

A GENERAL FRAMEWORK FOR WAVES IN RANDOM MEDIA WITH LONG-RANGE CORRELATIONS

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We consider waves propagating in a randomly layered medium with long-range correlations. An example of such a medium is studied in [19] and leads, in particular, to an asymptotic travel time described in terms of a fractional Brownian motion. Here we study the asymptotic transmitted pulse under very general assumptions on the long-range correlations. In the framework that we introduce in this paper, we prove in particular that the asymptotic time-shift can be described in terms of non-Gaussian and/or multifractal processes.

1. Introduction. Wave propagation in random media has been extensively studied for many years from both theoretical and applied points of view. In particular, the study of the effective shape of an acoustic pulse propagating through a layered medium has attracted a lot of attention [1, 5, 24]. Recently, applications to time reversal [10] have also been the subject of much interest. Currently, there is also a strong interest in problems related to noise and correlations [11]. In all these situations the statistical properties of the medium are important since they affect the statistical properties of the wave field.

In [5] the authors consider an acoustic pulse propagating in a one-dimensional random medium with rapidly decaying correlations. They rigorously prove the classical result of O’Doherty and Anstey [20] which establishes that the effective transmitted pulse is characterised by deterministic spreading and a random time-shift. More precisely, the deterministic spreading is expressed as a convolution with a Gaussian density, and the random time-shift is described in terms of a Brownian motion.

More recently, wave propagation and also homogenization in random media with long-range correlations and/or defined in terms of fractional Brownian motion [2, 13, 19, 23] have been considered. In [19], we extend the result of [5] to such a framework. Then, the asymptotic description of the transmitted pulse is dramatically different from what happens in a mixing case. Indeed, the pulse keeps its initial shape, and its random time-shift is now described in terms of a fractional Brownian motion whose Hurst index depends on the decay rate of the

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correlation function of the random fluctuations. We considered in [19] a particular form of a random process describing the medium, such that it was roughly speaking close to a Gaussian process. Thus, it still remains to study more general cases under the long-range assumption. This is the aim of the present work. We establish that under general long-range assumptions on the medium, the effective pulse still keeps its initial shape as observed in [19], but the time-shift can be very different, non-Gaussian, for instance, depending on the form of the random fluctuations. Moreover, our general result allows us to deal with media with a decay rate of correlations that varies along the propagation direction. This leads to an effective time-shift, described in terms of a multifractional random process which is, roughly speaking, a fractional Brownian motion with a varying Hurst index that reflects the nonhomogeneity of the propagation medium.

In Section 2 we introduce the problem and review the basic wave decomposition approach. Next, we establish the general technical result (Theorem 3.1) in Section 3. We apply this general result to non-Gaussian media in Section 4, to multifractal Gaussian media in Section 5 and to multifractal non-Gaussian media in Section 6 where we prove the main result of the paper (Theorem 6.1). We present a numerical illustration in Section 7. Finally, Section 8 is devoted to the derivation of Theorem 3.1.

2. Preliminaries.

2.1. *Wave decomposition.* The governing equations are the nondimensionalized Euler equations giving conservation of moments and mass

$$(2.1) \quad \rho^\varepsilon(z) \frac{\partial u^\varepsilon}{\partial t}(z, t) + \frac{\partial p^\varepsilon}{\partial z}(z, t) = 0,$$

$$(2.2) \quad \frac{1}{K^\varepsilon(z)} \frac{\partial p^\varepsilon}{\partial t}(z, t) + \frac{\partial u^\varepsilon}{\partial z}(z, t) = 0,$$

where t is the time, z is the depth into the medium, p^ε is the pressure and u^ε the particle velocity. The medium parameters are the density ρ^ε and the bulk-modulus K^ε (reciprocal of the compressibility). We assume that ρ^ε is a constant identically equal to one in our nondimensionalized setting, and $1/K^\varepsilon$ is modeled as follows:

$$(2.3) \quad \frac{1}{K^\varepsilon(z)} = \begin{cases} 1 + \mu^\varepsilon(z) & \text{for } z \in [0, Z], \\ 1 & \text{for } z \in \mathbb{R} - [0, Z], \end{cases}$$

where μ^ε is a centered random process. The number $\varepsilon > 0$ is a parameter that all quantities depend on. As we will see below it is introduced to describe the scales of the problem.

We introduce the right- and left-going waves

$$(2.4) \quad A^\varepsilon = p^\varepsilon + u^\varepsilon \quad \text{and} \quad B^\varepsilon = u^\varepsilon - p^\varepsilon.$$

The boundary conditions are of the form

$$(2.5) \quad A^\varepsilon(z = 0, t) = f(t/\varepsilon^\tau) \quad \text{and} \quad B^\varepsilon(z = Z, t) = 0$$

for a positive real number $\tau > 0$ and a source function f . In order to deduce a description of the transmitted pulse, we open a window of size ε^τ in the neighborhood of the travel time of the homogenized medium and define the processes

$$(2.6) \quad a^\varepsilon(z, s) = A^\varepsilon(z, z + \varepsilon^\tau s) \quad \text{and} \quad b^\varepsilon(z, s) = B^\varepsilon(z, -z + \varepsilon^\tau s).$$

Observe that the background or homogenized medium in our scaling has a constant speed of sound equal to unity and that the medium is matched so that in the frame introduced in (2.6) the pulse shape is constant if $\mu^\varepsilon \equiv 0$ or if we consider the homogenized medium [10]. We introduce next the Fourier transforms \hat{a}^ε and \hat{b}^ε of a^ε and b^ε , respectively,

$$\hat{a}^\varepsilon(z, \omega) = \int_{-\infty}^{\infty} e^{i\omega s} a^\varepsilon(z, s) ds \quad \text{and} \quad \hat{b}^\varepsilon(z, \omega) = \int_{-\infty}^{\infty} e^{i\omega s} b^\varepsilon(z, s) ds,$$

that satisfy

$$(2.7) \quad \frac{d\hat{a}^\varepsilon}{dz} = \frac{i\omega}{2} v^\varepsilon(z) (\hat{a}^\varepsilon - e^{-2i\omega z/\varepsilon^\tau} \hat{b}^\varepsilon), \quad \hat{a}^\varepsilon(0, \omega) = \hat{f}(\omega),$$

$$(2.8) \quad \frac{d\hat{b}^\varepsilon}{dz} = \frac{i\omega}{2} v^\varepsilon(z) (e^{2i\omega z/\varepsilon^\tau} \hat{a}^\varepsilon - \hat{b}^\varepsilon), \quad \hat{b}^\varepsilon(Z, \omega) = 0,$$

where we use the notation

$$(2.9) \quad v^\varepsilon = \frac{\mu^\varepsilon}{\varepsilon^\tau}.$$

Following [5, 10] we express the previous system of equations in terms of the propagator $P_\omega^\varepsilon(z)$ which can be written as

$$(2.10) \quad P_\omega^\varepsilon(z) = \begin{pmatrix} \alpha_\omega^\varepsilon(z) & \overline{\beta_\omega^\varepsilon(z)} \\ \beta_\omega^\varepsilon(z) & \overline{\alpha_\omega^\varepsilon(z)} \end{pmatrix},$$

and that satisfies

$$(2.11) \quad \frac{dP_\omega^\varepsilon}{dz}(z) = \mathcal{H}_\omega^\varepsilon\left(\frac{z}{\varepsilon^\tau}, z\right) P_\omega^\varepsilon(z), \quad P_\omega^\varepsilon(z = 0) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix},$$

with

$$\mathcal{H}_\omega^\varepsilon(z_1, z_2) = \frac{i\omega}{2} v^\varepsilon(z_2) \begin{pmatrix} 1 & -e^{-2i\omega z_1} \\ e^{2i\omega z_1} & -1 \end{pmatrix}.$$

Defining next the transmission coefficient T_ω^ε and the reflection coefficient R_ω^ε by

$$(2.12) \quad T_\omega^\varepsilon(z) = \frac{1}{\overline{\alpha_\omega^\varepsilon(z)}} \quad \text{and} \quad R_\omega^\varepsilon(z) = \frac{\beta_\omega^\varepsilon(z)}{\overline{\alpha_\omega^\varepsilon(z)}},$$

we can write

$$(2.13) \quad a^\varepsilon(Z, s) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-is\omega} T_\omega^\varepsilon(Z) \hat{f}(\omega) d\omega$$

and

$$(2.14) \quad b^\varepsilon(0, s) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-is\omega} R_\omega^\varepsilon(Z) \hat{f}(\omega) d\omega.$$

Hence, we shall study the asymptotics of the propagator P_ω^ε in order to characterize a^ε and b^ε as ε goes to 0.

2.2. A short-range medium. We recall now what happens in a mixing (or short-range) model when $\tau = 1$ and $\mu^\varepsilon(z) = \nu(z/\varepsilon^2)$. We assume that $\nu = \Phi \circ m$ where Φ is a bounded function and m is a centered Markov process with an invariant probability measure whose generator satisfies the Fredholm alternative. This implies that the covariance function $z \mapsto \mathbb{E}[\nu(0)\nu(z)]$ is integrable and then the correlation length σ of the medium is finite

$$\sigma^2 = \int_0^\infty \mathbb{E}[\nu(0)\nu(z)] dz \in [0, \infty).$$

This property is the mixing property or the short-range property. It is well known [5, 10] that under these assumptions the propagator equations P_ω^ε converge to a system of stochastic differential equations driven by independent Brownian motions from which we can deduce that $a^\varepsilon(Z, s) \rightarrow \tilde{a}(Z, s)$ as ε goes to 0 with

$$(2.15) \quad \tilde{a}(Z, s) = (f * G)(s - B),$$

where G is a centered Gaussian density with variance $\sigma^2 Z/2$ and B a Gaussian random variable that can be expressed in terms of a Brownian motion W as $B = \sigma W(Z)/\sqrt{2}$. Proving this result involves using the Diffusion Approximation Theorem [10] to get an asymptotic propagator from which we can deduce the expression of the limit $\tilde{a}(Z, s)$. Notice that, whereas the variance of B depends in particular on Φ , the result does not depend qualitatively on Φ in the sense that B remains Gaussian whatever Φ is.

2.3. A long-range medium. In [19], the propagation in a long-range medium is investigated. The model considered is defined in terms of a fractional Brownian motion. More precisely, we assume that ν^ε has the form

$$\nu^\varepsilon(z) = \varepsilon^{\kappa-\tau} \nu\left(\frac{z}{\varepsilon^2}\right) \quad \text{for } z \in [0, Z],$$

where $\kappa > 0$ and ν is a process that is expressed as $\nu(z) = \Phi(m(z))$ for every z where:

- Φ is an odd \mathcal{C}^∞ -function;

- m is a Gaussian process, centered, stationary and has a correlation function r_m which has the following asymptotic property as z goes to ∞ :

$$(2.16) \quad r_m(z) = \mathbb{E}[m(0)m(z)] \sim c_m z^{-\gamma}, \quad \gamma \in (0, 1).$$

The property (2.16) implies that the covariance function r_ν of ν is not integrable

$$\int_0^\infty |r_\nu(z)| dz = \infty,$$

which means that the correlation length is infinite. This is the so-called long-range property. We mention that a typical example of a process satisfying (2.16) can be constructed as

$$(2.17) \quad m(z) = W_H(z + 1) - W_H(z),$$

where B_H is a fractional Brownian motion (fBm in short) with Hurst parameter $H > 1/2$.

We assume τ, κ and γ satisfy $\tau - \kappa = \gamma$. In this case, we proved that $a^\varepsilon(Z, s) \rightarrow \tilde{a}(Z, s)$ with

$$(2.18) \quad \tilde{a}(Z, s) = f(s - B),$$

where B a Gaussian random variable. We can write B as $B = \sigma_H W_H(Z)$ where W_H is a fractional Brownian motion with Hurst parameter $H = (2 - \gamma)/2$ and σ_H is a positive constant that depends on H and Φ .

3. Medium assumptions and main technical result. The results presented above show that the asymptotic behavior of the pulse shape $a^\varepsilon(Z, s)$ strongly depends on the statistical properties of ν . The pulse shape is affected under short-range assumptions whereas it does not change under the long-range assumptions described above. In Sections 4 and 5 we carry out the analysis of the particular long-range media that we consider in this paper. To facilitate this analysis we establish in this section a theorem under the following general assumptions on $\nu^\varepsilon = \mu^\varepsilon/\varepsilon^\tau$. Let $\lambda > 0$ and define:

- Assumption A₁: As ε goes to 0, the finite-dimensional distributions of the process $\{\int_0^z \nu^\varepsilon(z') dz'\}_z$ converge to those of a process $V = \{V(z)\}_z$ with finite second-order moments.
- Assumption A₂(λ): There exist two symmetric, continuous and two-variable functions $\gamma : [0, Z]^2 \rightarrow [\gamma_-, \gamma_+] \subset (0, 1)$ and $R : [0, Z]^2 \rightarrow (0, \infty)$ such that for every $\delta > 0$, there exists $z_\delta > 0$ sufficiently large such that for every z_1, z_2 and ε satisfying $|z_1 - z_2| > \varepsilon^\lambda z_\delta$,

$$|\mathbb{E}[\nu^\varepsilon(z_1)\nu^\varepsilon(z_2)] - R(z_1, z_2)|z_1 - z_2|^{-\gamma(z_1, z_2)}| \leq \delta R(z_1, z_2)|z_1 - z_2|^{-\gamma(z_1, z_2)}.$$

- Assumption A₃(λ). For every $\rho > 0$ there exist $C_\rho > 0$ and $\gamma_\rho \in (0, 1)$ such that $|\mathbb{E}[\nu^\varepsilon(z_1)\nu^\varepsilon(z_2)]| \leq C_\rho |z_1 - z_2|^{-\gamma_\rho}$ for every $\varepsilon > 0$ and $|z_1 - z_2| < \varepsilon^\lambda \rho$.

Assumption A_1 corresponds to the convergence of the travel-times. Assumptions $A_2(\lambda)$ and $A_3(\lambda)$ are long-range assumptions for nonstationary processes. They describe how the long-range property varies with the propagation distance. In particular, these enable us to apply the next theorem to multifractal media (Sections 5 and 6), which are nonhomogeneous.

Here we give the main technical result of this paper. This theorem is next used in Sections 4, 5 and 6 to establish the asymptotic pulse shape respectively in non-Gaussian and multifractal media.

THEOREM 3.1. *Assume that there exists $\lambda > 0$ such that A_1 , $A_2(\lambda)$ and $A_3(\lambda)$ are satisfied. Then, as ε goes to 0, $\{a^\varepsilon(Z, s)\}_s$ converges in distribution in the space of continuous functions endowed with the uniform topology to the random process $\{\tilde{a}(Z, s)\}_s$ that can be written as*

$$(3.1) \quad \tilde{a}(Z, s) = f\left(s - \frac{1}{2}V(Z)\right).$$

Theorem 3.1 establishes that, under general long-range assumptions, if the travel-time converges then the asymptotic pulse keeps its initial shape but its time shift is described in terms of the asymptotic travel-time. As recalled in Section 2.3 this fact was observed in a particular case in [19]. In fact, the result of [19] follows from Theorem 3.1. Indeed, the model presented in Section 2.3 satisfies A_1 , $A_2(2)$ and $A_3(2)$. In particular, the finite-dimensional distributions of $\{\int_0^z v^\varepsilon(z') dz'\}_z$ converge to those of the process $\{2\sigma_H W_H(z)\}_z$, so that the asymptotic pulse is of the form (2.18).

Notice that the framework we study in this paper is in dramatic contrast with the mixing case where we observe a pulse spreading in addition to the time-shift. This is not so surprising if we remark that Theorem 3.1 does not apply to a process v^ε defined as in Section 2.2 by $v^\varepsilon(z) = \varepsilon^{-1}v(z/\varepsilon^2)$ where v is a mixing process. Indeed, if such a process v^ε satisfied assumption $A_2(\lambda)$ for some $\lambda > 0$, then we would have

$$\int_{z^*}^{\infty} \mathbb{E}[v^\varepsilon(z)v^\varepsilon(0)] dz \geq c^* \int_{z^*}^{\infty} \frac{dz}{z^{\gamma^*}} = \infty$$

for some $c^* > 0$, $z^* \in [0, Z]$ and $\gamma^* \in (0, 1)$, which contradicts the mixing assumption that gives

$$\int_{z^*}^{\infty} \mathbb{E}[v^\varepsilon(z)v^\varepsilon(0)] dz \leq \int_0^{\infty} \mathbb{E}[v(z)v(0)] dz < \infty.$$

To conclude this section we present a heuristic description of the link between the mixing and the long-range cases. For every ω we define

$$\mathbf{v}^\varepsilon = \mathbf{v}_\omega^\varepsilon := (v_1^\varepsilon, v_{2,\omega}^\varepsilon, v_{3,\omega}^\varepsilon),$$

where for every $z \in [0, Z]$ by

$$\begin{aligned} v_1^\varepsilon(z) &= \int_0^z v^\varepsilon(z') dz', \\ v_{2,\omega}^\varepsilon(z) &= \int_0^z v^\varepsilon(z') \cos\left(2\omega \frac{z'}{\varepsilon^\tau}\right) dz', \\ v_{3,\omega}^\varepsilon(z) &= \int_0^z v^\varepsilon(z') \sin\left(2\omega \frac{z'}{\varepsilon^\tau}\right) dz'. \end{aligned}$$

In both cases the three-dimensional process \mathbf{v}^ε plays a crucial role. In the mixing case \mathbf{v}^ε converges to the three-dimensional (nonstandard) Brownian motion $(B_1, B_{2,\omega}, B_{3,\omega})$. In the proof of the convergence

$$a^\varepsilon(Z, s) \longrightarrow \tilde{a}(Z, s) = (f * G)(s - B)$$

one then observes that the Gaussian variable B can be written as $B = B_1(Z)/2$, and that the Gaussian density G derives from $B_{2,\omega}$ and $B_{3,\omega}$ [5, 10, 12]. In the long-range case, let us assume that \mathbf{v}^ε converges to the three-dimensional process $(V, 0, 0)$. This fact was already observed in [18] for the fractional white noise. Now if we substitute $(B_1, B_{2,\omega}, B_{3,\omega})$ with $(V, 0, 0)$ in the expression of the limit $\tilde{a}(Z, s)$ we obtain $B = V(Z)/2$, $G = \delta_0$ (because in fact $\hat{G} \equiv 1$) and hence $\tilde{a}(Z, s) = f(s - V(Z)/2)$. This is what we establish in this paper, in particular by proving the convergence of \mathbf{v}^ε and the substitution mentioned just above.

4. Non-Gaussian asymptotics. In this section we study the case where v^ε has the form

$$v^\varepsilon(z) = \varepsilon^{\kappa-\tau} v\left(\frac{z}{\varepsilon^2}\right) \quad \text{for } z \in [0, Z],$$

where $\kappa > 0$ and v is a process that is assumed to have the form

$$v(z) = \Phi(m(z))$$

for every z where:

- Φ is a continuous function such that $\Phi(\sigma_0 \times \cdot)$ has a Hermite index equal to $K \in \mathbb{N}^*$, where $\sigma_0^2 = \mathbb{E}[m(0)^2]$.
- m is a continuous Gaussian process, centered, stationary and has a correlation function r_m which has the following asymptotic property as z goes to ∞ :

$$(4.1) \quad r_m(z) = \mathbb{E}[m(0)m(z)] \sim c_m z^{-\gamma},$$

where $0 < \gamma < 1/K$.

We denote the K th Hermite coefficient of $\Phi(\sigma_0 \times \cdot)$ by

$$J(K) = \mathbb{E}[\Phi(\sigma_0 X) P_K(X)],$$

where $X \sim \mathcal{N}(0, 1)$, and P_K is the K th Hermite polynomial. Applying Theorem 3.1 we get the following result.

THEOREM 4.1. *Assume that $\tau - \kappa = \gamma K$. Then, as ε goes to 0, $\{a^\varepsilon(Z, s)\}_s$ converges in distribution in the space of continuous functions endowed with the uniform topology to the random process $\{\tilde{a}(Z, s)\}_s$ that can be written as*

$$(4.2) \quad \tilde{a}(Z, s) = f\left(s - \frac{1}{2}W_H^K(Z)\right),$$

where W_H^K is the K th Hermite process of index $H = (2 - \gamma K)/2 \in (1/2, 1)$ defined for every z by

$$(4.3) \quad W_H^K(z) = \frac{c_m^{K/2}}{\sigma_0^K} \int_{\mathbb{R}^K} \mathcal{G}_{H,K}(z, x_1, \dots, x_K) \prod_{k=1}^K \hat{B}(dx_k)$$

with

$$\mathcal{G}_{H,K}(z, x_1, \dots, x_K) = \frac{J(K)(e^{-iz \sum_{j=1}^K x_j} - 1)}{K!C(H)^K \sum_{j=1}^K x_j} \prod_{k=1}^K \frac{x_k}{|x_k|^{(H-1)/K+3/2}},$$

where $\hat{B}(dx)$ is the Fourier transform of a Brownian measure,

$$C(H)^2 = \int_{-\infty}^{\infty} \frac{e^{-ix}}{|x|^{1+2(H-1)/K}} dx,$$

and the multiple stochastic integral is in the sense of [8].

For $H \in (1/2, 1)$ and $K \in \mathbb{N}^*$ given, the Hermite process defined by (4.3) was studied independently in [9] and [25]. Its increments are stationary and its covariance is

$$\mathbb{E}[W_H^K(z_1)W_H^K(z_2)] = \frac{1}{2}(|z_1|^{2H} + |z_2|^{2H} - |z_1 - z_2|^{2H}).$$

It is self-similar and H -Hölder. It is Gaussian if and only if $K = 1$; thus, it is a fractional Brownian motion if and only if $K = 1$. As a consequence, the result of [19] corresponds to the case of $K = 1$ in Theorem 4.1. Moreover, this result is in dramatic contrast to the short-range case where the asymptotics does not depend qualitatively on Φ .

PROOF OF THEOREM 4.1. Following [9] or [25], we find that the finite-dimensional distributions of the antiderivative of ν^ε converge to those of W_H^K ; therefore, A_1 is satisfied. Next we show that $A_2(2)$ and $A_3(2)$ hold. Because of the stationarity of m it is enough to show that

$$(4.4) \quad \mathbb{E}[\nu(0)\nu(z)] \sim c_\nu z^{-K\gamma} \quad \text{as } z \rightarrow \infty$$

for some constant $c_\nu > 0$. By the Hermite expansion we can write

$$\nu(z) = \Phi\left(\sigma_0 \frac{m(z)}{\sigma_0}\right) = \sum_{k=K}^{\infty} \frac{J(k)}{k!} P_k\left(\frac{m(z)}{\sigma_0}\right).$$

Using the properties of the Hermite polynomials we get

$$\begin{aligned}
 \mathbb{E}[v(0)v(z)] &= \sum_{k=K}^{\infty} \frac{J(k)^2}{(k!)^2} \mathbb{E}\left[P_k\left(\frac{m(0)}{\sigma_0}\right) P_k\left(\frac{m(z)}{\sigma_0}\right) \right] \\
 (4.5) \qquad &= \sum_{k=K}^{\infty} \frac{J(k)^2}{k! \sigma_0^{2k}} r_m(z)^k.
 \end{aligned}$$

Therefore, we need to study the limit of

$$z^{\gamma K} \mathbb{E}[v(0)v(z)] = \sum_{k=K}^{\infty} \frac{J(k)^2}{k! \sigma_0^{2k}} z^{\gamma K} r_m(z)^k.$$

Observe that for $k = K$ we have $z^{\gamma K} r_m(z) \sim c$ as $z \rightarrow \infty$, and for $k > K$ we have $z^{\gamma K} r_m(z)^k \rightarrow 0$. Moreover, we have the uniform upper bound for z sufficiently large

$$\frac{J(k)^2}{k! \sigma_0^{2k}} z^{\gamma K} |r_m(z)|^k \leq \frac{J(k)^2}{k!}.$$

Using the fact that $\sum_{k=1}^{\infty} \frac{J(k)^2}{k!} < \infty$, (4.4) follows from the uniform convergence theorem. \square

5. Application to multifractal media. In this section we study the case where the asymptotic medium is described in terms of a multifractional process. In all the situations described above, the media were asymptotically expressed in terms of fractional processes. A drawback of fractional processes for applications is the strong homogeneity of their properties, which are described by their (constant) Hurst index. Therefore, multifractional processes have attracted much attention [3, 21]. Multifractal processes have locally the same properties as fractional processes. Their properties are governed by a $(0, 1)$ -valued function h which is called the multifractional function. Some of the main properties are that multifractional processes are locally self-similar, and their pointwise Hölder exponents vary along their trajectory. In particular, multifractional processes are relevant in order to describe nonhomogeneous media. Before stating the main result of this section, we mention that the most famous multifractional process is the multifractional Brownian motion. It was independently introduced in [3, 21] and can be defined from the harmonizable representation of fractional Brownian motion for every z

$$(5.1) \qquad W_H(z) = \frac{1}{C(H)} \int_{-\infty}^{\infty} \frac{e^{-izx} - 1}{|x|^{H+1/2}} \hat{B}(dx),$$

where \hat{B} is the Fourier transform of a real Gaussian measure B , and the constant $C(H)$ is a renormalization constant and can be written as

$$(5.2) \qquad C(H)^2 = \int_{-\infty}^{\infty} \frac{|e^{-ix} - 1|^2}{|x|^{2H+1}} dx = \frac{\pi}{H \Gamma(2H) \sin(\pi H)}.$$

Now we consider a $(0, 1)$ -valued function h , and we substitute H by $h(z)$ for every z to obtain

$$(5.3) \quad W_h(z) = \frac{1}{\tilde{C}(z)} \int_{-\infty}^{\infty} \frac{e^{-izx} - 1}{|x|^{h(z)+1/2}} \hat{B}(dx),$$

where the constant $\tilde{C}(z)$ is a renormalization function.

We shall here use a different framework for the multifractal modeling that is convenient for the asymptotic analysis and describe this next. We assume that ν^ε has the form

$$\nu^\varepsilon(z) = \varepsilon^{\kappa(z)-\tau} \nu\left(\frac{z}{\varepsilon^2}, z\right) \quad \text{for } z \in [0, Z],$$

where κ is a positive function, and ν is a field that is written as $\nu(z_1, z_2) = \Phi(m(z_1, h(z_2)))$ for every z_1 and z_2 where:

- Φ is a continuous function with Hermite index 1.
- h is a continuous function taking values in $[h_-, h_+] \subset (1/2, 1)$.
- $m = \{m(z, H)\}_{z, H}$ is a centered and continuous Gaussian field such that $\mathbb{E}[m(z, H)^2] = 1$ for every z and H and such that there exists a continuous function $\mathbf{r}: [h_-, h_+]^2 \rightarrow (0, \infty)$ (that we call the asymptotic covariance of m) such that

$$\lim_{z_1 - z_2 \rightarrow \infty} \sup_{(H_1, H_2)} |\mathbf{r}(H_1, H_2) - (z_1 - z_2)^{2-H_1-H_2} \mathbb{E}[m(z_1, H_1)m(z_2, H_2)]| = 0.$$

These assumptions describe that the field m has the long-range property with respect to the variable z . They also express that for each H , the process $m(\cdot, H)$ is stationary and asymptotically fractional because it satisfies the classical invariance principle. As established in [6] this field enables us to define a process that is asymptotically multifractional.

Applying Theorem 3.1 we now get the following theorem.

THEOREM 5.1. *Let $\gamma(z) := \tau - \kappa(z)$, and assume $h(z) = (2 - \gamma(z))/2$. Then, as ε goes to 0, $\{a^\varepsilon(Z, s)\}_s$ converges in distribution in the space of continuous functions endowed with the uniform topology to the random process $\{\tilde{a}(Z, s)\}_s$ that can be written as*

$$(5.4) \quad \tilde{a}(Z, s) = f\left(s - \frac{1}{2}S_h(Z)\right),$$

where S_h is a centered Gaussian process with covariance for $z_1, z_2 \geq 0$ given by

$$(5.5) \quad \mathbb{E}[S_h(z_1)S_h(z_2)] = J(1)^2 \int_0^{z_1} du_1 \int_0^{z_2} du_2 \tilde{\mathcal{R}}(u_1, u_2),$$

where

$$\tilde{\mathcal{R}}(u_1, u_2) = \mathcal{R}(u_1, u_2; h(u_1), h(u_2))|u_1 - u_2|^{h(u_1)+h(u_2)-2}$$

with

$$(5.6) \quad \mathcal{R}(z_1, z_2; H_1, H_2) = \mathbf{r}(H_1, H_2)1_{z_1 \geq z_2} + \mathbf{r}(H_2, H_1)1_{z_1 < z_2}.$$

The process S_h was introduced in [6]. This process is continuous and multifractional in the sense that its pointwise Hölder exponent is $h(t_0)$ at the point t_0 :

$$\sup \left\{ H, \lim_{\varepsilon \rightarrow 0} \frac{S_h(t_0 + \varepsilon) - S_h(t_0)}{|\varepsilon|^H} = 0 \right\} = h(t_0).$$

Notice that in the case of h is constant Theorem 5.1 corresponds to the result of [19].

PROOF OF THEOREM 5.1. By the same procedure as in proving (4.4), we get from the asymptotic assumptions for $\{m(z, H)\}$ that

$$\lim_{z_1 - z_2 \rightarrow \infty} \sup_{(H_1, H_2) \in [h_-, h_+]^2} |(z_1 - z_2)^{2-H_1-H_2} \mathbb{E}[v(z_1, H_1)v(z_2, H_2)] - J(1)^2 \mathbf{r}(H_1, H_2)| = 0.$$

If we denote, respectively, v^ε and w^ε the antiderivatives of $z \mapsto v^\varepsilon(z)$ and $z \mapsto \varepsilon^{2h(z)-2}m(z/\varepsilon^2, h(z))$, then, by using the same argument as above we also get

$$(5.7) \quad \lim_{\varepsilon \rightarrow 0} \mathbb{E}[|v^\varepsilon(z) - J(1)w^\varepsilon(z)|^2] = 0,$$

which implies that the convergence of the finite-dimensional distributions of v^ε can be reduced to those of w^ε . Hence, without loss of generality and from the point of view of the analysis we can assume that $\Phi = \text{Id}$ and work with

$$v^\varepsilon(z) = J(1)\varepsilon^{2h(z)-2}m\left(\frac{z}{\varepsilon^2}, h(z)\right) = \varepsilon^{2h(z)-2}m\left(\frac{z}{\varepsilon^2}, h(z)\right).$$

Following [6], the finite-dimensional distributions of the antiderivative of v^ε converges to those of S_h , and thus A_1 is satisfied. Now we check $A_2(2)$. We let $\delta > 0$ and thanks to the asymptotic assumption on m , there exists z_δ such that for every z_1, z_2 and ε satisfying $|z_1 - z_2| > \varepsilon^2 z_\delta$ we have

$$\sup_{(H_1, H_2)} \left| \left| \frac{z_1 - z_2}{\varepsilon^2} \right|^{2-H_1-H_2} \mathbb{E} \left[m\left(\frac{z_1}{\varepsilon^2}, H_1\right) m\left(\frac{z_2}{\varepsilon^2}, H_2\right) \right] - \mathcal{R}\left(\frac{z_1}{\varepsilon^2}, \frac{z_2}{\varepsilon^2}; H_1, H_2\right) \right| < \delta.$$

Then, noting that $\mathcal{R}(z_1/\varepsilon^2, z_2/\varepsilon^2, H_1, H_2) = \mathcal{R}(z_1, z_2, H_1, H_2)$ and substituting (H_1, H_2) by $(h(z_1), h(z_2))$ we get

$$\left| \left| \frac{z_1 - z_2}{\varepsilon^2} \right|^{2-h(z_1)-h(z_2)} \mathbb{E} \left[m\left(\frac{z_1}{\varepsilon^2}, h(z_1)\right) m\left(\frac{z_2}{\varepsilon^2}, h(z_2)\right) \right] - \mathcal{R}(z_1, z_2; h(z_1), h(z_2)) \right| < \delta.$$

Letting $\mathcal{R}^*(z_1, z_2) := \mathcal{R}(z_1, z_2; h(z_1), h(z_2))$ and noticing that $\sup(1/\mathcal{R}^*) < \infty$ (because $\inf \mathcal{R}^* > 0$) we obtain

$$\begin{aligned} & |\mathbb{E}[v^\varepsilon(z_1)v^\varepsilon(z_2)] - \mathcal{R}^*(z_1, z_2)|z_1 - z_2|^{h(z_1)+h(z_2)-2}| \\ & < \delta \mathcal{R}^*(z_1, z_2)|z_1 - z_2|^{h(z_1)+h(z_2)-2} \sup(1/\mathcal{R}^*), \end{aligned}$$

which proves $A_2(2)$. It remains to check $A_3(2)$. Let $\rho > 0$. Because of the boundedness assumption on m , there exists a constant $C_1(\rho) > 0$ so that for every z_1, z_2 and ε satisfying $|z_1 - z_2|/\varepsilon^2 < \rho$, we have

$$\left| \mathbb{E} \left[m \left(\frac{z_1}{\varepsilon^2}, H_1 \right) m \left(\frac{z_2}{\varepsilon^2}, H_2 \right) \right] \right| \leq C_1(\rho).$$

Thus,

$$\begin{aligned} |\mathbb{E}[v^\varepsilon(z_1)v^\varepsilon(z_2)]| & \leq C_1(\rho)\varepsilon^{2h(z_1)+2h(z_2)-4} \\ & = C_1(\rho)|z_1 - z_2|^{h(z_1)+h(z_2)-2} \left| \frac{z_1 - z_2}{\varepsilon^2} \right|^{2-h(z_1)-h(z_2)} \\ & \leq C_1(\rho)|z_1 - z_2|^{h(z_1)+h(z_2)-2} \rho^{2-h(z_1)-h(z_2)} \\ & \leq C_2(\rho)|z_1 - z_2|^{h(z_1)+h(z_2)-2}, \end{aligned}$$

where $C_2(\rho)$ can be chosen such that $C_1(\rho)\rho^{2-h(z_1)-h(z_2)} \leq C_2(\rho)$. So $A_3(2)$ is satisfied and the proof can be concluded by applying Theorem 3.1. \square

We finish this subsection by applying Theorem 5.1 to an example that was mentioned in [6]. Let us consider W_H defined as in (5.1). We let

$$(5.8) \quad m(z, H) = W_H(z + 1) - W_H(z).$$

We compute the covariance between $m(z_1, H_1)$ and $m(z_2, H_2)$ for every z_1, z_2, H_1 and H_2

$$\begin{aligned} & \mathbb{E}[m(z_1, H_1)m(z_2, H_2)] \\ (5.9) \quad & = \frac{1}{2} \frac{C((H_1 + H_2)/2)^2}{C(H_1)C(H_2)} |z_1 - z_2|^{H_1+H_2} \\ & \quad \times \left(\left| 1 + \frac{1}{z_1 - z_2} \right|^{H_1+H_2} + \left| 1 - \frac{1}{z_1 - z_2} \right|^{H_1+H_2} - 2 \right). \end{aligned}$$

By Taylor's formula we get that the asymptotic covariance \mathbf{r} of $\{m(z, H)\}_{z, H}$ can be written as

$$(5.10) \quad \mathbf{r}(H_1, H_2) = \frac{1}{2}(H_1 + H_2)(H_1 + H_2 - 1) \frac{C((H_1 + H_2)/2)^2}{C(H_1)C(H_2)}.$$

Then applying Theorem 5.1 we get that $\{a^\varepsilon(Z, s)\}_s$ converges in distribution to $\tilde{a}(Z, s) = f(s - \frac{1}{2}S_h(Z))$ where

$$(5.11) \quad S_h(Z) = J(1) \int_{-\infty}^{\infty} \left(\int_0^Z \frac{-ix e^{-iux}}{C(h(u))|x|^{h(u)+1/2}} du \right) \hat{B}(dx).$$

As mentioned in Section 6.1 of [6], we also can observe that if we assume that h is differentiable then we can write $S_h(Z)$ as

$$(5.12) \quad S_h(Z) = J(1) \int_{-\infty}^{\infty} \hat{B}(dx) \left\{ \frac{(e^{-iZx} - 1)}{C(h(Z))|x|^{h(Z)+1/2}} - \int_0^Z \frac{(e^{-iux} - 1)}{|x|^{h(u)+1/2}} \left(\frac{\log|x|}{C(h(u))} - \frac{C'(h(u))}{C(h(u))^2} \right) h'(u) du \right\},$$

which means that $S_h(Z)$ is the sum of a multifractional Brownian motion as in (5.3) and of a regular process.

6. A non-Gaussian and multifractal medium. In this section we study the case of a medium that generalizes the media discussed above. We define $\{m(z, H)\}_{z, H}$ for every $z \geq 0$ by

$$(6.1) \quad m(z, H) = \frac{1}{C(H)} \int_{\mathbb{R}} \exp(-izx) \psi(x) |x|^{1/2-H} \hat{B}(dx),$$

where $H \in (1/2, 1)$, $C(H)$ is a renormalization constant, ψ is a complex-valued symmetric function and $\hat{B}(dx)$ is the Fourier transform of a real Gaussian measure. We assume that ψ is continuous, $\psi(0) = 1$ and satisfies $|\psi(x)| = \mathcal{O}_{|x| \rightarrow \infty}(|x|^{-1})$. Notice that the family of processes defined by (5.8) in terms of fractional Brownian motion $\{W_H(z)\}_{z, H}$ is an example of such a process.

Thus, $\{m(z, H)\}_{z, H}$ is a centered Gaussian field and its covariance can be written as

$$(6.2) \quad \mathbb{E}[m(z_1, H_1)m(z_2, H_2)] = \int_{\mathbb{R}} \frac{\exp(i(z_2 - z_1)x) |\psi(x)|^2}{C(H_1)C(H_2)|x|^{H_1+H_2-1}} dx.$$

Now we consider a function h that takes its values in $[h_-, h_+] \subset (1/2, 1)$ and a truncation function Φ with Hermite index $K \in \mathbb{N}^*$. We define v^ε as

$$v^\varepsilon(z) = \varepsilon^{\kappa(z)-\tau} v\left(\frac{z}{\varepsilon^2}, z\right),$$

where

$$v(z_1, z_2) = \Phi(m(z_1, \tilde{h}_K(z_2)))$$

with

$$\tilde{h}_K(z) = \frac{h(z) - 1}{K} + 1.$$

We can then show that v^ε satisfies assumptions $A_2(2)$ and $A_3(2)$. In particular, we have

$$(6.3) \quad \mathbb{E}[v^\varepsilon(z_1)v^\varepsilon(z_2)] \sim \frac{J(K)^2}{K!} \mathbf{r}(\tilde{h}_K(z_1), \tilde{h}_K(z_2)) |z_1 - z_2|^{h(z_1)+h(z_2)-2}$$

when $|z_1 - z_2|/\varepsilon^2$ goes to ∞ assuming that $\kappa(z) - \tau = 2h(z) - 2$, and \mathbf{r} is defined as in (5.10). Therefore, because Theorem 3.1 says that, under long-range assumptions, the asymptotic behavior of $a^\varepsilon(Z, s)$ is essentially given by the limit of $v^\varepsilon(z)$, we can conclude by the following result.

THEOREM 6.1. *As ε goes to 0, $\{a^\varepsilon(Z, s)\}_s$ converges in distribution in the space of continuous functions endowed with the uniform topology to the random process $\{\tilde{a}(Z, s)\}_s$ that can be written as*

$$(6.4) \quad \tilde{a}(Z, s) = f\left(s - \frac{1}{2}S_h^K(Z)\right),$$

where S_h^K is a centered process given for every z by

$$(6.5) \quad S_h^K(z) = \int_{\mathbb{R}^K} \mathcal{G}_{h,K}(z, x_1, \dots, x_K) \prod_{k=1}^K \hat{B}(dx_k),$$

where

$$\mathcal{G}_{h,K}(z, x_1, \dots, x_K) = \int_0^z \frac{J(K)e^{-iu \sum_{k=1}^K x_k}}{K!C(\tilde{h}_K(u))^K} \prod_{k=1}^K \frac{-ix_k}{|x_k|^{\tilde{h}_K(u)+1/2}} du.$$

Notice that the process S_h^K is equal (in distribution) to W_H^K of Section 4 if h is a constant equal to H , and is equal to S_h of Section 5 if $K = 1$. Because of these facts, S_h^K is in general non-Gaussian and multifractional. This shows that under general long-range assumptions the asymptotic time-shift is neither Gaussian, nor homogeneous. This is in dramatic contrast to the short-range case where the time shift is a Brownian motion, which is homogeneous and Gaussian.

PROOF OF THEOREM 6.1. We let

$$v^\varepsilon(z) = \int_0^z v^\varepsilon(u) du = \int_0^z du \varepsilon^{2h(u)-2} \Phi\left(m\left(\frac{u}{\varepsilon^2}, \tilde{h}_K(u)\right)\right)$$

and

$$w_K^\varepsilon(z) = \int_0^z du \varepsilon^{2h(u)-2} P_K\left(m\left(\frac{u}{\varepsilon^2}, \tilde{h}_K(u)\right)\right).$$

Using the same arguments as for the beginning of the proof of Theorem 5.1, and the fact that the Hermite index of Φ is K , we get

$$(6.6) \quad \lim_{\varepsilon \rightarrow 0} \mathbb{E} \left[\left| v^\varepsilon(z) - \frac{J(K)}{K!} w_K^\varepsilon(z) \right|^2 \right] = 0.$$

Then using the formula (see [14], for instance)

$$P_K \left(\int_{\mathbb{R}} \phi(x) \hat{B}(dx) \right) = \int_{\mathbb{R}^K} \prod_{k=1}^K \phi(x_k) \hat{B}(dx_k)$$

for every $\phi \in L^2(\mathbb{R})$ we get

$$\begin{aligned} w_K^\varepsilon(z) &= \int_0^z du \frac{\varepsilon^{2h(u)-2}}{C(h(u))^K} \int_{\mathbb{R}^K} e^{-iu \sum_{j=1}^K x_j / \varepsilon^2} \prod_{k=1}^K \frac{\psi(x_k)}{|x_k|^{\tilde{h}_K(u)-1/2}} \hat{B}(dx_k) \\ &= \int_{\mathbb{R}^K} \int_0^z du \prod_{k=1}^K \frac{\psi(x_k)}{|x_k|^{\tilde{h}_K(u)-1/2}} \hat{B}(dx_k) \frac{\varepsilon^{2h(u)-2}}{C(h(u))^K} e^{-iu \sum_{j=1}^K x_j / \varepsilon^2}. \end{aligned}$$

Then we make the substitution $x_k \rightarrow \varepsilon^2 x_k$ for every k

$$\begin{aligned} w_K^\varepsilon(z) &= \int_{\mathbb{R}^K} \int_0^z du \prod_{k=1}^K \frac{\psi(\varepsilon^2 x_k)}{|\varepsilon^2 x_k|^{\tilde{h}_K(u)-1/2}} \hat{B}(\varepsilon^2 dx_k) \frac{\varepsilon^{2h(u)-2}}{C(h(u))^K} e^{-iu \sum_{j=1}^K x_j} \\ &= \varepsilon^{-K} \int_{\mathbb{R}^K} \int_0^z du \prod_{k=1}^K \frac{\psi(\varepsilon^2 x_k)}{|x_k|^{\tilde{h}_K(u)-1/2}} \hat{B}(\varepsilon^2 dx_k) \frac{1}{C(h(u))^K} e^{-iu \sum_{j=1}^K x_j}. \end{aligned}$$

We let

$$\tilde{w}_K^\varepsilon(z) = \int_{\mathbb{R}^K} \int_0^z du \prod_{k=1}^K \frac{\psi(\varepsilon^2 x_k)}{|x_k|^{\tilde{h}_K(u)-1/2}} \hat{B}(dx_k) \frac{1}{C(h(u))^K} e^{-iu \sum_{j=1}^K x_j}.$$

The self-similarity of the Brownian motion gives that $\hat{B}(\varepsilon^2 dx_k)$ is equal in distribution to $\varepsilon \hat{B}(dx_k)$, then we get that

$$w_K^\varepsilon \stackrel{\text{f.d.d.}}{=} \tilde{w}_K^\varepsilon,$$

where $\stackrel{\text{f.d.d.}}{=}$ means the equality of the finite-dimensional distributions. Then, using the assumptions on ψ , we obtain the convergence a.s. of the finite-dimensional margins of $\frac{J(K)}{K!} \tilde{w}_K^\varepsilon$ to those of S_h^K , and thus the convergence of the finite-dimensional distributions of v^ε to those of S_h^K , so A_1 is satisfied. Now, as observed at the beginning of this section, using (6.2) and by the same procedure as in the proof of Theorem 5.1 we show that $A_2(2)$ and $A_3(2)$ hold. We can then conclude by Theorem 3.1. \square

7. Numerical illustration. We illustrate our results with some numerical simulations. In order to show the differences between the mixing and the long-range cases, numerical simulations of the transmitted pulses centered around the travel time are presented in [19]. They are carried out with a fractional white noise medium with Hurst index $H = 0.5$ (corresponding to the mixing case) and $H = 0.6$ (corresponding to the long-range case). These examples illustrate that the pulse shape is not affected by the random fluctuation of the medium when $H = 0.6$ and that it is modified via a convolution with a Gaussian kernel when $H = 0.5$.

Here we aim to illustrate the differences between fractional and multifractional cases. We present simulations of the asymptotic travel times we obtain for media with long-range correlation and different multifractional functions. For the sake of simplicity we restrict ourself to the Gaussian case presented in Section 5, and we let the propagation distance be one. For a fixed multifractional function h , the method we use to simulate the asymptotic travel time S_h is based on the method presented in [22] (pages 370–371) and the invariance principle proved in [6]. We first simulate the fractional white noise $\{Y_j(H)\}_j$ of index $H \in (1/2, 1)$ as in equation (7.11.1) of [22] (page 371). Then, using Theorem 2 of [6] we can use $\sum_{j=1}^{\lfloor Nt \rfloor} N^{-h(j/N)} Y_j(h(j/N))$ to approximate $S_h(t)$. In Figure 1 we show a trajectory of S_h with an increasing multifractional function. In Figure 2 we show a trajectory of S_h with an periodic multifractional function. In both figures we can observe that the regularity varies along the trajectory according to the local Hurst

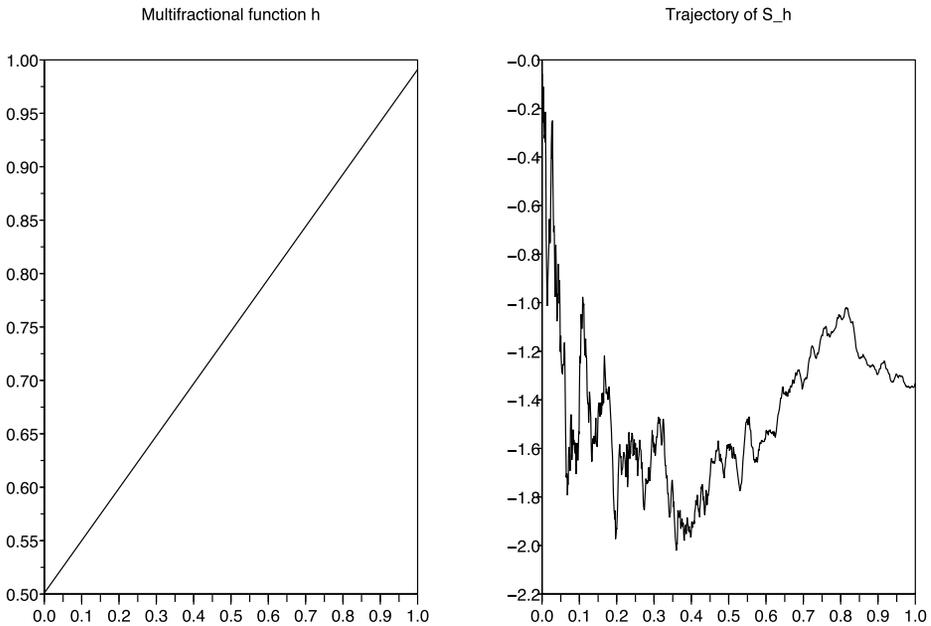


FIG. 1. Trajectory of S_h with an increasing multifractional function.

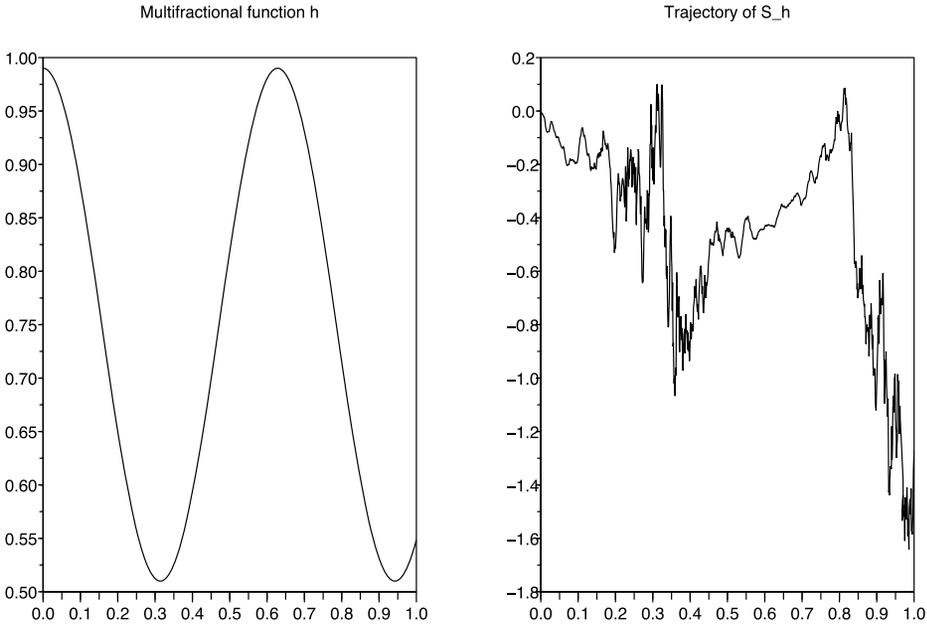


FIG. 2. Trajectory of S_h with a periodic multifractal function.

index. Modeling of this kind may, for instance, be relevant in the case the multi-scale crust of the sedimentary earth or in the context of the turbulent atmosphere. In both cases the field is typically strongly anisotropic with a roughness that depends on depth or height, respectively.

8. Proof of Theorem 3.1. We first give an outline of the proof. As recalled in Section 2 the process $\{a^\varepsilon(Z, s)\}_s$ can be written in terms of the propagator P_ω^ε , and thus the study of the convergence of $\{a^\varepsilon(Z, s)\}_s$ can be analyzed via asymptotic properties of P_ω^ε . The propagator P_ω^ε satisfies the equation

$$\frac{dP_\omega^\varepsilon}{dz}(z) = \mathcal{H}_\omega^\varepsilon\left(\frac{z}{\varepsilon^\tau}, z\right)P_\omega^\varepsilon(z),$$

that we can write in the form

$$(8.1) \quad dP_\omega^\varepsilon(z) = \frac{i\omega}{2} \sum_{j=1}^3 F_j P_\omega^\varepsilon(z) dv_j^\varepsilon(z),$$

where

$$F_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad F_2 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

and

$$F_3 = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix},$$

and v_1^ε , v_2^ε and v_3^ε are three processes of bounded variation that we can write as

$$\begin{aligned} v_1^\varepsilon(z) &= \int_0^z v^\varepsilon(z') dz', \\ v_2^\varepsilon(z) &= \int_0^z v^\varepsilon(z') \cos\left(2\omega \frac{z'}{\varepsilon^\tau}\right) dz', \\ v_3^\varepsilon(z) &= \int_0^z v^\varepsilon(z') \sin\left(2\omega \frac{z'}{\varepsilon^\tau}\right) dz'. \end{aligned}$$

Thanks to T. Lyons's rough paths theory for which we recall some tools in the [Appendix](#) we shall see that the convergence of P_ω^ε can be reduced for a convenient topology to the convergence of the process \mathbf{v}^ε defined as

$$\mathbf{v}^\varepsilon := (v_1^\varepsilon, v_2^\varepsilon, v_3^\varepsilon).$$

Hence, we first prove the convergence of \mathbf{v}^ε , then by [Theorem A.1](#) (see the [Appendix](#)) we deduce the convergence of P_ω^ε in [Section 8.1](#) and thanks to [\(2.13\)](#), we finally conclude by the convergence of $\{a^\varepsilon(Z, s)\}_s$ in [Section 8.2](#).

8.1. Convergence of the propagator. Using [Theorem A.1](#) and the expression [\(8.1\)](#), the asymptotic study of the propagator is reduced to finding the limit in a rough path space of $\mathbf{v}^\varepsilon := (v_1^\varepsilon, v_2^\varepsilon, v_3^\varepsilon)$. This is the aim of the following lemma.

LEMMA 8.1. *There exists $\gamma_* \in (0, 1)$ such that for every $p > 2/(2 - \gamma_*)$, as ε goes to 0, the increments of \mathbf{v}^ε converge in Ω_p to those of \mathbf{V} which can be written as*

$$\mathbf{V} = (V, 0, 0).$$

The proof of [Lemma 8.1](#) is based on establishing several technical lemmas that we do next. We let $r_{v^\varepsilon}(x, y) = \mathbb{E}[v^\varepsilon(x)v^\varepsilon(y)]$.

LEMMA 8.2. *There exist C and γ_* so that*

$$|r_{v^\varepsilon}(x, y)| \leq C|x - y|^{-\gamma_*}$$

for every x and y .

PROOF. The assumptions of [Theorem 3.1](#) imply that for every $\delta > 0$ there exists $z_\delta > 0$ such that for $|x - y| > \varepsilon^\lambda z_\delta$ we have

$$(1 - \delta)R(x, y)|x - y|^{-\gamma(x, y)} \leq r_{v^\varepsilon}(x, y) \leq (1 + \delta)R(x, y)|x - y|^{-\gamma(x, y)}.$$

Hence, taking $\delta = 1$ we get that for $|x - y| > \varepsilon^\lambda z_1$ we have

$$0 \leq r_{v^\varepsilon}(x, y) \leq C|x - y|^{-\gamma+}.$$

Moreover, thanks to the assumptions of Theorem 3.1, we know that there exist C_{z_1} and γ_{z_1} so that for $|x - y| \leq \varepsilon^\lambda z_1$ we have

$$0 \leq |r_{v^\varepsilon}(x, y)| \leq C_{z_1} |x - y|^{-\gamma_{z_1}}.$$

By choosing $\gamma_* := \max(\gamma_+, \gamma_{z_1})$ we get that there exists γ_* so that

$$|\mathbb{E}[v^\varepsilon(x)v^\varepsilon(y)]| \leq C|x - y|^{-\gamma_*}$$

for every x and y . \square

LEMMA 8.3. *For every $z \in [0, Z]$, as ε goes to 0 the sequences $v_2^\varepsilon(z)$ and $v_3^\varepsilon(z)$ converge to 0.*

PROOF. Without loss of generality we present the proof only for $v_2^\varepsilon(z)$ and with $2\omega = 1$. We have

$$\begin{aligned} \mathbb{E}[v_2^\varepsilon(z)^2] &= \int_0^z dx \int_0^z dy \cos\left(\frac{x}{\varepsilon^\tau}\right) \cos\left(\frac{y}{\varepsilon^\tau}\right) r_{v^\varepsilon}(x, y) \\ &= I_1^\varepsilon(z) + I_2^\varepsilon(z), \end{aligned}$$

with

$$I_1^\varepsilon(z) = \int_0^z dx \int_0^z dy \cos\left(\frac{x}{\varepsilon^\tau}\right) \cos\left(\frac{y}{\varepsilon^\tau}\right) R(x, y) |x - y|^{-\gamma(x, y)},$$

$$I_2^\varepsilon(z) = \int_0^z dx \int_0^z dy \cos\left(\frac{x}{\varepsilon^\tau}\right) \cos\left(\frac{y}{\varepsilon^\tau}\right) (r_{v^\varepsilon}(x, y) - R(x, y)) |x - y|^{-\gamma(x, y)}.$$

Let $\delta > 0$, and because of the assumptions of Theorem 3.1, we have that for $|x - y| > \varepsilon^\lambda z_\delta$ (with z_δ sufficiently large) $|r_{v^\varepsilon}(x, y) - R(x, y)| |x - y|^{-\gamma(x, y)} \leq \delta R(x, y) |x - y|^{-\gamma(x, y)}$ for every ε . Combining this with Lemma 8.2 we obtain

$$\begin{aligned} |I_2^\varepsilon(z)| &\leq \delta \int_0^z dx \int_0^z dy R(x, y) |x - y|^{-\gamma(x, y)} \\ &\quad + C_\delta \int_0^z dx \int_0^z dy |x - y|^{-\gamma_*} 1_{|x-y| \leq \varepsilon^\lambda z_\delta} \end{aligned}$$

so that

$$\limsup_{\varepsilon \rightarrow 0} |I_2^\varepsilon(z)| \leq \delta \int_0^z dx \int_0^z dy |x - y|^{-\gamma(x, y)}.$$

The inequality above is valid for every $\delta > 0$, and we conclude

$$\lim_{\varepsilon \rightarrow 0} I_2^\varepsilon(z) = 0.$$

We can deal with $I_1^\varepsilon(z)$ using a Riemann-type result. Indeed, the function $\tilde{R}: (x, y) \mapsto R(x, y) |x - y|^{-\gamma(x, y)}$ is integrable on $\Delta_z = [0, z]^2$, so we can approximate it by a sequence of constant by step functions $(R_N)_N$ such that

$$\lim_{N \rightarrow \infty} \int_0^z dx \int_0^z dy |\tilde{R}(x, y) - R_N(x, y)| = 0.$$

Moreover, we can write

$$|I_1^\varepsilon(z)| \leq \left| \int_0^z dx \int_0^z dy \cos\left(\frac{x}{\varepsilon^\tau}\right) \cos\left(\frac{y}{\varepsilon^\tau}\right) R_N(x, y) \right| \\ + \int_0^z dx \int_0^z dy |\tilde{R}(x, y) - R_N(x, y)|$$

for every ε and N . We easily see that

$$\lim_{\varepsilon \rightarrow 0} \int_0^z dx \int_0^z dy \cos\left(\frac{x}{\varepsilon^\tau}\right) \cos\left(\frac{y}{\varepsilon^\tau}\right) R_N(x, y) = 0$$

so that

$$\limsup_{\varepsilon \rightarrow 0} |I_1^\varepsilon(z)| \leq \int_0^z dx \int_0^z dy |\tilde{R}(x, y) - R_N(x, y)|$$

for every N . This finally shows

$$\lim_{\varepsilon \rightarrow 0} I_1^\varepsilon(z) = 0$$

and then

$$\lim_{\varepsilon \rightarrow 0} \mathbb{E}[v_2^\varepsilon(z)^2] = 0,$$

which completes the proof. \square

Now we deal with a technical lemma regarding the increments of \mathbf{v}^ε .

LEMMA 8.4. *There exist $C > 0$ and $\gamma_* \in (0, 1)$ such that for every z, ζ and $\varepsilon > 0$ we have*

$$\mathbb{E}[\|\mathbf{v}^\varepsilon(z) - \mathbf{v}^\varepsilon(\zeta)\|^2] \leq C|z - \zeta|^{2-\gamma_*}.$$

PROOF. Because of Lemma 8.2 there exists γ_* so that $|\mathbb{E}[v^\varepsilon(x)v^\varepsilon(y)]| \leq C|x - y|^{-\gamma_*}$ for every x and y . Then, for every $j = 1, 2, 3$, we have (taking $z > \zeta$)

$$\mathbb{E}[|v_j^\varepsilon(z) - v_j^\varepsilon(\zeta)|^2] \leq \int_\zeta^z dx \int_\zeta^z dy |\mathbb{E}[v^\varepsilon(x)v^\varepsilon(y)]| \\ \leq C \int_\zeta^z dx \int_\zeta^z dy |x - y|^{-\gamma_*} \\ \leq \frac{2C'}{(1 - \gamma_*)(2 - \gamma_*)} |z - \zeta|^{2-\gamma_*},$$

which completes the proof. \square

In the sequel we shall use the notation $H_* := (2 - \gamma_*)/2$. Using the above lemmas we next deduce the following lemma which deals with identification of the limit.

LEMMA 8.5. *The process \mathbf{V} defined in Lemma 8.1 is a.s. continuous (up to a modification). Moreover, as ε goes to 0, \mathbf{v}^ε converges to \mathbf{V} in the space of continuous functions endowed with the uniform norm.*

PROOF. Assumptions and Lemma 8.3 give the convergence of finite-dimensional distributions of \mathbf{v}^ε to those of \mathbf{V} . Using then the Kolmogorov criterion [4], Lemma 8.4, and the fact that $2H_* > 1$ we get the tightness of $(\mathbf{v}^\varepsilon)_\varepsilon$ in the space of continuous functions endowed with the uniform norm which establishes the proof. \square

Thanks to Lemma 8.5 we conclude with the proof of Lemma 8.1 by establishing the tightness in a rough paths sense.

LEMMA 8.6. *For every $p > 1/H_*$, the sequence $(\mathbf{v}^\varepsilon)_\varepsilon$ is tight in Ω_p and the process \mathbf{V} is a.s. of finite p -variation.*

PROOF OF LEMMAS 8.1 AND 8.6. Let $q \in (1/H_*, p)$. In view of Lemmas A.1 and 8.5 it is enough to prove

$$(8.2) \quad \lim_{A \rightarrow +\infty} \sup_{\varepsilon > 0} \mathbb{P}[V_q(\mathbf{v}^\varepsilon) > A] = 0.$$

Using Chebyshev’s inequality, the fact that $q < 2$, Lemma A.2, the Hölder inequality and Lemma 8.5 we find

$$\begin{aligned} \mathbb{P}[V_q(\mathbf{v}^\varepsilon) > A] &\leq \frac{1}{A^q} \mathbb{E}[V_q(\mathbf{v}^\varepsilon)^q] \\ &\leq \frac{C}{A^q} \sum_{n=1}^{+\infty} n^C \sum_{k=1}^{2^n} \mathbb{E}[\|\mathbf{v}^\varepsilon(z_k^n) - \mathbf{v}^\varepsilon(z_{k-1}^n)\|^q] \\ &\leq \frac{C}{A^q} \sum_{n=1}^{+\infty} n^C \sum_{k=1}^{2^n} \mathbb{E}[\|\mathbf{v}^\varepsilon(z_k^n) - \mathbf{v}^\varepsilon(z_{k-1}^n)\|^2]^{q/2} \\ &\leq \frac{C'}{A^q} \sum_{n=1}^{+\infty} n^C \sum_{k=1}^{2^n} \left(\frac{1}{2^n}\right)^{qH_*} \\ &\leq \frac{C'}{A^q} \sum_{n=1}^{+\infty} n^C \left(\frac{1}{2^n}\right)^{qH_*-1}, \end{aligned}$$

and since $qH_* > 1$ we deduce (8.2). \square

Finally, we can now derive the following lemma which deals with the convergence of the propagator.

LEMMA 8.7. *Let $\{\omega_1, \dots, \omega_n\}$ to be a collection of frequencies. Then, as ε goes to 0, the propagator vector $(P_{\omega_1}^\varepsilon, \dots, P_{\omega_n}^\varepsilon)$ converges in distribution in the space of continuous functions to $(P_{\omega_1}, \dots, P_{\omega_n})$ which is the asymptotic propagator P_ω that we can write as*

$$P_\omega(z) = \begin{pmatrix} \exp\left(\frac{i\omega}{2}V(z)\right) & 0 \\ 0 & \exp\left(-\frac{i\omega}{2}V(z)\right) \end{pmatrix}.$$

PROOF. By combining Theorem A.1, (8.1) and Lemma 8.1 we get that, as ε goes to 0, P_ω^ε converges in distribution in the space of continuous functions (endowed with the topology of the uniform convergence) to the solution P_ω of the following system of equations:

$$dP_\omega(z) = \frac{i\omega}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} P_\omega(z) dV(z).$$

This concludes the proof. \square

We remark that the situation here contrasts with the short-range case. Indeed, the asymptotic propagator is driven by one process in the long-range case whereas it is driven by three processes in the short-range case.

8.2. *Conclusion of the proof.* The remaining part of the proof of Theorem 3.1 follows the lines of [5, 10]; however, we present it here for completeness. Recall that thanks to the formula (2.13) we can write $a^\varepsilon(Z, s)$ in a Fourier-type formula using the transmission coefficient

$$(8.3) \quad a^\varepsilon(Z, s) = \frac{1}{2\pi} \int e^{-is\omega} T_\omega^\varepsilon(Z) \hat{f}(\omega) d\omega,$$

with the transmission coefficient being a functional of the propagator P_ω^ε . We shall use Lemma 8.7 to deduce the convergence of the transmitted wave.

Let $n \in \mathbb{N}$, $s_1 \leq \dots \leq s_n \in [0, \infty)$. We can write:

$$\begin{aligned} & \mathbb{E}[a^\varepsilon(Z, s_1) \cdots a^\varepsilon(Z, s_n)] \\ &= \mathbb{E}\left[\frac{1}{(2\pi)^n} \prod_{j=1}^n \int e^{-is_j\omega} T_\omega^\varepsilon(Z) \hat{f}(\omega) d\omega\right] \\ &= \frac{1}{(2\pi)^n} \int \cdots \int e^{-i\sum_{j=1}^n s_j\omega_j} \hat{f}(\omega_1) \cdots \hat{f}(\omega_n) \\ & \quad \times \mathbb{E}[T_{\omega_1}^\varepsilon(Z) \cdots T_{\omega_n}^\varepsilon(Z)] d\omega_1 \cdots d\omega_n. \end{aligned}$$

Thanks to Lemma 8.7 we have that as $\varepsilon \rightarrow 0$

$$\mathbb{E}[T_{\omega_1}^\varepsilon(Z) \cdots T_{\omega_n}^\varepsilon(Z)] \longrightarrow \mathbb{E}\left[\exp\left(\frac{iV(Z)}{2} \sum_{j=1}^n \omega_j\right)\right],$$

and then

$$\begin{aligned} & \mathbb{E}[a^\varepsilon(Z, s_1) \cdots a^\varepsilon(Z, s_n)] \\ & \rightarrow \frac{1}{(2\pi)^n} \int \cdots \int e^{-i \sum_{j=1}^n s_j \omega_j} \hat{f}(\omega_1) \cdots \hat{f}(\omega_n) \\ & \quad \times \mathbb{E} \left[\exp \left(\frac{iV(Z)}{2} \sum_{j=1}^n \omega_j \right) \right] d\omega_1 \cdots d\omega_n \\ & = \mathbb{E} \left[\frac{1}{(2\pi)^n} \prod_{j=1}^n \int e^{-i(s_j - V(Z)/2)\omega} \hat{f}(\omega) d\omega \right] \\ & = \mathbb{E} \left[\prod_{j=1}^n f(s_j - V(Z)/2) \right]. \end{aligned}$$

The tightness proof is similar to the proof of Lemma 3.2 in [5] and the convergence of $a^\varepsilon(Z, s)$ follows.

APPENDIX: DIFFERENTIAL EQUATIONS AND ROUGH PATHS

In this appendix we fix $p \in [1, 2)$ and consider a closed interval $I = [0, Z]$. We define the p -variation of a continuous function $w : I \rightarrow \mathbb{R}^n$ by

$$V_p(w) := \left(\sup_D \sum_{j=0}^{k-1} \|w(z_{j+1}) - w(z_j)\|^p \right)^{1/p},$$

where \sup_D runs over all finite partition $\{0 = z_0, \dots, z_k = Z\}$ of I and where here and below $\|\cdot\|$ refers to the L^2 norm. The space of all continuous functions of bounded variation (1-variation) is endowed with the p -variation distance

$$\|w\|_p = V_p(w) + \sup_{z \in [0, Z]} |w(z)|,$$

and is denoted by Ω_p^∞ . The closure of this metric space is called the space of all geometric rough paths and is denoted by Ω_p . One of the most important theorems of rough paths theory is the following:

THEOREM A.1 (T. Lyons’s Continuity Theorem). *Let¹ $G : \mathbb{R} \times \mathbb{R}^d \rightarrow \mathcal{L}(\mathbb{R}, \mathbb{R}^d)$ and $F : \mathbb{R} \times \mathbb{R}^d \rightarrow \mathcal{L}(\mathbb{R}^n, \mathbb{R}^d)$ be two smooth functions. Let y be the unique solution of the differential equation*

$$dy(z) = G(z, y(z)) dz + F(z, y(z)) dw(z), \quad y(z=0) = y_0,$$

¹Here $\mathcal{L}(\mathbb{R}, \mathbb{R}^d)$ [resp., $\mathcal{L}(\mathbb{R}^n, \mathbb{R}^d)$] denotes the space of all linear maps from \mathbb{R} (resp., \mathbb{R}^n) to \mathbb{R}^d .

where w is a bounded variation function. Then Itô's map $\mathcal{I}: w \mapsto y$ is continuous with respect to the p -variation distance from $\Omega_p^\infty(\mathbb{R}^n)$ to $\Omega_p^\infty(\mathbb{R}^d)$. Therefore there exists a unique extension of this map (that we still denote by \mathcal{I}) to the space $\Omega_p(\mathbb{R}^n)$

This theorem has been proved by T. Lyons and extensively studied and applied (see [7, 15–17]).

The proof of Theorem 3.1 is based on analysis of the tightness in the space of geometric rough paths. In the context of this we need to compute the p -variation for $p > 1$. To this effect we will need the following lemmas of which the first can be found, for instance, in [16], and the second in [15, 16].

LEMMA A.1. *Let $q \in [1, 2)$ and $(v^\varepsilon)_{\varepsilon>0}$ a family of continuous random processes of finite q -variation whose associated family of probability measures is tight in the space of continuous functions on I and satisfying*

$$(A.1) \quad \lim_{A \rightarrow +\infty} \sup_{\varepsilon > 0} \mathbb{P}[V_q(v^\varepsilon) > A] = 0.$$

Then the family of probability measures associated to $(v^\varepsilon)_{\varepsilon>0}$ is tight in Ω_p for every $p > q$.

LEMMA A.2. *For every $n \in \mathbb{N}$ and every $k = 0, 1, \dots, 2^n$, we let $z_k^n := Zk/2^n$. Let $q \in [1, 2)$ and v be a function of finite q -variation. Then there exist two positive constants C_1, C_2 which do not depend on v such that*

$$V_q(v)^q \leq C_1 \sum_{n=1}^{+\infty} n^{C_2} \sum_{k=1}^{2^n} \|v(z_k^n) - v(z_{k-1}^n)\|^q.$$

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