

Research Article

Positive Solutions of a Nonlinear Parabolic Partial Differential Equation

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We deal with the existence and uniqueness of positive solutions to a class of nonlinear parabolic partial differential equations, by using some fixed point theorems for mixed monotone operators with perturbation.

1. Introduction

In this paper, we consider a class of nonlinear parabolic partial differential equations of the form

$$\begin{aligned} u_t - 2\Delta u &= f(t, u, u) + g(t, u), \quad (x, t) \in \Omega \times (0, T), \\ u(x, t) &= 0, \quad (x, t) \in \Omega \times \{0\} \cup \partial\Omega \times (0, T), \end{aligned} \quad (1)$$

where Ω is a bounded smooth domain in \mathbf{R}^n and $0 < T < +\infty$; we denote $Q_T = \Omega \times (0, T)$.

Problems related to nonlinear parabolic equations arise in many mathematical models of applied science, such as nuclear science, chemical reactions, heat transfer, population dynamics, and biological sciences, and have attracted a great deal of attention in the literature; see [1–6] and the references therein. In recent years, there are many results about existence, uniqueness, blowing-up, global existence, critical exponent, and other properties of the solution; see [4, 5, 7–12], among others. Some of the authors who investigated parabolic equations were using the method of upper and lower solutions; see [11], for example. Different from the works mentioned above, in the present paper, we will utilize some fixed point theorems for mixed monotone operators with perturbation to study the existence and uniqueness of positive solutions to the nonlinear parabolic partial differential equation (1).

With this context in mind, the outline of this paper is as follows. In Section 2 we will recall certain results from the theory of notations and results of monotone operators.

In Section 3, we will provide some conditions under which problem (1) will have a unique positive solution. Finally, in Section 4, we will provide an example, which explicates the applicability of our result.

2. Preliminaries

In this sequel, we present some basic concepts in ordered Banach spaces and two fixed point theorems which we will use later. For convenience, we suggest that one refers to [13–16] for details.

Suppose that $(E, \|\cdot\|)$ is a real Banach space which is partially ordered by a cone $P \subset E$; that is, $x \leq y$ if and only if $y - x \in P$. If $x \leq y$ and $x \neq y$, then we denote $x < y$ or $y > x$. By θ we denote the zero element of E . Recall that a nonempty closed convex set $P \subset E$ is a cone if it satisfies (i) $x \in P, \lambda \geq 0 \Rightarrow \lambda x \in P$; (ii) $x \in P, -x \in P \Rightarrow x = \theta$. P is called normal if there exists a constant $N > 0$ such that, for all $x, y \in E, \theta \leq x \leq y$ implies that $\|x\| \leq N\|y\|$; in this case N is called the normality constant of P . We say that an operator $A : E \rightarrow E$ is increasing (decreasing) if $x \leq y$ implies that $Ax \leq Ay$ ($Ax \geq Ay$). For all $x, y \in E$, the notation $x \sim y$ means that there exist $\lambda > 0$ and $\mu > 0$ such that $\lambda x \leq y \leq \mu x$. Clearly, \sim is an equivalence relation. Given $h > \theta$ (i.e., $h \geq \theta$ and $h \neq \theta$), we denote by P_h the set $P_h = \{x \in E \mid x \sim h\}$. It is easy to see that $P_h \subset P$.

Definition 1 (see [13, 14]). $A : P \times P \rightarrow P$ is said to be a mixed monotone operator if $A(x, y)$ is increasing in x and

decreasing in y ; that is, u_i, v_i ($i = 1, 2$) $\in P$, $u_1 \leq u_2$, $v_1 \geq v_2$ imply that $A(u_1, v_1) \leq A(u_2, v_2)$. Element $x \in P$ is called a fixed point of A if $A(x, x) = x$.

Definition 2. An operator $A : P \rightarrow P$ is said to be subhomogeneous if it satisfies $A(tx) \geq tAx$, $\forall t \in (0, 1)$, $x \in P$.

Definition 3. Let $D = P$ and let β be a real number with $0 \leq \beta < 1$. An operator $A : D \rightarrow D$ is said to be β -concave if it satisfies $A(tx) \geq t^\beta A(x)$, $\forall t \in (0, 1)$, $x \in D$.

Lemma 4 (see Theorem 2.1 in [16]). Let $\beta \in (0, 1)$. $A : P \times P \rightarrow P$ is a mixed monotone operator and satisfies $A(tx, t^{-1}y) \geq t^\beta A(x, y)$, $\forall t \in (0, 1)$, $x, y \in P$. $B : P \rightarrow P$ is an increasing subhomogeneous operator. Assume that (i) there is $h_0 \in P_h$ such that $A(h_0, h_0) \in P_h$ and $Bh_0 \in P_h$ and (ii) there exists a constant $\delta_0 > 0$ such that $A(x, y) \geq \delta_0 Bx$, $\forall x, y \in P$. Then we have the following:

- (1) $A : P_h \times P_h \rightarrow P_h$ and $B : P_h \rightarrow P_h$;
- (2) there exist $u_0, v_0 \in P_h$ and $r \in (0, 1)$ such that

$$rv_0 \leq u_0 < v_0, \quad (2)$$

$$u_0 \leq A(u_0, v_0) + Bu_0 \leq A(v_0, u_0) + Bv_0 \leq v_0;$$

- (3) the operator equation $A(x, x) + Bx = x$ has a unique solution x^* in P_h ;
- (4) for any initial values $x_0, y_0 \in P_h$, constructing successively the sequences

$$\begin{aligned} x_n &= A(x_{n-1}, y_{n-1}) + Bx_{n-1}, \\ y_n &= A(y_{n-1}, x_{n-1}) + By_{n-1}, \\ n &= 1, 2, \dots, \end{aligned} \quad (3)$$

one has $x_n \rightarrow x^*$ and $y_n \rightarrow x^*$ as $n \rightarrow \infty$.

Lemma 5 (see Theorem 2.4 in [16]). Let $\beta \in (0, 1)$. $A : P \times P \rightarrow P$ is a mixed monotone operator and satisfies $A(tx, t^{-1}y) \geq tA(x, y)$, $\forall t \in (0, 1)$, $x, y \in P$. $B : P \rightarrow P$ is an increasing β -concave operator. Assume that (i) there is $h_0 \in P_h$ such that $A(h_0, h_0) \in P_h$ and $Bh_0 \in P_h$ and (ii) there exists a constant $\delta_0 > 0$ such that $A(x, y) \leq \delta_0 Bx$, $\forall x, y \in P$. Then we have the following:

- (1) $A : P_h \times P_h \rightarrow P_h$ and $B : P_h \rightarrow P_h$;
- (2) there exist $u_0, v_0 \in P_h$ and $r \in (0, 1)$ such that

$$rv_0 \leq u_0 < v_0, \quad (4)$$

$$u_0 \leq A(u_0, v_0) + Bu_0 \leq A(v_0, u_0) + Bv_0 \leq v_0;$$

- (3) the operator equation $A(x, x) + Bx = x$ has a unique solution x^* in P_h ;

- (4) for any initial values $x_0, y_0 \in P_h$, constructing successively the sequences

$$\begin{aligned} x_n &= A(x_{n-1}, y_{n-1}) + Bx_{n-1}, \\ y_n &= A(y_{n-1}, x_{n-1}) + By_{n-1}, \\ n &= 1, 2, \dots, \end{aligned} \quad (5)$$

one has $x_n \rightarrow x^*$ and $y_n \rightarrow x^*$ as $n \rightarrow \infty$.

3. Existence and Uniqueness of Positive Solutions

In this section, we will apply Lemmas 4 and 5 to study the problem (1), and we obtain some new results on the existence and uniqueness of positive solutions. The method used here is relatively new to the literature and so are the existence and uniqueness results of the nonlinear parabolic partial differential equations.

In our considerations, we work in the Banach space $E = C(\overline{Q_T}) = \{u : \overline{Q_T} \rightarrow \mathbf{R} \text{ is continuous}\}$ with the standard norm $\|u\| = \max\{|u(x, t)| : (x, t) \in \overline{Q_T}\}$. Notice that this space can be equipped with a partial order given by

$$u, v \in E, \quad u \leq v \iff u(x, t) \leq v(x, t), \quad (x, t) \in \overline{Q_T}. \quad (6)$$

Set $P = \{u \in C(\overline{Q_T}) \mid u(x, t) \geq 0, (x, t) \in \overline{Q_T}\}$, as the standard cone. It is clear that P is a normal cone in $C(\overline{Q_T})$ and the normality constant is 1.

The following assumptions on the nonlinear functions $f(x, u, v)$ and $g(x, u)$ are as follows:

- (H₁) $f : [0, T] \times [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is continuous and $g : [0, T] \times [0, +\infty) \rightarrow [0, +\infty)$ is continuous;
- (H₂) $f(t, u, v)$ is increasing in $u \in [0, +\infty)$, for fixed $t \in [0, T]$ and $v \in [0, +\infty)$, and decreasing in $v \in [0, +\infty)$, for fixed $t \in [0, T]$ and $u \in [0, +\infty)$, and $g(t, u)$ is increasing in $u \in [0, +\infty)$, for fixed $t \in [0, T]$;
- (H₃) $g(t, \lambda u) \geq \lambda g(t, u)$, for $\lambda \in (0, 1)$, $t \in [0, T]$, and $u \in [0, +\infty)$, and there exists a constant $\beta \in (0, 1)$ such that $f(t, \lambda u, \lambda^{-1}v) \geq \lambda^\beta f(t, u, v)$, $\forall t \in [0, T]$, $\lambda \in (0, 1)$, $u, v \in [0, +\infty)$;
- (H₄) there exists a constant $\delta_0 > 0$ such that $f(t, u, v) \geq \delta_0 g(t, u)$, $t \in [0, T]$, $u, v \geq 0$;
- (H₅) $\min_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi) > 0$, $\min_{(x,t) \in \overline{Q_T}} g(t, \varphi) > 0$, where φ is the positive solution of the equation

$$u_t - \Delta u = 1, \quad (x, t) \in \Omega \times (0, T), \quad (7)$$

$$u(x, t) = 0, \quad (x, t) \in \Omega \times \{0\} \cup \partial\Omega \times (0, T);$$

that is, $\varphi(x, t) \geq 0$ for $(x, t) \in \overline{Q_T}$. The existence of φ follows from Theorem 7 in [17, Chapter 7].

Theorem 6. Assume that (H₁)-(H₅) are satisfied. Then the nonlinear parabolic partial differential equation (1) has a unique positive solution u^* in P_φ .

Proof. We divide the proof into three steps.

Step 1. By the existence and uniqueness of linear parabolic partial differential equations, we consider the operator $A : E \times E \rightarrow E$ as the solution of (8) for given $u, v \in P_\varphi$ as follows:

$$\begin{aligned} \frac{\partial A(u, v)}{\partial t} - \Delta A(u, v) &= f(t, u, v) \quad \text{in } Q_T, \\ A(u, v) &= 0 \quad \text{on } \Omega \times \{0\} \cup \partial\Omega \times (0, T). \end{aligned} \quad (8)$$

Indeed, for $t \in [0, T]$, $u, v \in E$, we have $f(t, u, v) \in L^n(\overline{Q_T})$. From the regularity theory of the heat equation, we conclude that $A(u, v) \in W^{2,1}(\overline{Q_T})$, and there exists some $\alpha > 0$ such that $W^{2,1}(\overline{Q_T}) \subset C^{2\alpha, \alpha}(\overline{Q_T})$, so the operator $A(u, v)$ is well defined as the solution of (8) for given $u, v \in P_\varphi$. For $u, v \in P_\varphi$, $\exists r_u, r_v \in (0, 1)$ such that

$$\begin{aligned} r_u \varphi(x, t) &\leq u(x, t) \leq \frac{1}{r_u} \varphi(x, t), \\ r_v \varphi(x, t) &\leq v(x, t) \leq \frac{1}{r_v} \varphi(x, t), \end{aligned} \quad (9)$$

for $(x, t) \in \overline{Q_T}$. Let $r_0 = \min\{r_u, r_v\}$. Then from (H₃),

$$\begin{aligned} f(t, u(x, t), v(x, t)) &\geq f\left(t, r_0 \varphi(x, t), \frac{1}{r_0} \varphi(x, t)\right) \\ &\geq r_0^\beta f(t, \varphi(x, t), \varphi(x, t)), \\ f(t, u(x, t), v(x, t)) &\leq f\left(t, \frac{1}{r_0} \varphi(x, t), r_0 \varphi(x, t)\right) \\ &\leq \frac{1}{r_0^\beta} f(t, \varphi(x, t), \varphi(x, t)), \end{aligned} \quad (10)$$

for $(x, t) \in \overline{Q_T}$, $u, v \in P_\varphi$. By (H₃) and the above inequalities, we have

$$\begin{aligned} \frac{\partial A(u, v)}{\partial t} - \Delta A(u, v) &= f(t, u, v) \geq r_0^\beta f(t, \varphi, \varphi) \geq r_0^\beta \min_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi) \\ &= r_0^\beta \min_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi) \left(\frac{\partial \varphi}{\partial t} - \Delta \varphi \right), \\ \frac{\partial A(u, v)}{\partial t} - \Delta A(u, v) &\leq \frac{1}{r_0^\beta} f(t, \varphi, \varphi) \leq \frac{1}{r_0^\beta} \max_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi) \\ &= \frac{1}{r_0^\beta} \max_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi) \left(\frac{\partial \varphi}{\partial t} - \Delta \varphi \right), \end{aligned} \quad (11)$$

for $(x, t) \in Q_T$, $u, v \in P_\varphi$. By the comparison principle for parabolic partial differential equations [18, Lemma 3.1.8, page 108], we know that

$$\frac{1}{r_0^\beta} \max_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi) \varphi \geq A(u, v) \geq r_0^\beta \min_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi) \varphi \geq 0, \quad (12)$$

for $u, v \in P_\varphi$, which is satisfied by (H₅). So $A : P_\varphi \times P_\varphi \rightarrow P$.

Let $r_1 = r_0^\beta \min_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi)$ and $r_2 = (1/r_0^\beta) \max_{(x,t) \in \overline{Q_T}} f(t, \varphi, \varphi)$; we get that $r_2 \varphi \geq A(u, v) \geq r_1 \varphi$ for $u, v \in P_\varphi$; that is, $A(\varphi, \varphi) \in P_\varphi$. By (H₂), we have

$$\begin{aligned} \frac{\partial A_u(u, v)}{\partial t} - \Delta A_u(u, v) &= f_u(t, u, v) \geq 0, \\ \frac{\partial A_v(u, v)}{\partial t} - \Delta A_v(u, v) &= f_v(t, u, v) \leq 0, \end{aligned} \quad (13)$$

for $(x, t) \in Q_T$, $u, v \in P_\varphi$. Also, by the comparison principle for parabolic partial differential equations, we observe that $A_u \geq 0, A_v \leq 0$; that is, A is a mixed monotone operator. Moreover, by (H₃), we have

$$\begin{aligned} \frac{\partial A(\lambda u, \lambda^{-1} v)}{\partial t} - \Delta A(\lambda u, \lambda^{-1} v) &= f(t, \lambda u, \lambda^{-1} v) \geq \lambda^\beta f(t, u, v) \\ &= \frac{\partial (\lambda^\beta A(u, v))}{\partial t} - \Delta (\lambda^\beta A(u, v)), \end{aligned} \quad (14)$$

for $(x, t) \in Q_T$, $u, v \in P_\varphi$. Also, by the comparison principle for parabolic partial differential equations, we conclude that $A(\lambda u, \lambda^{-1} v) \geq \lambda^\beta A(u, v)$, for $u, v \in P_\varphi$.

Step 2. Similar to Step 1, we can also construct the operator $B : E \rightarrow E$ as the solution of (15) for given $u \in P_\varphi$:

$$\begin{aligned} \frac{\partial Bu}{\partial t} - \Delta Bu &= g(t, u) \quad \text{in } Q_T, \\ Bu &= 0 \quad \text{on } \Omega \times \{0\} \cup \partial\Omega \times (0, T), \end{aligned} \quad (15)$$

and we get the fact that the operator Bu is well defined as the solution of (15) for given $u \in P_\varphi$. From (H₃), we get

$$\begin{aligned} g(t, u(x, t)) &\geq g(t, r_0 \varphi(x, t)) \geq r_0 g(t, \varphi(x, t)), \\ g(t, u(x, t)) &\leq g\left(t, \frac{1}{r_0} \varphi(x, t)\right) \leq \frac{1}{r_0} g(t, \varphi(x, t)), \end{aligned} \quad (16)$$

for $(x, t) \in \overline{Q_T}$, $u \in P_\varphi$. By (H_3) and the above inequalities, we have

$$\begin{aligned} \frac{\partial Bu}{\partial t} - \Delta Bu &= g(t, u) \\ &\geq r_0 g(t, \varphi) \geq r_0 \min_{(x,t) \in \overline{Q_T}} g(t, \varphi) \\ &= r_0 \min_{(x,t) \in \overline{Q_T}} g(t, \varphi) \left(\frac{\partial \varphi}{\partial t} - \Delta \varphi \right), \\ \frac{\partial Bu}{\partial t} - \Delta Bu &= g(t, u) \\ &\leq \frac{1}{r_0} g(t, \varphi) \leq \frac{1}{r_0} \max_{(x,t) \in \overline{Q_T}} g(t, \varphi) \\ &= \frac{1}{r_0} \max_{(x,t) \in \overline{Q_T}} g(t, \varphi) \left(\frac{\partial \varphi}{\partial t} - \Delta \varphi \right), \end{aligned} \quad (17)$$

for $(x, t) \in Q_T$, $u \in P_\varphi$. Also, by the comparison principle for parabolic partial differential equations, we know that

$$\frac{1}{r_0} \max_{(x,t) \in \overline{Q_T}} g(t, \varphi) \varphi \geq Bu \geq r_0 \min_{(x,t) \in \overline{Q_T}} g(t, \varphi) \varphi \geq 0, \quad (18)$$

for $u \in P_\varphi$, which is satisfied by (H_5) . So $B : P_\varphi \rightarrow P$.

Let $r_3 = r_0 \min_{(x,t) \in \overline{Q_T}} g(t, \varphi)$ and $r_4 = (1/r_0) \max_{(x,t) \in \overline{Q_T}} g(t, \varphi)$; we get that $r_4 \varphi \geq Bu \geq r_3 \varphi$, where $u \in P_\varphi$; that is, $B\varphi \in P_\varphi$. By (H_2) , we have

$$\frac{\partial B_u u}{\partial t} - \Delta B_u u = g_u(t, u) \geq 0, \quad (19)$$

for $(x, t) \in Q_T$, $u \in P_\varphi$. By the comparison principle for parabolic partial differential equations, we observe that $B_u \geq 0$; that is, B is an increasing operator. Moreover, by (H_3) , we have

$$\begin{aligned} \frac{\partial B(\lambda u)}{\partial t} - \Delta B(\lambda u) &= g(t, \lambda u) \geq \lambda g(t, u) \\ &= \frac{\partial (\lambda Bu)}{\partial t} - \Delta (\lambda Bu), \end{aligned} \quad (20)$$

for $(x, t) \in Q_T$, $u \in P_\varphi$. By the comparison principle for parabolic partial differential equations, we conclude that $B(\lambda u) \geq \lambda Bu$, for $u \in P_\varphi$.

Step 3. By (H_4) , we have

$$\begin{aligned} \frac{\partial A(u, v)}{\partial t} - \Delta A(u, v) &= f(t, u, v) \geq \delta_0 g(t, u) \\ &= \frac{\partial (\delta_0 Bu)}{\partial t} - \Delta (\delta_0 Bu), \end{aligned} \quad (21)$$

for $(x, t) \in Q_T$, $u, v \in P_\varphi$. By the comparison principle for parabolic partial differential equations, we know that $A(u, v) \geq \delta_0 Bu$, where $u, v \in P_\varphi$.

Therefore, the operators A and B satisfy all the conditions in Lemma 4. Thus, the operator equation $A(u, u) + Bu = u$ has a unique solution u^* in P_φ . By

$$\begin{aligned} \frac{\partial u^*}{\partial t} &= \frac{\partial A(u^*, u^*)}{\partial t} + \frac{\partial Bu^*}{\partial t} \\ &= (\Delta A(u^*, u^*) + f(t, u^*, u^*)) + (\Delta Bu^* + g(t, u^*)) \\ &= 2\Delta u^* + f(t, u^*, u^*) + g(t, u^*), \\ &\quad (x, t) \in \Omega \times (0, T), \\ u^* &= A(u^*, u^*) + Bu^* = 0, \\ &\quad (x, t) \in \Omega \times \{0\} \cup \partial\Omega \times (0, T), \end{aligned} \quad (22)$$

we obtain that the nonlinear parabolic partial differential equation (1) has a unique positive solution u^* in P_φ . The proof is complete. \square

Further, we make some other assumptions on the nonlinear functions $f(t, u, v)$ and $g(t, u)$:

- (H_6) there exists a constant $\beta \in (0, 1)$ such that $g(t, \lambda u) \geq \lambda^\beta g(t, u)$, $\forall t \in [0, T]$, $\lambda \in (0, 1)$, $u \in [0, +\infty)$, and $f(t, \lambda u, \lambda^{-1}v) \geq \lambda f(t, u, v)$, for $\lambda \in (0, 1)$, $t \in [0, T]$, $u, v \in [0, +\infty)$;
- (H_7) there exists a constant $\delta_0 > 0$ such that $f(t, u, v) \leq \delta_0 g(t, u)$, $t \in [0, T]$, $u, v \geq 0$.

By using Lemma 5, we can also easily prove the following conclusion.

Theorem 7. Assume that (H_1) , (H_2) , (H_5) , (H_6) , and (H_7) are satisfied. Then the nonlinear parabolic partial differential equation (1) has a unique positive solution u^* in P_φ .

4. An Example

We now present one example to illustrate Theorem 6.

Example 1. Consider the following parabolic partial differential equation:

$$\begin{aligned} u_t - 2\Delta u &= u^{1/2} + (u+1)^{-1/3} + \frac{u}{u+1} a(t) \\ &\quad + b(t) + c, \quad (x, t) \in \Omega \times (0, 1), \end{aligned} \quad (23)$$

$$u(x, t) = 0, \quad (x, t) \in \Omega \times \{0\} \cup \partial\Omega \times (0, 1),$$

where $c > 0$ is a constant, $a, b : [0, 1] \rightarrow (0, +\infty)$ are continuous, and Ω is a bounded smooth domain in \mathbf{R}^n ; we denote $Q_1 = \Omega \times (0, 1)$. Set φ to be the positive solution of the following:

$$\begin{aligned} u_t - \Delta u &= 1, \quad (x, t) \in \Omega \times (0, 1), \\ u(x, t) &= 0, \quad (x, t) \in \Omega \times \{0\} \cup \partial\Omega \times (0, 1); \end{aligned} \quad (24)$$

that is, $\varphi(x, t) \geq 0$, for $(x, t) \in \overline{Q_1}$. We can conclude that the nonlinear parabolic partial differential equation (23) has a unique positive solution u^* in P_φ .

Proof. In this example, we take $0 < d < c$ and let

$$\begin{aligned} f(t, u, v) &= u^{1/2} + (v + 1)^{-1/3} + b(t) + d, \\ g(t, u) &= \frac{u}{u + 1} a(t) + c - d, \\ \beta &= \frac{1}{2}, \quad a^* = \max \{a(t) : t \in [0, 1]\}. \end{aligned} \quad (25)$$

Obviously, $a^* > 0$, $f : [0, 1] \times [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$ is continuous, and $g : [0, 1] \times [0, +\infty) \rightarrow [0, +\infty)$ is continuous. And $f(t, u, v)$ is increasing in $u \in [0, +\infty)$, for fixed $t \in [0, 1]$ and $v \in [0, +\infty)$, and decreasing in $v \in [0, +\infty)$, for fixed $t \in [0, 1]$ and $u \in [0, +\infty)$, and $g(t, u)$ is increasing in $u \in [0, +\infty)$, for fixed $t \in [0, 1]$. Besides, for $\lambda \in (0, 1)$, $t \in [0, 1]$, and $u, v \in [0, +\infty)$, we have

$$\begin{aligned} g(t, \lambda u) &= \frac{\lambda u}{\lambda u + 1} a(t) + c - d \\ &\geq \frac{\lambda u}{u + 1} a(t) + \lambda(c - d) = \lambda g(t, u), \\ f(t, \lambda u, \lambda^{-1} v) &= (\lambda u)^{1/2} + (\lambda^{-1} v + 1)^{-1/3} + b(t) + d \\ &\geq \lambda^{1/2} \left[u^{1/2} + (v + 1)^{-1/3} + b(t) + d \right] \\ &= \lambda^{1/2} f(t, u, v). \end{aligned} \quad (26)$$

Moreover, if we take $\delta_0 \in (0, d/(a^* + c - d))$, then we obtain

$$\begin{aligned} f(t, u, v) &= u^{1/2} + (v + 1)^{-1/3} + b(t) + d \geq d \\ &= \frac{d}{a^* + c - d} \cdot (a^* + c - d) \\ &\geq \delta_0 \left[\frac{u}{u + 1} a(t) + c - d \right] = \delta_0 g(t, u). \end{aligned} \quad (27)$$

Further, $\min_{(x,t) \in \overline{Q_1}} f(t, \varphi, \varphi) \geq d > 0$ and $\min_{(x,t) \in \overline{Q_1}} g(t, \varphi) \geq c - d > 0$.

Hence, all the conditions of Theorem 6 are satisfied. An application of Theorem 6 implies that the nonlinear parabolic partial differential equation (23) has a unique positive solution u^* in P_φ , where $P_\varphi = \{u \in C(\overline{Q_1}) \mid \text{there exist } \lambda = \lambda(u, \varphi), \mu = \mu(u, \varphi) > 0 \text{ such that } \lambda\varphi \leq u \leq \mu\varphi\}$. \square

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

Authors' Contribution

The authors declare that the study was realized in collaboration with the same responsibility. All authors read and approved the final paper.

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