# On the NLS dynamics for infinite energy vortex configurations on the plane 

Fabrice Bethuel, Robert L. Jerrard and Didier Smets


#### Abstract

We derive the asymptotical dynamical law for Ginzburg-Landau vortices in the plane under the Schrödinger dynamics, as the Ginz-burg-Landau parameter goes to zero. The limiting law is the wellknown point-vortex system. This result extends to the whole plane previous results of $[8,13]$ established for bounded domains, and holds for arbitrary degree at infinity. When this degree is non-zero, the total Ginzburg-Landau energy is infinite.


## 1. Introduction

The purpose of this paper is to investigate the dynamics of vortices for the nonlinear Schrödinger equation on the plane, when the total degree at infinity is non zero. The equation we are interested in, also often referred to as the Gross-Pitaevskii equation, is written on $\mathbb{R}^{2} \times \mathbb{R}$ as
$(G P)_{\varepsilon}$

$$
i \partial_{t} u_{\varepsilon}+\Delta u_{\varepsilon}=\frac{1}{\varepsilon^{2}}\left(\left|u_{\varepsilon}\right|^{2}-1\right) u_{\varepsilon}
$$

where $0<\varepsilon<1$ denotes a small parameter. This equation is Hamiltonian, with Hamiltonian given by the Ginzburg-Landau energy

$$
E_{\varepsilon}(u) \equiv \int_{\mathbb{R}^{2}} e_{\varepsilon}(u):=\int_{\mathbb{R}^{2}} \frac{|\nabla u|^{2}}{2}+\frac{\left(1-|u|^{2}\right)^{2}}{4 \varepsilon^{2}} .
$$

One peculiarity of $E_{\varepsilon}$ and $(G P)_{\varepsilon}$ is that finite energy fields do not tend to zero at infinity, but have instead to stay close to the unit circle $S^{1}$. The Gross-Pitaevskii equation possesses distinguished stationary solutions called

2000 Mathematics Subject Classification: 35B20, 35B40, 35Q55, 82D50.
Keywords: Vortex dynamics, NLS equation, superfluids.
vortices and labelled by an integer $d \in \mathbb{Z}^{*}$, which have the special form, for $z=x_{1}+\imath x_{2}$,

$$
u_{\varepsilon, d}(z) \equiv u_{\varepsilon, d}(r, \theta)=f_{\varepsilon, d}(r) \exp (i d \theta)=f_{\varepsilon, d}(r)\left(\frac{z}{|z|}\right)^{d}
$$

where $f_{\varepsilon, d}: \mathbb{R}^{+} \rightarrow[0,1]$ satisfies $f_{\varepsilon, d}(0)=0, f_{\varepsilon, d}(+\infty)=1$, and

$$
\frac{d^{2}}{d r^{2}} f_{\varepsilon, d}+\frac{1}{r} \frac{d}{d r} f_{\varepsilon, d}-\frac{d^{2}}{r^{2}} f_{\varepsilon, d}+\frac{1}{\varepsilon^{2}} f_{\varepsilon, d}\left(1-\left(f_{\varepsilon, d}\right)^{2}\right)=0
$$

Notice that $\varepsilon$ has the dimension of a length and that by scaling

$$
f_{\varepsilon, d}(r)=f_{1, d}\left(\frac{r}{\varepsilon}\right) .
$$

In particular $\varepsilon$ is the characteristic length scale describing the core of the vortex, and as $\varepsilon \rightarrow 0$

$$
u_{\varepsilon, d}(z) \rightarrow\left(\frac{z}{|z|}\right)^{d}=\exp \imath d \theta
$$

It is known (see e.g. [12]) that $\left|\nabla u_{\varepsilon, d}(z)\right| \sim d /|z|$ as $|z| \rightarrow+\infty$, so that

$$
\begin{equation*}
\int\left|\nabla u_{\varepsilon, d}\right|^{2}=+\infty \tag{1.1}
\end{equation*}
$$

On the other hand, the potential term remains bounded (actually $\left.\int\left(1-\left|u_{\varepsilon, d}\right|^{2}\right)^{2} / 4 \varepsilon^{2}=\pi d^{2}\right)$, as well as the modulus part of the gradient: $\int|\nabla| u_{\varepsilon, d}| |^{2}<+\infty$. Notice that $u_{\varepsilon, d}$ has winding number $d$ at infinity, in the sense that for each radius $r>0$ large enough ( actually for any radius $r>0$ in the case considered here) the map $\psi_{r}: \partial B_{r} \simeq S^{1} \rightarrow S^{1}$ given by

$$
\partial B_{r} \ni z \mapsto \frac{u_{\varepsilon, d}(z)}{\left|u_{\varepsilon, d}(z)\right|}
$$

has topological degree $d$. Actually it can easily be proved that any continuous field which does not vanish outside a compact set and has a nonzero degree at infinity has infinite energy.

In this paper, we wish to study multi-vortex configurations, and the dynamics near such configurations. More precisely, for given points $a_{1}, \ldots, a_{l}$ in $\mathbb{R}^{2}$, and integers $d_{1}, \ldots, d_{l}$ in $\mathbb{Z}^{*}$, we have in mind initial data of the form

$$
\begin{equation*}
u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)(z) \equiv \prod_{i=1}^{l} u_{\varepsilon, d_{i}}\left(z-a_{i}\right)=\prod_{i=1}^{l} f_{1, d_{i}}\left(\frac{\left|z-a_{i}\right|}{\varepsilon}\right)\left(\frac{z-a_{i}}{\left|z-a_{i}\right|}\right)^{d_{i}}, \tag{1.2}
\end{equation*}
$$

as well as small perturbations of the maps defined above.

Notice that if $\Sigma d_{i} \neq 0$, then

$$
\int_{\mathbb{R}^{2}}\left|\nabla u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right|^{2}=+\infty
$$

and that

$$
J\left(u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right) \rightharpoonup \pi \sum_{i=1}^{l} d_{i} \delta_{a_{i}} \text { in } \mathcal{D}^{\prime}\left(\mathbb{R}^{2}\right),
$$

where for a map $v: \mathbb{R}^{2} \rightarrow \mathbb{C}, J v$ denotes its Jacobian

$$
J v=\frac{1}{2} v_{x_{1}} \times v_{x_{2}} .
$$

We will often use the notation

$$
j v=v \times \nabla v
$$

Physically, $j v$ represents the momentum density associated with a wave function $v$. Note that $J v=\frac{1}{2} \nabla \times j v$, so that $J v$ is naturally interpreted as vorticity.

This program has already been successfully carried out, in the case $\left|d_{i}\right|=1$ for all $i$, on bounded domains with periodic, Dirichlet or Neumann boundary conditions by Colliander and Jerrard [8], Lin and Xin [13] and Jerrard and Spirn [11], for suitable modification $\tilde{u}_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)$ of $u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)$, according to the boundary condition. These papers show that the vortex dynamics is governed in the limit $\varepsilon \rightarrow 0$ by exactly the same ordinary differential equations that describe the motion of vortices in an ideal incompressible fluid, with suitable boundary condition.

In the bounded case, a crucial observation is the fact that the total energy is bounded and that $\tilde{u}_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)$ is almost energy minimizing for the given vortex configuration. More precisely, it is proved in [8] that if

$$
J\left(u_{\varepsilon}\right) \rightharpoonup \pi \sum_{i=1}^{l} d_{i} \delta_{a_{i}}
$$

then

$$
\liminf _{\varepsilon \rightarrow 0} E_{\varepsilon}\left(u_{\varepsilon}\right)-E_{\varepsilon}\left(\tilde{u}_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right) \geq 0 .
$$

Moreover the last inequality is coercive in the sense that, if the left-hand side is small, then $u_{\varepsilon}$ is close to $\tilde{u}_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)$ in various norms. This last property makes it possible to compare the dynamics of $(G P)_{\varepsilon}$ with that of the finite dimensional Hamiltonian system whose Hamiltonian is essentially given by $E_{\varepsilon}\left(\tilde{u}_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right)$.

Our main aim here is to extend the result to the whole plane and to initial data of the form $u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)$ and perturbations thereof. One of the main additional difficulties we have to face is the divergence of the total energy and various losses of control at infinity. A first issue is to solve the Cauchy problem. This is done in [6]. It is proved there that the Cauchy problem is globally well-posed in $\{U\}+H^{1}\left(\mathbb{R}^{2}\right)$, for any $U \in \mathcal{V}$, where

$$
\mathcal{V}=\left\{U \in L^{\infty}\left(\mathbb{R}^{2}, \mathbb{C}\right), \nabla^{k} U \in L^{2}, \forall k \geq 2, \nabla|U| \in L^{2},\left(1-|U|^{2}\right) \in L^{2}\right\}
$$

In particular, for any configuration $\left(a_{i}, d_{i}\right)$, since $u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)$ is in $\mathcal{V}$, the Cauchy problem is globally well-posed in $\left\{u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right\}+H^{1}\left(\mathbb{R}^{2}\right)$. It turns out that, for any $U \in \mathcal{V}$, one may define a renormalized energy in $\{U\}+H^{1}\left(\mathbb{R}^{2}\right)$, denoted $\mathcal{E}_{\varepsilon, U}$, whose definition depends on $U$, and that this renormalized energy remains constant in time, for $(G P)_{\varepsilon}$ and intial data in $\{U\}+H^{1}\left(\mathbb{R}^{2}\right)$, i.e

$$
\begin{equation*}
\forall t \in \mathbb{R}, \quad \mathcal{E}_{\varepsilon, U}\left(u_{\varepsilon}(., t)\right)=\mathcal{E}_{\varepsilon, U}\left(u_{\varepsilon}(., 0)\right) . \tag{1.3}
\end{equation*}
$$

More precisely, $\mathcal{E}_{\varepsilon, U}$ is given by

$$
\begin{equation*}
\mathcal{E}_{\varepsilon, U}(U+v)=\int_{\mathbb{R}^{2}} \frac{|\nabla v|^{2}}{2}-\int_{\mathbb{R}^{2}}(\Delta U) \cdot v+\int_{\mathbb{R}^{2}} \frac{\left(|U+v|^{2}-1\right)^{2}}{4 \varepsilon^{2}} . \tag{1.4}
\end{equation*}
$$

If moreover the map $U$ verifies the additional condition $|\nabla U(z)| \leq \frac{C}{\sqrt{|z|}}$ then the renormalized energy $\mathcal{E}_{\varepsilon, U}$ may be defined as follows (see Section 3)

$$
\begin{equation*}
\mathcal{E}_{\varepsilon, U}(u)=\lim _{R \rightarrow \infty} \int_{B(R)}\left[e_{\varepsilon}(u)-\frac{|\nabla U|^{2}}{2}\right] . \tag{1.5}
\end{equation*}
$$

We therefore restrict ourselves to the class

$$
\mathcal{V}_{*}=\left\{U \in \mathcal{V},|\nabla U(z)| \leq \frac{C}{\sqrt{|z|}}\right\} .
$$

In contrast with the classical energy, we will show in Section 4 that the renormalized energy is unbounded from below when the degree at infinity of $U$ is greater or equal to 2 in absolute value.

Working in $\{U\}+H^{1}\left(\mathbb{R}^{2}\right)$ for a single reference field $u$ is in some places too restrictive. In this direction, we introduce an equivalence relation on the set $\mathcal{V}_{*}$. First, observe that if $U \in \mathcal{V}$, its zero set is bounded so that its topological degree at infinity $\operatorname{deg}(U, \infty)$ is well defined. We write

$$
U \sim U^{\prime} \quad \text { iff } \quad \operatorname{deg}(U, \infty)=\operatorname{deg}\left(U^{\prime}, \infty\right) \quad \text { and } \quad|\nabla U|^{2}-\left|\nabla U^{\prime}\right|^{2} \in L^{1}\left(\mathbb{R}^{2}\right)
$$

and denote by $[U]$ the corresponding equivalence class. As a consequence of the second condition, if $U^{\prime} \in[U]$,

$$
\lim _{R \rightarrow+\infty} \int_{B(R)} e_{\varepsilon}(u)-\frac{|\nabla U|^{2}}{2} \text { exists }
$$

for any $u \in\left\{U^{\prime}\right\}+H^{1}\left(\mathbb{R}^{2}\right)$. This allows us to extend the definition of $\mathcal{E}_{\varepsilon, U}$ to $[U]+H^{1}\left(\mathbb{R}^{2}\right)$.

For every $d \in \mathbb{Z}$, we choose a smooth reference field $U_{d}$ such that

$$
\begin{equation*}
U_{d}=\left(\frac{z}{|z|}\right)^{d}=\exp i d \theta, \quad \forall z \in \mathbb{R}^{2} \backslash B(1) \tag{1.6}
\end{equation*}
$$

Notice that for any configuration of vortices $\left(a_{i}, d_{i}\right)$ with $\sum d_{i}=D$, one has $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right) \in\left[U_{d}\right]$, whereas $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right) \in\left\{U_{d}\right\}+H^{1}\left(\mathbb{R}^{2}\right)$ if and only if (see Lemma 4.4) $\sum d_{i} a_{i}=0$.

In the sequel, we decompose, for suitable choices of integer $n_{0} \in \mathbb{N}^{*}$ the plane $\mathbb{R}^{2}$ as $\mathbb{R}^{2}=B\left(2^{n_{0}}\right) \cup\left(\cup_{n=n_{0}}^{+\infty} A_{n}\right)$, where $A_{n}=B\left(2^{n+1}\right) \backslash B\left(2^{n}\right)$.
Definition 1. Let $a_{1}, \ldots, a_{l}$ be l points in $\mathbb{R}^{2}$, let $d_{i}= \pm 1$, for $i=1, \ldots$, l, and set $d=\Sigma d_{i}$. We say that a family $\left\{u_{\varepsilon}\right\}_{0<\varepsilon<1}$ of maps in $\left[U_{d}\right]+H^{1}\left(\mathbb{R}^{2}\right)$ is well-prepared with respect to the configuration $\left(a_{i}, d_{i}\right)$ if and only if there exists $R=2^{n_{0}}>\max \left\{\left|a_{i}\right|\right\}$ and $K_{0}>0$ such that

$$
\begin{gather*}
\lim _{\varepsilon \rightarrow 0}\left\|J u_{\varepsilon}-\pi \Sigma d_{i} \delta_{a_{i}}\right\|_{\left[C_{c}^{0,1}(B(R))\right]^{*}}=0  \tag{1.7}\\
\sup _{0<\varepsilon<1} E_{\varepsilon}\left(u_{\varepsilon}, A_{n}\right) \leq K_{0} \quad \forall n \geq n_{0} \tag{1.8}
\end{gather*}
$$

and

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0}\left[\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}\right)-\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right)\right]=0 \tag{1.9}
\end{equation*}
$$

Our main theorem then can be stated as
Theorem 1. Assume that $\left\{u_{\varepsilon}^{0}\right\}_{0<\varepsilon<1}$ is well-prepared with respect to the configuration $\left(a_{i}^{0}, d_{i}\right)$. Let $\left\{a_{i}(t)\right\}_{i=1, \ldots, l}$ denote the solution of the point-vortex system with initial data $\left(a_{i}^{0}\right)_{i=1, \ldots, l}$, that is

$$
\begin{cases}\frac{d}{d t} a_{i}(t)=\sum_{j \neq i} d_{j} \frac{\left(a_{i}(t)-a_{j}(t)\right)^{\perp}}{\left|a_{i}(t)-a_{j}(t)\right|^{2}}, & \text { for } i=1, \ldots, l  \tag{1.10}\\ a_{i}(0)=a_{i}^{0}, & \text { for } i=1, \ldots, l\end{cases}
$$

and let $\left(T_{*}, T^{*}\right)$ denote its maximal interval of existence. Then, for every $T_{*} \leq t<T^{*}$, the sequence $\left\{u_{\varepsilon}(., t)\right\}_{0<\varepsilon<1}$ is well-prepared with respect to the configuration $\left(a_{i}(t), d_{i}\right)$.

Notice that the system (1.10) is Hamiltonian, with Hamiltonian given by the Kirchhoff-Onsager functional

$$
W\left(\left(a_{i}, d_{i}\right)\right)=-\pi \sum_{i \neq j} d_{i} d_{j} \log \left|a_{i}-a_{j}\right|
$$

divided by $\pi$. As a matter of fact, this quantity appears in the computation of the expansion of the energy of $u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)$. We will show in Section 4 that

$$
\begin{aligned}
\int_{B(R)} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)=\pi & \sum_{i=1}^{l} d_{i}^{2}|\log \varepsilon|+\pi d^{2} \log R+W\left(\left(a_{i}, d_{i}\right)\right) \\
& +\sum_{i=1}^{l} \gamma\left(\left|d_{i}\right|\right)+o_{\varepsilon, R}(1)
\end{aligned}
$$

where $o_{\varepsilon, R}(1) \rightarrow 0$ as $\varepsilon \rightarrow 0$ and $R \rightarrow+\infty$, and where the constant $\gamma\left(\left|d_{i}\right|\right)$ is given by

$$
\begin{align*}
\gamma(d)=\pi( & \int_{0}^{1}\left|f_{1, d}^{\prime}\right|^{2} r d r-\int_{1}^{\infty}\left(1-f_{1, d}^{2}\right) \frac{d^{2}}{r} d r  \tag{1.11}\\
& \left.+\int_{0}^{1} f_{1, d}^{2} \frac{d^{2}}{r} d r+\int_{0}^{\infty} \frac{\left(1-f_{1, d}^{2}\right)^{2}}{2} r d r\right)
\end{align*}
$$

Therefore,

$$
\begin{aligned}
\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right)= & \pi \sum_{i=1}^{l} d_{i}^{2}|\log \varepsilon|+W\left(\left(a_{i}, d_{i}\right)\right)+\sum_{i=1}^{l} \gamma\left(\left|d_{i}\right|\right) \\
& +\int_{B(1)} \frac{\left|\nabla U_{d}\right|^{2}}{2}+o_{\varepsilon}(1)
\end{aligned}
$$

The proof of Theorem 1 borrows many ideas from [8] and [11]. The starting point in $[8]$ is the remarkable identity for the evolution of the Jacobian, valid for any solution $u$ of $(G P)_{\varepsilon}$,

$$
\begin{equation*}
\frac{d}{d t} J u=\left(\left|u_{x_{2}}\right|^{2}-\left|u_{x_{1}}\right|^{2}\right)_{x_{1} x_{2}}+\left(u_{x_{1}} \cdot u_{x_{2}}\right)_{x_{1} x_{1}}-\left(u_{x_{1}} \cdot u_{x_{2}}\right)_{x_{2} x_{2}} \tag{1.12}
\end{equation*}
$$

Integrating against a test function $\chi \in \mathcal{D}\left(\mathbb{R}^{2}\right)$, this yields

$$
\begin{equation*}
\frac{d}{d t} \int_{\mathbb{R}^{2}} \chi J u=\int_{\mathbb{R}^{2}}\left(\left|u_{x_{2}}\right|^{2}-\left|u_{x_{1}}\right|^{2}\right) \chi_{x_{1} x_{2}}+\left(u_{x_{1}} \cdot u_{x_{2}}\right)\left(\chi_{x_{1} x_{1}}-\chi_{x_{2} x_{2}}\right) \tag{1.13}
\end{equation*}
$$

which may be reformulated in complex notations as

$$
\begin{equation*}
\frac{d}{d t} \int_{\mathbb{R}^{2}} \chi J u=-2 \int_{\mathbb{R}^{2}} \operatorname{Im}\left(\omega(u) \frac{\partial^{2} \chi}{\partial \bar{z}^{2}}\right) \tag{1.14}
\end{equation*}
$$

where $\omega$ denotes the Hopf differential given by

$$
\begin{equation*}
\omega(u)=\left|u_{x_{1}}\right|^{2}-\left|u_{x_{2}}\right|^{2}-2 i u_{x_{1}} \cdot u_{x_{2}}=4 \partial_{z} u \overline{\partial_{\bar{z}} u} . \tag{1.15}
\end{equation*}
$$

To derive the motion law, one specifies (1.14) for test functions $\chi=\chi_{\text {aff }}$ which are affine near a point $a_{i}$ and vanish near all the other ones, and one takes advantage of the special form of the integral in (1.14) when $u$ is close to a map $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)$. Indeed, for the map

$$
u^{*}\left(a_{i}, d_{i}\right)=\lim _{\varepsilon \rightarrow 0} u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)=\prod_{i=1}^{l}\left(\frac{z-a_{i}}{\left|z-a_{i}\right|}\right)^{d_{i}}
$$

one computes

$$
\begin{equation*}
J\left(\left(u^{*}\left(a_{i}, d_{i}\right)\right)=\pi \sum_{i=1}^{l} d_{i} \delta_{a_{i}} \quad \text { and } \quad \omega\left(u^{*}\left(a_{i}, d_{i}\right)\right)=-\left(\sum_{i=1}^{l} \frac{d_{i}}{z-a_{i}}\right)^{2},\right. \tag{1.16}
\end{equation*}
$$

so that

$$
\begin{equation*}
\int_{\mathbb{R}^{2}} \chi J u^{*}\left(a_{i}, d_{i}\right)=\pi d_{i} \chi\left(a_{i}\right), \tag{1.17}
\end{equation*}
$$

and

$$
\begin{equation*}
-2 \int_{\mathbb{R}^{2}} \operatorname{Im}\left(\omega\left(u^{*}\left(a_{i}, d_{i}\right)\right) \frac{\partial^{2} \chi}{\partial \bar{z}^{2}}\right)=\pi \sum_{j \neq i} d_{i} d_{j} \frac{\left(a_{i}-a_{j}\right)^{\perp}}{\left|a_{i}-a_{j}\right|^{2}} \cdot \nabla \chi\left(a_{i}\right) . \tag{1.18}
\end{equation*}
$$

Replacing $u(\cdot, t)$ by $u^{*}\left(a_{i}(t), d_{i}\right)$ one obtains formally from (1.12)

$$
\frac{d}{d t} a_{i}(t) \cdot \nabla \chi\left(a_{i}(t)\right)=\sum_{j \neq i} d_{j} \frac{\left(a_{i}(t)-a_{j}(t)\right)^{\perp}}{\left|a_{i}(t)-a_{j}(t)\right|^{2}} \cdot \nabla \chi\left(a_{i}(t)\right)
$$

By varying $\nabla \chi\left(a_{i}\right)$ one is therefore led to (1.10). A rigorous justification of the previous limiting procedure requires precise control of the distance between $u(\cdot, t)$ and $u_{\varepsilon}^{*}\left(a_{i}(t), d_{i}\right)$. For bounded domains (using $\tilde{u}_{\varepsilon}^{*}$ instead of $u_{\varepsilon}^{*}$ ), this control was provided combining conservation of energy with the already mentioned coercivity property near the $\tilde{u}_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)$. In our context, the conservation of energy is replaced by the conservation of renormalized energy. The important new point is to establish a kind of coercivity of the renormalized energy about the reference map $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)$, with respect to perturbations at infinity. For that purpose, we use almost minimizing properties of the map $\left(\frac{z}{|z|}\right)^{d}$ on annuli. This property is strongly connected to topological properties of Ginzburg-Landau maps on annuli, which we expose in the next section. Thanks to the coercivity properties on annuli, we are able to adapt the stoppiing time argument of [8] to our setting. This adaptation which leads to the proof of Theorem 1 is carried out in Section 7 and 8.

## 2. Topological sectors and almost minimizing properties

Let $A=B(2) \backslash B(1)$ be a reference annulus. Although the zero set of Ginzburg-Landau maps on $A$ may be nonempty, a restriction on the Ginz-burg-Landau energy allows us to define a notion of degree with suitable continuity properties. First, notice that by Sobolev embedding, for $u \in$ $H^{1}(A)$, the restriction $u_{\mid \partial B(r)}$ is continuous for almost every $r \in[1,2]$. In particular, if it does not vanish, we may define the degree of $\frac{u}{|u|_{\partial B(r)}}$. We therefore define, for $u \in H^{1}(A)$, the set $B(u)$ as the subset of of radii $r$ of [1,2] for which the restriction of $u$ to $\partial B(r)$ is continuous and does not vanish. We set

$$
\begin{aligned}
& T_{d}=\left\{u \in H^{1}(A) \text { s.t. } \exists B \subset B(u), \operatorname{meas}(B) \geq \frac{3}{4}\right. \\
&\text { and } \forall r \in B \operatorname{deg}(\mathrm{u}, \partial \mathrm{~B}(\mathrm{r}))=\mathrm{d}\} .
\end{aligned}
$$

It is clear from the definition that $\left(\frac{z}{|z|}\right)^{d} \in T_{d}$ and that $T_{d} \cap T_{d^{\prime}}=\emptyset$ if $d \neq d^{\prime}$. Of course, $\cup_{d \in \mathbb{Z}} T_{d} \neq H^{1}(A)$. Next, we restrict ourselves to the sublevel sets $E_{\varepsilon}^{\Lambda}$ of $H^{1}(A)$ defined by

$$
E_{\varepsilon}^{\Lambda}=\left\{u \in H^{1}(A), \text { s.t. } E_{\varepsilon}(u, A) \equiv \int_{A} e_{\varepsilon}(u)<\Lambda\right\}
$$

and set

$$
S_{d, \varepsilon}^{\Lambda}=E_{\varepsilon}^{\Lambda} \cap T_{d} .
$$

The following result was proved by Almeida.
Theorem 2.1 ([1]). Let $\Lambda>0$ be given. There exists a constant $\varepsilon_{\Lambda}>0$, such that for every $0<\varepsilon<\varepsilon_{\Lambda}$, we have the partition

$$
\begin{equation*}
E_{\varepsilon}^{\Lambda}=\bigcup_{d \in \mathbb{Z}} S_{d, \varepsilon}^{\Lambda} \tag{2.1}
\end{equation*}
$$

Moreover, the map

$$
\operatorname{deg}: E_{\varepsilon}^{\Lambda} \rightarrow \mathbb{Z}, u \in S_{d, \varepsilon}^{\Lambda} \mapsto d
$$

is continuous.
It is also proved in [1] that, for $d \neq d^{\prime}$, the threshold energy between $S_{d, \varepsilon}^{\Lambda}$ and $S_{d^{\prime}, \varepsilon}^{\Lambda}$ satisfies the lower bound, for every $0<\varepsilon<\varepsilon_{\Lambda}$,

$$
\begin{array}{r}
\inf \left\{\sup _{s \in[0,1]} E_{\varepsilon}(p(s), A), p \in \mathcal{C}\left([0,1], H^{1}(A)\right), p(0) \in S_{d, \varepsilon}^{\Lambda}, p(1) \in S_{d^{\prime}, \varepsilon}^{\Lambda}\right\}  \tag{2.2}\\
\geq \sigma|\log \varepsilon| \geq 2 \Lambda
\end{array}
$$

where $\sigma>0$ is some universal constant. The set $S_{d, \varepsilon}^{\Lambda}$ is referred to in [1] as the topological sector of degree $d$. An elementary computation shows that $E_{\varepsilon}(\exp i d \theta, A)=\pi d^{2} \log 2$, so that the condition $\exp i d \theta \in E_{\varepsilon}^{\Lambda}$ is equivalent to $\Lambda>\pi d^{2} \log 2$.

Our next results stresses the almost minimizing properties of the map $\exp i d \theta .{ }^{1}$ Note that the proof shows that every energy-minimizer in a topological sector $S_{d, \varepsilon}^{\Lambda}$ is equivariant.

Lemma 2.1. Let $d \in \mathbb{Z}$. There exists a constant $C>0$ depending only on $d$ such that, for every $0<\varepsilon<1$, and for every $\Lambda$ such that $S_{d, \varepsilon}^{\Lambda}$ is nonempty,

$$
\begin{equation*}
\pi d^{2} \log 2=E_{\varepsilon}(\exp i d \theta, A) \leq \inf _{v \in S_{d, \varepsilon}^{A}} E_{\varepsilon}(v, A)+C \varepsilon^{2} \tag{2.3}
\end{equation*}
$$

Proof. It suffices of course to prove that (2.3) is satisfied for $\varepsilon$ sufficiently small, the other cases being treated by considering a sufficiently large constant $C$. It is proved in [1] that $E_{\varepsilon}$ satisfies the Palais-Smale condition in $E_{\varepsilon}^{\Lambda}$ and also (therefore) that the infimum appearing in (2.3) is achieved in each topological sector $S_{d, \varepsilon}^{\Lambda}$. We denote by $V_{d}$ one such minimizer. Since $E_{\varepsilon}\left(V_{d}\right) \leq \pi d^{2} \log 2$ and $V_{d}$ is a solution of the Euler-Lagrange equation with Neumann boundary conditions on $\partial A$, it follows from the $\eta$-ellipticity results proved in [4] (for the interior) and [7] (Theorem 3, for the boundary) that $\left|V_{d}\right| \geq \frac{2}{3}$ on $A$. We may hence write

$$
V_{d}=\rho \exp (i \varphi) \quad \text { on } A
$$

where $\rho \geq \frac{2}{3}$ and $\varphi: A \mapsto \mathbb{T}^{1}$ are smooth and satisfy

$$
\begin{equation*}
\int_{0}^{2 \pi} \frac{\partial \varphi}{\partial \theta}(r \exp (i \theta)) d \theta=2 \pi d \quad \forall r \in[1,2] . \tag{2.4}
\end{equation*}
$$

We claim that $V_{d}$ is equivariant, in the sense that

$$
\begin{equation*}
\exists \alpha \in \mathbb{T}^{1} \text { s.t. } \varphi(r \exp (i \theta))=\alpha+d \theta \tag{2.5}
\end{equation*}
$$

Proof of the claim (2.5). Let $W_{d}$ denote a minimizer among equivariant maps in $S_{d, \varepsilon}^{\Lambda}$. Up to a constant phase shift, we may assume that $W_{d}(r \exp (i \theta))=M(r) \exp (i d \theta)$, and we have

$$
E_{\varepsilon}\left(W_{d}\right)=\pi \int_{1}^{2}\left[M^{\prime}(r)^{2}+M(r)^{2} \frac{d^{2}}{r^{2}}+\frac{\left(1-M(r)^{2}\right)^{2}}{2 \varepsilon^{2}}\right] r d r
$$

[^0]The minimality of $W_{d}$ amounts to
$E_{\varepsilon}\left(W_{d}\right)=\min \left\{\pi \int_{1}^{2}\left[m^{\prime}(r)^{2}+m(r)^{2} \frac{d^{2}}{r^{2}}+\frac{\left(1-m(r)^{2}\right)^{2}}{2 \varepsilon^{2}}\right] r d r, m \in H^{1}([1,2])\right\}$.
For $r \in[1,2]$, we set

$$
\begin{equation*}
m(r):=f_{\partial B(r)} \rho . \tag{2.6}
\end{equation*}
$$

On the one hand, by Jensen's inequality we obtain

$$
\begin{align*}
\int_{A} \frac{|\nabla \rho|^{2}}{2}=\pi \int_{1}^{2} r\left(f_{\partial B(r)}|\nabla \rho|^{2}\right) d r \geq \pi \int_{1}^{2} r & \left(f_{\partial B(r)}|\nabla \rho|\right)^{2} d r  \tag{2.7}\\
& \geq \pi \int_{1}^{2}\left(m^{\prime}(r)\right)^{2} r d r
\end{align*}
$$

On the other hand,

$$
\begin{equation*}
\int_{A} \frac{\rho^{2}|\nabla \varphi|^{2}}{2}+\frac{\left(1-\rho^{2}\right)^{2}}{4 \varepsilon^{2}} \geq \int_{1}^{2} r\left[2 \pi^{2} \frac{d^{2}}{r^{2}}\left(\int_{0}^{2 \pi} \rho^{-2}\right)^{-1}+\int_{0}^{2 \pi} \frac{\left(1-\rho^{2}\right)^{2}}{4 \varepsilon^{2}}\right] d r \tag{2.8}
\end{equation*}
$$

Indeed, for each $r \in[1,2]$, minimization over $\varphi \in H^{1}([0,2 \pi])$ with the constraint (2.4) leads to $\partial_{\theta}\left(\rho^{2} \partial_{\theta} \varphi\right)=0$ and therefore to

$$
\frac{\partial \varphi}{\partial \theta}=\frac{C}{\rho^{2}} \quad \text { where } \quad C=2 \pi d\left(\int_{0}^{2 \pi} \rho^{-2}\right)^{-1}
$$

from which (2.8) follows. Notice that since $\rho \geq \frac{1}{2}$, for each $r \in[1,2]$

$$
2 \pi^{2} \frac{d^{2}}{r^{2}}\left(\int_{0}^{2 \pi} \rho^{-2}\right)^{-1}+\int_{0}^{2 \pi} \frac{\left(1-\rho^{2}\right)^{2}}{4 \varepsilon^{2}}=2 \pi^{2} \frac{d^{2}}{r^{2}}\left(\int_{0}^{2 \pi} S(\rho)\right)^{-1}+\int_{0}^{2 \pi} \frac{B(\rho)}{4 \varepsilon^{2}}
$$

where $S$ is a smooth function with uniformly bounded derivatives at all orders which coincide with $\rho^{-2}$ on the interval $[2 / 3,+\infty)$, and $B$ is a strictly convex smooth function which coincides with $\left(1-\rho^{2}\right)^{2}$ on $[2 / 3,+\infty)$ and which satisfies the growth condition $B(\rho) \leq C\left(1+\rho^{4}\right)$. For $\varepsilon$ sufficiently small, the functional

$$
I(\rho)=2 \pi^{2} \frac{d^{2}}{r^{2}}\left(\int_{0}^{2 \pi} S(\rho)\right)^{-1}+\int_{0}^{2 \pi} \frac{B(\rho)}{4 \varepsilon^{2}}
$$

is well-defined, smooth and strictly convex on $L^{4}([0,2 \pi])$. It possesses therefore a unique critical point over the affine space defined by the constraint (2.6). Since the constant function $\rho(r \exp (i \theta)) \equiv m(r)$ is clearly such a critical point, it is also the unique minimizer and we are lead to improve (2.8) by

$$
\begin{equation*}
\int_{A} \frac{\rho^{2}|\nabla \varphi|^{2}}{2}+\frac{\left(1-\rho^{2}\right)^{2}}{4 \varepsilon^{2}} \geq \int_{1}^{2} \pi\left[m(r)^{2} \frac{d^{2}}{r^{2}}+\frac{\left(1-m(r)^{2}\right)^{2}}{2 \varepsilon^{2}}\right] r d r \tag{2.9}
\end{equation*}
$$

Combining (2.7) and (2.9) we obtain

$$
E_{\varepsilon}\left(V_{d}\right) \geq E_{\varepsilon}\left(W_{d}\right)
$$

from which the claim follows since all the previous inequalities are strict unless $V_{d}$ is equivariant.
Proof of Lemma 2.1 completed. Since $V_{d}=W_{d}$ up to a constant phase shift, we have $\rho(r \exp (i \theta))=m(r)$. On the other hand, $m(r)$ solves the ordinary differential equation

$$
-m^{\prime \prime}(r)-\frac{1}{r} m^{\prime}(r)+\frac{d^{2}}{r^{2}} m(r)+\frac{1}{\varepsilon^{2}}\left(m(r)^{2}-1\right) m(r)=0 \quad \text { on }[1,2]
$$

with Neumann boundary condition. Since the constant functions $r \mapsto 1$ and $r \mapsto \sqrt{1-\varepsilon^{2} d^{2}}$ are respectively upper and lower solutions of the same equation, we infer from the maximum principle that

$$
1-\varepsilon^{2} d^{2} \leq m(r)^{2} \leq 1 \quad \forall r \in[1,2]
$$

from which (2.3) follows, noticing that $\left|e_{\varepsilon}\left(U_{d}\right)-e_{\varepsilon}\left(W_{d}\right)\right| \leq C\left[\left(1-m(r)^{2}\right)+\right.$ $\left.\left(1-m(r)^{2}\right)^{2} / \varepsilon^{2}\right]$ pointwise on $A$.

## 3. Energy at infinity and topological sectors

We use Theorem 2.1 next to define the smallest radius from which the degree (at infinity) is well defined and constant, even for functions whose zero set is unbounded. For that purpose, given $\Lambda>\Lambda_{d}:=2 \pi d^{2} \log 2$ we set

$$
S_{d}=S_{d, \varepsilon_{\Lambda}}^{\Lambda}
$$

An easy consequence of the definition of $\left[U_{d}\right]$ and (2.2) is
Corollary 3.1. Let $d \in \mathbb{Z}, \Lambda>\Lambda_{d}$ and $u \in\left[U_{d}\right]+H^{1}\left(\mathbb{R}^{2}\right)$. There exists an integer $n \in \mathbb{N}^{*}$, such that for any $k \geq n$, the function defined on the reference annulus $A$ by $z \mapsto u\left(2^{k} z\right)$, belongs to the topological sector $S_{d}$.

This leads us to
Definition 2. For $u \in\left[U_{d}\right]+H^{1}\left(\mathbb{R}^{2}\right)$, $n(u)$ is the smallest integer such that for $k \geq n(u)$ the function defined on the reference annulus $A$ by $z \mapsto$ $u\left(2^{k} z\right)$, belongs to the topological sector $S_{d}$. This integer is finite in view of Corollary 3.1.

We would like to emphasize that our definition of $n(u)$ does not depend on $\varepsilon$. By scaling and summation over the annuli $A_{n}=B\left(2^{n+1}\right) \backslash B\left(2^{n}\right)$ we infer from Lemma 2.1

Lemma 3.1. Let $d \in \mathbb{Z}$, and $u \in\left[U_{d}\right]+H^{1}\left(\mathbb{R}^{2}\right)$. Then, for any $k \geq n(u)$, we have, for every $0<\varepsilon<\varepsilon_{\Lambda}$

$$
\begin{equation*}
\int_{A^{k}}\left[e_{\varepsilon}(u)-\frac{\left|\nabla U_{d}\right|^{2}}{2}\right] \geq-C 2^{-2 k} \varepsilon^{2} \tag{3.1}
\end{equation*}
$$

It follows in particular that

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} \int_{B(R) \backslash B\left(2^{k}\right)}\left[e_{\varepsilon}(u)-\frac{\left|\nabla U_{d}\right|^{2}}{2}\right] \geq-C 2^{-2 k} \varepsilon^{2} \tag{3.2}
\end{equation*}
$$

and therefore

$$
\begin{equation*}
\mathcal{E}_{\varepsilon, U_{d}}(u) \geq-C 2^{-2 n(u)} \varepsilon^{2}-\int_{B\left(2^{n(u)}\right)} \frac{\left|\nabla U_{d}\right|^{2}}{2} \tag{3.3}
\end{equation*}
$$

Proof. By definition of $n(u)$, for $k \geq n(u)$ the map $T_{k}(u): A \rightarrow \mathbb{C}$, $z \mapsto u\left(2^{k} z\right)$ belongs to $S_{d}$, so that in view of Lemma 2.1 we have for every $0<\tilde{\varepsilon}<1$

$$
\begin{equation*}
\pi d^{2} \log 2 \leq E_{\tilde{\varepsilon}}\left(T_{k} u, A\right)+c \tilde{\varepsilon}^{2} \tag{3.4}
\end{equation*}
$$

On the other hand, by scaling we derive the identity

$$
E_{\varepsilon}(u, A)=E_{2-k_{\varepsilon}}\left(T_{k} u, A\right)
$$

whereas a direct compution shows that

$$
\int_{A^{k}} \frac{\left|\nabla U_{d}\right|^{2}}{2}=\pi d^{2} \log 2
$$

Choosing $\tilde{\varepsilon}=2^{-k} \varepsilon$ in (3.4) inequality (3.1) follows. Inequality (3.2) is obtained by summation of (3.1), for $k \geq n$. Finally, inequality (3.3) follows from (3.2) and (1.5).

Inequality (3.2) expresses the almost minimizing properties of $U_{d}$ at infinity. Taking into account the fact that $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)$ is very close to $U_{d}$ at infinity, we infer

Lemma 3.2. Let $d \in \mathbb{Z}, u \in\left[U_{d}\right]+H^{1}\left(\mathbb{R}^{2}\right), a_{1}, \ldots, a_{l} \in \mathbb{R}^{2}$ and $d_{1}, \ldots, d_{l} \in \mathbb{Z}^{*}$ such that $\sum d_{i}=d$. Then, for $k \geq 1+\max \left\{\log _{2}\left|a_{1}\right|, \ldots, \log _{2}\left|a_{l}\right|, n(u)\right\}$ and $R=2^{k}$ we have

$$
\begin{equation*}
\int_{B(R)} e_{\varepsilon}(u)-e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right) \leq \mathcal{E}_{\varepsilon, U_{d}}(u)-\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)+\frac{C}{R} \tag{3.5}
\end{equation*}
$$

where $C$ depends only on $l$ and $d$.
Proof. In view of (1.5), we have

$$
\begin{align*}
\int_{B(R)} e_{\varepsilon}\left(u_{\varepsilon}\right)- & e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)-\left[\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}\right)-\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)\right]  \tag{3.6}\\
= & \lim _{R^{\prime} \rightarrow+\infty}
\end{align*} \int_{B\left(R^{\prime}\right) \backslash B(R)}\left[e_{\varepsilon}\left(u_{\varepsilon}\right)-\frac{\left|\nabla U_{d}\right|^{2}}{2}\right] .
$$

It follows from (3.2) that the first limit in (3.6) is bounded from below by $-C R^{-2} \varepsilon^{2}$. For the second limit, we first infer from the explicit form of $u_{\varepsilon}^{*}$ and the know facts (see e.g. [12])

$$
f_{\varepsilon, d}=1+O\left(\left(\frac{\varepsilon}{|z|}\right)^{2}\right) \quad \text { and } \quad\left|\nabla f_{\varepsilon, d}\right|=O\left(\left(\frac{\varepsilon}{|z|}\right)^{3}\right)
$$

that for $|z| \geq R$,

$$
\begin{equation*}
\left|e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)(z)-\left|\nabla U_{d}\right|^{2}(z)\right| \leq \frac{C}{|z|^{3}}, \tag{3.7}
\end{equation*}
$$

where $C$ depends only on $d$. Integrating (3.7) on $B\left(R^{\prime}\right) \backslash B(R)$ yields the conclusion (3.5).

Notice in particular that, if the family $\left\{u_{\varepsilon}\right\}_{0<\varepsilon<1}$ is well-prepared with respect to the configuration $\left(a_{i}, d_{i}\right)$, and if the sequence $\left\{n\left(u_{\varepsilon}\right)\right\}_{0<\varepsilon<1}$ is bounded by a constant $k$ (which we will prove always holds) then for $R \geq 2^{k+1}$

$$
\int_{B(R)} e_{\varepsilon}\left(u_{\varepsilon}\right) \leq \int_{B(R)} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)+\frac{C}{R}+o(1) \quad \text { as } \varepsilon \rightarrow 0
$$

and we may then rely on the coercivity results on $B(R)$ proved in $[8,11]$ to show that $u_{\varepsilon}$ is sufficiently close to $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)$.

To finish this section, we provide a proof of (1.5)
Lemma 3.3. Let $U \in \mathcal{V}_{*}$ and $u \in\{U\}+H^{1}\left(\mathbb{R}^{2}\right)$. Then

$$
\mathcal{E}_{\varepsilon, U}(u)=\lim _{R \rightarrow \infty} \int_{B(R)}\left[e_{\varepsilon}(u)-\frac{|\nabla U|^{2}}{2}\right] .
$$

Proof. Writing $u=U+v$ where $v \in H^{1}\left(\mathbb{R}^{2}\right)$, we have by definition (1.4) and the continuity of integration

$$
\mathcal{E}_{\varepsilon, U}(u)=\lim _{R \rightarrow+\infty} \int_{B(R)} \frac{|\nabla v|^{2}}{2}-(\Delta U) \cdot v+\int_{\mathbb{R}^{2}} \frac{\left(|u|^{2}-1\right)^{2}}{4 \varepsilon^{2}} .
$$

By integration by parts
$\int_{B(R)} \frac{|\nabla v|^{2}}{2}-(\Delta U) \cdot v+\int_{\mathbb{R}^{2}} \frac{\left(|u|^{2}-1\right)^{2}}{4 \varepsilon^{2}}=\int_{B(R)} e_{\varepsilon}(u)-\frac{|\nabla U|^{2}}{2}-\int_{\partial B(R)} \frac{\partial U}{\partial r} v$.
We claim that

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} \int_{\partial B(R)} \frac{\partial U}{\partial r} v=0 \tag{3.8}
\end{equation*}
$$

To establish the claim (3.8) it suffices in view of the assumption $|\nabla U(z)| \leq$ $C / \sqrt{|z|}$ and Cauchy-Schwarz inequality to establish that

$$
\begin{equation*}
\lim _{R \rightarrow+\infty} \int_{\partial B(R)}|v|^{2}=0 \tag{3.9}
\end{equation*}
$$

This follows from the next lemma and the inclusion $W^{1,1}(\mathbb{R})$ into $\mathcal{C}_{0}(\mathbb{R})$.
Lemma 3.4. For $v \in H^{1}\left(\mathbb{R}^{2}\right)$, the function $f:[1,+\infty) \rightarrow \mathbb{R}$ defined by $f(r)=\int_{\partial B(r)}|v|^{2}$ belongs to $W^{1,1}([1,+\infty))$.
Proof. We write

$$
f(r)=r \int_{\partial B(1)}|v|^{2}(r y) d y
$$

so that

$$
\begin{aligned}
f^{\prime}(r) & =\int_{\partial B(1)}|v|^{2}(r y) d y+2 r \int_{\partial B(1)} v(r y) \frac{\partial v}{\partial r}(r y) d y \\
& =\frac{1}{r} \int_{\partial B(r)}|v|^{2}(y) d y+2 \int_{\partial B(r)} v(y) \frac{\partial v}{\partial r}(y) d y
\end{aligned}
$$

Hence

$$
\left|f^{\prime}(r)\right| \leq\left(1+\frac{1}{r}\right) \int_{\partial B(r)}|v|^{2}(y) d y+\int_{\partial B(r)}|\nabla v|^{2}(y) d y
$$

and the conclusion follows by integration.

## 4. Some properties of $u_{\varepsilon}^{*}$

In this Section we present some properties of the reference maps $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)$, where $a_{1}, \ldots, a_{l}$ are $l$ distinct points in $\mathbb{R}^{2}$, and $d_{1}, . ., d_{l}$ are $l$ integers in $\mathbb{Z}^{\star}$. We set $d=\sum_{i=1}^{l} d_{i}$. We consider also the limiting map $u_{0}^{*} \equiv u^{*}$ given by

$$
u^{*}\left(a_{i}, d_{i}\right)=\prod_{i=1}^{l}\left(\frac{z-a_{i}}{\left|z-a_{i}\right|}\right)^{d_{i}} .
$$

We recall that (see e.g. [3])

$$
\begin{equation*}
\left|\nabla u^{*}\right|=\left|\nabla \psi^{*}\right|, \quad \text { where } \quad \psi^{*}=\psi^{*}\left(a_{i}, d_{i}\right) \equiv \sum_{i=i}^{l} \log \left|z-a_{i}\right|, \tag{4.1}
\end{equation*}
$$

in particular, the real-valued function $\psi^{*}\left(a_{i}, d_{i}\right)$ satisfies the equation

$$
\begin{equation*}
\Delta \psi^{*}\left(a_{i}, d_{i}\right)=2 \pi \sum_{i=i}^{l} d_{i} \delta_{a_{i}} \quad \text { on } \mathbb{R}^{2} \tag{4.2}
\end{equation*}
$$

For $R \geq R_{a}:=2 \max _{i}\left\{\left|a_{i}\right|\right\}$ and $r \leq r_{a}:=\frac{1}{8} \min _{i \neq j}\left\{\left|a_{i}-a_{j}\right|\right\}$, we introduce the domain

$$
\Omega_{R, r}=B(R) \backslash \bigcup_{i=1}^{l} B\left(a_{i}, r\right)
$$

We first have
Lemma 4.1. As $R \rightarrow+\infty$,

$$
\begin{align*}
\int_{\Omega_{R, r}} \frac{\left|\nabla u^{*}\left(a_{i}, d_{i}\right)\right|^{2}}{2}=-\pi \sum_{i=1}^{l} d_{i}^{2} \log r-\pi \sum_{i \neq j} & d_{i} d_{j} \log \left|a_{i}-a_{j}\right|  \tag{4.3}\\
& +\pi d^{2} \log R+O\left(\frac{R_{a}}{R}\right)
\end{align*}
$$

whereas for $0<\varepsilon<1$,

$$
\begin{equation*}
\int_{\mathbb{R}^{2} \backslash \cup_{i=1}^{l} B\left(a_{i}, r\right)}\left|e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)-\frac{\left|\nabla u^{*}\left(a_{i}, d_{i}\right)\right|^{2}}{2}\right| \leq C\left(\frac{\varepsilon}{r}\right)^{2}, \tag{4.4}
\end{equation*}
$$

the constant $C$ depending only on $l$ and $\max _{i}\left(\left|d_{i}\right|\right)$.
Proof. The proof of identity (4.3) is classical (see e.g. [3]). It relies first on the identity (4.1), so that we may replace the integrand on the r.h.s of (4.3) by $\left|\nabla \psi^{*}\left(a_{i}, d_{i}\right)\right|^{2}$. To derive the result, one then uses equation (4.2) and integrations by parts, with suitable estimates for the boundary terms. For the proof of (4.4) one uses the aforementioned estimates for $f_{\varepsilon, d}$.

Concerning the energy near the core, we have
Lemma 4.2. Let $0<\varepsilon<1$. The following expansion holds for $j=1, \ldots$, l,

$$
\begin{equation*}
\int_{B\left(a_{j}, r\right)} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)=\pi d_{j}^{2} \log \frac{\varepsilon}{r}+\gamma\left(\left|d_{j}\right|\right)+O\left(\frac{r}{r_{a}}\right)^{2}+O\left(\frac{\varepsilon}{r}\right)^{2} . \tag{4.5}
\end{equation*}
$$

We omit the proof. Here $\gamma$ denotes a fixed function $\gamma: \mathbb{N} \rightarrow \mathbb{R}^{+}$whose values are given by (1.11). We are now in position to assert

Proposition 4.1. Let $0<\alpha<1$ be given. Let $0<\varepsilon<1$ be such that

$$
\begin{equation*}
r_{a}=\frac{1}{8} \min _{i \neq j}\left\{\left|a_{i}-a_{j}\right|\right\} \geq \varepsilon^{\alpha} . \tag{4.6}
\end{equation*}
$$

Then, for $R>R_{a}+1$, we have

$$
\begin{align*}
\int_{B(R)} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)= & \pi \sum_{i=1}^{l} d_{i}^{2}|\log \varepsilon|-\pi \sum_{i \neq j} d_{i} d_{j} \log \left|a_{i}-a_{j}\right|  \tag{4.7}\\
& +\sum_{i=1}^{l} \gamma\left(\left|d_{i}\right|\right)+\pi d^{2} \log R+O\left(\frac{R_{a}}{R}\right)+r_{\varepsilon}
\end{align*}
$$

where the remainder term $r_{\varepsilon}$ satisfies, for some constant $C_{\alpha}$ depending only on $\alpha, l$ and $\max _{i}\left|d_{i}\right|$,

$$
\begin{equation*}
r_{\varepsilon} \leq C_{\alpha} \varepsilon^{1-\alpha} \tag{4.8}
\end{equation*}
$$

Proof. We write

$$
\int_{B(R)} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)=\int_{\Omega_{R, r}} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)+\sum_{j=1}^{l} \int_{B\left(a_{j}, r\right)} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right) .
$$

It follows therefore from (4.3), (4.4) and (4.5) that

$$
\begin{aligned}
& \int_{B(R)} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)=\pi \sum_{i=1}^{l} d_{i}^{2}|\log \varepsilon|+W\left(a_{i}, d_{i}\right)+\pi d^{2} \log R+ \\
& O\left(\frac{R_{a}}{R}\right)+O\left(\frac{\varepsilon}{r}\right)^{2}+O\left(\frac{r}{r_{a}}\right)^{2} .
\end{aligned}
$$

Choosing $r$ such that $\frac{\varepsilon}{r}=\frac{r}{r_{a}}$, we obtain the conclusion (4.7) with the estimate (4.8), taking into account (4.6).

Proposition 4.1 has the following consequence for the renormalized energy Corollary 4.1. Let $0<\alpha<1$ be given and let $0<\varepsilon<1$ be such that the condition (4.6) holds. Then, we have

$$
\begin{align*}
\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right)= & \pi \sum_{i=1}^{l} d_{i}^{2}|\log \varepsilon|+W\left(a_{i}, d_{i}\right)+\sum_{i=1}^{l} \gamma\left(\left|d_{i}\right|\right)  \tag{4.9}\\
& +\int_{B(1)} \frac{\left|\nabla U_{d}\right|^{2}}{2}+r_{\varepsilon},
\end{align*}
$$

where $d=\sum_{i=1}^{l} d_{i}$ and the remainder term $r_{\varepsilon}$ satisfies the bound (4.8).
On exterior domains, similar computations yield
Lemma 4.3. For $R>R_{a}$ we have

$$
\left|\int_{B(2 R) \backslash B(R)} e_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)-\pi d^{2} \log 2\right| \leq C \frac{R_{a}}{R} .
$$

We finish this section with the following elementary observations. First we have
Lemma 4.4. Let $\left\{\left(a_{i}, d_{i}\right)\right\}_{i=1, \ldots, l}$ and $\left\{\left(a_{i}^{\prime}, d_{i}^{\prime}\right)\right\}_{i=1, \ldots, l^{\prime}}$ be two vortex configurations. For every $0 \leq \varepsilon<1$ the difference $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)-u_{\varepsilon}^{*}\left(a_{i}^{\prime}, d_{i}^{\prime}\right)$ belongs to $L^{2}\left(\mathbb{R}^{2}\right)$ if and only if

$$
\begin{equation*}
\sum_{i=1}^{l} d_{i}=\sum_{i=1}^{l^{\prime}} d_{i}^{\prime} \quad \text { and } \quad \sum_{i=1}^{l} d_{i} a_{i}=\sum_{i=1}^{l^{\prime}} d_{i}^{\prime} a_{i}^{\prime} \tag{4.10}
\end{equation*}
$$

In particular, for $0<\varepsilon<1$ the map $u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)$ belongs to $\left\{u_{\varepsilon}^{*}\left(a_{i}^{\prime}, d_{i}^{\prime}\right)\right\}+H^{1}\left(\mathbb{R}^{2}\right)$ if and only if condition (4.10) is satisfied.
Proof. For a given vortex configuration $\left\{\left(a_{i}, d_{i}\right)\right\}_{i=1, \ldots, l}$ we write for $i=$ $1, \ldots, l$,

$$
\left(\frac{z-a_{i}}{\left|z-a_{i}\right|}\right)^{d_{i}}=\left(\frac{z}{|z|}\right)^{d_{i}}\left(\frac{1-\frac{a_{i}}{z}}{\left|1-\frac{a_{i}}{z}\right|}\right)^{d_{i}} .
$$

Expanding for $|z| \rightarrow \infty$, we have

$$
\begin{aligned}
\left(\frac{1-\frac{a_{i}}{z}}{\left|1-\frac{a_{i}}{z}\right|}\right)^{d_{i}} & =\left(1-\frac{d_{i} a_{i}}{z}+O\left(\frac{1}{z^{2}}\right)\right)\left(1+\operatorname{Re} \frac{d_{i} a_{i}}{z}+O\left(\frac{1}{z^{2}}\right)\right) \\
& =1-\operatorname{Im} \frac{d_{i} a_{i}}{z}+O\left(\frac{1}{z^{2}}\right),
\end{aligned}
$$

so that

$$
u^{*}\left(a_{i}, d_{i}\right)=\left(\frac{z}{|z|}\right)^{d}-\left(\frac{z}{|z|}\right)^{d}\left(\operatorname{Im} \sum_{i=1, \ldots, l}^{l} \frac{d_{i} a_{i}}{z}+O\left(\frac{1}{z^{2}}\right)\right)
$$

In particular $u^{*}\left(a_{i}, d_{i}\right)-u^{*}\left(0, d^{\prime}\right)$ belongs to $L^{2}\left(\mathbb{R}^{2}\right)$ if and only if $d=d^{\prime}$ and $\sum_{i=1}^{l} d_{i} a_{i}=0$. The conclusion follows for $\varepsilon=0$ translating the origin. For the general case $0<\varepsilon<1$, one observes that, since $1-f_{\varepsilon, d}$ belongs to $L^{2}\left(\mathbb{R}^{2}\right)$, the difference

$$
u^{*}\left(a_{i}, d_{i}\right)-u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)=\left(1-\prod_{i=1}^{l} f_{\varepsilon, d_{i}}\left(\left|z-a_{i}\right|\right)\right) u^{*}\left(a_{i}, d_{i}\right)
$$

belongs to $L^{2}\left(\mathbb{R}^{2}\right)$.
Next, we have
Lemma 4.5. The renormalized energy $\mathcal{E}_{d, U_{d}}$ is bounded from below if and only if $|d| \leq 1$.

Proof. Assume $d \geq 2$. We consider the configuration of two vortices $\left\{a_{i}^{n}, d_{i}\right\}$ given by $a_{1}^{n}=(0,0), d_{1}=1, a_{2}^{n}=(n, 0), d_{2}=d-1>0$. We deduce from (4.9) that $\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right)$ behaves like $-\log n$ as $n \rightarrow+\infty$, and hence the conclusion.

When $d=1$, the conclusion follows from the locally minimizing properties of $u_{1}^{*}$ established by Mironescu [14].

When $d=0$ the renormalized energy is defined by integration of a pointwise non negative function.

## 5. Kirchhoff-Onsager functional and the renormalized energy

Proposition 4.1 shows that, removing the diverging and constant part of the energy, the Kirchhoff-Onsager functional is the next important part of the expansion in (4.7). In order to bridge our work with coercivity properties derived on bounded domains in $[8,11]$ we need to compare the KirchhoffOnsager functional with the renormalized energy considered there. For that purpose, let $\Omega$ be a bounded simply connected domain in $\mathbb{R}^{2}$ with $\mathcal{C}^{1}$ boundary, and let $G\left(a_{i}, d_{i}\right)$ be the function defined on $\Omega$ by

$$
\Delta G\left(a_{i}, d_{i}\right)=2 \pi \sum_{i=1}^{l} d_{i} \delta_{a_{i}} \text { in } \Omega, \quad G \equiv 0 \text { on } \partial \Omega .
$$

Let also $H(\cdot, y)$, for $y \in \Omega$, denote the solution of

$$
\Delta_{x} H(\cdot, y)=0 \text { in } \Omega, \quad H(x, y)=-\log |x-y| \text { for } x \in \partial \Omega .
$$

Then, for $x \in \Omega$,

$$
G\left(a_{i}, d_{i}\right)(x)=\sum_{i=1}^{l} d_{i}\left[\log \left|x-a_{i}\right|+H\left(x, a_{i}\right)\right] .
$$

The renormalized energy $W_{\Omega}\left(a_{i}, d_{i}\right)$ is defined to be

$$
\begin{equation*}
W_{\Omega}\left(a_{i}, d_{i}\right)=-\pi\left(\sum_{i \neq j} d_{i} d_{j} \log \left|a_{i}-a_{j}\right|+\sum_{i, j} d_{i} d_{j} H\left(a_{i}, a_{j}\right)\right) \tag{5.1}
\end{equation*}
$$

We next specify the domain $\Omega$ to the case $\Omega=B(R)$ and set $W_{R} \equiv W_{B(0, R)}$.
Proposition 5.1. Let $\left\{a_{i}, d_{i}\right\}_{i=1, \ldots, l}$ be a configuration of vortices and set $R_{a}=2 \max \left\{\left|a_{i}\right|\right\}$. Then, for $R>R_{a}+1$, we have

$$
\begin{equation*}
W_{R}\left(a_{i}, d_{i}\right)=W\left(a_{i}, d_{i}\right)+\pi d^{2} \log R+O\left(\frac{R_{a}}{R}\right) \tag{5.2}
\end{equation*}
$$

where $d=\sum_{i=1}^{l} d_{i}$.
Proof. In view of (5.1) we have

$$
W_{R}\left(a_{i}, d_{i}\right)-W\left(a_{i}, d_{i}\right)=-\pi \sum_{i, j} d_{i} d_{j} H\left(a_{i}, a_{j}\right)
$$

Since $H$ is harmonic in each of its variables and for each $j$

$$
H\left(\cdot, a_{j}\right)=-\log R+O\left(\frac{R_{a}}{R}\right)
$$

on the boundary of $\Omega$, we obtain

$$
\sum_{i, j} d_{i} d_{j} H\left(a_{i}, a_{j}\right)=-\sum_{i, j} d_{i} d_{j} \log R+O\left(\frac{R_{a}}{R}\right)
$$

and the conclusion follows from the identity $\sum_{i, j} d_{i} d_{j}=d^{2}$. (In fact we give an explicit formula for $H\left(x, a_{i}\right)$ below.)

Finally, we also recall the canonical harmonic map $u_{\Omega}^{*}$ on a bounded domain $\Omega$, with vortices $\left(a_{i}, d_{i}\right)$ and Neumann boundary conditions. This is characterized (up to a constant phase) by the fact that

$$
j u_{\Omega}^{*}=\sum_{i=1}^{\ell} d_{i} \nabla \times\left[\log \left|x-a_{i}\right|+H\left(x, a_{i}\right)\right]
$$

for $G$ as defined above, depending on $\Omega$. When $\Omega=B(R)$ we wil write $u_{R}^{*}$. Similar to the previous proposition, we have

Proposition 5.2. Let $\left\{a_{i}, d_{i}\right\}, R_{a}, R$ be as in Proposition 5.1. Then

$$
\begin{equation*}
\left|j u_{R}^{*}\left(x ; a_{i}, d_{i}\right)-j u^{*}\left(x ; a_{i}, d_{i}\right)\right|=O\left(\frac{R_{a}}{R^{2}}\right) . \tag{5.3}
\end{equation*}
$$

for all $x \in B(R)$.
Proof. It is a classical fact that $H(x, y)=-\log \left(\frac{|y|}{R}\left|x-\frac{y R^{2}}{|y|^{2}}\right|\right)$ as long as $y \neq 0$, and that $H(x, 0)=-\log R$. Thus

$$
\left|j u_{R}^{*}\left(x ; a_{i}, d_{i}\right)-j u^{*}\left(x ; a_{i}, d_{i}\right)\right| \leq \sum_{i=1}^{\ell}\left|\nabla \times H\left(x, a_{i}\right)\right|=\sum_{i=1}^{\ell}\left|x-\frac{a_{i} R^{2}}{\left|a_{i}\right|^{2}}\right|^{-1}
$$

If $a_{i}=0$ for some $i$, the corresponding term in the sum is of course replaced by 0 . It is now easy to deduce the conclusion, since $|x|<R^{2} / R_{a}$ in $B_{R}$, and $\left|\frac{a_{i} R^{2}}{\left|a_{i}\right|^{2}}\right| \geq 2 R^{2} / R_{a}$ for all $i$.

## 6. Coercivity for $\mathcal{E}_{\varepsilon, U_{d}}$

In this Section, we adapt to our setting coercivity results established in $[8,11]$. To that purpose, for a given configuration of vortices $\left\{a_{i}, d_{i}\right\}_{i=1, \ldots, l}$ and $u \in\left[U_{d}\right]+H^{1}\left(\mathbb{R}^{2}\right)$ where $d=\sum d_{i}$, the excess energy is defined as

$$
\Sigma_{\varepsilon} \equiv \Sigma_{\varepsilon}\left(u, a_{i}, d_{i}\right)=\mathcal{E}_{\varepsilon, U_{d}}(u)-\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right) .
$$

We also set

$$
r_{a}=\frac{1}{8} \min \left\{\left|a_{i}-a_{j}\right|, i \neq i\right\} \quad \text { and } \quad R_{a}=\max \left\{\left|a_{i}\right|\right\}
$$

We have
Theorem 6.1. Assume that $d_{i} \in\{-1,+1\}$ for all $i$, and let $r \leq r_{a}$ and $R>R_{a}$ be given. There exist constants $\varepsilon_{0}>0$ and $\eta_{0}>0$ (depending only on $\left.l, r, r_{a}, R_{a}, R\right)$ such that if $\varepsilon \leq \varepsilon_{0}$,

$$
\begin{equation*}
\eta \equiv\left\|J u-\pi \sum d_{i} \delta_{a_{i}}\right\|_{\left[W_{0}^{1, \infty}(B(R))\right]^{*}} \leq \eta_{0} \tag{6.1}
\end{equation*}
$$

and

$$
\begin{equation*}
2^{n(u)} \leq R, \tag{6.2}
\end{equation*}
$$

then

$$
\begin{equation*}
\int_{B(R) \backslash \cup B\left(a_{i}, r\right)} e_{\varepsilon}(|u|)+\frac{1}{8}\left|\frac{j(u)}{|u|}-j\left(u^{*}\left(a_{i}, d_{i}\right)\right)\right|^{2} \leq \Sigma_{\varepsilon}+C\left(\eta, \varepsilon, \frac{1}{R}\right) \tag{6.3}
\end{equation*}
$$

where $C$ is a continuous function which vanishes at the origin. Moreover, there exist points $b_{i} \in B\left(a_{i}, r / 2\right)$ such that

$$
\begin{equation*}
\left\|J u-\pi \sum d_{i} \delta_{b_{i}}\right\|_{\left[W_{0}^{1, \infty}(B(R))\right]^{*}} \leq D\left(R, \Sigma_{\varepsilon}\right) \varepsilon|\log \varepsilon| \tag{6.4}
\end{equation*}
$$

where $D$ is a continuous function on $\mathbb{R}^{2}$.
Condition (6.1) suggests that the vortex structure of $u$ inside $B(R)$ is sufficiently well approximated by the configuration $\left(a_{i}, d_{i}\right)$, and condition (6.2) ensures that no vortex of $u$ is hidden far away. Under those assumptions, the conclusion (6.3) asserts that the deviation of $u$ from the canonical map $u^{*}\left(a_{i}, d_{i}\right)$ is controlled by the excess $\Sigma_{\varepsilon}$ away from the vortices.

For sake of conciseness we will not present a self-contained proof Theorem 6.1 but instead rely on Theorem 2 in [11], which we use as a black box.
Proof of Theorem 6.1. First notice that there exists $\varepsilon_{2}>0$ such that if $\varepsilon<\varepsilon_{2}$ and $\varepsilon E_{\varepsilon}(u, B(R))>\sqrt{\varepsilon}$ then (6.3) trivially holds. Indeed, since $E_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right) \leq C|\log \varepsilon|+\log R$, for $\varepsilon$ small enough one even has $\frac{1}{2} E_{\varepsilon}(u) \leq \Sigma_{\varepsilon}$ so that (6.3) holds with $C=0$. In the sequel, we assume that $\varepsilon \leq \varepsilon_{2}$ and $\varepsilon E_{\varepsilon}(u, B(R)) \leq \sqrt{\varepsilon}$.

Let $K_{1}$ be the constant given by Theorem 2 in [11]. We choose $0<\varepsilon_{1} \leq \varepsilon_{2}$ and $\eta_{0}$ sufficiently small so that

$$
\begin{equation*}
4 x \leq \frac{r_{a}}{l^{3}} \sqrt{x} \quad \forall x \in\left[0, \eta_{0}\right] \quad \text { and } \quad \frac{r_{a}}{l^{3}} \sqrt{\eta_{0}+\sqrt{\varepsilon_{1}}} \leq \min \left(r, \frac{r_{a}}{l K_{1}}\right) . \tag{6.5}
\end{equation*}
$$

Finally, we choose $0<\varepsilon_{0} \leq \varepsilon_{1}$ sufficiently small so that

$$
\varepsilon_{0} \sqrt{\log \left(\frac{r_{a}}{l K_{1}}\right)} \leq \eta_{0}
$$

Assume that $u$ is such that (6.1) is satisfied. We distinguish two cases.
Case 1: $\varepsilon \sqrt{\log \left(\frac{r_{\alpha}}{\varepsilon}\right)} \leq \eta$. In that case, we will apply Theorem 2 in [11] with the choice $s_{\varepsilon}=\eta$. From (6.5) and the fact that $\varepsilon \leq \varepsilon_{2}$ we infer that $4 s_{\varepsilon} \leq \sigma^{*} \equiv \sqrt{\frac{T_{a}}{13}\left(s_{\varepsilon}+\varepsilon E_{\varepsilon}(u, B(R))\right)} \leq \frac{r_{a}}{l K_{1}}$ and therefore the conditions of Theorem 2 in [11] are satisfied and we get

$$
\begin{align*}
& \int_{B(R) \backslash \cup B\left(a_{i}, \sigma^{*}\right)} e_{\varepsilon}(|u|)+\frac{1}{4}\left|\frac{j(u)}{|u|}-j\left(u_{R}^{*}\left(a_{i}, d_{i}\right)\right)\right|^{2}  \tag{6.6}\\
& \quad \leq E_{\varepsilon}(u, B(R))-\pi l|\log \varepsilon|-l \gamma(1)-W_{R}\left(a_{i}, d_{i}\right)+C \sqrt{\frac{l^{5}}{r_{a}}(\eta+\sqrt{\varepsilon})}
\end{align*}
$$

where $C$ is universal.

By (6.5), $\sigma^{*} \leq r$ and we may therefore replace $\sigma^{*}$ by $r$ in (6.6). By (6.2) we may apply Lemma 3.2, and combining (3.5), (4.7) and (5.2) we obtain

$$
E_{\varepsilon}(u, B(R))-\pi l|\log \varepsilon|-l \gamma(1)-W_{R}\left(a_{i}, d_{i}\right) \leq \Sigma_{\varepsilon}+C\left(\frac{R_{a}}{R}+\sqrt{\varepsilon}\right) .
$$

Also, it follows from Proposition 5.2 that

$$
\left\|j u_{R}\left(a_{i}, d_{i}\right)-j u\left(a_{i}, d_{i}\right)\right\|_{L^{2}(B(R)}^{2} \leq C R_{a}^{2} / R^{2} \leq C R^{a} / R .
$$

Combining these estimates we find that

$$
\begin{aligned}
\left.\int_{B(R) \backslash \cup B\left(a_{i}, r\right)} e_{\varepsilon}(|u|)+\frac{1}{8} \right\rvert\, \frac{j(u)}{|u|} & -\left.j\left(u^{*}\left(a_{i}, d_{i}\right)\right)\right|^{2} \\
& \leq \Sigma_{\varepsilon}+C\left(\sqrt{\frac{l^{5}}{r_{a}}(\eta+\sqrt{\varepsilon})}+\frac{R_{a}}{R}+\sqrt{\varepsilon}\right) .
\end{aligned}
$$

Case 2: $\varepsilon \sqrt{\log \left(\frac{r_{a}}{\varepsilon}\right)}>\eta$. In that case, we apply Theorem 2 in [11] with the choice $s_{\varepsilon}=\varepsilon \sqrt{\log \left(\frac{r_{a}}{\varepsilon}\right)}$. This similarly leads to

$$
\begin{aligned}
& \int_{B(R) \backslash \cup B\left(a_{i}, r\right)} e_{\varepsilon}(|u|)+\frac{1}{8}\left|\frac{j(u)}{|u|}-j\left(u^{*}\left(a_{i}, d_{i}\right)\right)\right|^{2} \\
& \leq \Sigma_{\varepsilon}+C\left(\sqrt{\frac{l^{5}}{r_{a}} \varepsilon \log \left(\frac{r_{a}}{\varepsilon}\right)+\sqrt{\varepsilon}}+\frac{R_{a}}{R}+\sqrt{\varepsilon}\right) .
\end{aligned}
$$

The maximum between those two error terms may serve as a definition of the function $C$ which appears in (6.3). Without loss of generality, we may assume that $\eta_{0} \leq r_{a} /\left(8 K_{2} l^{5}\right)$, where $K_{2}$ is the constant appearing in [11, Theorem 3], so that the existence of the points $b_{i}$ and the estimate (6.4) follow by [11, Theorem 3].

## 7. Lipschitz continuity of vortex paths

The results in this section apply to initial data slightly more general than the one in Definition 1. More precisely, we keep assumptions (1.7) and (1.8), and we replace (1.9) by

$$
\begin{equation*}
\sup _{0<\varepsilon<1}\left[\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}\right)-\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{\star}\left(a_{i}, d_{i}\right)\right)\right] \leq K_{1} \tag{7.1}
\end{equation*}
$$

for some constant $K_{1}<+\infty$. Without loss of generality, we may assume, increasing possibly $K_{0}$, that $K_{0}>K_{1}+\pi d^{2} \log 2$.

The main result in this section is

Theorem 7.1. Let $\left(a_{i}^{0}, d_{i}\right)$ be a configuration of vortices such that $d_{i} \in$ $\{-1,+1\}$. Let $\left(u_{\varepsilon}^{0}\right)_{0<\varepsilon<1}$ satisfy (1.7),(1.8) and (7.1) with $u_{\varepsilon}^{0} \in\left[U_{d}\right]+H^{1}\left(\mathbb{R}^{2}\right)$ for all $0<\varepsilon<1$. There exist a time $T>0$, depending only on $K_{0}, K_{1}, r_{a}$ and $R$, a sequence $\varepsilon_{k} \rightarrow 0$, and Lipschitz paths $t \mapsto b_{i}(t)$ defined on $[0, T]$ such that $b_{i}(0)=a_{i}^{0}$ and

$$
\begin{equation*}
\sup _{t \in[0, T]}\left\|J u_{\varepsilon_{k}}(\cdot, t)-\pi \Sigma d_{i} \delta_{b_{i}(t)}\right\|_{\left[W_{0}^{1, \infty}(B(R))\right]^{*}} \rightarrow 0, \quad \text { as } k \rightarrow+\infty \tag{7.2}
\end{equation*}
$$

Moreover, there exist constants $C_{0}>0$ and $C_{1}>0$, depending only on $K_{0}$, $K_{1}, r_{a}$ and $R$, such that for all $t \in[0, T], n \geq n_{0}$ and $k \in \mathbb{N}$,

$$
\begin{equation*}
E_{\varepsilon_{k}}\left(u_{\varepsilon_{k}}(\cdot, t), A_{n}\right) \leq C_{0}, \tag{7.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathcal{E}_{\varepsilon_{k}, U_{d}}\left(u_{\varepsilon_{k}}(\cdot, t)\right)-\mathcal{E}_{\varepsilon_{k}, U_{d}}\left(u_{\varepsilon_{k}}^{*}\left(b_{i}(t), d_{i}\right)\right) \leq C_{1} . \tag{7.4}
\end{equation*}
$$

The proof relies on several arguments which we present separately.
Lemma 7.1. Assume $\Lambda>K_{0}$ and let $\left(u_{\varepsilon}^{0}\right)_{0<\varepsilon<1}$ be as in Theorem 7.1. Then, for $0<\varepsilon<\varepsilon_{\Lambda}$ and for $n \geq n_{0}$ we have $u_{\varepsilon}^{0}\left(2^{n}.\right) \in S_{d}=S_{d, \varepsilon_{\Lambda}}^{\Lambda}$.
Proof. By Corollary 3.1, $u_{\varepsilon}^{0}\left(2^{n}.\right) \in S_{d}$ for $n$ sufficiently large, say $n \geq n_{1}(\varepsilon)$, depending possibly on $\varepsilon$. Since by assumption $\Lambda>K_{0}$, for each $n \geq n_{0}$ the map $u_{\varepsilon}^{0}\left(2^{n}.\right)$ belongs to some $S_{d(n)}$. It remains to prove that $d(n) \equiv d$ for all $n \geq n_{0}$. Assume by contradiction that this does not hold, and let $N$ be the largest integer such that $d(N) \neq d$. Consider the mapping $p:[0,1] \rightarrow H^{1}(A)$ defined by $p(s)=u_{\varepsilon}^{0}\left(2^{N+s}.\right)$. We have $p(0) \in S_{d(N)}$ whereas $p(1) \in S_{d}$. It follows therefore by $(2.2)$ that there exists $s \in[0,1]$ such that $E_{\varepsilon}(p(s))>2 \Lambda$. In particular, this would imply

$$
E_{\varepsilon}\left(u_{\varepsilon}^{0}, A_{N} \cup A_{N+1}\right)>2 \Lambda>2 K_{0},
$$

a contradiction with assumption (1.8).
Throughout the rest of this paper, we assume

$$
\begin{equation*}
\Lambda>K_{0} \tag{7.5}
\end{equation*}
$$

The core argument (as in [8]) relies on the evolution equation (1.12) for the Jacobians.
Lemma 7.2. Let $\eta_{0}$ be given by Theorem 6.1 for the choice $r=r_{a}$, and let $T_{\varepsilon}$ be the largest time for which for all $0 \leq s \leq T_{\varepsilon}$

$$
\left\|J u_{\varepsilon}(\cdot, s)-\pi \sum d_{i} \delta_{a_{i}^{0}}\right\|_{\left[\mathcal{W}_{0}^{1, \infty}(B(R))\right]^{*}} \leq \eta_{0} \quad \text { and } \quad u_{\varepsilon}(\cdot, s) \in S_{d} \forall n \geq n_{0}
$$

Then we have

$$
\begin{equation*}
\liminf _{\varepsilon \rightarrow 0} T_{\varepsilon} \geq T\left(r_{a}, R, K_{0}, K_{1}\right)>0 \tag{7.6}
\end{equation*}
$$

Proof. First notice that since $u_{\varepsilon}(\cdot, t)-u_{\varepsilon}^{0}$ belongs to $\mathcal{C}\left(\mathbb{R}, H^{1}\left(\mathbb{R}^{2}\right)\right)$, the map $t \mapsto J u_{\varepsilon}(\cdot, t)$ is continuous with values in $L^{1}(B(R))$ and the maps $t \mapsto E_{\varepsilon}\left(u_{\varepsilon}(\cdot, t), A_{n}\right)$ are uniformly continuous with respect to $n \geq n_{0}$. This implies that

$$
T_{\varepsilon}>0 \quad \forall 0<\varepsilon<\varepsilon_{\Lambda} .
$$

Step 1. We have, for $s \in\left[0, T_{\varepsilon}\right]$

$$
E_{\varepsilon}\left(u_{\varepsilon}(\cdot, s), B(R)\right) \geq \pi l|\log \varepsilon|-C
$$

for some constant $C>0$ depending only on $r_{a}$ and $R$.
Proof. This directly follows from the positivity of $e_{\varepsilon}$ and the inequality

$$
\begin{equation*}
E_{\varepsilon}\left(u_{\varepsilon}(\cdot, s), B\left(a_{i}^{0}, r_{a}\right)\right) \geq \pi|\log \varepsilon|-C \tag{7.7}
\end{equation*}
$$

valid for any $i=1, \ldots, l$. This last inequality is itself a consequence of the bound $\left\|J u_{\varepsilon}(\cdot, s)-\pi d_{i} \delta_{a_{i}^{0}}\right\|_{\left[W_{0}^{1, \infty}\left(B\left(a_{i}^{0}, r_{a}\right)\right)\right]^{*}} \leq \eta_{0}$ and Theorem 3 in [10].
Step 2. There exists a constant $D>0$ such that for all $s \in\left[0, T_{\varepsilon}\right]$

$$
E_{\varepsilon}\left(u_{\varepsilon}(\cdot, s), A_{n}\right) \leq D, \quad \forall n \geq n_{0}
$$

Proof. We write the difference $E_{\varepsilon}\left(u_{\varepsilon}(\cdot, t), A_{n}\right)-E_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}^{0}, d_{i}\right), A_{n}\right)$ as

$$
\begin{align*}
& \sum_{k=n_{0}, k \neq n}^{+\infty}\left(E_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}^{0}, d_{i}\right), A_{k}\right)-E_{\varepsilon}\left(u_{\varepsilon}(\cdot, t), A_{k}\right)\right)  \tag{7.8}\\
&+E_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}^{0}, d_{i}\right), B(R)\right)-E_{\varepsilon}\left(u_{\varepsilon}(\cdot, t), B(R)\right) \\
&+\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}(\cdot, t)\right)-\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{*}\left(a_{i}^{0}, d_{i}\right)\right)
\end{align*}
$$

For the first term on the r.h.s of (7.8) we invoke Lemma 3.1 and Lemma 4.3 to assert that

$$
\begin{equation*}
\sum_{k=n_{0}, k \neq n}^{+\infty} E_{\varepsilon}\left(u_{\varepsilon}^{*}\left(a_{i}^{0}, d_{i}\right), A_{k}\right)-E_{\varepsilon}\left(u_{\varepsilon}(\cdot, t), A_{k}\right) \leq C_{1} . \tag{7.9}
\end{equation*}
$$

The second term is bounded thanks to Step 1, whereas the last one is bounded by conservation of $\mathcal{E}_{\varepsilon, U_{d}}$ and hypothesis (7.1). The conclusion follows.

Notice that the computation in Step 2 leading to the definition of the constant $D$ does not depend on the precise choice of the constant $\Lambda$ entering in the definition of the topological sectors $S_{d}$. Therefore, we may assume that

$$
\Lambda>D
$$

Step 3. We claim that

$$
n\left(u_{\varepsilon}\left(\cdot, T_{\varepsilon}\right)\right) \leq n_{0} \quad \forall t \in\left[0, T_{\varepsilon}\right]
$$

and that

$$
\left\|J u_{\varepsilon}\left(\cdot, T_{\varepsilon}\right)-\pi \sum d_{i} \delta_{a_{i}^{0}}\right\|_{\left[\mathcal{W}_{0}^{1, \infty}(B(R))\right]^{*}}=\eta_{0} .
$$

This is an immediate consequence of Step 2, (2.2) for the first assertion, and the definition of $T_{\varepsilon}$ for the second assertion.

At this stage, we invoke Theorem 6.1 with the choice $r=r_{a}$. Assumptions (6.1) and (6.2) are satisfied by definition of $T_{\varepsilon}$ so that we may assert that for all $s \in\left[0, T_{\varepsilon}\right]$

$$
\int_{B(R) \backslash \cup B\left(a_{i}^{0}, r_{a}\right)} e_{\varepsilon}\left(\left|u_{\varepsilon}(\cdot, s)\right|\right)+\frac{1}{8}\left|\frac{j\left(u_{\varepsilon}(\cdot, s)\right)}{\left|u_{\varepsilon}(\cdot, s)\right|}-j\left(u^{*}\left(a_{i}^{0}, d_{i}\right)\right)\right|^{2} \leq C
$$

where $C$ is independent of $\varepsilon$ and $s$.
Next, for $i=1, \ldots, l$, we consider real-valued functions $\chi_{i} \in \mathcal{D}\left(B\left(a_{i}^{0}, \frac{3 r_{a}}{2}\right)\right)$ such that $\chi_{i}$ is affine on $B\left(a_{i}^{0}, r_{a}\right)$ and $\left|\nabla \chi_{i}\left(a_{i}^{0}\right)\right|=1$.
Step 4. We have, for $0 \leq s, t \leq T_{\varepsilon}$

$$
\begin{equation*}
\left|\int\left\langle J u_{\varepsilon}(\cdot, t)-J u_{\varepsilon}(\cdot, s), \chi_{i}\right\rangle\right| \leq C\left|D^{2} \chi_{i} \|_{L^{\infty}}\right| t-s \mid . \tag{7.10}
\end{equation*}
$$

Proof. Since $\chi_{i}$ is affine on $B\left(a_{i}^{0}, r_{a}\right)$, it follows that $\operatorname{supp}\left(\frac{\partial^{2} \chi_{i}}{\partial \bar{z}^{2}}\right) \subset B\left(a_{i}^{0}, \frac{3 r_{a}}{2}\right) \backslash$ $B\left(a_{i}^{0}, r_{a}\right)$. The conclusion then follows from (1.12), (1.15) and the bound provided in Step 2, which yields, for all $s \in\left[0, T_{\varepsilon}\right]$,

$$
\left\|\omega\left(u_{\varepsilon}(\cdot, s)\right)\right\|_{L^{1}\left(B\left(a_{i}^{0}, \frac{3 r_{a}}{2}\right) \backslash B\left(a_{i}^{0}, r_{a}\right)\right)} \leq C .
$$

Step 5. Proof of Lemma 7.2 completed. For $0 \leq t \leq T_{\varepsilon}$, let $b_{i}(t) \in$ $B\left(a_{i}^{0}, \frac{r_{a}}{2}\right)$ be the points provided by Theorem 6.1 for $u_{\varepsilon}(\cdot, t)$ and satisfying (6.4), that is

$$
\begin{equation*}
\left\|J u_{\varepsilon}(\cdot, t)-\pi \sum d_{i} \delta_{b_{i}(t)}\right\|_{\left[W_{0}^{1, \infty}(B(R))\right]^{*}} \leq C \varepsilon|\log \varepsilon| . \tag{7.11}
\end{equation*}
$$

We write (in this Step $\|\cdot\|$ stands for $\|\cdot\|_{\left[W_{0}^{1, \infty}(B(R))\right]^{*}}$ )

$$
\begin{aligned}
\eta_{0} & =\left\|J u_{\varepsilon}\left(\cdot, T_{\varepsilon}\right)-\pi \Sigma d_{i} \delta_{a_{i}^{0}}\right\| \\
& \leq\left\|J u_{\varepsilon}\left(\cdot, T_{\varepsilon}\right)-\pi \Sigma d_{i} \delta_{b_{i}\left(T_{\varepsilon}\right)}\right\|+\left\|\pi \Sigma d_{i} \delta_{a_{i}^{0}}-\pi \Sigma d_{i} \delta_{b_{i}\left(T_{\varepsilon}\right)}\right\| .
\end{aligned}
$$

From the definition of $r_{a}$ and the fact that $b_{i}\left(T_{\varepsilon}\right) \in B\left(a_{i}^{0}, \frac{r_{a}}{2}\right)$ is follows that there exist real-valued functions $\chi_{i, \varepsilon}$ with the same properties as in Step 4, such that

$$
\left\|\pi \Sigma d_{i} \delta_{a_{i}^{0}}-\pi \Sigma d_{i} \delta_{b_{i}\left(T_{\varepsilon}\right)}\right\|=\left|\left\langle\pi \Sigma d_{i} \delta_{a_{i}^{0}}-\pi \Sigma d_{i} \delta_{b_{i}\left(T_{\varepsilon}\right)}, \Sigma \chi_{i, \varepsilon}\right\rangle\right| .
$$

Moreover, the functions $\chi_{i, \varepsilon}$ may be choosed in such a way that $\left\|D^{2} \chi_{i, \varepsilon}\right\|_{L^{\infty}}$ $\leq C$ independently of $i$ and $\varepsilon$. Therefore, we obtain using Step 4 and (7.11)

$$
\begin{aligned}
\eta_{0} \leq & \left\|J u_{\varepsilon}\left(\cdot, T_{\varepsilon}\right)-\pi \Sigma d_{i} \delta_{b_{i}\left(T_{\varepsilon}\right)}\right\|+\left|\left\langle\pi \Sigma d_{i} \delta_{a_{i}^{0}}-\pi \Sigma d_{i} \delta_{b_{i}\left(T_{\varepsilon}\right)}, \Sigma \chi_{i, \varepsilon}\right\rangle\right| \\
\leq & C\left(\left\|J u_{\varepsilon}\left(\cdot, T_{\varepsilon}\right)-\pi \Sigma d_{i} \delta_{b_{i}\left(T_{\varepsilon}\right)}\right\|+\left\|J u_{\varepsilon}^{0}-\pi \Sigma d_{i} \delta_{a_{i}^{0}}\right\|\right) \\
& +\left|\int\left\langle J u_{\varepsilon}\left(\cdot, T_{\varepsilon}\right)-J u_{\varepsilon}^{0}, \Sigma \chi_{i, \varepsilon}\right\rangle\right| \\
\leq & C \varepsilon|\log \varepsilon|+C T_{\varepsilon} .
\end{aligned}
$$

The conclusion (7.6) follows.
We are now in position to present the
Proof of Theorem 7.1. Using Lemma 7.2, (7.11) and a diagonal argument, we obtain the existence of a sequence $\varepsilon_{n} \rightarrow 0$ and paths $b_{i}(t)$ defined for $t \in \mathcal{Q} \equiv \mathbb{Q} \cap\left[0, T\left(r_{a}, R, K_{0}, K_{1}\right)\right]$ such that $b_{i}(0)=a_{i}^{0}$ and the norm in (7.2) converges to zero for each $t \in \mathcal{Q}$. Passing to the limit $\varepsilon_{k} \rightarrow 0$ in (7.10) we infer that the paths $b_{i}(\cdot)$ are lipschitz on $\mathcal{Q}$. We still denote by $b_{i}(\cdot)$ their unique lipschitz extension on $\left[0, T\left(r_{a}, R, K_{0}, K_{1}\right)\right]$. By compactness and (7.10) once more, it follows that the norm in (7.2) converges to zero uniformly for every $t \in\left[0, T\left(r_{a}, R, K_{0}, K_{1}\right)\right]$.

By Lemma 7.2 Step 2, the bound (7.3) holds for the whole family of $\operatorname{maps}\left(u_{\varepsilon}\right)_{0<\varepsilon<\varepsilon_{\Lambda}}$ and for $C_{0}=D$.

Finally, the bound (7.4) is a direct consequence of (7.1), the conservation of $\mathcal{E}_{\varepsilon, U_{d}}$, the continuity of the $b_{i}(\cdot)$ and the continuous dependence of $\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{*}\left(a_{i}, d_{i}\right)\right)$ on $a_{i}$.

The convergence of the Jacobians in (7.2) actually holds on larger balls passing possibly to a further subsequence. We have

Lemma 7.3. There exits a subsequence (still denoted by $\varepsilon_{k}$ ) such that for all for all $L \geq 2^{n_{0}}$,

$$
\sup _{t \in[0, T]}\left\|J u_{\varepsilon_{k}}(\cdot, t)-\pi \sum d_{i} \delta_{b_{i}(t)}\right\|_{\left[W_{0}^{1, \infty}(B(L))\right]^{*}} \rightarrow 0 \quad \text { as } k \rightarrow+\infty .
$$

Proof. From (7.8) and (7.9) we infer that for each $n \geq n_{0}$ and for $L \equiv$ $L_{n}=2^{n}$ there exists $C>0$ (depending on $n$ ) such that

$$
E_{\varepsilon_{k}}\left(u_{\varepsilon^{k}}^{0}, B(L)\right) \leq \pi l\left|\log \varepsilon_{k}\right|+C
$$

and therefore by compactness of the Jacobians (see e.g. [9]) there exists a subsequence (still denoted by $\varepsilon_{k}$ ) and a configuration ( $a_{i}^{\prime}, d_{i}^{\prime}$ ) such that

$$
\left\|J u_{\varepsilon_{k}}^{0}-\pi \sum d_{i}^{\prime} \delta_{a_{i}^{\prime}}\right\|_{\left[W_{0}^{1, \infty}\left(B\left(L_{n}\right)\right)\right]^{*}} \rightarrow 0 \quad \text { as } k \rightarrow+\infty
$$

By (1.8) and e.g. the lower energy bounds of Theorem 5 in [10] it follows that none of the $a_{i}^{\prime}$ lies in $B\left(2^{n}\right) \backslash B\left(2^{n_{0}}\right)$. By (1.7) we therefore obtain that the configurations $\left(a_{i}^{0}, d_{i}\right)$ and $\left(a_{i}^{\prime}, d_{i}^{\prime}\right)$ are identical. We may then replace $R=2^{n_{0}}$ by $R=L_{n}=2^{n}$ when using Theorem 7.1. A diagonal argument finally allows us to construct a fix subsequence which works for all $n$.

Let $\Sigma_{\mathfrak{v}}$ denote the trajectory set in $[0, T]$ :

$$
\Sigma_{\mathfrak{v}}:=\left\{\left(b_{i}(t), t\right), t \in[0, T], i=1, \ldots, l\right\}
$$

and $\mathcal{G}$ denote its complement in $\mathbb{R}^{2} \times[0, T]$. It follows from Lemma 7.3 and Theorem 6.1 that the sequence $\left(j u_{\varepsilon_{k}} /\left|u_{\varepsilon_{k}}\right|\right)$ is uniformly bounded in $L_{\text {loc }}^{2}(\mathcal{G})$. The next lemma characterizes its weak limit.

Lemma 7.4. There exists a subsequence (still denoted $\varepsilon_{k}$ ) such that

$$
\left.\frac{j\left(u_{\varepsilon_{k}}(\cdot, \cdot)\right)}{\left|u_{\varepsilon_{k}}(\cdot, \cdot)\right|} \rightharpoonup j u^{*}\left(b_{i}(\cdot), d_{i}\right)\right)
$$

weakly in $L_{\mathrm{loc}}^{2}(\mathcal{G})$ as $k \rightarrow+\infty$.
Proof. We already know from Lemma 7.3 that in $\mathcal{D}^{\prime}(B \times[0, T])$

$$
\operatorname{curl}\left(j u_{\varepsilon_{k}}\right)=2 J u_{\varepsilon_{k}} \rightarrow 2 \pi \sum d_{i} \delta_{b_{i}(\cdot)}=\operatorname{curl}\left(j u^{*}\left(b_{i}, d_{i}\right)\right)
$$

On the other hand, since $u_{\varepsilon_{k}}$ is a solution of $(G P)_{\varepsilon_{k}}$, we have in $\mathcal{D}^{\prime}(B \times[0, T])$

$$
\operatorname{div}\left(j u_{\varepsilon_{k}}\right)=-\varepsilon_{k} \frac{d}{d t} \frac{\left|u_{\varepsilon_{k}}\right|^{2}-1}{\varepsilon_{k}} \rightarrow 0=\operatorname{div}\left(j u^{*}\left(b_{i}, d_{i}\right)\right)
$$

Since by (6.3) and Lemma 7.3, $\left|u_{\varepsilon_{k}}\right| \rightarrow 1$ in $L_{\mathrm{loc}}^{p}(\mathcal{G})$ for every $p<+\infty$, we first infer that $j u_{\varepsilon_{k}}$ is uniformly bounded in $L_{\text {loc }}^{q}(\mathcal{G})$ for every $q<2$ and then, taking possibly subsequences, that

$$
j u_{\varepsilon_{k}}-j u^{*}\left(b_{i}, d_{i}\right) \rightharpoonup \nabla_{x}^{\perp} H
$$

in $L_{\text {loc }}^{q}(\mathcal{G})$ where $H$ is harmonic on $\mathcal{G}$. It also follows from Theorem 6.1 that

$$
\left\|\nabla_{x} H\right\|_{L^{2}(\mathcal{G})}^{2} \leq K_{1} T
$$

Standard singularity removal theory yields then that $H$ is harmonic on the whole $\mathbb{R}^{2} \times[0, T]$, and then that it is constant (in x only). Using once more the fact that $\left|u_{\varepsilon_{k}}\right| \rightarrow 1$ in $L_{\text {loc }}^{p}(\mathcal{G})$ for every $p<+\infty$, we thus obtain that $j u_{\varepsilon_{k}} /\left|u_{\varepsilon_{k}}\right|$ converges weakly to $j u^{*}\left(b_{i}, d_{i}\right)$ in $L_{\text {loc }}^{q}(\mathcal{G})$ for every $q<2$. The weak convergence in $L_{\text {loc }}^{2}(\mathcal{G})$ then follows from the already mentioned uniform bound of $j u_{\varepsilon_{k}} /\left|u_{\varepsilon_{k}}\right|$ in that space.

## 8. Dynamical law for the vortices

The purpose of this section is to present the proof of Theorem 1. To that aim, we consider a family $\left(u_{\varepsilon}^{0}\right)_{0<\varepsilon<1}$ well-prepared with respect to a configuration $\left(a_{i}^{0}, d_{i}\right)$, i.e. such that $d_{i} \in\{-1,+1\}$ and such that the conditions $(1.7),(1.8)$ and (1.9) are satisfied.

Notice that the results of Section 7, in particular Theorem 7.1, apply in the present situation, providing a sequence $\varepsilon_{k} \rightarrow 0$, Lipschitz paths $b_{i}(t)$ for $t \in[0, T]$ such that $b_{i}(0)=a_{i}^{0}$ and (7.2) (7.3) (7.4) are satisfied. The main point in order to prove Theorem 1 is to show that $b_{i}(t)=a_{i}(t)$ for all $i=$ $1, \ldots, l$, where $a_{i}(\cdot)$ denote the unique solution of the Cauchy problem (1.10) on its maximal interval of existence. ${ }^{2}$

We set

$$
\sigma(t)=\sum_{i=1}^{l}\left|a_{i}(t)-b_{i}(t)\right|
$$

for $t \in[0, T]$. Note that $\sigma(0)=0$ and that decreasing possibly the time $T$ provided by Theorem 7.1, we may assume that $\sigma(t) \leq r_{a}$ for $t \in[0, T]$. We will show that $\sigma$ is identically zero by a Gronwall type argument adapted from [8].

We set

$$
\Sigma_{\varepsilon_{k}}(t)=\mathcal{E}_{\varepsilon_{k}, U_{d}}\left(u_{\varepsilon_{k}}(\cdot, t)\right)-\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{*}\left(b_{i}(t), d_{i}\right)\right)
$$

Lemma 8.1. There exists $C>0$ such that

$$
\limsup _{k \rightarrow+\infty} \sup _{t \in[0, T]}\left(\Sigma_{\varepsilon_{k}}(t)-C \sigma(t)\right) \leq 0
$$

Proof. By conservation of renormalized energy we have

$$
\mathcal{E}_{\varepsilon_{k}, U_{d}}\left(u_{\varepsilon_{k}}(\cdot, t)\right)=\mathcal{E}_{\varepsilon_{k}, U_{d}}\left(u_{\varepsilon_{k}}^{0}\right)
$$

By Corollary 4.1 we have

$$
\limsup _{k \rightarrow+\infty}\left|\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{*}\left(b_{i}(t), d_{i}\right)\right)-\mathcal{E}_{\varepsilon, U_{d}}\left(u_{\varepsilon}^{*}\left(a_{i}^{0}, d_{i}\right)\right)\right| \leq\left|W\left(b_{i}(t), d_{i}\right)-W\left(a_{i}^{0}, d_{i}\right)\right|
$$

By conservation of $W$ under (1.10) we have

$$
W\left(a_{i}(t), d_{i}\right)=W\left(a_{i}^{0}, d_{i}\right)
$$

[^1]The conclusion then follows from the inequality

$$
\left|W\left(b_{i}(t), d_{i}\right)-W\left(a_{i}(t), d_{i}\right)\right| \leq C \sigma(t)
$$

which holds for $C>0$ depending only on $r_{a}$ and $R_{a}$ and for $t \in[0, T]$.
From Section 6 we infer
Lemma 8.2. There exists $C>0$ such that for every $L>0$ we have
$\limsup _{k \rightarrow+\infty} \sup _{t \in[0, T]} \int_{U}\left[e_{\varepsilon_{k}}\left(\left|u_{\varepsilon_{k}}(\cdot, t)\right|\right)+\left|\frac{j\left(u_{\varepsilon_{k}}(\cdot, t)\right)}{\left|u_{\varepsilon_{k}}(\cdot, t)\right|}-j\left(u^{*}\left(b_{i}(t), d_{i}\right)\right)\right|^{2}\right]-C \sigma(t) \leq 0$, where $U=B(L) \backslash \cup_{i=1}^{l} B\left(a_{i}^{0}, \frac{3 r_{a}}{2}\right)$.

Proof. Let

$$
\eta_{k}:=\sup _{t \in[0, T]}\left\|J u_{\varepsilon_{k}}(\cdot, t)-\pi \Sigma d_{i} \delta_{b_{i}(t)}\right\|_{\left[W_{0}^{1, \infty}(B(L))\right]^{*}},
$$

and note that Lemma 7.3 implies that $\eta_{k} \rightarrow 0$ as $k \rightarrow \infty$. For each $n \geq n_{0}$, let $\varepsilon_{0}(n)$ and $\eta_{0}(n)$ denote the constants provided in the statement of Theorem 6.1 for the choice $R=2^{n}$. Then exists $n_{k} \rightarrow \infty$ and nondecreasing (but not necessarily strictly increasing) in $k$ such that $\varepsilon_{k} \leq \varepsilon_{0}\left(n_{k}\right)$ and $\eta_{k} \leq \eta_{0}\left(n_{k}\right)$ for every large enough $k$. We can then use Theorem 6.1 to conclude that for
$\int_{U} e_{\varepsilon_{k}}\left(\left|u_{\varepsilon_{k}}(\cdot, t)\right|\right)+\left|\frac{j\left(u_{\varepsilon_{k}}(\cdot, t)\right)}{\left|u_{\varepsilon_{k}}(\cdot, t)\right|}-j\left(u^{*}\left(b_{i}(t), d_{i}\right)\right)\right|^{2} \leq C \Sigma_{\varepsilon_{k}}(t)+C\left(\eta_{k}, \varepsilon_{k}, 2^{-n_{k}}\right)$.
The conclusion follows letting $k \rightarrow+\infty$ and using Lemma 8.1.
The control of the difference between $u_{\varepsilon}$ and $u^{*}$ obtained in Lemma 8.2 allows us to control the difference of their Hopf differential, which was defined in (1.15) as

$$
\omega(u)=\left|u_{x_{1}}\right|^{2}-\left|u_{x_{2}}\right|^{2}-2 i u_{x_{1}} \cdot u_{x_{2}} .
$$

In the sequel, we set $A=\cup_{i=1}^{l} B\left(a_{i}^{0}, 2 r_{a}\right) \backslash B\left(a_{i}^{0}, \frac{3 r_{a}}{2}\right)$. Notice that pointwise on $A \times[0, T]$ we have

$$
\begin{equation*}
\mid \omega\left(u^{*}\left(a_{i}(t), d_{i}\right)\right)-\omega\left(u^{*}\left(b_{i}(t), d_{i}\right) \mid \leq C \sigma(t)\right. \tag{8.1}
\end{equation*}
$$

Lemma 8.3. There exists $C>0$ such that for $0 \leq t_{1} \leq t_{2} \leq T$ and $\varphi \in \mathcal{D}(A)$ we have

$$
\limsup _{k \rightarrow+\infty}\left|\int_{t_{1}}^{t_{2}} \int_{A}\left[\omega\left(u_{\varepsilon_{k}}\right)-\omega\left(u^{*}\left(b_{i}(\cdot), d_{i}\right)\right)\right] \varphi\right| \leq C\|\varphi\|_{L^{\infty}} \int_{t_{1}}^{t_{2}} \sigma(t) d t
$$

Proof. We start with the pointwise equality

$$
u_{x_{p}} \cdot u_{x_{q}}=\frac{u \times u_{x_{p}}}{|u|} \frac{u \times u_{x_{q}}}{|u|}+|u|_{x_{p}}|u|_{x_{q}}
$$

which applies to $u_{\varepsilon_{k}}(\cdot, t)$ and $u^{*}\left(b_{i}(t), d_{i}\right)$ almost everywhere on $U \times[0, T]$. Note that $u \times u_{x_{p}}$ is just the $p$ th component of $j u$, which we will write $(j u)_{p}$. Hence, since $\left|u^{*}\left(b_{i}, d_{i}\right)\right| \equiv 1, \omega\left(u_{\varepsilon_{k}}\right)-\omega\left(u^{*}\left(b_{i}, d_{i}\right)\right)$ has the form

$$
\begin{equation*}
\sum_{p, q=1}^{2} c_{p q}\left[\frac{\left(j u_{\varepsilon_{k}}\right)_{p}}{\left|u_{\varepsilon_{k}}\right|} \frac{\left(j u_{\varepsilon_{k}}\right)_{q}}{\left|u_{\varepsilon_{k}}\right|}-\left(j u^{*}\left(b_{i}, d_{i}\right)\right)_{p}\left(j u^{*}\left(b_{i}, d_{i}\right)\right)_{q}\right]+d_{p q}\left|u_{\varepsilon_{k}, x_{p}}\right|\left|u_{\varepsilon_{k}, x_{q}}\right| \tag{8.2}
\end{equation*}
$$

for certain numbers $c_{p q}, d_{p q} \in \mathbb{C}$. For real numbers $a_{p}, a_{q}$ and $a_{p}^{*}, a_{q}^{*}$ be have the equality

$$
\begin{equation*}
a_{p} a_{q}-a_{p}^{*} a_{q}^{*}=\left(a_{p}-a_{p}^{*}\right)\left(a_{q}-a_{q}^{*}\right)+a_{p}^{*}\left(a_{q}-a_{q}^{*}\right)+a_{q}^{*}\left(a_{q}-a_{q}^{*}\right) . \tag{8.3}
\end{equation*}
$$

We multiply (8.2) by $\varphi$ and rewrite, using (8.3) with $a_{q}=j\left(u_{\varepsilon_{k}}\right)_{p} /\left|u_{\varepsilon_{k}}\right|$ and $a_{p}^{*}=j\left(u^{*}\left(b_{i}, d_{i}\right)\right)_{p}$, and similarly $a_{q}, a_{q}^{*}$. Integrating over $A \times\left[t_{1}, t_{2}\right]$, letting $k \rightarrow+\infty$, and using Lemma 7.4, we see that the terms that are linear in $\left(j u_{\varepsilon_{k}}\right)_{p}-\left(j u^{*}\left(b_{i}, d_{i}\right)\right)_{p}$ vanish, and the remaining terms can be easily estimated to obtain

$$
\begin{aligned}
& \limsup _{k \rightarrow+\infty} \int_{t_{1}}^{t_{2}} \int_{A}\left[\omega\left(u_{\varepsilon_{k}}(\cdot, t)\right)-\omega\left(u^{*}\left(b_{i}, d_{i}\right)\right)\right] \varphi \\
& \quad \leq C\|\varphi\|_{L^{\infty}} \limsup _{k \rightarrow+\infty} \int_{t_{1}}^{t_{2}} \int_{A}\left[\left|\frac{j\left(u_{\varepsilon_{k}}\right)}{\left|u_{\varepsilon_{k}}\right|}-j\left(u^{*}\left(b_{i}, d_{i}\right)\right)\right|^{2}+|\nabla| u_{\varepsilon_{k}} \|^{2}\right] .
\end{aligned}
$$

The conclusion then follows from Lemma 8.2.
We are now in position to present the
Proof of Theorem 1 completed. We first consider the interval $[0, T]$ where $T$ is as above. Let $t \in[0, T]$ be a point of differentiability of all the Lipschitz functions $a_{i}$ and $b_{i}$ (almost all points $t$ have this property). Since all the points $a_{i}(t)$ and $b_{i}(t)$ belong to $B\left(a_{i}^{0}, \frac{r_{a}}{2}\right)$, there exists $\chi \in \mathcal{D}\left(\mathbb{R}^{2}\right)$ (depending on $t$ ) such that $\chi$ is affine on each $B\left(a_{i}^{0}, r_{a}\right),\left|\nabla \chi\left(a_{i}^{0}\right)\right|=1$, $\operatorname{supp} \frac{\partial^{2} \chi}{\partial \bar{z}^{2}} \subset A$ and

$$
\begin{equation*}
\sigma(t) \equiv \sum_{i=1}^{l}\left|a_{i}(t)-b_{i}(t)\right|=\left\langle\sum_{i=1}^{l} \delta_{a_{i}(t)}-\delta_{b_{i}(t)}, \chi\right\rangle . \tag{8.4}
\end{equation*}
$$

On the other hand, for every $0 \leq \delta \leq t$,

$$
\begin{equation*}
\sigma(t-\delta) \equiv \sum_{i=1}^{l}\left|a_{i}(t-\delta)-b_{i}(t-\delta)\right| \geq\left\langle\sum_{i=1}^{l} \delta_{a_{i}(t-\delta)}-\delta_{b_{i}(t-\delta)}, \chi\right\rangle \tag{8.5}
\end{equation*}
$$

Integrating (1.14) on $[t-\delta, t]$ and taking into account (1.17) and (1.18) we obtain

$$
\begin{align*}
& \left\langle\left(J u_{\varepsilon_{k}}(\cdot, t)-\pi \Sigma d_{i} \delta_{a_{i}(t)}\right)-\left(J u_{\varepsilon_{k}}(\cdot, t-\delta)-\pi \Sigma d_{i} \delta_{a_{i}(t-\delta)}\right), \chi\right\rangle  \tag{8.6}\\
& =-2 \int_{t-\delta}^{t} \int_{A} \operatorname{Im}\left(\left[\omega\left(u_{\varepsilon_{k}}\right)-\omega\left(u^{*}\left(a_{i}, d_{i}\right)\right)\right] \frac{\partial^{2} \chi}{\partial \bar{z}^{2}}\right) .
\end{align*}
$$

Passing to the limsup $k \rightarrow+\infty$ we are led, taking into account Lemma 7.3, Lemma 8.3, (8.5) and (8.1), to

$$
\sigma(t)-\sigma(t-\delta) \leq C \int_{t-\delta}^{t} \sigma(s) d s
$$

Passing to the limit $\delta \rightarrow 0$ we finally obtain

$$
\frac{d}{d t} \sigma(t) \leq C \sigma(t)
$$

and since $\sigma(0)=0$ Gronwall's lemma yields

$$
\sigma(t)=0 \quad \text { for } t \in[0, T] .
$$

The conditions (1.7) (1.8) and (1.9) are therefore satisfied for $a_{i}=a_{i}(t)$ and $t \in[0, T]$. Indeed, (1.7) is a consequence of Lemma 7.3 and the equality $a_{i}(t)=b_{i}(t),(1.8)$ was already proved in (7.3), and (1.9) follows from Lemma 8.1 and the fact that $\sigma \equiv 0$.

To conclude, it suffices to pass from the interval $[0, T]$ to $\left[T_{*}, T^{*}\right]$, i.e. the maximal interval of existence of (1.10). Since we obtained a lower bound on $T$ which depends only on $r_{a}$ and $R_{a}$, this is readily achieved considering translations in time and reversing time.

## References

[1] Almeida, L.: Threshold transition energies for Ginzburg-Landau functionals. Nonlinearity 12 (1999), 1389-1414.
[2] Golovaty, D. and Berlyand, L.: On uniqueness of vector-valued minimizers of the Ginzburg-Landau functional in annular domains. Calc. Var. Partial Differential Equations 14 (2002), 213-232.
[3] Bethuel, F., Brezis, H. and Hélein, F.: Ginzburg-Landau vortices. Progress in Nonlinear Differential Equations and their Applications 13. Birkhäuser, Boston, MA, 1994.
[4] Bethuel, F., Brezis, H. and Orlandi, G.: Small energy solutions to the Ginzburg-Landau equation. C. R. Acad. Sci. Paris Sér. I Math. 331 (2000), 763-770.
[5] Bethuel, F., Orlandi, G. and Smets, D.: Dynamics of multiple degree Ginzburg-Landau vortices. Comm. Math. Phys. 272 (2007), 229-261.
[6] Bethuel, F. and Smets, D.: A remark on the Cauchy problem for the 2D Gross-Pitaevskii equation with non zero degree at infinity. Differential Integral Equations 20 (2007), 325-338.
[7] Chiron, D.: Boundary problems for the Ginzburg-Landau equation. Commun. Contemp. Math. 7 (2005), 597-648.
[8] Colliander, J.E. and Jerrard, R. L.: Vortex dynamics for the Ginzburg-Landau-Schrödinger equation. Internat. Math. Res. Notices 1998, no. 7, 333-358.
[9] Jerrard, R. L. and Soner, H. M.: The Jacobian and the Ginzburg- Landau energy. Calc. Var. Partial Differential Equations 14 (2002), 151-191.
[10] Jerrard, R. L. and Spirn, D.: Refined Jacobian estimates for GinzburgLandau functionals. Indiana Univ. Math. J. 56 (2007), 135-186.
[11] Jerrard, R. L. and Spirn, D.: Refined Jacobian estimates and GrossPitaevsky vortex dynamics. Arch. Rat. Mech. Anal., to appear.
[12] Hervé, R. M. and Hervé, M.: Quelques propriétés des solutions de l'équation de Ginzburg-Landau sur un ouvert de $\mathbb{R}^{2}$. Potential Anal. 5 (1996), 591-609.
[13] Lin, F.-H. and Xin, J. X.: On the incompressible fluid limit and the vortex motion law of the nonlinear Schrödinger equation. Comm. Math. Phys. 200 (1999), 249-274.
[14] Mironescu, P.: Les minimiseurs locaux pour l'équation de GinzburgLandau sont à symétrie radiale. C. R. Acad. Sci. Paris Sér. I Math. 323 (1996), 593-598.

Recibido: 23 de mayo de 2007
Fabrice Bethuel
Laboratoire Jacques-Louis Lions Université Pierre et Marie Curie

Boîte courrier 187
75252 Paris Cedex 05 France bethuel@ann.jussieu.fr

Robert L. Jerrard
Department of Mathematics
University of Toronto
Toronto, Ontario, Canada M5S 2E4
rjerrard@math.toronto.edu
Didier Smets
Laboratoire Jacques-Louis Lions Université Pierre et Marie Curie

Boîte courrier 187
75252 Paris Cedex 05 France
smets@ann.jussieu.fr


[^0]:    ${ }^{1}$ See [2] for a somewhat related result.

[^1]:    ${ }^{2}$ In order to prove that the full family $\left(u_{\varepsilon}(\cdot, t)\right)_{0<\varepsilon<1}$ is well-prepared with respect to the configuration $\left(a_{i}(t), d_{i}\right)$, first notice that it suffices to show that for any sequence $\varepsilon_{k} \rightarrow 0$ the conditions corresponding to (1.7), (1.8) and (1.9) hold for a subsequence of $\varepsilon_{k}$. Indeed, the general case then follows from the uniqueness of the limits $\left(a_{i}(t), d_{i}\right)$.

