

Research Article

Analysis of a Patch Model for the Dynamical Transmission of Echinococcosis

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A patch model for echinococcosis due to dogs migration is proposed to explore the effect of dogs migration among patches on the spread of echinococcosis. We firstly define the basic reproduction number R_0 . The mathematical results show that the dynamics of the model can be completely determined by R_0 . If $R_0 < 1$, the disease-free equilibrium is globally asymptotically stable. When $R_0 > 1$, the model is permanence and endemic equilibrium is globally asymptotically stable. According to the simulations, it is shown that the larger diffusion of dogs from the lower epidemic areas to the higher prevalence areas can intensify the spread of echinococcosis. However, the larger diffusion of dogs from the higher prevalence areas to the lower epidemic areas can reduce the spread and is beneficial for disease control.

1. Introduction

Echinococcosis, which is often referred to as hydatid disease, is a parasitic disease that affects both humans and other mammals, such as sheep, dogs, rodents, and horses [1]. The two most clinically relevant species are *Echinococcus granulosus* and *Echinococcus multilocularis*, which cause cystic and alveolar echinococcosis respectively. Humans are incidental hosts and, in most cases, do not contribute to continuance of the parasite life cycle, except under unique circumstances [2].

The prevalent scope of echinococcosis in China is approximately 420 square kilometers, accounting for about 41.7% of the territory. The rate of incidence of echinococcosis has increased in the past decade. The operability of echinococcosis exceeds 10/100000 in each year. High-risk group subject to echinococcosis reaches up to 50 million, and the number of domestic animal amount being faced with the infection of echinococcosis is more than one hundred million, in which the amount of dogs is at least 5 million [3].

Mathematical modeling has become an important tool in analyzing the epidemiological characteristics of infectious disease and can provide useful control measures. Various models have been used to study different aspects of

echinococcosis [4–16]. The models included varied primarily on the basis of six key features that were differentially incorporated in their design [17]. These are (1) the inclusion of a “latent” class (with time delay from host exposure to infectiousness); (2) an age structure for definitive and/or intermediate hosts; (3) the presence of density dependent constraints; (4) accounting for seasonality; (5) stochastic parameters; (6) inclusion of a spatial and risk structures.

In [18], in order to explore effective control and prevention measures authors proposed a deterministic model to study the transmission dynamics of echinococcosis in Xinjiang. The results showed that the dynamics of the model was completely determined by the basic reproductive number R_0 . The model provided an approximate estimate of the basic reproduction number $R_0 = 1.67$.

Many epidemic models with population dispersal among patches have been proposed and studied (see [19–28]). Wang and Zhao [19] proposed an epidemic model to describe the dynamics of disease spread among patches due to population dispersal. The effect of population dispersal among n patches on the spread of a disease was investigated by Jin and Wang in [20]. To understand the effect of transport-related infection on disease spread, an epidemic model for several

regions which are connected by transportation of individuals has been proposed by Cui et al. in [21]. In [23], an SIS patch model with nonconstant transmission coefficients was formulated to investigate the effect of media coverage and human movement on the spread of infectious diseases among patches. Qiu [26] developed a mathematical model to explore the effect of host migration between two patches on the spread of a vector-host disease.

To date, few scholars have researched the echinococcosis transmission models with dogs migration among patches. Considering an increasing number of stray dogs, the dispersal is an essential trait for dogs population. Therefore, we expect to explore the effect of dogs migration among patches on the spread of echinococcosis.

The purpose of this paper is to model the transmission dynamics of echinococcosis spread between two patches due to dogs migration and describe the dynamics of the model. The remaining part of this paper is organized as follows. The model is presented in Section 2. The basic properties on the positivity and boundedness of solutions computing the basic reproduction number are in Section 3. In Section 4, we establish the global stability of the disease-free equilibrium for the model. In Section 5, we will apply the theory of permanence to obtain the permanence of the model. The global stability theorem of endemic equilibrium is stated and proved in Section 6. In Section 7, we give some examples to illustrate how the dogs migration affects the dynamics of echinococcosis. A brief discussion is given in Section 8.

2. Model Formulation

In this section, we mainly formulate an epidemic model to describe the transmission dynamics of echinococcosis spread between two discrete patches due to dogs diffusion.

We firstly formulate a model for the spread of echinococcosis in the i th patch. It follows from [18] that the parameters of humans do not affect dynamical behaviors of echinococcosis model. Hence in the paper we only consider dogs, livestock, and *Echinococcus* eggs in our model. We divide the dogs population in the i th patch into two classes: the susceptible population and the infected population denoted by $S_{Di}(t)$ and $I_{Di}(t)$, respectively. For livestock population, we divide the total livestock population in the i th patch into two classes: susceptible and infectious denoted by $S_{Li}(t)$ and $I_{Li}(t)$, respectively. The density of *Echinococcus* eggs in the i th patch is denoted by $x_i(t)$. Our assumptions on the dynamical transmission of echinococcosis in the i th patch are demonstrated in the flowchart (Figure 1).

If there is no dogs migration among patches, that is, the patches are isolated, we suppose that the echinococcosis dynamics in i th patch is governed by

$$\begin{aligned}\dot{S}_{Di} &= A_{1i} - \beta_{1i}S_{Di}I_{Li} - d_{1i}S_{Di} + \sigma_i I_{Di}, \\ \dot{I}_{Di} &= \beta_{1i}S_{Di}I_{Li} - (d_{1i} + \sigma_i) I_{Di}, \\ \dot{S}_{Li} &= A_{2i} - \beta_{2i}S_{Li}x_i - d_{2i}S_{Li}, \\ \dot{I}_{Li} &= \beta_{2i}S_{Li}x_i - d_{2i}I_{Li}, \\ \dot{x}_i &= a_i I_{Di} - d_i x_i.\end{aligned}\quad (1)$$

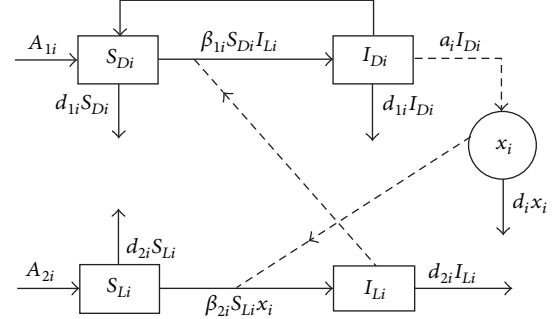


FIGURE 1: Transmission diagram for echinococcosis among dogs, livestock.

All parameters are assumed positive. For the dog population in the i th patch, A_{1i} describes the annual recruitment rate; d_{1i} is the natural death rate; σ_i denotes the recovery rate of transition from infected to noninfected dogs, including natural recovery rate and recovery due to anthelmintic treatment; $\beta_{1i}S_{Di}I_{Li}$ describes the transmission of echinococcosis between susceptible dogs and infectious livestock after the ingestion of cyst-containing organs of the infected livestock. For the livestock population in the i th patch, A_{2i} is the annual recruitment rate; d_{2i} is the death rate; $\beta_{2i}S_{Li}x_i$ describes the transmission of echinococcosis to livestock by the ingestion of *Echinococcus* eggs in the environment. For *Echinococcus* eggs in the i th patch, a_i denotes released rate from infected dogs; d_i is the mortality rate of eggs.

When two patches are connected, we assume that susceptible and infected dogs of every patch i leave for patch j at a per capita rate D_j . Then the dynamics of echinococcosis is governed by the following model:

$$\begin{aligned}\dot{S}_{Di} &= A_{1i} - \beta_{1i}S_{Di}I_{Li} - d_{1i}S_{Di} + \sigma_i I_{Di} - D_i S_{Di} + D_j S_{Dj}, \\ \dot{I}_{Di} &= \beta_{1i}S_{Di}I_{Li} - (d_{1i} + \sigma_i) I_{Di} - D_i I_{Di} + D_j I_{Dj}, \\ \dot{S}_{Li} &= A_{2i} - \beta_{2i}S_{Li}x_i - d_{2i}S_{Li}, \quad i, j = 1, 2, \quad i \neq j, \\ \dot{I}_{Li} &= \beta_{2i}S_{Li}x_i - d_{2i}I_{Li}, \\ \dot{x}_i &= a_i I_{Di} - d_i x_i.\end{aligned}\quad (2)$$

Motivated by biological background of model (2), we always assume that all solutions of model (2) satisfy the following positive initial conditions:

$$\begin{aligned}S_{Di}(0) &= S_{Di0} > 0, & I_{Di}(0) &= I_{Di0} > 0, \\ S_{Li}(0) &= S_{Li0} > 0, & I_{Li}(0) &= I_{Li0} > 0, \\ x_i(0) &= x_{i0} > 0.\end{aligned}\quad (3)$$

We can easily prove that the solution of model (2) with initial conditions (3) satisfies $S_{Di}(t) > 0$, $I_{Di}(t) > 0$, $S_{Li}(t) > 0$, and $I_{Li}(t) > 0$ for all $t > 0$. Here, we omit the proof.

3. Basic Properties and Basic Reproduction Number of the Model

In this section, we mainly present the preliminary results and derive reproduction number for model (2). In order to investigate the dynamics of model (2), we begin with stating some results on model (1). Model (1) has been analyzed in [18]. Model (1) admits a disease-free equilibrium $E_{0i} = (S_{Di}^0, 0, S_{Li}^0, 0, 0)$ and a unique positive equilibrium $E_i^* = (S_{Di}^*, I_{Di}^*, S_{Li}^*, I_{Li}^*, x_i^*)$, where

$$\begin{aligned} S_{Di}^0 &= \frac{A_{1i}}{d_{1i}}, & S_{Li}^0 &= \frac{A_{2i}}{d_{2i}}, \\ S_{Di}^* &= \frac{d_{2i}(d_{1i} + \sigma_i)(A_{1i}\beta_{2i}a_i + d_{1i}d_{2i}d_i)}{a_i\beta_{2i}d_{1i}(\beta_{1i}A_{2i} + d_{1i}d_{2i} + d_{2i}\sigma_i)}, \\ I_{Di}^* &= \frac{a_i\beta_{1i}\beta_{2i}A_{1i}A_{2i} - (d_{1i} + \sigma_i)d_{1i}d_{2i}^2d_i}{a_id_{1i}\beta_{2i}(\beta_{1i}A_{2i} + d_{1i}d_{2i} + d_{2i}\sigma_i)}, \\ S_{Li}^* &= \frac{d_id_{1i}(\beta_{1i}A_{2i} + d_{1i}d_{2i} + d_{2i}\sigma_i)}{\beta_{1i}(a_iA_{1i}\beta_{2i} + d_id_{1i}d_{2i})}, \\ I_{Li}^* &= \frac{a_i\beta_{1i}\beta_{2i}A_{1i}A_{2i} - (d_{1i} + \sigma_i)d_{1i}d_{2i}^2d_i}{d_{2i}\beta_{1i}(A_{1i}\beta_{2i}a_i + d_{1i}d_{2i}d_i)}, \\ x_i^* &= \frac{a_i\beta_{1i}\beta_{2i}A_{1i}A_{2i} - (d_{1i} + \sigma_i)d_{1i}d_{2i}^2d_i}{d_{1i}\beta_{2i}d(\beta_{1i}A_{2i} + d_{1i}d_{2i} + d_{2i}\sigma_i)}. \end{aligned} \quad (4)$$

The reproduction number of model (1) is established in [18], which can be expressed as

$$R_{0i} = \sqrt[3]{\frac{\beta_{1i}\beta_{2i}A_{1i}A_{2i}a_i}{(d_{1i} + \sigma_i)d_{1i}d_{2i}^2d_i}}. \quad (5)$$

From Theorems 3 and 5 in [18], we can obtain the following lemma.

Lemma 1. *Considering model (1), one has that*

- (a) *if $R_{0i} < 1$, then disease-free equilibrium E_{0i} is globally asymptotically stable;*
- (b) *if $R_{0i} > 1$, then positive equilibrium E_i^* is globally asymptotically stable.*

In order to obtain our main results, we need the following lemma. Consider the following linear equation:

$$\begin{aligned} \tilde{N}'_{D1}(t) &= A_{11} - d_{11}\tilde{N}_{D1}(t) - D_1\tilde{N}_{D1}(t) + D_2\tilde{N}_{D2}(t), \\ \tilde{N}'_{D2}(t) &= A_{12} - d_{12}\tilde{N}_{D2}(t) - D_2\tilde{N}_{D2}(t) + D_1\tilde{N}_{D1}(t). \end{aligned} \quad (6)$$

We have the following result on system (6).

Lemma 2. *System (6) has a unique equilibrium $N_D^0(N_{D1}^0, N_{D2}^0)$ which is globally stable, where*

$$\begin{aligned} N_{D1}^0 &= \frac{A_{11}(d_{12} + D_2) + A_{12}D_2}{d_{11}d_{12} + d_{11}D_2 + d_{12}D_1}, \\ N_{D2}^0 &= \frac{A_{12}(d_{11} + D_1) + A_{11}D_1}{d_{11}d_{12} + d_{11}D_2 + d_{12}D_1}. \end{aligned} \quad (7)$$

Proof. The Jacobian matrix of (6) at (N_{D1}^0, N_{D2}^0) is

$$J(N_D^0) = \begin{pmatrix} -(d_{11} + D_1) & D_2 \\ D_1 & -(d_{12} + D_2) \end{pmatrix}. \quad (8)$$

By simple calculations, the corresponding characteristic equation is

$$\Phi(\lambda) = \lambda^2 + a_1\lambda + a_0 = 0, \quad (9)$$

where

$$\begin{aligned} a_1 &= d_{11} + d_{12} + D_1 + D_2 > 0, \\ a_0 &= d_{11}d_{12} + d_{11}D_2 + d_{12}D_1 > 0. \end{aligned} \quad (10)$$

Therefore, all roots of $\Phi(\lambda)$ have negative real parts, and hence $N^0(N_{D1}^0, N_{D2}^0)$ is globally stable. \square

For any $\varepsilon > 0$, we define region Γ_ε as follows:

$$\begin{aligned} \Gamma_\varepsilon &= \left\{ (S_{D1}, I_{D1}, S_{L1}, I_{L1}, x_1, S_{D2}, I_{D2}, S_{L2}, I_{L2}, x_2) \in \mathbb{R}_+^{10}, \right. \\ &\quad S_{Di} + I_{Di} \leq N_{Di}^0 + \varepsilon, S_{Li} + I_{Li} \leq S_{Li}^0 + \varepsilon, \\ &\quad \left. x_i \leq \frac{a_i}{d_i} N_{Di}^0 + \left(1 + \frac{a_i}{d_i}\right) \varepsilon, i = 1, 2 \right\}. \end{aligned} \quad (11)$$

On the ultimate boundedness of solutions for model (2), we have the following result.

Lemma 3. *All solutions of model (2) with initial condition (3) ultimately turn into region Γ_ε as $t \rightarrow \infty$.*

Proof. Let $(S_{D1}(t), I_{D1}(t), S_{L1}(t), I_{L1}(t), x_1(t), S_{D2}(t), I_{D2}(t), S_{L2}(t), I_{L2}(t), x_2(t))$ be any solution of model (2) with initial conditions (3) and let $N_{Di}(t) = S_{Di}(t) + I_{Di}(t)$, $i = 1, 2$. From model (2) we have

$$\begin{aligned} \dot{N}_{D1}(t) &= A_{11} - d_{11}N_{D1}(t) - D_1N_{D1}(t) + D_2N_{D2}(t), \\ \dot{N}_{D2}(t) &= A_{12} - d_{12}N_{D2}(t) - D_2N_{D2}(t) + D_1N_{D1}(t), \end{aligned} \quad (12)$$

and then from Lemma 2 we have $\lim_{t \rightarrow \infty} N_{Di}(t) = N_{Di}^0$, $i = 1, 2$. Hence, for any $\varepsilon > 0$, there is a $t_1 > 0$ such that

$$S_{Di}(t) + I_{Di}(t) \leq N_{Di}^0 + \varepsilon, \quad i = 1, 2, \quad \forall t \geq t_1. \quad (13)$$

From the third and fourth equations of model (2), we have

$$\frac{d(S_{Li}(t) + I_{Li}(t))}{dt} = A_{2i} - d_{2i}(S_{Li}(t) + I_{Li}(t)), \quad (14)$$

and therefore, there exists a $t_2 > 0$ such that

$$S_{Li}(t) + I_{Li}(t) \leq S_{Li}^0 + \varepsilon, \quad i = 1, 2, \quad \forall t \geq t_2. \quad (15)$$

Finally, from the fifth equation of model (2), we have

$$\dot{x}_i(t) \leq a_i(N_{Di}^0 + \varepsilon) - d_ix_i(t), \quad i = 1, 2, \quad \forall t \geq t_1, \quad (16)$$

and then there is a $t_3 > t_1$ such that

$$\begin{aligned} x_i(t) &\leq \frac{a_i}{d_i} (N_{Di}^0 + \varepsilon) + \varepsilon \\ &= \frac{a_i}{d_i} N_{Di}^0 + \left(1 + \frac{a_i}{d_i}\right) \varepsilon, \quad i = 1, 2, \quad \forall t \geq t_3. \end{aligned} \quad (17)$$

Let $t^* = \max\{t_2, t_3\}$, and then for all $t > t^*$ we have

$$\begin{aligned} ((S_{D1}(t), I_{D1}(t), S_{L1}(t), I_{L1}(t), x_1(t), S_{D2}(t), \\ I_{D2}(t), S_{L2}(t), I_{L2}(t), x_2(t))) \in \Gamma_\varepsilon. \end{aligned} \quad (18)$$

This completes the proof of Lemma 3. \square

According to Lemma 3, all feasible solutions of model (2) enter or remain in the region Γ_ε as t becomes large enough. In what follows, the dynamics of model (2) can be considered only in Γ_ε .

Simple algebraic calculation shows that model (2) always has a unique disease-free equilibrium $E_0(N_{D1}^0, 0, S_{L1}^0, 0, 0, N_{D2}^0, 0, S_{L2}^0, 0, 0)$. According to the concepts of next generation matrix and reproduction number presented in [29, 30], we define

$$\begin{aligned} \mathcal{F} &= \begin{pmatrix} \beta_{11} S_{D1} I_{L1} \\ \beta_{21} S_{L1} x_1 \\ a_1 I_{D1} \\ \beta_{12} S_{D2} I_{L2} \\ \beta_{22} S_{L2} x_2 \\ a_2 I_{D2} \end{pmatrix}, \\ \mathcal{V} &= \begin{pmatrix} (d_{11} + \sigma_1) I_{D1} + D_1 I_{D1} - D_2 I_{D2} \\ d_{21} I_{L1} \\ d_1 x_1 \\ (d_{12} + \sigma_2) I_{D2} + D_2 I_{D1} - D_1 I_{D1} \\ d_{22} I_{L2} \\ d_2 x_2 \end{pmatrix}. \end{aligned} \quad (19)$$

Noting that the disease-free equilibrium of model (2) is E_0 , then

$$F = \begin{pmatrix} F_{11} & 0 \\ 0 & F_{22} \end{pmatrix}, \quad (20)$$

where

$$\begin{aligned} F_{11} &= \begin{pmatrix} 0 & \beta_{11} N_{D1}^0 & 0 \\ 0 & 0 & \beta_{21} S_{L1}^0 \\ a_1 & 0 & 0 \end{pmatrix}, \\ F_{22} &= \begin{pmatrix} 0 & \beta_{12} N_{D2}^0 & 0 \\ 0 & 0 & \beta_{22} S_{L2}^0 \\ a_2 & 0 & 0 \end{pmatrix}, \\ V &= \begin{pmatrix} d_{11} + \sigma_1 + D_1 & 0 & 0 & -D_2 & 0 & 0 \\ 0 & d_{21} & 0 & 0 & 0 & 0 \\ 0 & 0 & d_1 & 0 & 0 & 0 \\ -D_1 & 0 & 0 & d_{12} + \sigma_2 + D_2 & 0 & 0 \\ 0 & 0 & 0 & 0 & d_{22} & 0 \\ 0 & 0 & 0 & 0 & 0 & d_2 \end{pmatrix}. \end{aligned} \quad (21)$$

Denote $\Delta = d_1 d_2 d_{21} d_{22} [d_{11}(d_{12} + \sigma_2 + D_2) + \sigma_1(d_{12} + \sigma_2 + D_2) + D_1(d_{12} + \sigma_2)]$. After extensive algebraic calculations, we can obtain

$$FV^{-1} = \frac{1}{\Delta} \begin{pmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{pmatrix}, \quad (22)$$

where

$$\begin{aligned} M_{11} &= \begin{pmatrix} 0 & \frac{\Delta(A_{11}d_{12} + A_{11}D_2 + A_{12}D_2)}{d_{21}(d_{11}d_{12} + d_{11}D_2 + d_{12}D_1)} & 0 \\ 0 & 0 & \frac{\Delta\beta_{21}A_{21}}{d_{21}d_1} \\ d_1d_2d_{21}d_{22}a_1(d_{12} + \sigma_2 + D_2) & 0 & 0 \end{pmatrix}, \\ M_{12} &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ d_1d_2d_{21}d_{22}a_1D_2 & 0 & 0 \end{pmatrix}, \quad M_{21} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ d_1d_2d_{21}d_{22}a_2D_1 & 0 & 0 \end{pmatrix}, \\ M_{22} &= \begin{pmatrix} 0 & \frac{\Delta\beta_{12}(A_{11}D_1 + A_{12}d_{11} + A_{12}D_1)}{d_{22}(d_{11}d_{12} + d_{11}D_2 + d_{12}D_1)} & 0 \\ 0 & 0 & \frac{\Delta\beta_{22}A_{22}}{d_{22}d_2} \\ d_1d_2d_{21}d_{22}a_2(d_{11} + \sigma_1 + D_1) & 0 & 0 \end{pmatrix}. \end{aligned} \quad (23)$$

From the proof of Theorem 2 in [30], it follows that

$$R_0 < 1 \ (R_0 = 1, R_0 > 1) \iff s(J) < 1 \ (s(J) = 0, s(J) > 0), \quad (24)$$

where

$$J = F - V = \begin{pmatrix} -(d_{11} + \sigma_1 + D_1) & \beta_{11}N_{D1}^0 & 0 & D_2 & 0 & 0 \\ 0 & -d_{21} & \beta_{21}S_{L1}^0 & 0 & 0 & 0 \\ a_1 & 0 & -d_1 & 0 & 0 & 0 \\ D_1 & 0 & 0 & -(d_{12} + \sigma_2 + D_2) & \beta_{21}N_{D2}^0 & 0 \\ 0 & 0 & 0 & 0 & -d_{22} & \beta_{22}S_{L2}^0 \\ 0 & 0 & 0 & a_2 & 0 & -d_2 \end{pmatrix} \quad (25)$$

and $s(J)$ is the maximum real part of the eigenvalues of matrix J .

Using Theorem 2 in [30], we can easily obtain the following stability result.

Theorem 4. For model (2), one has that

- (a) if $R_0 < 1$, then disease-free equilibrium E_0 is locally asymptotically stable;
- (b) if $R_0 > 1$, then disease-free equilibrium E_0 is unstable.

4. Global Stability of the Disease-Free Equilibrium

We start by considering the global stability of disease-free equilibrium E_0 when $R_0 < 1$.

Theorem 5. The disease-free equilibrium E_0 of model (2) is globally asymptotically stable in Γ_ε if $R_0 < 1$.

Proof. From Theorem 4 we find that disease-free equilibrium E_0 is locally asymptotically stable if $R_0 < 1$. In the following we only need to prove the global attractiveness of E_0 . From (24) we can see that if $R_0 < 1$, then $s(J) < 0$. Hence, there is a small enough number $\varepsilon > 0$ such that $s(J_\varepsilon) < 0$, where $J_\varepsilon = J + \varepsilon J_1$ and

$$J_1 = \begin{pmatrix} 0 & \beta_{11} & 0 & 0 & 0 & 0 \\ 0 & 0 & \beta_{21} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \beta_{12} & 0 \\ 0 & 0 & 0 & 0 & 0 & \beta_{22} \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}. \quad (26)$$

Let $(S_{D1}(t), I_{D1}(t), S_{L1}(t), I_{L1}(t), x_1(t), S_{D2}(t), I_{D2}(t), S_{L2}(t), I_{L2}(t), x_2(t))$ be any solution of model (2) in Γ_ε , then

$$S_{Di}(t) \leq N_{Di}^0 + \varepsilon, \quad S_{Li}(t) \leq S_{Li}^0 + \varepsilon, \quad i = 1, 2, \quad \forall t \geq 0. \quad (27)$$

From model (2), it follows that

$$\begin{aligned} \dot{I}_{D1} &\leq \beta_{11}(N_{D1}^0 + \varepsilon)I_{L1} - (d_{11} + \sigma_1)I_{D1} - D_1I_{D1} + D_2I_{D2}, \\ \dot{I}_{L1} &\leq \beta_{21}(S_{L1}^0 + \varepsilon)x_1 - d_{21}I_{L1}, \\ \dot{x}_1 &\leq a_1I_{D1} - d_1x_1, \\ \dot{I}_{D2} &\leq \beta_{12}(N_{D2}^0 + \varepsilon)I_{L2} - (d_{12} + \sigma_2)I_{D2} - D_2I_{D2} + D_1I_{D1}, \\ \dot{I}_{L2} &\leq \beta_{22}(S_{L2}^0 + \varepsilon)x_2 - d_{22}I_{L2}, \\ \dot{x}_2 &\leq a_2I_{D2} - d_2x_2. \end{aligned} \quad (28)$$

Define an auxiliary linear system:

$$\begin{aligned} \bar{I}'_{D1} &= \beta_{11}(N_{D1}^0 + \varepsilon)\bar{I}_{L1} - (d_{11} + \sigma_1)\bar{I}_{D1} - D_1\bar{I}_{D1} + D_2\bar{I}_{D2}, \\ \bar{I}'_{L1} &= \beta_{21}(S_{L1}^0 + \varepsilon)\bar{x}_1 - d_{21}\bar{I}_{L1}, \\ \bar{x}'_1 &= a_1\bar{I}_{D1} - d_1\bar{x}_1, \\ \bar{I}'_{D2} &= \beta_{12}(N_{D2}^0 + \varepsilon)\bar{I}_{L2} - (d_{12} + \sigma_2)\bar{I}_{D2} - D_2\bar{I}_{D2} + D_1\bar{I}_{D1}, \\ \bar{I}'_{L2} &= \beta_{22}(S_{L2}^0 + \varepsilon)\bar{x}_2 - d_{22}\bar{I}_{L2}, \\ \bar{x}'_2 &= a_2\bar{I}_{D2} - d_2\bar{x}_2. \end{aligned} \quad (29)$$

Since system (29) is a linear system, the globally stability of origin is determined by the stability of matrix J_ε . Since $s(J_\varepsilon) < 0$, then all the eigenvalues of matrix J_ε have negative real parts. It then follows that each solution of (29) satisfies

$$\begin{aligned} \lim_{t \rightarrow +\infty} \bar{I}_{Di}(t) &= 0, & \lim_{t \rightarrow +\infty} \bar{I}_{Li}(t) &= 0, \\ \lim_{t \rightarrow +\infty} \bar{x}_i(t) &= 0, & i &= 1, 2. \end{aligned} \quad (30)$$

By the comparison principle we have

$$\begin{aligned} \lim_{t \rightarrow +\infty} I_{Di}(t) &= 0, & \lim_{t \rightarrow +\infty} I_{Li}(t) &= 0, \\ \lim_{t \rightarrow +\infty} x_i(t) &= 0, & i &= 1, 2. \end{aligned} \quad (31)$$

Then the limiting system of model (2) is

$$\begin{aligned}\dot{S}_{D1} &= A_{11} - d_{11}S_{D1} - D_1S_{D1} + D_2S_{D2}, \\ \dot{S}_{D2} &= A_{12} - d_{12}S_{D2} - D_2S_{D2} + D_1S_{D1}, \\ \dot{S}_{L1} &= A_{21} - d_{21}S_{L1}, \\ \dot{S}_{L2} &= A_{22} - d_{22}S_{L2}.\end{aligned}\quad (32)$$

By Lemma 2 we find that there is a unique equilibrium $(N_{D1}^0, N_{D2}^0, S_{L1}^0, S_{L2}^0)$ of system (32), which is globally asymptotically stable. Thus, according to the theory of asymptotic autonomous systems [31], we finally obtain that disease-free equilibrium E_0 is globally asymptotically stable for model (2) when $R_0 < 1$. This completes the proof of Theorem 5. \square

5. Permanence

We now turn to the case where $R_0 > 1$. We first establish the permanence for model (2).

Theorem 6. *Let $D_i > 0$, $i = 1, 2$. If $R_0 > 1$, then model (2) is permanent. Furthermore, model (2) also has at least one positive equilibrium $E^*(S_{D1}^*, I_{D1}^*, S_{L1}^*, I_{L1}^*, x_1^*, S_{D2}^*, I_{D2}^*, S_{L2}^*, I_{L2}^*, x_2^*)$.*

Proof. Define

$$\begin{aligned}X &= \{(S_{D1}, I_{D1}, S_{L1}, I_{L1}, x_1, S_{D2}, I_{D2}, S_{L2}, I_{L2}, x_2) : \\ &\quad S_{Di} \geq 0, I_{Di} \geq 0, S_{Li} \geq 0, I_{Li} \geq 0, x_i \geq 0, i = 1, 2\}, \\ X_0 &= \{(S_{D1}, I_{D1}, S_{L1}, I_{L1}, x_1, S_{D2}, I_{D2}, S_{L2}, I_{L2}, x_2) : \\ &\quad S_{Di} > 0, I_{Di} > 0, S_{Li} > 0, I_{Li} > 0, x_i > 0, i = 1, 2\}, \\ \partial X_0 &= X \setminus X_0, \\ M_\partial &= \{(S_{D1}(0), I_{D1}(0), S_{L1}(0), I_{L1}(0), x_1(0), \\ &\quad S_{D2}(0), I_{D2}(0), S_{L2}(0), I_{L2}(0), x_2(0)) : \\ &\quad (S_{D1}(t), I_{D1}(t), S_{L1}(t), I_{L1}(t), x_1(t), \\ &\quad S_{D2}(t), I_{D2}(t), S_{L2}(t), I_{L2}(t), x_2(t))\end{aligned}\quad (33)$$

satisfies model (2),

$$\begin{aligned}&(S_{D1}(t), I_{D1}(t), S_{L1}(t), I_{L1}(t), x_1(t), S_{D2}(t), \\ &\quad I_{D2}(t), S_{L2}(t), I_{L2}(t), x_2(t)) \in \partial X_0, \quad \forall t \geq 0.\end{aligned}\quad (34)$$

In order to prove Theorem 6, it suffices to show that ∂X_0 repels uniformly the solutions of X_0 .

Firstly, by the form of model (2), it is easy to see that both X and X_0 are positively invariant. Clearly, ∂X_0 is relatively closed in X . Furthermore, model (2) is point dissipative (see Lemma 3).

We now show that if $D_i > 0$, $i = 1, 2$, then

$$\begin{aligned}M_\partial &= \{(S_{D1}, 0, S_{L1}, 0, 0, S_{D2}, 0, S_{L2}, 0, 0) : \\ &\quad S_{Di} \geq 0, S_{Li} \geq 0, i = 1, 2\}.\end{aligned}\quad (35)$$

Assume

$$\begin{aligned}&(S_{D1}(0), I_{D1}(0), S_{L1}(0), I_{L1}(0), x_1(0), \\ &\quad S_{D2}(0), I_{D2}(0), S_{L2}(0), I_{L2}(0), x_2(0)) \in M_\partial.\end{aligned}\quad (36)$$

It suffices to show that

$$\begin{aligned}I_{D1}(t) &= I_{L1}(t) = x_1(t) = I_{D2}(t) \\ &= I_{L2}(t) = x_2(t) = 0, \quad \forall t \geq 0.\end{aligned}\quad (37)$$

Suppose not, then there exists a $t_0 \geq 0$ such that at least one of $I_{D1}(t_0)$, $I_{L1}(t_0)$, $x_1(t_0)$, $I_{D2}(t_0)$, $I_{L2}(t_0)$, or $x_2(t_0)$ is greater than zero. Here we only consider the case $I_{D1}(t_0) > 0$, $I_{D2}(t_0) = 0$, $S_{Di}(t_0) = 0$, $S_{Li}(t_0) = 0$, $I_{Li}(t_0) = 0$, and $x_i(t_0) = 0$, $i = 1, 2$. The other case can be deduced in the same way. Since

$$\begin{aligned}\dot{S}_{Di}(t_0) &= A_{1i} - \beta_{1i}S_{Di}(t_0)I_{Li}(t_0) - d_{1i}S_{Di}(t_0) + \sigma_iS_{Di}(t_0) \\ &\quad + D_iS_{Di}(t_0) - D_jS_{Dj}(t_0) \geq A_{1i} > 0, \\ \dot{S}_{Li}(t_0) &= A_{2i} - \beta_{2i}S_{Li}(t_0)x_i(t_0) - d_{2i}S_{Li}(t_0) = A_{2i} > 0, \\ \dot{x}_1(t_0) &= aI_{D1}(t_0) - d_1x_1(t_0) = aI_{D1}(t_0) > 0, \\ \dot{I}_{D1}(t) &\geq -(d_{11} + \sigma_1 + D_1)I_{D1}(t), \quad i = 1, 2, \quad i \neq j,\end{aligned}\quad (38)$$

it follows that there is an $\epsilon_0 > 0$ small enough such that $S_{Di}(t) > 0$, $S_{Li}(t) > 0$, $x_1(t) > 0$, and $I_{D1}(t) > 0$, $i = 1, 2$, for all $t_0 < t < t_0 + \epsilon_0$. If $I_{L1}(t_0 + (\epsilon_0/2)) > 0$, then we have

$$\dot{I}_{L1}(t) \geq -d_{21}I_{L1}(t). \quad (39)$$

This means that $I_{L1}(t) > 0$ for all $t \geq t_0 + (\epsilon_0/2)$. If $I_{L1}(t_0 + (\epsilon_0/2)) = 0$, it then follows from model (2) that

$$\dot{I}_{L1}\left(t_0 + \frac{\epsilon_0}{2}\right) = \beta_{21}S_{L1}\left(t_0 + \frac{\epsilon_0}{2}\right)x_1\left(t_0 + \frac{\epsilon_0}{2}\right) > 0. \quad (40)$$

It then follows that there exists an $\epsilon_1 < (\epsilon_0/2)$ such that

$$I_{L1}(t) > 0, \quad \forall t_0 + \frac{\epsilon_0}{2} < t < t_0 + \frac{\epsilon_0}{2} + \epsilon_1. \quad (41)$$

By the same way we can obtain that there exists an $\epsilon_2 < \epsilon_1$ such that

$$I_{D2}(t) > 0, \quad \forall t_0 + \frac{\epsilon_0}{2} < t < t_0 + \frac{\epsilon_0}{2} + \epsilon_2. \quad (42)$$

If $x_2(t_0 + (\epsilon_0/2) + (\epsilon_2/2)) > 0$, then we have

$$\dot{x}_2(t) \geq d_2x_2(t). \quad (43)$$

This means that $x_2(t) > 0$ for all $t > t_0 + (\epsilon_0/2) + (\epsilon_2/2)$; if $x_2(t_0 + (\epsilon_0/2) + (\epsilon_2/2)) = 0$, it then follows from model (2) that

$$\dot{x}_2\left(t_0 + \frac{\epsilon_0}{2} + \frac{\epsilon_2}{2}\right) = a_2I_{D2}\left(t_0 + \frac{\epsilon_0}{2} + \frac{\epsilon_2}{2}\right) > 0. \quad (44)$$

It then follows that there exists an $\epsilon_3 < (\epsilon_2/2)$ such that

$$x_2(t) > 0, \quad \forall t_0 + \frac{\epsilon_0}{2} + \frac{\epsilon_2}{2} < t < t_0 + \frac{\epsilon_0}{2} + \frac{\epsilon_2}{2} + \epsilon_3. \quad (45)$$

By the same way we can obtain that there exists an $\epsilon_4 < (\epsilon_3/2)$ such that

$$I_{L2}(t) > 0, \quad \forall t_0 + \frac{\epsilon_0}{2} + \frac{\epsilon_2}{2} + \frac{\epsilon_3}{2} < t < t_0 + \frac{\epsilon_0}{2} + \frac{\epsilon_2}{2} + \frac{\epsilon_3}{2} + \epsilon_4. \quad (46)$$

Thus for all $t \in (t_0 + (\epsilon_0/2) + (\epsilon_2/2) + (\epsilon_3/2), t_0 + (\epsilon_0/2) + (\epsilon_2/2) + (\epsilon_3/2) + \epsilon_4)$ we have $S_{Di}(t) > 0$, $I_{Di}(t) > 0$,

$$g(x) = \begin{pmatrix} g_1(x) \\ g_2(x) \\ g_3(x) \\ g_4(x) \end{pmatrix} = \begin{pmatrix} \frac{A_{11}(d_{12} + D_2 + \beta_{12}x) + A_{12}D_2}{(\beta_{11}x + d_{11})(\beta_{12}x + d_{12}) + D_1(\beta_{12}x + d_{12}) + D_2(\beta_{11} + d_{11})} \\ \frac{A_{12}(d_{11} + D_1 + \beta_{11}x) + A_{11}D_1}{(\beta_{11}x + d_{11})(\beta_{12}x + d_{12}) + D_1(\beta_{12}x + d_{12}) + D_2(\beta_{11} + d_{11})} \\ \frac{A_{12}}{d_{21} + \beta_{21}x} \\ \frac{A_{22}}{d_{22} + \beta_{22}x} \end{pmatrix}, \quad (47)$$

and we can see the fact that $\lim_{x \rightarrow 0} g(x) = (N_{D1}^0, N_{D2}^0, S_{L1}^0, S_{L2}^0)^T$. Hence we can choose $\delta > 0$ small enough such that

$$\begin{aligned} g_1(\delta) &= (A_{11}(d_{12} + D_2 + \beta_{12}\delta) + A_{12}D_2) \\ &\quad \times ((\beta_{11}\delta + d_{11})(\beta_{12}\delta + d_{12}) + D_1(\beta_{12}\delta + d_{12}) \\ &\quad + D_2(\beta_{11} + d_{11}))^{-1} > N_{D1}^0 - \theta, \\ g_2(\delta) &= (A_{12}(d_{11} + D_1 + \beta_{11}\delta) + A_{11}D_1) \\ &\quad \times ((\beta_{11}\delta + d_{11})(\beta_{12}\delta + d_{12}) + D_1(\beta_{12}\delta + d_{12}) \\ &\quad + D_2(\beta_{11} + d_{11}))^{-1} > N_{D2}^0 - \theta, \\ g_3(\delta) &= \frac{A_{12}}{d_{21} + \beta_{21}\delta} > S_{L1}^0 - \theta, \\ g_4(\delta) &= \frac{A_{22}}{d_{22} + \beta_{22}\delta} > S_{L2}^0 - \theta. \end{aligned} \quad (48)$$

Suppose $(S_{D1}(t), I_{D1}(t), S_{L1}(t), I_{L1}(t), x_1(t), S_{D2}(t), I_{D2}(t), S_{L2}(t), I_{L2}(t), x_2(t))$ is a solution of model (2) with $(S_{D1}(0), I_{D1}(0), S_{L1}(0), I_{L1}(0), x_1(0), S_{D2}(0), I_{D2}(0), S_{L2}(0), I_{L2}(0), x_2(0)) \in X_0$. We now claim that

$$\limsup_{t \rightarrow \infty} \max \{I_{D1}(t), I_{L1}(t), x_1(t), I_{D2}(t), I_{L2}(t), x_2(t)\} > \delta. \quad (49)$$

$S_{Li}(t) > 0$, $I_{Li}(t) > 0$, and $x_i(t) > 0$, $i = 1, 2$. This contradicts the assumption that $(S_{D1}(0), I_{D1}(0), S_{L1}(0), I_{L1}(0), x_1(0), S_{D2}(0), I_{D2}(0), S_{L2}(0), I_{L2}(0), x_2(0)) \in M_\theta$. This proves (35).

From (24) we can see that if $R_0 > 1$, then $s(J) > 0$. Hence, there is a small enough number $\theta > 0$ such that $s(J_\theta) > 0$, where $J_\theta = J - \theta J_1$ and J_1 is given by (26). Let

Suppose, for the sake of contradiction, that there exists a $T > 0$ such that $I_{Di} \leq \delta$, $I_{Li} \leq \delta$, and $x_i(t) \leq \delta$, $i = 1, 2$, for all $t \geq T$. Then by model (2) we have

$$\begin{aligned} \dot{S}_{D1}(t) &\geq A_{11} - (\beta_{11}\delta + d_{11})S_{D1} - D_1S_{D1} + D_2S_{D2}, \\ \dot{S}_{D2}(t) &\geq A_{12} - (\beta_{12}\delta + d_{12})S_{D2} - D_2S_{D2} + D_1S_{D1}, \\ \dot{S}_{L1}(t) &\geq A_{21} - (\beta_{21}\delta + d_{21})S_{L1}, \\ \dot{S}_{L2}(t) &\geq A_{22} - (\beta_{22}\delta + d_{22})S_{L2} \end{aligned} \quad (50)$$

for $t \geq T$. Consider the following auxiliary system:

$$\begin{aligned} \dot{\tilde{S}}_{D1}(t) &= A_{11} - (\beta_{11}\delta + d_{11})\tilde{S}_{D1} - D_1\tilde{S}_{D1} + D_2\tilde{S}_{D2}, \\ \dot{\tilde{S}}_{D2}(t) &= A_{12} - (\beta_{12}\delta + d_{12})\tilde{S}_{D2} - D_2\tilde{S}_{D2} + D_1\tilde{S}_{D1}, \\ \dot{\tilde{S}}_{L1}(t) &= A_{21} - (\beta_{21}\delta + d_{21})\tilde{S}_{L1}, \\ \dot{\tilde{S}}_{L2}(t) &= A_{22} - (\beta_{22}\delta + d_{22})\tilde{S}_{L2}. \end{aligned} \quad (51)$$

As in our analysis in Lemma 2, system (51) has a unique positive equilibrium $(g_1(\delta), g_2(\delta), g_3(\delta), g_4(\delta))$ which is globally stable. By (48) and comparison principle, there is a $\tau > 0$ such that $S_{D1}(t) \geq N_{D1}^0 - \theta$, $S_{D2}(t) \geq N_{D2}^0 - \theta$, $S_{L1}(t) \geq S_{L1}^0 - \theta$, and $S_{L2}(t) \geq S_{L2}^0 - \theta$ for all $t \geq T + \tau$. Consequently, for $t \geq T + \tau$, we have

$$\begin{aligned} \dot{I}_{D1}(t) &\geq \beta_{11}(N_{D1}^0 - \theta)I_{L1} - (d_{11} + \sigma_1 + D_1)I_{D1} + D_2I_{D2}, \\ \dot{I}_{L1}(t) &\geq \beta_{21}(S_{L1}^0 - \theta)x_1 - d_{21}I_{L1}, \end{aligned}$$

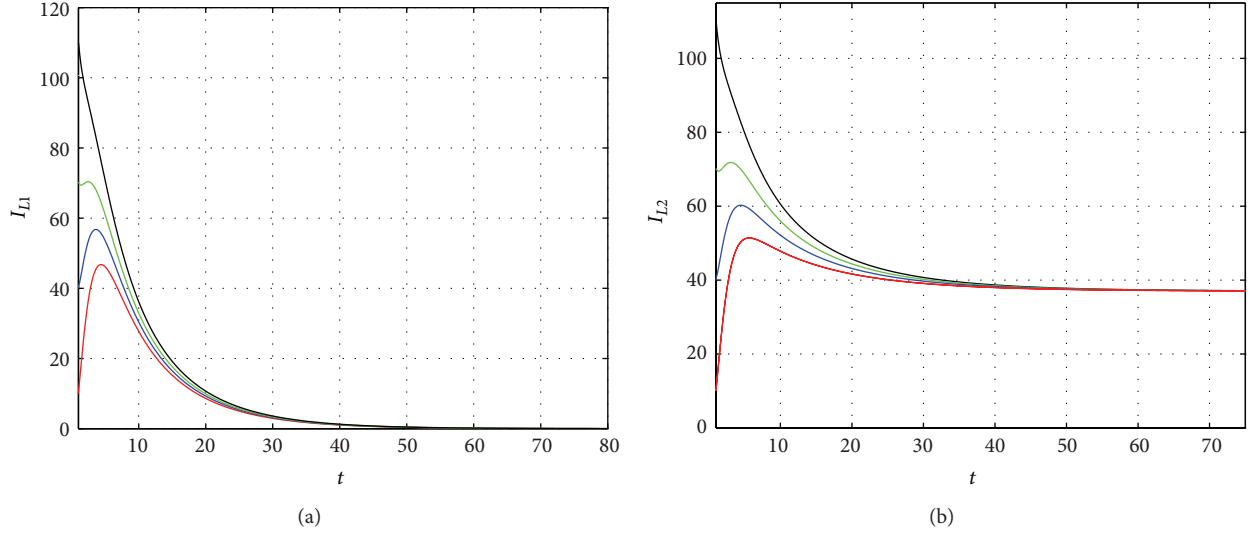


FIGURE 2: Time series of echinococcosis disease I_{Li} , $i = 1, 2$, when the two patches are isolated for the parameters given in Example 8.

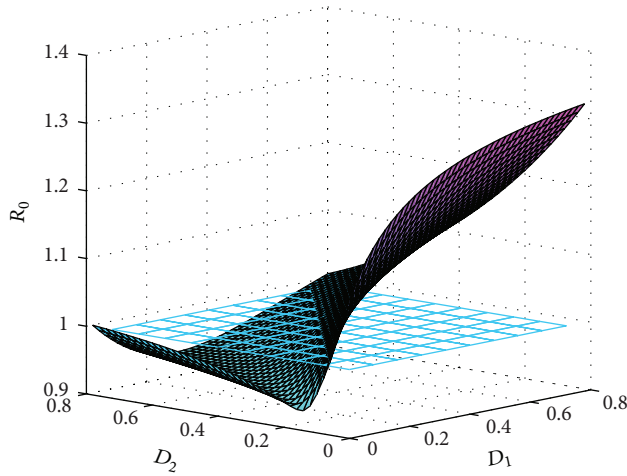


FIGURE 3: Surface plot of R_0 as a function of D_1 and D_2 for the parameters given in Example 8.

$$\begin{aligned}
 \dot{x}_1(t) &\geq a_1 I_{D1} - d_1 x_1, \\
 \dot{I}_{D2}(t) &\geq \beta_{12} (N_{D2}^0 - \theta) I_{L2} - (d_{12} + \sigma_2 + D_2) I_{D2} + D_1 I_{D1}, \\
 \dot{I}_{L2}(t) &\geq \beta_{22} (S_{L2}^0 - \theta) x_2 - d_{22} I_{L2}, \\
 \dot{x}_2(t) &\geq a_2 I_{D2} - d_2 x_2.
 \end{aligned} \tag{52}$$

Consider an auxiliary system

$$\begin{aligned}
 \dot{\tilde{I}}_{D1}(t) &= \beta_{11} (N_{D1}^0 - \theta) \tilde{I}_{L1} - (d_{11} + \sigma_1 + D_1) \tilde{I}_{D1} + D_2 \tilde{I}_{D2}, \\
 \dot{\tilde{I}}_{L1}(t) &= \beta_{21} (S_{L1}^0 - \theta) \tilde{x}_1 - d_{21} \tilde{I}_{L1},
 \end{aligned}$$

$$\dot{\tilde{x}}_1(t) = a_1 \tilde{I}_{D1} - d_1 \tilde{x}_1,$$

$$\dot{\tilde{I}}_{D2}(t) = \beta_{12} (N_{D2}^0 - \theta) \tilde{I}_{L2} - (d_{12} + \sigma_2 + D_2) \tilde{I}_{D2} + D_1 \tilde{I}_{D1},$$

$$\dot{\tilde{I}}_{L2}(t) = \beta_{22} (S_{L2}^0 - \theta) \tilde{x}_2 - d_{22} \tilde{I}_{L2},$$

$$\dot{\tilde{x}}_2(t) = a_2 \tilde{I}_{D2} - d_2 \tilde{x}_2.$$

(53)

The coefficient matrix of the right hand of (53) is J_θ . Since matrix J_θ has a positive eigenvalues $s(J_\theta)$ with a positive eigenvector, it follows from a comparison principle that $I_{Di}(t) \rightarrow \infty$, $I_{Li}(t) \rightarrow \infty$, and $x_i(t) \rightarrow \infty$ as $t \rightarrow \infty$, $i = 1, 2$, which leads to a contradiction. This proves (49). Hence $W^s(E_0) \cap X_0 = \emptyset$. Clearly, every forward orbit in M_∂ converges to E_0 . By Theorem 4.6 in [32] we are able to conclude that model (2) is uniformly persistent with respect to $(X_0, \partial X_0)$. Thus, by a well-known result in persistence theory in [33] we know that model (2) has at least one positive equilibrium $E^*(S_{D1}^*, I_{D1}^*, S_{L1}^*, I_{L1}^*, x_1^*, S_{D2}^*, I_{D2}^*, S_{L2}^*, I_{L2}^*, x_2^*)$. This completes the proof of Theorem 6. \square

6. Global Stability of E^*

We further have the following result on the stability of the endemic equilibrium.

Theorem 7. *If $R_0 > 1$, then model (2) admits a unique equilibrium $E^*(S_{D1}^*, I_{D1}^*, S_{L1}^*, I_{L1}^*, x_1^*, S_{D2}^*, I_{D2}^*, S_{L2}^*, I_{L2}^*, x_2^*)$, which is globally asymptotically stable.*

Proof. In Lemma 3, we have proved that $S_{Di}(t) + I_{Di}(t) \rightarrow N_{Di}^0$ and $S_{Li}(t) + I_{Li}(t) \rightarrow S_{Li}^0$ as $t \rightarrow \infty$, $i = 1, 2$. Therefore, in model (2) we can represent S_{Di} and S_{Li} by $N_{Di}^0 - I_{Di}(t)$ and

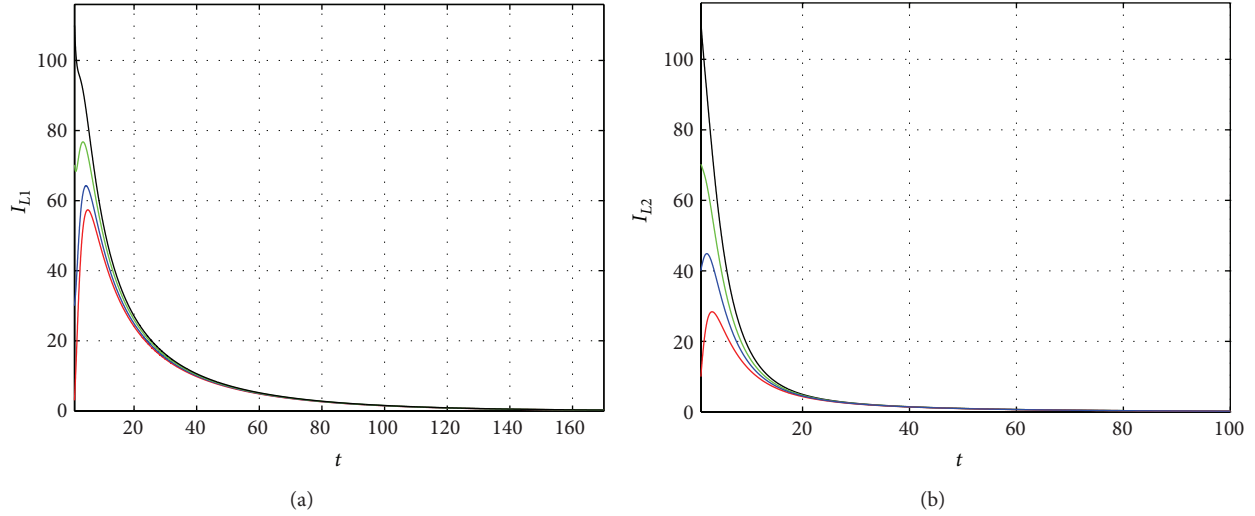


FIGURE 4: Time series of echinococcosis disease I_{Li} , $i = 1, 2$, when the two patches are connected with $D_1 = 0.8$, $D_2 = 0.2$.

$S_{Li}^0 - S_{Li}(t)$, $i = 1, 2$, respectively, and the model (2) will degenerate into the following system with six equations:

$$\begin{aligned}
 \dot{I}_{D1}(t) &= -(d_{11} + \sigma_1 + D_1) I_{D1} + \beta_{11} (N_{D1}^0 - I_{D1}) I_{L1} \\
 &\quad + D_2 I_{D2}, \\
 \dot{I}_{L1}(t) &= -d_{21} I_{L1} + \beta_{21} (S_{L1}^0 - I_{L1}) x_1, \\
 \dot{x}_1(t) &= a_1 I_{D1} - d_1 x_1, \\
 \dot{I}_{D2}(t) &= D_1 I_{D1} - (d_{12} + \sigma_2 + D_2) I_{D2} \\
 \dot{I}_{L2}(t) &= \beta_{12} (N_{D2}^0 - I_{D2}) I_{L2}, \\
 \dot{I}_{L2}(t) &= -d_{22} I_{L2} + \beta_{22} (S_{L2}^0 - I_{L2}) x_2, \\
 \dot{x}_2(t) &= a_2 I_{D2} - d_2 x_2.
 \end{aligned} \tag{54}$$

By Lemma 3, the dynamics of system (54) can be focused on the following region:

$$\begin{aligned}
 \Omega &= \left\{ (I_{D1}, I_{L1}, x_1, I_{D2}, I_{L2}, x_2) : 0 \leq I_{Di} \leq N_{Di}^0, \right. \\
 &\quad \left. 0 \leq I_{Li} \leq S_{Li}^0, 0 \leq x_i \leq \frac{a_i}{d_i} N_{Di}^0, i = 1, 2 \right\}.
 \end{aligned} \tag{55}$$

We will use the theory of cooperate system to prove the global stability of system (54). Therefore, we only verify the assumption in Corollary 3.2 [34] for system (54). Let

$$f(u) = \begin{pmatrix} f_1(u_1, u_2, u_3, u_4, u_5, u_6) \\ f_2(u_1, u_2, u_3, u_4, u_5, u_6) \\ f_3(u_1, u_2, u_3, u_4, u_5, u_6) \\ f_4(u_1, u_2, u_3, u_4, u_5, u_6) \\ f_5(u_1, u_2, u_3, u_4, u_5, u_6) \\ f_6(u_1, u_2, u_3, u_4, u_5, u_6) \end{pmatrix}$$

$$= \begin{pmatrix} -(d_{11} + \sigma_1 + D_1) u_1 + \beta_{11} (N_{D1}^0 - u_1) u_2 + D_2 u_4 \\ -d_{21} u_2 + \beta_{21} (S_{L1}^0 - u_2) u_3 \\ a_1 u_1 - d_1 u_3 \\ D_1 u_1 - (d_{12} + \sigma_2 + D_2) u_4 + \beta_{12} (N_{D2}^0 - u_4) u_5 \\ -d_{22} u_5 + \beta_{22} (S_{L2}^0 - u_5) u_6 \\ a_2 u_4 - d_2 u_6 \end{pmatrix}, \tag{56}$$

and then $f : \mathbb{R}_+^6 \rightarrow \mathbb{R}_+^6$ is a continuously differentiable map. Clearly $f(0) = 0$ and $f_i(u) \geq 0$ for all $u \in \Omega$ with $u_i = 0$, $i = 1, 2, \dots, 6$. Since $\partial f_i / \partial u_j \geq 0$ ($i \neq j$) for $u \in \Omega$, we have that f is cooperative on Ω . For every $p \in (0, 1)$ and $u \in \Omega$, we have

$$\begin{aligned}
 &f_1(pu_1, pu_2, pu_3, pu_4, pu_5, pu_6) \\
 &= -(d_{11} + \sigma_1 + D_1) pu_1 + \beta_{11} (N_{D1}^0 - pu_1) pu_2 + D_2 pu_4 \\
 &\geq -(d_{11} + \sigma_1 + D_1) pu_1 + \beta_{11} (N_{D1}^0 - u_1) pu_2 + D_2 pu_4 \\
 &= pf_1(u_1, u_2, u_3, u_4, u_5, u_6).
 \end{aligned} \tag{57}$$

Using the same argument, we can show that f is strictly sublinear on Ω . By computing $Df(u)$, we have

$$\left(\frac{\partial f_i}{\partial u_j} \right)_{1 \leq i, j \leq 6} = \begin{pmatrix} f_{11}(u) & f_{12}(u) \\ f_{21}(u) & f_{22}(u) \end{pmatrix}, \tag{58}$$

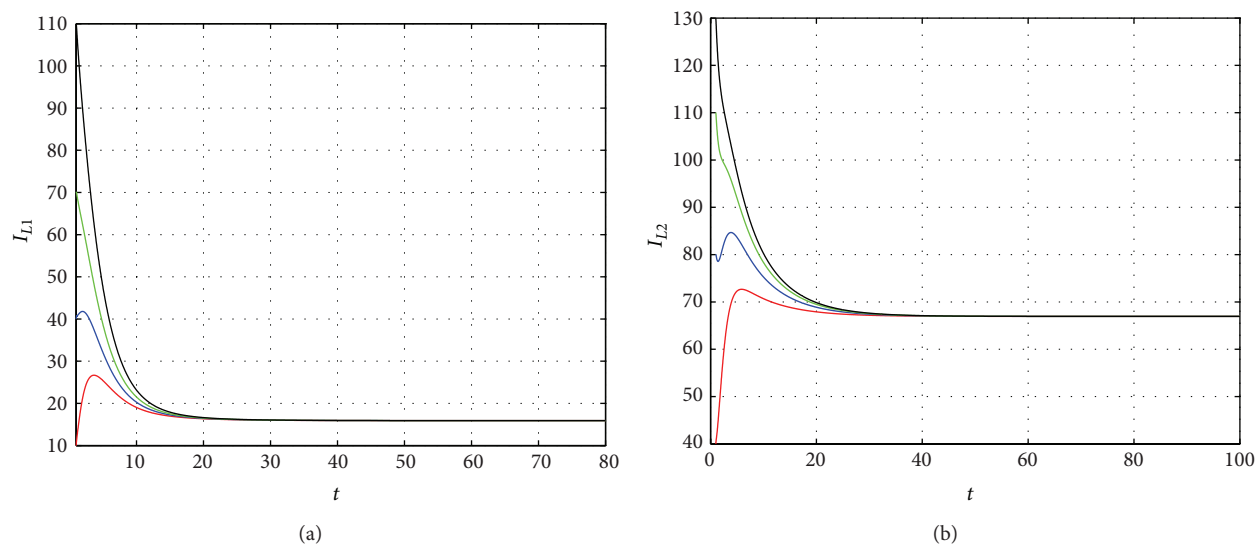


FIGURE 5: Time series of echinococcosis disease I_{Li} , $i = 1, 2$, when the two patches are connected with $D_1 = 0.2$, $D_2 = 0.8$.

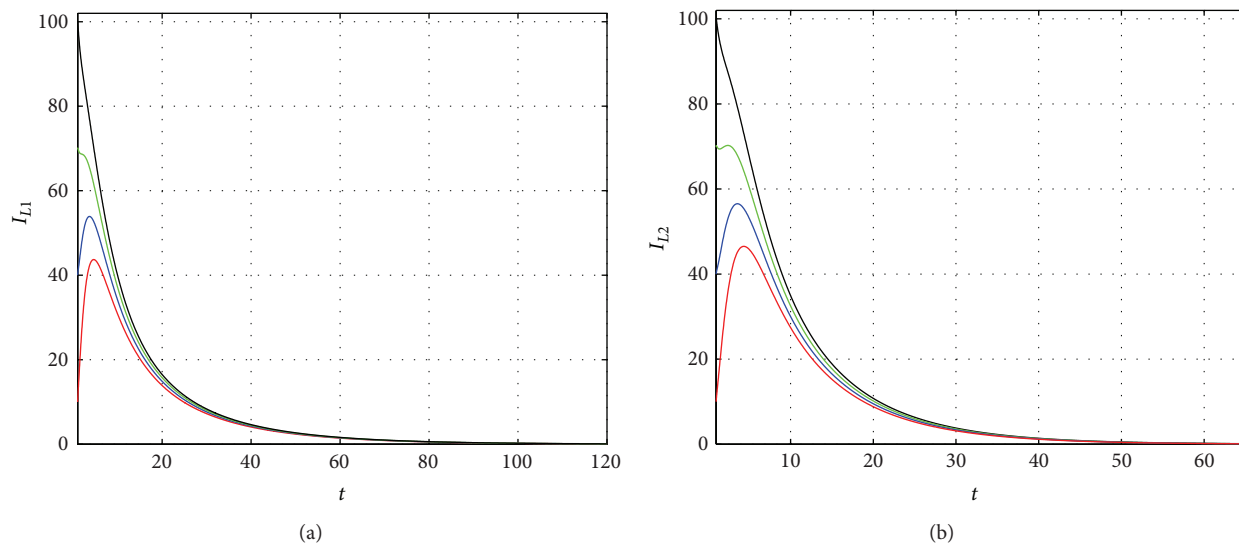


FIGURE 6: Time series of echinococcosis disease I_{Li} , $i = 1, 2$, when the two patches are isolated for the parameters given in Example 9.

where

$$\begin{aligned}
 f_{11}(u) &= \begin{pmatrix} -(d_{11} + \sigma_1 + D_1) - \beta_{11}u_2 & \beta_{11}(N_{D1}^0 - u_1) & 0 \\ 0 & -d_{21} - \beta_{21}u_3 & \beta_{21}(S_{L1}^0 - u_3) \\ a_1 & 0 & -d_1 \end{pmatrix}, \\
 f_{12}(u) &= \begin{pmatrix} D_2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad f_{21}(u) = \begin{pmatrix} D_1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \\
 f_{22}(u) &= \begin{pmatrix} -(d_{12} + \sigma_2 + D_2) - \beta_{12}u_5 & \beta_{12}(N_{D2}^0 - u_4) & 0 \\ 0 & -d_{22} - \beta_{22}u_6 & \beta_{22}(S_{L2}^0 - u_5) \\ a_2 & 0 & -d_2 \end{pmatrix}.
 \end{aligned} \tag{59}$$

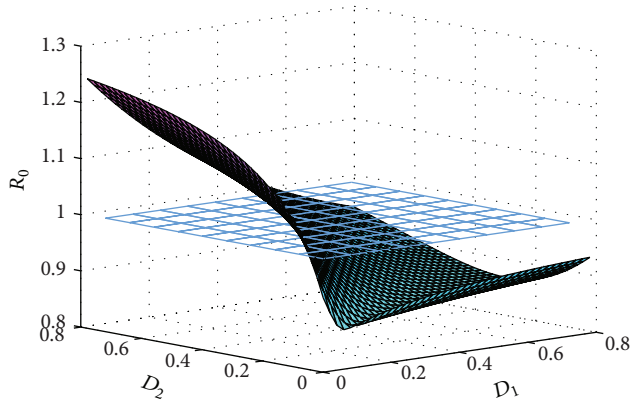


FIGURE 7: Surface plot of R_0 as a function of D_1 and D_2 for the parameters given in Example 9.

Clearly, $Df(u)$ is irreducible for $u \in \Omega$. From (24) we can see that if $R_0 > 1$, then $s(J) > 0$. Since $Df(0) = J$, we have $s(Df(0)) = s(J) > 0$. By Corollary 3.2 in [34], one can conclude that system (54) admits a unique positive equilibrium $(I_{D1}^*, I_{L1}^*, x_1^*, I_{D2}^*, I_{L2}^*, x_2^*)$, which is globally asymptotically stable. According to the theory of asymptotic autonomous systems [31], we further obtain that endemic equilibrium $E^*(S_{D1}^*, I_{D1}^*, S_{L1}^*, I_{L1}^*, x_1^*, S_{D2}^*, I_{D2}^*, S_{L2}^*, I_{L2}^*, x_2^*)$ is globally attractive for model (2). \square

7. Simulations

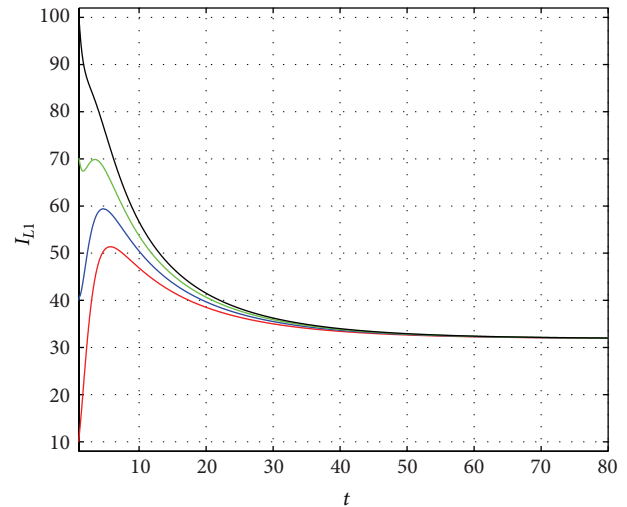
To complement the mathematical analysis carried out in the previous section, we now investigate some of the numerical properties of the two-patch model (2).

Example 8. Take parameters in model (2) as follows:

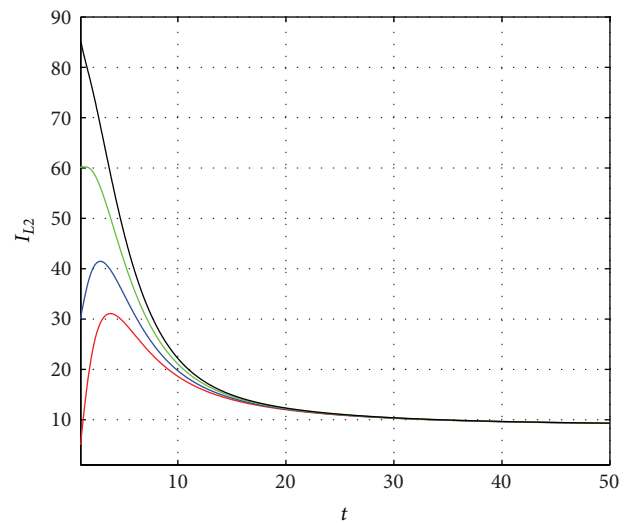
$A_{11} = 15$, $\beta_{11} = 0.00065$, $d_{11} = 0.3$, $\sigma_1 = 0.2$, $A_{21} = 80$, $\beta_{21} = 0.004$, $d_{21} = 0.4$, $a_1 = 150$, $d_1 = 33$, $A_{12} = 15$, $\beta_{12} = 0.0015$, $d_{12} = 0.3$, $\sigma_2 = 0.2$, $A_{22} = 80$, $\beta_{22} = 0.004$, $d_{22} = 0.4$, $a_2 = 150$, and $d_2 = 33$. If the two patches are isolated, by simple calculations we have $R_{01} = 0.8392$, $R_{02} = 1.1089$.

From Lemma 1 we have that the disease will die out in the first patch and will be endemic in the second patch (see Figure 2). From Figure 3 we can easily see that R_0 will be larger than 1 under the condition of a larger D_1 and a smaller D_2 . This means that the larger diffusion of dogs from the lower epidemic areas to the higher prevalence areas can intensify the spread of echinococcosis (see Figure 4). However, when D_1 is small and D_2 is large, R_0 will be smaller than 1. This indicates that the larger diffusion of dogs from the higher prevalence areas to the lower epidemic areas can reduce the spread and is beneficial for disease control (see Figure 5).

Example 9. We use the parameters given in Example 8 except that $A_{11} = 10$, $\beta_{11} = 0.0015$, $A_{21} = 70$, $A_{12} = 20$, and $\beta_{12} = 0.0005$. If the two patches are isolated, by simple calculations we have $R_{01} = 0.9266$, $R_{02} = 0.8463$.



(a)



(b)

FIGURE 8: Time series of echinococcosis disease I_{Li} , $i = 1, 2$, when the two patches are connected with $D_1 = 0.2$, $D_2 = 0.6$.

It follows from Lemma 1 that the disease will die out in both two patches when they are isolated (see Figure 6). However, from Figure 7 we can see that R_0 is not always less than 1. This suggests that dogs diffusion can cause the spread of echinococcosis in two patches (see Figure 8).

8. Discussion

In this paper, in order to model the transmission dynamics of echinococcosis spread between two patches due to dogs migration a patch model for echinococcosis is proposed. We define the basic reproduction number R_0 . The mathematical results show that the dynamics of the model is completely determined by R_0 . If $R_0 < 1$, the disease-free equilibrium is globally asymptotically stable. When $R_0 > 1$, the model is permanence and endemic equilibrium is globally asymptotically stable. According to the simulation

we have that the larger diffusion of dogs from a low epidemic area to the high prevalence area can intensify the disease spread. However, the larger diffusion of dogs from the high prevalence area to a low epidemic area can reduce the disease spread and is beneficial to disease control. Additionally, the model presented in this paper can be extended to describe the dynamical transmission of echinococcosis with dogs migration among more than two patches. We leave these in our future work.

Conflict of Interests

The authors declare that they have no financial and personal relationships with other people or organizations that can inappropriately influence their work and there are no professional or other personal interests of any nature or kind in any product, service, and/or company that could be construed as influencing the position presented in, or the review of, this paper.

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