## THE INTEGRATION OF A LIE ALGEBRA REPRESENTATION

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Let  $u: G \to A$  be a differentiable representation of a Lie group into a b-algebra. The differential  $u_0 = du_e$  of u at the neutral element e of G is a representation of the Lie algebra g of G into A. Because a Lie group is locally the union of one-parameter subgroups and since the infinitesimal generator of a differentiable (multiplicative) sub-semi-group of A determines this sub-semi-group, the representation  $u_0$  determines uif G is connected.

We shall be concerned with the converse: given a representation  $u_0$  of g, when can it be obtained by differentiating a representation u of G? We shall assume G connected and simply connected, which means that we are only interested in the local aspect of the problem.

Call  $a \in A$  integrable if a differentiable  $r: \mathbb{R} \to A$  can be found such that r(s + t) = r(s)r(t) and r'(0) = a. We can only hope to integrate  $u_0: g \to A$  to a differentiable  $u: G \to A$  if  $u_0x$  is integrable for all  $x \in g$ . We shall prove the

THEOREM. The set  $\mathfrak{h}$  of all elements  $x \in \mathfrak{g}$  such that  $u_0 x$  is integrable, is a Lie subalgebra of  $\mathfrak{g}$ ; the representation  $u_0$  can be integrated to a representation  $u: G \to A$  of the simply connected group G if and only if  $\mathfrak{h} = \mathfrak{g}$ .

This result is "best possible" in the following sense:

PROPOSITION 1. Given a real Lie algebra g and a subalgebra  $\mathfrak{h}$ , there exists a representation  $u_0: \mathfrak{g} \to A$  of g in a b-algebra A, so that

$$\mathfrak{h} = \{x \in \mathfrak{g} \mid u_0 x \text{ is integrable}\}$$
.

As a consequence of the theorem, we have the following result: Let x, y be two integrable elements of a *b*-algebra, and assume that the Lie algebra g they generate is finite-dimensional. Then all elements of g are integrable.

We cannot drop the assumption that g is finite-dimensional. There exists a b-algebra which contains integrable elements x, y such that neither x + y nor xy - yx is integrable.

Elementary properties of b-spaces and b-algebras can be found in [2] or [3]. Differentiable mappings into such spaces are investigated

in [4]. The results we need about differentiable semi-groups are established in [5], [6]. Our results are related to, but different from, those of R. T. Moore [1].

2. We first prove Proposition 1. Let G be a Lie group having g as Lie algebra and let H be the subgroup of G "generated" by  $\mathfrak{h}$ . Call A the ring of distributions on G whose support is compact and contained in H. The product in A is the convolution. A subset B of A is bounded if B is a bounded set of distributions with compact support, the union of the supports being relatively compact in H. Then, it is easily seen that the elements of g whose image by the natural inclusion  $u_0: g \to A$  are integrable, are precisely the elements of  $\mathfrak{h}$ . This completes the proof.

REMARK. If H is simply connected, the algebra A described above is the solution of a universal problem: every representation  $u: g \to A'$  of g in a b-algebra A' such that  $u\mathfrak{h}$  is integrable can be factorized in a unique way as  $u = v \circ u_0$ , where  $v: A \to A'$  is a morphism of b-algebras. An easy but somewhat technical modification of our definition of A would provide a solution of this problem in general (for an arbitrary H); the reader will have no difficulty to figure it out.

3. Let u be a differentiable mapping of a manifold D into another manifold D' or into a *b*-space E. We denote by  $du(x; \cdot)$  the derivative of u at x, so that  $du(x, \xi)$  is a tangent vector to D' at ux or an element of E when  $\xi$  is a tangent vector at  $x \in D$ . The chain rule says that if D, D', D'' are manifolds, if E is a *b*-space and if  $u: D \to D'$ ,  $v: D' \to D''$  or  $D' \to E$  are differentiable mappings, then

(1) 
$$d(v \circ u)(x; \xi) = dv(ux; du(x; \xi)) .$$

Let G be a Lie group whose neutral element will be denoted by e and let g be its Lie algebra. If  $x, y \in G$  and if  $\xi$  is a tangent vector at x, then  $y\xi$  and  $\xi y$  will be the tangent vectors at yx, xy respectively obtained by translating  $\xi$  to the left or to the right. We shall denote by  $\pi: G \times G \to G$  the product mapping  $(\pi(x, y) = xy)$ , by  $i: G \to G$  the inverse mapping  $(i(x) = x^{-1})$ , by  $Ad: G \to Autg$  the adjoint representation (Ad  $x \cdot \xi = x\xi x^{-1}$ ) and by ad the derivative of Ad at e  $(ad\xi \cdot \eta = [\xi, \eta])$ . We have

(2) 
$$d\pi(x, y; \xi, \eta) = x\eta + \xi y;$$

(3) 
$$di(x;\xi) = -x^{-1} \cdot \xi \cdot x^{-1}$$
.

Let H be a Lie group, let A be a b-algebra and let u denote

either a Lie group homomorphism  $G \to H$  or a differentiable mapping  $G \to A$  which is a homomorphism of G in the multiplicative group of A. Finally, set  $u_0 = du(e; \cdot): g \to \mathfrak{h} = \text{Lie } H$  or  $g \to A$  accordingly. Then

(4) 
$$du(x;\xi) = u(x)u_0(x^{-1}\xi) = u_0(\xi x^{-1})u(x)$$
.

In particular

(5) 
$$dAd(x;\xi) = Ad x \cdot ad(x^{-1}\xi) = ad(\xi x^{-1}) \cdot Ad x.$$

4. Let A be a b-algebra and  $A^*$  be the set of its invertible elements. A mapping  $u: D \to A^*$  will be called *differentiable* if both  $x \to u(x)$  and  $x \to u(x)^{-1}$  are differentiable mappings.

It is not difficult to construct differentiable A-valued mappings which are  $A^*$ -valued but are not differentiable  $A^*$ -valued mappings.

Consideration of the resolvent identity

$$a^{-1} - b^{-1} = -a^{-1}(a - b)b^{-1}$$

and standard proofs show that a differentiable mapping  $u: D \to A^*$  with values in  $A^*$  is a differentiable  $A^*$ -valued mapping in the above sense if and only if  $u^{-1}: D \to A$  is locally bounded. It turns out that

(6) 
$$du^{-1}(x;\xi) = -u^{-1}(x) \cdot du(x;\xi) \cdot u^{-1}(x)$$
.

5. From now on, G will be a connected, simply connected Lie group, g will be its Lie algebra, A a b-algebra and  $u_0: g \to A$  a representation. A differentiable submanifold D of G is called *right* (resp. *left*) integrable for  $u_0$  if a differentiable  $u: D \to A^*$  exists such that the equation (7) (resp. (8)) holds:

(7) 
$$du(x;\xi) = u_0(\xi \cdot x^{-1})u(x);$$

(8) 
$$du(x;\xi) = u(x)u_0(x^{-1}\cdot\xi)$$
.

It will follow from Proposition 2 that the representation  $u_0$  is integrable in the sense of §1 if and only if the manifold G itself is right or left integrable; therefore the terminology. We note that, if u satisfies (7), then

(9) 
$$du^{-1}(x;\xi) = -u^{-1}(x)u_0(\xi \cdot x^{-1}).$$

A right translate of a right integrable manifold is right integrable. If u satisfies (7), so does au for every  $a \in A^*$ .

LEMMA 1. Let D be connected, right integrable, containing e, and let u be a solution of (7) such that u(e) = 1. Then (10)  $u_0(x\xi x^{-1}) = u(x)u_0(\xi)u(x)^{-1}$ 

for all  $x \in D$  and  $\xi \in \mathfrak{g}$ .

It suffices to show that if  $\varphi: D \to A$  is defined by

$$\varphi(x) = u(x)^{-1}u_0(x\xi x^{-1})u(x)$$

then  $d\varphi = 0$ , and this follows from a straightforward computation using (7), (9), (5) and the fact that  $u_0: g \to A$  is a homomorphism of Lie algebras.

LEMMA 2. If D is connected, right integrable and contains e, it is also left integrable. Furthermore, the solution u of (7) such that u(e) = 1 is also a solution of (8).

This is clear since, by (10),

$$u(x)u_0(x^{-1}\xi) = u_0(x\cdot x^{-1}\xi\cdot x^{-1})u(x) = u_0(\xi x^{-1})u(x)$$
.

In view of Lemma 2, it is now meaningful to say that a manifold containing e is integrable.

6. Let D, D' be two differentiable manifolds. The rank  $r_x$  of a differentiable mapping  $u: D \to D'$  at a point  $x \in D$  is the dimension of the image of the derivative  $du(x; \cdot)$ . We recall that  $r_x$  is upper semi-continuous as a function of x. The mapping u is said to be regular at x if  $r_x$  is constant in a neighborhood of x; in that case, there exists a neighborhood U of x, a submanifold D'' of D', a manifold E and a diffeomorphism  $u': U \to D'' \times E$ , so that  $u|_U = p_{D''} \circ u'$ where  $p_{D''}$  denotes the projection of  $D'' \times E$  of its first factor.

LEMMA 3. For i = 1, 2, let  $D_i$  be an integrable submanifold of G containing e, and let  $u_i: D_i \to A$  be a solution of (7) mapping e on 1. Assume that the product mapping  $D_1 \times D_2 \to G$  is regular at (e, e). Then, one can find neighborhoods  $D'_1, D'_2$  of e in  $D_1, D_2$  respectively, so that  $D = D'_1 \cdot D'_2$  is an integrable manifold and the relation

(11) 
$$u(x_1 \cdot x_2) = u_1(x_1) \cdot u_2(x_2) \quad (x_i \in D'_i)$$

defines a mapping  $u: D \to A$  which is a solution of (7).

Put  $v(x_1, x_2) = u_1(x_1)u_2(x_2)$ , differentiate and apply (7), (10) and (2). This yields

(12) 
$$dv(x_1, x_2; \xi_1, \xi_2) = u_0(d\pi(x_1, x_2; \xi_1, \xi_2)x_2^{-1}x_1^{-1})v(x_1, x_2) .$$

In particular, dv = 0 whenever  $d\pi = 0$ . This, the regularity assump-

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tion and the implicit function theorem imply the existence of a function u satisfying (11) locally. In view of (12), this function is locally a solution of (7).

7. Our main theorem is an immediate consequence of the

**PROPOSITION 2.** Let D be an integrable submanifold of G of maximum dimension containing e and let  $u: D \rightarrow A$  be the solution of (7) with u(e) = 1. Then D is a local subgroup, u is a local homomorphism of D into  $A^*$  and D contains locally every integrable submanifold of G containing e.

We first show that

(\*) if D' is any integrable submanifold of G containing e, the tangent space to D' at e is contained in that of D.

Assume the contrary. Then there exists a neighborhood U of (e, e) in  $D \times D'$  such that, for every  $(x, x') \in U$ , the tangent space to  $x^{-1}D$  at e does not contain that to  $D'x'^{-1}$ . Let  $(f, f') \in U$  be a point where the product mapping  $D \times D' \to D \cdot D'$  is regular (one knows that the set of those points is dense). Then, by Lemma 3, there exist neighborhoods E of f in D and E' of f' in D' such that  $f^{-1}EE'f'^{-1}$  is an integrable manifold, which is obviously of dimension greater than that of D, in contradiction to the maximality assumption.

It follows from (\*) that the tangent space to D at any one of its points, say x, is a translate of its tangent space at e (take  $D' = x^{-1}D$ ). This ensures that D is a local group.

Since D is a local group, the product mapping  $D \times D \rightarrow D$  is regular in (e, e). It then follows from Lemma 3 that there exist a neighborhood U of (e, e) in  $D \times D$  and a function v defined in a neighborhood of e in D so that

$$v(x_1x_2) = u(x_1)u(x_2)$$

for  $(x_1, x_2) \in U$ . But then, for points  $x_1, x_2$  close enough to e, we have

$$u(x_1)u(x_2) = v(x_1x_2 \cdot e) = u(x_1x_2) \cdot u(e) = u(x_1x_2),$$

and u is a local representation.

Finally, if D' is integrable (right or left), it follows from (8) that the tangent space to D' at any one of its points is contained in a translate of the tangent space to D at e. If  $e \in D'$ , this implies that D' is locally (at e) contained in D.

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