Topological Methods in Nonlinear Analysis
Volume 49, No. 2, 2017, 647-664
DOI: 10.12775/TMNA.2017.001
(C) 2017 Juliusz Schauder Centre for Nonlinear Studies

Nicolaus Copernicus University

# INFINITELY MANY POSITIVE SOLUTIONS OF FRACTIONAL BOUNDARY VALUE PROBLEMS 

Bin Ge - Vicenţiu D. Rădulescu - Ji-Chun Zhang


#### Abstract

We are concerned with the qualitative analysis of solutions of a class of fractional boundary value problems with Dirichlet boundary conditions. By combining a direct variational approach with the theory of the fractional derivative spaces, we establish the existence of infinitely many distinct positive solutions whose $E^{\alpha}$-norms and $L^{\infty}$-norms tend to zero (to infinity, respectively) whenever the nonlinearity oscillates at zero (at infinity, respectively).


## 1. Introduction and statement of main result

In this paper, we consider the fractional boundary value problem of the following form:
(P) $\left\{\begin{array}{l}\frac{d}{d t}\left(\frac{1}{2}{ }_{0} D_{t}^{-\beta}\left(u^{\prime}(t)\right)+\frac{1}{2}{ }_{0} D_{T}^{-\beta}\left(u^{\prime}(t)\right)\right)+\nabla F(t, u(t))=0 \quad \text { a.a. } t \in[0, T], \\ u(0)=u(T)=0,\end{array}\right.$

2010 Mathematics Subject Classification. Primary: 35J20, 35J70; Secondary: 35R20.
Key words and phrases. Fractional differential equation; oscillatory nonlinearities; infinitely many solutions; variational methods.

Supported by the National Natural Science Foundation of China (Nos. 11201095, 11201098), the Youth Scholar Backbone Supporting Plan Project of Harbin Engineering University, the Fundamental Research Funds for the Central Universities, Postdoctoral research startup foundation of Heilongjiang (No. LBH-Q14044) and the Science Research Funds for Overseas Returned Chinese Scholars of Heilongjiang Province (No. LC201502).
V. Rădulescu was supported by Partnership Program in Priority Areas PN II, MEN UEFISCDI, project number PN-II-PT-PCCA-2013-4-0614.
where ${ }_{0} D_{t}^{-\beta}$ and ${ }_{0} D_{T}^{-\beta}$ are the left and right Riemann-Liouville fractional integrals of order $0 \leq \beta<1$, respectively, $F:[0, T] \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a given function and $\nabla F(t, x)$ is the gradient of $F$ at $x$.

Fractional differential equations are very efficient tools for the mathematical description of numerous phenomena in various fields of science and engineering, such as, viscoelasticity, electrochemistry, electromagnetism, economics, optimal control, porous media, etc., see [2], [4], [7], [14], [16]. In consequence, the subject of fractional differential equations is gaining much importance and attention. For details and examples, we refer to [8], [23], [13], [21], [10] and the references therein.

During the past years, there are many papers dealing with the existence of multiple solutions of fractional boundary value problems, for example [1], [3], [5], [6], [9], [15], [18]-[20], [22]. Chen and Tang [1] studied the existence and multiplicity of solutions for system ( P ) when the nonlinearlity $F$ is superquadradic, asymptotically quadratic, and subquadratic. Jiao and Zhou [11] obtained the existence of solutions for ( P ) by the mountain pass theorem under the Ambrosetti-Rabinowitz condition. Nyamoradi obtained in [18] the existence of infinitely many non-negative solutions of problem (P). In [3], by using the variational method, the existence of at least two nontrivial solutions for $(\mathrm{P})$ is established.

The aim of the present paper is to prove the existence of infinitely many distinct positive solutions for problem (P) under suitable oscillatory assumptions on the potential $F$ at zero or at infinity. Indeed, our main results (see Theorems 1.3 and 1.6 below) give sufficient conditions on the oscillatory terms such that problem (P) has infinitely many positive solutions. As a byproduct, these solutions can be constructed in such a way that their norms in a suitable space $E^{\alpha}$ tend to zero (to infinity, respectively) whenever the nonlinearity oscillates at zero (at infinity, respectively). These results correspond to the existence of infinitely many low-energy (respectively, high-energy) solutions, according to the oscillation properties of the nonlinear term.

In the present paper, in order to establish the existence of infinitely many solutions of system ( P ) we consider two distinct cases, according to the growth of the nonlinear term near the origin, respectively, in a neighborhood of infinity.
1.1. Oscillation near the origin. Now we are in the position to state our first main result which deals with the case when the nonlinearity $F$ exhibits an oscillation at the origin. For this case, we make the following assumptions.
$\mathrm{H}(\mathrm{F})_{1} F:[0, T] \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a function such that $F(t, 0)=0$ for almost all $t \in[0, T]$ and it satisfies the following founded facts:
(1) For all $x \in \mathbb{R}^{N}, t \mapsto F(t, x)$ is measurable.
(2) For almost all $t \in[0, T], x \mapsto F(t, x)$ is continuously differentiable.
(3) There exist $c \in C([0, T], \mathbb{R})$ and $0<\alpha_{0}<+\infty$ such that

$$
|\nabla F(t, x)|,|F(t, x)| \leq c(t)\left(1+|x|^{\alpha_{0}}\right)
$$

for almost all $t \in[0, T]$ and all $x \in \mathbb{R}^{N}$.
(4) $-\infty<\liminf _{|x| \rightarrow 0^{+}} \frac{F(t, x)}{|x|^{2}} \leq \limsup _{|x| \rightarrow 0^{+}} \frac{F(t, x)}{|x|^{2}}=+\infty$ uniformly for almost every $t \in[0, T]$.
(5) For every $k \in \mathbb{N}$, there exists $e_{k} \in \mathbb{R}^{N}$ with $\left|e_{k}\right|=1$ and there are two sequences $\left\{a_{k}\right\}$ and $\left\{b_{k}\right\}$ in $(0,+\infty)$ with $a_{k}<b_{k}, \lim _{k \rightarrow+\infty} b_{k}=0$ such that $\nabla F(t, \xi) \cdot e_{k} \leq 0$ for all $\xi \in\left[a_{k}, b_{k}\right] e_{k}$.

Remark 1.1. Hypotheses $\mathrm{H}(\mathrm{F})_{1}(4)$ and $\mathrm{H}(\mathrm{F})_{1}(5)$ imply an oscillatory behaviour of $F$ near the origin.

Remark 1.2. A simple example of a potential function satisfying hypothesis $\mathrm{H}(\mathrm{F})_{1}$ is

$$
F(t, x)= \begin{cases}0 & \text { if } x=0 \\ |x|^{\alpha(t)}[1+\sin (-5 \ln |x|)] & \text { if }|x|>0\end{cases}
$$

where $1<\alpha(t)<2$ for any $t \in[0, T]$.
Proof. It is easy to verify conditions (1) and (2) in $\mathrm{H}(\mathrm{F})_{1}$.
Obviously, $x \mapsto F(t, x)$ is continuously differentiable. By straightforward computation, we have

$$
\nabla F(t, x)=x \alpha(t)|x|^{\alpha(t)-2}[1+\sin (-5 \ln |x|)]-5 x|x|^{\alpha(t)-2} \cos (-5 \ln |x|) .
$$

Set $\alpha_{0}=\max _{t \in[0, T]} \alpha(t)$, then

So condition $\mathrm{H}(\mathrm{F})_{1}(3)$ holds. Then, for any $1 \leq k \in \mathbb{N}$ we can choose

$$
a_{k}:=\exp \left(-\frac{2 k \pi}{5}-\frac{\pi}{20}\right), \quad b_{k}:=\exp \left(-\frac{2 k \pi}{5}\right)
$$

which means $a_{k}<b_{k}, \lim _{k \rightarrow+\infty} b_{k}=0$. Then, for any $\xi \in\left[a_{k}, b_{k}\right] e_{k}, e_{k} \in \mathbb{R}^{N}$ and $\left|e_{k}\right|=1$, there exists $t_{0} \in[0,1]$ such that $\xi=\left[t_{0} a_{k}+\left(1-t_{0}\right) b_{k}\right] e_{k}$. Thus,

$$
\begin{aligned}
\nabla & F(t, \xi) \cdot e \\
& =\left(\xi \alpha(t)|\xi|^{\alpha(t)-2}[1+\sin (-5 \ln |\xi|)]-5 \xi|\xi|^{\alpha(t)-2} \cos (-5 \ln |\xi|)\right) \cdot e_{k} \\
& =\left(\alpha(t)|\xi|^{\alpha(t)-2}[1+\sin (-5 \ln |\xi|)]-5|\xi|^{\alpha(t)-2} \cos (-5 \ln |\xi|)\right) \xi \cdot e_{k} \\
& =(\alpha(t)[1+\sin (-5 \ln |\xi|)]-5 \cos (-5 \ln |\xi|))\left[t_{0} a_{k}+\left(1-t_{0}\right) b_{k}\right]^{\alpha(t)-2} \leq 0 .
\end{aligned}
$$

So condition $\mathrm{H}(\mathrm{F})_{1}(5)$ is satisfied.

To verify $\mathrm{H}(\mathrm{F})_{1}$ (4), we can choose

$$
x_{k}=\exp \left(-\frac{2 k \pi}{5}-\frac{3 \pi}{10}\right) e_{k} \quad \text { and } \quad y_{k}=\exp \left(-\frac{2 k \pi}{5}-\frac{\pi}{10}\right) e_{k}, \quad k \geq 1
$$

such that

$$
\begin{aligned}
& \liminf _{|x| \rightarrow 0^{+}} \frac{F(t, x)}{|x|^{2}}=\lim _{k \rightarrow+\infty} \frac{F\left(t, x_{k}\right)}{\left|x_{k}\right|^{2}} \\
& \quad=\lim _{k \rightarrow+\infty}\left[\exp \left(-\frac{2 k \pi}{5}-\frac{3 \pi}{10}\right)\right]^{\alpha(t)-2}\left(1+\sin \left(2 k \pi+\frac{3}{2} \pi\right)\right)=0>-\infty, \\
& \limsup _{|x| \rightarrow 0^{+}} \frac{F(t, x)}{|x|^{2}}=\lim _{k \rightarrow+\infty} \frac{F\left(t, y_{k}\right)}{\left|y_{k}\right|^{2}} \\
& \quad=\lim _{k \rightarrow+\infty}\left[\exp \left(-\frac{2 k \pi}{5}-\frac{\pi}{10}\right)\right]^{\alpha(t)-2}\left(1+\sin \left(2 k \pi+\frac{1}{2} \pi\right)\right)=+\infty
\end{aligned}
$$

uniformly for almost every $t \in[0, T]$. So condition $\mathrm{H}(\mathrm{F})_{1}(4)$ holds.
Theorem 1.3. Suppose that $\mathrm{H}(\mathrm{F})_{1}$ holds. Then there exists a sequence $\left\{u_{n}\right\} \subset E^{\alpha}$ of distinct positive solutions of problem ( P ) such that

$$
\lim _{n \rightarrow+\infty}\left\|u_{n}\right\|_{\alpha}=\lim _{n \rightarrow+\infty}\left|u_{n}\right|_{\infty}=0 .
$$

1.2. Oscillation at infinity. Next, we state the counterpart of Theorem 1.3 when the nonlinearity oscillates at infinity. The hypotheses on the potential $F$ are the following:
$\mathrm{H}(\mathrm{F})_{2} F:[0, T] \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a function such that $F(t, 0)=0$ for almost all $t \in[0, T]$ and it satisfies the following founded facts:
(1) For all $x \in \mathbb{R}^{N}, t \mapsto F(t, x)$ is measurable.
(2) For almost all $t \in[0, T], x \mapsto F(t, x)$ is continuously differentiable.
(3) There exist $c \in C([0, T], \mathbb{R})$ and $0<\alpha_{0}<+\infty$ such that

$$
|\nabla F(t, x)|,|F(t, x)| \leq c(t)\left(1+|x|^{\alpha_{0}}\right)
$$

for almost all $t \in[0, T]$ and all $x \in \mathbb{R}^{N}$.
(4) $-\infty<\liminf _{|x| \rightarrow+\infty} \frac{F(t, x)}{|x|^{2}} \leq \limsup _{|x| \rightarrow+\infty} \frac{F(t, x)}{|x|^{2}}=+\infty$ uniformly for almost every $x \in \mathbb{R}^{N}$.
(5) For every $k \in \mathbb{N}$, there exist $e_{k} \in \mathbb{R}^{N}$ with $\left|e_{k}\right|=1$ and there are two sequences $\left\{a_{k}\right\}$ and $\left\{b_{k}\right\}$ in $(0,+\infty)$ with $a_{k}<b_{k}, \lim _{k \rightarrow+\infty} a_{k}=+\infty$ such that $\nabla F(t, \xi) \cdot e_{k} \leq 0$ for all $\xi \in\left[a_{k}, b_{k}\right] e_{k}$.

Remark 1.4. Hypotheses $\mathrm{H}(\mathrm{F})_{2}$ (4) and $\mathrm{H}(\mathrm{F})_{2}$ (5) imply an oscillatory behaviour of $F$ near the infinity.

REmARK 1.5. A simple example of a potential function satisfying hypothesis $\mathrm{H}(\mathrm{F})_{2}$ is

$$
F(t, x)= \begin{cases}0 & \text { if } x=0 \\ |x|^{\alpha(t)}(1+\sin |x|) & \text { if }|x|>0\end{cases}
$$

where $2<\alpha(t)<\pi$ for any $t \in[0, T]$.
Proof. One can easily check that hypotheses (1) and (2) of $\mathrm{H}(\mathrm{F})_{2}$ are satisfied.

Obviously, $x \mapsto F(t, x)$ is continuously differentiable. Then

$$
\nabla F(t, x)= \begin{cases}0 & \text { if } x=0 \\ \alpha(t) x|x|^{\alpha(t)-2}(1+\sin |x|)+x|x|^{\alpha(t)-1} \cos |x| & \text { if }|x|>0\end{cases}
$$

Let $\alpha_{0}=\max _{t \in[0, T]} \alpha(t)$. Then

$$
|F(t, x)| \leq\left|| x | ^ { \alpha ( t ) } \left(1+\left.\sin (|x|)|\leq 2| x\right|^{\alpha(t)} \leq 2\left(1+|x|^{\alpha_{0}}\right)\right.\right.
$$

for all $x \in \mathbb{R}^{N}$ and all $t \in[0, T]$, and

$$
\begin{aligned}
|\nabla F(t, x)| & =\left.|\alpha(t) x| x\right|^{\alpha(t)-2}(1+\sin |x|)+x|x|^{\alpha(t)-1} \cos |x| \mid \\
& \leq 2|\alpha(t)||x|^{\alpha(t)-1}+|x|^{\alpha(t)} \leq\left(2 \alpha_{0}+1\right)\left(1+|x|^{\alpha_{0}}\right) .
\end{aligned}
$$

So condition $\mathrm{H}(\mathrm{F})_{2}(3)$ holds. Then, for any $1 \leq k \in \mathbb{N}$ we can choose

$$
a_{k}:=(2 k+1) \pi, \quad b_{k}:=\left(2 k+\frac{3}{2}\right) \pi,
$$

which means $a_{k}<b_{k}, \lim _{k \rightarrow+\infty} a_{k}=+\infty$ and, for any $\xi \in\left[a_{k}, b_{k}\right] e_{k}$ there exists $\lambda_{0} \in[0,1]$ such that $\xi=\left[\lambda_{0} a_{k}+\left(1-\lambda_{0}\right) b_{k}\right] e_{k}$, so

$$
\begin{aligned}
\nabla & F(t, \xi) \cdot e_{k} \\
& =\left(\alpha(t) \xi|\xi|^{\alpha(t)-2}(1+\sin |\xi|)+\xi|\xi|^{\alpha(t)-1} \cos |\xi|\right) \cdot e_{k} \\
& =\left(\alpha(t)|\xi|^{\alpha(t)-2}(1+\sin |\xi|)+|\xi|^{\alpha(t)-1} \cos |\xi|\right) \xi \cdot e_{k} \\
& =\left(\alpha(t)|\xi|^{\alpha(t)-2}(1+\sin |\xi|)+|\xi|^{\alpha(t)-1} \cos |\xi|\right)\left(\lambda_{0} a_{k}+\left(1-\lambda_{0}\right) b_{k}\right) \leq 0 .
\end{aligned}
$$

So condition $\mathrm{H}(\mathrm{F})_{2}$ (5) is satisfied. To verify $\mathrm{H}(\mathrm{F})_{2}$ (4), we can choose

$$
x_{k}:=\left(2 k+\frac{1}{2}\right) \pi e_{k}, \quad y_{k}:=\left(2 k+\frac{3}{2}\right) \pi e_{k},
$$

which implies

$$
\begin{aligned}
\liminf _{k \rightarrow+\infty} \frac{F(t, x)}{|x|^{2}} & =\lim _{k \rightarrow+\infty} \frac{F\left(t, y_{k}\right)}{\left|y_{k}\right|^{2}} \\
& =\lim _{k \rightarrow+\infty} \frac{\left|(2 k+3 / 2) \pi e_{k}\right|^{\alpha(t)}\left(1+\sin \left|(2 k+3 / 2) \pi e_{k}\right|\right)}{\left|(2 k+3 / 2) \pi e_{k}\right|^{2}} \\
& =\lim _{k \rightarrow+\infty}\left[\left(2 k+\frac{3}{2}\right) \pi\right]^{\alpha(t)-2}\left(1+\sin \left[\left(2 k+\frac{3}{2}\right) \pi\right]\right)=0>-\infty \\
\limsup _{k \rightarrow+\infty} \frac{F(t, x)}{|x|^{2}} & =\lim _{k \rightarrow+\infty} \frac{F\left(t, y_{k}\right)}{\left|y_{k}\right|^{2}} \\
& =\lim _{k \rightarrow+\infty} \frac{\left|(2 k+1 / 2) \pi e_{k}\right|^{\alpha(t)}\left(1+\sin \left|(2 k+3 / 2) \pi e_{k}\right|\right)}{\left|(2 k+1 / 2) \pi e_{k}\right|^{2}} \\
& =\lim _{k \rightarrow+\infty}\left[\left(2 k+\frac{1}{2}\right) \pi\right]^{\alpha(t)-2}\left(1+\sin \left[\left(2 k+\frac{1}{2}\right) \pi\right]\right)=+\infty
\end{aligned}
$$

uniformly for almost every $t \in[0, T]$. So condition $\mathrm{H}(\mathrm{F})_{2}(4)$ holds.
Theorem 1.6. Suppose that $\mathrm{H}(\mathrm{F})_{2}$ holds. Then there exists a sequence $\left\{u_{n}\right\} \subset E^{\alpha}$ of distinct positive solutions of problem $(\mathrm{P})$ such that

$$
\lim _{n \rightarrow+\infty}\left\|u_{n}\right\|_{\alpha}=\lim _{n \rightarrow+\infty}\left|u_{n}\right|_{\infty}=+\infty
$$

## 2. Preliminaries

In this part, we recall some definitions and display the variational setting which has been established for our problem.

Definition 2.1 ([12]). Let $f$ be a function defined on $[a, b]$ and $\tau>0$. The left and right Riemann-Liouville fractional integrals of order $\tau$ for the function $f$ denoted by ${ }_{a} D_{t}^{-\tau} f$ and ${ }_{t} D_{b}^{-\tau} f$, respectively, are defined by

$$
\begin{aligned}
{ }_{a} D_{t}^{-\tau} f(t) & =\frac{1}{\Gamma(\tau)} \int_{a}^{t}(t-s)^{\tau-1} f(s) d s, \quad t \in[a, b] \\
{ }_{t} D_{b}^{-\tau} f(t) & =\frac{1}{\Gamma(\tau)} \int_{t}^{b}(t-s)^{\tau-1} f(s) d s, \quad t \in[a, b]
\end{aligned}
$$

provided the right-hand sides are pointwise defined on $[a, b]$, where $\Gamma$ is the gamma function.

Definition 2.2 ([12]). Let $f$ be a function defined on $[a, b]$. The left and right Riemann-Liouville fractional derivatives of order $\tau$ for the function $f$ denoted by ${ }_{a} D_{t}^{\tau} f$ and ${ }_{t} D_{b}^{\tau} f$, respectively, are defined by

$$
{ }_{a} D_{t}^{\tau} f(t)=\frac{d^{n}}{d t^{n}}{ }_{a} D_{t}^{\tau-n} f(t)=\frac{1}{\Gamma(n-\tau)} \frac{d^{n}}{d t^{n}}\left(\int_{a}^{t}(t-s)^{n-\tau-1} f(s) d s\right),
$$

$$
\begin{aligned}
{ }_{t} D_{b}^{\tau} f(t) & =(-1)^{n} \frac{d^{n}}{d t^{n}}{ }_{t} D_{b}^{\tau-n} f(t) \\
& =\frac{1}{\Gamma(n-\tau)} \frac{d^{n}}{d t^{n}}\left(\int_{t}^{b}(t-s)^{n-\tau-1} f(s) d s\right),
\end{aligned}
$$

where $t \in[a, b], n-1 \leq \tau<n$ and $n \in \mathbb{N}$.
The left and right Caputo fractional derivatives are defined via the above Riemann-Liouville fractional derivatives. In particular, they are defined for functions belonging to the space of absolutely continuous functions, which we denote by $A C\left([a, b], \mathbb{R}^{N}\right) . A C^{k}\left([a, b], \mathbb{R}^{N}\right)(k=1,2, \ldots)$ is the space of functions $f$ such that $f \in C^{k}\left([a, b], \mathbb{R}^{N}\right)$. In particular, $A C\left([a, b], \mathbb{R}^{N}\right)=A C^{1}\left([a, b], \mathbb{R}^{N}\right)$.

Definition 2.3 ([12]). Let $\tau \geq 0$ and $n \in \mathbb{N}$. If $\tau \in[n-1, n)$ and $f \in$ $A C^{n}\left([a, b], \mathbb{R}^{N}\right)$, then the left and right Caputo fractional derivatives of order $\tau$ for the function $f$ denoted by ${ }_{a}^{c} D_{t}^{\tau} f$ and ${ }_{t}^{c} D_{b}^{\tau} f$, respectively, exist almost everywhere on $[a, b] .{ }_{a}^{c} D_{t}^{\tau} f(t)$ and ${ }_{t}^{c} D_{b}^{\tau} f(t)$ are represented by

$$
\begin{aligned}
& { }_{a}^{c} D_{t}^{\tau} f(t)={ }_{a} D_{t}^{\tau-n} f^{(n)}(t)=\frac{1}{\Gamma(n-\tau)}\left(\int_{a}^{t}(t-s)^{n-\tau-1} f^{(n)}(s) d s\right), \\
& { }_{t}^{c} D_{b}^{\tau} f(t)=(-1)_{t}^{n} D_{b}^{\tau-n} f^{(n)}(t)=\frac{1}{\Gamma(n-\tau)}\left(\int_{t}^{b}(t-s)^{n-\tau-1} f^{(n)}(s) d s\right),
\end{aligned}
$$

respectively, where $t \in[a, b]$.
Definition 2.4 ([11]). Let $0<\alpha \leq 1$ and $1<p<\infty$. The fractional derivative space $E_{0}^{\alpha, p}$ is defined by the closure of $C_{0}^{\infty}\left([0, T], \mathbb{R}^{N}\right)$ with respect to the norm

$$
\|u\|_{\alpha, p}=\left(\int_{0}^{T}|u(t)|^{p} d t+\int_{0}^{T}\left|{ }_{0}^{c} D_{t}^{\alpha} u(t)\right|^{p} d t\right)^{1 / p} \quad \text { for all } u \in E_{0}^{\alpha, p}
$$

where $C_{0}^{\infty}\left([0, T], \mathbb{R}^{N}\right)$ denotes the set of all functions $u \in C^{\infty}\left([0, T], \mathbb{R}^{N}\right)$ with $u(0)=u(T)=0$. It is obvious that the fractional derivative space $E_{0}^{\alpha, p}$ is the space of functions $u \in L^{p}\left([0, T], \mathbb{R}^{N}\right)$ having an $\alpha$-order Caputo fractional derivative ${ }_{0}^{c} D_{t}^{\alpha} u \in L^{p}\left([0, T], \mathbb{R}^{N}\right)$ and $u(0)=u(T)=0$.

Proposition 2.5 ([11]). Let $0<\alpha \leq 1$ and $1<p<\infty$. The fractional derivative space $E_{0}^{\alpha, p}$ is a reflexive and separable space.

Proposition 2.6 ([11]). Let $0<\alpha \leq 1$ and $1<p<\infty$. For all $u \in E_{0}^{\alpha, p}$ we have

$$
\|u\|_{L^{p}} \leq \frac{T^{\alpha}}{\Gamma(\alpha+1)}\left\|_{0}^{c} D_{t}^{\alpha} u\right\|_{L^{p}}
$$

Moreover, if $\alpha>1 / p$ and $1 / p+1 / q=1$, then

$$
\begin{equation*}
\|u\|_{\infty} \leq \frac{T^{(\alpha-1) / p}}{\Gamma(\alpha)((\alpha-1) q+1)^{1 / q}}\left\|_{0}^{c} D_{t}^{\alpha} u\right\|_{L^{p}} . \tag{2.1}
\end{equation*}
$$

According to (2.1), we can consider $E_{0}^{\alpha, p}$ with respect to the norm

$$
\|u\|_{\alpha, p}=\left\|_{0}^{c} D_{t}^{\alpha} u\right\|_{L^{p}}=\left(\int_{0}^{T}\left|{ }_{0}^{c} D_{t}^{\alpha} u\right|^{p} d t\right)^{1 / p}
$$

Proposition 2.7 ([11]). Let $0<\alpha \leq 1$ and $1<p<\infty$. Assume that $\alpha>1 / p$ and the sequence $u_{k}$ converges weakly to $u \in E_{0}^{\alpha, p}$, i.e. $u_{k} \rightharpoonup u$. Then $u_{k} \rightarrow u$ in $C\left([0, T], \mathbb{R}^{N}\right)$, i.e. $\left\|u_{k}-u\right\|_{\infty} \rightarrow 0$, as $k \rightarrow \infty$.

Making use of Definition 2.3, for any $u \in A C\left([0, T], \mathbb{R}^{N}\right)$ problem (P) is equivalent to the following problem:
$\left(\mathrm{P}_{1}\right) \begin{cases}\frac{d}{d t}\left(\frac{1}{2}{ }_{0} D_{t}^{\alpha-1}\left({ }_{0}^{c} D_{t}^{\alpha} u(t)\right)-\frac{1}{2}{ }_{t} D_{T}^{\alpha-1}\left({ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right)+\nabla F(t, u(t))=0 \\ u(0)=u(T)=0, & \text { a.e. } t \in[0, T],\end{cases}$
where $\alpha=1-\beta \in(1 / 2,1]$. In the following, we will treat problem $\left(\mathrm{P}_{1}\right)$ in the Hilbert space $E^{\alpha}=E_{0}^{\alpha, 2}$ with the corresponding norm $\|u\|_{\alpha}=\|u\|_{\alpha, 2}$. It follows from Theorem 4.1 in [11] that the functional $\varphi$ given by

$$
\varphi(u)=\int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t-\int_{0}^{T} F(t, u(t)) d t
$$

is continuously differentiable on $E^{\alpha}$. Moreover, for $u, v \in E^{\alpha}$ we have

$$
\begin{aligned}
\left\langle\varphi^{\prime}(u), v\right\rangle= & -\int_{0}^{T} \frac{1}{2}\left[\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} v(t)\right)+\left({ }_{t}^{c} D_{T}^{\alpha} u(t),{ }_{0}^{c} D_{t}^{\alpha} v(t)\right)\right] d t \\
& -\int_{0}^{T} \nabla F(t, u(t)) \cdot v(t) d t .
\end{aligned}
$$

Definition 2.8 ([11]). A function $u \in A C\left([0, T], \mathbb{R}^{N}\right)$ is called a solution of $(\mathrm{P})$ if
(a) $D^{\alpha}(u(t))$ is derivative for almost every $t \in[0, T]$, and
(b) $u$ satisfies (P),
where

$$
D^{\alpha}(u(t)):=\frac{1}{2}{ }_{0} D_{t}^{\alpha-1}\left({ }_{0}^{c} D_{t}^{\alpha} u(t)\right)-\frac{1}{2}{ }_{t} D_{T}^{\alpha-1}\left({ }_{t}^{c} D_{T}^{\alpha} u(t)\right) .
$$

Proposition 2.9 ([11]). If $1 / 2<\alpha \leq 1$, then for any $u \in E^{\alpha}$ we have

$$
|\cos (\pi \alpha)|\|u\|_{\alpha}^{2} \leq-\int_{0}^{T}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right) d t \leq \frac{1}{|\cos (\pi \alpha)|}\|u\|_{\alpha}^{2} .
$$

Now, we are going to prove our main results.

## 3. Proof of Theorem 1.3

For every fixed $k \in \mathbb{N}$, consider the set

$$
S_{k}=\left\{u \in E^{\alpha}: u(t) \neq 0 \text { and } u(t) \in\left[0, b_{k}\right] e_{k} \text { a.e. } t \in[0, T]\right\}
$$

where $b_{k}$ is from $\mathrm{H}(\mathrm{F})_{1}$ (5). The proof is divided into four steps as follows.
Step 1. We claim that $\varphi$ is bounded from below on $S_{k}$ and its infimum $m_{k}$ on $S_{k}$ is attained at $u_{k} \in S_{k}$.

On account of $\mathrm{H}(\mathrm{F})_{1}(3)$ and Proposition 2.9, for every $u \in S_{k}$ we have

$$
\begin{aligned}
\varphi(u) & =\int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t-\int_{0}^{T} F(t, u(t)) d t \\
& \geq \frac{|\cos (\pi \alpha)|}{2}\|u\|_{\alpha}^{2}-\int_{0}^{T} c(t)\left(1+|u(t)|^{\alpha_{0}}\right) d t \\
& \geq \frac{|\cos (\pi \alpha)|}{2}\|u\|_{\alpha}^{2}-\int_{0}^{T} c_{0}\left(1+|u(t)|^{\alpha_{0}}\right) d t \\
& \geq \frac{|\cos (\pi \alpha)|}{2}\|u\|_{\alpha}^{2}-c_{0} T-c_{0} \int_{0}^{T}|u(t)|^{\alpha_{0}} d t \\
& \geq \frac{|\cos (\pi \alpha)|}{2}\|u\|_{\alpha}^{2}-c_{0} T-c_{0} T\left|b_{k}\right|^{\alpha_{0}} \geq-c_{0} T-c_{0} T\left|b_{k}\right|^{\alpha_{0}}
\end{aligned}
$$

where $c_{0}=\max _{t \in[0, T]} c(t)$. It is clear that $S_{k}$ is convex and closed, thus weakly closed in $E^{\alpha}$. Let $m_{k}=\inf _{S_{k}} \varphi$, and $\left\{u_{k}^{n}\right\}_{n=1}^{\infty}$ be a sequence in $S_{k}$ such that $m_{k} \leq \varphi\left(u_{k}^{n}\right) \leq m_{k}+1 / n$ for all $n \in \mathbb{N}$. Then

$$
m_{k}+\frac{1}{n} \geq \varphi\left(u_{k}^{n}\right)=\int_{o}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}^{n}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{k}^{n}(t)\right)\right] d t-\int_{0}^{T} F\left(t, u_{k}^{n}(t)\right) d t
$$

which implies that

$$
\begin{aligned}
\frac{|\cos (\pi \alpha)|}{2}\left\|u_{k}^{n}\right\|_{\alpha}^{2} & \leq \int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}^{n}(t){ }_{t}^{c} D_{T}^{\alpha} u_{k}^{n}(t)\right)\right] d t \\
& \leq m_{k}+\frac{1}{n}+\int_{0}^{T} F\left(t, u_{k}^{n}(t)\right) d t \\
& \leq m_{k}+\frac{1}{n}+\int_{0}^{T} c(t)\left(1+\left|u_{k}^{n}(t)\right|^{\alpha_{0}}\right) d t \\
& \leq m_{k}+\frac{1}{n}+c_{0} T+c_{0} T\left|b_{k}\right|^{\alpha_{0}}
\end{aligned}
$$

for all $n \in \mathbb{N}$, thus $\left\{u_{k}^{n}(t)\right\}_{n=1}^{\infty}$ is bounded in $E^{\alpha}$.
By Proposition 2.5, one can easily see that there exists $\left\{u_{k}^{n}\right\}_{n=1}^{\infty} \in E^{\alpha}$ such that $u_{k}^{n} \rightharpoonup u_{k}$ in $E^{\alpha}$. As $\varphi$ is weak lower semicontinuous (see [17, Theorem 3.1,

Step 1]), $\varphi\left(u_{k}\right) \leq \lim _{n \rightarrow+\infty} \varphi\left(u_{k}^{n}\right)$. Then,

$$
m_{k} \leq \varphi\left(u_{k}\right) \leq \lim _{n \rightarrow+\infty} \varphi\left(u_{k}^{n}\right) \leq m_{k}+\frac{1}{n}
$$

which implies that $\varphi\left(u_{k}\right)=m_{k}$. Hence, $u_{k}$ is a minimum point of $\varphi$ over $S_{k}$.
Step 2. We show that $u_{k}(t) \in\left[0, a_{k}\right] e_{k}$ for almost every $t \in[0, T]$.
Let $A=\left\{t \in[0, T]: u_{k}(t) \notin\left[0, a_{k}\right] e_{k}\right\}=\left\{t \in[0, T]: u_{k}(t) \in\left[a_{k}, b_{k}\right] e_{k}\right\}$ and we can suppose that meas $(A)>0$. Define the function $h:[0,+\infty) e_{k} \rightarrow$ $[0,+\infty) e_{k}$ by

$$
h(s)= \begin{cases}a_{k} e_{k} & \text { if } s \in\left[a_{k},+\infty\right] e_{k} \\ s & \text { if } s \in\left[0, a_{k}\right] e_{k}\end{cases}
$$

Now, we set $v_{k}=h \circ u_{k}$. Since $h$ is a Lipschitz function and $h(0)=0$, the theorem of Marcus-Mizel [17] shows that $v_{k} \in E^{\alpha}$. Moreover, $v_{k}(t) \in\left[0, a_{k}\right] e_{k}$ for almost every $t \in[0, T]$. Consequently, $v_{k} \in S_{k}$ and

$$
v_{k}(x)= \begin{cases}u_{k}(t) & \text { if } t \in[0, T] \backslash A, \\ a_{k} e_{k} & \text { if } t \in A .\end{cases}
$$

By straightforward computation, we obtain

$$
\begin{aligned}
\varphi\left(v_{k}\right)-\varphi\left(u_{k}\right)= & \int_{[0, T]}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} v_{k}(t),{ }_{t}^{c} D_{T}^{\alpha} v_{k}(t)\right)\right] d t-\int_{[0, T]} F\left(t, v_{k}(t)\right) d t \\
& -\int_{[0, T]}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{k}(t)\right)\right] d t+\int_{[0, T]} F\left(t, u_{k}(t)\right) d t \\
= & \int_{[0, T] \backslash A}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{k}(t)\right)\right] d t \\
& +\int_{A}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} a_{k} e_{k},{ }_{t}^{c} D_{T}^{\alpha} a_{k} e_{k}\right)\right] d t \\
& -\int_{[0, T] \backslash A} F\left(t, u_{k}(t)\right) d t-\int_{A} F\left(t, a_{k} e_{k}\right) d t \\
& -\int_{[0, T] \backslash A}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{k}(t)\right)\right] d t \\
& -\int_{A}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{k}(t)\right)\right] d t \\
& +\int_{[0, T] \backslash A} F\left(t, u_{k}(t)\right) d t+\int_{A} F\left(t, u_{k}(t)\right) d t \\
= & -\int_{A}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{k}(t)\right)\right] d t \\
& -\int_{A}\left[F\left(t, a_{k} e_{k}\right)-F\left(t, u_{k}(t)\right)\right] d t .
\end{aligned}
$$

For every $t \in A, u_{k}(t) \in\left[a_{k}, b_{k}\right] e_{k}$, there exists a map $\lambda: A \rightarrow[0,1]$ such that $u_{k}(t)=a_{k} e_{k}+\lambda(t)\left(b_{k}-a_{k}\right) e_{k}$. By the Mean Value Theorem, it holds

$$
\begin{gathered}
\int_{A}\left[F\left(t, a_{k} e_{k}\right)-F\left(t, u_{k}(t)\right)\right] d t=\int_{A} \nabla F\left(t, \xi_{k}(t)\right) \cdot\left(a_{k} e_{k}-u_{k}(t)\right) d t \\
=\int_{A} \nabla F\left(t, \xi_{k}(t)\right) \cdot\left[a_{k} e_{k}-a_{k} e_{k}-\lambda(t)\left(b_{k}-a_{k}\right) e_{k}\right] d t \\
=\int_{A} \nabla F\left(t, \xi_{k}(t)\right) \cdot \lambda(t)\left(a_{k}-b_{k}\right) e_{k} d t
\end{gathered}
$$

By $\mathrm{H}(\mathrm{F})_{1}$ (5), we have $\xi_{k}(t) \in\left[a_{k}, b_{k}\right] e_{k}$ for almost every $t \in A$. Consequently,

$$
\int_{A}\left[F\left(t, a_{k} e_{k}\right)-F\left(t, u_{k}(t)\right)\right] d t \geq 0
$$

In conclusion, every term of the expression $\varphi\left(v_{k}\right)-\varphi\left(u_{k}\right) \leq 0$. On the other hand, since $v_{k} \in S_{k}$, then $\varphi\left(v_{k}\right) \geq \varphi\left(u_{k}\right)=\inf _{S_{k}} \varphi$. So, $\varphi\left(v_{k}\right)-\varphi\left(u_{k}\right)=0$. Namely,

$$
-\int_{A}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{k}(t)\right)\right] d t-\int_{A}\left[F\left(t, a_{k} e_{k}\right)-F\left(t, u_{k}(t)\right)\right] d t=0
$$

which implies that meas $(A)=0$.
Step 3. We show that $u_{k}$ is a local minimum point in $E^{\alpha}$.
Let $A^{\prime}=\left\{t \in[0, T]: u(t) \notin\left[0, a_{k}\right] e_{k}\right\}=\left\{t \in[0, T]: u(t) \in\left(a_{k}, b_{k}\right] e_{k}\right\}$. Set $v=h \circ u$, then we have
(3.1) $\varphi(u)-\varphi(v)$

$$
\begin{aligned}
= & \int_{[0, T]}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t-\int_{[0, T]} F(t, u(t)) d t \\
& -\int_{[0, T]}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} v(t),{ }_{t}^{c} D_{T}^{\alpha} v(t)\right)\right] d t+\int_{[0, T]} F(t, v(t)) d t
\end{aligned}
$$

$$
=\int_{[0, T] \backslash A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t
$$

$$
+\int_{A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t-\int_{[0, T] \backslash A^{\prime}} F(t, u(t)) d t
$$

$$
-\int_{A^{\prime}} F(t, u(t)) d t-\int_{[0, T] \backslash A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t
$$

$$
-\int_{A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} a_{k} e_{k},{ }_{t}^{c} D_{T}^{\alpha} a_{k} e_{k}\right)\right] d t
$$

$$
+\int_{[0, T] \backslash A^{\prime}} F(t, u(t)) d t+\int_{A^{\prime}} F\left(t, a_{k} e_{k}\right) d t
$$

$$
=\int_{A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t+\int_{A^{\prime}}\left[F\left(t, a_{k} e_{k}\right)-F(t, u(t))\right] d t
$$

From assumption $\mathrm{H}(\mathrm{F})_{1}$ (5), we have

$$
\int_{A^{\prime}}\left[F\left(t, a_{k} e_{k}\right)-F(t, u(t))\right] d t=\int_{A^{\prime}} \nabla F(t, \xi(t)) \cdot\left(a_{k} e_{k}-u(t)\right) d t \geq 0
$$

for almost every $t \in A^{\prime}$, where $\xi(t) \in\left[a_{k} e_{k}, u(t)\right] \subseteq\left[a_{k}, b_{k}\right] e_{k}$ for almost every $t \in A^{\prime}$. Consequently, $\varphi(u)-\varphi(v) \geq 0$. On the other hand, by $v \in S_{k}$, we have $\varphi(v) \geq \varphi\left(u_{k}\right)$. In view of (3.1), we derive

$$
\varphi(u)-\varphi(v) \geq \int_{A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t .
$$

Moreover, we have

$$
\begin{aligned}
\varphi(u) & \geq \varphi(v)+\int_{A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t \\
& \geq \varphi\left(u_{k}\right)+\int_{A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t \\
\geq & \varphi\left(u_{k}\right)+\int_{[0, T]}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t \\
& -\int_{[0, T] \backslash A^{\prime}}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u(t),{ }_{t}^{c} D_{T}^{\alpha} u(t)\right)\right] d t \\
\geq & \varphi\left(u_{k}\right)+\int_{[0, T]}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha}(u(t)-v(t)),{ }_{t}^{c} D_{T}^{\alpha}(u(t)-v(t))\right)\right] d t \\
\geq & \varphi\left(u_{k}\right)+\frac{|\cos (\pi \alpha)|}{2}\|u-v\|_{\alpha}^{2} .
\end{aligned}
$$

Since $h$ is continuous, there exists $\delta>0$ such that for every $u \in E^{\alpha},\|u-v\|_{\alpha}<\delta$, which implies that $u_{k}$ is a local minimum of $\varphi$.

Step 4. In this step the fact that $m_{k}=\inf _{S_{k}} \varphi<0$ and $\lim _{k \rightarrow+\infty} m_{k}=0$ is proved.

Let $B_{r_{0}}\left(t_{0}\right) \subset[0, T]$ be the ball with radius $r_{0} \in(0,1)$ and center $t_{0} \in[0, T]$. For $\xi \in \mathbb{R}^{N}$, define

$$
\eta_{\xi}(t)= \begin{cases}0 & \text { if } t \in[0, T] \backslash B_{r_{0}}\left(t_{0}\right),  \tag{3.2}\\ \xi & \text { if } t \in B_{r_{0} / 2}\left(t_{0}\right) \\ \frac{2 \xi}{r_{0}}\left(r_{0}-\left|t-t_{0}\right|\right) & \text { if } t \in B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right) .\end{cases}
$$

It is clear that $\eta_{\xi} \in E^{\alpha}$ and $\left|\eta_{\xi}(t)\right| \leq 2|\xi| / r_{0}$;

$$
\begin{aligned}
{ }_{0}^{c} D_{t}^{\alpha} \eta_{\xi}(t) \mid & =\left|\frac{1}{\Gamma(1-\alpha)} \int_{0}^{t}(t-s)^{-\alpha} \eta_{\xi}^{\prime} d s\right| \\
& \leq \frac{1}{\Gamma(1-\alpha)}\left(\int_{0}^{t}(t-s)^{-\alpha}\left|\eta_{\xi}^{\prime}\right| d s\right) \leq \frac{1}{\Gamma(1-\alpha)} \frac{2|\xi|}{r_{0}} \frac{t^{1-\alpha}}{1-\alpha}
\end{aligned}
$$

$$
\begin{align*}
\left\|\eta_{\xi}\right\|_{\alpha}^{2} & =\int_{0}^{T}\left|{ }_{0}^{c} D_{t}^{\alpha} \eta_{\xi}(t)\right|^{2} d t \leq \int_{0}^{T} \frac{1}{\Gamma^{2}(1-\alpha)} \frac{4|\xi|^{2}}{r_{0}^{2}} \frac{t^{2-2 \alpha}}{(1-\alpha)^{2}} d t  \tag{3.3}\\
& \leq \frac{1}{\Gamma^{2}(1-\alpha)} \frac{4 \xi^{2}}{r_{0}^{2}} \frac{1}{(1-\alpha)^{2}} \int_{0}^{T} t^{2-2 \alpha} d t \\
& \leq \frac{4|\xi|^{2}}{\Gamma^{2}(1-\alpha) r_{0}^{2}(1-\alpha)^{2}(3-2 \alpha)} T^{3-2 \alpha} .
\end{align*}
$$

From the left part of $\mathrm{H}(\mathrm{F})_{1}$ (4) we deduce the existence of some $l_{0}>0$ and $\lambda_{0} \in\left[0, a_{k}\right] e_{k}$ such that

$$
\begin{equation*}
\underset{t \in[0, T]}{\operatorname{essinf}} F(t, x) \geq-l_{0}|x|^{2} \quad \text { for all } x \in\left[0, \lambda_{0}\right] e_{k} \tag{3.4}
\end{equation*}
$$

There exists $L_{0}>0$ large enough to enable

$$
\begin{equation*}
C\left(r_{0}, \alpha, T\right)+l_{0} T<L_{0} r_{0} \tag{3.5}
\end{equation*}
$$

where

$$
C\left(r_{0}, \alpha, T\right)=\frac{1}{2|\cos (\pi \alpha)|} \frac{4 T^{3-2 \alpha}}{\Gamma^{2}(1-\alpha) r_{0}^{2}(3-2 \alpha)} .
$$

Taking into account the right part of $\mathrm{H}(\mathrm{F})_{1}(4)$, there is a sequence $\left\{\xi_{k}\right\} \in\left[0, \lambda_{0}\right]$ such that $\left\{\xi_{k}\right\} \in\left[0, a_{k}\right] e_{k}$ and

$$
\begin{equation*}
\operatorname{exssup}_{t \in[0, T]} F\left(t, \xi_{k}\right)>L_{0}\left|\xi_{k}\right|^{2} \quad \text { for all } k \in N \tag{3.6}
\end{equation*}
$$

Clearly, $\left|t-t_{0}\right| \in\left(r_{0} / 2, r_{0}\right), r_{0}-\left|t-t_{0}\right| \in\left(0, r_{0} / 2\right)$ for all $t \in B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right)$. Therefore,

$$
\frac{2 \xi_{k}}{r_{0}}\left(r_{0}-\left|t-t_{0}\right|\right) \in\left[0, \xi_{k}\right] \subset\left[0, \lambda_{0}\right] e_{k}, \quad \text { for all } t \in B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right)
$$

In view of Proposition 2.9 and (3.3), we deduce

$$
\begin{align*}
\int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} \eta_{\xi_{k}}(t),{ }_{t}^{c} D_{T}^{\alpha} \eta_{\xi_{k}}(t)\right)\right] d t \leq \frac{1}{2|\cos (\pi \alpha)|}\left\|\eta_{\xi_{k}}(t)\right\|_{\alpha}^{2}  \tag{3.7}\\
\leq \frac{1}{2|\cos (\pi \alpha)|} \frac{4 T^{3-2 \alpha}}{\Gamma^{2}(1-\alpha) r_{0}^{2}(3-2 \alpha)}\left|\xi_{k}\right|^{2}=C\left(r_{0}, \alpha, T\right)\left|\xi_{k}\right|^{2}
\end{align*}
$$

Combining (3.4) with (3.6), we obtain
(3.8) $\int_{0}^{T} F\left(t, \eta_{\xi}(t)\right) d t$

$$
\begin{aligned}
& =\int_{B_{r_{0} / 2}\left(t_{0}\right)} F\left(t, \eta_{\xi_{k}}(t)\right) d t+\int_{B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right)} F\left(t, \eta_{\xi_{k}}(t)\right) d t \\
& \geq \int_{B_{r_{0} / 2}\left(t_{0}\right)} F\left(t, \xi_{k}(t)\right) d t+\int_{B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right)} F\left(t, \frac{2 \xi_{k}}{r_{0}}\left(r_{0}-\left|t-t_{0}\right|\right)\right) d t \\
& \geq L_{0} r_{0}\left|\xi_{k}\right|^{2}-l_{0} T\left|\xi_{k}\right|^{2} .
\end{aligned}
$$

Let $k \in \mathbb{N}$ be a fixed number and let $\eta_{\xi_{k}} \in E^{\alpha}$ be the function from (3.2) corresponding to the value $\left|\xi_{k}\right|>0$. Then $\eta_{\xi_{k}} \in S_{k}$, and on account of (3.5), (3.7) and (3.8), one has

$$
\begin{align*}
\varphi\left(\eta_{\xi_{k}}\right) & =\int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} \eta_{\xi_{k}}(t),{ }_{t}^{c} D_{T}^{\alpha} \eta_{\xi_{k}}(t)\right)\right] d t-\int_{0}^{T} F\left(t, \eta_{\xi}(t)\right) d t  \tag{3.9}\\
& \leq C\left(r_{0}, \alpha, T\right)\left|\xi_{k}\right|^{2}-L_{0} r_{0}\left|\xi_{k}\right|^{2}+l_{0} T\left|\xi_{k}\right|^{2} \\
& \leq\left(C\left(r_{0}, \alpha, T\right)+l_{0} T-L_{0} r\right)\left|\xi_{k}\right|^{2}<0 .
\end{align*}
$$

Due to Step 3 and (3.9), we deduce that $m_{k}=\varphi\left(u_{k}\right)=\inf _{S_{k}} \varphi \leq \varphi\left(\eta_{\xi_{k}}\right)<0$.
Now we prove that $\lim _{k \rightarrow+\infty} m_{k}=0$. Observe that by assumption $\mathrm{H}(\mathrm{F})_{1}(3)$, one can find a constant $c_{0}=\max _{t \in[0, T]}>0$ such that

$$
|\nabla F(t, x)| \leq c_{0}\left(1+|x|^{\alpha_{0}}\right) \quad \text { for all } t \in[0, T], x \in \mathbb{R}^{N}
$$

Applying the Mean Value Theorem and the above inequality for every $x \in$ $\left[0, a_{k}\right] e_{k}$ and all $t \in[0, T]$, one can find a constant $c_{0}>0$ such that

$$
\begin{aligned}
|F(t, x)| & =|F(t, x)-F(t, 0)|=|\nabla F(t, \xi) \cdot x|=|\nabla F(t, \xi)||x| \\
& \leq c_{0}\left(1+|\xi|^{\alpha_{0}}\right)|x| \leq c_{0}|x|+c_{0} \lambda^{\alpha_{0}}|x|^{\alpha_{0}+1},
\end{aligned}
$$

where $\lambda \in[0,1]$ is such that $\xi=\lambda x$. Therefore

$$
\begin{aligned}
m_{k} & =\varphi\left(u_{k}\right)=\int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}(t){ }_{t}^{c} D_{T}^{\alpha} u_{k}(t)\right)\right] d t-\int_{0}^{T} F\left(t, u_{k}(t)\right) d t \\
& \geq \frac{|\cos (\pi \alpha)|}{2}\left\|u_{k}\right\|_{\alpha}^{2}-\int_{0}^{T} F\left(t, u_{k}(t)\right) d t \geq-\int_{0}^{T} F\left(t, u_{k}(t)\right) d t \\
& \geq-\int_{0}^{T}\left[c_{0}\left|u_{k}(t)\right|+c_{0} \lambda^{\alpha_{0}}\left|u_{k}(t)\right|^{\alpha_{0}+1}\right] d t \geq-c_{0} T\left(\left|b_{k}\right|+\lambda^{\alpha_{0}}\left|b_{k}\right|^{\alpha_{0}+1}\right) .
\end{aligned}
$$

Since $\lim _{k \rightarrow+\infty} b_{k}=0$, we have $\lim _{k \rightarrow+\infty} m_{k} \geq 0$. Note that $m_{k}<0$, hence $\lim _{k \rightarrow+\infty} m_{k}=0$.
Finally, since $u_{k}$ are local minima of $\varphi$, they are critical points of $\varphi$, thus weak solutions of (P). Due to Step 2 , there are infinitely many distinct $u_{k}$ with $\lim _{k \rightarrow+\infty}\left|u_{k}\right|_{\infty}=0$. Moreover, we have

$$
\begin{aligned}
\frac{|\cos (\pi \alpha)|}{2}\left\|u_{k}\right\|_{\alpha}^{2} & \leq \int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{k}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{k}(t)\right)\right] d t \\
& =m_{k}+\int_{0}^{T} F\left(t, u_{k}(t)\right) d t \leq m_{k}+c T\left(\left|b_{k}\right|+\lambda^{\alpha_{0}}\left|b_{k}\right|^{\alpha_{0}+1}\right)
\end{aligned}
$$

which means that $\lim _{k \rightarrow+\infty}\left\|u_{k}\right\|_{\alpha}=0$.
Next, we prove Theorem 1.6 when the nonlinearity oscillates at infinity.
Proof of Theorem 1.6. For every fixed $k \in \mathbb{N}$, consider the set

$$
T_{k}=\left\{u \in E^{\alpha}: u(x) \neq 0 \text { and } u(x) \in\left[0, b_{k}\right] e_{k} \text { for a.e. } x \in \mathbb{R}^{N}\right\},
$$

where $b_{k}$ is from $\mathrm{H}(\mathrm{F})_{2}(5)$. The first part of the proof is similar to that of Theorem 1.3. Indeed, we can prove that the functional $\varphi$ is bounded from below on $T_{k}$ and its infimum on $T_{k}$ is attained (see Step 1 of Theorem 1.3). Moreover, if $u_{k} \in T_{k}$ is chosen such that $\varphi\left(u_{k}\right)=\inf _{T_{k}} \varphi$, then $u_{k}(t) \in\left[0, a_{k}\right] e_{k}$ for almost every $t \in[0, T]$ (see Step 2 of Theorem 1.3), and $u_{k}$ is a local minimum point of $\varphi$ in $E^{\alpha}$ (see Step 3 of Theorem 1.3). Instead of Step 4, we prove

Step $4^{\prime}$. Let $\vartheta_{k}=\inf _{T_{k}} \varphi=\varphi\left(u_{k}\right)$, then $\lim _{k \rightarrow+\infty} \vartheta_{k}=-\infty$.
From $\mathrm{H}(\mathrm{F})_{2}$ (4), we deduce that there exist $l_{\infty}>0$ and $\lambda_{\infty}>0$ such that

$$
\begin{equation*}
\underset{t \in[0, T]}{\operatorname{essinf}} F(t, x) \geq-l_{\infty}|x|^{2} \quad \text { for all }|x|>l_{\infty} \tag{3.10}
\end{equation*}
$$

There exists $L_{\infty}>0$ large enough to enable

$$
\begin{equation*}
C\left(r_{0}, \alpha, T\right)+l_{\infty} T<L_{\infty} r_{0} . \tag{3.11}
\end{equation*}
$$

From the right hand side of $\mathrm{H}(\mathrm{F})_{2}(4)$, there is a sequence $\left\{\xi_{k}\right\} \subset \mathbb{R}^{N}$ such that $\lim _{k \rightarrow+\infty} \xi_{k}=+\infty$ and

$$
\begin{equation*}
\operatorname{esssup}_{t \in[0, T]} F\left(t, \xi_{k}\right)>L_{\infty}\left|\xi_{k}\right|^{2} \quad \text { for all } k \in \mathbb{N} . \tag{3.12}
\end{equation*}
$$

It is easy to see that

$$
\left|\eta_{\xi_{k}}(t)\right| \leq\left|\xi_{k}\right| \quad \text { for all } t \in B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right),
$$

since

$$
\eta_{\xi_{k}}(t)=\frac{2 \xi_{k}}{r_{0}}\left(r_{0}-\left|t-t_{0}\right|\right) \quad \text { for all } t \in B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right)
$$

Let $k \in \mathbb{N}$ be fixed and let $\eta_{\xi_{k}} \in E^{\alpha}$ be the function from (3.2) corresponding to the value $\xi_{k} \in \mathbb{R}^{N}$. Then $\eta_{\xi_{k}} \in T_{b_{k}}$, and on account of (3.10) and (3.12), we have

$$
\begin{align*}
\varphi\left(\eta_{\xi_{k}}\right)= & \int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} \eta_{\xi_{k}}(t),{ }_{t}^{c} D_{T}^{\alpha} \eta_{\xi_{k}}(t)\right)\right] d t-\int_{0}^{T} F\left(t, \eta_{\xi}(t)\right) d t  \tag{3.13}\\
\leq & \frac{1}{2|\cos (\pi \alpha)|}\left\|\eta_{\xi_{k}}\right\|_{\alpha}^{2}-\int_{B_{r_{0} / 2}\left(t_{0}\right)} F\left(t, \eta_{\xi_{k}}(t)\right) d t \\
& -\int_{\left(B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right)\right) \cap\left\{t:\left|\eta_{\xi_{k}}(t)\right|>\lambda_{\infty}\right\}} F\left(t, \eta_{\xi_{k}}(t)\right) d t \\
& -\int_{\left(B_{r_{0}}\left(t_{0}\right) \backslash B_{r_{0} / 2}\left(t_{0}\right)\right) \cap\left\{t:\left|\eta_{\xi_{k}}(t)\right| \leq \lambda_{\infty}\right\}} F\left(t, \eta_{\xi_{k}}(t)\right) d t \\
\leq & \frac{1}{2|\cos (\pi \alpha)|} \frac{4 T^{(3-2 \alpha)}}{\Gamma^{2}(1-\alpha) r_{0}^{2}(3-2 \alpha)}\left|\xi_{k}\right|^{2} \\
& -L_{\infty} r_{0}\left|\xi_{k}\right|^{2}+l_{\infty} T\left|\xi_{k}\right|^{2}-c T\left(1+\lambda_{\infty}^{\alpha_{0}}\right) \\
= & \left(C\left(r_{0}, \alpha, T\right)-L_{\infty}+l_{\infty} T\right)\left|\xi_{k}\right|^{2}+c T \lambda_{\infty}^{\alpha_{0}} .
\end{align*}
$$

From (3.11), (3.13) and $\lim _{k \rightarrow+\infty} \xi_{k}=+\infty$, we conclude that

$$
\begin{equation*}
\lim _{k \rightarrow+\infty} \varphi\left(\eta_{\xi_{k}}\right)=-\infty \tag{3.14}
\end{equation*}
$$

On the other hand, from $\varphi\left(u_{m_{k}}\right)=\min _{T_{b_{m_{k}}}} \varphi$, we have $\varphi\left(u_{m_{k}}\right) \leq \varphi\left(\eta_{\xi_{k}}(t)\right)$. Therefore, on account of (3.14), we have

$$
\begin{equation*}
\lim _{k \rightarrow+\infty} \varphi\left(u_{m_{k}}\right)=-\infty \tag{3.15}
\end{equation*}
$$

Since the sequence $\left\{\varphi\left(u_{k}\right)\right\}$ is non-increasing, so $\lim _{k \rightarrow+\infty} \vartheta_{k}=\lim _{k \rightarrow+\infty} \varphi\left(u_{k}\right)=-\infty$.
STEP 5. In this step the fact $\lim _{k \rightarrow+\infty}\left|u_{k}\right|_{\infty}=\lim _{k \rightarrow+\infty}\left\|u_{k}\right\|_{\alpha}=+\infty$ is proved.
Arguing by contradiction, assume that there exists a subsequence $\left\{u_{n_{k}}\right\}$ of $\left\{u_{k}\right\}$ such that $\left|u_{n_{k}}\right|_{\infty} \leq M$ for some $M>0$. In particular, $\left\{u_{n_{k}}\right\} \subset T_{b_{l}}$ for some $l \in \mathbb{N}$. Thus, for every $n_{k}>l$ we have

$$
\vartheta_{l} \geq \vartheta_{n_{k}}=\inf _{T_{n_{k}}} \varphi=\varphi\left(u_{n_{k}}\right) \geq \inf _{T_{l}} \varphi=\vartheta_{l} .
$$

Consequently, $\vartheta_{n_{k}}=\vartheta_{l}$ for every $n_{k}>l$. This fact contradicts with (3.15), which completes the first part of the proof.

Next, we prove $\lim _{k \rightarrow+\infty}\left\|u_{k}\right\|_{\alpha}=+\infty$.
Note that $1<\alpha_{0}<+\infty$, then by Proposition 2.7 , we have $E^{\alpha} \hookrightarrow C\left([0, T], \mathbb{R}^{N}\right)$ (compact embedding). Furthermore, there exists $c_{2}>0$ such that $\left|u_{k}\right|_{\infty} \leq$ $c_{2}\left\|u_{k}\right\|_{\alpha}$. Hence, there exists a constant $c_{3}>0$ such that

$$
\begin{aligned}
\int_{0}^{T} F\left(t, u_{k}(t)\right) d t & \leq \int_{0}^{T} c_{0}\left(1+\left|u_{k}(t)\right|^{\alpha_{0}}\right) d t \leq c_{0} T+c_{0}\left|u_{k}(t)\right|_{\infty}^{\alpha_{0}} T \\
& \leq c_{0} T+c_{0} c_{2}^{\alpha_{0}}\left\|u_{k}\right\|_{\alpha}^{\alpha_{0}} T \leq c_{0} T+c_{3}\left\|u_{k}\right\|_{\alpha}^{\alpha_{0}} T
\end{aligned}
$$

Let us assume that there exists a subsequence $\left\{u_{n_{k}}\right\}$ of $\left\{u_{k}\right\}$ such that for some $M>0$, we have $\left\|u_{n_{k}}\right\|_{\alpha} \leq M$. In particular, due to the above inequality,

$$
\begin{aligned}
\left|\varphi\left(u_{n_{k}}\right)\right| & =\left|\int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{n_{k}}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{n_{k}}(t)\right)\right] d t-\int_{0}^{T} F\left(t, u_{n_{k}}(t)\right) d t\right| \\
& \leq\left|\int_{0}^{T}\left[-\frac{1}{2}\left({ }_{0}^{c} D_{t}^{\alpha} u_{n_{k}}(t),{ }_{t}^{c} D_{T}^{\alpha} u_{n_{k}}(t)\right)\right] d t\right|+\left|\int_{0}^{T} F\left(t, u_{n_{k}}(t)\right) d t\right| \\
& \leq \frac{1}{2|\cos (\pi \alpha)|}\left\|u_{n_{k}}\right\|_{\alpha}^{2}+c_{0} T+c_{3}\left\|u_{k}\right\|_{\alpha} T
\end{aligned}
$$

is bounded. Hence $\vartheta_{n_{k}}=\varphi\left(u_{n_{k}}\right)$ is also bounded. This fact contradicts with $\lim _{k \rightarrow+\infty} \vartheta_{k}=-\infty$.

## References

[1] J. Chen and X.H. Tang, Existence and mulitiplicity of solutions for some fractional boundary value problem via critical point theory, Abstr. Appl. Anal. ArticleID 648635 (2012), 1-21.
[2] K. Diethelm and A.D. Freed, On the solution of nonlinear fractional differential equations used in the modeling of viscoplasticity, In: Scientific Computing in Chemical Engineering II - Computational Fluid Dynamics, Reaction Engineering, and Molecular Properties (F. Keil, W. Mackens, H. Voss, and J. Werther, eds.), Springer, Heidelberg, 1999, pp. 217-224.
[3] B. Ge, Multiple solutions for a class of fractional boundary value problems, Abstr. Appl. Anal. Article ID 468980 (2012), 1-16.
[4] W.G. Glockle and T.F. Nonnenmacher, A fractional calculus approach of self-similar protein dynamics, Biophys. J. 6 (1995), 46-53.
[5] P. Habets, R. Manásevich and F. Zanolin, A nonlinear boundary value problem with potential oscillating around the first eigenvalue, J. Differential Equations 117 (1995), 428-445.
[6] P. Habets, E. Serra and M. Tarallo, Multiplicity results for boundary value problems with potentials oscillating around resonance, J. Differential Equations 138 (1997), 133156.
[7] R. Hilfer, Applications of Fractional Calculus in Physics, World Scientific, New Jersey, 2000.
[8] H. Jafari and V. Daftardar-Gejui, Positive solutions of nonlinear fractional boundary value problems using Adomian decomposition method, Comput. Math. Appl. 180 (2006), 700-706.
[9] P. Jebelean, J. Mawhin and C. Šerban, Multiple periodic solutions for perturbed relativistic pendulum systems, Proc. Amer. Math. Soc. 143 (2015), 3020-3039.
[10] Q. JIANG, The existence of solutions to boundary value problems of fractional differential equations at resonance, Nonlinear Anal. 74 (2011), 1987-1994.
[11] F. Jiao and Y. Zhou, Existence of solutions for a class of fractional boundary value problems via critical point theory, Comput. Math. Appl. 62 (2011), 1181-1199.
[12] A.A. Kilbas, H.M. Srivastava and J.J. Trujillo, Theory and Applications of Fractional Differential Equations, Elsevier, Amsterdam, 2006.
[13] S.H. Liang and J.H. Zhang, Positive solutions for boundary value problems of nonlinear fractional differential equation, Nonlinear Anal. 71 (2009), 5545-5550.
[14] B.N. Lundstrom, M.H. Higgs, W.J. Spain and A.L. Fairhall, Fractional differentiation by neocortical pyramidal neurons, Nat. Neurosci. 11 (2008), 1335-1342.
[15] H. Lü, D. O'Regan and R.P. Agarwal, On the existence of multiple periodic solutions for the vector p-Laplacian via critical point theory, Appl. Math. Czech. 50 (6) (2005), 555-568.
[16] F. Mainardi, Fractional calculus: some basic problems in continuum and statistical mechanics, In: Fractals and Fractional Calculus in Continuum Mechanics (Udine, 1996), 291-348, CISM Course and Lectures, Vol. 378, Springer, Vienna, 1997.
[17] M. Marcus and V. Mizel, Every superposition operator mapping one Sobolev space into another is continuous, J. Funct. Anal. 33 (1979), 217-229.
[18] N. Nyamoradi, Infinitely many solutions for a class of fractional boundary value problems with Dirichlet boundary conditions, Mediterr. J. Math. 11 (2014), 75-87.
[19] H.R. Sun and Q.G. Zhang, Existence of solutions for a fractional boundary value problem via the Mountain Pass method and an iterative technique, Comput. Math. Appl. 64 (2012), 3436-3443
[20] K.M. Teng, H.G. Jia and H.F. Zhang, Existence and multiplicity results for fractional differential inclusions with Dirichlet boundary conditions, Comput. Math. Appl. 220 (2013), 792-801.
[21] Z.L. Wei, W. Dong and J.L. Che, Periodic boundary value problems for fractional differential equations involving a Riemann-Liouville fractional derivative, Nonlinear Anal. 73 (2010), 3232-3238.
[22] P. Zhang and C.L. Tang, Infinitely many periodic solutions for nonautonomous sublinear second-order Hamiltonian systems, Abstr. Appl. Anal. Article ID 620438 (2010), 1-10.
[23] S.Q. Zhang, Existence of a solution for the fractional differential eqution with nonlinear boundary conditions, Comput. Math. Appl. 61 (2011), 1202-1208.

Bin Ge
Department of Mathematics
Harbin Engineering University
Harbin, Heilongjiang, 150040, P.R. CHINA
E-mail address: gebin04523080261@163.com

Vicenţiu D. RĂdulescu
Department of Mathematics
Faculty of Sciences
King Abdulaziz University
P.O. Box 80203

Jeddah 21589, SAUDI ARABIA
and
Institute of Mathematics "Simion Stoilow"
Romanian Academy
21 Calea Grivitei
010702 Bucharest, ROMANIA
E-mail address: vicentiu.radulescu@imar.ro

Ji-Chun Zhang
Department of Mathematics
Harbin Engineering University
Harbin, Heilongjiang, 150040, P.R. CHINA
E-mail address: 986799294@qq.com

