# APPLICATIONS OF VARIATIONAL METHODS TO AN ANTI-PERIODIC BOUNDARY VALUE PROBLEM OF A SECOND-ORDER DIFFERENTIAL SYSTEM 

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$$
\begin{aligned}
& \text { ABSTRACT. In this paper, we discuss the existence of } \\
& \text { multiple solutions to a second order anti-periodic boundary } \\
& \text { value problem } \\
& \qquad \begin{array}{ll}
\ddot{x}(t)+M x(t)+\nabla F(t, x(t))=0 & \text { almost every } t \in[0, T], \\
x(0)=-x(T) & \dot{x}(0)=-\dot{x}(T)
\end{array} \\
& \text { by using variational methods and critical point theory. } \\
& \text { Furthermore, we obtain the existence of periodic solutions } \\
& \text { for corresponding second-order differential systems. }
\end{aligned}
$$

1. Introduction. The study of anti-periodic solutions for nonlinear evolution equations was initiated by Okochi [26]. Okochi studied the nonlinear parabolic equation in a real Hilbert space $H$, which is of the form

$$
\frac{d u(t)}{d t}+\partial \varphi(u(t)) \ni f(t)
$$

where $f \in L_{\text {loc }}^{2}(R ; H), \varphi$ is a proper lower semi-continuous (lsc) convex functional on $H$ and $\partial \varphi$ is the subdifferential of $\varphi$. By using fixed point theory, the existence of anti-periodic solutions was obtained in the case where $\partial \varphi$ is odd and $f$ is $T$-anti-periodic. Inspired by [26], anti-periodic problems for second- and higher-order differential equations have been extensively studied, see $[\mathbf{2}, \mathbf{3}, \mathbf{5}, \mathbf{6}, \mathbf{8}, \mathbf{9}, \mathbf{1 0}, \mathbf{1 1}, \mathbf{1 6}, \mathbf{1 7}, \mathbf{1 8}, \mathbf{1 9}$, $\mathbf{2 0}, \mathbf{2 2}, \mathbf{2 3}, \mathbf{2 5}, \mathbf{3 1}$ ] and the references therein. It is very important to study anti-periodic boundary value problems since they can be applied

[^0]to interpolation problems $[\mathbf{1 3}, 15]$, anti-periodic wavelets [7], the Hill differential operator $[\mathbf{1 4}]$ and physics $[\mathbf{1}, 4,21,27]$.

Many results have been obtained by using tools such as topological degree theory, lower and upper solution methods $[\mathbf{2}, \mathbf{3}, \mathbf{5}, \mathbf{6}, \mathbf{1 0}, \mathbf{1 6}$, $17,18,23,31,32]$, the maximal monotone or $m$-accretive operator $[2,6]$.

In [6], Aizicovici and Pavel established the existence, uniqueness and continuous dependence upon data of anti-periodic solutions to some first- and second-order evolution equations. In [31], Wang and Li studied the existence of solutions of the following antiperiodic boundary value problem for a second-order conservative system:

$$
\begin{cases}q^{\prime \prime}=u(t, q) & t \in[0, T]  \tag{1.1}\\ q(0)=-q(T) & q^{\prime}(0)=-q^{\prime}(T)\end{cases}
$$

By using fixed point theory together with Green's function, the existence result is as follows: assume that there exist constants $0 \leq c<8$ and $M>0$, such that

$$
|u(t, q)| \leq \frac{c}{T^{2}}|q|+M
$$

for all $t \in[0, T], q \in R^{1}$. Problem (1.2) has at least one solution.
In [32], Wang and Shen studied the antiperiodic boundary value problem as follows

$$
\begin{cases}x^{\prime \prime}+f(t, x(t))=0 & t \in[0, T]  \tag{1.2}\\ x(0)=-x(T) & x^{\prime}(0)=-x^{\prime}(T)\end{cases}
$$

By using Schauder's fixed point theorem and the lower and upper solutions method, some sufficient conditions for the existence of solutions are obtained: assume that there exist constants $0<r<2, l>0$, and functions $p, q, h \in C[0, T]$ such that

$$
u f(t, u) \leq p(t) u^{2}+q(t)|u|^{r}+h(t)
$$

for $t \in[0, T],|u|>1$. Further, suppose that

$$
\int_{0}^{T} p^{+}(s) d s<4
$$

where $p^{+}(t)=\max \{p(t), 0\}$. Then (1.2) has at least one solution. To the best of our knowledge, few authors have studied the existence of solutions for anti-periodic boundary value problems by using variational methods and critical point theory. As a result, the motivation of this paper is to fill the gaps in this area. We study the existence of multiple solutions to anti-periodic boundary value problems for the second-order differential system

$$
\begin{cases}\ddot{x}(t)+M x+\nabla F(t, x)=0 & \text { almost every } t \in[0, T]  \tag{1.3}\\ x(0)=-x(T) & \dot{x}(0)=-\dot{x}(T),\end{cases}
$$

$x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T} \in R^{n}, M$ is an $n \times n$ real symmetric matrix,

$$
F:[0, T] \times R^{n} \longrightarrow R,(t, x) \longmapsto F(t, x)
$$

is measurable in $t$ for each $x \in R^{n}$, and continuously differentiable in $x$ for almost every $t \in[0, T]$,

$$
\nabla F(t, x)=\left(\frac{\partial F(t, x)}{x_{1}}, \frac{\partial F(t, x)}{x_{2}}, \ldots, \frac{\partial F(t, x)}{x_{n}}\right)^{T}
$$

In particular, our aim of this paper is to apply critical point theory to problem (1.3) and prove the existence of at least two solutions when the eigenvalues of $M$ are less than $\pi^{2} / T^{2}$. In addition, we obtain the existence of $2 T$-periodic solutions for $\ddot{x}+M x+\nabla F(t, x)=0$. The constraint conditions on $F$ are new.

The main difficulties in the above problem are as follows:
(1) the construction of a suitable Banach space $X$;
(2) the construction of a functional $\varphi$ on the space $X$;
(3) how to prove the critical point of the functional $\varphi$ is only the solution of BVP (1.3).

In order to overcome these difficulties, especially (3), we prove an important fundamental lemma, which plays an important role in the proof of Lemma 2.4. The idea of this paper comes from [24, 28, 29].

The following lemmas will be needed in our argument, which may be found in $[12,24,29,33]$.

Lemma 1.1. ([33, Theorem 38A]). For the functional

$$
F: S \subseteq X \longrightarrow[-\infty,+\infty] \quad \text { with } S \neq \emptyset
$$

$\min _{u \in S} F(u)=\alpha$ has a solution in the following cases:
(i) $X$ is a real reflexive Banach space;
(ii) $S$ is bounded and weak sequentially closed;
(iii) $F$ is weak sequentially lower semi-continuous on $S$, i.e., by definition, for each sequence $\left(u_{n}\right)$ in $S$ such that $u_{n} \rightharpoonup u$ as $n \rightarrow \infty$, we have that $F(u) \leq \underline{\lim }_{n \rightarrow \infty} F\left(u_{n}\right)$ holds.

Lemma 1.2 ([12, 24, 29]). Let $E$ be a Banach space and $\varphi \in$ $C^{1}(E, R)$ satisfy the Palais-Smale condition, i.e., every sequence $\left\{x_{n}\right\}$ in $E$ satisfying $\varphi\left(x_{n}\right)$ is bounded, and $\varphi^{\prime}\left(x_{n}\right) \rightarrow 0$ has a convergent subsequence. Assume that there exist $x_{0}, x_{1} \in E$ and a bounded open neighborhood $\Omega$ of $x_{0}$ such that $x_{1} \in E \backslash \bar{\Omega}$ and

$$
\max \left\{\varphi\left(x_{0}\right), \varphi\left(x_{1}\right)\right\}<\inf _{x \in \partial \Omega} \varphi(x)
$$

Let

$$
\Gamma=\left\{h \mid h:[0,1] \longrightarrow E \text { is continuous and } h(0)=x_{0}, h(1)=x_{1}\right\}
$$

and

$$
c=\inf _{h \in \Gamma} \max _{s \in[0,1]} \varphi(h(s)) .
$$

Then, $c$ is a critical value of $\varphi$, that is, there exists an $x^{*} \in E$ such that $\varphi^{\prime}\left(x^{*}\right)=\Theta$ and $\varphi\left(x^{*}\right)=c$, where $c>\max \left\{\varphi\left(x_{0}\right), \varphi\left(x_{1}\right)\right\}$.

The remainder of the paper is organized as follows. In Section 2, some preliminary results will be given. In Section 3, we will state and prove the main results of the paper, as well as present some applications to (1.3).
2. Related lemmas. In order to begin, we introduce some notation. Here, and in the sequel, we assume that $T>0$ is the limit. For $x \in R^{n}, x=0$ means

$$
x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T}=(0,0, \ldots, 0)^{T}
$$

and $x>0$ means $x_{i}>0$ for all $i=1,2, \ldots, n$. For $x=\left(x_{1}, x_{2}\right.$, $\left.\ldots, x_{n}\right)^{T}, y=\left(y_{1}, y_{2}, \ldots, y_{n}\right)^{T} \in R^{n}$,

$$
x \cdot y=\sum_{i=1}^{n} x_{i} y_{i} .
$$

For $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right)^{T} \in R^{n}$,

$$
|x|=\left(\sum_{i=1}^{n} x_{i}^{2}\right)^{1 / 2}
$$

We define the space $X=\left\{x \in H^{1}\left([0, T], R^{n}\right): x(0)=-x(T)\right\}$ equipped with the norm

$$
\|x\|_{X}=\left(\int_{0}^{T}|\dot{x}(t)|^{2}+|x(t)|^{2} d t\right)^{1 / 2}
$$

We claim that $\left(X,\|\cdot\|_{X}\right)$ is a reflexive Banach space. In fact, $\left(H^{1}\left([0, T], R^{n}\right),\|\cdot\|_{X}\right)$ is a reflexive Banach space.

Now, we shall show that $\left(X,\|\cdot\|_{X}\right)$ is a closed subspace of $\left(H^{1}\left([0, T], R^{n}\right),\|\cdot\|_{X}\right)$. For any $\left(x_{n}\right) \in X, x_{n} \rightarrow x^{*}$ in $X$, i.e., $\left\|x_{n}-x^{*}\right\|_{X} \rightarrow 0$ as $n \rightarrow \infty$, which yields

$$
x_{n} \longrightarrow x^{*} \quad \text { in } C\left([0, T], R^{n}\right) \quad \text { and } \quad x^{*} \in H^{1}\left([0, T], R^{n}\right) .
$$

Since $x_{n}(0)=-x_{n}(T)$, we have $x^{*}(0)=-x^{*}(T)$. Thus, $\left(X,\|\cdot\|_{X}\right)$ is a closed subspace of $\left(H^{1}\left([0, T], R^{n}\right),\|\cdot\|_{X}\right)$. By fundamental analysis, $\left(X,\|\cdot\|_{X}\right)$ is a reflexive Banach space.

For each $x \in X$, put

$$
\begin{equation*}
\varphi(x):=\int_{0}^{T} \frac{1}{2}|\dot{x}(t)|^{2}-\frac{1}{2} M x(t) \cdot x(t)-F(t, x(t)) d t \tag{2.1}
\end{equation*}
$$

Clearly, $\varphi$ is a Gâteaux differentiable functional whose Gâteaux derivative at the point $x \in X$ is the functional $\varphi^{\prime}(x) \in X^{*}$, given by

$$
\begin{equation*}
\left\langle\varphi^{\prime}(x), v\right\rangle=\int_{0}^{T} \dot{x}(t) \cdot \dot{v}(t)-M x(t) \cdot v(t)-\nabla F(t, x(t)) \cdot v(t) d t \tag{2.2}
\end{equation*}
$$

for every $v \in X$. Obviously, $\varphi^{\prime}: X \rightarrow X^{*}$ is continuous.

Now, we shall cite an important fundamental lemma, which is useful in proving Lemma 2.4, i.e., the critical point of $\varphi$ is only the solution of BVP (1.3).

Let $Z=\left\{g \in C^{\infty}\left([0, T], R^{n}\right): g(0)=-g(T)\right\}$.

Lemma 2.1. ([30, Lemma 3.4]). Let $u, v \in L^{1}\left([0, T], R^{n}\right)$. If, for every $f \in Z$,

$$
\begin{equation*}
\int_{0}^{T}(u(t), \dot{f}(t)) d t=-\int_{0}^{T}(v(t), f(t)) d t \tag{2.3}
\end{equation*}
$$

where $(\cdot, \cdot)$ denotes the inner product and $\dot{f}$ is the derivative of the vector function $f$, then

$$
\begin{equation*}
\frac{2}{T} \int_{0}^{T} u(t)+t v(t) d t=\int_{0}^{T} v(t) d t \tag{2.4}
\end{equation*}
$$

and

$$
u(t)=\int_{0}^{t} v(s) d s+a_{0} \quad \text { for almost every } t \in[0, T], a_{0} \in R^{n}
$$

Remark 2.2. A function $v$ satisfying (2.3) is called a weak derivative of $u$. By a Fourier series argument, the weak derivative, if it exists, is unique. The weak derivative of $u$ will be denoted by $\dot{u}$.

Definition 2.3. A function $x \in X$ is said to be a classical solution of problem (1.3) if $x$ satisfies equation in (1.3) for almost every $t \in[0, T]$ and the boundary conditions of (1.3).

Lemma 2.4. If the function $x \in X$ is a critical point of the functional $\varphi$, then $x$ is a classical solution of problem (1.3).

Proof. Let $x \in X$ be a critical point of the functional $\varphi$. Then $\left\langle\varphi^{\prime}(x), v\right\rangle=0$ for every $v \in X$, i.e.,

$$
\int_{0}^{T} \dot{x}(t) \cdot \dot{v}(t)-M x(t) \cdot v(t)-\nabla F(t, x(t)) \cdot v(t) d t=0
$$

for all $v \in X$, and hence, for all $v \in Z$. By Lemma 2.1,

$$
\dot{x}(t)=-\int_{0}^{t} M x(s)+\nabla F(s, x(s)) d s+a_{0}
$$

for almost every $t \in[0, T], a_{0} \in R^{n}$. By Remark $2.2, \dot{x}$ has a weak derivative $\ddot{x}$ and

$$
\ddot{x}=-M x-\nabla F(t, x(t)) .
$$

Since $x \in X$ and $\nabla F(t, x)$ are continuous in $x$ for almost every $t \in[0, T]$, $\ddot{x}$ exists and is continuous for almost every $t \in[0, T]$. Thus, $\ddot{x}$ is a classical derivative of $\dot{x}$ for almost every $t \in[0, T]$. Therefore, $x$ satisfies the equation in (1.3) for almost every $t \in[0, T]$.

Moreover, since the derivative of $\dot{x}$ is $\ddot{x}$, by (2.4) in Lemma 2.1, we have

$$
\frac{2}{T} \int_{0}^{T} \dot{x}(t)+t \ddot{x}(t) d t=\int_{0}^{T} \ddot{x}(t) d t
$$

Now,
$\frac{2}{T} \int_{0}^{T} \dot{x}(t)+t \ddot{x}(t) d t=\frac{2}{T}\left[\int_{0}^{T} \dot{x}(t) d t+T \dot{x}(T)-\int_{0}^{T} \dot{x}(t) d t\right]=2 \dot{x}(T)$, and

$$
\int_{0}^{T} \ddot{x}(t) d t=\dot{x}(T)-\dot{x}(0)
$$

Thus, $\dot{x}(0)=-\dot{x}(T)$. Furthermore, $x \in X$ implies $x(0)=-x(T)$. Therefore, $x$ is a classical solution of (1.3).

Next, we shall show some properties between the norms which are useful in estimating the norm $\|\cdot\|_{X}$.

Lemma 2.5. If $x \in X$, then

$$
\|x\|_{L^{2}} \leq \frac{1}{\sqrt{\lambda_{0}}}\|\dot{x}\|_{L^{2}} \quad \text { and } \quad\|x\|_{\infty} \leq \frac{\sqrt{T}}{2}\|\dot{x}\|_{L^{2}}
$$

where

$$
\|x\|_{\infty}=\max _{t \in[0, T]}|x(t)|
$$

$\lambda_{0}=\pi^{2} / T^{2}$ is the first nonzero eigenvalue of the eigenvalue problem

$$
\begin{cases}\ddot{x}(t)+\lambda x(t)=0 & t \in[0, T], \lambda \in R  \tag{2.5}\\ x(0)=-x(T) & \dot{x}(0)=-\dot{x}(T)\end{cases}
$$

Proof. As is well known, (2.5) possesses a sequence of eigenvalues $\left(\lambda_{k}\right), \lambda_{k}=(2 k+1)^{2} \pi^{2} / T^{2}$, with

$$
0<\lambda_{0}<\lambda_{1}<\cdots<\lambda_{j}<\cdots
$$

For each $\lambda_{k}, k=0,1,2, \ldots,(2.5)$ possesses eigenfunctions

$$
\varphi_{k}(t)=a_{k} \cos \sqrt{\lambda_{k}} t+b_{k} \sin \sqrt{\lambda_{k}} t, \quad a_{k}, b_{k} \in R^{n}
$$

Let

$$
\bar{x}(t)= \begin{cases}x(t-2 k T) & t \in[2 k T,(2 k+1) T] \\ -x(t-(2 k+1) T) & t \in[(2 k+1) T,(2 k+2) T]\end{cases}
$$

Then $\bar{x}$ is a $2 T$-periodic function on $R^{n}$ satisfying $\bar{x}(t)=-\bar{x}(t+T)$. By the expression of Fourier expansion, we have

$$
\bar{x}(t)=\sum_{k=0}^{\infty}\left(a_{k} \cos \sqrt{\lambda_{k}} t+b_{k} \sin \sqrt{\lambda_{k}} t\right)
$$

Thus,

$$
\begin{aligned}
\int_{0}^{T}|x(t)|^{2} d t & =\frac{1}{2} \int_{0}^{2 T}|\bar{x}(t)|^{2} d t \\
& =\frac{1}{2} \int_{0}^{2 T}\left|\sum_{k=0}^{\infty}\left(a_{k} \cos \sqrt{\lambda_{k}} t+b_{k} \sin \sqrt{\lambda_{k}} t\right)\right|^{2} d t \\
& =\frac{1}{2} \int_{0}^{2 T} \sum_{k=0}^{\infty}\left|a_{k}\right|^{2} \cos ^{2} \sqrt{\lambda_{k}} t+\left|b_{k}\right|^{2} \sin ^{2} \sqrt{\lambda_{k}} t d t \\
& =\frac{1}{2} \sum_{k=0}^{\infty}\left[\left|a_{k}\right|^{2} \int_{0}^{2 T} \cos ^{2} \sqrt{\lambda_{k}} t d t+\left|b_{k}\right|^{2} \int_{0}^{2 T} \sin ^{2} \sqrt{\lambda_{k}} t d t\right] \\
& =\frac{T}{2} \sum_{k=0}^{\infty}\left(\left|a_{k}\right|^{2}+\left|b_{k}\right|^{2}\right)
\end{aligned}
$$

By the Parseval equality,

$$
\begin{aligned}
\int_{0}^{T}|\dot{x}(t)|^{2} d t & =\frac{1}{2} \int_{0}^{2 T}|\dot{\bar{x}}(t)|^{2} d t \\
& =\frac{1}{2} \int_{0}^{2 T}\left|\sum_{k=0}^{\infty}\left(-a_{k} \sqrt{\lambda_{k}} \sin \sqrt{\lambda_{k}} t+b_{k} \sqrt{\lambda_{k}} \cos \sqrt{\lambda_{k}} t\right)\right|^{2} d t \\
& =\frac{1}{2} \int_{0}^{2 T} \sum_{k=0}^{\infty}\left|a_{k}\right|^{2} \lambda_{k} \sin ^{2} \sqrt{\lambda_{k}} t+\left|b_{k}\right|^{2} \lambda_{k} \cos ^{2} \sqrt{\lambda_{k}} t d t \\
& =\frac{T}{2} \sum_{k=0}^{\infty}\left(\left|a_{k}\right|^{2}+\left|b_{k}\right|^{2}\right) \lambda_{k}
\end{aligned}
$$

Hence, we have $\|x\|_{L^{2}} \leq 1 / \sqrt{\lambda_{0}}\|\dot{x}\|_{L^{2}}$.
For the last inequality, we cite it from [11, Lemma 2.3]. For convenience, we prove it as follows. For $x \in X$, we have

$$
x(t)=x(0)+\int_{0}^{t} \dot{x}(s) d s \quad \text { and } \quad x(t)=x(T)-\int_{t}^{T} \dot{x}(s) d s
$$

Thus, we have

$$
\begin{aligned}
2 x(t) & =\int_{0}^{t} \dot{x}(s) d s-\int_{t}^{T} \dot{x}(s) d s \\
& \leq \int_{0}^{t}|\dot{x}(s)| d s+\int_{t}^{T}|\dot{x}(s)| d s \\
& =\int_{0}^{T}|\dot{x}(s)| d s
\end{aligned}
$$

It follows from Hölder's inequality that the result follows.

Since $M$ is a real symmetric matrix, $M$ has $n$ real eigenvalues, we denote $\lambda_{1}^{M}, \lambda_{2}^{M}, \ldots, \lambda_{n}^{M}$.

Lemma 2.6. For $\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}=\pi^{2} / T^{2}$, we have

$$
\begin{align*}
\theta_{1}\|\dot{x}\|_{L^{2}} & \leq\left(\int_{0}^{T}|\dot{x}(t)|^{2}-M x(t) \cdot x(t) d t\right)^{1 / 2}  \tag{2.6}\\
& \leq \theta_{2}\|\dot{x}\|_{L^{2}} \quad \text { for any } x \in X
\end{align*}
$$

where

$$
\theta_{1}= \begin{cases}\sqrt{1-\left(\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\} / \lambda_{0}\right)} & 0 \leq \max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0} \\ 1 & \max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<0\end{cases}
$$

and

$$
\theta_{2}=\left\{\begin{array}{lc}
1 & 0 \leq \min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\} \\
& <\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0} \\
\sqrt{1-\left(\min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\} / \lambda_{0}\right)} & \min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<0 \\
& <\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0} \\
\sqrt{1-\left(\min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\} / \lambda_{0}\right)} & \max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<0
\end{array}\right.
$$

that is to say,

$$
\left(\int_{0}^{T}|\dot{x}(t)|^{2}-M x(t) \cdot x(t) d t\right)^{1 / 2}
$$

is equivalent to $\|\dot{x}\|_{L^{2}}$.

Proof. If $0 \leq \max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}$, we have by Lemma 2.5

$$
\begin{aligned}
& \left(\int_{0}^{T}|\dot{x}(t)|^{2}-M x(t) \cdot x(t) d t\right)^{1 / 2} \\
& \quad \geq\left(\int_{0}^{T}|\dot{x}(t)|^{2}-\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}|x(t)|^{2} d t\right)^{1 / 2} \\
& \quad \geq\left(\int_{0}^{T}|\dot{x}(t)|^{2}-\frac{\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}}{\lambda_{0}}|\dot{x}(t)|^{2} d t\right)^{1 / 2} \\
& \quad=\theta_{1}\|\dot{x}\|_{L^{2}}
\end{aligned}
$$

If $\min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<0<\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}$,

$$
\begin{aligned}
& \left(\int_{0}^{T}|\dot{x}(t)|^{2}-M x(t) \cdot x(t) d t\right)^{1 / 2} \\
& \quad \leq\left(\int_{0}^{T}|\dot{x}(t)|^{2}-\min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}|x(t)|^{2} d t\right)^{1 / 2} \\
& \quad \leq\left(\int_{0}^{T}|\dot{x}(t)|^{2}-\frac{\min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}}{\lambda_{0}}|\dot{x}(t)|^{2} d t\right)^{1 / 2} \leq \theta_{2}\|\dot{x}\|_{L^{2}}
\end{aligned}
$$

If $0<\min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}$,

$$
\begin{aligned}
\left(\int_{0}^{T}|\dot{x}(t)|^{2}-\right. & M x(t) \cdot x(t) d t)^{1 / 2} \\
& \leq\left(\int_{0}^{T}|\dot{x}(t)|^{2}-\min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}|x(t)|^{2} d t\right)^{1 / 2} \leq\|\dot{x}\|_{L^{2}}
\end{aligned}
$$

If $\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<0$,

$$
\begin{aligned}
\|\dot{x}\|_{L^{2}} & \leq\left(\int_{0}^{T}|\dot{x}(t)|^{2}-M x(t) \cdot x(t) d t\right)^{1 / 2} \\
& \leq\left(\int_{0}^{T}|\dot{x}(t)|^{2}-\frac{\min _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}}{\lambda_{0}}|\dot{x}(t)|^{2} d t\right)^{1 / 2} \\
& \leq \theta_{2}\|\dot{x}\|_{L^{2}}
\end{aligned}
$$

The result follows.

Remark 2.7. $\|\cdot\|_{X}$ is equivalent to $\|\dot{x}\|_{L^{2}}$. In fact, by Lemma 2.5,

$$
\begin{equation*}
\|\dot{x}\|_{L^{2}} \leq\|x\|_{X}=\left(\int_{0}^{T}|\dot{x}|^{2}+|x|^{2} d t\right)^{1 / 2} \leq \sqrt{1+\frac{1}{\lambda_{0}}}\|\dot{x}\|_{L^{2}} \tag{2.7}
\end{equation*}
$$

Remark 2.8. If $\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}=\pi^{2} / T^{2},\|x\|_{X},\|\dot{x}\|_{L^{2}}$ and

$$
\left(\int_{0}^{T}|\dot{x}(t)|^{2}-M x(t) \cdot x(t) d t\right)^{1 / 2}
$$

are equivalent.

Lemma 2.9. Suppose that $\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}=\pi^{2} / T^{2}$, where $\lambda_{i}^{M}$, $i=1,2, \ldots, n$, are $n$ real eigenvalue of matrix $M$, and
(C1) there exist $\mu>2, l_{1}, l_{2}>0, r \in L^{1}\left([0, T], R^{+}\right)$,

$$
H(t, x):[0, T] \times R^{n} \longrightarrow R
$$

continuous in $x$ for almost every $t \in[0, T], H(t, x)>0$ for $x>0$, $t \in[0, T]$, such that

$$
F(t, x)=\frac{r(t)|x|^{\mu}}{\mu}+H(t, x)
$$

where

$$
\begin{equation*}
\limsup _{|x| \rightarrow+\infty} \frac{\mu H(t, x)-\nabla H(t, x) \cdot x}{|x|^{2}}=l_{0} \tag{2.8}
\end{equation*}
$$

(C2) $l_{0} / \lambda_{0}<(\mu / 2-1) \theta_{1}^{2}$, where $\theta_{1}$ is defined in Lemma 2.6. Then, $\varphi$ satisfies the Palais-Smale condition.

Proof. Let $\left(x_{n}\right) \subset X$ satisfy $\varphi\left(x_{n}\right)$ is bounded and

$$
\varphi^{\prime}\left(x_{n}\right) \longrightarrow 0 \quad \text { as } n \rightarrow \infty
$$

First, we shall show that $\left(x_{n}\right)$ is a bounded sequence in $X$. By (2.1)-(2.2),

$$
\begin{align*}
&\left(\frac{\mu}{2}-1\right)\left[\left\|\dot{x}_{n}\right\|_{L^{2}}^{2}-\int_{0}^{T} M x_{n} \cdot x_{n}(t) d t\right]  \tag{2.9}\\
&= \mu \varphi\left(x_{n}\right)-\left\langle\varphi^{\prime}\left(x_{n}\right), x_{n}\right\rangle+\mu \int_{0}^{T} F\left(t, x_{n}\right) d t \\
&-\int_{0}^{T} \nabla F\left(t, x_{n}\right) \cdot x_{n} d t
\end{align*}
$$

By (C1) and Lemma 2.5,

$$
\begin{align*}
\mu & \int_{0}^{T} F\left(t, x_{n}\right) d t-\int_{0}^{T} \nabla F\left(t, x_{n}\right) \cdot x_{n} d t  \tag{2.10}\\
& =\int_{0}^{T} r(t)\left|x_{n}\right|^{\mu}+\mu H\left(t, x_{n}\right)-\left[r(t) \phi_{\mu}\left(x_{n}\right)+\nabla H\left(t, x_{n}\right)\right] \cdot x_{n} d t \\
& =\int_{0}^{T} r(t)\left|x_{n}\right|^{\mu}+\mu H\left(t, x_{n}\right)-\left[r(t)\left|x_{n}\right|^{\mu}+\nabla H\left(t, x_{n}\right) \cdot x_{n}\right] d t \\
& =\int_{0}^{T} \mu H\left(t, x_{n}\right)-\nabla H\left(t, x_{n}\right) \cdot x_{n} d t
\end{align*}
$$

where $\phi_{\mu}(x)=|x|^{\mu-2} x$.
By (2.8), for any

$$
\begin{equation*}
\varepsilon \in\left(0, \lambda_{0}\left(\frac{\mu}{2}-1\right) \theta_{1}^{2}-l_{0}\right) \tag{2.11}
\end{equation*}
$$

there exists a positive constant $C>0$ satisfying

$$
\frac{\mu H(t, x)-\nabla H(t, x) \cdot x}{|x|^{2}}<l_{0}+\varepsilon \quad \text { for all }|x|>C .
$$

Thus, there exists a sufficiently large number $C^{\prime}>0$ satisfying

$$
\begin{equation*}
\mu H(t, x)-\nabla H(t, x) \cdot x<\left(l_{0}+\varepsilon\right)|x|^{2}+C^{\prime} \tag{2.12}
\end{equation*}
$$

for all $x \in R^{n}$.
By (2.10)-(2.12) and Lemma 2.5, we have

$$
\begin{align*}
\mu \int_{0}^{T} F\left(t, x_{n}\right) d t-\int_{0}^{T} \nabla F\left(t, x_{n}\right) \cdot x_{n} d t & \leq\left(l_{0}+\varepsilon\right)\left\|x_{n}\right\|_{L^{2}}^{2}+C^{\prime} T  \tag{2.13}\\
& \leq \frac{l_{0}+\varepsilon}{\lambda_{0}}\left\|\dot{x}_{n}\right\|_{L^{2}}^{2}+C^{\prime} T
\end{align*}
$$

By (2.6) and (2.9), we have

$$
\begin{equation*}
\left(\frac{\mu}{2}-1\right)\left[\left\|\dot{x}_{n}\right\|_{L^{2}}^{2}-\int_{0}^{T} M x_{n}(t) \cdot x_{n}(t) d t\right] \geq\left(\frac{\mu}{2}-1\right) \theta_{1}^{2}\left\|\dot{x}_{n}\right\|_{L^{2}}^{2} \tag{2.14}
\end{equation*}
$$

Substituting (2.13) and (2.14) into (2.9), we have

$$
\begin{align*}
\left(\frac{\mu}{2}-1\right) \theta_{1}^{2}\left\|\dot{x}_{n}\right\|_{L^{2}}^{2} \leq & \mu \varphi\left(x_{n}\right)-\left\langle\varphi^{\prime}\left(x_{n}\right), x_{n}\right\rangle  \tag{2.15}\\
& +\frac{l_{0}+\varepsilon}{\lambda_{0}}\left\|\dot{x}_{n}\right\|_{L^{2}}^{2}+C^{\prime} T
\end{align*}
$$

Suppose that $\left(\dot{x}_{n}\right)$ is unbounded in $L^{2}[0, T]$. Passing to a subsequence, we may assume, if necessary, that $\left\|\dot{x}_{n}\right\|_{L^{2}} \rightarrow \infty$ as $n \rightarrow \infty$. Dividing both sides of (2.15) by $\left\|\dot{x}_{n}\right\|_{L^{2}}^{2}$, we have

$$
\left(\frac{\mu}{2}-1\right) \theta_{1}^{2} \leq \frac{\mu \varphi\left(x_{n}\right)}{\left\|\dot{x}_{n}\right\|_{L^{2}}^{2}}-\frac{\left\langle\varphi^{\prime}\left(x_{n}\right), x_{n}\right\rangle}{\left\|\dot{x}_{n}\right\|_{L^{2}}^{2}}+\frac{l_{0}+\varepsilon}{\lambda_{0}}+\frac{C^{\prime} T}{\left\|\dot{x}_{n}\right\|_{L^{2}}^{2}} .
$$

Since $\varphi\left(x_{n}\right)$ is bounded and $\varphi^{\prime}\left(x_{n}\right) \rightarrow 0$, let $n \rightarrow \infty$ in the above inequality. Then, we have, by (2.11),

$$
\left(\frac{\mu}{2}-1\right) \theta_{1}^{2} \leq \frac{l_{0}+\varepsilon}{\lambda_{0}}<\left(\frac{\mu}{2}-1\right) \theta_{1}^{2}
$$

which is a contradiction. Therefore, $\left\|\dot{x}_{n}\right\|_{L^{2}}<\infty$, which, together with Remark 2.8, gives $\left\|x_{n}\right\|_{X}<\infty$.

From the reflexive property of $X$, we may extract a weakly convergent subsequence, which we call, for simplicity, $\left(x_{n}\right), x_{n} \rightharpoonup x$. In the following we shall show that $\left(x_{n}\right)$ converges strongly to $x$, i.e., $\left\|x_{n}-x\right\|_{X} \rightarrow 0$ as $n \rightarrow \infty$. By (2.2),

$$
\begin{aligned}
\left\langle\varphi^{\prime}\left(x_{n}\right)-\varphi^{\prime}(x), x_{n}-x\right\rangle & =\int_{0}^{T}\left|\dot{x}_{n}-\dot{x}\right|^{2}-M\left(x_{n}-x\right) \\
& \cdot\left(x_{n}-x\right)-\left(\nabla F\left(t, x_{n}\right)-\nabla F(t, x), x_{n}-x\right) d t
\end{aligned}
$$

By $x_{n} \rightharpoonup x$ in $X$, we see that $\left(x_{n}\right)$ converges uniformly to $x$ in $C([0, T])$, i.e., $\left\|x_{n}-x\right\|_{\infty} \rightarrow 0$ as $n \rightarrow \infty$. Hence,

$$
\int_{0}^{T}\left(\nabla F\left(t, x_{n}\right)-\nabla F(t, x)\right) \cdot\left(x_{n}-x\right) d t \longrightarrow 0 \quad \text { as } n \rightarrow \infty
$$

By $\varphi^{\prime}\left(x_{n}\right) \rightarrow 0$ and $x_{n} \rightharpoonup x$, we have

$$
\left\langle\varphi^{\prime}\left(x_{n}\right)-\varphi^{\prime}(x), x_{n}-x\right\rangle \longrightarrow 0
$$

Therefore,

$$
\int_{0}^{T}\left|\dot{x}_{n}-\dot{x}\right|^{2}-M\left(x_{n}-x\right) \cdot\left(x_{n}-x\right) d t \longrightarrow 0 \quad \text { as } n \rightarrow \infty
$$

By Remark 2.8, $\left\|x_{n}-x\right\|_{X} \rightarrow 0$ as $n \rightarrow \infty$.

## 3. Main results.

Theorem 3.1. Suppose that $\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}=\pi^{2} / T^{2}\left(\lambda_{i}^{M}, i=\right.$ $1,2, \ldots, n$, are $n$ real eigenvalues of real symmetric matrix $M$ ), and (C1)-(C2) hold. Furthermore, we assume that:
(C3) there exists $K_{0}>0$ such that

$$
\begin{aligned}
\frac{\theta_{1}^{2} \lambda_{0}}{2\left(1+\lambda_{0}\right)} K_{0}^{2}-\frac{\|r\|_{L^{1}} T^{\mu / 2}}{\mu 2^{\mu}} K_{0}^{\mu}-\max _{|x| \leq\left(\sqrt{T} K_{0} / 2\right)} & \int_{0}^{T} H(t, x) d t \\
& +\int_{0}^{T} H(t, 0) d t>0
\end{aligned}
$$

Then BVP (1.3) has at least two solutions.

Proof. We complete the proof with the following three steps.
Step 1. By Lemma 2.9, the functional $\varphi$ satisfies the Palais-Smale condition.

Step 2. We shall show that there exists a $K_{0}>0$ such that the functional $\varphi$ has a local minimum $x_{0} \in B_{K_{0}}:=\left\{x \in X:\|x\|_{X}<K_{0}\right\}$.

Let $K>0$, which will be determined later. First, we claim that $\bar{B}_{K}$ is bounded and weakly sequentially closed. In fact, let $\left(u_{n}\right) \subseteq \bar{B}_{K}$ and $\left(u_{n}\right) \rightharpoonup u$ as $n \rightarrow \infty$. By the Mazur theorem [24], there exists a sequence of convex combinations

$$
v_{n}=\sum_{j=1}^{n} \alpha_{n_{j}} u_{j}, \quad \sum_{j=1}^{n} \alpha_{n_{j}}=1, \quad \alpha_{n_{j}} \geq 0, j \in N
$$

such that $v_{n} \rightarrow u$ in $X$. Since $\bar{B}_{K}$ is a closed convex set, $\left(v_{n}\right) \subset \bar{B}_{K}$ and $u \in \bar{B}_{K}$. Now, we claim that $\varphi$ has a minimum $x_{0} \in \bar{B}_{K}$. We will show that $\varphi$ is weakly sequentially lower semi-continuous on $\bar{B}_{K}$. For this, let

$$
\varphi^{1}(x)=\frac{1}{2} \int_{0}^{T}|\dot{x}|^{2}-M x \cdot x d t, \quad \varphi^{2}(x)=\int_{0}^{T}-F(t, x) d t
$$

Then, $\varphi(x)=\varphi^{1}(x)+\varphi^{2}(x)$. By $x_{n} \rightharpoonup x$ on $X$, we have $\left(x_{n}\right)$ uniformly converges to $x$ in $C([0, T])$. Thus, $\varphi^{2}$ is weakly sequentially continuous. By Remark 2.8, $\varphi^{1}$ is continuous, which, together with the convexity of $\varphi^{1}$, gives that $\varphi^{1}$ is weakly sequentially lower semicontinuous. Therefore, $\varphi$ is weakly sequentially lower semi-continuous on $\bar{B}_{K}$. Further, $X$ is a reflexive Banach space, $\bar{B}_{K}$ is a bounded and weak sequentially closed set; thus, our claim follows from Lemma 1.1. Without loss of generality, we assume that $\varphi\left(x_{0}\right)=\min _{x \in \bar{B}_{K}} \varphi(x)$. Now we will show that

$$
\begin{equation*}
\varphi\left(x_{0}\right)<\inf _{x \in \partial B_{K}} \varphi(x) \tag{3.1}
\end{equation*}
$$

If this is true, the result of Step 2 holds.
In fact, for any $x \in \partial B_{K}$, by Lemma 2.5 , we have,

$$
\|x\|_{\infty} \leq \frac{\sqrt{T}}{2}\|x\|_{X}=\frac{\sqrt{T}}{2} K
$$

By (C1), (2.6), (2.7) and Lemma 2.5, we have

$$
\begin{aligned}
\varphi(x) \geq & \frac{\theta_{1}^{2}}{2}\|\dot{x}\|_{L^{2}}^{2}-\int_{0}^{T} r(t) \frac{|x|^{\mu}}{\mu}+H(t, x) d t \\
\geq & \geq \frac{\theta_{1}^{2} \lambda_{0}}{2\left(1+\lambda_{0}\right)} K^{2}-\frac{\|r\|_{L^{1}}}{\mu}\|x\|_{\infty}^{\mu}-\int_{0}^{T} H(t, x) d t \\
\geq & \frac{\theta_{1}^{2} \lambda_{0}}{2\left(1+\lambda_{0}\right)} K^{2}-\frac{\|r\|_{L^{1}} T^{\mu / 2}}{\mu 2^{\mu}}\|\dot{x}\|_{L^{2}}^{\mu}-\int_{0}^{T} H(t, x) d t \\
\geq & \frac{\theta_{1}^{2} \lambda_{0}}{2\left(1+\lambda_{0}\right)} K^{2}-\frac{\|r\|_{L^{1}} T^{\mu / 2}}{\mu 2^{\mu}}\|x\|_{X}^{\mu}-\int_{0}^{T} H(t, x) d t \\
\geq & \frac{\theta_{1}^{2} \lambda_{0}}{2\left(1+\lambda_{0}\right)} K^{2}-\frac{\|r\|_{L^{1}} T^{\mu / 2}}{\mu 2^{\mu}} K^{\mu} \\
& \quad-\max _{|x| \leq(\sqrt{T} / 2) K} \int_{0}^{T} H(t, x) d t .
\end{aligned}
$$

Noting

$$
\varphi(0)=-\int_{0}^{T} F(t, 0) d t=-\int_{0}^{T} H(t, 0) d t
$$

and $\varphi\left(x_{0}\right) \leq \varphi(0)$, let $K=K_{0}$. By (C3), we have $\inf _{x \in \partial B_{K_{0}}} \varphi(x)>$ $\varphi(0) \geq \min _{x \in \bar{B}_{K_{0}}} \varphi(x)$. Thus, (3.1) holds and $x_{0} \in B_{K_{0}}$.

Step 3. We shall show that there exists an $x_{1} \in X$ with $\left\|x_{1}\right\|_{X}>K_{0}$ such that $\varphi\left(x_{1}\right)<\inf _{x \in \partial B_{K_{0}}} \varphi(x)$.

Let $\widetilde{e}(t)=\sin (\pi / T) t(1,0, \ldots, 0)^{T}, \bar{\lambda}>0$. Then, by (C1),

$$
\begin{align*}
\varphi(\bar{\lambda} \widetilde{e})= & \int_{0}^{T} \frac{1}{2}|\bar{\lambda} \dot{\tilde{e}}|^{2}-\frac{1}{2} M \bar{\lambda} \widetilde{e} \cdot \bar{\lambda} \widetilde{e}-F(t, \bar{\lambda} \widetilde{e}) d t  \tag{3.3}\\
\leq & \int_{0}^{T} \frac{1}{2}\left|\bar{\lambda} \frac{\pi}{T} \cos \frac{\pi t}{T}\right|^{2}+\frac{\max _{1 \leq i \leq n}\left\{\left|\lambda_{i}^{M}\right|\right\}}{2}\left|\bar{\lambda} \sin \frac{\pi t}{T}\right|^{2} \\
& -F\left(t, \bar{\lambda} \sin \frac{\pi t}{T} e_{1}\right) d t \\
= & \left(\bar{\lambda} \frac{\pi}{T}\right)^{2} \frac{T}{4}+\max _{1 \leq i \leq n}\left\{\left|\lambda_{i}^{M}\right|\right\}|\bar{\lambda}|^{2} \frac{T}{4}
\end{align*}
$$

$$
\left.\begin{array}{rl} 
& -\int_{0}^{T} \frac{r(t)|\bar{\lambda}|^{\mu} \sin ^{\mu}(\pi t / T)}{\mu} d t-\int_{0}^{T} H\left(t, \bar{\lambda} \sin \frac{\pi t}{T} e_{1}\right) d t \\
\leq & (\bar{\lambda} \bar{\pi} \\
T
\end{array}\right)^{2} \frac{T}{4}+\max _{1 \leq i \leq n}\left\{\left|\lambda_{i}^{M}\right|\right\}|\bar{\lambda}|^{2} \frac{T}{4}-|\bar{\lambda}|^{\mu} \int_{0}^{T} \frac{r(t) \sin ^{\mu}(\pi t / T)}{\mu} d t . ~ \$
$$

Since

$$
\int_{0}^{T} r(t) \sin ^{\mu} \frac{\pi t}{T} d t>0
$$

and $\mu>2$, we have

$$
\lim _{\bar{\lambda} \longrightarrow+\infty} \varphi(\bar{\lambda} \widetilde{e})=-\infty .
$$

Thus, there exists a sufficiently large $\bar{\lambda}_{0}>0$ with $\left\|\bar{\lambda}_{0} \widetilde{e}\right\|>K_{0}$ such that

$$
\varphi\left(\bar{\lambda}_{0} \widetilde{e}\right)<\inf _{x \in \partial B_{K_{0}}} \varphi(x)
$$

Therefore, let $x_{1}=\bar{\lambda}_{0} \widetilde{e}$ and

$$
\varphi\left(x_{1}\right)<\inf _{x \in \partial B_{K_{0}}} \varphi(x)
$$

Lemma 1.2 now gives the critical value

$$
c=\inf _{h \in \gamma} \max _{t \in[0,1]} \varphi(h(t)),
$$

where

$$
\gamma=\left\{h \mid h:[0,1] \longrightarrow X \text { is continuous and } h(0)=x_{0}, h(1)=x_{1}\right\}
$$

that is, there exists an $x^{*} \in X$ such that $\varphi^{\prime}\left(x^{*}\right)=0$. Therefore, $x_{0}$ and $x^{*}$ are two critical points of $\varphi,\left\|x_{0}\right\|_{X}<K_{0}$. By Lemma $2.4 x_{0}$ and $x^{*}$ are two classical solutions of (1.3).

By Lemma 2.9 and Theorem 3.1, we have the following corollary.

Corollary 3.2. Suppose that $\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0},\left(\lambda_{i}^{M}, i=1\right.$, $2, \ldots, n$, are $n$ real eigenvalues of real symmetric matrix $M$ ), (C3) and
(C4) there exist $\mu>2, l_{1}, l_{2}>0, r \in L^{1}\left([0, T], R^{+}\right)$,

$$
H(t, x):[0, T] \times R^{n} \longrightarrow R
$$

continuous in $x$ for almost every $t \in[0, T], H(t, x)>0$ for $x>0$, $t \in[0, T]$, such that

$$
F(t, x)=\frac{r(t)|x|^{\mu}}{\mu}+H(t, x)
$$

and $\mu H(t, x)<\nabla H(t, x) \cdot x$ for $|x|$ sufficiently large. Then, BVP (1.3) has at least one solution.

Proof. Condition (C4) implies (C1) and (C2). Therefore, the result follows.

Finally, we consider the system

$$
\begin{equation*}
\ddot{x}+M x+\nabla F(t, x)=0, \quad \text { almost everywhere } t \in R, \tag{3.4}
\end{equation*}
$$

where

$$
F: R \times R^{n} \longrightarrow R \quad \text { and } \quad(t, x) \longmapsto F(t, x)
$$

is measurable in $t$ for each $x \in R^{n}$, and continuously differentiable in $x$ for almost every $t \in R$,

$$
\nabla F(t, x)=\left(\frac{\partial F(t, x)}{\partial x_{1}}, \frac{\partial F(t, x)}{\partial x_{2}}, \ldots, \frac{\partial F(t, x)}{\partial x_{n}}\right)^{T}
$$

Theorem 3.3. Assume that $\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}=\left(\pi^{2} / T^{2}\right),\left(\lambda_{i}^{M}\right.$, $i=1,2, \ldots, n$, are eigenvalues of real symmetric matrix $M$ ), (C1), (C2), (C3), and
(C5) $F(t+T, x)=F(t, x), \nabla F(t,-x)=-\nabla F(t, x)$ hold.
Then, (3.4) has at least two 2T-periodic solutions.

Proof. Assume that $x(t)$ is a solution of BVP (1.3). Let $x_{1}(t)=$ $-x(t-T)$ for $t \in[T, 2 T]$. Then, $\ddot{x}_{1}(t)=-\ddot{x}(t-T)$. By (C5), we have

$$
\nabla F\left(t, x_{1}(t)\right)=\nabla F(t-T,-x(t-T))=-\nabla F(t-T, x(t-T))
$$

Thus,

$$
\begin{aligned}
\ddot{x}_{1}(t)+M x_{1}(t)+\nabla F\left(t, x_{1}(t)\right)= & -\ddot{x}(t-T)-M x(t-T) \\
& -\nabla F(t-T, x(t-T))=0
\end{aligned}
$$

and

$$
\begin{array}{ll}
x_{1}(T)=-x(0), & x_{1}(2 T)=-x(T) \\
\dot{x}_{1}(T)=-\dot{x}_{1}(0), & \dot{x}_{1}(2 T)=-\dot{x}_{1}(T)
\end{array}
$$

Let

$$
\bar{x}(t)= \begin{cases}x(t) & t \in[0, T] \\ x_{1}(t) & t \in[T, 2 T]\end{cases}
$$

Then, $\bar{x}(t)$ is a solution of (3.4) with $x(0)=x(2 T), \dot{x}(0)=\dot{x}(2 T)$. Since $F(t, x)$ is 2T-periodic in $t, \bar{x}$ can be extended by $2 T$-periodic over $R$ to give a $2 T$-periodic solution of (3.4), and Theorem 3.1 gives the existence of two solutions. The result follows.

By Corollary 3.2 and Theorem 3.3 we have the following corollary.
Corollary 3.4. Suppose that $\max _{1 \leq i \leq n}\left\{\lambda_{i}^{M}\right\}<\lambda_{0}=\left(\pi^{2} / T^{2}\right)$, $\left(\lambda_{i}^{M}\right.$, $i=1,2, \ldots, n$, are $n$ real eigenvalues of real symmetric matrix $M$ ), (C3), (C4) and (C5) hold. Then, (3.4) has at least one 2T-periodic solution.

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