# COMPLEX HYPERSURFACES OF $P_{n}(C) \times P_{n}(C)$ 

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Recently, Simons [7] has established a fundamental formula for the Laplacian of the length of the second fundamental tensor of a submanifold of a Riemannian manifold and has obtained an application to a minimal hypersurface of a sphere. Ogiue [6] and others then obtained an important application of the formula of Simons' type to a complex submanifold of a complex space form.

On the other hand, Ludden and Okumura [3] obtained a remarkable application of the formula of Simons' type to a hypersurface of constant mean curvature immersed in the product $S^{n} \times S^{n}$ of two $n$-spheres.

In this paper we deal with complex hypersurfaces immersed in a Kaehler manifold $P_{n}(C) \times P_{n}(C)$ by a similar method.

In §1, we review some fundamental formulas for a complex hypersurface $M$ of the product $P_{n}(C) \times P_{n}(C)$ of two complex projective $n$-spaces and obtain a result: The scalar curvature $\rho$ of $M$ satisfies $\rho \leqq$ $2 n^{2}$. If the equality holds, then the tangent space of $M$ is invariant under an almost product structure on $P_{n}(C) \times P_{n}(C)$ (for simplicity, we say that $M$ is an invariant hypersurface), and $M$ is a totally geodesic hypersurface of $P_{n}(C) \times P_{n}(C)$ (Proposition 1.1).

In $\S 2$, using the formulas obtained in $\S 1$ we establish an integral formula of Simons' type and obtain results: A totally geodesic hypersurface, and a compact Kaehler hypersurface of $P_{n}(C) \times P_{n}(C)$ satisfying

$$
\int_{M}\left(\frac{2 n+1}{2 n-1} \varphi^{2}-(n+1) \varphi\right) d M \geqq 4 \int_{M}\left\|\nabla^{*} H\right\|^{2} d M
$$

are invariant hypersurfaces, where $\varphi=2$ trace $H^{2}$ (Theorems 2.1 and 2.2).
In $\S 3$, we consider an invariant hypersurface of $P_{n}(C) \times P_{n}(C)$ and obtain a result: A compact invariant Kaehler hypersurface $M$ of $P_{n}(C) \times$ $P_{n}(C)$ is a totally geodesic hypersurface, $\varphi \equiv(n+1) / 3$ or $\varphi(x)>(n+1) / 3$ at some $x \in M$ (Theorem 3.1).

Moreover, using a fact that a complete invariant Kaehler hypersurface of $P_{n}(C) \times P_{n}(C)$ is the product of $P_{n}(C)$ and a hypersurface of $P_{n}(C)$ (Theorem 3.3), we obtain the main results: A) If $\varphi \leqq(n+1) / 3$, then $M=P_{n-1}(C) \times P_{n}(C)$ or $n=2$ and $M=Q_{1}(C) \times P_{2}(C)$, where $Q_{1}(C)$
is a complex quadric. B) $P_{n-1}(C) \times P_{n}(C)$ is the only totally geodesic hypersurface of $P_{n}(C) \times P_{n}(C)$. C) $P_{n-1}(C) \times P_{n}(C)$ and $Q_{n-1}(C) \times P_{n}(C)$ are the only compact invariant Kaehler hypersurfaces of $P_{n}(C) \times P_{n}(C)$ with constant scalar curvature, where $Q_{n-1}(C)$ is the complex quadric (Theorems 3.5, 3.6 and 3.7).

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1. Complex hypersurfaces of $P_{n}(C) \times P_{n}(C)$. Let $P_{n}(C)$ be a complex projective $n$-space with the Fubini-Study metric of constant holomorphic sectional curvature 1. Consider the Riemannian product $P_{n}(C) \times$ $P_{n}(C)$. We denote by $\bar{P}$ and $\bar{Q}$ the projections of the tangent space of $P_{n}(C) \times P_{n}(C)$ to each component respectively. We put

$$
\begin{equation*}
\bar{F}=\bar{P}-\bar{Q} \tag{1.1}
\end{equation*}
$$

Then the Riemannian metric on $P_{n}(C) \times P_{n}(C)$ is given by

$$
\bar{g}(\bar{X}, \bar{Y})=g^{\prime}(\bar{P} \bar{X}, \bar{P} \bar{Y})+g^{\prime}(\bar{Q} \bar{X}, \bar{Q} \bar{Y})
$$

where $g^{\prime}$ is the Kaehler metric of $P_{n}(C)$. Then we have

$$
\begin{gather*}
\bar{P}+\bar{Q}=I,  \tag{1.2}\\
\bar{P}^{2}=\bar{P}, \quad \bar{Q}^{2}=\bar{Q},  \tag{1.3}\\
\bar{P} \bar{Q}=\bar{Q} \bar{P}=0,  \tag{1.4}\\
\bar{F}^{2}=I,  \tag{1.5}\\
\operatorname{trace} \bar{F}=0,  \tag{1.6}\\
\bar{g}(\bar{F} \bar{X}, \bar{Y})=\bar{g}(\bar{X}, \bar{F} \bar{Y}),  \tag{1.7}\\
\bar{\nabla}_{\bar{X}} \bar{F}=0, \tag{1.8}
\end{gather*}
$$

where $\bar{V}$ denotes the operator of covariant differentiation with respect to $\bar{g}$. We call $\bar{F}$ an almost product structure on $P_{n}(C) \times P_{n}(C)$.

The curvature tensor of $P_{n}(C)$ may be written as

$$
\begin{aligned}
R^{\prime}\left(X^{\prime},\right. & \left.Y^{\prime}\right) Z^{\prime} \\
= & \frac{1}{4}\left\{g^{\prime}\left(Y^{\prime}, Z^{\prime}\right) X^{\prime}-g^{\prime}\left(X^{\prime}, Z^{\prime}\right) Y^{\prime}+g^{\prime}\left(J^{\prime} Y^{\prime}, Z^{\prime}\right) J^{\prime} X^{\prime}\right. \\
& \left.\quad-g^{\prime}\left(J^{\prime} X^{\prime}, Z^{\prime}\right) J^{\prime} Y^{\prime}+2 g^{\prime}\left(X^{\prime}, J^{\prime} Y^{\prime}\right) J^{\prime} Z^{\prime}\right\},
\end{aligned}
$$

where $J^{\prime}$ denotes the complex structure of $P_{n}(C)$. We put

$$
\bar{J} \bar{X}=J^{\prime} \bar{P} \bar{X}+J^{\prime} \bar{Q} \bar{X}
$$

Then we can easily see that

$$
\begin{align*}
& J^{\prime} \bar{P}=\bar{P} \bar{J}, \quad J^{\prime} \bar{Q}=\bar{Q} \bar{J}  \tag{1.9}\\
& \bar{F} \bar{J}=\bar{J} \bar{F}, \quad \bar{J}^{2}=-I \\
& \bar{g}(\bar{J} \bar{X}, \bar{J} \bar{Y})=\bar{g}(\bar{X}, \bar{Y})
\end{align*}
$$

Therefore the curvature tensor of $P_{n}(C) \times P_{n}(C)$ is given by

$$
\begin{align*}
& \bar{R}(\bar{X}, \bar{Y}) \bar{Z}=\frac{1}{8}\{\bar{g}(\bar{Y}, \bar{Z}) \bar{X}-\bar{g}(\bar{X}, \bar{Z}) \bar{Y}+\bar{g}(\bar{J} \bar{Y}, \bar{Z}) \bar{J} \bar{X}  \tag{1.10}\\
& \quad-\bar{g}(\bar{J} \bar{X}, \bar{Z}) \bar{J} \bar{Y}+2 \bar{g}(\bar{X}, \bar{J} \bar{Y}) \bar{J} \bar{Z}+\bar{g}(\bar{F} \bar{Y}, \bar{Z}) \bar{F} \bar{X}-\bar{g}(\bar{F} \bar{X}, \bar{Z}) \bar{F} \bar{Y} \\
& \quad+\bar{g}(\bar{F} \bar{J} \bar{Y}, \bar{Z}) \bar{F} \bar{J} \bar{X}-\bar{F}(\bar{J} \bar{X}, \bar{Z}) \bar{F} \bar{J} \bar{Y}+2 \bar{g}(\bar{F} \bar{X}, \bar{J} \bar{Y}) \bar{F} \bar{J}\}
\end{align*}
$$

from which we can easily see that $P_{n}(C) \times P_{n}(C)$ is an Einstein Kaehler manifold because of (1.6), (1.7) and (1.9) (See [8], [10]).

Now, let $M$ be a complex hypersurface of $P_{n}(C) \times P_{n}(C)$, and $B$ the differential of the immersion $\underline{i}$ of $M$ into $P_{n}(C) \times P_{n}(C)$. Let $g$ and $J$ be the induced Riemannian metric and the induced complex structure on $M$, respectively, and $V$ denote the operator of covariant differentiation with respect to the Riemannian connection of $g$. Let $X, Y$ and $Z$ be tangent to $M$ and $N$ a unit normal vector. Then we have the following:

$$
\begin{gather*}
\bar{F} B X=B f X+u(X) N+\tilde{u}(X) \bar{J} N,  \tag{1.11}\\
\bar{F} N=B U+\lambda N+\tilde{\lambda} \bar{J} N  \tag{1.12}\\
g(U, X)=u(X), \quad g(J U, X)=\tilde{u}(X), \\
\widetilde{u}(X)=-u(J X), \quad J f=f J, \tilde{\lambda}=0, \\
\bar{\nabla}_{B X} B Y=B \nabla_{X} Y+h(X, Y) N+k(X, Y) \bar{J} N  \tag{1.13}\\
\bar{\nabla}_{B X} N=-B H X+s(X) \bar{J} N  \tag{1.14}\\
h(X, Y)=g(H X, Y), \quad k(X, Y)=g(J H X, Y) \\
H J=-J H, \quad \operatorname{trace} H=\operatorname{trace} H J=0
\end{gather*}
$$

(1.15) $\quad R(X, Y) Z$

$$
\begin{aligned}
= & \frac{1}{8}\{g(Y, Z) X-g(X, Z) Y+g(J Y, Z) J X-g(J X, Z) J Y \\
& +2 g(X, J Y) J Z+g(f Y, Z) f X-g(f X, Z) f Y \\
& +g(f J Y, Z) f J X-g(f J X, Z) f J Y+2 g(f X, J Y) f J Z\} \\
& +\{h(Y, Z) H X-h(X, Z) H Y\}+\{k(Y, Z) J H X-k(X, Z) J H Y\}
\end{aligned}
$$

—Gauss equation,

$$
\begin{align*}
& \left(\nabla_{X} H\right) Y-\left(\nabla_{Y} H\right) X-s(X) J H Y+s(Y) J H X  \tag{1.16}\\
& \quad=\frac{1}{8}\{u(X) f Y-u(Y) f X
\end{align*}
$$

$$
+u(J X) f J Y-u(J Y) f J X-2 g(f X, J Y) J U\}
$$

—Codazzi equation,

$$
\begin{align*}
& \left(\nabla_{X} s\right)(Y)-\left(\nabla_{Y} s\right)(X)=2 d s(X, Y)  \tag{1.17}\\
& \quad=X \cdot s(Y)-Y \cdot s(X)-s([X, Y]) \\
& = \\
& \quad 2 g\left(X, J H^{2} Y\right)+\frac{1}{4}\{u(X) u(J Y)-u(J X) u(Y) \\
& \quad+g(X, J Y)+\lambda g(f X, J Y)\}
\end{align*}
$$

——Ricci equation,

$$
\begin{array}{cc}
(1.18) & f^{2} X=X-u(X) U+u(J X) J U, \\
(1.19) & u(f X)=-\lambda u(X), \\
(1.20) & f U=-\lambda U, \\
(1.21) & u(U)=g(U, U)=1-\lambda^{2}, \\
(1.22) & \left(\nabla_{Y} f\right) X=h(Y, X) U+k(Y, X) J U+u(X) H Y-u(J X) J H Y, \\
(1.23) & \left(\nabla_{Y} u\right) X=\lambda h(Y, X)-h(Y, f X)-s(Y) u(J X), \\
(1.24) & \nabla_{X} U=-f H X+\lambda H X+s(X) J U, \\
(1.25) & X \cdot \lambda=-2 h(X, U)=-2 u(H X), \\
(1.26) & S(X, Y)=\frac{2 n+1}{4} g(X, Y)-\frac{1}{4} u(X) u(Y)-\frac{1}{4} u(J X) u(J Y) \\
& -\frac{1}{4} g(f X, Y) \lambda-2 g\left(H^{2} X, Y\right), \\
& \rho=2 n^{2}-\left(1-\lambda^{2}\right)-2 \operatorname{trace} H^{2}, \tag{1.27}
\end{array}
$$

where $f ; u, \tilde{u} ; U ; \lambda, \tilde{\lambda} ; h, k ; s ; S$ and $\rho$ define a symmetric linear transformation of the tangent bundle of $M$, two 1 -forms, a vector field, two functions on $M$, the second fundamental tensors of the hypersurface, a normal connection form, the Ricci tensor of $M$ and the scalar curvature of $M$, respectively (See [2], [3]).

If $u$ is identically zero, then $M$ is said to be an invariant hypersurface, that is, the tangent space $T_{x}(M)$ is invariant under $\bar{F}$. We can easily see by (1.21) that this is equivalent to $\lambda^{2}=1$.

Pick an orthonormal frame $\bar{E}_{A}, \bar{E}_{A^{*}}=\bar{J} \bar{E}_{A}, A=1, \cdots, 2 n$ in such a way that the first $2 n-1 \bar{E}_{A}$ 's satisfy $\bar{E}_{a}=B E_{a}$, and $\bar{E}_{2 n}=N^{(1)}$. Then
${ }^{(1)}$ We use the following convention on the range of indices unless otherwise stated:

$$
\begin{aligned}
& A, B, C, D=1, \cdots, 2 n \\
& a, b, c, d=1, \cdots, 2 n-1 \\
& i, j, k, l=1, \cdots, 2 n-1,1^{*}, \cdots, 2 n-1^{*}
\end{aligned}
$$

because of (1.6) and (1.11) we have

$$
\begin{aligned}
\operatorname{trace} f & =\sum g\left(f E_{i}, E_{i}\right) \\
& =\sum \bar{g}\left(B f E_{i}, B E_{i}\right)=\sum \bar{g}\left(\bar{F} B E_{i}, B E_{i}\right) \\
& =\sum \bar{g}\left(\bar{F} \bar{E}_{A}, \bar{E}_{A}\right)+\sum \bar{g}\left(\bar{F} \bar{E}_{A} *, \bar{E}_{A} *\right)-\bar{g}(\bar{F} N, N)-\bar{g}(\bar{F} \bar{J} N, \bar{J} N) \\
& =\operatorname{trace} \bar{F}-2 \lambda=-2 \lambda .
\end{aligned}
$$

From (1.21) and (1.27) we easily get
Proposition 1.1. The scalar curvature $\rho$ of $M$ satisfies $\rho \leqq 2 n^{2}$. If the equality holds, then $M$ is an invariant and totally geodesic hypersurface of $P_{n}(C) \times P_{n}(C)$.

We will see later Theorem 2.1 that "invariant" of Proposition 1.1 automatically holds.
2. Integral formulas of Simons' type. Consider the function $\varphi=$ 2 trace $H^{2}$. We will now compute the Laplacian $\Delta \varphi$. Since $M$ is a minimal submanifold of $P_{n}(C) \times P_{n}(C)$, the following holds ([1]):

$$
\begin{aligned}
\frac{1}{2} \Delta \varphi= & \sum\left\|\nabla^{*} H_{\alpha}\right\|^{2}+\sum \operatorname{trace}\left(H_{\alpha} H_{\beta}-H_{\beta} H_{\alpha}\right)^{2} \\
& -\sum\left(\operatorname{trace} H_{\alpha} H_{\beta}\right)^{2} \\
+ & \sum\left(4 \bar{g}\left(\bar{R}\left(\bar{E}_{i}, \bar{E}_{j}\right) \bar{E}_{\beta}, \bar{E}_{\alpha}\right) g\left(H_{\alpha} E_{j}, E_{k}\right) g\left(H_{\beta} E_{i}, E_{k}\right)\right. \\
& -\bar{g}\left(\bar{R}\left(\bar{E}_{\beta}, \bar{E}_{k}\right) \bar{E}_{k}, \bar{E}_{\alpha}\right) g\left(H_{\alpha} E_{i}, E_{j}\right) g\left(H_{\beta} E_{i}, E_{j}\right) \\
& +2 \bar{g}\left(\bar{R}\left(\bar{E}_{k}, \bar{E}_{j}\right) \bar{E}_{j}, \bar{E}_{i}\right) g\left(H_{\alpha} E_{i}, E_{l}\right) g\left(H_{\beta} E_{k}, E_{l}\right) \\
& \left.+2 \bar{g}\left(\bar{R}\left(\bar{E}_{k}, \bar{E}_{l}\right) \bar{E}_{j}, \bar{E}_{i}\right) g\left(H_{\alpha} E_{i}, E_{l}\right) g\left(H_{\beta} E_{j}, E_{k}\right)\right),
\end{aligned}
$$

where Greek indices $\alpha, \beta$ have the range $\left\{2 n, 2 n^{*}\right\}$, and $H_{2 n}=H, H_{2 n}^{*}=$ $J H$, and $\nabla_{X}^{*} H=\nabla_{X} H-s(X) J H$ ([2]). Using (1.9), (1.10), (1.11), (1.12), (1.15), (1.18), (1.21) and trace $f=-2 \lambda$, the last term of the right hand side of the above equation equals to

$$
\frac{n+1}{2} \varphi+\frac{1}{2} \lambda^{2} \varphi+2 \operatorname{trace}(f H)^{2}-3 \lambda \operatorname{trace} f H^{2}-6 g\left(H^{2} U, U\right)
$$

Moreover we have ([6])

$$
\sum \operatorname{trace}\left(H_{\alpha} H_{\beta}-H_{\beta} H_{\alpha}\right)^{2}=-8 \operatorname{trace} H_{2 n}^{4}=-8 \operatorname{trace} H^{4}
$$

Thus we have

$$
\begin{align*}
\frac{1}{2} \Delta \varphi= & \frac{n+1}{2} \varphi+\frac{1}{2} \lambda^{2} \varphi-\frac{1}{2} \varphi^{2}  \tag{2.1}\\
& +2 \operatorname{trace}(f H)^{2}-3 \lambda \operatorname{trace} f H^{2}-6 g\left(H^{2} U, U\right) \\
& -8 \operatorname{trace} H^{4}+2\left\|\nabla^{*} H\right\|^{2}
\end{align*}
$$

Next we want to compute $\operatorname{div}(f H U)$. Extend an orthonormal basis $E_{i}$ 's for $T_{x}(M)$ to vector fields in a neighborhood of $x$ in such a way that $\nabla E_{i}=0$ at $x$. Since $\operatorname{div} Z=\sum g\left(\nabla_{E_{i}} Z, E_{i}\right)$ for any vector field $Z$, we first have, for a vector field $X$,

$$
\begin{aligned}
& \nabla_{X}(f H U)=\left(\nabla_{x} f\right) H U+f\left(\nabla_{x} H\right) U+f H \nabla_{x} U \\
&= g\left(H^{2} U, X\right) U+g\left(J H^{2} U, X\right) J U+g(H U, U) H X-g(J H U, U) J H X \\
&+f\left(\left(\nabla_{U} H\right) X+s(X) J H U-s(U) J H X+\frac{1}{8}(u(X) f U-u(U) f X\right. \\
&+u(J X) f J U-u(J U) f J X-2 g(f X, J U) J U))+f H(-f H X \\
&+\lambda H X+s(X) J U) \\
&= g\left(H^{2} U, X\right) U+g\left(J H^{2} U, X\right) J U+g(H U, U) H X-g(J H U, U) J H X \\
&+f\left(\nabla_{U} H\right) X-s(U) f J H X+\frac{1}{8} \lambda^{2} u(X) U-\frac{1}{8}\left(1-\lambda^{2}\right)(X-u(X) U \\
&+u(J X) J U)+\frac{3}{8} \lambda^{2} u(J X) J U-(f H)^{2} X+\lambda f H^{2} X
\end{aligned}
$$

because of (1.16), (1.18), (1.20), (1.21), (1.22) and (1.24), from which it follows that

$$
\begin{aligned}
& \operatorname{div}(f H U)=2 g(H U, H U)+\operatorname{trace} f \nabla_{U} H-\frac{n}{2}\left(1-\lambda^{2}\right) \\
& \quad+\frac{1}{2}\left(1-\lambda^{2}\right)^{2}-\operatorname{trace}(f H)^{2}+\lambda \operatorname{trace} f H^{2}
\end{aligned}
$$

On the other hand, we have

$$
\text { trace } \begin{aligned}
f H & =\sum\left\{g\left(f H E_{a}, E_{a}\right)+g\left(f H J E_{a}, J E_{a}\right)\right\} \\
& =\sum\left\{g\left(J f H E_{a}, J E_{a}\right)+g\left(f H J E_{a}, J E_{a}\right)\right\} \\
& =\sum\left\{-g\left(f H J E_{a}, J E_{a}\right)+g\left(f H J E_{a}, J E_{a}\right)\right\}=0
\end{aligned}
$$

from which we obtain

$$
\begin{aligned}
0 & =\nabla_{X}(\operatorname{trace} f H) \\
& =\sum \nabla_{X}\left(g\left(f H E_{i}, E_{i}\right)\right) \\
& =\sum\left\{g\left(\left(\nabla_{X} f\right) H E_{i}, E_{i}\right)+g\left(f\left(\nabla_{X} H\right) E_{i}, E_{i}\right)\right\} \\
& =\sum\left\{g\left(H^{2} X, E_{i}\right) g\left(U, E_{i}\right)+g\left(H J H X, E_{i}\right) g\left(J U, E_{i}\right)\right.
\end{aligned}
$$

$$
\begin{aligned}
& \quad \text { COMPLEX HYPERSURFACES OF } P_{n}(C) \times P_{n}(C) \\
& + \\
& + \\
& +\operatorname{trace} f \nabla_{X} H \\
& = \\
& \text { trace } f \nabla_{X} H,
\end{aligned}
$$

because of (1.22), from which it follows that

$$
\begin{align*}
\operatorname{div}(f H U)= & 2 g(H U, H U)-\operatorname{trace}(f H)^{2}+\lambda \operatorname{trace} f H^{2}  \tag{2.2}\\
& -\frac{n}{2}\left(1-\lambda^{2}\right)+\frac{1}{2}\left(1-\lambda^{2}\right)^{2}
\end{align*}
$$

Now we compute $\operatorname{div}(\lambda H U)$. From (1.16), (1.24) and (1.25), we have

$$
\begin{aligned}
& \nabla_{X}(\lambda H U)=(X \cdot \lambda) H U+\lambda\left(\nabla_{X} H\right) U+\lambda H \nabla_{X} U \\
& = \\
& \quad-2 u(H X) H U+\lambda\left(\nabla_{U} H\right) X-\lambda s(U) J H X \\
& \quad+\frac{\lambda}{8}\{u(X) f U-u(U) f X+u(J X) f J U-2 g(f X, J U) J U\} \\
& \quad-\lambda H f H X+\lambda^{2} H^{2} X .
\end{aligned}
$$

Therefore

$$
\begin{align*}
\operatorname{div}(\lambda H U)= & -2 g(H U, H U)+\frac{1}{2} \lambda^{2}\left(1-\lambda^{2}\right)-\lambda \operatorname{trace} f H^{2}  \tag{2.3}\\
& +\frac{1}{2} \lambda^{2} \varphi
\end{align*}
$$

Thus we have

$$
\begin{align*}
& \frac{1}{2} \Delta \varphi+2 \operatorname{div}(f H U)-\operatorname{div}(\lambda H U)  \tag{2.4}\\
& \quad=\frac{n+1}{2} \varphi-\frac{1}{2} \varphi^{2}-8 \operatorname{trace} H^{4}-\frac{1}{2}\left(2 n-2+3 \lambda^{2}\right)\left(1-\lambda^{2}\right) \\
& \quad+2\left\|\nabla^{*} H\right\|^{2} .
\end{align*}
$$

From (2.2), (2.3) or (2.4) we easily get
Theorem 2.1. A totally geodesic hypersurface of $P_{n}(C) \times P_{n}(C)$ is an invariant hypersurface.

Assume that the hypersurface $M$ is compact. Integrating the above equation over $M$, we get, because of Green-Stokes' theorem,

$$
\begin{align*}
& \int_{M}\left\{\frac{n+1}{2} \varphi-\frac{1}{2} \varphi^{2}-8 \operatorname{trace} H^{4}\right.  \tag{2.5}\\
&\left.\quad-\frac{1}{2}\left(2 n-2+3 \lambda^{2}\right)\left(1-\lambda^{2}\right)+2\left\|\nabla^{*} H\right\|^{2}\right\} d M=0 .
\end{align*}
$$

Applying $(1 /(2 n-1)) \varphi^{2} \leqq 8$ trace $H^{4}([5])$ to (2.5), we have
Theorem 2.2. A compact Kaehler hypersurface of $P_{n}(C) \times P_{n}(C)$ satisfying

$$
\begin{equation*}
\int_{M}\left(\frac{2 n+1}{2 n-1} \varphi^{2}-(n+1) \varphi\right) d M \geqq 4 \int_{M}\left\|\nabla^{*} H\right\|^{2} d M \tag{2.6}
\end{equation*}
$$

is an invariant hypersurface.
Remark. From (2.5) and (2.6), we easily see that a compact Kaehler hypersurface with parallel second fundamental tensor of $P_{n}(C) \times P_{n}(C)$ satisfying $\varphi \geqq(2 n-1)(n+1) /(2 n+1)$ is an invariant hypersurface and $\varphi \equiv(2 n-1)(n+1) /(2 n+1)$. However, we will see later Theorem 3.7 that there exist no such invariant hypersurfaces.
3. Invariant hypersurfaces of $P_{n}(C) \times P_{n}(C)$. In this section we assume that the hypersurface $M$ is invariant, i.e., (1.11) can be written as

$$
\bar{F} B X=B f X
$$

Since the 1 -form $u$ and the vector field $U$ vanish identically, we have

$$
\begin{equation*}
1-\lambda^{2}=0 \tag{3.2}
\end{equation*}
$$

$$
\begin{equation*}
\nabla_{x} f=0 \tag{3.3}
\end{equation*}
$$

$$
\begin{equation*}
f^{2} X=X \tag{3.1}
\end{equation*}
$$

$$
\begin{equation*}
X \cdot \lambda=0 \tag{3.4}
\end{equation*}
$$

We may assume that $\lambda=1$ in the following discussions. Then the formula (2.5) becomes

$$
\begin{equation*}
\int_{M}\left\{\frac{n+1}{2} \varphi-\frac{1}{2} \varphi^{2}-8 \operatorname{trace} H^{4}+2\left\|\nabla^{*} H\right\|^{2}\right\} d M=0 . \tag{3.5}
\end{equation*}
$$

Thus noting that 8 trace $H^{4} \leqq \varphi^{2}$ ([5], [9]), we get
Theorem 3.1. Let $M$ be a compact invariant Kaehler hypersurface of $P_{n}(C) \times P_{n}(C)$. Then either $M$ is the totally geodesic hypersurface, $\varphi \equiv(n+1) / 3$, or $\varphi(x)>(n+1) / 3$ at some $x \in M$.

Corollary 3.2. Let $M$ be a compact invariant Kaehler hypersurface of $P_{n}(C) \times P_{n}(C)$. If $\varphi<(n+1) / 3$, then $M$ is a totally geodesic hypersurface.

Now let

$$
\begin{aligned}
T_{1}(x) & =\left\{X \in T_{x}(M) ; f X=X\right\} \\
T_{-1}(x) & =\left\{X \in T_{x}(M) ; f X=-X\right\}
\end{aligned}
$$

Then $x \rightarrow T_{1}(x)$ and $x \rightarrow T_{-1}(x)$ define ( $n-1$ )-dimensional and $n$-dimensional distributions respectively, since trace $f=-2 \lambda=-2$. By virtue of (3.3) it follows that both distributions are involutive. We easily see that if $X \in T_{1}$ and $Y \in T_{-1}$, then $\nabla_{Y} X \in T_{1}$ and $\nabla_{X} Y \in T_{-1}$. Hence both distributions are parallel. Moreover, for the vector fields $X$ and $Y$ chosen in the above way, we have $g\left(\nabla_{Z} X, Y\right)=0$ and $g\left(\nabla_{W} Y, X\right)=0$, where $Z \in T_{1}$ and $W \in T_{-1}$. Thus the maximal integral manifolds through each $x \in M$ of $T_{1}$ and $T_{-1}$ are both totally geodesic in $M$. By standard arguments (See [3]) we know that $M$ is a product of the maximal integral manifolds of the distributions $T_{1}$ and $T_{-1}$. In the next step we want to show that the maximal integral manifold of $T_{-1}$ is $P_{n}(C)$.

Let $X \in T_{-1}$. Then by virtue of (1.1) and (1.2) it follows that

$$
\bar{P} B X=\frac{1}{2}(I B X+\bar{F} B X)=\frac{1}{2}(B X+B f X)=0 .
$$

Thus $B X$ belongs to the tangent space $T\left(P_{n}(C)\right)$ which is defined by $V_{Q}=\{\bar{X} ; \bar{Q} \bar{X}=\bar{X}\}$. Conversely, if we take a vector field $\bar{X}$ belonging to $V_{Q}, \bar{X}$ can be written as a sum of the tangential components and the normal components. So we put

$$
\bar{X}=B X+\alpha N+\widetilde{\alpha} \bar{J} N
$$

Applying $\bar{P}$ to the above equation, we have

$$
\begin{aligned}
0 & =\bar{P} \bar{X}=\bar{P} B X+\alpha \bar{P} N+\tilde{\alpha} \bar{P} \bar{J} N \\
& =\frac{1}{2}\{(I B X+\bar{F} B X)+\alpha(I N+\bar{F} N)+\tilde{\alpha}(I \bar{J} N+\bar{F} \bar{J} N)\} \\
& =\frac{1}{2}\{B X+B f X+2 \alpha N+2 \tilde{\alpha} \bar{J} N\}
\end{aligned}
$$

from which we have

$$
f X=-X, \quad \alpha=0, \quad \tilde{\alpha}=0
$$

This means that $\bar{X}=B X$, and consequently $V_{Q}=B T_{-1}$. Thus, if $M$ is complete, the maximal integral manifold of $T_{-1}$ must be $P_{n}(C)$. If $X \in$ $T_{1}$, then the same discussion as above shows that $B X \in V_{P}=\{\bar{X} ; \bar{P} \bar{X}=\bar{X}\}$. Since the integral submanifold of $V_{P}$ is another $P_{n}(C)$, the maximal integral manifold of $T_{1}$ is a hypersurface of $P_{n}(C)$. Thus we have

Theorem 3.3. A complete invariant Kaehler hypersurface of $P_{n}(C) \times P_{n}(C)$ is a product manifold $M^{\prime} \times P_{n}(C)$, where $M^{\prime}$ is a Kaehler hypersurface of $P_{n}(C)$.

In order to get further results, we prove

Lemma 3.4. Let $P$ and $Q$ be the projection of $T(M)$ into $T\left(M^{\prime}\right)$ and $T\left(P_{n}(C)\right)$ respectively. Then we have

$$
\begin{equation*}
H Q=0 . \tag{3.6}
\end{equation*}
$$

Proof. By the definitions of $\bar{F}, P$ and $Q$, we have

$$
\bar{F} B Q X=(\bar{P}-\bar{Q}) B Q X=(\bar{P}-\bar{Q}) \bar{Q} B X=-\bar{Q} B X=-B Q X
$$

since $V_{Q}=B T_{-1}$. Hence

$$
\begin{align*}
\bar{V}_{B Y}(\bar{F} B Q X) & =-\bar{\nabla}_{B Y}(B Q X)  \tag{3.7}\\
& =-B \nabla_{Y}(Q X)-h(Y, Q X) N-k(Y, Q X) \bar{J} N
\end{align*}
$$

On the other hand, we have

$$
\begin{align*}
& \bar{V}_{B Y}(\bar{F} B Q X)  \tag{3.8}\\
&=\bar{F}\left(B \nabla_{Y}(Q X)+h(Y, Q X) N+k(Y, Q X) \bar{J} N\right) \\
& \quad=-B \nabla_{Y}(Q X)+h(Y, Q X) \bar{F} N+k(Y, Q X) \bar{F} \bar{J} N \\
& \quad=-B \nabla_{Y}(Q X)+h(Y, Q X) N+k(Y, Q X) \bar{J} N
\end{align*}
$$

because of the fact that $\nabla_{Y}(Q X) \in V_{Q}, \bar{F} N=N$ and $\bar{F} \bar{J} N=\bar{J} N$.
Comparing (3.7) and (3.8), we have $h(Y, Q X)=k(Y, Q X)=0$, from which (3.6) follows.

We consider the immersion $i^{\prime}: M^{\prime} \rightarrow M^{\prime} \times P_{n}(C)=M$, and denote the differential of $i^{\prime}$ by $B^{\prime}$. Then we have

$$
\begin{align*}
& \bar{V}_{B B^{\prime} Y^{\prime}} B B^{\prime} X^{\prime}=B B^{\prime} V^{\prime}{ }_{Y^{\prime}} X^{\prime}  \tag{3.9}\\
& \quad+\sum_{A=1}^{n+1} h_{A}^{\prime}\left(X^{\prime}, Y^{\prime}\right) N_{A}^{\prime}+\sum_{A=1}^{n+1} k_{A}^{\prime}\left(X^{\prime}, Y^{\prime}\right) \bar{J} N_{A}^{\prime},
\end{align*}
$$

where $X^{\prime}$ and $Y^{\prime} \in T\left(M^{\prime}\right)$, and $h_{A}^{\prime}$ and $k_{A}^{\prime}$ 's are the second fundamental tensors with respect to the normals $N_{A}^{\prime}$ and $\bar{J} N_{A}^{\prime}$ respectively. Now we choose the last normal $N_{n+1}^{\prime}$ in such a way that $N_{n+1}^{\prime}$ is the unit normal to $M^{\prime}$ in $P_{n}(C)$.

On the other hand, we have

$$
\begin{aligned}
& \overline{\bar{V}}_{B B^{\prime} Y^{\prime}} B B^{\prime} X^{\prime} \\
& \quad=B \nabla_{B^{\prime} Y^{\prime}} B^{\prime} X^{\prime}+h\left(B^{\prime} X^{\prime}, B^{\prime} Y^{\prime}\right) N+k\left(B^{\prime} X^{\prime}, B^{\prime} Y^{\prime}\right) \bar{J} N
\end{aligned}
$$

from which it follows that

$$
\begin{align*}
& \overline{\bar{V}}_{B B^{\prime} Y^{\prime}} B B^{\prime} X^{\prime}=B B^{\prime} \nabla_{Y^{\prime}}^{\prime} X^{\prime}  \tag{3.10}\\
& \quad+\sum_{\alpha=1}^{n} h_{\alpha}\left(X^{\prime}, Y^{\prime}\right) B N_{\alpha}+\sum_{\alpha=1}^{n} k_{\alpha}\left(X^{\prime}, Y^{\prime}\right) B J N_{\alpha} \\
& \quad+h\left(B^{\prime} X^{\prime}, B^{\prime} Y^{\prime}\right) N+k\left(B^{\prime} X^{\prime}, B^{\prime} Y^{\prime}\right) \bar{J} N
\end{align*}
$$

Comparing (3.9) and (3.10), we get

$$
\begin{aligned}
& h_{\alpha}\left(X^{\prime}, Y^{\prime}\right)=h_{\alpha}^{\prime}\left(X^{\prime}, Y^{\prime}\right), \quad k_{\alpha}\left(X^{\prime}, Y^{\prime}\right)=k_{\alpha}^{\prime}\left(X^{\prime}, Y^{\prime}\right), \\
& \text { for } \alpha=1, \cdots, n, \\
& h\left(B^{\prime} X^{\prime}, B^{\prime} Y^{\prime}\right)=h_{n+1}^{\prime}\left(X^{\prime}, Y^{\prime}\right), \\
& k\left(B^{\prime} X^{\prime}, B^{\prime} Y^{\prime}\right)=k_{n+1}^{\prime}\left(X^{\prime}, Y^{\prime}\right) .
\end{aligned}
$$

Since $M^{\prime}$ is a totally geodesic submanifold in $M^{\prime} \times P_{n}(C)$, it follows that $h_{\alpha}\left(X^{\prime}, Y^{\prime}\right)=k_{\alpha}\left(X^{\prime}, Y^{\prime}\right)=0$ for $\alpha=1, \cdots, n$. Also, for any positive integer $p$,

$$
\begin{aligned}
\operatorname{trace} H^{p}= & \sum g\left(H^{p} E_{a}, E_{a}\right)+\sum g\left(H^{p} J E_{a}, J E_{a}\right) \\
= & \sum_{A=1}^{n-1} g\left(H^{p} B^{\prime} E_{A}, B^{\prime} E_{A}\right)+\sum_{t=1}^{n} g\left(H^{p} N_{t}^{\prime}, N_{t}^{\prime}\right) \\
& +\sum_{A=1}^{n-1} g\left(H^{p} J B^{\prime} E_{A}, J B^{\prime} E_{A}\right)+\sum_{t=1}^{n} g\left(H^{p} J N_{t}^{\prime}, J N_{t}^{\prime}\right),
\end{aligned}
$$

where $N_{t}^{\prime}, t=1, \cdots, n$ are unit normals to $M^{\prime}$ in $M^{\prime} \times P_{n}(C)$. Since there exist $X_{t}$ in $T(M)$ such that $N_{t}^{\prime}=Q X_{t}$, we have $H^{p} N_{t}^{\prime}=0$, because of Lemma 3.4. Thus we get

$$
\begin{aligned}
\operatorname{trace} H^{p} & =\sum_{A=1}^{n-1} g\left(H^{p} B^{\prime} E_{A}, B^{\prime} E_{A}\right)+\sum_{A=1}^{n-1} g\left(H^{p} J B^{\prime} E_{A}, J B^{\prime} E_{A}\right) \\
& =\sum_{A=1}^{n-1} g\left(H_{n+1}^{\prime p} E_{A}, E_{A}\right)+\sum_{A=1}^{n-1} g\left(H_{n+1}^{\prime p} J^{\prime \prime} E_{A}, J^{\prime \prime} E_{A}\right) \\
& =\operatorname{trace} H_{n+1}^{\prime p},
\end{aligned}
$$

where $J^{\prime \prime}$ is the complex structure of $M^{\prime}$. This shows that, once we fix a choice of normals in the above way, trace $H^{p}$ is a function on $M^{\prime}$. The immersion $\underline{i}: M \rightarrow P_{n}(C) \times P_{n}(C)$ being $\underline{i}^{\prime} \times i d: M^{\prime} \times P_{n}(C) \rightarrow P_{n}(C) \times$ $P_{n}(C)$, we have that the second fundamental tensor $H_{n+1}^{\prime}$ is identical with that of $M^{\prime}$ in $P_{n}(C)$. Thus, denoting the second fundamental tensor of $M^{\prime}$ in $P_{n}(C)$ by $H^{\prime}$ we can easily see that if $\rho=2 n^{2}-\varphi=$ constant, then $\rho^{\prime}=n(n-1)-2 \operatorname{trace} H^{\prime 2}=n(n-1)-\varphi^{\prime}=$ constant, where $\rho^{\prime}$ is the scalar curvature of $M^{\prime}$.

If $\varphi=0$, it follows that $\varphi^{\prime}=0$ and consequently $M^{\prime}$ is totally geodesic in $P_{n}(C)$. Thus we have $M=P_{n-1}(C) \times P_{n}(C)$.

If $\varphi=(n+1) / 3$, then $\varphi^{\prime}=(n+1) / 3$. Hence $n=2$ and $M^{\prime}$ is imbedded as a complex quadric $Q_{1}(C)$ in $P_{2}(C)$ ([9]). Thus $M=Q_{1}(C) \times$ $P_{2}(C)$.

If $\varphi=n-1$, then $\varphi^{\prime}=n-1$. Thus $\rho^{\prime}=(n-1)^{2}$.
From the above fact, we have
Theorem 3.5. If $\varphi \leqq(n+1) / 3$, then $M=P_{n-1}(C) \times P_{n}(C)$ or $n=2$
and $M=Q_{1}(C) \times P_{2}(C)$.
Moreover, combining Theorem 2.1, we get
Theorem 3.6. $\quad P_{n-1}(C) \times P_{n}(C)$ is the only totally geodesic hypersurface of $P_{n}(C) \times P_{n}(C)$.

Applying Kon's theorem (See [4], Theorem 1) and combining Theorem 3.3, we have

Theorem 3.7. $\quad P_{n-1}(C) \times P_{n}(C)$ and $Q_{n-1}(C) \times P_{n}(C)$ are the only compact invariant Kaehler hypersurfaces of $P_{n}(C) \times P_{n}(C)$ with constant scalar curvature, where $Q_{n-1}(C)$ is the complex quadric.

Corollary 3.8. There exist no compact invariant Einstein Kaehler hypersurfaces of $P_{n}(C) \times P_{n}(C)$.

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