dirichlet problem associated with the equation $-\operatorname{div}(a(x, u, \nabla u)=h$, $h \in\left[W_{0}^{1,2}(\Omega, \omega)\right]^{*}$, has at least one solution $u$ in $W_{0}^{1, p}(\Omega, \omega)$. See also [16].

The purpose in this paper, is to prove the same results for the degenerate nonlinear elliptic equations

$$
-\operatorname{div}\left(v(x) \mathcal{A}(x, u(x), \nabla u(x))+\omega(x) \mathcal{A}_{0}(x, u(x))=f_{0}(x)-\sum_{j=1}^{n} D_{j} f_{j}(x)\right.
$$

When $\omega=v \equiv 1$ (the non weighted case) existence results for problem $(P)$ have been shown in [1].

The main result of this article is given in the next theorem, which is proved in the section 3 .

Theorem 1.2 Assume that conditions (H1)-(H4) hold. Let $\omega$ and $v$ be weights. If $v \leq \omega$, $\omega \in A_{p}, v \in A_{p}, 1<p<\infty, f_{0} / \omega \in L^{p^{\prime}}(\Omega, \omega)$ and $f_{j} / v \in L^{p^{\prime}}(\Omega, v)(j=1, \ldots, n)$, then problem ( $P$ ) has a solution $u \in W_{0}^{1, p}(\Omega, \omega, v)$.

The basic idea is to reduce the problem ( P ) to an operator equation $A u=T$ and apply the theorem below.

Theorem 1.3 Let $A: X \rightarrow X^{*}$ be a monotone, coercive and hemicontinuous operator on the real, separable, reflexive Banach space $X$. Then for each $T \in X^{*}$ the equation $A u=T$ has a solution $u \in X$.
Proof. See Theorem 26.A in [17].
Remark 1.4 Let $X$ be a Banach space and let $A: X \rightarrow X^{*}$ be an operator (where $X^{*}$ denotes the dual space of $X$ ).
(i) $A$ is called monotone iff

$$
\langle A u-A v, u-v\rangle \geq 0
$$

for all $u, v \in X$ (where $\langle f, u\rangle$ denotes the value of the linear functional $f \in X^{*}$ at point $u \in X)$.
(ii) $A$ is called coercive iff

$$
\lim _{\|u\| \rightarrow \infty} \frac{\langle A u, u\rangle}{\|u\|}=+\infty
$$

(iii) $A$ is said to be hemicontinuous iff the real function

$$
t \mapsto\left\langle A\left(u_{1}+t u_{2}\right), u_{3}\right\rangle
$$

is continuous on [0,1] for all $u_{1}, u_{2}, u_{3} \in X$ (see [17] for more informations about monotone, coercive and hemicontinuous operators.)

## 2 Definitions and basic results

Let $v$ be a locally integrable nonnegative function in $\mathbb{R}^{n}$ and assume that $0<v(x)<\infty$ almost everywhere. We say that $v$ belongs to the Muckenhoupt class $A_{p}, 1<p<\infty$, or that $v$ is an $A_{p}$-weight, if there is a constant $C=C_{p, v}$ such that

$$
\left(\frac{1}{|B|} \int_{B} v(x) d x\right)\left(\frac{1}{|B|} \int_{B} v^{1 /(1-p)}(x) d x\right)^{p-1} \leq C
$$

for all balls $B \subset \mathbb{R}^{n}$, where $|$.$| denotes the n$-dimensional Lebesgue measure in $\mathbb{R}^{n}$. If $1<q \leq p$, then $A_{q} \subset A_{p}$ (see [9],[10] or [14] for more informations about $A_{p}$-weights). The weight $v$ satisfies the doubling condition if $v(2 B) \leq C v(B)$, for all balls $B \subset \mathbb{R}^{n}$, where $v(B)=\int_{B} v(x) d x$ and $2 B$ denotes the ball with the same center as $B$ which is twice as large. If $v \in A_{p}$, then $v$ is doubling (see Corollary 15.7 in [10]).

As an example of $A_{p}$-weight, the function $v(x)=|x|^{\alpha}, x \in \mathbb{R}^{n}$, is in $A_{p}$ if and only if $-n<\alpha<n(p-1)$ (see Corollary 4.4, Chapter IX in [14]).

If $v \in A_{p}$, then

$$
\left(\frac{|E|}{|B|}\right)^{p} \leq C \frac{v(E)}{v(B)}
$$

whenever $B$ is a ball in $\mathbb{R}^{n}$ and $E$ is a measurable subset of $B$ (see 15.5 strong doubling property in [10]). Therefore, if $v(E)=0$ then $|E|=0$.

Definition 2.1 Let $v$ be a weight, and let $\Omega \subset \mathbb{R}^{n}$ be a bounded open set. For $1<p<\infty$, we define $L^{p}(\Omega, v)$ as the set of measurable functions $f$ on $\Omega$ such that

$$
\|f\|_{L^{p}(\Omega, v)}=\left(\int_{\Omega}|f(x)|^{p} v(x) d x\right)^{1 / p}<\infty
$$

Remark 2.2 If $v \in A_{p}, 1<p<\infty$, then since $v^{-1 /(p-1)}$ is locally integrable, we have

$$
L^{p}(\Omega, v) \subset L_{\mathrm{loc}}^{1}(\Omega)
$$

for every open set $\Omega$ (see Remark 1.2.4 in [15]). It thus makes sense to talk about weak derivatives of functions in $L^{p}(\Omega, v)$. We also have that the dual space of $L^{p}(\Omega, v)$ is the space $\left[L^{p}(\Omega, v)\right]^{*}=L^{p^{\prime}}\left(\Omega, v^{1-p^{\prime}}\right)$.

Definition 2.3 Let $\Omega \subset \mathbb{R}^{n}$ be bounded open set, and let $\omega$ and $v$ be $A_{p}$-weights, $1<p<\infty$. We define the weighted Sobolev space $W^{1, p}(\Omega, \omega, v)$ as the set of functions $u \in L^{p}(\Omega, \omega)$ with weak derivatives $D_{j} u \in L^{p}(\Omega, v)(j=1, . ., n)$. The norm of $u$ in $W^{1, p}(\Omega, \omega, v)$ is defined by

$$
\begin{equation*}
\|u\|_{W^{1, p}(\Omega, \omega, v)}=\left(\int_{\Omega}|u(x)|^{p} \omega(x) d x+\sum_{j=1}^{n} \int_{\Omega}\left|D_{j} u(x)\right|^{p} v(x) d x\right)^{1 / p} \tag{2.1}
\end{equation*}
$$

The space $W_{0}^{1, p}(\Omega, \omega, v)$ is the closure of $C_{0}^{\infty}(\Omega)$ with respect to the norm $\|u\|_{W^{1, p}(\Omega, \omega, v)}$.

Equipped by this norm, $W^{1, p}(\Omega, \omega, v)$ and $W_{0}^{1, p}(\Omega, \omega, v)$ are reflevixe Banach spaces (see [12] for more informations about the spaces $W^{1, p}(\Omega, \omega, v)$ ). The dual space of $W_{0}^{1, p}(\Omega, \omega, v)$ is the space $\left[W_{0}^{1, p}(\Omega, \omega, v)\right]^{*}=\left\{T=f_{0}-\operatorname{div} f: f=\right.$ $\left(f_{1}, \ldots, f_{n}\right), f_{0} / \omega \in L^{p^{\prime}}(\Omega, \omega)$ and $\left.f_{j} / v \in L^{p^{\prime}}(\Omega, v), j=1, \ldots, n\right\}$.

Remark 2.4 (i) If $v \in A_{p}, 1<p<\infty$, then $C^{\infty}(\Omega)$ is dense in $W^{1, p}(\Omega, v)=$ $W^{1, p}(\Omega, v, v)$ (see Corollary 2.1.6 in [15]).
(ii) If $v \leq \omega$ then $W_{0}^{1, p}(\Omega, \omega) \subset W_{0}^{1, p}(\Omega, \omega, v) \subset W_{0}^{1, p}(\Omega, v)$.

For a general theory of weighted Sobolev spaces $W^{1, p}(\Omega, v)$ with $v \in A_{p}$ see [10], [13] and [15]. For informations about weighted Sobolev spaces with others weights see [18]. And for informations about weighted Sobolev spaces $W^{k, p}(\Omega, \omega)$, where $\omega=\left\{\omega_{\alpha}(x),|\alpha| \leq k\right\}$ describes the family of weight functions $\omega_{\alpha}$, see [3].

It is evident that the weights $\omega$ and $v$ which satisfy $C_{1} \leq v(x) \leq \omega(x) \leq C_{2}$ ( $C_{1}$ and $C_{2}>0$ constants) for $x \in \Omega$, gives nothing new (the space $\mathrm{W}^{1, p}(\Omega, \omega, v)$ is then identical with the classical Sobolev space $\mathrm{W}^{1, p}(\Omega)$ ). Consequently, we shall interested above all in such weight functions $\omega$ and $v$ which either vanish somewhere in $\bar{\Omega}$ or increase to infinity (or both).

In this paper we use the following two theorems.
Theorem 2.5 Let $v \in A_{p}, 1<p<\infty$, and let $\Omega$ be a bounded open set in $\mathbb{R}^{n}$. If $u_{m} \rightarrow u$ in $L^{p}(\Omega, v)$ then there exist a subsequence $\left\{u_{m_{k}}\right\}$ and a function $\Phi \in L^{p}(\Omega, v)$ such that (i) $u_{m_{k}}(x) \rightarrow u(x), m_{k} \rightarrow \infty$, v-a.e. on $\Omega$;
(ii) $\left|u_{m_{k}}(x)\right| \leq \Phi(x)$, v-a.e. on $\Omega$.

Proof. The proof of this theorem follows the lines of Theorem 2.8.1 in [8].
Theorem 2.6 (The Weighted Sobolev Inequality)Let $\Omega$ be an open bounded set in $\mathbb{R}^{n}$ ( $n \geq 2$ ) and $v \in A_{p}(1<p<\infty)$. There exist constants $C_{\Omega}$ and $\delta$ positive such that for all $u \in W_{0}^{1, p}(\Omega, v)$ and all $\theta$ satisfying $1 \leq \theta \leq n /(n-1)+\delta$,

$$
\begin{equation*}
\|u\|_{L^{\theta p}(\Omega, v)} \leq C_{\Omega}\|\nabla u\|_{L^{p}(\Omega, v)} \tag{2.2}
\end{equation*}
$$

Proof. Its suffices to prove the inequalities for functions $u \in C_{0}^{\infty}(\Omega)$ (see Theorem 1.3 in [6]). To extend the estimates (2.2) to arbitrary $u \in W_{0}^{1, p}(\Omega, v)$, we let $\left\{u_{m}\right\}$ be a sequence of $C_{0}^{\infty}(\Omega)$ functions tending to $u$ in $W_{0}^{1, p}(\Omega, v)$. Applying the estimates (2.2) to differences $u_{m_{1}}-u_{m_{2}}$, we see that $\left\{u_{m}\right\}$ will be a Cauchy sequence in $L^{\theta p}(\Omega, v)$. Consequently the limit functions $u$ will lie in the desired spaces and satisfy (2.2).
Definition 2.7 Let $1<p<\infty, \omega$ and $v A_{p}$-weights, with $v \leq \omega$. We say that an element $u \in W_{0}^{1, p}(\Omega, \omega, v)$ is a (weak) solution of problem (P) if

$$
\begin{aligned}
& \sum_{j=1}^{n} \int_{\Omega} v(x) \mathcal{A}(x, u, \nabla u) . \nabla \varphi d x+\int_{\Omega} \mathcal{A}_{0}(x, u) \varphi \omega d x \\
= & \int_{\Omega} f_{0} \varphi d x+\sum_{j=1}^{n} \int_{\Omega} f_{j} D_{j} \varphi d x,
\end{aligned}
$$

for all $\varphi \in W_{0}^{1, p}(\Omega, \omega, v)$.

## 3 Proof of theorem 1.2

Step 1. We define

$$
\begin{aligned}
& B: W_{0}^{1, p}(\Omega, \omega, v) \times W_{0}^{1, p}(\Omega, \omega, v) \rightarrow \mathbb{R} \\
& B(u, \varphi)=\sum_{j=1}^{n} \int_{\Omega} v \mathcal{A}_{j}(x, u, \nabla u) D_{j} \varphi d x+\int_{\Omega} \mathcal{A}_{0}(x, u) \varphi \omega d x
\end{aligned}
$$

and

$$
\begin{aligned}
& T: W_{0}^{1, p}(\Omega, \omega, v) \rightarrow \mathbb{R} \\
& T(\varphi)=\int_{\Omega} f_{0} \varphi d x+\sum_{j=1}^{n} \int_{\Omega} f_{j} D_{j} \varphi d x .
\end{aligned}
$$

Then $u \in W_{0}^{1, p}(\Omega, \omega, v)$ is a (weak) solution to problem (P) if

$$
B(u, \varphi)=T(\varphi), \text { for all } \varphi \in W_{0}^{1, p}(\Omega, \omega, v)
$$

Using (H3), $f_{0} / \omega \in L^{p^{\prime}}(\Omega, \omega), f_{j} / v \in L^{p^{\prime}}(\Omega, v)(j=1,2 \ldots, n)$, Remark 2.4(ii) and Theorem 2.6, we have that

$$
\begin{equation*}
|T(\varphi)| \leq C\left(\left\|f_{0} / \omega\right\|_{L^{p^{\prime}}(\Omega, \omega)}+\sum_{j=1}^{n}\left\|f_{j} / v\right\|_{L^{p^{\prime}}(\Omega, v)}\right)\|\varphi\|_{W_{0}^{1, p}(\Omega, \omega, v)^{\prime}} \tag{3.1}
\end{equation*}
$$

and

$$
\begin{align*}
& |B(u, \varphi)| \leq \int_{\Omega}|\mathcal{A}(x, u, \nabla u)||\nabla \varphi| v d x+\int_{\Omega}\left|\mathcal{A}_{0}(x, u)\right||\varphi| \omega d x \\
& \leq \int_{\Omega}\left(K_{1}+h_{3}|u|^{\theta(p-1)}+h_{4}|\nabla u|^{p-1}\right)|\nabla \varphi| v d x+\int_{\Omega}\left(K_{2}+\tilde{h}_{3}|u|^{p-1}\right)|\varphi| \omega d x \\
& \leq C\left(\left\|K_{1}\right\|_{L^{p^{\prime}(\Omega, v)}}+\left\|h_{3}\right\|_{L^{\infty}(\Omega)}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{\theta(p-1)}+\left\|h_{4}\right\|_{L^{\infty}(\Omega)}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{p-1}\right. \\
& \left.+\left\|K_{2}\right\|_{L^{p^{\prime}}(\Omega, \omega)}+\left\|\tilde{h}_{3}\right\|_{L^{\infty}(\Omega)}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{p-1}\right)\|\varphi\|_{W_{0}^{1, p}(\Omega, \omega, v)} \tag{3.2}
\end{align*}
$$

Since $B(u,$.$) is linear for each u \in W_{0}^{1, p}(\Omega, \omega, v)$, there exists a linear and continuous operator $A: W_{0}^{1, p}(\Omega, \omega, v) \rightarrow\left[W_{0}^{1, p}(\Omega, \omega, v)\right]^{*}$ such that

$$
\langle A u, \varphi\rangle=B(u, \varphi), \text { for all } u, \varphi \in W_{0}^{1, p}(\Omega, \omega, v)
$$

and

$$
\begin{aligned}
\|A u\|_{*} & \leq C\left(\left\|K_{1}\right\|_{L^{p^{\prime}(\Omega, v)}}+\left\|h_{3}\right\|_{L^{\infty}(\Omega)}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{\theta(p-1)}+\left\|h_{4}\right\|_{L^{\infty}(\Omega)}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{p-1}\right. \\
& \left.+\left\|K_{2}\right\|_{L^{p^{\prime}(\Omega, \omega)}}+\left\|\tilde{h}_{3}\right\|_{L^{\infty}(\Omega)}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{p-1}\right)
\end{aligned}
$$

where $\|\cdot\|_{*}$ denotes the norm in $\left[W_{0}^{1, p}(\Omega, \omega, v)\right]^{*}$. Consequently, problem (P) is equivalent to the operator equation $A u=T, u \in W_{0}^{1, p}(\Omega, \omega, v)$.

Step 2. The operator $A: W_{0}^{1, p}(\Omega, \omega, v) \rightarrow\left[W_{0}^{1, p}(\Omega, \omega, v)\right]^{*}$ is continuous. In fact, we define the operators

$$
\begin{aligned}
& F_{j}: W_{0}^{1, p}(\Omega, \omega, v) \rightarrow L^{p^{\prime}}(\Omega, v),(j=1, \ldots, n) \\
& \left(F_{j} u\right)(x)=\mathcal{A}_{j}(x, u(x), \nabla u(x))
\end{aligned}
$$

and

$$
\begin{aligned}
& G: W_{0}^{1, p}(\Omega, \omega, v) \rightarrow L^{p^{\prime}}(\Omega, \omega) \\
& (G u)(x)=\mathcal{A}_{0}(x, u(x))
\end{aligned}
$$

We have that the operators $F_{j}$ and $G$ are bounded and continuous. In fact,
(i) Using (H3), Remark 2.4(ii) and Theorem 2.6, we obtain

$$
\begin{align*}
\left\|F_{j} u\right\|_{L^{p^{\prime}}(\Omega, v)}^{p^{\prime}} & =\int_{\Omega}\left|F_{j} u(x)\right|^{p^{\prime}} v d x=\int_{\Omega}\left|\mathcal{A}_{j}(x, u, \nabla u)\right|^{p^{\prime}} v d x \\
& \leq \int_{\Omega}\left(K_{1}+h_{3}|u|^{\theta(p-1)}+h_{4}|\nabla u|^{p-1}\right)^{p^{\prime}} v d x \\
& \leq C \int_{\Omega}\left[\left(K_{1}^{p^{\prime}}+h_{3}^{p^{\prime}}|u|^{\theta p}+h_{4}^{p^{\prime}}|\nabla u|^{p}\right) v\right] d x \\
& =C\left[\int_{\Omega} K_{1}^{p^{\prime}} v d x+\int_{\Omega} h_{3}^{p^{\prime}}|u|^{\theta p} v d x+\int_{\Omega} h_{4}^{p^{\prime}}|\nabla u|^{p} v d x\right] \\
& \leq C\left[\left\|K_{1}\right\|_{L^{p^{\prime}}(\Omega, v)}^{p^{\prime}}+\left\|h_{3}\right\|_{L^{\infty}(\Omega)}^{p^{p^{\prime}}} C_{\Omega}^{\theta p}\|\nabla u\|_{L^{p}(\Omega, v)}^{\theta p}\right. \\
& \left.+\left\|h_{4}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}}\|\nabla u\|_{L^{p}(\Omega, v)}^{p}\right] \\
& \leq C\left[\left\|K_{1}\right\|_{L^{p^{\prime}}(\Omega, v)}^{p^{\prime}}+\left\|h_{3}\right\|_{L^{\infty}(\Omega)}^{p^{p^{\prime}}} C_{\Omega}^{\theta p}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{\theta p}\right. \\
& +\left\|h_{4}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}\left(\Omega u \|_{W_{0}^{1, p}(\Omega, \omega, v)}^{p}\right] .} \tag{3.3}
\end{align*}
$$

Analogously, we have

$$
\begin{aligned}
& \|G u\|_{L^{p^{\prime}}(\Omega, \omega)}^{p^{\prime}}=\int_{\Omega}\left|\mathcal{A}_{0}(x, u)\right|^{p^{\prime}} \omega d x \\
\leq & \int_{\Omega}\left(K_{2}+\tilde{h}_{3}|u|^{p-1}\right)^{p^{\prime}} \omega d x \\
\leq & C\left(\left\|K_{2}\right\|_{L^{p^{\prime}(\Omega, \omega)}}^{p^{\prime}}+\left\|\tilde{h}_{3}\right\|_{L^{\infty}}^{p^{\prime}}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{p}\right) .
\end{aligned}
$$

(ii) Let $u_{m} \rightarrow u$ in $W_{0}^{1, p}(\Omega, \omega, v)$ as $m \rightarrow \infty$. We need to show that $F_{j} u_{m} \rightarrow F_{j} u$ in $L^{p^{\prime}}(\Omega, v)$ and $G u_{m} \rightarrow G u$ in $L^{p^{\prime}}(\Omega, \omega)$.
If $u_{m} \rightarrow u$ in $W_{0}^{1, p}(\Omega, \omega, v)$, then $u_{m} \rightarrow u$ in $L^{p}(\Omega, \omega)$ and $\nabla u_{m} \rightarrow \nabla u$ in $\left(L^{p}(\Omega, v)\right)^{n}$. Using Theorem 2.5, there exist a subsequence $\left\{u_{m_{k}}\right\}$, functions $\Phi_{1} \in L^{p}(\Omega, \omega)$ and $\Phi_{2} \in L^{p}(\Omega, v)$ such that

$$
\begin{aligned}
& u_{m_{k}}(x) \rightarrow u(x), \omega \text { - a.e. in } \Omega \\
& \left|u_{m_{k}}(x)\right| \leq \Phi_{1}(x) \omega \text { - a.e in } \Omega \\
& \nabla u_{m_{k}}(x) \rightarrow \nabla u(x), v-\text { a.e. in } \Omega \\
& \left|\nabla u_{m_{k}}(x)\right| \leq \Phi_{2}(x), v-\text { a.e. in } \Omega .
\end{aligned}
$$

Hence, using (H3), we obtain

$$
\begin{aligned}
& \left\|F_{j} u_{m_{k}}-F_{j} u\right\|_{L^{p^{\prime}}(\Omega, v)}^{p^{\prime}}=\int_{\Omega}\left|F_{j} u_{m_{k}}(x)-F_{j} u(x)\right|^{p^{\prime}} v d x \\
= & \left.\int_{\Omega} \mid \mathcal{A}_{j}\left(x, u_{m_{k^{\prime}}} \nabla u_{m_{k}}\right)-\mathcal{A}_{j}(x, u, \nabla u)\right)^{p^{\prime}} v d x \\
\leq & C \int_{\Omega}\left(\left|\mathcal{A}_{j}\left(x, u_{m_{k}}, \nabla u_{m_{k}}\right)\right|^{p^{\prime}}+\left|\mathcal{A}_{j}(x, u, \nabla u)\right|^{p^{\prime}}\right) v d x \\
\leq & C\left[\int_{\Omega}\left(K_{1}+h_{3}\left|u_{m_{k}}\right|^{\theta(p-1)}+h_{4}\left|\nabla u_{m_{k}}\right|^{p-1}\right)^{p^{p^{\prime}}} v d x\right. \\
+ & \left.\int_{\Omega}\left(K_{1}+h_{3}|u|^{\theta(p-1)}+h_{4}|\nabla u|^{p-1}\right)^{p^{\prime}} v d x\right] \\
\leq & C\left[\int_{\Omega} K_{1}^{p^{\prime}} v d x+\left\|h_{3}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} C_{\Omega}^{\theta p}\left(\left\|\nabla u_{m_{k}}\right\|_{L^{p}(\Omega, v)}^{\theta p}+\|\nabla u\|_{L^{p}(\Omega, v)}^{\theta p}\right)\right. \\
+ & \left.\left\|h_{4}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}}\left(\int_{\Omega}\left|\nabla u_{m_{k}}\right|^{p} v d x+\int_{\Omega}|\nabla u|^{p} v d x\right)\right] \\
\leq & C\left[\int_{\Omega} K_{1}^{p^{\prime}} v d x+\left\|h_{3}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} C_{\Omega}^{\theta p}\left\|\Phi_{2}\right\|_{L^{p}(\Omega, v)}^{\theta p}+\left\|h_{4}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} \int_{\Omega} \Phi_{2}^{p} v d x\right] \\
= & C \int_{\Omega}\left(K_{1}^{p^{\prime}}+\frac{\left\|h_{3}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} C_{\Omega}^{\theta p}\left\|\Phi_{2}\right\|_{L^{p}(\Omega, v)}^{\theta p}}{v(\Omega)}+\left\|h_{4}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} \Phi_{2}^{p}\right) v d x \\
= & C \int_{\Omega} g_{1}(x) v(x) d x
\end{aligned}
$$

where $0<v(\Omega)=\int_{\Omega} v d x<\infty, g_{1} \in L^{1}(\Omega, v)$ with

$$
g_{1}(x)=K_{1}^{p^{\prime}}(x)+\left\|h_{4}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} \Phi_{2}^{p}(x)+\frac{\left\|h_{3}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} C_{\Omega}^{\theta p}\left\|\Phi_{2}\right\|_{L^{p}(\Omega, v)}^{\theta_{p}^{p}}}{v(\Omega)} .
$$

Analogously, we have

$$
\begin{aligned}
& \left\|G u_{m_{k}}-G u\right\|_{L^{p^{\prime}(\Omega, \omega)}}^{p^{p^{\prime}}}=\int_{\Omega}\left|G u_{m_{k}}(x)-G u(x)\right|^{p^{\prime}} \omega d x \\
\leq & C \int_{\Omega}\left(\left|\mathcal{A}_{0}\left(x, u_{m_{k}}\right)\right|^{p^{\prime}}+\left|\mathcal{A}_{0}(x, u)\right|^{p^{\prime}}\right) \omega d x \\
\leq & C \int_{\Omega}\left(K_{2}+\tilde{h}_{3}\left|u_{m_{k}}\right|^{p-1}\right)^{p^{\prime}} \omega d x+\int_{\Omega}\left(K_{2}+\tilde{h}_{3}|u|^{p-1}\right)^{p^{\prime}} \omega d x \\
\leq & C\left[\int_{\Omega} K_{2}^{p^{\prime}} \omega d x+\left\|\tilde{h}_{3}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}}\left(\int_{\Omega}\left|u_{m_{k}}\right|^{p} \omega d x+\int_{\Omega}|u|^{p} \omega d x\right)\right] \\
\leq & C\left(\int_{\Omega}\left(K_{2}^{p^{\prime}}+\left\|\tilde{h}_{3}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} \Phi_{1}^{p}\right) \omega d x\right) \\
= & C \int_{\Omega} g_{2} \omega d x
\end{aligned}
$$

where $g_{2}(x)=K_{2}^{p^{\prime}}(x)+\left\|\tilde{h}_{3}\right\|_{L^{\infty}(\Omega)}^{p^{\prime}} \Phi_{1}^{p}(x)$ and $g_{2} \in L^{1}(\Omega, \omega)$.

By condition (H1), we have, as $k \rightarrow \infty$

$$
\begin{aligned}
& F_{j} u_{m_{k}}(x)=\mathcal{A}_{j}\left(x, u_{m_{k}}(x), \nabla u_{m_{k}}(x)\right) \rightarrow \mathcal{A}_{j}(x, u(x), \nabla u(x))=F_{j} u(x) \\
& G u_{m_{k}}(x)=\mathcal{A}_{0}\left(x, u_{m_{k}}(x)\right) \rightarrow \mathcal{A}_{0}(x, u(x))=G u(x)
\end{aligned}
$$

for almost all $x \in \Omega$. Therefore, by Dominated Convergence Theorem, we obtain

$$
\left\|F_{j} u_{m_{k}}-F_{j} u\right\|_{L^{p^{\prime}}(\Omega, v)} \rightarrow 0,
$$

and

$$
\left\|G u_{m_{k}}-G u\right\|_{L^{p^{\prime}}(\Omega, \omega)} \rightarrow 0
$$

that is, $F_{j} u_{m_{k}} \rightarrow F_{j} u$ in $L^{p^{\prime}}(\Omega, v)$ and $G u_{m_{k}} \rightarrow G u$ in $L^{p^{\prime}}(\Omega, \omega)$. By Convergence principle in Banach spaces, we have

$$
\begin{equation*}
F_{j} u_{m} \rightarrow F_{j} u \text { in } L^{p^{\prime}}(\Omega, v), \tag{3.4}
\end{equation*}
$$

and

$$
\begin{equation*}
G u_{m} \rightarrow G u \text { in } L^{p^{\prime}}(\Omega, \omega) . \tag{3.5}
\end{equation*}
$$

Finally, let $u_{m} \rightarrow u$ in $W_{0}^{1, p}(\Omega, \omega, v)$ as $m \rightarrow \infty$. We have

$$
\begin{aligned}
& \left|B\left(u_{m}, \varphi\right)-B(u, \varphi)\right| \\
& \leq \sum_{j=1}^{n} \int_{\Omega}\left|\mathcal{A}_{j}\left(x, u_{m}, \nabla u_{m}\right)-\mathcal{A}_{j}(x, u, \nabla u)\right|\left|D_{j} \varphi\right| v d x \\
& +\int_{\Omega}\left|\mathcal{A}_{0}\left(x, u_{m}\right)-\mathcal{A}_{0}(x, u)\right||\varphi| \omega d x \\
& =\sum_{j=1}^{n} \int_{\Omega}\left|F_{j} u_{m}-F_{j} u\left\|D_{j} \varphi\left|v d x+\int_{\Omega}\right| G u_{m}-G u\right\| \varphi\right| \omega d x \\
& \leq\left(\sum_{j=1}^{n}\left\|F_{j} u_{m}-F_{j} u\right\|_{L^{p^{\prime}(\Omega, v)}}+\left\|G u_{m}-G u\right\|_{L^{p^{\prime}(\Omega, \omega)}}\right)\|\varphi\|_{W_{0}^{1, p}(\Omega, \omega, v)}
\end{aligned}
$$

for all $\varphi \in W_{0}^{1, p}(\Omega, \omega, v)$. Hence,

$$
\left\|A u_{m}-A u\right\|_{*} \leq\left\|G u_{m}-G u\right\|_{L^{p^{\prime}}(\Omega, \omega)}+\sum_{j=1}^{n}\left\|F_{j} u_{m}-F_{j} u\right\|_{L^{p^{\prime}}(\Omega, v)}
$$

Therefore, by (3.4) and (3.5), $\left\|A u_{m}-A u\right\|_{*} \rightarrow 0$ as $m \rightarrow \infty$, that is, the operator $A$ is continuous.

Step 3. The operator $A$ is monotone. In fact, by Proposition 25.6 in [17] the operator $A: W_{0}^{1, p}(\Omega, \omega, v) \rightarrow\left[W_{0}^{1, p}(\Omega, \omega, v)\right]^{*}$ is monotone if and only if the function $h(t)=\langle A(u+t \varphi), \varphi\rangle, t \in[0,1]$, is increasing for all $u, \varphi \in W_{0}^{1, p}(\Omega, \omega, v)$. We have,

$$
\begin{aligned}
& h(t)=\langle A(u+t \varphi), \varphi\rangle=B(u+t \varphi, \varphi) \\
= & \left.\int_{\Omega}\left(v \mathcal{A}(x, u+t \varphi, \nabla(u+t \varphi)) \cdot \nabla \varphi+\omega \mathcal{A}_{0}(x, u+t \varphi)\right) \varphi\right) d x
\end{aligned}
$$

is monotone increasing as a functions of $t \in[0,1]$ by (H4).
Step 4. We need to show that the operator $A$ is coercive. We have, using (H2),

$$
\begin{aligned}
& \langle A u, u\rangle=B(u, u) \\
& =\int_{\Omega} v \mathcal{A}(x, u, \nabla u) \cdot \nabla u d x+\int_{\Omega} \mathcal{A}_{0}(x, u) u \omega d x \\
& \geq \int_{\Omega}\left(\lambda|\nabla u|^{p}-h_{0}(x)|\nabla u|-h_{1}(x)|u|-h_{2}(x)\right) v d x \\
& +\int_{\Omega}\left(\lambda|u|^{p}-\tilde{h}_{1}|u|-\tilde{h}_{2}\right) \omega d x \\
& \geq \lambda\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{p}-\left(\left\|h_{0}\right\|_{L^{p^{\prime}}(\Omega, v)}+\left\|h_{1} v / \omega\right\|_{L^{p^{\prime}}(\Omega, \omega)}\right)\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)} \\
& -\left\|\tilde{h}_{1}\right\|_{L^{p^{\prime}(\Omega, \omega)}}\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}-\left\|h_{2}\right\|_{L^{1}(\Omega, v)}-\left\|\tilde{h}_{2}\right\|_{L^{1}(\Omega, \omega)} .
\end{aligned}
$$

Hence since $p>1$, we have

$$
\begin{aligned}
\frac{\langle A u, u\rangle}{\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)} \geq} & \lambda\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}^{p-1}-\left\|h_{0}\right\|_{L^{p^{\prime}}(\Omega, v)}-\left\|h_{1} v / \omega\right\|_{L^{p^{\prime}}(\Omega, \omega)} \\
& -\left\|\tilde{h}_{1}\right\|_{L^{p^{\prime}}(\Omega, \omega)}-\frac{\left\|h_{2}\right\|_{L^{1}(\Omega, v)}}{\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}}-\frac{\left\|\tilde{h}_{2}\right\|_{L^{1}(\Omega, \omega)}}{\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}} .
\end{aligned}
$$

Therefore,

$$
\frac{\langle A u, u\rangle}{\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)}} \rightarrow \infty \text { as }\|u\|_{W_{0}^{1, p}(\Omega, \omega, v)} \rightarrow \infty
$$

that is, $A$ is coercive.
Therefore, by Theorem 1.3, the operator equation $A u=T$ has a solution $u \in W_{0}^{1, p}(\Omega, \omega, v)$ and it is a solution for problem $(P)$.

Example Let $\Omega=\left\{(x, y) \in \mathbb{R}^{2}: x^{2}+y^{2}<1\right\}, 1<p<\infty$ and consider the weight functions $v(x, y)=\left(x^{2}+y^{2}\right)^{-1 / 3 p}$ and $\omega(x, y)=\left(x^{2}+y^{2}\right)^{-1 / 2 p}\left(\omega, v \in A_{p}\right)$, the functions $\mathcal{A}_{i}: \Omega \times \mathbb{R} \times \mathbb{R}^{2} \rightarrow \mathbb{R}(i=1,2)$ and $\mathcal{A}_{0}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$
\begin{aligned}
& \mathcal{A}_{i}((x, y), \eta, \xi)=h_{4}(x, y)\left|\xi_{i}\right|^{p-1} \operatorname{sgn}\left(\xi_{i}\right) \\
& \mathcal{A}_{0}((x, y), \eta)=|\eta|^{p-1} \operatorname{sgn}(\eta)\left(2-\cos ^{2}(x y)\right)
\end{aligned}
$$

where $h_{4}(x, y)=2 \mathrm{e}^{x^{2}+y^{2}}$. It is easy to show that the functions $\mathcal{A}_{i}((x, y), \eta, \xi)$ ( $i=1,2$ ) and $\mathcal{A}_{0}((x, y), \eta)$ satisfy the conditions (H1), (H2) and (H3). By Remark 1.1, the conditions (H4) is satisfied, because if $\xi=\left(\xi_{1}, \xi_{2}\right), \xi^{\prime}=\left(\xi_{1}^{\prime}, \xi_{2}^{\prime}\right) \in \mathbb{R}^{2}$, $\eta, \eta^{\prime} \in \mathbb{R}\left(\xi \neq \xi^{\prime}\right.$ and $\left.\eta \neq \eta^{\prime}\right)$ we have

$$
\begin{aligned}
& {\left[\mathcal{A}((x, y), \eta, \xi)-\mathcal{A}\left((x, y), \eta^{\prime}, \xi^{\prime}\right)\right] \cdot\left(\xi-\xi^{\prime}\right)} \\
& =h_{4}(x, y)\left[\left(\left|\xi_{1}\right|^{p-1} \operatorname{sgn}\left(\xi_{1}\right)-\left|\xi_{1}^{\prime}\right|^{p-1} \operatorname{sgn}\left(\xi_{1}^{\prime}\right)\right)\left(\xi_{1}-\xi_{1}^{\prime}\right)\right. \\
& \left.+\left(\left|\xi_{2}\right|^{p-1} \operatorname{sgn}\left(\xi_{2}\right)-\left|\xi_{2}^{\prime}\right|^{p-1} \operatorname{sgn}\left(\xi_{2}^{\prime}\right)\right)\left(\xi_{2}-\xi_{2}^{\prime}\right)\right]>0
\end{aligned}
$$

and

$$
\begin{aligned}
& {\left[\mathcal{A}_{0}((x, y), \eta)-\mathcal{A}_{0}\left((x, y), \eta^{\prime}\right)\right]\left(\eta-\eta^{\prime}\right)} \\
& =\left(2-\cos ^{2}(x y)\right)\left(|\eta|^{p-1} \operatorname{sgn}(\eta)-\left|\eta^{\prime}\right|^{p-1} \operatorname{sgn}\left(\eta^{\prime}\right)\right)\left(\eta-\eta^{\prime}\right)>0
\end{aligned}
$$

Let us consider the partial differential operator

$$
\begin{aligned}
L u(x, y) & =-\operatorname{div}[v(x, y) \mathcal{A}((x, y), u, \nabla u)]+\omega(x, y) \mathcal{A}_{0}((x, y), u) \\
& =-\frac{\partial}{\partial x}\left[v(x, y) \mathcal{A}_{1}((x, y), u, \nabla u)\right]-\frac{\partial}{\partial y}\left[v(x, y) \mathcal{A}_{2}((x, y), u, \nabla u)\right] \\
& +\omega(x, y) \mathcal{A}_{0}((x, y), u) .
\end{aligned}
$$

Therefore, by Theorem 1.2, the problem

$$
\begin{aligned}
& L u(x, y)=\frac{\cos (x y)}{\left(x^{2}+y^{2}\right)^{\alpha}}-\frac{\partial}{\partial x}\left(\frac{\sin (x y)}{\left(x^{2}+y^{2}\right)^{\beta}}\right)-\frac{\partial}{\partial y}\left(\frac{\sin (x y)}{\left(x^{2}+y^{2}\right)^{\beta}}\right), \text { on } \Omega \\
& u(x, y)=0, \text { on } \partial \Omega
\end{aligned}
$$

where $\alpha<\left(2 p-p^{\prime}-1\right) / 2 p p^{\prime}$ and $\beta<\left(3 p-p^{\prime}-1\right) / 3 p p^{\prime}$, has a solution $u \in W_{0}^{1,2}(\Omega, \omega, v)$.

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