# UNIFORM STABILITY FOR ONE-DIMENSIONAL DELAY-DIFFERENTIAL EQUATIONS WITH DOMINANT DELAYED TERM 

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1. Introduction. For $q \geqq 0$ and $\alpha, \beta \in \boldsymbol{R}$, the one-dimensional differentialdifference equation

$$
\begin{equation*}
x^{\prime}(t)=-\alpha x(t)-\beta x(t-q) \tag{1.1}
\end{equation*}
$$

is a simple example of a delay-differential equation and has been studied from early times in the development of the stability theory of delay-differential equations. For (1.1), the theory of characteristic equations is valid and it is known that the zero solution of (1.1) is uniformly stable if and only if $\alpha$ and $\beta$ satisfy one of the following conditions:
$\left(R_{1}\right) \quad \alpha \geqq|\beta|$,
$\left(R_{2}\right) \quad \alpha=\beta \sin \eta, \quad 0 \leqq \beta q \leqq\left(\eta+\frac{\pi}{2}\right) / \cos \eta, \quad-\frac{\pi}{2}<\eta<\frac{\pi}{2}$,
$\left(R_{3}\right) \quad-\alpha=\beta, \quad 0 \leqq \beta q<1$,
that is, $(\alpha, \beta)$ is contained in the region (stability region) illustrated in Figure 1 with its boundary except for the point $(-1 / q, 1 / q)$. Moreover, the zero solution of (1.1) is uniformly asymptotically stable if and only if $(\alpha, \beta)$ is contained in the interior of $R_{1} \cup R_{2}$ (cf. [3], [7]). It is a feature that $R_{2}$ and $R_{3}$ become smaller as $q$ increases, while $R_{1}$ is independent of $q$.

On the other hand, the theory of characteristic equations is not applicable to the delay-differential equation such as

$$
\begin{equation*}
x^{\prime}(t)=-a(t) x(t)-b(t) x(t-r(t)) \tag{1.2}
\end{equation*}
$$

where $a, b:[0, \infty) \rightarrow \boldsymbol{R}$ and $r:[0, \infty) \rightarrow[0, q]$ are continuous functions. Liapunov's method seems to be the only way to investigate the behavior of solutions of (1.2). For (1.2), it is reasonable to expect a similar stability region for ( $\alpha, \beta$ ) under the conditions

$$
\begin{equation*}
0 \leqq \alpha \leqq a(t), \quad|b(t)| \leqq \beta \tag{1.3}
\end{equation*}
$$

or

$$
\begin{equation*}
\alpha \leqq a(t) \leqq 0, \quad 0 \leqq b(t) \leqq \beta . \tag{1.4}
\end{equation*}
$$



Figure 1

There are many works for the stability region which is independent of $q$ like the region $R_{1}$ (cf. [6], [8], [9], [12], [13]). But there are few works for the stability region corresponding to $R_{2}$ ([2], [16]). In the case $a(t) \equiv 0$ in (1.2), i.e., for the equation

$$
\begin{equation*}
x^{\prime}(t)=-b(t) x(t-r(t)), \tag{1.5}
\end{equation*}
$$

the stability of the zero solution has been much studied (cf. [4], [5], [10], [11], [14]). It is interesting that under the condition $0 \leqq b(t) \leqq \beta$, the zero solution of (1.5) is uniformly stable if $\beta q \leqq 3 / 2$, but there are equations with unbounded solutions if $\beta q>3 / 2$. The stability region $0 \leqq \beta q \leqq 3 / 2$ for (1.5) does not coincide with the stability region $0 \leqq \beta q \leqq \pi / 2$ for the differential-difference equation

$$
x^{\prime}(t)=-\beta x(t-q) .
$$

For a general delay-differential equation

$$
\begin{equation*}
x^{\prime}(t)=F\left(t, x_{t}\right), \tag{1.6}
\end{equation*}
$$

where $F:[0, \infty) \times C^{q} \rightarrow \boldsymbol{R}$, Yorke [17] has shown the uniform stability of the zero solution under the conditions

$$
\begin{equation*}
-\beta M(\phi) \leqq F(t, \phi) \leqq \beta M(-\phi) \quad \text { and } \quad 0 \leqq \beta q \leqq 3 / 2 \tag{1.7}
\end{equation*}
$$

where $M(\phi)=\max \left\{0, \sup _{s \in[-q, 0]} \phi(s)\right\}$. The author [15] proved the uniform stability for (1.6) under conditions more general than (1.7).

For the special case

$$
x^{\prime}(t)=-a(t)(x(t)-x(t-q))
$$

of (1.2), Atkinson-Haddock [1] has shown the uniform stability under the conditions including

$$
|a(t)| \leqq \alpha \quad \text { and } \quad \alpha q<1
$$

which corresponds to $\left(R_{3}\right)$.
Recently, the author and Sugie [16] have established a stability region for an equation more general than (1.2) under the conditions (1.4) and $|a(t)| \leqq b(t)$.

In this paper, we study the stability region which depends on $q$ for an equation more general than (1.2). Theorem 3.1 in Section 3 gives a stability region for (1.2) under (1.3), which corresponds to ( $R_{2}$ ) with $0 \leqq \eta<\pi / 2$. Theorem 4.1 in Section 4 gives a stability region for (1.2) under (1.4), which corresponds to ( $R_{2}$ ) with $-\pi / 2<\eta<0$ and includes the stability region given in [16]. The stability region obtained for (1.1) by the


Figure 2
results in this paper is illustrated in Figure 2. We also give some results on the asymptotic stability of the zero solution of (1.2). If $(\alpha, \beta)$ is contained in the interior of the regions $S_{1}$ and $S_{2}$ in Figure 2, it will be shown that the zero solution of (1.2) is asymptotically stable. (Figures 1 and 2 were drawn accurately by a computer and an $X-Y$ plotter.) Thanks are due to the referee for valuable comments.
2. Definitions and assumptions. For $q \geqq 0$, let $C^{q}$ be the space of continuous functions on $[-q, 0]$, and define the norm

$$
\|\phi\|=\sup _{s \in[-q, 0]}|\phi(s)|
$$

for $\phi \in C^{q}$. For $H>0$, let

$$
S(H)=\{x \in \boldsymbol{R}:|x|<H\} \quad \text { and } \quad C^{q}(H)=\left\{\phi \in C^{q}:\|\phi\|<H\right\} .
$$

If $\psi(\cdot)$ is a continuous function defined on $[-q, T]$ for some $T>0$, then for $0 \leqq t \leqq T$, we denote by $\psi_{t} \in C^{q}$ the function defined by $\psi_{t}(s)=\psi(t+s)$ for $s \in[-q, 0]$.

Consider the delay-differential equation

## (DDE)

$$
x^{\prime}(t)=F\left(t, x_{t}\right)
$$

where $F:[0, \infty) \times C^{q}(H) \rightarrow \boldsymbol{R}$ is continuous and $x^{\prime}(t)$ denotes the right-hand derivative of $x(t)$. For an initial function $\phi \in C^{q}(H)$ at $t_{0} \geqq 0$, we denote by $x\left(\cdot ; t_{0}, \phi\right)$ the solution of (DDE) such that $x_{t_{0}}=\phi$. We assume that $F(t, 0) \equiv 0$ so that $x(t) \equiv 0$ is a solution of (DDE), which is called the zero solution.

DEFINITION 2.1. The zero solution of (DDE) is said to be stable if for any $\varepsilon>0$ and $t_{0} \geqq 0$ there exists $\delta\left(t_{0}, \varepsilon\right)>0$ such that if $\phi \in C^{q}(\delta)$, then

$$
\left|x\left(t ; t_{0}, \phi\right)\right|<\varepsilon \quad \text { for all } \quad t \geqq t_{0} .
$$

The zero solution of (DDE) is uniformly stable if the above $\delta$ is independent of $t_{0}$.
DEFINITION 2.2. The zero solution of (DDE) is said to be asymptotically stable if it is stable and if for any $t_{0} \geqq 0$ there exists $\delta_{0}\left(t_{0}\right) \geqq 0$ such that if $\phi \in C^{q}\left(\delta_{0}\right)$, then

$$
x\left(t ; t_{0}, \phi\right) \rightarrow 0 \quad \text { as } \quad t \rightarrow \infty .
$$

DEFINITION 2.3. The zero solution of (DDE) is said to be uniformly asymptotically stable if it is uniformly stable and if there exists $\delta_{0}>0$ such that for each $\varepsilon>0$, there exists $T(\varepsilon)>0$ such that for any $t_{0} \geqq 0$ and $\phi \in C^{q}\left(\delta_{0}\right)$,

$$
\left|x\left(t ; t_{0}, \phi\right)\right|<\varepsilon \quad \text { for all } \quad t \geqq t_{0}+T(\varepsilon) .
$$

The following condition on $F(t, \phi)$ was given by Yorke [17]: There exists $\beta \geqq 0$ such that
$\left(\mathrm{A}_{1}\right) \quad-\beta M(\phi) \leqq F(t, \phi) \leqq \beta M(-\phi) \quad$ for all $\quad t \geqq 0 \quad$ and $\quad \phi \in C^{q}(H)$,
where $M(\phi)=\max \left\{0, \sup _{s \in[-q, 0]} \phi(s)\right\}$.
The author and Sugie [16] modified the above condition and proposed the following condition to show a stability region of the delay-differential equation which will be studied in Section 4: There exist $\beta \geqq 0$ and a non-negative continuous function $b(t)$ on $[0, \infty)$ such that
( $\mathrm{A}_{2}$ )

$$
b(t) \leqq \beta \quad \text { and }
$$

$$
-b(t) \sup _{s \in[-q, 0]} \phi(s) \leqq F(t, \phi) \leqq b(t) \sup _{s \in[-q, 0]}(-\phi(s))
$$

for all $t \geqq 0$ and $\phi \in C^{q}(H)$.
We note that $\left(\mathrm{A}_{2}\right)$ implies $\left(\mathrm{A}_{1}\right)$, and if $F(t, \phi)$ satisfies $\left(\mathrm{A}_{1}\right)$ then $F(t, 0) \equiv 0$ and

$$
|F(t, \phi)| \leqq \beta\|\phi\| \quad \text { for all } \quad t \geqq 0 \quad \text { and } \quad \phi \in C^{q}(H) .
$$

EXAMPLE 2.1. Let $f:[0, \infty) \times S(H) \rightarrow \boldsymbol{R}$ and $r:[0, \infty) \times C^{q}(H) \rightarrow[0, q]$ be continuous functions such that $0 \leqq x f(t, x) \leqq \beta x^{2}$ for all $(t, x) \in[0, \infty) \times S(H)$. Then $F(t, \phi)=$ $-f(t, \phi(-r(t, \phi)))$ satisfies $\left(\mathrm{A}_{1}\right)$.

For other examples of $F(t, \phi)$ satisfying $\left(\mathrm{A}_{1}\right)$, we refer to [17].
Example 2.2. Let $b:[0, \infty) \rightarrow[0, \infty)$ be a continuous function such that $0 \leqq b(t) \leqq \beta$ for some $\beta \geqq 0$, and let $r(t, \phi)$ be a continuous function as in Example 2.1. Then $F(t, \phi)=-b(t) \phi(-r(t, \phi))$ satisfies $\left(\mathrm{A}_{2}\right)$.

Example 2.3. Let $c(t, s)$ be a continuous non-negative function defined for all $-q \leqq s \leqq t$ such that

$$
\int_{-q}^{0} c(t, t+s) d s \leqq \beta q .
$$

Then

$$
F(t, \phi)=-\frac{1}{q} \int_{-q}^{0} c(t, t+s) \phi(s) d s
$$

satisfies $\left(\mathrm{A}_{2}\right)$.
Finally we give a lemma which is useful in later sections.
Lemma 2.1. Let $x(t)$ be a continuously differentiable function on $\left[T_{1}, T_{2}\right]$ such that $x\left(t_{1}\right)=0$ for some $t_{1} \in\left[T_{1}, T_{2}\right]$ and

$$
\frac{d}{d t}|x(t)| \leqq \alpha|x(t)|+c \quad \text { for all } \quad t \in\left[T_{1}, T_{2}\right]
$$

where $\alpha \neq 0$ and $c \geqq 0$. Then

$$
\begin{equation*}
|x(t)| \leqq \frac{c}{\alpha}\left(e^{\alpha\left|t-t_{1}\right|}-1\right) \quad \text { for all } \quad t \in\left[T_{1}, T_{2}\right] \tag{2.1}
\end{equation*}
$$

Proof. Let $t \in\left[t_{1}, T_{2}\right]$. Then

$$
|x(t)|=|x(t)|-\left|x\left(t_{1}\right)\right| \leqq \alpha \int_{t_{1}}^{t}|x(s)| d s+c\left(t-t_{1}\right)
$$

and hence

$$
\frac{d}{d t}\left\{\alpha e^{-\alpha\left(t-t_{1}\right)} \int_{t_{1}}^{t}|x(s)| d s\right\} \leqq \alpha c\left(t-t_{1}\right) e^{-\alpha\left(t-t_{1}\right)}
$$

for all $t \in\left[t_{1}, T_{2}\right]$. Integrating both sides from $t_{1}$ to $t$, we have

$$
\alpha e^{-\alpha\left(t-t_{1}\right)} \int_{t_{1}}^{t}|x(s)| d s \leqq-c\left(t-t_{1}\right) e^{-\alpha\left(t-t_{1}\right)}+\frac{c}{\alpha}\left(1-e^{-\alpha\left(t-t_{1}\right)}\right)
$$

and therefore

$$
\alpha \int_{t_{1}}^{t}|x(s)| d s \leqq-c\left(t-t_{1}\right)+\frac{c}{\alpha}\left(e^{\alpha\left(t-t_{1}\right)}-1\right),
$$

which proves (2.1). The proof in the case $t \in\left[T_{1}, t_{1}\right]$ is similar.
3. Stability region in Quadrant I. In this section, we consider the delaydifferential equation

$$
\begin{equation*}
x^{\prime}(t)=G(t, x(t))+F\left(t, x_{t}\right), \tag{3.1}
\end{equation*}
$$

where $G:[0, \infty) \times S(H) \rightarrow \boldsymbol{R}$ and $F:[0, \infty) \times C^{q}(H) \rightarrow \boldsymbol{R}$ are continuous. We assume that there exists $\alpha>0$ such that

$$
\begin{equation*}
x G(t, x) \leqq-\alpha x^{2} \quad \text { for all } \quad(t, x) \in[0, \infty) \times S(H) \tag{3.2}
\end{equation*}
$$

and that $F(t, \phi)$ satisfies $\left(\mathrm{A}_{1}\right)$ for some $\beta>0$.
Let $x(t)$ be a solution of (3.1) on $\left[t_{1}-q, t_{1}\right]$ such that $x(t)>0$ for all $t \in\left(t_{1}-q, t_{1}\right)$. Then $M\left(-x_{t_{1}}\right)=0$ and hence

$$
x\left(t_{1}\right) x^{\prime}\left(t_{1}\right)=x\left(t_{1}\right)\left(G\left(t_{1}, x\left(t_{1}\right)\right)+F\left(t, x_{t_{1}}\right)\right) \leqq-\alpha x^{2}\left(t_{1}\right) \leqq 0 .
$$

Similarly if $x(t)$ is a solution of (3.1) on $\left[t_{1}-q, t_{1}\right]$ such that $x(t)<0$ for all $t \in\left(t_{1}-q, t_{1}\right)$, then $x\left(t_{1}\right) x^{\prime}\left(t_{1}\right) \leqq 0$. Thus we have the following:

Lemma 3.1. For some $t_{1} \geqq 0$, let $x(t)$ be a solution of (3.1) on $\left[t_{1}-q, t_{1}\right]$ such that $|x(t)|>0$ for all $t \in\left(t_{1}-q, t_{1}\right)$. Then

$$
x\left(t_{1}\right) x^{\prime}\left(t_{1}\right) \leqq 0 .
$$

The above lemma shows that if $x(t)=x\left(t ; t_{0}, \phi\right)$ is a positive (or negative) solution of (3.1) defined on $\left[t_{0}, \infty\right.$ ) for $t_{0} \geqq 0$ and $\phi \in C^{q}(H)$, then $|x(t)|$ is a non-increasing function on $\left[t_{0}+q, \infty\right)$. Therefore, in order to show the uniform stability of the zero solution of (3.1), it suffices to investigate the behavior of solutions of (3.1) which cross the $t$-axis.

From now on we assume that $\alpha \geqq \beta$ or

$$
\theta=\frac{\beta^{2}}{\alpha^{2}}\left\{1-\frac{\beta-\alpha}{\beta}\left(1+\frac{2 \alpha \beta}{(\beta-\alpha)^{2}} e^{-\alpha q}\right)^{1 / 2}\right\} \leqq 1,
$$

and that ( $\mathrm{A}_{1}$ ) and (3.2) hold.
In the case $\beta<\alpha /\left(1-e^{-\alpha q}\right)$, we let $\tilde{\beta}=\alpha /\left(1-e^{-\alpha q}\right)$. Then $\left(\mathrm{A}_{1}\right)$ is also satisfied for $\tilde{\beta}$, and the corresponding $\theta$ satisfies $\theta=1 /\left(1+\left(1-\alpha^{2} / \tilde{\beta}^{2}\right)^{1 / 2}\right)<1$. Thus we may assume without loss of generality that

$$
\begin{equation*}
\frac{\beta}{\alpha}\left(1-e^{-\alpha q}\right) \geqq 1 \tag{3.3}
\end{equation*}
$$

Let $x(t)$ be a solution of (3.1) on $\left[t_{1}-2 q, T\right]$ for some $T>t_{1} \geqq 0$ such that

$$
x\left(t_{1}\right)=0 \quad \text { and } \quad x(t)>0 \quad \text { for all } t \in\left(t_{1}, T\right]
$$

and let $r=\sup _{s \in\left[t_{1}-2 q, t_{1}\right]}|x(s)|$. We shall show that

$$
\begin{equation*}
|x(t)| \leqq \theta r \quad \text { for all } \quad t \in\left[t_{1}, T\right] \tag{3.4}
\end{equation*}
$$

It suffices to show that for each $\varepsilon>0$,

$$
x(t)<\theta(r+\varepsilon) \quad \text { for all } \quad t \in\left[t_{1}, T\right] .
$$

Suppose that there exist $\varepsilon>0$ and $t_{3} \in\left(t_{1}, T\right]$ such that

$$
\begin{equation*}
x\left(t_{3}\right)=\theta(r+\varepsilon) \quad \text { and } \quad x(t)<\theta(r+\varepsilon) \quad \text { for all } \quad t \in\left[t_{1}, t_{3}\right) \tag{3.5}
\end{equation*}
$$

In practice, we have $t_{3} \leqq t_{1}+q$ by Lemma 3.1. By $\left(\mathrm{A}_{1}\right)$ and (3.2),

$$
\begin{equation*}
\frac{d}{d t}|x(t)| \leqq-\alpha|x(t)|+\beta r \quad \text { for all } \quad t \in\left[t_{1}-q, t_{1}\right] \tag{3.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{d}{d t}|x(t)| \leqq-\alpha x(t)+\beta(r+\varepsilon) \quad \text { for all } \quad t \in\left[t_{1}, t_{3}\right] \tag{3.7}
\end{equation*}
$$

It follows from Lemma 2.1 and (3.7) that

$$
\begin{equation*}
x(t) \leqq \frac{\beta}{\alpha}(r+\varepsilon)\left(1-e^{-\alpha\left(t-t_{1}\right)}\right) \quad \text { for all } \quad t \in\left[t_{1}, t_{3}\right] \tag{3.8}
\end{equation*}
$$

We also obtain by Lemma 2.1 and (3.6) that

$$
|x(t)| \leqq \frac{\beta}{\alpha} r\left(1-e^{-\alpha\left(t_{1}-t\right)}\right) \quad \text { for all } \quad t \in\left[t_{1}-q, t_{1}\right]
$$

Hence, it follows from $\left(\mathrm{A}_{1}\right)$ and (3.2) again that for $t \in\left[t_{1}, t_{3}\right]$,

$$
\begin{align*}
x^{\prime}(t) & \leqq-\alpha x(t)+\beta M\left(-x_{t}\right) \leqq-\alpha x(t)+\beta \sup _{s \in\left[t-q, t_{1}\right]}(-x(s)) \\
& \leqq-\alpha x(t)+\beta \sup _{s \in\left[t-q, t_{1}\right]}|x(s)| \leqq-\alpha x(t)+\frac{\beta^{2}}{\alpha} r \sup _{s \in\left[t-q, t_{1}\right]}\left(1-e^{-\alpha\left(t_{1}-s\right)}\right) \\
& \leqq-\alpha x(t)+\frac{\beta^{2}}{\alpha} r\left(1-e^{-\alpha\left(t_{1}+q-t\right)}\right) . \tag{3.9}
\end{align*}
$$

By (3.3), we can choose $t_{2} \geqq t_{1}$ in such a way that

$$
\begin{equation*}
\frac{\beta}{\alpha}\left(1-e^{-\alpha\left(t_{1}+q-t_{2}\right)}\right)=1 . \tag{3.10}
\end{equation*}
$$

Define a continuous function $y_{\varepsilon}(t)$ on $\left[t_{1}, \infty\right)$ by

$$
y_{\varepsilon}(t)=\frac{\beta}{\alpha}(r+\varepsilon)\left(1-e^{-\alpha\left(t-t_{1}\right)}\right)
$$

for $t \in\left[t_{1}, t_{2}\right]$ and

$$
\begin{aligned}
y_{\varepsilon}(t)= & \frac{\beta^{2}}{\alpha^{2}} r\left\{1-\left(\frac{\beta-\alpha}{2 \beta}+\frac{\alpha}{\beta-\alpha} e^{-\alpha q}\right) e^{-\alpha\left(t-t_{2}\right)}-\frac{\beta-\alpha}{2 \beta} e^{\alpha\left(t-t_{2}\right)}\right\} \\
& +\frac{\beta}{\alpha} \varepsilon\left(1-\frac{\beta}{\beta-\alpha} e^{-\alpha q}\right) e^{-\alpha\left(t-t_{2}\right)}
\end{aligned}
$$

for $t \geqq t_{2}$. Note that $y_{\varepsilon}(t)$ is the solution of

$$
y^{\prime}=-\alpha y+\frac{\beta^{2}}{\alpha} r\left(1-e^{-\alpha\left(t_{1}+q-t\right)}\right)
$$

on $\left[t_{2}, \infty\right)$ with

$$
y_{\varepsilon}\left(t_{2}\right)=\frac{\beta}{\alpha}(r+\varepsilon)\left(1-\frac{\beta}{\beta-\alpha} e^{-\alpha q}\right) .
$$

Moreover let

$$
z_{\varepsilon}(t)=\frac{\beta^{2}}{\alpha^{2}} r\left\{1-\left(\frac{\beta-\alpha}{2 \beta}+\frac{\alpha}{\beta-\alpha} e^{-\alpha q}\right) e^{-\alpha\left(t-t_{2}\right)}-\frac{\beta-\alpha}{2 \beta} e^{\alpha\left(t-t_{2}\right)}\right\}+\frac{\beta}{\alpha} \varepsilon\left(1-\frac{\beta}{\beta-\alpha} e^{-\alpha q}\right)
$$

for $t \geqq t_{2}$. Then $y_{\varepsilon}(t) \leqq z_{\varepsilon}(t)$ for all $t \geqq t_{2}$ and

$$
\begin{aligned}
\max _{t \in\left[t_{2}, T\right]} z_{\varepsilon}(t) & =z_{\varepsilon}\left(t_{2}+\frac{1}{2 \alpha} \log \left(1+\frac{2 \alpha \beta}{(\beta-\alpha)^{2}} e^{-\alpha q}\right)\right) \\
& =\frac{\beta^{2}}{\alpha^{2}} r\left\{1-\frac{\beta-\alpha}{\beta}\left(1+\frac{2 \alpha \beta}{(\beta-\alpha)^{2}} e^{-\alpha q}\right)^{1 / 2}\right\}+\frac{\beta}{\alpha} \varepsilon\left(1-\frac{\beta}{\beta-\alpha} e^{-\alpha q}\right) \\
& =\theta r+\frac{\beta}{\alpha} \varepsilon\left(1-\frac{\beta}{\beta-\alpha} e^{-\alpha q}\right),
\end{aligned}
$$

since

$$
z_{\varepsilon}^{\prime}(t)=\frac{\beta^{2}}{\alpha} r\left\{\left(\frac{\beta-\alpha}{2 \beta}+\frac{\alpha}{\beta-\alpha} e^{-\alpha q}\right) e^{-\alpha\left(t-t_{2}\right)}-\frac{\beta-\alpha}{2 \beta} e^{\alpha\left(t-t_{2}\right)}\right\} .
$$

In particular,

$$
y_{\varepsilon}\left(t_{2}\right)=z_{\varepsilon}\left(t_{2}\right)<\theta r+\frac{\beta}{\alpha} \varepsilon\left(1-\frac{\beta}{\beta-\alpha} e^{-\alpha q}\right),
$$

since $z_{\varepsilon}^{\prime}\left(t_{2}\right)>0$. Hence

$$
\frac{\beta}{\alpha}\left(1-\frac{\beta}{\beta-\alpha} e^{-\alpha q}\right)<\theta
$$

Observe that $y_{\varepsilon}(t)$ is increasing on $\left[t_{1}, t_{2}\right]$. We have

$$
\begin{equation*}
y_{\varepsilon}(t)<\theta(r+\varepsilon) \quad \text { for all } \quad t \geqq t_{1} \tag{3.11}
\end{equation*}
$$

If $t_{3} \leqq t_{2}$, then by (3.8) and (3.11)

$$
x(t) \leqq y_{\varepsilon}(t)<\theta(r+\varepsilon) \quad \text { for all } \quad t \in\left[t_{1}, t_{3}\right],
$$

which yields a contradiction at $t=t_{3}$. Hence $t_{2}<t_{3}$ and $x\left(t_{2}\right) \leqq y_{\varepsilon}\left(t_{2}\right)$. It follows from (3.9) and (3.11) that

$$
x(t) \leqq y_{\varepsilon}(t)<\theta(r+\varepsilon) \quad \text { for all } \quad t \in\left[t_{2}, t_{3}\right],
$$

which contradicts (3.5) at $t=t_{3}$. Thus (3.4) is proved.
In a similar way, under $\theta \leqq 1$, we can show (3.4) for any solution $x(t)$ of (3.1) on $\left[t_{1}-2 q, T\right]$ such that

$$
x\left(t_{1}\right)=0 \quad \text { and } \quad x(t)<0 \quad \text { for all } t \in\left(t_{1}, T\right] .
$$

(3.4) means that if a solution of $x(t)$ for (3.1) crosses the $t$-axis at some $t_{1}$, then

$$
|x(t)| \leqq \theta \sup _{s \in\left[t_{1}-2 q, t_{1}\right]}|x(s)| \text { as long as }|x(t)| \neq 0
$$

Therefore, together with Lemma 3.1, we obtain the following:
Lemma 3.2. Assume that $\theta \leqq 1$, and let $x(t)$ be a solution of (3.1) on $\left[t_{1}-2 q, T\right]$ for some $T>t_{1} \geqq 0$ such that $x\left(t_{1}\right)=0$. Then

$$
|x(t)| \leqq \theta \sup _{s \in\left[t_{1}-2 q, t_{1}\right]}|x(s)| \quad \text { for all } \quad t \in\left(t_{1}, T\right] .
$$

We now state a theorem on the uniform stability of the zero solution of (3.1).
Theorem 3.1. Suppose that there exist $\alpha>0$ and $\beta>0$ such that $\left(\mathrm{A}_{1}\right)$ and (3.2) hold and that $\alpha \geqq \beta$ or

$$
\begin{equation*}
\frac{\beta^{2}}{\alpha^{2}}\left\{1-\frac{\beta-\alpha}{\beta}\left(1+\frac{2 \alpha \beta}{(\beta-\alpha)^{2}} e^{-\alpha q}\right)^{1 / 2}\right\} \leqq 1 \tag{3.12}
\end{equation*}
$$

Then the zero solution of (3.1) is uniformly stable.
Proof. For $t_{0} \geqq 0$ and $\phi \in C^{q}\left(H e^{-2 \beta q}\right)$, let $x(t)=x\left(t ; t_{0}, \phi\right)$ be a solution of (3.1). By ( $\mathrm{A}_{1}$ ) and (3.2),

$$
x(t) x^{\prime}(t) \leqq \beta\left\|x_{t}\right\|^{2}
$$

and hence $\left\|x_{t}\right\|^{2} \leqq\|\phi\|^{2}+2 \beta \int_{t_{0}}^{t}\left\|x_{s}\right\|^{2} d s$. Then Gronwall's inequality implies that $\left\|x_{t}\right\| \leqq\|\phi\| e^{\beta\left(t-t_{0}\right)}$. Therefore $V(t)=\sup _{s \in[t-3 q, t]} x^{2}(s)$ is well defined for $t \geqq t_{0}+2 q$. We shall show that $V(t)$ is non-increasing for all $t \geqq t_{0}+2 q$. Suppose not. Then there exist a solution $x(t)=x\left(t ; t_{0}, \phi\right)$ and $t_{2}>t_{0}+2 q$ such that

$$
\begin{equation*}
V^{\prime}\left(t_{2}\right)>0 . \tag{3.13}
\end{equation*}
$$

It is easy to see that $V\left(t_{2}\right)=x^{2}\left(t_{2}\right)$ and $V^{\prime}\left(t_{2}\right)=2 x\left(t_{2}\right) x^{\prime}\left(t_{2}\right)>0$. By Lemma 3.1, there exists $t_{1} \in\left(t_{2}-q, t_{2}\right)$ such that $x\left(t_{1}\right)=0$. Then it follows from Lemma 3.2 that

$$
|x(t)| \leqq \theta \sup _{s \in\left[t_{1}-2 q, t_{1}\right]}|x(s)| \quad \text { for all } \quad t \in\left(t_{1}, t_{2}\right]
$$

and hence $V^{\prime}\left(t_{2}\right) \leqq 0$, which contradicts (3.13). The proof is now complete.
Remark 3.1. The condition (3.12) is also written as

$$
\begin{equation*}
\beta q \leqq-\frac{1}{\omega} \log \left(\frac{1}{2}(1-\omega)\left(2-\omega-\omega^{2}\right)\right) \tag{3.14}
\end{equation*}
$$

where $\omega=\alpha / \beta$. The region $S_{1}$ of points $(\alpha, \beta)$ which satisfy the conditions of Theorem 3.1 is illustrated in Figure 2.

Letting $\alpha \rightarrow 0$ in (3.12), we have $\beta q-1 / 2 \leqq 1$. This coincides with Yorke's condition below.

THEOREM [17, Theorem 1.1]. Suppose that there exists $\beta \geqq 0$ such that $\left(\mathrm{A}_{1}\right)$ holds and $\beta q \leqq 3 / 2$. Then the zero solution of

$$
\begin{equation*}
x^{\prime}(t)=F\left(t, x_{t}\right) \tag{3.15}
\end{equation*}
$$

is uniformly stable.
Yorke [17] also proved the uniform asymptotic stability for (3.15) under the conditions ( $\mathrm{A}_{1}$ ), $0<\beta q<3 / 2$ and

For all sequences $t_{n} \rightarrow \infty$ and $\phi_{n} \in C^{q}(H)$ converging to a constant nonzero function in $C^{q}(H), F\left(t_{n}, \phi_{n}\right)$ does not converge to 0 .

If $\left(\mathrm{A}_{1}\right)$ and (3.2) hold, then the right hand side of (3.1) satisfies (3.16), and so the uniform
asymptotic stability for (3.1) will be proved in a way similar to [17], but under $\left(\mathrm{A}_{1}\right)$ and (3.2), the proof is slightly easier.

Theorem 3.2. Suppose that there exist $\alpha>0$ and $\beta>0$ such that $\left(\mathrm{A}_{1}\right)$ and (3.2) hold and that $\alpha \geqq \beta$ or

$$
\frac{\beta^{2}}{\alpha^{2}}\left\{1-\frac{\beta-\alpha}{\beta}\left(1+\frac{2 \alpha \beta}{(\beta-\alpha)^{2}} e^{-\alpha q}\right)^{1 / 2}\right\}<1 .
$$

Then the zero solution of (3.1) is uniformly asymptotically stable.
Proof. Suppose that the zero solution is not uniformly asymptotically stable. Then there exist $\varepsilon>0$, sequences $\left\{\tau_{n}^{\prime}\right\},\left\{\phi_{n}\right\},\left\{T_{n}^{\prime}\right\}$ and a sequence $\left\{x\left(\cdot ; \tau_{n}^{\prime}, \phi_{n}\right)\right\}$ of solutions on $\left[\tau_{n}^{\prime}, \infty\right)$ such that $\tau_{n}^{\prime} \geqq 0, \phi_{n} \in C^{q}\left(H e^{-2 \beta q}\right), \quad T_{n}^{\prime} \rightarrow \infty$ as $n \rightarrow \infty$ and $\left|x\left(\tau_{n}^{\prime}+T_{n}^{\prime} ; \tau_{n}^{\prime}, \phi_{n}\right)\right|>\varepsilon$. Let $x^{n}(t)=x\left(t ; \tau_{n}^{\prime}, \phi_{n}\right)$. Then by the proof of Theorem 3.1 $v_{n}(t)=$ $\sup _{s \in[t-3 q, t]}\left|x^{n}(s)\right|$ is non-increasing for all $t \geqq \tau_{n}^{\prime}+2 q$ and

$$
\varepsilon<\left|x^{n}\left(\tau_{n}^{\prime}+T_{n}^{\prime}\right)\right| \leqq v_{n}\left(\tau_{n}^{\prime}+T_{n}^{\prime}\right) \leqq v_{n}\left(\tau_{n}^{\prime}+2 q\right)<H .
$$

Hence there exist sequences $\left\{\tau_{n}\right\}$ and $\left\{T_{n}\right\}$ such that

$$
\tau_{n}^{\prime}+2 q \leqq \tau_{n}<\tau_{n}+T_{n} \leqq \tau_{n}^{\prime}+T_{n}^{\prime}, \quad T_{n} \rightarrow \infty \quad \text { as } \quad n \rightarrow \infty
$$

and

$$
\begin{equation*}
v_{n}\left(\tau_{n}+T_{n}\right)>\theta v_{n}\left(\tau_{n}\right) \tag{3.17}
\end{equation*}
$$

We show that

$$
\begin{equation*}
x^{n}(t) \neq 0 \quad \text { for all } \quad t \in\left[\tau_{n}, \tau_{n}+T_{n}\right] \tag{3.18}
\end{equation*}
$$

Suppose that there exists $t_{n} \in\left[\tau_{n}, \tau_{n}+T_{n}\right]$ such that $x^{n}\left(t_{n}\right)=0$. Note that by the monotonicity of $v_{n}(t)$, we have

$$
v_{n}\left(\tau_{n}+T_{n}\right) \leqq v_{n}\left(t_{n}\right) \leqq \sup _{s \geqq t_{n}}\left|x^{n}(s)\right|
$$

It follows from Lemma 3.1 that

$$
\sup _{s \geqq t_{n}}\left|x^{n}(s)\right| \leqq \theta \sup _{s \in\left[t_{n}-2 q, t_{n}\right]}\left|x^{n}(s)\right| \leqq \theta \sup _{s \geqq t_{n}-3 q}\left|x^{n}(s)\right| \leqq \theta v_{n}\left(\tau_{n}\right),
$$

which contradicts (3.17). Therefore (3.18) is proved, and then by Lemma 3.1, $\left|x^{n}(t)\right|$ is non-increasing on $\left[\tau_{n}+q, \tau_{n}+T_{n}\right.$ ]. Hence

$$
\left|x^{n}(t)\right|>\varepsilon \quad \text { for all } \quad t \in\left[\tau_{n}+q, \tau_{n}+T_{n}\right]
$$

We may assume that $x^{n}(t)>\varepsilon$ for all $t \in\left[\tau_{n}+q, \tau_{n}+T_{n}\right]$. Then by ( $\mathrm{A}_{1}$ ) and (3.2),

$$
\begin{equation*}
\frac{d}{d t} x^{n}(t) \leqq-\alpha x^{n}(t)+\beta M\left(-x_{t}^{n}\right)<-\alpha \varepsilon \tag{3.19}
\end{equation*}
$$

for all $t \in\left[\tau_{n}+2 q, \tau_{n}+T_{n}\right]$, which implies that

$$
x^{n}\left(\tau_{n}+T_{n}\right) \leqq x^{n}\left(\tau_{n}+q\right)-\alpha \varepsilon\left(T_{n}-\tau_{n}-2 q\right) \rightarrow-\infty \quad \text { as } \quad n \rightarrow \infty,
$$

since $T_{n} \rightarrow \infty$. This is a contradiction and completes the proof.
Remark 3.2. For (3.15), suppose that

$$
\left(\mathrm{A}_{2}\right) \text { holds for some } 0<\beta q<3 / 2 \text { and } \liminf _{t \rightarrow \infty} b(t)>0
$$

Then $F(t, \phi)$ satisfies (3.16), and hence by [17] the zero solution of (3.15) is uniformly asymptotically stable. But we can also give a proof quite similar to the proof of Theorem 3.2 as follows: Suppose that $x^{n}(t)>\varepsilon$ for all $t \in\left[\tau_{n}+q, \tau_{n}+T_{n}\right]$. Then by $\left(\mathrm{A}_{2}\right)$

$$
\frac{d}{d t} x^{n}(t) \leqq b(t) \sup _{s \in[t-q, t]}(-x(s))<-\varepsilon b(t)
$$

for all $t \in\left[\tau_{n}+q, \tau_{n}+T_{n}\right]$, which yields a contradiction.
EXAMPLE 3.1. Let $a, b:[0, \infty) \rightarrow[0, \infty)$ and $r:[0, \infty) \rightarrow[0, q]$ be continuous functions such that

$$
a(t) \geqq \alpha \quad \text { and } \quad 0 \leqq b(t) \leqq \beta,
$$

for some $\alpha>0$ and $\beta>0$, and let $f, g: S(H) \rightarrow \boldsymbol{R}$ be continuous functions such that

$$
|f(x)| \leqq|x| \quad \text { for } \quad x \in S(H) \text { and } x f(x)>0 \text { for } x \neq 0 \text {, }
$$

and that

$$
|g(x)| \geqq|x| \text { for } x \in S(H) \text { and } x g(x)>0 \text { for } x \neq 0 \text {. }
$$

Then the delay-differential equation

$$
\begin{equation*}
x^{\prime}(t)=-a(t) g(x(t))-b(t) f(x(t-r(t))) \tag{3.20}
\end{equation*}
$$

satisfies ( $\mathrm{A}_{1}$ ) and (3.2). Hence, if

$$
\alpha \geqq \beta \quad \text { or } \quad \frac{\beta^{2}}{\alpha^{2}}\left\{1-\frac{\beta-\alpha}{\beta}\left(1+\frac{2 \alpha \beta}{(\beta-\alpha)^{2}} e^{-\alpha q}\right)^{1 / 2}\right\} \leqq 1,
$$

Theorems 3.1 and 3.2 imply that
(i) the zero solution of (3.20) is uniformly stable, and
(ii) if $\theta<1$, then the zero solution of (3.20) is uniformly asymptotically stable.
4. Stability region in Quadrant II. In this section, we consider the delaydifferential equation

$$
\begin{equation*}
x^{\prime}(t)=G(t, x(t))+F\left(t, x_{t}\right), \tag{4.1}
\end{equation*}
$$

where $G:[0, \infty) \times S(H) \rightarrow \boldsymbol{R}$ and $F:[0, \infty) \times C^{q}(H) \rightarrow \boldsymbol{R}$ are continuous. We assume that there exist $\alpha<0, \beta>0$ and a non-positive function $a(t)$ on $[0, \infty)$ such that

$$
\begin{equation*}
a(t) \geqq \alpha \quad \text { and } \quad|G(t, x)| \leqq-a(t)|x| \tag{4.2}
\end{equation*}
$$

for all $t \geqq 0$ and $x \in S(H)$, and that $F(t, \phi)$ satisfies $\left(\mathrm{A}_{2}\right)$. To avoid confusion, we let $\gamma=-\alpha$ and $c(t)=-a(t)$, so that we have

$$
c(t) \leqq \gamma \quad \text { and } \quad|G(t, x)| \leqq c(t)|x|
$$

We further assume that

$$
\begin{equation*}
-a(t)=c(t) \leqq b(t) \quad \text { for all } \quad t \geqq 0 \tag{4.3}
\end{equation*}
$$

and

$$
\begin{equation*}
-\alpha=\gamma \leqq \beta \quad \text { and } \quad \gamma q<1 \tag{4.4}
\end{equation*}
$$

For $\alpha<0$ and $\beta>0$, the equation (1.1) is an example of (4.1) satisfying (4.2)-(4.3), and if either $-\alpha=\gamma \geqq \beta$ or $\gamma q>1$, then the zero solution of (1.1) is unstable. Hence, it is quite reasonable to assume (4.4). For a continuous function $\psi:[0, \infty) \rightarrow \boldsymbol{R}$, we let $\psi_{+}(t)=$ $\max \{0, \psi(t)\}$ and $\psi_{-}(t)=\max \{0,-\psi(t)\}$.

Lemma 4.1. For some $t_{1} \geqq 0$ and $T>t_{1}+q$, let $x(t)$ be a solution of (4.1) on $\left[t_{1}, T\right]$ such that $x(t)>0$ for all $t \in\left(t_{1}, T\right]$. Then

$$
\begin{equation*}
\int_{t_{1}+q}^{t} x_{+}^{\prime}(s) d s \leqq \frac{\gamma q}{1-\gamma q} \int_{t_{1}}^{t_{1}+q} x_{+}^{\prime}(s) d s \tag{4.5}
\end{equation*}
$$

for all $t \in\left[t_{1}+q, T\right]$.
Proof. For $t \in\left[t_{1}+q, T\right]$, choose $q_{1} \in[0, q]$ so that $x\left(t-q_{1}\right)=\inf _{s \in[-q, 0]} x(t+s)$. Then by $\left(\mathrm{A}_{2}\right)$, (4.2) and (4.3),

$$
\begin{aligned}
x^{\prime}(t) & =G(t, x(t))+F\left(t, x_{t}\right) \leqq c(t) x(t)+b(t) \sup _{s \in[-q, 0]}(-x(t+s)) \\
& \leqq c(t) x(t)-b(t) \inf _{s \in[-q, 0]}(x(t+s)) \leqq c(t)\left(x(t)-x\left(t-q_{1}\right)\right) \\
& \leqq \gamma \int_{t-q_{1}}^{t} x^{\prime}(s) d s \leqq \gamma \int_{t-q}^{t} x_{+}^{\prime}(s) d s .
\end{aligned}
$$

Hence, integrating $x_{+}^{\prime}(t)$ from $t_{1}+q$ to $t$, we have

$$
\begin{aligned}
\int_{t_{1}+q}^{t} x_{+}^{\prime}(s) d s & \leqq \int_{t_{1}+q}^{t} \gamma \int_{s-q}^{s} x_{+}^{\prime}(u) d u d s \leqq \gamma \int_{t_{1}}^{t} x_{+}^{\prime}(u) \int_{u}^{u+q} d s d u \\
& \leqq \gamma q \int_{t_{1}}^{t_{1}+q} x_{+}^{\prime}(u) d u+\gamma q \int_{t_{1}+q}^{t} x_{+}^{\prime}(u) d u
\end{aligned}
$$

which proves (4.5).
In a similar way, we have the following:

Lemma 4.2. For some $t_{1} \geqq 0$ and $T>t_{1}+q$, let $x(t)$ be a solution of (4.1) on $\left[t_{1}, T\right]$ such that $x(t)<0$ for all $t \in\left(t_{1}, T\right]$. Then

$$
\begin{equation*}
\int_{t_{1}+q}^{t} x_{-}^{\prime}(s) d s \leqq \frac{\gamma q}{1-\gamma q} \int_{t_{1}}^{t_{1}+q} x_{-}^{\prime}(s) d s \tag{4.6}
\end{equation*}
$$

for all $t \in\left[t_{1}+q, T\right]$.
Lemma 4.3. For $t_{1} \geqq 0$ and $T>t_{1}$, let $x(t)$ be a solution of (4.1) on $\left[t_{1}-2 q, T\right]$ such that $|x(t)|>0$ for all $t \in\left[t_{1}-q, T\right]$. Then

$$
|x(t)| \leqq\left(1+\frac{\gamma q^{2}}{1-\gamma q}(\gamma+\beta)\right) \sup _{s \in\left[t_{1}-2 q, t_{1}\right]}|x(s)|
$$

for all $t \in\left[t_{1}, T\right]$.
Proof. It is clear from (4.2) and ( $\mathrm{A}_{2}$ ) that

$$
\left|x^{\prime}(t)\right| \leqq(\gamma+\beta)\left\|x_{t}\right\| \quad \text { for all } \quad t \in\left[t_{1}-q, T\right] .
$$

Hence if $x(t)>0$ for all $t \in\left(t_{1}-q, T\right]$, then by Lemma 4.1,

$$
\begin{aligned}
x(t) & \leqq x\left(t_{1}\right)+\int_{t_{1}}^{t} x_{+}^{\prime}(s) d s \leqq x\left(t_{1}\right)+\frac{\gamma q}{1-\gamma q} \int_{t_{1}-q}^{t_{1}}(\gamma+\beta)\left\|x_{s}\right\| d s \\
& \leqq x\left(t_{1}\right)+\frac{\gamma q^{2}}{1-\gamma q}(\gamma+\beta) \sup _{s \in\left[t_{1}-q, t_{1}\right]}\left\|x_{s}\right\| \leqq\left(1+\frac{\gamma q^{2}}{1-\gamma q}(\gamma+\beta)\right) \sup _{s \in\left[t_{1}-2 q, t_{1}\right]}|x(s)| .
\end{aligned}
$$

The proof in the other case $x(t)$ negative on $\left(t_{1}-q, T\right]$ is similar.
Lemma 4.4. Let $x(t)$ be a solution of (4.1) on $\left[t_{1}-2 q, T\right]$ for some $t_{1} \geqq 0$ and $T \geqq t_{1}+q$ such that $x\left(t_{1}\right)=0$ and $x(t)>0$ for all $t \in\left(t_{1}, T\right]$, and let $r=\sup _{s \in\left[t_{1}-2 q, t_{1}\right]}|x(s)|$. Suppose that there exists $\eta \geqq 0$ such that

$$
\begin{equation*}
\frac{\beta(\gamma+\beta)}{\gamma^{2}}\left(e^{\gamma q}-1-\gamma q\right) \leqq 1-\eta-\gamma q \tag{4.7}
\end{equation*}
$$

or

$$
\begin{equation*}
\frac{\beta}{\gamma}\left(e^{\nu q}-1\right)>1 \quad \text { and } \quad \frac{\beta}{\gamma}\left(e^{\gamma q}-\frac{\gamma+\beta}{\gamma} \log \frac{\gamma+\beta}{\beta}\right) \leqq 1-\eta-\gamma q . \tag{4.8}
\end{equation*}
$$

Then

$$
x(t) \leqq \int_{t_{1}}^{t} x_{+}^{\prime}(s) d s \leqq(1-\eta-\gamma q) r \quad \text { for all } \quad t \in\left[t_{1}, t_{1}+q\right] .
$$

Proof. We will carry out the proof in a way similar to that for Lemma 3.2. Unfortunately we cannot assume $\beta\left(e^{\gamma q}-1\right) / \gamma \geqq 1$, and for this reason the conditions of the lemma are complicated. Suppose that there exists $t_{4} \in\left(t_{1}, t_{1}+q\right]$ such that
$x\left(t_{4}\right)>(1-\eta-\gamma q) r$. Then we can choose $t_{3}<t_{4}$ so that $x(t)<(1-\eta-\gamma q) r$ for all $t \in\left(t_{1}, t_{3}\right)$ and

$$
\begin{equation*}
x\left(t_{3}\right)=(1-\eta-\gamma q) r . \tag{4.10}
\end{equation*}
$$

By ( $\mathrm{A}_{2}$ ) and (4.2),

$$
x^{\prime}(t) \leqq \gamma|x(t)|+\beta r \quad \text { for all } \quad t \in\left[t_{1}-2 q, t_{3}\right]
$$

and hence $x\left(t_{1}\right)=0$ yields that $x(t) \leqq\left(e^{\gamma\left(t-t_{1}\right)}-1\right) \beta r / \gamma$ for all $t \in\left[t_{1}, t_{3}\right]$. Therefore we have

$$
\begin{equation*}
x_{+}^{\prime}(t) \leqq \beta r e^{\gamma\left(t-t_{1}\right)} \quad \text { for all } \quad t \in\left[t_{1}, t_{3}\right] \tag{4.11}
\end{equation*}
$$

Further, it follows from Lemma 2.1 that

$$
|x(t)| \leqq \frac{\beta}{\gamma} r\left(e^{\gamma\left(t_{1}-t\right)}-1\right) \quad \text { for all } \quad t \in\left[t_{1}-2 q, t_{1}\right]
$$

Then by $\left(\mathrm{A}_{2}\right)$ and (4.2) again, we have for $t \in\left[t_{1}, t_{3}\right]$

$$
\begin{align*}
x^{\prime}(t) & \leqq \gamma x(t)+\beta \sup _{s \in[t-q, t]}(-x(s)) \leqq \gamma x(t)+\beta \sup _{s \in\left[t-q, t_{1}\right]}|x(s)| \\
& \leqq \beta r\left(e^{\gamma\left(t-t_{1}\right)}-1\right)+\frac{\beta^{2}}{\gamma} r\left(e^{\gamma\left(t_{1}+q-t\right)}-1\right) . \tag{4.12}
\end{align*}
$$

Therefore, by (4.11) and (4.12), we have for $t \in\left[t_{1}, t_{3}\right]$,

$$
x(t) \leqq \int_{t_{1}}^{t} x_{+}^{\prime}(s) d s \leqq \beta r \int_{t_{1}}^{t}\left(e^{\gamma\left(s-t_{1}\right)}-1\right) d s+\int_{t_{1}}^{t} \min \left\{\beta r, \frac{\beta^{2}}{\gamma} r\left(e^{\gamma\left(t_{1}+q-s\right)}-1\right)\right\} d s
$$

Suppose (4.7) holds. It then follows from $t_{3}<t_{1}+q$ that

$$
\begin{aligned}
x(t) & <\beta r \int_{t_{1}}^{t_{1}+q}\left(e^{\gamma\left(s-t_{1}\right)}-1\right) d s+\frac{\beta^{2}}{\gamma} r \int_{t_{1}}^{t_{1}+q}\left(e^{\gamma\left(t_{1}+q-s\right)}-1\right) d s \\
& =\frac{\beta(\gamma+\beta)}{\gamma^{2}}\left(e^{\gamma q}-1-\gamma q\right) r \leqq(1-\eta-\gamma q) r .
\end{aligned}
$$

Next suppose (4.8) holds and choose $t_{2} \in\left[t_{1}, t_{1}+q\right.$ ) so that

$$
e^{\gamma\left(t_{1}+q-t_{2}\right)}=(\gamma+\beta) / \beta
$$

Then we have for $t \in\left[t_{1}, t_{3}\right]$,

$$
\begin{aligned}
x(t) & \leqq \int_{t_{1}}^{t} x_{+}^{\prime}(s) d s<\beta r \int_{t_{1}}^{t_{1}+q}\left(e^{\gamma\left(s-t_{1}\right)}-1\right) d s+\int_{t_{1}}^{t_{2}} \beta r d s+\frac{\beta^{2}}{\gamma} r \int_{t_{2}}^{t_{1}+q}\left(e^{\gamma\left(t_{1}+q-s\right)}-1\right) d s \\
& =\frac{\beta}{\gamma}\left(e^{\gamma q}-\frac{\gamma+\beta}{\gamma} \log \frac{\gamma+\beta}{\beta}\right) r \leqq(1-\eta-\gamma q) r .
\end{aligned}
$$

In either case, we have a contradiction to (4.10) at $t=t_{3}$, and at the same time we have

$$
\int_{t_{1}}^{t} x_{+}^{\prime}(s) d s \leqq(1-\eta-\gamma q) r \quad \text { for all } \quad t \in\left[t_{1}, t_{1}+q\right]
$$

The proof is now complete.
Similarly,we have a lemma for negative solutions of (4.1):
Lemma 4.5. Let $x(t)$ be a solution of (4.1) on $\left[t_{1}-2 q, T\right]$ for some $t_{1} \geqq 0$ and $T \geqq t_{1}+q$ such that $x\left(t_{1}\right)=0$ and $x(t)<0$ for all $t \in\left(t_{1}, T\right]$, and let $r=\sup _{s \in\left[t_{1}-2 q, t_{1}\right]}|x(s)|$. Suppose that there exists $\eta \geqq 0$ such that (4.7) or (4.8) holds. Then

$$
|x(t)| \leqq \int_{t_{1}}^{t} x_{-}^{\prime}(s) d s \leqq(1-\eta-\gamma q) r \quad \text { for all } \quad t \in\left[t_{1}, t_{1}+q\right] .
$$

Theorem 4.1. Suppose that there exist $\alpha<0, \beta>0, a(t)<0$ and $b(t)>0$ satisfying ( $\mathrm{A}_{2}$ ) and (4.2)-(4.4), and

$$
\begin{equation*}
\frac{\beta(\beta-\alpha)}{\alpha^{2}}\left(e^{-\alpha q}-1+\alpha q\right) \leqq 1+\alpha q \tag{4.13}
\end{equation*}
$$

or

$$
\begin{equation*}
-\frac{\beta}{\alpha}\left(e^{-\alpha q}-1\right)>1 \quad \text { and } \quad-\frac{\beta}{\alpha}\left(e^{-\alpha q}+\frac{\beta-\alpha}{\alpha} \log \frac{\beta-\alpha}{\beta}\right) \leqq 1+\alpha q \tag{4.14}
\end{equation*}
$$

Then the zero solution of (4.1) is uniformly stable.
Proof. As above, we let $\gamma=-\alpha$, and show that

$$
\begin{equation*}
\left|x\left(t ; t_{0}, \phi\right)\right| \leqq\|\phi\|\left(1+\frac{\gamma q^{2}}{1-\gamma q}(\gamma+\beta)\right) e^{2(\gamma+\beta) q} \tag{4.15}
\end{equation*}
$$

for all $0 \leqq t_{0} \leqq t$ and $\phi \in C^{q}(H)$. Let

$$
\rho=\|\phi\|\left(1+\frac{\gamma q^{2}}{1-\gamma q}(\gamma+\beta)\right) e^{2(\gamma+\beta) q}
$$

and suppose (4.15) is false for some solution $x(t)=x\left(t ; t_{0}, \phi\right)$ of (4.1). Then there exists $t_{5}>t_{0}$ such that $\left|x\left(t_{5}\right)\right|>\rho$. By ( $\mathrm{A}_{2}$ ) and (4.2), $\left|x^{\prime}(t)\right| \leqq(\gamma+\beta)\left\|x_{t}\right\|$ and hence $|x(t)| \leqq\|\phi\| e^{2(\gamma+\beta) q}$ for all $t \in\left[t_{0}-q, t_{0}+2 q\right]$, which shows $t_{0}+2 q<t_{5}$. Then it follows from Lemma 4.3 that there exists $t_{1} \in\left[t_{0}+q, t_{5}\right)$ such that $x\left(t_{1}\right)=0$. Choose $t_{2}, t_{3}$ and $t_{4}$ so that $t_{0}+q \leqq t_{1} \leqq t_{2}<t_{3}<t_{4} \leqq t_{5}, x\left(t_{2}\right)=0,0<|x(t)| \leqq \rho$ for all $t \in\left[t_{2}, t_{3}\right]$ and

$$
\begin{equation*}
|x(t)|>\rho \quad \text { for all } \quad t \in\left(t_{3}, t_{4}\right] . \tag{4.16}
\end{equation*}
$$

We may suppose that $x(t)>0$ for all $t \in\left(t_{2}, t_{4}\right]$, since the argument for the other case is similar. By letting $\eta=0$ in Lemma 4.4, we have

$$
x(t) \leqq \int_{t_{2}}^{t_{2}+q} x_{+}^{\prime}(s) d s \leqq(1-\gamma q) \rho
$$

for all $t \in\left[t_{2}, t_{2}+q\right]$ and by Lemma 4.1

$$
x\left(t_{4}\right) \leqq x\left(t_{2}+q\right)+\int_{t_{2}+q}^{t_{4}} x_{+}^{\prime}(s) d s \leqq(1-\gamma q) \rho+\frac{\gamma q}{1-\gamma q}(1-\gamma q) \rho=\rho,
$$

which contradicts (4.16). This completes the proof.
REMARK 4.1. The region $S_{2}$ of points $(\alpha, \beta)$ which satisfy the conditions of Theorem 4.1 is illustrated in Figure 2. Letting $\alpha \rightarrow 0$ in (4.13) and (4.14), we have $\beta q \leqq 3 / 2$.

We shall study the asymptotic stability of the zero solution of (4.1). Consider the equation (1.1) in which $-\alpha=\beta<1 / q$. Then the zero solution is uniformly stable but not asymptotically stable. So we have to add an assumption to insure the asymptotic stability for (4.1). We assume for (4.1) that

$$
\begin{equation*}
\liminf _{t \rightarrow \infty}(a(t)+b(t))>0 \tag{4.17}
\end{equation*}
$$

Then there exist $\delta>0$ and $T_{1}>0$ such that

$$
\begin{equation*}
a(t)+b(t) \geqq \delta \quad \text { for all } \quad t \geqq T_{1} . \tag{4.18}
\end{equation*}
$$

First, we consider an eventually positive solution of (4.1): Let $x(t)$ be a solution of (4.1) such that there exists $T_{2} \geqq T_{1}$ such that

$$
\begin{equation*}
x(t)>0 \quad \text { for all } \quad t \geqq T_{2} . \tag{4.19}
\end{equation*}
$$

Then by Lemma 4.1,

$$
\begin{equation*}
\int_{T_{2}}^{\infty} x^{\prime}(s) d s<\infty \tag{4.20}
\end{equation*}
$$

Suppose that $\liminf _{t \rightarrow \infty} x(t)>0$. Then there exist $\varepsilon>0$ and $T_{3} \geqq T_{2}$ such that

$$
x(t)>\varepsilon \quad \text { for all } \quad t \geqq T_{3} .
$$

By (4.20), we can choose $T_{4} \geqq T_{3}$ so that

$$
\int_{T_{4}}^{\infty} x_{+}^{\prime}(t) d t<\varepsilon \delta / \gamma
$$

As in the proof of Lemma 4.1, by $\left(\mathrm{A}_{2}\right)$, (4.2) and (4.18),

$$
\begin{aligned}
x^{\prime}(t) & \leqq c(t) x(t)+b(t) \sup _{s \in[-q, 0]}(-x(t+s)) \\
& \leqq \gamma \int_{t-q}^{t} x_{+}^{\prime}(s) d s-(b(t)-c(t)) \inf _{s \in[-q, 0]} x(t+s) \leqq \gamma \int_{T_{4}}^{\infty} x_{+}^{\prime}(s) d s-\varepsilon \delta<0
\end{aligned}
$$

for all $t \geqq T_{4}+q$. Hence

$$
x(t) \rightarrow-\infty \quad \text { as } \quad t \rightarrow \infty
$$

which contradicts (4.19). Thus we have

$$
\begin{equation*}
\liminf _{t \rightarrow \infty} x(t)=0 . \tag{4.21}
\end{equation*}
$$

Suppose that limsup $\operatorname{sum}_{t \rightarrow \infty} x(t)>0$. Then by (4.21), there exist $\varepsilon>0$ and two sequences $\left\{\tau_{n}\right\}$ and $\left\{t_{n}\right\}$ tending to $\infty$ such that $\tau_{n}<t_{n}<\tau_{n+1}, x\left(\tau_{n}\right)=\varepsilon / 2, \varepsilon / 2<x(t)<\varepsilon$ for all $t \in\left(\tau_{n}, t_{n}\right)$ and $x\left(t_{n}\right)=\varepsilon$. Hence by (4.20)

$$
\varepsilon / 2=x\left(t_{n}\right)-x\left(\tau_{n}\right) \leqq \int_{\tau_{n}}^{t_{n}} x^{\prime}(s) d s \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty,
$$

which yields a contradiction. Thus we have

$$
\begin{equation*}
\lim _{t \rightarrow \infty} x(t)=0 \tag{4.22}
\end{equation*}
$$

for any eventually positive solution $x(t)$ of (4.1). In a similar way, we can show (4.22) for any eventually negative solution $x(t)$ of (4.1). In order to complete the proof of the asymptotic stability of the zero solution of (4.1), we show (4.22) for any oscillatory solution of (4.1). Suppose that

$$
\frac{\beta(\gamma+\beta)}{\gamma^{2}}\left(e^{\gamma q}-1-\gamma q\right)<1-\gamma q
$$

or

$$
\frac{\beta}{\gamma}\left(e^{\gamma q}-1\right)>1 \quad \text { and } \quad \frac{\beta}{\gamma}\left(e^{\nu q}-\frac{\gamma+\beta}{\gamma} \log \frac{\gamma+\beta}{\beta}\right)<1-\gamma q
$$

Then there exists $\eta>0$ such that (4.7) or (4.8) holds. Let $x(t)$ be a solution of (4.1) such that there exists a sequence $\left\{t_{n}\right\}$ tending to $\infty$ with $x\left(t_{n}\right)=0$ and $x(t) \neq 0$ for $t \neq t_{n}$. Let $r_{n}=\sup _{s \in\left[t_{n}-2 q, t_{n}\right]}|x(s)|$. In order to prove (4.22), it suffices to show that for each $n$,

$$
|x(t)| \leqq(1-\eta) r_{n} \quad \text { for all } \quad t \in\left[t_{n}, t_{n+1}\right]
$$

We may assume that $x(t)>0$ for all $t \in\left(t_{n}, t_{n+1}\right)$, since the proof in the other case is similar. If $t_{n+1} \leqq t_{n}+q$, then by Lemma 4.4,

$$
x(t) \leqq(1-\eta-\gamma q) r_{n} \leqq(1-\eta) r_{n} \quad \text { for all } \quad t \in\left(t_{n}, t_{n+1}\right) .
$$

If $t_{n+1}>t_{n}+q$, then by Lemma 4.4,

$$
x(t) \leqq \int_{t_{n}}^{t} x^{\prime}+(s) d s \leqq(1-\eta-\gamma q) r_{n} \quad \text { for all } \quad t \in\left(t_{n}, t_{n}+q\right]
$$

and by Lemma 4.1,

$$
x(t) \leqq x\left(t_{n}+q\right)+\int_{t_{n}+q}^{t} x^{\prime}(s) d s \leqq(1-\eta-\gamma q) r_{n}+\frac{\gamma q}{1-\gamma q}(1-\gamma q) r_{n}=(1-\eta) r_{n}
$$

for $t \in\left(t_{n}, t_{n+1}\right)$. Thus we have the following:
THEOREM 4.2. Suppose that there exist $\alpha<0, \beta>0, a(t)<0$ and $b(t)>0$ satisfying $\left(\mathrm{A}_{2}\right),(4.2)-(4.4)$ and (4.17). Further suppose that

$$
\begin{equation*}
\frac{\beta(\beta-\alpha)}{\alpha^{2}}\left(e^{-\alpha q}-1+\alpha q\right)<1+\alpha q \tag{4.23}
\end{equation*}
$$

or

$$
\begin{equation*}
-\frac{\beta}{\alpha}\left(e^{-\alpha q}-1\right)>1 \quad \text { and } \quad-\frac{\beta}{\alpha}\left(e^{-\alpha q}+\frac{\beta-\alpha}{\alpha} \log \frac{\beta-\alpha}{\beta}\right)<1+\alpha q . \tag{4.24}
\end{equation*}
$$

Then the zero solution of (4.1) is asymptotically stable.
EXAMPLE 4.1. Let $a, b:[0, \infty) \rightarrow[0, \infty)$ and $r:[0, \infty) \rightarrow[0, q]$ be continuous functions such that

$$
\alpha \leqq a(t) \leqq 0 \leqq b(t) \leqq \beta \quad \text { and } \quad a(t)+b(t) \geqq 0
$$

for some $\alpha<0$ and $\beta>0$, and let $g: S(H) \rightarrow \boldsymbol{R}$ be a continuous function such that

$$
|g(x)| \leqq|x| \text { for } x \in S(H) \text { and } x g(x)>0 \text { for } x \neq 0 .
$$

Then the delay-differential equation

$$
\begin{equation*}
x^{\prime}(t)=-a(t) g(x(t))-b(t) x(t-r(t)) \tag{4.25}
\end{equation*}
$$

satisfies $\left(\mathrm{A}_{2}\right)$ and (4.2)-(4.4). Hence it follows from Theorems 4.1 and 4.2 that
(i) if $\alpha$ and $\beta$ satisfy (4.13) or (4.14), then the zero solution of (4.25) is uniformly stable, and
(ii) if $a(t)$ and $b(t)$ satisfy (4.17) and if $\alpha$ and $\beta$ satisfy (4.23) or (4.24), then the zero solution of (4.25) is asymptotically stable.

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