## Research Article

# Existence of Solutions of Fractional Differential Equation with $p$-Laplacian Operator at Resonance 

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#### Abstract

By using the extension of Mawhin's continuation theorem due to Ge , we consider boundary value problems for fractional $p$ Laplacian equation. A new result on the existence of solutions for the fractional boundary value problem is obtained, which generalizes and enriches some known results to some extent from the literature.


## 1. Introduction and Preliminaries

Recently, fractional differential equations have played an important role in many fields such as physics, electrical circuits, and control theory (see [1-9]). Many scholars have paid more attention to boundary value problems for fractional differential equations (see [10-25]).

By using a fixed point theorem on a cone, Agarwal et al. (see [10]) considered a two-point boundary value problem at nonresonance given by

$$
\begin{gather*}
D_{0^{+}}^{\alpha} x(t)+f\left(t, x(t), D_{0^{+}}^{\mu} x(t)\right)=0,  \tag{1}\\
x(0)=x(1)=0,
\end{gather*}
$$

where $1<\alpha<2, \mu>0$ are real numbers, $\alpha-\mu \geq 1$, and $D_{0^{+}}^{\alpha}$ is the Riemann-Liouville fractional derivative.

By using the coincidence degree theory, Bai (see [20]) considered the following $m$-point fractional boundary value problems:

$$
\begin{gather*}
D_{0^{+}}^{\alpha} u(t)=f\left(t, u(t), D_{0^{+}}^{\alpha-1} u(t)\right)+e(t), \quad 0<t<1, \\
\left.I_{0^{+}}^{2-\alpha} u(t)\right|_{t=0}=0, \quad u(1)=\sum_{i=1}^{m-2} \beta_{i} u\left(\eta_{i}\right), \tag{2}
\end{gather*}
$$

where $1<\alpha \leq 2$ is a real number, $\beta_{i} \in \mathbb{R}, \eta_{i} \in(0,1)$ are given constants such that $\sum_{i=1}^{m-2} \beta_{i} \eta_{i}^{m-1}=1$, and $D_{0^{+}}^{\alpha}, I_{0^{+}}^{\alpha}$ are the Riemann-Liouville differentiation and integration.

The turbulent flow in a porous medium is a fundamental mechanics problem. For studying this type of problems, Leibenson (see [26]) introduced the $p$-Laplacian equation as follows:

$$
\begin{equation*}
\left(\phi_{p}\left(x^{\prime}(t)\right)\right)^{\prime}=f\left(t, x(t), x^{\prime}(t)\right) \tag{3}
\end{equation*}
$$

where $\phi_{p}(s)=|s|^{p-2} s, p>1$. Obviously, $\phi_{p}$ is invertible and its inverse operator is $\phi_{q}$, where $q>1$ is a constant such that $1 / p+1 / q=1$.

In the past few decades, many important results relative to (3) with certain boundary value conditions have been obtained. We refer the reader to [27-31] and the references cited therein. However, to the best of our knowledge, there are relatively few results on boundary value problems for fractional $p$-Laplacian equations.

Motivated by the work above, in this paper, we investigate the existence of solutions for boundary value problem (BVP for short) of fractional $p$-Laplacian equation with the following form:

$$
\begin{gather*}
D_{0^{+}}^{\beta} \phi_{p}\left(D_{0^{+}}^{\alpha} x(t)\right)=f\left(t, x(t), D_{0^{+}}^{\alpha} x(t)\right), \quad t \in[0,1]  \tag{4}\\
D_{0^{+}}^{\alpha} x(0)=D_{0^{+}}^{\alpha} x(1)=x^{\prime}(0)=0
\end{gather*}
$$

where $0<\beta \leq 1,1<\alpha \leq 2, D_{0^{+}}^{\alpha}$ is Caputo fractional derivative, and $f:[0,1] \times \mathbb{R}^{2} \rightarrow \mathbb{R}$ is continuous.

BVP (4) happens to be at resonance in the sense that its associated linear homogeneous boundary value problem

$$
\begin{gather*}
D_{0^{+}}^{\beta} \phi_{p}\left(D_{0^{+}}^{\alpha} x(t)\right)=0, \quad t \in[0,1]  \tag{5}\\
D_{0^{+}}^{\alpha} x(0)=D_{0^{+}}^{\alpha} x(1)=x^{\prime}(0)=0
\end{gather*}
$$

has a nontrivial solution $x(t)=c$, where $c \in \mathbb{R}$.
For the convenience of the reader, we present here some necessary basic knowledge and definitions about fractional calculus theory, which can be found, for instance, in [32-35].

Definition 1. The Riemann-Liouville fractional integral operator of order $\alpha>0$ of a function $x:(0,+\infty) \rightarrow \mathbb{R}$ is given by

$$
\begin{equation*}
I_{0^{+}}^{\alpha} x(t)=\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} x(s) d s \tag{6}
\end{equation*}
$$

provided that the right side integral is pointwise defined on ( $0,+\infty$ ).

Definition 2. The Caputo fractional derivative of order $\alpha>0$ of a continuous function $x:(0,+\infty) \rightarrow \mathbb{R}$ is given by

$$
\begin{equation*}
D_{0^{+}}^{\alpha} x(t)=I_{0^{+}}^{n-\alpha} \frac{d^{n} x(t)}{d t^{n}}=\frac{1}{\Gamma(n-\alpha)} \int_{0}^{t}(t-s)^{n-\alpha-1} x^{(n)}(s) d s \tag{7}
\end{equation*}
$$

where $n$ is the smallest integer greater than or equal to $\alpha$, provided that the right side integral is pointwise defined on $(0,+\infty)$.

Lemma 3. Assume that $D_{0^{+}}^{\alpha} x \in C[0,1], \alpha>0$. Then

$$
\begin{equation*}
I_{0^{+}}^{\alpha} D_{0^{+}}^{\alpha} x(t)=x(t)+c_{0}+c_{1} t+c_{2} t^{2}+\cdots+c_{n-1} t^{n-1} \tag{8}
\end{equation*}
$$

where $c_{i}=-x^{(i)}(0) / i!, i=0,1,2, \ldots, n-1$, and here $n$ is the smallest integer greater than or equal to $\alpha$.

Now, one briefly recalls some notations and an abstract existence result, which can be found in [36].

Definition 4. Let $X$ and $Y$ be two Banach spaces with norms $\|\cdot\|_{X}$ and $\|\cdot\|_{Y}$, respectively. A continuous operator

$$
\begin{equation*}
M: X \cap \operatorname{dom} M \longrightarrow Y \tag{9}
\end{equation*}
$$

is said to be quasilinear if
(i) $\operatorname{Im} M:=M(X \cap \operatorname{dom} M)$ is a closed subset of $Y$,
(ii) $\operatorname{Ker} M:=\{X \cap \operatorname{dom} M: M u=0\}$ is linearly homeomorphic to $\mathbb{R}^{n}, n<\infty$.

Definition 5. Let $X$ be a real Banach space and let $\widehat{X} \subset X$. The operator $P: X \rightarrow \widehat{X}$ is said to be a projector provided that $P^{2}=P, P\left(\lambda_{1} x_{1}+\lambda_{2} x_{2}\right)=\lambda_{1} P\left(x_{1}\right)+\lambda_{2} P\left(x_{2}\right)$ for $x_{1}, x_{2} \in X$ and $\lambda_{1}, \lambda_{2} \in \mathbb{R}$. The operator $Q: X \rightarrow \widehat{X}$ is said to be a semiprojector provided $Q^{2}=Q$.

Definition 6 (see [36]). Let $\widehat{X}=\operatorname{Ker} M$ and let $\widetilde{X}$ be the complement space of $\widehat{X}$ in $X$, and then $X=\widehat{X} \oplus \widetilde{X}$. On the other hand, suppose that $\widehat{Y}$ is a subspace of $Y$ and $\tilde{Y}$ is the complement space of $\widehat{Y}$ in $Y$ so that $Y=\widehat{Y} \oplus \widetilde{Y}$. Let $P: X \rightarrow \widehat{X}$ be a projector, let $Q: Y \rightarrow \widehat{Y}$ be a semiprojector, and let $\Omega \subset X$ be an open and bounded set with origin $\theta \in \Omega$, where $\theta$ is the origin of a linear space.

Suppose that $N_{\lambda}: \bar{\Omega} \rightarrow Y, \lambda \in[0,1]$, is a continuous operator. Denote $N_{1}$ by $N$. Let $\Sigma_{\lambda}=\left\{x \in \bar{\Omega}: M x=N_{\lambda} x\right\}$. $N_{\lambda}$ is said to be $M$-compact in $\bar{\Omega}$ if there is $\widehat{Y} \subset Y$ with $\operatorname{dim} \widehat{Y}$ $=\operatorname{dim} \widehat{X}$ and an operator $R: \bar{\Omega} \times[0,1] \rightarrow X$ continuous and compact such that, for $\lambda \in[0,1]$,

$$
\begin{gather*}
(I-Q) N_{\lambda}(\bar{\Omega}) \subset \operatorname{Im} M \subset(I-Q) Y  \tag{10}\\
Q N_{\lambda} x=\theta, \quad \lambda \in(0,1) \Longleftrightarrow Q N x=\theta \tag{11}
\end{gather*}
$$

$R(\cdot, 0)$ is the zero operator and $\left.R(\cdot, \lambda)\right|_{\Sigma_{\lambda}}=\left.(I-P)\right|_{\Sigma_{\lambda}}$,

$$
\begin{equation*}
M[P+R(\cdot, \lambda)]=(I-Q) N_{\lambda} . \tag{12}
\end{equation*}
$$

Lemma 7 (see [36] Ge-Mawhin's continuation theorem). Let $X$ and $Y$ be two Banach spaces with norms $\|\cdot\|_{X}$ and $\|\cdot\|_{Y}$, respectively. $\Omega \subset X$ is an open and bounded nonempty set. Suppose that

$$
\begin{equation*}
M: X \cap \operatorname{dom} M \longrightarrow Y \tag{14}
\end{equation*}
$$

is a quasilinear operator and

$$
\begin{equation*}
N_{\lambda}: \bar{\Omega} \longrightarrow Y, \quad \lambda \in[0,1] \tag{15}
\end{equation*}
$$

is $M$-compact in $\bar{\Omega}$. In addition, if

$$
\begin{aligned}
& \left(\mathrm{C}_{1}\right) M x \neq N_{\lambda} x, \forall(x, \lambda) \in(\operatorname{dom} M \cap \partial \Omega) \times(0,1) \\
& \left(\mathrm{C}_{2}\right) Q N x \neq 0, \text { for } x \in \operatorname{dom} M \cap \partial \Omega \\
& \left(\mathrm{C}_{3}\right) \operatorname{deg}(J Q N, \text { Ker } M \cap \Omega, 0) \neq 0
\end{aligned}
$$

where $N=N_{1}$, then the equation $M x=N x$ has at least one solution in $\bar{\Omega}$.

In this paper, we take $Y=C[0,1]$ with the norm $\|x\|_{\infty}=$ $\max _{t \in[0,1]}|x(t)|$ and $X=\left\{x \mid x, D_{0^{+}}^{\alpha} x \in Y\right\}$ with the norm $\|x\|_{X}=\max \left\{\|x\|_{\infty},\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty}\right\}$. By means of the linear functional analysis theory, we can prove that $X$ is a Banach space.

Define the operator $M: \operatorname{dom} M \subset X \rightarrow Y$ by

$$
\begin{equation*}
M x=D_{0^{+}}^{\beta} \phi_{p}\left(D_{0^{+}}^{\alpha} x\right) \tag{16}
\end{equation*}
$$

where

$$
\begin{align*}
\operatorname{dom} M=\{ & x \in X \mid D_{0^{+}}^{\beta} \phi_{p}\left(D_{0^{+}}^{\alpha} x\right) \in Y \\
& \left.D_{0^{+}}^{\alpha} x(0)=D_{0^{+}}^{\alpha} x(1)=x^{\prime}(0)=0\right\} \tag{17}
\end{align*}
$$

Define the operator $N: X \rightarrow Y$ by

$$
\begin{equation*}
N x(t)=f\left(t, x(t), D_{0^{+}}^{\alpha} x(t)\right), \quad \forall t \in[0,1] \tag{18}
\end{equation*}
$$

Then BVP (4) is equivalent to the operator equation. Consider

$$
\begin{equation*}
M x=N x, \quad x \in \operatorname{dom} M \tag{19}
\end{equation*}
$$

## 2. Main Result

We will always assume that the nonlinearity $f(t, u, v)$ will be retained:
$\left(\mathrm{H}_{1}\right)$ there exist nonnegative functions $a, b, c \in Y$ such that

$$
\begin{align*}
&|f(t, u, v)| \leq a(t)+b(t)|u|^{p-1}+c(t)|v|^{p-1}, \quad \forall t \in[0,1], \\
&(u, v) \in \mathbb{R}^{2} ; \tag{20}
\end{align*}
$$

$\left(\mathrm{H}_{2}\right)$ there exists a constant $B>0$ such that
either

$$
\begin{equation*}
u f(t, u, v)>0, \quad \forall t \in[0,1], v \in \mathbb{R},|u|>B \tag{21}
\end{equation*}
$$

or

$$
\begin{equation*}
u f(t, u, v)<0, \quad \forall t \in[0,1], v \in \mathbb{R},|u|>B . \tag{22}
\end{equation*}
$$

Moreover, we will always assume that $f:[0,1] \times \mathbb{R}^{2} \rightarrow \mathbb{R}$ is continuous and

$$
\begin{equation*}
\frac{1}{\Gamma(\beta+1)}\left(\frac{2\|b\|_{\infty}}{(\Gamma(\alpha+1))^{p-1}}+\|c\|_{\infty}\right)<1 \tag{23}
\end{equation*}
$$

Now, we begin with some lemmas below.
Lemma 8. Let $M$ be defined by (16), and then

$$
\begin{equation*}
\text { Ker } M=\{x \in X \mid x(t)=c \in \mathbb{R}, \forall t \in[0,1]\}, \tag{24}
\end{equation*}
$$

$$
\begin{equation*}
\operatorname{Im} M=\left\{y \in Y \mid \int_{0}^{1}(1-s)^{\beta-1} y(s) d s=0\right\} \tag{25}
\end{equation*}
$$

and $M$ is a quasilinear operator
Proof. By Lemma 3, $D_{0^{+}}^{\beta} \phi_{p}\left(D_{0^{+}}^{\alpha} x(t)\right)=0$ has solution:

$$
\begin{align*}
x(t) & =c_{0}+c_{1} t+I_{0^{+}}^{\alpha} \phi_{q}\left(c_{2}\right) \\
& =c_{0}+c_{1} t+\frac{\phi_{q}\left(c_{2}\right)}{\Gamma(\alpha+1)} t^{\alpha}, \quad c_{0}, c_{1}, c_{2} \in \mathbb{R} \tag{26}
\end{align*}
$$

which satisfies

$$
\begin{equation*}
D_{0^{+}}^{\alpha} x(t)=\phi_{q}\left(c_{2}\right) . \tag{27}
\end{equation*}
$$

Combining with the boundary value condition $D_{0^{+}}^{\alpha} x(0)=0$ and $x^{\prime}(0)=0$, we can get that (24) holds.

If $y \in \operatorname{Im} M$, then there exists a function $x \in \operatorname{dom} M$ such that $y(t)=D_{0^{+}}^{\beta} \phi_{p}\left(D_{0^{+}}^{\alpha} x(t)\right)$. Based on Lemma 3, we have

$$
\begin{align*}
D_{0^{+}}^{\alpha} x(t) & =\phi_{q}\left(I_{0^{+}}^{\beta} y(t)+c\right) \\
& =\phi_{q}\left(\frac{1}{\Gamma(\beta)} \int_{0}^{t}(t-s)^{\beta-1} y(s) d s+c\right), \quad c \in \mathbb{R} . \tag{28}
\end{align*}
$$

From condition $D_{0^{+}}^{\alpha} x(0)=0$, one has $c=0$. By the condition $D_{0^{+}}^{\alpha} x(1)=0$, we obtain that

$$
\begin{equation*}
\int_{0}^{1}(1-s)^{\beta-1} y(s) d s=0 . \tag{29}
\end{equation*}
$$

Thus, we get (25).
Then we have $\operatorname{dim} \operatorname{Ker} M=1$ and $M(\operatorname{dom} M \cap X) \subset Y$ closed. Therefore, $M$ is a quasilinear operator.

Lemma 9. Let $\Omega \subset X$ be an open and bounded set; then $N_{\lambda}$ is $M$-compact in $\bar{\Omega}$.

Proof. Define the continuous projector $P: X \rightarrow \widehat{X}$ and the semiprojector $Q: Y \rightarrow \widehat{Y}:$

$$
\begin{gather*}
P x(t)=x(0), \quad \forall t \in[0,1] \\
Q y(t)=\beta \int_{0}^{1}(1-s)^{\beta-1} y(s) d s, \quad \forall t \in[0,1] \tag{30}
\end{gather*}
$$

where $\widehat{X}=\operatorname{Ker} M$ and $\widehat{Y}=\operatorname{Im} Q$.
Obviously, $\operatorname{Im} P=\operatorname{Ker} M$ and $P^{2} x(t)=P x(t)$. It follows from $x=(x-P x)+P x$ that $X=\operatorname{Ker} P+\operatorname{Ker} M$. By a simple calculation, we can get Ker $M \cap \operatorname{Ker} P=\{0\}$. Then we get

$$
\begin{equation*}
X=\operatorname{Ker} M \oplus \operatorname{Ker} P=\widehat{X} \oplus \widetilde{X} \tag{31}
\end{equation*}
$$

By the definition of $Q$, we can get

$$
\begin{equation*}
Q^{2} y=Q y \cdot \beta \int_{0}^{1}(1-s)^{\beta-1} d s=Q y \tag{32}
\end{equation*}
$$

Let $y=(y-Q y)+Q y$, where $y-Q y \in \operatorname{Ker} Q=\operatorname{Im} M$, $Q y \in \operatorname{Im} Q$. It follows from $\operatorname{Ker} Q=\operatorname{Im} M$ and $Q^{2} y=Q y$ that $\operatorname{Im} Q \cap \operatorname{Im} M=\{0\}$. Then, we have

$$
\begin{equation*}
Y=\operatorname{Im} Q \oplus \operatorname{Im} M=\widehat{Y} \oplus \widetilde{Y} \tag{33}
\end{equation*}
$$

Thus
$\operatorname{dim} \widehat{X}=\operatorname{dim} \operatorname{Ker} M=\operatorname{dim} \operatorname{Im} Q=\operatorname{dim} \widehat{Y}$.
Let $\Omega \subset X$ be an open and bounded set with $\theta \in \Omega$. For each $x \in \Omega$, we can get $Q\left[(I-Q) N_{\lambda} x\right]=0$. Thus, $(I-Q) N_{\lambda} x \in$ $\operatorname{Im} M=\operatorname{Ker} Q$. Take any $y \in \operatorname{Im} M$ in the type $y=(y-Q y)+$ $\mathrm{Q} y$. Since $\mathrm{Q} y=0$, we can get $(I-Q) y \in Y$. So (10) holds. It is easy to verify (11).

Furthermore, define $R: \bar{\Omega} \times[0,1] \rightarrow \widetilde{X}$ by

$$
\begin{align*}
& R(x, \lambda)(t) \\
& \begin{aligned}
&=\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} \phi_{q} \\
& \times\left(\frac{1}{\Gamma(\beta)} \int_{0}^{s}(s-\tau)^{\beta-1}\right. \\
&\left.\times\left((I-Q) N_{\lambda} x(\tau)\right) d \tau\right) d s
\end{aligned}
\end{align*}
$$

By the continuity of $f$, it is easy to get that $R(x, \lambda)$ is continuous on $\bar{\Omega} \times[0,1]$. Moreover, for all $x \in \bar{\Omega}$, there exists a constant $T>0$ such that $\left.\mid I_{0^{+}}^{\beta}(I-Q) N_{\lambda} x(\tau)\right) \mid \leq T$, so we can easily obtain that $R(\bar{\Omega}, \lambda)$ is uniformly bounded. By the Arzelà-Ascoli theorem, we just need to prove that $R: \bar{\Omega} \times[0,1] \rightarrow \widetilde{X}$ is equicontinuous. Furthermore, for $0 \leq t_{1}<t_{2} \leq 1,(x, \lambda) \in \bar{\Omega} \times[0,1]$, we have

$$
\begin{align*}
& \left|R(x, \lambda)\left(t_{2}\right)-R(x, \lambda)\left(t_{1}\right)\right| \\
& =\mid I_{0^{+}}^{\alpha} \phi_{q}\left(I_{0^{+}}^{\beta}(I-Q) N_{\lambda} x\left(t_{2}\right)\right)  \tag{36}\\
& \quad-I_{0^{+}}^{\alpha} \phi_{q}\left(I_{0^{+}}^{\beta}(I-Q) N_{\lambda} x\left(t_{1}\right)\right) \mid .
\end{align*}
$$

By $\left|I_{0^{+}}^{\beta}(I-Q) N_{\lambda} x\right| \leq T$, we have

$$
\begin{align*}
& \left|I_{0^{+}}^{\alpha} \phi_{q}\left(I_{0^{+}}^{\beta}(I-Q) N_{\lambda} x\left(t_{2}\right)\right)-I_{0^{+}}^{\alpha} \phi_{q}\left(I_{0^{+}}^{\beta}(I-Q) N_{\lambda} x\left(t_{1}\right)\right)\right| \\
& \left.\leq \frac{1}{\Gamma(\alpha)} \right\rvert\, \int_{0}^{t_{2}}\left(t_{2}-s\right)^{\alpha-1} \phi_{q}\left(I_{0^{+}}^{\beta}(I-Q) N_{\lambda} x(s)\right) d s \\
& \quad-\int_{0}^{t_{1}}\left(t_{1}-s\right)^{\alpha-1} \phi_{q}\left(I_{0^{+}}^{\beta}(I-Q) N_{\lambda} x(s)\right) d s \mid \\
& \leq \frac{\phi_{q}(T)}{\Gamma(\alpha)}\left[\int_{0}^{t_{1}}\left(t_{2}-s\right)^{\alpha-1}-\left(t_{1}-s\right)^{\alpha-1} d s\right. \\
& \left.\quad \quad+\int_{t_{1}}^{t_{2}}\left(t_{2}-s\right)^{\alpha-1} d s\right] \\
& =\frac{\phi_{q}(T)}{\Gamma(\alpha+1)}\left(t_{2}^{\alpha}-t_{1}^{\alpha}\right) . \tag{37}
\end{align*}
$$

Since $t^{\alpha}$ is uniformly continuous on $[0,1]$, so $R(\bar{\Omega}, \lambda)$ is equicontinuous. Similarly, we can get that $I_{0^{+}}^{\beta}((I-$ Q) $\left.N_{\lambda} x(\tau)\right) \subset C[0,1]$ is equicontinuous, and considering that $\phi_{q}(s)$ is uniformly continuous on $[-T, T]$, we get that $D_{0^{+}}^{\alpha} R(\bar{\Omega}, \lambda)=I_{0^{+}}^{\beta}\left((I-Q) N_{\lambda}(\bar{\Omega})\right)$ is also equicontinuous. So we can obtain that $R(\bar{\Omega}, \lambda) \rightarrow \widetilde{X}$ is compact.

For each $x \in \Sigma_{\lambda}=\left\{x \in \bar{\Omega}: M x=N_{\lambda} x\right\}$, we have $D_{0^{+}}^{\beta} \phi_{p}\left(D_{0^{+}}^{\alpha} x(t)\right)=N_{\lambda} x(t) \in \operatorname{Im} M$. Thus,

$$
\begin{aligned}
& R(x, \lambda)(t) \\
& \begin{aligned}
&=\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} \phi_{q} \\
& \times\left(\frac{1}{\Gamma(\beta)} \int_{0}^{s}(s-\tau)^{\beta-1}\right. \\
&\left.\times\left((I-Q) N_{\lambda} x(\tau)\right) d \tau\right) d s
\end{aligned}
\end{aligned}
$$

$$
\begin{align*}
& =\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} \phi_{q} \\
& \\
& \quad \times\left(\frac{1}{\Gamma(\beta)} \int_{0}^{s}(s-\tau)^{\beta-1}\right.  \tag{38}\\
& \\
& \left.\quad \times D_{0^{+}}^{\beta} \phi_{p}\left(D_{0^{+}}^{\alpha} x(\tau)\right) d \tau\right) d s
\end{align*}
$$

which together with $D_{0^{+}}^{\alpha} x(0)=x^{\prime}(0)=0$ yields that

$$
\begin{equation*}
R(x, \lambda)(t)=x(t)-x(0)=[(I-P) x](t) . \tag{39}
\end{equation*}
$$

It is easy to verify that $R(x, 0)(t)$ is the zero operator. So (12) holds.

On the other hand, consider

$$
\begin{align*}
& M[P x+R(x, \lambda)](t) \\
& \begin{aligned}
&=M[ \frac{1}{\Gamma(\alpha)} \\
& \times \int_{0}^{t}(t-s)^{\alpha-1} \phi_{q}\left(\frac{1}{\Gamma(\beta)} \int_{0}^{s}(s-\tau)^{\beta-1}\right. \\
&\left.\times\left((I-Q) N_{\lambda} x(\tau)\right) d \tau\right) d s \\
&\quad+x(0)] \\
&=\left[\left((I-Q) N_{\lambda}\right) x\right](t) .
\end{aligned} \\
& \quad
\end{align*}
$$

So (13) holds. Then we get that $N_{\lambda}$ is $M$-compact in $\bar{\Omega}$. The proof is complete.

Lemma 10. Suppose that $\left(H_{1}\right),\left(H_{2}\right)$ hold; then the set

$$
\begin{equation*}
\Omega_{1}=\{x \in \operatorname{dom} M \backslash \operatorname{Ker} M \mid M x=\lambda N x, \lambda \in(0,1)\} \tag{41}
\end{equation*}
$$

is bounded.
Proof. Take $x \in \Omega_{1}$; then $M x=\lambda N x, D_{0^{+}}^{\alpha} x(0)=x^{\prime}(0)=0$, and $N x \in \operatorname{Im} M$. $\operatorname{By}$ (25), we have

$$
\begin{equation*}
\int_{0}^{1}(1-s)^{\beta-1} f\left(s, x(s), D_{0^{+}}^{\alpha} x(s)\right) d s=0 \tag{42}
\end{equation*}
$$

Then, by the integral mean value theorem, there exists a constant $\xi \in(0,1)$ such that $f\left(\xi, x(\xi), D_{0^{+}}^{\alpha} x(\xi)\right)=0$. So, from $\left(H_{2}\right)$, we get $|x(\xi)| \leq B$. By $x^{\prime}(0)=0$, we get

$$
\begin{align*}
x(t) & =x(0)+x^{\prime}(0) t+I_{0^{+}}^{\alpha} D_{0^{+}}^{\alpha} x(t) \\
& =x(0)+\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} D_{0^{+}}^{\alpha} x(s) d s . \tag{43}
\end{align*}
$$

Take $t=\xi$; we have

$$
\begin{equation*}
x(\xi)=x(0)+\frac{1}{\Gamma(\alpha)} \int_{0}^{\xi}(\xi-s)^{\alpha-1} D_{0^{+}}^{\alpha} x(s) d s \tag{44}
\end{equation*}
$$

Then we have

$$
\begin{align*}
|x(0)| & \leq|x(\xi)|+\frac{1}{\Gamma(\alpha)} \int_{0}^{\xi}(\xi-s)^{\alpha-1}\left|D_{0^{+}}^{\alpha} x(s)\right| d s \\
& \leq|x(\xi)|+\frac{1}{\Gamma(\alpha)}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty} \cdot \frac{1}{\alpha} \xi^{\alpha}  \tag{45}\\
& \leq B+\frac{1}{\Gamma(\alpha+1)}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty} .
\end{align*}
$$

So we get

$$
\begin{align*}
|x(t)| & \leq|x(0)|+\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1}\left|D_{0^{+}}^{\alpha} x(s)\right| d s \\
& \leq|x(0)|+\frac{1}{\Gamma(\alpha)}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty} \cdot \frac{1}{\alpha} t^{\alpha}  \tag{46}\\
& \leq B+\frac{2}{\Gamma(\alpha+1)}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty}, \quad \forall t \in[0,1]
\end{align*}
$$

That is,

$$
\begin{equation*}
\|x\|_{\infty} \leq B+\frac{2}{\Gamma(\alpha+1)}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty} \tag{47}
\end{equation*}
$$

By $M x=\lambda N x$ and $D_{0^{+}}^{\alpha} x(0)=0$, we get

$$
\begin{align*}
\phi_{p}\left(D_{0^{+}}^{\alpha} x(t)\right) & =\lambda I_{0^{+}}^{\beta} N x(t) \\
& =\frac{\lambda}{\Gamma(\beta)} \int_{0}^{t}(t-s)^{\beta-1} f\left(s, x(s), D_{0^{+}}^{\alpha} x(s)\right) d s \tag{48}
\end{align*}
$$

So, from $\left(H_{1}\right)$, we have

$$
\begin{align*}
&\left|\phi_{p}\left(D_{0^{+}}^{\alpha} x(t)\right)\right| \leq \frac{1}{\Gamma(\beta)} \int_{0}^{t}(t-s)^{\beta-1}\left|f\left(s, x(s), D_{0^{+}}^{\alpha} x(s)\right)\right| d s \\
& \leq \frac{1}{\Gamma(\beta)} \int_{0}^{t}(t-s)^{\beta-1}\left(a(s)+b(s)|x(s)|^{p-1}\right. \\
&\left.+c(s)\left|D_{0^{+}}^{\alpha} x(s)\right|^{p-1}\right) d s \\
& \leq \frac{1}{\Gamma(\beta)}\left(\|a\|_{\infty}+\|b\|_{\infty}\|x\|_{\infty}^{p-1}\right. \\
&\left.+\|c\|_{\infty}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty}^{p-1}\right) \cdot \frac{1}{\beta} t^{\beta} \\
& \leq \frac{1}{\Gamma(\beta+1)}\left(\|a\|_{\infty}+\|b\|_{\infty}\|x\|_{\infty}^{p-1}\right. \\
&\left.\quad+\|c\|_{\infty}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty}^{p-1}\right), \quad \forall t \in[0,1] \tag{49}
\end{align*}
$$

which together with $\left|\phi_{p}\left(D_{0^{+}}^{\alpha} x(t)\right)\right|=\left|D_{0^{+}}^{\alpha} x(t)\right|^{p-1}$ and (47) yields that

$$
\begin{align*}
\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty}^{p-1} \leq \frac{1}{\Gamma(\beta+1)}[ & \|a\|_{\infty}+\|b\|_{\infty} \\
& \times\left(B+\frac{2}{\Gamma(\alpha+1)}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty}\right)^{p-1} \\
& \left.+\|c\|_{\infty}\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty}^{p-1}\right] \tag{50}
\end{align*}
$$

In view of (23), we can see that there exists a constant $M_{1}>0$ such that

$$
\begin{equation*}
\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty} \leq M_{1} \tag{51}
\end{equation*}
$$

Thus, from (47), we get

$$
\begin{equation*}
\|x\|_{\infty} \leq B+\frac{2 M_{1}}{\Gamma(\alpha+1)}:=M_{2} \tag{52}
\end{equation*}
$$

Combining (51) with (52), we have

$$
\begin{equation*}
\|x\|_{X}=\max \left\{\|x\|_{\infty},\left\|D_{0^{+}}^{\alpha} x\right\|_{\infty}\right\} \leq \max \left\{M_{1}, M_{2}\right\}:=M . \tag{53}
\end{equation*}
$$

Therefore, $\Omega_{1}$ is bounded. The proof is complete.
Lemma 11. Suppose that $\left(\mathrm{H}_{2}\right)$ holds; then the set

$$
\begin{equation*}
\Omega_{2}=\{x \in \operatorname{Ker} M \mid N x \in \operatorname{Im} M\} \tag{54}
\end{equation*}
$$

is bounded.
Proof. For $x \in \Omega_{2}$, we have $x(t)=c, c \in \mathbb{R}$ and $N x \in \operatorname{Im} M$. Then we get

$$
\begin{equation*}
\int_{0}^{1}(1-s)^{\beta-1} f(s, c, 0) d s=0 \tag{55}
\end{equation*}
$$

which together with $\left(\mathrm{H}_{2}\right)$ implies $|c| \leq B$. Thus, we have

$$
\begin{equation*}
\|x\|_{X} \leq \max \{B, 0\}=B \tag{56}
\end{equation*}
$$

Hence, $\Omega_{2}$ is bounded. The proof is complete.
Lemma 12. Suppose that the first part of $\left(\mathrm{H}_{2}\right)$ holds; then the set

$$
\begin{equation*}
\Omega_{3}=\{x \in \operatorname{Ker} M \mid \lambda x+(1-\lambda) Q N x=0, \lambda \in[0,1]\} \tag{57}
\end{equation*}
$$

is bounded.
Proof. For $x \in \Omega_{3}$, we have $x(t)=c, c \in \mathbb{R}$, and

$$
\begin{equation*}
\lambda c+(1-\lambda) \beta \int_{0}^{1}(1-s)^{\beta-1} f(s, c, 0) d s=0 \tag{58}
\end{equation*}
$$

If $\lambda=0$, then $|c| \leq B$ because of the first part of $\left(\mathrm{H}_{2}\right)$. If $\lambda \in(0,1]$, we can also obtain $|c| \leq B$. Otherwise, if $|c|>B$, in view of the first part of $\left(\mathrm{H}_{2}\right)$, one has

$$
\begin{equation*}
\lambda c^{2}+(1-\lambda) \beta \int_{0}^{1}(1-s)^{\beta-1} c f(s, c, 0) d s>0 \tag{59}
\end{equation*}
$$

which contradicts (58). Therefore, $\Omega_{3}$ is bounded. The proof is complete.

Remark 13. If the second part of $\left(\mathrm{H}_{2}\right)$ holds, then the set

$$
\begin{equation*}
\Omega_{3}^{\prime}=\{x \in \operatorname{Ker} M-\lambda x+(1-\lambda) Q N x=0, \lambda \in[0,1]\} \tag{60}
\end{equation*}
$$

is bounded.
Theorem 14. Let $f:[0,1] \times \mathbb{R}^{2} \rightarrow \mathbb{R}$ be continuous. Suppose that $\left(H_{1}\right),\left(H_{2}\right)$ hold. Then BVP (4) has at least one solution.

Proof. Set $\Omega=\left\{x \in X \mid\|x\|_{X}<\max \{M, B\}+1\right\}$. It follows from Lemmas 8 and 9 that $M$ is a quasilinear operator and $N_{\lambda}$ is $M$-compact on $\bar{\Omega}$. By Lemmas 10 and 11 , we get that the following two conditions are satisfied:

$$
\begin{aligned}
& \left(\mathrm{C}_{1}\right) M x \neq N_{\lambda} x, \forall(x, \lambda) \in(\operatorname{dom} M \cap \partial \Omega) \times(0,1), \\
& \left(\mathrm{C}_{2}\right) Q N x \neq 0, \text { for } x \in \operatorname{dom} M \cap \partial \Omega
\end{aligned}
$$

Take

$$
\begin{equation*}
H(x, \lambda)= \pm \lambda x+(1-\lambda) Q N x \tag{61}
\end{equation*}
$$

According to Lemma 12 (or Remark 13), we know that $H(x, \lambda) \neq 0$ for $x \in \operatorname{Ker} M \cap \partial \Omega$. Therefore

$$
\begin{align*}
\operatorname{deg} & \left(\left.Q N\right|_{\operatorname{Ker} M}, \Omega \cap \operatorname{Ker} M, 0\right) \\
& =\operatorname{deg}(H(\cdot, 0), \Omega \cap \operatorname{Ker} M, 0) \\
& =\operatorname{deg}(H(\cdot, 1), \Omega \cap \operatorname{Ker} M, 0)  \tag{62}\\
& =\operatorname{deg}( \pm I, \Omega \cap \operatorname{Ker} M, 0) \neq 0 .
\end{align*}
$$

So the condition $\left(C_{3}\right)$ of Lemma 7 is satisfied. By Lemma 7, we can get that $M x=N x$ has at least one solution in dom $M \cap$ $\bar{\Omega}$. Therefore BVP (4) has at least one solution. The proof is complete.

## 3. Example

In this section, we will give an example to illustrate our main result.

Example 1. Consider the following BVP:

$$
\begin{align*}
& D_{0^{+}}^{3 / 4} \phi_{3}\left(D_{0^{+}}^{3 / 2} x(t)\right)=-\frac{25}{3}+\frac{1}{3} x^{2}(t) \\
&+t e^{-\left|D_{0^{+}}^{3 / 2} x(t)\right|}, \quad t \in[0,1]  \tag{63}\\
& D_{0^{+}}^{3 / 2} x(0)=D_{0^{+}}^{3 / 2} x(1)=x^{\prime}(0)=0
\end{align*}
$$

Corresponding to BVP (4), we get that $p=3, \alpha=3 / 2, \beta=$ $3 / 4$, and

$$
\begin{equation*}
f(t, u, v)=-\frac{25}{3}+\frac{1}{3} u^{2}+t e^{-|v|} \tag{64}
\end{equation*}
$$

Choose $a(t)=10, b(t)=1 / 3, c(t)=0, B=5$. By a simple calculation, we can get that $\|b\|_{\infty}=1 / 3,\|c\|_{\infty}=0$ and

$$
\begin{equation*}
\frac{1}{\Gamma(3 / 4+1)}\left(\frac{2 / 3}{(\Gamma(3 / 2+1))^{2}}+0\right)<1 \tag{65}
\end{equation*}
$$

Obviously, BVP (63) satisfies all conditions of Theorem 14. Hence, it has at least one solution.

## 4. Conclusions

In this paper, the boundary value problem for $p$-Laplacian equation at resonance is investigated. In view of the boundary value problem (4) is equivalent to the operator equation (19); we only need to find a fixed point of the operator equation (19). Firstly, we established the sufficient conditions of existence of boundary value problem for $p$-Laplacian equation. Then, by using the extension of Mawhin's continuation theorem due to Ge , we got the fixed point of operator equation (19).

## Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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