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# AN INEQUALITY FOR EXPECTATION OF MEANS OF POSITIVE RANDOM VARIABLES 

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#### Abstract

Suppose that $X, Y$ are positive random variables and $m$ is a numerical (commutative) mean. We prove that the inequality $\mathrm{E}(m(X, Y)) \leq$ $m(\mathrm{E}(X), \mathrm{E}(Y))$ holds if and only if the mean is generated by a concave function. With due changes we also prove that the same inequality holds for all operator means in the Kubo-Ando setting. The case of the harmonic mean was proved by C. R. Rao and B. L. S. Prakasa Rao.


## 1. Introduction and preliminaries

Let $x, y$ be positive real numbers. The arithmetic, geometric, harmonic, and logarithmic means are defined by

$$
\begin{aligned}
& m_{a}(x, y)=\frac{x+y}{2}, \quad m_{g}(x, y)=\sqrt{x y} \\
& m_{h}(x, y)=\frac{2}{x^{-1}+y^{-1}}, \quad m_{l}(x, y)=\frac{x-y}{\log x-\log y} .
\end{aligned}
$$

Suppose $X, Y: \Omega \rightarrow(0,+\infty)$ are positive random variables. Linearity of the expectation operator trivially implies

$$
\mathrm{E}\left(m_{a}(X, Y)\right)=m_{a}(\mathrm{E}(X), \mathrm{E}(Y))
$$

On the other hand, the Cauchy-Schwarz inequality implies

$$
\mathrm{E}\left(m_{g}(X, Y)\right) \leq m_{g}(\mathrm{E}(X), \mathrm{E}(Y))
$$

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Notice that the perspective of a concave function is concave.

## 3. Means for positive numbers

We use the notation $\mathbb{R}_{+}=(0,+\infty)$.
Definition 3.1. A bivariate mean [9] is a function $m: \mathbb{R}_{+} \times \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$such that
(1) $m(x, x)=x$.
(2) $m(x, y)=m(y, x)$.
(3) $x<y \Rightarrow x<m(x, y)<y$.
(4) $x<x^{\prime}$ and $y<y^{\prime} \Rightarrow m(x, y)<m\left(x^{\prime}, y^{\prime}\right)$.
(5) $m$ is continuous.
(6) $m$ is positively homogeneous; that is, $m(t x, t y)=t \cdot m(x, y)$ for $t>0$.

We use the notation $\mathcal{M}_{\text {num }}$ for the set of bivariate means described above.
Definition 3.2. Let $\mathcal{F}_{\text {num }}$ denote the class of functions $f: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$such that
(1) $f$ is continuous.
(2) $f$ is monotone increasing.
(3) $f(1)=1$.
(4) $t f\left(t^{-1}\right)=f(t)$ for $t>0$.

The following result is straightforward.
Proposition 3.3. There is a bijection between $\mathcal{M}_{\text {num }}$ and $\mathcal{F}_{\text {num }}$ given by the formulas

$$
m_{f}(x, y)=y f\left(y^{-1} x\right) \quad \text { and } \quad f_{m}(t)=m(1, t)
$$

for positive numbers $x, y$, and $t$.
3.1. Some examples of means. The functions in Table 1 are all concave and even operator concave.

However, there exist nonconcave functions in $\mathcal{F}_{\text {num }}$. Consider, for example, the function

$$
g(x)=\frac{1}{4} \begin{cases}x+3 & 0 \leq x \leq 1 \\ 3 x+1 & x \geq 1\end{cases}
$$

This piecewise affine function is convex and belongs to $\mathcal{F}_{\text {num }}$.

## 4. The main result: COMmutative case

Theorem 4.1. Take a function $f \in \mathcal{F}_{\text {num }}$. The inequality

$$
\begin{equation*}
\mathrm{E}\left(m_{f}(X, Y)\right) \leq m_{f}(\mathrm{E}(X), \mathrm{E}(Y)) \tag{4.1}
\end{equation*}
$$

holds for arbitrary positive random variables $X$ and $Y$ if and only if $f$ is concave.
Proof. Suppose inequality (4.1) holds for a function $f$. Take $\Omega=\{1,2\}$ as a state space with probabilities $p$ and $1-p$, and let $Y$ be the constant function 1 . We set $X(1)=x_{1}$ and $X(2)=x_{2}$ for given $x_{1}, x_{2}>0$. We then have $\mathrm{E}(Y)=1$, and thus

$$
m_{f}(\mathrm{E}(X), \mathrm{E}(Y))=\mathrm{E}(Y) f\left(\frac{\mathrm{E}(X)}{\mathrm{E}(Y)}\right)=f\left(p x_{1}+(1-p) x_{2}\right)
$$

Table 1.

| Name | function | mean |
| :---: | :---: | :---: |
| arithmetic | $\frac{1+x}{2}$ | $\frac{x+y}{2}$ |
| WYD,$\beta \in(0,1)$ | $\frac{x^{\beta}+x^{1-\beta}}{2}$ | $\frac{x^{\beta} y^{1-\beta}+x^{1-\beta} y^{\beta}}{2}$ |
| geometric | $\sqrt{x}$ | $\sqrt{x y}$ |
| harmonic | $\frac{2 x}{x+1}$ | $\frac{2}{x^{-1}+y^{-1}}$ |
| logarithmic | $\frac{x-1}{\log x}$ | $\frac{x-y}{\log x-\log y}$ |

We also have

$$
m_{f}(X, Y)(1)=Y(1) f\left(\frac{X(1)}{Y(1)}\right)=f\left(x_{1}\right)
$$

and

$$
m_{f}(X, Y)(2)=Y(2) f\left(\frac{X(2)}{Y(2)}\right)=f\left(x_{2}\right)
$$

Therefore,

$$
\begin{aligned}
p f\left(x_{1}\right)+(1-p) f\left(x_{2}\right) & =\mathrm{E}\left(m_{f}(X, Y)\right) \leq m_{f}(\mathrm{E}(X), \mathrm{E}(Y)) \\
& =f\left(p x_{1}+(1-p) x_{2}\right),
\end{aligned}
$$

implying that $f$ is concave.
Suppose on the other hand that $f$ is concave, and consider two positive random variables $X$ and $Y$. We only have to prove the theorem under the assumption that $X$ and $Y$ are simple random variables (finite linear combinations of indicator functions). The general case then follows since any positive random variable is a pointwise increasing limit of simple random variables. The (different) values of $X$ are denoted by $x_{1}, \ldots, x_{n}$ with associated (marginal or unconditional) probabilities $p_{1}, \ldots, p_{n}$. The (different) values of $Y$ are denoted by $y_{1}, \ldots, y_{m}$ with associated (marginal or unconditional) probabilities $q_{1}, \ldots, q_{m}$.

The stochastic variable $m_{f}(X, Y)$ takes the values $m_{f}\left(x_{i}, y_{j}\right)$ with probabilities $P\left(X=x_{i}, Y=y_{j}\right)$ for $i=1, \ldots, n$ and $j=1, \ldots, m$ (possibly counted with multiplicity). The mean $m_{f}$ is the perspective of $f$, and thus concave by Proposition 2.2. We may therefore apply Jensen's inequality and obtain

$$
\begin{aligned}
\mathrm{E}\left(m_{f}(X, Y)\right) & =\sum_{i=1}^{n} \sum_{j=1}^{m} P\left(X=x_{i}, Y=y_{j}\right) m_{f}\left(x_{i}, y_{j}\right) \\
& \leq m_{f}\left(\sum_{i=1}^{n} \sum_{j=1}^{m} P\left(X=x_{i}, Y=y_{j}\right)\left(x_{i}, y_{j}\right)\right)
\end{aligned}
$$

$$
\begin{aligned}
= & m_{f}\left(\sum_{i=1}^{n} \sum_{j=1}^{m} P\left(X=x_{i}, Y=y_{j}\right) x_{i}\right. \\
& \left.\sum_{j=1}^{m} \sum_{i=1}^{n} P\left(X=x_{i}, Y=y_{j}\right) y_{j}\right)
\end{aligned}
$$

where we interchanged the summations in the second argument of $m_{f}$. Since the sums of the joint probabilities

$$
\sum_{j=1}^{m} P\left(X=x_{i}, Y=y_{j}\right)=p_{i} \quad \text { and } \quad \sum_{i=1}^{n} P\left(X=x_{i}, Y=y_{j}\right)=q_{j}
$$

we obtain

$$
\mathrm{E}\left(m_{f}(X, Y)\right) \leq m_{f}\left(\sum_{i=1}^{n} p_{i} x_{i}, \sum_{j=1}^{m} q_{j} y_{j}\right)=m_{f}(\mathrm{E}(X), \mathrm{E}(Y))
$$

which is the desired inequality (4.1).

## 5. Noncommutative perspective

For the basic results of this section we refer to [2], [1], and [3]. Let $f$ be a function defined in the open positive half-line. In Section 2 we recalled the perspective of $f$ as the function of two variables $\mathcal{P}_{f}(t, s)=s f\left(s^{-1} t\right)$, where $t, s>0$. Depending on the application, we may also consider the function $(t, s) \rightarrow \mathcal{P}_{f}(s, t)$ and denote this as the perspective of $f$.

If $A$ and $B$ are commuting positive definite matrices, then the matrix $\mathcal{P}_{f}(A, B)$ is well defined by the functional calculus, and it coincides with $B f\left(B^{-1} A\right)$. However, even if $A$ and $B$ do not commute, by choosing an appropriate ordering, one may define the perspective.

Definition 5.1. Let $f$ be a function defined in the open positive half-line. The (noncommutative) perspective $\mathcal{P}_{f}$ of $f$ is then defined by setting

$$
\mathcal{P}_{f}(A, B)=A^{1 / 2} f\left(A^{-1 / 2} B A^{-1 / 2}\right) A^{1 / 2}
$$

for positive definite operators $A$ and $B$.
For the following basic result confer [2, Theorem 2.2], [3, Theorem 1.1], and [1, Theorem 2.2].

Theorem 5.2. The (noncommutative) perspective $\mathcal{P}_{f}$ is convex if and only if $f$ is operator convex.

Let $f:(0, \infty) \rightarrow \mathbf{R}$ be a convex function. Since the perspective $\mathcal{P}_{f}$ is both convex and positively homogenous, we obtain the inequality

$$
\mathcal{P}_{f}\left(\sum_{i=1}^{n} \lambda_{i} x_{i}, \sum_{i=1}^{n} \lambda_{i} y_{i}\right) \leq \sum_{i=1}^{n} \lambda_{i} \mathcal{P}_{f}\left(x_{i}, y_{i}\right)
$$

for tuples $\left(x_{1}, \ldots, x_{n}\right)$ and $\left(y_{1}, \ldots, y_{n}\right)$ of positive numbers and positive numbers $\lambda_{1}, \ldots, \lambda_{n}$. By setting all $\lambda_{i}=1$, this entails the inequality

$$
\mathcal{P}_{f}(\operatorname{Tr} A, \operatorname{Tr} B) \leq \operatorname{Tr} \mathcal{P}_{f}(A, B)
$$

for commuting positive definite matrices $A$ and $B$.
The transformer inequality for the noncommutative perspective of an operator convex function is essentially proved in [5, Theorem 2.2]. Since the perspective of an operator convex function is a convex regular operator map, the statement also follows from [7, Lemma 2.1].

Proposition 5.3 (the transformer inequality). Let $f:(0, \infty) \rightarrow \mathbb{R}$ be an operator convex function. The noncommutative perspective $\mathcal{P}_{f}$ satisfies the inequality

$$
\mathcal{P}_{f}\left(C^{*} A C, C^{*} B C\right) \leq C^{*} \mathcal{P}_{f}(A, B) C
$$

for every contraction $C$ and positive definite operators $A$ and $B$.
Notice that by homogeneity we obtain

$$
\mathcal{P}_{f}\left(C^{*} A C, C^{*} B C\right) \leq C^{*} \mathcal{P}_{f}(A, B) C
$$

for any operator $C$. In particular, if $C$ is invertible, then we have

$$
\mathcal{P}_{f}(A, B) \leq\left(C^{*}\right)^{-1} \mathcal{P}_{f}\left(C^{*} A C, C^{*} B C\right) C^{-1} \leq \mathcal{P}_{f}(A, B)
$$

Hence there is equality, and thus

$$
\begin{equation*}
C^{*} \mathcal{P}_{f}(A, B) C=\mathcal{P}_{f}\left(C^{*} A C, C^{*} B C\right) \tag{5.1}
\end{equation*}
$$

Proposition 5.4. Let $\mathcal{P}_{f}$ be the noncommutative perspective of an operator convex function $f:(0, \infty) \rightarrow \mathbb{R}$, and let $c_{1}, \ldots, c_{n}$ be operators on a Hilbert space $\mathcal{H}$ such that $c_{1}^{*} c_{1}+\cdots+c_{n}^{*} c_{n}=1$. Then

$$
\mathcal{P}_{f}\left(\sum_{i=1}^{n} c_{i}^{*} A_{i} c_{i}, \sum_{i=1}^{n} c_{i}^{*} B_{i} c_{i}\right) \leq \sum_{i=1}^{n} c_{i}^{*} \mathcal{P}_{f}\left(A_{i}, B_{i}\right) c_{i}
$$

for positive definite operators $A_{1}, \ldots, A_{n}$ and $B_{1}, \ldots, B_{n}$ acting on $\mathcal{H}$.
Proof. The perspective $\mathcal{P}_{f}$ is a convex regular operator map of two variables (see [5], [3], and [7]). The statement thus follows from Jensen's inequality for convex regular operator maps (see [7, Theorem 2.2]).

## 6. Operator means in the sense of Kubo-Ando

The celebrated Kubo-Ando theory of matrix means (see [8], [9], [4]) may today be considered as part of the theory of perspectives of positive operator concave functions. This setting is simpler than the general theory of perspectives since a positive operator concave function necessarily is increasing, while a positive operator convex function may not necessarily be monotonic.

Definition 6.1. A bivariate mean for pairs of positive operators is a function

$$
(A, B) \rightarrow m(A, B)
$$

defined in and with values in positive definite operators on a Hilbert space and satisfying, mutatis mutandis, conditions (1) to (5) in Definition 3.1. In addition, the transformer inequality

$$
C^{*} m(A, B) C \leq m\left(C^{*} A C, C^{*} B C\right)
$$

holds for positive definite $A, B$ and arbitrary $C$.
Notice that the transformer inequality replaces (6) in Definition 3.1. We denote by $\mathcal{M}_{\mathrm{op}}$ the set of matrix means.

Example 6.2. The arithmetic, geometric, and harmonic (matrix) means are defined respectively by setting

$$
\begin{aligned}
A \nabla B & =\frac{1}{2}(A+B) \\
A \# B & =A^{1 / 2}\left(A^{-1 / 2} B A^{-1 / 2}\right)^{1 / 2} A^{1 / 2}, \\
A!B & =2\left(A^{-1}+B^{-1}\right)^{-1}
\end{aligned}
$$

We recall that a function $f:(0, \infty) \rightarrow \mathbb{R}$ is said to be operator monotone (increasing) if

$$
A \leq B \quad \Rightarrow \quad f(A) \leq f(B)
$$

for positive definite operators on an arbitrary Hilbert space. An operator monotone function $f$ is said to be symmetric if $f(t)=t f\left(t^{-1}\right)$ for $t>0$ and normalized if $f(1)=1$.

Definition 6.3. $\mathcal{F}_{\text {op }}$ is the class of functions $f: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$such that
(1) $f$ is operator monotone increasing,
(2) $t f\left(t^{-1}\right)=f(t) t>0$,
(3) $f(1)=1$.

The fundamental result, due to Kubo and Ando, is the following.
Theorem 6.4. There is bijection between $\mathcal{M}_{\mathrm{op}}$ and $\mathcal{F}_{\mathrm{op}}$ given by the formula

$$
m_{f}(A, B)=A^{1 / 2} f\left(A^{-1 / 2} B A^{-1 / 2}\right) A^{1 / 2}
$$

Remark 6.5. All the functions in $\mathcal{F}_{\mathrm{op}}$ are (operator) concave, making the operator case quite different from the numerical one.

If $\rho$ is a density matrix and $A$ is self-adjoint, then the expectation of $A$ in the state $\rho$ is defined by setting $\mathrm{E}_{\rho}(A)=\operatorname{Tr}(\rho A)$.

## 7. The main result: noncommutative case

Theorem 7.1. Take $f \in \mathcal{F}_{\text {op }}$. Then

$$
\begin{equation*}
\mathrm{E}_{\rho}\left(m_{f}(A, B)\right) \leq m_{f}\left(\mathrm{E}_{\rho}(A), \mathrm{E}_{\rho}(B)\right) \tag{7.1}
\end{equation*}
$$

Proof. Consider a spectral resolution

$$
\rho=\sum_{i=1}^{n} \lambda_{i} e_{i}
$$

of the density matrix $\rho$ in terms of one-dimensional orthogonal eigenprojections $e_{1}, \ldots, e_{n}$ with corresponding eigenvalues $\lambda_{1}, \ldots, \lambda_{n}$ counted with multiplicity. By setting $c_{i}=\lambda_{i}^{1 / 2} e_{i}$ for $i=1, \ldots, n$, we obtain

$$
\mathrm{E}_{\rho}(A)=\operatorname{Tr} \rho A=\operatorname{Tr} \sum_{i=1}^{n} c_{i}^{*} A c_{i}
$$

for any operator $A$. By using the transformer inequality, we obtain

$$
\begin{aligned}
\mathrm{E}_{\rho}\left(m_{f}(A, B)\right) & =\operatorname{Tr} \sum_{i=1}^{n} c_{i}^{*} m_{f}(A, B) c_{i} \\
& \leq \operatorname{Tr} m_{f}\left(\sum_{i=1}^{n} c_{i}^{*} A c_{i}, \sum_{i=1}^{n} c_{i}^{*} B c_{i}\right) \\
& \leq m_{f}\left(\operatorname{Tr} \sum_{i=1}^{n} c_{i}^{*} A c_{i}, \operatorname{Tr} \sum_{i=1}^{n} c_{i}^{*} B c_{i}\right) \\
& =m_{f}\left(\mathrm{E}_{\rho}(A), \mathrm{E}_{\rho}(B)\right)
\end{aligned}
$$

where in the second inequality we used that the operators

$$
\sum_{i=1}^{n} c_{i}^{*} A c_{i} \quad \text { and } \quad \sum_{i=1}^{n} c_{i}^{*} B c_{i}
$$

are commuting.

## 8. The random matrix case

Let $(\Omega, \mathcal{F}, P)$ be a probability space. A map $X: \Omega \rightarrow M_{n}$ is called a random matrix. We may write

$$
X=\left(X_{i, j}\right)_{i, j=1}^{n}: \Omega \rightarrow M_{n},
$$

and say that $X$ is a positive definite random matrix if

$$
X(\omega)=\left(X_{i, j}(\omega)\right)_{i, j=1}^{n}
$$

is positive definite for $P$-almost all $\omega \in \Omega$. We may readily consider other types of definiteness for random matrices.

Definition 8.1. A positive semidefinite random matrix $\rho: \Omega \rightarrow M_{n}$ is called a random density matrix if $\operatorname{Tr} \rho=1$ for $P$-almost all $\omega \in \Omega$.

Let $X$ and $\rho$ be random matrices on the probability space $(\Omega, \mathcal{F}, P)$, and suppose that $\rho$ is a random density matrix. We introduce the pointwise expectation $\mathrm{E}_{\rho}(X)$ by setting

$$
\left(\mathrm{E}_{\rho} X\right)(\omega)=\operatorname{Tr} \rho(\omega) X(\omega), \quad \omega \in \Omega
$$

The pointwise expectation $\mathrm{E}_{\rho}(X)$ is a random variable with mean

$$
\mathrm{E}\left(\mathrm{E}_{\rho}(X)\right)=\int_{\Omega} \operatorname{Tr} \rho(\omega) X(\omega) d P(\omega)
$$

If $\rho$ is a constant density matrix, then

$$
\mathrm{E}\left(\mathrm{E}_{\rho}(X)\right)=\operatorname{Tr} \rho \int_{\Omega} X(\omega) d P(\omega)=\operatorname{Tr} \rho \mathrm{E}(X)=\mathrm{E}_{\rho}(\mathrm{E}(X))
$$

where $\mathrm{E}(X)$ is the constant matrix with entries

$$
\mathrm{E}(X)_{i, j}=\int_{\Omega} X_{i, j}(\omega) d P(\omega), \quad i, j=1, \ldots, n
$$

Theorem 8.2. Let $X$ and $Y$ be positive definite random matrices on a probability space $(\Omega, \mathcal{F}, P)$. For $f \in \mathcal{F}_{\text {op }}$, we obtain the inequality

$$
\operatorname{EE}_{\rho}\left(m_{f}(X, Y)\right) \leq m_{f}\left(\operatorname{EE}_{\rho}(X), \operatorname{EE}_{\rho}(Y)\right)
$$

for each random density matrix $\rho$ on $(\Omega, \mathcal{F}, P)$.
Proof. The matrices $X(\omega), Y(\omega)$, and $\rho(\omega)$ are positive definite, and $\rho(\omega)$ has a unit trace for almost all $\omega \in \Omega$. The inequality between random variables

$$
\mathrm{E}_{\rho(\omega)}\left(m_{f}(X(\omega), Y(\omega))\right) \leq m_{f}\left(\mathrm{E}_{\rho(\omega)}(X(\omega)), \mathrm{E}_{\rho(\omega)}(Y(\omega))\right)
$$

is therefore valid by our noncommutative inequality in Theorem 7.1. In particular, by taking the mean on both sides, we obtain

$$
\begin{aligned}
\mathrm{EE}_{\rho}\left(m_{f}(X, Y)\right) & \leq \mathrm{E}\left(m_{f}\left(\mathrm{E}_{\rho}(X), \mathrm{E}_{\rho}(Y)\right)\right) \\
& \leq m_{f}\left(\operatorname{EE}_{\rho}(X), \mathrm{EE}_{\rho}(Y)\right)
\end{aligned}
$$

where in the last inequality we used the commutative inequality in Theorem 4.1.

Notice that Theorem 8.2 reduces to the noncommutative inequality when $\Omega$ is a one-point space, and reduces to the commutative inequality when $n=1$. If $\rho$ is a constant matrix, then the order of E and $\mathrm{E}_{\rho}$ in the inequality may be reversed.

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