# MULTIPLICATION OPERATORS 

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1. Introduction. The prototype for partially ordered linear spaces is $C[X]$, the space of all real valued continuous functions on a topological space $X$, with the natural ordering defined by: $f \geqq 0$ if and only if $f(x) \geqq 0$ for all $x \in X$. If $V$ is a real linear space with a partial order defined by a suitable positive cone $P$, then $V$ has a canonical embedding in a function space $C[X]$.

The containing space $C[X]$ has a more elaborate structure than did the original space $V$; in particular, $C[X]$ is an algebra. If we take any aspect of $C[X]$, we may ask how it appears when transferred back to $V$. This paper deals with one aspect of this.

Among the linear operators on $C[X]$, an interesting class that arises in many contexts is the class of multiplication operators. These are defined by:

$$
T(f)=g \quad \text { where } \quad g(x)=\phi(x) f(x) \quad x \in X
$$

and where $\phi$ is a specific member of $C[X]$.
The central result in this paper is a simple characterization, in terms of order, of the linear operators on $V$ which become multiplication operators when $V$ is represented in a function space $C[X]$. This in turn yields a new and more transparent proof of the Stone-Krein theorem on ordered algebras.
2. A simpler case. Let $V$ be a real linear space. We assume that there is a convex cone $P$ with vertex at 0 which defines an order relation $\leqq$ in $V$ by $x \leqq y$ if and only if $y-x \equiv P$. On $P$, we impose three conditions:

$$
\begin{equation*}
P \cap-P=\{0\} \tag{1}
\end{equation*}
$$

$P$ is generating
$P$ is linearly closed in $V$.
The second condition implies that every element $x \in V$ is the difference of positive elements; the third condition requires that every line meet $P$ in a (possibly unbounded) closed interval. Note that we do not impose any further lattice properties on $V$, nor do we assume that there is an order unit. If $V^{\prime}$ denotes the dual space of $V$, consisting of all linear functionals on $V$, then $V^{\prime}$ has a natural partial ordering derived from that of $V$. A functional $L$ is said to be positive if $L(x) \geqq 0$ for

[^0]all $x \geqq 0$; the positive cone in $V^{\prime}$ is $P^{\prime}$. The space $V^{\prime}$ will not in general obey all the properties (1), (2), (3).

Let $\mathscr{L}(V)$ denote the algebra of all linear transformations on $V$. We single out a subclass $\mathfrak{A} \subset \mathscr{L}(V)$ consisting of the order-bounded transformations:

Definition 1. An operator $T \in \mathscr{L}(V)$ is order bounded if there is a constant $r$ such that

$$
\begin{equation*}
-r x \leqq T x \leqq r x \text { for all } x \geqq 0 \text { in } V \tag{4}
\end{equation*}
$$

We observe that $\mathfrak{A}$ is a subalgebra of $\mathscr{L}(V)$ containing the identity operator $I$; for, if $T_{1}$ and $T_{2}$ are in $\mathfrak{N}$, with associated constants $r_{1}$ and $r_{2}$, then it follows readily from (4) that $T_{1} T_{2}$ obeys (4) with $r=3 r_{1} r_{2}$. We wish to show that $V$ has function space representations in which the algebra $\mathfrak{Y}$ becomes multiplication operators. We will prove this first under the strong restriction that $V$ has an "order unit", and then remove this restriction.

Let us suppose that there is an element $e \in V$ such that $e \geqq 0$ and (5) for every $x \geqq 0$, there is $\lambda>0$ such that $x \leqq \lambda e$.

This restriction can be described geometrically: the point $e$ is a radially interior point of $P$, so that every line thru $e$ meets $P$ in a line segment containing $e$ as interior point.

Theorem 1. Let $V$ be a partially ordered linear space obeying (1), (2), (3) and (5). Let $\mathfrak{H}$ be the order bounded operators on $V$. Then there is a compact set $\Gamma$ and an order preserving representation $\theta: x \rightarrow \hat{x}$ of $V$ onto a subspace of $C[\Gamma]$, and an isomorphism $\bar{\theta}: T \rightarrow \widehat{T}$ of $\mathfrak{A}$ into the multiplication operators on $C[\Gamma]$ such that

$$
\theta(T x)=\hat{T} \hat{x}
$$

for all $x \in V, T \in \mathfrak{Y}$.
Otherwise described, the diagram

commutes. Corresponding to $T$, there is a function $\phi \in C[\Gamma]$ such that if $T x=y$, then $\widehat{y}(p)=\phi(p) \hat{x}(p)$, for all $p \in \Gamma$.

Corollary 1. $\mathfrak{\{}$ is a commutative subalgebra of $\mathscr{L}(V)$.
The method we use will be to construct certain appropriate real homomorphisms of $\mathfrak{A}$. Recall first the important notion of a minimal positive element (See Brelot [3] for background.)

Definition 2. An element $u \geqq 0$ in $V$ is said to be minimal if $0 \leqq x \leqq u$ implies that $x=\lambda u$ for some real $\lambda$.

This can be described geometrically: $u$ is minimal if the ray $\rho$ generated by $u$ is extremal in $P$, and this is so if $u$ cannot be expressed as the midpoint of two points in $P$ that are not on $\rho$. In contrast with the situation for finite dimensional spaces, a cone $P$ in a general linear space will usually have no extremal rays (or minimal elements). This is the case for $C[X]$ when $X$ is the line, but is not the case if $X$ is discrete. The dual cone $P^{\prime}$ of positive linear functionals on $V$ can be better behaved; however, if $V$ is the space $L^{1}[0,1]$, neither $P$ nor $P^{\prime}$ have extremal rays.

Lemma 1. If $P$ is the positive cone in a space $V$ and $P$ contains a radially interior point, then $P^{\prime}$ has a separating family of extremal rays.

This is more or less familiar. (See Bonsall [2], Kadison [8], Kelly [9].) One defines a norm in $V$ by

$$
\|x\|=\inf \{\text { all } r \text { with }-r e \leqq x \leqq r e\}
$$

Let $D$ be the functionals $L$ on $V$ such that $\|L\| \leqq 1$ and $L(e)=1$. This is then a $w^{*}$ compact convex set in the dual space of $\langle V,\| \|\rangle$. Invoking the Krein-Milman theorem, $D$ has extreme points $L_{0}$ whose convex hull is dense in $D$. These are in fact minimal positive elements in $V^{\prime}$, generating extremal rays in $P^{\prime}$. Moreover, if $L_{0}(x)=0$ for all $L_{0}$, then $x=0$.

The key to the proof of Theorem 1 is the observation that minimal elements of $P$ will yield homomorphism of $\mathfrak{A}$ onto the reals. If $T \in \mathfrak{A}$, then by (4) there is a number $r$ such that

$$
\begin{equation*}
0 \leqq r x+T x \leqq 2 r x \quad \text { all } x \geqq 0 \tag{6}
\end{equation*}
$$

Let $x=u$, a minimal element of $P$. Then, we see at once that $u$ is an eigenvector for $T$. Denoting the corresponding eigenvalue by $\lambda(T)$, we have $T u=\lambda(T) u$, holding for all $T \in \mathfrak{N}$. But, it then follows that $T \rightarrow \lambda(T)$ is a homomorphism of $\mathfrak{A}$ onto the real field $k$; for, given $T_{1}$ and $T_{2}$, we have

$$
\begin{aligned}
\lambda\left(T_{1} T_{2}\right) u & =T_{1} T_{2}(u) \\
& =T_{1}\left(\lambda\left(T_{2}\right) u\right) \\
& =\lambda\left(T_{1}\right) \lambda\left(T_{2}\right) u .
\end{aligned}
$$

Unfortunately, except in unusual cases, $P$ will not have any minimal elements. Let us go over to the adjoint algebra $\mathfrak{N}^{*} \subset \mathscr{L}\left(V^{\prime}\right)$ consisting of all operators $T^{*}$ for $T \in \mathfrak{Y}$. $T^{*}$ is defined on $V^{\prime}$, the dual space of $V$, by:

$$
\begin{array}{ll}
T^{*}(L)(x)=L(T x) & \text { all } L \in V^{\prime}  \tag{7}\\
\text { all } x \in V
\end{array}
$$

and the mapping $T \rightarrow T^{*}$ is an anti-isomorphism of $\mathfrak{N}^{2}$ onto $\mathfrak{A}^{*}$. From (7) and (5), we see that if $T$ obeys (4), then

$$
\begin{equation*}
-r L \leqq T^{*}(L) \leqq r L \quad \text { all } L \geqq 0 \tag{8}
\end{equation*}
$$

Thus, $\mathfrak{2} *$ is an algebra of order-bounded operators on the partially ordered space $V^{\prime}$. By Lemma 1, since $P$ was assumed to have an order unit $e$, there are many minimal elements $L_{0}$ in $P^{\prime}$.

Let $D$ be the convex cross-section of $P^{\prime}$ consisting of all $L \geqq 0$ with $L(e)=1$. Each extreme point of $D$ is a minimal positive element in $P^{\prime}$ and generates an extremal ray; let $\Gamma$ be the closure of the set of extreme points in $D$, in the $w^{*}$ topology arising from the natural norm topology on $V$. By the simple argument given above, each $L_{0} \in \Gamma$ yields a real homomorphism $\lambda_{L_{0}}$ of $\mathfrak{I}^{*}$, defined by the equation

$$
T^{*}\left(L_{0}\right)=\lambda_{L_{0}}\left(T^{*}\right) L_{0} .
$$

Since $\mathscr{A}^{*}$ is (anti) isomorphic to $\mathfrak{Q}^{*}, \lambda_{\mathcal{I}_{0}}$ in turn defines a real homomorphism $h_{x_{0}}$ of $\mathfrak{A}$; using (7), this takes the explicit form:

$$
\begin{equation*}
L_{0}(T x)=h_{L_{0}}(T) L_{0}(x) \tag{10}
\end{equation*}
$$

all $x \in V$
all $T \in \mathfrak{A}$.
all $L_{0} \in \Gamma$

By Lemma 1, the functionals $L_{0}$ separate $V$ so that the collection of homomorphisms $h_{x_{0}}$ separate $\mathfrak{A}$. We may conclude that $\mathfrak{A}$ is isomorphic to a product of fields $k$, and is therefore commutative; this proves the corollary.

To complete the proof of Theorem 1, we examine (10). We first represent $V$ in $C[\Gamma]$, mapping $x$ onto $\theta(x)=\widehat{x}$ where $\hat{x}\left(L_{0}\right)=L_{0}(x)$ for all $L_{0} \in \Gamma$. Since $L_{0}(e)=1$ for all $L_{0}, \hat{e}$ is the constant function 1 ; in fact, the mapping $\theta$ is one-to-one and order preserving. For fixed $T \in \mathfrak{A}$, define a function $\phi$ on $\Gamma$ by

$$
\begin{equation*}
\phi\left(L_{0}\right)=h_{L_{0}}(T) . \tag{11}
\end{equation*}
$$

Let $T x=y$; then, (10) can be rewritten as:

$$
\begin{equation*}
\hat{y}\left(L_{0}\right)=\phi\left(L_{0}\right) \hat{x}\left(L_{0}\right) . \tag{12}
\end{equation*}
$$

The representation $\theta$ is such that every order-bounded operator $T$ is carried into a multiplication operator on $C[\Gamma]$, and the correspondence is an isomorphism of $\mathfrak{U}$ with a subalgebra of $\mathscr{L}(C[\Gamma])$, and in fact, with a subalgebra of $C[\Gamma]$ itself.
3. The Krein-Stone theorem. Before removing the assumption that $V$ possesses an order unit $e$, we insert an immediate application
of our results. (See Stone [14], Krein [10], Kadison [8]).
Theorem 2. Let $A$ be a real algebra with unit $e$ and having a partial order such that if $x \geqq 0, y \geqq 0$, then $x+y \geqq 0$ and $x y \geqq 0$. Assume further that, as a linear space, A obeys restrictions (1), (2), (3) and (5). Then, $A$ is commutative and can be represented as a subalgebra of a function algebra $C[X]$.

Proof. Consider the left regular representation of $A$. This sends $a \in A$ into the operator $U_{a} \in \mathscr{L}(A)$ where $U_{a}(x)=a x$ for all $x \in A$. Since $A$ has a unit, this is an isomorphism of $A$ onto a subalgebra $\bar{A} \subset \mathscr{L}(A)$. By virture of (5), we can choose $r$ depending upon $a$ so that $-r e \leqq a \leqq r e$. If $x \geqq 0$, then $-r x \leqq a x \leqq r x$ so that $U_{a}$ is an order bounded operator on the linear space $\langle A,+\rangle$. Hence, $\bar{A} \subset \mathfrak{N}$, and since this is a commutative algebra, so is $A$.

As a matter of fact, it is not necessary in this proof to assume that $A$ is even associative, since this too can be deduced from the representation. Since $U_{a} U_{b}=U_{b} U_{a}$, it follows that $a(b x)=b(a x)$ for all $x \in A$; with $x=e$, we find that $A$ is commutative. Then, $a(b c)=a(c b)$ while $b(a c)=(a c) b$ and $A$ is associative.

Conversely, we note that Corollary 1 follows from Theorem 2, since $\mathfrak{N}$ itself is an ordered algebra, with $I$ as unit.

Other proofs which have been given for this result rely upon the construction of appropriate real homomorphisms $h$ of $A$. These are linear functionals on $\langle A,+\rangle$ which are multiplicative and obey $h(e)=1$. It is natural to look for these among the extreme points of an appropriate convex set $D$ in the dual space of $\langle A,+\rangle$. Since any finite set of distinct real homomorphisms of $A$ are linearly independent, the collection of $h$ are precisely the extreme points of the convex set $D_{0}$ which they generate. Unfortunately, we cannot obtain $D_{0}$ directly. Instead, one selects a $D \supset D_{0}$, easily described, and then proves $D=D_{0}$. For example, the method adopted in Tate [15], Kadison [8] and Kelley [9] is to select $D$ as all functionals $L$ on $\langle A,+\rangle$ such that $L(e)=1$ and $L\left(x^{2}\right) \geqq 0$ for all $x \in A$. We note that the proof of $D=D_{0}$ depends strongly upon the hypotheses on $A$; one can construct a finite dimensional algebra $B$ for which $D$ is a closed disc, having a circle for its extreme points, but such that $B$ has no proper real homomorphisms.
4. Reduction of the general case. Suppose now that $V$ is not assumed to satisfy (5). This is true for example, of the space $C_{0}[R]$ of functions with compact support, continuous on the real line $R$. We reduce this case to the previous one. Let $e$ be an element in $P$ and form

$$
\begin{equation*}
V(e)=\{\text { all } x \in V \text { such that for some } \lambda,-\lambda e \leqq x \leqq \lambda e\} \tag{13}
\end{equation*}
$$

This is a linear subspace of $V$; it inherits a partial order from $V$, and in its positive cone $P \cap V(e)$, the element $e$ is an order unit. Suppose that $T \in \mathfrak{A}$. Then, from (4), if $x \in V(e)$, then for the appropriate $\lambda$, we have

$$
-3 \lambda r e \leqq T x \leqq 3 \lambda r e
$$

Thus, $V(e)$ is left invariant under all operators $T \in \mathfrak{A}$. Accordingly, if we restrict $\mathfrak{A}$ to $V(e)$, we obtain a representation of $\mathfrak{A}$ in $\mathscr{L}(V(e))$. Applying Theorem 1 to the resulting algebra, we find that $\mathfrak{N}$ is commutative in its action on $V(e)$, and also obtain a representation (homomorphic) of $\mathfrak{N}$ as multiplication operators on an appropriate function space $C\left[\Gamma_{e}\right]$. Finally, as $e$ ranges over $P$, the subspaces $V(e)$ cover $V$, and we have proved the following result:

Theorem 3. Let $V$ be a partially ordered linear space obeying (1), (2) and (3), but not necessarily (5). Let $\mathfrak{A}$ be its algebra of order bounded operators. Then, $\mathfrak{A}$ is commutative, and corresponding to any positive element $e$ in $V$, there is a compact set $\Gamma_{e}$, an order preserving linear representation $\theta$ of $V(e)$ into $C\left[\Gamma_{e}\right]$ and a homomorphism $\bar{\theta}$ of $\mathfrak{A}$ into the multiplication operators on $C\left[\Gamma_{e}\right]$ such that $\theta(T x)=\bar{\theta}(T) \theta(x)$ for all $x \in V(e)$ and $T \in \mathfrak{A}$.

A footnote to this is in order. Although we have shown that the algebra $\mathfrak{A}$ is commutative, we have not shown that it need contain more than the multiples of the identity operator $I$. This can in fact, happen, although it does not in most of the interesting cases discussed in the next section. A glance at the finite dimensional case will be helpful. Let $P$ be a polyhedral cone in $n$-space, and let $u_{1}, u_{2}, \cdots u_{N}$ generate its extremal rays. Each $u_{j}$ is an eigenvector for all the order bounded operators $T \in \mathfrak{A}$, and in turn generates real homomorphisms $h_{\text {; }}$ of $\mathfrak{A}$, with

$$
T\left(u_{j}\right)=h_{j}(T) u_{j}
$$

Suppose that the $\left\{u_{j}\right\}_{1}^{N}$ are such that $N>n$ and every set of $n$ is independent. Then, it follows that all the $h_{\mathrm{j}}$ coincide on $\mathfrak{A}$. Since together they define a faithful representation of $\mathfrak{A}$, we conclude that $\mathfrak{A}$ consists exactly of the scalar multiples of $I$. In contrast, if $N=n$, and the $u_{j}$ form a basis, then $\mathfrak{A}$ becomes the algebra of diagonal matrices; these, of course, are the multiplication operators in this representation.
5. Examples. In this section, we give a number of interesting illuastrations of Theorem 3, together with a counterexample to show the necessity of the assumption that $P$ is a linearly closed cone.

First, choose $V$ as the space $C_{0}[X]$ of all real valued continuous functions on the locally compact space $X$ which vanish at infinity. With
the usual ordering ( $f \geqq 0$ means $f(p) \geqq 0$ for all $p \in X$ ) this is a partially ordered linear space satisfying the hypotheses of Theorem 3. Note in particular that $C_{0}[X]$ does not have an order unit. What are the order bounded operators on $C_{0}[X]$ ? Applying Theorem 3, we choose any $e \geqq 0$ in $C_{\mathrm{C}}[X]$ and form the subspace $V(e)$. By (13), $f \in V(e)$ if and only if $f / e$ is a bounded function on $X$. Thus, $V(e)$ is isomorphic to the space of bounded continuous functions on the open support $O_{e}$ of $e$. The set $\Gamma_{e}$ is the Čech compactification of $O_{e}$, which contains $O_{e}$ densely. Any point $p \in O_{e}$ defines a minimal functional $L_{p}$ on $V(e)$ so that by (10) and (12),

$$
\begin{equation*}
L_{p}(T f)=(T f)(p)=\phi(p) f(p) \tag{14}
\end{equation*}
$$

for all $p \in 0_{e}$ and any $T \in \mathfrak{Y}$. If $X$ is $\sigma$-compact, we can take $e$ so that $O_{e}=X$, and we find that the only order bounded transformations on $C_{0}[X]$ are those defined as point-wise multiplication by bounded continuous functions $\phi$ on $X$. If $X$ is not $\sigma$-compact, we arrive at the same conclusion by varying $e$.

We note that if $V$ is $C[X]$ itself, a simple and direct characterization of the order bounded operators is available. Using the fact that if $f\left(p_{0}\right)=0$, then we may write $f=f_{1}-f_{2}$ where $f_{i} \geqq 0$ and $f_{i}\left(p_{0}\right)=0$, it readily follows from the characteristic property of $T$ that $(T f)\left(p_{0}\right)=0$. Applying this to $f=g-g\left(p_{0}\right)$, we have $T g=\phi g$ where $\phi=T(1)$.

Another interesting special case is obtained by taking $V$ as the space $H$ of all bounded harmonic functions on an open domain $\Omega$. The constant function is an order unit for $H$ so that we do not need the full machinery of Theorem 3. The extremal rays in $P$ are generated by the R.S. Martin minimal functions (see Brelot [3]) and $H$ is represented as a subspace of the space of continuous functions on the ideal boundary $\Gamma$ of $\Omega$. The order bounded transformations are represented in turn as $C[\Gamma]$ itself; for any $T \in \mathfrak{A}, T f$ is the harmonic function $g \in H$ which is described by the (abstract) Dirichlet problem $\left.g\right|_{\Gamma}=\left.\phi f\right|_{F}$ where $\phi$ is the function in $C[\Gamma]$ corresponding to $T$. Note that $T$ is not a multiplication on $\Omega$ itself. With $\Omega$ chosen as the unit disc and $\phi(x, y)=x$, we have $T(1)=x, T(y)=x y$, but $T(x)=(1 / 2)\left\{x^{2}-y^{2}+1\right\}$, and $T(x y)=$ $(1 / 4)\left\{3 x^{2} y-y^{3}+y\right\}$.

A somewhat more complicated illustration is provided by the space $C[X: E]$ of all bounded functions $f$ on a locally compact space $X$ with values in a fixed partially ordered linear space $E$. We order this by saying $f \geqq g$ when $f(p) \geqq g(p)$ for all $p \in X$. We shall also assume that $E$ has an order unit $e$ and require that each $f$ be continuous when $E$ is given the norm topology associated with $e$. If $v \in E$, denote by $\bar{v}$ the constant function on $X$ with value $v$. Note that $\bar{e}$ is then an order unit for $C[X: E]$. To apply Theorem 3, we must determine minimal functionals in the dual space of $V$. We can find one associated with each point
$p_{0} \in X$ and any minimal functional $\theta$ on $E$; define $L_{0}$ on $C[X: E]$ by $L_{0}(f)=\theta\left(f\left(p_{0}\right)\right)$. The following argument proves that $L_{0}$ is indeed minimal. Suppose $0 \leqq L \leqq L_{0}$. Then, for any $v \geqq 0$ in $E, 0 \leqq L(\bar{v})=$ $\theta(v)$. Thus, $v \rightarrow L(\bar{v})$ is a positive linear functional on $E$ which is dominated by $\theta$. Since $\theta$ is minimal on $E$, there is a constant $\rho$ such that $L(\bar{v})=\rho \theta(\bar{v})=\rho L_{0}(\bar{v})$ for all $v \geqq 0$ in $E$ (and thus for all $v \in E$ ). Suppose now that $f \in C[X: E]$ with $f(p) \leqq f\left(p_{0}\right)$ for all $p \in X$; we shall say that such a function $f$ takes a maximum value at $p_{0}$ and that $f \in \mathscr{F}_{p_{0}}$. Setting $v=f\left(p_{0}\right)$, we have $\bar{v}-f \geqq 0$ so that $0 \leqq L(\bar{v}-f) \leqq L_{0}(\bar{v}-f)$. But, $L_{0}(\bar{v}-f)=\theta\left(v-f\left(p_{0}\right)\right)=0$ so that $L(f)=L(\bar{v})=\rho L_{0}(\bar{v})=\rho L_{0}(f)$. Thus, $L=\rho L_{0}$ on the linear span of the special class $\mathscr{F}_{p_{0}}$. Consider now a general function $F \in C[X: E]$; since $F$ is bounded, $\|F(p)\| \leqq M$ for all $p \equiv X$. Define $g, g_{1}$, and $g_{2}$ on $X$ by:

$$
\begin{aligned}
g(p) & =F(p)-F\left(p_{0}\right) \\
g_{1}(p) & =\frac{1}{2}\{2\|g(p)\| e+g(p)\} \\
g_{2}(p) & \left.=\frac{1}{2}\{2\|g(p)\| e-g(p)\}\right\}
\end{aligned} \quad \quad p \in X
$$

One sees that $g_{i} \geqq 0$ and $g_{i}\left(p_{0}\right)=0$, with $\left\|g_{i}(p)\right\| \leqq 3 M$ for all $p \in X$. Moreover,

$$
g(p)=\left\{4 M-g_{2}(p)\right\}-\left\{4 M-g_{1}(p)\right\}
$$

for all $p \in X$, so that $g \in \mathscr{F}_{p_{0}}-\mathscr{F}_{p_{0}}$. We conclude that $L(F)=\rho L_{0}(F)$, so that $L_{0}$ is indeed a minimal positive functional on $C[X: E]$.

Let $\Gamma$ be the set of extreme points in the set $D$ of functionals $\alpha$ on $E$ with $\alpha \geqq 0$ and $\alpha(e)=1$. Applying Theorem 3 , we find that any order bounded operator $T$ has the property that

$$
\begin{equation*}
\alpha\left(T(f)\left(p_{0}\right)\right)=\alpha\left(T(\bar{e})\left(p_{0}\right)\right) \alpha\left(f\left(p_{0}\right)\right) \tag{15}
\end{equation*}
$$

for all $f \in C[X: E], p_{0} \in X$ and $\alpha \in \Gamma$. If we represent the functions $f$ in $C[X: E]$ as functions $f$ on $X \times \Gamma$, then

$$
\bar{\theta}(T f)(p, \alpha)=\phi(p, \alpha) f(p, \alpha)
$$

for all $(p, \alpha)$.
The original space $C[X: E]$ is not an algebra, but is a module over the algebra $C[X]$. Formula (9) shows immediately that any order bounded transformation on $C[X: E]$ is in fact algebraic. If $\psi \in C[X]$ and $f \in C[X: E]$, then $T(\psi f)=\psi T(f)$. For,

$$
\begin{aligned}
\alpha(T(\psi f)(p)) & =\phi(p, \alpha) \alpha(\psi(p) f(p)) \\
& =\psi(p) \phi(p, \alpha) \alpha(f(p)) \\
& =\psi(p) \alpha(T(f)(p)) \\
& =\alpha(\psi(p) T(f)(p))
\end{aligned}
$$

for each $p \in X$ and $\alpha \in \Gamma$.
Finally, we use a familiar example to show that the most crucial hypothesis on the partially ordered linear space $V$ in Theorem 1 and 3 is that $P$ be linearly closed. Take for $V$ the space of all polynomials, with the ordering: $a_{0}+a_{1} x+\cdots+a_{m} x^{m}>0$ if $a_{m}>0$. $P$ satisfies the first and second requirements, but is not linearly closed; in fact

$$
\lambda\left(x^{2}\right)+(1-\lambda)(-x) \in P \text { only if } \lambda>0
$$

There is no order unit. We can still introduce the algebra $\mathfrak{A}$ of order bounded transformations on $V$. It is easy to see, however, that $\mathfrak{A}$ is not commutative. Let $T$ be defined on $V$ by $T\left(x^{n}\right)=q_{n}$ where $q_{n}$ is a polynominal of degree less than $n$. Then, $I \pm T \geqq 0$ so that $T \in \mathfrak{A}$. In particular, $T_{1}=x\left(d^{2} / d x^{2}\right)$ and $T_{2}=d / d x$ are in $\mathfrak{A}$; however, $T_{1} T_{2} \neq T_{2} T_{1}$. In this example, the reason for this can be traced to the fact that $P$ is so large that there are too many positive linear operators on $V$, (and no non-degenerate positive linear functionals).

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