## Research Article

# Strong Global Attractors for 3D Wave Equations with Weakly Damping 

Fengjuan Meng ${ }^{1,2}$<br>${ }^{1}$ Department of Mathematics, Nanjing University, Nanjing 210093, China<br>${ }^{2}$ Department of Mathematics, Taizhou College, Nanjing Normal University, Taizhou 225300, China<br>Correspondence should be addressed to Fengjuan Meng, fjmengnju@163.com

Received 30 March 2012; Accepted 13 April 2012
Academic Editor: Shaoyong Lai
Copyright © 2012 Fengjuan Meng. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

We consider the existence of the global attractor $\mathcal{A}_{1}$ for the 3D weakly damped wave equation. We prove that $\mathcal{A}_{1}$ is compact in $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times H_{0}^{1}(\Omega)$ and attracts all bounded subsets of $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times H_{0}^{1}(\Omega)$ with respect to the norm of $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times H_{0}^{1}(\Omega)$. Furthermore, this attractor coincides with the global attractor in the weak energy space $H_{0}^{1}(\Omega) \times L^{2}(\Omega)$.

## 1. Introduction

Let $\Omega \subset R^{3}$ be a bounded domain with smooth boundary $\partial \Omega$. We consider the following weakly damped wave equation:

$$
\begin{equation*}
u_{t t}+\alpha u_{t}-\Delta u+\varphi(u)=f \quad \text { in } \Omega \times R^{+} \tag{1.1}
\end{equation*}
$$

with the boundary condition

$$
\begin{equation*}
\left.u\right|_{\partial \Omega}=0 \tag{1.2}
\end{equation*}
$$

and initial conditions:

$$
\begin{equation*}
u(\cdot, 0)=u_{0}, \quad u_{t}(\cdot, 0)=u_{1}, \quad \text { in } \Omega \tag{1.3}
\end{equation*}
$$

where $\alpha>0, \varphi$ is the nonlinear term, and $f$ is a given external forcing term.

Nonlinear wave equation of the type (1.1) arises as an evolutionary mathematical model in many branched of physics, for example, (i) modeling a continuous Josephson junction with $\varphi(u)=\beta \sin u$; (ii) modeling a relativistic quantum mechanics with $\varphi(u)=$ $|u|^{\gamma} u$. A relevant problem is to investigate the asymptotic dynamical behavior of these mathematical models. The understanding of the asymptotic behavior of dynamical systems is one of the most important problems of modern mathematical physics. One way to treat this problem is to analyse the existence of its global attractor.

The existence of global attractors for the classical wave equations in $H_{0}^{1}(\Omega) \times L^{2}(\Omega)$ and the regularities of the global attractors has been studied extensively in many monographs and lectures, for example, see [1-7] and references therein.

However, to our knowledge, the research about the stronger attraction of global attractors for the damped wave equations with respect to the norm of $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times$ $H_{0}^{1}(\Omega)$ is fewer, only has been found in [8-10]. In the above three papers, the global attractors in strong topological space $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times H_{0}^{1}(\Omega)$ were established, the attraction with respect to the norm of $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times H_{0}^{1}(\Omega)$ was proved by the asymptotic compactness of the operator semigroup.

Recently, we consider (1.1) in $n$ dimensional space where the nonlinear term $\varphi$ without polynomial growth is in [11].

In this paper, our aim is to prove the existence of a global attractor for (1.1) in strong topological space $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times H_{0}^{1}(\Omega)$ where the nonlinear term $\varphi$ with some polynomial growth. For simplicity, we consider the space dimension is 3, as we know, when the space dimension is lagerer than 3, the case is similar as in 3D, when the space dimension is 1 or 2 , the case is more easier. The attraction with respect to the norm of $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times H_{0}^{1}(\Omega)$ will be proved by a method different from [8-10]. Furthermore, this attractor coincides with the global attractor in the weak energy space $H_{0}^{1}(\Omega) \times L^{2}(\Omega)$.

The basic assumptions about the external forcing term $f$ and the nonlinear term $\varphi$ are as follows. Let $f \in L^{2}(\Omega)$ be independent of time, and let the nonlinear term $\varphi \in C^{1}(R, R)$ satisfy the following assumptions:

$$
\begin{gather*}
\liminf _{|s| \rightarrow \infty} \frac{\Phi(s)}{s^{2}} \geq 0, \quad \text { here } \Phi(s)=\int_{0}^{s} \varphi(\tau) d \tau  \tag{1.4}\\
\limsup _{|s| \rightarrow \infty} \frac{\left|\varphi^{\prime}(s)\right|}{s^{2}}=0 \tag{1.5}
\end{gather*}
$$

moreover, there exists a constant $C_{0}>0$ such that

$$
\begin{equation*}
\liminf _{|s| \rightarrow \infty} \frac{s \varphi(s)-C_{0} \Phi(s)}{s^{2}} \geq 0 \tag{1.6}
\end{equation*}
$$

Throughout this paper, we use the following notations. Let $\Omega$ be a bounded subset of $R^{n}$ with sufficiently smooth boundary, $A=-\Delta . V=H_{0}^{1}(\Omega), H=L^{2}(\Omega)$, and $D(A)=H^{2}(\Omega) \cap$ $H_{0}^{1}(\Omega)$ with the corresponding norms $\|u\|=\left(\int_{\Omega}|\nabla u(x)|^{2} d x\right)^{1 / 2},|u|=\left(\int_{\Omega}|u(x)|^{2} d x\right)^{1 / 2}$ and
$|\Delta u|=\left(\int_{\Omega}|\Delta u(x)|^{2} d x\right)^{1 / 2}$, respectively. The norms in $L^{p}(\Omega), 1 \leq p<\infty$ are denoted by $|u|_{p}=$ $\left(\int_{\Omega}|u|^{p} d x\right)^{1 / p}$, the scalar products of $V, H$ are denoted by

$$
\begin{equation*}
((u, v))=\int_{\Omega} \nabla u(x) \nabla v(x) d x, \quad(u, v)=\int_{\Omega} u(x) v(x) d x \tag{1.7}
\end{equation*}
$$

respectively. We have $D(A) \subset V \subset H=H^{*} \subset V^{*}, H^{*}$ and $V^{*}$ are the dual spaces of $H$ and $V$, respectively, and each space is dense in the following one and the injections are continuous. Then, we introduce the product Hilbert spaces $\mathscr{H}_{0}=V \times H=H_{0}^{1}(\Omega) \times L^{2}(\Omega), \mathscr{H}_{1}=D(A) \times V=$ $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right) \times H_{0}^{1}(\Omega)$, endowed with the standard product norms:

$$
\begin{equation*}
\left\|\left\{u_{1}, u_{2}\right\}\right\|_{\mathscr{A}_{0}}^{2}=\left\|u_{1}\right\|_{V}^{2}+\left\|u_{2}\right\|_{H^{\prime}}^{2} \quad\left\|\left\{u_{1}, u_{2}\right\}\right\|_{\mathscr{L}_{1}}^{2}=\left\|u_{1}\right\|_{D(A)}^{2}+\left\|u_{2}\right\|_{V}^{2} \tag{1.8}
\end{equation*}
$$

Denote by $C$ any positive constant which may be different from line to line and even in the same line, we also denote the different positive constants by $C_{i}, i \in \mathbb{N}$, for special differentiation.

The rest of the paper is organized as follows. In the next section, for the convenience of the reader, we recall some basic concepts about the global attractors and recapitulate some abstract results. In Section 3, we present our main results.

## 2. Preliminaries

In this section, we first recall some basic concepts and theorems, which are important for getting our main results. We refer to $[2,5,6,12,13]$ and the references therein for more details. Then, we outline some known results about (1.1)-(1.3).

Definition 2.1. The mappings $S(t)$, where $S: X \times[0,+\infty) \rightarrow X$, is said to be a $C^{0}$ semigroup on $X$, if $\{S(t)\}_{t \geq 0}$ satisfies
(1) $S(0) u=u$ for all $u \in X$;
(2) $S\left(t_{1}\right)\left(S\left(t_{2}\right) u\right)=S\left(t_{1}+S_{2}\right)(u)$ for all $u \in X$ and $t_{1}, t_{2} \in R^{+}$;
(3) the mapping $S: X \times(0, \infty) \rightarrow X$ is continuous.

Definition 2.2. Let $\{S(t)\}_{t \geq 0}$ be a semigroup on a metric space $(E, d)$. A subset $\mathcal{A}$ of $E$ is called a global attractor for the semigroup, if $\mathcal{A}$ is compact and enjoys the following properties:
(1) $\mathcal{A}$ is invariant, that is, $S(t) \mathcal{A}=\mathcal{A}$, for all $t \geq 0$;
(2) $A$ attracts all bounded sets of $E$. That is, for any bounded subset $B$ of $E$,

$$
\begin{equation*}
d(S(t) B, \mathcal{A}) \longrightarrow 0, \quad \text { as } t \longrightarrow 0 \tag{2.1}
\end{equation*}
$$

where $d(B, A)$ is the semidistance of two sets $B$ and $A$ :

$$
\begin{equation*}
d(B, A)=\sup _{x \in B} \inf _{y \in A} d(x, y) \tag{2.2}
\end{equation*}
$$

Definition 2.3. A $C^{0}$ semigroup $\{S(t)\}_{t \geq 0}$ in a Banach space $X$ is said to satisfy the condition $(C)$ if for any $\varepsilon>0$ and for any bounded set $B$ of $X$, there exist $t(B)>0$ and a finite dimensional subspace $X_{1}$ of $X$ such that $\left\{\|P S(t) x\|_{X}, x \in B, t \geq t(B)\right\}$ is bounded and

$$
\begin{equation*}
\|(I-P) S(t) x\|_{X}<\varepsilon, \quad t \geq t(B), x \in B \tag{2.3}
\end{equation*}
$$

where $P: X \rightarrow X_{1}$ is a bounded projector.
Definition 2.4. Let $\{S(t)\}_{t \geq 0}$ be a semigroup on a metric space $(E, d)$. A set $B_{0} \subset E$ is called an absorbing set for the semigroup $\{S(t)\}_{t \geq 0}$, if and only if for every bounded set $B \subset E$, there exists a $T_{0}=T_{0}(B)>0$ such that $S(t) B \subset B_{0}$ for all $t \geq T_{0}$.

Theorem 2.5. Let $X$ be a Banach space and let $\{S(t)\}_{t \geq 0}$ be a $C^{0}$ semigroup in $X$. Then, there is a global attractor for $\{S(t)\}_{t \geq 0}$ in $X$ if the following conditions hold true:
(1) $\{S(t)\}_{t \geq 0}$ satisfies the condition (C), and
(2) there is a bounded absorbing set $B \subset X$.

In [12], the authors have discussed the relations between Condition $(C)$ and $\omega$-limit compact and proved that, in uniformly convex Banach space, Condition $(C)$ is equivalent to $\omega$-limit compact, if the semigroup has a bounded absorbing set.

Next, we recall the result about the global attractor in $\mathscr{H}_{0}$ whose proofs are omitted here, the reader is referred to [6] and the reference therein.

Theorem 2.6. Under the conditions (1.4), (1.5), (1.6), the solution semigroup $\{S(t)\}_{t \geq 0}$ of the problem (1.1)-(1.3) has a global attractor $\mathscr{A}_{0}$ in $\mathscr{H}_{0} \cdot \mathscr{A}_{0}$ is included and bounded in $\mathscr{H}_{1}$.

## 3. Main Results

According to the standard Fatou-Galerkin method, it is easy to obtain the existence and uniqueness of solutions and the continuous dependence to the initial value of (1.1)-(1.3). We address the reader to [6] and the reference therein. Here, we only state the result as follows.

Lemma 3.1. Let conditions (1.4), (1.5), (1.6) hold, then for any $T>0$ and $\left(u_{0}, u_{1}\right) \in \mathscr{H}_{0}$, there exists a unique solution of (1.1)-(1.3) such that

$$
\begin{equation*}
\left\{u, u_{t}\right\} \in C\left([0, T] ; \mathscr{H}_{0}\right) \tag{3.1}
\end{equation*}
$$

If, furthermore,

$$
\begin{equation*}
\left(u_{0}, u_{1}\right) \in \mathscr{A}_{1} \tag{3.2}
\end{equation*}
$$

then $u$ satisfies

$$
\begin{equation*}
\left\{u, u_{t}\right\} \in C\left([0, T] ; \mathscr{H}_{1}\right) \tag{3.3}
\end{equation*}
$$

We define the mappings:

$$
\begin{equation*}
S(t):\left\{u_{0}, u_{1}\right\} \longrightarrow\left\{u(t), u_{t}(t)\right\} \quad \forall t \in R . \tag{3.4}
\end{equation*}
$$

By Lemma 3.1, it is easy to see that $\{S(t)\}_{t \geq 0}$ is $C_{0}$ semigroup in the energy phase spaces $\mathscr{H}_{0}$ and $\mathscr{H}_{1}$.

In order to verify the existence of the bounded absorbing set in $\mathscr{H}_{1}$, we need the result about the existence of the bounded absorbing set in $\mathscr{H}_{0}$. First, we establish the bounded absorbing set in $\mathscr{H}_{0}$. Its proof is essentially established in [6] and the reference therein, and we only need to make a few minor changes for our problem. Here, we only give the following lemma.

Lemma 3.2. Under the conditions (1.4), (1.5), (1.6), $\{S(t)\}_{t \geq 0}$ has a bounded absorbing set $\mathcal{B}_{0} \triangleq$ $B_{\mathscr{H}_{0}}\left(0, \rho_{0}\right)$ in $\mathscr{H}_{0}$, that is, for any $\varepsilon>0$ and any bounded subset $B_{0} \subset \mathscr{H}_{0}$, there is a positive constant $t_{0}=t\left(B_{0}, \rho_{0}\right)$ such that

$$
\begin{equation*}
S(t) B \subset B_{0} \quad \text { for any } t \geq t_{0}, u_{0}, u_{1} \in B_{0} \tag{3.5}
\end{equation*}
$$

Next, let us establish the existence of the bounded absorbing set in $\mathscr{H}_{1}$.
Lemma 3.3. Under the conditions (1.4), (1.5), (1.6), $\{S(t)\}_{t \geq 0}$ has a bounded absorbing set $\mathbb{B} \triangleq$ $B_{\mathscr{H}_{1}}\left(0, \rho_{1}\right)$ in $\mathscr{H}_{1}$, that is, for any $\varepsilon>0$ and any bounded subset $B \subset \mathscr{H}_{1}$, there is a positive constant $T=T\left(B, \rho_{1}\right)$ such that

$$
\begin{equation*}
S(t) B \subset B \quad \text { for any } t \geq T, u_{0}, u_{1} \in B \tag{3.6}
\end{equation*}
$$

Proof. Take the scalar product in $H$ of (1.1) with $A v=A u_{t}+\sigma A u$, we have

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t}\left(|A u|^{2}+\|v\|^{2}\right)+\sigma|A u|^{2}+(\alpha-\sigma)\|v\|^{2}-\sigma(\alpha-\sigma)(A u, v)+(\varphi(u), A v)=(f, A v) \tag{3.7}
\end{equation*}
$$

For $0<\sigma \leq \sigma_{0}, \sigma_{0}=\left\{\alpha / 4, \lambda_{1} / 2 \alpha\right\}$, by Hölder inequality, Poincaré inequality, and Cauchy inequality we have

$$
\begin{align*}
\sigma|A u|^{2} & +(\alpha-\sigma)\|v\|^{2}-\sigma(\alpha-\sigma)(A u, v) \\
& \geq \sigma|A u|^{2}+(\alpha-\sigma)\|v\|^{2}-\frac{\sigma(\alpha-\sigma)}{\sqrt{\lambda_{1}}}|A u|\|v\| \\
& \geq \sigma|A u|^{2}+\frac{3}{4} \alpha\|v\|^{2}-\frac{\sigma \alpha}{\sqrt{\lambda_{1}}}|A u|\|v\|  \tag{3.8}\\
& \geq \sigma|A u|^{2}+\frac{3}{4} \alpha\|v\|^{2}-\left(\frac{\sigma}{2}|A u|^{2}+\frac{\sigma \alpha^{2}}{2 \lambda_{1}}\|v\|^{2}\right) \\
& \geq \frac{\sigma}{2}|A u|^{2}+\frac{\alpha}{2}\|v\|^{2} .
\end{align*}
$$

It follows from (1.5) that, for any $\varepsilon>0$, there exists a constant $C_{1}>0$, such that

$$
\begin{equation*}
\left|\varphi^{\prime}(s)\right| \leq \varepsilon|s|^{2}+C_{1}, \quad \forall s \in \mathbb{R} \tag{3.9}
\end{equation*}
$$

Hence,

$$
\begin{align*}
& |((\varphi(u), v))| \\
& \quad=\left|\int_{\Omega} \varphi^{\prime}(u) \cdot \nabla u \cdot \nabla v\right| d x \\
& \quad \leq \int_{\Omega}\left|\varphi^{\prime}(u)\right| \cdot|\nabla u| \cdot|\nabla v| d x \\
& \quad \leq \varepsilon \int_{\Omega}|u|^{2} \cdot|\nabla u| \cdot|\nabla v| d x+C_{1} \int_{\Omega}|\nabla u| \cdot|\nabla v| d x  \tag{3.10}\\
& \quad \leq \varepsilon\left(\int_{\Omega}|u|^{4} \cdot|\nabla u|^{2} d x\right)^{1 / 2} \cdot\|v\|+C_{1}\|u\| \cdot\|v\| \\
& \quad \leq \varepsilon\left(\int_{\Omega}|u|^{6} d x\right)^{1 / 3} \cdot\left(\int_{\Omega}|\nabla u|^{6} d x\right)^{1 / 6} \cdot\|v\|+C_{1}\|u\| \cdot\|v\| \\
& \quad \leq \varepsilon\|u\|^{2} \cdot C_{2}^{2} \cdot|A u| \cdot\|v\|+\frac{\alpha}{16}\|v\|^{2}+\frac{4 C_{1}^{2}}{\alpha}\|u\|^{2}
\end{align*}
$$

where $C_{2}$ is the positive constant satisfying

$$
\begin{gather*}
C_{2}\|u\|^{2} \geq\left(\int_{\Omega}|u|^{6} d x\right)^{1 / 3}, \\
C_{2}|A u| \geq\left(\int_{\Omega}|\nabla u|^{6} d x\right)^{1 / 6},  \tag{3.11}\\
(f, A v)=\frac{d}{d t}(f, A u)+\sigma(f, A u) \leq \frac{d}{d t}(f, A u)+\frac{\sigma}{8}|A u|^{2}+2 \sigma|f|^{2} \tag{3.12}
\end{gather*}
$$

If $\left(u_{0}, v_{0}\right)$ belongs to a bounded set $B$ of $\mathscr{H}_{1}$, then $B$ is also bounded in $\mathscr{H}_{0}$, and for $t \geq t_{0}$, by Lemma 3.2, we have

$$
\begin{equation*}
\|u\|^{2}+\left|u_{t}\right|^{2} \leq \rho_{0}^{2} \tag{3.13}
\end{equation*}
$$

$t_{0}, \rho_{0}$ are given in Lemma 3.2 Choose

$$
\begin{equation*}
0<\varepsilon^{2} \leq \frac{\alpha \sigma}{16 \rho_{0}^{4} C_{2}^{4}} \tag{3.14}
\end{equation*}
$$

it follows from (3.10) that

$$
\begin{align*}
|((\varphi(u), v))| & \leq \frac{\alpha}{8}\|v\|^{2}+\frac{4 \varepsilon^{2}}{\alpha}\|u\|^{4} C_{2}^{4}|A u|^{2}+\frac{4 C_{1}^{2}}{\alpha} \\
& \leq \frac{\alpha}{8}\|v\|^{2}+\frac{\sigma}{4}|A u|^{2}+\frac{4 C_{1}^{2}}{\alpha} \rho_{0}^{2}, \quad t \geq t_{0} \tag{3.15}
\end{align*}
$$

Combining with (3.8), (3.12), and (3.15), by the Hölder inequality and the Young inequality, we deduce from that (3.7):

$$
\begin{equation*}
\frac{d}{d t}\left(|A u|^{2}+\|v\|^{2}-2(f, A u)\right)+\frac{\sigma}{4}|A u|^{2}+\frac{\alpha}{4}|v|^{2} \leq 4 \sigma|f|^{2}+\frac{8 C_{1}^{2}}{\alpha} \rho_{0}^{2} \tag{3.16}
\end{equation*}
$$

Let $y=|A u-f|^{2}+\|v\|^{2}$, from the above inequality, we can obtain

$$
\begin{align*}
\frac{d y}{d t}+\frac{\sigma}{8} y & \leq \frac{d y}{d t}+\frac{\sigma}{8}\left(|A u|^{2}+\|v\|^{2}+|f|^{2}\right)+\frac{\sigma}{4}|A u||f| \\
& =\frac{d y}{d t}+\frac{\sigma}{4}\left(|A u|^{2}+\|v\|^{2}\right)-\frac{\sigma}{8}\left(|A u|^{2}+\|v\|^{2}\right)+\frac{\sigma}{4}|A u||f|+\frac{\sigma}{8}|f|^{2} \\
& \leq 4 \sigma|f|^{2}+\frac{8 C_{1}^{2}}{\alpha} \rho_{0}^{2}-\frac{\sigma}{8}\left(|A u|^{2}+\|v\|^{2}\right)+\frac{\sigma}{8}\left(|A u|^{2}+|f|^{2}\right)+\frac{\sigma}{8}|f|^{2}  \tag{3.17}\\
& \leq 4 \sigma|f|^{2}+\frac{8 C_{1}^{2}}{\alpha} \rho_{0}^{2}+\frac{\sigma}{4}|f|^{2}-\frac{\sigma}{8}\|v\|^{2} \\
& \leq \frac{\sigma}{4}|f|^{2}+4 \sigma|f|^{2}+\frac{8 C_{1}^{2}}{\alpha} \rho_{0}^{2} \\
& \leq \frac{9}{2} \sigma|f|^{2}+\frac{8 C_{1}^{2}}{\alpha} \rho_{0}^{2}
\end{align*}
$$

Let $C_{3}=(9 / 2) \sigma|f|^{2}+\left(8 C_{1}^{2} / \alpha\right) \rho_{0}^{2}$. By the Gronwall lemma, we have

$$
\begin{equation*}
y(t) \leq y\left(t_{0}\right) \exp \left(-\frac{\sigma}{8}\left(t-t_{0}\right)\right)+\frac{8 C_{3}}{\sigma} \tag{3.18}
\end{equation*}
$$

Defining $\rho_{1}^{\prime}$ by

$$
\begin{equation*}
\rho_{1}^{\prime 2}=\frac{8 C_{3}}{\sigma} \tag{3.19}
\end{equation*}
$$

we see that

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} y(t) \leq \rho_{1}^{\prime 2} \tag{3.20}
\end{equation*}
$$

and we conclude that

The ball of $\mathscr{H}_{1}, \mathcal{B} \triangleq B_{\mathscr{L}_{1}}\left(0, \rho_{1}\right)$, centered at $\left(A^{-1} f, 0\right)$ of radius $\rho_{1}>\rho_{1}^{\prime}+\rho_{0}$, is absorbing in $\mathscr{H}_{1}$ for the semigroup $S(t), t \geq 0$.

We now give the property of compactness about the nonlinear operator $\varphi$ which will be needed in the proof of the condition ( $C$ ).

Lemma 3.4. Assume that $\varphi \in C^{1}(R, R)$ and $\varphi: D(A) \rightarrow V$ are defined by

$$
\begin{equation*}
((\varphi(u), v))=\int_{\Omega} \varphi^{\prime}(u) \nabla u \nabla v d x \tag{3.21}
\end{equation*}
$$

for all $u \in D(A), v \in H_{0}^{1}(\Omega)$. Then, $\varphi$ is continuous compact.
Proof. Let $\left\{u_{m}\right\}$ be a bounded sequence in $D(A)$. Without loss of generality, we assume that $\left\{u_{m}\right\}$ weakly converges to $u_{0}$ in $D(A)$, since $D(A)$ is reflexive. By the Sobolev embedding theorem, we know that $H^{2}(\Omega) \hookrightarrow L^{\infty} \bigcap H^{1}(\Omega)$ and the embedding $H^{2}(\Omega) \hookrightarrow H^{1}(\Omega)$ is compact in $R^{3}$. Hence, we have that

$$
\begin{equation*}
u_{m} \longrightarrow u_{0} \quad \text { in } H^{1} \tag{3.22}
\end{equation*}
$$

Furthermore, there exists a constant $C$ such that

$$
\begin{equation*}
\left\|u_{0}\right\|_{L^{\infty}} \bigcap_{H^{1}(\Omega)} \leq C, \quad\left\|u_{m}\right\|_{L^{\infty}} \bigcap_{H^{1}(\Omega)} \leq C \tag{3.23}
\end{equation*}
$$

It is sufficient to prove that $\left\{\varphi\left(u_{m}\right)\right\}$ converges to $\left\{\varphi\left(u_{0}\right)\right\}$ in $V$ :

$$
\begin{align*}
\left\|\varphi\left(u_{m}\right)-\varphi\left(u_{0}\right)\right\| & =\left(\int_{\Omega}\left|\varphi^{\prime}\left(u_{m}\right) \nabla\left(u_{m}\right)-\varphi^{\prime}\left(u_{0}\right) \nabla u_{0}\right|^{2} d x\right)^{1 / 2} \\
& \leq\left(\int_{\Omega}\left|\varphi^{\prime}\left(u_{m}\right)\right|^{2}\left|\nabla\left(u_{m}\right)-\nabla u_{0}\right|^{2} d x\right)^{1 / 2}+\left(\int_{\Omega}\left|\nabla u_{0}\right|^{2}\left|\varphi^{\prime}\left(u_{m}\right)-\varphi^{\prime}\left(u_{0}\right)\right|^{2} d x\right)^{1 / 2} \tag{3.24}
\end{align*}
$$

On the one hand, for the first term in (3.24), combining with (3.23) and the continuity of $\varphi^{\prime}(\cdot)$, we have

$$
\begin{equation*}
\int_{\Omega}\left|\varphi^{\prime}\left(u_{m}\right)\right|^{2}\left|\nabla\left(u_{m}\right)-\nabla u_{0}\right|^{2} d x \leq C_{\left\|u_{m}\right\|_{L^{\infty}(\Omega)}}\left\|\nabla\left(u_{m}\right)-\nabla u_{0}\right\|^{2} \tag{3.25}
\end{equation*}
$$

On the other hand, for the second term in (3.24), using the continuity of $\varphi^{\prime}(\cdot)$,

$$
\begin{equation*}
\int_{\Omega}\left|\nabla u_{0}\right|^{2}\left|\varphi^{\prime}\left(u_{m}\right)-\varphi^{\prime}\left(u_{0}\right)\right|^{2} d x \longrightarrow 0, \quad \text { as } m \longrightarrow 0 \tag{3.26}
\end{equation*}
$$

follows immediately by dominated convergence theorem.

Also, considering (3.22), passing to the limit in (3.24), we can obtain

$$
\begin{equation*}
\lim _{m \rightarrow \infty}\left\|\varphi\left(u_{m}\right)-\varphi\left(u_{0}\right)\right\|=0 \tag{3.27}
\end{equation*}
$$

This completes the proof.
Lemma 3.5. Suppose the conditions (1.4), (1.5), (1.6) hold, the solution semigroup $\{S(t)\}_{t \geq 0}$ of the problem (1.1)-(1.3) satisfies the condition (C) in $\mathscr{H}_{1}$.

Proof. Let $\left\{\omega_{i}\right\}$ be an orthonormal basis of $L^{2}(\Omega)$ which consists of eigenvalues of $A$. The corresponding eigenvalues are denoted by $\left\{\lambda_{j}\right\}_{j=1}^{\infty}$ :

$$
\begin{equation*}
0<\lambda_{1} \leq \lambda_{2} \leq \lambda_{3} \leq \cdots \leq \lambda_{j} \leq \cdots, \quad \lambda_{j} \longrightarrow \infty \tag{3.28}
\end{equation*}
$$

with

$$
\begin{equation*}
A \omega_{i}=\lambda_{i} \omega_{i}, \quad \forall i \in \mathbb{N} \tag{3.29}
\end{equation*}
$$

Let $V_{m}=\operatorname{span}\left\{\omega_{1}, \ldots, \omega_{m}\right\}$ in $V$ and let $P_{m}: V \rightarrow V_{m}$ be an orthogonal projector. We write

$$
\begin{equation*}
u=P_{m} u+\left(I-P_{m}\right) u \triangleq u_{1}+u_{2} \tag{3.30}
\end{equation*}
$$

Taking the scalar product of (1.1) in $H$ with $A v_{2}=A u_{2 t}+\sigma A u_{2}$, we find

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t}\left(\left|A u_{2}\right|^{2}+\left\|v_{2}\right\|^{2}\right)+\sigma\left|A u_{2}\right|^{2}+(\alpha-\sigma)\left\|v_{2}\right\|^{2}-\sigma(\alpha-\sigma)\left(A u_{2}, v_{2}\right)+\left(\varphi(u), A v_{2}\right)=\left(f, A v_{2}\right) \tag{3.31}
\end{equation*}
$$

Choose $0<\sigma \leq \sigma_{0}$, similar to (3.8), we have

$$
\begin{equation*}
\sigma\left|A u_{2}\right|^{2}+(\alpha-\sigma)\left\|v_{2}\right\|^{2}-\sigma(\alpha-\sigma)\left(A u_{2}, v_{2}\right) \geq \frac{\sigma}{2}\left|A u_{2}\right|^{2}+\frac{\alpha}{2}\left\|v_{2}\right\|^{2} \tag{3.32}
\end{equation*}
$$

Since $f \in L^{2}(\Omega), \varphi: D(A) \rightarrow V$ is compact by Lemma 3.4, for any $\varepsilon>0$, there exists some $m$ such that

$$
\begin{gather*}
\left|\left(I-P_{m}\right) f\right|_{H} \leq \varepsilon,  \tag{3.33}\\
\left\|\left(I-P_{m}\right) \varphi(u)\right\|_{V} \leq \varepsilon, \quad \forall u \in B_{1}\left(0, \rho_{1}\right), \tag{3.34}
\end{gather*}
$$

where $\rho_{1}$ is given by Lemma 3.2.

By exploiting the Hölder inequality and Cauchy inequality, we have

$$
\begin{align*}
\left(\varphi(u), A v_{2}\right) & \leq\left\|\left(I-P_{m}\right) \varphi\right\|\left\|v_{2}\right\| \leq \varepsilon\left\|v_{2}\right\| \leq \frac{\alpha}{4}\left\|v_{2}\right\|^{2}+\frac{\varepsilon^{2}}{\alpha}  \tag{3.35}\\
(f, A v) & =\frac{d}{d t}(f, A u)+\sigma(f, A u)  \tag{3.36}\\
& \leq \frac{d}{d t}(f, A u)+\frac{\sigma}{4}|A u|^{2}+\sigma|f|^{2}
\end{align*}
$$

By (3.33) and (3.36), we have

$$
\begin{align*}
\left(f, A v_{2}\right) & =\frac{d}{d t}\left(f_{2}, A u_{2}\right)+\sigma\left(f, A u_{2}\right) \\
& \leq \frac{d}{d t}\left(f_{2}, A u_{2}\right)+\frac{\sigma}{4}\left|A u_{2}\right|^{2}+\sigma\left|f_{2}\right|^{2}  \tag{3.37}\\
& \leq \frac{d}{d t}\left(f_{2}, A u_{2}\right)+\frac{\sigma}{4}\left|A u_{2}\right|^{2}+\sigma \varepsilon^{2}
\end{align*}
$$

where $f_{2} \triangleq\left(I-P_{m}\right) f$.
Hence, combining with (3.32), (3.35), and (3.37), we obtain from (3.31) that

$$
\begin{equation*}
\frac{d}{d t}\left(\left|A u_{2}\right|^{2}+\left\|v_{2}\right\|^{2}-2\left(f_{2}, A u_{2}\right)\right)+\frac{\sigma}{2}\left(\left|A u_{2}\right|^{2}+\left\|v_{2}\right\|^{2}\right) \leq\left(2 \sigma+\frac{2}{\alpha}\right) \varepsilon^{2} \tag{3.38}
\end{equation*}
$$

Let $y=\left|A u_{2}-f_{2}\right|^{2}+\left\|v_{2}\right\|^{2}$, from the above inequality, similar to (3.17), we can obtain

$$
\begin{align*}
\frac{d y}{d t}+\frac{\sigma}{4} y & \leq \frac{d y}{d t}+\frac{\sigma}{4}\left(\left.\left|A u_{2}\right|^{2}+\left|\left|v_{2} \|^{2}+\left|f_{2}\right|^{2}\right)+\frac{\sigma}{2}\right| A u_{2}| | f_{2} \right\rvert\,\right. \\
& \leq\left(\frac{5 \sigma}{2}+\frac{2}{\alpha}\right) \varepsilon^{2} \tag{3.39}
\end{align*}
$$

Let $C_{4}=5 \sigma / 2+2 / \alpha$. By the Gronwall lemma, we have

$$
\begin{equation*}
y(t) \leq y\left(t_{1}\right) \exp \left(-\frac{\sigma}{4}\left(t-t_{1}\right)\right)+\frac{4 C_{4} \varepsilon^{2}}{\sigma} \tag{3.40}
\end{equation*}
$$

Choosing $t_{2}=t_{1}+(4 / \sigma) \ln \left(\rho_{1}^{2} / \varepsilon^{2}\right)$, it follows that

$$
\begin{equation*}
y(t) \leq\left(1+\frac{4 C_{4}}{\sigma}\right) \varepsilon^{2}, \quad t \geq t_{2} \tag{3.41}
\end{equation*}
$$

That is,

$$
\begin{equation*}
\left|A u_{2}-f_{2}\right|^{2}+\left\|v_{2}\right\|^{2} \leq \tilde{C} \varepsilon^{2} \tag{3.42}
\end{equation*}
$$

for all $t \geq t_{2}$, where $\widetilde{C}=\left(1+4 C_{4} / \sigma\right)$.
Thus we complete the proof.
We are now in a position to state our main results as follows.
Theorem 3.6. Under the conditions (1.4), (1.5), (1.6), problem (1.1)-(1.3) has a global attractor $\mathcal{A}_{1}$ in $\mathscr{H}_{1}$; it attracts all bounded subsets of $\mathscr{H}_{1}$ with respect to the norm of $\mathscr{H}_{1}$.

Proof. By Lemmas 3.1, 3.3, and 3.5, the conditions of Theorem 2.5 are satisfied. The proof is complete.

Corollary 3.7. The global attractor $\mathcal{A}_{0}$ in $\mathscr{H}_{0}$ is coincides with $\mathcal{A}_{1}$ in $\mathscr{H}_{1}$, that is, $\mathscr{A}_{0}=\mathcal{A}_{1}$.
Proof. By Theorem 2.6, $\mathscr{A}_{0}$ is a bounded set of $\mathscr{H}_{1}$, combining with Theorem 3.6, we can easily get $\mathcal{A}_{0}=\mathcal{A}_{1}$.

## Acknowledgment

The author of this paper would like to express her gratitude to Professor Chengkui Zhong for his guidance and encouragement, and to the reviewer, for valuable comments and suggestions. This work was supported in part by the Scientific Research Foundation of Graduate School of Nanjing University (2012CL21) and Taizhou Natural Science and Technology Development Project 2011.

## References

[1] J. M. Ball, "Global attractors for damped semilinear wave equations," Discrete and Continuous Dynamical Systems. Series A, vol. 10, no. 1-2, pp. 31-52, 2004.
[2] A. V. Babin and M. I. Vishik, Attractors of Evolution Equations, vol. 25 of Studies in Mathematics and Its Applications, North-Holland, Amsterdam, The Netherlands, 1992.
[3] V. V. Chepyzhov and M. I. Vishik, Attractors for Equations of Mathematical Physics, vol. 49 of American Mathematical Society Colloquium Publications, American Mathematical Society, Providence, RI, USA, 2002.
[4] I. Chueshov and I. Lasiecka, "Long-time behavior of second order evolution equations with nonlinear damping," Memoirs of the American Mathematical Society, vol. 195, no. 912, 183 pages, 2008.
[5] J. K. Hale, Asymptotic Behavior of Dissipative Systems, vol. 25 of Mathematical Surveys and Monographs, American Mathematical Society, Providence, RI, USA, 1988.
[6] R. Temam, Infinite-Dimensional Dynamical Systems in Mechanics and Physics, vol. 68 of Applied Mathematical Sciences, Springer, New York, NY, USA, 2nd edition, 1997.
[7] V. Pata and S. Zelik, "A remark on the damped wave equation," Communications on Pure and Applied Analysis, vol. 5, no. 3, pp. 609-614, 2006.
[8] A. Kh. Khanmamedov, "On a global attractor for the strong solutions of the 2-D wave equation with nonlinear damping," Applicable Analysis, vol. 88, no. 9, pp. 1283-1301, 2009.
[9] A. Kh. Khanmamedov, "Global attractors for 2-D wave equations with displacement-dependent damping," Mathematical Methods in the Applied Sciences, vol. 33, no. 2, pp. 177-187, 2010.
[10] A. Kh. Khanmamedov, "Global attractors for strongly damped wave equations with displacement dependent damping and nonlinear source term of critical exponent," Discrete and Continuous Dynamical Systems. Series A, vol. 31, no. 1, pp. 119-138, 2011.
[11] F. J. Meng and C. K. Zhong, "Strong global attractor for weakly damped wave equations," submitted.
[12] Q. Ma, S. Wang, and C. Zhong, "Necessary and sufficient conditions for the existence of global attractors for semigroups and applications," Indiana University Mathematics Journal, vol. 51, no. 6, pp. 1541-1559, 2002.
[13] J. C. Robinson, Infinite-Dimensional Dynamical Systems, Cambridge Texts in Applied Mathematics, Cambridge University Press, Cambridge, UK, 2001.

