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# HALF LIGHTLIKE SUBMANIFOLDS IN INDEFINITE $\mathcal{S}$-MANIFOLDS 

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#### Abstract

In an indefinite metric $g$.f.f-manifold, we study half lightlike submanifolds $M$ tangent to the characteristic vector fields. We discuss the existence of totally umbilical half lightlike submanifolds of an indefinite $\mathcal{S}$ space form.


## 0. Introduction

Sasakian manifolds with semi-Riemannian metric have been considered ([11]), and recently many authors ( $[2,3,8,9,10]$ ) study lightlike submanifolds of indefinite Sasakian manifolds. In analogy with the framework of Riemannian geomtery, Brunetti and Pastore [2] introduced indefinite $\mathcal{S}$-manifolds have represented a natural generalization of indefinite Sasakian manifolds. They have studied the geometry of lightlike hypersurfaces of indefinite $\mathcal{S}$-manifolds [3]. In the case of an indefinite Sasakian manifolds, Jin [10] extended lightlike hypersurfaces to half lightlike submanifolds, which is a special case of $r$-lightlike submanifolds [5] such that $r=1$ and its geometry is more general than that of coisotropic submanifolds. It will be extended to half lightlike submanifolds on an indefinite $\mathcal{S}$-manifold.

We begin with some basic information about half lightlike submanifolds of a semi-Riemannian manifold in Section 1. Afterwards, for an indefinite metric $g . f . f$ manifold we consider a half lightlike submanifold $M$ tangent to the charateristic vector fields, we introduce a particular screen distribution $S(T M)$, using the properties of the indefinite $\mathcal{S}$-manifold. Then we deal with totally umbilical half lightlike submanifolds of an indefinite $\mathcal{S}$-space form in Section 3.

## 1. Lightlike Submanifolds

It is well known that the radical distribution $\operatorname{Rad}(T M)=T M \cap T M^{\perp}$ of half lightlike submanifolds $M$ of a semi-Rimannian manifold $(\bar{M}, \bar{g})$ of codimension 2

[^0]is a vector subbundle of the tangent bundle $T M$ and the normal bundle $T M^{\perp}$, of rank 1. Thus there exists complementary non-degenerate distributions $S(T M)$ and $S\left(T M^{\perp}\right)$ of $\operatorname{Rad}(T M)$ in $T M$ and $T M^{\perp}$ respectively, which called the screen and coscreen distribution on $M$, such that
\[

$$
\begin{equation*}
T M=\operatorname{Rad}(T M) \oplus_{o r t h} S(T M), T M^{\perp}=\operatorname{Rad}(T M) \oplus_{o r t h} S\left(T M^{\perp}\right) \tag{1.1}
\end{equation*}
$$

\]

where the symbol $\oplus_{\text {orth }}$ denotes the orthogonal direct sum. We denote such a half lightlike submanifold by $M=(M, g, S(T M))$. Denote by $F(M)$ the algebra of smooth functions on $M$ and by $\Gamma(E)$ the $F(M)$ module of smooth sections of any vector bundle $E$ over $M$. Choose $L \in \Gamma\left(S\left(T M^{\perp}\right)\right)$ as a unit vector field with $\bar{g}(L, L)=\omega= \pm 1$. Consider the orthogonal complementary distribution $S(T M)^{\perp}$ to $S(T M)$ in $T \bar{M}$. Certainly $\xi \in \Gamma(\operatorname{Rad}(T M))$ and $L$ belong to $\Gamma\left(S(T M)^{\perp}\right)$. Hence we have the following orthogonal decomposition

$$
S(T M)^{\perp}=S\left(T M^{\perp}\right) \oplus_{o r t h} S\left(T M^{\perp}\right)^{\perp}
$$

where $S\left(T M^{\perp}\right)^{\perp}$ is the orthogonal complementary to $S\left(T M^{\perp}\right)$ in $S(T M)^{\perp}$. For any null section $\xi$ of $\operatorname{Rad}(T M)$ on a coordinate neighborhood $\mathcal{U} \subset M$, there exists a uniquely defined null vector field $N \in \Gamma(l \operatorname{tr}(T M))$ [5] satisfying

$$
\begin{equation*}
\bar{g}(\xi, N)=1, \bar{g}(N, N)=\bar{g}(N, X)=\bar{g}(N, L)=0, \forall X \in \Gamma(S(T M)) \tag{1.2}
\end{equation*}
$$

We call $N, l \operatorname{tr}(T M)$ and $\operatorname{tr}(T M)=S\left(T M^{\perp}\right) \oplus_{\text {orth }} l \operatorname{tr}(T M)$ the lightlike transversal vector field, lightlike transversal vector bundle and transversal vector bundle of $M$ with respect to $S(T M)$ respectively. Thus $T \bar{M}$ is decomposed as follows:

$$
\begin{align*}
T \bar{M} & =T M \oplus \operatorname{tr}(T M)=\{\operatorname{Rad}(T M) \oplus \operatorname{tr}(T M)\} \oplus_{o r t h} S(T M)  \tag{1.3}\\
& =\{\operatorname{Rad}(T M) \oplus \operatorname{ltr}(T M)\} \oplus_{o r t h} S(T M) \oplus_{o r t h} S\left(T M^{\perp}\right)
\end{align*}
$$

Let $\bar{\nabla}$ be the Levi-Civita connection of $\bar{M}$ and $P$ the projection morphism of $\Gamma(T M)$ on $\Gamma(S(T M))$ with respect to the decomposition (1.1). The local Gauss and Weingarten formulas of $M$ and $S(T M)$ are given respectively by

$$
\begin{gather*}
\bar{\nabla}_{X} Y=\nabla_{X} Y+B(X, Y) N+D(X, Y) L  \tag{1.4}\\
\bar{\nabla}_{X} N=-A_{N} X+\tau(X) N+\rho(X) L  \tag{1.5}\\
\bar{\nabla}_{X} L=-A_{L} X+\mu(X) N  \tag{1.6}\\
\nabla_{X} P Y=\nabla_{X}^{*} P Y+C(X, P Y) \xi  \tag{1.7}\\
\nabla_{X} \xi=-A_{\xi}^{*} X-\tau(X) \xi \tag{1.8}
\end{gather*}
$$

for all $X, Y \in \Gamma(T M)$, where $\nabla$ and $\nabla^{*}$ are induced linear connections on $T M$ and $S(T M)$ respectively, $B$ and $D$ are called the local second fundamental forms of $M, C$ is called the local second fundamental form on $S(T M) . A_{N}, A_{\xi}^{*}$ and $A_{L}$ are linear operators on $T M$ and $\tau, \rho$ and $\phi$ are 1-forms on $T M$. We say that $h(X, Y)=B(X, Y) N+D(X, Y) L$ is the second fundamental tensor of $M$. Since $\bar{\nabla}$ is torsion-free, $\nabla$ is also torsion-free, and $B$ and $D$ are symmetric. From the facts $B(X, Y)=\bar{g}\left(\bar{\nabla}_{X} Y, \xi\right)$ and $D(X, Y)=\omega \bar{g}\left(\bar{\nabla}_{X} Y, L\right)$, we know that $B$ and $D$ are independent of the choice of $S(T M)$ and satisfy

$$
\begin{equation*}
B(X, \xi)=0, D(X, \xi)=-\omega \mu(X), \forall X \in \Gamma(T M) \tag{1.9}
\end{equation*}
$$

The induced connection $\nabla$ of $M$ is not metric and satisfies

$$
\begin{equation*}
\left(\nabla_{X} g\right)(Y, Z)=B(X, Y) \eta(Z)+B(X, Z) \eta(Y) \tag{1.10}
\end{equation*}
$$

for all $X, Y, Z \in \Gamma(T M)$, where $\eta$ is a 1-form on $T M$ such that

$$
\begin{equation*}
\eta(X)=\bar{g}(X, N), \forall X \in \Gamma(T M) \tag{1.11}
\end{equation*}
$$

But the connection $\nabla^{*}$ on $S(T M)$ is metric. The above three local second fundamental forms are related to their shape operators by

$$
\begin{array}{cc}
B(X, Y)=g\left(A_{\xi}^{*} X, Y\right), & \bar{g}\left(A_{\xi}^{*} X, N\right)=0, \\
C(X, P Y)=g\left(A_{N} X, P Y\right), & \bar{g}\left(A_{N} X, N\right)=0, \\
\omega D(X, P Y)=g\left(A_{L} X, P Y\right), & \bar{g}\left(A_{L} X, N\right)=\omega \rho(X), \\
\omega D(X, Y)=g\left(A_{L} X, Y\right)-\mu(X) \eta(Y), \forall X, Y \in \Gamma(T M)
\end{array}
$$

By (1.12) and (1.13), we show that $A_{\xi}^{*}$ and $A_{N}$ are $\Gamma(S(T M))$-valued shape operators related to $B$ and $C$ respectively and $A_{\xi}^{*}$ is self-adjoint on $T M$ and

$$
\begin{equation*}
A_{\xi}^{*} \xi=0 \tag{1.16}
\end{equation*}
$$

But $A_{N}$ is not self-adjoint on $S(T M)$. We know that $A_{N}$ is self-adjoint in $S(T M)$ if and only if $S(T M)$ is an integrable distribution [5]. From (1.15), we show that $A_{L}$ is not self-adjoint on $T M . A_{L}$ is self-adjoint in $T M$ if and only if $\mu(X)=0$ for all $X \in \Gamma(S(T M))$ [9]. From (1.4), (1.8) and (1.9), we have

$$
\begin{equation*}
\bar{\nabla}_{X} \xi=-A_{\xi}^{*} X-\tau(X) \xi-\omega \mu(X) L, \forall X \in \Gamma(T M) \tag{1.17}
\end{equation*}
$$

Denote by $\bar{R}$ and $R$ the curvature tensors of the connections $\bar{\nabla}$ and $\nabla$ respectively. Using the local Gauss-Weingarten formulas (1.4) $\sim$ (1.6) for $M$, we have the Gauss-Codazzi equations for $M$, for all $X, Y, Z \in \Gamma(T M)$ :

$$
\begin{align*}
& \bar{R}(X, Y) Z \\
= & R(X, Y) Z+B(X, Z) A_{N} Y-B(Y, Z) A_{N} X \\
& +D(X, Z) A_{L} Y-D(Y, Z) A_{L} X+\left\{\left(\nabla_{X} B\right)(Y, Z)\right.  \tag{1.18}\\
& -\left(\nabla_{Y} B\right)(X, Z)+\tau(X) B(Y, Z)-\tau(Y) B(X, Z) \\
& +\mu(X) D(Y, Z)-\mu(Y) D(X, Z)\} N+\left\{\left(\nabla_{X} D\right)(Y, Z)\right. \\
& \left.-\left(\nabla_{Y} D\right)(X, Z)+\rho(X) B(Y, Z)-\rho(Y) B(X, Z)\right\} L
\end{align*}
$$

## 2. Characteristic Half Lightlike Submanifolds of Indefinite $g . f . f$-Manifolds

A manifold $\bar{M}$ is called a globally framed f-manifold (or g.f.f-manifold) if it is endowed with a non null $(1,1)$-tensor field $\bar{\phi}$ of constant rank, such that $\operatorname{ker} \bar{\phi}$ is parallelizable i.e. there exist global vector fields $\overline{\xi_{\alpha}}, \alpha \in\{1, \cdots, r\}$, with their dual 1- forms $\bar{\eta}^{\alpha}$, satisfying $\bar{\phi}^{2}=-I+\sum_{\alpha=1}^{r} \bar{\eta}^{\alpha} \otimes \bar{\xi}_{\alpha}$ and $\bar{\eta}^{\alpha}\left(\bar{\xi}_{\beta}\right)=\delta_{\beta}^{\alpha}$.

The $g$.f. $f$-manifold $\left(\bar{M}^{2 n+r}, \bar{\phi}, \bar{\xi}_{\alpha}, \bar{\eta}^{\alpha}\right), \alpha \in\{1, \cdots, r\}$, is said to be an indefinite metric $g . f . f$-manifold if $\bar{g}$ is a semi-Riemannian metric, with index $\nu$, $0<\nu<2 n+r$, satisfying the following compatibility condtion

$$
\bar{g}(\bar{\phi} X, \bar{\phi} Y)=\bar{g}(X, Y)-\sum_{\alpha=1}^{r} \epsilon_{\alpha} \bar{\eta}^{\alpha}(X) \bar{\eta}^{\alpha}(Y)
$$

for any $X, Y \in \Gamma(T \bar{M})$, being $\epsilon_{\alpha}= \pm 1$ according to whether $\bar{\xi}_{\alpha}$ is spacelike or timelike. Then, for any $\alpha \in\{1, \cdots, r\}$, one has $\bar{\eta}^{\alpha}(X)=\epsilon_{\alpha} \bar{g}\left(X, \bar{\xi}_{\alpha}\right)$. An indefinite metric g.f.f-manifold is called an indefinite $\mathcal{S}$-manifold if it is normal and $d \bar{\eta}^{\alpha}=\Phi$, for any $\alpha \in\{1, \cdots, r\}$, where $\Phi(X, Y)=\bar{g}(X, \bar{\phi} Y)$ for any $X$, $Y \in \Gamma(T \bar{M})$. The normality condition is expressed by the vanishing of the tensor field $N=N_{\bar{\phi}}+2 \sum_{\alpha=1}^{r} d \bar{\eta}^{\alpha} \otimes \bar{\xi}_{\alpha}, N_{\bar{\phi}}$ the Nijenhuis torsion of $\bar{\phi}$. Furthermore, as proved in [2], the Levi-Civita connection of an indefinite $\mathcal{S}$-manifold satisfies:

$$
\begin{equation*}
\left(\bar{\nabla}_{X} \bar{\phi}\right) Y=\bar{g}(\bar{\phi} X, \bar{\phi} Y) \bar{\xi}+\bar{\eta}(Y) \bar{\phi}^{2}(X) \tag{2.1}
\end{equation*}
$$

where $\bar{\xi}=\sum_{\alpha=1}^{r} \bar{\xi}_{\alpha}$ and $\bar{\eta}=\sum_{\alpha=1}^{r} \epsilon_{\alpha} \bar{\eta}^{\alpha}$. We recall that $\bar{\nabla}_{X} \bar{\xi}_{\alpha}=-\epsilon_{\alpha} \bar{\phi} X$ and $\operatorname{ker} \bar{\phi}$ is an integrable flat distribution since $\bar{\nabla}_{\bar{\xi}_{\alpha}} \bar{\xi}_{\beta}=0$.( more details in [2]).

An indefinite $\mathcal{S}$-manifold $\left(\bar{M}, \bar{\phi}, \bar{\xi}_{\alpha}, \bar{\eta}^{\alpha}\right)$ is called an indefinite $\mathcal{S}$-space form, denoted by $\bar{M}(c)$, if it has the constant $\bar{\phi}$-sectional curvature $c$ [2]. The curvature
tensor $\bar{R}$ of this space form $\bar{M}(c)$ is given by

$$
\begin{align*}
& 4 \bar{R}(X, Y, Z, W) \\
= & -(c+3 \epsilon)\{\bar{g}(\bar{\phi} Y, \bar{\phi} Z) \bar{g}(\bar{\phi} X, \bar{\phi} W)-\bar{g}(\bar{\phi} X, \bar{\phi} Z) \bar{g}(\bar{\phi} Y, \bar{\phi} W)\} \\
& -(c-\epsilon)\{\Phi(W, X) \Phi(Z, Y)-\Phi(Z, X) \Phi(W, Y)+2 \Phi(X, Y) \Phi(W, Z)\}  \tag{2.2}\\
& -\{\bar{\eta}(W) \bar{\eta}(X) \bar{g}(\bar{\phi} Z, \bar{\phi} Y)-\bar{\eta}(W) \bar{\eta}(Y) \bar{g}(\bar{\phi} Z, \bar{\phi} X) \\
& +\bar{\eta}(Y) \bar{\eta}(Z) \bar{g}(\bar{\phi} W, \bar{\phi} X)-\bar{\eta}(Z) \bar{\eta}(X) \bar{g}(\bar{\phi} W, \bar{\phi} Y)\}
\end{align*}
$$

for any vector fields $X, Y, Z, W \in \Gamma(T \bar{M})$.
Theorem 2.1. Let $M$ be a half lightlike submanifold of an indefinite $\mathcal{S}$-manifold $\bar{M}$ such that all the charateristic vector fields $\bar{\xi}_{\alpha}$ are tangent to $M$. Then there exist a screen $S(T M)$ such that

$$
\bar{\phi}\left(S(T M)^{\perp}\right) \subset S(T M) .
$$

Proof. Since $\bar{\phi}$ is skew symmetric with respect to $\bar{g}$, we have $\bar{g}(\bar{\phi} \xi, \xi)=0$. Thus $\bar{\phi} \xi$ blongs to $T M \oplus S\left(T M^{\perp}\right)$. If $\operatorname{Rad}(T M) \cap \bar{\phi}(\operatorname{Rad}(T M)) \neq\{0\}$, then there exists a non-vanishing smooth real valued function $f$ such that $\bar{\phi} \xi=f \xi$. Apply $\bar{\phi}$ to the equation and $\bar{\phi}$-properties, we have $\left(f^{2}+1\right) \xi=0$. Therefore, we get $f^{2}+1=0$, which is a contradition. Thus $\operatorname{Rad}(T M) \cap \bar{\phi}(\operatorname{Rad}(T M))=$ $\{0\}$. Moreover, if $S\left(T M^{\perp}\right) \cap \bar{\phi}(\operatorname{Rad}(T M)) \neq\{0\}$, then there exists a nonvanishing smooth real valued function $h$ such that $\bar{\phi} \xi=h L$. In this case, we have $h^{2}=\bar{g}(h L, h L)=\bar{g}(\bar{\phi} \xi, \bar{\phi} \xi)=0$, which is a contradiction to $h \neq 0$. Thus we have $S\left(T M^{\perp}\right) \cap \bar{\phi}(\operatorname{Rad}(T M))=\{0\}$. This enables one to choose a screen distribution $S(T M)$ such that it cotains $\bar{\phi}(\operatorname{Rad}(T M))$ as a vector subbundle. From the facts $\bar{g}(\bar{\phi} N, N)=0$ and $\bar{g}(\bar{\phi} N, \xi)=-\bar{g}(N, \bar{\phi} \xi)=0$, using the above method, we also show that $\bar{\phi}(\operatorname{trr}(T M))$ is a vector subbundle of $S(T M)$ of rank 1 . On the other hand, from the facts $\bar{g}(\bar{\phi} L, L)=0, \bar{g}(\bar{\phi} L, \xi)=-\bar{g}(L, \bar{\phi} \xi)=0$ and $\bar{g}(\bar{\phi} L, N)=-\bar{g}(L, \bar{\phi} N)=0$, we show that $\bar{\phi}\left(S\left(T M^{\perp}\right)\right)$ is also a vector subbundle of $S(T M)$.

Note 2. Although $S(T M)$ is not unique, it is canonically isomorphic to the factor vector bundle $T M^{*}=T M / \operatorname{Rad}(T M)$ considered by Kupeli [12]. Thus all screens $S(T M)$ are mutually isomorphic. For this reason, we consider only half lightlike submanifolds equipped with a screen $S(T M)$ such that $\bar{\phi}\left(S(T M)^{\perp}\right) \subset$ $S(T M)$. We call such a screen $S(T M)$ the generic screen of $M$.

Definition 1. Let $M$ be a half lightlike submanifold of $\bar{M}$ such that all the charateristic vector fields $\bar{\xi}_{\alpha}$ are tangent to $M$. A screen distribution $S(T M)$ is said to be characteristic if $\operatorname{ker} \bar{\phi} \subset S(T M)$ and $\bar{\phi}\left(S(T M)^{\perp}\right) \subset \Gamma(S(T M))$.

Definition 2. A half lightlike submanifold $M$ of $\bar{M}$ is said to be characteristic if $\operatorname{ker} \bar{\phi} \subset T M$ and a characteristic screen distribution $(S(T M))$ is chosen.

Proposition 2.1. [3]. Let $(M, g, S(T M))$ be a lightlike hypersurface of an indefinite $\mathcal{S}$-manifold $\left(\bar{M}, \bar{\phi}, \bar{\xi}_{\alpha}, \bar{\eta}^{\alpha}, \bar{g}\right)$. Then $M$ is a characteristic lightlike submanifold of $\bar{M}$.

By Theorem 2.1, the characteristic screen $S(T M)$ is expressed as follow:

$$
S(T M)=\{\bar{\phi}(\operatorname{Rad}(T M)) \oplus \bar{\phi}(l t r(T M))\} \oplus_{o r t h} \bar{\phi}\left(S\left(T M^{\perp}\right) \oplus_{o r t h} D_{o}\right.
$$

where $D_{o}$ is the uniquely defined non-degenerate ditribution. Then each $\bar{\xi}_{\alpha} \in D_{o}$ and the general decompositions (1.1) and (1.3) reduce to

$$
\begin{gather*}
T M=D_{o} \oplus \mathcal{F}  \tag{2.3}\\
T \bar{M}=D_{o} \oplus \mathcal{E}  \tag{2.4}\\
T M=D \oplus \bar{\phi}(l \operatorname{tr}(T M)) \oplus \bar{\phi}\left(S\left(T M^{\perp}\right)\right) \tag{2.5}
\end{gather*}
$$

where $D:=D_{o} \oplus \bar{\phi}(\operatorname{Rad}(T M)) \oplus \operatorname{Rad}(T M)$ and

$$
\begin{aligned}
\mathcal{E} & :=\{\bar{\phi}(\operatorname{Rad}(T M)) \oplus \bar{\phi}(\operatorname{ltr}(T M))\} \oplus\left\{\operatorname{Rad}(T M) \oplus \operatorname{ltr}(T M) \oplus S\left(T M^{\perp}\right)\right\} \\
\mathcal{F} & :=\{\bar{\phi}(\operatorname{Rad}(T M)) \oplus \bar{\phi}(l \operatorname{tr}(T M))\} \oplus \operatorname{Rad}(T M)
\end{aligned}
$$

Similar to the definition of $\bar{\phi}$-invariant submanifold([1], p122), we adopt the condtion $\bar{\phi}(\mathcal{V}) \subseteq \mathcal{V}$ for the $\bar{\phi}$-invariance of a distribution $\mathcal{V}$. Then $D_{0}$ and $D$ are $\bar{\phi}$ invariant. Obviously, considering the orthogoanl decompositions $D_{o}=D_{o}^{\prime} \perp \operatorname{ker} \phi$ and $D=D^{\prime} \perp \operatorname{ker} \phi$, we get $\bar{\phi}\left(D_{o}^{\prime}\right)=D_{o}^{\prime}, \bar{\phi}\left(D^{\prime}\right)=D^{\prime}$, and the decompositions in (2.3) $\sim(2.5)$ are reduced. For example,

$$
T M=D_{o}^{\prime} \oplus \operatorname{ker} \phi \oplus \mathcal{F}
$$

Now, Consider null vector fields $U$ and $V$, and a non-null vector field $W$ such that

$$
\begin{equation*}
U=-\bar{\phi} N, \quad V=-\bar{\phi} \xi, \quad W=-\bar{\phi} L \tag{2.6}
\end{equation*}
$$

Denote by $S$ the projection morphism of $T M$ on $D$. From (3.3) any vector field $X$ on $M$ is expressed as follows

$$
\begin{equation*}
X=S X+u(X) U+w(X) W, \quad \bar{\phi} X=\phi X+u(X) N+w(X) L \tag{2.7}
\end{equation*}
$$

where $u, v$ and $w$ are 1-forms locally defined on $M$ by

$$
\begin{equation*}
u(X)=g(X, V), \quad v(X)=g(X, U), \quad w(X)=\epsilon g(X, W) \tag{2.8}
\end{equation*}
$$

and $\phi$ is a tensor field of type $(1,1)$ globally defined on $M$ by

$$
\phi X=\bar{\phi} S X, \quad \forall X \in \Gamma(T M)
$$

We note that if $X \in \Gamma(T M)$, then $S X \in C, \phi X=\bar{\phi}(S X) \in D$, so that $S(\phi X)=\phi X$. Furthermore, since $\bar{\phi}(\phi X)=\bar{\phi}(S \phi X)=\bar{\phi} S(\phi X)=\phi^{2} X$, we can write $\phi^{2} X=-X+\bar{\eta}^{\alpha}(X) \bar{\xi}_{\alpha}+u(X) U+w(X) W$ by applying $\bar{\phi}$ to the second equation in (2.7). Finally, since $U \in \bar{\phi}(l \operatorname{tr}(T M))$ and $W \in \bar{\phi}\left(S\left(T M^{\perp}\right)\right)$, we have $\phi U=0, \phi W=0, \bar{\eta}^{\alpha} \circ \phi=0$, and $u(\phi X)=0, w(\phi X)=0$ for any $X \in \Gamma(T M)$. Thus we can state the following:

Theorem 2.2. Let $\left(\bar{M}, \bar{\phi}, \bar{\xi}_{\alpha}, \bar{\eta}^{\alpha}\right)$ be an indefinite $\mathcal{S}$-manifold, and let $(M, g$, $S(T M)$ ) be a characteristic half lightlike submanifold of $\bar{M}$ such that $\xi$ and $N$ are globally defined on $M$. Then $\left(\bar{M}, \bar{\phi}, \bar{\xi}_{\alpha}, U, L, \bar{\eta}^{\alpha}, u, w\right)$ is a g.f.f-manifold.

For any $X, Y \in \Gamma(T M)$, we compute the field $\left(\nabla_{X} \phi\right) Y$. Using (1.4), (1.5) and (2.7), we get

$$
\begin{aligned}
\left(\bar{\nabla}_{X} \bar{\phi}\right) Y= & \left(\nabla_{X} \phi\right) Y-u(Y) A_{N} X-w(Y) A_{L} X \\
& +\left\{B(X, \phi Y)+\left(\nabla_{X} u\right)(Y)+u(Y) \tau(X)+w(Y) \varphi(X)\right\} N \\
& +\left\{D(X, \phi Y)+\left(\nabla_{X} w\right) Y+u(Y) \phi(X)\right\} L \\
& +B(X, Y) U+D(X, Y) W
\end{aligned}
$$

then, from (2.1), comparing the components along $T M, \operatorname{ltr}(T M)$ and $S\left(T M^{\perp}\right)$, we have:

$$
\begin{align*}
\left(\nabla_{X} \phi\right) Y= & u(Y) A_{N} X+w(Y) A_{L} X-B(X, Y) U \\
& -D(X, Y) W+\bar{g}(\bar{\phi} X, \bar{\phi} Y) \bar{\xi}+\bar{\eta}(Y) \bar{\phi}^{2}(X)  \tag{2.9}\\
\left(\nabla_{X} u\right)(Y)= & -B(X, \phi Y)-u(Y) \tau(X)-w(Y) \varphi(X) \tag{2.10}
\end{align*}
$$

Definition 3. Let $\left(\bar{M}, \bar{\phi}, \bar{\xi}_{\alpha}, \bar{\eta}^{\alpha}, \bar{g}\right)$ be an indefinite $g . f . f$-manifold and $(M, g$, $S(T M)$ ) a half lightlike submanifold of $\bar{M}$. Then $M$ is called totally geodesic if any geodesic of $M$ with respect to the induced connection $\nabla$ is a geodesic of $M$ with respect to $\bar{\nabla}$.

It is easy to see that $M$ is totally geodesic if and only if the local second fundamental forms $B, D$ vanish identically.(i.e., $B \equiv 0$ and $D \equiv 0$ )

Theorem 2.3. Let $\left(\bar{M}, \bar{\phi}, \bar{\xi}_{\alpha}, \bar{\eta}^{\alpha}, \bar{g}\right)$ be an indefinite $\mathcal{S}$-manifold and $(M, g$, $S(T M))$ a half lightlike submanifold of $\bar{M}$. Then $M$ is totally geodesic if and only if for any $X \in \Gamma(T M)$ and for any $Y \in \Gamma(D)$,

$$
\begin{align*}
\left(\nabla_{X} \phi\right) Y & =\bar{g}(\bar{\phi} X, \bar{\phi} Y) \bar{\xi}+\bar{\eta}(Y) \bar{\phi}^{2}(X)  \tag{2.12}\\
A_{N} X & =-\left(\nabla_{X} \phi\right) U+\bar{g}(X, U) \bar{\xi}  \tag{2.13}\\
A_{L} X & =-\left(\nabla_{X} \phi\right) W+\bar{g}(X, W) \bar{\xi} \tag{2.14}
\end{align*}
$$

Proof. We assume that $M$ is totally geodesic, that is for all $X, Y \in \Gamma(T M)$, $B(X, Y) \equiv 0$ and $D(X, Y) \equiv 0$. In (2.9), for any $Y \in \Gamma(D)$, we have $u(Y)=0$ and $w(Y)$, and hence $\left(\nabla_{X} \phi\right) Y=\bar{g}(\bar{\phi} X, \bar{\phi} Y) \bar{\xi}+\bar{\eta}(Y) \bar{\phi}^{2}(X)$. Again, replacing $Y$ in (2.9) by $U$, we have $\left(\nabla_{X} \phi\right) U=A_{N} X+\bar{g}(\bar{\phi} X, \bar{\phi} U) \bar{\xi}+\bar{\eta}(U) \bar{\phi}^{2}(X)$, from which we obtain $A_{N} X=-\left(\nabla_{X} \phi\right) U+\bar{g}(X, U) \bar{\xi}$ In analogy with (2.13), we have $A_{L} X=-\left(\nabla_{X} \phi\right) W+\bar{g}(X, W) \bar{\xi}$

Conversely, we suppose that the conditions (2.12), (2.13), and (2.14) hold. If $Y \in \Gamma(T M)$, using decompositon (2.5), there exists locally smooth functions $f$ and $h$ such that $Y=Y_{d}+f U+h W$, and for any $X \in \Gamma(T M)$, we obtain $B(X, Y)=$ $B\left(X, Y_{d}\right)+f B(X, U)+h B(X, W)$ and $D(X, Y)=D\left(X, Y_{d}\right)+f D(X, U)+$ $h D(X, W)$. Using (2.9) and (2.12) with $Y=Y_{d}$, we find $B\left(X, Y_{d}\right) U+D\left(X, Y_{d}\right) W=$ $u\left(Y_{d}\right) A_{N} X+w\left(Y_{d}\right) A_{L} X=0$, which implies $B\left(X, Y_{d}\right)=D\left(X, Y_{d}\right)=0$. From (2.9), putting $Y=U$ and using (2.13), we get $B(X, U) U+D(X, U) W=0$, which implies $B(X, U)=D(X, U)=0$. Again, from (2.9), putting $Y=W$ and using (2.14), we get $B(X, W) U+D(X, W) W=0$, which implies $B(X, W)=$ $D(X, W)=0$. The proof is complete.

## 3. Totally Umbilical Half Lightlike Submanifolds of an Indefinite $\mathcal{S}$-MANIFOLD

Definition 4. Let $\left(\bar{M}, \bar{\phi}, \bar{\xi}_{\alpha}, \bar{\eta}^{\alpha}, \bar{g}\right)$ be an indefinite $\mathcal{S}$-manifold and $(M, g$, $S(T M)$ ) a half lightlike submanifold of $\bar{M}$. We say that $M$ is totally umbilical [6] if, on any coordinate neighborhood $\mathcal{U}$, there is a smooth vector field $\mathcal{H} \in \Gamma(\operatorname{tr}(T M))$ such that

$$
h(X, Y)=\mathcal{H} g(X, Y), \forall X, Y \in \Gamma(T M) .
$$

In case $\mathcal{H}=0$ on $\mathcal{U}$, we say that $M$ is totally geodesic.
It is easy to see that $M$ is totally umbilical if and only if, on each coordinate neighborhood $\mathcal{U}$, there exist smooth functions $\beta$ and $\delta$ such that

$$
\begin{equation*}
B(X, Y)=\beta g(X, Y), D(X, Y)=\delta g(X, Y), \forall X, Y \in \Gamma(T M) . \tag{3.1}
\end{equation*}
$$

Theorem 3.1. Let $M$ be a totally umbilical half lightlike submanifold of an indefinite $\mathcal{S}$-manifold $\bar{M}$. Then $M$ is totally geodesic.

Proof. Apply the operator $\bar{\nabla}_{X}$ to $\bar{g}(\bar{\phi} \xi, L)=0$ with $X \in \Gamma(T M)$ and use (1.5), (1.6), (1.12), (1.14) and (1.17), we have

$$
B(X, \bar{\phi} L)=D(X, \bar{\phi} \xi), \forall X \in \Gamma(T M) .
$$

As $M$ is totally umbilical, from the last equation and (3.1), we have

$$
\beta g(X, \bar{\phi} L)=\omega \delta g(X, \bar{\phi} \xi), \forall X \in \Gamma(T M) .
$$

Replace $X$ by $\bar{\phi} N$ and $\bar{\phi} L$ in this equation by turns, we have

$$
\begin{equation*}
0=\omega \delta, \quad \omega \beta=0 \tag{3.2}
\end{equation*}
$$

Thus we have $\mathcal{H}=0$.
Theorem 3.2. Let $\left(\bar{M}(c), \bar{\phi}, \bar{\xi}_{\alpha}, \bar{\eta}^{\alpha}, \bar{g}\right)$ be an indefinite $\mathcal{S}$-space form and ( $M, g, S(T M)$ ) a half lightlike submanifold of $\bar{M}$. If $(M, g, S(T M))$ is totally umbilical, then $c=\epsilon=\sum_{\alpha=1}^{r} \epsilon_{\alpha}$.

Proof. Since $\bar{\eta}(\xi)=0$ and $\bar{g}(\bar{\phi} \xi, \bar{\phi} X)=0$ for any $X \in \Gamma(T M), \bar{M}(c)$ is an indefinite $\mathcal{S}$-space form implies the Riemannian curvature $\bar{R}$ in (2.2) is given by

$$
\begin{align*}
& 4 \bar{R}(X, Y, Z, \xi) \\
= & -(c-\epsilon)\{\Phi(\xi, X) \Phi(Z, Y)-\Phi(Z, X) \Phi(\xi, Y)+2 \Phi(X, Y) \Phi(\xi, Z)\}  \tag{3.3}\\
= & -(c-\epsilon)\{\bar{g}(V, X) \Phi(Z, Y)-\Phi(Z, X) \bar{g}(V, Y)+2 \Phi(X, Y) \bar{g}(V, Z)\},
\end{align*}
$$

for any $X, Y, Z, \in \Gamma(T M)$. So, replacing $X, Y, Z$ by $P X, \xi, P Z$ in (3.3), we find

$$
\begin{align*}
& 4 \bar{R}(X, Y, Z, \xi) \\
= & -(c-\epsilon)\{-\bar{g}(V, P X) \bar{g}(P Z, V)-2 \bar{g}(X, V) \bar{g}(V, Z)\}  \tag{3.4}\\
= & 3(c-\epsilon) u(P Z) u(P X)
\end{align*}
$$

On the other hand, from (1.18), we have

$$
\begin{align*}
& \bar{R}(X, Y, Z, \xi) \\
= & \left(\nabla_{X} B\right)(Y, Z)-\left(\nabla_{Y} B\right)(X, Z)+\tau(X) B(Y, Z)  \tag{3.5}\\
- & \tau(Y) B(X, Z)+\mu(X) D(Y, Z)-\mu(Y) D(X, Z)
\end{align*}
$$

Theorem 3.1, $\bar{R}(X, Y, Z, \xi)=0$ and therefore, we have $4 \bar{R}(X, Y, Z, \xi)=3(c-$ є) $u(P Z) u(P X)$. Choosing $X=Z=U \in \Gamma(S(T M))$, we obtain $c=\epsilon$.

Corollary 3.3. There is no totally umbilical characteristic half lightlike submanifolds of an indefinite $\mathcal{S}$-space form $\bar{M}(c)$ with $c \neq \epsilon$.

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