# DOWNSIDE RISK MINIMIZATION VIA A LARGE DEVIATIONS APPROACH ${ }^{1}$ 

By Hideo Nagai

Osaka University
We consider minimizing the probability of falling below a target growth rate of the wealth process up to a time horizon $T$ in an incomplete market model, and then study the asymptotic behavior of minimizing probability as $T \rightarrow \infty$. This problem can be closely related to an ergodic risk-sensitive stochastic control problem in the risk-averse case. Indeed, in our main theorem, we relate the former problem concerning the asymptotics for risk minimization to the latter as its dual. As a result, we obtain an expression of the limit value of the probability as the Legendre transform of the value of the control problem, which is characterized as the solution to an H-J-B equation of ergodic type, in the case of a Markovian incomplete market model.

1. Introduction. Risk management is a main topic in the study of finance. In the present paper, we consider the problem of minimizing the downside risk associated with an investor's total wealth in a certain incomplete market model. More precisely, let $S_{t}^{0}$ be the price of a riskless asset with the dynamics $d S_{t}^{0}=r_{t} S_{t}^{0} d t$, $\left(S_{t}^{1}, \ldots, S_{t}^{m}\right)$ the prices of the risky assets, and $N_{t}^{i}, i=0, \ldots, m$, the number of shares of $i$ th security. Then the total wealth that the investor possesses is defined as

$$
V_{t}=\sum_{i=0}^{m} N_{t}^{i} S_{t}^{i}
$$

and we assume a self-financing condition,

$$
d V_{t}=\sum_{i=0}^{m} N_{t}^{i} d S_{t}^{i}
$$

When setting the proportion of the portfolio invested in the $i$ th security as $h_{t}^{i}=$ $\frac{N_{t}^{i} S_{t}^{i}}{V_{t}}$, we have

$$
\frac{d V_{t}}{V_{t}}=\sum_{i=0}^{m} h_{t}^{i} \frac{d S_{t}^{i}}{S_{t}^{i}},
$$

[^0]and the total wealth is denoted by $V_{t}=V_{t}(h)$, which is the solution to this stochastic differential equation for a given strategy $h_{t}$. Let us consider minimizing the probability
\[

$$
\begin{equation*}
P\left(\frac{1}{T} \log \frac{V_{T}(h)}{S_{T}^{0}} \leq \kappa\right) \tag{1.1}
\end{equation*}
$$

\]

for a given target growth rate $\kappa$ by selecting portfolio choice $h$. Let us make clear the meaning of the probability. If we choose strategy $\left(h_{t}^{0}, h_{t}^{1}, \ldots, h_{t}^{m}\right)=$ $(1,0, \ldots, 0)$, then we have

$$
d \log V_{t}=\frac{d V_{t}}{V_{t}}=\frac{d S_{t}^{0}}{S_{t}^{0}}=d \log S_{t}^{0}
$$

Thus, the probability is always 1 for large time $T$ and $\kappa>0$. Accordingly, in considering the above minimization, we investigate the extent for which we can improve the probability by selecting a strategy, as compared with the trivial strategy of investing the total wealth in a riskless asset. The latter strategy is considered the benchmark in terms of finance.

We shall consider the asymptotic behavior of the probability

$$
\begin{equation*}
\underline{\lim _{T \rightarrow \infty}} \frac{1}{T} \inf _{h .} \log P\left(\frac{1}{T} \log \frac{V_{T}(h)}{S_{T}^{0}} \leq \kappa\right) \tag{1.2}
\end{equation*}
$$

According to the theory of large deviation, it is natural to relate (1.2) to

$$
\begin{equation*}
\hat{\chi}(\gamma):=\underline{\lim _{T \rightarrow \infty}} \frac{1}{T} \inf _{h .} \log E\left[e^{\gamma \log \left(V_{T}(h) / S_{T}^{0}\right)}\right] \tag{1.3}
\end{equation*}
$$

for $\gamma<0$. Namely, as $T \rightarrow \infty$,

$$
\frac{1}{T} \inf _{h .} \log P\left(\frac{1}{T} \log \frac{V_{T}(h)}{S_{T}^{0}} \in(-\infty, \kappa]\right) \rightarrow-\inf _{k \in(-\infty, \kappa]} \sup _{\gamma<0}\{\gamma k-\hat{\chi}(\gamma)\}
$$

is expected to hold since the Legendre transform $I(k)$ of $\hat{\chi}(\gamma)$,

$$
I(k)=\sup _{\gamma<0}\{\gamma k-\hat{\chi}(\gamma)\},
$$

is regarded as the rate function of the asymptotics, if $\hat{\chi}(\gamma)$ is a convex function; cf. [10]. Note that we can see from Hölder's inequality that $\log E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma}\right]=$ $\log E\left[e^{\gamma \log \left(V_{T}(h) / S_{T}^{0}\right)}\right]$ is a convex function of $\gamma$, but this does not always imply the convexity of its infimum

$$
\begin{equation*}
\inf _{h .} \log E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma}\right]=\inf _{h .} \log E\left[e^{\gamma \log \left(V_{T}(h) / S_{T}^{0}\right)}\right] \tag{1.4}
\end{equation*}
$$

Therefore, the convexity of $\hat{\chi}(\gamma)$ cannot be determined immediately and the above idea does not directly apply. In the present paper, we will find the convexity of
$\hat{\chi}(\gamma)$ by identifying the solution of the H-J-B equation of ergodic type with the limit value (1.3); cf. Proposition 4.2 and Corollary 4.1. Then we shall see that the duality relation between (1.2) and (1.3) holds under suitable conditions, as expected; cf. Theorem 2.4.

Minimization (1.4), which is equivalent to power utility maximization, could be regarded as a risk-sensitive control problem. The infinite time horizon counterpart of (1.4) without a benchmark,

$$
\begin{equation*}
\inf _{h .} \underline{\lim }_{T \rightarrow \infty} \frac{1}{T} \log E\left[e^{\gamma \log V_{T}(h)}\right] \tag{1.5}
\end{equation*}
$$

has been extensively studied as risk-sensitive control (e.g., $[4,5,13-15,20,21$, $24,28,30]$ ), and a benchmarked case has recently been reported in [9]. From the viewpoint of stochastic control theory, it may appear more natural, compared with the above relationship between (1.2) and (1.3), to relate

$$
\begin{equation*}
\inf _{h .} \underline{\lim _{T \rightarrow \infty}} \frac{1}{T} \log E\left[e^{\gamma \log \left(V_{T}(h) / S_{T}^{0}\right)}\right] \tag{1.6}
\end{equation*}
$$

to

$$
\begin{equation*}
\inf _{h .} \underline{\lim } \frac{1}{T \rightarrow \infty} \log P\left(\frac{1}{T} \log \frac{V_{T}(h)}{S_{T}^{0}} \leq \kappa\right) \tag{1.7}
\end{equation*}
$$

which is considered in the present paper as well; cf. Theorem 2.5.
We note that the problem relating (1.2) to (1.3) is thought to be equivalent to considering

$$
\underline{\lim _{T \rightarrow \infty}} \frac{1}{T} \inf \log P\left(\frac{1}{T} \log V_{T}(h) \leq \kappa\right)
$$

and

$$
\check{\chi}(\gamma):=\underline{\lim _{T \rightarrow \infty}} \frac{1}{T} \inf _{h .} \log E\left[e^{\gamma \log V_{T}(h)}\right]
$$

without a benchmark. However, the arguments in this article may be simpler than in the case without a benchmark (cf. Remark 2.2).

In previous papers [19, 29], we studied similar asymptotic behavior without benchmarks for linear Gaussian models in relation to the asymptotics of risksensitive portfolio optimization. Indeed, we established a duality relation between these problems, and as a result, an explicit expression of the limit value of the probability minimizing downside risk for each case of full and partial information. To obtain those results, the key analysis involved Poisson equations derived by taking derivatives with respect to $\gamma$ of the H-J-B equations of ergodic type corresponding to risk-sensitive control over an infinite time horizon. Since the solutions of the H-J-B equations can be explicitly expressed as quadratic functions by using the solutions of the Riccati equations for linear Gaussian models, analysis of
the differentiability of the solutions of the Riccati equations with respect to $\gamma$ was essential in those works.

In the present paper, we shall consider general diffusion market models and discuss the above-mentioned duality relation between the asymptotics of the minimization of downside risk and the risk-sensitive stochastic control for large time. Since the solutions of H-J-B equations of ergodic type do not always have explicit expressions, we need to consider, in general, the differentiablity with respect to $\gamma$ of $\mathrm{H}-\mathrm{J}$-B equations of ergodic type. The analysis is presented in Sections 5 and 6 based on the results concerning H-J-B equations of ergodic type and related stochastic control problems given in Sections 3 and 4. Here, we mention the ongoing work of Hata and Sheu [22], which is closely related to the present paper and examines similar problems under the assumptions that $\alpha(x)$ in (2.2) in Section 2 is bounded and that $\beta(x)^{*} x \leq-c|x|^{2}$ for $|x| \geq R$ in place of (2.19). We shall explain more precisely the relationships between these papers in Remark 2.3.

We note that maximization of an upside chance probability for the long term was studied by Pham [31, 32] for continuous time models, and then by Stettner [34] for discrete time models, in relation to risk-sensitive portfolio optimization in the riskseeking case. By regarding the maximization problem as large deviation control, Pham established a duality relation between these two types of problems. Explicit calculation of the limit value is given in the case of 1-dimensional Gaussian models. The problem was later extended to a nonlinear case by Hata and Sekine [20, 21] and also to the partial information case by Hata and Iida [18] for 1-dimensional Gaussian models. See also related works [6, 7, 35]. However, asymptotic estimates of downside risk probabilities and upside chance probabilities cannot be obtained in parallel. Indeed, obtaining the estimates of downside risk is rather difficult than those of upside chance and further analysis of H-J-B equations is required to show the estimates as was shown in [19]. Further note that large deviations control (1.7) is an unconventional optimization problem, and thus we need to employ a new approach to study it.
2. Setting up and main results. Consider a market model with $m+1$ securities and $n$ factors, where the bond price is governed by the ordinary differential equation

$$
\begin{equation*}
d S^{0}(t)=r\left(X_{t}\right) S^{0}(t) d t, \quad S^{0}(0)=s^{0} \tag{2.1}
\end{equation*}
$$

The other security prices and factors are assumed to satisfy the stochastic differential equations

$$
\begin{align*}
& d S^{i}(t)=S^{i}(t)\left\{\alpha^{i}\left(X_{t}\right) d t+\sum_{k=1}^{n+m} \sigma_{k}^{i}\left(X_{t}\right) d W_{t}^{k}\right\}  \tag{2.2}\\
& S^{i}(0)=s^{i}, \quad i=1, \ldots, m
\end{align*}
$$

and

$$
\begin{align*}
d X_{t} & =\beta\left(X_{t}\right) d t+\lambda\left(X_{t}\right) d W_{t}  \tag{2.3}\\
X(0) & =x
\end{align*}
$$

where $W_{t}=\left(W_{t}^{k}\right)_{k=1, \ldots,(n+m)}$ is a standard $m+n$-dimensional Brownian motion process on a probability space $(\Omega, \mathcal{F}, P)$. Let $N_{t}^{i}$ be the number of the shares of the $i$ th security. Then, the total wealth that the investor possesses is defined as

$$
V_{t}=\sum_{i=0}^{m} N_{t}^{i} S_{t}^{i}
$$

and the proportion of the portfolio invested in the $i$ th security is

$$
h_{t}^{i}=\frac{N_{t}^{i} S_{t}^{i}}{V_{t}}, \quad i=0,1,2, \ldots, m
$$

$N_{t}=\left(N_{t}^{0}, N_{t}^{1}, N_{t}^{2}, \ldots, N_{t}^{m}\right)\left[\right.$ or, $\left.h_{t}=\left(h_{t}^{1}, \ldots, h_{t}^{m}\right)\right]$ is called self-financing if

$$
d V_{t}=\sum_{i=0}^{m} N_{t}^{i} d S_{t}^{i}=\sum_{i=0}^{m} \frac{V_{t} h_{t}^{i}}{S_{t}^{i}} d S_{t}^{i}
$$

Thus, under the self-financing condition, we have

$$
\begin{aligned}
\frac{d V_{t}}{V_{t}} & =h_{t}^{0} r\left(X_{t}\right) d t+\sum_{i=1}^{m} h_{t}^{i}\left\{\alpha^{i}\left(X_{t}\right) d t+\sum_{j=1}^{n+m} \sigma_{j}^{i}\left(X_{t}\right) d W_{t}^{j}\right\} \\
& =r\left(X_{t}\right) d t+\sum_{i=1}^{m} h_{t}^{i}\left\{\left(\alpha^{i}\left(X_{t}\right)-r\left(X_{t}\right)\right) d t+\sum_{j=1}^{n+m} \sigma_{j}^{i}\left(X_{t}\right) d W_{t}^{j}\right\}
\end{aligned}
$$

Here we note that $h_{t}$ is defined as an $m$-vector consisting of $h_{t}^{1}, \ldots, h_{t}^{m}$ since $h_{t}^{0}=1-\sum_{i=1}^{m} h_{t}^{i}$ holds by definition.

The filtration that must be satisfied by admissible investment strategies

$$
\mathcal{G}_{t}=\sigma(S(u), X(u), u \leq t)
$$

is relevant in the present problem, and we introduce the following definition.

DEFINITION 2.1. $h(t)_{0 \leq t \leq T}$ is said to be an investment strategy if $h(t)$ is an $R^{m}$ valued $\mathcal{G}_{t}$-progressively measurable stochastic process such that

$$
P\left(\int_{0}^{T}|h(s)|^{2} d s<\infty\right)=1
$$

The set of all investment strategies is denoted by $\mathcal{H}(T)$. For a given $h \in \mathcal{H}(T)$, the process $V_{t}=V_{t}(h)$ representing the total wealth of the investor at time $t$ is determined by the stochastic differential equation shown above.

$$
\begin{align*}
\frac{d V_{t}}{V_{t}} & =r\left(X_{t}\right) d t+h(t)^{*}\left(\alpha\left(X_{t}\right)-r\left(X_{t}\right) \mathbf{1}\right) d t+h(t)^{*} \sigma\left(X_{t}\right) d W_{t}  \tag{2.4}\\
V_{0} & =v_{0}
\end{align*}
$$

where $\mathbf{1}=(1,1, \ldots, 1)^{*}$.
We are interested in the asymptotics of minimization of a downside risk for a given constant $\kappa$ in comparison with investing the whole portfolio in a riskless security as the benchmark

$$
\begin{equation*}
J(\kappa):=\underline{\lim }_{T \rightarrow \infty} \frac{1}{T} \inf _{h \in \mathcal{H}(T)} \log P\left(\frac{1}{T} \log \frac{V_{T}(h)}{S_{T}^{0}} \leq \kappa\right) \tag{2.5}
\end{equation*}
$$

We also examine downside risk minimization with the benchmark $S^{0}$ over an infinite time horizon,

$$
\begin{equation*}
J_{\infty}(\kappa):=\inf _{h \in \mathcal{H}} \underline{\lim _{T \rightarrow \infty}} \frac{1}{T} \log P\left(\frac{1}{T} \log \frac{V_{T}(h)}{S_{T}^{0}} \leq \kappa\right) \tag{2.6}
\end{equation*}
$$

where

$$
\mathcal{H}=\{h ; h \in \mathcal{H}(T), \forall T\}
$$

$J(\kappa)$ will be shown to be related to the following risk-sensitive asset allocation problem with benchmark $S^{0}$. Namely, for a given constant $\gamma<0$, let us consider the asymptotics

$$
\begin{equation*}
\hat{\chi}(\gamma)=\underline{\lim }_{T \rightarrow \infty} \frac{1}{T} \inf _{h \in \mathcal{A}(T)} J(v, x ; h ; T) \tag{2.7}
\end{equation*}
$$

where

$$
\begin{equation*}
J(v, x ; h ; T)=\log E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma}\right]=\log E\left[e^{\gamma \log \left(V_{T}(h) / S_{T}^{0}\right)}\right] \tag{2.8}
\end{equation*}
$$

and $h$ ranges over the set $\mathcal{A}(T)$ of all admissible investment strategies defined by

$$
\mathcal{A}(T)=\left\{h \in \mathcal{H}(T) ; E\left[e^{\gamma \int_{0}^{T} h_{s}^{*} \sigma\left(X_{s}\right) d W_{s}-\left(\gamma^{2} / 2\right) \int_{0}^{T} h_{s}^{*} \sigma \sigma^{*}\left(X_{s}\right) h_{s} d s}\right]=1\right\}
$$

Then we shall see that (2.5) could be considered the dual problem to (2.7), while (2.6) is the dual problem to risk-sensitive asset allocation over an infinite time horizon,

$$
\begin{equation*}
\chi_{\infty}(\gamma)=\inf _{h \in \mathcal{A}} \underline{\lim } \frac{1}{T \rightarrow \infty} J(v, x ; h ; T) \tag{2.9}
\end{equation*}
$$

where

$$
\mathcal{A}=\{h ; h \in \mathcal{A}(T) ; \forall T\} .
$$

We shall consider these problems under the assumptions that

$$
\begin{equation*}
\alpha \text { and } \beta \text { are globally Lipschitz, } \lambda \in C_{b}^{2}, \sigma, r \in C_{b}^{1}, \alpha, \beta \in C^{1} \tag{2.10}
\end{equation*}
$$

and

$$
\begin{cases}c_{1}|\xi|^{2} \leq \xi^{*} \lambda \lambda^{*}(x) \xi \leq c_{2}|\xi|^{2}, & c_{1}, c_{2}>0, \xi \in R^{n},  \tag{2.11}\\ c_{1}|\zeta|^{2} \leq \zeta^{*} \sigma \sigma^{*}(x) \zeta \leq c_{2}|\zeta|^{2}, & \zeta \in R^{m},\end{cases}
$$

hold. In considering these problems, we first introduce the value function

$$
\begin{equation*}
v(t, x)=\inf _{h . \in \mathcal{A}(T-t)} \log E\left[e^{\gamma \log \left(V_{T-t}(h) / S_{T-t}^{0}\right)}\right] . \tag{2.12}
\end{equation*}
$$

Note that

$$
e^{\gamma \log V_{T}}=v_{0}^{\gamma} e^{\gamma \int_{0}^{T}\left\{r\left(X_{s}\right)+h_{s}^{*} \hat{\alpha}\left(X_{s}\right)-(1 / 2) h_{s}^{*} \sigma \sigma^{*}\left(X_{s}\right) h_{s}\right\} d s+\gamma \int_{0}^{T} h_{s}^{*} \sigma\left(X_{s}\right) d W_{s},}
$$

where $\hat{\alpha}(x)=\alpha(x)-r(x) \mathbf{1}$. Therefore

$$
e^{\gamma\left(\log V_{T}-\log S_{T}^{0}\right)}=v_{0}^{\gamma} e^{\gamma \int_{0}^{T} \eta\left(X_{s}, h_{s}\right) d s+\gamma \int_{0}^{T} h_{s}^{*} \sigma\left(X_{s}\right) d W_{s}-\left(\gamma^{2} / 2\right) \int_{0}^{T} h_{s}^{*} \sigma \sigma^{*}\left(X_{s}\right) h_{s} d s},
$$

where

$$
\eta(x, h)=h^{*} \hat{\alpha}(x)-\frac{1-\gamma}{2} h^{*} \sigma \sigma^{*}(x) h .
$$

By introducing a probability measure

$$
P^{h}(A)=E\left[e^{\gamma \int_{0}^{T} h_{s}^{*} \sigma\left(X_{s}\right) d W_{s}-\left(\gamma^{2} / 2\right) \int_{0}^{T} h_{s}^{*} \sigma \sigma^{*}\left(X_{s}\right) h_{s} d s}: A\right],
$$

the dynamics of the factor process can be written as

$$
d X_{t}=\left\{\beta\left(X_{t}\right)+\gamma \lambda \sigma^{*}\left(X_{t}\right) h_{t}\right\} d t+\lambda\left(X_{t}\right) d W_{t}^{h}, \quad X_{0}=x
$$

with the new Brownian motion process $W_{t}^{h}$ defined by

$$
W_{t}^{h}:=W_{t}-\gamma \int_{0}^{t} \sigma^{*}\left(X_{s}\right) h_{s} d s
$$

and the value function written as

$$
\begin{equation*}
v(t, x)=\gamma \log v_{0}+\inf _{h \in \mathcal{A}(T)} \log E^{h}\left[e^{\gamma \int_{0}^{T-t} \eta\left(X_{s}, h_{s}\right) d s}\right] . \tag{2.13}
\end{equation*}
$$

The H-J-B equation for the value function $v(t, x)$ is

$$
\left\{\begin{aligned}
& \frac{\partial v}{\partial t}++\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} v\right]+\frac{1}{2}(D v)^{*} \lambda \lambda^{*} D v \\
& \quad+\inf _{h}\left\{\left[\beta+\gamma \lambda \sigma^{*} h\right]^{*} D v+\gamma \eta(x, h)\right\}=0 \\
& v(T, x)=\gamma \log v_{0}
\end{aligned}\right.
$$

which is also written as

$$
\left\{\begin{array}{l}
\frac{\partial v}{\partial t}+\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} v\right]+\beta_{\gamma}^{*} D v+\frac{1}{2}(D v)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D v-U_{\gamma}=0  \tag{2.14}\\
v(T, x)=\gamma \log v_{0}
\end{array}\right.
$$

where

$$
\begin{aligned}
\beta_{\gamma} & =\beta+\frac{\gamma}{1-\gamma} \lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \hat{\alpha} \\
N_{\gamma}^{-1} & =I+\frac{\gamma}{1-\gamma} \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma
\end{aligned}
$$

and

$$
U_{\gamma}=-\frac{\gamma}{2(1-\gamma)} \hat{\alpha}^{*}\left(\sigma \sigma^{*}\right)^{-1} \hat{\alpha}
$$

## REMARK 2.1.

$$
\begin{aligned}
& \inf _{h \in R^{m}}\left\{\left[\gamma \lambda \sigma^{*} h\right]^{*} D v+\gamma \eta(x, h)\right\} \\
&=\inf _{h \in R^{m}}\{ {\left.\left[\gamma \lambda \sigma^{*} h\right]^{*} D v-\frac{\gamma(1-\gamma)}{2} h^{*} \sigma \sigma^{*} h+\gamma h^{*} \hat{\alpha}\right\} } \\
&=\inf _{h \in R^{m}}\{ -\frac{\gamma(1-\gamma)}{2}\left[h-\frac{1}{1-\gamma}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D v\right)\right]^{*} \\
& \times \sigma \sigma^{*}\left[h-\frac{1}{1-\gamma}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D v\right)\right] \\
&\left.+\frac{\gamma}{2(1-\gamma)}\left(\hat{\alpha}+\sigma \lambda^{*} D v\right)^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D v\right)\right\}
\end{aligned}
$$

Therefore, the function

$$
\hat{h}(t, x):=\frac{1}{1-\gamma}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D v\right)
$$

defines the generator of the optimal diffusion $\hat{L}$ for $\inf _{h \in \mathcal{A}(T)} J(v, x ; h ; T)$ :

$$
\hat{L} \psi:=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \psi\right]+\left[\beta+\frac{\gamma}{1-\gamma} \lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D v\right)\right]^{*} D \psi
$$

which is seen in Proposition 2.1.
Set $\bar{v}=-v$. Then,

$$
\left\{\begin{array}{l}
\frac{\partial \bar{v}}{\partial t}+\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{v}\right]+\beta_{\gamma}^{*} D \bar{v}-\frac{1}{2}(D \bar{v})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{v}+U_{\gamma}=0  \tag{2.15}\\
\bar{v}(T, x)=-\gamma \log v_{0}
\end{array}\right.
$$

Since $I-\sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \geq 0$, which is easily seen by taking $\xi=\sigma^{*} \zeta+\mu$, with $\mu$ orthogonal to the range of $\sigma^{*}$, and seeing that $\xi^{*}\left(I-\sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma\right) \xi=\mu^{*} \mu$, we have

$$
\begin{equation*}
\frac{1}{1-\gamma} I \leq N^{-1} \leq I \tag{2.16}
\end{equation*}
$$

As for existence of a solution to (2.15) satisfying sufficient regularities, we have the following results; cf. [3, 28].

Theorem 2.1 ([3, 28]). Assume (2.10) and (2.11). Then H-J-B equation (2.15) has a solution such that

$$
\begin{aligned}
\bar{v}(t, x)+\gamma \log v_{0} & \geq 0, \\
\bar{v}, \frac{\partial \bar{v}}{\partial t}, \frac{\partial \bar{v}}{\partial x_{k}}, \frac{\partial^{2} \bar{v}}{\partial x_{k} \partial x_{j}} & \in L^{p}\left(0, T ; L_{\mathrm{loc}}^{p}\left(R^{n}\right)\right), \quad 1<\forall p<\infty, \\
\frac{\partial^{2} \bar{v}}{\partial t^{2}}, \frac{\partial^{2} \bar{v}}{\partial x_{k} \partial t}, \frac{\partial^{3} \bar{v}}{\partial x_{k} \partial x_{j} \partial x_{l}}, \frac{\partial^{3} \bar{v}}{\partial x_{k} \partial x_{j} \partial t} & \in L^{p}\left(0, T ; L_{\mathrm{loc}}^{p}\left(R^{n}\right)\right), \\
\frac{\partial \bar{v}}{\partial t} & \leq 0,
\end{aligned}
$$

and

$$
\begin{aligned}
|\nabla \bar{v}|^{2}-k_{0} \frac{\partial \bar{v}}{\partial t} \leq C & \left(\left|\nabla Q_{\gamma}\right|_{2 \rho}^{2}+\left|Q_{\gamma}\right|_{2 \rho}^{2}+\left|\nabla\left(\lambda \lambda^{*}\right)\right|_{2 \rho}^{2}\right. \\
& \left.+\left|\nabla \beta_{\gamma}\right|_{2 \rho}+\left|\beta_{\gamma}\right|_{2 \rho}^{2}+\left|U_{\gamma}\right|_{2 \rho}+\left|\nabla U_{\gamma}\right|_{2 \rho}+1\right)
\end{aligned}
$$

for $x \in B_{\rho}$ and $t \in[0, T)$, where $Q_{\gamma}=\lambda N_{\gamma}^{-1} \lambda^{*}, k_{0}=\frac{4(1+c)(1-\gamma)}{-\gamma}, c>0,|f|_{2 \rho}=$ $\sup _{\left\{x ; x \in B_{2 \rho}\right\}}|f(x)|, C$ is a universal constant and $B_{\rho}=\left\{x \in R^{n} ;|x|<\rho\right\}$.

For $\hat{h}(t, x)$, we consider the stochastic differential equation

$$
d X_{t}=\left\{\beta\left(X_{t}\right)+\gamma \lambda \sigma^{*}\left(X_{t}\right) \hat{h}\left(t, X_{t}\right)\right\} d t+\lambda\left(X_{t}\right) d W_{t}^{\hat{h}}, \quad X_{0}=x
$$

and define $\hat{h}_{t}:=\hat{h}\left(t, X_{t}\right)$ for the solution $X_{t}$ of the stochastic differential equation. Note that the solution of this stochastic differential equation is obtained by the change of measure from the solution of (2.3). Indeed, we can see that $\nabla v$ has at most linear growth under assumptions (2.10) and (2.11) from the above gradient estimates, and therefore,

$$
E\left[e^{\gamma \int_{0}^{T} \hat{h}\left(s, X_{s}\right)^{*} \sigma\left(X_{s}\right) d W_{s}-\left(\gamma^{2} / 2\right) \int_{0}^{T} \hat{h}\left(s, X_{s}\right)^{*} \sigma \sigma^{*}\left(X_{s}\right) \hat{h}\left(s, X_{s}\right) d s}\right]=1
$$

holds. Thus

$$
P^{\hat{h}}(A):=E\left[e^{\gamma \int_{0}^{T} \hat{h}\left(s, X_{s}\right)^{*} \sigma\left(X_{s}\right) d W_{s}-\left(\gamma^{2} / 2\right) \int_{0}^{T} \hat{h}\left(s, X_{s}\right)^{*} \sigma \sigma^{*}\left(X_{s}\right) \hat{h}\left(s, X_{s}\right) d s} ; A\right]
$$

defines a probability measure. Under this measure, $X_{t}$ turns out to be a solution of the above stochastic differential equation.

The following is a verification theorem, the proof of which is almost the same as the proof of Proposition 2.1, [28], and thus is omitted here.

Proposition 2.1 ([28]). Assume (2.10) and (2.11). Then $\hat{h}_{t}^{(\gamma, T)} \equiv \hat{h}_{t}:=\hat{h}(t$, $\left.X_{t}\right) \in \mathcal{A}(T)$ and it is optimal
(2.17) $\quad v(0, x)=\inf _{h .} \log E\left[e^{\gamma\left(\log V_{T}(h)-\log S_{T}^{0}\right)}\right]=\log E\left[e^{\gamma\left(\log V_{T}(\hat{h})-\log S_{T}^{0}\right)}\right]$.

Let us consider an H-J-B equation of ergodic type that is thought to be the limit equation of (2.14). Namely,

$$
\begin{equation*}
\chi=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} w\right]+\beta_{\gamma}^{*} D w+\frac{1}{2}(D w)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D w-U_{\gamma} . \tag{2.18}
\end{equation*}
$$

Set

$$
G(x):=\beta(x)-\lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \hat{\alpha}(x)
$$

and assume that

$$
\begin{equation*}
G(x)^{*} x \leq-c_{G}|x|^{2}+c_{G}^{\prime}, \quad c_{G}, c_{G}^{\prime}>0 \tag{2.19}
\end{equation*}
$$

and

$$
\begin{equation*}
\hat{\alpha}^{*}\left(\sigma \sigma^{*}\right)^{-1} \hat{\alpha} \rightarrow \infty \quad \text { as }|x| \rightarrow \infty \tag{2.20}
\end{equation*}
$$

Under these assumptions, we have a solution to the H-J-B equation of ergodic type, and the proof is given in Proposition 3.1 in Section 3.

Proposition 2.2. Assume (2.10), (2.11), (2.19) and (2.20). Then (2.18) has a solution $\left(\chi, w^{(\gamma)}\right)$ such that $w \in C^{2}\left(R^{n}\right)$,

$$
w(x) \rightarrow-\infty \quad \text { as }|x| \rightarrow \infty
$$

and the solution satisfying this condition is unique up to additive constants with respect to $w$.

We further assume that

$$
\begin{equation*}
\hat{\alpha}^{*}\left(\sigma \sigma^{*}\right)^{-1} \hat{\alpha} \geq c_{0}|x|^{2}-c_{0}^{\prime}, \quad c_{0}, c_{0}^{\prime}>0 \tag{2.21}
\end{equation*}
$$

Then we have the following theorem, and the proof is given after Proposition 4.2 in Section 4.

THEOREM 2.2. Under assumptions (2.10), (2.11), (2.19) and (2.21), we have

$$
\hat{\chi}(\gamma)=\underline{\lim }_{T \rightarrow \infty} \frac{1}{T} v(0, x ; T)=\chi(\gamma)
$$

The following results are important to prove our main results, and the proofs are given in Lemma 6.3, Lemma 7.1 and Corollary 4.1.

THEOREM 2.3. Let $\left(\chi, w^{(\gamma)}\right)$ be a solution to (2.18). Then under the assumptions of Theorem 2.2, $\chi(\gamma)$ and $w^{(\gamma)}$ are differentiable with respect to $\gamma$ and $\chi(\gamma)$ is convex. Their derivatives satisfy

$$
\begin{align*}
\chi^{\prime}(\gamma)= & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} w_{\gamma}\right]+\left(\beta_{\gamma}^{*}+\left(D w^{(\gamma)}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*}\right) D w_{\gamma} \\
& +\frac{1}{2(1-\gamma)^{2}}\left\{\hat{\alpha}+\sigma \lambda^{*} D w^{(\gamma)}\right\}^{*}\left(\sigma \sigma^{*}\right)^{-1}\left\{\hat{\alpha}+\sigma \lambda^{*} D w^{(\gamma)}\right\} \tag{2.22}
\end{align*}
$$

where $w_{\gamma}=\frac{\partial w^{(\gamma)}}{\partial \gamma}$. Furthermore,

$$
\lim _{\gamma \rightarrow-\infty} \chi^{\prime}(\gamma)=0
$$

REMARK 2.2. It is important to know the limit value $\lim _{\gamma \rightarrow-\infty} \chi^{\prime}(\gamma)$ since it determines the left endpoint of the interval of the target growth rate $\kappa$, which makes $J(\kappa)$ finite. Here we compare the results above with those to be expected for the case without a benchmark, considering asymptotics

$$
\check{\chi}(\gamma):=\lim _{T \rightarrow \infty} \frac{1}{T} \mathrm{inf}_{h .} \log E\left[e^{\gamma \log V_{T}(h)}\right] .
$$

The H-J-B equation of ergodic type of this problem becomes

$$
\check{\chi}=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \check{w}\right]+\beta_{\gamma}^{*} D \check{w}+\frac{1}{2}(D \check{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \check{w}-U_{\gamma}+\gamma r(x),
$$

and we can obtain its derivative

$$
\begin{aligned}
\check{\chi}^{\prime}(\gamma)= & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \check{w}_{\gamma}\right]+\left(\beta_{\gamma}^{*}+(D \check{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*}\right) D \check{w}_{\gamma} \\
& +\frac{1}{2(1-\gamma)^{2}}\left\{\hat{\alpha}+\sigma \lambda^{*} D \check{w}\right\}^{*}\left(\sigma \sigma^{*}\right)^{-1}\left\{\hat{\alpha}+\sigma \lambda^{*} D \check{w}\right\}+r
\end{aligned}
$$

through almost the same arguments as the current ones provided to obtain the results in the present article. The difference appears in considering the asymptotics of $\chi^{\prime}(\gamma)$ as $\gamma \rightarrow-\infty$. Indeed,

$$
\lim _{\gamma \rightarrow-\infty} \check{\chi}^{\prime}(\gamma)=\lim _{\gamma \rightarrow-\infty} \int r(x) \check{m}_{\gamma}(d x)<\infty
$$

could be seen as in [22], where $\check{m}_{\gamma}(d x)$ is the invariant measure of $\check{L}$-diffusion process and $\check{L}$ is defined by

$$
\check{L} \psi=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \psi\right]+\left(\beta_{\gamma}+\lambda N_{\gamma}^{-1} \lambda^{*} D \check{w}\right)^{*} D \psi
$$

Note that $\check{L}$ corresponds to $\bar{L}$ defined by (4.16) in the present paper and can be shown to be ergodic under suitable conditions in a manner similar to the proof of Proposition 4.3.

Now we can state our main theorems. The proofs are given in Sections 7 and 8.
THEOREM 2.4. Under the assumptions of Theorem 2.2, for $0<\kappa<\hat{\chi}^{\prime}(0-)$,

$$
\begin{equation*}
J(\kappa)=-\inf _{k \in(-\infty, \kappa]} \sup _{\gamma<0}\{\gamma k-\hat{\chi}(\gamma)\}=-\sup _{\gamma<0}\{\gamma \kappa-\hat{\chi}(\gamma)\} . \tag{2.23}
\end{equation*}
$$

Moreover, for $\gamma(\kappa)$ such that $\hat{\chi}^{\prime}(\gamma(\kappa))=\kappa \in\left(0, \hat{\chi}^{\prime}(0-)\right)$, take a strategy $\hat{h}_{t}^{(\gamma(\kappa), T)}$ defined in Proposition 2.1. Then,

$$
J(\kappa)=\lim _{T \rightarrow \infty} \frac{1}{T} \log P\left(\frac{1}{T} \log \frac{V_{T}\left(\hat{h}^{(\gamma(\kappa), T)}\right)}{S_{T}^{0}} \leq \kappa\right)
$$

For $\kappa<0$,

$$
J(\kappa)=-\sup _{\gamma<0}\{\gamma \kappa-\hat{\chi}(\gamma)\}=-\infty
$$

For the solution $w=w^{(\gamma)}$ to H-J-B equation ergodic type (2.18), let us set

$$
\bar{h}(x)=\frac{1}{1-\gamma}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)(x)
$$

Further consider the stochastic differential equation

$$
\begin{equation*}
d X_{t}=\left\{\beta\left(X_{t}\right)+\gamma \lambda \sigma^{*}\left(X_{t}\right) \bar{h}\left(X_{t}\right)\right\} d t+\lambda\left(X_{t}\right) d W_{t}^{\bar{h}}, \quad X_{0}=x \tag{2.24}
\end{equation*}
$$

and define $\bar{h}_{t}^{(\gamma(\kappa))}:=\bar{h}\left(X_{t}\right)$ for the solution $X_{t}$ of the stochastic differential equation. Then we have the following theorem.

THEOREM 2.5. Under the assumptions of Theorem 2.2, let $0<\kappa<\hat{\chi}^{\prime}(0-)$ and $\gamma(\kappa)$ be the same as above. We also assume that

$$
\begin{equation*}
\left(D w^{(\gamma)}\right)^{*} \lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*} D w^{(\gamma)}<\hat{\alpha}^{*}\left(\sigma \sigma^{*}\right)^{-1} \hat{\alpha}, \quad \gamma=\gamma(\kappa) \tag{2.25}
\end{equation*}
$$

Then

$$
J_{\infty}(\kappa)=J(\kappa)=-\inf _{k \in(-\infty, \kappa]} \sup _{\gamma<0}\{\gamma k-\hat{\chi}(\gamma)\}=-\sup _{\gamma<0}\{\gamma \kappa-\hat{\chi}(\gamma)\}
$$

and

$$
J(\kappa)=\lim _{T \rightarrow \infty} \frac{1}{T} \log P\left(\log \frac{V_{T}\left(h^{(\gamma(\kappa))}\right)}{S_{T}^{0}} \leq \kappa T\right)
$$

REMARK 2.3. In our previous paper [19], we studied similar problems without benchmarks in the case of linear Gaussian models. Specifically, we discussed the case where $\alpha(x)=A x+a, \beta(x)=B x+b, \sigma(x) \equiv \sigma, \lambda(x) \equiv \lambda$ and $r(x) \equiv r$,
in which $A, B, \sigma$ and $\lambda$ (resp., $a$ and $b$ ) are all constant matrices (resp., vectors), and $r$ is a constant. Under the main assumption that

$$
G:=B-\lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} A \text { is stable }
$$

which corresponds to (2.19) above, we obtained results similar to Theorems 2.4 and 2.5. The present paper is a natural extension to general diffusion incomplete market models. On the other hand, Hata and Sheu [22] treat the case where $\alpha(x)$ is bounded, and $\beta(x)^{*} x \leq-c|x|^{2}$ for $|x| \geq R$, in which linear Gaussian models are excluded. In that case, $U_{\gamma}$ becomes bounded and they employ quite different methods from ours to analyze H-J-B equation (2.18), while assumption (2.21) is crucial in our settings. For that reason our theorems do not include the case where $\alpha(x)$ is bounded.

REMARK 2.4. The generator of the optimal diffusion process governed by (2.24) for risk-sensitive control problem (2.9) is defined by

$$
L_{\infty} \psi:=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \psi\right]+\left[\beta_{\gamma}^{*}+\frac{\gamma}{1-\gamma}(D w)^{*} \lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*}\right] D \psi
$$

On the other hand, in proving Theorem 2.2 we introduce another type of stochastic control problem (4.9) with (4.7). The generator of the optimal diffusion process for this problem is defined by (4.16).

$$
\bar{L} \psi=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \psi\right]+\left[\beta_{\gamma}^{*}+(D w)^{*} \lambda N_{\gamma}^{-1} \lambda^{*}\right] D \psi
$$

where $w$ is a solution to H-J-B equation (2.18) of ergodic type. Then we note that $\bar{L}$ is related to $L_{\infty}$ through the gauge transform,

$$
\left[e^{-w} L_{\infty} e^{w}\right] \varphi=[\bar{L}-(\gamma \eta-\chi(\gamma))] \varphi
$$

Further, we see that $\psi_{\infty}:=e^{w}$ is an eigenfunction of $L_{\infty}+\gamma \eta$

$$
\left(L_{\infty}+\gamma \eta\right) \psi_{\infty}=\chi(\gamma) \psi_{\infty}
$$

for the principal eigenvalue $\chi(\gamma)$; cf. [11]. Note that $\bar{L}$ is ergodic as is seen in Proposition 4.3, while $L_{\infty}$ is not always ergodic.

Example. We assume (2.10) and (2.11) and that $\beta(x)=B(x) x+b(x)$, $\alpha(x)=A(x) x+a(x)$ with an $m \times n($ resp., $n \times n)$ matrix-valued bounded function $A$ (resp., $B$ ), and an $m$ (resp., $n$ )-vector-valued bounded function $a$ (resp., $b$ ) such that:
(i) $A^{*} A(x) \geq C I_{n}, \exists C>0$;
(ii) the real parts of all eigenvalues of $\left(B^{*}-A^{*} A\right)(x)$ is less than $-C_{B}$, $C_{B}>0$;
(iii) $\operatorname{Range}\left(\lambda^{*}-\sigma^{*} A\right) \subset \operatorname{Kernel}(\sigma)$.

In this case

$$
\begin{aligned}
G(x)^{*} x \equiv & \beta(x)^{*} x-\hat{\alpha}^{*}\left(\sigma \sigma^{*}\right)^{-1} \lambda^{*}(x) x \\
= & (B(x) x+b(x))^{*}-(A(x) x+a(x)-r(x) \mathbf{1})^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*}(x) x \\
= & (B(x) x+b(x))^{*} x-x^{*} A^{*}(x)\left(\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*}-A\right)(x) x \\
& +x^{*} A^{*} A(x) x-(a(x)-r(x) \mathbf{1})^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*}(x) x \\
= & x^{*}\left(B^{*}-A^{*} A\right)(x) x+b(x)^{*} x-(a(x)-r(x) \mathbf{1})^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*}(x) x,
\end{aligned}
$$

and we see that (2.19) holds. Furthermore, (2.21) holds because of (i).
3. H-J-B equations of ergodic type. Instead of (2.18), we shall study an H-$J$-B equation of ergodic type for $\bar{w}=-w^{(\gamma)}$.

$$
\begin{equation*}
-\chi=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{w}\right]+\beta_{\gamma}^{*} D \bar{w}-\frac{1}{2}(D \bar{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}+U_{\gamma} . \tag{3.1}
\end{equation*}
$$

Proposition 3.1. Assume (2.10), (2.11), (2.19) and (2.20). Then (3.1) has a solution $(\chi, \bar{w})$ such that $\bar{w} \in C^{2}\left(R^{n}\right)$,

$$
\bar{w}(x) \rightarrow \infty \quad \text { as }|x| \rightarrow \infty
$$

and the solution satisfying this condition is unique up to additive constants with respect to $\bar{w}$.

REMARK 3.1. The following notation is useful for the task at hand. Set $\Sigma:=$ $\left(\sigma \sigma^{*}\right)^{-1} \sigma$. Then

$$
\Sigma^{*}=\sigma^{*}\left(\sigma \sigma^{*}\right)^{-1}, \quad \Sigma \Sigma^{*}=\left(\sigma \sigma^{*}\right)^{-1}, \quad \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma=\sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma
$$

Moreover, we see that

$$
\Sigma N_{\gamma}^{-1}=\frac{1}{1-\gamma} \Sigma, \quad N_{\gamma}=I-\gamma \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma=I-\gamma \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma
$$

To prove Proposition 3.1, we first consider the H-J-B equation of discounted type,

$$
\begin{equation*}
\varepsilon v_{\varepsilon}=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} v_{\varepsilon}\right]+\beta_{\gamma}^{*} D v_{\varepsilon}-\frac{1}{2}\left(D v_{\varepsilon}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D v_{\varepsilon}+U_{\gamma} \tag{3.2}
\end{equation*}
$$

Note that (3.2) can be written as

$$
\begin{align*}
\varepsilon v_{\varepsilon}= & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} v_{\varepsilon}\right]+G^{*} D v_{\varepsilon}-\frac{1}{2}\left(\lambda^{*} D v_{\varepsilon}-\Sigma^{*} \hat{\alpha}\right)^{*} N_{\gamma}^{-1}\left(\lambda^{*} D v_{\varepsilon}-\Sigma^{*} \hat{\alpha}\right)  \tag{3.3}\\
& +\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}
\end{align*}
$$

Then, we consider the linear equation

$$
\begin{equation*}
\varepsilon \varphi_{\varepsilon}=L \varphi_{\varepsilon}+\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha} \tag{3.4}
\end{equation*}
$$

where

$$
L \varphi=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \varphi\right]+G^{*} D \varphi
$$

Under assumptions (2.10), (2.11) and (2.19), (3.4) has a solution $\varphi_{\varepsilon} \in C^{2}\left(R^{n}\right)$. Indeed, set $\psi_{1}(x)=c|x|^{2}, c>0$. Then, by taking $c$ to be sufficiently large, we can see that there exists $R_{0}$ such that for $R>R_{0}$,

$$
L \psi_{1}+\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}<0 \quad \text { in } B_{R}^{c}
$$

Therefore, when setting

$$
\Phi_{\varepsilon}(x)=\frac{M}{\varepsilon}+\psi_{1}(x), \quad M=\sup _{x \in B_{R}}\left|L \psi_{1}(x)+\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}(x)\right|,
$$

$\Phi_{\varepsilon}(x)$ turns out to be a supersolution to (3.4), and we can see that there exists a solution $\varphi_{\varepsilon} \in C^{2}\left(R^{n}\right)$ to (3.4) such that $0 \leq \varphi_{\varepsilon} \leq \Phi_{\varepsilon}(x)$ since $v \equiv 0$ is a subsolution.

We note that $\varphi_{\varepsilon}(x)$ is a supersolution to (3.2) which is the same equation as (3.3).

Lemma 3.1. Under the assumptions of Proposition 3.1, (3.2) has a solution such that $v_{\varepsilon} \in C^{2}\left(R^{n}\right)$ and $0 \leq v_{\varepsilon} \leq \varphi_{\varepsilon}$.

Proof. In proving the existence of the solution, we introduce a Dirichlet problem on $B_{R}, R>0$ :

$$
\begin{align*}
\varepsilon v_{\varepsilon} & =\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} v_{\varepsilon}\right]+\beta_{\gamma}^{*} D v_{\varepsilon}-\frac{1}{2}\left(D v_{\varepsilon}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D v_{\varepsilon}+U_{\gamma} \quad \text { in } B_{R},  \tag{3.5}\\
v_{\varepsilon}(x) & =\varphi_{\varepsilon}, \quad x \in \partial B_{R} .
\end{align*}
$$

Owing to Theorem 8.3 ([25], Chapter 4), Dirichlet problem (3.4) has a solution $v_{\varepsilon}$. We extend $v_{\varepsilon}$ to the whole Euclidean space as

$$
v_{\varepsilon, R}= \begin{cases}v_{\varepsilon}(x), & x \in B_{R}, \\ \varphi_{\varepsilon}, & x \in B_{R}^{c} .\end{cases}
$$

Then we can see that $v_{\varepsilon, R}$ is nonincreasing with respect to $R$. Indeed, for $R<R^{\prime}$, $v_{\varepsilon, R}$ is a supersolution to (3.3) in $B_{R^{\prime}}$, and we have

$$
\begin{aligned}
\varepsilon\left(v_{\varepsilon, R}-\right. & \left.v_{\varepsilon, R^{\prime}}\right) \\
\geq & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2}\left(v_{\varepsilon, R}-v_{\varepsilon, R^{\prime}}\right)\right]+\beta_{\gamma}^{*} D\left(v_{\varepsilon, R}-v_{\varepsilon, R^{\prime}}\right) \\
& -\frac{1}{2}\left(D v_{\varepsilon, R}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D v_{\varepsilon, R}+\frac{1}{2}\left(D v_{\varepsilon, R^{\prime}}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D v_{\varepsilon, R^{\prime}} \quad \text { in } B_{R}^{\prime} \\
= & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2}\left(v_{\varepsilon, R}-v_{\varepsilon, R^{\prime}}\right)\right]+\beta_{\gamma}^{*} D\left(v_{\varepsilon, R}-v_{\varepsilon, R^{\prime}}\right) \\
& -\frac{1}{2}\left(D v_{\varepsilon, R}+D v_{\varepsilon, R^{\prime}}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D\left(v_{\varepsilon, R}-v_{\varepsilon, R^{\prime}}\right) .
\end{aligned}
$$

Therefore, from the maximum principle (cf. Theorem 3.1 in [16]) we see that

$$
\begin{equation*}
v_{\varepsilon, R}-v_{\varepsilon, R^{\prime}} \geq 0 \tag{3.6}
\end{equation*}
$$

since $v_{\varepsilon, R}(x)=v_{\varepsilon, R^{\prime}}(x), x \in \partial B_{R^{\prime}}$. We further note that

$$
\begin{equation*}
v_{\varepsilon, R} \geq 0 \tag{3.7}
\end{equation*}
$$

for each $R$ because $\psi_{0}(x) \equiv 0$ is a subsolution to (3.2), and the maximum principle again applies.

Similar to the proof of Lemma 2.6 in [23], we have the following gradient estimate: for each $R$ and $r<\frac{R}{2}$,

$$
\begin{equation*}
\left\|\nabla v_{\varepsilon, R}\right\|_{L^{\infty}\left(B_{r}\right)} \leq M_{r} \tag{3.8}
\end{equation*}
$$

where $M_{r}$ is a constant independent of $R, \varepsilon$. Thus, when taking a sequence $R_{n}$ such that $R_{n} \uparrow \infty, v_{\varepsilon, R_{n}}$ forms a family of uniformly bounded and equicontinuous functions. Thus we can choose a subsequence $v_{\varepsilon, R_{n_{k}}}$ converging to a continuous function $v_{\varepsilon}$. Furthermore, since

$$
\begin{equation*}
\left\|v_{\varepsilon, R_{n}}\right\|_{H^{1}\left(B_{r}\right)} \leq M_{r}^{\prime} \tag{3.9}
\end{equation*}
$$

for a positive constant $M_{r}^{\prime}$ independent of $R_{n}$ and $\varepsilon$, it converges weakly in $H_{\mathrm{loc}}^{1}\left(R^{n}\right)$ to $v_{\varepsilon}$ by taking a subsequence if necessary. By similar arguments to Lemma 6.8 in [23], the convergence can be strengthened as $\nabla v_{\varepsilon, R_{n_{k}}}$ converges strongly in $L_{\mathrm{loc}}^{2}\left(R^{n}\right)$ to $\nabla v_{\varepsilon}$. As a result we can see from the regularity theorems that we have a solution $v_{\varepsilon} \in C^{2}\left(R^{n}\right)$ to (3.2). Since $v_{\varepsilon, R} \leq \varphi_{\varepsilon}$, for each $R>0$ from the maximum principle as well as (3.7), we see that $0 \leq v_{\varepsilon} \leq \varphi_{\varepsilon}$.

Set

$$
\psi_{\delta}(x):=e^{\delta|x|^{2}}, \quad \delta>0
$$

Then, by taking $\delta$ to be sufficiently small, we can see that there exists $R_{1}$ such that for $R>R_{1}$,

$$
L \psi_{\delta}(x)<-1 \quad \text { in } B_{R}^{c}
$$

Therefore, we see that $L$ and $\psi_{\delta}$ satisfy assumption (A.3) in the last section. Set $K\left(x ; \psi_{\delta}\right)=-L \psi_{\delta}$,

$$
F_{\psi}:=\left\{u(x) \in W_{\mathrm{loc}}^{2, p}\left(R^{n}\right) ; \underset{x \in B_{R}^{c}}{\operatorname{ess} \sup } \frac{|u(x)|}{\psi_{\delta}(x)}<\infty\right\}
$$

and

$$
F_{K}:=\left\{f(x) \in L_{\mathrm{loc}}^{\infty}\left(R^{n}\right) ; \operatorname{ess}_{x \in B_{R}^{c}}^{\operatorname{ess}} \frac{|f(x)|}{K(x ; \psi \delta)}<\infty\right\}
$$

Then for $f \in F_{K}$ there exists a solution $\varphi \in F_{\psi}$ to

$$
0=L \varphi+f
$$

if and only if

$$
\int f(x) m(d x)=0
$$

where $m(d x)$ is an invariant measure for $L$; cf. Proposition A. 4 in in the Appendix. Therefore, setting

$$
\begin{equation*}
\chi_{0}=\int \frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}(x) m(d x) \tag{3.10}
\end{equation*}
$$

there exists a solution $\varphi_{0} \in F_{\psi}$ to

$$
\chi_{0}=L \varphi_{0}+\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}(x)
$$

and it is known that $\varepsilon \varphi_{\varepsilon}$ converges to $\chi_{0}$ as $\varepsilon \rightarrow 0$ uniformly on each compact set.
Now we can prove Proposition 3.1.
Proof of Proposition 3.1. We first note that

$$
0 \leq v_{\varepsilon} \leq \varphi_{\varepsilon}
$$

because of Lemma 3.1. Therefore, we have

$$
\left\|\varepsilon v_{\varepsilon}\right\|_{L^{\infty}\left(B_{r}\right)} \leq K_{r}
$$

where $K_{r}$ is a constant independent of $\varepsilon$. Moreover,

$$
\left\|\nabla v_{\varepsilon}\right\|_{L^{\infty}\left(B_{r}\right)} \leq K_{r}^{\prime}
$$

for a positive constant $K_{r}^{\prime}$ independent of $\varepsilon$ in view of (3.8). Thus, similarly to the proof of Theorem 3.1 in [23], we can prove the existence of the solution $(-\chi, \bar{w})$ to (3.1) such that $\bar{w} \in W_{\mathrm{loc}}^{2, p}$. From regularity theorems we see that $\bar{w} \in C^{2}\left(R^{n}\right)$. The proof of uniqueness is similar to the proof of Lemma 3.2 in [26].

Now we have the following proposition.
Proposition 3.2. Under the assumptions of Proposition 3.1, the solution $\bar{w}$ to (3.1) satisfies

$$
\begin{equation*}
|\nabla \bar{w}(x)|^{2} \leq c\left(|x|^{2}+1\right) \tag{3.11}
\end{equation*}
$$

where $c$ is a positive constant. If we further assume (2.21), then, for each $\gamma_{0}<0$, there exists a positive constant $c\left(\gamma_{0}\right)$ such that the nonnegative solution $\bar{w}(x)=$ $\bar{w}(x ; \gamma), \gamma \leq \gamma_{0}$, satisfies

$$
\begin{equation*}
\bar{w}(x) \geq c\left(\gamma_{0}\right)|x|^{2}, \quad|x| \geq \exists R^{\prime} \tag{3.12}
\end{equation*}
$$

Proof. Set $Q_{\gamma}:=\lambda N_{\gamma}^{-1} \lambda^{*}$. Then we shall prove for each $x_{0} \in R^{n}$ that

$$
\begin{align*}
&|\nabla \bar{w}|^{2}\left(x_{0}\right) \leq K\left(\left|\nabla Q_{\gamma}\right|_{r}^{2}+\frac{1}{r^{2}}\left|Q_{\gamma}\right|_{r}^{2}+\left|\beta_{\gamma}\right|_{r}^{2}\right. \\
&\left.\quad+\left|U_{\gamma}\right|_{r}+\left|\nabla U_{\gamma}\right|_{r}+\frac{\left|\beta_{\gamma}\right|_{r}}{r}+\left|\nabla \beta_{\gamma}\right|_{r}+c\right) \tag{3.13}
\end{align*}
$$

for positive constants $K$ and $c$, where $|f|_{r}=|f|_{L^{\infty}{ }_{\left(B_{r}\left(x_{0}\right)\right)} \text {. Note that (3.13) im- }}$ plies (3.11) because of our assumptions on the coefficients $\sigma, \lambda, \beta, \alpha$ and $r$.

We have $\chi(\gamma) \leq 0$ since $\varepsilon v_{\varepsilon} \geq 0$ and $\varepsilon v_{\varepsilon} \rightarrow-\chi(\gamma) \leq \chi_{0}$ as $\varepsilon \rightarrow 0$. In the following $\beta_{\gamma}, Q_{\gamma}$ and $U_{\gamma}$ are abbreviated to $\beta, Q$ and $U$, respectively. $|\cdot|_{r}$ is abbreviated to $|\cdot|$.

By differentiating (3.1) with respect to $x_{k}$, we have

$$
\begin{align*}
0= & \frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i j k} w+\frac{1}{2}\left(\lambda \lambda^{*}\right)_{k}^{i j} D_{i j} w+\beta^{i} D_{i k} w+\beta_{k}^{i} D_{i} w \\
& -D_{i} w Q^{i j} D_{j k} w-\frac{1}{2} D_{i} w Q_{k}^{i j} D_{j} w+U_{k} \tag{3.14}
\end{align*}
$$

Set

$$
F=|\nabla w|^{2}=\sum_{k=1}^{n}\left|D_{k} w\right|^{2}
$$

Then we have

$$
\begin{aligned}
&-\frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i j} F-\beta^{i} D_{i} F+Q^{i j} D_{i} w D_{j} F \\
&=-\left(\lambda \lambda^{*}\right)^{i j} D_{j k} w D_{i k} w \\
&-D_{k} w\left\{\left(\lambda \lambda^{*}\right)^{i j} D_{i j k} w+2 \beta^{i} D_{i k} w-2 Q^{i j} D_{j} w D_{i k} w\right\} \\
&=-\left(\lambda \lambda^{*}\right)^{i j} D_{j k} w D_{i k} w \\
&+D_{k} w\left\{\left(\lambda \lambda^{*}\right)_{k}^{i j} D_{i j} w+2 \beta_{k}^{i} D_{i} w-D_{i} w Q_{k}^{i j} D_{j} w+2 U_{k}\right\} \\
& \leq-\frac{1}{2 n c_{2}}\left\{\left(\lambda \lambda^{*}\right)^{i j} D_{i j} w\right\}^{2}-\frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{j k} w D_{i k} w+\frac{c}{2 \delta}|\nabla w|^{2}+\frac{c \delta}{2}\left|D^{2} w\right|^{2} \\
&+2|\nabla \beta \| \nabla w|^{2}+|\nabla Q|^{2}|\nabla w|^{3}+2|\nabla U||\nabla w| \\
& \leq-\frac{1}{2 n c_{2}}\left(-2 \chi-2 \beta^{i} D_{i} w+D_{i} w Q^{i j} D_{j} w-2 U\right)^{2}+\frac{2 c_{2}}{\delta}|\nabla w|^{2} \\
&+2|\nabla \beta \| \nabla w|^{2}+|\nabla Q|^{2}|\nabla w|^{3}+2|\nabla U| \nabla w \mid .
\end{aligned}
$$

Here we have used (3.14) and the matrix inequality

$$
(\operatorname{tr}[A B])^{2} \leq n C \operatorname{tr}\left[A B^{2}\right]
$$

for symmetric matrix $B$ and nonnegative definite symmetric matrix $A$, where $C$ is the maximum eigenvalue of $A$. Set

$$
\tau(x):= \begin{cases}\left(\frac{\left|x-x_{0}\right|^{2}}{r^{2}}-1\right)^{2}, & \left|x-x_{0}\right| \leq r \\ 0, & \left|x-x_{0}\right|>r\end{cases}
$$

Then $\operatorname{tr}\left[\lambda \lambda^{*} D^{2} \tau\right] \geq-\frac{4 n}{r^{2}} c_{2},(D \tau)^{*} \lambda \lambda^{*} D \tau \leq \frac{16 c_{2}}{r^{2}} \tau$ and $|D \tau|^{2} \leq \frac{16 c_{2}}{c_{1} r^{2}} \tau$. Let $x$ be the maximum point of $\tau F$ in $B_{r}\left(x_{0}\right)$. Then $D(\tau F)(x)=0$ and $\operatorname{tr}\left[\lambda \lambda^{*} \times\right.$ $\left.D^{2}(\tau F)\right](x) \leq 0$. Therefore, from the maximum principle we have

$$
\begin{aligned}
0 \leq & -\frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i j}(\tau F)-\beta^{i} D_{i}(\tau F)+Q^{i j} D_{j} w D_{i}(\tau F) \\
= & \tau\left\{-\frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i j} F-\beta^{i} D_{i} F+Q^{i j} D_{j} w D_{i} F\right\} \\
& -\frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i j} \tau F-\left(\lambda \lambda^{*}\right)^{i j} D_{i} \tau D_{j} F-\left(\beta^{i} D_{i} \tau\right) F+\left(Q^{i j} D_{j} w D_{i} \tau\right) F \\
\leq & \tau\left[-\frac{1}{2 n c_{2}}\left(-2 \chi-2 \beta^{i} D_{i} w+D_{i} w Q^{i j} D_{j} w-2 U\right)^{2}+\frac{2 c_{2}}{\delta}|\nabla w|^{2}\right. \\
& \left.+2|\nabla \beta \| \nabla w|^{2}+|\nabla Q|^{2}|\nabla w|^{3}+2|\nabla U||\nabla w|\right] \\
& -F\left\{\frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i j} \tau-\frac{\left(\lambda \lambda^{*}\right)^{i j} D_{i} \tau D_{j} \tau}{\tau}-\beta^{i} D_{i} \tau+Q^{i j} D_{j} w D_{i} \tau\right\} .
\end{aligned}
$$

Since $\frac{1}{1-\gamma} \lambda \lambda^{*} \leq Q \leq \lambda \lambda^{*}$, by taking $\delta$ to be sufficiently small, $c(\gamma)|D w|^{2} \leq-2 \beta^{*} D w+(D w)^{*} Q D w+\frac{1}{\delta}|\beta|^{2} \leq\left(c_{2}+1\right)|D w|^{2}+\left(1+\frac{1}{\delta}\right)|\beta|^{2}$ for a positive constant

$$
\begin{equation*}
c(\gamma)=\frac{c_{1}}{1-\gamma}-\delta>0 \tag{3.15}
\end{equation*}
$$

Therefore, it follows that

$$
\begin{aligned}
0 \leq & -\tau\left(-2 \beta^{*} D w+(D w)^{*} Q D w+\frac{1}{\delta}|\beta|^{2}\right)^{2} \\
& +2 \tau\left(-2 \beta^{*} D w+(D w)^{*} Q D w+\frac{1}{\delta}|\beta|^{2}\right)\left(\frac{1}{\delta}|\beta|^{2}+2 U+2 \chi\right) \\
& -\tau\left(\frac{1}{\delta}|\beta|^{2}+2 U+2 \chi\right)^{2}+\tau\left(2|\nabla \beta||\nabla w|^{2}+|\nabla Q||\nabla w|^{3}+2|\nabla U||\nabla w|\right) \\
& +\frac{2 n c_{2}}{r^{2}} F+\frac{16 c_{2}}{r^{2}} F+|\beta| \frac{4 \sqrt{c_{2}}}{\sqrt{c_{1}} r} \tau^{1 / 2} F+\frac{4 \sqrt{c_{2}}}{\sqrt{c_{1}} r} \tau|Q| F^{3 / 2}
\end{aligned}
$$

$$
\begin{aligned}
\leq & -\tau c(\gamma)^{2}|\nabla w|^{4}+2 \tau\left\{\left.\left(c_{2}+1\right) \nabla w\right|^{2}+\left(1+\frac{1}{\delta}\right)|\beta|^{2}\right\}\left(\frac{1}{\delta}|\beta|^{2}+2 U\right) \\
& +\left(\frac{2 n c_{2}}{r^{2}}+\frac{16 c_{2}}{r^{2}}\right) F+|\beta| \frac{4 \sqrt{c_{2}}}{\sqrt{c_{1}} r} \tau^{1 / 2} F+\frac{4 \sqrt{c_{2}}}{\sqrt{c_{1}} r} \tau|Q| F^{3 / 2} \\
& +\tau\left(2|\nabla \beta| F+|\nabla Q| F^{3 / 2}+2|\nabla U| F^{1 / 2}\right) .
\end{aligned}
$$

We can assume $F \geq|\beta|^{2}$ and $F \geq|\nabla U|$; thus,

$$
\begin{aligned}
0 \leq & -c(\gamma)^{2} \tau F^{2}+2\left(c_{2}+2+\frac{1}{\delta}\right) \tau F\left(\frac{1}{\delta}|\beta|^{2}+2 U\right) \\
& +\left(\frac{2 n c_{2}}{r^{2}}+\frac{16 c_{2}}{r^{2}}\right) F+|\beta| \frac{4 \sqrt{c_{2}}}{\sqrt{c_{1}}} \tau^{1 / 2} F+\frac{4 \sqrt{c_{2}}}{\sqrt{c_{1}} r} \tau|Q| F^{3 / 2} \\
& +\tau\left(2|\nabla \beta| F+|\nabla Q| F^{3 / 2}+2 F^{3 / 2}\right) .
\end{aligned}
$$

Accordingly, we have

$$
\begin{aligned}
0 \leq & -c(\gamma)^{2} \tau F+\left(|\nabla Q|+\frac{4 \sqrt{c_{2}}}{\sqrt{c_{1}} r}|Q|+2\right)(\tau F)^{1 / 2} \\
& +2\left(c_{2}+2+\frac{1}{\delta}\right)\left(\frac{1}{\delta}|\beta|^{2}+2 U\right)+\frac{2 n c_{2}}{r^{2}}+\frac{16 c_{2}}{r^{2}}+\frac{4|\beta| \sqrt{c_{2}}}{\sqrt{c_{1}} r}+2|\nabla \beta| .
\end{aligned}
$$

Therefore, we obtain

$$
\begin{aligned}
\frac{1}{2} c(\gamma)^{2} \tau F \leq & \frac{1}{2 c(\gamma)^{2}}\left(|\nabla Q|+\frac{4 \sqrt{c_{2}}}{\sqrt{c_{1}}}|Q|+2\right)^{2} \\
& +c_{\delta}\left(\frac{1}{\delta}|\beta|^{2}+2 U\right)+\frac{c}{r^{2}}+\frac{c|\beta|}{r}+2|\nabla \beta|
\end{aligned}
$$

with $c_{\delta}=2\left(c_{2}+2+\frac{1}{\delta}\right)$ and universal constant $c>0$. Including the case where $|\beta|^{2} \geq F,|\nabla U| \geq F$, we obtain

$$
\begin{aligned}
F\left(x_{0}\right)= & \tau\left(x_{0}\right) F\left(x_{0}\right) \leq(\tau F)(x) \\
\leq & \frac{c}{c(\gamma)^{4}}\left(|\nabla Q|^{2}+\frac{1}{r^{2}}|Q|^{2}+c\right) \\
& +\frac{c_{\delta}^{\prime}}{c(\gamma)^{2}}\left(|\beta|^{2}+U+\frac{|\beta|}{r}+|\nabla \beta|+\frac{1}{r}\right)+|\nabla U|,
\end{aligned}
$$

and (3.13) has been proved.
Now let us prove (3.12). For each $\rho>0$ take a point $x_{\rho} \in R^{n}$ such that $\left|x_{\rho}\right|=\rho$. Set

$$
R(x)=c_{\rho}\left(1-\frac{4\left|x-x_{\rho}\right|^{2}}{\rho^{2}}\right) \quad \text { in } D_{\rho}=\left\{x ;\left|x-x_{\rho}\right| \leq \frac{\rho}{2}\right\}
$$

where $c_{\rho}$ is a positive constant determined later. Then, $R(x) \geq 0$ in $D_{\rho}$ and $R(x)=$ 0 on $\partial D_{\rho}$. Set

$$
z(x)=\bar{w}(x)-R(x)
$$

Then,

$$
z(x)=\bar{w}(x) \geq 0, \quad x \in \partial D_{\rho}
$$

Note that

$$
\xi^{*} \lambda N_{\gamma}^{-1} \lambda^{*} \xi \leq c_{2}|\xi|^{2}, \quad \xi \in R^{n}
$$

Then we have

$$
\begin{aligned}
-\chi- & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} z\right]-\beta^{*} D z \\
= & -\frac{1}{2}(D \bar{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}+U_{\gamma}+\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} R\right]+\beta^{*} D R \\
= & -\frac{1}{2} D(\bar{w}+R)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D(\bar{w}-R)-\frac{1}{2}(D R)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D R+U_{\gamma} \\
& +\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} R\right]+\beta^{*} D R \\
\geq & -\frac{1}{2} D(\bar{w}+R)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D z-\frac{c_{2}}{2}|D R|^{2}+U_{\gamma}+\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} R\right]+\beta^{*} D R
\end{aligned}
$$

Noting that $\left|\beta_{\gamma}(x)\right| \leq c \rho, x \in D_{\rho}$, for a positive constant independent of $\gamma$,

$$
\begin{aligned}
-\chi & -\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} z\right]-\beta^{*} D z+\frac{1}{2} D(\bar{w}+R)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D z \\
& \geq-\frac{c_{2}}{2}|D R|^{2}+U(x)-\frac{4 c_{\rho}}{\rho^{2}} \operatorname{tr}\left[\lambda \lambda^{*}\right]-4 c c \rho \\
& \geq-\frac{8 c_{2} c_{\rho}^{2}}{\rho^{2}}+\frac{-\gamma}{2(1-\gamma)} c_{0}\left(\frac{|\rho|^{2}}{4}+1\right)-\frac{4 c_{2} n c_{\rho}}{\rho^{2}}-4 c c_{\rho} \\
& \geq-\left(8 c_{2} \frac{c_{\rho}^{2}}{\rho^{2}}+4 c_{2} n \frac{c_{\rho}}{\rho^{2}}+4 c c_{\rho}\right)+\frac{-\gamma_{0} c_{0} \rho^{2}}{8\left(1-\gamma_{0}\right)}+\frac{-\gamma_{0} c_{0}}{2\left(1-\gamma_{0}\right)} .
\end{aligned}
$$

By setting $c_{\rho}=c\left(\gamma_{0}\right) \rho^{2}$ with $c\left(\gamma_{0}\right)$ such that $8 c_{2} c\left(\gamma_{0}\right)^{2}+4 c c\left(\gamma_{0}\right)<\frac{-\gamma_{0} c_{0}}{8\left(1-\gamma_{0}\right)}$ and $4 c_{2} n c\left(\gamma_{0}\right)<\frac{-\gamma_{0} c_{0}}{2\left(1-\gamma_{0}\right)}$, we see that

$$
-\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} z\right]-\beta^{*} D z+\frac{1}{2} D(\bar{w}+R)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D z \geq M>0 \quad \text { in } D_{\rho}
$$

for some positive constant and sufficiently large $\rho$. Then $z$ is superharmonic in $D_{\rho}$ and $z(x) \geq 0, x \in \partial D_{\rho}$. Therefore $z(x) \geq 0, x \in D_{\rho}$, from which we have

$$
z\left(x_{\rho}\right)=\bar{w}\left(x_{\rho}\right)-c_{\rho} \geq 0
$$

Hence, $\bar{w}\left(x_{\rho}\right) \geq c\left(\gamma_{0}\right) \rho^{2}$.
4. H-J-B equations and related stochastic control problems. Let us come back to H-J-B equation (2.15). According to assumption (2.10), we have a positive constant $c_{\beta}$ such that

$$
\left|\beta_{\gamma}(x)\right|^{2} \leq c_{\beta}\left(|x|^{2}+1\right)
$$

We strengthen condition (2.20) to (2.21). Then we have the following lemma.
Lemma 4.1. Assume (2.10), (2.11), (2.21) and $v_{0} \geq 1$. Then for each $t<T$ there exist positive constants $k=k(T-t)$ and $k^{\prime}=k^{\prime}(T-t)$ such that

$$
\begin{equation*}
\bar{v}(t, x ; T) \geq k|x|^{2}-k^{\prime} \tag{4.1}
\end{equation*}
$$

Proof. Choose a positive constant $c$ such that

$$
c_{\gamma}-\frac{c}{2} c_{\beta}>0
$$

and set $b=c_{\gamma}-\frac{c}{2} c_{\beta}$, where $c_{\gamma}=-\frac{\gamma c_{0}}{2(1-\gamma)}$, and set

$$
R(t, x):=\frac{1}{2} x^{*} P(t) x+q(t)
$$

where $P(t)$ is a solution to the Riccati equation

$$
\begin{equation*}
\dot{P}(t)-\left(\frac{c_{2}}{1-\gamma}+\frac{1}{c}\right) P(t) I_{n} P(t)+b I_{n}=0, \quad P(T)=0 \tag{4.2}
\end{equation*}
$$

and $q(t)$ is a solution to the ordinary equation

$$
\begin{equation*}
\dot{q}(t)+\frac{c_{1}}{2} \operatorname{tr}[P(t)]-\frac{c c_{\beta}}{2}-c_{\gamma}^{\prime}=0, \quad q(T)=-\gamma \log v_{0}, \tag{4.3}
\end{equation*}
$$

where $c_{\gamma}^{\prime}=-\frac{c_{0}^{\prime} \gamma}{2(1-\gamma)}$. Set

$$
z(t, x):=\bar{v}(t, x)-R(t, x)
$$

Then

$$
\begin{aligned}
-\frac{\partial z}{\partial t}- & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} z\right]-\beta_{\gamma}^{*} D z \\
= & \frac{1}{2}(D \bar{v})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{v}+U_{\gamma}+\frac{\partial R}{\partial t}+\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} R\right]+\beta^{*} D R \\
= & -\frac{1}{2} D(\bar{v}+R)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D(\bar{v}-R)-\frac{1}{2} D R^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D R+U_{\gamma} \\
& +\frac{\partial R}{\partial t}+\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} R\right]+\beta^{*} D R \\
\geq & -\frac{1}{2} D(\bar{v}+R)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D(\bar{v}-R)-\frac{c_{2}}{2(1-\gamma)}(D R)^{*} I_{n} D R+c_{\gamma}|x|^{2}-c_{\gamma}^{\prime} \\
& +\frac{1}{2} x^{*} \dot{P}(t) x+\dot{q}(t)+\frac{c_{1}}{2} \operatorname{tr}[P(t)]-\frac{c}{2} \beta_{\gamma}^{*} \beta_{\gamma}-\frac{1}{2 c}(D R)^{*} D R .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
-\frac{\partial z}{\partial t}- & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} z\right]-\beta^{*} D z+\frac{1}{2} D(\bar{v}+R)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D z \\
\geq & \frac{1}{2} x^{*} \dot{P}(t) x-\frac{1}{2}\left(\frac{c_{2}}{1-\gamma}+\frac{1}{c}\right) x^{*} P(t) I_{n} P(t) x+\left(c_{\gamma}-\frac{c c_{\beta}}{2}\right)|x|^{2} \\
& +\dot{q}(t)+\frac{c_{1}}{2} \operatorname{tr}[P(t)]-\frac{c c_{\beta}}{2}-c_{\gamma}^{\prime} \\
\geq & \frac{1}{2}\left(c_{\gamma}-\frac{c c_{\beta}}{2}\right)|x|^{2} \geq 0
\end{aligned}
$$

Thus we see that $z(t, x)$ is super harmonic in $[0, T) \times R^{n}$, and $z(T, x)=0$. Therefore we have $z(t, x)=\bar{v}(t, x)-R(t, x) \geq 0$, that is,

$$
\bar{v}(t, x) \geq R(t, x)=\frac{1}{2} x^{*} P(t) x+q(t) .
$$

Since $P(t)$ is positive definite,

$$
\bar{v}(t, x) \geq k|x|^{2}-k^{\prime}, \quad k=k(T-t), k^{\prime}=k^{\prime}(T-t)>0 .
$$

Let us rewrite (2.15) as

$$
\left\{\begin{array}{l}
0=\frac{\partial \bar{v}}{\partial t}+\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{v}\right]+G^{*} D \bar{v}  \tag{4.4}\\
\quad-\frac{1}{2}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)^{*} N_{\gamma}^{-1}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)+\frac{1}{2} \hat{\alpha}^{*} \Sigma \Sigma^{*} \hat{\alpha}, \\
\bar{v}(T, x)=-\gamma \log v_{0} .
\end{array}\right.
$$

Noting that

$$
\begin{aligned}
& -\frac{1}{2}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)^{*} N_{\gamma}^{-1}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right) \\
& =\inf _{z \in R^{n+m}}\left\{\frac{1}{2} z^{*} N_{\gamma} z-z^{*} \Sigma^{*} \hat{\alpha}+(\lambda z)^{*} D \bar{v}\right\} \\
& =\inf _{z \in R^{n+m}}\left[\frac{1}{2}\left\{z+N_{\gamma}^{-1}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)\right\}^{*} N_{\gamma}\left\{z+N_{\gamma}^{-1}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)\right\}\right. \\
& \\
& \left.\quad-\frac{1}{2}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)^{*} N_{\gamma}^{-1}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)\right]
\end{aligned}
$$

we can rewrite it again as

$$
\left\{\begin{array}{l}
0=\frac{\partial \bar{v}}{\partial t}+\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{v}\right]+G^{*} D \bar{v}+\inf _{z \in R^{n+m}}\left\{(\lambda z)^{*} D \bar{v}+\varphi(x, z)\right\},  \tag{4.5}\\
\bar{v}(T, x)=-\gamma \log v_{0},
\end{array}\right.
$$

where

$$
\varphi(x, z)=\frac{1}{2} z^{*} N_{\gamma} z-z^{*} \Sigma^{*} \hat{\alpha}+\frac{1}{2} \hat{\alpha}^{*} \Sigma \Sigma^{*} \hat{\alpha}, \quad N_{\gamma}=I-\gamma \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma .
$$

This H-J-B equation corresponds to the following stochastic control problem, the value of which is defined as

$$
\begin{equation*}
\inf _{Z . \in \tilde{\mathcal{A}}(T)} E\left[\int_{0}^{T} \varphi\left(Y_{s}, Z_{s}\right) d s-\gamma \log v_{0}\right] \tag{4.6}
\end{equation*}
$$

where $Y_{t}$ is a controlled process governed by the stochastic differential equation

$$
\begin{equation*}
d Y_{t}=\lambda\left(Y_{t}\right) d W_{t}+\left\{G\left(Y_{t}\right)+\lambda\left(Y_{t}\right) Z_{t}\right\} d t, \quad Y_{0}=x \tag{4.7}
\end{equation*}
$$

with control $Z_{t} \in \tilde{\mathcal{A}}(T)$. Here, $\tilde{\mathcal{A}}(T)$ is the set of all $R^{n+m}$ valued progressively measurable processes such that

$$
E\left[\int_{0}^{T}\left|Z_{s}\right|^{2} d s\right]<\infty
$$

To study this problem, we introduce a value function for $0 \leq t \leq T$,

$$
v_{*}(t, x)=\inf _{Z \in \tilde{\mathcal{A}}(T-t)} E\left[\int_{0}^{T-t} \varphi\left(Y_{s}, Z_{s}\right) d s-\gamma \log v_{0}\right] .
$$

By the verification theorem, the solution $\bar{v}$ to (4.5) can be identified with the value function $v_{*}$. Indeed, set

$$
\hat{z}(s, x)=-N_{\gamma}^{-1}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)(s, x)
$$

which attains the infimum in (4.5), and consider the stochastic differential equation

$$
\begin{equation*}
d \hat{Y}_{t}=\lambda\left(\hat{Y}_{t}\right) d W_{t}+\left\{G\left(\hat{Y}_{t}\right)+\lambda\left(\hat{Y}_{t}\right) \hat{Z}\left(t, \hat{Y}_{t}\right)\right\} d t, \quad Y_{0}=x \tag{4.8}
\end{equation*}
$$

From the estimates obtained in Theorem 2.1, we see that (4.8) has a unique solution. It is also seen by using Itô's theorem that

$$
\bar{v}(0, x)=E\left[\int_{0}^{T} \varphi\left(\hat{Y}_{s}, \hat{Z}_{s}\right) d s-\gamma \log v_{0}\right]
$$

holds, where $\hat{Z}_{s}=\hat{Z}\left(s, \hat{Y}_{s}\right)$. In a similar way, we can see that

$$
\bar{v}(0, x) \leq E\left[\int_{0}^{T} \varphi\left(Y_{S}, Z_{s}\right) d s-\gamma \log v_{0}\right]
$$

for each $Z . \in \tilde{\mathcal{A}}(T)$, hence, $\bar{v}(0, x)=v_{*}(0, x)$.
Let us consider the following stochastic control problem with the averaging cost criterion:

$$
\begin{equation*}
\rho(\gamma)=\inf _{Z . \in \mathcal{A}} \limsup _{T \rightarrow \infty} \frac{1}{T} E\left[\int_{0}^{T} \varphi\left(Y_{s}, Z_{s}\right) d s\right], \tag{4.9}
\end{equation*}
$$

where $Y_{t}$ is a controlled process governed by controlled stochastic differential equation (4.7) with control $Z_{t}$. The solution $Y_{t}$ of (4.7) is sometimes written as $Y_{t}^{(Z)}$ to make clear the dependence on control $Z_{t}$, and the set $\tilde{\mathcal{A}}$ of all admissible controls is defined as follows:
$\tilde{\mathcal{A}}=\left\{Z . ; Z_{t}\right.$ is an $R^{n+m}$ valued progressively measurable process such that

$$
\left.\limsup _{T \rightarrow \infty} \frac{1}{T} E\left[\left|Y_{T}^{(Z)}\right|^{2}\right]=0, E\left[\int_{0}^{T}\left|Z_{s}\right|^{2} d s\right]<\infty, \forall T\right\}
$$

Corresponding to this stochastic control problem, H-J-B equation of ergodic type (3.1) can be written as

$$
\begin{equation*}
-\chi(\gamma)=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{w}\right]+G^{*} D \bar{w}+\inf _{z \in R^{n+m}}\left\{(\lambda z)^{*} D \bar{w}+\varphi(x, z)\right\} \tag{4.10}
\end{equation*}
$$

We then set

$$
\begin{equation*}
\hat{z}(x)=-N_{\gamma}^{-1}\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right)(x) \tag{4.11}
\end{equation*}
$$

and consider stochastic differential equation

$$
\begin{align*}
d \bar{Y}_{t} & =\lambda\left(\bar{Y}_{t}\right) d W_{t}+\left\{G\left(\bar{Y}_{t}\right)+\lambda\left(\bar{Y}_{t}\right) \hat{z}\left(\bar{Y}_{t}\right)\right\} d t \\
& =\lambda\left(\bar{Y}_{t}\right) d W_{t}+\left\{\beta_{\gamma}-\lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}\right\}\left(\bar{Y}_{t}\right) d t  \tag{4.12}\\
\bar{Y}_{0} & =x
\end{align*}
$$

We shall prove the following proposition.

PROPOSITION 4.1. $\quad-\chi(\gamma)=\rho(\gamma)$ and

$$
\begin{equation*}
\rho(\gamma)=\lim _{T \rightarrow \infty} \frac{1}{T} E\left[\int_{0}^{T} \varphi\left(\bar{Y}_{S}, \bar{Z}_{s}\right) d s\right] \tag{4.13}
\end{equation*}
$$

where $\bar{Z}_{s}=\hat{z}\left(\bar{Y}_{s}\right)$.

For the proof of this proposition, we prepare the following lemma.

Lemma 4.2. Under assumptions (2.10), (2.11), (2.19) and (2.21) the following estimates hold. For each $\gamma_{1}<\gamma_{0}<0$ there exist positive constants $\delta>0$ and $C>0$ independent of $T$ and $\gamma$ with $\gamma_{1} \leq \gamma \leq \gamma_{0}$ such that

$$
\begin{equation*}
E\left[e^{\delta \bar{w}\left(\bar{Y}_{T}\right)}\right] \leq C \tag{4.14}
\end{equation*}
$$

and also

$$
\begin{equation*}
E\left[e^{\delta\left|\bar{Y}_{T}\right|^{2}}\right] \leq C \tag{4.15}
\end{equation*}
$$

Proof. Let us set

$$
\begin{align*}
\bar{L} \psi & =\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \psi\right]+(G+\lambda \hat{z})^{*} D \psi  \tag{4.16}\\
& =\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \psi\right]+\left(\beta_{\gamma}-\lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}\right)^{*} D \psi
\end{align*}
$$

Then we have

$$
\begin{aligned}
-\chi(\gamma)= & \bar{L} \bar{w}+\varphi(x, \hat{z}(x)) \\
= & \bar{L} \bar{w}+\frac{1}{2}\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right)^{*} N_{\gamma}^{-1}\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right) \\
& +\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right)^{*} N^{-1} \Sigma^{*} \hat{\alpha}+\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha} \\
= & \bar{L} \bar{w}+\frac{1}{2}\left(\lambda^{*} D \bar{w}\right)^{*} N_{\gamma}^{-1} \lambda^{*} D \bar{w}-\frac{\gamma}{2(1-\gamma)} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha} .
\end{aligned}
$$

Therefore, by applying Itô's formula, we have

$$
\begin{aligned}
e^{\delta \bar{w}\left(\bar{Y}_{t}\right)}-e^{\delta \bar{w}\left(\bar{Y}_{0}\right)}= & \delta \int_{0}^{t}\left\{\bar{L} \bar{w}\left(\bar{Y}_{s}\right)+\frac{\delta}{2}(D \bar{w})^{*} \lambda \lambda^{*} D \bar{w}\right\} e^{\delta \bar{w}^{\prime}}\left(\bar{Y}_{s}\right) d s \\
& +\delta \int_{0}^{t} e^{\delta \bar{w}}(D \bar{w})^{*} \lambda\left(\bar{Y}_{S}\right) d W_{s} \\
= & \delta \int_{0}^{t}\left\{-\chi-\frac{1}{2}(D \bar{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}\right. \\
& \left.+\frac{\gamma}{2(1-\gamma)} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}+\frac{\delta}{2}(D \bar{w})^{*} \lambda \lambda^{*} D \bar{w}\right\} e^{\delta \bar{w}}\left(\bar{Y}_{s}\right) d s \\
& +\delta \int_{0}^{t} e^{\delta \bar{w}}(D \bar{w})^{*} \lambda\left(\bar{Y}_{S}\right) d W_{s}
\end{aligned}
$$

Thus, for $p>0$,

$$
\begin{aligned}
d\left(e^{\delta \bar{w}\left(\bar{Y}_{t}\right)} e^{p \delta t}\right)= & e^{p \delta t} d e^{\delta \bar{w}\left(\bar{Y}_{t}\right)}+p \delta e^{p \delta t} e^{\delta \bar{w}\left(\bar{Y}_{t}\right)} d t \\
= & e^{p \delta t} \delta\left\{-\chi-\frac{1}{2}(D \bar{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}\right. \\
& \left.+\frac{\gamma}{2(1-\gamma)} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}+\frac{\delta}{2}(D \bar{w})^{*} \lambda \lambda^{*} D \bar{w}+p\right\} e^{\delta \bar{w}}\left(\bar{Y}_{t}\right) d t \\
& +\delta e^{p \delta t} e^{\delta \bar{w}\left(\bar{Y}_{t}\right)}(D \bar{w})^{*} \lambda\left(\bar{Y}_{t}\right) d W_{t} .
\end{aligned}
$$

Taking into account (2.21) and (2.16), for $\delta>0$ such that $\delta<\frac{c_{1}}{1-\gamma}$, we have

$$
\begin{aligned}
-\chi & -\frac{1}{2}(D \bar{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}+\frac{\gamma}{2(1-\gamma)} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}+\frac{\delta}{2}(D \bar{w})^{*} \lambda \lambda^{*} D \bar{w}+p \\
& \leq-k_{1}|x|^{2}+k_{2}
\end{aligned}
$$

for $k_{1}, k_{2}>0$. Thus, we obtain

$$
\begin{aligned}
e^{\delta \bar{w}\left(\bar{Y}_{t}\right)+p \delta t} \leq & e^{\delta \bar{w}(x)}+\delta \int_{0}^{t} e^{p \delta s+\delta \bar{w}\left(\bar{Y}_{s}\right)}\left\{-k_{1}\left|\bar{Y}_{s}\right|^{2}+k_{2}\right\} d s \\
& +\delta \int_{0}^{t} e^{p \delta s+\delta \bar{w}\left(\bar{Y}_{s}\right)}(D \bar{w})^{*} \lambda\left(\bar{Y}_{s}\right) d W_{s}
\end{aligned}
$$

Therefore, taking

$$
\tau=\tau_{R}:=\inf \left\{t ;\left|\bar{Y}_{t}\right| \geq R\right\}
$$

and setting

$$
k_{3}=\sup _{|y| \leq \sqrt{k_{2} / k_{1}}} \bar{w}(y)
$$

we see that

$$
\begin{aligned}
E\left[e^{\delta \bar{w}\left(\bar{Y}_{t \wedge \tau}\right)+p \delta(t \wedge \tau)}\right] & \leq e^{\delta \bar{w}(x)}+\delta E\left[\int_{0}^{t \wedge \tau} e^{p \delta s+\delta \bar{w}\left(\bar{Y}_{s}\right)}\left\{-k_{1}\left|\bar{Y}_{S}\right|^{2}+k_{2}\right\} d s\right] \\
& \leq e^{\delta \bar{w}(x)}+\delta k_{2} E\left[\int_{0}^{t \wedge \tau} e^{p \delta s+\delta \bar{w}\left(\bar{Y}_{s}\right)} \mathbf{1}_{\left\{\left|\bar{Y}_{S}\right|^{2} \leq k_{2} / k_{1}\right\}} d s\right] \\
& \leq e^{\delta \bar{w}(x)}+\delta k_{2} e^{\delta k_{3}} E\left[\int_{0}^{t \wedge \tau} e^{p \delta s} d s\right] \\
& =e^{\delta \bar{w}(x)}+k_{2} e^{\delta k_{3}} E\left[\frac{1}{p}\left(e^{p \delta(t \wedge \tau)}-1\right)\right] .
\end{aligned}
$$

By letting $R$ tend to $\infty$, we have

$$
E\left[e^{\delta \bar{w}\left(\bar{Y}_{t}\right)+p \delta t}\right] \leq e^{\delta \bar{w}(x)}+k_{2} e^{\delta k_{3}} \frac{1}{p}\left(e^{p \delta t}-1\right) .
$$

Hence,

$$
\begin{aligned}
E\left[e^{\delta \bar{w}\left(\bar{Y}_{t}\right)}\right] & \leq e^{-p \delta t+\delta \bar{w}(x)}+k_{2} e^{\delta k_{3}} \frac{1}{p}\left(1-e^{-p \delta t}\right) \\
& \leq e^{\delta \bar{w}(x)}+k_{2} e^{\delta k_{3}} \frac{1}{p}
\end{aligned}
$$

Finally, we see that (4.15) follows from (4.14) because of (3.12).

Proof of Proposition 4.1. From (4.10) it follows that

$$
-\chi(\gamma) \leq \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{w}\right]+G^{*} D \bar{w}+(\lambda z)^{*} D \bar{w}+\varphi(x, z)
$$

for each $z \in R^{n+m}$. Therefore, for each control $Z_{t}$ we have

$$
\begin{aligned}
\bar{w}\left(Y_{t}\right)-\bar{w}(x)= & \int_{0}^{T}\left(D \bar{w}\left(Y_{s}\right)\right)^{*} \lambda\left(Y_{s}\right) d W_{s}+\int_{0}^{T}\left\{G\left(Y_{s}\right)+\lambda\left(Y_{s}\right) Z_{s}\right\}^{*} D \bar{w}\left(Y_{s}\right) d s \\
& +\frac{1}{2} \int_{0}^{T} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{w}\right]\left(Y_{s}\right) d s \\
\geq & \int_{0}^{T}\left(D \bar{w}\left(Y_{s}\right)\right)^{*} \lambda\left(Y_{s}\right) d W_{s}-\chi T-\int_{0}^{T} \varphi\left(Y_{s}, Z_{s}\right) d s
\end{aligned}
$$

Thus,

$$
\bar{w}(x)-\chi T \leq E\left[\int_{0}^{T} \varphi\left(Y_{s}, Z_{s}\right) d s+\bar{w}\left(Y_{T}\right)\right]
$$

from which we obtain

$$
\begin{aligned}
-\chi & \leq \limsup _{T \rightarrow \infty} \frac{1}{T} E\left[\int_{0}^{T} \varphi\left(Y_{s}, Z_{s}\right) d s+\bar{w}\left(Y_{T}\right)\right] \\
& =\limsup _{T \rightarrow \infty} \frac{1}{T} E\left[\int_{0}^{T} \varphi\left(Y_{s}, Z_{s}\right) d s\right]
\end{aligned}
$$

since $|\bar{w}(y)|^{2} \leq c|y|^{2}+c^{\prime}$. Namely, we have $-\chi(\gamma) \leq \rho(\gamma)$. On the other hand, by taking $Z_{t}=\bar{Z}_{t}$, we have

$$
\bar{w}\left(\bar{Y}_{t}\right)-\bar{w}(x)=\int_{0}^{T}\left(D \bar{w}\left(\bar{Y}_{s}\right)\right)^{*} \lambda\left(\bar{Y}_{s}\right) d W_{s}-\chi T-\int_{0}^{T} \varphi\left(\bar{Y}_{s}, \bar{Z}_{s}\right) d s
$$

and thus

$$
\bar{w}(x)-\chi T=E\left[\int_{0}^{T} \varphi\left(\bar{Y}_{s}, \bar{Z}_{s}\right) d s+\bar{w}\left(\bar{Y}_{T}\right)\right]
$$

Lemma 4.2 implies

$$
-\chi=\limsup _{T \rightarrow \infty} \frac{1}{T} E\left[\int_{0}^{T} \varphi\left(\bar{Y}_{S}, \bar{Z}_{S}\right) d s\right] \geq \rho
$$

and we see that $-\chi(\gamma)=\rho(\gamma)$.
Let us define
(4.17) $\bar{\chi}(\gamma)=\limsup _{T \rightarrow \infty} \frac{1}{T} \inf _{Z \in \tilde{\mathcal{A}}} E\left[\int_{0}^{T} \varphi\left(Y_{S}, Z_{S}\right) d s\right]=\limsup _{T \rightarrow \infty} \frac{1}{T} \bar{v}(0, x ; T)$.

Then we can see that

$$
\bar{\chi} \leq \rho(\gamma)=-\chi(\gamma)
$$

Proposition 4.2. Assume (2.10), (2.11), (2.19) and (2.21). Then

$$
\bar{\chi}(\gamma)=\rho(\gamma)=-\chi(\gamma) .
$$

The proof of Theorem 2.2 follows directly from this proposition since $\bar{\chi}(\gamma)=$ $-\hat{\chi}(\gamma)$ because of Proposition 2.1.

For the proof of the present proposition, we prepare some lemmas.
For each $T>0$, we take the controlled process $\hat{Y}_{t}=\hat{Y}_{t}^{(T)}$ defined by (4.8) and control $\hat{z}\left(t, \hat{Y}_{t}^{(T)}\right)$. Taking a sequence $\left\{T_{n}\right\}$ such that

$$
\bar{\chi}=\lim _{T_{n} \rightarrow \infty} \frac{1}{T_{n}} \bar{v}\left(0, x ; T_{n}\right)=\lim _{T_{n} \rightarrow \infty} \frac{1}{T_{n}} E\left[\int_{0}^{T_{n}} \varphi\left(\hat{Y}_{t}^{\left(T_{n}\right)}, \hat{z}\left(t, \hat{Y}_{t}^{\left(T_{n}\right)}\right)\right) d t\right],
$$

we have the following lemma.
Lemma 4.3. Under the assumptions of Proposition 4.2, for each $t>0$ we have

$$
\begin{equation*}
\liminf _{T_{n} \rightarrow \infty} \frac{1}{T_{n}} E\left[\left|\hat{Y}_{T_{n}-t}^{\left(T_{n}\right)}\right|^{2}\right]=0 \tag{4.18}
\end{equation*}
$$

Proof. Set

$$
\hat{L} \psi:=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \psi\right]+(G+\lambda \hat{z}(t, x))^{*} D \psi .
$$

Then

$$
\begin{aligned}
\bar{v}(T & \left.-t, \hat{Y}_{T-t} ; T\right)-\bar{v}(0, x ; T) \\
& =\int_{0}^{T-t}\left(\frac{\partial \bar{v}}{\partial t}+\hat{L}\left(s, \hat{Y}_{s}\right)\right) d s+\int_{0}^{T-t}(D \bar{v})\left(s, \hat{Y}_{s}\right) d W_{s} \\
& =-\int_{0}^{T-t} \varphi\left(\hat{Y}_{S}, \hat{z}\left(s, \hat{Y}_{S}\right)\right) d s+\int_{0}^{T-t}\left(D \bar{v}\left(s, \hat{Y}_{S}\right)\right)^{*} \lambda\left(\hat{Y}_{S}\right) d W_{s}
\end{aligned}
$$

Therefore,

$$
\bar{v}\left(0, x ; T_{n}\right)=E\left[\int_{0}^{T_{n}-t} \varphi\left(\hat{Y}_{s}^{\left(T_{n}\right)}, \hat{z}\left(s, \hat{Y}_{s}^{\left(T_{n}\right)}\right)\right) d s+\bar{v}\left(T_{n}-t, \hat{Y}_{T_{n}-t}^{\left(T_{n}\right)} ; T_{n}\right)\right] .
$$

Since

$$
\limsup _{T_{n} \rightarrow \infty} \frac{1}{T_{n}} E\left[\int_{0}^{T_{n}-t} \varphi\left(\hat{Y}_{s}^{\left(T_{n}\right)}, \hat{z}\left(s, \hat{Y}_{s}^{\left(T_{n}\right)}\right) d s\right] \geq \bar{\chi}\right.
$$

we have

$$
\begin{equation*}
\liminf _{T_{n} \rightarrow \infty} \frac{1}{T_{n}} E\left[\bar{v}\left(T_{n}-t, \hat{Y}_{T_{n}-t}^{\left(T_{n}\right)} ; T_{n}\right)\right]=0 \tag{4.19}
\end{equation*}
$$

Noting that $\bar{v}\left(T_{n}-t, x ; T_{n}\right) \geq k|x|^{2}-k^{\prime}, k=k(t)$ and $k^{\prime}=k^{\prime}(t)$, because of Lemma 4.1, we obtain

$$
0 \leq \liminf _{T_{n} \rightarrow \infty} \frac{1}{T_{n}} k E\left[\left|\hat{Y}_{T_{n}-t}^{\left(T_{n}\right)}\right|^{2}\right] \leq 0
$$

and our lemma has been proved.
LEMMA 4.4. Under the assumptions of Proposition 4.2, there exists a subsequence $\left\{T_{n}^{\prime}\right\} \subset\left\{T_{n}\right\}$ such that

$$
\lim _{T_{n}^{\prime} \rightarrow \infty} \frac{1}{T_{n}^{\prime}} E\left[\left|\hat{Y}_{T_{n}^{\prime}}^{\left(T_{n}^{\prime}\right)}\right|^{2}\right]=0
$$

Proof.

$$
\begin{aligned}
\left|\hat{Y}_{T}^{(T)}\right|^{2}-\left|\hat{Y}_{T-t}^{(T)}\right|^{2}= & 2 \int_{T-t}^{T}\left(\hat{Y}_{s}^{(T)}\right)^{*} \lambda\left(\hat{Y}_{s}^{(T)}\right) d W_{s} \\
& +2 \int_{T-t}^{T} \hat{Y}_{s}^{(T)}\left\{G\left(\hat{Y}^{(T)}\right)+\lambda\left(\hat{Y}_{s}^{(T)}\right) \hat{z}\left(s, \hat{Y}_{s}^{(T)}\right)\right\} d s \\
& +\int_{T-t}^{T} \operatorname{tr}\left[\lambda \lambda\left(\hat{Y}_{s}^{(T)}\right)\right] d s
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
E\left[\left|\hat{Y}_{T}^{(T)}\right|^{2}\right]=E\left[\left|\hat{Y}_{T-t}^{(T)}\right|^{2}\right]+2 E\left[\int _ { T - t } ^ { T } \hat { Y } _ { s } ^ { ( T ) } \left\{G\left(\hat{Y}^{(T)}\right)\right.\right. & \left.+\lambda\left(\hat{Y}_{s}^{(T)}\right) \hat{z}\left(s, \hat{Y}_{s}^{(T)}\right)\right\} d s \\
& \left.+\int_{T-t}^{T} \operatorname{tr}\left[\lambda \lambda\left(\hat{Y}_{s}^{(T)}\right)\right] d s\right]
\end{aligned}
$$

By using the gradient estimates in Theorem 2.1 and (2.19) we obtain

$$
y^{*} G(y)+y^{*} \lambda(y) \hat{z}(s, y) \leq c\left(|y|^{2}+1\right)
$$

for some positive constant $c$ and

$$
\begin{aligned}
E\left[\left|\hat{Y}_{T}^{(T)}\right|^{2}\right] & \leq E\left[\left|\hat{Y}_{T-t}^{(T)}\right|^{2}\right]+c E\left[\int_{T-t}^{T}\left|\hat{Y}_{s}^{(T)}\right|^{2} d s\right] \\
& \leq E\left[\left|\hat{Y}_{T-t}^{(T)}\right|^{2}\right]+c^{\prime} E\left[\int_{T-t}^{T} \varphi\left(\hat{Y}_{s}^{(T)}, \hat{z}\left(s, \hat{Y}_{s}^{(T)}\right)\right) d s\right]
\end{aligned}
$$

since (2.21) is assumed and

$$
\begin{aligned}
\varphi(x, \hat{z}(t, x)) & =\frac{1}{2} \hat{z}(t, x)^{*} N_{\gamma} \hat{z}(t, x)-\hat{z}(t, x)^{*} \Sigma^{*} \hat{\alpha}+\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha} \\
& =\frac{1}{2}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)^{*} N_{\gamma}\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)
\end{aligned}
$$

$$
\begin{aligned}
& +\left(\lambda^{*} D \bar{v}-\Sigma^{*} \hat{\alpha}\right)^{*} N_{\gamma}^{-1} \Sigma^{*} \hat{\alpha}+\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha} \\
= & \frac{1}{2}(D \bar{v})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{v}-\frac{\gamma}{2(1-\gamma)} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha} .
\end{aligned}
$$

By Itô's formula,

$$
\begin{aligned}
& \bar{v}\left(T, \hat{Y}_{T} ; T\right)-\bar{v}\left(T-t, \hat{Y}_{T-t} ; T\right) \\
& \quad=-\int_{T-t}^{T} \varphi\left(\hat{Y}_{S}, \hat{z}\left(s, \hat{Y}_{S}\right)\right) d s+\int_{T-t}^{T}\left(D \bar{v}\left(s, \hat{Y}_{s}\right)\right)^{*} \lambda\left(\hat{Y}_{s}\right) d W_{s}
\end{aligned}
$$

and we have

$$
E\left[\int_{T-t}^{T} \varphi\left(\hat{Y}_{s}, \hat{z}\left(s, \hat{Y}_{S}\right)\right) d s\right]=E\left[\bar{v}\left(T-t, \hat{Y}_{T-t} ; T\right)\right] .
$$

Take a subsequence $\left\{T_{n}^{\prime}\right\} \subset\left\{T_{n}\right\}$ such that

$$
\lim _{T_{n}^{\prime} \rightarrow \infty} \frac{1}{T_{n}^{\prime}} E\left[\bar{v}\left(T_{n}^{\prime}-t, \hat{Y}_{T_{n}^{\prime}-t} ; T_{n}^{\prime}\right)\right]=0
$$

and

$$
\lim _{T_{n}^{\prime} \rightarrow \infty} \frac{1}{T_{n}^{\prime}} E\left[\left|\hat{Y}_{T_{n}^{\prime}-t}^{\left(T_{n}^{\prime}\right)}\right|^{2}\right]=0 .
$$

Then we have

$$
\begin{aligned}
0 \leq \limsup _{T_{n}^{\prime} \rightarrow \infty} \frac{1}{T_{n}^{\prime}} E\left[\left|\hat{Y}_{T_{n}^{\prime}}^{\left(T_{n}^{\prime}\right)}\right|^{2}\right] \leq & \lim _{T_{n}^{\prime} \rightarrow \infty} \frac{1}{T_{n}^{\prime}} E\left[\left|\hat{Y}_{T_{n}^{\prime}-t}^{\left(T_{n}^{\prime}\right)}\right|^{2}\right] \\
& +c^{\prime} \lim _{T_{n}^{\prime} \rightarrow \infty} \frac{1}{T_{n}^{\prime}} E\left[\int_{T_{n}^{\prime}-t}^{T_{n}^{\prime}} \varphi\left(\hat{Y}_{s}^{\left(T_{n}^{\prime}\right)}, \hat{z}\left(s, \hat{Y}_{s}^{\left(T_{n}^{\prime}\right)}\right)\right) d s\right]=0,
\end{aligned}
$$

and thus the lemma has been proved.
Proof of Proposition 4.2. For each $\varepsilon$ there exists $T_{\varepsilon}$ such that

$$
\begin{gathered}
E\left[\left|\hat{Y}_{T_{\varepsilon}}^{\left(T_{\varepsilon}\right)}\right|^{2}\right]<\varepsilon T_{\varepsilon}, \quad \bar{w}(x)<\varepsilon T_{\varepsilon} \\
\left|\bar{\chi}-\frac{1}{T_{\varepsilon}} E\left[\int_{0}^{T_{\varepsilon}} \varphi\left(\hat{Y}_{s}^{\left(T_{\varepsilon}\right)}, \hat{Z}_{s}^{\left(T_{\varepsilon}\right)}\right) d s\right]\right|<\varepsilon .
\end{gathered}
$$

Set

$$
Z_{s}^{(\varepsilon)}= \begin{cases}\hat{Z}_{s}^{\left(T_{\varepsilon}\right)}, & s<T_{\varepsilon} \\ 0, & T_{\varepsilon} \leq s\end{cases}
$$

and consider $Y_{t}^{(\varepsilon)}$ defined by

$$
d Y_{t}^{(\varepsilon)}=\lambda\left(Y_{t}^{(\varepsilon)}\right) d W_{t}+\left\{G\left(Y_{t}^{(\varepsilon)}\right)+\lambda\left(Y_{t}^{(\varepsilon)}\right) Z_{t}^{(\varepsilon)}\right\} d t, \quad Y_{0}^{(\varepsilon)}=x
$$

Then, for $t \geq T_{\varepsilon}$,

$$
Y_{t}^{(\varepsilon)}=Y_{T_{\varepsilon}}^{(\varepsilon)}+\int_{T_{\varepsilon}}^{t} \lambda\left(Y_{s}^{(\varepsilon)}\right) d W_{s}+\int_{T_{\varepsilon}}^{t} G\left(Y_{s}^{(\varepsilon)}\right) d s
$$

and

$$
\begin{aligned}
d\left|Y_{t}^{(\varepsilon)}\right|^{2}= & 2\left(Y_{t}^{(\varepsilon)}\right)^{*} \lambda\left(Y_{t}^{(\varepsilon)}\right) d W_{t}+2\left(Y_{t}^{(\varepsilon)}\right)^{*} G\left(Y_{t}^{(\varepsilon)}\right)+\int_{T_{\varepsilon}}^{t} G\left(Y_{t}^{(\varepsilon)}\right) d t \\
& +\operatorname{tr}\left[\lambda \lambda^{*}\left(Y_{t}^{(\varepsilon)}\right)\right] d t
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
e^{p t} \mid Y_{t}^{(\varepsilon)} & \left.\right|^{2} \\
= & e^{p T_{\varepsilon}}\left|Y_{T_{\varepsilon}}^{(\varepsilon)}\right|^{2}+2 \int_{T_{\varepsilon}}^{t} e^{p s}\left(Y_{s}^{(\varepsilon)}\right)^{*} \lambda\left(Y_{s}^{(\varepsilon)}\right) d W_{s} \\
& \quad+\int_{T_{\varepsilon}}^{t} e^{p s}\left\{2\left(Y_{s}^{(\varepsilon)}\right)^{*} G\left(Y_{s}^{(\varepsilon)}\right)+p\left|Y_{s}^{(\varepsilon)}\right|^{2}+\operatorname{tr}\left[\lambda \lambda^{*}\left(Y_{s}^{(\varepsilon)}\right)\right]\right\} d s \\
\leq & e^{p T_{\varepsilon}}\left|Y_{T_{\varepsilon}}^{(\varepsilon)}\right|^{2}+2 \int_{T_{\varepsilon}}^{t} e^{p s}\left(Y_{s}^{(\varepsilon)}\right)^{*} \lambda\left(Y_{s}^{(\varepsilon)}\right) d W_{s}+\int_{T_{\varepsilon}}^{t} e^{p s}\left\{-k_{1}\left|Y_{s}^{(\varepsilon)}\right|^{2}+k_{2}\right\} d s
\end{aligned}
$$

for some positive constants $k_{1}, k_{2}>0$. By using stopping time arguments, for $t \geq$ $T_{\varepsilon}$, we have

$$
\begin{aligned}
E\left[e^{p t}\left|Y_{t}^{(\varepsilon)}\right|^{2}\right] & \leq E\left[e^{p T_{\varepsilon}}\left|Y_{T_{\varepsilon}}\right|^{2}\right]+E\left[\int_{T_{\varepsilon}}^{t} e^{p s} k_{2} d s\right] \\
& =E\left[e^{p T_{\varepsilon}}\left|Y_{t}^{(\varepsilon)}\right|^{2}\right]+\frac{k_{2}}{p}\left(e^{p t}-e^{p T_{\varepsilon}}\right)
\end{aligned}
$$

Thus, we see that

$$
E\left[\left|Y_{t}^{(\varepsilon)}\right|^{2}\right] \leq E\left[\left|Y_{T_{\varepsilon}}^{(\varepsilon)}\right|^{2}\right]+\frac{k_{2}}{p}
$$

from which we obtain $\lim \sup _{t \rightarrow \infty} \frac{1}{t} E\left[\left|Y_{t}^{(\varepsilon)}\right|^{2}\right]=0$. Hence, $Z^{(\varepsilon)} \in \tilde{\mathcal{A}}_{\infty}$. Now, by applying Itô's formula, we have

$$
\begin{aligned}
\bar{w}\left(Y_{T_{\varepsilon}}^{(\varepsilon)}\right)-\bar{w}(x)= & \int_{0}^{T_{\varepsilon}}\left(D \bar{w}\left(Y_{s}^{(\varepsilon)}\right)\right)^{*} \lambda\left(Y_{s}^{(\varepsilon)}\right) d W_{s} \\
& +\int_{0}^{T_{\varepsilon}}\left\{G\left(Y_{s}^{(\varepsilon)}\right)+\lambda\left(Y_{s}^{(\varepsilon)}\right) Z_{s}^{(\varepsilon)}\right\}^{*} D \bar{w}\left(Y_{s}^{(\varepsilon)}\right) d s \\
& +\frac{1}{2} \int_{0}^{T_{\varepsilon}} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{w}\right]\left(Y_{s}^{(\varepsilon)}\right) d s \\
\geq & \int_{0}^{T_{\varepsilon}}\left(D \bar{w}\left(Y_{s}^{(\varepsilon)}\right)\right)^{*} \lambda\left(Y_{s}^{(\varepsilon)}\right) d W_{s}-\chi T_{\varepsilon}-\int_{0}^{T_{\varepsilon}} \varphi\left(Y_{s}^{(\varepsilon)}, Z_{s}^{(\varepsilon)}\right) d s
\end{aligned}
$$

Therefore,

$$
\bar{w}(x)-\chi T_{\varepsilon} \leq E\left[\int_{0}^{T_{\varepsilon}} \varphi\left(Y_{s}^{(\varepsilon)}, Z_{s}^{(\varepsilon)}\right) d s+\bar{w}\left(Y_{T_{\varepsilon}}^{(\varepsilon)}\right)\right]
$$

from which we have

$$
\begin{aligned}
-\chi & \leq \frac{1}{T_{\varepsilon}} E\left[\int_{0}^{T_{\varepsilon}} \varphi\left(Y_{s}^{(\varepsilon)}, Z_{s}^{(\varepsilon)}\right) d s\right]+\frac{1}{T_{\varepsilon}} E\left[\bar{w}\left(Y_{T_{\varepsilon}}^{(\varepsilon)}\right)\right] \\
& \leq \varepsilon+\bar{\chi}+c \varepsilon
\end{aligned}
$$

for some positive constant $c>0$. Therefore, $-\chi \leq \bar{\chi}+c \varepsilon$ for any $\varepsilon$, and we have $-\chi \leq \bar{\chi}$. This completes the proof of the proposition.

The following is a direct consequence of Proposition 4.1.

Corollary 4.1. Under the assumptions of Proposition 4.2, $\rho(\gamma)$ is a concave function on $(-\infty, 0)$, and $\hat{\chi}(\gamma)$ is a convex function.

Indeed,

$$
\varphi=\frac{1}{2} z^{*} z-\frac{\gamma}{2} z^{*} \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma z-z^{*} \Sigma^{*} \hat{\alpha}+\frac{1}{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha}
$$

is a concave function of $\gamma$, and the infimum of a family of concave functions $\rho(\gamma)$ is concave.

Proposition 4.3. Under the assumptions of Proposition 3.1, $\bar{L}$ is ergodic.
Proof.

$$
\bar{L} \bar{w}=-\frac{1}{2}(D \bar{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}+\frac{\gamma}{2(1-\gamma)} \hat{\alpha}^{*} \Sigma \Sigma^{*} \hat{\alpha}-\chi \rightarrow-\infty
$$

as $|x| \rightarrow \infty$, and $\bar{L} \bar{w} \leq-c,|x| \gg 1$ and $c>0$. Moreover, $\bar{w}(x) \rightarrow \infty,|x| \rightarrow \infty$, and the Hasminskii conditions (cf. [17]) hold.
5. Derived Poisson equation. We are going to consider a Poisson equation formally obtained by differentiating H-J-B equation (3.1) of ergodic type with respect to $\gamma$. Namely, we consider

$$
\begin{aligned}
-\theta(\gamma)= & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} u\right]+G^{*} D u-\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right)^{*} N_{\gamma}^{-1} \lambda^{*} D u \\
& -\frac{1}{2(1-\gamma)^{2}}\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right)^{*} \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right)
\end{aligned}
$$

Since

$$
\begin{gathered}
-\frac{1}{2(1-\gamma)^{2}}\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right)^{*} \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right) \\
\quad=-\frac{1}{2(1-\gamma)^{2}}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right)^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right)
\end{gathered}
$$

we can write

$$
\begin{equation*}
-\theta(\gamma)=\bar{L} u-\frac{1}{2(1-\gamma)^{2}}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right)^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right) \tag{5.1}
\end{equation*}
$$

Note that $\bar{L}$ is ergodic in light of Proposition 4.3, and the pair $(u, \theta(\gamma))$ of a function $u$ and a constant $\theta(\gamma)$ is the solution to (5.1). Let us set

$$
\mathcal{D}=B_{R_{0}}=\left\{x \in R^{n} ;|x|<R_{0}\right\}
$$

and let $R_{0}$ be sufficiently large so that

$$
\begin{equation*}
K(x ; \bar{w}):=\frac{1}{2}(D \bar{w})^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}-\frac{\gamma}{2(1-\gamma)} \hat{\alpha}^{*} \Sigma \Sigma^{*} \hat{\alpha}+\chi>0 \tag{5.2}
\end{equation*}
$$

$$
x \in \mathcal{D}^{c}
$$

for $\gamma_{-} \leq \gamma_{0}<0$, which is possible because of assumption (2.21). Therefore, we see that $\bar{L}$ and $\bar{w}$ satisfy assumption (A.3) in the Appendix and also

$$
\sup _{x \in \mathcal{D}^{c}} \frac{\left|f^{(\gamma)}(x)\right|}{K(x: \bar{w})}<\infty
$$

for

$$
f^{(\gamma)}=-\frac{1}{2(1-\gamma)^{2}}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right)^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right) .
$$

In the following we always take a solution $\bar{w}$ to (3.1) such that $\bar{w}(x)>0$. Thus, according to Proposition A. 4 we can show the existence of the solution $(u, \theta(\gamma)$ ) to (5.1).

Corollary 5.1. Equation (5.1) has a solution $(u, \theta(\gamma))$ such that

$$
\sup _{x \in \mathcal{D}^{c}} \frac{|u|}{\bar{w}}<\infty, \quad u \in W_{\mathrm{loc}}^{2, p}
$$

and

$$
\theta(\gamma)=\int \frac{1}{2(1-\gamma)^{2}}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right)^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right) m_{\gamma}(y) d y
$$

Moreover, this solution $и$ is unique up to additive constants.

Proof. It can be clearly seen that

$$
\frac{1}{2(1-\gamma)^{2}}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right)^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\sigma \lambda^{*} D \bar{w}-\hat{\alpha}\right) \in F_{K}
$$

and Proposition A. 4 applies.

## 6. Differentiability of $\mathbf{H}-\mathrm{J}-\mathrm{B}$ equation.

Lemma 6.1. Under the assumptions of Proposition 4.2,

$$
\begin{equation*}
\int e^{\delta|x|^{2}} m_{\gamma}(d x) \leq c \tag{6.1}
\end{equation*}
$$

where $c$ and $\delta$ are positive constants independent of $\gamma_{1} \leq \gamma \leq \gamma_{0}<0$.
Proof. Inequality (6.1) is a direct consequence of (4.15) in Lemma 4.2 since $\bar{Y}_{t}$ is an ergodic diffusion process with the invariant measure $m_{\gamma}(d x)$.

In the following, we always work under the assumptions of Theorem 2.2 (Proposition 4.2).

LEMMA 6.2. Let $\left(\bar{w}^{(\gamma)}, \chi(\gamma)\right)$ and $\left(\bar{w}^{(\gamma+\Delta)}, \chi(\gamma+\Delta)\right)$ be solutions to (3.1) with $\gamma$ and $\gamma+\Delta$, respectively, such that $\bar{w}^{(\gamma)}(0)=\bar{w}^{(\gamma+\Delta)}(0)=c_{w}>0$. Then $\bar{w}^{(\gamma+\Delta)}$ converges to $\bar{w}^{(\gamma)}$ in $H_{\mathrm{loc}}^{1}$ strongly and uniformly on each compact set.

Proof. We have

$$
\left\|\bar{w}^{(\gamma+\Delta)}\right\|_{L^{\infty}\left(B_{2 r}\right)} \leq 2 r\left\|\nabla \bar{w}^{(\gamma+\Delta)}\right\|_{L^{\infty}\left(B_{2 r}\right)} \leq c_{1}(\gamma, r)
$$

and

$$
\begin{array}{r}
\left|\bar{w}^{(\gamma+\Delta)}(x)-\bar{w}^{(\gamma+\Delta)}(y)\right| \leq|x-y|\left\|\nabla \bar{w}^{(\gamma+\Delta)}\right\|_{L^{\infty}\left(B_{2 r}\right)} \leq c_{2}(\gamma, r) \\
x, y \in B_{2 r},
\end{array}
$$

for each $r$ in light of (3.11) and (3.15), where $c_{i}(\gamma, r)$ is a positive constant independent of $\Delta, i=1,2$. Therefore it follows that $\left\{\bar{w}^{(\gamma+\Delta)}\right\}_{\Delta}$ is bounded in $H^{1}\left(B_{2 r}\right)$ and converges to some $\tilde{w}$ in $H^{1}\left(B_{2 r}\right)$ weakly for each $r$ and also uniformly on each compact set by taking a subsequence if necessary. Note that $\chi(\gamma+\Delta)$ converges to $\chi(\gamma)$ because $\chi(\gamma)$ is convex on $(-\infty, 0)$ and thus continuous. Take a function $\tau \in C_{0}^{\infty}\left(B_{2 r}\right)$ such that $\tau(x) \equiv 1, x \in B_{r}$, and $0 \leq \tau \leq 1$. With $\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau$, we test

$$
\begin{aligned}
-\chi(\gamma+\Delta)= & \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} \bar{w}^{(\gamma+\Delta)}\right]+\beta_{\gamma+\Delta}^{*} D \bar{w}^{(\gamma+\Delta)} \\
& -\frac{1}{2}\left(D \bar{w}^{(\gamma+\Delta)}\right)^{*} \lambda N_{\gamma+\Delta}^{-1} \lambda^{*} D \bar{w}^{(\gamma+\Delta)}+U_{\gamma+\Delta}
\end{aligned}
$$

and obtain

$$
\begin{aligned}
-\int_{B_{2 r}} & \chi(\gamma+\Delta)\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x \\
= & -\int_{B_{2 r}} \frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i} \bar{w}^{(\gamma+\Delta)} D_{j}\left(\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau\right) d x \\
& +\int_{B_{2 r}} \tilde{\beta}_{\gamma+\Delta}^{*} D \bar{w}^{(\gamma+\Delta)}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x \\
& -\frac{1}{2} \int_{B_{2 r}}\left(D \bar{w}^{(\gamma+\Delta)}\right)^{*} \lambda N_{\gamma+\Delta}^{-1} \lambda^{*} D \bar{w}^{(\gamma+\Delta)}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x \\
& +\int_{B_{2 r}} U_{\gamma+\Delta}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x
\end{aligned}
$$

where $\tilde{\beta}_{\gamma}^{i}=\beta_{\gamma}^{i}-\frac{1}{2} \sum_{j} \frac{\partial\left(\lambda \lambda^{*}\right)^{i j}}{\partial x^{j}}$. Therefore,

$$
\begin{aligned}
& \int_{B_{2 r}} \frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) D_{j}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x \\
&=-\int_{B_{2 r}} \frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i} \tilde{w} D_{j}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x \\
&-\int_{B_{2 r}} \frac{1}{2}\left(\lambda \lambda^{*}\right)^{i j} D_{i} \bar{w}^{(\gamma+\Delta)} D_{j} \tau\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) d x \\
&+\int_{B_{2 r}} \tilde{\beta}_{\gamma+\Delta}^{*} D \bar{w}^{(\gamma+\Delta)}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x \\
&-\frac{1}{2} \int_{B_{2 r}}\left(D \bar{w}^{(\gamma+\Delta)}\right)^{*} \lambda N_{\gamma+\Delta}^{-1} \lambda^{*} D \bar{w}^{(\gamma+\Delta)}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x \\
&+\int_{B_{2 r}} U_{\gamma+\Delta}\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x+\int_{B_{2 r}} \chi(\gamma+\Delta)\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right) \tau d x
\end{aligned}
$$

Since all terms of the right-hand side converge to 0 , we see that $D\left(\bar{w}^{(\gamma+\Delta)}-\tilde{w}\right)$ converges strongly to 0 in $L^{2}\left(B_{r}\right)$ and $\bar{w}^{(\gamma+\Delta)}$ to $\tilde{w}$ strongly in $H^{1}\left(B_{r}\right)$. Thus, we obtain our present lemma because $(\bar{w}, \chi(\gamma))$ satisfies (3.1), and the solution is unique up to additive constants with respect to $\bar{w}$.

LEMMA 6.3. Let $\left(u^{(\gamma+\Delta)}, \theta(\gamma+\Delta)\right)$ be a solution to

$$
\begin{equation*}
-\theta(\gamma+\Delta)=\bar{L}(\gamma+\Delta) u^{(\gamma+\Delta)}+f^{(\gamma+\Delta)} \tag{6.2}
\end{equation*}
$$

where

$$
\begin{aligned}
f^{(\gamma+\Delta)}= & -\frac{1}{2(1-\gamma-\Delta)^{2}}\left(\lambda^{*} D \bar{w}^{(\gamma+\Delta)}-\Sigma^{*} \hat{\alpha}\right)^{*} \\
& \times \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma\left(\lambda^{*} D \bar{w}^{(\gamma+\Delta)}-\Sigma^{*} \hat{\alpha}\right)
\end{aligned}
$$

Then, as $|\Delta| \rightarrow 0, \theta(\gamma+\Delta)$ converges to $\theta(\gamma)$ and $u^{(\gamma+\Delta)}$ converges to $u^{(\gamma)}$ in $H_{\mathrm{loc}}^{1}$ strongly and uniformly on each compact set, where $\left(u^{(\gamma)}, \theta(\gamma)\right)$ is a solution to (5.1).

Proof. Note that $\left|f^{(\gamma+\Delta)}(x)\right| \leq c\left(1+|x|^{2}\right), \exists c>0$, and that $f^{(\gamma+\Delta)}(x) \rightarrow$ $f^{(\gamma)}$ almost everywhere by taking a subsequence, if necessary, since $w^{(\gamma+\Delta)}$ converges strongly in $H_{\mathrm{loc}}^{1}$ to $w^{(\gamma)}$ by Lemma 6.2. Moreover, we note that $\left\{m_{\gamma+\Delta}(d x)\right\}=\left\{m_{\gamma+\Delta}(x) d x\right\}$ is tight because of Lemma 6.1. Therefore, it converges weakly to some probability measure $\tilde{m}(d x)$ by taking a subsequence if necessary. The limit can be identified with $m_{\gamma}(d x)=m_{\gamma}(x) d x$, and $m_{\gamma}(x)$ is the only function satisfying (A.24) for $\bar{L}(\gamma)$ and $\int m_{\gamma}(x) d x=1$. Thus $m_{\gamma+\Delta}(x) d x$ converges to $m_{\gamma}(x) d x$ weakly. Therefore,

$$
\theta(\gamma+\Delta)=-\int f^{(\gamma+\Delta)}(x) m_{\gamma+\Delta}(x) d x
$$

converges to $\theta(\gamma)$.
On the other hand, since $u^{(\gamma+\Delta)}$ is a solution to (6.2) it satisfies

$$
\sup _{x \in \mathcal{D}^{c}} \frac{\left|u^{(\gamma+\Delta)}\right|}{\bar{w}^{(\gamma+\Delta)}}<\infty
$$

and we have $\left|\bar{w}^{(\gamma+\Delta)}\right| \leq c\left(1+|x|^{2}\right)$. Therefore, we see that $u^{(\gamma+\Delta)}$ is locally bounded by a constant independent of $\Delta$. Then, by testing (6.2) with $u^{(\gamma+\Delta)} \tau$, we can see that $\left\|u^{(\gamma+\Delta)}\right\|_{H^{1}\left(B_{r}\right)}$ is bounded for each $r$. Therefore, by taking a subsequence if necessary, $u^{(\gamma+\Delta)}$ converges in $H_{\text {loc }}^{1}$ weakly to a function $\tilde{u}$, which turns out to be the solution $u^{(\gamma)}$ to (5.1). By similar arguments as in the proof of Lemma 6.2, we can see it converges in $H_{\text {loc }}^{1}$ strongly. Furthermore, by Theorem 9.11 in [16], we see that

$$
\begin{aligned}
\left\|u^{(\gamma+\Delta)}\right\|_{W^{2, p}\left(B_{r}\right)} & \leq C\left(\left\|u^{(\gamma+\Delta)}\right\|_{L^{p}\left(B_{2 r}\right)}+\left\|f^{(\gamma+\Delta)}+\theta(\gamma+\Delta)\right\|_{L^{p}\left(B_{2 r}\right)}\right) \\
& \leq C\left(\left\|u^{(\gamma+\Delta)}\right\|_{L^{\infty}\left(B_{2 r}\right)}+\left\|f^{(\gamma+\Delta)}+\theta(\gamma+\Delta)\right\|_{L^{p}\left(B_{2 r}\right)}\right)
\end{aligned}
$$

for each $r>0$, where $C$ is a constant depending on $c_{1}, c_{2}$ and the $L^{\infty}\left(B_{2 r}\right)$ norms of the coefficients of $\bar{L}(\gamma+\Delta)$. Thus, by the Sobolev imbedding theorem, $\left\{u^{(\gamma+\Delta)}\right\}$ is equicontinuous, and thus $u^{(\gamma+\Delta)}$ converges uniformly to $u^{(\gamma)}$ on each compact set.

Lemma 6.4. Let $\left(\bar{w}^{(\gamma)}, \chi(\gamma)\right)$ and $\left(\bar{w}^{(\gamma+\Delta)}, \chi(\gamma+\Delta)\right)$ be solutions to (3.1) with $\gamma$ and $\gamma+\Delta$, respectively. Set $\chi^{(\Delta)}=\frac{\chi(\gamma+\Delta)-\chi(\gamma)}{\Delta}$ and $\zeta^{(\Delta)}=\frac{\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}}{\Delta}$. Then

$$
\lim _{|\Delta| \rightarrow 0} \chi^{(\Delta)}=\theta(\gamma)
$$

and

$$
\lim _{|\Delta| \rightarrow 0} \zeta^{(\Delta)}(x)=u^{(\gamma)}(x), \quad x \in R^{n}
$$

Here, $\left(u^{(\gamma)}, \theta(\gamma)\right)$ is the solution to (5.1).
Proof. Here we abbreviate $u^{(\gamma)}$ to $u$. From (3.1) it follows that

$$
\begin{aligned}
&-\chi(\gamma+\Delta)+\chi(\gamma) \\
&= \frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2}\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right)\right]+\beta_{\gamma+\Delta}^{*} D \bar{w}^{(\gamma+\Delta)} \\
&-\beta_{\gamma}^{*} D \bar{w}^{(\gamma)}-\frac{1}{2}\left(D \bar{w}^{(\gamma+\Delta)}\right)^{*} \lambda N_{\gamma+\Delta}^{-1} \lambda^{*} D \bar{w}^{(\gamma+\Delta)} \\
&+\frac{1}{2}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}^{(\gamma)}+U_{\gamma+\Delta}-U_{\gamma} \\
&=\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2}\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right)\right]+\beta_{\gamma}^{*} D\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right) \\
&-\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right)-\frac{1}{2}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}^{(\gamma)} \\
&+\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}^{(\gamma+\Delta)}-\frac{1}{2}\left(D \bar{w}^{(\gamma+\Delta)}\right)^{*} \lambda N_{\gamma+\Delta}^{-1} \lambda^{*} D \bar{w}^{(\gamma+\Delta)} \\
&+\left(\beta_{\gamma+\Delta}-\beta_{\gamma}\right)^{*} D \bar{w}^{(\gamma+\Delta)}+U_{\gamma+\Delta}-U_{\gamma} \\
&= \bar{L}(\gamma)\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right) \\
&-\frac{1}{2} D\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma+\Delta}^{-1} \lambda^{*} D\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right) \\
&+\left(\beta_{\gamma+\Delta}-\beta_{\gamma}\right)^{*} D \bar{w}^{(\gamma+\Delta)}+\frac{1}{2}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda\left(N_{\gamma+\Delta}^{-1}-N_{\gamma}^{-1}\right) \lambda^{*} D \bar{w}^{(\gamma)} \\
&-\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda\left(N_{\gamma+\Delta}^{-1}-N_{\gamma}^{-1}\right) \lambda^{*} D \bar{w}^{(\gamma+\Delta)}+U_{\gamma+\Delta}-U_{\gamma} .
\end{aligned}
$$

Therefore we have

$$
\begin{equation*}
-\chi^{(\Delta)}=\bar{L}(\gamma) \zeta^{(\Delta)}+f_{1}^{(\Delta)}(x)-g^{(\Delta)}(x) \tag{6.3}
\end{equation*}
$$

where

$$
\begin{aligned}
f_{1}^{(\Delta)}(x)= & \frac{\left(\beta_{\gamma+\Delta}-\beta_{\gamma}\right)^{*}}{\Delta} D \bar{w}^{(\gamma+\Delta)}+\frac{1}{2}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda \frac{\left(N_{\gamma+\Delta}^{-1}-N_{\gamma}^{-1}\right)}{\Delta} \lambda^{*} D \bar{w}^{(\gamma)} \\
& -\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda \frac{\left(N_{\gamma+\Delta}^{-1}-N_{\gamma}^{-1}\right)}{\Delta} \lambda^{*} D \bar{w}^{(\gamma+\Delta)}+\frac{U_{\gamma+\Delta}-U_{\gamma}}{\Delta}
\end{aligned}
$$

and

$$
g^{(\Delta)}(x)=\frac{1}{2 \Delta} D\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma+\Delta}^{-1} \lambda^{*} D\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right) .
$$

Note that $f_{1}^{(\Delta)}$ is dominated by $c\left(1+|x|^{2}\right)$ with a certain positive constant $c$ and that it converges almost everywhere to $f^{(\gamma)}$ by taking a subsequence, if necessary,
because

$$
\begin{aligned}
\frac{\partial \beta_{\gamma}}{\partial \gamma} & =\frac{1}{(1-\gamma)^{2}} \lambda \Sigma^{*} \hat{\alpha} \\
\frac{\partial N_{\gamma}^{-1}}{\partial \gamma} & =\frac{1}{(1-\gamma)^{2}} \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma \\
\frac{\partial U_{\gamma}}{\partial \gamma} & =-\frac{1}{2(1-\gamma)^{2}} \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma .
\end{aligned}
$$

Therefore,

$$
\begin{equation*}
-\chi_{1}^{(\Delta)}:=\int f_{1}^{(\Delta)}(x) m_{\gamma}(d x) \rightarrow \int f(x) m_{\gamma}(d x)=-\theta(\gamma), \quad|\Delta| \rightarrow 0 \tag{6.4}
\end{equation*}
$$

Moreover, for $\Delta>0$,

$$
\begin{equation*}
-\chi_{1}^{(\Delta)} \geq-\chi^{(\Delta)} \tag{6.5}
\end{equation*}
$$

Let us consider the equation

$$
\begin{equation*}
-\chi_{1}^{(\Delta)}=\bar{L}(\gamma) u_{1}^{(\Delta)}+f_{1}^{(\Delta)} \tag{6.6}
\end{equation*}
$$

We shall see that $u_{1}^{(\Delta)}-u \rightarrow 0$ as $\Delta \rightarrow 0$ by specifying suitable ambiguity constants. For that, set

$$
z^{(\Delta)}:=u_{1}^{(\Delta)}-u, \quad F^{(\Delta)}:=f_{1}^{(\Delta)}-f+\chi_{1}^{(\Delta)}-\theta(\gamma) .
$$

Then we have

$$
\bar{L}(\gamma) z^{(\Delta)}+F^{(\Delta)}=0, \quad z^{(\Delta)} \in W_{\mathrm{loc}}^{2, p}, \quad \sup _{\mathcal{D}^{c}} \frac{\left|z^{(\Delta)}\right|}{\bar{w}^{(\gamma)}}<\infty
$$

By considering constructing the solution to this equation according to the proof of Proposition A. 4 in the Appendix, we see that $z^{(\Delta)} \rightarrow 0$ as $\Delta \rightarrow 0$. To begin, let $\Psi^{(\Delta)}$ be the solution to (A.19) for $L_{0}=\bar{L}(\gamma), f=F^{(\Delta)}$ and $\xi^{(\Delta)}$ the solution to (A.20) for $L_{0}=\bar{L}(\gamma), f=F^{(\Delta)}$ and $\Psi=\Psi^{(\Delta)}$. The operator $T$ is defined as

$$
T F^{(\Delta)}(x)=\xi^{(\Delta)}(x), \quad x \in \Gamma_{1}
$$

and the operator $P$ is defined in the same way as in (A.10) by replacing $L_{0}$ with $\bar{L}(\gamma)$ in (A.4) and (A.9). Then starting with $\zeta_{0}^{(\Delta)}=\Psi^{(\Delta)}, \eta_{0}^{(\Delta)}=\xi^{(\Delta)}$, we define the sequence $\zeta_{k}^{(\Delta)}, \eta_{k}^{(\Delta)}, k=1,2, \ldots$, successively as the solution to (A.9) with $\phi=\eta_{k-1}^{(\Delta)}$ and $L_{0}=\bar{L}(\gamma)$, and as the solution to (A.4) with $h=\zeta_{k}^{(\Delta)}$ and $L_{0}=$ $\bar{L}(\gamma)$, respectively. Then we obtain

$$
\bar{\eta}^{(\Delta)}(x)=\left.\sum_{k=0}^{\infty} \eta_{k}^{(\Delta)}\right|_{\Gamma_{1}}=\sum_{k=0}^{\infty} P^{k}\left(T F^{(\Delta)}\right)(x)
$$

and the estimate for $\bar{\eta}^{(\Delta)}$,

$$
\left\|\bar{\eta}^{(\Delta)}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq K\left\|T F^{(\Delta)}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \frac{1}{1-e^{-\rho}}
$$

To estimate $\left\|T F^{(\Delta)}\right\|_{L^{\infty}\left(\Gamma_{1}\right)}$, we set $\xi_{1}^{(\Delta)}$ to be the solution to

$$
\left\{\begin{array}{l}
\bar{L}(\gamma) \xi_{1}^{(\Delta)}+F^{(\Delta)}=0, \quad \overline{\mathcal{D}}^{c} \\
\left.\xi_{1}^{(\Delta)}\right|_{\Gamma}=0,
\end{array}\right.
$$

and $\xi_{2}^{(\Delta)}=\xi^{(\Delta)}-\xi_{1}^{(\Delta)}$. Then $\xi_{2}^{(\Delta)}$ satisfies

$$
\left\{\begin{array}{l}
\bar{L}(\gamma) \xi_{2}^{(\Delta)}=0, \\
\left.\xi_{2}^{(\Delta)}\right|_{\Gamma}=\left.\Psi^{(\Delta)}\right|_{\Gamma},
\end{array}\right.
$$

and we have

$$
\left\|\xi_{2}^{(\Delta)}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq\left\|\xi_{2}^{(\Delta)}\right\|_{L^{\infty}\left(\mathcal{D}^{c}\right)} \leq\left\|\Psi^{(\Delta)}\right\|_{L^{\infty}(\Gamma)} \leq K_{1}\left\|F^{(\Delta)}\right\|_{L^{\infty}\left(\mathcal{D}_{1}\right)}
$$

for some constant $K_{1}>0$. On the other hand, to estimate $\left\|\xi_{1}^{(\Delta)}\right\|_{L^{\infty}\left(\Gamma_{1}\right)}$, we set

$$
\xi_{1}^{(\Delta)}:=v^{(\Delta)}\left(\bar{w}^{(\gamma)}\right)^{\alpha}, \quad \alpha>1
$$

We can assume that $\mathcal{D}$ is sufficiently large so that

$$
\begin{array}{r}
-U_{\gamma}-\frac{1}{2}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}^{(\gamma)}-\chi(\gamma)+\frac{\alpha-1}{\bar{w}^{(\gamma)}}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda \lambda^{*} D \bar{w}^{(\gamma)}<-M \\
x \in \mathcal{D}^{c}
\end{array}
$$

for some $M>0$. Since

$$
\begin{aligned}
\bar{L}(\gamma) \xi_{1}^{(\Delta)}= & \left(\bar{w}^{(\gamma)}\right)^{\alpha} \bar{L}(\gamma) v^{(\Delta)}+\alpha v^{(\Delta)}\left(\bar{w}^{(\gamma)}\right)^{\alpha-1} \bar{L}(\gamma) \bar{w}^{(\gamma)} \\
& +\alpha\left(D v^{(\Delta)}\right)^{*} \lambda \lambda^{*} \frac{D \bar{w}^{(\gamma)}}{\bar{w}^{(\gamma)}}\left(\bar{w}^{(\gamma)}\right)^{\alpha} \\
& +\alpha(\alpha-1) v^{(\Delta)}\left(\frac{D \bar{w}^{(\gamma)}}{\bar{w}^{(\gamma)}}\right)^{*} \lambda \lambda^{*} \frac{D \bar{w}^{(\gamma)}}{\bar{w}^{(\gamma)}}\left(\bar{w}^{(\gamma)}\right)^{\alpha},
\end{aligned}
$$

$v^{(\Delta)}$ satisfies

$$
\left\{\begin{array}{l}
\bar{L}(\gamma) v^{(\Delta)}+\alpha\left(\frac{D \bar{w}^{(\gamma)}}{\bar{w}^{(\gamma)}}\right)^{*} \lambda \lambda^{*} D v^{(\Delta)} \\
\quad+\frac{\alpha}{\bar{w}^{(\gamma)}}\left\{\bar{L}(\gamma) \bar{w}^{(\gamma)}+\frac{\alpha-1}{\bar{w}^{(\gamma)}}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda \lambda^{*} D \bar{w}^{(\gamma)}\right\} v^{(\Delta)}=-\frac{F^{(\Delta)}}{\left(\bar{w}^{(\gamma)}\right)^{\alpha}} \\
\left.v^{(\Delta)}\right|_{\partial \mathcal{D}}=0
\end{array}\right.
$$

Noting that

$$
\begin{aligned}
& \bar{L}(\gamma) \bar{w}^{(\gamma)}+\frac{\alpha-1}{\bar{w}^{(\gamma)}}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda \lambda^{*} D \bar{w}^{(\gamma)} \\
& =-U_{\gamma}-\frac{1}{2}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}^{(\gamma)}-\chi(\gamma)+\frac{\alpha-1}{\bar{w}^{(\gamma)}}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda \lambda^{*} D \bar{w}^{(\gamma)} \\
& <-M, \quad x \in \mathcal{D}^{c},
\end{aligned}
$$

we have

$$
\left|v^{(\Delta)}(x)\right| \leq K_{2} \sup _{\mathcal{D}^{c}} \frac{\left|F^{(\Delta)}\right|}{\left(\bar{w}^{(\gamma)}\right)^{\alpha}},
$$

and thus

$$
\left\|\xi_{1}^{(\Delta)}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq K_{2} \sup _{\mathcal{D}^{c}} \frac{\left|F^{(\Delta)}\right|}{\left(\bar{w}^{(\gamma)}\right)^{\alpha}}\left\|\left(\bar{w}^{(\gamma)}\right)^{\alpha}\right\|_{L^{\infty}\left(\Gamma_{1}\right)}
$$

Moreover, $\xi_{1}^{(\Delta)}=v^{(\Delta)}\left(\bar{w}^{(\gamma)}\right)^{\alpha} \rightarrow 0$ uniformly on each compact set as $\Delta \rightarrow 0$. Therefore, $\xi^{(\Delta)} \rightarrow 0$ uniformly on each compact set and we also obtain the estimates

$$
\left\|\xi^{(\Delta)}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq K_{1}\left\|F^{(\Delta)}\right\|_{L^{\infty}\left(\mathcal{D}_{1}\right)}+K_{2} \sup _{\mathcal{D}^{c}} \frac{\left|F^{(\Delta)}\right|}{\left(\bar{w}^{(\gamma)}\right)^{\alpha}}\left\|\left(\bar{w}^{(\gamma)}\right)^{\alpha}\right\|_{L^{\infty}\left(\Gamma_{1}\right)}
$$

and

$$
\left\|\bar{\eta}^{(\Delta)}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq K_{1}^{\prime}\left\|F^{(\Delta)}\right\|_{L^{\infty}\left(\mathcal{D}_{1}\right)}+K_{2}^{\prime} \sup _{\mathcal{D}^{c}} \frac{\left|F^{(\Delta)}\right|}{\left(\bar{w}^{(\gamma)}\right)^{\alpha}}\left\|\left(\bar{w}^{(\gamma)}\right)^{\alpha}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} .
$$

Let $\tilde{\zeta}^{(\Delta)}$ be the solution to (A.26) for $L_{0}=\bar{L}(\gamma), f=F^{(\Delta)}$ and $\bar{\eta}=\bar{\eta}^{(\Delta)}$. Then $\tilde{\zeta}^{(\Delta)} \rightarrow 0$ uniformly as $\Delta \rightarrow 0$ since $\left\|\bar{\eta}^{(\Delta)}\right\|$ is estimated as shown above. Let $\tilde{\eta}^{(\Delta)}$ be the solution to (A.20) for $L_{0}=\bar{L}(\gamma), f=F^{(\Delta)}$ and $\Psi=\tilde{\zeta}^{(\Delta)}$. Then, as above, $\tilde{\eta}^{(\Delta)} \rightarrow 0$ uniformly on each compact set as $\Delta \rightarrow 0$. Since $z^{(\Delta)}=\tilde{\zeta}^{(\Delta)}$ in $\mathcal{D}_{1}$ and $z^{(\Delta)}=\tilde{\eta}^{(\Delta)}$ in $\mathcal{D}^{c}$, we conclude that $z^{(\Delta)} \rightarrow 0$ uniformly on each compact set.

In a similar manner, we have

$$
\begin{aligned}
-\chi^{(\Delta)}= & \bar{L}(\gamma+\Delta) \zeta^{(\Delta)}+\frac{\left(\beta_{\gamma+\Delta}-\beta_{\gamma}\right)^{*}}{\Delta} D w^{(\gamma)} \\
& +\frac{1}{2}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda \frac{N_{\gamma}^{-1}-N_{\gamma+\Delta}^{-1}}{\Delta} \lambda^{*} D \bar{w}^{(\gamma)}+\frac{U_{\gamma+\Delta}-U_{\gamma}}{\Delta} \\
& +\frac{1}{2 \Delta} D\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right)^{*} \lambda N_{\gamma+\Delta}^{-1} \lambda^{*} D\left(\bar{w}^{(\gamma+\Delta)}-\bar{w}^{(\gamma)}\right) .
\end{aligned}
$$

By setting

$$
\begin{aligned}
f_{2}^{(\Delta)}(x):= & \frac{\left(\beta_{\gamma+\Delta}-\beta_{\gamma}\right)^{*}}{\Delta} D w^{(\gamma)}+\frac{1}{2}\left(D \bar{w}^{(\gamma)}\right)^{*} \lambda \frac{N_{\gamma}^{-1}-N_{\gamma+\Delta}^{-1}}{\Delta} \lambda^{*} D \bar{w}^{(\gamma)} \\
& +\frac{U_{\gamma+\Delta}-U_{\gamma}}{\Delta},
\end{aligned}
$$

we have

$$
\begin{equation*}
-\chi^{(\Delta)}=\bar{L}(\gamma+\Delta) \zeta^{(\Delta)}+f_{2}^{(\Delta)}(x)+g^{(\Delta)}(x) \tag{6.7}
\end{equation*}
$$

Since $m_{\gamma+\Delta}(x) d x$ converges to $m_{\gamma}(x) d x$ weakly, and $f_{2}^{(\Delta)}$ converges almost everywhere to $f(x)$ by taking a subsequence if necessary, as above, we have

$$
\begin{equation*}
-\chi_{2}^{(\Delta)}:=\int f_{2}^{(\Delta)}(x) m_{\gamma+\Delta}(x) d x \rightarrow \int f(x) m_{\gamma}(x) d x=-\theta(\gamma) \tag{6.8}
\end{equation*}
$$

$$
\text { as }|\Delta| \rightarrow 0 .
$$

Moreover, for $\Delta>0$,

$$
\begin{equation*}
-\chi_{2}^{(\Delta)} \leq-\chi^{(\Delta)} \tag{6.9}
\end{equation*}
$$

We consider

$$
\begin{equation*}
-\chi_{2}^{(\Delta)}=\bar{L}(\gamma+\Delta) u_{2}^{(\Delta)}+f_{2}^{(\Delta)} \tag{6.10}
\end{equation*}
$$

Then, in the same manner as above, we see that $u_{2}^{(\Delta)}-u^{(\gamma+\Delta)} \rightarrow 0$, as $|\Delta| \rightarrow 0$, by specifying ambiguity constants. Since $u^{(\gamma+\Delta)}$ converges to $u, u_{2}^{(\Delta)}$ does the same.

From (6.4), (6.5), (6.8) and (6.9), it follows that

$$
\begin{equation*}
\lim _{\Delta \downarrow 0}-\chi^{(\Delta)}=-\theta(\gamma) \tag{6.11}
\end{equation*}
$$

The converse inequalities of (6.5) and (6.9) hold for $\Delta<0$, and we have

$$
\begin{equation*}
\lim _{\Delta \uparrow 0}-\chi^{(\Delta)}=-\theta(\gamma) \tag{6.11}
\end{equation*}
$$

Hence, we see that $-\chi^{(\Delta)} \rightarrow-\theta(\gamma)$ as $|\Delta| \rightarrow 0$. From (6.3) and (6.6), we have

$$
-\chi_{1}^{(\Delta)}+\chi^{(\Delta)}=\bar{L}(\gamma)\left(u_{1}^{(\Delta)}-\zeta^{(\Delta)}\right)+g^{(\Delta)},
$$

and through arguments similar to those above, we see that

$$
\liminf _{\Delta \downarrow 0}\left(u_{1}^{(\Delta)}(x)-\zeta^{(\Delta)}(x)\right) \geq 0
$$

since $g^{(\Delta)}(x) \geq 0$ for $\Delta>0$ and $\chi^{(\Delta)}-\chi_{1}^{(\Delta)} \rightarrow 0$ as $|\Delta| \rightarrow 0$. Similarly, from (6.7) and (6.10), we have

$$
-\chi_{2}^{(\Delta)}+\chi^{(\Delta)}=\bar{L}(\gamma+\Delta)\left(u_{2}^{(\Delta)}-\zeta^{(\Delta)}\right)-g^{(\Delta)}
$$

and see that

$$
\underset{\Delta \downarrow 0}{\limsup }\left(u_{2}^{(\Delta)}(x)-\zeta^{(\Delta)}(x)\right) \leq 0
$$

Therefore,

$$
\lim _{\Delta \downarrow 0} \zeta^{(\Delta)}(x)=u(x)
$$

We likewise have

$$
\limsup _{\Delta \uparrow 0}\left(u_{1}^{(\Delta)}(x)-\zeta^{(\Delta)}(x)\right) \leq 0
$$

and

$$
\liminf _{\Delta \uparrow 0}\left(u_{2}^{(\Delta)}(x)-\zeta^{(\Delta)}(x)\right) \geq 0
$$

since $g^{(\Delta)}(x) \leq 0$ for $\Delta<0$. Therefore, we obtain

$$
\lim _{\Delta \uparrow 0} \zeta^{(\Delta)}(x)=u(x)
$$

and Lemma 6.4 follows.
REMARK 6.1. Since $u=u^{(\gamma)}=\frac{\partial \bar{w}}{\partial \gamma}$ is a solution to (5.1), it has a polynomial growth order. More precisely, we have

$$
|u(x)| \leq C\left(1+|x|^{2}\right), \quad \exists C>0
$$

cf. Corollary 5.1 and (3.11). Furthermore, we can see that $\frac{\partial u}{\partial x_{l}}$ also has a polynomial growth order for each $l$. Indeed, $u_{l}:=\frac{\partial u}{\partial x_{l}}$ satisfies

$$
0=\frac{1}{2} D_{i}\left(a^{i j} D_{j} u_{l}\right)+B^{i} D_{i} u_{l}-D_{l} f+\frac{1}{2} D_{i}\left(a_{l}^{i j} D_{j} u\right)+B_{l}^{i} D_{i} u,
$$

where

$$
\begin{aligned}
a^{i j}(x) & =\left(\lambda \lambda^{*}\right)^{i j}(x) \\
B^{j}(x) & =\beta_{\gamma}^{j}(x)-\frac{1}{2} D_{i}\left((\lambda \lambda)^{i j}\right)-\left(\lambda N_{\gamma}^{-1} \lambda^{*} D \bar{w}\right)^{j} \\
f & =\frac{1}{2(1-\gamma)^{2}}\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right)^{*} \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma\left(\lambda^{*} D \bar{w}-\Sigma^{*} \hat{\alpha}\right), \\
a_{l}^{i j} & =\frac{\partial a^{i j}}{\partial x_{l}}, \quad B_{l}^{i}=\frac{\partial B^{i}}{\partial x_{l}}
\end{aligned}
$$

Therefore, if we set $f_{i}=-\frac{1}{2} a_{l}^{i j} D_{j} u, i \neq l$, and $f_{l}=-\frac{1}{2} a_{l}^{l j} D_{j} u-f$, then $u_{l}$ satisfies

$$
\begin{equation*}
\int\left(\frac{1}{2} a^{i j} D_{j} u_{l}-f_{i}\right) \xi_{x_{i}} d x+\int\left(B^{i} D_{i} u_{l}+B_{l}^{i} D_{i} u\right) \xi d x=0 \tag{6.14}
\end{equation*}
$$

for each $\xi \in W_{0}^{1,2}\left(B_{\rho}\left(x_{0}\right)\right), \rho>0, x_{0} \in R^{n}$. We note that
$\left\|f_{i}\right\|_{L^{p / 2}\left(B_{\rho}\left(x_{0}\right)\right)},\left\|B^{i}\right\|_{L^{p / 2}\left(B_{\rho}\left(x_{0}\right)\right)},\left\|B_{l}^{i} D_{i} u\right\|_{L^{p / 2}\left(B_{\rho}\left(x_{0}\right)\right)} \leq \mu\left(x_{0}\right) \leq C\left(1+\left|x_{0}\right|^{m_{0}}\right)$,

$$
\exists C>0, m_{0}>0,
$$

which can be seen in light of our assumptions since $u$ is a solution to (5.1), and $\bar{w}$ is a solution to (3.1). Equation (6.14) corresponds to (13.4) in [25], Chapter 3, Section 13. Therefore, by the same arguments as in that work,

$$
\int_{A_{k}, \rho}\left|\nabla u_{l}\right|^{2} \zeta^{2} d x \leq \gamma\left(x_{0}\right)\left[\int_{A_{k, \rho}}\left(u_{l}-k\right)^{2}|\nabla \zeta|^{2} d x+\left(k^{2}+1\right)\left|A_{k, \rho}\right|^{1-2 / p}\right]
$$

is seen to hold, where $\zeta$ is a cut-off function supported by $B_{\rho}\left(x_{0}\right), A_{k, \rho}=\{x \in$ $\left.B_{\rho}\left(x_{0}\right) ; u_{l}(x)>k\right\}$, and $\gamma\left(x_{0}\right)$ is a constant dominated by $C\left(1+\left|x_{0}\right|^{m_{1}}\right), C>$ $0, m_{1}>0$. From this inequality we obtain inequality (5.12) for $u=u_{l}$ in [25], Chapter 2, Section 5. Hence, similarly to the proof of Lemma 5.4 in [25], Chapter 2 , we see that $u_{l}$ has a polynomial growth order.
7. Proof of Theorem 2.4. We first state the following lemma.

LEMMA 7.1. Under the assumptions of Theorem 2.3,

$$
\begin{equation*}
\chi^{\prime}(-\infty):=\lim _{\gamma \rightarrow-\infty} \chi^{\prime}(\gamma)=0 \tag{7.1}
\end{equation*}
$$

Proof. Note that

$$
0 \leq \lim _{\gamma \rightarrow-\infty} \chi^{\prime}(\gamma) \leq \chi^{\prime}\left(\gamma_{0}\right)
$$

for $\gamma_{0}<0$ and that $\chi^{\prime}(\gamma)$ is nondecreasing. Therefore, $\chi^{\prime}(-\infty)$ exists. Furthermore,

$$
\frac{\chi(\gamma)}{\gamma}=-\frac{1}{\gamma} \int_{\gamma}^{\gamma_{0}} \chi^{\prime}(t) d t+\frac{\chi\left(\gamma_{0}\right)}{\gamma}
$$

and $\lim _{\gamma \rightarrow-\infty} \frac{\chi(\gamma)}{\gamma}=0$ since $-\chi_{0} \leq \chi(\gamma) \leq 0$. Here, $\chi_{0}$ is a constant defined by (3.10). Hence, we obtain (7.1).

We next give the proof of Theorem 2.4. For $\gamma<0$, we have

$$
\begin{aligned}
\log P\left(\frac{\log V_{T}(h)-\log S_{T}^{0}}{T} \leq \kappa\right) & =\log P\left(\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma} \geq e^{\gamma \kappa T}\right) \\
& \leq \log \left\{E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma}\right] e^{-\gamma \kappa T}\right\} \\
& =\log E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma}\right]-\gamma \kappa T
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
\inf _{h} \log P\left(\frac{\log V_{T}(h)-\log S_{T}^{0}}{T} \leq \kappa\right) & \leq \inf _{h} \log E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma}\right]-\gamma \kappa T \\
& \leq v(0, x ; T)-\gamma \kappa T
\end{aligned}
$$

from which we obtain

$$
\liminf _{T \rightarrow \infty} \frac{1}{T} \inf _{h} \log P\left(\frac{\log V_{T}(h)-\log S_{t}^{0}}{T} \leq \kappa\right) \leq \chi(\gamma)-\gamma \kappa
$$

for all $\gamma<0$. Hence, we have

$$
\liminf _{T \rightarrow \infty} \frac{1}{T} \inf _{h} \log P\left(\frac{\log V_{T}(h)-\log S_{T}^{0}}{T} \leq \kappa\right) \leq \inf _{\gamma<0}\{\chi(\gamma)-\gamma \kappa\} .
$$

The converse inequality is more difficult to prove. Take a constant $\kappa$ and $\varepsilon>0$ such that $\kappa-\varepsilon>0$. Then there exists $\gamma_{\varepsilon}$ such that

$$
\begin{equation*}
\inf _{\gamma<0}\{\chi(\gamma)-\gamma(\kappa-\varepsilon)\}=\chi\left(\gamma_{\varepsilon}\right)-\gamma_{\varepsilon} \chi^{\prime}\left(\gamma_{\varepsilon}\right) \tag{7.2}
\end{equation*}
$$

We write $\gamma_{\varepsilon}$ as $\gamma$ for simplicity in the following. Let us introduce a probability measure $\tilde{P}$ defined by

$$
\left.\frac{d \tilde{P}}{d P}\right|_{\mathcal{G}_{T}}=e^{M_{T}^{\gamma}-(1 / 2)\left\langle M^{\gamma}\right\rangle_{T}}
$$

where

$$
M_{t}^{\gamma}=\int_{0}^{t}\left\{\frac{\gamma}{1-\gamma} \hat{\alpha}^{*} \Sigma+(D w)^{*} \lambda N_{\gamma}^{-1}\right\}\left(X_{s}\right) d W_{s}
$$

Then $\tilde{W}_{t}=W_{t}-\int_{0}^{t}\left\{\frac{\gamma}{1-\gamma} \Sigma^{*} \hat{\alpha}+N_{\gamma}^{-1} \lambda^{*} D w\right\}\left(X_{s}\right) d s$ is a martingale under the probability measure $\tilde{P}$ and

$$
\begin{align*}
d X_{t} & =\beta\left(X_{t}\right) d t+\lambda\left(X_{t}\right) d W_{t} \\
& =\left\{\beta+\frac{\gamma}{1-\gamma} \lambda \Sigma^{*} \hat{\alpha}+\lambda N_{\gamma}^{-1} \lambda^{*} D w\right\}\left(X_{t}\right) d t+\lambda\left(X_{t}\right) d \tilde{W}_{t} . \tag{7.3}
\end{align*}
$$

Note that $\left(X_{t}, \tilde{P}\right)$ has the same law as the diffusion process $\left(\bar{Y}_{t}, P\right)$ governed by stochastic differential equation (4.12). We further note $\mathrm{H}-\mathrm{J}-\mathrm{B}$ equation of ergodic type (2.18) can be written as

$$
\begin{equation*}
\chi(\gamma)=\bar{L} w-\frac{1}{2}(D w)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D w-U_{\gamma} \tag{7.4}
\end{equation*}
$$

by using $\bar{L}$ defined by (4.16). On the other hand, (5.1) is written as

$$
\begin{align*}
\chi^{\prime}(\gamma) & =\bar{L} w_{\gamma}+\frac{1}{2(1-\gamma)^{2}}\left(\sigma \lambda^{*} D w+\hat{\alpha}\right)^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\sigma \lambda^{*} D w+\hat{\alpha}\right) \\
& =\bar{L} w_{\gamma}+\frac{1}{2(1-\gamma)^{2}}\left(\lambda^{*} D w+\Sigma^{*} \hat{\alpha}\right)^{*} \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma\left(\lambda^{*} D w+\Sigma^{*} \hat{\alpha}\right)  \tag{7.5}\\
& =: \bar{L} w_{\gamma}+V_{1}(x)
\end{align*}
$$

owing to Lemma 6.3, where $w_{\gamma}=\frac{\partial w}{\partial \gamma}$. Now we have

$$
\begin{aligned}
& \log V_{T}(h)-\log S_{T}^{0} \\
& =\log v+\int_{0}^{T}\left\{h_{s}^{*} \hat{\alpha}\left(X_{s}\right)-\frac{1}{2} h_{s}^{*} \sigma \sigma^{*}\left(X_{s}\right) h_{s}\right\} d s+\int_{0}^{T} h_{s}^{*} \sigma\left(X_{s}\right) d W_{s} \\
& =\log v+\int_{0}^{T} h_{s}^{*} \sigma\left(X_{s}\right) d \tilde{W}_{s} \\
& +\int_{0}^{T}\left\{h_{s}^{*} \hat{\alpha}\left(X_{s}\right)-\frac{1}{2} h_{s}^{*} \sigma \sigma^{*}\left(X_{s}\right) h_{s}+\frac{\gamma}{1-\gamma} h_{s}^{*} \sigma \Sigma^{*} \hat{\alpha}\left(X_{s}\right)\right. \\
& \left.+h_{s}^{*} \sigma N_{\gamma}^{-1} \lambda^{*} D w\left(X_{s}\right)\right\} d s \\
& =\log v+\int_{0}^{T} h_{s}^{*} \sigma\left(X_{s}\right) d \tilde{W}_{s} \\
& +\int_{0}^{T}\left\{\frac{1}{1-\gamma}\left(h_{s}^{*} \hat{\alpha}\left(X_{s}\right)+h_{s}^{*} \sigma \lambda^{*} D w\left(X_{s}\right)\right)-\frac{1}{2} h_{s}^{*} \sigma \sigma^{*}\left(X_{s}\right) h_{s}\right\} d s \\
& =\log v+\int_{0}^{T}\left\{h_{s}-\frac{1}{1-\gamma}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\right\}^{*} \sigma\left(X_{s}\right) d \tilde{W}_{s} \\
& +\int_{0}^{T} \frac{1}{1-\gamma}\left\{\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\right\}^{*} \sigma\left(X_{s}\right) d \tilde{W}_{s} \\
& -\frac{1}{2} \int_{0}^{T}\left\{h_{s}-\frac{1}{1-\gamma}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\right\}^{*} \\
& \times \sigma \sigma^{*}\left\{h_{s}-\frac{1}{1-\gamma}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\right\} d s \\
& +\frac{1}{2(1-\gamma)^{2}} \int_{0}^{T}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)^{*}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\left(X_{s}\right) d s \\
& =\log v+M_{T}^{h}-\frac{1}{2}\left\langle M^{h}\right\rangle_{T} \\
& +\int_{0}^{T} \frac{1}{1-\gamma}\left\{\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\right\}^{*} \sigma\left(X_{s}\right) d \tilde{W}_{s} \\
& +\int_{0}^{T} V_{1}\left(X_{s}\right) d s,
\end{aligned}
$$

and we set

$$
M_{t}^{h}:=\int_{0}^{t}\left\{h_{s}-\frac{1}{1-\gamma}\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\right\}^{*} \sigma\left(X_{s}\right) d \tilde{W}_{s} .
$$

Note that $\kappa-\varepsilon=\chi^{\prime}(\gamma)$. Then it follows that

$$
\begin{aligned}
\tilde{P}\left(\frac{1}{T}\right. & \left.\left(\log V_{T}(h)-\log S_{T}^{0}\right)>\kappa\right) \\
\leq & \tilde{P}\left(\frac{1}{T} \log v+\frac{1}{T} \int_{0}^{T} V_{1}\left(X_{s}\right) d s>\chi^{\prime}(\gamma)+\frac{\varepsilon}{3}\right) \\
& +\tilde{P}\left(\frac{1}{T}\left(M_{T}^{h}-\frac{1}{2}\left\langle M^{h}\right\rangle_{T}\right)>\frac{\varepsilon}{3}\right) \\
& +\tilde{P}\left(\frac{1}{T} \int_{0}^{T} \frac{1}{1-\gamma}\left\{\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\right\}^{*} \sigma\left(X_{s}\right) d \tilde{W}_{s}>\frac{\varepsilon}{3}\right)
\end{aligned}
$$

Taking Lemma 4.2 into account, we have

$$
\begin{aligned}
& \tilde{P}\left(\frac{1}{T} \int_{0}^{T} \frac{1}{1-\gamma}\left\{\left(\sigma \sigma^{*}\right)^{-1}\left(\hat{\alpha}+\sigma \lambda^{*} D w\right)\right\}^{*} \sigma\left(X_{s}\right) d \tilde{W}_{s}>\frac{\varepsilon}{3}\right) \\
& \quad \leq \frac{9}{\varepsilon^{2} T^{2}} \tilde{E}\left[\int_{0}^{T} V_{1}\left(X_{s}\right) d s\right] \\
& \quad \leq \frac{C}{\varepsilon^{2} T}
\end{aligned}
$$

for some positive constant $C$ and

$$
\tilde{P}\left(\frac{1}{T}\left(M_{T}^{h}-\frac{1}{2}\left\langle M^{h}\right\rangle_{T}\right)>\frac{\varepsilon}{3}\right) \leq e^{-\varepsilon T / 3} \tilde{E}\left[e^{M_{T}^{h}-(1 / 2)\left\langle M^{h}\right\rangle_{T}}\right] \leq e^{-\varepsilon T / 3}
$$

Thus, by using the following lemma, we can see that

$$
\begin{equation*}
\tilde{P}\left(\frac{1}{T}\left(\log V_{T}(h)-\log S_{T}^{0}\right)>\kappa\right)<\varepsilon \tag{7.6}
\end{equation*}
$$

for sufficiently large $T$.

Lemma 7.2. For sufficiently large $T$ we have

$$
\tilde{P}\left(\frac{\log v}{T}+\frac{1}{T} \int_{0}^{T} V_{1}\left(X_{s}\right) d s>\chi^{\prime}(\gamma)+\frac{\varepsilon}{3}\right) \leq \frac{\varepsilon}{2}
$$

Proof. By Itô's formula,

$$
\begin{aligned}
w_{\gamma} & \left(X_{T}\right)-w_{\gamma}\left(X_{0}\right) \\
& =\int_{0}^{T}\left\{\bar{L}(\gamma) w_{\gamma}\left(X_{s}\right)\right\} d s+\int_{0}^{T}\left(\nabla w_{\gamma}\left(X_{s}\right)\right)^{*} \lambda\left(X_{s}\right) d \tilde{W}_{s} \\
& =-\int_{0}^{T} V_{1}\left(X_{s}\right) d s+\chi^{\prime}(\gamma) T+\int_{0}^{T}\left(\nabla w_{\gamma}\left(X_{s}\right)\right)^{*} \lambda\left(X_{s}\right) d \tilde{W}_{s}
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
\frac{1}{T} \int_{0}^{T} V_{1}\left(X_{s}\right) d s= & \chi^{\prime}(\gamma)+\frac{1}{T}\left\{w_{\gamma}(x)-w_{\gamma}\left(X_{T}\right)\right\} \\
& +\frac{1}{T} \int_{0}^{T}\left(\nabla w_{\gamma}\left(X_{s}\right)\right)^{*} \lambda\left(X_{s}\right) d \tilde{W}_{s}
\end{aligned}
$$

Thus,

$$
\begin{aligned}
\tilde{P}\left(\frac{1}{T}\right. & \left.\log v+\frac{1}{T} \int_{0}^{T} V_{1}\left(X_{s}\right) d s>\chi^{\prime}(\gamma)+\frac{\varepsilon}{3}\right) \\
= & \tilde{P}\left(\frac{1}{T} \log v+\frac{1}{T}\left\{w_{\gamma}(x)-w_{\gamma}\left(X_{T}\right)\right\}+\frac{1}{T} \int_{0}^{T}\left(\nabla w_{\gamma}\left(X_{s}\right)\right)^{*} d \tilde{W}_{s}>\frac{\varepsilon}{3}\right) \\
\leq & \tilde{P}\left(\frac{1}{T} \log v>\frac{\varepsilon}{9}\right)+\tilde{P}\left(\frac{1}{T}\left\{w_{\gamma}(x)-w_{\gamma}\left(X_{T}\right)\right\}>\frac{\varepsilon}{9}\right) \\
& +\tilde{P}\left(\frac{1}{T} \int_{0}^{T}\left(\nabla w_{\gamma}\left(X_{s}\right)\right)^{*} d \tilde{W}_{s}>\frac{\varepsilon}{9}\right) \\
\leq & \frac{81}{\varepsilon^{2} T^{2}} E\left[\left|w_{\gamma}(x)-w_{\gamma}\left(X_{T}\right)\right|^{2}\right]+\frac{81}{\varepsilon^{2} T^{2}} E\left[\int_{0}^{T}\left(D w_{\gamma}\right)^{*} \lambda \lambda^{*} D w_{\gamma}\left(X_{s}\right) d s\right]
\end{aligned}
$$

Hence, by taking $T$ and $R$ to be sufficiently large, we obtain our present lemma because of Lemma 4.2; cf. Remark 6.1.

Let us complete the proof of Theorem 2.4 for $0<\kappa<\chi^{\prime}(0-)$. Set

$$
\tilde{M}_{t}^{\gamma}=\int_{0}^{t}\left\{\frac{\gamma}{1-\gamma} \hat{\alpha}^{*} \Sigma+(D w)^{*} \lambda N_{\gamma}^{-1}\right\}\left(X_{s}\right) d \tilde{W}_{s}
$$

and

$$
\begin{aligned}
& A_{1}=\left\{-\tilde{M}_{T}^{\gamma} \geq-\varepsilon T\right\}, \\
& A_{2}=\left\{-\frac{1}{2}\left\langle M^{\gamma}\right\rangle_{T} \geq\left(\chi(\gamma)-\gamma \chi^{\prime}(\gamma)-\varepsilon\right) T\right\}, \\
& A_{3}=\left\{\frac{1}{T}\left(\log V_{T}(h)-\log S_{T}^{0}\right) \leq \kappa\right\} .
\end{aligned}
$$

Then

$$
\begin{aligned}
& P\left(\frac{1}{T}\left(\log V_{T}(h)-S_{T}^{0}\right) \leq \kappa\right) \\
& \quad=\tilde{E}\left[e^{-\tilde{M}_{T}^{\gamma}-(1 / 2)\left\langle M^{\gamma}\right\rangle_{T}} ; \frac{1}{T}\left(\log V_{T}(h)-S_{T}^{0}\right) \leq \kappa\right] \\
& \quad \geq \tilde{E}\left[e^{-\tilde{M}_{T}^{\gamma}-(1 / 2)\left\langle M^{\gamma}\right\rangle_{T}} ; A_{1} \cap A_{2} \cap A_{3}\right] \\
& \quad \geq e^{\left(\chi(\gamma)-\gamma \chi^{\prime}(\gamma)-2 \varepsilon\right) T} \tilde{P}\left(A_{1} \cap A_{2} \cap A_{3}\right) \\
& \quad \geq e^{\left(\chi(\gamma)-\gamma \chi^{\prime}(\gamma)-2 \varepsilon\right) T}\left\{1-\tilde{P}\left(A_{1}^{c}\right)-\tilde{P}\left(A_{2}^{c}\right)-\tilde{P}\left(A_{3}^{c}\right)\right\} .
\end{aligned}
$$

We have seen that $\tilde{P}\left(A_{3}^{c}\right)<\varepsilon$ holds for sufficiently large $T$ in (7.6), and it is straightforward to see that likewise $\tilde{P}\left(A_{1}^{c}\right)<\varepsilon$ for sufficiently large $T$. Therefore, taking the following lemma into account as well, we have

$$
P\left(\frac{1}{T}\left(\log V_{T}(h)-\log S_{T}^{0}\right) \leq \kappa\right) \geq e^{\left(\chi(\gamma)-\gamma \chi^{\prime}(\gamma)-2 \varepsilon\right) T}(1-3 \varepsilon) \quad \forall h \in \mathcal{H}(T)
$$

for sufficiently large $T$, and

$$
\begin{aligned}
\underline{\lim _{T \rightarrow \infty}} \frac{1}{T} \inf _{h \in \mathcal{H}(T)} \log P\left(\frac{\log V_{T}(h)-\log S_{T}^{0}}{T} \leq \kappa\right) & \geq \chi(\gamma)-\gamma \chi^{\prime}(\gamma)-2 \varepsilon \\
& =\chi(\gamma)-\gamma(\kappa-\varepsilon)-2 \varepsilon \\
& \geq \inf _{\gamma<0}\{\chi(\gamma)-\gamma(\kappa-\varepsilon)\}-2 \varepsilon
\end{aligned}
$$

for each $\varepsilon$. Since $\chi(\gamma)$ is smooth and convex, $J(\kappa)=\inf _{\gamma<0}\{\chi(\gamma)-\gamma \kappa\}, \kappa>0$, is strictly concave, and thus continuous. Hence,

$$
\varliminf_{T \rightarrow \infty} \frac{1}{T} \inf _{h \in \mathcal{H}(T)} \log P\left(\frac{\log V_{T}(h)-\log S_{T}^{0}}{T} \leq \kappa\right) \geq \inf _{\gamma<0}\{\chi(\gamma)-\gamma \kappa\} .
$$

LEMMA 7.3. Under the assumptions of Theorem 2.4,

$$
\tilde{P}\left(\frac{1}{2}\left\langle M^{\gamma}\right\rangle_{T} \geq-\left(\chi(\gamma)-\gamma \chi^{\prime}(\gamma)-\varepsilon\right) T\right)<\varepsilon
$$

holds for sufficiently large $T$.
Proof. First note that

$$
\frac{1}{2} N_{\gamma}^{-1}-\frac{1}{2}\left(N_{\gamma}^{-1}\right)^{2}=-\frac{\gamma}{2(1-\gamma)^{2}} \Sigma^{*}\left(\Sigma \Sigma^{*}\right)^{-1} \Sigma
$$

and

$$
\frac{\gamma}{2(1-\gamma)}-\frac{\gamma}{2(1-\gamma)^{2}}=-\frac{\gamma^{2}}{2(1-\gamma)^{2}}
$$

Then, from (7.4) and (7.5), we have

$$
\begin{aligned}
\chi(\gamma)-\gamma \chi^{\prime}(\gamma)= & \bar{L}\left(w-\gamma w_{\gamma}\right)-\frac{1}{2}(D w)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D w-U_{\gamma}-\gamma V_{1}(x) \\
= & \bar{L}\left(w-\gamma w_{\gamma}\right)-\frac{1}{2}(D w)^{*} \lambda N_{\gamma}^{-1} \lambda^{*} D w-\frac{\gamma}{(1-\gamma)^{2}}\left(\lambda \Sigma^{*} \hat{\alpha}\right)^{*} D w \\
& +\frac{1}{2}(D w)^{*} \lambda\left(N_{\gamma}^{-1}-\left(N_{\gamma}^{-1}\right)^{2}\right) \lambda^{*} D w-\gamma^{2} 2(1-\gamma)^{2} \hat{\alpha} \Sigma \Sigma^{*} \hat{\alpha} \\
= & \bar{L}\left(w-\gamma w_{\gamma}\right) \\
& -\frac{1}{2}\left(\frac{\gamma}{1-\gamma} \Sigma^{*} \hat{\alpha}+N_{\gamma}^{-1} \lambda^{*} D w\right)^{*}\left(\frac{\gamma}{1-\gamma} \Sigma^{*} \hat{\alpha}+N_{\gamma}^{-1} \lambda^{*} D w\right) .
\end{aligned}
$$

Set

$$
V_{2}(x)=\frac{1}{2}\left(\frac{\gamma}{1-\gamma} \Sigma^{*} \hat{\alpha}+N_{\gamma}^{-1} \lambda^{*} D w\right)^{*}\left(\frac{\gamma}{1-\gamma} \Sigma^{*} \hat{\alpha}+N_{\gamma}^{-1} \lambda^{*} D w\right)
$$

Then

$$
\frac{1}{2}\left\langle M^{\gamma}\right\rangle_{t}=\int_{0}^{t} V_{2}\left(X_{s}\right) d s
$$

By Itô's formula, we have

$$
\begin{aligned}
(w- & \left.\gamma w_{\gamma}\right)\left(X_{t}\right)-\left(w-\gamma w_{\gamma}\right)\left(X_{0}\right) \\
& =\int_{0}^{t} \bar{L}(\gamma)\left(w-\gamma w_{\gamma}\right)\left(X_{s}\right) d s+\int_{0}^{t} D\left(w-\gamma w_{\gamma}\right)\left(X_{s}\right)^{*} \lambda\left(X_{s}\right) d \tilde{W}_{s} \\
& =\left\{\chi(\gamma)-\gamma \chi^{\prime}(\gamma)\right\} t+\int_{0}^{t} V_{2}\left(X_{s}\right) d s+\int_{0}^{t} D\left(w-\gamma w_{\gamma}\right)\left(X_{s}\right)^{*} \lambda\left(X_{s}\right) d \tilde{W}_{s}
\end{aligned}
$$

Thus,

$$
\begin{aligned}
& \tilde{P}\left(\frac{1}{2}\left\langle M^{\gamma}\right\rangle_{T}+\left\{\chi(\gamma)-\gamma \chi^{\prime}(\gamma)\right\} T>\varepsilon T\right) \\
&= \tilde{P}\left(\left(w-\gamma w_{\gamma}\right)\left(X_{T}\right)-\left(w-\gamma w_{\gamma}\right)(x)\right. \\
&\left.\quad-\int_{0}^{t} D\left(w-\gamma w_{\gamma}\right)\left(X_{s}\right)^{*} \lambda\left(X_{s}\right) d \tilde{W}_{s}>\varepsilon T\right) \\
& \leq \tilde{P}\left(\left(w-\gamma w_{\gamma}\right)\left(X_{T}\right)>\frac{\varepsilon T}{3}\right)+\tilde{P}\left(-\left(w-\gamma w_{\gamma}\right)(x)>\frac{\varepsilon T}{3}\right) \\
& \quad+\tilde{P}\left(-\int_{0}^{t} D\left(w-\gamma w_{\gamma}\right)\left(X_{s}\right)^{*} \lambda\left(X_{s}\right) d \tilde{W}_{s}>\frac{\varepsilon T}{3}\right)
\end{aligned}
$$

Hence, we obtain the present lemma in the same way as Lemma 7.2.
For $\kappa<0$, we shall prove Theorem 2.4. By convexity, we have

$$
\chi(-1) \geq \chi(\gamma)+\chi^{\prime}(\gamma)(-1-\gamma), \quad \gamma<-1 .
$$

That is,

$$
\chi(\gamma)-\gamma \kappa \leq \chi(-1)+\chi^{\prime}(\gamma)+\gamma\left(\chi^{\prime}(\gamma)-\kappa\right) .
$$

$\chi^{\prime}(\gamma)$ is monotonically nondecreasing, and $\chi^{\prime}(\gamma) \rightarrow 0$ as $\gamma \rightarrow-\infty$. Therefore, we see that

$$
\chi(\gamma)-\gamma \kappa \rightarrow-\infty \quad \text { as } \gamma \rightarrow-\infty
$$

Hence,

$$
\inf _{\gamma<0}\{\chi(\gamma)-\gamma \kappa\}=-\infty
$$

On the other hand, by taking $h=0$, we have $V_{T}(h)=v \exp (r T)$ and

$$
P\left(\frac{\log V_{T}(h)-\log S_{T}^{0}}{T} \leq \kappa\right)=0
$$

for sufficiently large $T$. Thus, $J(\kappa)=-\infty$.
8. Proof of Theorem 2.5. For a given constant $0<\kappa<\chi^{\prime}(0-)$, take $\gamma(\kappa)$ such that $\chi^{\prime}(\gamma(\kappa))=\kappa$, namely,

$$
\inf _{\gamma<0}\{\chi(\gamma)-\gamma \kappa\}=\chi(\gamma(\kappa))-\gamma(\kappa) \kappa
$$

Then, since

$$
\inf _{h .} \log P\left(\frac{\log V_{T}(h)-\log S_{T}^{0}}{T} \leq \kappa\right) \leq \inf _{h .} \log E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma(\kappa)}\right]-\gamma(\kappa) \kappa T
$$

we have

$$
J(\kappa) \leq \underline{\lim } \frac{1}{T \rightarrow \infty} \inf _{h .} \log E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma(\kappa)}\right]-\gamma(\kappa) \kappa .
$$

Therefore, if we prove that

$$
\begin{align*}
\varliminf_{T \rightarrow \infty} \frac{1}{T} \mathrm{inf}_{h .} \log E\left[\left(\frac{V_{T}(h)}{S_{T}^{0}}\right)^{\gamma(\kappa)}\right] & =\lim _{T \rightarrow \infty} \frac{1}{T} \log E\left[\left(\frac{V_{T}\left(h^{(\gamma(\kappa))}\right)}{S_{T}^{0}}\right)^{\gamma(\kappa)}\right]  \tag{8.1}\\
& =\chi(\gamma(\kappa)),
\end{align*}
$$

then we complete the proof of the present theorem because

$$
J(\kappa) \leq J_{\infty}(\kappa) \leq \lim _{T \rightarrow \infty} \frac{1}{T} \log E\left[\left(\frac{V_{T}\left(h^{(\gamma(\kappa))}\right)}{S_{T}^{0}}\right)^{\gamma(\kappa)}\right]-\gamma(\kappa) \kappa
$$

and $J(\kappa)=\inf _{\gamma<0}\{\chi(\gamma)-\gamma \kappa\}$ by Theorem 2.4. (8.1) is proved in the following proposition.

Proposition 8.1. Under the assumptions of Theorem 2.5, (8.1) holds.
Proof. Let $w=w^{(\gamma(\kappa))}$ be a solution to (2.18) for $\gamma=\gamma(\kappa)$ and $\bar{h}_{t}^{(\gamma)}=$ $\bar{h}\left(X_{t}\right)$, where $X_{t}$ is the solution to (2.24). Noting that

$$
\begin{align*}
\eta(x, \bar{h}) & =\bar{h}^{*} \hat{\alpha}-\frac{1-\gamma}{2} \bar{h}^{*} \sigma \sigma^{*} \bar{h}  \tag{8.2}\\
& =\frac{1}{2(1-\gamma)} \hat{\alpha}^{*} \sigma \sigma^{*} \hat{\alpha}-\frac{1}{2(1-\gamma)}(D w)^{*} \lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*} D w
\end{align*}
$$

we have

$$
\begin{aligned}
w\left(X_{t}\right)- & w\left(X_{0}\right) \\
= & \int_{0}^{t}\left\{\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} w\right]+\left(\beta+\gamma \lambda \sigma^{*} \bar{h}\right)^{*} D w\right\}\left(X_{s}\right) d s \\
& +\int_{0}^{t}(D w)^{*} \lambda\left(X_{s}\right) d W_{s}^{\bar{h}} \\
= & \int_{0}^{t}\left\{\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} w\right]+\beta_{\gamma}^{*} D w\right. \\
& \left.+\frac{\gamma}{1-\gamma}(D w)^{*} \lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*} D w\right\}\left(X_{s}\right) d s \\
& \left.+\int_{0}^{t}(D w)^{*} \lambda\left(X_{s}\right) d W_{s}^{\bar{h}} \quad-\frac{1}{2}(D w)^{*} \lambda \lambda^{*} D w\right\}\left(X_{s}\right) d s \\
= & \int_{0}^{t}\left\{\chi+U_{\gamma}+\frac{\gamma}{2(1-\gamma)}(D w)^{*} \lambda \sigma^{*}\left(\sigma \sigma^{*}\right)^{-1} \sigma \lambda^{*} D w\right. \\
& +\int_{0}^{t}(D w)^{*} \lambda\left(X_{s}\right) d W_{s}^{\bar{h}} \\
= & \int_{0}^{t}\left\{\chi-\gamma \eta\left(X_{s}, \bar{h}_{s}^{(\gamma)}\right)-\frac{1}{2}(D w)^{*} \lambda \lambda^{*} D w\left(X_{s}\right)\right\} d s \\
& +\int_{0}^{t}(D w)^{*} \lambda\left(X_{s}\right) d W_{s}^{\bar{h}} .
\end{aligned}
$$

Thus,

$$
\begin{aligned}
E^{\bar{h}} & {\left[e^{\int_{0}^{T} \gamma \eta\left(X_{s}, \bar{h}_{s}^{(\gamma)}\right) d s}\right] } \\
& \quad=E^{\bar{h}}\left[e^{\chi T+w(x)-w\left(X_{T}\right)+\int_{0}^{T}(D w)^{*} \lambda\left(X_{s}\right) d W_{s}^{\bar{h}}-(1 / 2) \int_{0}^{T}(D w)^{*} \lambda \lambda^{*} D w\left(X_{s}\right) d s}\right]
\end{aligned}
$$

Let us introduce a new measure $\check{P}$ defined by

$$
\frac{d \check{P}}{d P^{\bar{h}}}=e^{\int_{0}^{T}(D w)^{*} \lambda\left(X_{s}\right) d W_{s}^{\bar{h}}-(1 / 2) \int_{0}^{T}(D w)^{*} \lambda \lambda^{*} D w\left(X_{s}\right) d s}
$$

Then

$$
\check{W}_{t}=W_{t}^{\bar{h}}-\int_{0}^{t} \lambda^{*} D w\left(X_{s}\right) d s
$$

is a Brownian motion process under $\check{P}$ and

$$
d X_{t}=\left\{\beta\left(X_{t}\right)+\gamma \lambda \sigma^{*} \bar{h}\left(X_{t}\right)+\lambda \lambda^{*} D w\left(X_{t}\right)\right\} d t+\lambda\left(X_{t}\right) d \check{W}_{t} .
$$

Therefore,

$$
\begin{aligned}
e^{-w\left(X_{T}\right)} & -e^{-w(x)} \\
= & -\int_{0}^{T} e^{-w\left(X_{s}\right)}(D w)^{*} \lambda\left(X_{s}\right) d \check{W}_{s} \\
& +\int_{0}^{T} e^{-w\left(X_{s}\right)}\left\{-\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} w\right]-\left(\beta+\gamma \lambda \sigma^{*} \bar{h}\right)^{*} D w\right. \\
& \left.\quad-\frac{1}{2}(D w)^{*} \lambda \lambda^{*} D w\right\}\left(X_{s}\right) d s \\
=- & \quad \int_{0}^{T} e^{-w\left(X_{s}\right)}(D w)^{*} \lambda\left(X_{s}\right) d \check{W}_{s} \\
& \quad-\int_{0}^{T} e^{-w\left(X_{s}\right)}\left\{\frac{1}{2} \operatorname{tr}\left[\lambda \lambda^{*} D^{2} w\right]+\beta_{\gamma}^{*} D w\right.
\end{aligned} \quad \begin{aligned}
& \gamma \\
&\left.\quad+\frac{1}{2}(D w)^{*} \lambda \lambda^{*} D w\right\}\left(x_{s}\right) d s \\
&=-\int_{0}^{T} e^{-w\left(X_{s}\right)}(D w)^{*} \lambda\left(X_{s}\right) d \check{W}_{s}-\int_{0}^{T} e^{-w\left(X_{s}\right)}\left\{\chi-\gamma \eta\left(X_{s}, \bar{h}_{s}^{(\gamma)}\right)\right\} d s .
\end{aligned}
$$

Then, by the arguments using the stopping time, we have

$$
\begin{aligned}
E^{\bar{h}} & {\left[e^{\int_{0}^{T} \gamma \eta\left(X_{s}, \bar{h}_{s}^{(\gamma)}\right) d s}\right] } \\
& =e^{\chi T+w(x)} \check{E}\left[e^{-w\left(X_{T}\right)}\right] \\
& =e^{\chi T+w(x)} \check{E}\left[e^{-w(x)}+\int_{0}^{T} e^{-w\left(X_{s}\right)}\left\{\gamma \eta\left(X_{s}, \bar{h}_{s}^{(\gamma)}\right)-\chi\right\} d s\right] .
\end{aligned}
$$

Hence, we obtain

$$
\lim _{T \rightarrow \infty} \frac{1}{T} \log E^{\bar{h}}\left[e^{\int_{0}^{T} \gamma \eta\left(X_{s}, \bar{h}_{s}^{(\gamma)}\right) d s}\right] \leq \chi(\gamma)
$$

by taking into account (2.25) and (8.2). The converse inequality holds since $\bar{h}_{s}^{(\gamma)} \in$ $\mathcal{A}(T)$.

## APPENDIX

Let $L_{0}$ be an elliptic operator defined by

$$
L_{0} u:=\frac{1}{2} \sum_{i, j} a^{i j}(x) D_{i j} u+\sum_{i} b^{i}(x) D_{i} u
$$

(A.1)

$$
=\frac{1}{2} \sum_{i, j} D_{i}\left(a^{i j}(x) D_{j} u\right)+\sum_{i} \tilde{b}^{i}(x) D_{i} u,
$$

where $a^{i j}(x)$ and $b^{i}(x)$ are Lipschitz continuous functions such that

$$
\begin{equation*}
k_{0}|y|^{2} \leq y^{*} a(x) y \leq k_{1}|y|^{2} \quad \forall y \in R^{N}, k_{0}, k_{1}>0 \tag{A.2}
\end{equation*}
$$

and $\tilde{b}^{i}=b^{i}-\frac{1}{2} \sum_{j} D_{j} a^{j i}$. We assume that there exists a positive function $\psi \in$ $C^{2}\left(R^{N}\right)$ such that

$$
\begin{cases}\psi(x) \rightarrow \infty, & \text { as }|x| \rightarrow \infty  \tag{A.3}\\ -L_{0} \psi-\frac{c_{a}}{\psi}(D \psi)^{*} a D \psi>0, & x \in B_{R_{0}}^{c}, \exists R_{0}>0, c_{a}>0, \\ L_{0} \psi<-1, & x \in B_{R_{0}}^{c} .\end{cases}
$$

Set $K(x ; \psi)=-L_{0} \psi$,

$$
\begin{aligned}
& F_{\psi}=\left\{u \in W_{\mathrm{loc}}^{2, p} ; \underset{x \in B_{R_{0}}^{c}}{\operatorname{ess} \sup } \frac{|u(x)|}{\psi(x)}<\infty\right\}, \\
& F_{K}=\left\{f \in L_{\mathrm{loc}}^{\infty} ; \underset{x \in B_{R_{0}}^{c}}{\operatorname{esssup}} \frac{|f(x)|}{K(x ; \psi)}<\infty\right\}
\end{aligned}
$$

and

$$
\mathcal{D}=B_{R_{0}}=\left\{x \in R^{N} ;|x|<R_{0}\right\} .
$$

Then we consider the following exterior Dirichlet problem for a given bounded continuous function $h$ on $\Gamma=\partial \mathcal{D}$ :

$$
\left\{\begin{array}{l}
-L_{0} \xi=0, \quad x \in \overline{\mathcal{D}}^{c}  \tag{A.4}\\
\left.\xi\right|_{\Gamma}=h
\end{array}\right.
$$

Proposition A.1. Exterior Dirichlet problem (A.4) has a unique bounded solution $\xi \in W_{\text {loc }}^{2, p} \cap L^{\infty}, 1<p<\infty$.

Proof. We first show uniqueness. Note that

$$
-L_{0} \psi=K(x ; \psi)>0, \quad x \in \mathcal{D}^{c}
$$

and set $\xi=\mu \psi$. Then

$$
0=L_{0} \xi=\left(-L_{0} \mu\right) \psi-\left(L_{0} \psi\right) \mu-(D \mu)^{*} a D \psi
$$

Therefore, $\mu$ satisfies

$$
\left\{\begin{array}{l}
-L_{0} \mu-\left(\frac{D \psi}{\psi}\right)^{*} a D \mu-\frac{L_{0} \psi}{\psi} \mu=0  \tag{A.5}\\
\left.\mu\right|_{\Gamma}=\frac{h}{\psi} \quad \text { and } \quad \mu(x) \rightarrow 0 \quad \text { as }|x| \rightarrow \infty
\end{array}\right.
$$

Let $\mu_{1}$ and $\mu_{2}$ be solutions to (A.5). Then $g:=\mu_{1}-\mu_{2}$ satisfies

$$
\left\{\begin{array}{l}
-L_{0} g-\left(\frac{D \psi}{\psi}\right)^{*} a D g-\frac{L_{0} \psi}{\psi} g=0  \tag{A.6}\\
\left.g\right|_{\Gamma}=0 \quad \text { and } \quad g(x) \rightarrow 0 \quad \text { as }|x| \rightarrow \infty
\end{array}\right.
$$

To prove uniqueness, it is sufficient to show that the solution $g$ to (A.6) is trivial. For each $\varepsilon>0$, there exists $R_{\varepsilon}$ such that $|g| \leq \varepsilon, B_{R_{\varepsilon}}^{c}$. Take $R \geq R_{\varepsilon} \vee R_{0}$. Then we see that

$$
|g| \leq \varepsilon, \quad B_{R} \cap \mathcal{D}^{c}
$$

since $\psi>0$ and $K(x ; \psi)>0$ in $\mathcal{D}^{c}$. Thus, we see that $g=0$ because $\varepsilon$ is arbitrary.
Let us show the existence of the solution to (A.4). We can assume $h \geq 0$. Consider the following Dirichlet problem for $R>R_{0}$ :

$$
\begin{cases}-L_{0} \xi_{R}=0, & B_{R} \cap \overline{\mathcal{D}}^{c}  \tag{A.7}\\ \left.\xi_{R}\right|_{\Gamma}=h, & \left.\xi_{R}\right|_{\partial B_{R}}=0\end{cases}
$$

Then we have

$$
\begin{equation*}
\left\|\xi_{R}\right\|_{L^{\infty}\left(B_{R} \cap \mathcal{D}^{c}\right)} \leq\|h\|_{L^{\infty}(\Gamma)} \tag{A.8}
\end{equation*}
$$

It is clear that $\xi_{R} \leq \xi_{R^{\prime}}$ and $R<R^{\prime}$ by the maximum principle. Therefore, there exists $\xi \in L^{\infty}\left(R^{n} \cap \mathcal{D}^{c}\right)$ and

$$
\xi_{R} \rightarrow \xi, \quad\|\xi\|_{L^{\infty}\left(\mathcal{D}^{c}\right)} \leq\|h\|_{L^{\infty}(\Gamma)}
$$

When taking

$$
\mathcal{D}^{*} \subset \subset \tilde{\mathcal{D}} \subset B_{R} \cap \mathcal{D}^{c}
$$

we see that

$$
\left\|\xi_{R}\right\|_{W^{2, p}\left(\mathcal{D}^{*}\right)} \leq c\left\|\xi_{R}\right\|_{L^{p}(\tilde{\mathcal{D}})} \leq c^{\prime}\left\|\xi_{R}\right\|_{L^{\infty}(\tilde{\mathcal{D}})} \leq c^{\prime}\|h\|_{L^{\infty}(\Gamma)}
$$

Thus, $\xi_{R}$ converges to $\xi$ weakly in $W_{\text {loc }}^{1, q}$. Regularity theorems show that $\xi \in W_{\text {loc }}^{2, q}$.

Let us take a bounded domain $\mathcal{D}_{1}$ such that $\mathcal{D} \subset \mathcal{D}_{1}$ and a bounded Borel function $\phi$ on $\Gamma_{1}=\partial \mathcal{D}_{1}$. We consider a Dirichlet problem

$$
\left\{\begin{array}{l}
-L_{0} \zeta=0, \quad \mathcal{D}_{1}  \tag{A.9}\\
\left.\zeta\right|_{\Gamma_{1}}=\phi
\end{array}\right.
$$

which admits a solution $\zeta \in W^{2, p}\left(\mathcal{D}_{1}\right) \cap L^{\infty}$. For this solution, we consider exterior Dirichlet problem (A.4) with $h=\zeta$. Then we introduce an operator $P: \mathbf{B}\left(\Gamma_{1}\right) \mapsto \mathbf{B}\left(\Gamma_{1}\right)$ defined by

$$
\begin{equation*}
P \phi(x)=\xi(x), \quad x \in \Gamma_{1}, \tag{A.10}
\end{equation*}
$$

where $\xi(x)$ is the solution to (A.4) with $h=\zeta$. In a similar manner to Lemma 5.1 in [1], Chapter II, we have

$$
\sup _{B \in \mathcal{B}\left(\Gamma_{1}\right), x, y \in \Gamma_{1}} \lambda_{x, y}(B)<1
$$

where

$$
\lambda_{x, y}(B)=P \chi_{B}(x)-P \chi_{B}(y), \quad B \in \mathcal{B}\left(\Gamma_{1}\right)
$$

Moreover, we have the following proposition; cf. Theorem 4.1, Chapter II in [1].

Proposition A.2. Operator $P$ defined above satisfies the following properties.

$$
\begin{equation*}
\|P \phi\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq\|\phi\|_{L^{\infty}\left(\Gamma_{1}\right)}, \quad P 1(x)=1 \tag{A.11}
\end{equation*}
$$

and for some $\delta>0$,
(A.12) $\quad P \chi_{B}(x)-P \chi_{B}(y) \leq 1-\delta, \quad x, y \in \Gamma_{1}, B \in \mathcal{B}\left(\Gamma_{1}\right)$.

Furthermore, there exists a probability measure $\pi(d x)$ on $\left(\Gamma_{1}, \mathcal{B}\left(\Gamma_{1}\right)\right)$ such that

$$
\begin{align*}
&\left|P^{n} \phi(x)-\int \phi(x) \pi(d x)\right| \leq K\|\phi\|_{L^{\infty}} e^{-\rho n}  \tag{A.13}\\
& \\
& \rho=\log \frac{1}{1-\delta}, K=\frac{2}{1-\delta}
\end{align*}
$$

and

$$
\begin{equation*}
\int \phi(x) \pi(d x)=\int P \phi(x) \pi(d x) \tag{A.14}
\end{equation*}
$$

for any bounded Borel function $\phi$.

Consider an exterior Dirichlet problem for a given function $f \in F_{K}$ :

$$
\left\{\begin{array}{l}
-L_{0} u=f, \quad x \in \overline{\mathcal{D}}^{c},  \tag{A.15}\\
\left.u\right|_{\Gamma}=0 .
\end{array}\right.
$$

Then we have the following proposition.
Proposition A.3. For a given function $f \in F_{K}$, there exists a unique solution $u \in W_{\text {loc }}^{2, p}, 1<p<\infty$, to (A.15) such that

$$
\sup _{x \in \mathcal{D}^{c}} \frac{|u(x)|}{\psi(x)}<\infty
$$

Proof. Assume that $f \geq 0, f \in F_{K}$. For $R>R_{0}$ we consider a Dirichlet problem on $B_{R} \cap \mathcal{D}^{c}$ :

$$
\left\{\begin{array}{l}
-L_{0} u_{R}=f, \quad x \in B_{R} \cap \overline{\mathcal{D}}^{c},  \tag{A.16}\\
\left.u_{R}\right|_{\Gamma}=0,\left.\quad u_{R}\right|_{\partial B_{R}}=0 .
\end{array}\right.
$$

There exists a unique solution $u_{R} \in W_{0}^{2, p}\left(B_{R} \cap \overline{\mathcal{D}}^{c}\right)$. Set

$$
c_{f}=\underset{x \in \mathcal{D}^{c}}{\operatorname{ess} \sup } \frac{|f(x)|}{K(x ; \psi)} .
$$

Then we have

$$
\begin{equation*}
0 \leq u_{R} \leq c_{f} \psi \tag{A.17}
\end{equation*}
$$

To see that, set $\tilde{u}_{R}:=u_{R}-c_{f} \psi$. Then

$$
\begin{aligned}
-L_{0} \tilde{u}_{R} & =-L_{0} u_{R}+c_{f} L_{0} \psi \\
& =f-c_{f} K(x ; \psi) \leq 0, \quad \overline{\mathcal{D}}^{c} \cap B_{R}
\end{aligned}
$$

Therefore,

$$
\tilde{u}_{R} \leq 0, \quad \overline{\mathcal{D}}^{c} \cap B_{R},
$$

since $\tilde{u}_{R}$ is subharmonic in $\overline{\mathcal{D}}^{c} \cap B_{R}$ and $\tilde{u}_{R} \leq 0$ on $\Gamma \cup \partial B_{R}$. Hence, we have $u_{R} \leq c_{f} \psi$.

On the other hand,

$$
-L_{0} u_{R}=f \geq 0, \quad B_{R} \cap \overline{\mathcal{D}}^{c}
$$

Hence, $u_{R}$ is superharmonic and $u_{R}=0$ on $\Gamma \cap \partial B_{R}$. Thus,

$$
u_{R} \geq 0, \quad B_{R} \cap \overline{\mathcal{D}}^{c}
$$

and (A.17) holds.
If $f \leq 0, f \in F_{K}$ and $c_{f}=\operatorname{ess}_{\sup }^{x \in \mathcal{D}^{c}} \frac{|f(x)|}{K(x ; \psi)}$, then, through the same arguments for $-f$, we obtain

$$
-c_{f} \psi \leq u_{R}^{-} \leq 0
$$

where $-u_{R}^{-}$is the corresponding solution to (A.16). Therefore, for general $f=$ $f^{+}-f^{-}$, we have

$$
-c_{f} \psi \leq u_{R} \leq c_{f} \psi
$$

Let $u_{R}^{+}$be a solution to (A.16) for $f^{+}$. Then, $u_{R}^{+}$is nondecreasing with respect to $R$ because of the maximum principle. Indeed, for $R<R^{\prime}$, we have

$$
\begin{aligned}
-L_{0}\left(u_{R^{\prime}}^{+}-u_{R}^{+}\right)=0, & B_{R} \cap \overline{\mathcal{D}}^{c}, \\
u_{R^{\prime}}^{+}-u_{R}^{+} \geq 0, & \Gamma \cup \partial B_{R} .
\end{aligned}
$$

Since $u_{R}^{+}$is dominated by $c_{f} \psi$, there exists $u^{+}$such that

$$
u^{+}(x)=\lim _{R \rightarrow \infty} u_{R}^{+}(x),\left.\quad u^{+}(x)\right|_{\Gamma}=0
$$

Let us show that $u^{+}(x)$ satisfies

$$
-L_{0} u^{+}=f^{+}, \quad \overline{\mathcal{D}}^{c}
$$

Set

$$
\mathcal{D}^{*}:=B_{R} \cap \overline{\mathcal{D}}^{c}, \quad \mathcal{D}^{\prime} \subset \subset \mathcal{D}^{*} \cup \partial \mathcal{D}^{*}
$$

Then we have

$$
\begin{aligned}
\left\|u^{+}\right\|_{2, p ; \mathcal{D}^{\prime}} & \leq c\left(\left\|u^{+}\right\|_{p ; \mathcal{D}^{*}}+\left\|f^{+}\right\|_{p ; \mathcal{D}^{*}}\right) \\
& \leq c^{\prime}\left(\left\|u^{+}\right\|_{\infty ; \mathcal{D}^{*}}+\left\|f^{+}\right\|_{p ; \mathcal{D}^{*}}\right.
\end{aligned}
$$

For $\mathcal{D}^{\prime \prime} \subset \mathcal{D}^{\prime}$ injection $W^{2, p}\left(\mathcal{D}^{\prime}\right) \hookrightarrow W^{1, q}\left(\mathcal{D}^{\prime \prime}\right), 1 \leq q \leq \frac{n p}{n-p}$, is compact. Therefore, $u_{R}^{+} \rightarrow u^{+}$weakly in $W_{\text {loc }}^{1, q}$ for each $1 \leq q<\infty$ and $u^{+}$is a weak solution to

$$
\left\{\begin{array}{l}
-L_{0} u^{+}=f^{+}, \quad R^{n} \cap \overline{\mathcal{D}}^{c} \\
\left.u^{+}\right|_{\Gamma}=0
\end{array}\right.
$$

By the regularity theorem $u^{+} \in W_{\text {loc }}^{2, p}, \forall p>1$.
Similarly, we have $u^{-} \in W_{\text {loc }}^{2, p}$, which is a solution to

$$
\left\{\begin{array}{l}
-L_{0} u^{-}=f^{-}, \quad R^{n} \cap \overline{\mathcal{D}}^{c} \\
\left.u^{-}\right|_{\Gamma}=0
\end{array}\right.
$$

Now let us prove uniqueness. For $i=1,2$, we assume that $u_{i}$ is a solution to (A.15) such that

$$
-c_{f} \psi \leq u_{i} \leq c_{f} \psi, \quad u_{i} \in W_{\mathrm{loc}}^{2, p}
$$

Then $u=u_{1}-u_{2}$ satisfies

$$
\begin{cases}-L_{0} u=0, & \overline{\mathcal{D}}^{c},  \tag{A.18}\\ \left.u\right|_{\Gamma}=0, & -2 c_{f} \psi \leq u \leq 2 c_{f} \psi, u \in W_{\mathrm{loc}}^{2, p}\end{cases}
$$

We shall prove that $u$ satisfying (A.18) is trivial, $u \equiv 0$. For this purpose, we set

$$
u=v \psi^{\alpha}, \quad \alpha=1+c_{a}>1
$$

where $c_{a}>0$ is the constant that appears in (A.3). Since $-L_{0} u=0$ we have

$$
L_{0} v+2 a\left(\frac{D \psi}{\psi}\right)^{*} a D v+\frac{\alpha v}{\psi}\left\{L_{0} \psi+\frac{\alpha-1}{\psi}(D \psi)^{*} a D \psi\right\}=0
$$

Note that

$$
-L_{0} \psi-\frac{\alpha-1}{\psi}(D \psi)^{*} a D \psi=K(x ; \psi)-\frac{\alpha-1}{\psi}(D \psi)^{*} a D \psi \geq 0
$$

for $|x| \gg 1$ under assumption (A.3). Moreover,

$$
v=\frac{u}{\psi^{\alpha}} \rightarrow 0 \quad \text { as }|x| \rightarrow \infty
$$

Hence, from the maximum principle, we see that $v \equiv 0$ as in the proof of Proposition A.1.

Let $f$ be a function on $R^{n}$ such that $f$ is bounded in $\mathcal{D}$ and $f \in F_{K}\left(\mathcal{D}^{c}\right)$, and $\mathcal{D}_{1}$ a bounded domain such that $\mathcal{D} \subset \mathcal{D}_{1}$. We consider

$$
\left\{\begin{array}{l}
-L_{0} \Psi=f, \quad \mathcal{D}_{1}  \tag{A.19}\\
\left.\Psi\right|_{\Gamma_{1}}=0
\end{array}\right.
$$

and

$$
\left\{\begin{array}{l}
-L_{0} \xi=f, \quad R^{n} \cap \overline{\mathcal{D}}^{c},  \tag{A.20}\\
\left.\xi\right|_{\Gamma}=\left.\Psi\right|_{\Gamma} .
\end{array}\right.
$$

Then we set

$$
T f(x)=\xi(x), \quad x \in \Gamma_{1},
$$

and

$$
\begin{equation*}
\nu(f)=\frac{\int_{\Gamma_{1}} T f(\sigma) \pi(d \sigma)}{\int_{\Gamma_{1}} T 1(\sigma) \pi(d \sigma)} . \tag{A.21}
\end{equation*}
$$

We further consider

$$
\left\{\begin{array}{l}
-L_{0} z=f  \tag{A.22}\\
z \in W_{\mathrm{loc}}^{2, p},
\end{array} \quad \sup _{x \in \mathcal{D}^{c}} \frac{|z|}{\psi}<\infty\right.
$$

Then, as in the proof of Theorem 5.3, in [1], Chapter II, we obtain the following proposition. Here, we only give the proof of the existence of the solution for use in Section 6.

Proposition A.4. Equation (A.22) has a solution unique up to additive constants if and only if $v(f)=0$. Moreover,

$$
\begin{equation*}
\nu(f)=\int m(y) f(y) d y \tag{A.23}
\end{equation*}
$$

for $m \in L^{1}\left(R^{n}\right), m \geq 0$ and $-L_{0}^{*} m=0$ in distribution sense

$$
\begin{equation*}
\int m(y)\left(-L_{0} z\right) d y=0, \quad z \in W_{\mathrm{loc}}^{2, p} \tag{A.24}
\end{equation*}
$$

such that $z \in F_{\psi}$ and $-L_{0} z \in F_{K}$. Furthermore, $m(x)$ is the only function in $L^{1}$ satisfying (A.24) and

$$
\int m(x) d x=1
$$

Proof of existence. Let $\zeta_{0}=\Psi$ and $\eta_{0}=\xi$, where $\Psi$ (resp., $\xi$ ) is the solution to (A.19) [resp., (A.20)]. For each $k=1,2, \ldots$ define $\zeta_{k}$ and $\eta_{k}$ as follows. Let $\zeta_{k}$ be the solution to (A.9) for $\phi=\eta_{k-1}$, and $\eta_{k}$ the solution to (A.4) for $h=\zeta_{k}$. Then

$$
\left.\eta_{0}(x)\right|_{\Gamma_{1}}=T f(x),\left.\quad \eta_{n}(x)\right|_{\Gamma_{1}}=P^{n}(T f)(x), \quad n=1,2, \ldots
$$

Since $\int_{\Gamma_{1}} T f(x) \pi(d x)=0$, we have

$$
\left|P^{n}(T f)(x)\right| \leq K\|T f\|_{L^{\infty}\left(\Gamma_{1}\right)} e^{-\rho n}
$$

by (A.13). Set $\tilde{\eta}_{n}(x)=\sum_{k=0}^{n} \eta_{k}(x), \tilde{\zeta}_{n}(x)=\sum_{k=0}^{n} \zeta_{k}(x)$. Then

$$
\left.\tilde{\eta}_{n}\right|_{\Gamma_{1}}=T f+P(T f)+\cdots+P^{n}(T f) .
$$

Therefore, we see that there exists $\bar{\eta} \in C\left(\Gamma_{1}\right)$ such that $\left\|\tilde{\eta}_{n}-\bar{\eta}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \rightarrow 0$, $n \rightarrow 0$. Moreover, we have

$$
\left\|\tilde{\eta}_{n}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq K\|T f\|_{L^{\infty}\left(\Gamma_{1}\right)} \frac{1}{1-e^{-\rho}}
$$

Note that $\tilde{\zeta}_{n}$ is the solution to

$$
\left\{\begin{array}{l}
-L_{0} \tilde{\zeta}_{n}=f,  \tag{A.25}\\
\tilde{\zeta}_{n} \Gamma_{\Gamma_{1}}=\tilde{\eta}_{n-1} \mid \Gamma_{1}
\end{array} \quad \mathcal{D}_{1}\right.
$$

and $\tilde{\eta}_{n}$ the solution to (A.20) with $\Psi(x)=\tilde{\zeta}_{n}$. Noting that

$$
\left\|\tilde{\zeta}_{n}-\tilde{\zeta}_{m}\right\|_{L^{\infty}\left(\mathcal{D}_{1}\right)} \leq\left\|\tilde{\zeta}_{n}-\tilde{\zeta}_{m}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq\left\|\tilde{\eta}_{n-1}-\tilde{\eta}_{m-1}\right\|_{L^{\infty}\left(\Gamma_{1}\right)}
$$

we see that $\tilde{\zeta}_{n}$ converges in $C\left(\overline{\mathcal{D}}_{1}\right)$ and weakly in $W_{\text {loc }}^{1, q}$ since its $W_{\text {loc }}^{2, p}$ norm is bounded; cf. Theorem 9.11 in [16]. By the regularity theorems, the limit $\bar{\zeta} \in W_{\text {loc }}^{2, p} \cap C\left(\overline{\mathcal{D}}_{1}\right)$ and satisfies

$$
\left\{\begin{array}{l}
-L_{0} \tilde{\zeta}=f, \quad \mathcal{D}_{1}  \tag{A.26}\\
\left.\tilde{\zeta}\right|_{\Gamma_{1}}=\bar{\eta}
\end{array}\right.
$$

On the other hand, $\tilde{\eta}_{n}-\xi$ is the solution to (A.4) with $h=\tilde{\zeta}_{n}-\left.\Psi\right|_{\Gamma}=\left.\sum_{i=1}^{n} \zeta_{i}\right|_{\Gamma}$ and

$$
\left\|\tilde{\eta}_{n}-\xi\right\|_{L^{\infty}(\Gamma)} \leq\left\|\sum_{j=1}^{n} \zeta_{j}\right\|_{L^{\infty}(\Gamma)} \leq\left\|\sum_{j=0}^{n-1} \eta_{j}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} \leq\left\|\tilde{\eta}_{n-1}\right\|_{L^{\infty}\left(\Gamma_{1}\right)} .
$$

Thus, we see that

$$
\left\|\tilde{\eta}_{n}-\xi\right\|_{L^{\infty}\left(\mathcal{D}^{c}\right)} \leq\left\|\tilde{\eta}_{n-1}\right\|_{L^{\infty}\left(\Gamma_{1}\right)}
$$

and $\tilde{\eta}_{n}$ converges in $C\left(\mathcal{D}^{c}\right)$ and weakly in $W_{\text {loc }}^{1, q}\left(\mathcal{D}^{c}\right)$. The limit $\tilde{\eta} \in W_{\text {loc }}^{2, p}\left(\mathcal{D}^{c}\right) \cap$ $C\left(\mathcal{D}^{c}\right)$ and satisfies (A.20) with $\Psi=\tilde{\zeta}$. Setting $z=\tilde{\zeta}$ in $\mathcal{D}_{1}$ and $z=\tilde{\eta}$ in $\mathcal{D}^{c}$, we have a solution to (A.22).

Acknowledgments. The author thanks the anonymous referee for careful reading the manuscript and giving valuable suggestions. The author also thanks Dr. Y. Watanabe for fruitful discussions.

## REFERENCES

[1] Bensoussan, A. (1988). Perturbation Methods in Optimal Control. Wiley, Chichester. MR0949208
[2] Bensoussan, A. (1992). Stochastic Control of Partially Observable Systems. Cambridge Univ. Press, Cambridge. MR1191160
[3] Bensoussan, A., Frehse, J. and Nagai, H. (1998). Some results on risk-sensitive control with full observation. Appl. Math. Optim. 37 1-41. MR1485061
[4] Bielecki, T. R. and Pliska, S. R. (1999). Risk-sensitive dynamic asset management. Appl. Math. Optim. 39 337-360. MR1675114
[5] Bielecki, T. R., Pliska, S. R. and Sheu, S.-J. (2005). Risk sensitive portfolio management with Cox-Ingersoll-Ross interest rates: The HJB equation. SIAM J. Control Optim. 44 1811-1843 (electronic). MR2193508
[6] Browne, S. (1999). Beating a moving target: Optimal portfolio strategies for outperforming a stochastic benchmark. Finance Stoch. 3 275-294. MR1842287
[7] Browne, S. (1999). The risk and rewards of minimizing shortfall probability. J. Portfolio Management 25 76-85.
[8] Bucy, R. S. and Joseph, P. D. (1987). Filtering for Stochastic Processes with Applications to Guidance, 2nd ed. Chelsea, New York. MR0879420
[9] Davis, M. and Lleo, S. (2008). Risk-sensitive benchmarked asset management. Quant. Finance 8 415-426. MR2435642
[10] Dembo, A. and Zeitouni, O. (1998). Large Deviations Techniques and Applications, 2nd ed. Applications of Mathematics (New York) 38. Springer, New York. MR1619036
[11] DOnsker, M. D. and Varadhan, S. R. S. (1976). On the principal eigenvalue of secondorder elliptic differential operators. Comm. Pure Appl. Math. 29 595-621. MR0425380
[12] Fleming, W. H. and Rishel, R. W. (1975). Deterministic and Stochastic Optimal Control. Springer, Berlin. MR0454768
[13] Fleming, W. H. and Sheu, S.-J. (1999). Optimal long term growth rate of expected utility of wealth. Ann. Appl. Probab. 9 871-903. MR1722286
[14] Fleming, W. H. and Sheu, S. J. (2000). Risk-sensitive control and an optimal investment model. Math. Finance 10 197-213. MR1802598
[15] Fleming, W. H. and Sheu, S. J. (2002). Risk-sensitive control and an optimal investment model. II. Ann. Appl. Probab. 12 730-767. MR1910647
[16] Gilbarg, D. and Trudinger, N. S. (1983). Elliptic Partial Differential Equations of Second Order, 2nd ed. Grundlehren der Mathematischen Wissenschaften [Fundamental Principles of Mathematical Sciences] 224. Springer, Berlin. MR0737190
[17] HAS'minSkiĬ, R. Z. (1980). Stochastic Stability of Differential Equations. Monographs and Textbooks on Mechanics of Solids and Fluids: Mechanics and Analysis 7. Sijthoff \& Noordhoff, Alphen aan den Rijn. MR0600653
[18] Hata, H. and IIda, Y. (2006). A risk-sensitive stochastic control approach to an optimal investment problem with partial information. Finance Stoch. 10 395-426. MR2244352
[19] Hata, H., Nagai, H. and Sheu, S.-J. (2010). Asymptotics of the probability minimizing a "down-side" risk. Ann. Appl. Probab. 20 52-89. MR2582642
[20] Hata, H. and Sekine, J. (2005). Solving long term optimal investment problems with Cox-Ingersoll-Ross interest rates. Adv. Math. Econ. 8 231-255.
[21] Hata, H. and Sekine, J. (2010). Explicit solution to a certain non-ELQG risk-sensitive stochastic control problem. Appl. Math. Optim. 62 341-380. MR2727339
[22] Hata, H. and Sheu, S. J. (2009). "Down-side risk" probability minimization problem for a multidimensional model with stochastic volatilty. Preprint.
[23] Kaise, H. and Nagai, H. (1999). Ergodic type Bellman equations of risk-sensitive control with large parameters and their singular limits. Asymptot. Anal. 20 279-299. MR1715337
[24] Kuroda, K. and Nagai, H. (2002). Risk-sensitive portfolio optimization on infinite time horizon. Stoch. Stoch. Rep. 73 309-331. MR1932164
[25] Ladyzhenskaya, O. A. and Ural'tseva, N. N. (1968). Linear and Quasilinear Elliptic Equations. Academic Press, New York. MR0244627
[26] Nagai, H. (1996). Bellman equations of risk-sensitive control. SIAM J. Control Optim. 34 74-101. MR1372906
[27] Nagai, H. (2001). Risk-sensitive dynamic asset management with partial information. In Stochastics in Finite and Infinite Dimensions 321-339. Birkhäuser, Boston, MA. MR1797094
[28] Nagai, H. (2003). Optimal strategies for risk-sensitive portfolio optimization problems for general factor models. SIAM J. Control Optim. 41 1779-1800 (electronic). MR1972534
[29] NAGAI, H. (2011). Asymptotics of the probability minimizing a "down-side" risk under partial information. Quant. Finance 11 789-803.
[30] Nagai, H. and Peng, S. (2002). Risk-sensitive dynamic portfolio optimization with partial information on infinite time horizon. Ann. Appl. Probab. 12 173-195. MR1890061
[31] Pham, H. (2003). A large deviations approach to optimal long term investment. Finance Stoch. 7 169-195. MR1968944
[32] PHAM, H. (2003). A risk-sensitive control dual approach to a large deviations control problem. Systems Control Lett. 49 295-309. MR2011524
[33] RISHEL, R. (1999). Optimal portfolio management with partial observations and power utility function. In Stochastic Analysis, Control, Optimization and Applications 605-619. Birkhäuser, Boston, MA. MR1702984
[34] Stettner, L. (2004). Duality and risk sensitive portfolio optimization. In Mathematics of Finance (G. Yin and Q. Zhang, eds.). Contemp. Math. 351 333-347. Amer. Math. Soc., Providence, RI. MR2076552
[35] Stutzer, M. (2003). Portfolio choice with endogenous utility: A large deviations approach. J. Econometrics 116 365-386. MR2002529

Division of Mathematical Science for Social Systems<br>Graduate School of Engineering Science<br>Osaka University<br>TOYONAKA, 560-8531<br>JAPAN<br>E-MAIL: nagai@ sigmath.es.osaka-u.ac.jp


[^0]:    Received September 2009; revised April 2011.
    ${ }^{1}$ Supported in part by a Grant-in-aid for Scientific Research 20340019 JSPS.
    MSC2010 subject classifications. 35J60, 49L20, 60F10, 91B28, 93E20.
    Key words and phrases. Large deviation, long-term investment, risk-sensitive stochastic control, $\mathrm{H}-\mathrm{J}-\mathrm{B}$ equation of ergodic type.

