Existence of Positive Solution to Schrödinger-type Semipositone Problems with Mixed Nonlinear Boundary Conditions

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Abstract. We studied the existence of a positive solution to Schrödinger-type semipositone problems with mixed nonlinear boundary conditions. By considering the cases when the reaction term with a parameter satisfies a superlinear and a sublinear growth condition at infinity, we established the existence of a positive solution for the large and small values of the parameter, respectively. The proofs are mainly based on the sub- and supersolution method for the sublinear case and the mountain pass lemma with $C^{1,\alpha}(\overline{\Omega})$ -regularity for the superlinear case.

1. Introduction and main results

Owing to its suitability to describe a wide range of physical phenomena, the semilinear equation

(1.1)
$$\begin{cases} -\Delta u = \lambda f(u), & x \in \Omega, \\ u = 0, & x \in \partial \Omega \end{cases}$$

related to reaction-diffusion models, has been widely and intensively studied for a long time. In (1.1) $\Delta u = \operatorname{div}(\nabla u)$, Ω is a bounded domain in \mathbb{R}^N , $\partial\Omega$ is a smooth boundary of Ω , λ is a positive real parameter, and $f: [0, \infty) \to \mathbb{R}$ is a function. The existence of solutions of (1.1) according to the nonlinear behavior of f has been of particular interest. Several researchers have investigated problems with nonnegative f functions, while studies on models with sign-changing f functions, specifically when f(0) < 0, have been relatively rare. This case, known as the semipositone problem, has been extensively studied in the literature. Lions [31] reported that the study of positive solutions to semipositone problems is more challenging than the case of $f(0) \ge 0$.

Since then, several researchers have employed different conditions for (1.1). In one of these studies, a nonlinear boundary condition was applied instead of a Dirichlet boundary

Received April 9, 2020; Accepted July 26, 2020.

Communicated by Eiji Yanagida.

²⁰¹⁰ Mathematics Subject Classification. 35J66, 35J20.

Key words and phrases. existence, positive solution, semipositone problems, nonlinear boundary conditions, Schrödinger equations.

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condition

(1.2)
$$\begin{cases} -\Delta u = \lambda f(u), & x \in \Omega, \\ \frac{\partial u}{\partial \eta} + g(u)u = 0, & x \in \partial \Omega \end{cases}$$

where $\frac{\partial}{\partial \eta}$ is an outward normal derivative and $g: [0, \infty) \to (0, \infty)$ is a function. The nonlinear boundary condition in (1.2), naturally arises in several applications, for example, in thermal explosion models [23, 27], convection-diffusion systems, corrosion/oxidation models, and metal-insulator or metal-oxide semiconductor systems [3, 6, 15, 18, 26, 34, 37].

Recently, Butler et al. [8] studied positive radial solutions to the boundary value problem on the exterior of a ball,

(1.3)
$$\begin{cases} -\Delta u = \lambda K(|x|)f(u), & x \in \Omega, \\ \frac{\partial u}{\partial \eta} + g(u)u = 0, & |x| = r_0, \\ u = 0, & |x| \to \infty \end{cases}$$

where $\Omega = \{x \in \mathbb{R}^N : N > 2, |x| > r_0 \text{ with } r_0 > 0\}, K \colon (r_0, \infty) \to (0, \infty) \text{ is a continuous function such that } \lim_{r \to \infty} K(r) = 0 \text{ and } g \text{ is continuous. They transformed (1.3) by the change of variable } r = |x|, t = \left(\frac{r}{r_0}\right)^{2-N}$, into a one-dimensional problem with a mixed nonlinear boundary condition

$$\begin{cases} -u''(t) = \lambda h(t) f(u(t)), & t \in (0,1) \\ \frac{(N-2)}{r_0} u'(1) + g(u(1))u(1) = 0, \\ u(0) = 0, \end{cases}$$

where $h(t) = \frac{r_0^2}{(2-N)^2} t^{\frac{-2(N-2)}{N-2}} K(r_0 t^{\frac{1}{2-N}}).$

For simplicity, it is natural to consider an autonomous nonlinear partial differential equation (PDE) problem instead of the ordinary differential equation (ODE) above. Thus, in this paper, we are focusing on the existence of a positive solution of

(1.4)
$$\begin{cases} -\Delta u + V(x)u = \lambda f(u), & x \in \Omega = \Omega_1 \setminus \overline{\Omega}_2, \\ \frac{\partial u}{\partial \eta} + g(u)u = 0, & x \in \partial \Omega_1, \\ u = 0, & x \in \partial \Omega_2, \end{cases}$$

which allows $V \equiv 0$ (therefore, the Laplacian is its special case). In (1.4), Ω_1 and Ω_2 are subsets of $\Omega \subset \mathbb{R}^N$ with $\overline{\Omega}_2 \subsetneq \Omega_1$, which are nonempty bounded domains in \mathbb{R}^N , N > 2, $\partial \Omega_1$ is a smooth boundary of Ω_1 with outward normal η , $\partial \Omega_2$ is a smooth boundary of Ω_2 and λ is a positive real parameter. In addition, $\partial \Omega = \partial \Omega_1 \cup \partial \Omega_2$. Throughout this paper, we assume that

(H) $V \in L^{\infty}(\Omega), f \in C^{1}([0,\infty)), g \in C^{\alpha}([0,\infty), (0,\infty))$ for some $0 < \alpha < 1$.

The first equation in (1.4) is derived based on the nonlinear Schrödinger equation, which is detailed in the seminal paper [36]. Nonlinear Schrödinger equations have been intensively studied to demonstrate the existence of solutions that act according to V on the whole space \mathbb{R}^N (see [5, 24, 32] or references therein) or on bounded domains with linear boundary conditions under the assumption $f(0) \ge 0$ [19]. A numerical solution was treated in [28] for linear Schrödinger equations with a nonlinear boundary condition.

This paper presents the first ever investigation of the existence of a positive solution of (1.4) that includes the Laplacian as a special case under the simultaneous assumptions of f(0) < 0 and a mixed nonlinear boundary condition when sufficient conditions on V, f, and g are imposed.

In this study, we are interested in two different growth conditions on f:

(f₀)
$$\lim_{s\to\infty} \frac{f(s)}{s} = 0$$
 (sublinear),

(f_{∞}) lim_{$s\to\infty$} $\frac{f(s)}{s} = \infty$ (superlinear).

For the case (f_0) , sub- and supersolution methods have widely been used to obtain a positive solution for Laplacian semipositone problems, that is, the case of $V \equiv 0$ with Dirichlet boundary conditions on bounded domains (see [2, 4, 10, 16]). Recently, such a method was applied to a Laplacian (not semipositone) problem with a nonlinear boundary condition [23]. We further assume that

- (F₁) $f(s) \to \infty$ as $s \to \infty$,
- (G₁) there exists M > 0 such that $g(s) \ge M$ for $s \ge 0$,
- (V₁) there exists $c_V > 0$ such that $V(x) \ge -c_V > -\frac{1}{\|e\|_{\infty}}$ for $x \in \Omega$, when e is the positive solution of

$$\begin{cases} -\Delta e = 1 & \text{in } \Omega, \\ \frac{\partial e}{\partial \eta} + Me = 0 & \text{on } \partial \Omega \end{cases}$$

Then, we establish our main result for the case when f is sublinear near infinity.

Theorem 1.1. Let us assume (H), (f₀), (F₁), (G₁), and (V₁). Then, for a sufficiently large λ , the problem (1.4) has a positive solution $u_{\lambda} \in C^{2}(\Omega) \cap C^{1,\alpha}(\overline{\Omega})$ for some $\alpha \in (0, 1)$.

For the case (f_{∞}) , the scaling method combined with the degree theory [13] and the mountain pass lemma with $C^{1,\alpha}(\overline{\Omega})$ -regularity [9,35] are frequently used to demonstrate the existence of a positive solution for semipositone Laplacian (or *p*-Laplacian) problems with Dirichlet boundary conditions. Here, more precise assumptions are given for this case. First, to introduce a variational structure, we extend f from $[0,\infty)$ to \mathbb{R} such that $f \in C^1(\mathbb{R}, \mathbb{R})$ and assume that (f₁) there exist A > 0, B > 0 and $q \in (1, \frac{N+2}{N-2})$ such that

$$\begin{cases} A(u^{q} - 1) \le f(u) \le B(u^{q} + 1) & \text{for } u > 0, \\ f(u) = 0 & \text{for } u \le -1. \end{cases}$$

We also extend g from $[0,\infty)$ to \mathbb{R} such that $g \in C^{\alpha}(\mathbb{R},(0,\infty))$ for some $\alpha \in (0,1)$ and assume that

(g₁) there exist $0 < m_g < M_g < \infty$ such that $m_g \leq g(s) \leq M_g$ for all $s \in \mathbb{R}$,

and V satisfies

(v₁)
$$V(x) \ge 0$$
 a.e. in Ω .

We further assume Ambrosetti–Rabinowitz-type conditions such that

(f₂) there exist $\theta > \frac{2M_g}{m_g}$ and $C \in \mathbb{R}$ such that

(1.5)
$$uf(u) \ge \theta F(u) + C,$$

where $F(u) = \int_0^u f(s) \, ds$.

Remark 1.2. The condition (1.5) implies that f satisfies the Ambrosetti–Rabinowitz condition as $\theta > \frac{2M_g}{m_g} > 2$.

Here, we establish our main result for the case when f is superlinear near infinity.

Theorem 1.3. Let us assume (H), (f₁), (f₂), (g₁), and (v₁). There exists $\lambda^* > 0$ such that if $\lambda \in (0, \lambda^*)$, then the equation (1.4) has a positive solution $u_{\lambda} \in C^2(\Omega) \cap C^{1,\beta}(\overline{\Omega})$ for some $\beta \in (0, 1)$.

Remark 1.4. (i) We emphasize that our two main results remain valid even for the case $V \equiv 0$. In this case, the main problem in Theorem 1.3 is that the coercive term, such as V(x)u, disappears. To overcome this, we observe that the coercivity induced by the boundary condition from the assumption g(u)u is strictly positive. This motivates the definition of an equivalent norm in $H^1(\Omega)$ defined in (3.1), with respect to which the energy functional corresponding to (1.4) can be analyzed.

(ii) The condition on g is restrictive. For the more general case for g, we refer to [28], where it is treated by a linear Schrödinger equation.

This paper is organized as follows: In Section 2, we establish the method of obtaining sub- and supersolutions for (1.4) and provide a proof of Theorem 1.1. In Section 3, we present a proof of Theorem 1.3 by using the mountain pass argument.

2. Sublinear semipositone

In this section, we establish the method of obtaining sub- and supersolutions for (1.4) and provide a proof of Theorem 1.1.

2.1. Method of sub- and supersolutions

A subsolution of (1.4) is defined as a function $\psi \colon \overline{\Omega} \to \mathbb{R}$ satisfying

$$\begin{cases} -\Delta \psi + V(x)\psi \le \lambda f(\psi), & x \in \Omega, \\ \frac{\partial \psi}{\partial \eta} + g(\psi)\psi \le 0, & x \in \partial \Omega_1, \\ \psi \le 0, & x \in \partial \Omega_2, \end{cases}$$

while a supersolution of (1.4) is defined as a function $\phi \colon \overline{\Omega} \to \mathbb{R}$ satisfying

$$\begin{cases} -\Delta \phi + V(x)\phi \ge \lambda f(\phi), & x \in \Omega, \\ \frac{\partial \phi}{\partial \eta} + g(\phi)\phi \ge 0, & x \in \partial \Omega_1, \\ \phi \ge 0, & x \in \partial \Omega_2. \end{cases}$$

To prove our second result, the following lemma is used.

Lemma 2.1. If a subsolution ψ and a supersolution ϕ of (1.4) exist such that $\psi \leq \phi$ on $\overline{\Omega}$, then (1.4) has at least one solution $u \in C^2(\Omega) \cap C^{1,\alpha}(\overline{\Omega})$ satisfying $\psi \leq u \leq \phi$ on $\overline{\Omega}$.

Proof. By applying the results in [1] and [25] to (1.4), it can be shown that, under the ordering assumptions of this lemma, there exists $u \in W^{2,p}(\Omega)$ for p > N. Thus, based on the Sobolev embedding theorem $u \in C^{1,\alpha}(\overline{\Omega})$ (see [17, Theorem 6, p. 270]). This implies that $f(u) \in C^1(\overline{\Omega})$ and $g(u)u \in C^{\alpha}(\overline{\Omega})$. Consequently, according to [22, Theorem 6.25] and [30, Theorem 2], $u \in C^2(\Omega) \cap C^{1,\alpha}(\overline{\Omega})$ is a classical solution of (1.4).

Lemma 2.2. Let us assume (V_1) . Then, the following problem

(2.1)
$$\begin{cases} -\Delta w + V(x)w = 1 & \text{in } \Omega, \\ \frac{\partial w}{\partial \eta} + Mw = 0 & \text{on } \partial \Omega \end{cases}$$

has a solution w such that w(x) > 0 for $x \in \overline{\Omega}$ and $\frac{\partial w}{\partial \eta} < 0$ on $\partial \Omega$.

Proof. For K > 0 such that $\frac{1}{K} \leq 1 - c_V ||e||_{\infty}$, let z = Ke, then

$$-\Delta z + V(x)z = K(-\Delta e + V(x)e) = K(1 + V(x)e) \ge K(1 - c_V e) \ge K(1 - c_V ||e||_{\infty}) \ge 1$$

and $\frac{\partial z}{\partial \eta} + Mz = 0$ on $\partial\Omega$. Thus, z is a supersolution of (2.1) and z(x) > 0 for $x \in \overline{\Omega}$. As zero is the trivial subsolution of (2.1) but not a solution of (2.1), according to the sub-supersolution theorem, there exists a solution w of (2.1) such that $0 \leq w(x) \leq z(x)$. Here, we claim that w(x) > 0 for $x \in \Omega$ and $\frac{\partial w}{\partial \eta} < 0$ on $\partial\Omega$. Otherwise, there exists $x_0 \in \Omega$ such that $w(x_0) = 0$. Then, we find that $1 = -\Delta w(x_0) + V(x_0)w(x_0) \leq 0$ as $||V|| < \infty$, which is a contradiction. Hence, w > 0 in Ω , and using the Hopf maximum principle, we obtain $\frac{\partial w}{\partial \eta} < 0$ on $\partial\Omega$. Finally, we conclude that w > 0 for all $x \in \overline{\Omega}$ because w satisfies the boundary condition of (2.1).

Let λ_1 and ϕ_1 be the first eigenvalue and the corresponding eigenfunction of

$$\begin{cases} -\Delta \phi + V(x)\phi = \lambda \phi & \text{in } \Omega, \\ \phi = 0 & \text{on } \partial \Omega. \end{cases}$$

Then, $\phi_1(x) > 0$ for $x \in \Omega$ and $\frac{\partial \phi_1}{\partial \eta} < 0$ on $\partial \Omega$ [14,20,33].

2.2. Proof of Theorem 1.1

First, we construct a subsolution. Since $\phi_1 > 0$ in Ω and $\frac{\partial \phi_1}{\partial \eta} < 0$ on $\partial \Omega$, there exist $\delta > 0$ and m > 0 such that

$$2|\nabla\phi_1|^2 - (2\lambda_1 + c_V)\phi_1^2 \ge m \quad \text{in } \{x \in \Omega \mid d(x, \partial\Omega) < \delta\}$$

Define $\Omega_{\delta} := \{x \in \Omega \mid d(x, \partial \Omega) < \delta\}$. Then, there exists $\mu > 0$ such that

 $\phi_1^2 \ge \mu \quad \text{in } \Omega \setminus \Omega_\delta.$

Let $\underline{f} = \min_{s \in [0,\infty)} f(s) < 0$. From (F₁), we find that there exists L > 0 such that

(2.2)
$$\frac{(-\underline{f})}{m}(\lambda_1 + c_V) < f(s) \quad \text{for } s > L,$$

and such that

(2.3)
$$\frac{\lambda(-\underline{f})}{m}\mu > L \quad \text{for sufficiently large } \lambda \gg 1.$$

Let us denote $\rho := \frac{\lambda(-f)}{m}$ and define $\psi = \rho \phi_1^2$. We estimate $-\Delta \psi + V(x)\psi$ in Ω_{δ} as

$$\begin{aligned} -\Delta \psi + V(x)\psi &= -2\rho |\nabla \phi_1|^2 + 2\rho (\lambda_1 - V(x))\phi_1^2 + \rho V(x)\phi_1^2 \\ &= -2\rho |\nabla \phi_1|^2 + 2\rho \lambda_1 \phi_1^2 - \rho V(x)\phi_1^2 \\ &\leq -\rho (2|\nabla \phi_1|^2 - (2\lambda_1 + c_V)\phi_1^2) \\ &\leq -\rho m = \lambda \underline{f} \leq \lambda f(\psi). \end{aligned}$$

We also have in $\Omega \setminus \Omega_{\delta}$, from (2.2) and (2.3),

$$-\Delta \psi + V(x)\psi \leq -\rho \left(2|\nabla \phi_1|^2 - (2\lambda_1 + c_V)\phi_1^2\right) \leq \frac{\lambda(-\underline{f})}{m}(2\lambda_1 + c_V)\phi_1^2$$
$$\leq \frac{\lambda(-\underline{f})}{m}(2\lambda_1 + c_V) \leq \lambda f\left(\frac{\lambda(-\underline{f})}{m}\phi_1^2\right) = \lambda f(\psi)$$

as $\mu \leq \phi_1^2 \leq 1$. Since $\psi = 0$ and $\frac{\partial \psi}{\partial \eta} + g(\psi)\psi = 0$ on $\partial \Omega$, ψ is a subsolution of (1.4) for $\lambda \gg 1$.

Next, we construct a supersolution. Let us define $\overline{f}(s) := \max_{t \leq s} f(t)$. Then, $f(s) \leq \overline{f}(s)$, \overline{f} is monotone increasing and $\lim_{s \to \infty} \frac{\overline{f}(s)}{s} = 0$. This implies that there exists $M_{\lambda} \gg 1$ such that $M_{\lambda}w \geq \psi$ and satisfies

(2.4)
$$\frac{\overline{f}(M_{\lambda}\|w\|_{\infty})}{M_{\lambda}\|w\|_{\infty}} \leq \frac{1}{\lambda\|w\|_{\infty}}.$$

Let $\zeta = M_{\lambda} w$. Then, using (2.4) and the definition of \overline{f} , we can write

$$-\Delta \zeta + V(x)\zeta = M_{\lambda}(-\Delta w + V(x)w) = M_{\lambda}$$

$$\geq \lambda \overline{f}(M_{\lambda} ||w||_{\infty}) \geq \lambda \overline{f}(M_{\lambda}w) \geq \lambda f(M_{\lambda}w) = \lambda f(\zeta).$$

Moreover, on $\partial \Omega$, $\zeta > 0$ and

$$\frac{\partial \zeta}{\partial \eta} + g(\zeta)\zeta = M_{\lambda} \left(\frac{\partial w}{\partial \eta} + g(M_{\lambda}w)w\right) \ge M_{\lambda} \left(\frac{\partial w}{\partial \eta} + Mw\right) = 0.$$

By considering a sufficiently large M_{λ} such that $M_{\lambda}w \ge \rho \phi_1^2$ in Ω , ζ becomes a supersolution satisfying $\psi \le \zeta$. Thus, the proof is completed.

3. Superlinear semipositone

In this section, we present a proof of Theorem 1.3 by using the mountain pass argument.

3.1. Preliminary

Let $H^1(\Omega) = \{u : u \in L^2(\Omega), \nabla u \in (L^2(\Omega))^N\}$ be a standard Sobolev space with the norm $\|u\|_{H^1(\Omega)}^2 = \int_{\Omega} (|\nabla u|^2 + |u|^2)$. We define

$$H := \{ u \in H^1(\Omega) : u = 0 \text{ on } \partial\Omega_2 \}$$

and the inner product

$$(u,v) := \int_{\Omega} \nabla u \cdot \nabla v \, dx + m_g \int_{\partial \Omega_1} uv \, d\sigma, \quad \forall \, u, v \in H,$$

where $d\sigma$ denotes the surface measure on $\partial \Omega_1$ and $m_g > 0$ is defined in (g₁). Then, H is a Hilbert space with an associated norm

(3.1)
$$\|u\|_{H}^{2} := \int_{\Omega} |\nabla u|^{2} dx + m_{g} \int_{\partial \Omega_{1}} u^{2} d\sigma, \quad \forall u \in H.$$

Owing to the imbedding provided by Cherrier [11,12,29], there exists $c_I, c_{II} > 0$ such that

(3.2)
$$c_I \|u\|_{H^1(\Omega)} \le \|u\|_H \le c_{II} \|u\|_{H^1(\Omega)}, \quad \forall u \in H^1(\Omega).$$

Thus, the space H is complete with respect to the norm $\|\cdot\|_{H}$. A weak solution of (1.4) is defined as $u \in H$ satisfying

(3.3)
$$\int_{\Omega} (\nabla u \cdot \nabla \psi + V(x)u\psi) \, dx - \lambda \int_{\Omega} f(u)\psi \, dx + \int_{\partial\Omega_1} g(u)u\psi \, d\sigma = 0 \quad \text{for all } \psi \in H.$$

We define the energy functional E_{λ} associated with the problem (1.4) as

$$E_{\lambda}(u) = \frac{1}{2} \int_{\Omega} (|\nabla u|^2 + V(x)u^2) \, dx - \lambda \int_{\Omega} F(u) \, dx + \int_{\partial \Omega_1} G(u) \, d\sigma, \quad u \in H.$$

where $G(t) := \int_0^t g(s)s \, ds$. It is well-known that E_{λ} is a C^1 functional and the critical points of E_{λ} are the weak solutions of (1.4). We denote the norm in the $L^p(\Omega)$ space by $\|\cdot\|_p$ and the norm in the Sobolev space $W^{1,p}(\Omega)$ by $\|\cdot\|_{1,p}$.

3.2. Existence of a solution of mountain pass type

In this subsection, we prove that E_{λ} satisfies the mountain pass geometry in the first two lemmas and equation (1.4) has a solution $u_{\lambda} \in H_D^1(\Omega)$ using the mountain pass theorem in the last lemma. Before stating the lemmas, we note that, from the condition (f₁), there exist $A_1 > 0$, $B_1 > 0$ such that

$$F(u) \le B_1(|u|^{q+1}+1) \text{ for all } u \in \mathbb{R}$$

and

(3.4)
$$F(u) \ge A_1(|u|^{q+1} - 1) \text{ for all } u \ge 0.$$

For simplicity, we denote $r = \frac{1}{q-1}$ and let $\psi \in H$ be a positive function with $\|\psi\|_H = 1$. Let us define a constant

(3.5)
$$\mu = \left(\frac{M_g + m_g \|V\|_{\infty} \|\psi\|_2^2}{A_1 m_g \|\psi\|_{q+1}^{q+1}}\right)^r,$$

which is used in the following lemma.

Lemma 3.1. There exists $\lambda_1 > 0$ such that if $\lambda \in (0, \lambda_1)$, then $E_{\lambda}(\mu \lambda^{-r} \psi) \leq 0$.

Proof. Let $s = \mu \lambda^{-r}$. Using (3.4), we obtain

$$\begin{split} E_{\lambda}(s\psi) &= \frac{s^2}{2} \int_{\Omega} (|\nabla\psi|^2 + V(x)\psi^2) \, dx - \lambda \int_{\Omega} F(s\psi) \, dx + \int_{\partial\Omega_1} G(s\psi) \, d\sigma \\ &\leq \frac{s^2}{2} \int_{\Omega} (|\nabla\psi|^2 + V(x)\psi^2) \, dx - \lambda A_1 \int_{\Omega} (s^{q+1}|\psi|^{q+1} - 1) \, dx + \frac{M_g}{2} \int_{\partial\Omega_1} s^2 \psi^2 \, d\sigma \\ &\leq \frac{s^2}{2} \frac{M_g}{m_g} \|\psi\|_H^2 + \frac{s^2}{2} \|V\|_{\infty} \|\psi\|_2^2 - \lambda A_1 s^{q+1} \|\psi\|_{q+1}^{q+1} + \lambda A_1 |\Omega|. \end{split}$$

By substituting (3.5) into (3.6), we find

$$\begin{split} E_{\lambda}(s\psi) &\leq \frac{\mu^{2}\lambda^{-2r}}{2} \frac{M_{g}}{m_{g}} + \frac{\mu^{2}\lambda^{-2r}}{2} \|V\|_{\infty} \|\psi\|_{2}^{2} - \lambda A_{1}\mu^{q+1}\lambda^{-r(q+1)} \|\psi\|_{q+1}^{q+1} + \lambda A_{1}|\Omega| \\ &= \mu^{2}\lambda^{-2r} \left[\frac{1}{2} \left(\frac{M_{g}}{m_{g}} + \|V\|_{\infty} \|\psi\|_{2}^{2} \right) - A_{1}\mu^{q-1} \|\psi\|_{q+1}^{q+1} \right] + \lambda A_{1}|\Omega| \\ &= -\frac{\mu^{2}\lambda^{-2r}}{2} \left(\frac{M_{g}}{m_{g}} + \|V\|_{\infty} \|\psi\|_{2}^{2} \right) + \lambda A_{1}|\Omega|. \end{split}$$

By taking $\lambda_1 < \min \left\{ 1, \left(\frac{\mu^2(M_g + m_g \|V\|_{\infty} \|\psi\|_2^2)}{2A_1 m_g |\Omega|} \right)^{\frac{1}{1+2r}} \right\}$, the lemma is proven.

Lemma 3.2. There exist
$$\tau \in (0, \mu)$$
 and $\lambda_2 \in (0, 1)$ such that, if $||u||_H = \tau \lambda^{-r}$, then $E_{\lambda}(u) \geq \frac{1}{8}(\tau \lambda^{-r})^2$ for all $\lambda \in (0, \lambda_2)$.

Proof. First, we notice that there exists $K_1 > 0$ such that $||u||_{q+1} \leq K_1 ||u||_H$ for $u \in H$ according to the Sobolev embedding theorem and (3.2). Let

(3.7)
$$\tau < \min\left\{ (4B_1 K_1^{q+1})^{-r}, \mu \right\}$$

If $||u||_H = \tau \lambda^{-r}$, then, according to (3.4) and because $V(x) \ge 0$ a.e. in Ω ,

$$\begin{split} E_{\lambda}(u) &= \frac{1}{2} \int_{\Omega} (|\nabla u|^{2} + V(x)u^{2}) \, dx - \lambda \int_{\Omega} F(u) \, dx + \int_{\partial\Omega_{1}} G(u) \, dx \\ &\geq \frac{1}{2} \int_{\Omega} |\nabla u|^{2} \, dx - \lambda \int_{\Omega} B_{1}(|u|^{q+1} + 1) \, dx + \frac{m_{g}}{2} \int_{\partial\Omega_{1}} u^{2} \, d\sigma \\ &\geq \frac{1}{2} \|u\|_{H}^{2} - \lambda B_{1} \|u\|_{q+1}^{q+1} - \lambda B_{1} |\Omega| \\ &\geq \frac{1}{2} \|u\|_{H}^{2} - \lambda B_{1} K_{1}^{q+1} \|u\|_{H}^{q+1} - \lambda B_{1} |\Omega| \\ &= \lambda^{-2r} \left[\frac{1}{2} \tau^{2} - B_{1} K_{1}^{q+1} \tau^{q+1} - \lambda^{1+2r} B_{1} |\Omega| \right] \\ &\geq \lambda^{-2r} \left[\frac{1}{4} \tau^{2} - \lambda^{1+2r} B_{1} |\Omega| \right], \end{split}$$

where (3.7) is used at the last inequality. Next, we consider $\lambda > 0$ such that $\lambda < \left(\frac{\tau^2}{8B_1|\Omega|}\right)^{\frac{1}{1+2r}} := \lambda_2$. Then, $E_{\lambda}(u) \ge \frac{1}{8}(\tau\lambda^{-r})^2$ if $||u||_H = \tau\lambda^{-r}$.

Lemma 3.3. Let $\lambda_3 = \min\{\lambda_1, \lambda_2, 1\}$. There exists $c_1 > 0$ such that for each $\lambda \in (0, \lambda_3)$, the functional E_{λ} has a mountain pass type critical point u_{λ} satisfying $E_{\lambda}(u_{\lambda}) \leq c_1 \lambda^{-2r}$.

Proof. First, we show that E_{λ} satisfies the Palais–Smale condition. We assume that $\{u_n\}$ is a sequence in H such that $\{E_{\lambda}(u_n)\}$ is bounded and $\lim_{n\to\infty} ||E'_{\lambda}(u_n)||_{H^*} = 0$. By setting $\rho > 0$ as a constant such that $|E_{\lambda}(u_n)| \leq \rho$ for all $n = 1, 2, \ldots$, we have

(3.8)
$$\frac{1}{2} \int_{\Omega} (|\nabla u_n|^2 + V(x)u_n^2) \, dx - \lambda \int_{\Omega} F(u_n) \, dx + \int_{\partial \Omega_1} G(u_n) \, d\sigma \le \rho$$

and

(3.9)
$$\left| \int_{\Omega} (\nabla u_n \cdot \nabla \psi + V(x)u_n\psi) \, dx - \lambda \int_{\Omega} f(u_n)\psi \, dx - \int_{\partial\Omega_1} g(u_n)u_n\psi \, d\sigma \right|$$
$$= o(1) \|\psi\|_H, \quad \forall \psi \in H.$$

Notably, from (3.8), we find that due to the condition (f_2) ,

(3.10)
$$\frac{1}{2} \|u_n\|_H^2 + \frac{1}{2} \int_{\Omega} V(x) u_n^2 dx \le \rho + \lambda \int_{\Omega} F(u_n) dx \\ \le \rho + \frac{\lambda}{\theta} \int_{\Omega} (f(u_n) u_n - C) dx$$

Then, substituting u_n for ψ into (3.9), we obtain

(3.11)
$$\lambda \int_{\Omega} f(u_n) u_n \, dx \leq \int_{\Omega} (|\nabla u_n|^2 + V(x) u_n^2) \, dx + M_g \int_{\partial \Omega_1} u_n^2 \, d\sigma + o(1) \|u_n\|_H \\ \leq \frac{M_g}{m_g} \|u_n\|_H^2 + \int_{\Omega} V(x) u_n^2 \, dx + o(1) \|u_n\|_H.$$

By combining (3.10) and (3.11), as $\frac{1}{\theta} < \frac{M_g}{m_g \theta} < \frac{1}{2}$, it follows that $\sup_n ||u_n||_H \le c < \infty$ for some c > 0, which implies that $\{u_n\}$ is bounded in H. Therefore, there exists $u_\lambda \in H$ such that

$$(3.12) u_n \rightharpoonup u_\lambda \quad \text{in } H.$$

It should be noted that, due to the compact embedding $H^1(\Omega) \hookrightarrow L^p(\Omega)$ for all $1 \leq p < \frac{2N}{N-2} =: 2^*$, there exists a subsequence $\{u_{n_k}\}$, denoted by $\{u_n\}$, such that $u_n \to u_\lambda$ in $L^p(\Omega)$ for all $1 \leq p < 2^*$. Thus, we can write

(3.13)
$$\int_{\Omega} V(x)u_n\psi\,dx \to \int_{\Omega} V(x)u_\lambda\psi\,dx, \quad \int_{\Omega} f(u_n)\psi\,dx \to \int_{\Omega} f(u_\lambda)\psi\,dx, \quad \forall\,\psi\in H,$$

and

(3.14)
$$\int_{\Omega} V(x)u_n^2 dx \to \int_{\Omega} V(x)u_\lambda^2 dx, \quad \int_{\Omega} f(u_n)u_n dx \to \int_{\Omega} f(u_\lambda)u_\lambda dx$$

as $n \to \infty$. Due to the compactness of trace embedding $H^1(\Omega) \hookrightarrow L^2(\partial \Omega)$,

(3.15)
$$\int_{\partial\Omega_1} g(u_n) u_n \psi \, d\sigma \to \int_{\partial\Omega_1} g(u_\lambda) u_\lambda \psi \, d\sigma, \quad \forall \, \psi \in H,$$

(3.16)
$$\int_{\partial\Omega_1} g(u_n) u_n^2 \, d\sigma \to \int_{\partial\Omega_1} g(u_\lambda) u_\lambda^2 \, d\sigma$$

as $n \to \infty$. Using (3.8), (3.12), (3.13) and (3.15), we find that u_{λ} is a weak solution of (1.4) and from (3.8), (3.14) and (3.16), it follows that $\int_{\Omega} |\nabla u_n|^2 \to \int_{\Omega} |\nabla u_{\lambda}|^2$ as $n \to \infty$. This proves that E_{λ} satisfies the Palais–Smale condition.

Next, using (3.6) we can write

$$E_{\lambda}(s\psi) \leq \frac{s^2}{2} \frac{M_g}{m_g} \|\psi\|_H^2 + \frac{s^2}{2} \|V\|_{\infty} \|\psi\|_2^2 - \lambda A_1 s^{q+1} \|\psi\|_{q+1}^{q+1} + \lambda A_1 |\Omega|$$

Let us denote $H(s) := s^2 D - s^{q+1}E + \lambda A_1 |\Omega|$, where $D = \frac{1}{2} \left(\frac{M_g}{m_g} \|\psi\|_H^2 + \|V\|_{\infty} \|\psi\|_2^2 \right)$ and $E = A_1 \|\psi\|_{q+1}^{q+1}$. Then, H(s) reaches its maximum at the value of $s = \left(\frac{2D}{(q+1)E} \right)^r$. Consequently, we obtain that

$$\max_{s \ge 0} E_{\lambda}(s\psi) \le \frac{2^{2r} D^{1+2r}(q-1)}{E^{2r}(q+1)^{2r+1}} \lambda^{-2r} + \lambda |A_1| |\Omega|$$

=: $\tilde{c}_1 \lambda^{-2r} + \lambda |A_1| |\Omega| \le \tilde{c}_1 \lambda^{-2r} + \lambda^{-2r} |A_1| |\Omega| =: c_1 \lambda^{-2r}.$

Therefore, according to the mountain pass theorem, there exists $u_{\lambda} \in H$ such that $E'_{\lambda}(u_{\lambda}) = 0$ and

$$\frac{1}{8}(\tau\lambda^{-r})^2 \le E_\lambda(u_\lambda) \le c_1\lambda^{-2r}.$$

3.3. Positivity of solutions

Lemma 3.4. Let $u_{\lambda} \in H$ be the solution in Lemma 3.3. Then $u_{\lambda} \in C^{1,\alpha}(\overline{\Omega})$ for some $\alpha \in (0,1)$.

Proof. Based on the same argument as that in Theorem 1.2 in [21], it can be shown that any solution of (1.4) is bounded. Furthermore, we conclude that $u_{\lambda} \in C^{1,\alpha}(\overline{\Omega})$ using Theorem 2 in [30].

Lemma 3.5. Let $u_{\lambda} \in H$ be a solution in Lemma 3.3. Then, there exists $M_1 > 0$ such that

$$M_1 \lambda^{-r} \le \|u\|_{\infty}.$$

Proof. According to Lemma 3.2, $E_{\lambda}(u_{\lambda}) \geq \frac{1}{8}(\tau \lambda^{-r})^2 =: c_1 \lambda^{-2r}$. Considering that $F(s) \geq \min F > -\infty$ and $f(s)s \leq B_1(|s|^{q+1} + |s|)$ for all $s \in \mathbb{R}$, we obtain

$$\begin{split} \lambda \int_{\Omega} f(u_{\lambda}) u_{\lambda} \, dx &= \int_{\Omega} (|\nabla u_{\lambda}|^2 + V(x) u_{\lambda}^2) \, dx + \int_{\partial \Omega_1} g(u_{\lambda}) u_{\lambda}^2 \, d\sigma \\ &= 2E_{\lambda}(u_{\lambda}) + 2\lambda \int_{\Omega} F(u_{\lambda}) \, dx - 2 \int_{\partial \Omega_1} G(u_{\lambda}) \, d\sigma + \int_{\partial \Omega_1} g(u_{\lambda}) u_{\lambda}^2 \, d\sigma \\ &\geq \frac{1}{4} (\tau \lambda^{-r})^2 + 2\lambda |\Omega| \min F - (M_g - m_g) \|u_{\lambda}\|_{L^2(\partial \Omega_1)}^2, \end{split}$$

which implies that there exists $\tilde{c} > 0$ such that $(M_g - m_g) \|u_\lambda\|_{L^2(\partial\Omega_1)}^2 + \lambda \int_{\Omega} f(u_\lambda) u_\lambda dx \ge \tilde{c}\lambda^{-2r}$. Thus, $\lim_{\lambda \to 0} \|u_\lambda\|_{\infty} = +\infty$. Nevertheless, according to (f₁),

$$\lambda \int_{\Omega} f(u_{\lambda}) u_{\lambda} \, dx \leq B_1 \lambda \int_{\Omega} (|u_{\lambda}|^{q+1} + |u_{\lambda}|) \, dx$$
$$\leq 2B_1 \lambda |\Omega| ||u_{\lambda}||_{\infty}^{q+1}$$

holds, based on the fact that $0 < \lambda < 1$. Thus, we obtain

$$\widetilde{c}\lambda^{-2r} \leq 2B_1 |\Omega|\lambda||u_\lambda||_{\infty}^{q+1} + (M_g - m_g)||u_\lambda||_{L^2(\partial\Omega_1)}^2$$
$$\leq (2B_1 |\Omega|\lambda + (M_g - m_g)|\partial\Omega_1|)||u_\lambda||_{\infty}^{q+1}.$$

Consequently, we find that

$$||u_{\lambda}||_{\infty}^{q+1} \ge d_1 \lambda^{-2r-1}$$
 or $||u_{\lambda}||_{\infty}^{q+1} \ge d_2 \lambda^{-2r}$,

where $d_1 = \frac{\tilde{c}}{2} (2B_1 |\Omega|)^{-1}$ and $d_2 = \frac{\tilde{c}}{2} ((M_g - m_g) |\partial \Omega_1|)^{-1}$, which implies that

$$||u_{\lambda}||_{\infty}^{q+1} \ge d_1 \lambda^{-2r-1}$$
 for sufficiently small λ .

By setting $M_1 = (d_1)^{\frac{1}{q+1}}$, the proof is completed.

Lemma 3.6. Let $u_{\lambda} \in H$ be the same as that in Lemma 3.3. Then, there exists $c_2 > 0$ such that

$$\|u\|_{H^1(\Omega)}^2 \le c_2 \lambda^{-2r}, \quad \forall \, \lambda \in (0, \lambda_3).$$

Proof. As $V(x) \ge 0$, according to (3.3), we obtain

(3.17)
$$\int_{\Omega} |\nabla u_{\lambda}|^2 dx + \int_{\partial \Omega_1} g(u_{\lambda}) u_{\lambda}^2 d\sigma \leq \lambda \int_{\Omega} f(u_{\lambda}) u_{\lambda} dx.$$

Multiplying (3.17) by $\left(1-\frac{2}{\theta}\right)$ and using (1.5), we find

$$\begin{split} & \left(1 - \frac{2}{\theta}\right) \left[\int_{\Omega} |\nabla u_{\lambda}|^{2} dx + \int_{\partial \Omega_{1}} g(u_{\lambda}) u_{\lambda}^{2} d\sigma\right] \\ & \leq \lambda \int_{\Omega} f(u_{\lambda}) u_{\lambda} dx - 2\lambda \int_{\Omega} \frac{1}{\theta} f(u_{\lambda}) u_{\lambda} dx \\ & \leq \lambda \int_{\Omega} f(u_{\lambda}) u_{\lambda} dx - 2\lambda \int_{\Omega} \left[F(u_{\lambda}) + \frac{C}{\theta}\right] dx \\ & \leq 2E(u_{\lambda}) - 2 \int_{\partial \Omega_{1}} G(u_{\lambda}) d\sigma + \int_{\partial \Omega_{1}} g(u_{\lambda}) u_{\lambda}^{2} d\sigma + \frac{2\lambda |C|}{\theta} \end{split}$$

Based on condition (g), we obtain

$$\left(1-\frac{2}{\theta}\right)\int_{\Omega}|\nabla u_{\lambda}|^{2}\,dx + \left(m_{g}-\frac{2M_{g}}{\theta}\right)\int_{\partial\Omega_{1}}u_{\lambda}^{2}\,d\sigma \leq 2c_{1}\lambda^{-2r} + \frac{2\lambda|C|}{\theta} \leq \bar{c}\lambda^{-2r}$$

for some $\overline{c} > 0$, which implies that $\|u\|_{H^1(\Omega)}^2 \leq c_2 \lambda^{-2r}$ with $c_2 := c_{II}^{-1} \left(1 - \frac{2}{\theta} \frac{M_g}{m_g}\right)^{-1} \overline{c}$. \Box

Proof of Theorem 1.3. Let us suppose on the contrary that there exists a sequence $\{\lambda_j\}$, $0 < \lambda_j < 1$ converging to 0 such that the measure $m(\{x \in \Omega : u_{\lambda_j}(x) \le 0\}) > 0$, where u_{λ_j} is a weak solution corresponding to λ_j . Let $w_j = \frac{u_{\lambda_j}}{\|u_{\lambda_j}\|_{\infty}}$. Then, we can write

$$\begin{cases} -\Delta w_j + V(x)w_j = \lambda f(u_{\lambda_j}) ||u_{\lambda_j}||_{\infty}^{-1}, & x \in \Omega, \\ \frac{\partial w_j}{\partial \eta} + g(u_{\lambda_j})w_j = 0, & x \in \partial \Omega_1, \\ u = 0, & x \in \partial \Omega_2. \end{cases}$$

According to Lemmas 3.5 and 3.6, there exists a constant $c_3 > 0$ such that

$$\|w_j\|_{H^1(\Omega)} \le c_3.$$

According to [7, 21, 30], the sequence $\{w_j\}$ is uniformly bounded in $C^{1,\alpha}(\overline{\Omega})$ for some $\alpha \in (0, 1)$, and thus, for any $\beta \in (0, \alpha)$, the sequence $\{w_j\}$ has a subsequence $\{w_{j_k}\}$, denoted by $\{w_j\}$ that converges in $C^{1,\beta}(\overline{\Omega})$. Let us denote its limit as w.

We establish that w > 0 on Ω . It should be noted that $p := \frac{2Nr}{N-2} > 1$ as $1 < q < \frac{N+2}{N-2}$. Then, according to (f_1) and the Sobolev embedding theorem, we obtain

$$\int_{\Omega} |f(u_{\lambda_j})|^p ||u_{\lambda_j}||_{\infty}^{-p} dx \le 2^{p-1} B^p \int_{\Omega} (u_{\lambda_j}^{p(q-1)} + 1) dx$$
$$\le C \left(||u_{\lambda_j}||_{H^1(\Omega)}^{\frac{2N}{N-2}} + 1 \right),$$

where C > 0 is a constant independent of j and, without the loss of generality, we assume that $||u_{\lambda_j}||_{\infty} > 1$. Thus, $\{\lambda_j f(u_{\lambda_j}) ||u_{\lambda_j}||_{\infty}\}$ is bounded in $L^p(\Omega)$, which implies that it converges weakly in $L^p(\Omega)$. Let $z \in L^p(\Omega)$ be its weak limit. Since $\lambda_j ||u_{\lambda_j}||_{\infty}^{-1} \to 0$ as $j \to \infty$ and $f(u_{\lambda_j})$ is bounded from below, $z \ge 0$. Now, as

$$\int_{\partial\Omega} |g(u_{\lambda_j})|^2 \, d\sigma \le M_g^2 |\partial\Omega|,$$

there exists a subsequence $\{g(u_{\lambda_{j_k}})\}$ of $\{g(u_{\lambda_j})\}$, denoted by $\{g(u_{\lambda_j})\}$, and $\tilde{g} \in L^2(\partial\Omega)$ such that $\{g(u_{\lambda_{j_k}})\}$ converges weakly to \tilde{g} in $L^2(\partial\Omega)$. Evidently, $m_g \leq \tilde{g} \leq M_g$ a.e. on $\partial\Omega$. Indeed, as $0 < m_g \leq g(u_{\lambda_j}) \leq M_g < \infty, \forall j$, it holds that

$$\int_{\partial\Omega} m_g \psi \, d\sigma \leq \int_{\partial\Omega} \widetilde{g} \psi \, d\sigma \leq \int_{\partial\Omega} M_g \psi \, d\sigma, \quad \forall \, \psi \geq 0 \text{ and } \psi \in L^2(\partial\Omega),$$

which implies that $m_g \leq \tilde{g} \leq M_g$ a.e. on $\partial \Omega$.

For $\psi \in C^{\infty}(\Omega)$, it holds that

$$\int_{\Omega} z\psi \, dx = \lim_{j \to \infty} \int_{\Omega} \lambda_j f(u_{\lambda_j}) \|u_{\lambda_j}\|_{\infty}^{-1} \psi \, dx$$
$$= \lim_{j \to \infty} \left(\int_{\Omega} (\nabla w_j \cdot \nabla \psi + V(x) w_j \psi) \, dx + \int_{\partial \Omega} g(u_{\lambda_j}) w_j \psi \, d\sigma \right)$$
$$= \int_{\Omega} (\nabla w \cdot \nabla \psi + V(x) w \psi) \, dx + \int_{\partial \Omega} \widetilde{g} w \psi \, d\sigma.$$

Thus, $-\Delta w + V(x)w = z \ge 0$ in Ω , which implies that $\min_{\overline{\Omega}} w = \min_{\partial\Omega} w$ according to the weak maximum principle. If $\min_{\partial\Omega} w \ge 0$, then the claim is proven. Suppose that there exists $x_0 \in \partial\Omega$ such that $\min_{\partial\Omega} w = w(x_0) < 0$. As w satisfies $\frac{\partial w}{\partial \eta} + \tilde{g}w = 0$ on $\partial\Omega$ and $\tilde{g} > 0$, it can be seen that $\frac{\partial w}{\partial \eta}(x_0) > 0$. This implies that there exists a local interior negative minimum. Let x_1 be its minimum point in Ω . Then, $w(x_1) < 0$ and $D_{i,j}w(x_1) \ge 0$, for all $i, j = 1, \ldots N$, which contradicts with $-\Delta w + V(x)w \ge 0$ in Ω . Thus, $w \ge 0$ on $\overline{\Omega}$. By applying the Hopf maximum principle, $\frac{\partial w}{\partial \eta}(x) < 0$ for all $x \in \partial\Omega$, which gives w > 0 on $\overline{\Omega}$.

Here, due to the convergence of $\{w_j\}$ to w in $C^{1,\beta}$, for a sufficiently large j, $w_j(x) > 0$ for all $x \in \Omega$. Therefore, $u_{\lambda_j}(x) > 0$ for all $x \in \Omega$, which contradicts the assumption on the measure $m\{x \in \Omega : u_{\lambda_j}(x) \le 0\} > 0$. This proves Theorem 1.3.

Acknowledgments

Ko was supported by a National Research Foundation of Korea (NRF) grant funded by the Korean Government (NRF-2017R1D1A1B03030681) and Sim was supported by a National Research Foundation of Korea (NRF) grant funded by the Korean Government (NRF2018R1D1A3A03000678).

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