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Research Article

Bifurcations of Tumor-Immune Competition Systems with Delay

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A tumor-immune competition model with delay is considered, which consists of two-dimensional nonlinear differential equation. The conditions for the linear stability of the equilibria are obtained by analyzing the distribution of eigenvalues. General formulas for the direction, period, and stability of the bifurcated periodic solutions are given for codimension one and codimension two bifurcations, including Hopf bifurcation, steady-state bifurcation, and B-T bifurcation. Numerical examples and simulations are given to illustrate the bifurcations analysis and obtained results.

1. Introduction

In this century, cancer remains one of the most dangerous killers of humankind; every year millions of people suffer from cancer and die from this disease throughout the world; see Boyle et al. [1]. Recently, there has been much interest in mathematical modeling of immune response with the intruder (see, e.g., Liu et al. [2, 3], Yafia [4], d'Onofrio et al. [5, 6], and the references cited therein). In fact, mathematical models are feasible to propose simple models which are capable of displaying some of the essential immunological phenomena. The delayed models of tumor and immune response interactions have been studied extensively; we refer to Bi and Ruan [7], Yafia [8], Mayer et al. [9], Yafia [10], and the references cited therein, which have shown that various bifurcations can occur in such models. It is interesting to consider the nonlinear dynamics of the delayed tumorimmune model.

In 1994, Kuznetsov et al. [11] took into account the penetration of tumor cells (TCs) by effector cells (ECs) and proposed a model describing the response of ECs to the growth of TCs. They assumed that interactions between ECs and TCs *in vitro* can be described by the kinetic scheme shown in Figure 1, where E, T, C, T^* , and E^* are the local concentrations of ECs, TCs, EC-TC complexes, inactivated

ECs, and lethally hit TCs, respectively. Then the Kuznetsov and Taylor model is as follows:

$$\frac{dE}{dt} = c + F(C, T) - d_1 E - k_1 E T + (k_{-1} + k_3) C,$$

$$\frac{dT}{dt} = aT (1 - bT_{tot}) - k_1 E T + (k_{-1} + k_2) C,$$

$$\frac{dC}{dt} = k_1 E T - (k_{-1} + k_2 + k_3) C,$$

$$\frac{dT^*}{dt} = k_3 C - d_2 T^*,$$

$$\frac{dE^*}{dt} = k_2 C - d_3 E^*,$$
(1)

where c is the normal rate of the flow of adult ECs into the tumor site, F(C, T) describes the accumulation of effector cells in the tumor cells localization due to the presence of the tumor, d_1, d_2 , and d_3 are the coefficients of the processes of destruction and migration for E, EC, and TC, respectively, a is the coefficient of the maximal growth of tumor, and b is the environment capacity. Kuznetsov et al. [11] claimed that experimental observations motivate the approximation $dC/dt \approx 0$; therefore, it is reasonable to assume that $C \approx KET$

$$E + T \xrightarrow{k_1} C \xrightarrow{k_2} E^* + T$$

$$E + T \xrightarrow{k_{-1}} C \xrightarrow{k_2} T^* + E$$

FIGURE 1: Kinetic scheme describing interactions between ECs and TCs.

with $K = k_1/(k_1 + k_2 + k_3)$. Kuznetsov et al. [11] also suggested that the function F is in the Michaelis-Menten form F(C,T) = F(E,T) = (fC/(g+T))(f,g>0). In 2003, Gałach [12] suggested that the function F should be in a Lotka-Volterra form $F(C,T) = F(E,T) = n_1ET$; then the model (1) can be reduced to

$$\frac{\mathrm{d}x}{\mathrm{d}t} = c + n_1 xy - m_1 xy - d_1 x,$$

$$\frac{\mathrm{d}y}{\mathrm{d}t} = ay (1 - by) - m_2 xy,$$
(2)

where x denotes the dimensionless density of ECs, y stands for the dimensionless density of the population of TCs, $m_1 = kk_2$, $m_2 = kk_3$, and all coefficients are positive. Set $x = x_0x'$, $y = y_0y'$, $t = (1/m_2x_0)t'$, $x_0 > 0$, $y_0 > 0$. Replace x with x' and y with y'. Then (2) can be written as

$$\frac{\mathrm{d}x}{\mathrm{d}t} = \sigma + nxy - mxy - \delta x,$$

$$\frac{\mathrm{d}y}{\mathrm{d}t} = \alpha y (1 - \beta y) - xy,$$
(3)

where $\sigma = s/m_2 x_0^2$, $n = n_1 y_0/m_2 x_0$, $m = m_1 y_0/m_2 x_0$, $\delta = d_1/m_2 x_0$, $\alpha = a/m_2 x_0$, and $\beta = b y_0$.

Mayer et al. [9] and Asachenkov et al. [13] pointed out that the delays should be taken into account to describe the times necessary for molecule production, proliferation, differentiation of cells, transport, and so forth. In fact, the immune system needs time to develop a suitable response after the invasion of tumor cells; the binding of EC and TC also needs time. Therefore, we introduce time delays into the model of immune response. Integrating models [9–11], we will consider the model as follows:

$$\frac{\mathrm{d}x}{\mathrm{d}t} = \sigma + \zeta x (t - \tau_1) y (t - \tau_1) - \delta x,$$

$$\frac{\mathrm{d}y}{\mathrm{d}t} = \alpha y (1 - \beta_2 y) - x (t - \tau_2) y (t - \tau_2),$$
(4)

where $\zeta=n-m$; if the stimulation coefficient of the immune system exceeds the neutralization coefficient of ECs in the process of the formation of EC-TC complexes, then $\zeta>0$. Yafia [4] studied the linear stability of the equilibria and the existence of Hopf bifurcation for model (4) with $\tau_1=\tau_2=0$. Yafia [10] and Gałach [12] obtained similar results as those of Yafia [4] for (4) with $\tau_2=0$. Recently, Bi and Xiao [14] give conditions for the properties of Hopf bifurcated periodic solution and existence of the global Hopf bifurcation for (4) with $\tau_2=0$.

In this paper, we will consider the dynamical behaviors of model (4) with $\tau_1 = \tau_2 = \tau$. The rest of this paper

is organized as follows. In Section 2, the linear analysis of the model is carried out and local stability of the equilibria and the conditions of Hopf bifurcation are given. Section 3 is devoted to the analysis of Hopf, steady-state bifurcations, and B-T bifurcation. Numerical results and simulations are carried out to illustrate the main results. A brief discussion and more numerical simulations are given in Section 4.

2. Local Analysis

In this section, we will study the local stability of the equilibria and the Hopf bifurcations of system

$$\frac{\mathrm{d}x}{\mathrm{d}t} = \sigma + \zeta x (t - \tau) y (t - \tau) - \delta x,$$

$$\frac{\mathrm{d}y}{\mathrm{d}t} = \alpha y (1 - \beta_2 y) - x (t - \tau) y (t - \tau).$$
(5)

It is easy to obtain that system (5) have three equilibria $P_0(\sigma/\delta, 0)$, $P_1(x_1, y_1)$, and $P_2(x_2, y_2)$, where

$$x_{1} = \frac{-\alpha (\beta \delta - \zeta) - \sqrt{\Delta}}{2\zeta},$$

$$y_{1} = \frac{\alpha (\beta \delta + \zeta) + \sqrt{\Delta}}{2\alpha \beta \zeta},$$

$$x_{2} = \frac{-\alpha (\beta \delta - \zeta) + \sqrt{\Delta}}{2\zeta},$$

$$y_{2} = \frac{\alpha (\beta \delta + \zeta) - \sqrt{\Delta}}{2\alpha \beta \zeta},$$
(6)

 $\Delta = \alpha^2 (\beta \delta - \zeta)^2 + 4\alpha \beta \zeta \sigma > 0$. It is easy to see that $x_1 < 0$. Because the number of tumor cells or effect cells is positive, we only consider the dynamical behaviors of the equilibria P_0 (tumor-free point) and P_2 in the rest of the paper.

Let $z_1(t) = x(t) - x^*$, $z_2(t) = y(t) - y^*$. System (5) can be written as

$$z'_{1}(t) = \alpha_{1}z_{1}(t) + \alpha_{2}z_{1}(t-\tau) + \alpha_{3}z_{2}(t-\tau) + \zeta z_{1}(t-\tau)z_{2}(t-\tau),$$

$$z'_{2}(t) = \beta_{1}z_{1}(t-\tau) + \beta_{2}z_{2}(t) + \beta_{3}z_{2}(t-\tau) - \alpha\beta z_{2}^{2}(t) - z_{1}(t-\tau)z_{2}(t-\tau),$$
(7)

where $\alpha_1 = -\delta < 0$, $\alpha_2 = \zeta y^* \ge 0$, $\alpha_3 = \zeta x^* > 0$, $\beta_1 = -y^* \le 0$, $\beta_2 = \alpha - 2\alpha\beta y^*$, $\beta_3 = -x^* < 0$ and (x^*, y^*) is the coordinate of the equilibrium.

It is easy to see that the linear system of system (7) is

$$z'_{1}(t) = \alpha_{1}z_{1}(t) + \alpha_{2}z_{1}(t-\tau) + \alpha_{3}z_{2}(t-\tau),$$

$$z'_{2}(t) = \beta_{1}z_{1}(t-\tau) + \beta_{2}z_{2}(t) + \beta_{3}z_{2}(t-\tau),$$
(8)

where α_1 , α_2 , α_3 , β_1 , β_2 , and β_3 are the same as those in (7).

2.1. Tumor-Free Point. The characteristic equation of system (8) at the tumor-free equilibrium P_0 is

$$\Delta(\lambda) = (\lambda + \delta) \left(\lambda - \alpha + \frac{\sigma}{\delta} e^{-\lambda \tau}\right) = 0.$$
 (9)

Then we have the following results.

Lemma 1. (*I*) If $\alpha = \sigma/\delta$, then

- (1) Equation (9) has a simple zero root, and all other roots have negative real parts as $0 \le \tau < \delta/\sigma$;
- (2) Equation (9) has a double zero root, and all other roots have negative real parts as $\tau = \delta/\sigma$;
- (3) Equation (9) has at least one root with positive real parts as $\tau > \delta/\sigma$.
- (II) If $\alpha < \sigma/\delta$, then
- (1) all roots of (9) have negative real parts as $0 \le \tau < \tau_0$;
- (2) Equation (9) has a pair of conjugate purely imaginary roots $\pm i\omega_+$, and all other roots have negative real parts as $\tau = \tau_0$;
- (3) Equation (9) has at least one root with positive real parts as $\tau > \tau_0$.
- (III) Equation (9) has a negative root $-\delta$, and all other roots have positive real parts as $\alpha > \sigma/\delta$.

Proof. $\lambda = 0$ is a root of (9) if and only if $\alpha = \sigma/\delta$. If $\tau = 0$, (9) has two roots $\lambda_1 = -\delta$ and $\lambda_2 = \alpha - \sigma/\delta$. Then there are three cases: (1) $\lambda_2 = 0$ as $\alpha = \sigma/\delta$; (2) $\lambda_2 < 0$ as $\alpha < \sigma/\delta$; (3) $\lambda_2 > 0$ as $\alpha > \sigma/\delta$.

We will consider the case $\tau > 0$ as follows. If $\alpha = \sigma/\delta$, $\tau = \delta/\sigma$, then

$$\Delta'(\lambda) = 2\lambda - \alpha + \frac{\sigma}{\delta}e^{-\lambda\tau} - \tau\lambda\frac{\sigma}{\delta}e^{-\lambda\tau} + \delta - \sigma\tau e^{-\lambda\tau}; \quad (10)$$

hence, $\Delta'(\lambda)|_{\lambda=0} = 0$, and $\Delta''(\lambda)|_{\lambda=0} = \delta^2/\sigma > 0$. Thus $\lambda = 0$ is the double zero root of (9).

If (9) has purely imaginary roots, then the roots must be the solution of

$$\Delta_0(\lambda) = \lambda - \alpha + \frac{\sigma}{\delta} e^{-\lambda \tau} = 0.$$
 (11)

Assume that $\lambda = i\omega(\omega > 0)$ is the root of (11); that is,

$$-\alpha + \frac{\sigma}{\delta}\cos\omega\tau = 0,$$

$$\omega - \frac{\sigma}{\delta}\sin\omega\tau = 0;$$
(12)

that is $\omega^2 = \sigma^2/\delta^2 - \alpha^2$. Hence (11) has a positive root $\omega_+ = \sqrt{\sigma^2/\delta^2 - \alpha^2}$ if and only if $\alpha < \sigma/\delta$, and the corresponding critical values are

$$\tau_k = \frac{1}{\omega_{\perp}} \left\{ \operatorname{arc} \cos \frac{\alpha \delta}{\sigma} + 2k\pi \right\}, \quad k = 0, 1, 2, \dots$$
 (13)

Using Rouché theorem, we know that conclusions (II)(1), (II)(2), and (III) hold.

If $0<\tau<\delta/\sigma, \alpha=\sigma/\delta$, we can obtain $\Delta_0'(\lambda)|_{\lambda=0}=1-(\sigma/\delta)\tau>0, \ \Delta_0(0)=0.$ Noting the continuous of the function $\Delta_0(\lambda)$, we know that there is at least a $\lambda<0$ such that $\Delta_0(\lambda)<0$. On the other hand, it is easy to see that $\lim_{\lambda\to-\infty}\Delta_0(\lambda)=+\infty$; then there exists $\lambda<0$ such that $\Delta_0(\lambda)=0$.

Differentiating both sides of (11) with respect to τ , we have

$$\frac{\mathrm{d}\lambda}{\mathrm{d}\tau} = \frac{\lambda \left(\sigma/\delta\right) e^{-\lambda\tau}}{1 - \left(\sigma/\delta\right) \tau e^{-\lambda\tau}}.$$
(14)

If $\tau \neq \delta/\sigma$, then

$$\frac{\mathrm{d}\lambda}{\mathrm{d}\tau}\bigg|_{\lambda=0} = \frac{\lambda (\sigma/\delta) e^{-\lambda\tau}}{1 - (\sigma/\delta) \tau e^{-\lambda\tau}}\bigg|_{\lambda=0} = 0.$$
 (15)

Using Rouché theorem, we know that the conclusions of (I)(1) and (I)(2) are true.

If $\tau = \delta/\sigma$, then

$$\lim_{\lambda \to 0} \frac{d\tau}{d\lambda} = \lim_{\lambda \to 0} \frac{-\tau (\sigma/\delta) (-\tau) e^{-\lambda \tau}}{(\sigma/\delta) e^{-\lambda \tau} - (\sigma/\delta) \tau \lambda e^{-\lambda \tau}} = \tau^2.$$
 (16)

Thus

$$\operatorname{sgn}\left\{\operatorname{Re}\left(\frac{\mathrm{d}\lambda}{\mathrm{d}\tau}\right)\bigg|_{\lambda=0}\right\} = \operatorname{sgn}\left\{\operatorname{Re}\left(\frac{\mathrm{d}\tau}{\mathrm{d}\lambda}\right)\bigg|_{\lambda=0}\right\} = 1 > 0. \tag{17}$$

Hence the conclusion (I)(3) is true.

Noting

$$\operatorname{sgn}\left\{\operatorname{Re}\left(\frac{\mathrm{d}\lambda}{\mathrm{d}\tau}\right)\bigg|_{\lambda=i\omega_{+}}\right\} = \operatorname{sgn}\left\{\operatorname{Re}\left(\frac{\mathrm{d}\tau}{\mathrm{d}\lambda}\right)\bigg|_{\lambda=i\omega_{+}}\right\}$$

$$= \operatorname{sgn}\left\{\frac{\sin\omega_{+}\tau}{(\sigma/\delta)\omega_{+}}\right\} \qquad (18)$$

$$= \operatorname{sgn}\left\{\left(\frac{\delta}{\sigma}\right)^{2}\right\} = 1 > 0,$$

then (II)(3) is proved. Then all the proof is finished. \Box

Thus the following results can be obtained by Lemma 1.

Theorem 2. (*I*) If $\alpha = \sigma/\delta$, then

- (1) system (5) undergoes a codimension one steady-state bifurcation at the tumor-free equilibrium P_0 as $0 < \tau < \delta/\sigma$:
- (2) the tumor-free equilibrium P_0 is a B-T singular equilibrium as $\tau = \delta/\sigma$.
- (II) If $\alpha < \sigma/\delta$, then
- (1) the tumor-free equilibrium P_0 is asymptotically stable as $0 \le \tau < \tau_0$;
- (2) the tumor-free equilibrium P_0 is unstable as $\tau > \tau_0$;
- (3) system (5) undergoes Hopf bifurcation at the tumor-free equilibrium P_0 as $\tau = \tau_k$.
- (III) The tumor-free equilibrium P_0 is unstable as $\alpha > \sigma/\delta$.

2.2. Positive Equilibrium. If $\alpha\delta - \sigma > 0$, then the positive equilibrium P_2 exists. The characteristic equation of system (8) at the point P_2 is

$$\lambda^2 + p\lambda + q\lambda e^{-\lambda \tau} + r + le^{-\lambda \tau} = 0, \tag{19}$$

where

$$p = -(\alpha - \delta - 2\alpha\beta y_2),$$

$$q = x_2 - \zeta y_2,$$

$$r = -\delta (\alpha - 2\alpha\beta y_2),$$

$$l = \delta x_2 + \zeta y_2 (\alpha - 2\alpha\beta y_2).$$
(20)

Lemma 3. *If* $\alpha\delta - \sigma > 0$, $\beta < \alpha\delta/2(\alpha\delta - \sigma)$, then

- (1) all roots of (19) have negative real parts as $0 \le \tau < \tau'_0$;
- (2) Equation (19) has a pair of conjugate purely imaginary roots $i\widetilde{\omega}_+$, and all other roots have negative real parts as $\tau = \tau_0'$;
- (3) Equation (19) has at least one root with positive real parts as $\tau > \tau'_0$.

Proof. Noting $\beta < \alpha\delta/2(\alpha\delta - \sigma)$, $1 - 2\beta v_2 > 0$, one has

$$r + l = \zeta \alpha y_2 \left(1 - 2\beta y_2 \right) + \delta \alpha \beta y_2 > 0; \tag{21}$$

thus (19) has no zero root.

If $\tau = 0$, then (19) can be written as

$$\lambda^{2} + (p+q)\lambda + r + l = 0.$$
 (22)

It is easy to see

$$p + q = \delta - \alpha (1 - 2\beta y_2) + x_2 - \zeta y_2 = \delta + (\alpha \beta - \zeta) y_2 > 0,$$
 (23)

and then all roots of (22) have negative real parts.

If $\tau > 0$, we assume that (19) has a pair of purely imaginary roots $\lambda = i\omega$ ($\omega > 0$); thus

$$-\omega^{2} + l\cos\omega\tau + q\omega\sin\omega\tau + r = 0,$$

$$p\omega + q\omega\cos\omega\tau - l\sin\omega\tau = 0,$$
(24)

and hence

$$\omega^4 + (p^2 - 2r - q^2)\omega^2 + r^2 - l^2 = 0.$$
 (25)

Noting r + l > 0, r < 0, then we have r - l < 0 and $r^2 - l^2 = (r + l)(r - l) < 0$. That is to say, (25) has only one positive root

$$\widetilde{\omega}_{+} = \sqrt{\frac{-\left(p^{2} - 2r - q^{2}\right) + \sqrt{\left(p^{2} - 2r - q^{2}\right)^{2} - 4\left(r^{2} - l^{2}\right)}}{2}},$$
(26)

and the corresponding critical value is

$$\tau'_{k} = \begin{cases} \frac{1}{\widetilde{\omega}_{+}} \left\{ \arctan \frac{lp\widetilde{\omega}_{+} + q\widetilde{\omega}_{+} \left(\widetilde{\omega}_{+}^{2} - r\right)}{l\left(\widetilde{\omega}_{+}^{2} - r\right) - pq\widetilde{\omega}_{+}^{2}} + 2k\pi \right\} \\ if \ l\left(\widetilde{\omega}_{+}^{2} - r\right) - pq\widetilde{\omega}_{+}^{2} > 0; & k \in \mathbb{N}. \end{cases} \\ \frac{1}{\widetilde{\omega}_{+}} \left\{ \arctan \frac{lp\widetilde{\omega}_{+} + q\widetilde{\omega}_{+} \left(\widetilde{\omega}_{+}^{2} - r\right)}{l\left(\widetilde{\omega}_{+}^{2} - r\right) - pq\widetilde{\omega}_{+}^{2}} + (2k+1)\pi \right\}, \\ if \ l\left(\widetilde{\omega}_{+}^{2} - r\right) - pq\widetilde{\omega}_{+}^{2} < 0. \end{cases}$$

$$(27)$$

We can also give the following transversal condition:

$$\operatorname{sgn}\left\{\operatorname{Re}\left(\frac{\mathrm{d}\lambda}{\mathrm{d}\tau}\right)\Big|_{\lambda=i\widetilde{\omega}_{+}}\right\}$$

$$=\operatorname{sgn}\left\{\operatorname{Re}\left(\frac{\mathrm{d}\tau}{\mathrm{d}\lambda}\right)\Big|_{\lambda=i\widetilde{\omega}_{+}}\right\}$$

$$=\operatorname{sgn}\left\{\operatorname{Re}\left(\frac{2\lambda+p}{\lambda\left(q\lambda+l\right)e^{-\lambda\tau}}+\frac{q}{\lambda\left(q\lambda+l\right)}\right)\Big|_{\lambda=i\widetilde{\omega}_{+}}\right\}$$

$$=\operatorname{sgn}\left\{2\left(\widetilde{\omega}_{+}^{2}-r\right)+p^{2}-q^{2}\right\}$$

$$=\operatorname{sgn}\left\{-\left(p^{2}-2r-q^{2}\right)+\left(p^{2}-2r-q^{2}\right)+\sqrt{\left(p^{2}-2r-q^{2}\right)^{2}-4\left(r^{2}-l^{2}\right)}\right\}$$

$$=1>0.$$
(28)

Then all results of this theorem have been proven.

From Lemma 3, the following theorem can be obtained directly.

Theorem 4. *Suppose that* $\alpha\delta - \sigma > 0$, $\beta < \alpha\delta/2(\alpha\delta - \sigma)$; *then*

- (1) the positive equilibrium P_2 is stable as $0 \le \tau < \tau'_0$;
- (2) the positive equilibrium P_2 is unstable as $\tau > \tau'_0$;
- (3) system (5) undergoes a Hopf bifurcation at the equilibrium P_2 as $\tau = \tau_k$.

3. Direction and Stability of the Bifurcations

3.1. Hopf Bifurcation. In the previous section, we know that system (5) undergoes Hopf bifurcation at the tumor-free equilibrium P_0 and positive equilibrium P_2 under certain conditions. In this section, we will study the stability and direction of the Hopf bifurcated periodic solution by using the center manifold reduction and normal form theory of retarded functional differential equations due to the ideals of Faria and Magalhães [15, 16]. Throughout this section, we always assume that system (5) undergoes Hopf bifurcations at the equilibrium P (P_0 or P_2) as the critical parameter $\tau = \tau_k$ and the corresponding purely imaginary roots are $\pm i\omega_k$.

Normalizing the delay τ in system (7) by the time-scaling $t \to t/\tau$, then (7) is transformed into

$$z'_{1}(t) = \tau \left[\alpha_{1} z_{1}(t) + \alpha_{2} z_{1}(t-1) + \alpha_{3} z_{2}(t-1) + \zeta z_{1}(t-1) z_{2}(t-1) \right],$$

$$z'_{2}(t) = \tau \left[\beta_{1} z_{1}(t-1) + \beta_{2} z_{2}(t) + \beta_{3} z_{2}(t-1) - \alpha \beta z_{2}^{2}(t) - z_{1}(t-1) z_{2}(t-1) \right].$$
(29)

This scaling is irrelevant for the study of the stability of the equilibrium but will be crucial for the Hopf bifurcation analysis.

Let $z(t) = \begin{cases} z_1(t) \\ z_2(t) \end{cases}$. we transformed (29) into an FDE in $C([-1,0],\mathbb{R}^2)$:

$$\dot{z}(t) = N(\tau)(z_t) + F(z_t, \tau), \tag{30}$$

where $N(\varphi): C([-1,0],\mathbb{R}^2) \to \mathbb{R}^2$, $F(\varphi): C([-1,0]\mathbb{R}^2) \to \mathbb{R}^2$, are given by

$$N(\tau)(\varphi) = \tau \begin{pmatrix} \alpha_{1}\varphi_{1}(0) + \alpha_{2}\varphi_{1}(-1) + \alpha_{3}\varphi_{2}(-1) \\ \beta_{1}\varphi_{1}(-1) + \beta_{2}\varphi_{2}(0) + \beta_{3}\varphi_{2}(-1) \end{pmatrix},$$

$$F(\varphi, \tau) = \tau \begin{pmatrix} \zeta\varphi_{1}(-1)\varphi_{2}(-1) \\ -\alpha\beta\varphi_{2}^{2}(0) - \varphi_{1}(-1)\varphi_{2}(-1) \end{pmatrix},$$
(31)

where $\varphi = \operatorname{col}(\varphi_1, \varphi_2) \in C([-1, 0], \mathbb{R}^2)$. Let $\Lambda = \{i\omega_k, -i\omega_k\}$. Setting the new parameter $\gamma = \tau - \tau_k$, then (30) can be written as

$$\dot{z}(t) = N(\tau_{\iota})(z_{\iota}) + \tilde{F}(z_{\iota}, \gamma), \tag{32}$$

where $\tilde{F}(z_t, \gamma) = N(\gamma)(z_t) + F(z_t, \tau_k + \gamma)$.

Assume that A is the infinitesimal generator of $\dot{z}(t) = N(\tau_k)(z_t)$ satisfying $A\Phi = \Phi B$ with

$$B = \begin{pmatrix} i\omega_k & 0\\ 0 & -i\omega_k \end{pmatrix},\tag{33}$$

and A has a pair of conjugate purely imaginary roots $\pm i\omega_k$. Denote that P is the invariant space of A associated with Λ ; then dim P=2. We can decompose $C:=C([-1,0],\mathbb{R}^2)$ to $C=P\bigoplus Q$ by the formal adjoint theory for FDEs by Hale [17]. Considering complex coordinates, we still denote C as $([-1,0],C^2)$. Let $\Phi=(\Phi_1,\Phi_2)$ be the bases of P, where

$$\Phi_1 = e^{i\omega_k \theta} \nu, \quad \Phi_2 = \overline{\Phi}_1, \quad \theta \in [-1, 0],$$
(34)

 $v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$ is a vector in C^2 and $N(\tau_k)\Phi_1 = i\omega_k v$.

Choose a basis Ψ for the adjoint space P^* , such that $(\Psi, \Phi) = I_2$, where (\cdot, \cdot) is the bilinear form on $C^* \times C$ associated with the adjoint equation. Thus, $\Psi = \text{col}(\Psi_1, \Psi_2)$ with

$$\Psi_1 = e^{-i\omega_k \tilde{\theta}} u^T, \quad \Psi_2 = \overline{\Psi}_1, \quad u = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \\ \tilde{\theta} \in [0, 1],$$
(35)

such that $(\Psi_1, \Phi_1) = 1$, $(\Psi_1, \Phi_2) = 0$. Then

$$v = \begin{pmatrix} 1 \\ \frac{i\omega_k - (\alpha_1 + \alpha_2 e^{-i\omega_k}) \tau_k}{\tau_k \alpha_3 e^{-i\omega_k}} \end{pmatrix},$$

$$u = u_1 \begin{pmatrix} 1 \\ \frac{i\omega_k - (\alpha_1 + \alpha_2 e^{-i\omega_k}) \tau_k}{\tau_k \beta_1 e^{-i\omega_k}} \end{pmatrix},$$
(36)

and $1/u_1 = 1 + (1 + \beta_3 e^{-i\omega_k})v_2((i\omega_k - (\alpha_1 + \alpha_2 e^{-i\omega_k})\tau_k)/\tau_k\beta_1 e^{-i\omega_k}) + (\alpha_2 + 2\alpha_3 v_2)e^{-i\omega_k}.$

Take the enlarged phase space BC, defined as

$$BC := \Big\{ \varphi : [-1,0] \longrightarrow \mathbb{C}^2 \mid \varphi \text{ is continuous on } [-1,0) \,,$$

$$\lim_{\theta \to 0^{-}} \varphi(\theta) \text{ exists}$$

(37)

The projection $\pi: BC \to P$ is defined as

$$\pi(\varphi + X_0 b) = \Phi[(\Psi, \varphi) + \Psi(0) b], \quad \forall \varphi \in C, \ b \in \mathbb{R}^2;$$
(38)

thus we have the decomposition $BC = P \bigoplus \operatorname{Ker} \pi$. Let $z_t = \Phi x + y$, $x \in \mathbb{C}^2$, $y \in \operatorname{ker}(\pi) \cap C^1 := Q^1$, we can decompose (32) to

$$\dot{x} = Bx + \Psi(0) \tilde{F}(\Phi x + y, \gamma),$$

$$\frac{dy}{dx} = A_{Q^{1}}y + (I - \pi) X_{0} \tilde{F}(\Phi x + y, \gamma),$$
(39)

where

$$X_0(\theta) = \begin{cases} I, & \theta = 0; \\ 0, & -1 \le \theta < 0. \end{cases}$$

$$\tag{40}$$

We write the Taylor expansion as follows:

$$\Psi(0) \tilde{F}(\Phi x + y, \gamma) = \frac{1}{2} f_2^1(x, y, \gamma) + \frac{1}{3!} f_3^1(x, y, \gamma) + \text{h.o.t.},$$

$$(I - \pi) X_0 \tilde{F}(\Phi x + y, \gamma) = \frac{1}{2} f_2^2(x, y, \gamma) + \frac{1}{3!} f_3^2(x, y, \gamma) + \text{h.o.t.},$$

$$(41)$$

where f_k^1 and f_k^2 are homogeneous polynomials in x, y, and γ of degree k, k=2,3, with coefficients in \mathbb{C}^2 and Ker π , h.o.t. stands for higher order terms. The normal form method implies a normal form on the center manifold of the origin for (32) which is

$$\dot{x} = Bx + \frac{1}{2}g_2^1(x, 0, \gamma) + \frac{1}{3!}g_3^1(x, 0, \gamma) + \text{h.o.t.},$$
 (42)

where $g_2^1(x, 0, \gamma)$ and $g_3^1(x, 0, \gamma)$ are homogeneous polynomials in x and y, respectively.

From (39), it follows that

$$f_2^1(x,0,\gamma) = 2\Psi(0)\left[N(\gamma)(\Phi x) + F(\Phi x, \tau_k)\right]; \qquad (43)$$

that is,

$$f_2^1(x,0,\gamma) = 2\left(\frac{A_1x_1\gamma + A_2x_2\gamma + a_{20}x_1^2 + a_{11}x_1x_2 + a_{02}x_2^2}{\overline{A_1x_2\gamma + \overline{A_2x_1\gamma + \overline{a_{02}x_1^2 + \overline{a_{11}x_1x_2 + \overline{a_{20}x_2^2}}}}\right),$$
(44)

where

$$A_{1} = \frac{i\omega_{k}}{\tau_{k}} u^{T} v, \qquad A_{2} = \frac{-i\omega_{k}}{\tau_{k}} u^{T} \overline{v},$$

$$a_{20} = \tau_{k} \left[u_{1} e^{-2i\omega_{k}} \zeta v_{1} v_{2} + u_{2} \left(-\alpha \beta v_{2}^{2} - e^{-2i\omega_{k}} v_{1} v_{2} \right) \right],$$

$$a_{11} = \tau_{k} \left[\zeta u_{1} \left(v_{1} \overline{v}_{2} + \overline{v}_{1} v_{2} \right) - u_{2} \left(2\alpha \beta v_{2} \overline{v}_{2} + v_{1} \overline{v}_{2} + \overline{v}_{1} v_{2} \right) \right],$$

$$a_{02} = \tau_{k} \left[u_{1} e^{2i\omega_{k}} \zeta \overline{v}_{1} \overline{v}_{2} + u_{2} \left(-\alpha \beta \overline{v}_{2}^{2} - e^{2i\omega_{k}} \overline{v}_{1} \overline{v}_{2} \right) \right].$$

$$(45)$$

Thus

$$g_2^1(x,0,\gamma) = \text{Proj}_{\text{Ker}(M_2^1)} f_2^1(x,0,\gamma) = \begin{pmatrix} 2A_1 x_1 \gamma \\ 2\overline{A_1} x_2 \gamma \end{pmatrix}.$$
 (46)

We will compute the cubic terms $g_3^1(x, 0, \gamma)$ as follows. Since $O(|x|\gamma^2)$ are irrelevant to determine the generic Hopf bifurcation, then

$$J = \operatorname{span}\left\{ \begin{pmatrix} x_1^2 x_2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ x_1 x_2^2 \end{pmatrix} \right\}; \tag{47}$$

hence

$$g_3^1(x,0,\gamma) = \text{Proj}_I \overline{f}_3^1(x,0,0) + o(|x|\gamma^2),$$
 (48)

where $\overline{f}_3^1(x,0,0)=(3/2)[(D_xf_2^1)u_2^1-(D_xu_2^1)g_2^1]_{(x,0,0)}+(3/2)[(D_yf_2^1)u_2^2]_{(x,0,0)}.$ In order to obtain $g_3^1(x,0,\gamma)$, we need to compute $f_3^1(x,0,0)$; that is, $\operatorname{Proj}_I[(D_xf_2^1)u_2^1]_{(x,0,0)},$ $\operatorname{Proj}_I[(D_xu_2^1)g_2^1]_{(x,0,0)},$ and $\operatorname{Proj}_I[(D_yf_2^1)u_2^2]_{(x,0,0)}$ should be given; we will compute them as follows.

Firstly, knowing that

$$f_{2}^{1}(x,0,0) = 2 \begin{pmatrix} a_{20}x_{1}^{2} + a_{11}x_{1}x_{2} + a_{02}x_{2}^{2} \\ \overline{a}_{02}x_{1}^{2} + \overline{a}_{11}x_{1}x_{2} + \overline{a}_{20}x_{2}^{2} \end{pmatrix},$$

$$u_{2}^{1}(x,0) = \frac{2}{i\omega_{k}} \begin{pmatrix} a_{20}x_{1}^{2} - a_{11}x_{1}x_{2} - \frac{1}{3}a_{02}x_{2}^{2} \\ \frac{1}{3}\overline{a}_{02}x_{1}^{2} + \overline{a}_{11}x_{1}x_{2} - \overline{a}_{20}x_{2}^{2} \end{pmatrix},$$

$$(49)$$

then

$$\operatorname{Proj}_{J}\left[\left(D_{x}f_{2}^{1}\right)u_{2}^{1}\right]_{(x,0,0)}$$

$$=\frac{4}{i\omega_{k}}\left(\frac{\left(-a_{20}a_{11}+\frac{2}{3}\left|a_{02}\right|^{2}+\left|a_{11}\right|^{2}\right)x_{1}^{2}x_{2}}{\left(-\frac{2}{3}\left|a_{02}\right|^{2}-\left|a_{11}\right|^{2}+\overline{a_{20}a_{11}}\right)x_{1}x_{2}^{2}}\right)$$

$$=4\left(\frac{A_{3}x_{1}^{2}x_{2}}{\bar{A}_{3}x_{1}x_{2}^{2}}\right).$$
(50)

Secondly, noting (46), we know that $g_2^1(x, 0, 0) = 0$; then $\text{Proj}_I[(D_x u_2^1)g_2^1]_{(x,0,0)} = 0$.

Lastly, we will compute $\operatorname{Proj}_{J}[(D_{y}f_{2}^{1})u_{2}^{2}]_{(x,0,0)}$ as follow. Let $h=u_{2}^{2}=h_{200}x_{1}^{2}+h_{020}x_{2}^{2}+h_{002}\gamma^{2}+h_{110}x_{1}x_{2}+h_{101}x_{1}\gamma+h_{011}x_{2}\gamma$. Noting $g_{2}^{2}=0$, one has

$$M_{2}^{2}h\left(x,\gamma\right) = f_{2}^{2} = 2\left(I - \pi\right)X_{0}\widetilde{F}\left(\Phi x,\gamma\right)$$

$$= 2\left(I - \pi\right)X_{0}\left[N\left(\gamma\right)\left(\Phi x\right) + F\left(\Phi x,\tau_{k}\right)\right].$$
(51)

On the other hand, we know that

$$M_{2}^{2}h(x,\gamma)$$

$$= D_{x}h(x,\gamma)Bx - A_{Q^{1}}h(x,\gamma)$$

$$= D_{x}h(x,\gamma)Bx$$

$$- \left[\dot{h}(x,\gamma) + X_{0}\left(L(\tau_{k})(h(x,\gamma)) - \dot{h}(x,\gamma)(0)\right)\right].$$
(52)

If $\gamma = 0$, then

$$\dot{h}(x) - D_x h(x) Bx = 2\Phi \Psi(0) F(\Phi x, \tau_k),
\dot{h}(x)(0) - L(\tau_k) (h(x)) = 2F(\Phi x, \tau_k).$$
(53)

Let

$$W(\theta) = \Phi x + y = \Phi_1 x_1 + \Phi_2 x_2 + y(\theta)$$

$$= e^{i\omega_k \theta} v x_1 + e^{-i\omega_k \theta} \overline{v} x_2 + y(\theta), \qquad (54)$$

$$\widetilde{W}(\theta) = \Phi x = \Phi_1 x_1 + \Phi_2 x_2 = e^{i\omega_k \theta} v x_1 + e^{-i\omega_k \theta} \overline{v} x_2.$$

From

$$f_{2}^{1}(x, y, 0) = 2\tau_{k} \begin{pmatrix} \zeta W_{1}(-1) W_{2}(-1) \\ -\alpha \beta W_{2}^{2}(0) - W_{1}(-1) W_{2}(-1) \end{pmatrix}, \\ \overline{u}^{T} \begin{pmatrix} \zeta W_{1}(-1) W_{2}(-1) \\ -\alpha \beta W_{2}^{2}(0) - W_{1}(-1) W_{2}(-1) \end{pmatrix},$$

$$(55)$$

we obtain

$$\left[\left(D_{y} f_{2}^{1} \right) h \right]_{(x,0,0)} = 2 \begin{pmatrix} \zeta \widetilde{W}_{2} \left(-1 \right) h^{1} \left(-1 \right) + \zeta \widetilde{W}_{1} \left(-1 \right) h^{2} \left(-1 \right) \\ -\widetilde{W}_{2} \left(-1 \right) h^{1} \left(-1 \right) - \widetilde{W}_{1} \left(-1 \right) h^{2} \left(-1 \right) - 2\alpha \beta \widetilde{W}_{2} \left(0 \right) h^{2} \left(0 \right) \end{pmatrix} \\ \tau_{k} \overline{u}^{T} \begin{pmatrix} \zeta \widetilde{W}_{2} \left(-1 \right) h^{1} \left(-1 \right) + \zeta \widetilde{W}_{1} \left(-1 \right) h^{2} \left(-1 \right) \\ -\widetilde{W}_{2} \left(-1 \right) h^{1} \left(-1 \right) - \widetilde{W}_{1} \left(-1 \right) h^{2} \left(-1 \right) - 2\alpha \beta \widetilde{W}_{2} \left(0 \right) h^{2} \left(0 \right) \end{pmatrix} \end{pmatrix}, \tag{56}$$

$$\operatorname{Proj}_{J}\left[\left(D_{y}f_{2}^{1}\right)u_{2}^{2}\right]_{(x,0,0)} = 2\left(\frac{A_{4}x_{1}^{2}x_{2}}{A_{4}x_{1}x_{2}^{2}}\right),\tag{57}$$

where

$$\begin{split} A_4 &= \tau_k \left[u_1 \zeta \left(e^{-i\omega_k} v_2 h_{110}^1 \left(-1 \right) + e^{i\omega_k} \overline{v}_2 h_{200}^1 \left(-1 \right) \right. \\ &\left. + e^{-i\omega_k} v_1 h_{110}^2 \left(-1 \right) + e^{i\omega_k} \overline{v}_1 h_{200}^2 \left(-1 \right) \right) \right] \\ &+ u_2 \tau_k \left[-e^{-i\omega_k} v_2 h_{110}^1 \left(-1 \right) - e^{i\omega_k} \overline{v}_2 h_{200}^1 \left(-1 \right) \right. \\ &\left. - e^{-i\omega_k} v_1 h_{110}^2 \left(-1 \right) - e^{i\omega_k} \overline{v}_1 h_{200}^2 \left(-1 \right) \right] \\ &- u_2 \tau_k \left[2\alpha \beta \left(v_2 h_{110}^2 \left(0 \right) + \overline{v}_2 h_{200}^2 \left(0 \right) \right) \right]. \end{split}$$
 (58)

In order to obtain A_4 , we need to compute $h_{110}(\theta)$, $h_{200}(\theta)$. From (53), it follows that

$$\dot{h}_{110} = 2 \left(\Phi_1, \Phi_2 \right) \left(\frac{a_{11}}{a_{11}} \right),$$

$$\dot{h}_{110} \left(0 \right) - L \left(\tau_k \right) \left(h_{110} \right) = \tau_k \left(\frac{a_1}{b_1} \right),$$

$$\dot{h}_{200} - 2i\omega_k h_{200} = 2 \left(\Phi_1, \Phi_2 \right) \left(\frac{a_{20}}{a_{02}} \right),$$

$$\dot{h}_{200} \left(0 \right) - L \left(\tau_k \right) \left(h_{200} \right) = \tau_k \left(\frac{a_2}{b_2} \right),$$
(59)

where $a_1 = 2[\zeta(v_1\overline{v}_2 + \overline{v}_1v_2)], b_1 = 2[-2\alpha\beta v_2\overline{v}_2 - (v_1\overline{v}_2 + \overline{v}_1v_2)],$ $a_2 = 2[\zeta v_1v_2e^{-2i\omega_k}],$ and $b_2 = 2[-\alpha\beta v_2^2 - e^{-2i\omega_k}v_1v_2].$ Solving (59), we can obtain

$$h_{110} = 2\left[\frac{a_{11}}{i\omega_k}\Phi_1 - \frac{\overline{a}_{11}}{i\omega_k}\Phi_2\right] + C_1,$$

$$h_{200} = 2\left[\frac{a_{20}}{-i\omega_k}\Phi_1 + \frac{\overline{a}_{02}}{-3i\omega_k}\Phi_2\right] + C_2e^{2i\omega_k\theta},$$
(60)

where

$$C_{1} = \begin{pmatrix} C_{1}^{1} \\ C_{1}^{2} \end{pmatrix},$$

$$C_{1}^{1} = \frac{\begin{vmatrix} a_{1} & -\alpha_{3} \\ b_{1} & -(\beta_{2} + \beta_{3}) \end{vmatrix}}{\begin{vmatrix} -(\alpha_{1} + \alpha_{2}) & -\alpha_{3} \\ -\beta_{1} & -(\beta_{2} + \beta_{3}) \end{vmatrix}},$$

$$C_{1}^{2} = \frac{\begin{vmatrix} -(\alpha_{1} + \alpha_{2}) & a_{1} \\ -\beta_{1} & b_{1} \end{vmatrix}}{\begin{vmatrix} -(\alpha_{1} + \alpha_{2}) & -\alpha_{3} \\ -\beta_{1} & -(\beta_{2} + \beta_{3}) \end{vmatrix}},$$

$$C_{2} = \begin{pmatrix} C_{2}^{1} \\ C_{2}^{2} \end{pmatrix},$$

$$C_{1}^{2} = \frac{\begin{vmatrix} \tau_{k}a_{2} & -\tau_{k}\alpha_{3}e^{-2i\omega_{k}} \\ \tau_{k}b_{2} & 2i\omega_{k} + \tau_{k}\beta_{2} + \tau_{k}\beta_{3}e^{-2i\omega_{k}} \end{vmatrix}}{\begin{vmatrix} 2i\omega_{k} - \tau_{k}\alpha_{1} - \tau_{k}\alpha_{2}e^{-2i\omega_{k}} & -\tau_{k}\alpha_{3}e^{-2i\omega_{k}} \\ -\tau_{k}\beta_{1}e^{-2i\omega_{k}} & 2i\omega_{k} + \tau_{k}\beta_{2} + \tau_{k}\beta_{3}e^{-2i\omega_{k}} \end{vmatrix}},$$

$$C_{2}^{2} = \frac{\begin{vmatrix} 2i\omega_{k} - \tau_{k}\alpha_{1} - \tau_{k}\alpha_{2}e^{-2i\omega_{k}} & \tau_{k}\alpha_{2} \\ -\tau_{k}\beta_{1}e^{-2i\omega_{k}} & \tau_{k}b_{2} \end{vmatrix}}{\begin{vmatrix} 2i\omega_{k} - \tau_{k}\alpha_{1} - \tau_{k}\alpha_{2}e^{-2i\omega_{k}} & -\tau_{k}\alpha_{3}e^{-2i\omega_{k}} \\ -\tau_{k}\beta_{1}e^{-2i\omega_{k}} & 2i\omega_{k} + \tau_{k}\beta_{2} + \tau_{k}\beta_{3}e^{-2i\omega_{k}} \end{vmatrix}}.$$

$$(61)$$

Hence

$$g_3^1(x,0,0) = \begin{pmatrix} (6A_3 + 3A_4) x_1^2 x_2 \\ (6\overline{A}_3 + 3\overline{A}_4) x_1 x_2^2 \end{pmatrix}.$$
 (62)

Thus, the normal form of system (42) has the form

$$\dot{x} = Bx + \left(\frac{A_1 x_1 \gamma}{A_1 x_2 \gamma}\right) + \frac{1}{3!} \begin{pmatrix} (6A_3 + 3A_4) x_1^2 x_2 \\ (6\overline{A}_3 + 3\overline{A}_4) x_1 x_2^2 \end{pmatrix} + o\left(|x|^4 + |x| \gamma^2\right).$$
(63)

Let $x_1 = \xi_1 - i\xi_2$, $x_2 = \xi_1 + i\xi_2$, $\xi_1 = \rho \cos \omega$, and $\xi_2 = \rho \sin \omega$. Then the normal form becomes

$$\dot{\rho} = r_1 \gamma \rho + r_2 \rho^3 + O\left(\gamma^2 \rho + \left| (\rho, \gamma) \right|^4 \right),$$

$$\dot{\omega} = -\omega_k - \operatorname{Im}\left(A_1\right) \gamma - \operatorname{Im}\left(A_3 + \frac{1}{2}A_4\right) \rho^2 + o\left(\left| (\rho^2, \gamma) \right| \right),$$
(64)

where $r_1 = \text{Re } A_1$, $r_2 = \text{Re}(A_3 + (1/2)A_4)$. Summarizing all above, we have the following theorem.

Theorem 5. The flow on the center manifold of the equilibrium P at $\gamma = 0$ is given by (64). Also the following results hold:

(1) the Hopf bifurcation is supercritical if $r_1r_2 < 0$ and subcritical if $r_1r_2 > 0$;

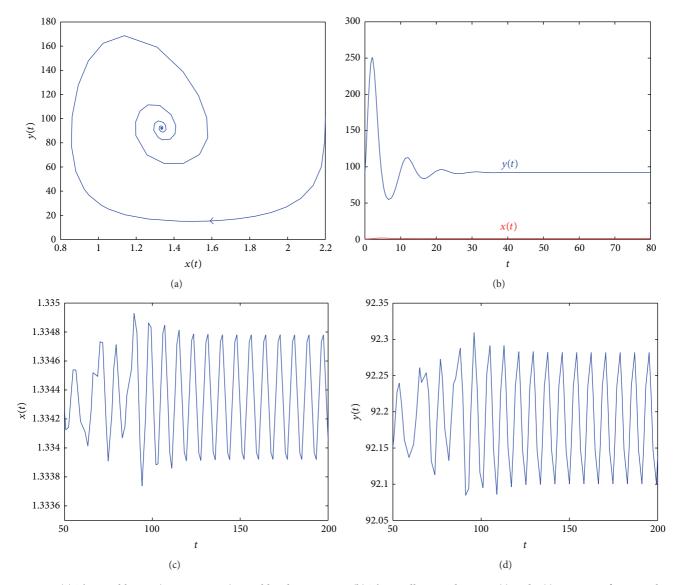


FIGURE 2: (a) The equilibrium (1.3344, 92.1911) is stable when $\tau = 0.2$. (b) The oscillation solutions x(t) and y(t) in terms of time t when $\tau = 0.2 < \tau_0$. (c) The oscillation solution x(t) in terms of t when $\tau = 0.372892$. (d) The oscillation solution y(t) in terms of t.

- (2) the bifurcated periodic solution is stable if $r_2 < 0$ and unstable if $r_2 > 0$;
- (3) the period of the bifurcated periodic solution is

$$p(\gamma) = \frac{2\pi}{\omega_k} - \frac{2\pi\gamma \left(r_2 \operatorname{Im}(A_1) - r_1 \operatorname{Im}(A_3 + (1/2)A_4)\right)}{r_2\omega_k^2} + O(\gamma^2).$$
(65)

In the following, we will give some simulations to illustrate the results of Theorems 4 and 5 for model (4). We cite the parameters in [11], that is, $\sigma=0.1181,~\zeta=0.0031,~\delta=0.3743,~\alpha=1.636,$ and $\beta=0.002.$ Then (4) has a tumor-free equilibrium (0.3155,0), which is unstable, and a positive equilibrium (1.33435,92.1911), which is locally asymptotically stable. We only simulate local properties of the

stable equilibrium (1.33435, 92.1911) here in Figures 2(a) and 2(b).

Remark 6. From Figures 2(c) and 2(d), we can see that the amplitude vibration for x(t) is much bigger than that of y(t); also both x(t) and y(t) with respect to t are not so smooth. Then the Hopf bifurcated periodic solution on (x(t), y(t)) plan is not given here. At the same time, we can see that the dynamical behaviors of the system have been changed although τ is small.

3.2. Steady-State Bifurcation. From Section 2, we know that system (5) undergoes a steady-state bifurcation at the tumorfree equilibrium P_0 as $\alpha = \sigma/\delta$, $0 < \tau < \delta/\sigma$. In this section, we will discuss the properties of the steady-state bifurcation by using the center manifold reduction and normal form theories of retarded functional differential equations.

At the tumor-free equilibrium P_0 , we write system (5) as an FDE:

$$\dot{z}(t) = N(z_t) + F(z_t), \tag{66}$$

where

$$N(\varphi) = \tau \begin{pmatrix} -\delta\varphi_1(0) + \zeta \frac{\sigma}{\delta}\varphi_2(-1) \\ \alpha\varphi_2(0) - \frac{\sigma}{\delta}\varphi_2(-1) \end{pmatrix},$$

$$F(\varphi) = \tau \begin{pmatrix} \zeta\varphi_1(-1)\varphi_2(-1) \\ -\alpha\beta\varphi_2^2(0) - \varphi_1(-1)\varphi_2(-1) \end{pmatrix}.$$
(67)

Letting $\alpha = (\sigma/\delta) + \gamma$, then (66) can be written as

$$\dot{z}(t) = N\left(\frac{\sigma}{\delta}\right)(z_t) + \tilde{F}(z_t, \gamma), \tag{68}$$

where $\tilde{F}(z_t, \gamma) = N(\gamma)(z_t) + F(z_t, \gamma)$.

Assuming that A is the infinitesimal generator of $\dot{z}(t) = N(\sigma/\delta)(z_t)$, then A has a simple zero root. Set $\Lambda = \{0\}$ and we denote by P the invariant space of A associated with Λ ; then dim P = 1. We can decompose $C := C([-1,0],\mathbb{R}^2)$ to $C = P \bigoplus Q$ by the formal adjoint theory for FDEs by Hale [17]. Let $P = \operatorname{span}(\Phi)$ be the bases for P, where $\Phi = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$, which is a vector in \mathbb{R}^2 satisfying

$$N\left(\frac{\sigma}{\delta}\right)\Phi = \dot{\Phi}\left(0\right). \tag{69}$$

Choose a basis Ψ for the adjoint space P^* , where $\Psi=(u_1,u_2)$, which is a vector in \mathbb{R}^{2*} satisfying $\Psi N(\sigma/\delta)=-\dot{\Psi}(0)$. Thus we can obtain

$$\Phi = \begin{pmatrix} 1 \\ \frac{\delta^2}{\zeta \sigma} \end{pmatrix}, \qquad \Psi = \left(0, \frac{1}{\left(\delta^2 / \zeta \sigma\right) - \left(\tau \delta / \zeta\right)}\right). \tag{70}$$

According to the method of Faria and a similar computation in the last section, we can obtain

$$f_{2}^{1}(x,0,\gamma) = 2\Psi(0) \left[N(\gamma) (\Phi x) + F(\Phi x, \tau_{k}) \right]$$

$$= 2 \frac{\tau}{\delta/\sigma - \tau} \left[\gamma \frac{\delta}{\sigma} x - \left(\left(\beta \delta^{2} \right) / \zeta \sigma + \delta/\sigma \right) x^{2} \right]. \tag{71}$$

Noting

$$\operatorname{Ker}\left(M_{2}^{1}\right) = \operatorname{span}\left\{x^{2}, x\gamma, \gamma^{2}\right\},\tag{72}$$

one has

$$g_{2}^{1}(x,0,\gamma) = \operatorname{Proj}_{\operatorname{Ker}(M_{2}^{1})} f_{2}^{1}(x,0,\gamma)$$

$$= 2 \frac{\tau}{\delta/\sigma - \tau} \left[\gamma \frac{\delta}{\sigma} x - \left(\frac{\beta \delta^{2}}{\zeta \sigma} + \frac{\delta}{\sigma} \right) x^{2} \right].$$
(73)

Thus, the normal form of system (5) is

$$\dot{x} = \frac{\tau}{\delta/\sigma - \tau} \left[\gamma \frac{\delta}{\sigma} x - \left(\frac{\beta \delta^2}{\zeta \sigma} + \frac{\delta}{\sigma} \right) x^2 \right] + o\left(x^2 \right). \tag{74}$$

Then the following two results are obvious.

Theorem 7. If $\alpha = \sigma/\delta$, $0 < \tau < \delta/\sigma$, then the tumor-free equilibrium P_0 is stable.

Theorem 8. If $0 < \tau < \delta/\sigma$, $\alpha = \sigma/\delta + \gamma$, and γ is small enough, then

- (1) the tumor-free equilibrium P_0 is stable as $\gamma > 0$ and unstable as $\gamma < 0$;
- (2) system (5) undergoes transcritical bifurcation at the tumor-free equilibrium P_0 .

3.3. Bogdanov-Takens Bifurcation. From Theorem 2 we know that the tumor-free equilibrium P_0 is a B-T singular equilibrium of the system (5) as $\alpha = \sigma/\delta$, $\tau = \delta/\sigma$. In this section, we will discuss the bifurcations of the system (5) at P_0 .

At tumor-free equilibrium P_0 , we can write (5) as an FDE:

$$\dot{z}(t) = N(z_t) + F(z_t), \tag{75}$$

where

$$N\left(\varphi\right) = \tau \begin{pmatrix} -\delta\varphi_{1}\left(0\right) + \zeta\frac{\sigma}{\delta}\varphi_{2}\left(-1\right) \\ \alpha\varphi_{2}\left(0\right) - \frac{\sigma}{\delta}\varphi_{2}\left(-1\right) \end{pmatrix}, \tag{76}$$
$$F\left(\varphi\right) = \tau \begin{pmatrix} \zeta\varphi_{1}\left(-1\right)\varphi_{2}\left(-1\right) \\ -\alpha\beta\varphi_{2}^{2}\left(0\right) - \varphi_{1}\left(-1\right)\varphi_{2}\left(-1\right) \end{pmatrix}.$$

Let $\alpha = \sigma/\delta + \gamma_1$, $\tau = \delta/\sigma + \gamma_2$. Then system (75) can be written as

$$\dot{z}(t) = N\left(\frac{\sigma}{\delta}\right)(z_t) + \tilde{F}(z_t, \gamma), \tag{77}$$

where $\tilde{F}(z_t, \gamma) = N(\gamma)(z_t) + F(z_t, \gamma), \gamma = \begin{pmatrix} \gamma_1 \\ \gamma_2 \end{pmatrix}$.

Assuming that A is the infinitesimal generator of $\dot{z}(t) = N(\sigma/\delta)(z_t)$, then A has double zero roots. Set $\Lambda = \{0\}$ and denote by P the invariant space of A associated with Λ ; then dim P = 2. We can decompose $C := C([-1,0],\mathbb{R}^2)$ as $C = P \bigoplus Q$ by the formal adjoint theory for FDEs by Hale [17]. Assume that $P = \operatorname{span}(\Phi)$ and $P^* = \operatorname{span}(\Psi)$. On the other hand, we know that $A\Phi = \Phi B$, where

$$B = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix},\tag{78}$$

that is, $N\Phi=\dot{\Phi}(0)=\Phi B, \Psi N=-\dot{\Psi}(0)=-B\Psi,$ and $(\Psi,\Phi)=I_2.$ Let

$$A' = \begin{pmatrix} -\frac{\delta^2}{\sigma} & 0\\ 0 & 1 \end{pmatrix}, \qquad B' = \begin{pmatrix} 0 & \zeta\\ 0 & -1 \end{pmatrix}. \tag{79}$$

(81)

From Lemma 3.1 by Xu and Huang [18], we can get

$$\Phi(\theta) = \begin{pmatrix} \frac{\sigma}{\delta^2} & \frac{\sigma}{\delta^2} \theta - \frac{\sigma^2}{\delta^4} \\ \frac{1}{\zeta} & \frac{1}{\zeta} (\theta + 1) \end{pmatrix},$$
(80)
$$\Psi(\tilde{\theta}) = \begin{pmatrix} 0 & -\frac{4}{3}\zeta - 2\zeta\tilde{\theta} \\ 0 & 2\zeta \end{pmatrix}.$$

Using the method of Faria and the last section, we can obtain

$$f_{2}^{1}(x,0,\gamma) = 2\Psi(0)\left[N(\gamma)(\Phi x) + F(\Phi x,\tau_{k})\right]$$

$$= 2\left(\frac{-\frac{4}{3}\left[\frac{\delta}{\sigma}\gamma_{1}x_{1} + \left(\frac{\delta}{\sigma}\gamma_{1} + \frac{\sigma}{\delta}\gamma_{2}\right)x_{2} - \left(\frac{\beta}{\zeta} + \frac{1}{\delta}\right)x_{1}^{2} + \left(-\frac{2\beta}{\zeta} + \frac{\sigma}{\delta^{3}} + \frac{1}{\delta}\right)x_{1}x_{2} - \frac{\beta}{\zeta}x_{2}^{2}\right]}{2\left[\frac{\delta}{\sigma}\gamma_{1}x_{1} + \left(\frac{\delta}{\sigma}\gamma_{1} + \frac{\sigma}{\delta}\gamma_{2}\right)x_{2} - \left(\frac{\beta}{\zeta} + \frac{1}{\delta}\right)x_{1}^{2} + \left(-\frac{2\beta}{\zeta} + \frac{\sigma}{\delta^{3}} + \frac{1}{\delta}\right)x_{1}x_{2} - \frac{\beta}{\zeta}x_{2}^{2}\right]}\right).$$
(82)

On the other hand, the basis of $Ker(M_2^1)$ is

$$\begin{pmatrix} 0 \\ x_1 \gamma_1 \end{pmatrix}, \qquad \begin{pmatrix} 0 \\ x_2 \gamma_1 \end{pmatrix},$$

$$\begin{pmatrix} 0 \\ x_1^2 \end{pmatrix}, \qquad \begin{pmatrix} 0 \\ x_1 x_2 \end{pmatrix},$$

$$\begin{pmatrix} 0 \\ x_1 \gamma_2 \end{pmatrix}, \qquad \begin{pmatrix} 0 \\ x_2 \gamma_2 \end{pmatrix},$$

$$\begin{pmatrix} 0 \\ \gamma_1^2 \end{pmatrix}, \qquad \begin{pmatrix} 0 \\ \gamma_2^2 \end{pmatrix}, \qquad \begin{pmatrix} 0 \\ \gamma_1 \gamma_2 \end{pmatrix},$$
(83)

and then we can obtain

$$g_{2}^{1}(x,0,\gamma) = \operatorname{Proj}_{\operatorname{Ker}(M_{2}^{1})} f_{2}^{1}(x,0,\gamma)$$

$$= 2 \left(2 \left[\frac{\delta}{\sigma} \gamma_{1} x_{1} + \left(\frac{\delta}{\sigma} \gamma_{1} + \frac{\sigma}{\delta} \gamma_{2} \right) x_{2} - \left(\frac{\beta}{\zeta} + \frac{1}{\delta} \right) x_{1}^{2} + \left(-\frac{2\beta}{\zeta} + \frac{\sigma}{\delta^{3}} + \frac{1}{\delta} \right) x_{1} x_{2} \right] \right).$$
(84)

Thus, the normal form of the system (5) is

$$\dot{x}_1 = x_2,$$

$$\dot{x}_2 = a_1 x_1 + a_2 x_2 + b_1 x_1^2 + b_2 x_1 x_2 + \text{h.o.t,}$$
(85)

where

$$a_{1} = 2\frac{\delta}{\sigma}\gamma_{1}, \qquad a_{2} = 2\left(\frac{\delta}{\sigma}\gamma_{1} + \frac{\sigma}{\delta}\gamma_{2}\right),$$

$$b_{1} = -2\left(\frac{\beta}{\zeta} + \frac{1}{\delta}\right), \qquad b_{2} = 2\left(-\frac{2\beta}{\zeta} + \frac{\sigma}{\delta^{3}} + \frac{1}{\delta}\right).$$
(86)

From above, we know that the following result can be obtained with the help of the theories of Xu and Huang [18] and Chow and Hale [19].

Theorem 9. Assume that $\alpha = \sigma/\delta + \gamma_1$, $\tau = \delta/\sigma + \gamma_2$, $b_2 > 0$, and γ is small enough; then system (5) undergoes Bogdanov-Takens bifurcation at the tumor-free equilibrium P_0 . Furthermore, on the (a_1, a_2) -parameter plane, both H and HL

are located in the area $a_1 > 0$, $a_2 < 0$ and H is on the left of HL, where H is Hopf bifurcation curve defined by

$$H = \left\{ (\gamma_1, \gamma_2) : a_2(\gamma_1, \gamma_2) = \frac{b_2}{b_1} a_1(\gamma_1, \gamma_2) + h.o.t., a_1(\gamma_1, \gamma_2) > 0 \right\},$$
(87)

HL is the homoclinic bifurcation curve defined by

$$HL = \left\{ 0 \left(\gamma_1, \gamma_2 \right) \right.$$

$$: a_2 \left(\gamma_1, \gamma_2 \right) = \mu \left(\sqrt{a_1 \left(\gamma_1, \gamma_2 \right)} \right) a_1 \left(\gamma_1, \gamma_2 \right)$$

$$+ h.o.t., a_1 \left(\gamma_1, \gamma_2 \right) > 0 \right\},$$

$$(88)$$

and μ is a continuously differentiable function with $\mu(0) = 6b_2/7b_1$.

Take the same parameter in last section, that is, $\sigma = 0.1181$, $\zeta = 0.0031$, $\delta = 0.3743$, and $\beta = 0.002$; then

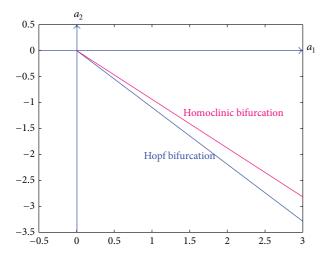


FIGURE 3: The bifurcation diagram of system (5) at the tumor-free equilibrium P_0 .

the tumor-free equilibrium is (0.3155, 0). From Theorem 9, we can obtain that the Hopf bifurcation curve is $a_2 = -1.0955a_1$ and the homoclinic bifurcation is $a_2 = -0.939a_1$. Then on (a_1, a_2) -parameter plane, the bifurcation diagram of system (5) at the equilibrium P_0 is in Figure 3.

4. Discussion

We have studied the nonlinear dynamics of Kuznetsov, Makalkin, and Taylor's model with delay, which is a two-dimensional model of tumor cells and immune system. We first provided linear analysis of the model with delays at the possible equilibria, namely, the tumor-free and positive equilibria, and discussed the existence of Hopf bifurcation at the equilibria. We investigated the Hopf bifurcation, Bogdanov-Takens bifurcation, and steady-state bifurcation in the model. Numerical simulations were presented to illustrate the theoretical analysis and results.

Our analysis on the existence and stability of the tumorfree equilibrium corresponds to this elimination process and on the existence and stability of the positive equilibrium corresponds to coexistence of the immune system and the tumor system. Our results on the existence and stability of the Hopf bifurcated periodic solutions of P_2 describe the equilibrium process. When a stable periodic orbit exists, it can be understood that the tumor and the immune system can coexist although the cancer is not eliminated. The conditions for the parameters provide theories basis to control the development or progression of the tumors. The phenomena have been observed in some models as d'Onofrio [5], Kuznetsov et al. [11], and Bi and Xiao [14]. In particular, Bi and Ruan [7] have shown that various bifurcations, including Hopf bifurcation, Bautin bifurcation, and Hopf-Hopf bifurcation, can occur in such models. Our results on the existence and stability of the bifurcated (Hopf, Bogdanov-Takens, and steady-state) periodic solutions describe rich dynamical behaviors of P_0 , which show that the elimination process is so complex and difficult to control.

Finally, we should point out that we have studied the local dynamical behaviors of P_0 and P_2 . As the example in our paper showed these two equilibria may coexist. Correspondingly, the system can exhibit more degenerate bifurcations including Hopf-Hopf and resonant higher codimension bifurcations. It would be interesting to consider these dynamics of the delayed model.

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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